

UNIVERSITY OF CALGARY
FACULTY OF SCIENCE
Department of Geoscience



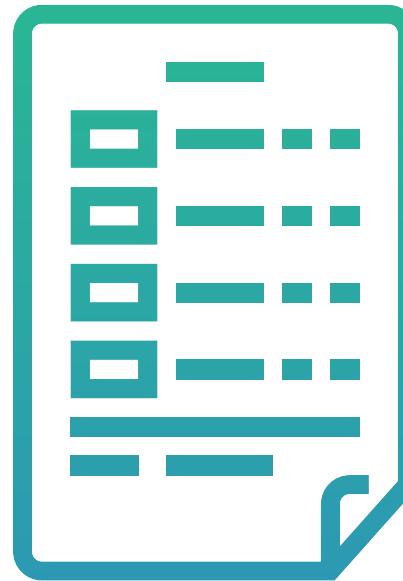
CREWES Data Science

Lecture 8: Regression 1

Marcelo Guarido

www.crewes.org



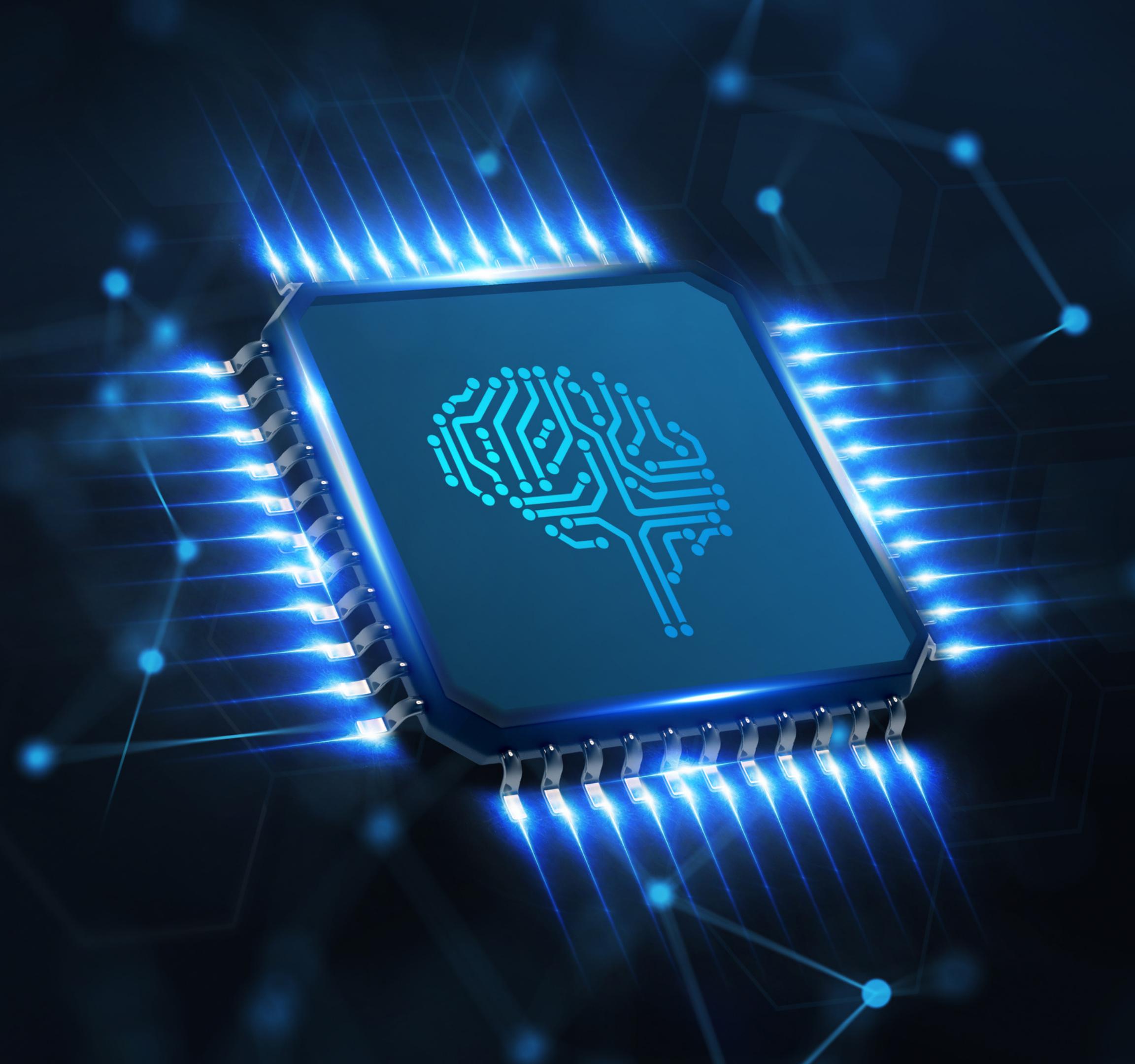


Today's Agenda

- Part 1:** Machine Learning
- Part 2:** Linear Regression
- Part 3:** SV Regressor
- Part 4:** Neural Networks
- Part 5:** Live Coding

Part 1:

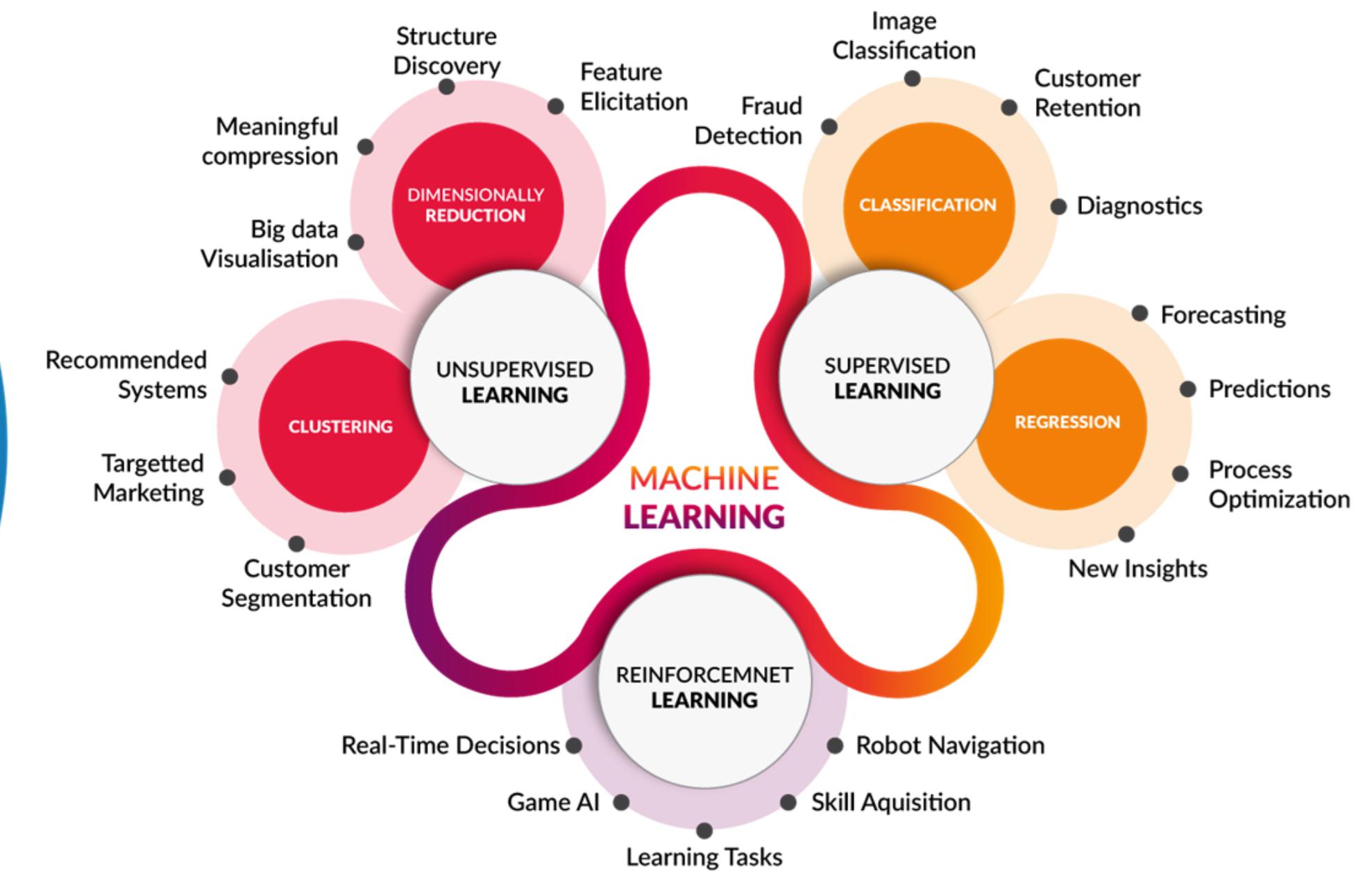
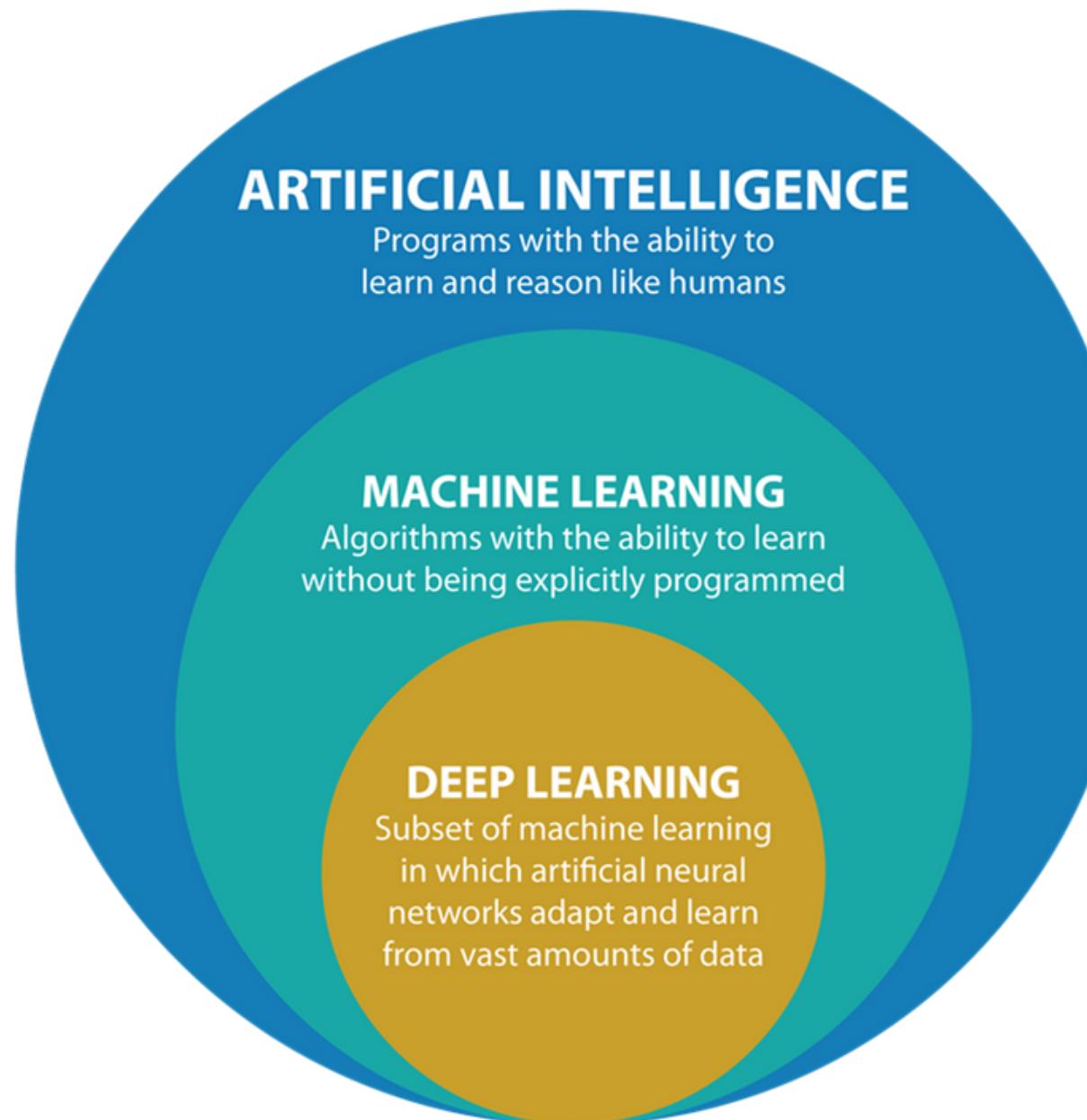
MACHINE LEARNING



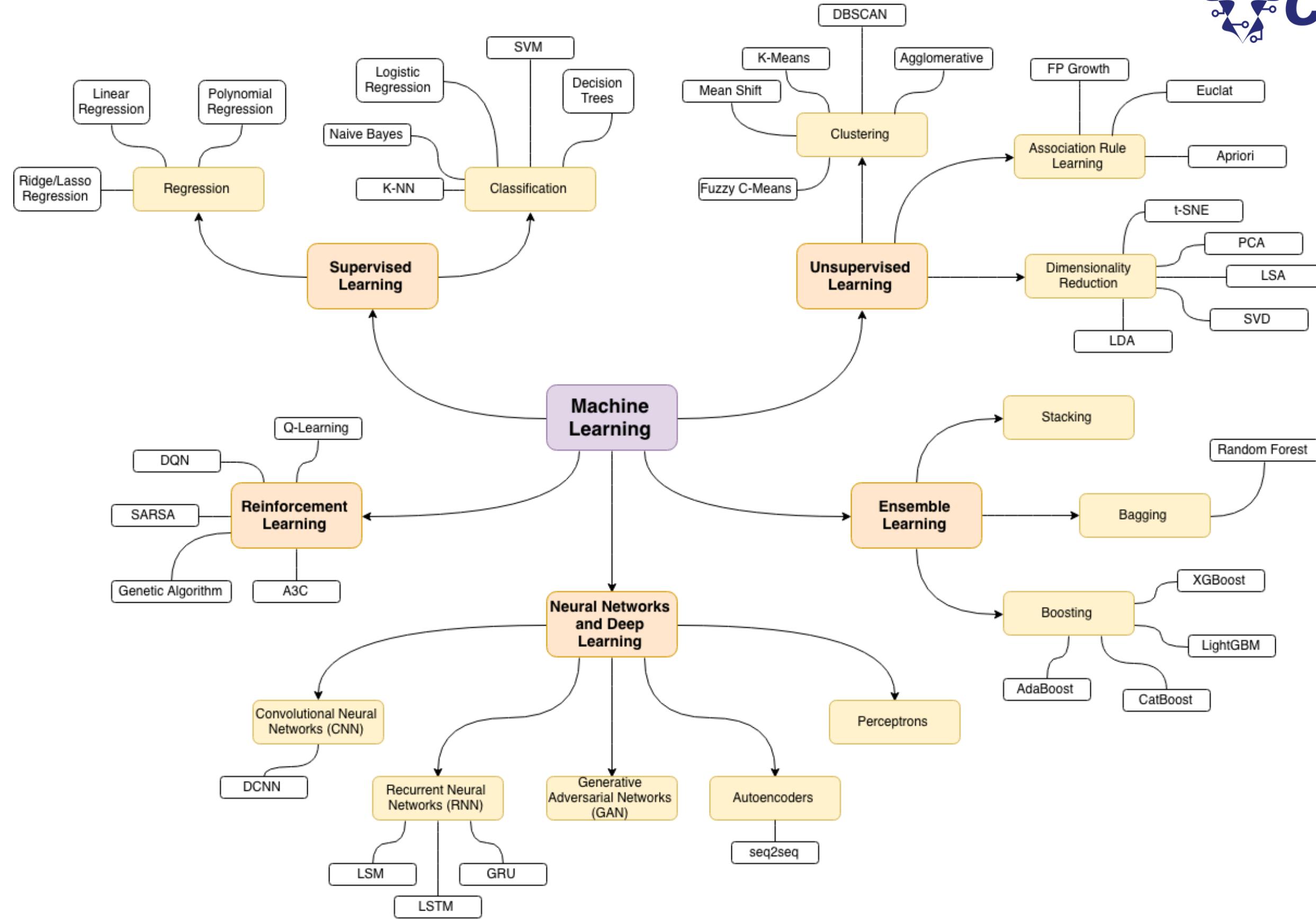
Machine Learning

“ *Machine learning* is a field of computer science that gives computer systems the ability to "learn" (i.e. progressively improve performance on a specific task) with data, without being explicitly programmed. ”

Machine Learning



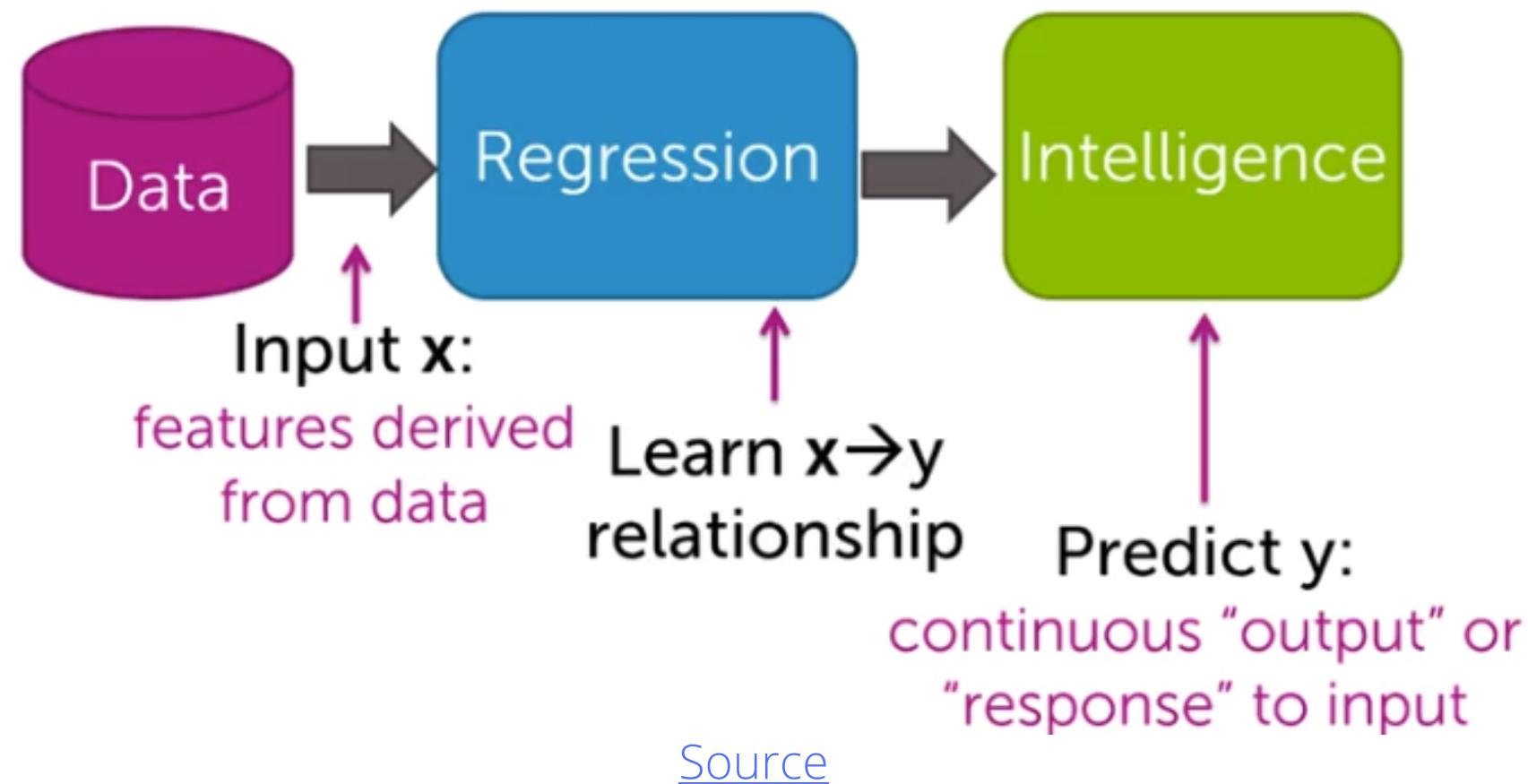
Figures from [Argility](#)

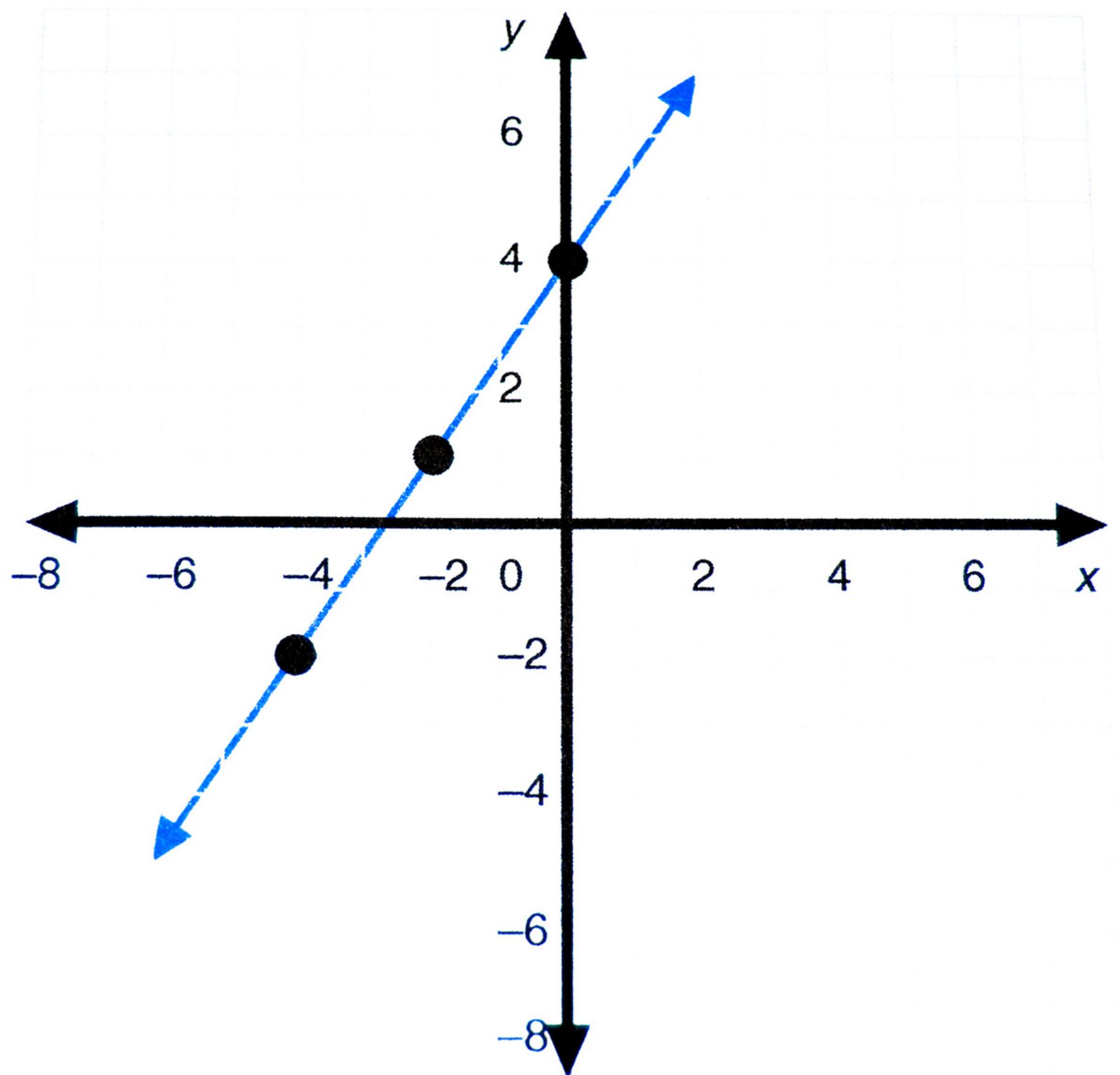


Regression

What is regression?

From features to predictions

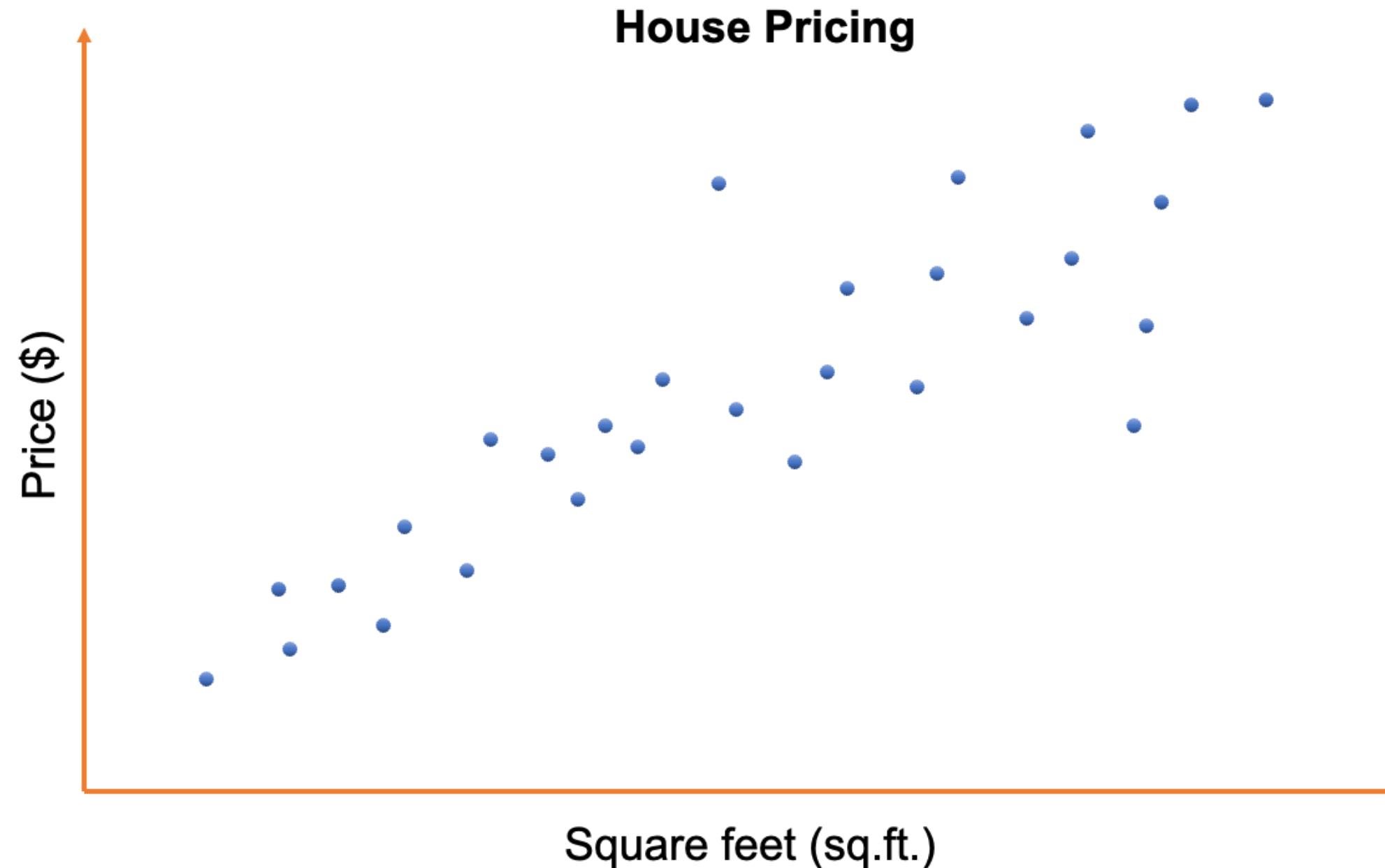




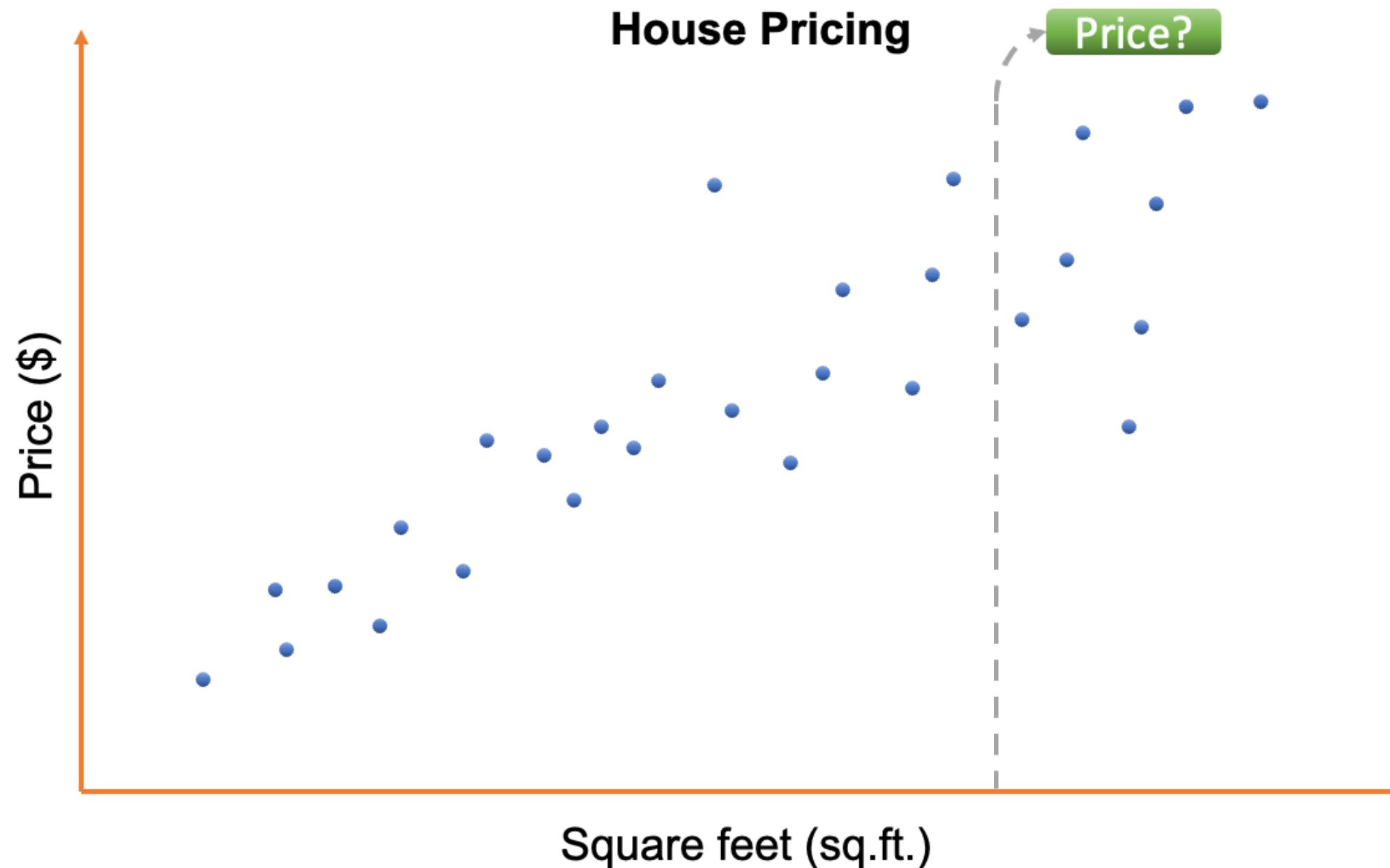
Part 2:

LINEAR REGRESSION

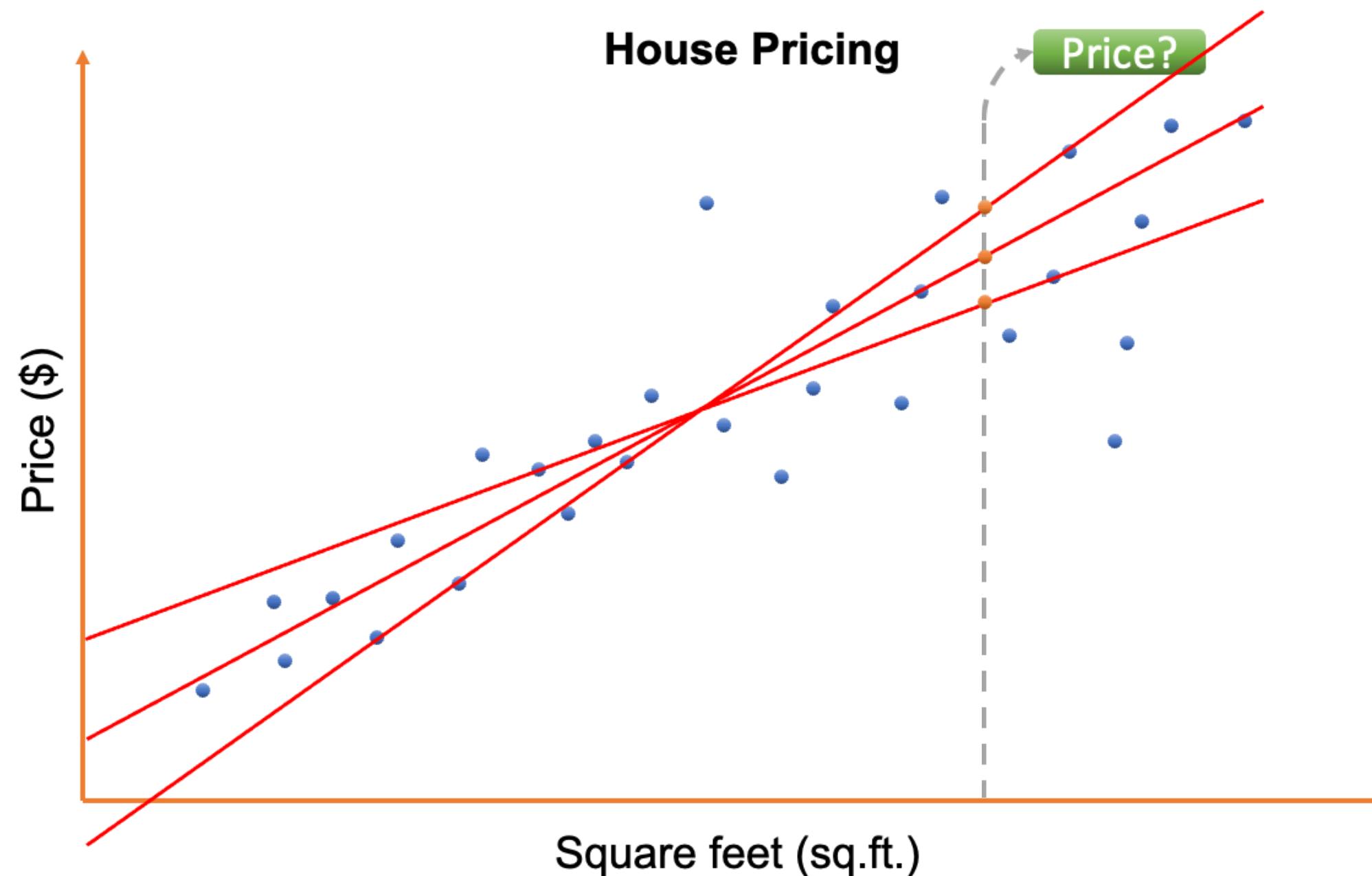
Linear Regression



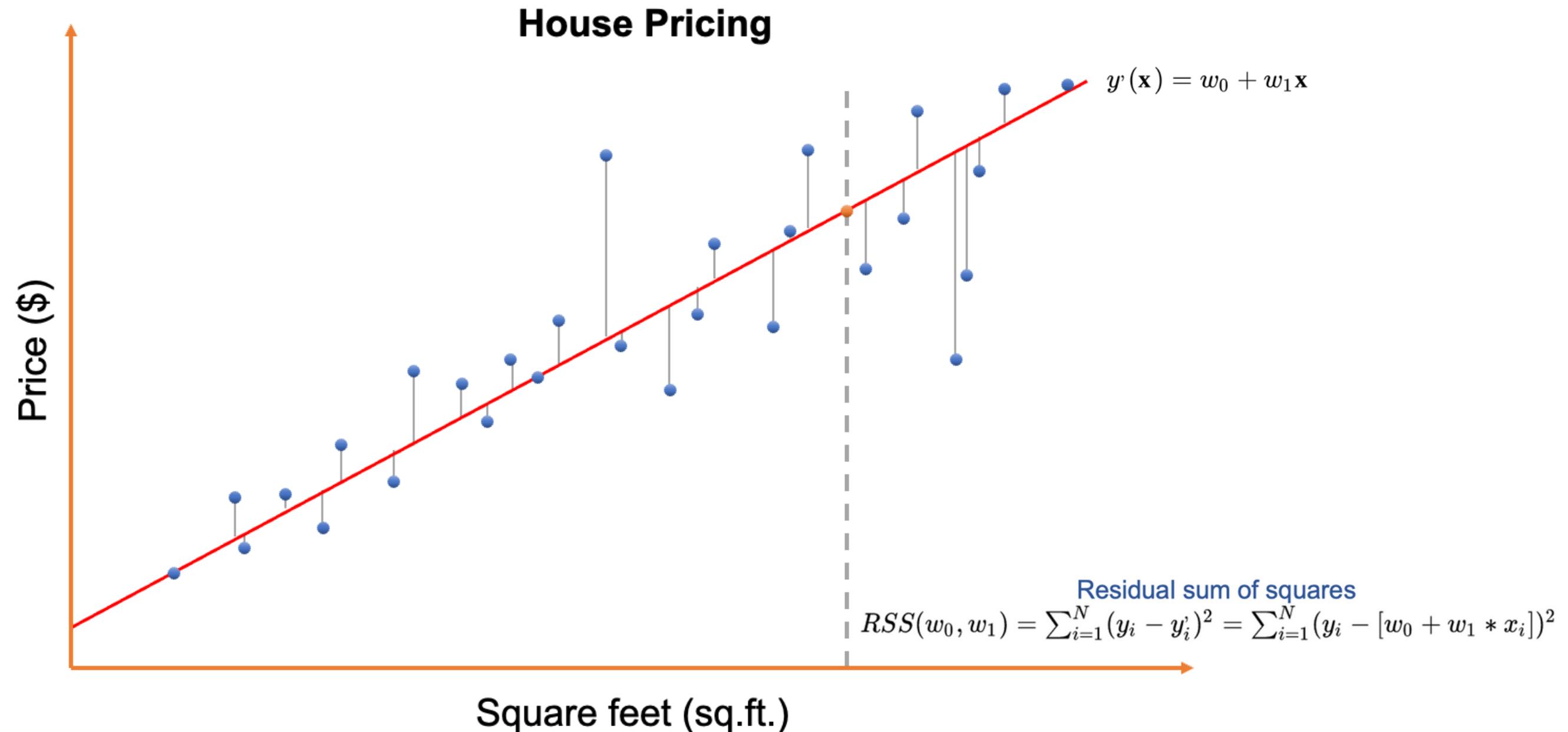
Linear Regression



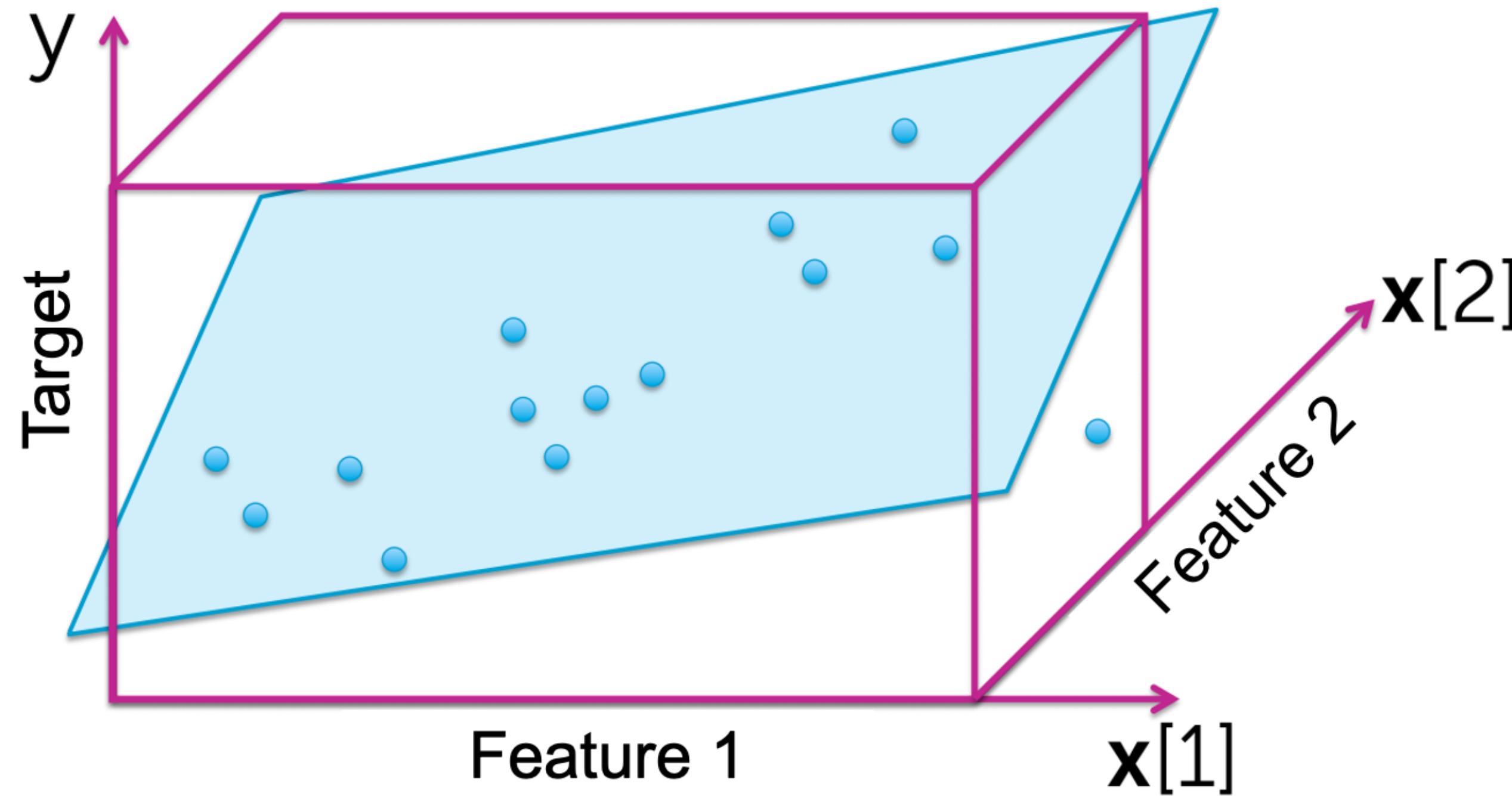
Linear Regression



Linear Regression



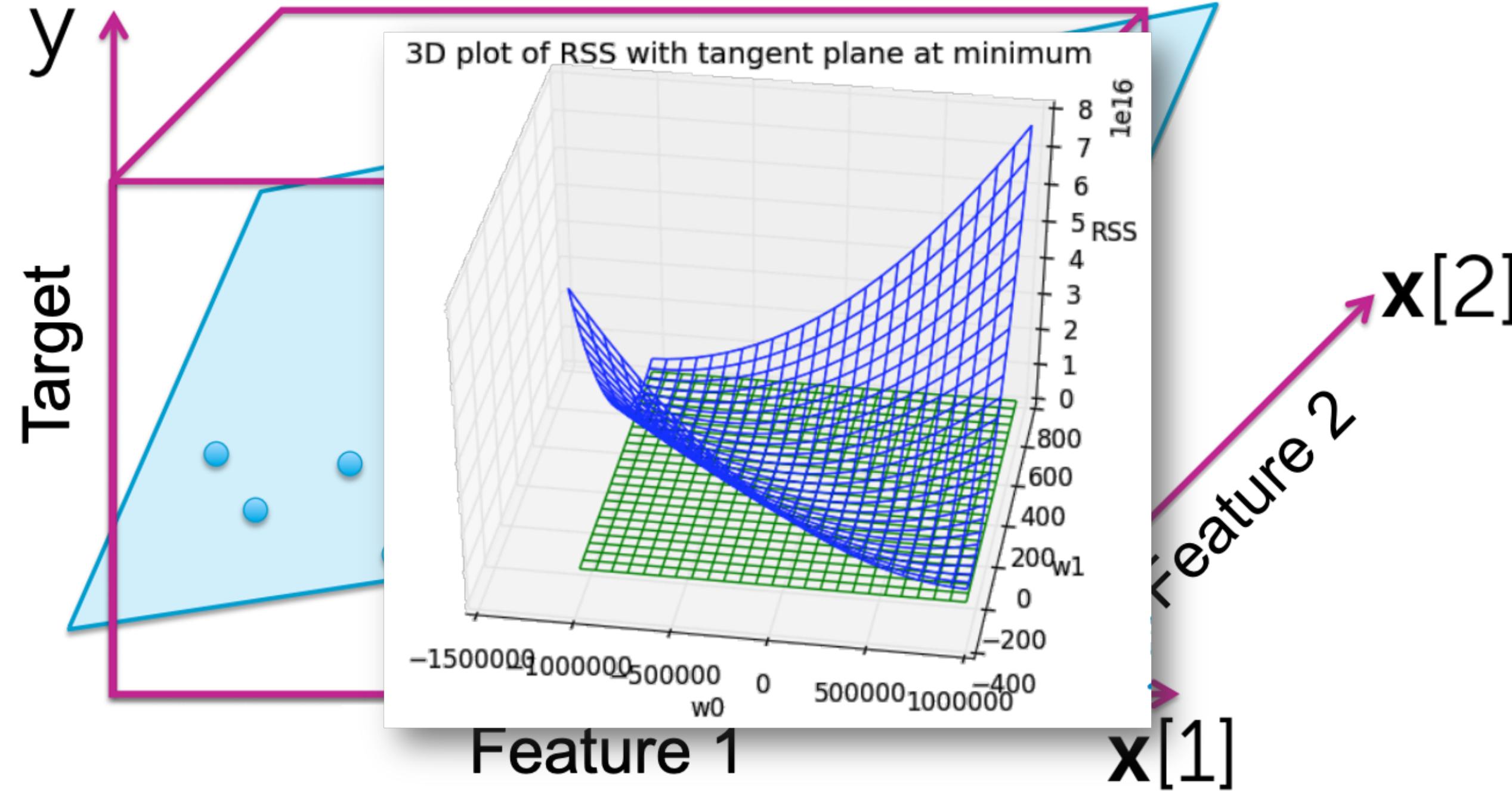
Linear Regression



Linear Regression

Hard to find analytical solution

Gradient Descent



Linear Regression

Pros

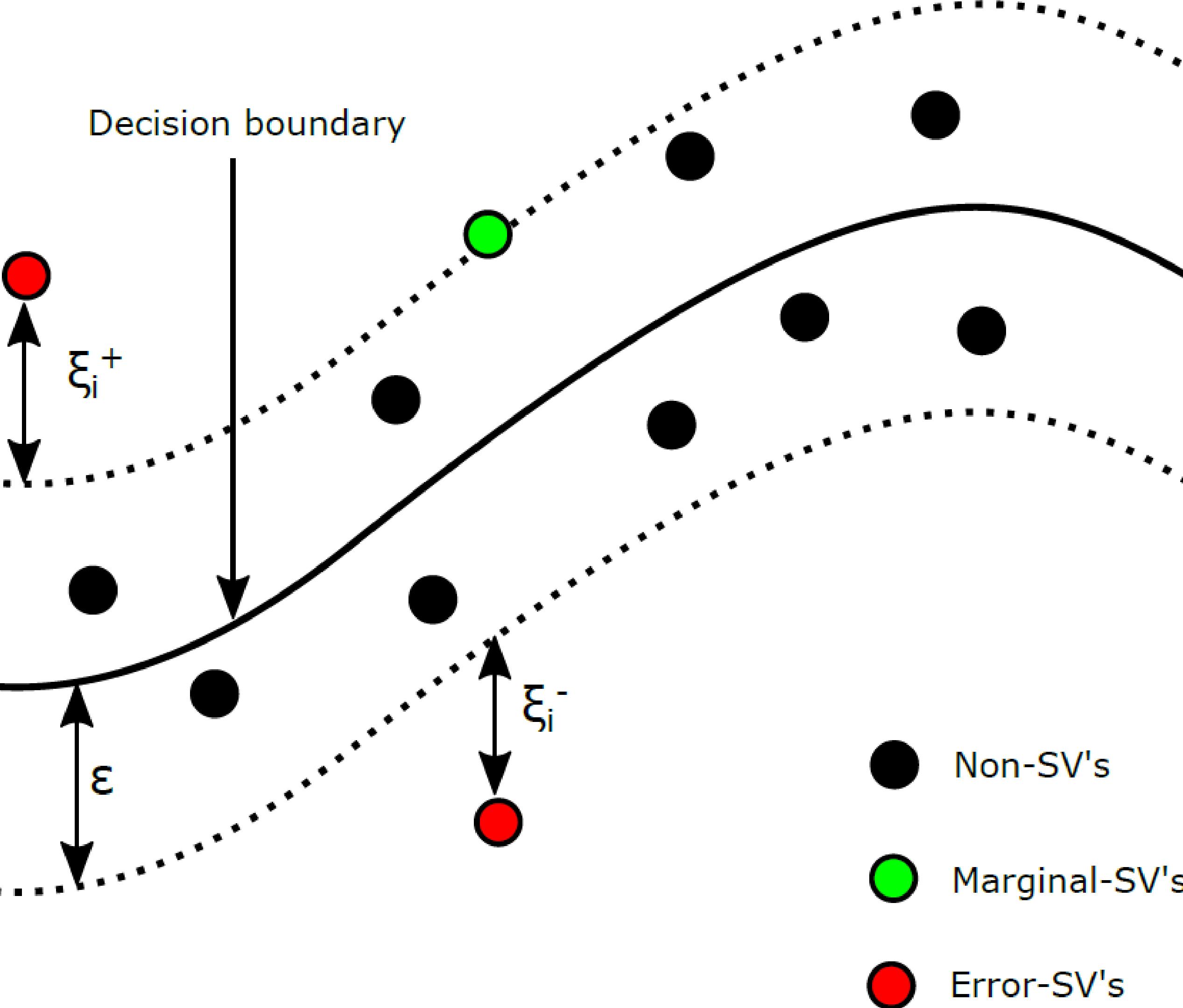
- Robust
- Easy to understand and interpret
- Low computing cost

Cons

- Only capture linear correlation
- Affected by outliers
- Requires normalized inputs
- Can't easily handle categorical features

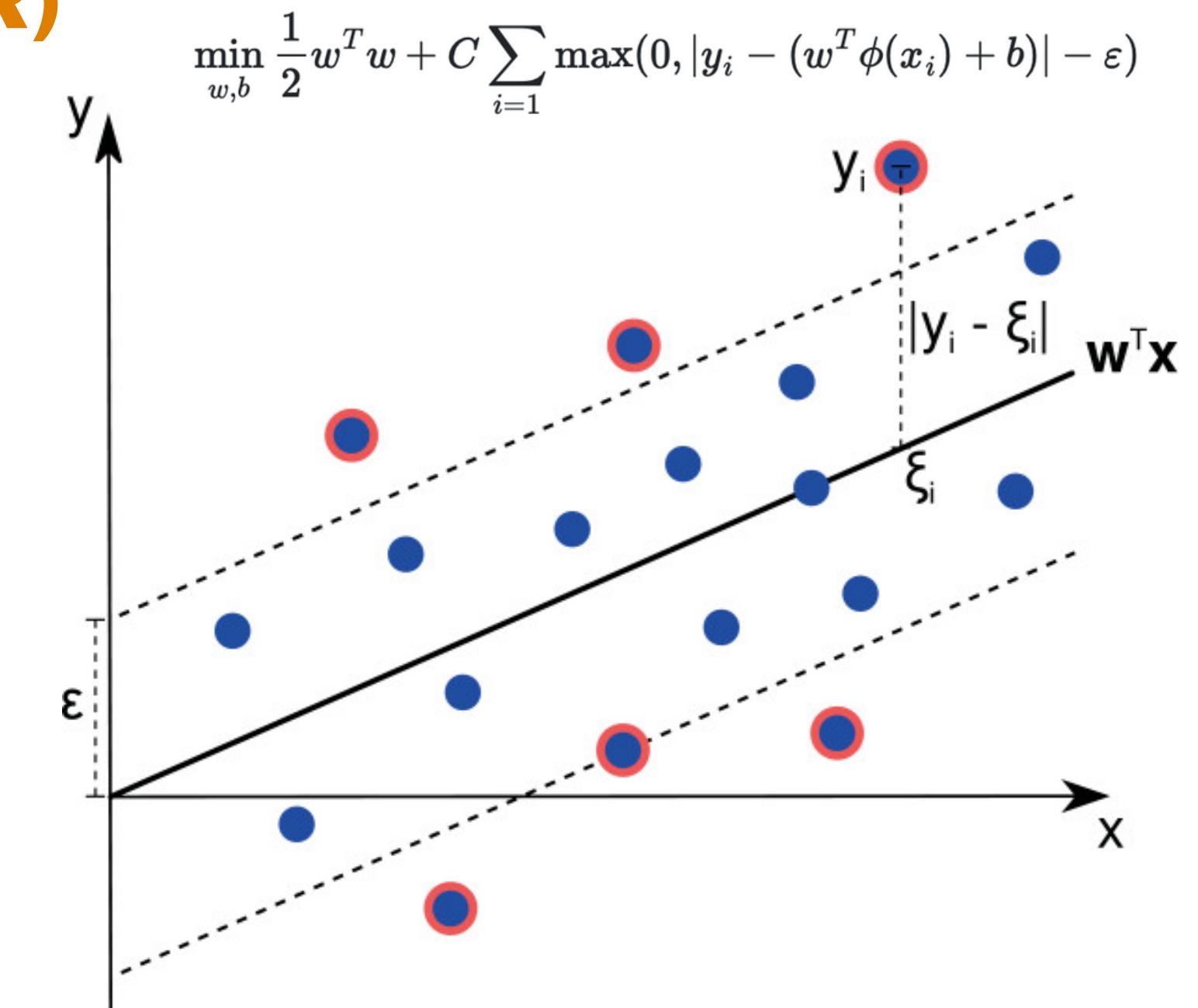
Part 3:

SV REGRESSOR



Support Vector Regressor (SVR)

- Find a line or curve that better fits the data
- Optimize for more points inside the error interval
- Can use different kernels, such as:
 - Linear: equation of a line
 - Poly: polynomial equation
 - RBF: radial-basis function, also known as "squared exponential"
- Less affected by outliers



[Source](#)

Support Vector Regressor (SVR)

Pros

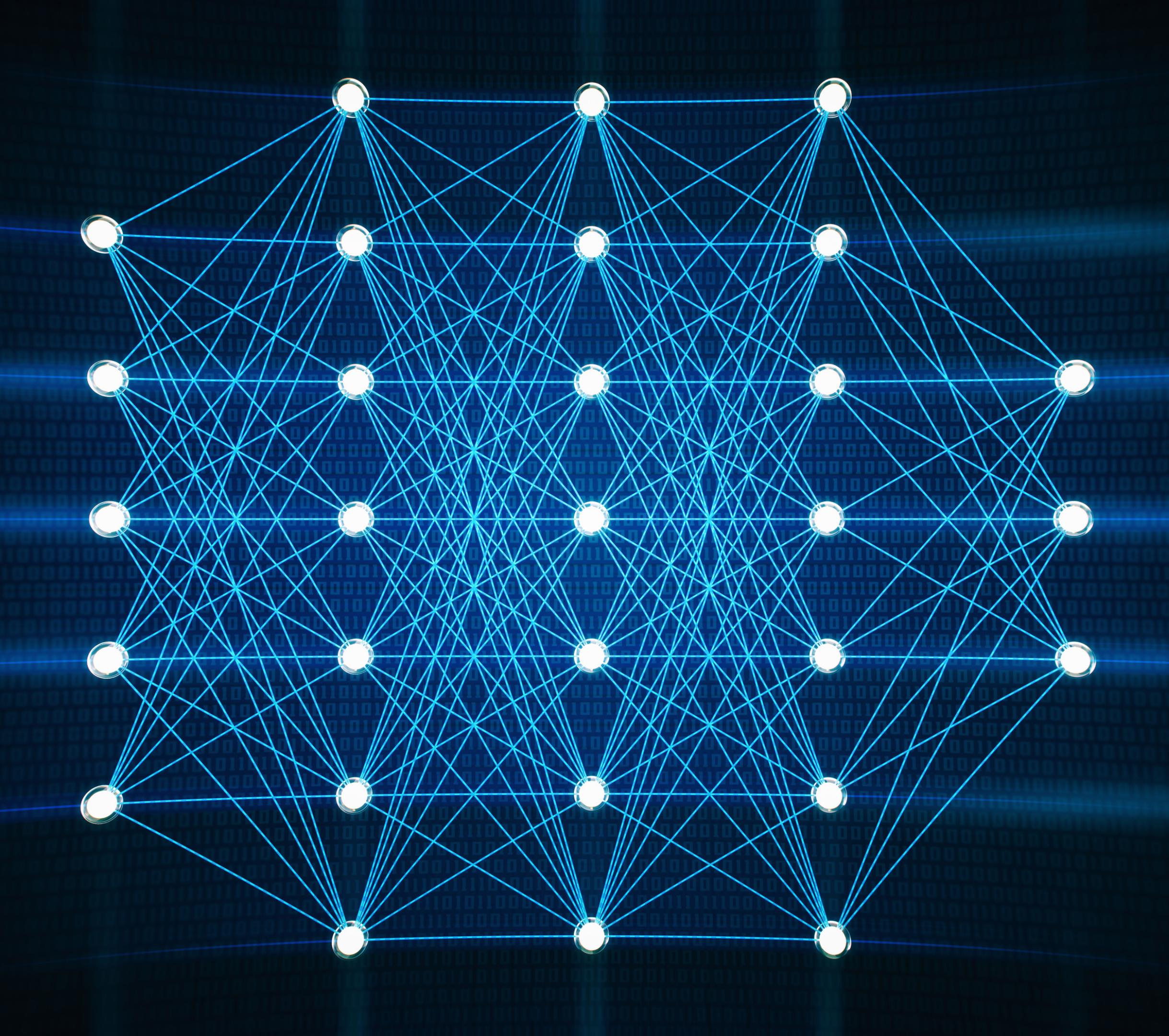
- Robust
- Can use different kernels
- Less affected by outliers

Cons

- Hard to parameterize
- Requires normalized inputs
- Can't easily handle categorical features
- High computation cost

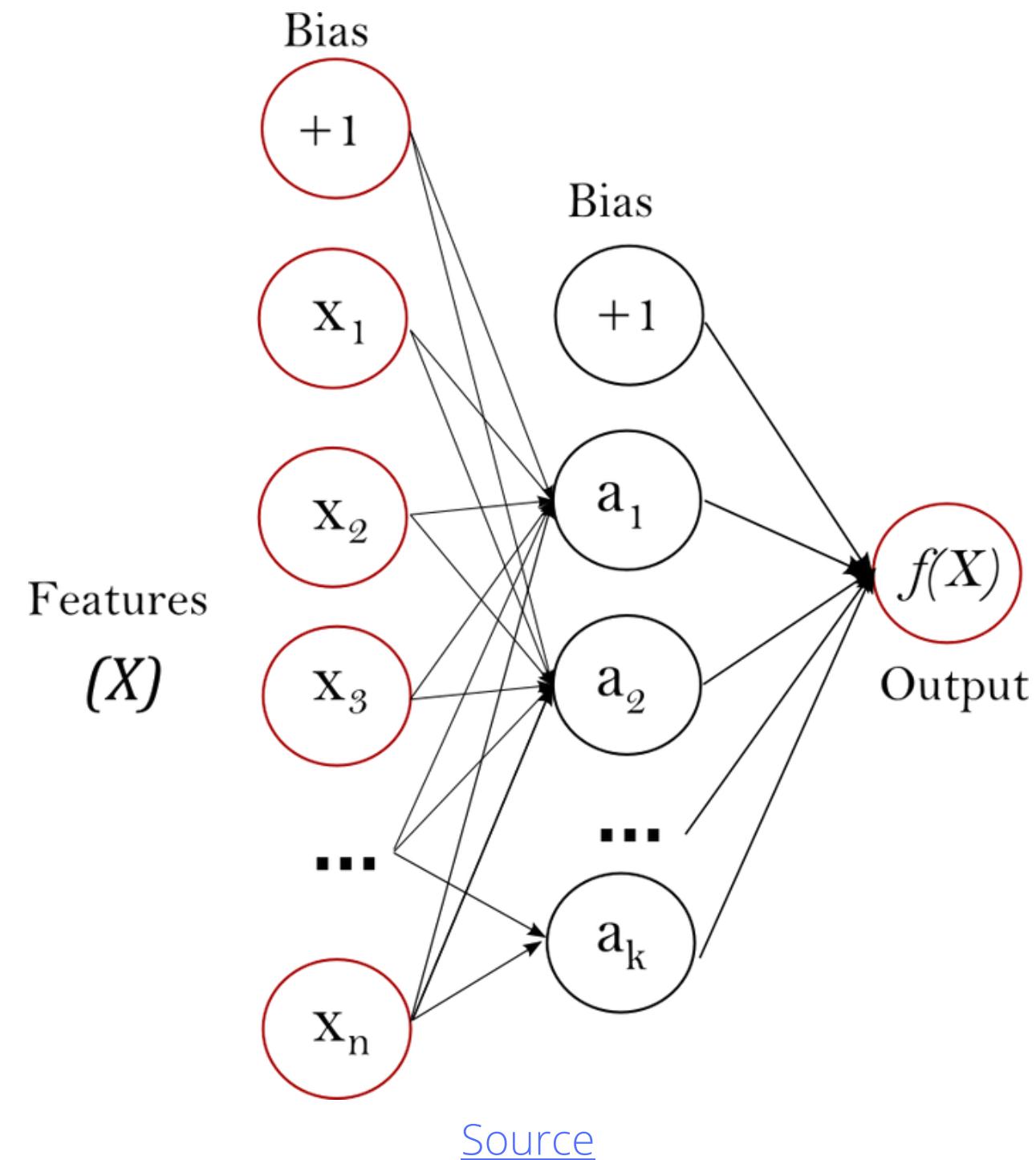
Part 4:

NEURAL NETWORKS

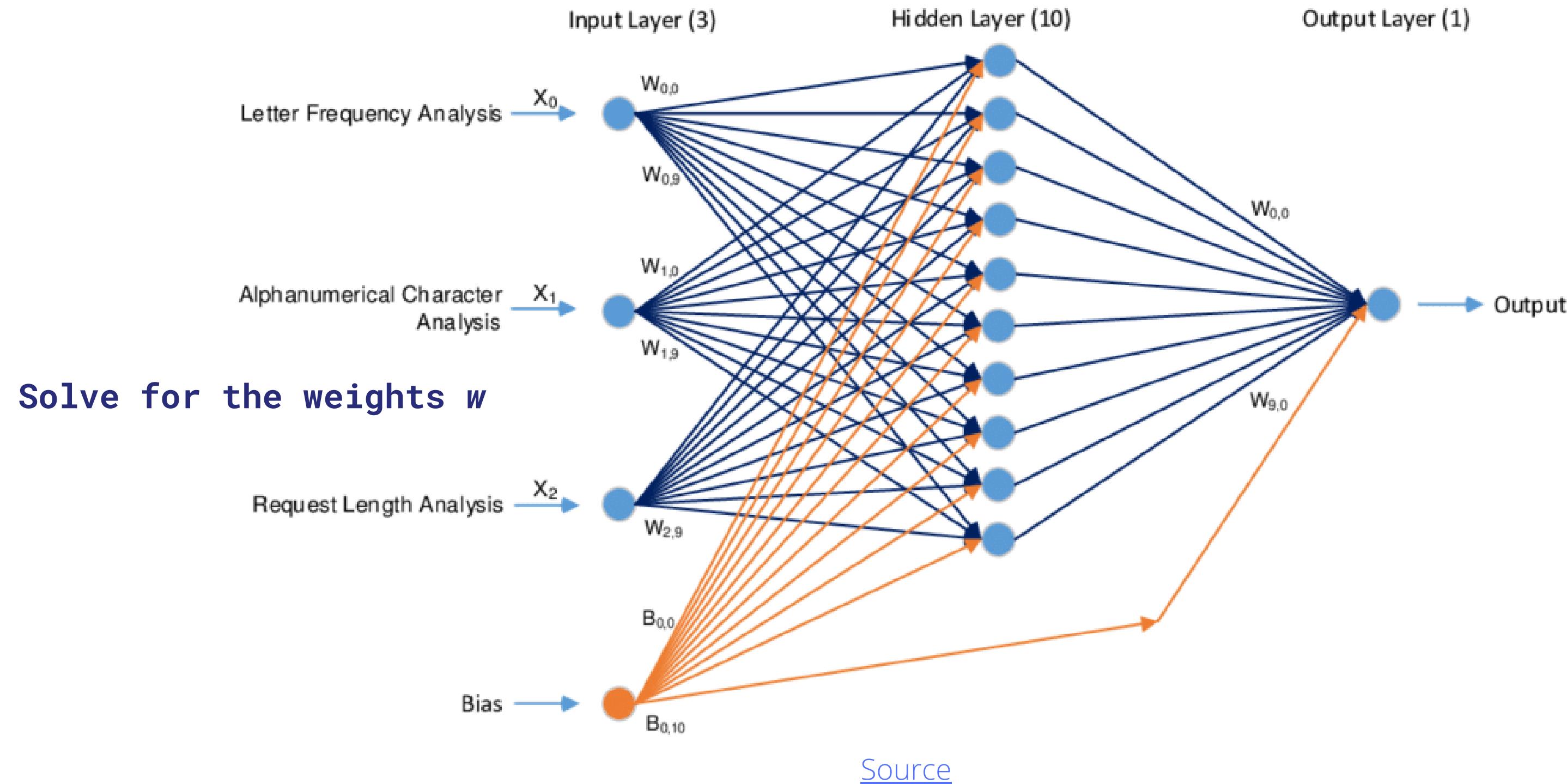


Neural Networks

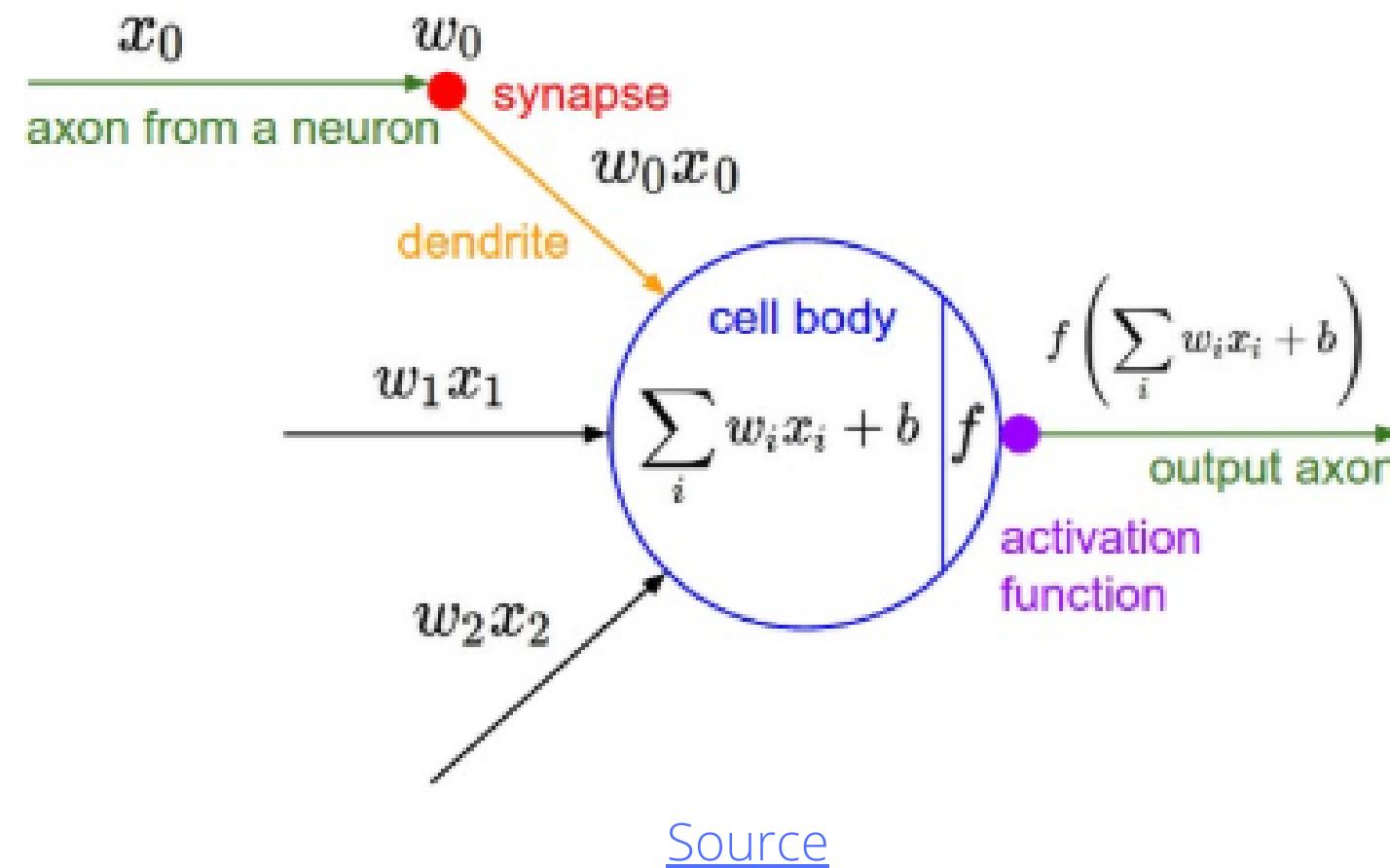
- Also called "multi-layer perceptron" (MLP)
- Contains different types of layers:
 - *Input layer*: input features
 - *Hidden layers*: internal calculations
 - *Output layer*: predictions
- MLP with 2 or more hidden layers are also called *deep learning*.



Neural Networks

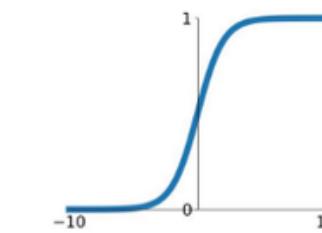


Activation Functions



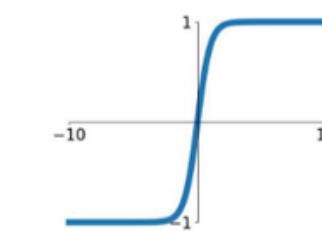
Sigmoid

$$\sigma(x) = \frac{1}{1+e^{-x}}$$



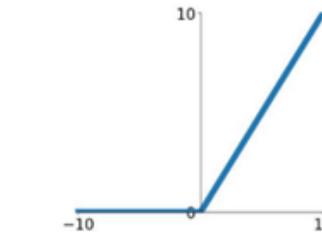
tanh

$$\tanh(x)$$



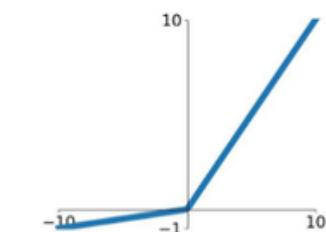
ReLU

$$\max(0, x)$$



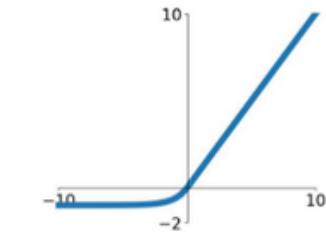
Leaky ReLU

$$\max(0.1x, x)$$



Maxout

$$\max(w_1^T x + b_1, w_2^T x + b_2)$$



ELU

$$\begin{cases} x & x \geq 0 \\ \alpha(e^x - 1) & x < 0 \end{cases}$$

Activation functions are used to introduce non-linearity to the model

Neural Networks

Pros

- Non-linear
- Flexible
- Works in most scenarios

Cons

- Hard to interpret
- Requires normalized inputs
- Can't easily handle categorical features
- Requires a large amount of data
- High computation cost

Part 5:

LIVE CODING (PYTHON)

```
    mirror_mod.mirror_object = selected_object
    mirror_mod.mirror_axis = "MIRROR_X"
    mirror_mod.mirror_use_x = True
    mirror_mod.mirror_use_y = False
    mirror_mod.mirror_use_z = False
    mirror_mod.mirror_axis = "MIRROR_Y"
    mirror_mod.mirror_use_x = False
    mirror_mod.mirror_use_y = True
    mirror_mod.mirror_use_z = False
    mirror_mod.mirror_axis = "MIRROR_Z"
    mirror_mod.mirror_use_x = False
    mirror_mod.mirror_use_y = False
    mirror_mod.mirror_use_z = True

    #selection at the end -add
    mirror_ob.select= 1
    mirror_mod.select=1
    bpy.context.scene.objects.active = mirror_mod
    ("Selected" + str(modifier_index))
    mirror_ob.select = 0
    bpy.context.selected_objects = []
    data.objects[one.name].select = 1
    print("please select exactly one object")

--- OPERATOR CLASSES ----

@types.Operator:
    @X mirror to the selected
    @object.mirror_mIRROR_X"
    @mirror X"

    @context):
        @context.active_object is not
```