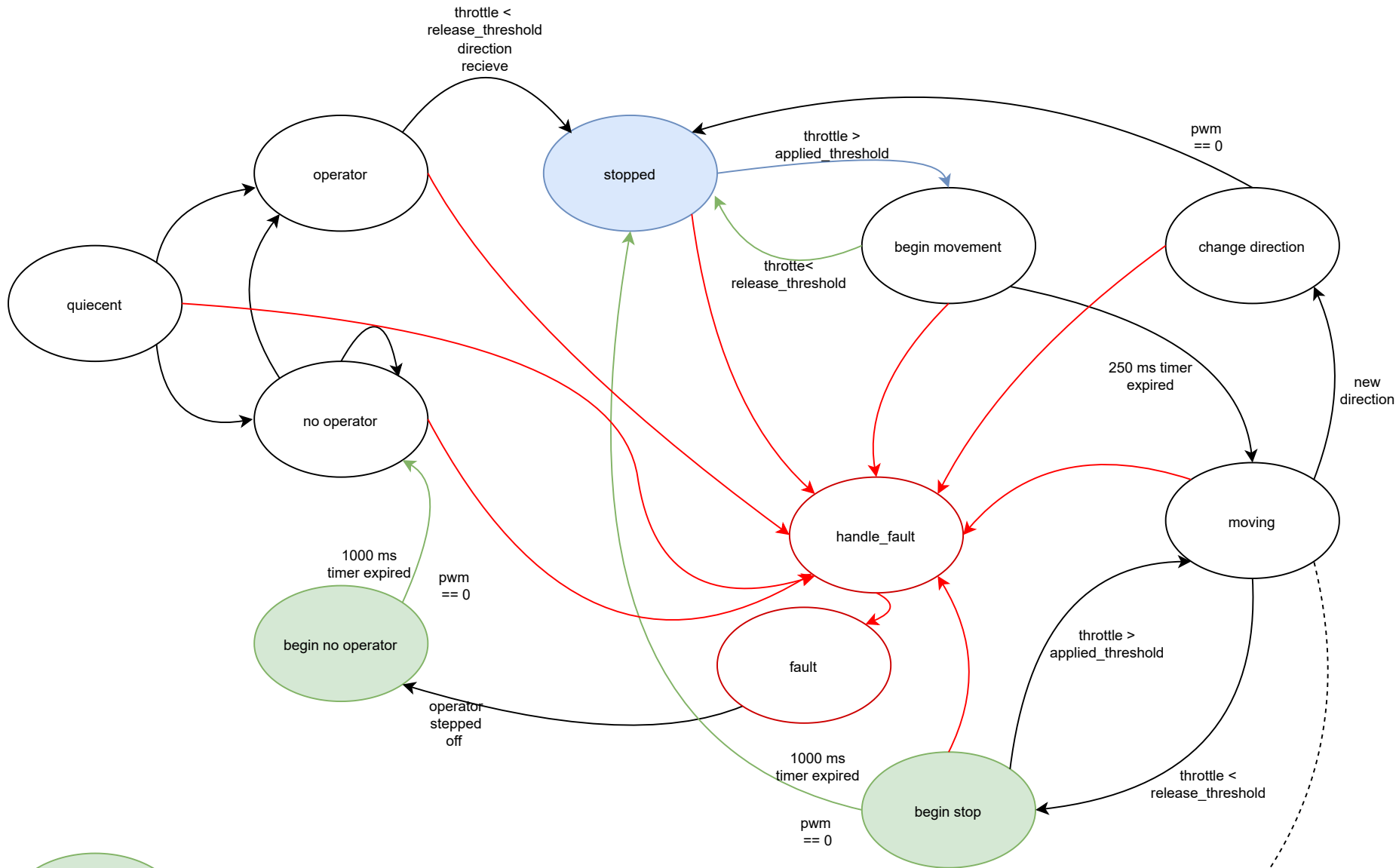


release\_threshold = 10  
applied\_threshold = 15



setting brake when exiting the state

releasign the brake when exiting the state

operator detection, over temperature, cover removed, tipping detection, low battery, over current, E-stop, apply break after 1 second delay. do not apply break if the operator jumped off the machine

motor	ECO	Normal	Transport	direction change
side brush	80%	100%	0	no change
brush	80%	100%	0	no change
Vacuum	80%	100%	0	no change
Traction	100%	80%	100%	0
Deck	down	down	up	no change