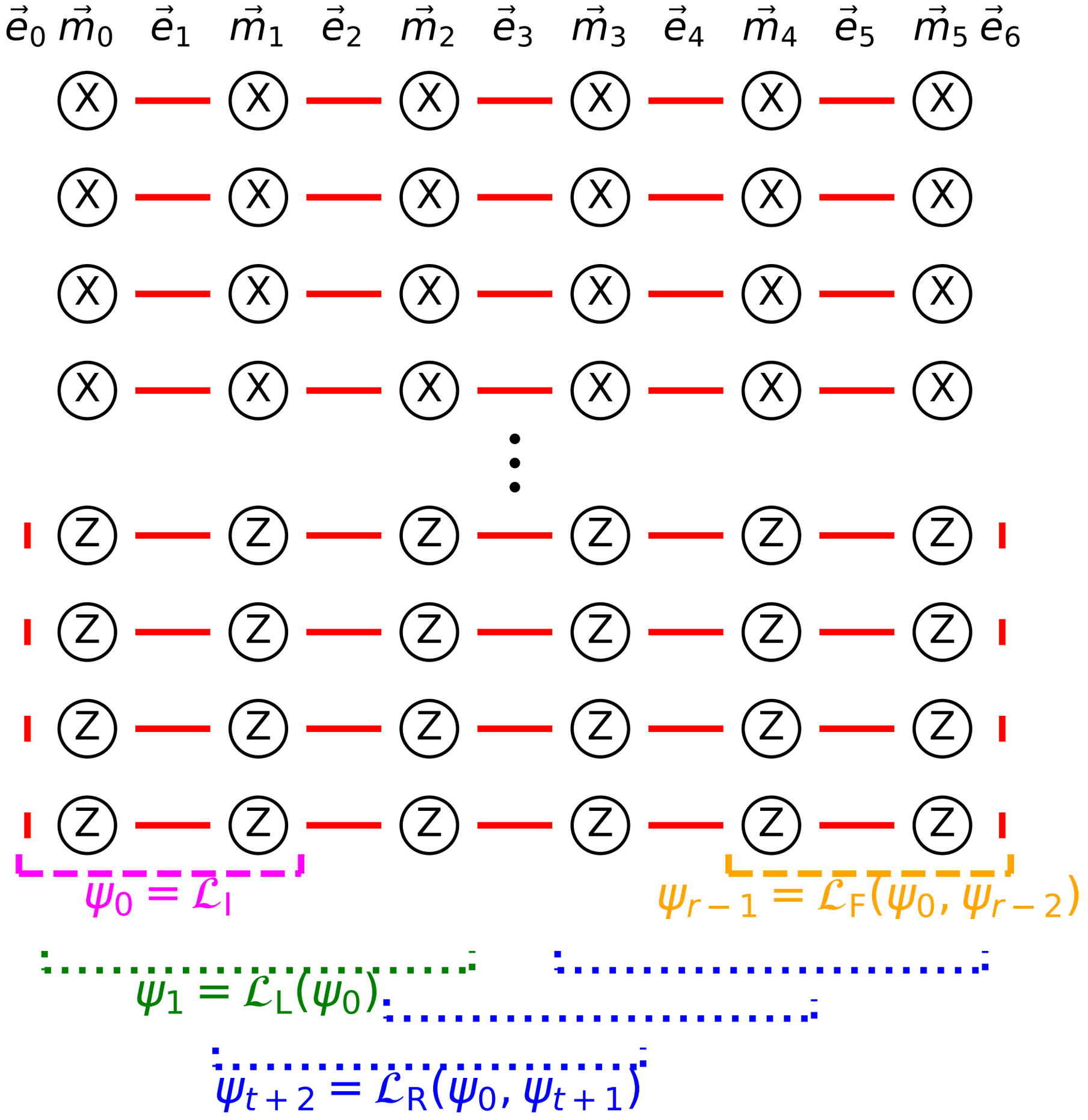
$\vec{e}_0$ $\vec{m}_0$ $\vec{e}_1$ $\vec{m}_1$ $\vec{e}_2$ $\vec{m}_2$ $\vec{e}_3$ $\vec{m}_3$ $\vec{e}_4$ $\vec{m}_4$ $\vec{e}_5$ $\vec{m}_5$ $\vec{e}_6$
X
Z
$\psi_0 = \mathcal{L}_{\mathrm{I}}$
$\psi_{r-1} = \mathcal{L}_{\mathrm{F}}(\psi_0, \psi_{r-2})$
$\psi_1 = \mathcal{L}_{\mathrm{L}}(\psi_0)$
$\psi_{t+2} = \mathcal{L}_{\mathrm{R}}(\psi_0, \psi_{t+1})$