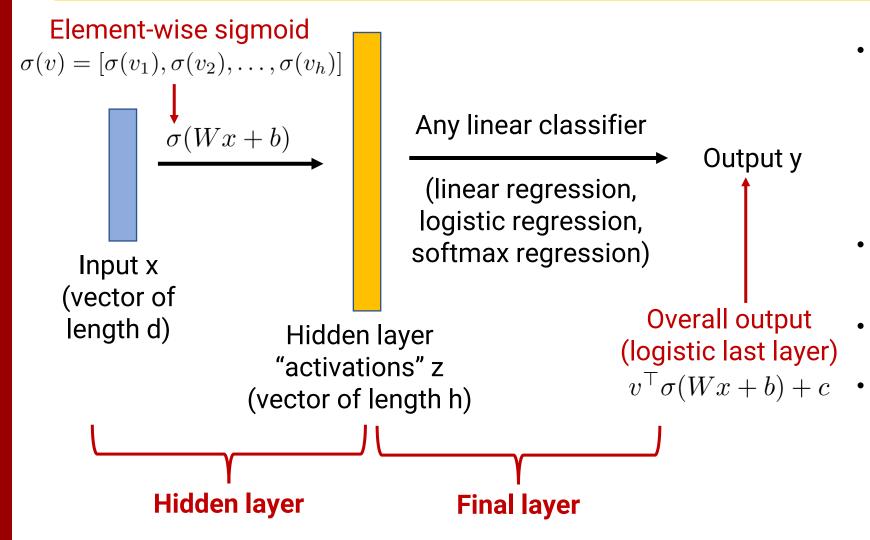
Neural Networks II: Backpropagation

Robin Jia USC CSCI 467, Fall 2023 September 26, 2023

Recap: Neural Networks



- Hidden layer: A bunch of logistic regression classifiers
 - Parameters: w_j and b_j for each classifier
 - Equivalently: matrix W (h x d) and vector b (length h)
 - Produces "activations" = learned feature vector
- Final layer: A linear classifier
 - E.g. if logistic regression, has parameter vector *v* and bias *c*
- Parameters of model are $\theta = (W, b, v, c)$
- One neural network is built of many basic mathematical operations put together
 - Sum, product, exponentiation, etc.

Recap: Stochastic gradient descent

Goal: Find parameters
$$\theta$$
 that minimize $\frac{1}{n}\sum_{i=1}^n\ell\left(y^{(i)},g(x^{(i)})\right)$ Model's output, depends on parameters θ

Gradient Descent

$$\theta \leftarrow \theta - \eta \cdot \frac{1}{n} \sum_{i=1}^{n} \nabla_{\theta} \ell \left(y^{(i)}, g(x^{(i)}) \right)$$

Average of per-example gradients

- Intuition: Tweaking θ in direction of negative gradient should decrease loss
- Disadvantage: 1 update is O(n) time
- Idea: Approximate with sample mean

Stochastic Gradient Descent

- 1. Sample a *batch* B of examples from the training dataset
- Do the update

$$\theta \leftarrow \theta - \eta \cdot \frac{1}{|B|} \sum_{(x,y) \in B} \nabla_{\theta} \ell(y, g(x))$$

Sample mean within batch

Today: How to compute gradients?

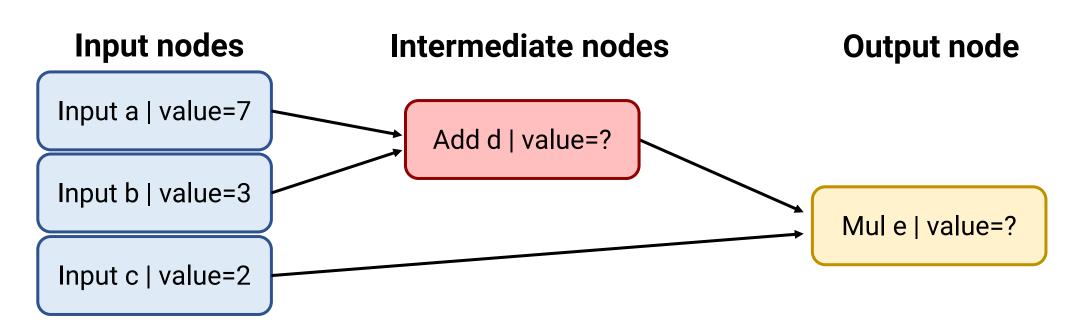
$$\theta \leftarrow \theta - \eta \cdot \frac{1}{|B|} \sum_{(x,y) \in B} \nabla_{\theta} \ell(y,g(x))$$

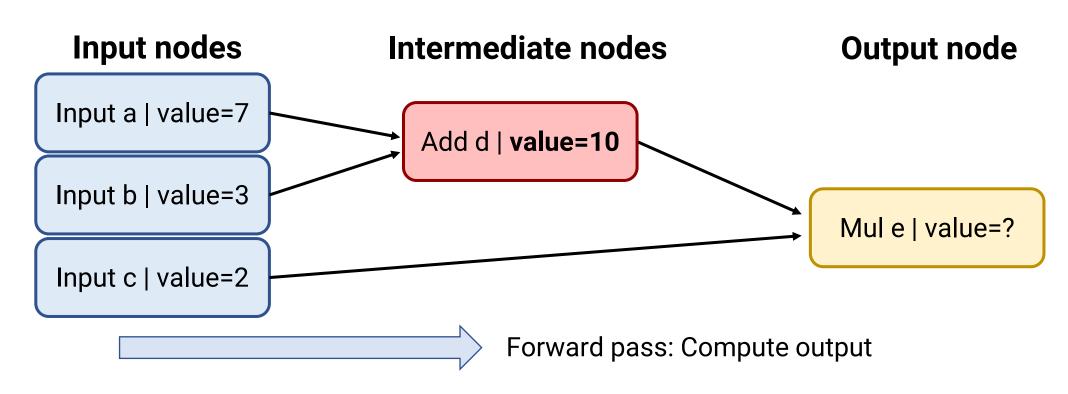
How to compute this gradient?

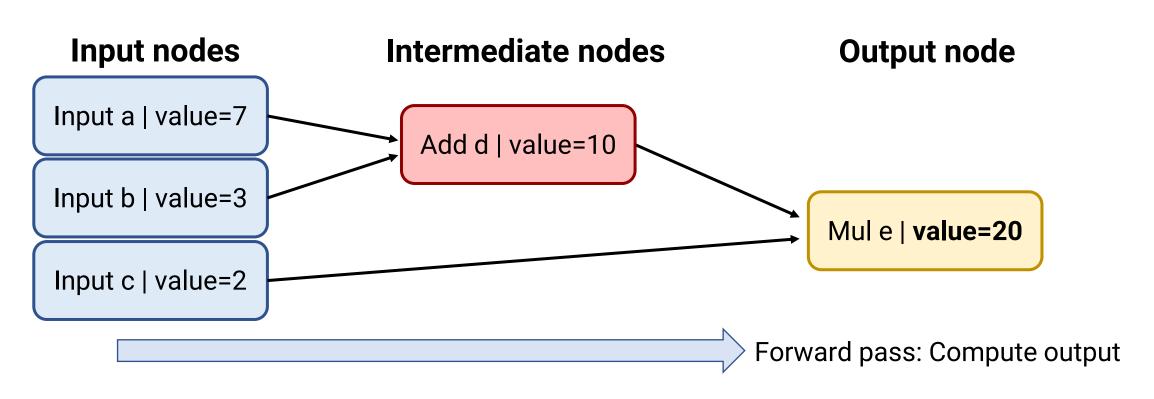
- Taking gradients by hand is tedious, and we have to re-do it every time we want to change the "architecture"
 - Change number of layers
 - Change from sigmoid to tanh
 - Etc...
- Let's make a program do it for us!

Today's Plan

- The computation graph
- Backpropagation on trees
- Backpropagation on DAGs







Gradient checking

- Numerical gradients: A simpler but less efficient way to compute gradients
- What does $\partial y/\partial x$ mean?
 - If I change *x* by epsilon, by what proportion of epsilon does *y* change?
- We can just compute this for every input node!
- Pro: Easy to implement, useful to check correctness
- Con: Slow—requires O(#inputs) function evaluations

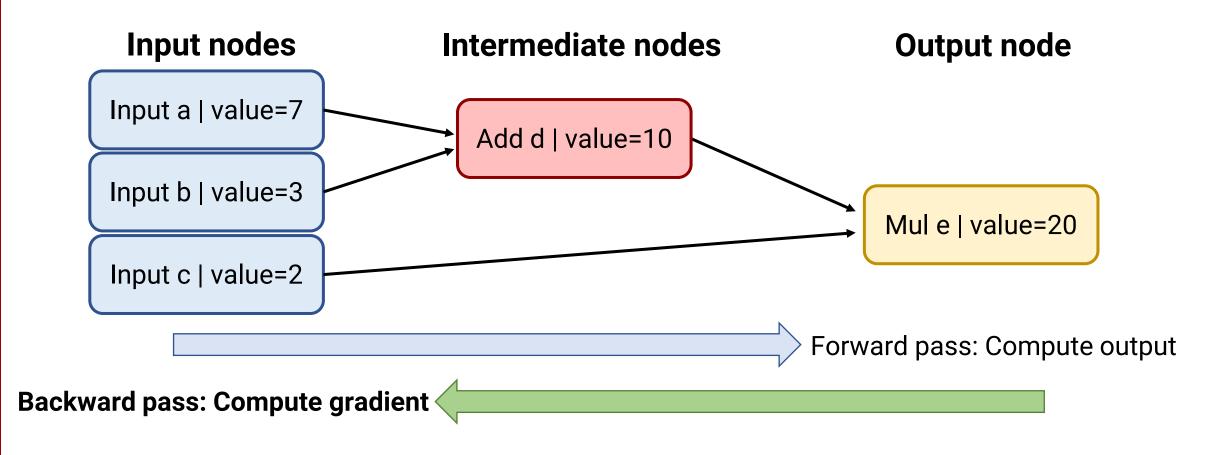


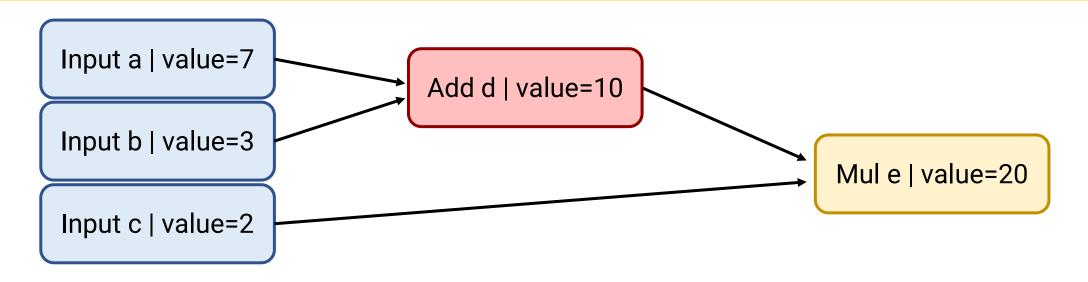
Let's implement!



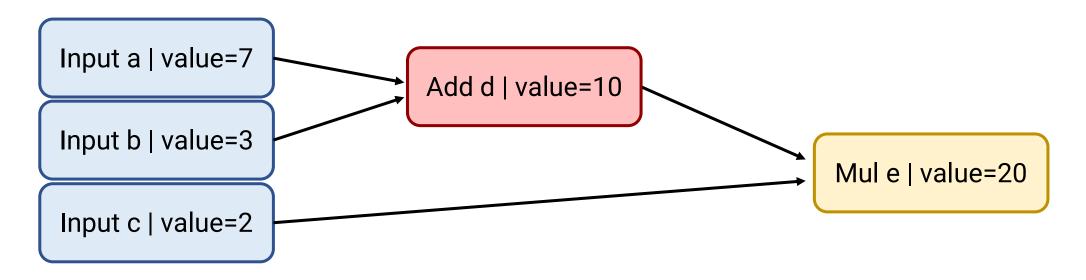
Today's Plan

- The computation graph
- Backpropagation on trees
- Backpropagation on DAGs

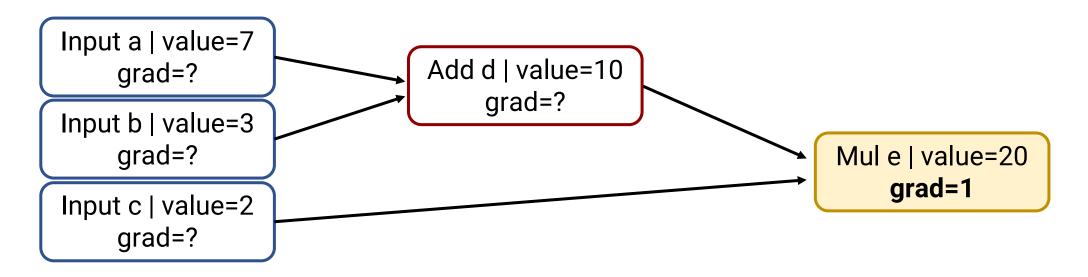




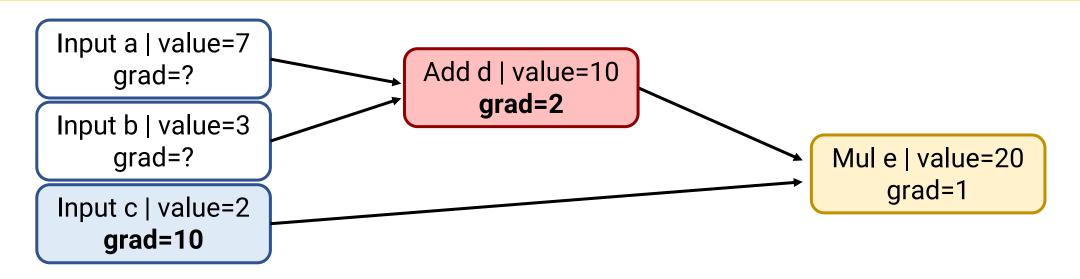
- For now: assume that the computation graph is a tree
 - Each node is only used in a single computation
 - Root of tree is output
 - Leaves of tree are inputs
- Idea: Recursively compute $\partial(output)/\partial(node)$ for each node, starting at output



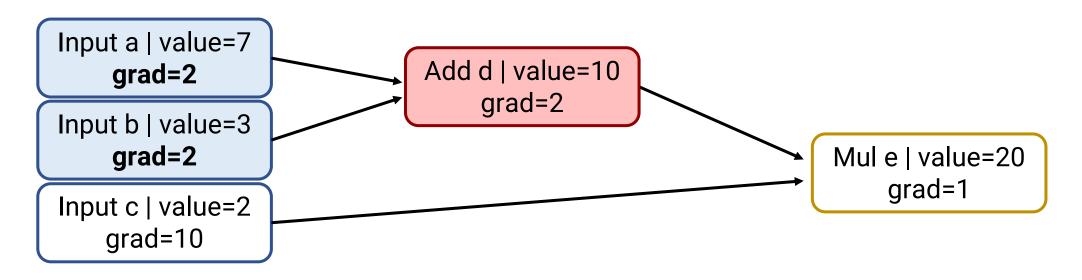
• Goal: Compute gradient [∂e/∂a, ∂e/∂b, ∂e/∂c]



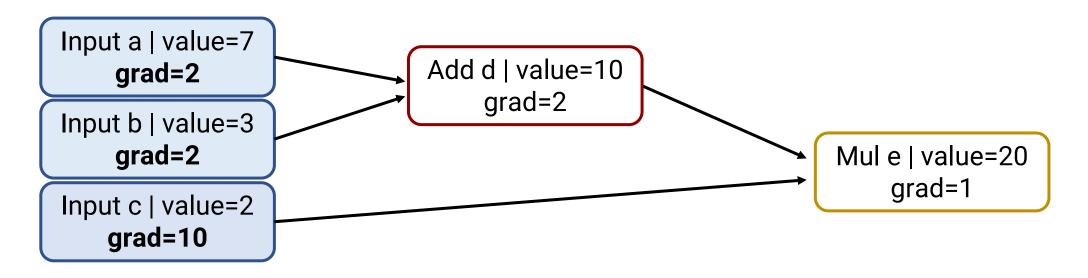
- Goal: Compute gradient [∂e/∂a, ∂e/∂b, ∂e/∂c]
- Step 1: Base case: $\partial e/\partial e = 1$



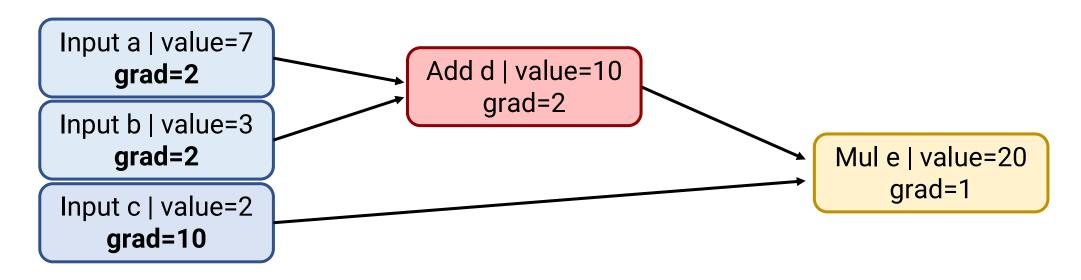
- Goal: Compute gradient [∂e/∂a, ∂e/∂b, ∂e/∂c]
- Step 2: How does Mul (node e) "distribute" gradient to its children?
 - $\partial(x^*y)/\partial x = y$
 - Chain Rule: $\frac{\partial(out)}{\partial x} = \frac{\partial(out)}{\partial(x^*y)} * \frac{\partial(x^*y)}{\partial x} = \frac{\partial(out)}{\partial(x^*y)} * y$
 - · General rule: Child gets parent's gradient * value of other child



- Goal: Compute gradient [∂e/∂a, ∂e/∂b, ∂e/∂c]
- Step 3: How does Add (node d) "distribute" gradient to its children?
 - $\partial(x+y)/\partial x = 1$
 - Chain Rule: $\frac{\partial(out)}{\partial x} = \frac{\partial(out)}{\partial(x+y)} * \frac{\partial(x+y)}{\partial x} = \frac{\partial(out)}{\partial(x+y)} * \frac{1}{\partial x}$
 - General rule: Child gets parent's gradient * 1



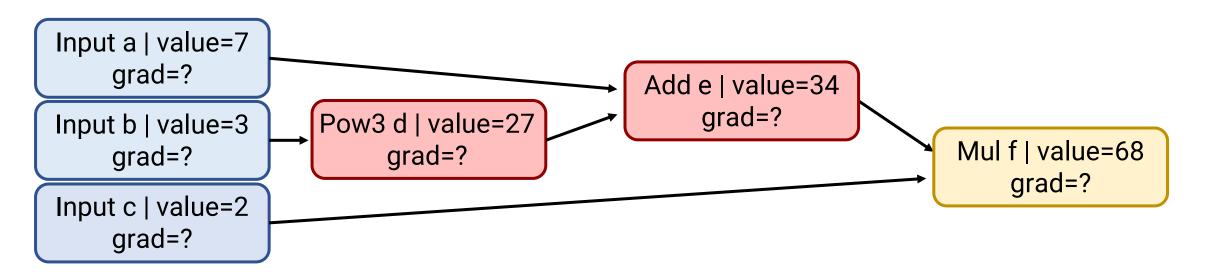
- Goal: Compute gradient [∂e/∂a, ∂e/∂b, ∂e/∂c]
- Step 4: Leaf nodes
 - Don't need to do anything

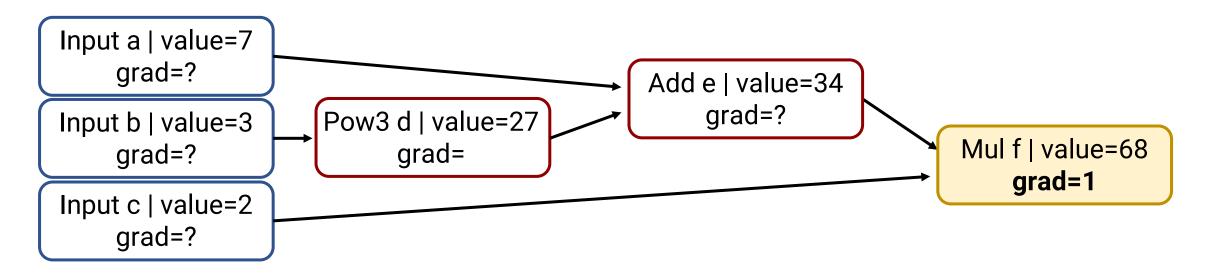


- Goal: Compute gradient [∂e/∂a, ∂e/∂b, ∂e/∂c]
- Overall Recipe
 - Do forward pass
 - Start at root and recurse over children
 - Each node knows how to take gradient of itself with respect to each child
 - By Chain Rule, child.grad = parent.grad * ∂(parent)/∂(child)

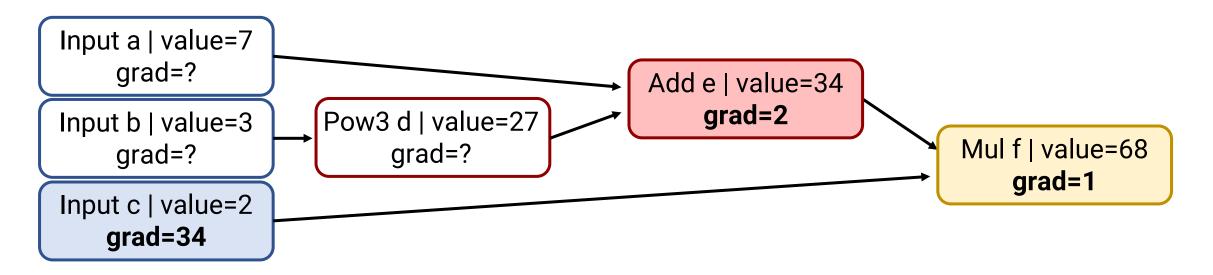
Let's implement!



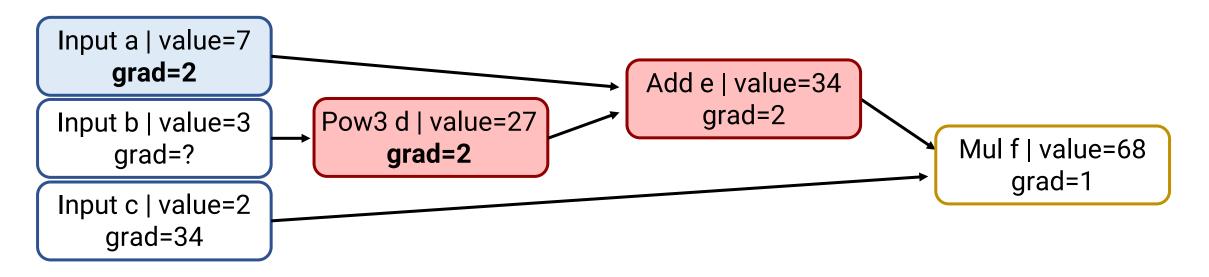




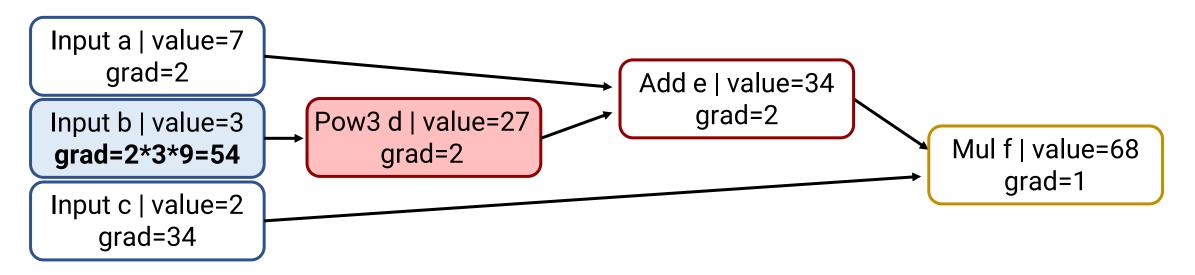
- Goal: Compute gradient [∂f/∂a, ∂f/∂b, ∂f/∂c]
- Step 1: Base case: $\partial f/\partial f = 1$



- Goal: Compute gradient [∂f/∂a, ∂f/∂b, ∂f/∂c]
- Step 2: Distribute Mul (node f) gradient to children

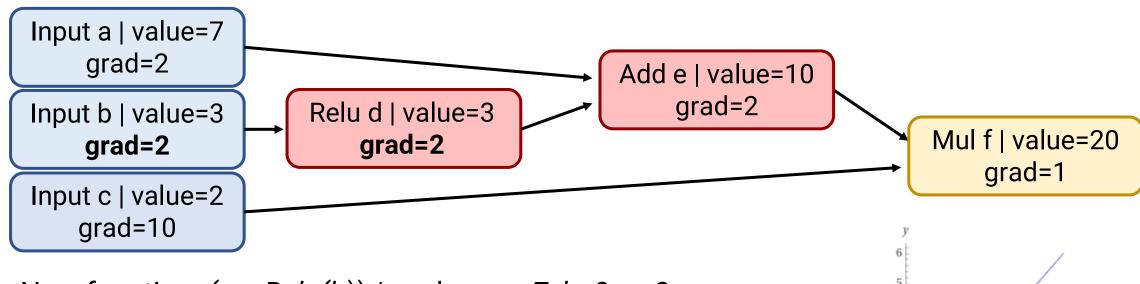


- Goal: Compute gradient [∂f/∂a, ∂f/∂b, ∂f/∂c]
- Step 3: Distribute Add (node e) gradient to children

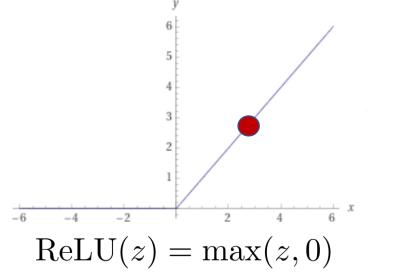


- Goal: Compute gradient [∂f/∂a, ∂f/∂b, ∂f/∂c]
- Step 4: Distribute Pow3 (node d) gradient to children
 - $\partial(x^p)/\partial x = p * x^{p-1}$
 - By Chain Rule: Child gets parent's gradient * p * child^{p-1}

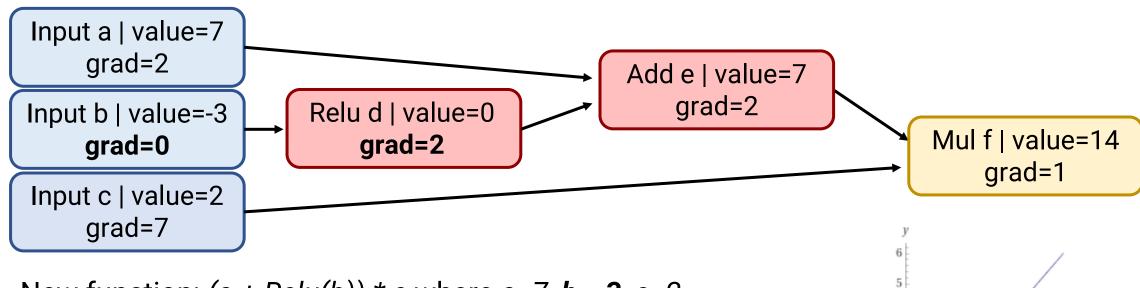
ReluNode



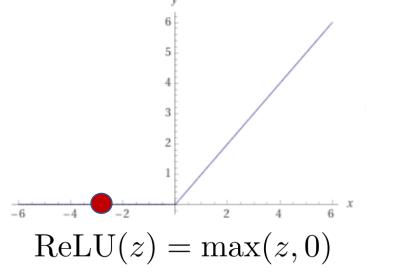
- Steps 1-3 are the same
- Step 4: Relu
 - $\partial (Relu(x))/\partial x = 1$ if x > 0, 0 if $x \le 0$
 - If child > 0, child.grad = parent.grad * 1
 - If child ≤ 0, child.grad = 0



ReluNode



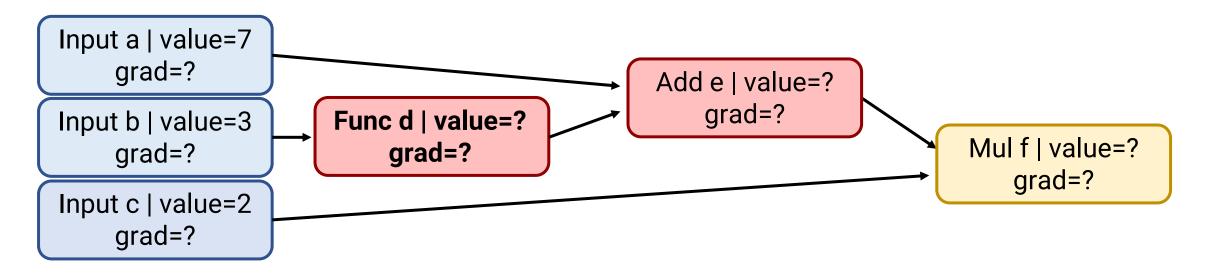
- Steps 1-3 are the same
- Step 4: Relu
 - $\partial (Relu(x))/\partial x = 1$ if x > 0, 0 if $x \le 0$
 - If child > 0, child.grad = parent.grad * 1
 - If child ≤ 0, child.grad = 0



Let's implement!



Generic Unary Function



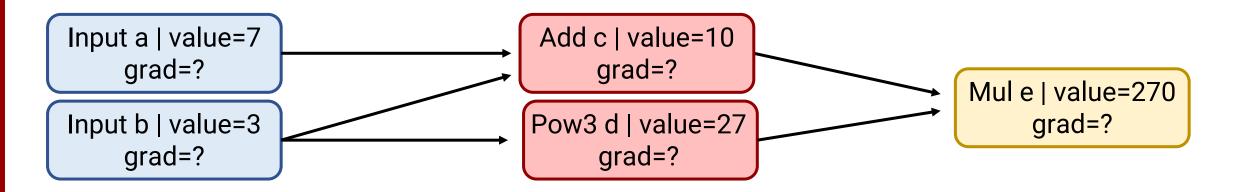
- Steps 1-3 are the same
- Step 4: Func (generic function)
 - child.grad = parent.grad * ∂(Func(child))/∂child

Announcements

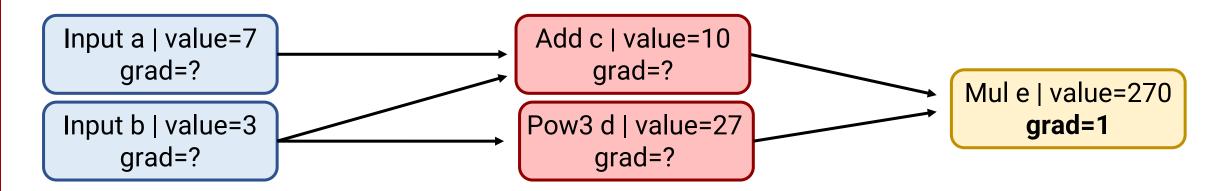
- Project proposals due today @ 11:59pm
 - Submit as a group on Gradescope, one submission per group
- HW2 released, due Thursday, October 5
- Midterm exam Tuesday, October 10
 - In-class, 80 minutes
 - Allowed one double-sided 8.5x11 sheet of notes
 - I highly recommend writing this yourself (good for memory)

Today's Plan

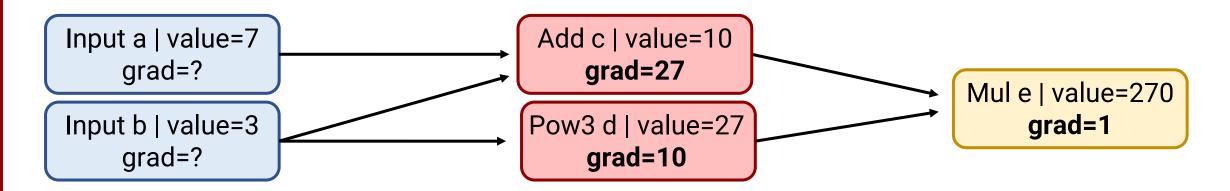
- The computation graph
- Backpropagation on trees
- Backpropagation on DAGs



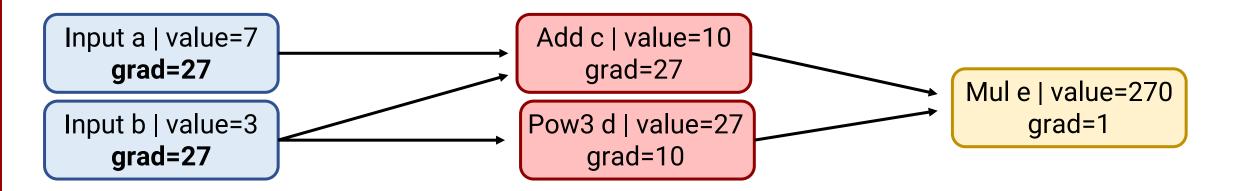
- This is no longer a tree!
- Still a directed acyclic graph
- Let's see why our previous algorithm fails



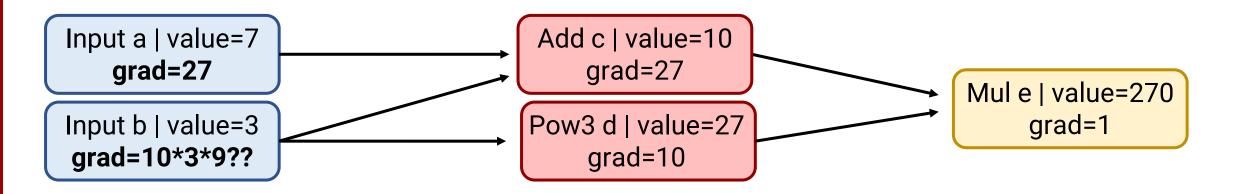
- Goal: Compute gradient [∂e/∂a, ∂e/∂b]
- Step 1: Base case: $\partial e/\partial e = 1$



- Goal: Compute gradient $[\partial f/\partial a, \partial f/\partial b]$
- Step 2: Distribute Mul (node e) gradient to children

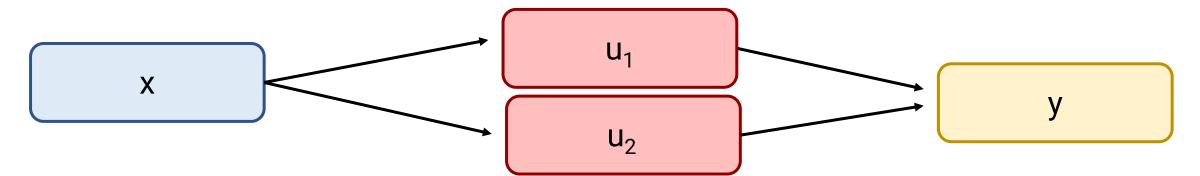


- Goal: Compute gradient $[\partial e/\partial a, \partial e/\partial b]$
- Step 3: Distribute Add (node c) gradient to children



- Goal: Compute gradient [∂e/∂a, ∂e/∂b]
- Step 4: Distribute Pow3 (node d) gradient to child
 - By Chain Rule: Child gets parent's gradient * p * child^{p-1}
- Problem: We have overwritten the gradient from b to Add (node c)!

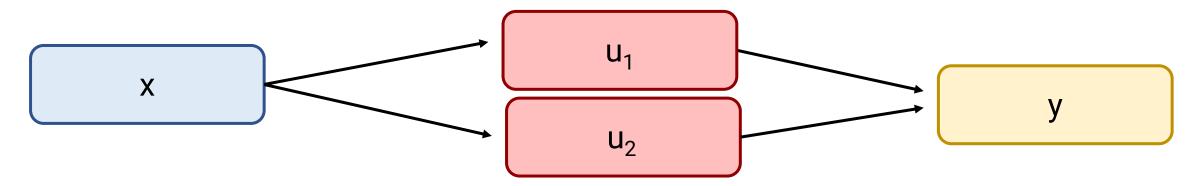
Multivariate chain rule



- Minimal example
 - u₁ and u₂ depend on variable x (i.e., x has two parents)
 - y depends on both u₁ and u₂

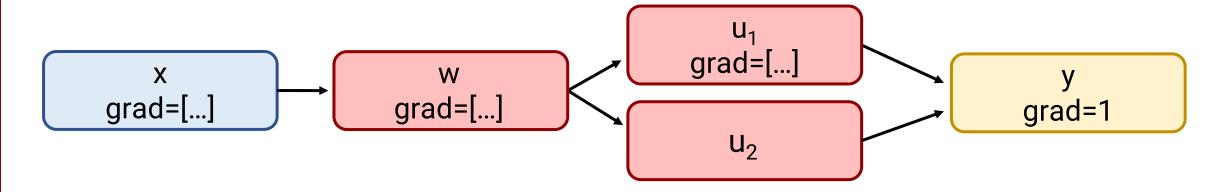
- Dot product of $[\partial y/\partial u_1, \partial y/\partial u_2] \& [\partial u_1/\partial x, \partial u_2/\partial x]$
- By Multivariate Chain Rule: $\partial y/\partial x = \frac{\partial y}{\partial u_1} * \frac{\partial u_1}{\partial x} + \frac{\partial y}{\partial u_2} * \frac{\partial u_2}{\partial x}$
 - Changing x by epsilon changes each parent a bit; Effects add for small epsilon
 - Generalization of multiplying derivatives is matrix multiplication of Jacobians

Multivariate chain rule



- Minimal example
 - u_1 and u_2 depend on variable x (i.e., x has two parents)
 - y depends on both u₁ and u₂
- By Multivariate Chain Rule: $\partial y/\partial x = \partial y/\partial u_1 * \partial u_1/\partial x + \partial y/\partial u_2 * \partial u_2/\partial x$
- node.grad = sum over parents of parent.grad * ∂(parent)/∂(child)
- At each parent node, run child.grad += parent.grad * ∂(parent)/∂(child)

What order of traversal?

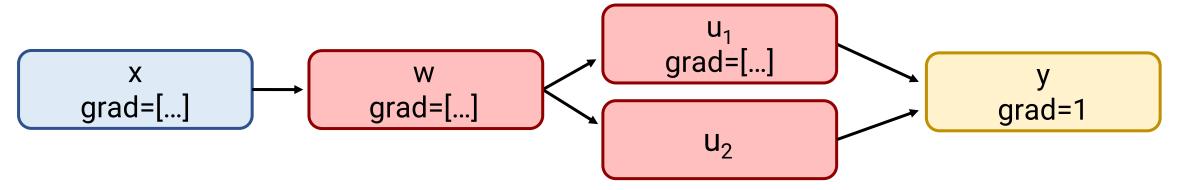


Current code:

- y.backward()
 - u1.backward()
 - w.backward()
 - x.backward()
 - u2.backward()
 - w.backward()
 - x.backward()

- Going recursively double-counts
 - First call to w.backward() makes final x.grad too large
- Solution: Topological sort the nodes
 - Iterate in reverse order, starting from output
 - Ensures that we process each node after all of its parents

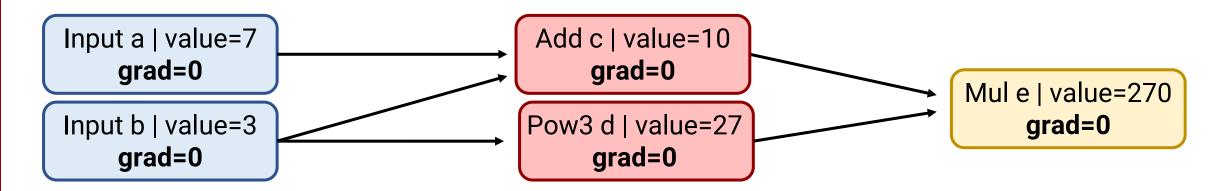
What order of traversal?



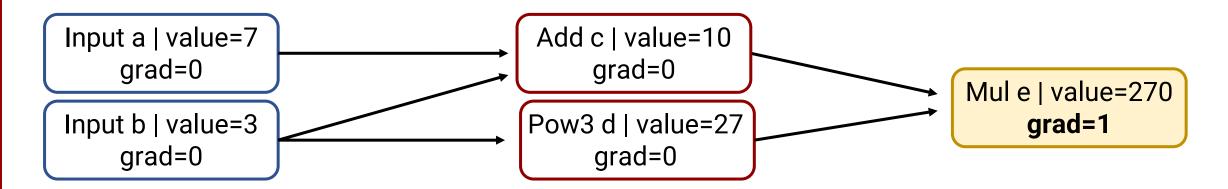
Better code:

- topo_order = [x, w, u₁, u₂, y]
- Iterate in reverse order:
 - y.backward()
 - u2.backward()
 - u1.backward()
 - w.backward()
 - x.backward()

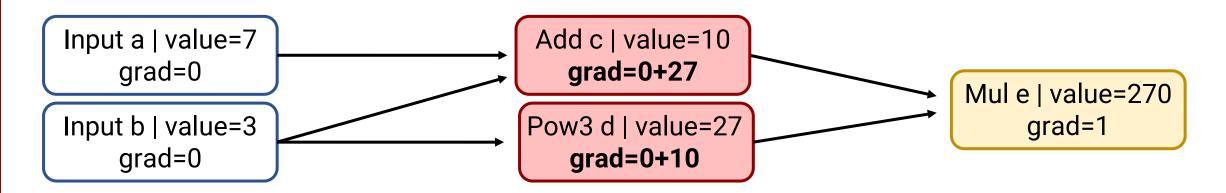
- Going recursively double-counts
 - First call to w.backward() makes final x.grad too large
- Solution: Topological sort the nodes
 - Iterate in reverse order, starting from output
 - Ensures that we process each node after all of its parents



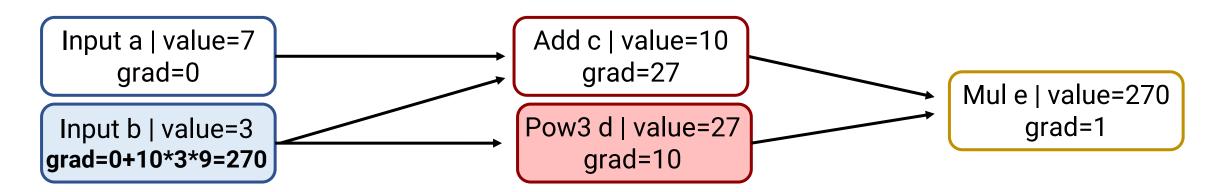
- Goal: Compute gradient $[\partial e/\partial a, \partial e/\partial b]$
- Topological sort: [a, b, c, d, e]
- Step 0: Initialize all gradients to 0



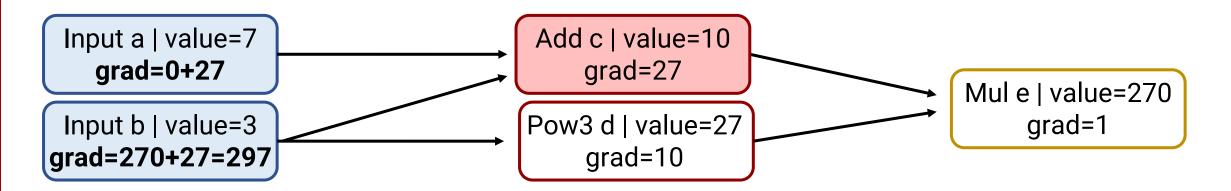
- Goal: Compute gradient $[\partial e/\partial a, \partial e/\partial b]$
- Topological sort: [a, b, c, d, e]
- Step 1: Base case: $\partial e/\partial e = 1$



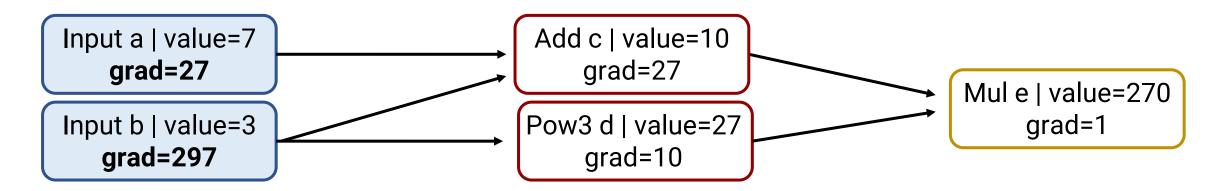
- Goal: Compute gradient $[\partial e/\partial a, \partial e/\partial b]$
- Topological sort, reversed: [e, d, c, b, a]
- Step 2: Propagate Mul node e to children



- Goal: Compute gradient $[\partial e/\partial a, \partial e/\partial b]$
- Topological sort, reversed: [e, d, c, b, a]
- Step 3: Propagate Pow3 node d to child



- Goal: Compute gradient $[\partial e/\partial a, \partial e/\partial b]$
- Topological sort, reversed: [e, d, c, b, a]
- Step 4: Propagate Add node c to children

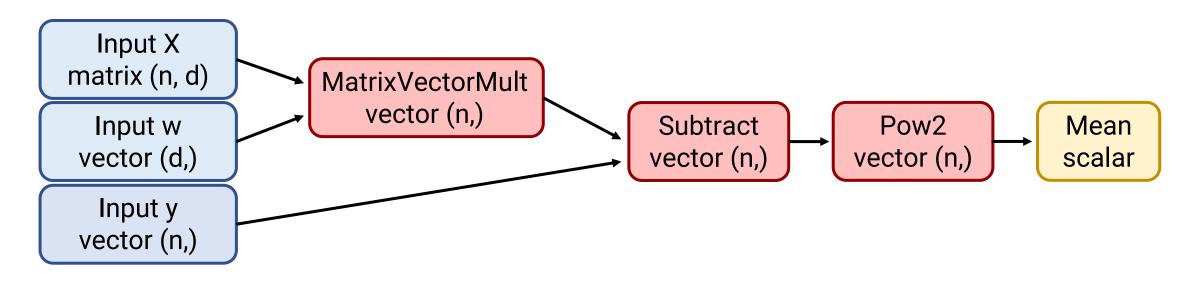


- Goal: Compute gradient $[\partial e/\partial a, \partial e/\partial b]$
- Topological sort, reversed: [e, d, c, b, a]
- Step 5, 6: a.backward(), b.backward() do nothing

Let's implement!



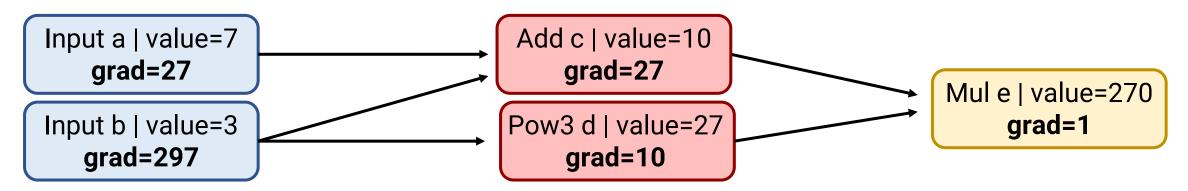
Backpropagation for vectors and matrices



Computation graph for mean($(Xw - y)^2$), i.e. Linear Regression

- Basically the same, but each node can be a vector or matrix!
 - Each node.grad stores ∇_{node} output
 - Parents know how to update ∇_{child} output based on ∇_{parent} output

Conclusion



- Backpropagation computes gradient of output with respect to all nodes in computation graph
 - Forward pass: Compute values of all nodes
 - Backward pass: Iterate through nodes in reverse order,
 At each parent node, run child.grad += parent.grad * ∂(parent)/∂(child)
- Big picture: Makes it easy to run gradient descent on arbitrary computation graphs
 - Easy to try new architectures for neural networks