

EV_2_3_Diseño de robot con CAD- Ansys Dinámica y control de robots.

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07 de junio del 2019



Objetivo

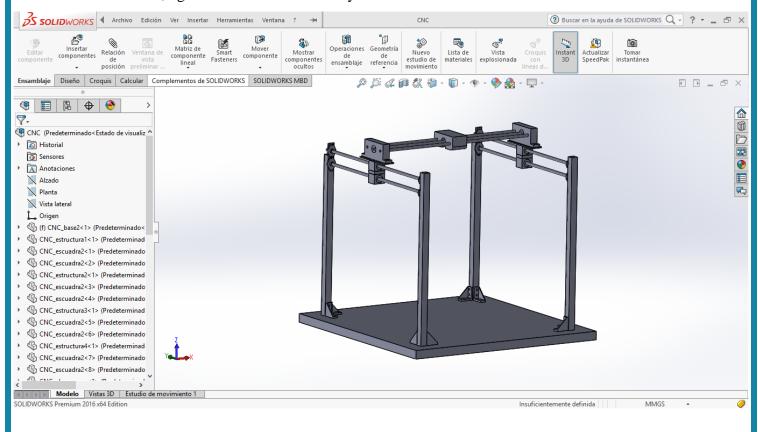
Diseñar en software CAD el robot manipulador seleccionado y en software CAE realizar los análisis estructurales y de esfuerzos presentes en dicho robot.

Materiales

- PC.
- Software CAD (en este caso Solidworks) y software CAE (en este caso Ansys).

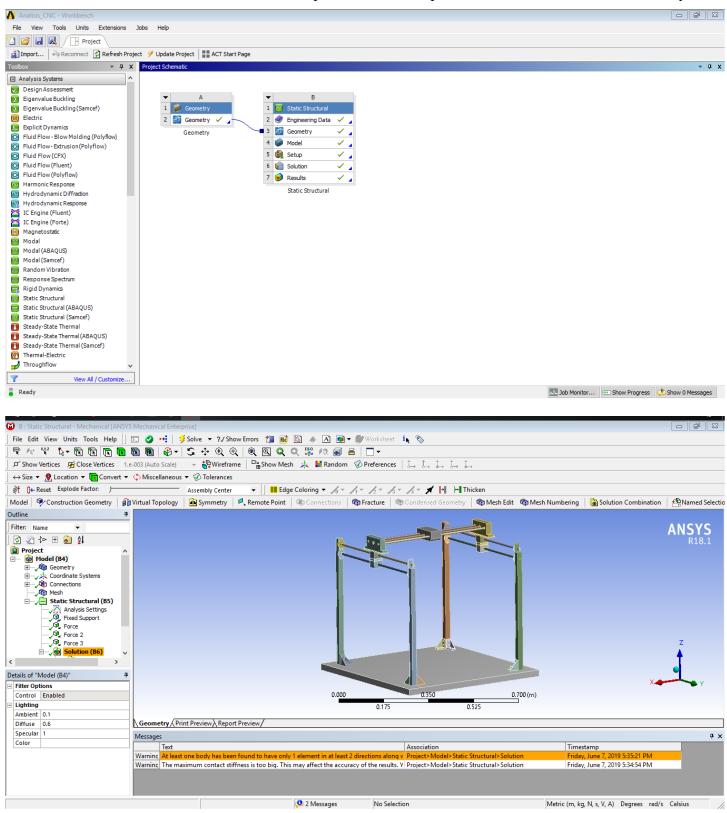
Procedimiento

1.- Con base en los conocimientos adquiridos sobre dibujo en ingeniería, se diseña el prototipo de robot seleccionado, siguiendo los estándares del SI y demás:





2.- Una vez obtenido el ensamble completo del robot, se procede a analizar su estructura en Ansys:

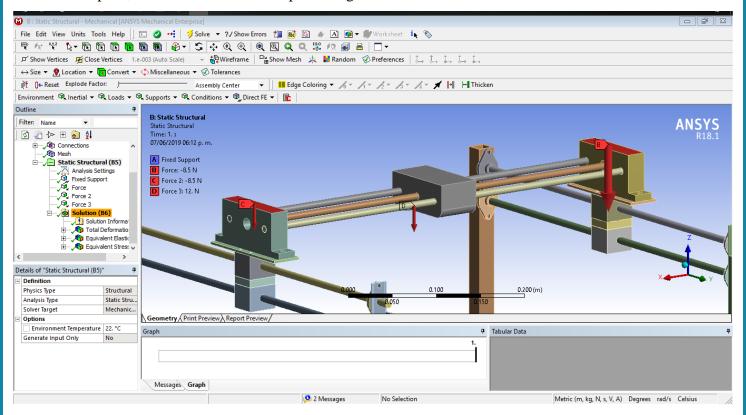


EV_2_3_Diseño de robot con CAD- Ansys



Resultados

Se inició el análisis del robot colocando diferentes fuerzas en base a los puntos de mayor y soporte de peso, tal es el caso de los tres puntos siguientes:



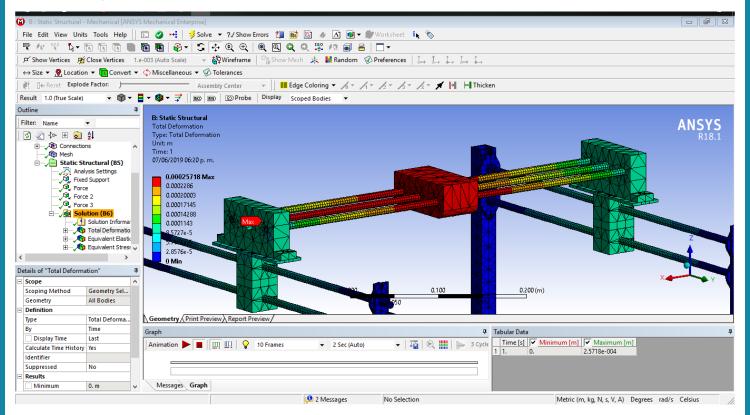
Las dimensiones del robot son las reales en cada una de las piezas utilizadas.

En los puntos B y C la fuerza aplicada hacia abajo es de 8.5 N, pues el peso que estos puntos en la estructura van a soportar será de 850 g cada uno. El peso total para toda la extensión de la estructura es 1.7 kg.

En el punto D es donde se concentra el mayor peso, pues en esa zona es donde se colocará una pinza de máximo 200 g que levantará un peso máximo de 1 kg. El resultado a grandes rasgos es una fuerza de 12 N.

Los siguientes análisis se basan en las fuerzas aplicadas, en su totalidad lo que necesitamos saber es la deformación total a causa de las fuerzas B, C y D:





Como se observa en la imagen, la zona roja representa la máxima deformación en m que sufre el robot. Sus valores son tan mínimos que puede despreciarse si respetamos el peso máximo admitido que es de 1.2 kg.

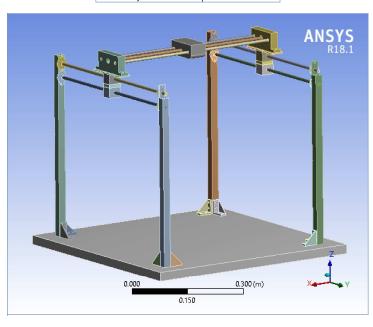
Se realizaron otras dos simulaciones, utilizando pesos de 5.2 kg y 10.2 kg. La deformación sigue siendo mínima pues su máximo en 10.2 kg es de 0.00257 m. Pero no ignoremos que esto es solo una simulación. Si le colocáramos un peso de 10.2 kg al punto D del robot, la deformación sería diferente en valores. También debemos tener en cuenta que tres de las barras cilíndricas presentes son husillos, y se encargan de la movilidad del robot, por lo que al aumentar el peso en el punto D, el torque necesario para el movimiento aumentaría.

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Project

	Friday, June 7, 2019
Last Saved	Friday, June 7, 2019
Product Version	18.1 Release
Save Project Before Solution	No
Save Project After Solution	No



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- Model (B4)
 - o Geometry
 - Parts
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 - Contact Regions
 - o Mesh
 - o Static Structural (B5)
 - Analysis Settings
 Loads

 - Solution (B6)
 Solution Information
 Results
- Material Data
 - o Polyethylene
 - o Structural Steel
 - o Aluminum Alloy
 - o Stainless Steel

Report Not Finalized

Not all objects described below are in a finalized state. As a result, data may be incomplete, obsolete or in error. View first state problem. To finalize this report, edit objects as needed and solve the analyses.

Units

TABLE 1

Unit System	Metric (m, kg, N, s, V, A) Degrees rad/s Celsius
Angle	Degrees
Rotational Velocity	rad/s
Temperature	Celsius

Model (B4)

Geometry

TABLE 2 Model (B4) > Geometry

Model (B4) > Geometry						
Object Name	Geometry					
State	Fully Defined					
	Definition					
Source	C:\Users\jesus\Documents\Ansys\CNC.scdoc					
Туре	SpaceClaim					
Length Unit	Meters					
Element Control	Program Controlled					
Display Style	Body Color					
Во	unding Box					
Length X	0.61 m					
Length Y	0.61 m					
Length Z	0.5715 m					
P	Properties					
Volume	1.0353e-002 m³					
Mass	14.422 kg					
Scale Factor Value	1.					
:	Statistics					
Bodies	41					
Active Bodies	41					
Nodes	144010					
Elements	41653					
Mesh Metric	None					
Basic G	eometry Options					
Solid Bodies	Yes					
Surface Bodies	Yes					
Line Bodies	Yes					
Parameters	Independent					
Parameter Key						
Attributes	Yes					
Attribute Key						
Named Selections	Yes					
Named Selection Key						
Material Properties	Yes					
Advanced	Geometry Options					
Use Associativity	Yes					
Coordinate Systems	Yes					
Coordinate System Key						
Reader Mode Saves Updated File	No					
Use Instances	Yes					
Smart CAD Update	Yes					
Compare Parts On Update	No					

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Attach File Via Temp File	Yes
Temporary Directory	C:\Users\jesus\AppData\Local\Temp
Analysis Type	3-D
Mixed Import Resolution	None
Decompose Disjoint Geometry	Yes
Enclosure and Symmetry Processing	Yes

TABLE 3
Model (B4) > Geometry > Parts

					> Geometry > Pa					
Object Name	CNC_base2 \Solid1	CNC_estructura1 \Solid1	CNC_escuadra2 \Solid1	CNC_escuadra2 \Solid1	CNC_escuadra2 \Solid1	CNC_escuadra2 \Solid1	CNC_escuadra2 \Solid1	CNC_escuadra2 \Solid1	CNC_escuadra2 \Solid1	CNC_
State						Meshed				
					Graphic	s Properties				
Visible						Yes				
Transparency						1				
					Def	finition				
Suppressed		No								
Stiffness Behavior						Flexible				
Coordinate						efault Coordinate S	Puntom			
System					U	elauli Coordinale s	bystein			
Reference						By Environmer	nt			
Temperature							п.			
Behavior						None				
Assignment	Polyethylene	Structural Steel			Ma	aterial	um Alloy			
Nonlinear Effects	Polyetriylerie	Structural Steel				Yes	alli Alloy			
Thermal Strain						162				
Effects						Yes				
					Boun	ding Box				
Length X	0.61 m	2.e-002 m	1.7e-002 m	1.7e-002 m 3.8e-002 m 1.7e-002 m		3.8e-002 m	1.7e-002 m	3.8		
Length Y	0.61 m	2.e-002 m	3.8e-002 m 1.7e-002 m 3.8e-002 m 1.7e-002 m 3.8e-002 m				1.7			
Length Z	2.5e-002 m	0.5 m				3.8e-	002 m	•		
					Pro	perties				
Volume	9.2946e-003 m³	6.893e-005 m³				6.73136	e-006 m³			
Mass	8.8299 kg	0.5411 kg				1.86466	e-002 kg			
Centroid X	4.1673e-002 m	0.29168 m	0.29289 m	0.26966 m	-0.18632 m	-0.20	954 m	-0.18632 m	0.29289 m	0.2
Centroid Y	-9.4711e- 003 m	0.24038 m	0.21852 m	0.241	74 m	0.21852 m	-0.23746 m	-0.26068 m	-0.23746 m	-0.2
Centroid Z	0.61 m	0.85993 m		•		0.634	451 m	•	•	
Moment of Inertia	0.27408	1.0164e-002				4.06186	006 kg·m²			
lp1	kg·m²	kg·m²				4.00106-	ooo kg III			
Moment of Inertia	0.27408	1.0164e-002				1.6329e-	006 kg·m²			
lp2	kg·m²	kg·m²								
Moment of Inertia	0.54725	5.9048e-005		4.6632e-006 kg·m²						
lp3	kg·m²	kg·m²			C+-	itistics				
Nodes	30069	4807			318		09			
Elements	5718	2319					98			
Mesh Metric	37 10	2018				None	<i>3</i> 0			
INICSTI INICITIC					CAD	Attributes				
PartTolerance:					CAD	0.00000001				
Color:143.149.175						0.00000001				
COIOI. 143. 149. 173										

TABLE 4 Model (B4) > Geometry > Parts

C									
Object Name	NC_estructura3 \Solid1	CNC_estructura4 \Solid1	CNC_chumacera\Solid1	CNC_chumacera\Solid1	CNC_chumacera\Solid1	CNC_chumacera\Solid1	CNC_chumacera\Solid1		
State						Meshed			
	Graphics Properties								
Visible			Yes						
Transparency			1						
		Definition							
Suppressed						No			
Stiffness Behavior						Flexible			
Coordinate						Default Coordinate Sy	etem		
System						Delault Cooldinate Sy	/sterri		
Reference									
Temperature			•						
Behavior			None						
Material									
Assignment	Structur	al Steel	Aluminum Alloy						
Nonlinear Effects			Yes						
Thermal Strain Effects						Yes			
						Bounding Box			
Length X	2.e-0	02 m				2.7e-	002 m		
Length Y	2.e-0	02 m				9.e-0	003 m		
Length Z	0.5	m				4.5001	e-002 m		
			!			Properties			
Volume 7	'.2632e-005 m ³	7.2626e-005 m ³				3.0961	e-006 m³		
Mass	0.57016 kg	0.57012 kg				8.5763	e-003 kg		
Centroid X	-0.20834 m	0.29168 m	0.29167 m	-0.20833 m	0.29167 m	-0.20833 m	0.291		
Centroid Y	-0.25	95 m	-0.24	702 m	0.228	307 m	-0.24702 m		
Centroid Z	0.87244 m	0.87242 m		1.1	m				
Moment of Inertia	1.1828e-002	1.1825e-002				8 16200	007 kg·m²		
lp1	kg·m²	kg·m²				0.10296-	oor ky iii		
	1.1828e-002	1.1826e-002				3 6663e-	007 kg·m²		
lp2	kg·m²	kg·m²				0.00000-			

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Moment of Inertia	6.222e-005 kg·m²	6.2217e-005 kg·m²	1.1271e-006 kg·m²
			Statistics
Nodes	5148	5135	598
Elements	2488	2477	250
Mesh Metric			None
			CAD Attributes
PartTolerance:			0.0000001
Color:143.149.175			

TABLE 5
Model (B4) > Geometry > Parts

State Visible Transparency Suppressed Stiffness Behavior Coordinate System Reference	husillo\Solid1	CNC_husillo\Solid1	CNC_husillo\Solid1	CNC_husillo\Solid1		CNC_husillo\Solid1 Meshed cs Properties Yes	CNC_soporte\Solid1	CNC_soporte\Solia
Visible Transparency Suppressed Stiffness Behavior Coordinate System Reference					Graphic	s Properties		
Transparency Suppressed Stiffness Behavior Coordinate System Reference					Graphic			
Transparency Suppressed Stiffness Behavior Coordinate System Reference						Voc		
Suppressed Stiffness Behavior Coordinate System Reference						169		
Stiffness Behavior Coordinate System Reference						1		
Stiffness Behavior Coordinate System Reference					De	finition		
Coordinate System Reference						No		
System Reference						Flexible		
Reference					1	Default Coordinate Sys	stem	
					·		5.0111	
						By Environment		
Temperature								
Behavior						None aterial		
Assignment			Stainles	no Ctool	IV.	iateriai	Polyeth	vlono
Nonlinear Effects			Stanlies	S SIEEI		Yes	Folyetti	ylerie
Thermal Strain								
Effects						Yes		
					Bou	nding Box		
Length X 8.6	.e-003 m						02 m	
	0.5 m	8.e-003 m	9.8527e-003 m	0.5	m	8.e-003 m	0.123 m	
Length Z	8.e-00	03 m	9.8527e-003 m		8.e-003 m		5.2e-0	02 m
					Pr	operties		
Volume			2.5132e	-005 m³			1.0705e-	
Mass			0.194				0.1016	
	.20833 m	5.2673e		0.29167 m	-0.20833 m	3.0673e-002 m	0.29178 m	-0.20822 m
	394e-004 m	2.5497e-002 m	-4.1503e-002 m	5.2894e			-8.0034e-003 m	
	1.1 m	1.148	3 m	1.06	3 m	1.148 m	1.141	8 m
Moment of Inertia	4.0381e-003 kg·m² 2.9057e-005 kg·m²					05 kg·m²		
Moment of Inertia	4.0381e-003 kg·m² 9.2566e-005 kg·m²							
Moment of Inertia	1.5425e-006 kg·m² 1.1344e-004 kg·m²							
					St	atistics		
Nodes	9322 1522							
Elements			17	60			77:	5
Mesh Metric						None		
				•	CAD	Attributes		
PartTolerance:						0.0000001		
Color:143.149.175								

TABLE 6 Model (B4) > Geometry > Parts

Object Name	CNC_camisa\Solid1	NC camisa\Solid1 CNC placa\Solid1 CNC placa\Solid1 CNC placa\Solid1 CNC relleno\Solid1 CNC relleno\Solid1 CNC balero\Solid1 CNC bale						
State		Meshed						
			Graphics Proper	ties				
Visible				Yes				
Transparency				1				
			Definition					
Suppressed				No				
Stiffness Behavior			F	lexible				
Coordinate System			Default Co	ordinate System				
Reference Temperature			Ву Е	nvironment				
Behavior				None				
			Material					
Assignment	Aluminum Alloy Polyethylene Aluminum Alloy Structural Steel							
Nonlinear Effects	Yes							
Thermal Strain Effects	Yes							
			Bounding Box	(
Length X		3.5e-002 m	-		5.e-0	03 m	4.8e-002 m	
Length Y	3.e-002 m	0.123 m	3.e-0	02 m	2.1e-0	02 m	9.5e-002 m	
Length Z	2.8e-002 m	3.e-003 m	8.92e	-003 m	2.1e-0	02 m	3.9e-002 m	
			Properties					
Volume	2.6576e-005 m ³	1.2712e-005 m³		-006 m³	1.4804e	-006 m³	1.5364e-004 m ³	
Mass	7.3615e-002 kg	1.2077e-002 kg	2.5944	-002 kg	4.1007e		1.2061 kg	
Centroid X	0.2916	67 m -0.20833 m	0.29167 m	-0.20833 m	-0.21683 m	0.28317 m	4.122e-002 m	
Centroid Y	-7.4875e-003 m			-8.0034e-003 n				
Centroid Z	1.0629 m	1.1155 m	1.08	15 m	1.14	8 m	1.1505 m	
Moment of Inertia	1.0328e-005 kg·m²	05 kg·m² 1.2488e-006 kg·m² 2.8205e-006 kg·m² 1.3773e-007 kg·m²					3.93e-004 kg·m²	
Moment of Inertia lp2	1.3214e-005 kg·m²	1.5139e-005 kg·m²	4.5942e-	006 kg·m²	1.3773e-0	07 kg·m²	1.2161e-003 kg·m²	
Moment of Inertia Ip3	1.3262e-005 kg·m²	1.6369e-005 kg·m²	2.1178e-	006 kg·m²	2.5839e-0	07 kg·m²	1.1353e-003 kg·m²	

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Statistics							
2812	948	70	157	1602			
1728	114	6	16	850			
Mesh Metric None							
CAD Attributes							
PartTolerance: 0.00000001							
Color:143.149.175							
			2812 948 70 1728 114 6 None CAD Attributes	2812 948 70 157 1728 114 6 16 None CAD Attributes			

Coordinate Systems

-	ABLE 7						
	Model (B4) > Coordinate Systems > Coordinate System						
Object Name	Global Coordinate System						
State	Fully Defined						
De	efinition						
Туре	Cartesian						
Coordinate System ID	0.						
	Origin						
Origin X	0. m						
Origin Y	0. m						
Origin Z	0. m						
Directi	onal Vectors						
X Axis Data	[1. 0. 0.]						
Y Axis Data	[0. 1. 0.]						
Z Axis Data	[0, 0, 1, 1						

Connections

TABLE 8

Model (B4) > Connections					
Object Name	Connections				
State	Fully Defined				
Auto Detection					
Generate Automatic Connection On Refresh	Yes				
Transparency					
Enabled	Yes				

TABLE 9
Model (B4) > Connections > Contacts

tions > Contacts								
Contacts								
Fully Defined								
ion								
Contact								
Scope								
Geometry Selection								
All Bodies								
ection								
Slider								
0.								
2.587e-003 m								
No								
Yes								
Off								
Include								
No								
No								
Include All								
Bodies								
Bodies								
ics								
68								
68								

TABLE 10

	Model (B4) > Connections > Contacts > Contact Regions										
Object Name	Contact Region	Contact Region 2	Contact Region 3	Contact Region 4	Contact Region 5	Contact Region 6	Contact Region 7	Contact Region 8	Contact Region 9	Contact Region 10	Contact Region 11
State						Fully Def	ined				
	Scope										
Scoping Method						Geometry S	election				
Contact						1 Fac	е				
Target						1 Fac	е				
Contact Bodies						CNC_base2	\Solid1				
Target Bodies	CNC_estructura1 \Solid1	CNC_estructura1 CNC_escuadra2\Solid1 CNC_estructura2 CNC_estructura CNC_estructura2 CNC_estructura3 CNC_estructura3 CNC_estructura3 CNC_estructura4 CNC_estructura4 CNC_estructura4 CNC_estructura5 CNC_estructura5 CNC_estructura6 CNC_estructura6 CNC_estructura6 CNC_estructura6 CNC_estructura7 CNC_estructura7 CNC_estructura8 CNC_estruc							CNC_estructura3 \Solid1		
					Def	inition					
Туре						Bonde	d				
Scope Mode						Automa	itic				
Behavior						Program Co	ntrolled				
Trim Contact						Program Co	ntrolled				
Trim Tolerance						2.587e-0	03 m				
Suppressed						No					
					Adv	anced					
Formulation						Program Co	ntrolled				
Detection Method	ion Method Program Controlled										
Penetration Tolerance	Program Controlled										
Elastic Slip						Program Co	ntrolled				

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Tolerance								
Normal Stiffness	Program Controlled							
Update Stiffness	Program Controlled							
Pinball Region	Program Controlled							
	Geometric Modification							
Contact Geometry Correction	None							
Target Geometry Correction	None							

	TABLE 11 Model (B4) > Connections > Contacts > Contact Regions										
Object Name	Contact Region 12	Contact Contact Contact Contact Contact Contact Contact									Contact Region 22
State						Fully Defined					
					Sco						
Scoping Method						Seometry Selection					
Contact						1 Face					
Target						1 Face					
Contact Bodies	CNC_base2\Solid1			CNC_estructure	ra1\Solid1				NC_escuadr	a2\Solid1	
Target Bodies	CNC_estructura4 \Solid1	CNC_escua	adra2\Solid1	CNC_chum		CNC_husillo\Solid1	CNC_estruc	ctura2\Solid1	CNC_estruc	ctura3\Solid1	CNC_estructura4 \Solid1
					Defin						
Туре						Bonded					
Scope Mode						Automatic					
Behavior						Program Controlled					
Trim Contact					F	Program Controlled					
Trim Tolerance						2.587e-003 m					
Suppressed						No					
					Adva						
Formulation					F	Program Controlled					
Detection Method					F	Program Controlled					
Penetration Tolerance					F	Program Controlled					
Elastic Slip Tolerance					F	Program Controlled					
Normal Stiffness					F	Program Controlled					
Update Stiffness	Program Controlled										
Pinball Region	Program Controlled										
	Geometric Modification										
Contact Geometry Correction						None					
Target Geometry Correction						None					

				Model (B4) >		ABLE 12	s > Contact Regions				
Object Name	Contact Region 23	Contact Region 24	Contact Region 25	Contact Region 26	Contact Region 27	Contact Region 28	Contact Region 29	Contact Region 30	Contact Region 31	Contact Region 32	Contact Region
State						Scope	Defined				
Scoping Method							ry Selection				
Contact						1	Face				
Target						1	Face				
Contact Bodies	CNC_escuadra2 \Solid1	С	NC_estructu	ra2\Solid1	С	NC_estructu	ra3\Solid1	С	NC_estructu	ra4\Solid1	CNC_chumacera\
Target Bodies	CNC_estructura4 \Solid1	CNC_chum	acera\Solid1	CNC_husillo\Solid1	CNC_chum	acera\Solid1	CNC_husillo\Solid1	CNC_chum	acera\Solid1	CNC_husillo\Solid1	CNC_chumacera\
						Definition					
Туре						Вс	onded				
Scope Mode						Aut	omatic				
Behavior						Program	Controlled				
Trim						Program	Controlled				
Contact Trim											
Tolerance						2.587	'e-003 m				
Suppressed							No				
Eleti	Ι					Advanced					
Formulation Detection							Controlled				
Method						Program	Controlled				
Penetration Tolerance						Program	Controlled				
Elastic Slip Tolerance						Program	Controlled				
Normal Stiffness						Program	Controlled				
Update Stiffness						Program	Controlled				
Pinball Region	Program Controlled										
Region	Geometric Modification										
Contact Geometry Correction							lone				
Target Geometry Correction						N	lone				

TABLE 13

Object Name				Model (B4) > C	onnections > Contacts >	Contact Regions						
Scoping	Object Name	Contact Region 34	Contact Region 35	Contact Region 36	Contact Region 37	Contact Region 38	Contact Region 39	Region	Region	Region	Region	
Scoping Method Geometry Selection Trace Trac	State		•	•	Fully	Defined	•					
Method Contact 1 Face 2 Faces 1 Face 2 Faces 1 Face 2 Faces 1 Face Contact												
Target	Scoping Method	Geometry Selection										
Contact Rodies	Contact					ace						
Bodies Target CNC_husillo\Solid1 CNC_chumacera\Solid1 CNC_husillo\Solid1 CNC_chumacera\Solid1 CNC_chum	Target	1 Face	2 Faces		1 Face		2 Faces			1 Face		
Type	Bodies				CNC_chun	nacera\Solid1						
Type	Target Bodies	CNC_husillo\Solid1	CNC_chumacera\Solid1	CNC_husillo\Solid1		CNC_husillo\Solid1	CNC_chumacera\Solid1		CNC	_husillo\S	3olid1	
Scope Automatic												
Mode Autoritation Behavior Program Controlled Trim Program Controlled Trim 2.587e-003 m Suppressed No Advanced Formulation Program Controlled Detection Program Controlled Method Program Controlled Penetration Program Controlled Tolerance Program Controlled Elastic Silp Program Controlled Normal Stiffness Update Program Controlled Stiffness Program Controlled Pinball Program Controlled Region Program Controlled Geometric Modification None Cortection None					Во	nded						
Trim 2.587e-003 m Suppressed No Suppressed Program Controlled					Auto	omatic						
Contact Program Controlled Trim 2.587e-003 m Suppressed No Advanced Formulation Program Controlled Detection Program Controlled Method Program Controlled Tolerance Program Controlled Elastic Slip Program Controlled Normal Program Controlled Stiffness Program Controlled Stiffness Program Controlled Pinball Program Controlled Region Program Controlled Contact Region to the controlled of	Behavior				Program	Controlled						
Contact Cont					Program	Controlled						
Tolerance 2.58/e-U3 m					- Trogram	Controlled						
Suppressed No												
Formulation Program Controlled Detection Program Controlled Penetration Program Controlled Penetration Program Controlled Elastic Slip Program Controlled Normal Program Controlled Normal Program Controlled Update Program Controlled Update Program Controlled Fishill Program Controlled Program Controlled Contact Geometry None Target Geometry None None						No						
Detection Method Penetration Tolerance Elastic Slip Tolerance Normal Stiffness Update Stiffness Program Controlled Program Controlled Program Controlled Program Controlled Program Controlled Update Program Controlled Program Controlled Program Controlled Program Controlled		•			Advanced							
Method Penetration Tolerance Elastic Slip Tolerance Normal Stiffness Update Stiffness Update Stiffness Program Controlled Program Controlled Program Controlled Program Controlled Program Controlled Program Controlled Program Controlled Program Controlled Normal Stiffness Program Controlled Program Controlled Program Controlled Program Controlled None Geometric Modification None Target Geometry None	Formulation				Program	Controlled						
Tolerance					Program	Controlled						
Elastic Slip Tolerance Program Controlled Normal Stiffness Program Controlled Update Stiffness Program Controlled Pinball Region Program Controlled Contact Geometry Correction None Target Geometry None None None					Program	Controlled						
Normal Stiffness Update Update Stiffness Program Controlled Prinball Region Contact Geometry Correction Target Geometry None None None	Elastic Slip				Program	Controlled						
Update Stiffness Program Controlled	Normal				Program	Controlled						
Pinball Program Controlled Region Geometric Modification Contact Geometry None Correction Target Geometry None	Update				Program	Controlled						
Region Program Controlled Geometric Modification Contact Geometry Correction Target Geometry None												
Geometric Modification												
Geometry None Correction Target Geometry None												
Target Geometry None	Geometry											
	Target Geometry				N	one						

TABLE 14

Model (B4) > Connections > Contacts > Contact Regions

ct | Contact Region 40 | Contact | Contac

Object Name	Contact Region 45	Contact Region 46	Contact Region 47	Contact Region 48	Contact Region 49	Contact Region 50	Contact Region 51	Contact Region 52	Contact Region 53	Contact Region 54	Contact Region 55	
State						Fully De	fined	•				
		Scope										
Scoping Method						Geometry S	election					
Contact						1 Fac	e					
Target						1 Fac	e					
Contact Bodies						CNC_husill	o\Solid1					
Target Bodies	CNC_cam	isa\Solid1	CNC_sop	orte\Solid1	CNC_basepinza\Solid1	CNC_sop	orte\Solid1	CNC_basepinza\Solid1	CNC_can	nisa\Solid1	CNC_soporte\Solid1	
					D	efinition			-			
Туре						Bond	ed					
Scope Mode						Autom	atic					
Behavior						Program Co						
Trim Contact						Program Co	ntrolled					
Trim Tolerance						2.587e-0	03 m					
Suppressed		No										
	Advanced											
Formulation						Program Co	ontrolled					
Detection						Program Co	ntrolled					
Method												
Penetration Tolerance						Program Co	ontrolled					
Elastic Slip Tolerance						Program Co	ontrolled					
Normal Stiffness						Program Co	ontrolled					
Update Stiffness						Program Co	ontrolled					
Pinball Region	Program Controlled											
	Geometric Modification											
Contact												
Geometry Correction		None										
Target Geometry Correction						Non	e					

TABLE 15
Model (B4) > Connections > Contacts > Contact Regions

				Widdel (D4)	Connections - Con	itacis - contact ite	giona			
Object Name	Contact Region 56	Contact Region 57	Contact Region 58	Contact Region 59	Contact Region 60	Contact Region 61	Contact Region 62	Contact Region 63	Contact Region 64	Contact 6

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State		Fully Defined														
		Scope														
Scoping Method		Geometry Selection														
Contact		1 Face		2 Faces	1 Face	2 Faces			ace							
Target		1 Face		2 Faces	1 Face	2 Faces		1 F	ace							
Contact Bodies	CNC_h	usillo\Solid1		CNC_sop	orte\Solid1			CNC_can	nisa\Solid1							
Target Bodies	CNC_balero\Solid1	CNC_basepinza\Solid1	CNC_placa\Solid1	CNC_balero\Solid1		CNC_balero\Solid1	CNC_placa\Solid1	CNC_relleno\Solid1	CNC_pla							
					Definition											
Туре					Bond	led										
Scope Mode					Autom	natic										
Behavior					Program C	ontrolled										
Trim Contact					Program C	ontrolled										
Trim Tolerance					2.587e-0	003 m										
Suppressed					No	1										
Опррісозси					Advanced	<u>'</u>										
Formulation					Program C	ontrolled										
Detection Method					Program C											
Penetration																
Tolerance					Program C	ontrolled										
Elastic Slip Tolerance					Program C	ontrolled										
Normal Stiffness					Program C	ontrolled										
Update					Program C	ontrolled										
Stiffness Pinball																
Region																
Contact	Geometric Modification															
Geometry	None															
Target Geometry Correction					Non	ne			None							

TABLE 16

Model (B4) > Connection	ne > Contacte > Co	ntact Pogione		
	Contact Region 67			
State		Defined		
State	Scope	Jellileu		
Scoping Method		Selection		
Contact		ace		
Target		ace		
Contact Bodies		nisa\Solid1		
Target Bodies		eno\Solid1		
	Definition			
Туре		nded		
Scope Mode	Auto	matic		
Behavior		Controlled		
Trim Contact	ntact Program Controlled			
Trim Tolerance	2.587e	-003 m		
Suppressed	N	lo		
	Advanced			
Formulation	Program	Controlled		
Detection Method	Program	Controlled		
Penetration Tolerance	Program	Controlled		
Elastic Slip Tolerance		Controlled		
Normal Stiffness	Program	Controlled		
Update Stiffness	Program	Controlled		
Pinball Region		Controlled		
	tric Modification			
Contact Geometry Correction		ne		
Target Geometry Correction	No	ne		

Mesh

TABLE 17

Mesh									
Mesh									
Solved									
Display									
Body Color									
Mechanical									
0									
Program Controlled									
Adaptive									
Fine									
Default									
Assembly									
Fast									
Coarse									

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Automatic Mesh Based Defeaturing	On
Defeature Size	Default
Minimum Edge Length	2.e-003 m
Quality	
Check Mesh Quality	Yes, Errors
Error Limits	Standard Mechanical
Target Quality	Default (0.050000)
Smoothing	Medium
Mesh Metric	None
Inflation	
Use Automatic Inflation	None
Inflation Option	Smooth Transition
Transition Ratio	0.272
Maximum Layers	5
Growth Rate	1.2
Inflation Algorithm	Pre
View Advanced Options	No
Advanced	
Number of CPUs for Parallel Part Meshing	Program Controlled
Straight Sided Elements	No
Number of Retries	Default (4)
Rigid Body Behavior	Dimensionally Reduced
Mesh Morphing	Disabled
Triangle Surface Mesher	Program Controlled
Topology Checking	No
Pinch Tolerance	Please Define
Generate Pinch on Refresh	No
Statistics	
Nodes	144010
Elements	41653

Static Structural (B5)

TABLE 18

Model (B4) > Analysis					
Object Name	Static Structural (B5)				
State Solved					
Definiti	on				
Physics Type	Structural				
Analysis Type	Static Structural				
Solver Target	Mechanical APDL				
Options					
Environment Temperature	22. °C				
Generate Input Only	No				

TABLE 19
Model (B4) > Static Structural (B5) > Analysis Settings

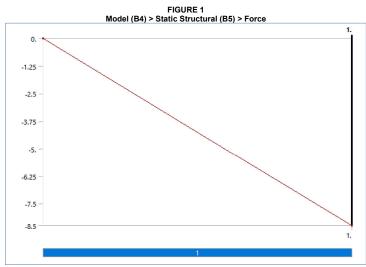
	Model (B4) > Static Structural (B5) > Analysis Settings				
Object Name	Analysis Settings				
State	Fully Defined				
Step Controls					
Number Of Steps	1.				
Current Step Number	1.				
Step End Time	1. s				
Auto Time Stepping	Program Controlled				
	Solver Controls				
Solver Type	Program Controlled				
Weak Springs	Off				
Solver Pivot Checking	Program Controlled				
Large Deflection	Off				
Inertia Relief	Off				
	Rotordynamics Controls				
Coriolis Effect	Off				
	Restart Controls				
Generate Restart Points	Program Controlled				
Retain Files After Full Solve	No				
Combined Restart Files	Program Controlled				
	Nonlinear Controls				
Newton-Raphson Option	Program Controlled				
Force Convergence	Program Controlled				
Moment Convergence	Program Controlled				
Displacement Convergence	Program Controlled				
Rotation Convergence	Program Controlled				
Line Search	Program Controlled				
Stabilization	Off				
	Output Controls				
Stress	Yes				
Strain	Yes				
Nodal Forces	No				
Contact Miscellaneous	No				
General Miscellaneous	No				
Store Results At	All Time Points				
	Analysis Data Management				
Solver Files Directory	C:\Users\jesus\AppData\Local\Temp\WB_LSKJCGM_jesus_11052_2\unsaved_project_files\dp0\SYS\MECH				
Future Analysis	None				
Scratch Solver Files Directory					
Save MAPDL db	No				
Delete Unneeded Files	Yes				

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Nonlinear Solution	No
Solver Units	Active System
Solver Unit System	mks

TABLE 20

Model (B4) > Static Structural (B5) > Loads					
Object Name	Fixed Support Force Force 2 Force 3				
State	Fully Defined				
	Sco	оре			
Scoping Method	Geometry Selection				
Geometry	1 Face				
	Defir	nition			
Туре	Fixed Support		For	ce	
Suppressed			No		
Define By	Vector			tor	
Magnitude	-8.5 N (ramped) 12. N (ramped)				
Direction	Defined				



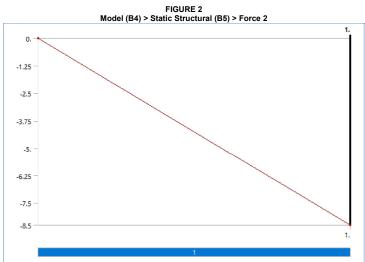
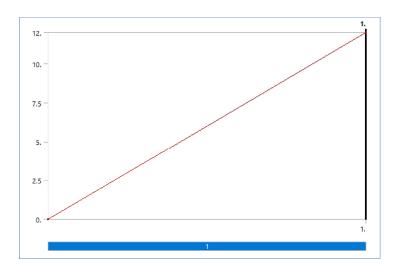


FIGURE 3 Model (B4) > Static Structural (B5) > Force 3

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Solution (B6)

TABLE 21 Model (B4) > Static Structural (B5) > Solution

Solution (B6)	
Solved	
finement	
1.	
2.	
n	
Done	
31. s	
2.4785 GB	
46.563 MB	
ing	
No	

TABLE 22

Model (B4) > Static Structural (B5) > Solution (B6) > Solution Information

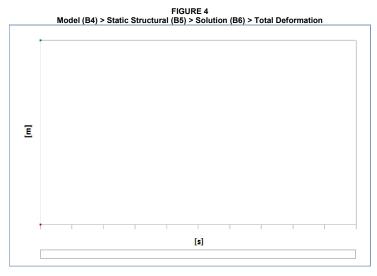
Object Name | Solution Information

Solution Information
Solved
ation
Solver Output
0
0
2.5 s
All
isibility
Yes
All FE Connectors
All Nodes
Connection Type
No
Single
Lines

TABLE 23

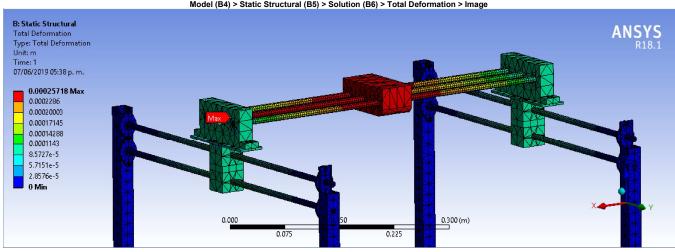
Model (B4) > Static Structural (B5) > Solution (B6) > Results					
Object Name	Total Deformation	Equivalent Elastic Strain	Equivalent Stress		
State	Solved				
		Scope			
Scoping Method		Geometry Selection	on		
Geometry		All Bodies			
		Definition			
Туре	Total Deformation	Equivalent Elastic Strain	Equivalent (von-Mises) Stress		
Ву		Time			
Display Time		Last			
Calculate Time History		Yes			
Identifier					
Suppressed		No			
		Results			
Minimum	0. m	0. m/m	0. Pa		
Maximum	2.5718e-004 m	4.45e-004 m/m	1.1956e+007 Pa		
Minimum Occurs On		CNC_base2\Solid	11		
Maximum Occurs On	CNC_husillo\Solid1	CNC_soporte\Solid1	CNC_husillo\Solid1		
		Information			
Time		1. s			
Load Step		1			
Substep	Substep 1				
Iteration Number 1					
Integration Point Results					
Display Option	Display Option Averaged				
Average Across Bodies No					

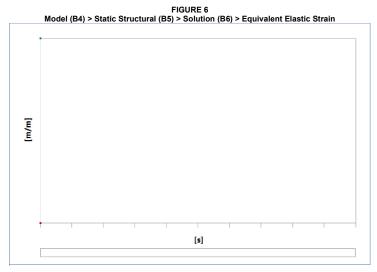
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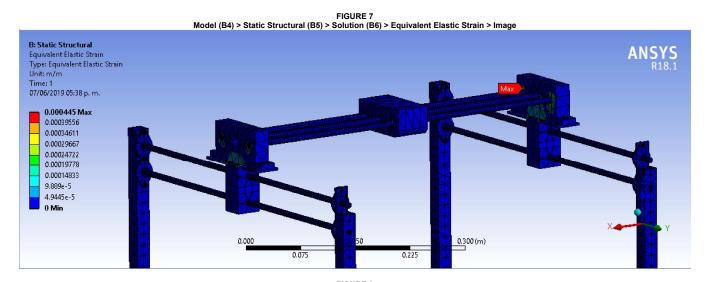
| TABLE 24 | Model (B4) > Static Structural (B5) > Solution (B6) > Total Deformation | Time [s] | Minimum [m] | Maximum [m] | 1. | 0. | 2.5718e-004 |

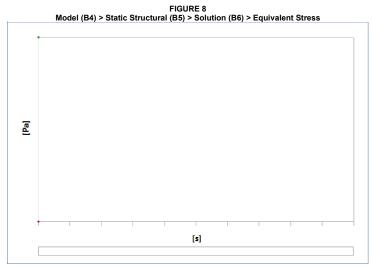
FIGURE 5
Model (B4) > Static Structural (B5) > Solution (B6) > Total Deformation > Image

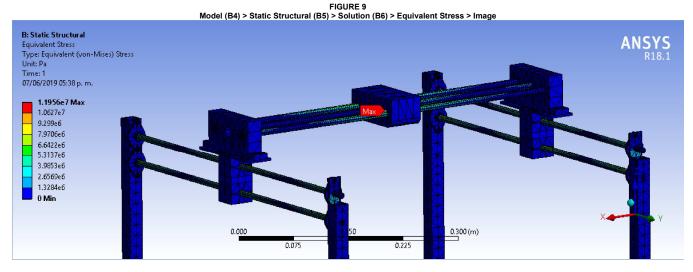




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Material Data

Polyethylene

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> TABLE 27 Polyethylene > Constants

Density	950 kg m^-3
Isotropic Secant Coefficient of Thermal Expansion	2.3e-004 C^-1
Specific Heat	2300 J kg^-1 C^-1
Isotropic Thermal Conductivity	0.28 W m^-1 C^-1

TABLE 28 Polyethylene > Appearance
Red Green Blue 130 154 176

TABLE 29

Polyethylene > Compressive Ultimate Strength

Compressive Ultimate Strength Pa

TABLE 30

Polyethylene > Compressive Yield Strength

Compressive Yield Strength Pa 0

TABLE 31
Polyethylene > Tensile Yield Strength

Tensile Yield Strength Pa 2.5e+007

TABLE 32

Polyethylene > Tensile Ultimate Strength
Tensile Ultimate Strength Pa 3.3e+007

TABLE 33

Polyethylene > Isotropic Secant Coefficient of Thermal Expansion

Zero-Thermal-Strain Reference Temperature C 22

TABLE 34

Polyethylene > Isotropic Elasticity

Temperature C Young's Modulus Pa Poisson's Ratio Bulk Modulus Pa Shear Modulus Pa 1.1e+009 0.42 2.2917e+009 3.8732e+008

Structural Steel

TABLE 35 Structural Steel > Constants

Density	7850 kg m^-3
Isotropic Secant Coefficient of Thermal Expansion	1.2e-005 C^-1
Specific Heat	434 J kg^-1 C^-1
Isotropic Thermal Conductivity	60.5 W m^-1 C^-1
Isotronic Resistivity	1 7e-007 ohm m

TABLE 36 Structural Steel > Appearance Red Green Blue

132 139 179

Structural Steel > Compressive Ultimate Strength
Compressive Ultimate Strength Pa

TABLE 38

Structural Steel > Compressive Yield Strength
Compressive Yield Strength Pa

2.5e+008

TABLE 39

Structural Steel > Tensile Yield Strength

Tensile Yield Strength Pa 2.5e+008

TABLE 40
Structural Steel > Tensile Ultimate Strength
Tensile Ultimate Strength Pa

4.6e+008

TABLE 41

Structural Steel > Isotropic Secant Coefficient of Thermal Expansion

Zero-Thermal-Strain Reference Temperature C 22

TABLE 42

Structural Steel > Alternating Stress Mean Stress

Alternating Stress Pa Cycles Mean Stress Pa 3.999e+009 10 2.827e+009 20 0 1.896e+009 50 0 100 1.413e+009 0 1.069e+009 200

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4.41e+008	2000	0
2.62e+008	10000	0
2.14e+008	20000	0
1.38e+008	1.e+005	0
1.14e+008	2.e+005	0
8.62e+007	1.e+006	0

TABLE 43 Structural Steel > Strain-Life Parameters

Strength Coefficient Pa	Strength Exponent	Ductility Coefficient	Ductility Exponent	Cyclic Strength Coefficient Pa	Cyclic Strain Hardening Exponent
9.2e+008	-0.106	0.213	-0.47	1.e+009	0.2

TABLE 44

Structural Steel > Isotropic Elasticity

Temperature C	Young's Modulus Pa	Poisson's Ratio	Bulk Modulus Pa	Shear Modulus Pa
	2.e+011	0.3	1.6667e+011	7.6923e+010

TABLE 45

Structural Steel > Isotropic Relative Permeability

Relative Permeability 10000

Aluminum Alloy

TABLE 46

Aluminum Alloy > Constants

Density	2770 kg m^-3
Isotropic Secant Coefficient of Thermal Expansion	2.3e-005 C^-1
Specific Heat	875 J kg^-1 C^-1

TABLE 47

Aluminum Alloy > Appearance
Red Green Blue

138 104 46

TABLE 48
Aluminum Alloy > Compressive Ultimate Strength
Compressive Ultimate Strength Pa

TABLE 49

Aluminum Alloy > Compressive Yield Strength

Compressive Yield Strength Pa

2.8e+008

TABLE 50

Aluminum Alloy > Tensile Yield Strength
Tensile Yield Strength Pa

2.8e+008

TABLE 51 Aluminum Alloy > Tensile Ultimate Strength

Tensile Ultimate Strength Pa 3.1e+008

TABLE 52

Aluminum Alloy > Isotropic Secant Coefficient of Thermal Expansion

Zero-Thermal-Strain Reference Temperature C

TABLE 53
Aluminum Alloy > Isotropic Thermal Conductivity

Thermal Conductivity W m^-1 C^-1	Temperature C
114	-100
144	0
165	100
175	200

TABLE 54

Aluminum Alloy > Alternating Stress R-Ratio

Alternating Stress Pa	Cycles	R-Ratio
2.758e+008	1700	-1
2.413e+008	5000	-1
2.068e+008	34000	-1
1.724e+008	1.4e+005	-1
1.379e+008	8.e+005	-1
1.172e+008	2.4e+006	-1
8.963e+007	5.5e+007	-1
8.274e+007	1.e+008	-1
1.706e+008	50000	-0.5
1.396e+008	3.5e+005	-0.5
1.086e+008	3.7e+006	-0.5
8.791e+007	1.4e+007	-0.5
7.757e+007	5.e+007	-0.5
7.239e+007	1.e+008	-0.5
1.448e+008	50000	0
1.207e+008	1.9e+005	0
1.034e+008	1.3e+006	0
9.308e+007	4.4e+006	0

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8.618e+007	1.2e+007	0
7.239e+007	1.e+008	0
7.412e+007	3.e+005	0.5
7.067e+007	1.5e+006	0.5
6.636e+007	1.2e+007	0.5
6.205e+007	1.e+008	0.5

TABLE 55 Aluminum Alloy > Isotropic Resistivity

Resistivity ohm m	Temperature C
2.43e-008	0
2.67e-008	20
3.63e-008	100

TABLE 56

Aluminum Alloy > Isotropic Elasticity

Temperature C	Young's Modulus Pa	Poisson's Ratio	Bulk Modulus Pa	Shear Modulus Pa
	7.1e+010	0.33	6.9608e+010	2.6692e+010

TABLE 57

Aluminum Alloy > Isotropic Relative Permeability

Relative Permeability

Stainless Steel

TABLE 58

Stainless Steel > Constants

Density	7750 kg m^-3
Isotropic Secant Coefficient of Thermal Expansion	1.7e-005 C^-1
	480 J kg^-1 C^-1
Isotropic Thermal Conductivity	15.1 W m^-1 C^-1
Isotropic Resistivity	7 7e-007 ohm m

TABLE 59

Stainless Steel > Appearance Red Green Blue 176 154 176

TABLE 60 Stainless Steel > Compressive Ultimate Strength

Compressive Ultimate Strength Pa

TABLE 61 Stainless Steel > Compressive Yield Strength Compressive Yield Strength Pa

2.07e+008

TABLE 62

Stainless Steel > Tensile Yield Strength
Tensile Yield Strength Pa
2.07e+008

TABLE 63

Stainless Steel > Tensile Ultimate Strength

Tensile Ultimate Strength Pa 5.86e+008

TABLE 64 Stainless Steel > Isotropic Secant Coefficient of Thermal Expansion

Zero-Thermal-Strain Reference Temperature C

TABLE 65

Stainless Steel > Isotropic Elasticity

Temperature C	Young's Modulus Pa	Poisson's Ratio	Bulk Modulus Pa	Shear Modulus Pa
	1.93e+011	0.31	1.693e+011	7.3664e+010

TABLE 66

Stainless Steel > Isotropic Relative Permeability

Relative Permeability