

# Macroeconomics

## Lecture 12 – Topics in Macroeconomic Policy

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Fall 2023

# Outline

## 1 Monetary policy: discretion vs. commitment

- Optimal discretionary policy
- Optimal policy with commitment

## 2 Fiscal policy

- Government budget sustainability
- Ricardian equivalence
- RBC with government and lump-sum taxes

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## Goals of monetary policy

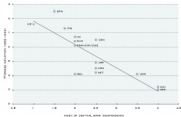
So far, policy monetary modelling in New Keynesian model followed **positive**, or descriptive, approach → **Taylor Rule**

Sufficient reaction to inflation → **active** Taylor Rule → equilibrium **determinacy** (Blanchard Kahn)

How about other goals?

- ▷ Maximize household utility (case of **benevolent** central bank)
- ▷ Other incentives (e.g. non-benevolent government & non-independent central bank) → suboptimal focus on GDP, neglect of inflation

# Central bank independence and inflation: data



Source: Federal Reserve Bank of St. Louis Annual Report 2009, Figure 1.

## Central Bank loss function

Consider the following **loss function** of the central bank (CB):

$$E_0 \sum_{t=0}^{\infty} \beta^t \frac{1}{2} \left( \pi_t^2 + \alpha_{\pi} x_t^2 \right)$$

where  $x_t = y_t - y_t^e$  and  $y_t^e$  is the log of **efficient GDP** (what a social planner would choose)

$y_t \neq y_t^e (\neq y_t^f)$ , because of sticky prices and market power of firms

In case of **benevolent CB**,  $\alpha_{\pi} = \frac{\kappa}{\varepsilon}$ , with  $\kappa$  the slope of the New Keynesian Phillips curve and  $\varepsilon$  the elasticity of goods substitution.  
CB non-independent  $\Rightarrow \alpha_{\pi}$  too high

Why inflation affects welfare? Recall that GDP depends on **price dispersion**:  $y_t = a_t + (1 - \alpha)\alpha_t - (1 - \alpha) \ln \left[ \int_0^1 \left( \frac{p_t(i)}{P_t} \right)^{\frac{\varepsilon}{\varepsilon-1}} di \right]^{\frac{\varepsilon-1}{\varepsilon}}$  and price dispersion is higher with higher inflation

## Phillips Curve with supply shock

$$\pi_t = \beta E_t \pi_{t+1} + \kappa \tilde{y}_t \quad (\text{New Keynesian Phillips curve})$$

...can be rewritten to have  $x_t$  instead of  $\tilde{y}_t$ :

$$\tilde{y}_t = y_t - y_t^f = y_t - y_t^d + (y_t^d - y_t^f) = x_t + y_t^d - y_t^f$$

so:

$$\begin{aligned} \pi_t &= \beta E_t \pi_{t+1} + \kappa(x_t + y_t^d - y_t^f) \\ &= \beta E_t \pi_{t+1} + \kappa x_t + \underbrace{\kappa(y_t^d - y_t^f)}_{\tilde{\pi}_t} \end{aligned}$$

$\tilde{\pi}_t = \beta E_t \tilde{\pi}_{t+1} + \kappa y_t + \varepsilon_t$

$\varepsilon_t$  assumed random: a **supply-side shock** a.k.a. cost-push shock

We will study a response of the CB to a one-off increase in  $x_t$

## Discretion vs. commitment

A policy that is decided upon each period is called **discretionary policy**

- ▷ advantage – immediate reaction to shocks
- ▷ disadvantage – the Central Bank does not follow a rule  $\Rightarrow$  does not influence  $E_t \pi_{t+1}$ , which determines  $\pi_t$

A policy that is pre-announced and always enacted as announced is a policy with **commitment**

We will look at discretionary and commitment policies in turn



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## Discretionary policy: static problem

The Central Bank only looks at period  $t$  trade-off between output gap and inflation:

$$\begin{aligned}
 \mathcal{L}_t &= \frac{\lambda}{2}(\pi_t^2 + \alpha_x x_t^2) + \lambda(\pi_t - \beta E_t \pi_{t+1} - kx_t - a_t) \\
 \min_{\pi_t, x_t} \quad & \frac{1}{2}(\pi_t^2 + \alpha_x x_t^2) \\
 \text{s.t.} \quad & \pi_t = \underbrace{\beta E_t \pi_{t+1}}_{\text{ignored}} + kx_t + a_t
 \end{aligned}$$

$\frac{\partial \mathcal{L}_t}{\partial \pi_t} = \pi_t + \lambda = 0$   
 $\frac{\partial \mathcal{L}_t}{\partial x_t} = \alpha_x x_t - \frac{\lambda k}{\beta} = 0$

Households and firms do not know the loss function of the CB  $\Rightarrow$  cannot solve CB problem for future periods  $\Rightarrow$  expectations not influenced by discretionary policy, can be ignored in minimization

Current shock value  $a_t$  is known by CB, future ones expected null

$$\text{Solution } x_t = -\frac{\beta}{\alpha_x} \pi_t$$

## Shock response: inflation and output

$$s_t > 0; \quad s_t = 0, \quad t \geq 1$$

$$j_t = \beta E_t j_{t+1} + \kappa x_t s_t; \quad x_t = -\frac{\kappa}{\pi_x} j_t$$

$$1 + \frac{\kappa^2}{\pi_x} = \frac{\pi_x + \kappa^2}{\pi_x}$$

$$j_t = \beta \frac{\pi_x}{\pi_x + \kappa^2} j_{t+1} + \kappa \cdot \left(-\frac{\kappa}{\pi_x}\right) j_t + s_t$$

$$\left(1 + \frac{\kappa^2}{\pi_x}\right) j_t = \beta \frac{\pi_x}{\pi_x + \kappa^2} j_{t+1} + s_t \quad | \cdot \frac{\pi_x + \kappa^2}{\pi_x}$$

$$j_t = \frac{\beta \pi_x}{\pi_x + \kappa^2} E_t j_{t+1} + \frac{\pi_x + \kappa^2}{\pi_x} s_t$$

$$j_t < E_t \sum_{k=0}^{\infty} \left(\frac{\beta \pi_x}{\pi_x + \kappa^2}\right)^k \frac{\pi_x + \kappa^2}{\pi_x} s_{t+k}$$

$$j_t < \frac{\pi_x + \kappa^2}{\pi_x} s_t; \quad j_t < 0, \quad t > 0$$

$$x_t = -\frac{\kappa}{\pi_x} j_t > 0; \quad x_t < 0, \quad t > 0$$



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## Policy with commitment: dynamic problem

$$\min_{\{x_t, \pi_t\}_{t=0}^{\infty}} E_0 \sum_{t=0}^{\infty} \beta^t \frac{1}{2} (x_t^2 + \alpha_s x_t^2)$$

$$\pi_t = \underbrace{\beta E_t x_{t+1}}_{\text{chosen by CB}} + \alpha x_t + s_t$$

omitted by the exp.  
 $E_0 E_2 \pi_{t+1}$

$$\mathcal{L} = E_0 \sum_{t=0}^{\infty} \beta^t \left( \frac{1}{2} (x_t^2 + \alpha_s x_t^2) + \lambda_t (\pi_t - \beta \pi_{t+1} - \alpha x_t - s_t) \right)$$

$$\mathcal{L} = \dots$$

$$+ E_0 \beta^t \left( \frac{1}{2} (x_t^2 + \alpha_s x_t^2) + \lambda_t (\pi_t - \beta \pi_{t+1} - \alpha x_t - s_t) \right)$$

$$+ E_0 \beta^{t+1} \left( \frac{1}{2} (x_{t+1}^2 + \alpha_s x_{t+1}^2) + \lambda_{t+1} (\pi_{t+1} - \beta \pi_{t+2} - \alpha x_{t+1} - s_{t+1}) \right)$$

$$+ \dots$$

$$\frac{\partial \mathcal{L}}{\partial \pi_{t+1}} = E_0 \beta^t \lambda_t (-\beta) + E_0 \beta^{t+1} (\pi_{t+1} + \lambda_{t+1}) = 0; \quad E_0 \lambda_t = E_0 [\pi_{t+1} + \lambda_{t+1}]$$

$$\mathcal{L} = \dots$$

$$\mathbb{E}_0 \beta^t \left( \frac{1}{2} (\pi_t^2 + \alpha_s x_t^2) + \lambda_t (\pi_t - \beta \pi_{t+1} - \kappa x_t - s_t) \right)$$

$$+ \mathbb{E}_0 \beta^{t+1} \left( \frac{1}{2} (\pi_{t+1}^2 + \alpha_s x_{t+1}^2) + \lambda_{t+1} (\pi_{t+1} - \beta \pi_{t+2} - \kappa x_{t+1} - s_{t+1}) \right)$$

+ ...

$$\frac{\partial \mathcal{L}}{\partial \pi_{t+1}} = \mathbb{E}_0 \beta^t \lambda_t (-\beta) + \mathbb{E}_0 \beta^{t+1} (-\pi_{t+2} + \lambda_{t+1}) = 0;$$

$$\lambda_t = \mathbb{E}_0 [\pi_{t+1} + \lambda_{t+1}]$$

$$\text{in } t=0: \lambda_0 = \pi_0 + \lambda_1$$

$$\lambda_{t+1} = \pi_t + \lambda_t \Rightarrow \pi_t = -\lambda_t$$

$$\frac{\partial \mathcal{L}}{\partial x_t} = \mathbb{E}_0 \beta^t (\alpha_s x_t - \lambda_t \kappa) = 0 \Leftrightarrow \mathbb{E}_0 x_t = \frac{\kappa \mathbb{E}_0 \lambda_t}{\alpha_s}$$

$$\Rightarrow \boxed{x_t = \frac{\kappa}{\alpha_s} \lambda_t = -\frac{\kappa}{\alpha_s} \pi_t}$$

Period & perspective:

$$\underline{E_t \lambda_t = E_t [J_{t+1} + \lambda_{t+1}]}$$

$$E_t x_t = \frac{K}{\alpha_2} J_t$$

$$\lambda_t = E_t [J_{t+1} + \lambda_{t+1}]$$

$$x_t = \frac{K}{\alpha_2} \lambda_t \Rightarrow \lambda_t = \frac{\alpha_2}{K} x_t$$

$$\lambda_t = E_t \underbrace{J_{t+1}}_{\text{known}} + E_t \underbrace{\frac{\alpha_2}{K} x_{t+1}}_{\text{known } E_t \text{ dropped}}$$

$$x_t = -\frac{K}{\alpha_2} J_t$$

$$\frac{\alpha_2}{K} x_t = J_{t+1} + \frac{\alpha_2}{K} x_{t+1} \mid \cdot \frac{K}{\alpha_2}$$

$$x_t = \frac{K}{\alpha_2} J_{t+1} + x_{t+1}$$

$$\begin{aligned} J_t + J_{t+1} \\ = p_t - (p_{t+1} - p_t) + p_{t+1} \\ = p_t - p_{t+1} + p_{t+1} + p_t \\ = 2p_t \end{aligned}$$

$$x_{t-1} = \frac{K}{\alpha_2} J_t + x_t \Rightarrow x_t = x_{t-1} - \frac{K}{\alpha_2} J_t$$

$$x_t = -\frac{K}{\alpha_2} J_t - \frac{K}{\alpha_2} J_{t-1} - \frac{K}{\alpha_2} (J_{t-1} + J_{t-2})$$

$$\begin{aligned} x_t &= -\frac{K}{\alpha_2} \sum_{i=0}^{t-1} J_{t-i} \\ &= -\frac{K}{\alpha_2} (p_t - p_{t-1}) \end{aligned}$$

$$\Leftarrow x_2 = x_1 - \frac{K}{\alpha_2} J_2 = -\frac{K}{\alpha_2} (J_1 + J_2 + J_3)$$

$$x_t = -\frac{k_2}{k_2 + k_1} J_t$$

$$= -\frac{k_2}{k_2} (p_t - p_{t-1})$$

$$J_t = \beta E_t J_{t+1} + K x_t + \varepsilon_t$$

$$p_t - p_{t-1} = \beta E_t (p_{t+1} - p_t) + K \left(-\frac{k_2}{k_2}\right) (p_t - p_{t-1}) + \varepsilon_t$$

Diff. equation of order 2, solution:

$$1 + \alpha_2$$

$$\beta = \frac{1 - \sqrt{1 - 4\alpha_1\alpha_2}}{2\alpha_1}$$

$$\alpha = \frac{\alpha_2}{K_2 \left(\frac{1}{\beta}\right) + K^2}$$

$$p_t - p_{t-1} = \beta (p_{t+1} - p_t + \varepsilon_t)$$

$$p_t - p_{t-1} = \beta \varepsilon_t$$

$$x_t = \frac{k_2}{k_2} \left( \frac{K_2}{K} x_{t-1} + \varepsilon_t \right)$$



## Policy with commitment: solution

The optimality condition is in terms of price level, or cumulative inflation:

$$x_t = -\frac{\kappa}{\alpha_x}(p_t - p_{-1}) = -\frac{\kappa}{\alpha_x} \sum_{k=0}^t \pi_k$$

Using Phillips curve, price level dynamics is:

$$p_t - p_{-1} = \delta(p_{t-1} - p_{-1} + s_t)$$

with  $\delta = \frac{1 - \sqrt{1 - 4\lambda\alpha^2}}{2\lambda\alpha}$  and  $a = \frac{\alpha_x}{\alpha_x(1 + \beta) + \alpha\sigma^2}$

Output gap dynamics is then:

$$x_t = \delta x_{t-1} - \frac{\kappa\delta}{\alpha_x} s_t \quad ; \quad x_0 = -\frac{\kappa\delta}{\alpha_x} s_0$$

## Discretion vs. commitment: impulse responses



Source: Gal textbook, Figure 5.1.

Commitment improves both output gap and inflation in  $t = 0$

**How?**  $\rightarrow$  by creating expectations about lower future inflation, via persistent negative output gap

In sum, output-inflation trade-off is better over the long horizon  $\Rightarrow$  CB losses smaller under commitment

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## Government budget constraint

The government has real spending  $G_t$  financed with taxes  $T_t$  and **government debt** accumulation  $D_{t+1} - D_t$



The government budget constraint can be written with the same logic as for household:

$$\begin{aligned} G_t + r_{t-1}D_t &= T_t + D_{t+1} - D_t \\ \Leftrightarrow D_{t+1} - D_t &= \underbrace{r_{t-1}D_t}_{\text{debt service}} + \underbrace{G_t - T_t}_{\text{primary deficit}} \\ &\quad \underbrace{\hspace{10em}}_{\text{total deficit}} \\ \Leftrightarrow D_{t+1} &= D_t(1 + r_{t-1}) + G_t - T_t \end{aligned}$$

Last equation = **recursive** (as many others in course)  $\Rightarrow$  can express  $D_t$  it as an infinite sum

## Government budget sustainability

$$D_0 = \sum_{t=0}^{\infty} \frac{T_t - G_t}{R_{0,t}} + \underbrace{\lim_{t \rightarrow \infty} \frac{D_t}{R_{0,t}}}_{=0}$$

with cumulative returns defined as:

$R_{0,0} = 1$ ,  $R_{0,1} = (1 + r_0)$ ,  $R_{0,2} = (1 + r_0)(1 + r_1)$  and  
 $R_{0,t} = (1 + r_0)(1 + r_1) \dots (1 + r_{t-1})$

- Future **primary surpluses** must be used to repay initial government debt
- The earlier primary surplus in the future, the more impact on debt dynamics
- Interest rates matter**  $\Rightarrow$  one can have a New Keynesian model with CB setting nominal rates  $\rightarrow$  government has incentive to put pressure on CB for lower rates!

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See version without  
annotations!

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## RBC with government

Use the joint budget constraint obtained before:

$$\begin{aligned} \max_{C_t, N_t, K_{t+1}, B_{t+1}} \quad & E_0 \sum_{t=0}^{\infty} \beta^t u(C_t, N_t, G_t) \\ \text{s.t.} \quad & C_t + I_t + B_{t+1} = w_t N_t + R_t K_t + (1 + r_{t-1})B_t + \Pi_t - T_t \\ & K_{t+1} = (1 - \delta)K_t + I_t \\ & D_{t+1} = (1 + r_{t-1})D_t + G_t - T_t \end{aligned}$$

as before,  $B_{t+1}$  is only needed to obtain the Euler equation; it is neutral by Ricardian equivalence



# RBC with government – closing the model

Preferences:

- Assume  $u(C_t, N_t, G_t)$  **additively separable** in  $(C_t, N_t)$  and  $G_t$

- e.g.  $\ln C_t = \theta \frac{N_t^{1+\gamma}}{1+\gamma} + \frac{G_t^{1-\gamma}}{1-\gamma}$

- Then  $u'_C, u'_N$  do not depend on  $G_t \Rightarrow$  **no direct effect on household choices**

Aggregate resource constraint:

$$Y_t = A_t F(K_t, N_t) = C_t + I_t + G_t$$

Handwritten diagram showing the derivation of the government spending constraint. It starts with the resource constraint  $Y_t = C_t + I_t + G_t$ . Then it shows  $C_t = (1 - \beta) \omega Y_t$ , which is crossed out with a red line. Next, it shows  $G_t = (1 - \beta) \omega Y_t$ , which is also crossed out with a red line. Finally, it shows  $G_{t-1} = \omega Y_{t-1}$ .

Government spending can follow an AR(1), like TFP:

- $\ln G_t = (1 - \rho_g) \ln(\omega Y_m) + \rho_g \ln G_{t-1} + \varepsilon_t^G \Rightarrow G_{tt} = \omega Y_{tt}$

- $\ln A_t = \rho_A \ln A_{t-1} + \varepsilon_t^A$

## Effect of government spending on consumer

Ricardian equivalence: any fiscal policy  $\{G_t, T_t, D_t\}_{t=0}^{\infty}$  with lump-sum taxes will have the same effect as the policy  $\{G_t\}_{t=0}^{\infty}, T_t = G_t, D_t = 0$ :

$$C_t + I_t = w_t N_t + R_t K_t + \Pi_t - G_t$$

The effect of an increase of  $G_t$  is then same as a negative income shock from consumer perspective:

- ▶ Use intuition on consumption smoothing to understand response of  $C_t, I_t$
  - ▶ Response of  $Y_t$  more ambiguous since  $Y_t = C_t + I_t + G_t$ , but tends to be positive
- ⇒ If government spending shock is the only source of cycles,  $C_t$  **countercyclical** ⇒ worse empirical performance than TFP shock

## Impulse responses – positive shock of $G$

Cobb-Douglas production,  $y(C_t, L_t, G_t) = \ln C_t - \theta \frac{L_t^{1+\eta}}{1+\eta} + \frac{G_t^{1-\varphi}}{1-\varphi}$  and

$\alpha$	$\beta$	$\eta$	$\phi$	$\theta$	$\rho_A$	$\rho_K$	$\omega$
1/3	0.99	1	0.025	4	0.97	0.95	0.2

