

Mitigating disruption to voluntary movement caused by velocity-dependent stretch reflex via α -MN collateral projection to γ -MNs: A simulation study

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INTRODUCTION

Spindle afferents provide proprioceptive feedback signals that inform the CNS about the position and movement of the body [1]; And, thus, are thought to be important for kinesthesia, posture, and balance control [1-4]. However, their function during voluntary movement is not fully understood [5].

The velocity-dependent stretch reflexes (i.e., Ia afferents) in lengthening muscles (i.e., 'antagonist' in the single-joint system) can, if not modulated, disrupt or stop joint rotations induced by the shortening muscles (i.e., 'agonists' in the single-joint system) compromise movement accuracy [6-7].

It remains an open question, however, the extent to which velocity-dependent stretch reflexes disrupt voluntary movement, and whether and how they should be inhibited in limbs with numerous mono- and multi-articular muscles

GOAL

Investigate (i) how velocity-dependent stretch reflexes perturb limb movements in the general case of numerous multi-articular muscles, and (ii) whether modulation of velocity-dependent stretch reflex gain can mitigate these disruptions.

METHODS

I. Open-loop and closed-loop simulations with unmodulated reflex gain

We used a 25-Hill-type muscles computational model of Rhesus Macaque arm [8] to simulate (i) 1,100 open-loop movements with feedforward alpha-MN commands only (Fig. 1A) and (ii) their closed-loop simulation by adding unmodulated positive homonymous muscle velocity feedback (i.e., velocity-dependent stretch reflex) (Fig. 1B).

II. Closed-loop simulations with modulated reflex gain

We modulated stretch reflex gain as per **idealized α - γ co-activation** (Fig. 2A) and by **scaling the gain by the homologous α -drive to γ -MNs** via an α -MN collateral [9-13] (Fig. 2B)

Analysis

We quantified disruption (Fig. 3) to the open-loop movements endpoint trajectories (i.e., cumulative residual) and final position (i.e., terminal error) of the hand, and the effect on the disruptions when stretch reflex gain was modulated.

RESULTS

I. Unmodulated velocity-dependent stretch reflexes cause large, variable disruptions of the endpoint trajectories in task-dependent ways

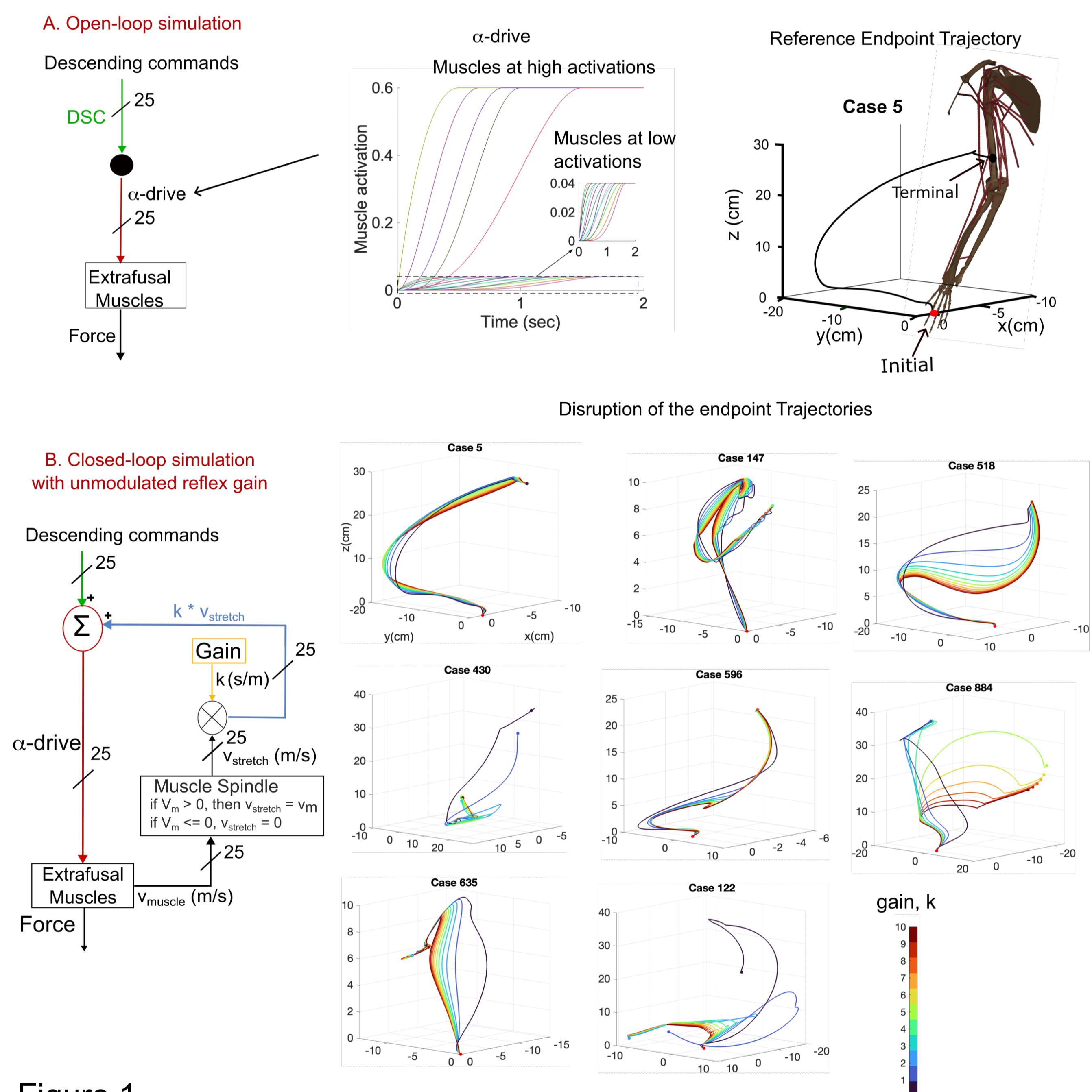


Figure 1

RESULTS (cont.).

III. Over all 1,100 arm movement, the cumulative residual and terminal error were large at higher reflex gains and became significantly reduced when modulating reflex gain as per **idealized α - γ co-activation** (B) and via **homologous α -MN collateral drive** (C). However, in a few movements (Cases. 705, 785, 1009, 827, 51, 159, 675) the disruptions were relatively larger.

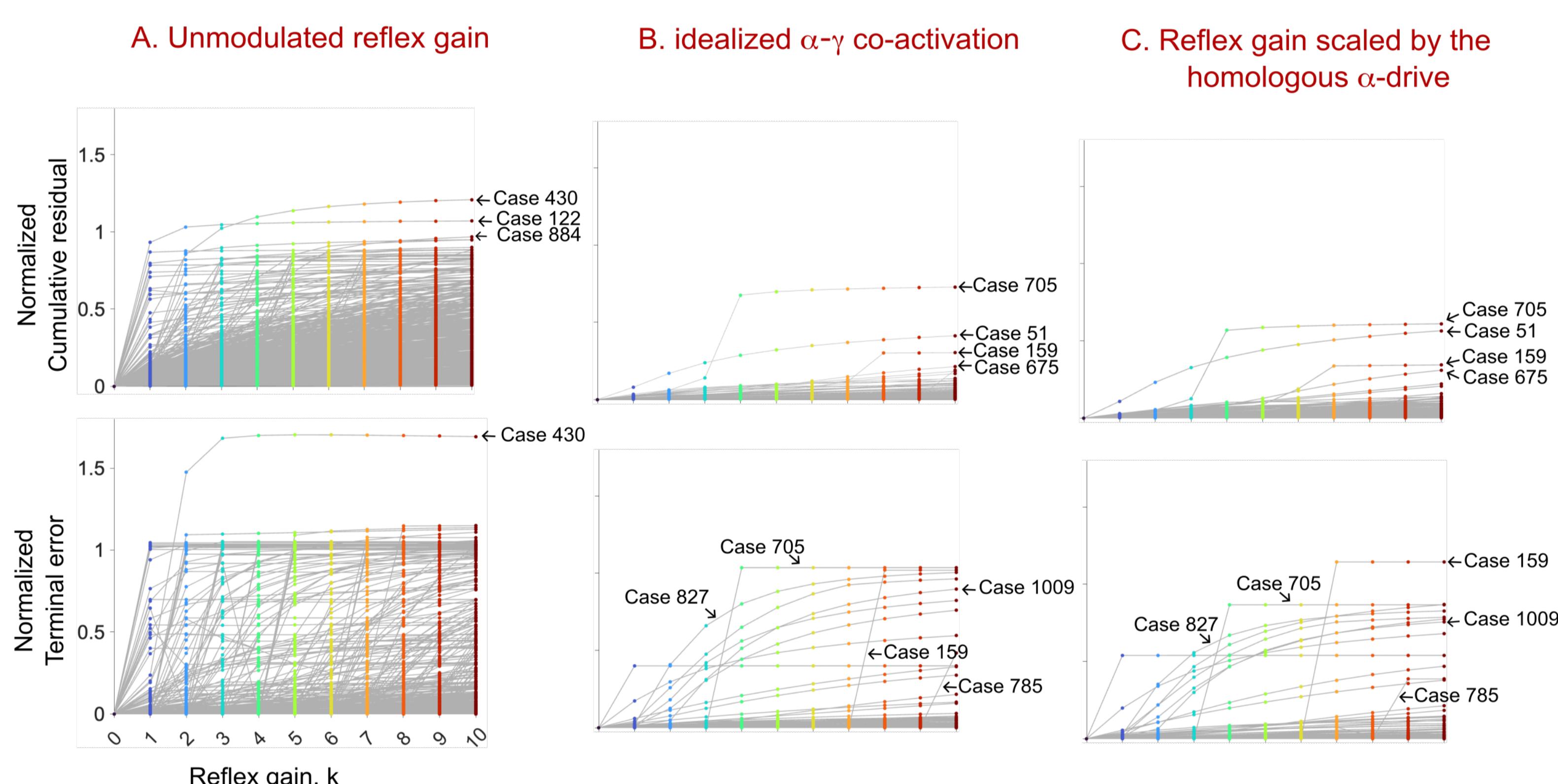


Figure 3

DISCUSSION

- Our results show that the disruptions of the movements caused by the velocity-dependent stretch reflexes are large, variable, and task-dependent enough to need inhibition, as has been proposed, but never quantified, by Sherrington [13] and others [7, 14, 15].

- Both idealized α - γ co-activation and an excitatory collateral from α -MN axon to γ -MNs can effectively mitigate the disruptions caused by unmodulated velocity-dependent stretch reflex.

- α - γ co-activation hinge on the assumption that the system has sufficiently accurate knowledge of the time-varying variables that determine musculotendon lengths and velocities. However, time delays and uncertainty can conspire to pollute such estimates if they rely on the supra-spinal processing of sensory signals to estimate body state or create appropriate motor actions.

- Our proposed mechanism simply scales velocity-dependent stretch reflex by an excitatory α -MN collateral. Such collateral projection among MNs have long been observed in studies of the cat and mouse spinal cord [9-13]. This mechanism is an alternative to α - γ co-activation that is evolutionary and physiologically plausible at the level of a homologous α -to- γ collateral.

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