



NYC CVPD Event Format Specification

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Document Number

REVISION HISTORY					
DATE	REV.	BY	SPCR	SECTION	DESCRIPTION
5/7/2018	1.0	Keith Patton			Release
11/1/2018	1.1	Keith Patton			Added message NycCvpdAsdMobility and data frame VehLocRecord
01/30/2019	1.2	Roger Babu			Added new Parameters to DF_ParameterSet; Minor Case Sensitive changes in alignment with J2735.
2/6/2019	1.3	David Benevelli			Added pedSig to EventType, EventAlertActive values defined, modified event format specification to eliminate MIB reference.
2/7/2019	1.4	Roger Babu			Minor Case Sensitive changes and punctuation corrections.
2/20/2019	1.5	Roger Babu			Added Serial Number to NycCvpdASDMobility.
3/12/2019	1.6	Roger Babu			Adding Elevation to VehLocRecord
4/30/2019	1.7	Roger Babu			Adding LocationSource Field

REVISION HISTORY					
DATE	REV.	BY	SPCR	SECTION	DESCRIPTION
10/10/2019	1.8	David Benevelli			<p>DE_RFLevel definition updated to reflect ASD output of 0.5 dBm steps.</p> <p>Added:</p> <ul style="list-style-type: none"> - DE_GroupId - grpId (DE_GroupId) to DF_EventHeader <p>Added vehicle location to define location of vehicle when first and last messages received for:</p> <ul style="list-style-type: none"> - MAPRecordRf - SPaTRecordRf - TIMRecordRf - Used HV BSM rather than VehLocRecord.
10/14/2019	1.9	Roger Babu			<ul style="list-style-type: none"> - DE_RFLevel range changed to -300 to 301 to reflect real world receive signal strengths. - Changed all DFullTime definitions to DDateTime definition to be able to record events with milliseconds time accuracy.

REVISION HISTORY					
DATE	REV.	BY	SPCR	SECTION	DESCRIPTION
10/05/2020	2.0	Roger Babu			<ul style="list-style-type: none">- Modified LocationSource ENUMs- Added new parameters to ParameterSet

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The following data dictionary specification is provided for the transmittal of Event Data from the ASD to the TMC. Data elements and frames not defined in this document can be referenced from the SAE International's J2735-201603 Dedicated Short Range Communications (DSRC) Message Set Dictionary.

1 Messages

1.1 MSG_NycCvpdEvent

This message collects the information for each event and puts it in a single structure. Sizes are not specified for the various lists as the maximum number of messages for an event cannot be reliability calculated.

ASN.1 Representation:

```
NycCvpdEvent ::= SEQUENCE {
    eventHeader      EventHeader,
    bsmList          SEQUENCE OF BSMEvent,
    mapList          SEQUENCE OF MAPEvent OPTIONAL,
    spatList         SEQUENCE OF SPaTEvent OPTIONAL,
    timList          SEQUENCE OF TIMEvent OPTIONAL,
    ...
}
```

1.2 MSG_NycCvpdRSURF

This message collects the BSM messages used to evaluate the RF distribution around an RSU. The TMC will pull this message back on a frequent basis to keep the effective size small.

NycCvpdRSURF ::= SEQUENCE OF BSMRecordRSURF

1.3 MSG_NycCvpdASDRF

This message collects the BSM, MAP, SPaT and TIM messages to evaluate the RF distribution around an ASD.

```
NycCvpdASDRF ::= SEQUENCE {
    asdSerialNumber  VisibleString,
    bsmRFList        SEQUENCE OF BSMRecordASDRF OPTIONAL,
    mapRFList        SEQUENCE OF MAPRecordRF OPTIONAL,
    spatRFList       SEQUENCE OF SPaTRecordRF OPTIONAL,
    timRFList        SEQUENCE OF TIMRecordRF OPTIONAL
}
```

1.4 MSG_NycCvpdTravelTime

This message reports the BSMs for calculating travel time at the TMC. These will be the BSMs recorded when the vehicle is in the center of the intersection. This data is collected by the RSU.

```

NycCvpdTravelTime ::= SEQUENCE {
    bsmList          SEQUENCE OF BSMRecordTravelTime,
    ...
}

```

1.5 MSG_NycCvpdASDMobility

This message reports the BSMs collected by the ASD to track the overall movement of a vehicle through the system to evaluate overall mobility. This message contains information to identify the vehicle and therefore must be encrypted on the ASD for transmittal to the RSU for upload to the TMC.

```

NycCvpdASDMobility ::= SEQUENCE {
    vehID            VINstring, -- As specified in J2735 paragraph 7.225
    asdSerialNumber  VisibleString,
    locList          SEQUENCE OF VehLocRecord,
    timeRecordResolution  TimeRecordResolution,
    ...
}

```

2 Data Frames

2.1 DF_BSMRecord

The BSMRecord data frame adds a message header to each BSM message recorded by either the ASD or RSU.

```

BSMRecord ::=SEQUENCE {
    msgHeader          MsgHeader, bsmMsg
                     BasicSafetyMessage
}

```

2.2 DF_BSMEvent

The BSMEvent data frame adds the EventMsgSeqNum data element to all of the BSMRecord data frames that are part of the event.

```

BSMEvent ::= SEQUENCE {
    seqNum            EventMsgSeqNum,
    bsmRecord          BSMRecord
}

```

2.3 DF_BSMRecordRSURF

This data frame collects the RF data for remote vehicles as seen from an RSU. A change in the tempID of the remote vehicle will trigger the previous BSM recording as the last vehicle sighting and the current BSM as the first sighting of the new vehicle.


```
BSMRecordRSURF ::= SEQUENCE {
    firstBSMTime      DDateTime,
    firstBSM          BSMRecord,
    lastBSMTime       DDateTime,
    lastBSM           BSMRecord
}
```

2.4 DF_BSMRecordASDRF

This data frame collects the RF data for remote vehicles as seen from an ASD. The host vehicle BSM must also be recorded to gather information about the location of the host vehicle with respect to the remote vehicle. A change in the tempID of the remote vehicle will trigger the previous BSM recording as the last vehicle sighting and the current BSM as the first sighting of the new vehicle.

```
BSMRecordASDRF ::= SEQUENCE {
    firstBSMTime      DDateTime,
    firstHVBSM        BSMRecord,
    firstRVBSM        BSMRecord,
    lastBSMTime       DDateTime,
    lastHVBSM         BSMRecord,
    lastRVBSM         BSMRecord
}
```

2.5 DF_BSMRecordTravelTime

The BSMRecordTravelTime is used to collect the BSM that will be used for the travel time calculations at central. Each record will contain the standard message header along with the detection geo zone and the BSM itself.

```
BSMRecordTravelTime ::= SEQUENCE {
    msgHeader          MsgHeader,
    geoZone            GeoZone,
    bsmMsg             BasicSafetyMessage
}
```

2.6 DF_EventHeader

This data frame captures the meta information about the event. If the event is an internal event (ex. red light violation warning or a speed warning) the hostVehID and the targetVehID will be the same. The triggerHvSeqNum and triggerTvSeqNum will also be the same.

```
EventHeader ::= SEQUENCE {
    eventTimeStamp      DDateTime,
    locationSource      LocationSource,
    asdSerialNumber     VisibleString,
    asdFirmwareVersion  VisibleString,
    eventAlertActive    EventAlertActive,
    eventAlertSent      EventAlertSent,
    eventAlertHeard     EventAlertHeard,
    hostVehID           TemporaryID,
    targetVehID         TemporaryID,

```

triggerHVSeqNum

EventMsgSeqNum,

--The sequence number of the HV BSM that triggered the event

```

        triggerTVSeqNum      EventMsgSeqNum,
        --The sequence number of the TV BSM that triggered the event
        eventType            EventType,
        parameters            ParameterSet,
        grpId                 GroupId,
        ...
    }

```

2.7 DF_MAPRecord

This data frame contains a list of Map messages for the event

```

MAPRecord ::= SEQUENCE {
    msgHeader      MsgHeader,
    mapMsg         MapData
}

```

2.8 DF_MAPEvent

This data frame contains a list of Map messages for the event

```

MAPEvent ::= SEQUENCE {
    seqNum      EventMsgSeqNum,
    mapRecAct    MAPRecord
}

```

2.9 DF_MAPRecordRF

This data frame collects the information on the received MAP messages to evaluate the RF effectiveness.

```

MAPRecordRF ::= SEQUENCE {
    firstMAPTime      DDateTime,
    firstMAPRecord    MAPRecord,
    lastMAPTime       DDateTime,
    lastMAPRecord     MAPRecord,
    firstMAPLocation  BasicSafetyMessage,
    lastMAPLocation   BasicSafetyMessage
}

```

2.10 DF_MsgHeader

This data frame is attached to each message (BSM, SPaT, TIM, MAP) by the receiving device (ASD or RSU).

```

MsgHeader ::= SEQUENCE { myRFLevel
                        RFLevel,
                        authenticated    MsgAuthenticated
}

```

2.11 DF_ParameterSet

This data frame captures the parameters in force in the ASD at the time of the event.

```
ParameterSet ::=SEQUENCE {
    recordingROI          NumericString OPTIONAL,
    -- the number of seconds before the event
    timeRecordBefore      NumericString,
    -- the number of seconds after the event
    timeRecordFollow      NumericString,
    timeRecordResolution  TimeRecordResolution,
    -- for this specific type of event minSpdThreshold
    minSpdThreshold       NumericString,
    timeToCrash           NumericString OPTIONAL,
    excessiveCurveSpd     NumericString OPTIONAL,
    excessiveSpd          NumericString OPTIONAL,
    excessiveSpdTime      NumericString OPTIONAL,
    excessiveCurveSpdTime NumericString OPTIONAL,
    excessiveZoneSpd      NumericString OPTIONAL,
    excessiveZoneSpdTime  NumericString OPTIONAL,
    minCurveSpd           NumericString OPTIONAL,
    minZoneSpd            NumericString OPTIONAL,
    stopBarTolerance      NumericString OPTIONAL,
    yellowDurationTolerance NumericString OPTIONAL,
    hardBrakingThreshold  NumericString OPTIONAL,
    assumedDriverBraking  NumericString OPTIONAL,
    postedHeightLimit     NumericString OPTIONAL,
    postedSizeLimit       NumericString OPTIONAL,
    postedZoneSpeed       NumericString OPTIONAL,
    regulatorySpeed       NumericString OPTIONAL,
    ...
}
```

2.12 DF_SPaTRecord

This data frame assembles the additional information required to record SPaT messages.

```
SPaTRecord ::= SEQUENCE {
    msgHeader  MsgHeader,
    spatMsg    SPAT
}
```

2.13 DF_SPaTRecordRF

This data frame collects the SPaT data for evaluation of RF effectiveness.

```
SPaTRecordRF ::= SEQUENCE {
    firstSPaTTime      DDateTime,
```



```

        lastSPaTTime      DDateTime,
        lastSPaTRecord    SPaTRecord
    ,
        firstSPaTLocation BasicSafetyMessage,
        lastSPaTLocation  BasicSafetyMessage
    }

```

2.14 DF_SPaTEvent

This data frame adds the message sequence number for the SPaT message within an event.

```

SPaTEvent ::= SEQUENCE {
    seqNum      EventMsgSeqNum,
    spatRecord  SPaTRecord
}

```

2.15 DF_TIMRecord

This data Frame adds the additional information to a TIM for recording and evaluation.

```

TIMRecord ::= SEQUENCE {
    msgHeader  MsgHeader,
    timMsg     TravelerInformation
}

```

2.16 DF_TIMRecordRF

This data frame collects the information on the received TIM messages to evaluate the RF effectiveness.

```

TIMRecordRF ::= SEQUENCE {
    firstTIMTime      DDateTime,
    firstTIMRecord    TIMRecord,
    lastTIMTime       DDateTime,
    lastTIMRecord     TIMRecord,
    firstTIMLocation  BasicSafetyMessage,
    lastTIMLocation   BasicSafetyMessage
}

```

2.17 DF_TIMEvent

This data frame captures additional information for TIM messages received during an event.

```

TIMEvent ::= SEQUENCE {
    seqNum      EventMsgSeqNum,
    timRecord   TIMRecord
}

```

2.18 DF_VehLocRecord

This data frame captures the vehicle location at a specific time. Since this is providing data to evaluate overall mobility, time resolution greater than 1 second is not required.

```
VehLocRecord::= SEQUENCE {
    timeStamp
    DDateTime
    , longitude      Longitude,
    latitude         Latitude,
    elevation        Elevation
}
```

3 Data Elements

3.1 DE_EventAlertActive

This data element records the control state of audible notifications – they are either Silent (FALSE) or Active (TRUE) mode, with the default being the Active mode. If this data element is TRUE, then audible notifications are active in the ASD.

EventAlertActive::=BOOLEAN

3.2 DE_EventAlertHeard

This data element flags if the alert generated by this event was heard/detected. If this event did not send an alert, indicated when EventAlertSent is FALSE, then this data element must be FALSE.

EventAlertHeard::=BOOLEAN

3.3 DE_EventAlertSent

This data element flags the event as an event generating an alert. In the case of multiple events occurring simultaneously the performance analysis needs to know which event generated an alert. If this event sent an alert the value will be TRUE. A higher priority event may occur and result in this event's alert being suppressed in which case this event's value will be FALSE.

EventAlertSent::=BOOLEAN

3.4 DE_EventMsgSeqNum

This data element captures the order in which messages are received or stored for the event the oldest message (BSM, SPaT, TIM or MAP) will be 1. The first message in each event will start at 1.

EventMsgSeqNum ::=INTEGER (1..16384)

3.5 DE_EventType

This data element reports the event type.

```
EventType::=ENUMERATED {
    unknown (0),
```

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```

    fcw (1),
    eebl (2),
    bsw (3),
    lcw (4),
    ima (5),
    vtrw (6),
    spdcomp (7),
    cspdcomp (8),
    spdcompwz (9),
    rlvw (10),
    ovcturnprohibit (11),
    ovcclearancelimit (12),
    evacinfo (13),
    pedinxwalk (14),
    pedSig (15)

}

```

3.6 DE_GeoZone

This data element is part of the BsmRecord and records the geozone for BSMs recorded to support the central travel time calculations. A value of 0 for GeoZone indicates that the BSM was not in a defined detection geo zone.

NOTE: The range is set at 0 to 128. We do not expect more than 16 zones per RSU.

GeoZone ::= INTEGER(0..128)

3.7 DE_RFLevel

This data element captures the RF level of the received message. The measurement shall be in increments of 0.5 dBm. Internal messages will have a reading of 301.

RFLevel ::= INTEGER (-300..301)

3.8 DE_TimeRecordResolution

This is a data element that specifies the rate at which event data is logged.

```

TimeRecordResolution ::= ENUMERATED {
    resOneTenthOfSec, -- every 1/10 second
    resTwoTenthOfSec, -- every 2/10 second
    resFiveTenthsOfSec, -- every 5/10 second
    resEverySec, -- every 1 second
    resEveryTwoSec, -- every 2 seconds
    resEveryFiveSec, -- every 5 seconds
    resEveryTenSec -- every 10 seconds
}

```


3.9 DE_MsgAuthenticated

This data element is a Boolean value to indicate if the message was authenticated by the ASD.

MsgAuthenticated ::= BOOLEAN

3.10 DE_LocationSource

This data element defines the data fusion process used to enhance location accuracy.

```
LocationSource ::= ENUMERATED {  
    unknown (0),  
    directgps (1),  
    gps (2),  
    gpsrsu (3)  
}
```

3.11 DE_GroupId

This data element contains the assigned group identification number for managing the OTA updates.
See the list of OTA Groups.

```
GroupId ::= INTEGER (0..255)
```