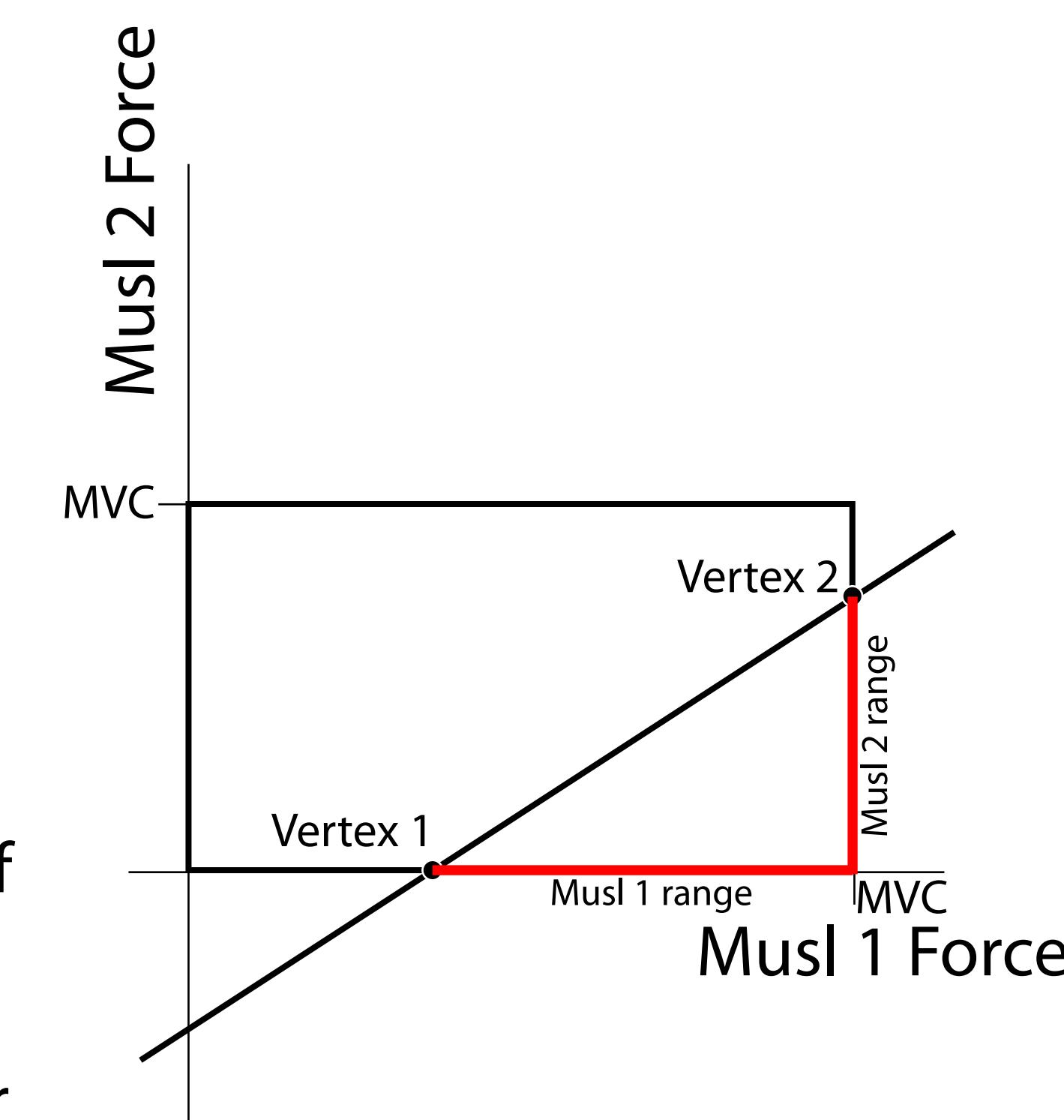
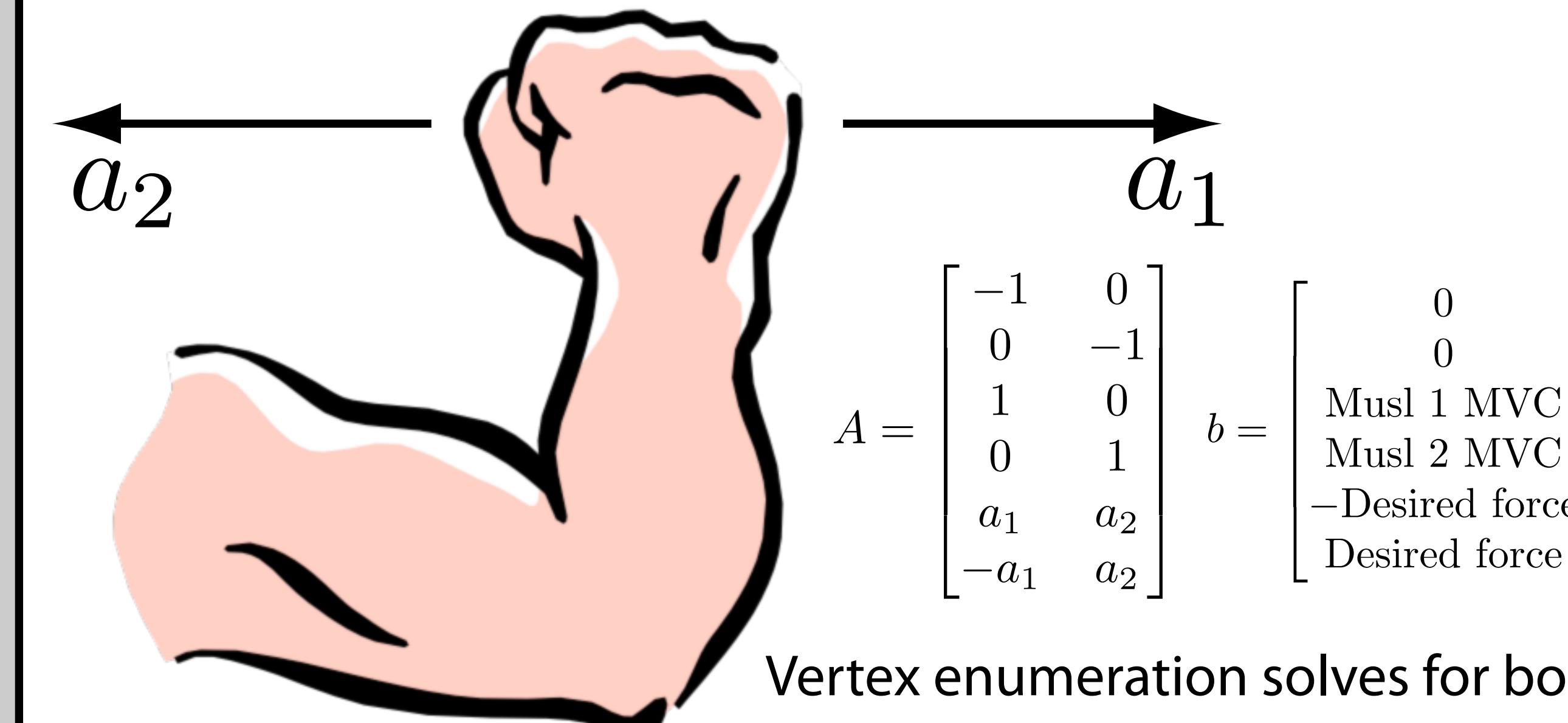
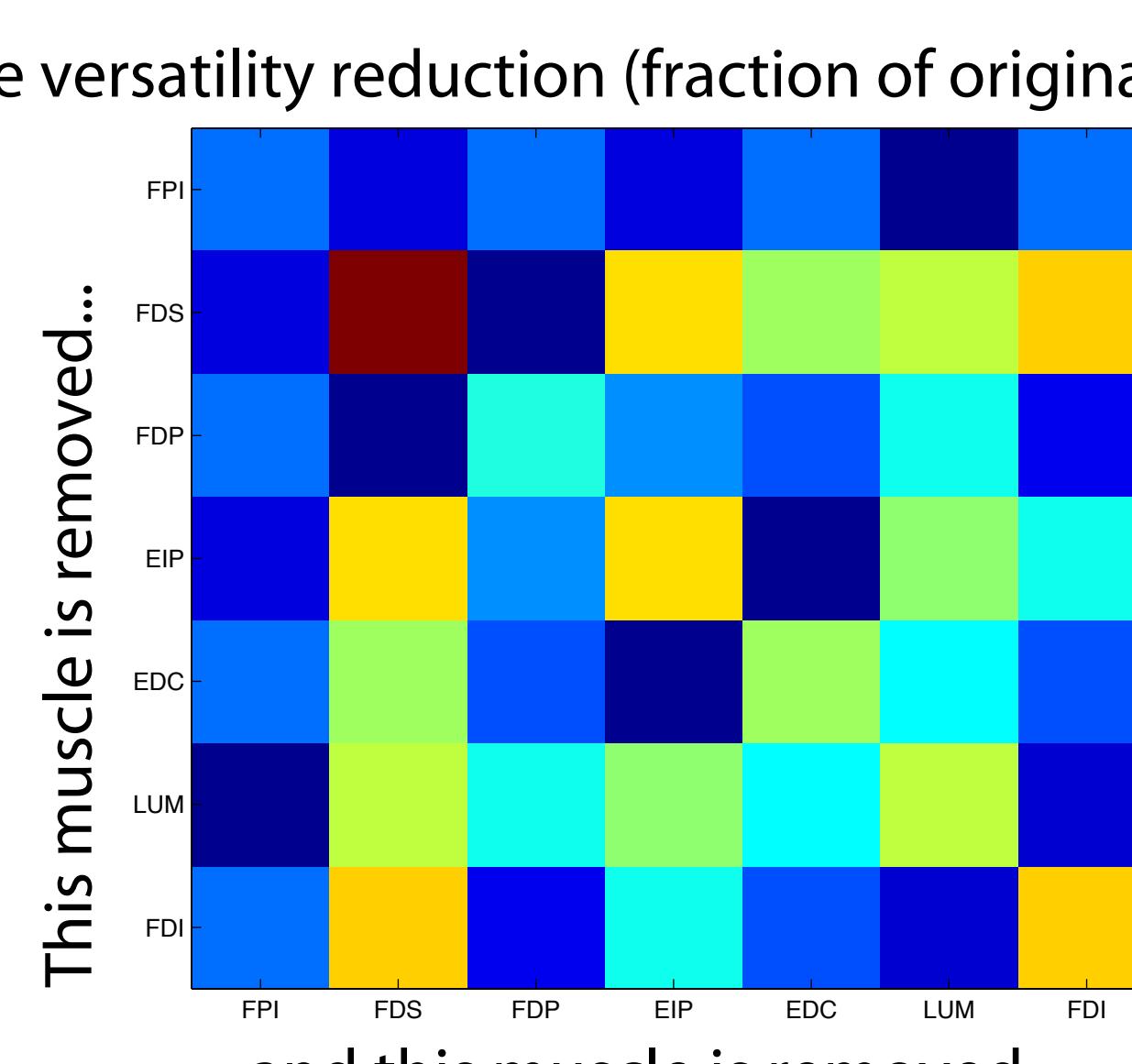
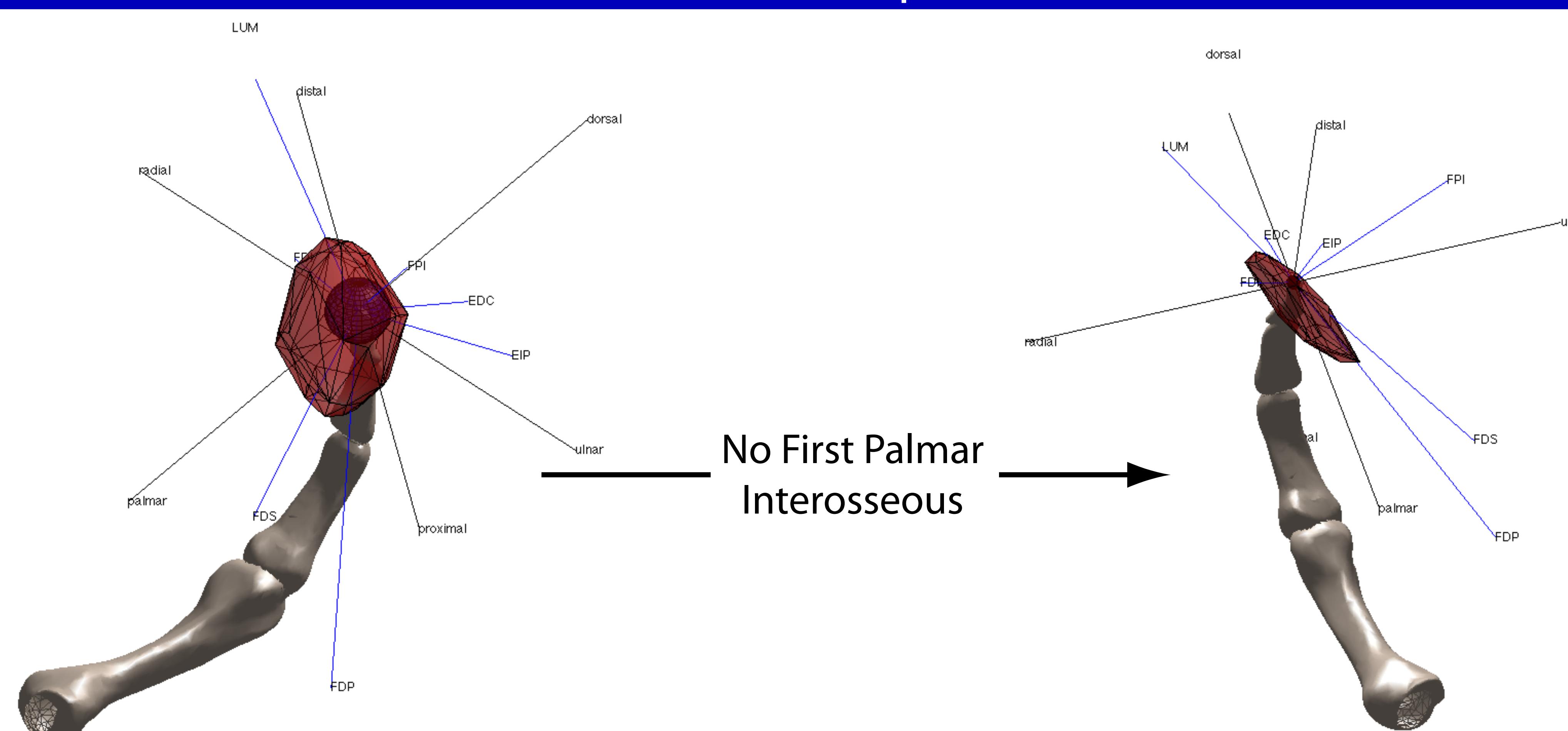
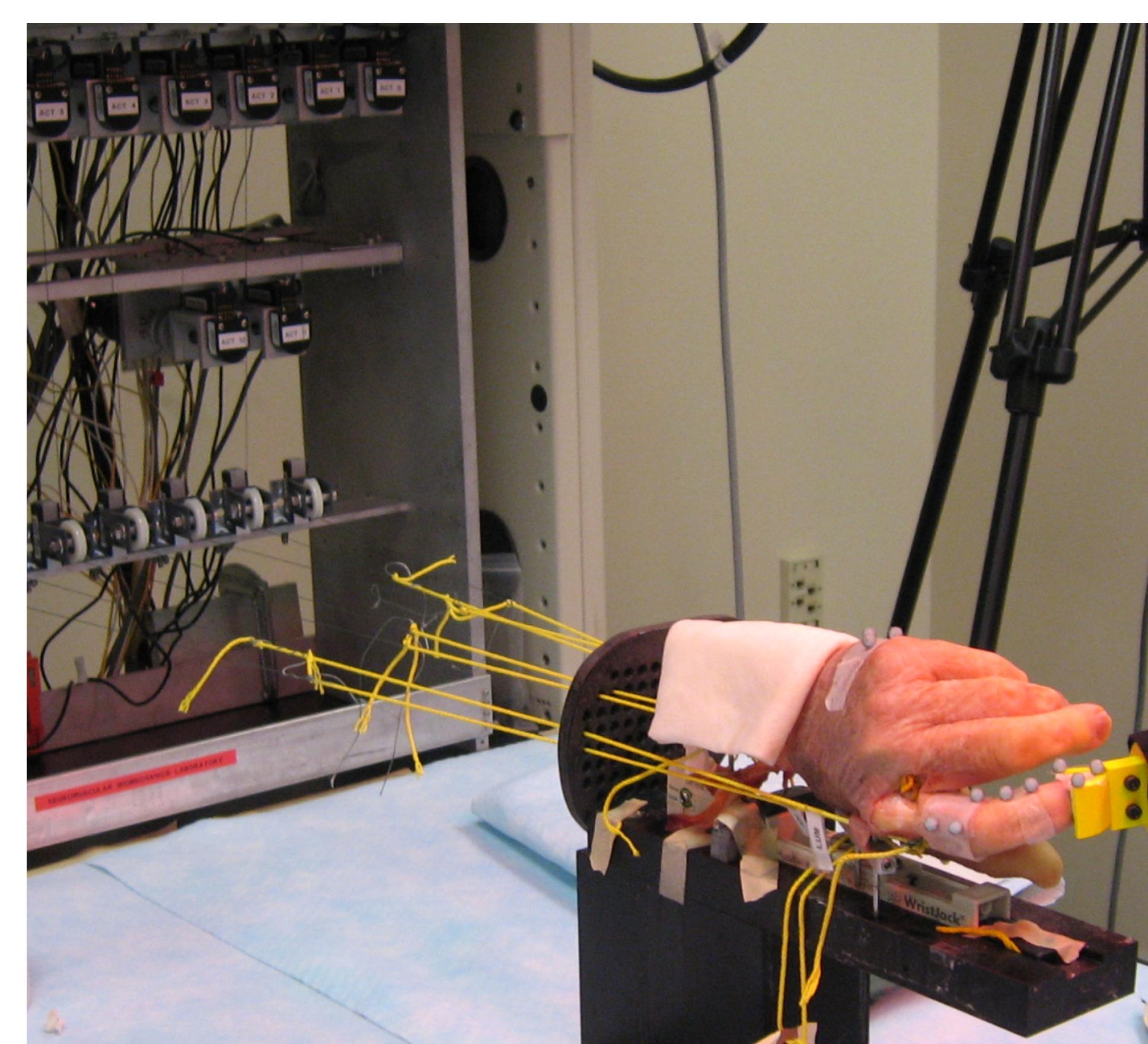


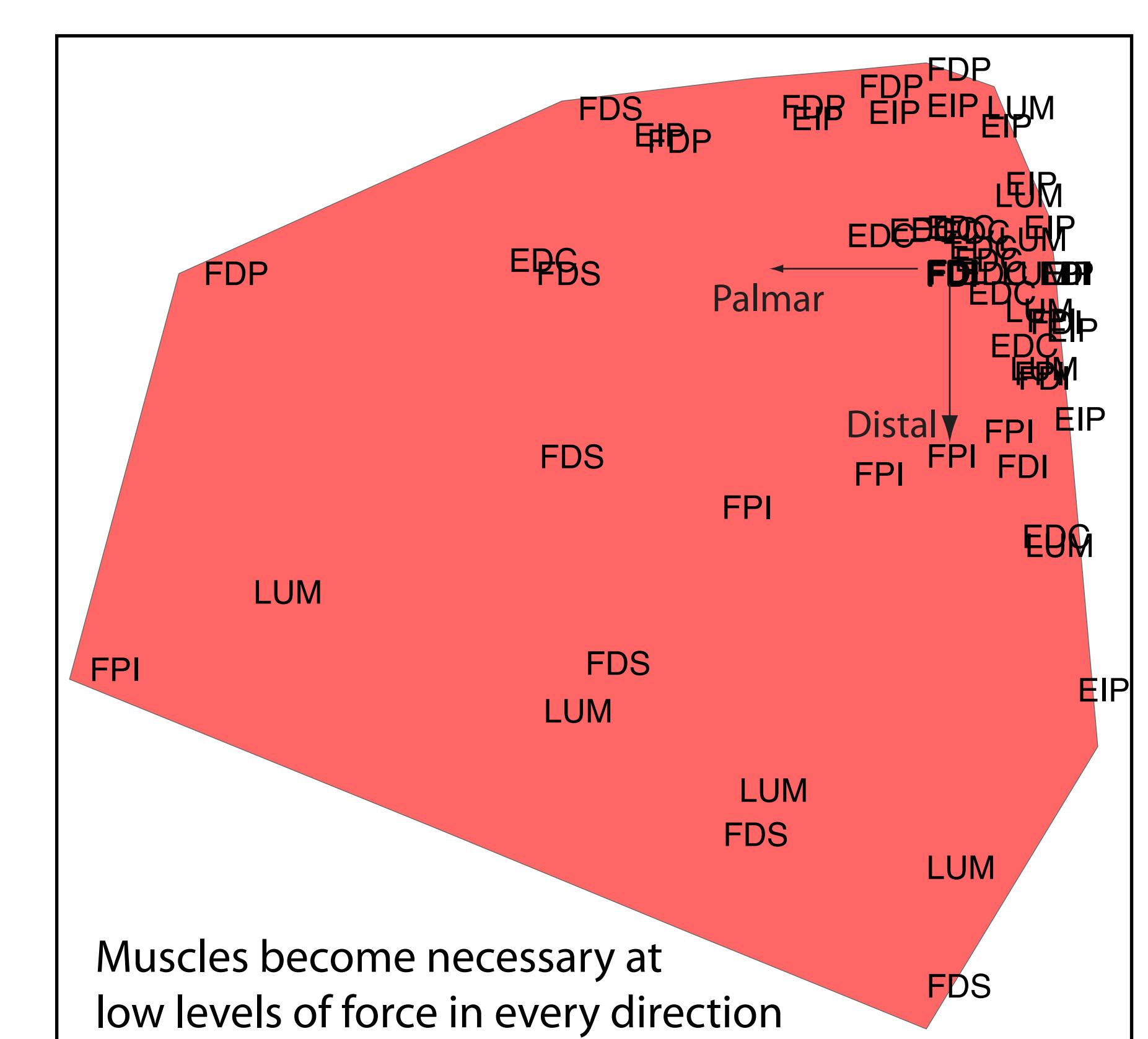
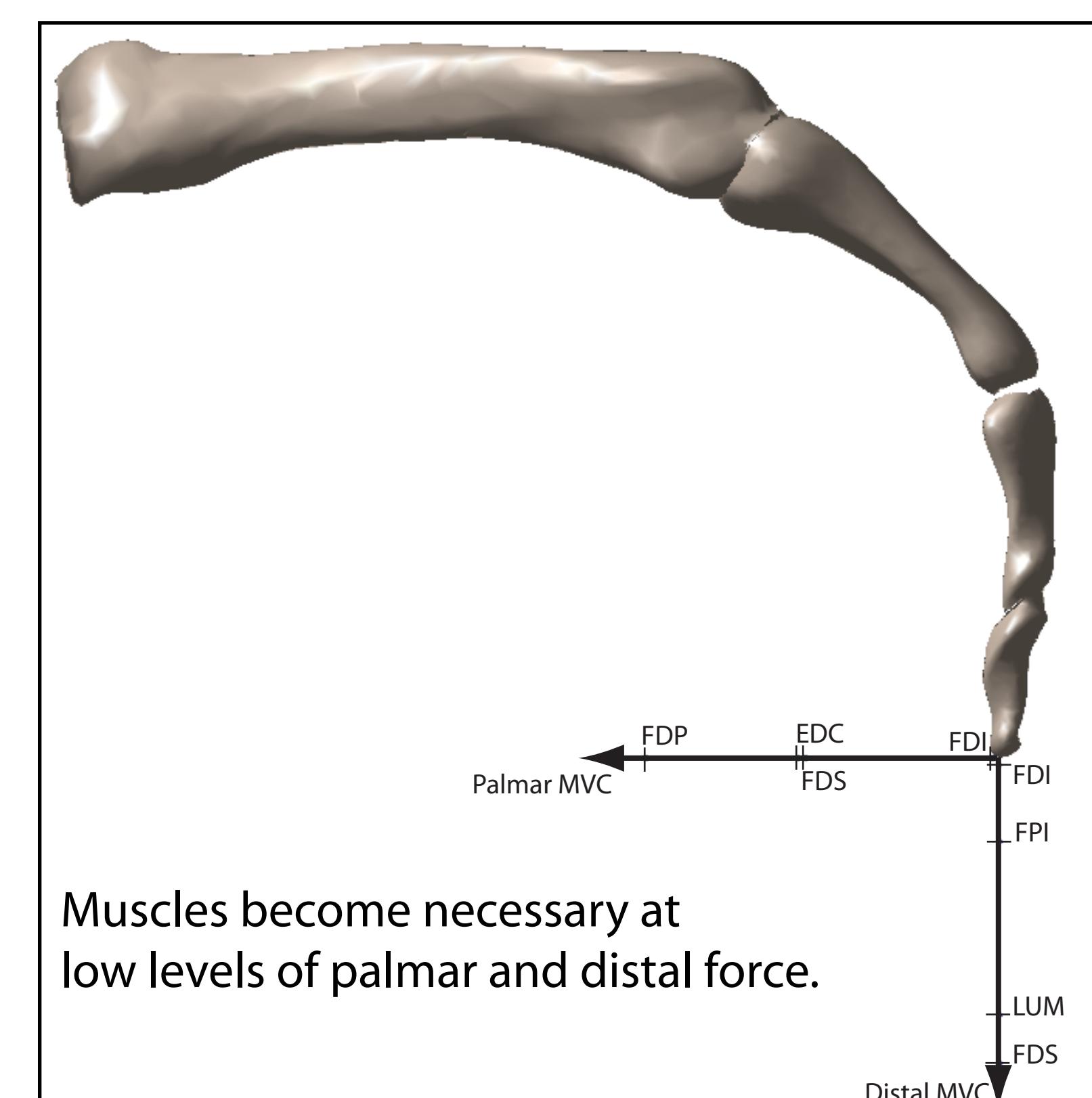
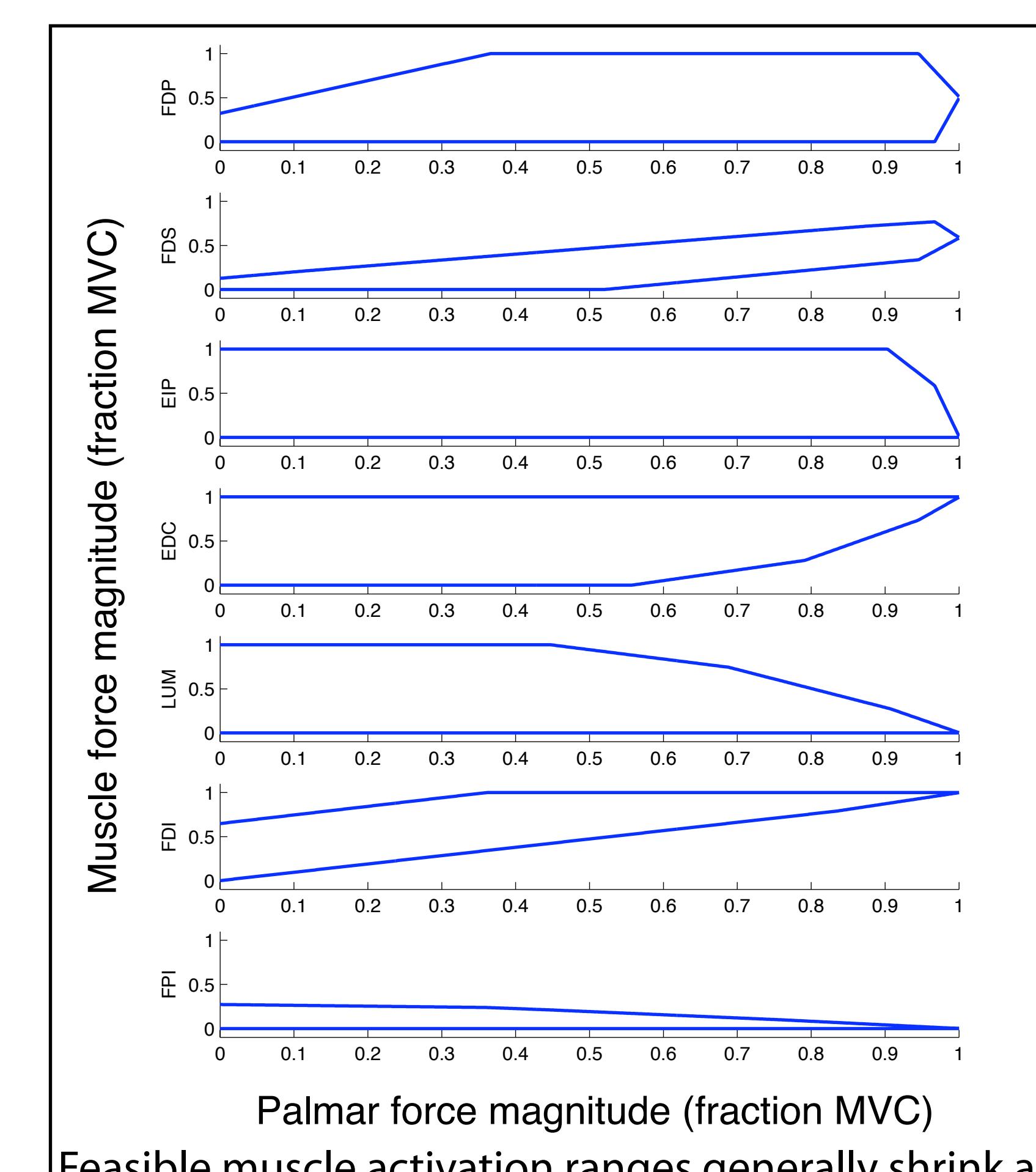
1. If you lose a muscle, the other muscles can compensate
 2. There is an infinite number of different combinations of muscle forces that will produce the same joint torque



1. Fresh cadaver arm resected at mid-forearm, dissected to reveal tendons for index finger.
 2. Tendon tensions computer controlled.
 3. Index fingertip attached rigidly to 6 DOF load cell (JR3, Woodland, CA).
 4. Feasible force set measured using all possible combinations of active and inactive muscles:
Input 1: [1,0,0,0,0,0] : Record JR3 reading
Input 2: [0,1,0,0,0,0] : Record JR3 reading
...
Input 7: [0,0,0,0,0,1] : Record JR3 reading
Input 8: [1,1,0,0,0,0] : Record JR3 reading
...
Input 127: [1,1,1,1,1,1] : Record JR3 reading



1. FDI necessary for even the smallest forces
 2. EDC/FDS required for >50% palmar force
 3. FPI required for >30% distal force
 4. Feasible activation ranges usually shrink for all muscles as force magnitude increases.
 5. Different muscles become necessary in different force directions.



1. Just because the number of muscles exceeds the number of degrees of freedom doesn't mean that muscles are redundant.
 2. Redundancy depends on musculoskeletal geometry - must be quantified.
 3. The CNS may not have as much latitude in choosing muscle activations as is usually assumed.
 4. The muscular system is not robust to muscle weakness.

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