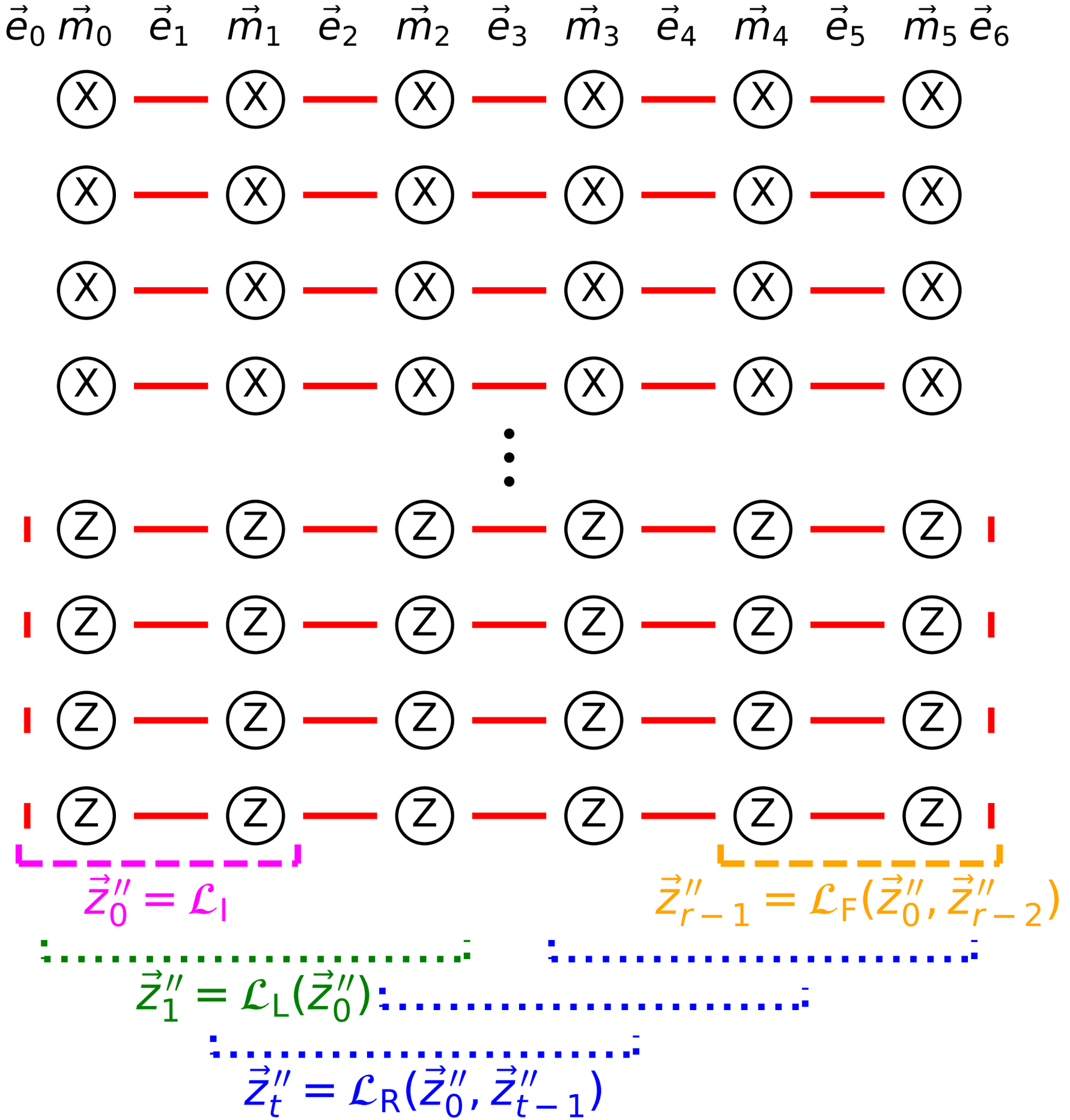
$\vec{e}_0$ $\vec{m}_0$ $\vec{e}_1$ $\vec{m}_1$ $\vec{e}_2$ $\vec{m}_2$ $\vec{e}_3$ $\vec{m}_3$ $\vec{e}_4$ $\vec{m}_4$ $\vec{e}_5$ $\vec{m}_5$ $\vec{e}_6$
X
Z
$\vec{z}''_0 = \mathcal{L}_{\mathrm{I}}$
$\vec{z}''_{r-1} = \mathcal{L}_{\mathrm{F}}(\vec{z}''_0, \vec{z}''_{r-2})$
$\vec{z}''_1 = \mathcal{L}_{\mathrm{L}}(\vec{z}''_0)$
$\vec{z}''_t = \mathcal{L}_{\mathrm{R}}(\vec{z}''_0, \vec{z}''_{t-1})$