Uı	niversidad de Guadalajara CUCEI - Almost Retired			1
	Universidad de Guadalajara CUCEI		8 Graphs	<b>10</b>
			8.1 Cutpoints and bridges	10
	<ul> <li>Abraham Baltazar Murillo Sandoval</li> <li>Roberto Jesús García Pino</li> </ul>		8.2 Tarjan	10
	<ul> <li>Roberto Jesus Garcia Pino</li> <li>Jesús Uriel Guzmán-Mendoza</li> </ul>		8.3 Two sat $\mathcal{O}(2 \cdot n)$	10
	Jesus Offer Guzman-Mendoza		8.4 LCA	11
			8.5 Virtual tree $\mathcal{O}(n \cdot log n)$ "lca tree"	11
$\mathbf{C}$	ontents		8.6 Dynamic connectivity	11
			8.7 Euler-tour + HLD + LCA $\mathcal{O}(n \cdot log n)$	12
1	Data structures	2	8.8 Centroid $\mathcal{O}(n \cdot log n)$	12
	1.1 Sparse table	$2 \mid$	8.9 Guni $\mathcal{O}(n \cdot log n)$	13
	1.2 Fenwick 2D offline	3	· - /	13
	1.3 Persistent segtree	3	8.10 Link-Cut tree $\mathcal{O}(n \cdot log n)$	19
	1.4 Li Chao	3	9 Flows	14
	1.5 Wavelet	4	9.1 Hopcroft Karp $\mathcal{O}(e\sqrt{v})$	14
	1.6 Static to dynamic	4	9.2 Hungarian $\mathcal{O}(n^2 \cdot m)$	14
	1.7 Ordered tree	$\frac{4}{4}$		
	1.8 Treap	4	9.3 Blossom $\mathcal{O}(n^3)$	15
	1.9 Persistent Treap	$5 \mid$	9.4 Dinic $\mathcal{O}(\min(e \cdot flow, v^2 \cdot e))$	16
2	Dynamic programming	5	9.5 Min-Cost flow $\mathcal{O}(\min(e \cdot flow, v^2 \cdot e))$	16
_	2.1 All submasks of a mask	5	10.0	1 17
	2.2 Broken profile $\mathcal{O}(n \cdot m \cdot 2^n)$ with $n \leq m$	5	10 Game theory	17
	2.3 Convex hull trick $\mathcal{O}(n^2) \Rightarrow \mathcal{O}(n)$	5	10.1 Grundy numbers	17
	2.4 Divide and conquer $\mathcal{O}(k \cdot n^2) \Rightarrow \mathcal{O}(k \cdot nlogn)$ .	6	11 Math	17
	2.5 Knuth $\mathcal{O}(n^3) \Rightarrow \mathcal{O}(n^2)$	6		
	2.6 Matrix exponentiation $\mathcal{O}(n^3 \cdot log n) \cdot \dots \cdot \dots$	6	11.1 Bits	17
	2.7 SOS dp	6	11.2 Bitset	17
			11.3 Probability	17
3	Geometry	6	11.4 Gauss jordan $\mathcal{O}(n^2 \cdot m)$	18
	3.1 Geometry	6	11.5 Xor basis	18
	3.2 Radial order	7	40 G 11 1 1	
	3.3 Sort along line	7	12 Combinatorics	18
4	Point	7	12.1 Choose	18
-	4.1 Point	7	12.2 Factorial	18
	4.2 Angle between vectors	7	12.3 Factorial mod small prime	19
	4.3 Closest pair of points $\mathcal{O}(n \cdot log n)$	7	12.4 Pascal	19
	4.4 KD Tree	7	12.5 Stars and bars	19
			12.6 Lucas	19
5	Lines and segments	8	12.7 Burnside lemma	19
	5.1 Line	8	12.8 Catalan	19
	5.2 Segment	8	12.9 Bell numbers	19
	5.3 Projection	8	12.10Stirling numbers	19
	5.4 Distance point line	8	12.11Stirling numbers 2	19
	5.5 Distance point segment	8 8		
	5.6 Distance segment segment	0	13 Number theory	19
6	Circle	8	13.1 Amount of divisors $\mathcal{O}(n^{1/3})$	19
	6.1 Circle	8	13.2 Chinese remainder theorem	20
	6.2 Distance point circle	9	13.3 Euclid $\mathcal{O}(log(a \cdot b))$	20
	6.3 Common area circle circle	9	13.4 Inverse	20
	6.4 Minimum enclosing circle $\mathcal{O}(n)$ wow!!	9	13.5 Phi $\mathcal{O}(\sqrt{n})$	20
			13.6 Miller rabin $\mathcal{O}(Witnesses \cdot (logn)^3)$	20
7	Polygon	9	13.7 Pollard Rho $\mathcal{O}(n^{1/4})$	20
	7.1 Area polygon	9	)	
	7.2 Perimeter	9	14 Polynomials	20
	7.3 Cut polygon line	9	14.1 Berlekamp Massey	20
	7.4 Common area circle polygon $\mathcal{O}(n)$	9	14.2 Lagrange $\mathcal{O}(n)$	21
	7.5 Point in polygon	10	14.3 FFT	21
	7.6 Convex hull $\mathcal{O}(nlogn)$	10	14.4 Primitive root	21
	7.7 Is convex	10		$\frac{21}{22}$
	7.8 Point in convex polygon $\mathcal{O}(logn)$	10	14.5 NTT	22

```
Universidad de Guadalajara CUCEI - Almost Retired
                                                       22
15 Strings
  22
  15.2 KMP automaton \mathcal{O}(Alphabet * n) \dots \dots
                                                       22
                                                       22
  22
  23
  15.6 Suffix array \mathcal{O}(nlogn) . . . . . . . . . . . . . . . . .
                                                       23
  15.7 Aho Corasick \mathcal{O}(\sum s_i) . . . . . . . . . . . . . . . . .
                                                       24
  24
  15.9 Suffix automaton \mathcal{O}(\sum s_i) . . . . . . . . . . . .
Think twice, code once
Template.cpp
#pragma GCC optimize("Ofast,unroll-loops,no-stack-protector")
#include <bits/stdc++.h>
using namespace std;
#define fore(i, 1, r) for (auto i = (1) - ((1) > (r)); i != (r
    ) - ((1) > (r)); i += 1 - 2 * ((1) > (r)))
#define sz(x) int(x.size())
#define all(x) begin(x), end(x)
#ifdef LOCAL
#include "debug.h"
#else
#define debug(...)
using ld = long double; using lli = long long;
int main() {
  cin.tie(∅)->sync_with_stdio(∅), cout.tie(∅);
Debug.h
#include <bits/stdc++.h>
using namespace std;
template <class A, class B>
ostream& operator<<(ostream& os, const pair<A, B>& p) {
  return os << "(" << p.first << ", " << p.second << ")";</pre>
template <class A, class B, class C>
basic_ostream<A, B>& operator<<(basic_ostream<A, B>& os, const
     C& c) {
  os << "[";
  for (const auto& x : c) os << ", " + 2 * (&x == &*begin(c))</pre>
      << x;
  return os << "]";</pre>
void print(string s) { cout << endl; }</pre>
template <class H, class... T>
void print(string s, const H& h, const T&... t) {
  const static string reset = "\033[0m", blue = "\033[1;34m",
      purple = "\033[3;95m";
  bool ok = 1;
  do {
    if (s[0] == '\"') ok = 0;
    else cout << blue << s[0] << reset;</pre>
    s = s.substr(1);
  } while (s.size() && s[0] != ',');
  if (ok) cout << ": " << purple << h << reset;</pre>
  print(s, t...);
```

```
#define debug(...) print(#__VA_ARGS__, __VA_ARGS__)
Randoms
 mt19937 rng(chrono::steady_clock::now().time_since_epoch().
     count());
Compilation (gedit /.zshenv)
 compile() {
  alias flags='-Wall -Wextra -Wfatal-errors -Wshadow -w -
       mcmodel=medium'
   g++-11 --std=c++17 $2 ${flags} $1.cpp -o $1
 go() {
  file=$1
  name="${file%.*}"
  compile ${name} $3
   ./${name} < $2
 run() { go $1 $2 "" }
 debug() { go $1 $2 -DLOCAL }
 random() { # Make small test cases!!!
   red='\x1B[0;31m' green='\x1B[0;31m' removeColor='\x1B[0m'
   file=$1
   name="${file%.*}"
   compile ${name} ""
  compile gen ""
   compile brute ""
   for ((i = 1; i <= 300; i++)); do
     printf "Test case #${i}"
     ./gen > tmp
     diff -ywi <(./name < tmp) <(./brute < tmp) > $nameDiff
     if [[ $? -eq 0 ]]; then
       printf "${green} Accepted ${removeColor}\n"
       printf "${red} Wrong answer ${removeColor}\n"
     fi
   done
 }
     Data structures
1
```

#### 1.1 Sparse table

```
template <class T, class F = function<T(const T&, const T&)>>
struct Sparse {
  vector<T> sp[21]; // n <= 2^21</pre>
  Ff;
  int n;
 Sparse(T* begin, T* end, const F& f) : Sparse(vector<T>(
      begin, end), f) {}
  Sparse(const vector<T>& a, const F& f) : f(f), n(sz(a)) {
    sp[0] = a;
    for (int k = 1; (1 << k) <= n; k++) {
      sp[k].resize(n - (1 << k) + 1);
      fore (1, 0, sz(sp[k])) {
        int r = 1 + (1 << (k - 1));
        sp[k][1] = f(sp[k - 1][1], sp[k - 1][r]);
      }
    }
  }
 T query(int 1, int r) {
```

```
#warning Can give TLE D:, change it to a log table
     int k = _{l}(r - l + 1);
    return f(sp[k][1], sp[k][r - (1 << k) + 1]);
  T queryBits(int 1, int r) {
    optional<T> ans;
     for (int len = r - l + 1; len; len -= len & -len) {
      int k = __builtin_ctz(len);
      ans = ans ? f(ans.value(), sp[k][1]) : sp[k][1];
      1 += (1 << k);
    }
    return ans.value();
};
1.2
      Fenwick 2D offline
template <class T>
struct Fenwick2D { // add, build then update, query
  vector<vector<T>> fenw;
  vector<vector<int>> ys;
  vector<int> xs;
  vector<ii> pts;
  void add(int x, int y) { pts.pb({x, y}); }
  void build() {
    sort(all(pts));
    for (auto&& [x, y] : pts) {
      if (xs.empty() || x != xs.back()) xs.pb(x);
       swap(x, y);
    fenw.resize(sz(xs)), ys.resize(sz(xs));
     sort(all(pts));
    for (auto&& [x, y] : pts) {
       swap(x, y);
       int i = lower_bound(all(xs), x) - xs.begin();
       for (; i < sz(fenw); i |= i + 1)
         if (ys[i].empty() || y != ys[i].back()) ys[i].pb(y);
    }
     fore (i, 0, sz(fenw)) fenw[i].resize(sz(ys[i]), T());
  void update(int x, int y, T v) {
    int i = lower_bound(all(xs), x) - xs.begin();
    for (; i < sz(fenw); i |= i + 1) {
      int j = lower_bound(all(ys[i]), y) - ys[i].begin();
       for (; j < sz(fenw[i]); j |= j + 1) fenw[i][j] += v;</pre>
    }
  }
  T query(int x, int y) {
    T v = T();
    int i = upper_bound(all(xs), x) - xs.begin() - 1;
    for (; i \ge 0; i \& i + 1, --i) {
      int j = upper_bound(all(ys[i]), y) - ys[i].begin() - 1;
       for (; j \ge 0; j \&= j + 1, --j) v += fenw[i][j];
    }
    return v;
  }
};
1.3
      Persistent segtree
template <class T>
struct Per {
   int 1, r;
  Per *left, *right;
  T val;
```

```
Per(int 1, int r) : l(1), r(r), left(0), right(0) {}
   Per* pull() {
     val = left->val + right->val;
     return this:
   }
   void build() {
     if (1 == r) return;
     int m = (1 + r) >> 1;
     (left = new Per(1, m))->build();
     (right = new Per(m + 1, r)) -> build();
     pull();
   template <class... Args>
   Per* update(int p, const Args&... args) {
     if (p < 1 || r < p) return this;
     Per* t = new Per(1, r);
     if (1 == r) {
       t->val = T(args...);
       return t;
     }
     t->left = left->update(p, args...);
     t->right = right->update(p, args...);
     return t->pull();
   }
   T query(int 11, int rr) {
     if (r < ll || rr < l) return T();</pre>
     if (ll <= l && r <= rr) return val;
     return left->query(ll, rr) + right->query(ll, rr);
   }
 };
1.4 Li Chao
 struct LiChao {
   struct Fun {
     11i m = \emptyset, c = -INF;
     1li operator()(lli x) const { return m * x + c; }
   } f;
   lli 1, r;
   LiChao *left, *right;
   LiChao(lli 1, lli r, Fun f) : 1(1), r(r), f(f), left(∅),
        right(0) {}
   void add(Fun& g) {
     lli m = (l + r) >> 1;
     bool bl = g(1) > f(1), bm = g(m) > f(m);
     if (bm) swap(f, g);
     if (1 == r) return;
     if (bl != bm)
       left ? left->add(g) : void(left = new LiChao(l, m, g));
       right ? right->add(g) : void(right = new LiChao(m + 1, r
            , g));
   }
   1li query(lli x) {
     if (1 == r) return f(x);
     11i m = (1 + r) >> 1;
     if (x \le m) return max(f(x), left ? left > query(x) : -INF)
     return max(f(x), right ? right->query(x) : -INF);
   }
 };
```

```
Wavelet
```

```
struct Wav {
 int lo, hi;
 Wav *left, *right;
 vector<int> amt;
  template <class Iter>
 Wav(int lo, int hi, Iter& b, Iter& e) : lo(lo), hi(hi) { //
      array 1-indexed, check on reference (&)
    if (lo == hi || b == e) return;
    amt.reserve(e - b + 1);
    amt.pb(₀);
    int mid = (lo + hi) >> 1;
    auto leq = [mid](auto x) { return x <= mid; };</pre>
    for (auto it = b; it != e; it++) amt.pb(amt.back() + leq(*
        it));
    auto p = stable_partition(b, e, leq);
    left = new Wav(lo, mid, b, p);
    right = new Wav(mid + 1, hi, p, e);
  // kth value in [1, r]
 int kth(int 1, int r, int k) {
    if (r < 1) return 0;</pre>
    if (lo == hi) return lo;
    if (k <= amt[r] - amt[l - 1]) return left->kth(amt[l - 1]
        + 1, amt[r], k);
   return right->kth(l - amt[l - 1], r - amt[r], k - amt[r] +
         amt[1 - 1]);
 }
  // Count all values in [1, r] that are in range [x, y]
  int count(int 1, int r, int x, int y) {
    if (r < 1 || y < x || y < lo || hi < x) return 0;
    if (x \le lo \&\& hi \le y) return r - l + 1;
    return left->count(amt[l - 1] + 1, amt[r], x, y) +
           right->count(l - amt[l - 1], r - amt[r], x, y);
 }
};
      Static to dynamic
template <class Black, class T>
struct StaticDynamic {
 Black box[25];
  vector<T> st[25];
 void insert(T& x) {
    int p = 0;
    while (p < 25 \&\& !st[p].empty()) p++;
    st[p].pb(x);
    fore (i, 0, p) {
      st[p].insert(st[p].end(), all(st[i]));
      box[i].clear(), st[i].clear();
    for (auto y : st[p]) box[p].insert(y);
    box[p].init();
 }
};
    Ordered tree
```

```
It's a set/map, for a multiset/multimap (? add them as pairs
(alil i)
#include <ext/pb_ds/assoc_container.hpp>
#include <ext/pb_ds/tree_policy.hpp>
using namespace __gnu_pbds;
template <class K, class V = null_type>
using OrderedTree =
```

```
tree<K, V, less<K>, rb_tree_tag,
          tree_order_statistics_node_update>;
 #define rank order_of_key
 #define kth find_by_order
1.8
       Treap
 struct Treap {
   static Treap* null;
   Treap *left, *right;
   unsigned pri = rng(), sz = 0;
   int val = 0;
   void push() {
     // propagate like segtree, key-values aren't modified!!
   Treap* pull() {
     sz = left->sz + right->sz + (this != null);
     // merge(left, this), merge(this, right)
     return this;
   }
   Treap() { left = right = null; }
   Treap(int val) : val(val) {
     left = right = null;
     pull();
   template <class F>
   pair<Treap*, Treap*> split(const F& leg) { // {<= val, > val
     if (this == null) return {null, null};
     push();
     if (leq(this)) {
       auto p = right->split(leq);
       right = p.f;
       return {pull(), p.s};
     } else {
       auto p = left->split(leq);
       left = p.s;
       return {p.f, pull()};
   }
   Treap* merge(Treap* other) {
     if (this == null) return other;
     if (other == null) return this;
    push(), other->push();
     if (pri > other->pri) {
       return right = right->merge(other), pull();
     } else {
       return other->left = merge(other->left), other->pull();
   }
   pair<Treap*, Treap*> leftmost(int k) { // 1-indexed
     return split([&](Treap* n) {
       int sz = n->left->sz + 1;
       if (k >= sz) {
         k = sz;
         return true;
       return false;
     });
   }
```

```
auto split(int x) {
     return split([&](Treap* n) { return n->val <= x; });</pre>
  Treap* insert(int x) {
     auto&& [leq, ge] = split(x);
     // auto &&[le, eq] = split(x); // uncomment for set
    return leq->merge(new Treap(x))->merge(ge); // change leq
         for le for set
  }
  Treap* erase(int x) {
     auto&& [leq, ge] = split(x);
     auto&& [le, eq] = leq\rightarrowsplit(x - 1);
     auto&& [kill, keep] = eq->leftmost(1); // comment for set
     return le->merge(keep)->merge(ge); // le->merge(ge) for
  }
}* Treap::null = new Treap;
1.9 Persistent Treap
struct PerTreap {
  static PerTreap* null;
  PerTreap *left, *right;
  unsigned pri = rng(), sz = 0;
  int val;
  void push() {
     // propagate like segtree, key-values aren't modified!!
  PerTreap* pull() {
    sz = left->sz + right->sz + (this != null);
     // merge(left, this), merge(this, right)
     return this;
  PerTreap(int val = 0) : val(val) {
    left = right = null;
     pull();
  }
  PerTreap(PerTreap* t)
       : left(t->left), right(t->right), pri(t->pri), sz(t->sz)
            {
     val = t->val;
  }
   template <class F>
  pair<PerTreap*, PerTreap*> split(const F& leq) { // {<= val,</pre>
     if (this == null) return {null, null};
     push();
     PerTreap* t = new PerTreap(this);
     if (leq(this)) {
       auto p = t->right->split(leq);
       t->right = p.f;
      return {t->pull(), p.s};
     } else {
       auto p = t->left->split(leq);
       t->left = p.s;
      return {p.f, t->pull()};
    }
  }
  PerTreap* merge(PerTreap* other) {
     if (this == null) return new PerTreap(other);
     if (other == null) return new PerTreap(this);
```

```
push(), other->push();
     PerTreap* t;
     if (pri > other->pri) {
       t = new PerTreap(this);
       t->right = t->right->merge(other);
     } else {
       t = new PerTreap(other);
       t->left = merge(t->left);
     return t->pull();
   }
   auto leftmost(int k) { // 1-indexed
     return split([&](PerTreap* n) {
       int sz = n->left->sz + 1;
       if (k >= sz) {
         k = sz;
         return true:
       return false;
     });
   }
   auto split(int x) {
     return split([&](PerTreap* n) { return n->val <= x; });</pre>
 }* PerTreap::null = new PerTreap;
     Dynamic programming
       All submasks of a mask
   for (int B = A; B > 0; B = (B - 1) & A)
       Broken profile \mathcal{O}(n \cdot m \cdot 2^n) with n \leq m
Count all the ways you can arrange 1x2 and 2x1 tiles on an n \cdot m
board.
 11i dp[2][N + 1][1 << N];
 dp[0][0][0] = 1;
 fore (c, 0, m) {
   fore (r, 0, n + 1)
     fore (mask, 0, 1 << n) {</pre>
       if (r == n) { // transition to next column
         dp[~c & 1][0][mask] += dp[c & 1][r][mask];
         continue;
       }
       if (~(mask >> r) & 1) {
         dp[c \& 1][r + 1][mask | (1 << r)] += dp[c \& 1][r][mask]
         if (~(mask >> (r + 1)) & 1)
           dp[c \& 1][r + 2][mask] += dp[c \& 1][r][mask];
         dp[c \& 1][r + 1][mask \& ~(1 << r)] += dp[c \& 1][r][
     }
   memset(dp[c & 1], 0, sizeof(dp[c & 1])); // clear
 // Answer in dp[m & 1][0][0]
       Convex hull trick \mathcal{O}(n^2) \Rightarrow \mathcal{O}(n)
2.3
dp[i] = \min_{j < i} (dp[j] + b[j] * a[i])
dp[i][j] = \min_{k < j} (dp[i-1][k] + b[k] * a[j])
b[j] \ge b[j+1] optionally a[i] \le a[i+1]
```

// for doubles, use INF = 1/.0, div(a,b) = a / b

```
struct Line {
   mutable lli m, c, p;
   bool operator<(const Line& 1) const { return m < 1.m; }</pre>
   bool operator<(lli x) const { return p < x; }</pre>
   lli operator()(lli x) const { return m * x + c; }
 };
 template <bool MAX>
 struct DynamicHull : multiset<Line, less<>> {
   lli div(lli a, lli b) { return a / b - ((a ^ b) < 0 && a % b
   bool isect(iterator i, iterator j) {
     if (j == end()) return i->p = INF, 0;
     if (i->m == j->m)
       i-p = i-c > j-c ? INF : -INF;
       i - p = div(i - c - j - c, j - m - i - m);
     return i->p >= j->p;
   void add(lli m, lli c) {
     if (!MAX) m = -m, c = -c;
     auto k = insert(\{m, c, \emptyset\}), j = k++, i = j;
     while (isect(j, k)) k = erase(k);
     if (i != begin() && isect(--i, j)) isect(i, j = erase(j));
     while ((j = i) != begin() && (--i)->p >= j->p) isect(i, j)
          erase(j));
   1li query(lli x) {
     if (empty()) return OLL;
     auto f = *lower_bound(x);
     return MAX ? f(x) : -f(x);
   }
 };
       Divide and conquer \mathcal{O}(k \cdot n^2) \Rightarrow \mathcal{O}(k \cdot n \log n)
Split the array of size n into k continuous groups. k \leq n
cost(a, c) + cost(b, d) \le cost(a, d) + cost(b, c) with a \le b \le c \le d
 11i dp[2][N];
 void solve(int cut, int 1, int r, int optl, int optr) {
   if (r < 1) return;</pre>
   int mid = (1 + r) / 2;
   pair<lli, int> best = {INF, -1};
   fore (p, optl, min(mid, optr) + 1)
     best = min(best, \{dp[\sim ut \& 1][p - 1] + cost(p, mid), p\});
   dp[cut & 1][mid] = best.f;
   solve(cut, 1, mid - 1, optl, best.s);
   solve(cut, mid + 1, r, best.s, optr);
 fore (i, 1, n + 1) dp[1][i] = cost(1, i);
 fore (cut, 2, k + 1) solve(cut, cut, n, cut, n);
       Knuth \mathcal{O}(n^3) \Rightarrow \mathcal{O}(n^2)
2.5
dp[l][r] = \min_{l \le k \le r} \{dp[l][k] + dp[k][r]\} + cost(l, r)
  opt(l, r-1) \le opt(l, r) \le opt(l+1, r)
 11i dp[N][N];
 int opt[N][N];
```

```
fore (len, 1, n + 1)
   fore (1, 0, n) {
     int r = 1 + len - 1;
     if (r > n - 1) break;
     if (len <= 2) {</pre>
       dp[1][r] = 0;
       opt[1][r] = 1;
       continue;
     dp[1][r] = INF;
     fore (k, opt[1][r - 1], opt[1 + 1][r] + 1) {
       lli cur = dp[1][k] + dp[k][r] + cost(1, r);
       if (cur < dp[l][r]) {</pre>
         dp[1][r] = cur;
         opt[1][r] = k;
     }
   }
       Matrix exponentiation \mathcal{O}(n^3 \cdot logn)
If TLE change Mat to array<array<T, N>, N>
 template <class T>
 struct Mat : vector<vector<T>>> {
   int n, m;
   Mat(int n, int m) : vector<vector<T>>(n, vector<T>(m)), n(n)
        , m(m) {}
   Mat<T> operator*(const Mat<T>& other) {
     assert(m == other.n);
     Mat<T> ans(n, other.m);
     fore (k, 0, m)
       fore (i, 0, n)
         fore (j, 0, other.m) ans[i][j] += (*this)[i][k] *
              other[k][j];
     return ans;
   Mat<T> pow(lli k) {
     assert(n == m);
     Mat<T> ans(n, n);
     fore (i, 0, n) ans[i][i] = 1;
     for (; k > 0; k >>= 1) {
       if (k & 1) ans = ans * *this;
       *this = *this * *this;
     }
     return ans;
 };
       SOS dp
 // dp[mask] = Sum of all dp[x] where x is a submask of mask
 fore (i, 0, N) // N = amount of bits
   fore (mask, 0, 1 << N)
     if (mask >> i & 1) dp[mask] += dp[mask ^ (1 << i)];</pre>
 // dp[mask] = Sum of all dp[x] where mask is a submask of x
 fore (i, 0, N)
   for (int mask = (1 \ll N) - 1; mask >= 0; mask--)
     if (mask >> i & 1) dp[mask ^ (1 << i)] += dp[mask];</pre>
     Geometry
3
3.1
       Geometry
 const ld EPS = 1e-20;
```

const ld INF = 1e18;

```
const ld PI = acos(-1.0);
enum { ON = -1, OUT, IN, OVERLAP };
#define eq(a, b) (abs((a) - (b)) \leq +EPS)
#define neq(a, b) (!eq(a, b))
#define geq(a, b) ((a) - (b) >= -EPS)
#define leq(a, b) ((a) - (b) <= +EPS)
#define ge(a, b) ((a) - (b) > +EPS)
#define le(a, b) ((a) - (b) < -EPS)
int sgn(ld a) { return (a > EPS) - (a < -EPS); }</pre>
3.2 Radial order
struct Radial {
  Pt c:
  Radial(Pt c) : c(c) {}
  int cuad(Pt p) const {
    if (p.x > 0 \&\& p.y >= 0) return 0;
    if (p.x \le 0 \&\& p.y > 0) return 1;
    if (p.x < 0 \&\& p.y \le 0) return 2;
    if (p.x \ge 0 \& p.y < 0) return 3;
    return -1;
  }
  bool operator()(Pt a, Pt b) const {
    Pt p = a - c, q = b - c;
    if (cuad(p) = cuad(q)) return p.y * q.x < p.x * q.y;
    return cuad(p) < cuad(q);</pre>
  }
};
3.3
      Sort along line
void sortAlongLine(vector<Pt>& pts, Line 1) {
   sort(all(pts), [&](Pt a, Pt b) { return a.dot(l.v) < b.dot(l</pre>
       .v); });
}
     Point
4
     Point
4.1
struct Pt {
  ld x, y;
   explicit Pt(ld x = 0, ld y = 0) : x(x), y(y) {}
  Pt operator+(Pt p) const { return Pt(x + p.x, y + p.y); }
  Pt operator-(Pt p) const { return Pt(x - p.x, y - p.y); }
  Pt operator*(ld k) const { return Pt(x * k, y * k); }
  Pt operator/(ld k) const { return Pt(x / k, y / k); }
  ld dot(Pt p) const {
    // 0 if vectors are orthogonal
    // - if vectors are pointing in opposite directions
    // + if vectors are pointing in the same direction
    return x * p.x + y * p.y;
  ld cross(Pt p) const {
    // 0 if collinear
    // - if p is to the right of a
    // + if p is to the left of a
    // gives you 2 * area
    return x * p.y - y * p.x;
  ld norm() const { return x * x + y * y; }
  ld length() const { return sqrtl(norm()); }
  Pt unit() const { return (*this) / length(); }
  Pt perp() const { return Pt(-y, x); }
```

```
ld angle() const {
     1d ang = atan2(y, x);
     return ang + (ang < 0 ? 2 * acos(-1) : 0);
   Pt rotate(ld angle) const {
    // counter-clockwise rotation in radians
     // degree = radian * 180 / pi
     return Pt(x * cos(angle) - y * sin(angle), x * sin(angle)
         + y * cos(angle));
   }
   int dir(Pt a, Pt b) const {
     // where am I on the directed line ab
     return sgn((a - *this).cross(b - *this));
   bool operator<(Pt p) const { return eq(x, p.x) ? le(y, p.y)</pre>
        : le(x, p.x); }
   bool operator==(Pt p) const { return eq(x, p.x) && eq(y, p.y
       ); }
   bool operator!=(Pt p) const { return !(*this == p); }
   friend ostream& operator<<(ostream& os, const Pt& p) {</pre>
     return os << "(" << p.x << ", " << p.y << ")";
   friend istream& operator>>(istream& is, Pt& p) { return is
       >> p.x >> p.y; }
 };
4.2
       Angle between vectors
 ld angleBetween(Pt a, Pt b) {
   ld x = a.dot(b) / a.length() / b.length();
   return acosl(max(-1.0, min(1.0, x)));
 }
       Closest pair of points \mathcal{O}(n \cdot log n)
 pair<Pt, Pt> closestPairOfPoints(vector<Pt>& pts) {
   sort(all(pts), [&](Pt a, Pt b) { return le(a.y, b.y); });
   set<Pt> st;
   ld ans = INF;
   Pt p, q;
   int pos = 0;
   fore (i, 0, sz(pts)) {
     while (pos < i && geq(pts[i].y - pts[pos].y, ans)) st.</pre>
         erase(pts[pos++]);
     auto lo = st.lower_bound(Pt(pts[i].x - ans - EPS, -INF));
     auto hi = st.upper_bound(Pt(pts[i].x + ans + EPS, -INF));
     for (auto it = lo; it != hi; ++it) {
       ld d = (pts[i] - *it).length();
       if (le(d, ans)) ans = d, p = pts[i], q = *it;
     st.insert(pts[i]);
   return {p, q};
 }
      KD Tree
Returns nearest point, to avoid self-nearest add an id to the point
 struct Pt {
   // Geometry point mostly
   ld operator[](int i) const { return i == 0 ? x : y; }
 };
```

```
struct KDTree {
  Pt p;
  int k;
  KDTree *left, *right;
  template <class Iter>
  KDTree(Iter 1, Iter r, int k = \emptyset) : k(k), left(\emptyset), right(\emptyset)
    int n = r - 1;
    if (n == 1) {
      p = *1;
      return;
    nth\_element(1, 1 + n / 2, r, [\&](Pt a, Pt b) \{ return a[k] \}
          < b[k]; \});
    p = *(1 + n / 2);
    left = new KDTree(1, 1 + n / 2, k ^ 1);
    right = new KDTree(1 + n / 2, r, k^1);
  pair<ld, Pt> nearest(Pt x) {
    if (!left && !right) return {(p - x).norm(), p};
    vector<KDTree*> go = {left, right};
    auto delta = x[k] - p[k];
    if (delta > 0) swap(go[0], go[1]);
    auto best = go[0]->nearest(x);
    if (best.f > delta * delta) best = min(best, go[1]->
         nearest(x));
    return best;
  }
};
```

## 5 Lines and segments

#### 5.1 Line

```
struct Line {
 Pt a, b, v;
 Line() {}
 Line(Pt a, Pt b) : a(a), b(b), v((b - a).unit()) {}
 bool contains(Pt p) { return eq((p - a).cross(b - a), 0); }
 int intersects(Line 1) {
    if (eq(v.cross(1.v), 0)) return eq((1.a - a).cross(v), 0)
        ? 1e9 : 0;
    return 1;
 }
  int intersects(Seg s) {
    if (eq(v.cross(s.v), 0)) return eq((s.a - a).cross(v), 0)
        ? 1e9 : 0;
    return a.dir(b, s.a) != a.dir(b, s.b);
  template <class Line>
 Pt intersection(Line 1) { // can be a segment too
   return a + v * ((1.a - a).cross(1.v) / v.cross(1.v));
 }
 Pt projection(Pt p) { return a + v * proj(p - a, v); }
 Pt reflection(Pt p) { return a * 2 - p + v * 2 * proj(p - a,
       v); }
};
```

```
5.2 Segment
```

```
struct Seg {
  Pt a, b, v;
   Seg() {}
  Seg(Pt a, Pt b) : a(a), b(b), v(b - a) {}
  bool contains(Pt p) {
     return eq(v.cross(p - a), ∅)
       && leq((a - p).dot(b - p), ∅);
   }
   int intersects(Seg s) {
     int d1 = a.dir(b, s.a), d2 = a.dir(b, s.b);
     if (d1 != d2) return s.a.dir(s.b, a) != s.a.dir(s.b, b);
     return d1 == 0 && (contains(s.a) || contains(s.b) || s.
         contains(a) || s.contains(b)) ? 1e9 : 0;
   }
   template <class Seg>
  Pt intersection(Seg s) { // can be a line too
     return a + v * ((s.a - a).cross(s.v) / v.cross(s.v));
   }
 };
5.3
      Projection
 ld proj(Pt a, Pt b) { return a.dot(b) / b.length(); }
       Distance point line
 ld distance(Pt p, Line 1) {
  Pt q = 1.projection(p);
   return (p - q).length();
 }
       Distance point segment
 ld distance(Pt p, Seg s) {
   if (le((p - s.a).dot(s.b - s.a), 0))
     return (p - s.a).length();
   if (le((p - s.b).dot(s.a - s.b), 0))
     return (p - s.b).length();
   return abs((s.a - p).cross(s.b - p) / (s.b - s.a).length());
 }
      Distance segment segment
 ld distance(Seg a, Seg b) {
   if (a.intersects(b)) return 0.L;
   return min({distance(a.a, b), distance(a.b, b),
               distance(b.a, a), distance(b.b, a)});
 }
     Circle
6
6.1
     Circle
 struct Cir : Pt {
  ld r;
  Cir() {}
  Cir(ld x, ld y, ld r) : Pt(x, y), r(r) \{\}
  Cir(Pt p, ld r) : Pt(p), r(r) {}
   int inside(Cir c) {
     ld l = c.r - r - (*this - c).length();
     return ge(1, 0) ? IN : eq(1, 0) ? ON : OVERLAP;
  }
   int outside(Cir c) {
     ld 1 = (*this - c).length() - r - c.r;
     return ge(1, 0) ? OUT : eq(1, 0) ? ON : OVERLAP;
   }
   int contains(Pt p) {
```

```
ld l = (p - *this).length() - r;
    return le(1, 0) ? IN : eq(1, 0) ? ON : OUT;
  Pt projection(Pt p) {
    return *this + (p - *this).unit() * r;
  }
  vector<Pt> tangency(Pt p) { // point outside the circle
    Pt v = (p - *this).unit() * r;
    1d d^2 = (p - *this).norm(), d = sqrt(d^2);
    if (leq(d, 0)) return {}; // on circle, no tangent
    Pt v1 = v * (r / d);
    Pt v2 = v.perp() * (sqrt(d2 - r * r) / d);
    return \{*this + v1 - v2, *this + v1 + v2\};
  vector<Pt> intersection(Cir c) {
    ld d = (c - *this).length();
    if (eq(d, 0) || ge(d, r + c.r) || le(d, abs(r − c.r)))
      return {}; // circles don't intersect
    Pt v = (c - *this).unit();
    1d = (r * r + d * d - c.r * c.r) / (2 * d);
    Pt p = *this + v * a;
    if (eq(d, r + c.r) \mid\mid eq(d, abs(r - c.r)))
       return {p}; // circles touch at one point
    ld h = sqrt(r * r - a * a);
    Pt q = v.perp() * h;
    return {p - q, p + q}; // circles intersects twice
  template <class Line>
  vector<Pt> intersection(Line 1) {
    // for a segment you need to check that the point lies on
         the segment
    ld h2 = r * r - 1.v.cross(*this - 1.a) *
            1.v.cross(*this - 1.a) / 1.v.norm();
    Pt p = 1.a + 1.v * 1.v.dot(*this - 1.a) / 1.v.norm();
    if (eq(h2, 0)) return \{p\}; // line tangent to circle
    if (le(h2, ∅)) return {}; // no intersection
    Pt q = 1.v.unit() * sqrt(h2);
    return {p - q, p + q}; // two points of intersection (
  }
  Cir(Pt a, Pt b, Pt c) {
    // find circle that passes through points a, b, c
    Pt mab = (a + b) / 2, mcb = (b + c) / 2;
    Seg ab(mab, mab + (b - a).perp());
    Seg cb(mcb, mcb + (b - c).perp());
    Pt o = ab.intersection(cb);
    *this = Cir(o, (o - a).length());
  }
};
6.2
     Distance point circle
ld distance(Pt p, Cir c) {
    return max(0.L, (p - c).length() - c.r);
}
6.3
       Common area circle circle
ld commonArea(Cir a, Cir b) {
  if (le(a.r, b.r)) swap(a, b);
  ld d = (a - b).length();
  if (leq(d + b.r, a.r)) return b.r * b.r * PI;
  if (geq(d, a.r + b.r)) return 0.0;
  auto angle = [\&](1d x, 1d y, 1d z) {
    return acos((x * x + y * y - z * z) / (2 * x * y));
```

```
};
   auto cut = [\&](\mathbf{ld} \times, \mathbf{ld} \cdot r) {
    return (x - \sin(x)) * r * r / 2;
  ld a1 = angle(d, a.r, b.r), a2 = angle(d, b.r, a.r);
   return cut(a1 * 2, a.r) + cut(a2 * 2, b.r);
       Minimum enclosing circle \mathcal{O}(n) wow!!
Cir minEnclosing(vector<Pt>& pts) { // a bunch of points
   shuffle(all(pts), rng);
   Cir c(0, 0, 0);
   fore (i, 0, sz(pts))
     if (!c.contains(pts[i])) {
       c = Cir(pts[i], 0);
       fore (j, 0, i)
         if (!c.contains(pts[j])) {
           c = Cir((pts[i] + pts[j]) / 2, (pts[i] - pts[j]).
               length() / 2);
           fore (k, ∅, j)
             if (!c.contains(pts[k]))
               c = Cir(pts[i], pts[j], pts[k]);
     }
   return c;
     Polygon
       Area polygon
ld area(const vector<Pt>& pts) {
  1d sum = 0;
   fore (i, 0, sz(pts))
     sum += pts[i].cross(pts[(i + 1) % sz(pts)]);
   return abs(sum / 2);
      Perimeter
7.2
ld perimeter(const vector<Pt>& pts) {
   1d sum = 0;
   fore (i, 0, sz(pts))
     sum += (pts[(i + 1) % sz(pts)] - pts[i]).length();
   return sum;
       Cut polygon line
vector<Pt> cut(const vector<Pt>& pts, Line 1) {
   vector<Pt> ans;
   int n = sz(pts);
   fore (i, 0, n) {
     int j = (i + 1) \% n;
     if (geq(l.v.cross(pts[i] - l.a), 0)) // left
       ans.pb(pts[i]);
     Seg s(pts[i], pts[j]);
    if (l.intersects(s) == 1) {
       Pt p = 1.intersection(s);
       if (p != pts[i] && p != pts[j]) ans.pb(p);
    }
  }
  return ans;
}
       Common area circle polygon \mathcal{O}(n)
ld commonArea(Cir c, const vector<Pt>& poly) {
   auto arg = [&](Pt p, Pt q) {
     return atan2(p.cross(q), p.dot(q));
   auto tri = [&](Pt p, Pt q) {
    Pt d = q - p;
```

```
Universidad de Guadalajara CUCEI - Almost Retired
    1d a = d.dot(p) / d.norm(), b = (p.norm() - c.r * c.r) / d
         .norm();
    1d \det = a * a - b;
    if (leq(det, ∅)) return arg(p, q) * c.r * c.r;
    1d s = max(0.L, -a - sqrt(det)), t = min(1.L, -a + sqrt(
         det));
    if (t < 0 || 1 <= s) return arg(p, q) * c.r * c.r;
    Pt u = p + d * s, v = p + d * t;
    return u.cross(v) + (arg(p, u) + arg(v, q)) * c.r * c.r;
  };
  1d \text{ sum} = 0;
   fore (i, 0, sz(poly))
    sum += tri(poly[i] - c, poly[(i + \frac{1}{2}) % sz(poly)] - c);
   return abs(sum / 2);
7.5
      Point in polygon
int contains(const vector<Pt>& pts, Pt p) {
   int rays = 0, n = sz(pts);
   fore (i, 0, n) {
    Pt a = pts[i], b = pts[(i + 1) % n];
    if (ge(a.y, b.y)) swap(a, b);
    if (Seg(a, b).contains(p)) return ON;
    rays ^= leq(a.y, p.y) && le(p.y, b.y) &&
            p.dir(a, b) > 0;
  }
  return rays & 1 ? IN : OUT;
}
       Convex hull \mathcal{O}(nlogn)
vector<Pt> convexHull(vector<Pt> pts) {
  vector<Pt> hull;
   sort(all(pts), [&](Pt a, Pt b) {
    return a.x == b.x ? a.y < b.y : a.x < b.x;
  pts.erase(unique(all(pts)), pts.end());
   fore (i, 0, sz(pts)) {
    while (sz(hull) >= 2 && hull.back().dir(pts[i], hull[sz(
         hull) -2]) < 0)
       hull.pop_back();
    hull.pb(pts[i]);
  }
  hull.pop_back();
  int k = sz(hull);
  fore (i, sz(pts), 0) {
    while (sz(hull) >= k + 2 && hull.back().dir(pts[i], hull[
         sz(hull) - 2]) < 0)
       hull.pop_back();
    hull.pb(pts[i]);
  hull.pop_back();
   return hull;
}
      Is convex
bool isConvex(const vector<Pt>& pts) {
   int n = sz(pts);
  bool pos = 0, neg = 0;
   fore (i, 0, n) {
    Pt a = pts[(i + 1) % n] - pts[i];
    Pt b = pts[(i + 2) % n] - pts[(i + 1) % n];
    int dir = sgn(a.cross(b));
    if (dir > 0) pos = 1;
    if (dir < 0) neg = 1;
  }
  return !(pos && neg);
}
```

Point in convex polygon  $\mathcal{O}(logn)$ 

```
bool contains(const vector<Pt>& a, Pt p) {
   int lo = 1, hi = sz(a) - 1;
   if (a[0].dir(a[lo], a[hi]) > 0) swap(lo, hi);
   if (p.dir(a[0], a[lo]) >= 0 || p.dir(a[0], a[hi]) <= 0)</pre>
        return false;
   while (abs(lo - hi) > 1) {
     int mid = (lo + hi) >> 1;
     (p.dir(a[0], a[mid]) > 0 ? hi : lo) = mid;
   }
   return p.dir(a[lo], a[hi]) < 0;</pre>
 }
     Graphs
8
       Cutpoints and bridges
 int tin[N], fup[N], timer = 0;
 void weakness(int u, int p = -1) {
   tin[u] = fup[u] = ++timer;
   int children = 0;
   for (int v : graph[u])
     if (v != p) {
       if (!tin[v]) {
         ++children;
         weakness(v, u);
         fup[u] = min(fup[u], fup[v]);
         if (fup[v] >= tin[u] \&\& !(p == -1 \&\& children < 2)) //
               u is a cutpoint
           if (fup[v] > tin[u]) // bridge u -> v
       }
       fup[u] = min(fup[u], tin[v]);
 }
8.2
      Tarjan
 int tin[N], fup[N];
 bitset<N> still:
 stack<int> stk;
 int timer = 0;
 void tarjan(int u) {
   tin[u] = fup[u] = ++timer;
   still[u] = true;
   stk.push(u);
   for (auto& v : graph[u]) {
     if (!tin[v]) tarjan(v);
     if (still[v]) fup[u] = min(fup[u], fup[v]);
   if (fup[u] == tin[u]) {
     int v;
     do {
       v = stk.top();
       stk.pop();
       still[v] = false;
       // u and v are in the same scc
     } while (v != u);
   }
 }
8.3
       Two sat \mathcal{O}(2 \cdot n)
v: true, ~v: false
  implies(a, b): if a then b
          a => b
      b
 \mathbf{a}
              Т
      F
 F
              Τ
 Τ
      Τ
 F
      Τ
              Τ
 Τ
      F
              F
```

```
setVal(a): set a = true
setVal(~a): set a = false
 struct TwoSat {
   int n;
   vector<vector<int>> imp;
   \label{eq:twoSat} \textbf{TwoSat}(\textbf{int} \ k) \ : \ n(k + 1), \ \ \text{imp}(2 * n) \ \{\} \ // \ 1-\textbf{indexed}
   void either(int a, int b) { // a || b
     a = max(2 * a, -1 - 2 * a);
     b = max(2 * b, -1 - 2 * b);
     imp[a ^ 1].pb(b);
     imp[b ^ 1].pb(a);
   void implies(int a, int b) { either(~a, b); }
   void setVal(int a) { either(a, a); }
   optional<vector<int>> solve() {
     int k = sz(imp);
     vector<int> s, b, id(sz(imp));
     function<void(int)> dfs = [&](int u) {
       b.pb(id[u] = sz(s)), s.pb(u);
       for (int v : imp[u]) {
         if (!id[v]) dfs(v);
         else
           while (id[v] < b.back())</pre>
             b.pop_back();
       if (id[u] == b.back())
          for (b.pop_back(),++k; id[u] < sz(s); s.pop_back())</pre>
           id[s.back()] = k;
     };
     vector<int> val(n);
     fore (u, 0, sz(imp))
       if (!id[u]) dfs(u);
     fore (u, 0, n) {
       int x = 2 * u;
       if (id[x] == id[x ^ 1]) return nullopt;
       val[u] = id[x] < id[x ^ 1];
     return optional(val);
   }
 };
8.4 LCA
 const int LogN = 1 + __lg(N);
 int par[LogN][N], depth[N];
 void dfs(int u, int par[]) {
   for (auto& v : graph[u])
     if (v != par[u]) {
       par[v] = u;
       depth[v] = depth[u] + 1;
       dfs(v, par);
     }
 }
 int lca(int u, int v) {
   if (depth[u] > depth[v]) swap(u, v);
   fore (k, LogN, 0)
     if (depth[v] - depth[u] >= (1 << k))
       v = par[k][v];
   if (u == v) return u;
   fore (k, LogN, 0)
```

```
if (par[k][v] != par[k][u])
       u = par[k][u], v = par[k][v];
   return par[0][u];
 int dist(int u, int v) {
   return depth[u] + depth[v] - 2 * depth[lca(u, v)];
 }
 void init(int r) {
   dfs(r, par[0]);
   fore (k, 1, LogN)
     fore (u, 1, n + 1)
       par[k][u] = par[k - 1][par[k - 1][u]];
 }
8.5
      Virtual tree \mathcal{O}(n \cdot logn) "lca tree"
 vector<int> virt[N];
 int virtualTree(vector<int>& ver) {
   auto byDfs = [&](int u, int v) {
     return tin[u] < tin[v];</pre>
   };
   sort(all(ver), byDfs);
   fore (i, sz(ver), 1)
     ver.pb(lca(ver[i - 1], ver[i]));
   sort(all(ver), byDfs);
   ver.erase(unique(all(ver)), ver.end());
   for (int u : ver)
     virt[u].clear();
   fore (i, 1, sz(ver))
     virt[lca(ver[i - 1], ver[i])].pb(ver[i]);
   return ver[0];
 }
       Dynamic connectivity
 struct DynamicConnectivity {
   struct Query {
     int op, u, v, at;
   Dsu dsu; // with rollback
   vector<Query> queries;
   map<ii, int> mp;
   int timer = -1;
   DynamicConnectivity(int n = 0) : dsu(n) {}
   void add(int u, int v) {
     mp[minmax(u, v)] = ++timer;
     queries.pb({'+', u, v, INT_MAX});
   }
   void rem(int u, int v) {
     int in = mp[minmax(u, v)];
     queries.pb(\{'-', u, v, in\});
     queries[in].at = ++timer;
     mp.erase(minmax(u, v));
   }
   void query() {
     queries.push_back({'?', -1, -1, ++timer});
   void solve(int 1, int r) {
     if (1 == r) {
       if (queries[1].op == '?') // solve the query here
         return:
```

```
int m = (1 + r) >> 1;
     int before = sz(dsu.mem);
     for (int i = m + 1; i <= r; i++) {
       Query& q = queries[i];
       if (q.op == '-' && q.at < 1) dsu.unite(q.u, q.v);</pre>
     solve(1, m);
     while (sz(dsu.mem) > before) dsu.rollback();
     for (int i = 1; i <= m; i++) {
       Ouery& g = gueries[i];
       if (q.op == '+' \&\& q.at > r) dsu.unite(q.u, q.v);
     solve(m + 1, r);
     while (sz(dsu.mem) > before) dsu.rollback();
 };
       Euler-tour + HLD + LCA \mathcal{O}(n \cdot logn)
8.7
Solves subtrees and paths problems
 int par[N], nxt[N], depth[N], sz[N];
 int tin[N], tout[N], who[N], timer = 0;
 int dfs(int u) {
   sz[u] = 1;
   for (auto& v : graph[u])
     if (v != par[u]) {
       par[v] = u;
       depth[v] = depth[u] + 1;
       sz[u] += dfs(v);
       if (graph[u][0] == par[u] || sz[v] > sz[graph[u][0]])
         swap(v, graph[u][0]);
   return sz[u];
 void hld(int u) {
   tin[u] = ++timer, who[timer] = u;
   for (auto& v : graph[u])
     if (v != par[u]) {
       nxt[v] = (v == graph[u][0] ? nxt[u] : v);
       hld(v);
   tout[u] = timer;
 template <bool OverEdges = 0, class F>
 void processPath(int u, int v, F f) {
   for (; nxt[u] != nxt[v]; u = par[nxt[u]]) {
     if (depth[nxt[u]] < depth[nxt[v]]) swap(u, v);</pre>
     f(tin[nxt[u]], tin[u]);
   }
   if (depth[u] < depth[v]) swap(u, v);</pre>
   f(tin[v] + OverEdges, tin[u]);
 int lca(int u, int v) {
   int last = -1;
   processPath(u, v, [&](int 1, int r) {
     last = who[1];
   });
   return last;
 }
 void updatePath(int u, int v, lli z) {
   processPath(u, v, [&](int 1, int r) {
     tree->update(1, r, z);
```

```
});
 }
 void updateSubtree(int u, lli z) {
   tree->update(tin[u], tout[u], z);
 1li queryPath(int u, int v) {
   11i sum = 0;
   processPath(u, v, [&](int 1, int r) {
     sum += tree->query(1, r);
   }):
   return sum;
 }
 1li queryPathWithOrder(int u, int v, int x) {
   int _lca = lca(u, v); assert(_lca != -1);
   vector<pair<int, int>> firstHalf, secondHalf, ranges;
   processPath(u, _lca, [&] (int l, int r) {
     firstHalf.push_back(make_pair(r, 1));
   });
   processPath(_lca, v, [&] (int 1, int r) {
     1 += tin[_lca] == 1;
     if (1 <= r) {
       secondHalf.push_back(make_pair(1, r));
   });
   reverse(all(secondHalf));
   ranges = firstHalf;
   ranges.insert(end(ranges), begin(secondHalf), end(secondHalf
       ));
   int who = -1;
   for (auto [begin, end] : ranges) {
     // if begin <= end: left to right, aka. normal
     // if begin > end: right to left,
     // e.g. begin = 3, end = 1
     // order must go 3, 2, 1
     if ((who = tree -> solve(begin, end, x)) != -1) {
       // e.g. first node in the path(u, v) with value less
            than or equal to x
       break;
     }
   }
   return who;
 }
 1li querySubtree(int u) {
   return tree->query(tin[u], tout[u]);
 }
       Centroid \mathcal{O}(n \cdot log n)
8.8
Solves "all pairs of nodes" problems
 int cdp[N], sz[N];
 bitset<N> rem;
 int dfsz(int u, int p = -1) {
   sz[u] = 1;
   for (int v : graph[u])
     if (v != p && !rem[v]) sz[u] += dfsz(v, u);
   return sz[u];
 }
```

```
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 int centroid(int u, int size, int p = -1) {
   for (int v : graph[u])
     if (v != p && !rem[v] && 2 * sz[v] > size)
       return centroid(v, size, u);
   return u:
 }
 void solve(int u, int p = -1) {
   cdp[u = centroid(u, dfsz(u))] = p;
   rem[u] = true;
   for (int v : graph[u])
     if (!rem[v]) solve(v, u);
       Guni \mathcal{O}(n \cdot log n)
Solve subtrees problems
 int cnt[C], color[N];
 int sz[N];
 int guni(int u, int p = -1) {
   sz[u] = 1;
   for (auto& v : graph[u])
     if (v != p) {
       sz[u] += guni(v, u);
       if (sz[v] > sz[graph[u][0]] || p == graph[u][0])
         swap(v, graph[u][0]);
   return sz[u];
 void update(int u, int p, int add, bool skip) {
   cnt[color[u]] += add;
   fore (i, skip, sz(graph[u]))
     if (graph[u][i] != p) update(graph[u][i], u, add, 0);
 void solve(int u, int p = -1, bool keep = 0) {
   fore (i, sz(graph[u]), 0)
     if (graph[u][i] != p)
       solve(graph[u][i], u, !i);
   update(u, p, +1, 1); // add
   // now cnt[i] has how many times the color i appears in the
       subtree of u
   if (!keep) update(u, p, -1, 0); // remove
 }
```

## Link-Cut tree $\mathcal{O}(n \cdot log n)$

Solves dynamic trees problems, can handle subtrees and paths maybe with a high constant

```
struct LinkCut {
  struct Node {
   Node *left{0}, *right{0}, *par{0};
    bool rev = 0;
    int sz = 1;
    int sub = 0, vsub = 0; // subtree
    lli path = 0; // path
    1li self = 0; // node info
    void push() {
      if (rev) {
        swap(left, right);
        if (left) left->rev ^= 1;
```

```
if (right) right->rev ^= 1;
      rev = 0;
    }
  void pull() {
    sz = 1:
    sub = vsub + self;
    path = self;
    if (left) {
      sz += left->sz;
      sub += left->sub:
      path += left->path;
    if (right) {
      sz += right->sz;
      sub += right->sub;
      path += right->path;
    }
  }
  void addVsub(Node* v, 11i add) {
    if (v) vsub += 1LL * add * v->sub;
  }
};
vector<Node> a;
LinkCut(int n = 1) : a(n) {}
void splay(Node* u) {
  auto assign = [&](Node* u, Node* v, int d) {
    if (v) v->par = u;
    if (d \ge 0) (d = 0 ? u \ge 1 eft : u \ge right) = v;
  auto dir = [&](Node* u) {
    if (!u->par) return -1;
    return u->par->left == u ? 0 :
           (u-par-right == u ? 1 : -1);
  auto rotate = [&](Node* u) {
    Node *p = u->par, *g = p->par;
    int d = dir(u);
    assign(p, d ? u->left : u->right, d);
    assign(g, u, dir(p));
    assign(u, p, !d);
    p->pull(), u->pull();
  };
  while (~dir(u)) {
    Node *p = u->par, *g = p->par;
    if (~dir(p)) g->push();
    p->push(), u->push();
    if (~dir(p)) rotate(dir(p) == dir(u) ? p : u);
    rotate(u);
  u->push(), u->pull();
void access(int u) {
  Node* last = NULL;
  for (Node* x = &a[u]; x; last = x, x = x->par) {
    splay(x);
    x->addVsub(x->right, +1);
    x->right = last;
    x->addVsub(x->right, -1);
    x->pull();
  }
```

```
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```

```
splay(&a[u]);
 void reroot(int u) {
    access(u);
    a[u].rev ^= 1;
 void link(int u, int v) {
    reroot(v), access(u);
    a[u].addVsub(v, +1);
    a[v].par = &a[u];
    a[u].pull();
 void cut(int u, int v) {
    reroot(v), access(u);
    a[u].left = a[v].par = NULL;
    a[u].pull();
 }
 int lca(int u, int v) {
    if (u == v) return u;
    access(u), access(v);
   if (!a[u].par) return -1;
    return splay(&a[u]), a[u].par ? -1 : u;
 int depth(int u) {
    access(u);
    return a[u].left ? a[u].left->sz : 0;
  // get k-th parent on path to root
 int ancestor(int u, int k) {
   k = depth(u) - k;
    assert(k \ge 0);
    for (;; a[u].push()) {
      int sz = a[u].left->sz;
      if (sz == k) return access(u), u;
      if (sz < k)
        k = sz + 1, u = u - ch[1];
      else
        u = u - ch[0];
    }
    assert(0);
 1li queryPath(int u, int v) {
    reroot(u), access(v);
    return a[v].path;
 }
 1li querySubtree(int u, int x) {
    // query subtree of u, x is outside
    reroot(x), access(u);
    return a[u].vsub + a[u].self;
 void update(int u, lli val) {
    access(u);
    a[u].self = val;
    a[u].pull();
 }
 Node& operator[](int u) { return a[u]; }
};
```

### 9 Flows

```
9.1 Hopcroft Karp \mathcal{O}(e\sqrt{v})
 struct HopcroftKarp {
   int n, m;
   vector<vector<int>> graph;
   vector<int> dist, match;
   HopcroftKarp(int k) : n(k + 1), graph(n), dist(n),
                          match(n, 0) {} // 1-indexed!!
   void add(int u, int v) {
     graph[u].pb(v), graph[v].pb(u);
   bool bfs() {
     queue<int> qu;
     fill(all(dist), -1);
     fore (u, 1, n)
       if (!match[u]) dist[u] = 0, qu.push(u);
     while (!qu.empty()) {
       int u = qu.front();
       qu.pop();
       for (int v : graph[u])
         if (dist[match[v]] == -1) {
           dist[match[v]] = dist[u] + 1;
           if (match[v]) qu.push(match[v]);
     return dist[0] != -1;
   bool dfs(int u) {
     for (int v : graph[u])
       if (!match[v] || (dist[u] + 1 == dist[match[v]] && dfs(
            match[v]))) {
         match[u] = v, match[v] = u;
         return 1;
       }
     dist[u] = 1 << 30;
     return 0;
   int maxMatching() {
     int tot = 0;
     while (bfs())
       fore (u, 1, n) tot += match[u] ? 0 : dfs(u);
     return tot;
   }
 };
       Hungarian \mathcal{O}(n^2 \cdot m)
9.2
n jobs, m people for max assignment
 template <class C>
 pair<C, vector<int>> Hungarian(vector<vector<C>>& a) { // max
   int n = sz(a), m = sz(a[0]), p, q, j, k; // n \le m
   vector<C> fx(n, numeric_limits<C>::min()), fy(m, 0);
   vector\langle int \rangle x(n, -1), y(m, -1);
   fore (i, 0, n)
     fore (j, 0, m) fx[i] = max(fx[i], a[i][j]);
   fore (i, 0, n) {
     vector\langle int \rangle t(m, -1), s(n + 1, i);
     for (p = q = 0; p \le q \&\& x[i] \le 0; p++)
       for (k = s[p], j = 0; j < m && x[i] < 0; j++)
         if (abs(fx[k] + fy[j] - a[k][j]) < EPS && t[j] < 0) {
           s[++q] = y[j], t[j] = k;
```

```
if (s[q] < 0)
            for (p = j; p \ge 0; j = p)
              y[j] = k = t[j], p = x[k], x[k] = j;
        }
    if (x[i] < 0) {</pre>
     C d = numeric_limits<C>::max();
      fore (k, 0, q + 1)
        fore (j, 0, m)
          if (t[j] < 0)
            d = min(d, fx[s[k]] + fy[j] - a[s[k]][j]);
      fore (j, 0, m) fy[j] += (t[j] < 0 ? 0 : d);
      fore (k, 0, q + 1) fx[s[k]] -= d;
      i--;
 }
 C cost = 0;
 fore (i, 0, n) cost += a[i][x[i]];
 return make_pair(cost, x);
}
```

## 9.3 Blossom $\mathcal{O}(n^3)$

Maximum matching on non-bipartite non-weighted graphs

```
struct Blossom {
 int n, m;
 vector<int> mate, p, d, bl;
 vector<vector<int>>> b, g;
 Blossom(int n): n(n), m(n + n / 2), mate(n, -1), b(m), p(m)
       , d(m), bl(m), g(m, vector < int > (m, -1)) {}
 void add(int u, int v) { // 0-indexed!!!!!
   g[u][v] = u;
    g[v][u] = v;
 }
 void match(int u, int v) {
    g[u][v] = g[v][u] = -1;
   mate[u] = v;
   mate[v] = u;
 vector<int> trace(int x) {
    vector<int> vx;
    while (true) {
      while (bl[x] != x)
        x = bl[x];
      if (!vx.empty() && vx.back() == x)
       break;
      vx.pb(x);
      x = p[x];
   }
    return vx;
  void contract(int c, int x, int y, vector<int>& vx, vector<</pre>
      int>& vy) {
   b[c].clear();
    int r = vx.back();
    while (!vx.empty() && !vy.empty() && vx.back() == vy.back
         ()) {
      r = vx.back();
      vx.pop_back();
      vy.pop_back();
    b[c].pb(r);
    b[c].insert(b[c].end(), vx.rbegin(), vx.rend());
```

```
b[c].insert(b[c].end(), vy.begin(), vy.end());
  fore (i, 0, c + 1)
    g[c][i] = g[i][c] = -1;
  for (int z : b[c]) {
    bl[z] = c;
    fore (i, 0, c) {
      if (g[z][i] != -1) {
        g[c][i] = z;
        g[i][c] = g[i][z];
    }
  }
}
vector<int> lift(vector<int>& vx) {
  vector<int> A;
  while (sz(vx) \ge 2) {
    int z = vx.back();
    vx.pop_back();
    if (z < n) {
      A.pb(z);
      continue;
    int w = vx.back();
    int i = (sz(A) % 2 == 0 ? find(all(b[z]), g[z][w]) - b[z
        ].begin() : 0);
    int j = (sz(A) \% 2 == 1 ? find(all(b[z]), g[z][A.back()
         ]) - b[z].begin() : 0);
    int k = sz(b[z]);
    int dif = (sz(A) % 2 == 0 ? i % 2 == 1 : j % 2 == 0) ? 1
          : k - 1;
    while (i != j) {
      vx.pb(b[z][i]);
      i = (i + dif) \% k;
    vx.pb(b[z][i]);
  }
  return A;
}
int solve() {
  for (int ans = 0;; ans++) {
    fill(d.begin(), d.end(), 0);
    queue<int> Q;
    fore (i, 0, m)
      bl[i] = i;
    fore (i, 0, n) {
      if (mate[i] == -1) {
        Q.push(i);
        p[i] = i;
        d[i] = 1;
      }
    }
    int c = n;
    bool aug = false;
    while (!Q.empty() && !aug) {
      int x = Q.front();
      Q.pop();
      if (bl[x] != x)
        continue;
      fore (y, 0, c) {
        if (bl[y] == y \&\& g[x][y] != -1) {
          if (d[y] == 0) {
            p[y] = x;
            d[y] = 2;
            p[mate[y]] = y;
            d[mate[y]] = 1;
```

```
Q.push(mate[y]);
            } else if (d[y] == 1) {
              vector<int> vx = trace(x);
              vector<int> vy = trace(y);
              if (vx.back() == vy.back()) {
                contract(c, x, y, vx, vy);
                Q.push(c);
                p[c] = p[b[c][0]];
                d[c] = 1;
                C++;
              } else {
                aug = true;
                vx.insert(vx.begin(), y);
                vy.insert(vy.begin(), x);
                vector<int> A = lift(vx);
                vector<int> B = lift(vy);
                A.insert(A.end(), B.rbegin(), B.rend());
                for (int i = 0; i < sz(A); i += 2) {
                  match(A[i], A[i + 1]);
                  if (i + 2 < sz(A))
                    add(A[i + 1], A[i + 2]);
                }
              }
              break:
            }
          }
        }
      }
      if (!aug)
        return ans;
    }
 }
};
      Dinic \mathcal{O}(\min(e \cdot flow, v^2 \cdot e))
template <class F>
struct Dinic {
 struct Edge {
    int v, inv;
    F cap, flow;
    Edge(int v, F cap, int inv) : v(v), cap(cap), flow(0), inv
 };
 F EPS = (F)1e-9;
 int s, t, n;
 vector<vector<Edge>> graph;
 vector<int> dist, ptr;
 Dinic(int n) : n(n), graph(n), dist(n), ptr(n), s(n - 2), t(
      n - 1) {}
 void add(int u, int v, F cap) {
    graph[u].pb(Edge(v, cap, sz(graph[v])));
    graph[v].pb(Edge(u, 0, sz(graph[u]) - 1));
 bool bfs() {
    fill(all(dist), -1);
    queue<int> qu({s});
    dist[s] = 0;
    while (sz(qu) && dist[t] == -1) {
      int u = qu.front();
      qu.pop();
      for (Edge& e : graph[u])
        if (dist[e.v] == -1)
          if (e.cap - e.flow > EPS) {
```

```
dist[e.v] = dist[u] + 1;
            qu.push(e.v);
    return dist[t] != -1;
 F dfs(int u, F flow = numeric_limits<F>::max()) {
    if (flow <= EPS || u == t) return max<F>(0, flow);
    for (int& i = ptr[u]; i < sz(graph[u]); i++) {</pre>
      Edge& e = graph[u][i];
      if (e.cap - e.flow > EPS \&\& dist[u] + 1 == dist[e.v]) {
        F pushed = dfs(e.v, min<F>(flow, e.cap - e.flow));
        if (pushed > EPS) {
          e.flow += pushed;
          graph[e.v][e.inv].flow -= pushed;
          return pushed;
      }
    }
    return 0;
  }
  F maxFlow() {
    F flow = 0;
    while (bfs()) {
      fill(all(ptr), 0);
      while (F pushed = dfs(s)) flow += pushed;
    return flow;
 bool leftSide(int u) {
    // left side comes from sink
    return dist[u] != -1;
 }
};
      Min-Cost flow \mathcal{O}(\min(e \cdot flow, v^2 \cdot e))
template <class C, class F>
struct Mcmf {
  struct Edge {
    int u, v, inv;
    F cap, flow;
    C cost;
    Edge(int u, int v, C cost, F cap, int inv) : u(u),
      v(v), cost(cost), cap(cap), flow(∅), inv(inv) {}
  };
  F EPS = (F)1e-9;
  int s, t, n;
  vector<vector<Edge>> graph;
  vector<Edge*> prev;
  vector<C> cost;
  vector<int> state;
 Mcmf(int n) : n(n), graph(n), cost(n),
    state(n), prev(n), s(n - 2), t(n - 1) {}
 void add(int u, int v, C cost, F cap) {
    graph[u].pb(Edge(u, v, cost, cap, sz(graph[v])));
    graph[v].pb(Edge(v, u, -cost, 0, sz(graph[u]) - 1));
  }
 bool bfs() {
    fill(all(state), 0);
    fill(all(cost), numeric_limits<C>::max());
    deque<int> qu;
```

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```
qu.push_back(s);
    state[s] = 1, cost[s] = 0;
    while (sz(qu)) {
      int u = qu.front();
      qu.pop_front();
      state[u] = 2;
      for (Edge& e : graph[u])
        if (e.cap - e.flow > EPS)
          if (cost[u] + e.cost < cost[e.v]) {
            cost[e.v] = cost[u] + e.cost;
            prev[e.v] = &e;
            if (state[e.v] == 2 || (sz(qu) &&
              cost[qu.front()] > cost[e.v])) {
              qu.push_front(e.v);
            } else
                if (state[e.v] == 0)
                  qu.push_back(e.v);
            state[e.v] = 1;
    }
    return cost[t] != numeric_limits<C>::max();
 pair<C, F> minCostFlow() {
   C cost = 0;
   F flow = 0;
    while (bfs()) {
      F pushed = numeric_limits<F>::max();
      for (Edge* e = prev[t]; e != nullptr; e = prev[e->u])
        pushed = min(pushed, e->cap - e->flow);
      for (Edge* e = prev[t]; e != nullptr; e = prev[e->u])
        e->flow += pushed;
        graph[e->v][e->inv].flow -= pushed;
        cost += e->cost * pushed;
      flow += pushed;
    return make_pair(cost, flow);
};
```

# 10 Game theory

## 10.1 Grundy numbers

If the moves are consecutive  $S = \{1, 2, 3, ..., x\}$  the game can be solved like  $stackSize \pmod{x+1} \neq 0$ 

```
int mem[N];
int mex(set<int>& st) {
  int x = 0;
  while (st.count(x)) x++;
  return x;
int grundy(int n) {
  if (n < 0) return INF;</pre>
  if (n == 0) return 0;
  int& g = mem[n];
  if (g == -1) {
    set<int> st;
    for (int x : {a, b}) st.insert(grundy(n - x));
    g = mex(st);
  }
  return g;
}
```

#### 11 Math

#### 11.1 Bits

$\mathrm{Bits}{++}$						
Operations on int	Function					
x & -x	Least significant bit in $x$					
lg(x)	Most significant bit in $x$					
c = x&-x, r = x+c;	Next number after $x$ with same					
(((r^x) » 2)/c)   r	number of bits set					
builtin_	Function					
popcount(x)	Amount of 1's in $x$					
clz(x)	0's to the <b>left</b> of biggest bit					
$\operatorname{ctz}(\mathbf{x})$	0's to the <b>right</b> of smallest bit					

#### 11.2 Bitset

$\mathrm{Bitset}{<}\mathrm{Size}{>}$						
Operation	Function					
_Find_first()	Least significant bit					
$_{\rm Find}_{\rm next(idx)}$	First set bit after index $idx$					
any(), none(), all()	Just what the expression says					
set(), reset(), flip()	Just what the expression says x2					
to_string('.', 'A')	Print 011010 like .AA.A.					

### 11.3 Probability

#### Conditional

The event A happens and the event B has already happened

$$P(A|B) = \frac{P(A \cap B)}{P(B)}$$

If independent events

$$P(A|B) = P(A), P(B|A) = P(B)$$

#### Bayes theorem

$$P(A|B) = \frac{P(B|A) \cdot P(A)}{P(B)}$$

#### **Binomial**

$$B = \binom{n}{x} \cdot p^x \cdot (1-p)^{n-x}$$

n = number of trials

x = number of success from n trials

p = probability of success on a single trial

#### Geometric

Probability of success at the nth-event after failing the others

$$G = (1 - p)^{n-1} \cdot p$$

n = number of trials

p = probability of success on a single trial

#### Poisson

$$Po = \frac{\lambda^k \cdot e^{-\lambda}}{k!}$$

 $\lambda =$  number of times an event is expected (occurs / time) k = number of occurring events in the limited period of time

Example: The event happens 4 times per minute and we want k events to happen in 10 minutes, then  $\lambda = 4 \cdot 10 = 40$ 

Universidad de Guadalajara CUCEI - Almost Retired Expected value

```
E_x = \sum_{\forall x} x \cdot p(x)
```

return 0;

```
11.4 Gauss jordan \mathcal{O}(n^2 \cdot m)
template <class T>
pair<int, vector<T>> gauss(vector<vector<T>> a, vector<T> b)
{
  const double EPS = 1e-6;
  int n = a.size(), m = a[0].size();
   for (int i = 0; i < n; i++) a[i].push_back(b[i]);</pre>
  vector<int> where(m, -1);
   for (int col = 0, row = 0; col < m and row < n; col++) {</pre>
     int sel = row;
     for (int i = row; i < n; ++i)</pre>
       if (abs(a[i][col]) > abs(a[sel][col])) sel = i;
     if (abs(a[sel][col]) < EPS) continue;</pre>
     for (int i = col; i <= m; i++)</pre>
       swap(a[sel][i], a[row][i]);
     where[col] = row;
     for (int i = 0; i < n; i++)</pre>
       if (i != row) {
         T c = a[i][col] / a[row][col];
         for (int j = col; j <= m; j++)</pre>
           a[i][j] -= a[row][j] * c;
       }
     row++;
  }
   vector<T> ans(m, ∅);
   for (int i = 0; i < m; i++)
     if (where[i] != -1)
       ans[i] = a[where[i]][m] / a[where[i]][i];
   for (int i = 0; i < n; i++) {
    T sum = 0;
     for (int j = 0; j < m; j++) sum += ans[j] * a[i][j];</pre>
     if (abs(sum - a[i][m]) > EPS)
       return pair(0, vector<T>());
   for (int i = 0; i < m; i++)
     if (where[i] == -1) return pair(INF, ans);
   return pair(1, ans);
}
11.5
       Xor basis
template <int D>
struct XorBasis {
  using Num = bitset<D>;
  array<Num, D> basis, keep;
  vector<int> from;
  int n = 0, id = -1;
  XorBasis() : from(D, -1) { basis.fill(∅); }
  bool insert(Num x) {
     ++id;
    Num k;
     fore (i, D, 0)
       if (x[i]) {
         if (!basis[i].any()) {
           k[i] = 1, from[i] = id, keep[i] = k;
           basis[i] = x, n++;
           return 1;
         }
         x ^= basis[i], k ^= keep[i];
       }
```

```
}
   optional<Num> find(Num x) {
     // is x in xor-basis set?
     // v ^ (v ^ x) = x
     Num v;
     fore (i, D, 0)
       if (x[i]) {
         if (!basis[i].any()) return nullopt;
         x ^= basis[i];
         v[i] = 1;
       }
     return optional(v);
   }
   optional<vector<int>>> recover(Num x) {
     auto v = find(x);
     if (!v) return nullopt;
     Num t;
     fore (i, D, 0)
       if (v.value()[i]) t ^= keep[i];
     vector<int> ans;
     for (int i = t._Find_first(); i < D; i = t._Find_next(i))</pre>
       ans.pb(from[i]);
     return ans;
   }
   optional<Num> operator[](lli k) {
     lli tot = (1LL \ll n);
     if (k > tot) return nullopt;
     Num v = 0;
     fore (i, D, 0)
       if (basis[i]) {
         11i low = tot / 2;
         if ((low < k && v[i] == 0) || (low >= k && v[i]))
           v ^= basis[i];
         if (low < k) k = low;
         tot /= 2;
       }
     return optional(v);
 };
12
       Combinatorics
12.1
        Choose
```

```
\binom{n}{k} = \binom{n-1}{k-1} + \binom{n-1}{k}
     \binom{n}{k_1, k_2, \dots, k_m} = \frac{n!}{k_1! * k_2! * \dots * k_m!}
1li choose(int n, int k) {
  if (n < 0 \mid \mid k < 0 \mid \mid n < k) return 0LL;
  return fac[n] * ifac[k] % MOD * ifac[n - k] % MOD;
}
lli choose(int n, int k) {
  lli r = 1;
  int to = min(k, n - k);
  if (to < 0) return 0;</pre>
  fore (i, 0, to) r = r * (n - i) / (i + 1);
  return r;
}
```

#### 12.2**Factorial**

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```
fac[0] = 1LL;
fore (i, 1, N) fac[i] = lli(i) * fac[i - 1] % MOD;
ifac[N - 1] = fpow(fac[N - 1], MOD - 2, MOD);
for (int i = N - 2; i >= 0; i--)
    ifac[i] = lli(i + 1) * ifac[i + 1] % MOD;
```

### 12.3 Factorial mod small prime

```
lli facMod(lli n, int p) {
    lli r = 1LL;
    for (; n > 1; n /= p) {
        r = (r * ((n / p) % 2 ? p - 1 : 1)) % p;
        fore (i, 2, n % p + 1) r = r * i % p;
    }
    return r % p;
}
```

## 12.4 Pascal

```
fore (i, 0, N) {
  choose[i][0] = choose[i][i] = 1;
  for (int j = 1; j <= i; j++)
     choose[i][j] = choose[i - 1][j - 1] + choose[i - 1][j];
}</pre>
```

#### 12.5 Stars and bars

Enclosing n objects in k boxes

$$\binom{n+k-1}{k-1} = \binom{n+k-1}{n}$$

#### **12.6** Lucas

Changes  $\binom{n}{k} \mod p$ , with  $n \ge 2e6, k \ge 2e6$  and  $p \le 1e7$ 

$$\binom{n}{k} \equiv \prod_{i=0}^{n} \binom{n_i}{k_i} \bmod p$$

#### 12.7 Burnside lemma

Burnside's lemma is a result in group theory that can help when counting objects with symmetry taken into account. It gives a formula to count objects, where two objects that are related by a symmetry (rotation or reflection, for example) are not to be counted as distinct.

let G be a finite group. For each g in G let f(g) denote the set of elements that are fixed by g.

$$|classes| = \frac{1}{|G|} \cdot \sum_{g \in G} f(g)$$

## 12.8 Catalan

Number of ways to insert n pairs of parentheses in a word of n+1 letters.

Consider all the  $\binom{2n}{n}$  paths on squared paper that start at (0, 0), end at (n, n) and at each step, either make a (+1,+1) step or a (+1,-1) step. Then the number of such paths that never go below the x-axis.

Number of ordered rooted trees with n nodes, not including the root.

$$C_n = \frac{(2n)!}{(n+1)! \cdot n!}$$

$$C_n = \binom{2n}{n} - \binom{2n}{n+1}$$

	i	0/1	2	3	$\mid 4 \mid$	5	6	7	8	9	10	:
	$C_i$	1	2	5	14	42	132	429	1430	4862	16796	
catalan[0] = 1LL;												
fore (i, 0, N) {												
catalan[i + 1] = catalan[i] * <b>lli</b> (4 * i + 2) % MOD												

\* fpow(i +  $\frac{2}{2}$ , MOD -  $\frac{2}{2}$ ) % MOD;

#### 12.9 Bell numbers

}

The number of ways a set of n elements can be partitioned into **nonempty** subsets

$$B_{n+1} = \sum_{k=0}^{n} {n \choose k} \cdot B_k$$

$$\begin{array}{|c|c|c|c|c|c|c|c|c|} \hline i & 5 & 6 & 7 & 8 & 9 & 10 & 11 \\ \hline B_i & 52 & 203 & 877 & 4140 & 21147 & 115975 & 678570 \\ \hline \end{array}$$

### 12.10 Stirling numbers

Count the number of permutations of n elements with k disjoint cycles Signed way, k>0

$$s(0,0) = 1, \ s(n,0) = s(0,n) = 0 \\ s(n,k) = -(n-1) \cdot s(n-1,k) + s(n-1,k-1)$$

The unsigned way doesn't have sign |-(n-1)|

The sum of products of the  $\binom{n}{k}$  subsets of size k of  $\{0,1,...n-1\}$  is s(n,n-k)

## 12.11 Stirling numbers 2

How many ways are of dividing a set of n different objects into k nonempty subsets.  $\binom{n}{k}$ 

```
\begin{split} s2(0,0) &= 1, \ s2(n,0) = s2(0,n) = 0 \\ s2(n,k) &= s2(n-1,k-1) + k \cdot s2(n-1,k) \\ s2(n,k) &= \frac{1}{k!} \sum_{i=0}^k (-1)^i \cdot \binom{k}{i} \cdot (k-i)^n \\ \text{Mint stirling2(int n, int k) } \{ \\ \text{Mint sum = 0;} \\ \text{fore (i, 0, k + 1)} \\ \text{sum += fpow<Mint>(-1, i) * choose(k, i)} \\ &\quad * \text{fpow<Mint>(k - i, n);} \\ \text{return sum * ifac(k);} \}; \end{split}
```

# 13 Number theory

# 13.1 Amount of divisors $\mathcal{O}(n^{1/3})$

```
ull amountOfDivisors(ull n) {
  ull cnt = 1;
  for (auto p : primes) {
    if (1LL * p * p * p > n) break;
    if (n % p == 0) {
      ull k = 0;
      while (n > 1 && n % p == 0) n /= p, ++k;
      cnt *= (k + 1);
    }
  ull sq = mysqrt(n); // the last x * x <= n
  if (miller(n))
    cnt *= 2;
  else if (sq * sq == n && miller(sq))</pre>
```

```
cnt *= 3;
   else if (n > 1)
     cnt *= 4;
   return cnt;
        Chinese remainder theorem
13.2
  • x \equiv 3 \pmod{4}
  • x \equiv 5 \pmod{6}
  • x \equiv 2 \pmod{5}
 x \equiv 47 \pmod{60}
pair<lli, lli> crt(pair<lli, lli> a, pair<lli, lli> b) {
  if (a.s < b.s) swap(a, b);
  auto p = euclid(a.s, b.s);
  lli g = a.s * p.f + b.s * p.s, l = a.s / g * b.s;
  if ((b.f - a.f) % g != 0) return {-1, -1}; // no solution
  p.f = a.f + (b.f - a.f) % b.s * p.f % b.s / g * a.s;
  return {p.f + (p.f < 0) * 1, 1};
13.3
       Euclid \mathcal{O}(log(a \cdot b))
pair<lli, lli> euclid(lli a, lli b) {
  if (b == 0) return {1, 0};
  auto p = euclid(b, a % b);
  return {p.s, p.f - a / b * p.s};
13.4 Inverse
lli inv(lli a, lli m) {
  a %= m;
  assert(a);
  return a == 1 ? 1 : m - 1LL * inv(m, a) * m / a;
       Phi \mathcal{O}(\sqrt{n})
13.5
lli phi(lli n) {
  if (n == 1) return 0;
  lli r = n;
  for (lli i = 2; i * i <= n; i++)
     if (n % i == 0) {
       while (n % i == 0) n /= i;
       r = r / i;
  if (n > 1) r -= r / n;
  return r;
13.6 Miller rabin \mathcal{O}(Witnesses \cdot (logn)^3)
ull mul(ull x, ull y, ull MOD) {
  lli ans = x * y - MOD * ull(1.L / MOD * x * y);
  return ans + MOD * (ans < 0) - MOD * (ans >= lli(MOD));
}
// use mul(x, y, mod) inside fpow
bool miller(ull n) {
  if (n < 2 || n % 6 % 4 != 1) return (n | 1) == 3;
  ull k = \__builtin\_ctzll(n - 1), d = n >> k;
   for (ull p : {2, 325, 9375, 28178, 450775, 9780504, 17952650
       22}) {
    ull x = fpow(p % n, d, n), i = k;
     while (x != 1 && x != n - 1 && p % n && i--)
       x = mul(x, x, n);
     if (x != n - 1 && i != k) return 0;
  }
  return 1;
}
        Pollard Rho \mathcal{O}(n^{1/4})
```

```
ull rho(ull n) {
  auto f = [n](ull x) { return mul(x, x, n) + 1; };
 ull x = 0, y = 0, t = 30, prd = 2, i = 1, q;
 while (t++ % 40 || __gcd(prd, n) == 1) {
    if (x == y) x = ++i, y = f(x);
    if (q = mul(prd, max(x, y) - min(x, y), n)) prd = q;
    x = f(x), y = f(f(y));
  return __gcd(prd, n);
// if used multiple times, try memorization!!
// try factoring small numbers with sieve
void pollard(ull n, map<ull, int>& fac) {
  if (n == 1) return;
  if (miller(n)) {
    fac[n]++;
  } else {
    ull x = rho(n);
    pollard(x, fac);
    pollard(n / x, fac);
  }
}
```

## 14 Polynomials

## 14.1 Berlekamp Massey

For a linear recurrence of length n you need to feed at least 2n terms into Berlekamp-Massey to guarantee getting the same or equivalent recurrence

```
template <class T>
struct Berlekamp {
  int n:
  vector\langle T \rangle s, t, pw[20];
  vector<T> combine(vector<T> a, vector<T> b) {
    vector\langle T \rangle ans(sz(t) * 2 + 1);
    for (int i = 0; i \le sz(t); i++)
      for (int j = 0; j \le sz(t); j++)
        ans[i + j] += a[i] * b[j];
    for (int i = 2 * sz(t); i > sz(t); --i)
      for (int j = 0; j < sz(t); j++)
        ans[i - 1 - j] += ans[i] * t[j];
    ans.resize(sz(t) + 1);
    return ans;
  }
  Berlekamp(const vector<T>& s) : n(sz(s)), t(n), s(s) {
    vector<T> x(n), tmp;
    t[0] = x[0] = 1;
    T b = 1;
    int len = 0, m = 0;
    fore (i, 0, n) {
      ++m;
      for (int j = 1; j \le len; j++) d += t[j] * s[i - j];
      if (d == 0) continue;
      tmp = t;
      T coef = d / b;
      for (int j = m; j < n; j++) t[j] -= coef * x[j - m];
      if (2 * len > i) continue;
      len = i + 1 - len;
      x = tmp;
      b = d;
      m = 0;
    t.resize(len + 1);
```

}

```
t.erase(t.begin());
                                                                          }
     for (auto& x : t) x = -x;
                                                                        for (int k = 1; k < n; k <<= 1)
     pw[0] = vector < T > (sz(t) + 1), pw[0][1] = 1;
                                                                          for (int i = 0; i < n; i += k << 1)
     fore (i, 1, 20) pw[i] = combine(pw[i - 1], pw[i - 1]);
                                                                            fore (j, 0, k) {
                                                                              Complex t = a[i + j + k] * root[j + k];
   }
                                                                              a[i + j + k] = a[i + j] - t;
   T operator[](lli k) {
                                                                              a[i + j] = a[i + j] + t;
     vector\langle T \rangle ans(sz(t) + 1);
                                                                            }
     ans[0] = 1;
                                                                        if (inv) {
                                                                          reverse(1 + all(a));
     fore (i, 0, 20)
       if (k & (1LL << i)) ans = combine(ans, pw[i]);</pre>
                                                                          for (auto\& x : a) x /= n;
     T val = 0:
                                                                        }
     fore (i, 0, sz(t)) val += ans[i + 1] * s[i];
                                                                      }
     return val;
                                                                      template <class T>
                                                                      vector<T> convolution(const vector<T>& a, const vector<T>& b)
 };
                                                                        if (a.empty() || b.empty()) return {};
       Lagrange \mathcal{O}(n)
                                                                        int n = sz(a) + sz(b) - 1, m = n;
Calculate the extrapolation of f(k), given all the sequence
                                                                        while (n != (n \& -n)) ++n;
f(0), f(1), f(2), ..., f(n)
  \sum_{i=1}^{10} i^5 = 220825
                                                                        vector<complex<double>> fa(all(a)), fb(all(b));
 template <class T>
                                                                        fa.resize(n), fb.resize(n);
                                                                        FFT(fa, false), FFT(fb, false);
 struct Lagrange {
                                                                        fore (i, 0, n) fa[i] *= fb[i];
   int n:
                                                                        FFT(fa, true);
   vector<T> y, suf, fac;
                                                                        vector<T> ans(m);
   Lagrange(vector<T>& y) : n(sz(y)), y(y), suf(n + 1, 1), fac(
                                                                        fore (i, 0, m) ans[i] = round(real(fa[i]));
       n, 1) {
     fore (i, 1, n) fac[i] = fac[i - 1] * i;
                                                                        return ans;
   }
                                                                      }
   T operator[](lli k) {
                                                                      template <class T>
     for (int i = n - 1; i \ge 0; i--)
                                                                      vector<T> convolutionTrick(const vector<T>& a,
       suf[i] = suf[i + 1] * (k - i);
                                                                                                  const vector<T>& b) { // 2 FFT's
                                                                                                       instead of 3!!
                                                                        if (a.empty() || b.empty()) return {};
     T pref = 1, val = 0;
     fore (i, 0, n) {
       T \text{ num} = pref * suf[i + 1];
                                                                        int n = sz(a) + sz(b) - 1, m = n;
       T den = fac[i] * fac[n - 1 - i];
                                                                        while (n != (n \& -n)) ++n;
       if ((n - 1 - i) \% 2) den *= -1;
                                                                        vector<complex<double>> in(n), out(n);
       val += y[i] * num / den;
       pref *= (k - i);
                                                                        fore (i, 0, sz(a)) in[i].real(a[i]);
                                                                        fore (i, 0, sz(b)) in[i].imag(b[i]);
     }
     return val;
   }
                                                                        FFT(in, false);
 };
                                                                        for (auto& x : in) x *= x;
                                                                        fore (i, 0, n) out[i] = in[-i & (n - 1)] - conj(in[i]);
                                                                        FFT(out, false);
14.3 FFT
 template <class Complex>
                                                                        vector<T> ans(m);
 void FFT(vector<Complex>& a, bool inv = false) {
                                                                        fore (i, 0, m) ans[i] = round(imag(out[i]) / (4 * n));
   const static double PI = acos(-1.0);
                                                                        return ans;
   static vector<Complex> root = {0, 1};
   int n = sz(a);
                                                                     14.4 Primitive root
   for (int i = 1, j = 0; i < n - 1; i++) {
                                                                      int primitive(int p) {
     for (int k = n \gg 1; (j ^= k) < k; k \gg 1);
                                                                        auto fpow = [&](lli x, int n) {
     if (i < j) swap(a[i], a[j]);</pre>
                                                                          lli r = 1;
   }
   int k = sz(root);
                                                                          for (; n > 0; n >>= 1) {
   if (k < n)
                                                                            if (n \& 1) r = r * x % p;
     for (root.resize(n); k < n; k <<= 1) {</pre>
                                                                            x = x * x % p;
       Complex z(cos(PI / k), sin(PI / k));
       fore (i, k >> 1, k) {
                                                                          return r;
         root[i << 1] = root[i];
                                                                        };
         root[i << 1 | 1] = root[i] * z;
```

for (int g = 2; g < p; g++) {

```
bool can = true:
     for (int i = 2; i * i < p; i++)
       if ((p - 1) % i == 0) {
         if (fpow(g, i) == 1) can = false;
         if (fpow(g, (p-1) / i) == 1) can = false;
    if (can) return g;
  }
   return -1;
}
14.5
       NTT
template <const int G, const int M>
void NTT(vector<Modular<M>>>& a, bool inv = false) {
  static vector<Modular<M>> root = {0, 1};
  static Modular<M> primitive(G);
  int n = sz(a);
   for (int i = 1, j = 0; i < n - 1; i++) {
     for (int k = n \gg 1; (j ^= k) < k; k \gg 1);
     if (i < j) swap(a[i], a[j]);</pre>
  int k = sz(root);
  if (k < n)
     for (root.resize(n); k < n; k <<= 1) {</pre>
       auto z = primitive.pow((M - 1) / (k << 1));
       fore (i, k >> 1, k) {
         root[i << 1] = root[i];
         root[i << 1 | 1] = root[i] * z;
     }
  for (int k = 1; k < n; k <<= 1)
     for (int i = 0; i < n; i += k << 1)
       fore (j, 0, k) {
         auto t = a[i + j + k] * root[j + k];
         a[i + j + k] = a[i + j] - t;
         a[i + j] = a[i + j] + t;
  if (inv) {
     reverse(1 + all(a));
     auto invN = Modular<M>(1) / n;
     for (auto& x : a) x = x * invN;
  }
}
template <int G = 3, const int M = 998244353>
vector<Modular<M>> convolution(vector<Modular<M>> a, vector<</pre>
     Modular<M>>> b) {
  // find G using primitive(M)
   // Common NTT couple (3, 998244353)
  if (a.empty() || b.empty()) return {};
  int n = sz(a) + sz(b) - 1, m = n;
  while (n != (n & -n)) ++n;
  a.resize(n, 0), b.resize(n, 0);
  NTT < G, M > (a), NTT < G, M > (b);
  fore (i, 0, n) a[i] = a[i] * b[i];
  NTT<G, M>(a, true);
  return a;
}
       Strings
      KMP \mathcal{O}(n)
15.1
```

## 15

```
• aaabaab - [0, 1, 2, 0, 1, 2, 0]
• abacaba - [0, 0, 1, 0, 1, 2, 3]
```

```
template <class T>
```

```
vector<int> lps(T s) {
   vector<int> p(sz(s), ∅);
   for (int j = 0, i = 1; i < sz(s); i++) {
     while (j \&\& (j == sz(s) || s[i] != s[j])) j = p[j - 1];
     if (j < sz(s) \&\& s[i] == s[j]) j++;
     p[i] = j;
   }
   return p;
 }
 // positions where t is on s
 template <class T>
 vector<int> kmp(T& s, T& t) {
   vector<int> p = lps(t), pos;
   debug(lps(t), sz(s));
   for (int j = 0, i = 0; i < sz(s); i++) {
     while (j \&\& (j == sz(t) || s[i] != t[j])) j = p[j - 1];
     if (j < sz(t) \&\& s[i] == t[j]) j++;
     if (j == sz(t)) pos.pb(i - sz(t) + 1);
   }
   return pos;
 }
15.2
      KMP automaton \mathcal{O}(Alphabet * n)
 template <class T, int ALPHA = 26>
 struct KmpAutomaton : vector<vector<int>>> {
   KmpAutomaton() {}
   KmpAutomaton(T s) : vector<vector<int>>(sz(s) + 1, vector<</pre>
        int>(ALPHA)) {
     s.pb(0);
     vector<int> p = lps(s);
     auto& nxt = *this;
     nxt[0][s[0] - 'a'] = 1;
     fore (i, 1, sz(s))
       fore (c, 0, ALPHA)
         nxt[i][c] = (s[i] - 'a' == c ? i + 1 : nxt[p[i - 1]][c]
              ]);
   }
 };
        Manacher \mathcal{O}(n)
15.3
  • aaabaab - [[0, 1, 1, 0, 0, 2, 0], [0, 1, 0, 2, 0, 0, 0]]
  • abacaba - [[0,0,0,0,0,0],[0,1,0,3,0,1,0]]
 template <class T>
 vector<vector<int>> manacher(T& s) {
   vector<vector<int>>> pal(2, vector<int>(sz(s), 0));
   fore (k, 0, 2) {
     int 1 = 0, r = 0;
     fore (i, 0, sz(s)) {
       int t = r - i + !k;
       if (i < r) pal[k][i] = min(t, pal[k][l + t]);</pre>
       int p = i - pal[k][i], q = i + pal[k][i] - !k;
       while (p \ge 1 \& q + 1 < sz(s) \& s[p - 1] == s[q + 1])
         ++pal[k][i], --p, ++q;
       if (q > r) 1 = p, r = q;
     }
   }
   return pal;
```

#### 15.4Hash

bases = [1777771, 10006793, 10101283, 10101823, 10136359,10157387, 10166249] mods = [999727999, 1000000123, 1000002193, 1000008223,1000009999, 1000027163, 1070777777

```
struct Hash : array<int, 2> {
   static constexpr array<int, 2> mod = {1070777777, 1070777777
       };
#define oper(op) \
  friend Hash operator op(Hash a, Hash b) { \
     fore (i, 0, sz(a)) \
      a[i] = (1LL * a[i] op b[i] + mod[i]) % mod[i]; \
     return a; \
  } \
  oper(+) oper(-) oper(*)
} pw[N], ipw[N];
struct Hashing {
  vector<Hash> h;
   static void init() {
     // Ensure all base[i] > alphabet
     pw[0] = ipw[0] = \{1, 1\};
    Hash base = {12367453, 14567893};
    Hash inv = {::inv(base[0], base.mod[0]),
                 ::inv(base[1], base.mod[1])};
     fore (i, 1, N) {
      pw[i] = pw[i - 1] * base;
       ipw[i] = ipw[i - 1] * inv;
    }
  }
  Hashing(string\& s) : h(sz(s) + 1) {
     fore (i, 0, sz(s)) {
      int x = s[i] - 'a' + 1;
      h[i + 1] = h[i] + pw[i] * Hash{x, x};
    }
  }
  Hash query(int 1, int r) {
    return (h[r + 1] - h[l]) * ipw[l];
  }
  lli queryVal(int 1, int r) {
    Hash hash = query(1, r);
     return (1LL * hash[0] << 32) | hash[1];
  }
};
// // Save len in the struct and when you do a cut
// Hash merge(vector<Hash>& cuts) {
// Hash f = \{0, 0\};
//
     fore (i, sz(cuts), 0) {
//
       Hash g = cuts[i];
//
       f = g + f * pw[g.len];
// }
    return f;
// }
        Min rotation \mathcal{O}(n)
15.5

 baabaaa - 4

  • abacaba - 6
 template <class T>
int minRotation(T& s) {
  int n = sz(s), i = 0, j = 1;
  while (i < n \&\& j < n) \{
     int k = 0;
     while (k < n \&\& s[(i + k) \% n] == s[(j + k) \% n]) k++;
     (s[(i + k) \% n] \le s[(j + k) \% n] ? j : i) += k + 1;
     j += i == j;
  }
  return i < n ? i : j;
```

## $ig| \ \mathbf{15.6} \quad \mathbf{Suffix} \ \mathbf{array} \ \mathcal{O}(nlogn)$

• Duplicates  $\sum_{i=1}^{n} lcp[i]$ 

}

• Longest Common Substring of various strings Add notUsed characters between strings, i.e. a + \$ + b + # + c Use two-pointers to find a range [l, r] such that all notUsed characters are present, then query(lcp[l+1], ..., lcp[r]) for that window is the common length.

```
template <class T>
struct SuffixArray {
 int n;
 Ts;
  vector<int> sa, pos, sp[25];
  SuffixArray(const T& x) : n(sz(x) + 1), s(x), sa(n), pos(n)
      {
    s.pb(0);
    fore (i, 0, n) sa[i] = i, pos[i] = s[i];
    vector<int> nsa(sa), npos(n), cnt(max(260, n), 0);
    for (int k = 0; k < n; k ? k *= 2 : k++) {
      fill(all(cnt), 0);
      fore (i, 0, n)
        nsa[i] = (sa[i] - k + n) % n, cnt[pos[i]]++;
      partial_sum(all(cnt), cnt.begin());
      for (int i = n - 1; i \ge 0; i - -)
        sa[--cnt[pos[nsa[i]]]] = nsa[i];
      for (int i = 1, cur = 0; i < n; i++) {
        cur += (pos[sa[i]] != pos[sa[i - 1]] ||
                pos[(sa[i] + k) % n] != pos[(sa[i - 1] + k) %
                     n]);
        npos[sa[i]] = cur;
      }
      pos = npos;
      if (pos[sa[n - 1]] >= n - 1) break;
    sp[0].assign(n, 0);
    for (int i = 0, j = pos[0], k = 0; i < n - 1; ++i, ++k) {
      while (k \ge 0 \&\& s[i] != s[sa[j - 1] + k])
        sp[0][j] = k--, j = pos[sa[j] + 1];
    for (int k = 1, pw = 1; pw < n; k++, pw <<= 1) {
      sp[k].assign(n, ∅);
      for (int 1 = 0; 1 + pw < n; 1++)
        sp[k][1] = min(sp[k - 1][1], sp[k - 1][1 + pw]);
    }
 }
 int lcp(int 1, int r) {
    if (1 == r) return n - 1;
    tie(1, r) = minmax(pos[1], pos[r]);
    int k = __lg(r - 1);
    return min(sp[k][1 + 1], sp[k][r - (1 << k) + 1]);
 }
 auto at(int i, int j) {
    return sa[i] + j < n ? s[sa[i] + j] : 'z' + 1;</pre>
  }
 int count(T& t) {
    int 1 = 0, r = n - 1;
    fore (i, 0, sz(t)) {
      int p = 1, q = r;
      for (int k = n; k > 0; k >>= 1) {
        while (p + k < r \&\& at(p + k, i) < t[i]) p += k;
        while (q - k > 1 \&\& t[i] < at(q - k, i)) q -= k;
```

```
l = (at(p, i) == t[i] ? p : p + 1);
       r = (at(q, i) == t[i] ? q : q - 1);
       if (at(1, i) != t[i] \&\& at(r, i) != t[i] || 1 > r)
           return 0:
     }
    return r - 1 + 1;
  }
  bool compare(ii a, ii b) {
    // s[a.f...a.s] < s[b.f...b.s]
     int common = lcp(a.f, b.f);
     int szA = a.s - a.f + 1, szB = b.s - b.f + 1;
     if (common >= min(szA, szB))
       return tie(szA, a) < tie(szB, b);</pre>
     return s[a.f + common] < s[b.f + common];</pre>
  }
};
        Aho Corasick \mathcal{O}(\sum s_i)
15.7
struct AhoCorasick {
  struct Node : map<char, int> {
     int link = 0, up = 0;
     int cnt = 0, isWord = 0;
  };
  vector<Node> trie;
   AhoCorasick(int n = 1) { trie.reserve(n), newNode(); }
  int newNode() {
     trie.pb({});
     return sz(trie) - 1;
  void insert(string& s, int u = 0) {
     for (char c : s) {
       if (!trie[u][c]) trie[u][c] = newNode();
       u = trie[u][c];
     trie[u].cnt++, trie[u].isWord = 1;
   int next(int u, char c) {
    while (u && !trie[u].count(c)) u = trie[u].link;
     return trie[u][c];
  }
  void pushLinks() {
     queue<int> qu;
     qu.push(0);
     while (!qu.empty()) {
       int u = qu.front();
       qu.pop();
       for (auto& [c, v] : trie[u]) {
         int l = (trie[v].link = u ? next(trie[u].link, c) : 0)
         trie[v].cnt += trie[l].cnt;
         trie[v].up = trie[l].isWord ? l : trie[l].up;
         qu.push(v);
       }
    }
   template <class F>
  void goUp(int u, F f) {
     for (; u != 0; u = trie[u].up) f(u);
```

```
}
   int match(string& s, int u = 0) {
     int ans = 0;
     for (char c : s) {
       u = next(u, c);
       ans += trie[u].cnt;
     return ans;
   Node& operator[](int u) { return trie[u]; }
 };
        Eertree \mathcal{O}(\sum s_i)
15.8
 struct Eertree {
   struct Node : map<char, int> {
     int link = 0, len = 0;
   };
   vector<Node> trie;
   string s = "$";
   int last;
   Eertree(int n = 1) {
     trie.reserve(n), last = newNode(), newNode();
     trie[0].link = 1, trie[1].len = -1;
   }
   int newNode() {
     trie.pb({});
     return sz(trie) - 1;
   int next(int u) {
     while (s[sz(s) - trie[u].len - 2] != s.back())
       u = trie[u].link;
     return u;
   }
   void extend(char c) {
     s.push_back(c);
     last = next(last);
     if (!trie[last][c]) {
       int v = newNode();
       trie[v].len = trie[last].len + 2;
       trie[v].link = trie[next(trie[last].link)][c];
       trie[last][c] = v;
     last = trie[last][c];
   }
   Node& operator[](int u) { return trie[u]; }
   void substringOccurrences() {
     fore (u, sz(s), 0)
       trie[trie[u].link].occ += trie[u].occ;
   }
   1li occurences(string& s, int u = 0) {
     for (char c : s) {
       if (!trie[u].count(c)) return 0;
       u = trie[u][c];
     return trie[u].occ;
   }
 };
```

#### Universidad de Guadalajara CUCEI - Almost Retired

## 15.9 Suffix automaton $\mathcal{O}(\sum s_i)$

- sam[u].len sam[sam[u].link].len = distinct strings
- Number of different substrings (dp)  $\mathcal{O}(\sum s_i)$

$$diff(u) = 1 + \sum_{v \in trie[u]} diff(v)$$

• Total length of all different substrings (2 x dp)

$$totLen(u) = \sum_{v \in trie[u]} diff(v) + totLen(v)$$

- Leftmost occurrence  $\mathcal{O}(|s|)$  trie[u].pos = trie[u].len 1 if it is **clone** then trie[clone].pos = trie[q].pos
- All occurrence positions
- Smallest cyclic shift  $\mathcal{O}(|2*s|)$  Construct sam of s+s, find the lexicographically smallest path of sz(s)
- Shortest non-appearing string  $\mathcal{O}(|s|)$

```
nonAppearing(u) = \min_{v \in trie[u]} nonAppearing(v) + 1
```

```
struct SuffixAutomaton {
  struct Node : map<char, int> {
    int link = -1, len = 0;
 };
 vector<Node> trie;
 int last;
 SuffixAutomaton(int n = 1) {
    trie.reserve(2 * n), last = newNode();
 }
 int newNode() {
    trie.pb({});
    return sz(trie) - 1;
 }
 void extend(char c) {
    int u = newNode();
    trie[u].len = trie[last].len + 1;
    int p = last;
    while (p != -1 && !trie[p].count(c)) {
      trie[p][c] = u;
      p = trie[p].link;
    }
    if (p == -1)
      trie[u].link = 0;
    else {
      int q = trie[p][c];
      if (trie[p].len + 1 == trie[q].len)
        trie[u].link = q;
      else {
        int clone = newNode();
        trie[clone] = trie[q];
        trie[clone].len = trie[p].len + 1;
        while (p != -1 && trie[p][c] == q) {
          trie[p][c] = clone;
          p = trie[p].link;
        trie[q].link = trie[u].link = clone;
      }
    }
    last = u;
 }
 string kthSubstring(lli kth, int u = 0) {
    // number of different substrings (dp)
    string s = "";
```

```
while (kth > 0)
      for (auto& [c, v] : trie[u]) {
        if (kth <= diff(v)) {</pre>
          s.pb(c), kth--, u = v;
          break;
        kth -= diff(v);
      }
    return s;
  }
  void substringOccurrences() {
    // trie[u].occ = 1, trie[clone].occ = 0
    vector<int> who(sz(trie) - 1);
    iota(all(who), 1);
    sort(all(who), [&](int u, int v) {
      return trie[u].len > trie[v].len;
    });
    for (int u : who) {
      int 1 = trie[u].link;
      trie[l].occ += trie[u].occ;
    }
  }
 lli occurences(string& s, int u = 0) {
    for (char c : s) {
      if (!trie[u].count(c)) return 0;
      u = trie[u][c];
    return trie[u].occ;
 int longestCommonSubstring(string& s, int u = 0) {
    int mx = 0, len = 0;
    for (char c : s) {
      while (u && !trie[u].count(c)) {
        u = trie[u].link;
        len = trie[u].len;
      if (trie[u].count(c)) u = trie[u][c], len++;
      mx = max(mx, len);
    return mx;
  string smallestCyclicShift(int n, int u = 0) {
    string s = "";
    fore (i, 0, n) {
      char c = trie[u].begin()->f;
      s += c;
      u = trie[u][c];
    }
    return s;
  int leftmost(string& s, int u = 0) {
    for (char c : s) {
      if (!trie[u].count(c)) return -1;
      u = trie[u][c];
    return trie[u].pos - sz(s) + 1;
  }
 Node& operator[](int u) { return trie[u]; }
};
```