Part 0



Part 1:

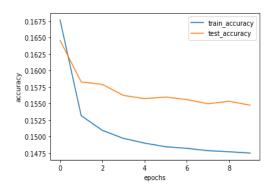
Activation function: Sigmoid, Relu and identity

Cross Entropy Function: Softmax and cross entropy functions were implemented.

Network and training

After training, the results were alike

Figure 0: Training of feed forward



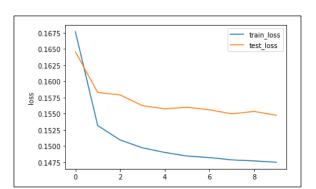


Figure 1: Graph for training and testing accuracy Figure 2: Graph for training and testing loss

Part 2:

Convolution Neural Network

In model of conv_net,

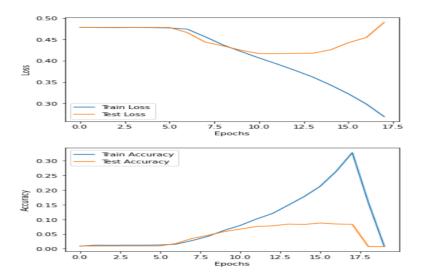


Figure 4: Top image is about training and testing loss, lower image is for training and testing accuracy.

Part 3:

My conv2D code runs but it is too time consuming. So, could not generate graph due to the shortage of time.

```
### TODO: Set target device for computations
device = torch.device('cuda' if torch.cuda.is_available() else 'cpu')
  ### TODO: Initialize my_conv2d
  model = my_conv2d(in_channels=3, out_channels=1, kernel_size=3)
  ### TODO: Put model parameters on target device
  model.to(device)
  train_loss_tracker = []
  train_accuracy_tracker = []
  test_loss_tracker = []
  test_accuracy_tracker = []
  for epoch in range(epochs):
       print(f'Epoch: \{epoch\}')
       train_loss, train_accuracy = Train(model, train_dl, device)
test_loss, test_accuracy = Test(model, test_dl, device)
        train loss tracker.append(sum(train loss)/len(train loss))
       train_accuracy_tracker.append(sum(train_accuracy)/len((train_accuracy)))
       test_loss_tracker.append(test_loss)
       test_accuracy_tracker.append(test_accuracy)
print('\t training loss/accuracy: {0:.3f}/{1:.3f}'.format(sum(train_loss)/len(train_loss), sum(train_accuracy)/len((train_accuracy))
print('\t testing loss/accuracy: {0:.3f}/{1:.3f}'.format(test_loss, test_accuracy))
  torch.save(model.state dict(), 'model extra credit.pth')
  Epoch: 0
: class my_conv2d(nn.Module):
       ### EXTRA CREDIT FOR UNDERGRADUATES - ### TODO: Compulsory for graduates
        ### Complete this class to have the perform the convolution similar to torch.nn.Conv2d
       def __init__(self, in_channels, out_channels, kernel_size, stride=1):
            super(my_conv2d, self).__init__()
self.in_channels = in_channels
            self.out_channels = out_channels
self.kernel_size = kernel_size
            self.stride = stride
self.padding = 0
            self.dialation = 1
            self.groups = 1
            self.k = np.sqrt(self.groups / self.in_channels * self.kernel_size**2)
            self.bias = torch.FloatTensor(self.out channels).uniform (-self.k, self.k)
            self.weight = torch.FloatTensor(self.out_channels, self.in_channels//self.groups, self.kernel_size, self.kernel_size).uni
       def forward(self, x):
            w_out = (x.size(2) - self.weight.size(2))//self.stride + 1
h_out = (x.size(3) - self.weight.size(3))//self.stride + 1
            x_unfold = torch.nn.functional.unfold(x, kernel_size=(self.kernel_size, self.kernel_size))
output_unfolded = x_unfold.transpose(1, 2).matmul(self.weight.view(self.weight.size(0), -1).t()).transpose(1, 2)
            output_folded = torch.nn.functional.fold(output_unfolded, output_size=(w_out, h_out), kernel_size=(1,1))
            return output_folded
```

Figure: training and Myconv2D implementation

Ablation of Study

```
### TODO: visualize the sample image
plt.imshow(sample_image.permute([1,2,0]))
plt.show()
```

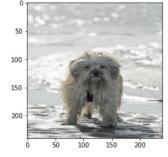


Figure 5: Sample image for AlexNet

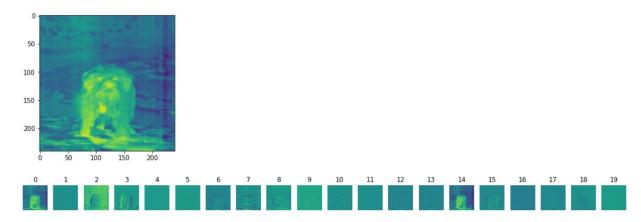


Figure 6: 20 images after convolution