



Autonomous Driving And Parking Technology

Unfollow



ADAPT is a futuristic concept solution that tackles the parking problem in busy urban areas and big cities by fusing Autonomous Vehicles and Smart Parking Infrastructure, aiming to provide comfort, safety, practicality, and ease of mind for our users.

Repositories 19 **Projects** **Packages** **Members** 8 **Teams** 1

Settings

Search... Sort ▾

- adapt_behplan** Python ☆ 0 🔑 0
Behavior planning
Updated 24 minutes ago
- adapt_roucomp** Private Python ☆ 0 🔑 0
route computer
Updated 5 days ago
- adapt_trajp** Python ☆ 0 🔑 0
Updated last week
- adapt_envmod** Python ☆ 0 🔑 0
Environment Model
Updated last week
- adapt_msgs** CMake ☆ 0 🔑 0
Updated last week
- adapt_main** Python ☆ 1 🔑 0
Main repository for ADAPT
Updated last week
- adapt_obj** Python ☆ 0 🔑 0
Object detection
Updated 2 weeks ago
- adapt_livtrac** Python ☆ 0 🔑 0
Live Tracker
Updated 2 weeks ago

Members 8 >

Teams 1 >

Owners
8 members · 19 repositories

-
-  **adapt_loc** HTML ☆ 0 🔗 0
Updated 2 weeks ago
-
-  **adapt_inf_spotupd** Python ☆ 0 🔗 0
Updated last month
-
-  **dum_spotsl** Python ☆ 0 🔗 0
This is just a dummy node for Parking Spot selector, which prints the x and y coordinates in ENU of parking spots so that it can be subscribed by the spot updater to update the parking spot list.
Updated last month
-
-  **adapt_inf_trans** Python ☆ 0 🔗 0
Updated last month
-
-  **adapt_transceiver** Python ☆ 0 🔗 0
Transceiver - we are using this component for transmitting and receiving messages
Updated last month
-
-  **adapt_spotsl** HTML ☆ 0 🔗 0
Updated last month
-
-  **adapt_vi** Python ☆ 0 🔗 0
Vehicle Interface
Updated last month

<< < 1 > >>