# MSO4000 and DPO4000 Series Digital Phosphor Oscilloscopes

**Programmer Manual** 



MSO4000 and DPO4000 Series
Digital Phosphor Oscilloscopes

**Programmer Manual** 

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# **Table of Contents**

Getting Started	1-1
Setting Up Remote Communications	1-1
Command Syntax	2-1
Command and Query Structure	2-1
Clearing the oscilloscope	2-3
Command Entry	2-3
Constructed Mnemonics	2-5
Argument Types	2-7
Command Groups	2-11
Acquisition Command Group	2-11
Alias Command Group.	2-12
Bus Command Group	2-13
Calibration and Diagnostic Command Group	2-17
Cursor Command Group	2-17
Display Command Group.	2-19
Ethernet Command Group	2-20
File System Command Group	2-21
Hard Copy Command Group	2-22
Histogram Command Group	2-24
Horizontal Command Group	2-24
Mark Command Group.	2-25
Math Command Group.	2-26
Measurement Command Group	2-27
Miscellaneous Command Group	2-30
PictBridge Command Group	2-32
Power Command Group	2-32
Save and Recall Command Group	2-40
Search Command Group	2-41
Status and Error Command Group	2-48
Trigger Command Group	2-49
Vertical Command Group.	2-60
Waveform Transfer Command Group	2-63
Zoom Command Group	2-68
Commands Listed in Alphabetical Order	2-71
Status and Events	3-1
Registers	3-1
Queues	3-4
Event Handling Sequence.	3-5
Synchronization Methods	3-7

#### Table of Contents

Appendix A: Character Set	<b>A-</b> 1
Appendix B: Reserved Words	B-1
Appendix C: Factory Defaults	C-1
Default Setup	<b>C-</b> 1
Appendix D: Programming Example	D-1
Index	

# **List of Figures**

Figure 3-1: The Standard Event Status Register (SESR)	3-1
Figure 3-2: The Status Byte Register (SBR)	3-2
Figure 3-3: The Device Event Status Enable Register (DESER)	3-3
Figure 3-4: The Event Status Enable Register (ESER)	3-3
Figure 3-5: The Service Request Enable Register (SRER)	3-4
Figure 3-6: Status and Event Handling Process.	3-6
Figure 3-7: Command Processing Without Using Synchronization	3-8
Figure 3-8: Processing Sequence With Synchronization.	3-8

# **List of Tables**

Table 1-1: USB Device Parameters	1-2
Table 2-1: Symbols for Backus-Naur Form	2-1
Table 2-2: Command Message Elements	2-2
Table 2-3: Comparison of Header Off and Header On Responses	2-3
Table 2-4: End of Message Terminator	2-5
Table 2-5: Channel Mnemonics.	2-6
Table 2-6: Cursor Mnemonics	2-6
Table 2-7: Math Specifier Mnemonics	2-6
Table 2-8: Measurement Specifier Mnemonics	2-6
Table 2-9: Reference Waveform Mnemonics	2-6
Table 2-10: Numeric Arguments.	2-7
Table 2-11: Quoted String Argument	2-7
Table 2-12: Block Argument	2-8
Table 2-13: Acquisition Commands.	2-11
Table 2-14: Alias Commands	2-12
Table 2-15: Bus Commands	2-13
Table 2-16: Calibration and Diagnostic Commands.	2-17
Table 2-17: Cursor Commands	2-18
Table 2-18: Display Commands	2-20
Table 2-19: Ethernet Commands	2-20
Table 2-20: File System Commands	2-22
Table 2-21: Hard Copy Commands	2-22
Table 2-22: Histogram Commands	2-24
Table 2-23: Horizontal Commands	2-24
Table 2-24: Mark Commands	2-25
Table 2-25: Math Commands	2-26
Table 2-26: Measurement Commands	2-27
Table 2-27: Miscellaneous Commands	2-30
Table 2-28: PictBridge Commands	2-32
Table 2-29: Power Commands	2-32
Table 2-30: Save and Recall Commands	2-40
Table 2-31: Status and Error Commands	2-48
Table 2-32: Trigger Commands	2-49
Table 2-33: Vertical Commands	2-60
Table 2-34: Binary data ranges	2-64
Table 2-35: Waveform Transfer Commands.	2-66
Table 2-36: Zoom Commands	2-68
Table 2-37: Supported display formats.	2-95

Table 2-38: Channel Offset Range	2-126
Table 2-39: DATa and WFMOutpre Parameter Settings	2-153
Table 2-40: FPAnel:PRESS arguments	2-184
Table 2-41: FPAnel:TURN arguments	2-185
Table 2-42: Advanced Math expression elements	2-210
Table 2-43: Available HDTV formats	2-490
Table 2-44: Video Line Numbering Ranges	2-491
Table 2-45: Waveform Suffixes	2-525
Table 3-1: SESR Bit Functions	. 3-2
Table 3-2: SBR Bit Functions	. 3-2
Table 3-3: Oscilloscope operations that can generate OPC	. 3-7
Table 3-4: No Event Messages.	3-12
Table 3-5: Command Error Messages (CME Bit 5)	3-13
Table 3-6: Execution Error Messages (EXE Bit 4)	3-13
Table 3-7: Device Error Messages (DDE Bit 3)	3-16
Table 3-8: System Event Messages.	3-16
Table 3-9: Execution Warning Messages (EXE Bit 4)	3-17
Table 3-10: Execution Warning Messages (EXE Bit 4)	3-17
Table 3-11: Internal Warning Messages	3-17
Table C-1: Default values	C-1

## **Getting Started**

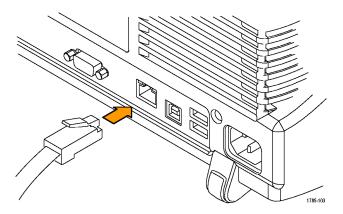
This manual explains the use of commands for remotely controlling your oscilloscope. With this information, you can write computer programs to perform functions, such as setting the front-panel controls, taking measurements, performing statistical calculations, and exporting data for use in other programs.

## **Setting Up Remote Communications**

You can remotely communicate between your oscilloscope and PC via the Ethernet, USB, and, GPIB using the TEK-USB-488 Adapter.

#### **Ethernet**

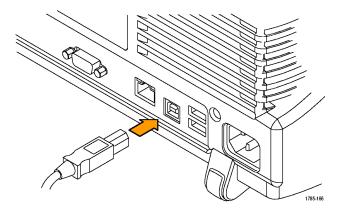
If you are using Ethernet, start by connecting an appropriate Ethernet cable to the Ethernet port (RJ-45 connector) on the rear panel of your oscilloscope. This connects the oscilloscope to a 10/100 Base-T local area network.



To change the Ethernet settings on your oscilloscope, do the following:

- 1. On the front panel, push Utility.
- 2. Push Utility Page.
- **3.** Select **I/O** with the Multipurpose knob.
- 4. Push Ethernet Network Settings.
- **5.** On the side-bezel menu, if you are on a DHCP Ethernet network and using a through cable, set DHCP/BOOTP to **On**.
- **6.** If you are using a cross-over cable, set DHCP/BOOTP to **Off**, and set a hard coded TCPIP address.

USB If you are using USB, start by connecting an appropriate USB cable to the USB 2.0 high-speed device port on the rear panel of your oscilloscope.



With USB, the system automatically configures itself. To verify that the USB is enabled:

- 1. On the front panel, push Utility.
- 2. Push Utility Page.
- **3.** Select **I/O** with the Multipurpose knob.
- **4.** Push **USB**, and verify that USB is enabled.
- **5.** If USB is disabled, push **Connect to computer** on the side-bezel menu.

After connection, the host, with appropriate software, can list the oscilloscope as a USB device with the following parameters. (See Table 1-1.)

**Table 1-1: USB Device Parameters** 

Parameter	Value
Manufacturer ID	0x0699 (decimal 1689)
Product ID	0x0401 (decimal 1025)
Serial number	Serial number
Manufacturer description	"Tektronix"
Interface description	"USBTMC-USB488"
·	

#### **GPIB**

To use GPIB, start by connecting an appropriate USB cable to the USB 2.0 high speed device port on the rear panel of your oscilloscope. Connect the other end to the TEK-USB-488 Adapter host port. Then connect a GPIB cable from the TEK-USB-488 Adapter to your PC.

Supply power to the Adapter in either of these two ways:

- 1. Use the optional 5  $V_{\text{DC}}$  power adapter connected to the 5  $V_{\text{DC}}$  power input on the Adapter.
- **2.** Use an appropriate USB cable connected to a powered USB host port on your PC and the Device port on the TEK-USB-488 Adapter.

The oscilloscope has a USB 2.0 High speed device port to control the oscilloscope through USBTMC or GPIB with a TEK-USB-488 Adapter. The USBTMC protocol allows USB devices to communicate using IEEE488 style messages. This lets you run your GPIB software applications on USB hardware.



Before setting up the oscilloscope for remote communication using the electronic (physical) GPIB interface, you should familiarize yourself with the following GPIB requirements:

- A unique device address must be assigned to each device on the bus. No two devices can share the same device address.
- No than 15 devices can be connected to any one line.
- One device should be connected for every 6 feet (2 meters) of cable used.
- No than 65 feet (20 meters) of cable should be used to connect devices to a bus.
- At least two-thirds of the devices on the network should be powered on while using the network.
- Connect the devices on the network in a star or linear configuration. Do not use loop or parallel configurations.

To function correctly, your oscilloscope must have a unique device address. The default setting for the GPIB configuration is GPIB Address 1.

To change the GPIB address settings, do the following:

- 1. On the front panel, push Utility.
- 2. Push Utility Page.
- **3.** Select **I/O** with the Multipurpose knob.
- 4. Push GPIB.
- **5.** Enter the GPIB address on the side-bezel menu, using the multipurpose knob. This will set the GPIB address on an attached TEK-USB-488 Adapter

The oscilloscope is now set up for bidirectional communication with your controller.

#### **Documentation**

The following documents are available for download on the Manuals Finder Web site at *www.tektronix.com*:

*MSO4000 and DPO4000 Series Digital Phosphor Oscilloscopes User Manual.* Information about installing and operating the oscilloscope.

*Getting Started with OpenChoice* <sup>TM</sup> *Solutions Manual*. Options for getting data from your oscilloscope into any one of several available analysis tools.

MSO4000 and DPO4000 Series Digital Phosphor Oscilloscopes Technical Reference. Oscilloscope specifications and a performance verification procedure.

**TekVISA Programmer Manual**. Description of TekVISA, the Tektronix implementation of the VISA Application Programming Interface (API). TekVISA is industry-compliant software for writing interoperable oscilloscope drivers in a variety of Application Development Environments (ADEs).

# **Command Syntax**

You can control the operations and functions of the oscilloscope through the Ethernet port or the USB 2.0 device port using commands and queries. The related topics listed below describe the syntax of these commands and queries. The topics also describe the conventions that the oscilloscope uses to process them. See the *Command Groups* topic in the table of contents for a listing of the commands by command group, or use the index to locate a specific command.

# Backus-Naur Form Notation

This documentation describes the commands and queries using Backus-Naur Form (BNF) notation. Refer to the following table for the symbols that are used.

Table 2-1: Symbols for Backus-Naur Form

Symbol	Meaning
<>	Defined element
=	Is defined as
	Exclusive OR
{}	Group; one element is required
[]	Optional; can be omitted
	Previous element(s) may be repeated
()	Comment

## **Command and Query Structure**

Commands consist of set commands and query commands (usually called commands and queries). Commands modify oscilloscope settings or tell the oscilloscope to perform a specific action. Queries cause the oscilloscope to return data and status information.

Most commands have both a set form and a query form. The query form of the command differs from the set form by its question mark at the end. For example, the set command ACQuire: MODe has a query form ACQuire: MODe?. Not all commands have both a set and a query form. Some commands have set only and some have query only.

#### Messages

A command message is a command or query name followed by any information the oscilloscope needs to execute the command or query. Command messages may contain five element types, defined in the following table.

**Table 2-2: Command Message Elements** 

Symbol	Meaning	
<header></header>	This is the basic command name. If the header ends with a question mark, the command is a query. The header may begin with a colon (:) character. If the command is concatenated with other commands, the beginning colon is required. Never use the beginning colon with command headers beginning with a star (*).	
<mnemonic></mnemonic>	This is a header subfunction. Some command headers have only one mnemonic. If a command header has multiple mnemonics, a colon (:) character always separates them from each other.	
<argument></argument>	This is a quantity, quality, restriction, or limit associated with the header. Some commands have no arguments while others have multiple arguments. A <space> separates arguments from the header. A <comma> separates arguments from each other.</comma></space>	
<comma></comma>	A single comma is used between arguments of multiple-argument commands. Optionally, there may be white space characters before and after the comma.	
<space></space>	A white space character is used between a command header and the related argument. Optionally, a white space may consist of multiple white space characters.	

#### Commands

Commands cause the oscilloscope to perform a specific function or change one of the settings. Commands have the structure:

[:]<Header>[<Space><Argument>[<Comma> <Argument>]...]

A command header consists of one or more mnemonics arranged in a hierarchical or tree structure. The first mnemonic is the base or root of the tree and each subsequent mnemonic is a level or branch off the previous one. Commands at a higher level in the tree may affect those at a lower level. The leading colon (:) always returns you to the base of the command tree.

#### Queries

Queries cause the oscilloscope to return status or setting information. Queries have the structure:

- [:]<Header>
- [:]<Header>[<Space><Argument> [<Comma><Argument>]...]

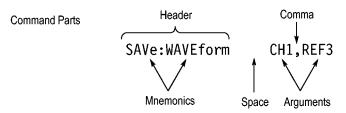
You can specify a query command at any level within the command tree unless otherwise noted. These branch queries return information about all the mnemonics below the specified branch or level.

#### **Headers**

Use the HEADer command to control whether the oscilloscope returns headers as part of the query response. If header is on, the query response returns command headers, then formats itself as a valid set command. When header is off, the response includes only the values. This may make it easier to parse and extract the information from the response. The table below shows the difference in responses.

Table 2-3: Comparison of Header Off and Header On Responses

Query	Header Off	Header On
TIME?	14:30:00	:TIME "14:30:00"
ACQuire:NUMAVg?	100	:ACQUIRE:NUMAVG 100



## Clearing the oscilloscope

You can clear the Output Queue and reset the oscilloscope to accept a new command or query by using the selected Device Clear (DCL) function.

## **Command Entry**

The following rules apply when entering commands:

- You can enter commands in upper or lower case.
- You can precede any command with white space characters. White space characters include any combination of the ASCII control characters 00 through 09 and 0B through 20 hexadecimal (0 through 9 and 11 through 32 decimal).
- The oscilloscope ignores commands consisting of any combination of white space characters and line feeds.

#### **Abbreviating**

You can abbreviate many oscilloscope commands. Each command in this documentation shows the minimum acceptable abbreviations in capitals. For example, you can enter the command ACQuire:NUMAvg simply as ACQ:NUMA or acq:numa.

Abbreviation rules may change over time as new oscilloscope models are introduced. Thus, for the most robust code, use the full spelling.

If you use the HEADer command to have command headers included as part of query responses, you can further control whether the returned headers are abbreviated or are full-length with the VERBose command.

#### Concatenating

You can concatenate any combination of set commands and queries using a semicolon (;). The oscilloscope executes concatenated commands in the order received.

When concatenating commands and queries, you must follow these rules:

 Separate completely different headers by a semicolon and by the beginning colon on all commands except the first one. For example, the commands TRIGGer: MODE NORMal and ACQuire: NUMAVg 8, can be concatenated into the following single command:

TRIGger: MODe NORMal;: ACQuire: NUMAVg 8

2. If concatenated commands have headers that differ by only the last mnemonic, you can abbreviate the second command and eliminate the beginning colon. For example, you can concatenate the commands ACQuire: MODe ENVelope and ACQuire: NUMAVq 8 into a single command:

ACQuire: MODe ENVelope; NUMAVg 8

The longer version works equally well:

ACQuire: MODe ENVelope;: ACQuire: NUMAVg 8

**3.** Never precede a star (\*) command with a colon:

ACQuire:STATE 1;\*OPC

Any commands that follow will be processed as if the star command was not there so the commands, ACQuire:MODe ENVelope;\*OPC;NUMAVg 8 will set the acquisition mode to envelope and set the number of acquisitions for averaging to 8.

4. When you concatenate queries, the responses to all the queries are concatenated into a single response message. For example, if the display graticule is set to Full and the display style is set to dotsonly, the concatenated query DISplay: GRAticule?; STYle:DOTsonly? will return the following.

If the header is on:

DISPLAY: GRATICULE FULL; : DISPLAY: STYLE: DOTSONLY 1

If the header is off:

FULL;1

**5.** Set commands and queries may be concatenated in the same message. For example,

ACQuire: MODe SAMple; NUMAVg?; STATE?

is a valid message that sets the acquisition mode to sample. The message then queries the number of acquisitions for averaging and the acquisition state. Concatenated commands and queries are executed in the order received.

Here are some invalid concatenations:

DISPlay:STYle:NORMal;ACQuire:NUMAVg 8 (no colon before ACQuire)

DISPlay:GRAticule FULL;:DOTSONLY OFF (extra colon before DOTSonly. You could use DISPlay:DOTsonly OFF instead)

DISPlay:GRAticule FULL;:\*TRG (colon before a star (\*) command)

MATH:HORizontal:SCAle 1.0e-1;HORizontal:POSition 5.0el (levels of the mnemonics are different; either remove the second use of HORizontal: or place:MATH in front of HORizontal:POSition)

#### **Terminating**

This documentation uses <EOM> (End of Message) to represent a message terminator

Table 2-4: End of Message Terminator

Symbol	Meaning
<eom></eom>	Message terminator

The end-of-message terminator must be the END message (EOI asserted concurrently with the last data byte). The last data byte may be an ASCII line feed (LF) character.

This oscilloscope does not support ASCII LF only message termination. The oscilloscope always terminates outgoing messages with LF and EOI.

#### **Constructed Mnemonics**

Some header mnemonics specify one of a range of mnemonics. For example, a channel mnemonic can be CH1, CH2, CH3, or CH4. You use these mnemonics in the command just as you do any other mnemonic. For example, there is a CH1:POSition command, and there is also a CH2:POSition command. In the command descriptions, this list of choices is abbreviated as CH<x>.

#### Cursor Position Mnemonics

When cursors are displayed, commands may specify which cursor of the pair to use.

**Table 2-5: Channel Mnemonics** 

Symbol	Meaning
CH <x></x>	A channel specifier; <x> is 1 through 4.</x>

**Table 2-6: Cursor Mnemonics** 

Symbol	Meaning
CURSOR <x></x>	A cursor selector; <x> is either 1 or 2.</x>
POSITION <x></x>	A cursor selector; <x> is either 1 or 2.</x>
HPOS <x></x>	A cursor selector; <x> is either 1 or 2.</x>

#### **Math Specifier Mnemonics**

Commands can specify the mathematical waveform to use as a mnemonic in the header.

**Table 2-7: Math Specifier Mnemonics** 

Symbol	Meaning
Math <x></x>	A math waveform specifier; <x> is 1.</x>

# Measurement Specifier Mnemonics

Commands can specify which measurement to set or query as a mnemonic in the header. Up to eight automated measurements may be displayed.

**Table 2-8: Measurement Specifier Mnemonics** 

Symbol	Meaning
MEAS <x></x>	A measurement specifier; <x> is 1 through 4.</x>

#### **Channel Mnemonics**

Commands specify the channel to use as a mnemonic in the header.

#### Reference Waveform Mnemonics

Commands can specify the reference waveform to use as a mnemonic in the header.

**Table 2-9: Reference Waveform Mnemonics** 

Symbol	Meaning
REF <x></x>	A reference waveform specifier; <x> is 1, 2, 3, or 4 for 4-channel oscilloscopes and 1 or 2 for 2-channel oscilloscopes.</x>

## **Argument Types**

Commands use arguments such as enumeration, numeric, quoted string and block. Each of these arguments are listed in detail below.

#### **Enumeration**

Enter these arguments as unquoted text words. Like key words, enumeration arguments follow the same convention where the portion indicated in uppercase is required and that in lowercase is optional.

For example: SAVe: WAVEform: FILEFormat INTERNal

#### **Numeric**

Many oscilloscope commands require numeric arguments. The syntax shows the format that the oscilloscope returns in response to a query. This is also the preferred format when sending the command to the oscilloscope though any of the formats will be accepted. This documentation represents these arguments as described below.

**Table 2-10: Numeric Arguments** 

Symbol	Meaning
<nr1></nr1>	Signed integer value
<nr2></nr2>	Floating point value without an exponent
<nr3></nr3>	Floating point value with an exponent
 bin>	Digital data in binary format

Most numeric arguments will be automatically forced to a valid setting, by either rounding or truncating,, when an invalid number is input, unless otherwise noted in the command description.

#### **Quoted String**

Some commands accept or return data in the form of a quoted string, which is simply a group of ASCII characters enclosed by a single quote (') or double quote ("). The following is an example of a quoted string: "This is a quoted string". This documentation represents these arguments as follows:

**Table 2-11: Quoted String Argument** 

Symbol	Meaning
<qstring></qstring>	Quoted string of ASCII text

A quoted string can include any character defined in the 7-bit ASCII character set. Follow these rules when you use quoted strings:

- 1. Use the same type of quote character to open and close the string. For example: "this is a valid string".
- **2.** You can mix quotation marks within a string as long as you follow the previous rule. For example: "this is an 'acceptable' string".
- **3.** You can include a quote character within a string by repeating the quote. For example: "here is a "" mark".
- **4.** Strings can have upper or lower case characters.
- **5.** If you use a GPIB network, you cannot terminate a quoted string with the END message before the closing delimiter.
- **6.** A carriage return or line feed embedded in a quoted string does not terminate the string. The return is treated as another character in the string.
- 7. The maximum length of a quoted string returned from a query is 1000 characters.

Here are some invalid strings:

"Invalid string argument' (quotes are not of the same type)

Several oscilloscope commands use a block argument form, as defined in the

"test<EOI>" (termination character is embedded in the string)

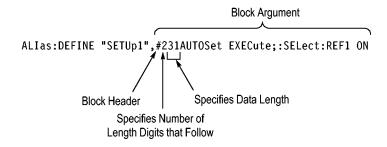
## table below.

Table 2-12: Block Argument

Block

Symbol	Meaning	
<nzdig></nzdig>	A nonzero digit character in the range of 1–9	
<dig></dig>	A digit character, in the range of 0–9	
<dchar></dchar>	A character with the hexadecimal equivalent of 00 through FF (0 through 255 decimal)	
<block></block>	A block of data bytes defined as: <block> ::= {#<nzdig><dig>[<dig>][<dchar>]  #0[<dchar>]<terminator>}</terminator></dchar></dchar></dig></dig></nzdig></block>	

<NZDig> specifies the number of <Dig> elements that follow. Taken together, the <NZDig> and <Dig> elements form a decimal integer that specifies how many <DChar> elements follow.



# **Command Groups**

This manual lists the MSO4000 and DPO4000 Series IEEE488.2 commands in two ways. First, it presents them by functional groups. Then, it lists them alphabetically. The functional group list starts below. The alphabetical list provides detail on each command. (See page 2-71, *Commands Listed in Alphabetical Order*.)

## **Acquisition Command Group**

Use the commands in the Acquisition Command Group to set up the modes and functions that control how the oscilloscope acquires signals input to the channels, and processes them into waveforms.

Using the commands in this group, you can do the following:

- Start and stop acquisitions.
- Control whether each waveform is simply acquired, averaged, or enveloped over successive acquisitions of that waveform.
- Set the controls or conditions that start and stop acquisitions.
- Control acquisition of channel waveforms.
- Set acquisition parameters.

**Table 2-13: Acquisition Commands** 

Command	Description
ACQuire?	Returns acquisition parameters
ACQuire:MAGnivu	Sets or returns the MagniVu feature
ACQuire:MAXSamplerate?	Returns the maximum real-time sample rate
ACQuire:MODe	Sets or returns the acquisition mode
ACQuire:NUMACq?	Returns number of acquisitions that have occurred
ACQuire:NUMAVg	Sets or returns the number of acquisitions for an averaged waveform
ACQuire:STATE	Starts or stops the acquisition system
ACQuire:STOPAfter	Sets or returns whether the acquisition is continuous or single sequence

## **Alias Command Group**

Use the Alias commands to define new commands as a sequence of standard commands. You may find this useful when repeatedly using the same commands to perform certain tasks like setting up measurements.

Aliases are similar to macros but do not include the capability to substitute parameters into alias bodies. The alias mechanism obeys the following rules:

- The alias name must consist of a valid IEEE488.2 message unit, which may not appear in a message preceded by a colon, comma, or a command or query program header.
- The alias name may not appear in a message followed by a colon, comma, or question mark.
- An alias name must be distinct from any keyword or keyword short form.
- An alias name cannot be redefined without first being deleted using one of the alias deletion functions.
- Alias names do not appear in response messages.

Table 2-14: Alias Commands

Command	Description
ALlas	Sets or returns the alias state
ALIas:CATalog?	Returns a list of the currently defined alias labels
ALIas:DEFine	Assigns a sequence of program messages to an alias label
ALIas:DELEte	Removes a specified alias
ALIas:DELEte:ALL	Deletes all existing aliases
ALIas:DELEte[:NAMe]	Removes a specified alias
ALIas[:STATE]	Sets or returns the alias state

## **Bus Command Group**

Use the Bus commands when working with serial or parallel bus measurements.

- Install the DPOEMBD application module when working with I<sup>2</sup>C or SPI bus signals.
- Install the DPO4COMP module when working with RS-232, RS-422, RS-485, or UART bus signals.
- Install the DPO4AUDIO module when working with I<sup>2</sup>S, Left Justified (LJ), Right Justified (RJ), or TDM bus signals.
- Install the DPO4AUTO or DPO4AUTOMAX module when working with CAN or LIN bus signals.
- Install the DPO4AUTOMAX module when working with FlexRay bus signals.

**NOTE.** LIN and FlexRay work on DPO4000s with serial numbers greater than C020000 and on all MSO4000s.

**NOTE.** The parallel bus commands work with MSO4000 Series oscilloscopes only.

**NOTE**. The Search Command Group and the Trigger Command Group also contain bus-related commands.

Table 2-15: Bus Commands

Commands	Description
BUS?	Returns the parameters for each bus
BUS:B <x>:AUDio:BITDelay</x>	Sets or returns the number of delay bits for the AUDIO bus
BUS:B <x>:AUDio:BITOrder</x>	Sets or returns the bit order for the AUDIO bus
BUS:B <x>:AUDio:CHANnel:SIZe</x>	Sets or returns the number of bits per channel for the AUDIO bus
BUS:B <x>:AUDio:CLOCk:POLarity</x>	Sets or returns the clock polarity for the AUDIO bus
BUS:B <x>:AUDio:CLOCk:SOUrce</x>	Sets or returns the clock source waveform for the AUDIO bus
BUS:B <x>:AUDio:DATa:POLarity</x>	Sets or returns the data polarity for the AUDIO bus
BUS:B <x>:AUDio:DATa:SIZe</x>	Sets or returns the number of bits per word for the AUDIO bus

Table 2-15: Bus Commands (cont.)

Commands	Description
BUS:B <x>:AUDio:DATa:SOUrce</x>	Sets or returns the data source waveform for the AUDIO bus
BUS:B <x>:AUDio:DISplay:FORMat</x>	Sets or returns the display format for the AUDIO bus
BUS:B <x>:AUDio:FRAME:SIZe</x>	Sets or returns the number of channels in each frame for the AUDIO bus
BUS:B <x>:AUDio:FRAMESync:POLarity</x>	Sets or returns the frame sync polarity for the AUDIO bus
BUS:B <x>:AUDio:FRAMESync:SOUrce</x>	Sets or returns the frame sync source waveform for the AUDIO bus
BUS:B <x>:AUDio:TYPe</x>	Sets or returns the audio format (type) for the AUDIO bus
BUS:B <x>:AUDio:WORDSel:POLarity</x>	Sets or returns the word select polarity for the AUDIO bus
BUS:B <x>:AUDio:WORDSel:SOUrce</x>	Sets or returns the word select source waveform for the AUDIO bus
BUS:B <x>:CAN:BITRate</x>	Sets or returns the bit rate for the CAN bus
BUS:B <x>:CAN:PRObe</x>	Sets or returns the probing method used to probe the CAN bus
BUS:B <x>:CAN:SAMPLEpoint</x>	Sets or returns the sample point (in %) to sample during each bit period
BUS:B <x>:CAN:SOUrce</x>	Sets or returns the CAN data source
BUS:B <x>:DISplay:FORMAt</x>	Sets the display format for the numerical information in the specified bus waveform
BUS:B <x>:DISplay:TYPe</x>	Sets the display type for the specified bus
BUS:B <x>:FLEXray:BITRate</x>	Sets or returns the bit rate for FLEXRAY
BUS:B <x>:FLEXray:CHannel</x>	Sets or returns the FLEXRAY ID format
BUS:B <x>:FLEXray:SIGnal</x>	Sets or returns the FLEXRAY standard
BUS:B <x>:FLEXray:SOUrce</x>	Sets or returns the FLEXRAY data source
BUS:B <x>:l2C:ADDRess:RWINClude</x>	Sets and returns whether the read/write bit is included in the address
BUS:B <x>:I2C{:CLOCK :SCLK}:SOUrce</x>	Sets or returns the I2C SCLK source
BUS:B <x>:I2C{:DATA :SDATA}:SOUrce</x>	Sets or returns the I2C SDATA source
BUS:B <x>:LABel</x>	Sets or returns the waveform label for the specified bus
BUS:B <x>:LIN:BITRate</x>	Sets or returns the bit rate for LIN
BUS:B <x>:LIN:IDFORmat</x>	Sets or returns the LIN ID format
BUS:B <x>:LIN:POLARity</x>	Sets or returns the LIN polarity
BUS:B <x>:LIN:SAMPLEpoint</x>	Sets or returns the sample point (in %) at which to sample during each bit period

Table 2-15: Bus Commands (cont.)

Commands	Description
BUS:B <x>:LIN:SOUrce</x>	Sets or returns the LIN data source
BUS:B <x>:LIN:STANDard</x>	Sets or returns the LIN standard
BUS:B <x>:PARallel:BIT<x>:SOUrce</x></x>	Sets or returns the Parallel bit source for the specified bus
BUS:B <x>:PARallel:CLOCK:EDGE</x>	Sets or returns the Parallel clock edge for the specified bus
BUS:B <x>:PARallel:CLOCK:ISCLOCKed</x>	Sets or returns the Parallel bus clock function for the specified bus
BUS:B <x>:PARallel:CLOCK:SOUrce</x>	Sets or returns the Parallel clock source for the specified bus
BUS:B <x>:PARallel:WIDth</x>	Sets or returns the width of the Parallel bus
BUS:B <x>:POSition</x>	Sets or returns the position of the specified bus waveform
BUS:B <x>:RS232C:BITRate</x>	Sets or returns the RS-232 bit rate for the specified bus
BUS:B <x>:RS232C:DATABits</x>	Sets or returns the number of bits for the data frame
BUS:B <x>:RS232C:DELIMiter</x>	Sets or returns the RS-232 delimiting value for a packet on the specified bus
BUS:B <x>:RS232C:DISplaymode</x>	Sets or returns the display mode for the specified bus display and event table
BUS:B <x>:RS232C:PARity</x>	Sets or returns parity for RS-232 data
BUS:B <x>:RS232C:POLarity</x>	Sets or returns the RS-232C polarity for the specified bus
BUS:B <x>:RS232C:RX:SOUrce</x>	Sets or returns the RS-232 RX source
BUS:B <x>:RS232C:TX:SOUrce</x>	Sets or returns the RS-232 TX Source
BUS:B <x>:SPI:BITOrder</x>	Sets or returns the bit order for the specified SPI bus
BUS:B <x>:SPI{:CLOCK :SCLK}:POLARity</x>	Sets or returns the SPI SCLK polarity
BUS:B <x>:SPI{:CLOCK :SCLK}:SOUrce</x>	Sets or returns the SPI SCLK source
BUS:B <x>:SPI:DATA{:IN :MISO}:POLARity</x>	Sets or returns the SPI MISO polarity
BUS:B <x>:SPI:DATA{:IN :MISO}:SOUrce</x>	Sets or returns the SPI MISO source
BUS:B <x>:SPI:DATA{:OUT :MOSI}: POLARity</x>	Sets or returns the SPI MOSI polarity
BUS:B <x>:SPI:DATA{:OUT :MOSI}:SOUrce</x>	Sets or returns the SPI MOSI source
BUS:B <x>:SPI:DATA:SIZe</x>	Sets or returns the number of bits per word for the specified bus
BUS:B <x>:SPI:FRAMING</x>	Sets or returns the SPI framing type
BUS:B <x>:SPI:IDLETime</x>	Sets or returns the SPI bus idle time in seconds for the specified bus

Table 2-15: Bus Commands (cont.)

Commands	Description
BUS:B <x>:SPI{:SELect :SS}:POLARity</x>	Sets or returns the SPI SS polarity
BUS:B <x>:SPI{:SELect :SS}:SOUrce</x>	Sets or returns the SPI SS source
BUS:B <x>:STATE</x>	Turns the specified bus on and off
BUS:B <x>:TYPE</x>	Sets or returns the specified bus type
BUS:B <x>:USB:BITRate</x>	Sets or returns the USB bit rate
BUS:B <x>:USB:PRObe</x>	Sets or returns the type of probes attached to the USB signal
BUS:B <x>:USB:SOUrce:DIFFerential</x>	Sets or returns the USB source channels when using a differential probe
BUS:B <x>:USB:SOUrce:DMINus</x>	Sets or returns the USB D- source channel
BUS:B <x>:USB:SOUrce:DPLUs</x>	Sets or returns the USB D+ source channel
BUS:LOWerthreshold:CH <x></x>	Sets or returns the lower threshold for each channel
BUS:THReshold:CH <x></x>	Sets or returns the threshold for a channel
BUS:THReshold:D <x></x>	Sets or returns the threshold for a digital channel
BUS:UPPerthreshold:CH <x></x>	Sets or returns the upper threshold for each channel

## **Calibration and Diagnostic Command Group**

The Calibration and Diagnostic commands provide information about the current state of oscilloscope calibration. They also initiate internal signal path calibration (SPC) or execute diagnostic tests. Commands that are specific to factory calibration are not described in this manual. They are described in the Service manual, located on the DPO4000 Documentation CD-ROM in PDF format. You can also order a printed copy.

**Table 2-16: Calibration and Diagnostic Commands** 

Command	Description
*CAL?	Instructs the oscilloscope to perform self-calibration and returns the oscilloscope self calibration status
CALibrate:FACtory:STATus?	Returns the factory calibration status value saved in nonvolatile memory
CALibrate:INTERNal	Starts a signal path compensation
CALibrate:INTERNal:STARt	Starts the internal signal path calibration
CALibrate:INTERNal:STATus?	Returns the current status of the internal signal path calibration
CALibrate:RESults?	Returns the status of all calibration subsystems without performing an SPC operation
CALibrate:RESults:FACtory?	Returns the status of internal and factory calibration
CALibrate:RESults:SPC?	Returns the results of the last SPC operation
DIAg:LOOP:OPTion	Sets the self-test loop option
DIAg:LOOP:OPTion:NTIMes	Sets the self-test loop option to run N times
DIAg:LOOP:STOP	Stops the self-test at the end of the current loop
DIAg:RESUIt:FLAg?	Returns the pass/fail status from the last self-test sequence execution
DIAg:RESUlt:LOG?	Returns the internal results log from the last self-test sequence execution
DIAg:SELect: <function></function>	Selects one of the available self-test areas
DIAg:STATE	Sets the oscilloscope operating state
DIAg:SELect	Runs self tests on the specified system subsystem

## **Cursor Command Group**

Use the commands in the Cursor Command Group to control the cursor display and readout. You can use these commands to control the setups for cursor 1 and cursor 2, such as cursor position.

You can also use the commands to select one of the following cursor functions:

- Off. Turns off the display of all cursors.
- Waveform Cursors. Consists of two cursors. Waveform cursors enable you to conveniently measure waveform amplitude and time.
- Screen Cursors. Consists of two pairs of independent horizontal and vertical cursors. You can use these cursors to indicate an arbitrary position within the waveform display area.

**Table 2-17: Cursor Commands** 

Command	Description
CURSor?	Returns cursor settings
CURSor:DDT?	Returns the cursor deltaY/deltaT (dY/dT) readout
CURSor:FUNCtion	Sets or returns the cursor type
CURSor:HBArs?	Returns hbar cursor settings
CURSor:HBArs:DELTa?	Returns hbars cursors vertical difference
CURSor:HBArs:POSITION <x></x>	Sets or returns the hbar cursor <x> vertical position</x>
CURSor:HBArs:UNIts	Returns hbar cursor units
CURSor:HBArs:USE	Sets the horizontal bar cursor measurement scale, for use with ratio cursors
CURSor:MODe	Sets or returns whether cursors move in unison or separately
CURSor:VBArs?	Sets or returns the position of vertical bar cursors
CURSor:VBArs:ALTERNATE <x>?</x>	Returns the alternate readout for the waveform (Vbar) cursors
CURSor:VBArs:DELTa?	Returns the horizontal difference between vbar cursors
CURSor:VBArs:HPOS <x>?</x>	Returns the vertical value of the specified vertical bar tick
CURSor:VBArs:POSITION <x></x>	Sets or returns the vbar cursor <x> horizontal position</x>
CURSor:VBArs:UNIts	Sets or returns the horizontal units for vbar cursors
CURSor:VBArs:USE	Sets the vertical bar cursor measurement scale
CURSor:VBArs:VDELTa?	Returns the vertical difference between the two vertical bar cursor ticks
CURSor:XY:POLar:RADIUS:DELta?	Returns the difference between the cursors X radius and the cursor Y radius

**Table 2-17: Cursor Commands (cont.)** 

Command	Description
CURSor:XY:POLar:RADIUS:POSITION <x>?</x>	Returns the polar radius of the specified cursor
CURSor:XY:POLar:RADIUS:UNIts?	Returns the polar radius units
CURSor:XY:POLar:THETA:DELta?	Returns the XY cursor polar coordinate delta
CURSor:XY:POLar:THETA:POSITION <x>?</x>	Returns the cursor X or cursor Y polar coordinate
CURSor:XY:POLar:THETA:UNIts?	Returns the cursor polar coordinate units
CURSor:XY:PRODUCT:DELta?	Returns the difference between the cursors X position and cursor Y position
CURSor:XY:PRODUCT:POSITION <x>?</x>	Returns the position of the X or Y cursor used to calculate the X × Y cursor measurement
CURSor:XY:PRODUCT:UNIts?	Returns the XY cursor product units
CURSor:XY:RATIO:DELta?	Returns the ratio of the difference between the cursor X position and cursor Y position
CURSor:XY:RATIO:POSITION <x>?</x>	Returns the X or Y position for the specified cursor
CURSor:XY:RATIO:UNIts?	Returns the X and Y cursor units for the ratio measurement
CURSor:XY:READOUT	Sets or returns the XY cursor readout selection.
CURSor:XY:RECTangular:X:DELta?	Returns the cursor X delta value in rectangular coordinates
CURSor:XY:RECTangular:X:POSITION <x></x>	Sets or returns the cursor X rectangular coordinates
CURSor:XY:RECTangular:X:UNIts?	Returns the Cursor X rectangular units
CURSor:XY:RECTangular:Y:DELta?	Returns The cursor Y delta value in rectangular coordinates
CURSor:XY:RECTangular:Y:POSITION <x>&gt;</x>	Sets or returns the cursor Y rectangular coordinate
CURSor:XY:RECTangular:Y:UNIts?	Returns the cursor Y rectangular units

## **Display Command Group**

Use the commands in the Display Command Group to change the graticule style, the display intensities, and to set the characteristics of the waveform display.

**NOTE.** Your settings globally affect all displayed waveforms.

**Table 2-18: Display Commands** 

Command	Description
DISplay?	Returns current display settings
DISplay:CLOCk	Sets or returns the display of the date/time stamp
DISplay:DIGital:HElght	Sets or returns the number of available digital waveform position slots
DISplay:GRAticule	Sets or returns the type of graticule that is displayed
DISplay:FORMat	Sets or returns the display format
DISplay:INTENSITy?	Returns all display intensity settings
DISplay:INTENSITy:BACKLight	Sets or returns the backlight intensity for the display
DISplay:INTENSITy:GRAticule	Sets or returns the graticule intensity for the display
DISplay:INTENSITy:WAVEform	Sets or returns the intensity of the waveforms
DISplay:PERSistence	Sets or returns display persistence setting
DISplay:STYle:DOTsonly	Sets a dots-only display
MESSage	Sets or queries message box (screen annotation) parameters
MESSage:BOX	Sets or returns the coordinates of the message box
MESSage:CLEAR	Clears the contents of the message box.
MESSage:SHOW	Sets or returns the contents of the message box
MESSage:STATE	Controls the display of the message box

## **Ethernet Command Group**

Use the commands in the Ethernet Command Group to set up the Ethernet remote interface.

**Table 2-19: Ethernet Commands** 

Command	Description
ETHERnet:DHCPbootp	Sets or returns the network initialization search for a DHCP/BOOTP server
ETHERnet:DNS:IPADDress	Sets or returns the network Domain Name Server (Dns) IP address
ETHERnet:DOMAINname	Sets or returns the network domain name
ETHERnet:ENET:ADDress?	Returns the Ethernet address value assigned to the oscilloscope

Table 2-19: Ethernet Commands (cont.)

Command	Description
ETHERnet:GATEWay:IPADDress	Sets or returns the remote interface gateway IP address
ETHERnet:HTTPPort	Sets or returns the remote interface HTTP port value
ETHERnet:IPADDress	Sets or returns the IP address assigned to the oscilloscope
ETHERnet:NAME	Sets or returns the network name assigned to the oscilloscope
ETHERnet:PASSWord	Sets or returns the Ethernet access password
ETHERnet:PING	Causes the oscilloscope to ping the gateway IP address
ETHERnet:PING:STATUS?	Returns the results from pinging the gateway IP address
ETHERnet:SUBNETMask	Sets or returns the remote interface subnet mask value

## **File System Command Group**

Use the commands in the File System Command Group to help you use CompactFlash and USB media. You can use the commands to do the following:

- List the contents of a directory
- Create and delete directories
- Create, read, rename, or delete a file
- Format media

When using these commands, keep the following points in mind:

- File arguments are always enclosed within double quotes: "D:/MYDIR/TEK00001.SET"
- File names follow the non-case sensitive, MSDOS format: [DRIVE:][\PATH\]filename
- Path separators may be either forward slashes (/) or back slashes (\)

**NOTE.** Using back slash as a path separator may produce some unexpected results, depending on how your application treats escaped characters. Many applications recognize the sequence of back slash followed by an alphabetic character as an escaped character, and, as such, interpret that alphabetic character as a control character. For example, the sequence "\n" may be interpreted as a newline character; "\t" may be interpreted as a tab character. To ensure that this interpretation does not occur, you can use double back slashes. For example, "D:\\testfile.txt".

**Table 2-20: File System Commands** 

Command	Description
FILESystem?	Returns the file system state
FILESystem:CWD	Sets or returns the current working directory for FILESystem commands
FILESystem:DELEte	Deletes a named file or directory
FILESystem:DIR?	Returns a list of directory contents
FILESystem:FORMat	Formats a named drive
FILESystem:FREESpace?	Returns the number of bytes of free space on the current drive
FILESystem:LDIR?	Returns a semicolon separated list of every file and directory in a folder.
FILESystem:MKDir	Creates a new directory
FILESystem:READFile	Writes the contents of the specified file to the specified interface
FILESystem:REName	Assigns a new name to an existing file
FILESystem:RMDir	Deletes a named directory
FILESystem:WRITEFile	Writes the specified block data to the oscilloscope current working directory

## **Hard Copy Command Group**

Use the commands in the Hard Copy Command Group to make hard copies. PictBridge commands belong to a separate group. (See page 2-32, *PictBridge Command Group*.)

**Table 2-21: Hard Copy Commands** 

Command	Description
HARDCopy	Sends a copy of the screen display to the selected printer
HARDCopy:ACTIVeprinter	Sets or returns the currently active printer

Table 2-21: Hard Copy Commands (cont.)

Command	Description
HARDCopy:INKSaver	Changes hard copy output to print color traces and graticule on a white background
HARDCopy:LAYout	Sets or returns the page orientation for hard copy
HARDCopy:PREVIEW	Previews the current screen contents with the InkSaver palette applied
HARDCopy:PRINTer:ADD	Adds a network printer to the list of available printers
HARDCopy:PRINTer:DELete	Removes a network printer from the list of available printers
HARDCopy:PRINTer:LIST?	Returns the list of currently attached printers
HARDCopy:PRINTer:REName	Renames a network printer in the list of available printers

# **Histogram Command Group**

Use the commands in the Histogram Command Group to set up a histogram for measurements.

**Table 2-22: Histogram Commands** 

Description
Returns all histogram parameters
Sets or returns the histogram box coordinates
Clears the histogram count and statistics
Returns the histogram data
Sets or returns the scaling of the histogram display
Returns the time of the last bin of the histogram
Sets or returns the type of the histogram, vertical or horizontal
Sets or queries the source used to create the histogram
Returns the time of the first bin of the histogram

# **Horizontal Command Group**

Use the commands in the Horizontal Command Group to control the oscilloscope horizontal parameters.

**Table 2-23: Horizontal Commands** 

Command	Description
HORizontal?	Returns settings for the horizontal commands
HORizontal:DELay:MODe	Sets or returns the horizontal delay mode
HORizontal:DELay:TIMe	Sets or returns the horizontal delay time
HORizontal:DIGital:RECOrdlength: MAGnivu?	Returns the record length of the MagniVu digital acquisition
HORizontal:DIGital:RECOrdlength:MAIN?	Returns the record length of the main digital acquisition
HORizontal:DIGital:SAMPLERate: MAGnivu?	Returns the sample rate of the Magnivu digital acquisition
HORizontal:DIGital:SAMPLERate:MAIN?	Returns the sample rate of the main digital acquisition
HORizontal:POSition	Sets or returns the horizontal position, in percent, that is used when delay is off

Table 2-23: Horizontal Commands (cont.)

Command	Description
HORizontal:PREViewstate?	Returns the display system preview state
HORizontal:RECOrdlength	Sets or returns the record length
HORizontal:SAMPLERate	Sets or returns the sample rate
HORizontal:SCAle	Sets or returns the horizontal scale

# **Mark Command Group**

Use the commands in the Mark Command Group to identify areas of the acquired waveform that warrant further investigation.

Table 2-24: Mark Commands

Command	Description
MARK	Move to the next or previous mark on the waveform or returns all learnable settings from the mark commands
MARK:CREATE	Creates a mark on a particular waveform or all waveforms in a column
MARK:DELEte	Deletes a mark on a particular waveform, all waveforms in a column, or all marks
MARK:FREE?	Returns how many marks are free to be used
MARK:SELected:END?	Returns the end of the selected mark, in terms of 0 to 100% of the waveform
MARK:SELected:FOCUS?	Returns the focus of the selected mark, in terms of 0 to 100% of the waveform
MARK:SELected:MARKSINCOLumn?	Returns how many marks are in the current zoom pixel column
MARK:SELected:OWNer?	Returns the owner of the selected mark
MARK:SELected:SOURCE?	Returns the source waveform of the selected mark
MARK:SELected:STARt?	Returns the start of the selected mark, in terms of 0 to 100% of the waveform
MARK:SELected:STATe?	Returns the on or off state of the selected mark
MARK:SELected:ZOOm:POSition?	Returns the position of the selected mark, in terms of 0 to 100% of the upper window
MARK:TOTal?	Returns how many marks are used

## **Math Command Group**

Use the commands in the Math Command Group to create and define a math waveform. Use the available math functions to define your math waveform.

The math waveform you create depends on sources listed in the math expression. If you change these sources, the math waveform you previously defined will be affected.

Math expressions can be simple, containing no mathematical computation, such as CH1, which specifies that a waveform shows the signal source of Channel 1. Math expressions can also be complex, consisting of up to 128 characters and comprising many sources, functions, and operands.

When a live waveform is updated or a reference waveform is altered, math waveforms containing those waveforms as sources are also updated to reflect the changes. Remember that sources must exist, but do not need to be displayed, to be used in and to update math waveforms.

**Table 2-25: Math Commands** 

Command	Description
MATH[1]?	Returns the definition of the math waveform
MATH[1]:DEFine	Sets or returns the current math function as a text string
MATH[1]:HORizontal:SCAle	Sets or returns the math horizontal display scale for FFT or for Dual Math waveforms
MATH[1]:HORizontal:UNIts	Returns the math waveform horizontal unit value
{MATH MATH1}:LABel	Sets or queries the waveform label for the math waveform
MATH[1]:SPECTral:MAG	Sets or returns the units of spectral magnification in the math string
MATH[1]:SPECTral:WINdow	Sets or returns the window function for math waveform spectral input data
MATH[1]:VERTical:POSition	Sets or returns the vertical position of the currently selected math type
MATH[1]:VERTical:SCAle	Sets or returns the vertical scale of the currently selected math type
MATH[1]:VERTical:UNIts	Returns the math waveform vertical units
MATH[1]:HORizontal:POSition	Sets or returns the math horizontal display position for FFT or (non-live) math reference waveforms
MATH[1]:TYPe	Sets or returns the math waveform mode type

Table 2-25: Math Commands (cont.)

Command	Description
MATHVAR?	Returns all numerical values used within math expressions
MATHVAR:VAR <x></x>	Sets or returns numerical values you can use within math expressions

## **Measurement Command Group**

Use the commands in the Measurement Command Group to control the automated measurement system.

Up to four automated measurements can be displayed on the screen. In the commands, these measurement readouts are named MEAS<x>, where <x> is the measurement number

In addition to the four displayed measurements, the measurement commands let you specify an additional measurement, IMMed. The immediate measurement has no front-panel equivalent. Immediate measurements are never displayed. Because they are computed only when needed, immediate measurements slow the waveform update rate less than displayed measurements.

Whether you use displayed or immediate measurements, use the VALue query to obtain measurement results.

Measurement commands can set and query measurement parameters. You can assign some parameters, such as waveform sources, differently for each measurement. Other parameters, such as reference levels, have only one value, which applies to all measurements.

**Table 2-26: Measurement Commands** 

Command	Description
MEASUrement?	Returns all measurement parameters
MEASUrement:CLEARSNapshot	Removes the measurement snapshot display
MEASUrement:GATing	Sets or returns the measurement gating
MEASUrement:IMMed?	Returns all immediate measurement setup parameters
MEASUrement:IMMed:DELay?	Returns information about the immediate delay measurement
MEASUrement:IMMed:DELay:DIRection	Sets or returns the search direction to use for immediate delay measurements
MEASUrement:IMMed:DELay:EDGE <x></x>	Sets or returns the slope of the edge used for immediate delay "from" and "to" waveform measurements

Table 2-26: Measurement Commands (cont.)

Command	Description
MEASUrement:IMMed:SOUrce <x></x>	Sets or returns the "from" source for all single channel immediate measurements
	Sets or returns the source to measure "to" for two-channel measurements
MEASUrement:IMMed:TYPe	Sets or returns the type of the immediate measurement
MEASUrement:IMMed:UNIts?	Returns the units of the immediate measurement
MEASUrement:IMMed:VALue?	Returns the value of the immediate measurement
MEASUrement:INDICators?	Returns all measurement indicator parameters
MEASUrement:INDICators:HORZ <x>?</x>	Returns the position of the specified horizontal measurement indicator
MEASUrement:INDICators:NUMHORZ?	Returns the number of horizontal measurement indicators currently being displayed
MEASUrement:INDICators:NUMVERT?	Returns the number of vertical measurement indicators currently being displayed
MEASUrement:INDICators:STATE	Sets or returns the state of visible measurement indicators
MEASUrement:INDICators:VERT <x>?</x>	Returns the value of the specified vertical measurement indicator
MEASUrement:MEAS <x>?</x>	Returns all measurement parameters
MEASUrement:MEAS <x>:COUNt?</x>	Returns the number of values accumulated since the last statistical reset
MEASUrement:MEAS <x>:DELay?</x>	Returns the delay measurement parameters for the specified measurement
MEASUrement:MEAS <x>:DELay:DIRection</x>	Sets or returns the search direction to use for delay measurements
MEASUrement:MEAS <x>:DELay:EDGE<x></x></x>	Sets or returns the slope of the edge to use for delay "from" and "to" waveform measurements
MEASUrement:MEAS <x>:MAXimum?</x>	Returns the maximum value found since the last statistical reset
MEASUrement:MEAS <x>:MEAN?</x>	Returns the mean value accumulated since the last statistical reset
MEASUrement:MEAS <x>:MINImum?</x>	Returns the minimum value found since the last statistical reset

Table 2-26: Measurement Commands (cont.)

Command	Description
MEASUrement:MEAS <x>:SOUrce<x></x></x>	Sets or returns the "from" source for all single channel immediate measurements
	Sets or returns the source to measure "to" for two-channel measurements
MEASUrement:MEAS <x>:STATE</x>	Sets or returns whether the specified measurement slot is computed and displayed
MEASUrement:MEAS <x>:STDdev?</x>	Returns the standard deviation of values accumulated since the last statistical reset
MEASUrement:MEAS <x>:TYPe</x>	Sets or returns the measurement <x> type</x>
MEASUrement:MEAS <x>:UNIts?</x>	Returns measurement <x> units</x>
MEASUrement:MEAS <x>:VALue?</x>	Returns the value of measurement <x></x>
MEASUrement:METHod	Sets or returns the method used for calculating reference levels
MEASUrement:REFLevel?	Returns the current reference level parameters
MEASUrement:REFLevel:ABSolute:HIGH	Sets or returns the top reference level for rise time
MEASUrement:REFLevel:ABSolute:LOW	Sets or returns the low reference level for rise time
MEASUrement:REFLevel:ABSolute:MID	Sets or returns the mid reference level for measurements
MEASUrement:REFLevel:ABSolute:MID <x></x>	Sets or returns the mid reference level in absolute units (e.g. volts)
MEASUrement:REFLevel:ABSolute:MID2	Sets or returns the mid reference level for delay "to" measurements
MEASUrement:REFLevel:METHod	Sets or returns the method for assigning high and low reference levels
MEASUrement:REFLevel:PERCent:HIGH	Sets or returns the top reference percent level for rise time
MEASUrement:REFLevel:PERCent:LOW	Sets or returns the low reference percent level for rise time
MEASUrement:REFLevel:PERCent:MID	Sets or returns the mid reference percent level for waveform measurements
MEASUrement:REFLevel:PERCent:MID2	Sets or returns the mid reference percent level for second waveform measurements
MEASUrement:REFLevel:ABSolute:MID <x></x>	Sets or returns the mid reference level for the specified channel in absolute volts
MEASUrement:REFLevel:PERCent:MID <x></x>	Sets or returns the mid reference level for the specified channel in percent
MEASUrement:SNAPShot	Displays the measurement snapshot list

Table 2-26: Measurement Commands (cont.)

Command	Description
MEASUrement:STATIstics	Clears or returns all of the statistics accumulated for all period measurements (MEAS1 through MEAS4)
MEASUrement:STATIstics:MODE	Turns measurement statistics on or off
MEASUrement:STATIstics:WElghting	Controls the responsiveness of the mean and standard deviation to waveform changes

# **Miscellaneous Command Group**

Use the commands in the Miscellaneous Command Group to perform actions that do not fit into other categories.

Several commands and queries are common to all 488.2-1987 devices. The 488.2-1987 standard defines these commands. The common commands begin with an asterisk (\*) character.

**Table 2-27: Miscellaneous Commands** 

Command	Description
AUTOSet	Sets the vertical, horizontal and trigger controls to provide a stable display of the appropriate waveform. This is equivalent to pressing the front panel Autoset button
AUTOSet:ENAble	Enables or disables the autoset feature
CLEARMenu	Clears the current menu from the display
DATE	Sets or returns the date displayed by the oscilloscope
*DDT	Sets or returns the commands that will be executed by the group execute trigger
DESkew	Causes the deskew values for all channels to be set to the recommended values
DESkew:DISPlay	Sets or returns the state of the deskew table display
FPAnel:PRESS	Simulates the action of pressing a specified front-panel button
FPAnel:TURN	Duplicates the action of turning a specified front-panel control knob
GPIBUsb:ADDress?	Returns the current GPIB address
GPIBUsb:ID?	Returns the identification string of the connected adaptor module and firmware version

Table 2-27: Miscellaneous Commands (cont.)

Command	Description
HEADer	Sets or returns the Response Header Enable State
ID?	Returns identifying information about the oscilloscope and its firmware
*IDN?	Returns the same information as the ID? command except the data is formatted according to Tektronix Codes & Formats
LANGuage	Sets or returns the user interface display language
LOCk	Sets or returns the front panel lock state
*LRN?	Returns a listing of oscilloscope settings
NEWpass	Changes the password for user protected data
PASSWord	Enables the *PUD and NEWpass set commands
REM	Specifies a comment, which is ignored by the oscilloscope
SET?	Returns a listing of oscilloscope settings
TEKSecure	Initializes both waveform and setup memories
TIME	Sets or returns the time displayed by the oscilloscope
TOTaluptime?	Returns the total number of hours that the oscilloscope has been turned on since the nonvolatile memory was last programmed
*TRG	Performs the group execute trigger (GET)
*TST?	Tests the interface and returns the status
UNLock	Unlocks front panel
USBTMC?	Returns the USBTMC information used by the USB hosts to determine the instrument interfaces
USBTMC:PRODUCTID:DECimal?	Returns the USBTMC product ID
USBTMC:PRODUCTID:HEXadecimal?	Returns the USBTMC product ID
USBTMC:SERIALnumber?	Returns the instrument serial number
USBTMC:VENDORID:DECimal?	Returns the USBTMC vendor ID
USBTMC:VENDORID:HEXadecimal?	Returns the USBTMC vendor ID
VERBose	Sets or returns the verbose state

# **PictBridge Command Group**

Use the commands in the PictBridge Command Group to store printer settings.

Table 2-28: PictBridge Commands

Command	Description
PICTBridge:DATEPrint	Enables or disables printing the date on the print output
PICTBridge:DEFault	Sets the arguments for all PICTBridge commands to their default values
PICTBridge:IDPrint	Enables or disables printing the oscilloscope model and serial number on the print output
PICTBridge:IMAGESize	Sets or returns the image print size
PICTBridge:PAPERSize	Sets the output print paper size
PICTBridge:PAPERType	Sets or returns the paper type
PICTBridge:PRINTQual	Sets or returns the output print quality
USBDevice:CONFigure	Enables or disables the rear USB port for use with Pictbridge printers

## **Power Command Group**

Use the commands in the Power Command Group for power analysis. The power measurements include:

- Power quality
- Switching loss
- Safe operating area
- Harmonics
- Ripple
- Modulation analysis

This command group is available when the DPO4PWR application module is installed.

**Table 2-29: Power Commands** 

Command	Description
POWer:CURRENTSOurce	Sets or returns the current source for the power application
POWer:DISplay	Sets or returns the display state for the power application
POWer:GATESOurce	Sets or returns the gate source for the power application

**Table 2-29: Power Commands (cont.)** 

Command	Description
POWer:GATing	Sets or returns the power application gating
POWer:HARMonics:DISPlay:SELect	Sets or returns the harmonics to be displayed when the harmonics standard is None
POWer:HARMonics:DISPlay:TYPe	Sets or returns the display type for harmonics tests
POWer:HARMonics:FREQRef	Sets or returns the frequency reference waveform for harmonics tests
POWer:HARMonics:FREQRef: FIXEDFREQValue	Sets or returns the fixed reference frequency value for harmonics measurements
POWer:HARMonics:IEC:CLAss	Sets or returns the filtering class for IEC harmonics
POWer:HARMonics:IEC:FILter	Sets or returns the enabled state for filtering of IEC harmonics
POWer:HARMonics:IEC:FUNDamental	Sets or returns the fundamental current for IEC harmonics
POWer:HARMonics:IEC:GROUPing	Sets or returns the enabled state for grouping of IEC harmonics
POWer:HARMonics:IEC:INPUTPOWer	Sets of returns the class D input power for IEC harmonics
POWer:HARMonics:IEC:LINEFREQuency	Sets or returns the line frequency for the IEC standard
POWer:HARMonics:IEC:OBSPERiod	Sets or returns the IEC observation period
POWer:HARMonics:IEC:POWERFACtor	Sets or returns the power factor for IEC harmonics
POWer:HARMonics:MIL:FUNDamental: CALCmethod	Sets or returns the measurement method for the MIL harmonics fundamental frequency
POWer:HARMonics:MIL:FUNDamental: USER:CURRent	Sets or returns RMS amperes for User calculation method
POWer:HARMonics:MIL:LINEFREQuency	Sets or returns the line frequency for MIL-STD-1399 harmonics tests
POWer:HARMonics:MIL:POWERLEVel	Sets or returns the power level for MIL-STD-1399 harmonics tests
POWer:HARMonics:NR_HARMonics	Sets of returns the number of harmonics (a value in the range of 20 to 400) when the harmonics standard is NONe
POWer:HARMonics:RESults:HAR<1-400>: FREQuency?	Returns the frequency of the harmonic

Table 2-29: Power Commands (cont.)

Command	Description
POWer:HARMonics:RESults:HAR<1-400>: IECMAX?	The IEC standard specifies harmonics measurements to be computed in windows of time, with each time window being nominally 200 ms. This returns the maximum of the RMS magnitude of the harmonic, computed across successive 200 ms time windows within an observation period entered by the user
POWer:HARMonics:RESults:HAR<1-400>: LIMit?	The IEC and MIL standards specify a limit for each harmonic magnitude. Returns the limit in absolute units, or as a percentage of the fundamental as specified by the standard. IEC Class C (Table 2) and MIL standards specify the limit as a percentage of the fundamental
POWer:HARMonics:RESults:HAR<1-400>: PHASe?	Returns the phase of the harmonic in degrees. The phase is measured relative to the zero-crossing of the reference waveform. When there is no reference waveform, the phase is relative to the fundamental component
POWer:HARMonics:RESults:HAR<1-400>: RMS:ABSolute?	Returns the RMS magnitude of the harmonic expressed in absolute units
POWer:HARMonics:RESults:HAR<1-400>: RMS:PERCent?	Returns the RMS magnitude of the harmonic expressed as a percentage of the fundamental
POWer:HARMonics:RESults:HAR<1-400>: TEST:IEC:CLASSALIMit?	Returns PASS, FAIL or NA. Specifies if the IEC Class A higher harmonic limit (and conditions) are met
POWer:HARMonics:RESults:HAR<1-400>: TEST:IEC:NORMAL?	Returns PASS, FAIL or NA. Specifies if the Normal IEC harmonic limits are met
POWer:HARMonics:RESults:HAR<1-400>: TEST:IEC:POHCLIMit?	Returns PASS, FAIL or NA. Specifies if the higher harmonic limit (and conditions) for the 21st and higher order odd harmonics are met
POWer:HARMonics:RESults:HAR<1-400>: TEST:MIL:NORMAL?	Returns the test result for the specified harmonic for the MIL-STD-1399 testing standard
POWer:HARMonics:RESults:IEC: FUNDamental?	Returns the IEC fundamental frequency
POWer:HARMonics:RESults:IEC: HARM3ALTernate?	Returns the IEC harmonics test result for the 3rd harmonic: PASS, FAIL or NA
POWer:HARMonics:RESults:IEC: HARM5ALTernate?	Returns the IEC harmonics test result for the 5th harmonic: PASS, FAIL or NA
POWer:HARMonics:RESults:IEC:POHC?	Returns the IEC POHC measurement

Table 2-29: Power Commands (cont.)

Command	Description
POWer:HARMonics:RESults:IEC:POHL?	Returns the IEC POHL measurement
POWer:HARMonics:RESults:IEC:POWer?	Returns the IEC input power measurement
POWer:HARMonics:RESults:IEC: POWERFactor?	Returns the IEC power factor measurement
POWer:HARMonics:RESults:PASSFail?	Returns the overall harmonics test result: PASS, FAIL or NA
POWer:HARMonics:RESults:RMS?	Returns the root mean square value of the source waveform
POWer:HARMonics:RESults:SAVe	Saves the harmonic results to the specified file in CSV format
POWer:HARMonics:RESults:THDF?	Returns the Total Harmonic Distortion (THD) in percentage, measured as a ratio to the RMS value of the fundamental component of the source waveform
POWer:HARMonics:RESults:THDR?	Returns the Total Harmonic Distortion (THD) in percentage, measured as a ratio to the RMS value of the source waveform
POWer:HARMonics:SOURce	Sets or returns the source waveform for harmonics tests
POWer:HARMonics:STANDard	Sets or returns the standard for harmonics tests
POWer:INDICators	Sets or returns the state of the measurement indicators for the power application
POWer:MODulation:SOUrce	Sets or returns the source waveform for modulation tests
POWer:MODulation:TYPe	Sets or returns the modulation type
POWer:QUALity:APPpwr?	Returns the apparent power measurement
POWer:QUALity:DISplay:APPpwr	Sets or returns the display state for the apparent power readout
POWer:QUALity:DISplay:FREQuency	Sets or returns the display state for the frequency readout
POWer:QUALity:DISplay:ICRESTfactor	Sets or returns the display state for the current crest factor readout
POWer:QUALity:DISplay:IRMS	Sets or returns the display state for the rms current (IRMS) readout
POWer:QUALity:DISplay:PHASEangle	Sets or returns the display state for the phase angle readout
POWer:QUALity:DISplay:POWERFACtor	Sets or returns the display state for the power factor readout
POWer:QUALity:DISplay:REACTpwr	Sets or returns the display state for the reactive power readout

Table 2-29: Power Commands (cont.)

Command	Description
POWer:QUALity:DISplay:TRUEpwr	Sets or returns the display state for the true power readout
POWer:QUALity:DISplay:VCRESTfactor	Sets or returns the display state for the voltage crest factor readout
POWer:QUALity:DISplay:VRMS	Sets or returns the display state for the rms voltage (VRMS) readout
POWer:QUALity:FREQREFerence	Sets or returns the power quality frequency reference
POWer:QUALity:FREQuency?	Returns the frequency measurement
POWer:QUALity:ICRESTfactor?	Returns the current crest factor measurement
POWer:QUALity:IRMS?	Returns the rms current measurement
POWer:QUALity:PHASEangle?	Returns the phase angle measurement
POWer:QUALity:POWERFACtor?	Returns the power factor measurement
POWer:QUALity:REACTpwr?	Returns the reactive power measurement
POWer:QUALity:TRUEpwr?	Returns the true power measurement
POWer:QUALity:VRMS?	Returns the rms voltage measurement
POWer:REFLevel:ABSolute	Sets the reference levels to their default unit values
POWer:REFLevel:ABSolute:HIGH	Sets or returns the top reference level for rise time
POWer:REFLevel:ABSolute:LOW	Sets or returns the low reference level for rise time
POWer:REFLevel:ABSolute:MID<1-3>	Sets or returns the mid reference level for measurements
POWer:REFLevel:HYSTeresis	Sets or returns the measurement reference level hysteresis value
POWer:REFLevel:METHod	Sets or returns the method used to calculate the 0% and 100% reference level
POWer:REFLevel:PERCent	Sets the reference levels to the default percentage values
POWer:REFLevel:PERCent:HIGH	Sets or returns the top reference percent level for rise time
POWer:REFLevel:PERCent:LOW	Sets or returns the low reference percent level for rise time
POWer:REFLevel:PERCent:MID<1-3>	Sets or returns the mid reference percent level for waveform measurements
POWer:RIPPle	Sets the vertical offset of the source waveform
POWer:RIPPle:RESults:AMPLitude?	Returns the peak-to-peak ripple measurement

Table 2-29: Power Commands (cont.)

Command	Description
POWer:RIPPle:RESults:MAX?	Returns the maximum of the peak-to-peak ripple measurements
POWer:RIPPle:RESults:MEAN?	Returns the mean of the peak-to-peak ripple measurements
POWer:RIPPle:RESults:MIN?	Returns the minimum of the peak-to-peak ripple measurement
POWer:RIPPle:RESults:STDdev?	Returns the standard deviation of the peak-to-peak ripple measurements
POWer:RIPPle:SOUrce	Sets or returns the source waveform for ripple tests
POWer:SOA:LINear:XMAX	Sets or returns the user XMAX value for use in linear SOA calculations
POWer:SOA:LINear:XMIN	Sets or returns the user XMIN value for use in linear SOA calculations
POWer:SOA:LINear:YMAX	Sets or returns the user YMAX value for use in linear SOA calculations
POWer:SOA:LINear:YMIN	Sets or returns the user YMIN value for use in linear SOA calculations
POWer:SOA:LOG:XMAX	Sets or returns the user XMAX value for use in log SOA calculations
POWer:SOA:LOG:XMIN	Sets or returns the user XMIN value for use in log SOA calculations
POWer:SOA:LOG:YMAX	Sets or returns the user YMAX value for use in log SOA calculations
POWer:SOA:LOG:YMIN	Sets or returns the user YMIN value for use in log SOA calculations
POWer:SOA:MASK:DEFine	Sets or returns the X (Volts) and Y (Amps) coordinates of the current SOA mask
POWer:SOA:MASK:MAXAmps	Sets or returns the maximum current applied to SOA mask testing
POWer:SOA:MASK:MAXVolts	Sets or returns the maximum voltage applied to SOA mask testing
POWer:SOA:MASK:MAXWatts	Sets or returns the maximum power applied to SOA mask testing
POWer:SOA:MASK:NR_PT?	Returns the number of mask points defined
POWer:SOA:MASK:STATe	Sets or returns the state of the mask for SOA calculations
POWer:SOA:MASK:STOPOnviol	Sets or returns the enabled state of the mask stop on violation condition
POWer:SOA:PLOTTYPe	Sets or returns the SOA plot type
POWer:SOA:RESult:FAlLures:QTY?	Returns the number of failures in the test

Table 2-29: Power Commands (cont.)

Command	Description
POWer:SOA:RESult:NUMACq?	Returns the number of acquisitions in the test
POWer:SOA:RESult:STATe?	Returns the pass/fail state of the SOA test
POWer:STATIstics	Clears all the accumulated statistics of all measurements
POWer:STATIstics:MODE	Enables or disables the display of the measurement statistics
POWer:STATIstics:WEIghting	Sets the number of samples which are included for the statistics computations for mean and the standard deviation
POWer:SWLoss:CONDCALCmethod	Sets or returns the power application switching loss conduction calculation method
POWer:SWLoss:CONDuction:ENERGY: MAX?	Returns the maximum conduction energy for the switching loss calculation
POWer:SWLoss:CONDuction:ENERGY: MEAN?	Returns the mean conduction energy for the switching loss calculation
POWer:SWLoss:CONDuction:ENERGY: MIN?	Returns the minimum conduction energy for the switching loss calculation
POWer:SWLoss:CONDuction:POWER: MAX?	Returns the maximum conduction power for the switching loss calculation
POWer:SWLoss:CONDuction:POWER: MEAN?	Returns the mean conduction power for the switching loss calculation
POWer:SWLoss:CONDuction:POWER: MIN?	Returns the minimum conduction power for the switching loss calculation
POWer:SWLoss:DISplay	Sets or returns the display selection for switching loss results
POWer:SWLoss:GATe:POLarity	Sets or returns the switching loss gate polarity
POWer:SWLoss:GATe:TURNON	Sets or returns the gate turn on level for switching loss power measurements
POWer:SWLoss:NUMCYCles?	Returns the number of cycles counted for the switching loss calculation
POWer:SWLoss:RDSon	Sets or returns RDSON value for use in switching loss calculations when the conduction calculation method is RDSON
POWer:SWLoss:REFLevel:ABSolute: GATEMid	Sets or returns the mid voltage reference level used in switching loss power measurements in volts
POWer:SWLoss:REFLevel:ABSolute: LOWCurrent	Sets or returns the low current reference level used in switching loss power measurements in amperes

Table 2-29: Power Commands (cont.)

Command	Description
POWer:SWLoss:REFLevel:ABSolute: LOWVoltage	Sets or returns the low voltage reference level used in switching loss power measurements in volts
POWer:SWLoss:REFLevel:PERCent: GATEMid	Sets or returns the mid voltage reference level used in switching loss power measurements in percentage
POWer:SWLoss:REFLevel:PERCent: LOWCurrent	Sets or returns the low current reference level used in switching loss power measurements in percentage
POWer:SWLoss:REFLevel:PERCent: LOWVoltage	Sets or returns the low voltage reference level used in switching loss power measurements in percentage
POWer:SWLoss:TOFF:ENERGY:MAX?	Returns the maximum Toff energy switching loss calculation
POWer:SWLoss:TOFF:ENERGY:MEAN?	Returns the mean Toff energy switching loss calculation
POWer:SWLoss:TOFF:ENERGY:MIN?	Returns the minimum Toff energy switching loss calculation
POWer:SWLoss:TOFF:POWER:MAX?	Returns the maximum Toff power switching loss calculation
POWer:SWLoss:TOFF:POWER:MEAN?	Returns the mean Toff power switching loss calculation
POWer:SWLoss:TOFF:POWER:MIN?	Returns the minimum Toff power switching loss calculation
POWer:SWLoss:TON:ENERGY:MAX?	Returns the maximum Ton energy switching loss calculation
POWer:SWLoss:TON:ENERGY:MEAN?	Returns the mean Ton energy switching loss calculation
POWer:SWLoss:TON:ENERGY:MIN?	Returns the minimum Ton energy switching loss calculation
POWer:SWLoss:TON:POWER:MAX?	Returns the maximum Ton power switching loss calculation
POWer:SWLoss:TON:POWER:MEAN?	Returns the mean Ton power switching loss calculation
POWer:SWLoss:TON:POWER:MIN?	Returns the minimum Ton power switching loss calculation
POWer:SWLoss:TOTal:ENERGY:MAX?	Returns the maximum total energy switching loss calculation
POWer:SWLoss:TOTal:ENERGY:MEAN?	Returns the mean total energy switching loss calculation
POWer:SWLoss:TOTal:ENERGY:MIN?	Returns the minimum total energy switching loss calculation

Table 2-29: Power Commands (cont.)

Command	Description
POWer:SWLoss:TOTal:POWER:MAX?	Returns the maximum total power switching loss calculation
POWer:SWLoss:TOTal:POWER:MEAN?	Returns the mean total power switching loss calculation
POWer:SWLoss:TOTal:POWER:MIN?	Returns the minimum total power switching loss calculation
POWer:SWLoss:VCEsat	Sets or returns VCESAT value for use in switching loss calculations when the conduction calculation method is VCESAT
POWer:TYPe	Sets or returns the power application measurement type
POWer:VOLTAGESOurce	Sets or returns the voltage source for the power application

## **Save and Recall Command Group**

Use the commands in the Save and Recall Command Group to store and retrieve waveforms and settings. When you save a setup, you save all the settings of the oscilloscope. When you recall a setup, the oscilloscope restores itself to the state it was in when you originally saved the setting.

Table 2-30: Save and Recall Commands

Command	Description
FACtory	Resets the oscilloscope to factory default settings
*RCL	Recalls saved oscilloscope settings
RECAll:SETUp	Recalls saved oscilloscope settings
RECAll:WAVEform	Recalls a stored waveform to a reference location
*SAV	Stores the state of the oscilloscope to a specified memory location
SAVe:ASSIgn:TYPe	Sets or returns the assignment of the save button
SAVe:EVENTtable:BUS <x></x>	Saves event table data from bus <x> to a specified file</x>
SAVe:IMAGe	Saves a capture of the screen image to the specified file
-	·

Table 2-30: Save and Recall Commands (cont.)

Command	Description
SAVe:IMAGe:FILEFormat	Sets or returns the file format to use for saving screen images. The file format is not automatically determined by the file name extension. You need to choose a file name with an extension which is consistent with the selected file format
SAVe:IMAGe:INKSaver	Sets or returns the current inksaver setting for the SAVe:IMAGe command
SAVe:IMAGe:LAYout	Sets or returns the layout to use for saved screen images
SAVe:SETUp	Saves the state of the oscilloscope to a specified memory location or file
SAVe:WAVEform	Saves a waveform to one of the reference memory locations or a file
SAVe:WAVEform:FILEFormat	Sets or returns the format for saved waveforms
SAVe:WAVEform:GATIng	Specifies whether save waveform operations should save the entire waveform or a specified portion of the waveform
SETUP <x>:DATE?</x>	Returns the date when the specified oscilloscope setup was saved
SETUP <x>:LABEL</x>	Sets or returns the specified oscilloscope setup label
SETUP <x>:TIME?</x>	Returns the time when the specified oscilloscope setup was saved

# **Search Command Group**

Use the commands in the Search Commands Group to seek out information in waveform records.

#### **Search Commands**

Command	Description
SEARCH?	Returns all search-related settings
SEARCH:SEARCH <x>:COPy</x>	Copies the search criteria to the trigger, or the trigger criteria to the search
SEARCH:SEARCH <x>:STATE</x>	Sets the search state to on or off
SEARCH:SEARCH <x>:TOTAL?</x>	Returns the total number of matches for search <x></x>
SEARCH:SEARCH <x>:TRIGger:A:BUS?</x>	Returns the search trigger bus type

Command	Description
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:AUDio:CONDition</x></x>	Sets or returns the search trigger condition for the AUDIO bus: Start of Frame or Data
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:AUDio:DATa:HIVALue</x></x>	Sets or returns the search trigger data upper word for the AUDIO bus
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:AUDio:DATa:OFFSet</x></x>	Sets or returns the search trigger data offset for the AUDIO bus
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:AUDio:DATa:QUALifier</x></x>	Sets or returns the search trigger data qualifier for the AUDIO bus
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:AUDio:DATa:VALue</x></x>	Sets or returns the search trigger data lower word for the AUDIO bus
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:AUDio:DATa:WORD</x></x>	Sets or returns the search trigger data alignment for the AUDIO bus
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:CAN:CONDition</x></x>	Sets or returns the search condition for CAN search
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:CAN:DATa:DIRection</x></x>	Sets or returns the CAN search condition to be valid on a READ, WRITE or either
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:CAN:DATa:QUALifier</x></x>	Sets or returns the CAN data qualifier
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:CAN:DATa:SIZe</x></x>	Sets or returns the length of the data string in bytes to be used for CAN search
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:CAN:DATa:VALue</x></x>	Sets or returns the binary data string to be used for CAN search
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:CAN:FRAMEtype</x></x>	Sets or returns the CAN Frame Type to be used
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:CAN{:IDentifier :ADDRess}:MODe</x></x>	Sets or returns the CAN addressing mode to standard or extended format
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:CAN{:IDentifier :ADDRess}:VALue</x></x>	Sets or returns the binary address string to be used for CAN search
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:FLEXray:CONDition</x></x>	Sets or returns the trigger condition for FLEXRAY
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:FLEXray:CYCLEcount:HIVALue</x></x>	Sets or returns the binary data string to be used for FLEXRAY cycle count high value
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:FLEXray:CYCLEcount:QUALifier</x></x>	Sets or returns the FLEXRAY cycle count qualifier
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:FLEXray:CYCLEcount:VALue</x></x>	Sets or returns the binary data string to be used for FLEXRAY cycle count low value
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:FLEXray:DATa:HIVALue</x></x>	Sets or returns the high binary data string
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:FLEXray:DATa:OFFSet</x></x>	Sets or returns the offset of the data string in bytes
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:FLEXray:DATa:QUALifier</x></x>	Sets or returns the FLEXRAY data qualifier

Command	Description
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:FLEXray:DATa:SIZe</x></x>	Sets or returns the length of the data string in bytes
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:FLEXray:DATa:VALue</x></x>	Sets or returns the low binary data string
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:FLEXray:EOFTYPE</x></x>	Sets or returns the end of frame type
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:FLEXray:ERRTYPE</x></x>	Sets or returns the error type
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:FLEXray:FRAMEID:HIVALue</x></x>	Sets or returns the binary data string used for FLEXRAY frame ID high value
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:FLEXray:FRAMEID:QUALifier</x></x>	Sets or returns the FLEXRAY frame ID qualifier
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:FLEXray:FRAMEID:VALue</x></x>	Sets or returns the binary data string to be used for FLEXRAY frame ID low value
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:FLEXray:FRAMEType</x></x>	Sets or returns the frame type
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:FLEXray:HEADER:CRC</x></x>	Sets or returns the CRC portion of the binary header string
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:FLEXray:HEADER:CYCLEcount</x></x>	Sets or returns the cycle count portion of the binary header string
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:FLEXray:HEADER:FRAMEID</x></x>	Sets or returns the frame id portion of the binary header string
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:FLEXray:HEADER:INDBits</x></x>	Sets or returns the indicator bits portion of the binary header string
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:FLEXray:HEADER:PAYLength</x></x>	Sets or returns the payload length portion of the binary header string
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:12C:ADDRess:MODe</x></x>	Sets or returns the I2C address mode to 7 or 10-Bit
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:12C:ADDRess:TYPe</x></x>	Sets or returns the I2C address type to I2C special addresses
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:12C:ADDRess:VALue</x></x>	Sets or returns the binary address string to be used for I2C search
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:12C:CONDition</x></x>	Sets or returns the search condition for I2C search
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:12C:DATa:DIRection</x></x>	Sets or returns the I2C search condition to be valid on a READ, WRITE or either
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:12C:DATa:SIZe</x></x>	Sets or returns the length of the data string in bytes to be used for I2C search
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:12C:DATa:VALue</x></x>	Sets or returns the binary data string to be used for I2C search
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:LIN:CONDition</x></x>	Sets or returns the search condition for a LIN search

Command	Description
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:LIN:DATa:HIVALue</x></x>	Sets or returns the binary data string
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:LIN:DATa:QUALifier</x></x>	Sets or returns the LIN data qualifier
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:LIN:DATa:SIZe</x></x>	Sets or returns the length of the data string in bytes
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:LIN:DATa:VALue</x></x>	Sets or returns the binary data string used for a LIN search
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:LIN:ERRTYPE</x></x>	Sets or returns the error type used for a LIN Search
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:LIN:IDentifier:VALue</x></x>	Sets or returns the binary address string used for LIN search
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:PARallel:VALue</x></x>	Sets or returns the binary data string to be used for a Parallel search
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:RS232C:CONDition</x></x>	Sets or returns the trigger condition for an RS-232 trigger
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:RS232C:RX:DATa:SIZe</x></x>	Sets or returns the length of the data string for an RS-232 trigger, if the trigger condition is RX
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:RS232C:RX:DATa:VALue</x></x>	Sets or returns the binary data string for an RS-232 trigger, if the condition involves RX
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:RS232C:TX:DATa:SIZe</x></x>	Sets or returns the length of the data string to be used for an RS-232 Trigger, if the Trigger condition is TX
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:RS232C:TX:DATa:VALue</x></x>	Sets or returns the binary data string to be used for an RS-232 trigger, if the condition involves RX
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:SPI:CONDition</x></x>	Sets or returns the search condition for SPI search
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:SPI:DATa{:MISO :IN}:VALue</x></x>	Sets or returns the binary data string to be used for SPI search if the search condition is MISO or MISOMOSI
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:SPI:DATa{:MOSI :OUT}:VALue</x></x>	Sets or returns the binary data string for an SPI search if the search condition is MISO or MISOMOSI
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:SPI:DATa:SIZe</x></x>	Sets or returns the length of the data string in bytes to be used for SPI search
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:USB:ADDRess:HIVALue</x></x>	Sets or returns the high limit for USB address searches
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:USB:ADDRess:VALue</x></x>	Sets or returns the value for USB address searches
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:USB:CONDition</x></x>	Sets or returns the USB search trigger condition

Command	Description
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:USB:DATa:HIVALue</x></x>	Sets or returns the high limit for USB data searches
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:USB:DATa:OFFSet</x></x>	Sets or returns the data offset for USB data searches
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:USB:DATa:SIZe</x></x>	Sets or returns the number of data bytes for USB searches
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:USB:DATa:TYPe</x></x>	Sets or returns the data type for USB searches
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:USB:DATa:VALue</x></x>	Sets or returns the data value for USB data searches
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:USB:ENDPoint:VALue</x></x>	Sets or returns the endpoint value for USB searches
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:USB:ERRORTYPe</x></x>	Sets or returns the error type for USB searches
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:USB:HANDSHAKEType</x></x>	Sets or returns the handshake type for USB searches
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:USB:QUALifier</x></x>	Sets or returns the qualifier for USB searches
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:USB:SOFFRAMENUMber</x></x>	Sets or returns the SOF number for USB searches
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:USB:SPECIALType</x></x>	Sets or returns the special packet type for USB searches
SEARCH:SEARCH <x>:TRIGger:A:BUS: B<x>:USB:TOKENType</x></x>	Sets or returns the token type for USB searches
SEARCH:SEARCH <x>:TRIGger:A:BUS: SOUrce</x>	Sets or returns the bus for a serial search
SEARCH:SEARCH <x>:TRIGger:A:EDGE: SLOpe</x>	Sets or returns the slope for an edge search
SEARCH:SEARCH <x>:TRIGger:A:EDGE: SOUrce</x>	Sets or returns the source waveform for an edge search
SEARCH:SEARCH <x>:TRIGger:A:LEVel</x>	Sets or returns the level for an edge search
SEARCH:SEARCH <x>:TRIGger:A:LEVel: CH<x></x></x>	Sets or returns the level for an edge search of the specified channel
SEARCH:SEARCH <x>:TRIGger:A:LEVel: MATH</x>	Sets or returns the math waveform level for edge search
SEARCH:SEARCH <x>:TRIGger:A:LEVel: REF<x></x></x>	Sets or returns the reference waveform level for edge search
SEARCH:SEARCH <x>:TRIGger:A:LOGIc: FUNCtion</x>	Sets or returns the logic operator for the logic search
SEARCH:SEARCH <x>:TRIGger:A:LOGIc: INPut:CH<x></x></x>	Sets or returns the Boolean logic criteria for the logic search

Command	Description
SEARCH:SEARCH <x>:TRIGger:A:LOGIc: INPut:CLOCk:EDGE</x>	Sets or returns whether the clock edge is rise or fall for a logic search
SEARCH:SEARCH <x>:TRIGger:A:LOGIc: INPut:CLOCk:SOUrce</x>	Sets or returns the clock source definition for logic search
SEARCH:SEARCH <x>:TRIGger:A:LOGIc: INPut:D<x></x></x>	Sets or returns the criteria for a logic search to determine where to place a mark for digital channel <x></x>
SEARCH:SEARCH <x>:TRIGger:A:LOGIc: INPut:MATH</x>	Sets or returns the Boolean logic criteria for the logic search
SEARCH:SEARCH <x>:TRIGger:A:LOGIc: INPut:REF<x></x></x>	Sets or returns the Boolean logic criteria for the logic search
SEARCH:SEARCH <x>:TRIGger:A:LOGIc: PATtern:INPut:CH<x></x></x>	Sets or returns the Boolean logic criteria for the logic search
SEARCH:SEARCH <x>:TRIGger:A:LOGIc: PATtern:INPut:D<x></x></x>	Sets or returns the criteria for a pattern search to determine where to place a mark for digital channel <x></x>
SEARCH:SEARCH <x>:TRIGger:A:LOGIc: PATtern:INPut:MATH</x>	Sets or returns the Boolean logic criteria for the logic search
SEARCH:SEARCH <x>:TRIGger:A:LOGIc: PATtern:INPut:REF<x></x></x>	Sets or returns the Boolean logic criteria for the logic search
SEARCH:SEARCH <x>:TRIGger:A:LOGIc: PATtern:WHEn</x>	Sets or returns the condition for generating a logic pattern search
SEARCH:SEARCH <x>:TRIGger:A:LOGIc: PATtern:WHEn:LESSLimit</x>	Sets or returns the maximum time that the selected pattern may be true
SEARCH:SEARCH <x>:TRIGger:A:LOGIc: PATtern:WHEn:MORELimit</x>	Sets or returns the minimum time that the selected pattern may be true
SEARCH:SEARCH <x>:TRIGger:A:LOGIc: THReshold:CH<x></x></x>	Sets or returns the channel threshold level for an logic search
SEARCH:SEARCH <x>:TRIGger:A:LOGIc: THReshold:MATH</x>	Sets or returns the math waveform threshold level for logic search
SEARCH:SEARCH <x>:TRIGger:A:LOGIc: THReshold:REF<x></x></x>	Sets or returns the reference waveform threshold level for logic search
SEARCH:SEARCH <x>:TRIGger:A: LOWerthreshold:CH<x></x></x>	Sets or returns the lower waveform threshold level for all channel waveform searches
SEARCH:SEARCH <x>:TRIGger:A: LOWerthreshold:MATH</x>	Sets or returns the lower waveform threshold level for all math waveform searches
SEARCH:SEARCH <x>:TRIGger:A: LOWerthreshold:REF<x></x></x>	Sets or returns the lower waveform threshold level for all reference waveform searches
SEARCH:SEARCH <x>:TRIGger:A: PULSEWidth:POLarity</x>	Sets or returns the polarity for a pulse search
SEARCH:SEARCH <x>:TRIGger:A: PULSEWidth:SOUrce</x>	Sets or returns the source waveform for a pulse search

Command	Description
SEARCH:SEARCH <x>:TRIGger:A: PULSEWidth:WHEn</x>	Sets or returns the condition for generating a pulse width search
SEARCH:SEARCH <x>:TRIGger:A: PULSEWidth:WIDth</x>	Sets or returns the pulse width setting for a pulse width search
SEARCH:SEARCH <x>:TRIGger:A:RUNT: POLarity</x>	Sets or returns the polarity setting for a runt search
SEARCH:SEARCH <x>:TRIGger:A:RUNT: SOUrce</x>	Sets or returns the source setting for a runt search
SEARCH:SEARCH <x>:TRIGger:A:RUNT: WHEn</x>	sets or returns the condition setting for a runt search
SEARCH:SEARCH <x>:TRIGger:A:RUNT: WIDth</x>	Sets or returns the width setting for a runt search
SEARCH:SEARCH <x>:TRIGger:A: SETHold:CLOCk:EDGE</x>	Sets or returns the clock slope setting for a setup/hold search
SEARCH:SEARCH <x>:TRIGger:A: SETHold:CLOCk:SOUrce</x>	Sets or returns the clock source setting for an setup/hold search
SEARCH:SEARCH <x>:TRIGger:A: SETHold:CLOCk:THReshold</x>	Sets or returns the clock threshold setting for an setup/hold search
SEARCH:SEARCH <x>:TRIGger:A: SETHold:DATa:SOUrce</x>	Sets or returns the data source setting for an setup/hold search
SEARCH:SEARCH <x>:TRIGger:A: SETHold:DATa:THReshold</x>	Sets or returns the data threshold setting for an setup/hold search
SEARCH:SEARCH <x>:TRIGger:A: SETHold:HOLDTime</x>	Sets or returns the hold time setting for an setup/hold search
SEARCH:SEARCH <x>:TRIGger:A: SETHold:SETTime</x>	Sets or returns the setup time setting for an setup/hold search
SEARCH:SEARCH <x>:TRIGger:A: SETHold:THReshold:CH<x></x></x>	Sets or returns the trigger search setup and hold threshold for the selected channel
SEARCH:SEARCH <x>:TRIGger:A: SETHold:THReshold{:MATH :MATH1}</x>	Sets or returns the trigger search setup and hold threshold for the math waveform
SEARCH:SEARCH <x>:TRIGger:A: SETHold:THReshold:REF<x></x></x>	Sets or returns the trigger search setup and hold threshold for the selected reference waveform
SEARCH:SEARCH <x>:TRIGger:A{: TRANsition :RISEFall}:DELTatime</x>	Sets or returns the transition time setting for an transition search
SEARCH:SEARCH <x>:TRIGger:A{: TRANsition :RISEFall}:POLarity</x>	Sets or returns the polarity setting for an transition search
SEARCH:SEARCH <x>:TRIGger:A{: TRANsition :RISEFall}:SOUrce</x>	Sets or returns the source setting for an transition search
SEARCH:SEARCH <x>:TRIGger:A{: TRANsition :RISEFall}:WHEn</x>	Sets or returns the condition setting for an transition search

Command	Description
SEARCH:SEARCH <x>:TRIGger:A:TYPe</x>	Sets or returns the trigger type setting for a search
SEARCH:SEARCH <x>:TRIGger:A: UPPerthreshold:CH<x></x></x>	Sets or returns the waveform upper threshold level for all channel waveform searches
SEARCH:SEARCH <x>:TRIGger:A: UPPerthreshold:MATH</x>	Sets or returns the waveform upper threshold level for all math waveform searches
SEARCH:SEARCH <x>:TRIGger:A: UPPerthreshold:REF<x></x></x>	Sets or returns the waveform upper threshold level for all reference waveform searches

# **Status and Error Command Group**

Use the commands in the Status and Error Command Group to determine the status of the oscilloscope and control events.

Several commands and queries used with the oscilloscope are common to all IEEE488.2 compliant devices. The IEEE Std 488.2-1987 defines these commands and queries. The common commands begin with an asterisk (\*) character.

**Table 2-31: Status and Error Commands** 

Command	Description
ALLEv?	Returns all events and their messages
BUSY?	Returns oscilloscope status
*CLS	Clears status
DESE	Sets or returns the bits in the Device Event Status Enable Register
*ESE	Sets or returns the bits in the Event Status Enable Register
*ESR?	Returns the contents of the Standard Event Status Register
EVENT?	Returns event code from the event queue
EVMsg?	Returns event code, message from the event queue
EVQty?	Return number of events in the event queue
*OPC	Generates the operation complete message in the standard event status register when all pending operations are finished
	Or returns "1" when all current operations are finished
*PSC	Sets or returns the power on status flag
*PUD	Sets or returns a string of protected user data

Table 2-31: Status and Error Commands (cont.)

Command	Description
*RST	Resets the oscilloscope to factory default settings
*SRE	Sets or returns the bits in the Service Request Enable Register
*STB?	Returns the contents of the Status Byte Register
*WAI	Prevents the oscilloscope from executing further commands until all pending operations finish

## **Trigger Command Group**

Use the commands in the Trigger Command Group to control all aspects of triggering for the oscilloscope.

There are two triggers: A and B. Where appropriate, this command set has parallel construction between triggers.

You can set the A or B triggers to edge mode. Edge triggering lets you display a waveform at or near the point where the signal passes through a voltage level of your choosing.

You can also set A triggers to pulse, logic, or video modes. With pulse triggering, the oscilloscope triggers whenever it detects a pulse of a certain width or height. Logic triggering lets you logically combine the signals on one or channels. The oscilloscope then triggers when it detects a certain combination of signal levels. Video triggering enables you to trigger on the most common Standard Definition video standards.

**Table 2-32: Trigger Commands** 

Command	Description
TRIGger	Forces a trigger event to occur
TRIGger:A	Sets A trigger level to 50% or returns current A trigger parameters
TRIGger:A:BUS	Sets or returns the serial trigger type
TRIGger:A:BUS:B <x>:AUDio:CONDition</x>	Sets or returns the trigger condition for the AUDIO bus: Start of Frame or Data

Table 2-32: Trigger Commands (cont.)

Command	Description
TRIGger:A:BUS:B <x>:AUDio:DATa:HIVALue</x>	Sets or returns the trigger data upper word for the AUDIO bus
TRIGger:A:BUS:B <x>:AUDio:DATa:OFFSet</x>	Sets or returns the trigger data offset for the AUDIO bus
TRIGger:A:BUS:B <x>:AUDio:DATa:QUALifier</x>	Sets or returns the trigger data qualifier for the AUDIO bus
TRIGger:A:BUS:B <x>:AUDio:DATa:VALue</x>	Sets or returns the trigger data lower word for the AUDIO bus
TRIGger:A:BUS:B <x>:AUDio:DATa:WORD</x>	Sets or returns the trigger data alignment for the AUDIO bus.
TRIGger:A:BUS:B <x>:CAN:CONDition</x>	Sets or returns the CAN condition
TRIGger:A:BUS:B <x>:CAN:DATa:DIRection</x>	Sets or returns the CAN trigger condition to be valid on a READ, WRITE, or either
TRIGger:A:BUS:B <x>:CAN:DATa:QUALifier</x>	Sets or returns the CAN data qualifier
TRIGger:A:BUS:B <x>:CAN:DATa:SIZe</x>	Sets or returns the length of the data string in bytes to be used for CAN trigger
TRIGger:A:BUS:B <x>:CAN:DATa:VALue</x>	Sets or returns the binary data string to be used for CAN trigger
TRIGger:A:BUS:B <x>:CAN:FRAMEtype</x>	Sets or returns the CAN trigger frame type
TRIGger:A:BUS:B <x>:CAN{:IDentifier :ADDRess}:MODe</x>	Sets or returns the CAN addressing mode
TRIGger:A:BUS:B <x>:CAN{:IDentifier :ADDRess}:VALue</x>	Sets or returns the binary address string used for the CAN trigger
TRIGger:A:BUS:B <x>:FLEXray:CONDition</x>	Sets or returns the trigger condition for FLEXRAY
TRIGger:A:BUS:B <x>:FLEXray:CYCLEcount:HIVALue</x>	Sets or returns the binary data string to be used for FLEXRAY cycle count high value
TRIGger:A:BUS:B <x>:FLEXray:CYCLEcount:QUALifier</x>	Sets or returns the FLEXRAY cycle count qualifier

Table 2-32: Trigger Commands (cont.)

Command	Description
TRIGger:A:BUS:B <x>:FLEXray:CYCLEcount:VALue</x>	Sets or returns the binary data string to be used for FLEXRAY cycle count low value
TRIGger:A:BUS:B <x>:FLEXray:DATa:HIVALue</x>	Sets or returns the high binary data string to be used for FLEXRAY trigger
TRIGger:A:BUS:B <x>:FLEXray:DATa:OFFSet</x>	Sets or returns the offset of the data string in bytes
TRIGger:A:BUS:B <x>:FLEXray:DATa:QUALifier</x>	Sets or returns the FLEXRAY data qualifier
TRIGger:A:BUS:B <x>:FLEXray:DATa:SIZe</x>	Sets or returns the length of the data string in bytes
TRIGger:A:BUS:B <x>:FLEXray:DATa:VALue</x>	Sets or returns the low binary data string to be used for FLEXRAY trigger condition
TRIGger:A:BUS:B <x>:FLEXray:EOFTYPE</x>	Sets or returns the end of file type
TRIGger:A:BUS:B <x>:FLEXray:ERRTYPE</x>	Sets or returns the error type
TRIGger:A:BUS:B <x>:FLEXray:FRAMEID:HIVALue</x>	Sets or returns the binary data string to be used for FLEXRAY frame ID high value
TRIGger:A:BUS:B <x>:FLEXray:FRAMEID:QUALifier</x>	Sets or returns the FLEXRAY frame ID qualifier
TRIGger:A:BUS:B <x>:FLEXray:FRAMEID:VALue</x>	Sets or returns the binary data string to be used for FLEXRAY frame ID low value
TRIGger:A:BUS:B <x>:FLEXray:FRAMEType</x>	Sets or returns the frame type
TRIGger:A:BUS:B <x>:FLEXray:HEADER:CRC</x>	Sets or returns the CRC portion of the binary header string
TRIGger:A:BUS:B <x>:FLEXray:HEADER:CYCLEcount</x>	Sets or returns the cycle count portion of the binary header string
TRIGger:A:BUS:B <x>:FLEXray:HEADER:FRAMEID</x>	Sets or returns the frame id portion of the binary header string
TRIGger:A:BUS:B <x>:FLEXray:HEADER:INDBits</x>	Sets or returns the indicator bits portion of the binary header string

Table 2-32: Trigger Commands (cont.)

Command	Description
TRIGger:A:BUS:B <x>:FLEXray:HEADER:PAYLength</x>	Sets or returns the payload length portion of the binary header string
TRIGger:A:BUS:B <x>:l2C:ADDRess:MODe</x>	Sets or returns the I2C address mode to 7 or 10-bit
TRIGger:A:BUS:B <x>:l2C:ADDRess:TYPe</x>	Sets or returns the I2C address type to USER
TRIGger:A:BUS:B <x>:l2C:ADDRess:VALue</x>	Sets or returns the binary address string used for the I2C trigger
TRIGger:A:BUS:B <x>:I2C:CONDition</x>	Sets or returns the trigger condition for I2C trigger
TRIGger:A:BUS:B <x>:I2C:DATa:DIRection</x>	Sets or returns the I2C trigger condition valid on a READ, WRITE, or either
TRIGger:A:BUS:B <x>:l2C:DATa:SIZe</x>	Sets or returns the length of the data string in bytes to be used for I2C trigger
TRIGger:A:BUS:B <x>:I2C:DATa:VALue</x>	Sets or returns the binary data string used for I2C triggering
TRIGger:A:BUS:B <x>:LIN:CONDition</x>	Sets or returns the trigger condition for LIN
TRIGger:A:BUS:B <x>:LIN:DATa:HIVALue</x>	Sets or returns the binary data string to be used for LIN trigger
TRIGger:A:BUS:B <x>:LIN:DATa:QUALifier</x>	Sets or returns the LIN data qualifier
TRIGger:A:BUS:B <x>:LIN:DATa:SIZe</x>	Sets or returns the length of the data string in bytes to be used for LIN trigger
TRIGger:A:BUS:B <x>:LIN:DATa:VALue</x>	Sets or returns the binary data string
TRIGger:A:BUS:B <x>:LIN:ERRTYPE</x>	Sets or returns the error type
TRIGger:A:BUS:B <x>:LIN:IDentifier:VALue</x>	Sets or returns the binary address string used for LIN trigger
TRIGger:A:BUS:B <x>:PARallel:VALue</x>	Sets or returns the binary data string to be used for a Parallel trigger
TRIGger:A:BUS:B <x>:RS232C:CONDition</x>	Sets or returns the condition for an RS-232C trigger

Table 2-32: Trigger Commands (cont.)

Command	Description
TRIGger:A:BUS:B <x>:RS232C:RX:DATa:SIZe</x>	Sets or returns the length of the data string in Bytes for an RX RS-232 Trigger
TRIGger:A:BUS:B <x>:RS232C:RX:DATa:VALue</x>	Sets or returns the binary data string for an RX RS-232 trigger
TRIGger:A:BUS:B <x>:RS232C:TX:DATa:SIZe</x>	Sets or returns the length of the data string for a TX RS-232 trigger
TRIGger:A:BUS:B <x>:RS232C:TX:DATa:VALue</x>	Sets or returns the binary data string for an RS-232 trigger if the trigger condition involves TX
TRIGger:A:BUS:B <x>:SPI:CONDition</x>	Sets or returns the trigger condition for SPI triggering
TRIGger:A:BUS:B <x>:SPI:DATa{:IN :MISO}:VALue</x>	Sets or returns the binary data string to be used for SPI trigger
TRIGger:A:BUS:B <x>:SPI:DATa{:OUT :MOSI}:VALue</x>	Sets or returns the binary data string used for the SPI trigger
TRIGger:A:BUS:B <x>:SPI:DATa:SIZe</x>	Sets or returns the length of the data string in bytes to be used for SPI trigger
TRIGger:A:BUS:B <x>:USB:ADDRess:HIVALue</x>	Sets or returns the high limit for the USB trigger address
TRIGger:A:BUS:B <x>:USB:ADDRess:VALue</x>	Sets or returns the value for the USB trigger address
TRIGger:A:BUS:B <x>:USB:CONDition</x>	Sets or returns the USB trigger condition
TRIGger:A:BUS:B <x>:USB:DATa:HIVALue</x>	Sets or returns the high limit for the USB trigger data
TRIGger:A:BUS:B <x>:USB:DATa:OFFSet</x>	Sets or returns the data offset for the USB trigger data
TRIGger:A:BUS:B <x>:USB:DATa:SIZe</x>	Sets or returns the number of data bytes for the USB trigger
TRIGger:A:BUS:B <x>:USB:DATa:TYPe</x>	Sets or returns the data type for the USB trigger
TRIGger:A:BUS:B <x>:USB:DATa:VALue</x>	Sets or returns the data value for the USB trigger

Table 2-32: Trigger Commands (cont.)

Description
Sets or returns the endpoint value for the USB trigger
Sets or returns the error type for the USB trigger
Sets or returns the handshake type for the USB trigger
Sets or returns the qualifier for USB trigger
Sets or returns the SOF number for the USB trigger
Sets or returns the special packet type for the USB trigger
Sets or returns the token type for the USB trigger
Sets or returns the source for a bus trigger
Returns the source, coupling and source for the A edge trigger
Sets or returns the type of coupling for the A edge trigger
Sets or returns the slope for the A edge trigger
Sets or returns the source for the A edge trigger
Returns the A trigger holdoff parameters
Sets or returns the A trigger holdoff time
Sets or returns the trigger level for the A trigger
Sets or returns the trigger level for the AUXIN port
Specifies or returns the trigger level for the specified trigger channel
Sets or returns the trigger level for the specified digital channel

Table 2-32: Trigger Commands (cont.)

Command	Description
TRIGger:A:LOGIc?	Returns all A trigger logic settings
TRIGger:A:LOGIc:CLAss	Sets or returns the type of A trigger logic
TRIGger:A:LOGIc:FUNCtion	Sets or returns the logical combination of the input channels for the A logic trigger
TRIGger:A:LOGIc:INPut?	Returns the logic input values for all channels
TRIGger:A:LOGIc:INPut:CH <x></x>	Specifies or returns the logic setting for the specified channel
TRIGger:A:LOGIc:INPut:CLOCk:EDGE	Sets the polarity of the clock channel
TRIGger:A:LOGIc:INPut:CLOCk:SOUrce	Sets or returns the channel to use as the clock source
TRIGger:A:LOGIc:INPut:D <x></x>	Sets or returns the logic pattern for a trigger on digital channel <x></x>
TRIGger:A:LOGIc:PATtern?	Returns the conditions for generating an A logic pattern trigger
TRIGger:A:LOGIc:PATtern:DELTatime	Sets or returns the pattern trigger delta time value
TRIGger:A:LOGIc:PATtern:INPut:D <x></x>	Sets or returns the A logic trigger pattern for a trigger on digital channel <x></x>
TRIGger:A:LOGIc:PATtern:WHEn	Sets or returns the pattern logic condition on which to trigger the oscilloscope
TRIGger:A:LOGIc:PATtern:WHEn:LESSLimit	Sets or returns the maximum time that the selected pattern may be true and still generate an A logic pattern trigger
TRIGger:A:LOGIc:PATtern:WHEn:MORELimit	Sets or returns the minimum time that the selected pattern may be true and still generate an A logic pattern trigger
TRIGger:A:LOGIc:THReshold:CH <x></x>	Sets or queries the trigger A logic threshold voltage for the specified channel

Table 2-32: Trigger Commands (cont.)

Command	Description
TRIGger:A:LOGIc:THReshold:D <x></x>	Sets or returns the trigger A logic threshold level for the specified digital channel
TRIGger:A:LOWerthreshold:CH <x></x>	Sets or returns the lower threshold for the channel selected
TRIGger:A:LOWerthreshold:D <x></x>	Sets the A trigger lower threshold for the digital channel selected
TRIGger:A:LOWerthreshold{:EXT :AUX}	Sets or returns the lower threshold for the Auxiliary input.
TRIGger:A:MODe	Sets or returns the A trigger mode
TRIGger:A:PULse?	Returns the A pulse trigger parameters
TRIGger:A:PULse:CLAss	Sets or returns the type of pulse on which to trigger
TRIGger:A:PULSEWIDth?	Returns the trigger A pulse width parameters
TRIGger:A:PULSEWidth:POLarity	Sets or returns the polarity for the A pulse width trigger
TRIGger:A:PULSEWidth:SOUrce	Sets or returns the source for the pulse width trigger
TRIGger:A:PULSEWidth:WHEn	Sets or returns the criteria for width specification of pulse width trigger events
TRIGger:A:PULSEWidth:WIDth	Sets or returns the width setting for the pulse width trigger
TRIGger:A:RUNT?	Returns the current A runt pulse trigger logic parameters
TRIGger:A:RUNT:POLarity	Sets or returns the polarity for the A pulse runt trigger
TRIGger:A:RUNT:SOUrce	Sets or returns the source for the A pulse trigger
TRIGger:A:RUNT:WHEn	Sets or returns the type of pulse width the trigger checks for when it uncovers a runt
TRIGger:A:RUNT:WIDth	Sets or returns the minimum width for A pulse runt trigger

Table 2-32: Trigger Commands (cont.)

Command	Description
TRIGger:A:SETHold?	Returns settings for setup and hold violation triggering
TRIGger:A:SETHold:CLOCk?	Returns clock edge polarity, voltage threshold and source input for setup/hold triggering
TRIGger:A:SETHold:CLOCk:EDGE	Sets or returns the clock edge polarity for setup and hold triggering
TRIGger:A:SETHold:CLOCk:SOUrce	Sets or returns the clock source for the A logic trigger setup and hold input
TRIGger:A:SETHold:CLOCk:THReshold	Sets or returns the clock voltage threshold for setup and hold trigger
TRIGger:A:SETHold:DATa?	Returns the voltage threshold and data source for the setup/hold trigger
TRIGger:A:SETHold:DATa:SOUrce	Sets or returns the data source for the setup and hold trigger
TRIGger:A:SETHold:DATa:THReshold	Sets or returns the data voltage threshold for setup and hold trigger
TRIGger:A:SETHold:HOLDTime	Sets or returns the hold time for the setup and hold violation triggering
TRIGger:A:SETHold:SETTime	Sets or returns the setup time for setup and hold violation triggering
TRIGger:A:SETHold:THReshold:CH <x></x>	Sets or queries the threshold for the channel
TRIGger:A:SETHold:THReshold:D <x></x>	Sets the A trigger setup and hold threshold for the selected digital channel
TRIGger:A:UPPerthreshold:CH <x></x>	Sets the upper threshold for the channel selected
TRIGger:A{:TRANsition :RISEFall}?	Returns the delta time, polarity, and both upper and lower threshold limits for the transition time trigger
TRIGger:A{:TRANsition :RISEFall}:DELTatime	Sets or returns the delta time used in calculating the transition value

Table 2-32: Trigger Commands (cont.)

Command	Description
TRIGger:A{:TRANsition :RISEFall}:POLarity	Sets or returns the polarity for the A pulse transition trigger
TRIGger:A{:TRANsition :RISEFall}:SOUrce	Sets or returns the source for transition trigger
TRIGger:A{:TRANsition :RISEFall}:WHEn	Sets or returns the relationship of delta time to transitioning signal
TRIGger:A:TYPe	Sets or returns the type of A trigger
TRIGger:A:VIDeo?	Returns the video parameters for the A trigger
TRIGger:A:VIDeo:CUSTom{:FORMat :TYPE}	Sets or returns the video trigger format
TRIGger:A:VIDeo:CUSTom:LINEPeriod	Sets or queries the line period
TRIGger:A:VIDeo:CUSTom:SCAN	Sets or returns the horizontal line scan rate of the A video trigger
TRIGger:A:VIDeo:CUSTom:SYNCInterval	Sets or queries the sync interval
TRIGger:A:VIDeo:HDtv:FORMat	Sets or returns the HDTV video signal format on which to trigger
TRIGger:A:VIDeo:HOLDoff:FIELD	Sets or returns the video trigger holdoff
TRIGger:A:VIDeo:LINE	Sets or returns the video line number on which the oscilloscope triggers
TRIGger:A:VIDeo:POLarity	Sets or returns the polarity of the A video trigger
TRIGger:A:VIDeo:SOUrce	Sets or returns the polarity of the video trigger
TRIGger:A:VIDeo:STANdard	Sets or returns the video standard
TRIGger:A:VIDeo{:SYNC :FIELD}	Sets or returns the video field trigger
TRIGger:B	Sets the B trigger level to 50% or returns the B trigger parameters
TRIGger:B:BY	Sets or returns B trigger time or event qualifiers

Table 2-32: Trigger Commands (cont.)

Command	Description
TRIGger:B:EDGE?	Returns B trigger edge type parameters
TRIGger:B:EDGE:COUPling	Sets or returns the type of B trigger coupling
TRIGger:B:EDGE:SLOpe	Sets or returns the B edge trigger slope
TRIGger:B:EDGE:SOUrce	Sets or returns the B edge trigger source
TRIGger:B:EVENTS?	Returns the current B trigger events parameter
TRIGger:B:EVENTS:COUNt	Sets or returns the number of events that must occur before the B trigger occurs
TRIGger:B:LEVel	Sets or returns the level for the B trigger
TRIGger:B:LEVel:CH <x></x>	Sets or returns the level for the B trigger for a specific channel
TRIGger:B:LEVel:D <x></x>	Sets or returns the B trigger level for digital channel <x></x>
TRIGger:B:LOWerthreshold:CH <x></x>	Sets or returns the B trigger lower threshold for the channel selected
TRIGger:B:LOWerthreshold:D <x></x>	Sets or queries the B trigger lower threshold for the digital channel selected
TRIGger:B:STATE	Returns the current state of the B trigger
TRIGger:B:TIMe	Sets or returns the B trigger delay time
TRIGger:B:TYPe	Sets or returns the type of B trigger
TRIGger:B:UPPerthreshold:CH <x></x>	Sets or returns the B trigger upper threshold for the channel selected
TRIGger:EXTernal?	Returns external trigger parameters
TRIGger:EXTernal:PRObe	Sets or returns the attenuation factor value of the external probe connector
TRIGger:EXTernal:YUNIts?	Returns the external trigger vertical (Y) units value

Table 2-32: Trigger Commands (cont.)

Command	Description
TRIGger:FREQuency?	Returns the trigger frequency in hertz, if available
TRIGger:STATE?	Returns the current state of the triggering system

# **Vertical Command Group**

Use the commands in the Vertical Command Group to control the vertical setup of all live (channel) waveforms for acquisition and display of channel, reference, and math waveforms.

**Table 2-33: Vertical Commands** 

Command	Description
AUXin?	Returns auxiliary input parameters
AUXin:PRObe	Returns all information concerning the probe attached to auxilary input
AUXin:PRObe:AUTOZero	Sets the TekVPI probe attached to the auxiliary input to autozero
AUXin:PRObe:COMMAND	Sets the state of the specified probe control
AUXin:PRObe:DEGAUss	Starts a degauss/autozero cycle on a TekVPI current probe attached to the auxiliary input
AUXin:PRObe:DEGAUss:STATE?	Returns the degauss state of the TekVPI current probe attached to the auxiliary input
AUXin:PRObe:FORCEDRange	Sets or returns the range of the TekVPI probe attached to the auxiliary input
AUXin:PRObe:GAIN	Sets or returns the gain factor of the probe that is attached to the auxiliary input
AUXin:PRObe:ID:SERnumber?	Returns the serial number of the probe that is attached to the auxiliary input
AUXin:PRObe:ID:TYPE?	Returns the type of probe that is attached to the auxiliary input
AUXin:PRObe:RESistance?	Returns the resistance of the probe that is attached to the Auxiliary input
AUXin:PRObe:SIGnal	Sets or returns the input bypass setting on VPI probes that support input bypass
AUXin:PRObe:UNIts?	Returns the units of measure of the probe that is attached to the auxiliary input
CH <x>?</x>	Returns vertical parameters for the specified channel

**Table 2-33: Vertical Commands (cont.)** 

Command	Description
CH <x>:AMPSVIAVOLTs:ENAble</x>	Sets or returns the state of the amps via volts feature for the specified channel
CH <x>:AMPSVIAVOLTs:FACtor</x>	Sets or returns the amps via volts factor for the specified channel
CH <x>:BANdwidth</x>	Sets or returns the bandwidth of the specified channel
CH <x>:COUPling</x>	Sets or returns the coupling setting for the specified channel
CH <x>:DESKew</x>	Sets or returns the deskew time for the specified channel
CH <x>:INVert</x>	Sets or returns the invert function for the specified channel
CH <x>:LABel</x>	Sets or returns the waveform label for channel <x></x>
CH <x>:OFFSet</x>	Sets or returns the channel offset
CH <x>:POSition</x>	Sets or returns the channel vertical position
CH <x>:PRObe?</x>	Returns the gain, resistance, units, and ID of the probe that is attached to the specified channel
CH <x>:PRObe:AUTOZero</x>	Sets the TekVPI probe attached to the specified channel input to autozero
CH <x>:PRObe:COMMAND</x>	Sets the state of the specified probe control
CH <x>:PRObe:DEGAUss</x>	Starts a degauss/autozero cycle on a TekVPI current probe attached to the specified channel input
CH <x>:PRObe:DEGAUss:STATE?</x>	Returns the state of the probe degauss
CH <x>:PRObe:FORCEDRange</x>	Sets or returns the range on a TekVPI probe attached to the specified channel
CH <x>:PRObe:GAIN</x>	Sets or returns the gain factor of the probe that is attached to the specified channel
CH <x>:PRObe:ID?</x>	Returns the type and serial number of the probe that is attached to the specified channel
CH <x>:PRObe:ID:SERnumber?</x>	Returns the serial number of the probe that is attached to the specified channel
CH <x>:PRObe:ID:TYPE?</x>	Returns the type of probe that is attached to the specified channel
CH <x>:PRObe:MODel</x>	Sets or returns the probe model for the specified channel
CH <x>:PRObe:PROPDELay</x>	Sets or returns the propagation delay for the probe connected to the specified channel

**Table 2-33: Vertical Commands (cont.)** 

Command	Description
CH <x>:PRObe:RECDESkew?</x>	Returns the recommended deskew for the probe connected to the specified channel
CH <x>:PRObe:RESistance?</x>	Returns the resistance of the probe that is attached to the specified channel
CH <x>:PRObe:SIGnal</x>	Sets or returns the input bypass setting of channel <x>TekVPI probe</x>
CH <x>:PRObe:UNIts?</x>	Returns the units of measure of the probe that is attached to the specified channel
CH <x>:SCAle</x>	Sets or returns the vertical scale of the specified channel
CH <x>:TERmination</x>	Sets or returns channel input termination
CH <x>:YUNits</x>	Sets or returns the units for the specified channel
D <x></x>	Returns parameters for digital channel <x></x>
D <x>:LABel</x>	Sets or returns the waveform label for digital channel <x></x>
D <x>:THREshold</x>	Sets or returns the logical threshold for digital channel <x></x>
D <x>:POSition</x>	Sets or returns the vertical position for digital channel <x></x>
DESkew	Causes the deskew values for all channels to be set to the recommended values
DESkew:DISPlay	Sets or returns the state of the deskew table display
REF <x>?</x>	Returns reference waveform data for channel <x></x>
REF <x>:DATE?</x>	Returns the date that a reference waveform was stored
REF <x>:HORizontal:DELay:TIMe</x>	Sets or returns the horizontal position of the specified reference waveform in percent of the waveform that is displayed to the right of the center vertical graticule
REF <x>:HORizontal:SCAle</x>	Sets or returns the horizontal scale for a reference waveform
REF <x>:LABel</x>	Sets or returns the specified reference waveform label
	Sets or returns the vertical position for reference channel <x></x>
REF <x>:TIMe?</x>	Returns the time that a reference waveform was stored
REF <x>:VERTical:POSition</x>	Sets or returns the vertical position of the specified reference waveform

Table 2-33: Vertical Commands (cont.)

Command	Description
REF <x>:VERTical:SCAle</x>	Sets or returns the reference waveform vertical scale in vertical units/div
SELect	Returns information on which waveforms are on or off and which waveform is selected.
SELect:BUS <x></x>	Turns on or off the specified bus waveform or returns whether the specified bus channel is on or off
SELect:CH <x></x>	Turns on or off the specified waveform or returns whether the specified channel is on or off
SELect:CONTROI	Sets or returns the waveform that is selected as the implied recipient of channel-related commands
SELect:D <x></x>	Turns on the display of digital channel <x> and resets the acquisition</x>
SELect:MATH[1]	Turns on or off the math waveform or returns whether the math waveform is on or off
SELect:REF <x></x>	Turns on or off the specified reference waveform or returns whether the specified reference waveform is on or off

### **Waveform Transfer Command Group**

Use the commands in the Waveform Transfer Command Group to transfer waveform data points to and from the oscilloscope. Waveform data points are a collection of values that define a waveform. One data value usually represents one data point in the waveform record. When working with envelope waveforms, each data value is either the minimum or maximum of a min/max pair.

Before you transfer waveform data, you must specify the data format, record length, and waveform source or destination.

#### **Data Formats**

All data points for DPO and MSO models are signed integer format only. Valid data widths for CH1-CH4, MATH, REF1-REF4 and D0-D15 are 1 and 2-byte widths. The valid data widths for the digital collection is either 4 or 8-byte widths.

The oscilloscope can transfer waveform data in either ASCII or binary format. You specify the format with the DATa:ENCdg command.

**ASCII Data.** ASCII data is represented by signed integer values. The range of the values depends on the byte width specified. One byte wide data ranges from -128 to 127. Two byte wide data ranges from -32768 to 32767.

Each data value requires two to seven characters. This includes one to five characters to represent the value, another character, if the value is negative, to represent a minus sign, and a comma to separate the data points.

An example ASCII waveform data string may look like this:

**NOTE.** You can use ASCII to obtain a readable and easier to format output than binary. However, the oscilloscope may require bytes to send the same values with ASCII than with binary, reducing transmission speed.

The use of ASCII for waveform data transfer is inefficient. ASCII-formatted Waveform (WAVFRM?) and Curve (CURVE?) queries, exceeding 1 M points, are not supported.

**Binary Data.** Binary data is represented by signed integer or positive integer values. The range of the values depends on the byte width specified. When the byte width is one, signed integer data ranges from -128 to 127, and positive integer values range from 0 to 255. When the byte width is two, the values range from -32768 to 32767. and positive integer values range from 0 to 65,535.

Table 2-34: Binary data ranges

Byte width	Signed integer range	Positive integer range
1	-128 to 127	0 to 255
2	32,768 to 32,767	0 to 65,535

The defined binary formats also specify the order in which the bytes are transferred. The four binary formats are RIBinary, RPBinary, SRIbinary, and SRPbinary.

RIBinary is signed integer where the most significant byte is transferred first, and RPBinary is positive integer where the most significant byte is transferred first. SRIbinary and SRPbinary correspond to RIBinary and RPBinary respectively but use a swapped byte order where the least significant byte is transferred first. The byte order is ignored when DATa:WIDth is set to 1.

# Waveform Data and Record Lengths

You can transfer multiple points for each waveform record. You can transfer a portion of the waveform or you can transfer the entire record. You can use the DATa:STARt and DATa:STOP commands to specify the first and last data points of the waveform record.

When transferring data into the oscilloscope, you must first specify the record length of the destination waveform record. You do this with the WFMInpre:NR Pt

command. Next, specify the first data point within the waveform record. For example, when you set DATa:STARt to 1, data points will be stored starting with the first point in the record. The oscilloscope will ignore the value set by DATa:STOP when reading in data. It will stop reading data when there is no data to read or when it has reached the specified record length.

When transferring data from the oscilloscope, you must specify the first and last data points in the waveform record. Setting DATa:STARt to 1 and DATa:STOP to the record length will always return the entire waveform.

# Waveform Data Locations and Memory Allocation

The DATa:SOUrce command specifies the waveform source when transferring a waveform from the oscilloscope. You can only transfer one waveform at a time. Waveforms sent to the oscilloscope are always stored in one of the reference memory locations. Use the DATa:DESTination command to specify a reference memory location.

#### **Waveform Preamble**

Each waveform you transfer has an associated waveform preamble, which contains information such as horizontal scale, vertical scale, and the other settings in effect when the waveform was created. Refer to the individual WFMInpre and WFMOutpre commands for information.

#### **Scaling Waveform Data**

Once you transfer the waveform data to the controller, you can convert the data points into voltage values for analysis using information from the waveform preamble.

# Transferring Waveform Data from the Oscilloscope

You can transfer waveforms from the oscilloscope to an external controller using the following sequence:

- 1. Select the waveform source(s) using DATa:SOUrce.
- 2. Specify the waveform data format using DATa:ENCdg.
- 3. Specify the number of bytes per data point using WFMOutpre:BYT Nr.
- **4.** Specify the portion of the waveform that you want to transfer using DATa:STARt and DATa:STOP.
- **5.** Transfer waveform preamble information using the WFMOutpre? query.
- **6.** Transfer waveform data from the oscilloscope using the CURVe? query.

# Transferring Waveform Data to the Oscilloscope

You can transfer waveforms to the oscilloscope from an external controller using the following sequence:

- 1. Specify the reference waveform using DATa:DESTination.
- 2. Specify the record length of the reference waveform using WFMPre:NR Pt.
- **3.** Specify the waveform data format using WFMInpre:ENCdg.
- **4.** Specify the number of bytes per data point using WFMInpre:BYT Nr.
- 5. Specify first data point in the waveform record using DATa:STARt.
- **6.** Transfer waveform preamble information using WFMInpre.
- 7. Transfer waveform data to the oscilloscope using CURVe.

**Table 2-35: Waveform Transfer Commands** 

Command	Description
CURVe	The command format transfers waveform data to the oscilloscope (reference waveform specified by DATa:DESTination)
	The query format transfers waveform data from oscilloscope specified by the DATa:SOUrce command
DATa	Sets the format and location of the waveform data that is transferred with the CURVe Command
	Or returns the format and location of the waveform data that is transferred with the CURVe? command
DATa:DESTination	Sets or returns the reference waveform for storing waveform data sent to the oscilloscope
DATa:ENCdg	Sets or returns the format of outgoing waveform data
DATa:SOUrce	Sets or returns the location of waveform data transferred from the oscilloscope
DATa:STARt	Sets or returns the starting point in waveform transfer
DATa:STOP	Sets or returns the ending data point in waveform transfer
WAVFrm?	Returns a branch query containing waveform data in either binary or ASCII format, waveform formatting data, and the location of the waveform data source
WFMInpre?	Returns the waveform formatting specification to be applied to the next incoming CURVE command data

Table 2-35: Waveform Transfer Commands (cont.)

Command	Description
WFMInpre:BIT_Nr	Sets or returns the number of bits per binary waveform point for the incoming waveform
WFMInpre:BN_Fmt	Sets or returns the format of binary data for the incoming waveform
WFMInpre:BYT_Nr	Sets or returns the data width for the incoming waveform
WFMInpre:BYT_Or	Sets or returns the byte order of waveform points for the incoming waveform
WFMInpre:ENCdg	Sets or returns the type of encoding for incoming waveform data
WFMInpre:NR_Pt	Sets or returns the number of points in the incoming waveform record
WFMInpre:PT_Fmt	Sets or returns the point format of incoming waveform data
WFMInpre:PT_Off	This query always returns a 0
WFMInpre:XINcr	Sets or returns the horizontal sampling interval between incoming waveform points
WFMInpre:XUNit	Sets or returns the horizontal units of the incoming waveform
WFMInpre:XZEro	Sets or returns the time of the first point in the incoming waveform
WFMInpre:YMUIt	Sets or returns the vertical scale factor, per digitizing level, of the incoming waveform points
WFMInpre:YOFf	Sets or returns the vertical position of the incoming waveform in digitizing levels
WFMInpre:YUNit	Sets or returns the vertical units of the incoming waveform
WFMInpre:YZEro	Sets or returns the vertical offset of the incoming waveform
WFMOutpre?	Returns the waveform formatting data for the waveform specified by the DATA:SOURCE command
WFMOutpre:BIT_Nr	Sets or returns the number of bits per waveform point that outgoing waveforms contain
WFMOutpre:BN_Fmt	Sets or returns the format of binary data for the outgoing waveform
WFMOutpre:BYT_Nr	Sets or returns the data width for the outgoing waveform
WFMOutpre:BYT_Or	Sets or returns the byte order of waveform points for the outgoing waveform

Table 2-35: Waveform Transfer Commands (cont.)

Description
Sets or returns the type of encoding for outgoing waveforms
This query always returns a 0 if the waveform specified by DATA:SOUrce is on or displayed
Returns the number of points for the waveform transmitted in response to a CURVe? query
Returns the point format for the outgoing waveform
This query always returns a 0 if the waveform specified by DATA:SOUrce is on or displayed
This query always returns LINEAR
Returns a string describing the acquisition parameters for the outgoing waveform
Returns the horizontal sampling interval for the outgoing waveform
Returns the horizontal units for the outgoing waveform
Returns the time of the first point in the outgoing waveform
Returns the vertical scale factor per digitizing level for the outgoing waveform
Returns the vertical position in digitizing levels for the outgoing waveform
Returns the vertical units for the outgoing waveform
Returns the vertical offset for the outgoing waveform

# **Zoom Command Group**

Use the commands in the Zoom Command Group to expand and position the waveform display horizontally, without changing the time base settings.

Table 2-36: Zoom Commands

Command	Description
ZOOm?	Returns the horizontal positioning and scaling of the zoom display
ZOOm:MODe	Sets or returns the zoom mode
ZOOm:ZOOM <x>?</x>	Returns the current horizontal positioning and scaling of the zoom display

Table 2-36: Zoom Commands (cont.)

Command	Description
ZOOm:ZOOM <x>:FACtor?</x>	Returns the zoom factor of the zoom window. <x> can only be 1</x>
ZOOm:ZOOM <x>:POSition</x>	Sets or returns the horizontal position of the zoom window in terms of 0 to 100% of the overview window. <x> can only be 1</x>
ZOOm:ZOOM <x>:SCAle</x>	Sets or returns the horizontal zoom scale of the zoom window. <x> can only be 1</x>
ZOOm:ZOOM <x>:STATE</x>	Specifies or returns a trace as zoomed, on or off. <x> can only be 1</x>

# **Commands Listed in Alphabetical Order**

### **ACQuire?** (Query Only)

Returns the following current acquisition parameters:

- Stop after
- Acquisition state
- Mode
- Number of averages
- Sampling mode

**Group** Acquisition

Syntax ACQuire?

Related Commands ACQuire:MODe, ACQuire:NUMACq?, ACQuire:NUMAVg,

ACQuire:STOPAfter

# ACQuire: MAGnivu

Sets or returns the MagniVu feature, which provides up to 32 times signal detail for fast viewing of short events. This feature is not recommended for slow data formats such as RS-232.

**NOTE.** MagniVu channel sampling is available on MSO oscilloscopes only.

**Group** Acquisition

**Syntax** ACQuire:MAGnivu {<NR1>|OFF|ON}

ACQuire:MAGnivu?

**Arguments** <NR1> = 0 disables the MagniVu feature; any other value turns this feature on.

ON enables the MagniVu feature.

OFF disables the MagniVu feature.

# **ACQuire: MAXSamplerate? (Query Only)**

Returns the maximum real-time sample rate, which varies from model to model.

**Group** Acquisition

**Syntax** ACQuire:MAXSamplerate?

**Examples** ACQUIRE: MAXSAMPLERATE? might return 2.5000E+9 in a DPO4034 indicating

the maximum real-time sample rate is 2.5GS/s.

#### **ACQuire:MODe**

Sets or returns the acquisition mode of the oscilloscope for all live waveforms.

Waveforms are the displayed data point values taken from acquisition intervals. Each acquisition interval represents a time duration set by the horizontal scale (time per division). The oscilloscope sampling system always samples at the maximum rate, so the acquisition interval may include than one sample.

The acquisition mode (which you set using this ACQuire:MODe command) determines how the final value of the acquisition interval is generated from the many data samples.

**Group** Acquisition

Syntax ACQuire:MODe {SAMple|PEAKdetect|HIRes|AVErage|ENVelope}

ACQuire: MODe?

Related Commands ACQuire: NUMAVg, CURVe

Arguments SAMple specifies that the displayed data point value is the first sampled value that is taken during the acquisition interval. In sample mode, all waveform data has 8 bits of precision. You can request 16 bit data with a CURVe query but the

lower-order 8 bits of data will be zero. SAMple is the default mode.

PEAKdetect specifies the display of high-low range of the samples taken from a single waveform acquisition. The high-low range is displayed as a vertical column that extends from the highest to the lowest value sampled during the acquisition interval. PEAKdetect mode can reveal the presence of aliasing or narrow spikes.

HIRes specifies Hi Res mode where the displayed data point value is the average of all the samples taken during the acquisition interval. This is a form

of averaging, where the average comes from a single waveform acquisition. The number of samples taken during the acquisition interval determines the number of data values that compose the average.

AVErage specifies averaging mode, in which the resulting waveform shows an average of SAMple data points from several separate waveform acquisitions. The oscilloscope processes the number of waveforms you specify into the acquired waveform, creating a running exponential average of the input signal. The number of waveform acquisitions that go into making up the average waveform is set or queried using the ACQuire:NUMAVg command.

**ENVelope** specifies envelope mode, where the resulting waveform shows the PEAKdetect range of data points from every waveform acquisition.

#### **Examples**

ACQUIRE: MODE ENVELOPE sets the acquisition mode to display a waveform that is an envelope of many individual waveform acquisitions.

ACQUIRE: MODE? might return: ACQuire: MODE AVERAGE indicating that the displayed waveform is the average of the specified number of waveform acquisitions.

# ACQuire: NUMACq? (Query Only)

Returns the number of waveform acquisitions that have occurred since starting acquisition with the ACQuire:STATE:RUN command. This value is reset to zero when any acquisition, horizontal, or vertical arguments that affect the waveform are changed. The maximum number of acquisitions that can be counted is 2<sup>32</sup> 1.

**Group** Acquisition

**Syntax** ACQuire: NUMACq?

Related Commands ACQuire:STATE

Returns ACQuire: NUMACQ? might return: ACQUIRE: NUMACQ 350 indicating that 350

acquisitions have occurred since executing an ACQuire:STATE RUN command.

# **ACQuire:NUMAVg**

Sets or returns the number of waveform acquisitions that make up an averaged waveform. Use the ACQuire:MODe command to enable the Average mode. Sending this command is equivalent to turning a multipurpose knob to enter the number of waveform acquisitions to average.

**Group** Acquisition

Syntax ACQuire:NUMAVg <NR1>

ACQuire: NUMAVg?

Related Commands ACQuire:MODe

**Arguments** <NR1> is the number of waveform acquisitions to average. The range of values is

from 2 to 512 in powers of two.

**Examples** ACQUIRE: NUMAVG 16 specifies that 16 waveform averages will be performed

before exponential averaging starts.

ACQUIRE: NUMAVG? might return: ACQUIRE: NUMAVG 64 indicating that there

are 64 acquisitions specified for averaging.

#### **ACQuire:STATE**

Starts or stops acquisitions. When state is set to ON or RUN, a new acquisition will be started. If the last acquisition was a single acquisition sequence, a new single sequence acquisition will be started. If the last acquisition was continuous, a new continuous acquisition will be started.

If RUN is issued in the middle of completing a single sequence acquisition (for example, averaging or enveloping), the acquisition sequence is restarted, and any accumulated data is discarded. Also, the oscilloscope resets the number of acquisitions. If the RUN argument is issued while in continuous mode, acquisition continues.

**Group** Acquisition

Syntax ACQuire:STATE {OFF|ON|RUN|STOP|<NR1>}

ACQuire:STATE?

Related Commands ACQuire:STOPAfter

**Arguments** OFF stops acquisitions.

STOP stops acquisitions.

ON starts acquisitions.

RUN starts acquisitions.

<NR1> = 0 stops acquisitions; any other value starts acquisitions.

**Examples** 

ACQUIRE: STATE RUN starts the acquisition of waveform data and resets the count

of the number of acquisitions.

ACQUIRE: STATE? might return: ACQUIRE: STATE 0 indicating that the

acquisition is stopped.

#### **ACQuire:STOPAfter**

Sets or returns whether the oscilloscope continually acquires acquisitions or acquires a single sequence.

**Group** Acquisition

Syntax ACQuire:STOPAfter {RUNSTop|SEQuence}

ACQuire:STOPAfter?

Related Commands ACQuire:STATE

**Arguments** RUNSTop specifies that the oscilloscope will continually acquire data, if

ACQuire: STATE is turned on.

SEQuence specifies that the next acquisition will be a single-sequence acquisition.

**Examples** ACQUIRE: STOPAFTER RUNSTOP sets the oscilloscope to continually acquire data.

ACQUIRE: STOPAFTER? might return: ACQUIRE: STOPAFTER SEQUENCE indicating that the next acquisition the oscilloscope makes will be of the

single-sequence type.

#### **ALlas**

Sets or returns the state of alias functionality. Use Alias commands to define new commands as a sequence of standard commands. You may find this useful when repeatedly using the same commands to perform certain tasks like setting up measurements. Aliases are similar to macros but do not include the capability to substitute parameters into alias bodies.

To use Alias commands, first define the alias, then turn on the alias state.

**Group** Alias

Syntax ALIas {OFF|ON|<NR1>}

ALIas?

**Related Commands** ALIas:DEFine

ALIas[:STATE]

Arguments

OFF turns alias expansion off. If a defined alias is sent when ALIas is off, a command error (110) will be generated.

ON turns alias expansion on. When a defined alias is received, the specified command sequence is substituted for the alias and executed.

<NR1> = 0 disables alias mode; any other value enables alias mode.

**Examples** 

ALIAS ON turns the alias feature on. When a defined alias is received, the specified command sequence is substituted for the alias and executed.

ALIAS? might return: ALIAS 1 indicating that the alias feature is on.

### ALIas:CATalog? (Query Only)

Returns a list of the currently defined alias labels, separated by commas. If no aliases are defined, the query returns the string "".

**Group** Alias

**Syntax** ALIas: CATalog?

**Examples** 

ALIAS:CATALOG? might return the string :ALIAS:CATALOG

"SETUP1", "TESTMENU1", "DEFAULT" showing that there are three aliases

named SETUP1, TESTMENU1, and DEFAULT.

#### **ALlas:DEFine**

Assigns a sequence of program messages to an alias label. These messages are then substituted for the alias whenever it is received as a command or query, provided that ALIas:STATE has been turned on. The query form of this command returns the definitions of a selected alias.

**NOTE.** Attempting to give two aliases the same name causes an error. To give a new alias the name of an existing alias, the existing alias must first be deleted.

**Group** Alias

Syntax ALIas:DEFine <QString><,>{<QString>|<Block>}

ALIas:DEFine? <QString>

**Related Commands** ALIas[:STATE]

**Arguments** The first **<QString>** is the alias label.

This label cannot be a command name. Labels must start with a letter and can contain only letters, numbers, and underscores; other characters are not allowed.

The label must be less than or equal to 12 characters.

The second<QString> or <Block> is a complete sequence of program messages.

The messages can contain only valid commands that must be separated by semicolons and must follow all rules for concatenating commands. The sequence

must be less than or equal to 256 characters.

**Examples** ALIAS:DEFINE "ST1", ": RECALL: SETUP 5;: AUTOSET

EXECUTE;:SELECT:CH1 ON" defines an alias named "ST1" that sets

up the oscilloscope.

ALIAS:DEFINE? "ST1" returns :ALIAS:DEFINE "ST1",#246 :RECALL:SETUP 5;:AUTOSET EXECUTE;:SELECT:CH1 ON

# ALIas:DELEte (No Query Form)

Removes a specified alias and is identical to ALIas:DELEte:NAMe. An error message is generated if the named alias does not exist.

Group Alias

Syntax ALIas:DELEte <QString>

Related Commands \*ESR?, ALIas:DELEte:ALL

**Arguments** <QString> is the name of the alias to be removed. Using ALIas:DELEte

without specifying an alias causes an execution error. <QString> must be a

previously defined value.

**Examples** ALIAS: DELETE "SETUP1" deletes the alias named SETUP1.

### ALIas:DELEte:ALL (No Query Form)

Deletes all existing aliases.

**Group** Alias

Syntax ALIas:DELEte:ALL

Related Commands ALIas:DELEte, ALIas:DELEte[:NAMe]

**Examples** ALIAS: DELETE: ALL deletes all existing aliases.

### ALIas:DELEte[:NAMe] (No Query Form)

Removes a specified alias. This command is identical to ALIas:DELEte

**Group** Alias

Syntax ALIas:DELEte[:NAMe] <QString>

**Arguments** <QString> is the name of the alias to remove. Using ALIas:DELEte[:NAMe]

without specifying an alias causes an execution error. <QString> must be an

existing alias.

**Examples** ALIAS:DELETE[:NAME] "STARTUP" deletes the alias named STARTUP.

ALIas[:STATE]

Turns aliases on or off. This command is identical to the ALIas command.

**Group** Alias

Syntax ALIas[:STATE] {<NR1>|OFF|ON}

ALIas[:STATE]?

**Arguments** OFF or  $\langle NR1 \rangle = 0$  turns alias expansion off. If a defined alias is sent when

ALIas:STATE is OFF, a command error (102) is generated.

ON or <NR1>0 turns alias expansion on. When a defined alias is received, the

specified command sequence is substituted for the alias and executed.

**Examples** ALIAS[:STATE] OFF turns the command alias feature off.

ALIAS[:STATE]? returns 0 when the alias feature is off.

# **ALLEv?** (Query Only)

Prompts the oscilloscope to return all events and their messages (delimited by commas), and removes the returned events from the Event Queue. Use the \*ESR? query to enable the events to be returned. This command is similar to repeatedly sending \*EVMsg? queries to the oscilloscope.

**Group** Status and Error

Syntax ALLEV?

**Related Commands** \*ESR?, EVMsg?

**Examples** ALLEV? might return: ALLEV 2225, "Measurement error, No waveform

to measure; "420,"Query UNTERMINATED;"

#### **AUTOSet (No Query Form)**

Sets the vertical, horizontal, and trigger controls of the oscilloscope to automatically acquire and display the selected waveform.

**Group** Miscellaneous

**Syntax** AUTOSet {EXECute|UNDo}

**Arguments** EXECute autosets the displayed waveform.

UNDo restores the oscilloscope settings to those present prior to the autoset

execution.

**Examples** 

AUTOSET EXECUTE vertical, horizontal, and trigger controls of the oscilloscope to

automatically acquire and display the selected waveform.

#### AUTOSet: ENAble

Enables or disables the autoset feature. This is useful for classroom purposes where the instructor wants the students to achieve the desired instrument settings without the benefit of the autoset feature. This setting is not saved in setup files or SET? or \*LRN? queries. The default state is 1 (autoset enabled).

Miscellaneous Group

AUTOSet:ENAble {OFF|ON|0|1} **Syntax** 

AUTOSet: ENAble?

OFF or 0 disables autoset. **Arguments** 

ON or 1 enables autoset.

**Examples** AUTOSET: ENABLE 1 enables the front-panel **Autoset** button.

AUTOSET: ENABLE? might return AUTOSET: ENABLE 0 indicating that the autoset

feature is disabled.

## **AUXin?** (Query Only)

Returns all auxiliary input parameters.

Group Vertical

Syntax AUXin?

#### AUXin:PRObe

Returns all information concerning the probe attached to auxiliary input.

Group Vertical

AUXin: PRObe **Syntax** 

AUXin: PRObe?

#### **Examples**

AUXIN:PROBE? might return AUXIN:PROBE:ID:TYPE "No Probe Detected";SERNUMBER "";:AUXIN:PROBE:UNITS "";RESISTANCE 1.0000E+6 giving information about the probe attached to the AUX In input.

### AUXin:PRObe:AUTOZero (No Query Form)

Sets the TekVPI probe attached to the Aux In input to autozero. The oscilloscope will ignore this command if the Auxiliary input does not have a TekVPI probe connected to it.

**Group** Vertical

**Syntax** AUXin:PRObe:AUTOZero {EXECute}

**Arguments** EXECute sets the probe to autozero.

Examples AUXin:PROBE:AUTOZERO EXECUTE

### AUXin:PRObe:COMMAND (No Query Form)

Sets the state of the probe control specified with the first argument to the state specified with the second argument. The commands and states are unique to the attached probe type. Only certain VPI probes support this command. See the probe documentation for how to set these string arguments.

**Group** Vertical

Syntax AUXin:PRObe:COMMAND <QString>, <QString>

**Arguments** <QString> are quoted strings specifying the probe command and value to set in

the probe attached to the auxiliary input.

**Examples** AUXIN: PROBE: COMMAND "OUTPUT", "ON" turns the output of a Tektronix

VPI-DPG probe on.

AUXIN:PROBE:COMMAND "MODE", "4-4V1MHz" sets a Tektronix VPI-DPG

probe to the 4-4V1MHz mode.

AUXIN: PROBE: COMMAND? "MODE" might return AUXIN: PROBE: COMMAND

"MODE", "4-4V1MHZ".

# AUXin:PRObe:DEGAUss (No Query Form)

Starts a degauss/autozero cycle on a TekVPI current probe attached to the Aux In input. If you send this command to a probe that does not support this function, it is ignored

**Group** Vertical

Syntax AUXin:PRObe:DEGAUSS {EXECute}

**Arguments** EXECute starts a probe degauss cycle.

**Examples** AUXin:PROBE:DEGAUSS EXECUTE degausses the probe attached to the Aux

In input.

### AUXin:PRObe:DEGAUss:STATE? (Query Only)

Returns the state of the probe degauss (NEEDED, RECOMMENDED, PASSED, FAILED, RUNNING). The command will return PASSED for probes that do not support degauss operations.

**Group** Vertical

**Syntax** AUXin:PRObe:DEGAUSS:STATE?

**Examples** AUXin:PROBE:DEGAUSS:STATE? might return:

AUXin:PROBE:DEGAUSS:STATE PASSED indicating that the probe has been

degaussed.

# AUXin:PRObe:FORCEDRange

Changes or returns the range on a TekVPI probe attached to the Aux In input.

**Group** Vertical

Syntax AUXin:PRObe:FORCEDRange <NR3>

AUXin: PRObe: FORCEDRange?

**Arguments** <NR3> is the probe range, which is probe dependent.

AUXin:PRObe:GAIN

Sets or returns the gain factor of a probe that is attached to the Aux In input.

**Group** Vertical

Syntax AUXin:PRObe:GAIN <NR3>

AUXin:PRObe:GAIN?

**Arguments** <NR3> is the probe gain, which is probe dependent.

**Examples** AUXin:PROBE:GAIN? might return:AUXin:PROBE:GAIN 100.0000E-3

indicating that the attached 10x probe delivers 0.1 V to the Aux In BNC for every

1.0 V applied to the probe input.

AUXin:PRObe:ID:SERnumber? (Query Only)

Returns the serial number of the probe that is attached to the auxiliary input.

**Group** Vertical

Syntax AUXin:PRObe:ID:SERnumber?

AUXin:PRObe:ID:TYPE? (Query Only)

Returns the type of probe that is attached to the auxiliary input.

**Group** Vertical

Syntax AUXin:PRObe:ID:TYPE?

AUXin:PRObe:RESistance? (Query Only)

Returns the resistance of the probe attached to the front panel Aux In connector.

**Group** Vertical

**Syntax** AUXin:PRObe:RESistance?

**Examples** 

AUXin:PRObe:RESistance? might return :AUXin:PROBE:RESISTANCE 1.0000E+6 indicating that the input resistance of the probe attached to the front panel Aux In connector is  $1~M\Omega$ .

**NOTE.** This query will return 0.0 if no probe is attached or the attached probe does not report the input resistance.

#### AUXin:PRObe:SIGnal

This command changes the input bypass setting on VPI probes that support input bypass, for example the TCP0001. If sent to a probe that does not support input bypass, it is ignored.

**Group** Vertical

**Syntax** AUXin:PRObe:SIGnal {BYPass|PASS}

AUXin: PRObe: SIGnal?

**Arguments** ByPass sets the probe to Bypass mode.

PASS sets the probe to Pass mode.

## AUXin:PRObe:UNIts? (Query Only)

Returns a string describing the units of measure of the probe attached to the Aux In input.

**Group** Vertical

Syntax AUXin:PRObe:UNIts?

**Examples** AUXin:PROBE:UNITS? might return: :AUXin:PROBE:UNITS "V" indicating

that the units of measure for the attached probe are volts.

### **BUS?** (Query Only)

Returns the parameters for each bus. These parameters affect either the Serial

Trigger Setup or the Bus Display.

**Conditions** This command requires a serial bus analysis module.

**Group** Bus

Syntax BUS?

#### BUS:B<x>:AUDio:BITDelay

Sets or returns the number of delay bits for the AUDIO bus.

**NOTE.** This command is applicable only for TDM audio bus type (BUS:B<x>AUDio:TYPe TDM)

**Conditions** This command requires DPO4AUDIO application module.

**Group** Bus

Syntax BUS:B<x>:AUDio:BITDelay <NR1>

BUS:B<x>:AUDio:BITDelay?

**Arguments** <NR1> specifies the number of delay bits.

**Examples** BUS:B1:AUDIO:BITDELAY 2 sets the bit delay to 2.

BUS:B1:AUDIO:BITDELAY? might return :BUS:B1:AUDIO:BITDELAY 1

indicating that the number of delay bits is 1.

#### BUS:B<x>:AUDio:BITOrder

Sets or returns the bit order for the AUDIO bus.

**Conditions** This command requires DPO4AUDIO application module.

**Group** Bus

Syntax BUS:B<x>:AUDio:BITOrder {MSB|LSB}

BUS:B<x>:AUDio:BITOrder?

**Arguments** MSB specifies that the most significant bit will be expected first in the order.

LSB specifies that the least significant bit will be expected first in the order.

**Examples** BUS:B1:AUDIO:BITORDER LSB sets the bit order to LSB.

BUS:B1:AUDIO:BITORDER? might return:BUS:B1:AUDIO:BITORDER MSB

indicating that the MSB is first in the bit order.

#### BUS:B<x>:AUDio:CHANnel:SIZe

Sets or returns the number of bits per channel for the AUDIO bus.

**NOTE.** This command is applicable only for TDM audio bus type

(BUS:B<x>AUDio:TYPe TDM)

**Conditions** This command requires DPO4AUDIO application module.

**Group** Bus

Syntax BUS:B<x>:AUDio:CHANnel:SIZe <NR1>

BUS:B<x>:AUDio:CHANnel:SIZe?

**Arguments** <NR1> specifies the number of bits per channel.

**Examples** BUS:B1:AUDIO:CHANNEL:SIZE 8 sets the number of bits per channel to 8.

BUS:B1:AUDIO:CHANNEL:SIZE? might return

:BUS:B1:AUDIO:CHANNEL:SIZe 24 indicating that the number of bits per

channel is 24.

# BUS:B<x>:AUDio:CLOCk:POLarity

Sets or returns the clock polarity for the AUDIO bus.

**Conditions** This command requires DPO4AUDIO application module.

**Group** Bus

Syntax BUS:B<x>:AUDio:CLOCk:POLarity {FALL|RISe}

BUS:B<x>:AUDio:CLOCk:POLarity?

**Arguments** FALL sets falling edge as the clock polarity.

RISe sets rising edge as the clock polarity.

**Examples** BUS:B1:AUDIO:CLOCK:POLARITY Fall sets the clock polarity to Fall.

BUS:B1:AUDIO:CLOCK:POLARITY? might return

:BUS:B1:AUDIO:CLOCK:POLARITY RISe indicating that the clock polarity

is set to Rise.

#### BUS:B<x>:AUDio:CLOCk:SOUrce

Sets or returns the clock source waveform for the AUDIO bus.

**Conditions** This command requires DPO4AUDIO application module.

**Group** Bus

Syntax BUS:B<x>:AUDio:CLOCk:SOUrce {CH1|CH2|CH3|CH4|

D0|D1|D2|D3|D4|D5|D6|D7|D8|D9|D10|D11|D12|D13|D14|D15}

BUS:B<x>:AUDio:CLOCk:SOurce?

**Arguments** CH1-Ch4 or D0-D15 specifies the clock source for the audio bus.

**Examples** BUS:B1:AUDIO:CLOCK:SOURCE D1 sets D1 as the clock source for the audio

bus.

BUS:B1:AUDIO:CLOCK:SOURCE? might return

:BUS:B1:AUDIO:CLOCK:SOURCE CH1 indicating that the clock source is

set to CH1.

# BUS:B<x>:AUDio:DATa:POLarity

Sets or returns the data polarity for the AUDIO bus.

**Conditions** This command requires DPO4AUDIO application module.

**Group** Bus

Syntax BUS:B<x>:AUDio:DATa:POLarity {NORMal|INVERTed}

BUS:B<x>:AUDio:DATa:POLarity?

**Arguments** NORMal specifies positive data polarity for the audio bus.

INVERTEd specifies negative data polarity for the audio bus.

**Examples** BUS:B1:AUDIO:DATA:POLARITY INVERTEd sets the data polarity to Inverted.

BUS:B1:AUDIO:DATA:POLARITY? might return

:BUS:B1:AUDIO:DATA:POLARITY NORMAL indicating that the data polarity is

set to Normal.

#### BUS:B<x>:AUDio:DATa:SIZe

Sets or returns the number of bits per word for the AUDIO bus.

**NOTE.** The number of bits specified for this command must be always less than or equal to the number of bits per channel (BUS:B < x > :AUDio:CHANnel:SIZe)

**Conditions** This command requires DPO4AUDIO application module.

Group Bus

Syntax BUS:B<x>:AUDio:DATa:SIZe <NR1>

BUS:B<x>:AUDio:DATa:SIZe?

**Arguments** NR1 specifies the number of bits per word.

**Examples** BUS:B1:AUDIO:DATA:SIZE 8 sets the number of bits per word to 8.

BUS:B1:AUDIO:DATA:SIZE? might return :BUS:B1:AUDIO:DATA:SIZE 24

indicating that the number of bits per word is set to 24.

#### BUS:B<x>:AUDio:DATa:SOUrce

Sets or returns the data source waveform for the AUDIO bus.

**Conditions** This command requires DPO4AUDIO application module.

Group Bus

Syntax BUS:B<x>:AUDio:DATa:SOUrce {CH1|CH2|CH3|CH4|

D0|D1|D2|D3|D4|D5|D6|D7|D8|D9|D10|D11|D12|D13|D14|D15}

BUS:B<x>:AUDio:DATa:SOUrce?

**Arguments** CH1-Ch4 or D0-D15 specifies the channel to use for data source for the audio

bus.

**Examples** BUS:B1:AUDIO:DATA:SOURCE D1 sets the data source to D1.

BUS:B1:AUDIO:DATA:SOURCE? might return:BUS:B1:AUDIO:DATA:SOURCE

CH3 indicating that the data source is set to CH3.

# BUS:B<x>:AUDio:DISplay:FORMat

Sets or returns the display format for the AUDIO bus.

**Conditions** This command requires DPO4AUDIO application module.

**Group** Bus

**Syntax** BUS:B<x>:AUDio:DISplay:FORMat

{BINary|HEXadecimal|SIGNEDDECimal} BUS:B<x>:AUDio:DISplay:FORMat?

**Arguments** BINary specifies a binary data display.

HEXadecimal specifies a hexadecimal data display.

SIGNEDDECimal specifies a signed decimal data display.

**Examples** BUS:B1:AUDIO:DISPLAY:FORMAT BINARY sets the display format to Binary.

BUS:B1:AUDIO:DISPLAY:FORMAT? might return

:BUS:B1:AUDIO:DISPLAY:FORMAT SIGNEDDECIMAL indicating that the

display format is set to signed decimal.

#### BUS:B<x>:AUDio:FRAME:SIZe

Sets or returns the number of channels in each frame for the AUDIO bus.

NOTE. This command is applicable only for TDM audio bus type

(BUS:B<X>AUDio:TYPe TDM)

**Conditions** This command requires DPO4AUDIO application module.

**Group** Bus

Syntax BUS:B<x>:AUDio:FRAME:SIZe <NR1>

BUS:B<x>:AUDio:FRAME:SIZe?

**Arguments** <NR1> specifies the number of channels in each frame.

**Examples** BUS:B1:AUDIO:FRAME:SIZE 2 sets the frame size to 2.

BUS:B1:AUDIO:FRAME:SIZE? might return :BUS:B1:AUDIO:FRAME:SIZE 8

indicating that the number of channels in each frame is set to 8.

#### BUS:B<x>:AUDio:FRAMESync:POLarity

Sets or returns the frame sync polarity for the AUDIO bus.

**Conditions** This command requires DPO4AUDIO application module.

**Group** Bus

Syntax BUS:B<x>:AUDio:FRAMESync:POLarity {FALL|RISe}

BUS:B<x>:AUDio:FRAMESync:POLarity?

**Arguments** FALL specifies the falling edge as the frame sync polarity.

RISe specifies the rising edge as the frame sync polarity.

**Examples** BUS:B1:AUDIO:FRAMESYNC:POLARITY FALL sets the falling edge for frame

sync polarity.

BUS:B1:AUDIO:FRAMESYNC:POLARITY? might return

:BUS:B1:AUDIO:FRAMESYNC:POLARITY RISe indicating that the

polarity is set to Rise.

# BUS:B<x>:AUDio:FRAMESync:SOUrce

Sets or returns the frame sync source waveform for the AUDIO bus.

**Conditions** This command requires DPO4AUDIO application module.

**Group** Bus

Syntax BUS:B<x>:AUDio:FRAMESync:SOUrce {CH1|CH2|CH3|CH4|

D0|D1|D2|D3|D4|D5|D6|D7|D8|D9|D10|D11|D12|D13|D14|D15}

BUS:B<x>:AUDio:FRAMESync:SOUrce?

**Arguments** CH1-CH4 or D0-D15 specifies the channel to use as the frame sync source.

**Examples** BUS:B1:AUDIO:FRAMESYNC:SOURCE CH1 sets CH1 as the frame sync source.

BUS:B1:AUDIO:FRAMESYNC:SOURCE? might return

:BUS:B1:AUDIO:FRAMESYNC:SOURCE Ch2 indicating that the source is set to

Ch2.

#### BUS:B<x>:AUDio:TYPe

Sets or returns the audio format (type) for the AUDIO bus.

**Conditions** This command requires DPO4AUDIO application module.

**Group** Bus

Syntax BUS:B<x>:AUDio:TYPe {I2S|LJ|RJ|TDM}

BUS:B<x>:AUDio:TYPe?

**Arguments** 12S specifies I<sup>2</sup>S audio format.

LJ specifies left-justified audio format.

RJ specifies right justified audio format.

TDM specifies time-division multiplexing audio format.

**Examples** BUS:B1:AUDIO:TYPE RJ sets right-justified as the audio format.

BUS:B1:AUDIO:TYPE? might return:BUS:B1:AUDIO:TYPE I2S indicating

that the audio format is set to I2S.

### BUS:B<x>:AUDio:WORDSel:POLarity

Sets or returns the word select polarity for the AUDIO bus.

**Conditions** This command requires DPO4AUDIO application module.

Group Bus

Syntax BUS:B<x>:AUDio:WORDSel:POLarity {NORMal|INVERTed}

BUS:B<x>:AUDio:WORDSel:POLarity?

**Arguments** NORMal specifies positive WORDSel polarity.

INVERTed specifies negative WORDSel polarity.

**Examples** BUS:B1:AUDIO:WORDSEL:POLARITY NORMal sets normal as the word select

polarity.

BUS:B1:AUDIO:WORDSE1:POLARITY? might return

:BUS:B1:AUDIO:WORDSEL:POLARITY NORMAL indicating that the word select

polarity is set to normal.

#### BUS:B<x>:AUDio:WORDSel:SOUrce

Sets or returns the word select source waveform for the AUDIO bus.

**Conditions** This command requires DPO4AUDIO application module.

**Group** Bus

Syntax BUS:B<x>:AUDio:WORDSel:SOUrce {CH1|CH2|CH3|CH4

|D0|D1|D2|D3|D4|D5|D6|D7|D8|D9|D10|D11|D12|D13|D14|D15}

BUS:B<x>:AUDio:WORDSel:Source?

**Arguments** CH1-CH4 specifies the channel to use as the word select source.

D0-D15 specifies the digital channel to use as the word select source.

**Examples** BUS:B1:AUDIO:WORDSEL:SOURCE CH1 sets CH1 as the word select source.

BUS:B1:AUDIO:WORDSEL:SOURCE? might return

:BUS:B1:AUDIO:WORDSEL:SOURCE CH2 indicating that the word select source

is set to CH2.

#### BUS:B<x>:CAN:BITRate

Sets or returns the bit rate for CAN bus  $\langle x \rangle$ , where x is the bus number.

**Conditions** This command requires a DPO4AUTO application module.

**Group** Bus

**Syntax** BUS:B<x>:CAN:BITRate

<NR1>|{RATE10K|RATE20K|RATE33K|RATE37K|RATE50K|RATE62K|
RATE83K|RATE92K|RATE100K|RATE125K|RATE250K|RATE500K|

RATE800K | RATE1M }

BUS:B<x>:CAN:BITRate?

**Arguments** <NR1> is the bit rate. The instrument supports bit rates at 10 bps intervals. You

can enter any positive integer, and the instrument will coerce the value to the

closest supported bit rate.

**Returns** The query always returns the numerical bit rate value.

**Examples** bus:b1:can:bitrate rate400k sets the CAN bit rate to 400K.

bus:b1:can:bitrate? might return :BUS:B1:CAN:BITRATE RATE800K

indicating the bit rate is set to 800K.

#### BUS:B<x>:CAN:PRObe

Sets or returns the probing method to probe CAN bus  $\langle x \rangle$ , where x is the bus

number.

**Conditions** This command requires a DPO4AUTO application module.

**Group** Bus

Syntax BUS:B<x>:CAN:PRObe {CANH|CANL|RX|TX|DIFFerential}

BUS:B<x>:CAN:PRObe?

**Arguments** CANH specifies the single-ended CANH signal, as specified by the CAN standard.

CANL specifies the single-ended CANL signal, as specified by the CAN standard.

RX specifies the receive signal on the bus side of the CAN transceiver.

TX specifies the transmit signal.

DIFFerential specifies the differential CAN signal.

# BUS:B<x>:CAN:SAMPLEpoint

Sets or returns the sampling point during each bit period for bus  $\langle x \rangle$ , where x

is the bus number

**Conditions** This command requires a DPO4AUTO application module.

Group Bus

Syntax BUS:B<x>:CAN:SAMPLEpoint <NR1>

BUS:B<x>:CAN:SAMPLEpoint?

**Arguments** <NR1> is the sample point in percent. Values are limited to 25, 30, ... 70, 75.

#### BUS:B<x>:CAN:SOUrce

Sets or returns the CAN bus data source for bus <x>, where x is the bus number.

**Conditions** This command requires a DPO4AUTO application module.

**Group** Bus

Syntax BUS:B<x>:CAN:SOUrce {CH1|CH2|CH3|CH4|

D0|D1|D2|D3|D4|D5|D6|D7|D8|D9|D10|D11|D12|D13|D14|D15}

BUS:B<x>:CAN:SOUrce?

**Arguments** CH1-CH4 is the analog channel to use as the data source.

D0-D15 is the digital channel to use as the data source.

## BUS:B<x>:DISplay:FORMAt

Sets or returns the display format for the numerical information in the bus waveform, where <x> is the bus number. The display formats supported depend on the BUS:B<x>:TYPE.

Table 2-37: Supported display formats

Bus type	Display format	
Parallel	BINary   HEXadecimal	
I <sub>2</sub> C	BINary   HEXadecimal	
SPI	BINary   HEXadecimal	
CAN	BINary   HEXadecimal	
RS232C	BINary   HEXadecimal   ASCII	
Audio	BINary   HEXadecimal   ASCII   SIGNEDDECimal <sup>1</sup>	
LIN	BINary   HEXadecimal   MiXed	
FlexRay	BINary   HEXadecimal   MIXed	
USB	BINary   HEXadecimal   MIXed   MIXED2	

<sup>1</sup> SIGNEDDECimal is set using the audio application BUS:B<x>:AUDio:DISplay:FORMat command.

**Conditions** This command requires a serial bus analysis module.

**Group** Bus

**Syntax** BUS:B<x>:DISplay:FORMAt

{BINary|HEXadecimal|ASCII|MIXed|MIXED2}

BUS:B<x>:DISplay:FORMAt?

**Related Commands** BUS:B<x>:TYPE

**Arguments** BINary – All values are displayed in binary.

HEXadecimal – All values are displayed in hexadecimal.

ASCII – All values are displayed in an ASCII format, for RS-232 only.

MIXed – Values are displayed in a mixture of hexadecimal, binary, and decimal, depending on the field.

MIXED2 – Values are displayed in a mixture of hexadecimal, binary, decimal and ASCII, depending on the field.

## BUS:B<x>:DISplay:TYPe

Sets or returns the display type for bus  $\langle x \rangle$ , where x is the bus number. You can set up the bus to display the protocol information, the logic waveforms that comprise the bus, or both.

**Conditions** This command requires a serial bus analysis module.

**Group** Bus

Syntax BUS:B<x>:DISplay:TYPe {BUS|BOTh}

BUS:B<x>:DISplay:TYPe?

**Arguments** BUS displays the bus waveforms only.

BOTh displays both the bus and logic waveforms.

## BUS:B<x>:FLEXray:BITRate

Sets or returns the bit rate for FLEXRAY.

**Group** Bus

Syntax BUS:B<x>:FLEXray:BITRate <NR1>

BUS:B<x>:FLEXray:BITRate?

**Arguments** <NR1> specifies the FLEXRAY bit rate. You can enter any positive integer, and

the instrument will coerce the value to the closest supported bit rate.

**Examples** BUS:B1:FLEXRAY:BITRATE 9600 sets the FLEXRAY bit rate to 9600 bits per

second.

BUS:B1:FLEXRAY:BITRATE? might return BUS:B1:FLEXRAY:BITRATE 10000000 indicating the FLEXRAY bit rate is 10,000,000 bits per second.

## BUS:B<x>:FLEXray:CHannel

Sets or returns the FLEXRAY ID format.

**Group** Bus

**Syntax** BUS:B<x>:FLEXray:CHannel {A|B}

BUS:B<x>:FLEXray:CHannel?

**Arguments** A sets the FLEXRAY id format to channel A.

B sets the FLEXRAY id format to channel B.

**Examples** BUS:B1:FLEXRAY:CHANNEL B sets the FLEXRAY id format to channel B.

BUS:B1:FLEXRAY:CHANNEL? might return BUS:B1:FLEXRAY:CHANNEL A

indicating that FLEXRAY id format is channel A.

# BUS:B<x>:FLEXray:SIGnal

Sets or returns the FLEXRAY standard.

**Group** Bus

Syntax BUS:B<x>:FLEXray:SIGnal {BDIFFBP|BM|TXRX}

BUS:B<x>:FLEXray:SIGnal?

**Arguments** BDIFFBP sets the FLEXRAY standard to BDIFFBP.

BM sets the FLEXRAY standard to BM.

TXRX sets the FLEXRAY standard to TXRX.

**Examples** BUS:B1:FLEXRAY:SIGNAL BM sets the FLEXRAY standard is BM.

BUS:B1:FLEXRAY:SIGNAL? might return BUS:B1:FLEXRAY:SIGNAL

BDIFFBP indicating the FLEXRAY standard is BDIFFBP.

### BUS:B<x>:FLEXray:SOUrce

Sets or returns the FLEXRAY data source.

**Group** Bus

**Syntax** BUS:B<x>:FLEXray:SOUrce

{CH1|CH2|CH3|CH4|D0|D1|D2|D3|D4|D5|D6|D7|D8|D9|D10|D11|D12|D13|D14|D15]

BUS:B<x>:FLEXray:SOUrce?

**Arguments** CH<x> sets the FLEXRAY source to channel x, where x is 1 to 4.

D<x> sets the FLEXRAY source to digital channel x, where x is 1 to 16.

**Examples** BUS:B1:FLEXRAY:SOURCE CH4 sets the FLEXRAY source to channel 4.

BUS:B1:FLEXRAY:SOURCE? might return BUS:B1:FLEXRAY:SOURCE CH1

indicating the FLEXRAY source is channel 1.

#### BUS:B<x>:I2C:ADDRess:RWINClude

Sets and returns whether the read/write bit is included in the address.

**Group** Bus

Syntax BUS:B<x>:I2C:ADDRess:RWINClude {<NR1>|OFF|ON}

BUS:B<x>:I2C:ADDRess:RWINClude?

**Arguments**  $\langle NR1 \rangle = 0$  does not include the read/write bit in the addess; any other value

includes the read/write bit in the address..

OFF does not include the read/write bit in the address.

ON includes the read/write bit in the address.

**Examples** BUS:B1:I2C:ADDRESS:RWINCLUDE ON includes the read/write bit in the

address.

BUS:B1:I2C:ADDRESS:RWINCLUDE? might return

BUS:B1:I2C:ADDRESS:RWINCLUDE 0 indicating the read/write bit is not

included in the address.

## BUS:B<x>:I2C{:CLOCK|:SCLK}:SOUrce

Sets or returns the I2C SCLK source for bus <x>, where x is the bus number.

**Conditions** This command requires a DPO4EMBD or DPO4COMP application module.

**Group** Bus

Syntax BUS:B<x>:I2C{:CLOCK|:SCLK}:SOUrce {CH1|CH2|CH3|CH4|

D0|D1|D2|D3|D4|D5|D6|D7|D8|D9|D10|D11|D12|D13|D14|D15}

BUS:B<x>:I2C{:CLOCK|:SCLK}:SOUrce?

**Arguments** CH1-CH4 specifies the analog channel to use as the I2C SCLK source.

D0-D15 specifies the digital channel to use as the I2C SCLK source.

### BUS:B<x>:I2C{:DATA|:SDATA}:SOUrce

Sets or returns the I2C SDATA source for bus <x>, where x is the bus number.

**Conditions** This command requires a DPO4EMBD application module.

**Group** Bus

Syntax BUS:B<x>:I2C{:DATA|:SDATA}:SOUrce {CH1|CH2|CH3|CH4|

D0|D1|D2|D3|D4|D5|D6|D7|D8|D9|D10|D11|D12|D13|D14|D15}

BUS:B<x>:I2C{:DATA|:SDATA}:SOurce?

**Arguments** CH1-CH4 specifies the analog channel to use as the I2C SDATA source.

D0-D15 specifies the digital channel to use as the I2C SCLK source.

#### BUS:B<x>:LABel

Sets or returns the waveform label for bus < x>, where x is the bus number

1 through 4.

**Group** Bus

Syntax BUS:B<x>:LABel <Qstring>

BUS:B<x>:LABel?

**Arguments** <Qstring> is an alphanumeric string of text, enclosed in quotes, that contains the

text label information for bus <x>. The text string is limited to 30 characters.

#### BUS:B<x>:LIN:BITRate

Sets or returns the bit rate for LIN.

**Group** Bus

Syntax BUS:B<x>:LIN:BITRate <NR1>

BUS:B<x>:LIN:BITRate?

**Arguments** <NR1> is the LIN bit rate. You can enter any positive integer, and the instrument

will coerce the value to the closest supported bit rate.

**Examples** BUS:B1:LIN:BITRATE 9600 sets the bit rate 9600.

BUS:B1:LIN:BITRATE? might return BUS:B1:LIN:BITRATE 2400 indicating

the bit rate is set to 2400.

### BUS:B<x>:LIN:IDFORmat

Sets or returns the LIN ID format.

**Group** Bus

Syntax BUS:B<x>:LIN:IDFORmat {NOPARity|PARity}

BUS:B<x>:LIN:IDFORmat?

**Arguments** NOPARity sets the LIN id format to no parity.

PARity sets the LIN id format to parity.

**Examples** BUS:B1:LIN:IDFORMAT PARITY sets the LIN id format to parity.

BUS:B1:LIN:IDFORMAT? might return BUS:B1:LIN:IDFORMAT NOPARITY

indicating the LIN id format is no parity.

### BUS:B<x>:LIN:POLARity

Sets or returns the LIN polarity.

**Group** Bus

Syntax BUS:B<x>:LIN:POLARity {NORMal|INVerted}

BUS:B<x>:LIN:POLARity?

**Arguments** NORMal specifies normal LIN polarity.

INVerted specifies inverted LIN polarity.

**Examples** BUS:B1:LIN:POLARITY INVERTED sets the LIN polarity to INVERTED...

BUS:B1:LIN:POLARITY? might return BUS:B1:LIN:POLARITY NORMAL

indicating the LIN polarity is normal.

## BUS:B<x>:LIN:SAMPLEpoint

Sets or returns the sample point (in %) at which to sample during each bit period.

**Group** Bus

Syntax BUS:B<x>:LIN:SAMPLEpoint <NR1>

BUS:B<x>:LIN:SAMPLEpoint?

**Arguments** <NR1> is the sample point (in %) at which to sample during each bit period.

**Examples** BUS:B1:LIN:SAMPLEPOINT 10 sets the sample point is at 10% of the bit period

BUS:B1:LIN:SAMPLEPOINT? might return BUS:B1:LIN:SAMPLEPOINT 50

indicating that the sample point is at 50% of the bit period

### BUS:B<x>:LIN:SOUrce

Sets or returns the LIN data source.

**Group** Bus

Syntax BUS:B<x>:LIN:SOUrce

{CH1|CH2|CH3|CH4|D0|D1|D2|D3|D4|D5|D6|D7|D8|D9|D10|D11|D12|D13|D14|D15]

BUS:B<x>:LIN:SOUrce?

**Arguments** CH<x> specifies the LIN source channel where x is 1 to 4.

D<x> specifies the LIN source channel where x is 1 to 16.

**Examples** BUS:B1:LIN:SOURCE CH4 sets the LIN source to channel 4.

BUS:B1:LIN:SOURCE? might return BUS:B1:LIN:SOURCE CH1 indicating

the LIN source is channel 1.

### BUS:B<x>:LIN:STANDard

Sets or returns the LIN standard.

**Group** Bus

Syntax BUS:B<x>:LIN:STANDard {V1X|V2X|MIXed}

BUS:B<x>:LIN:STANDard?

**Arguments** V1X sets the LIN standard to V1X.

V2X sets the LIN standard to V2X

MIXed sets the LIN standard to MIXED.

**Examples** BUS:B1:LIN:STANDARD V1X sets the LIN standard is V1X.

BUS:B1:LIN:STANDARD? might return BUS:B1:LIN:STANDARD V2X

indicating the LIN standard is V2X.

### BUS:B<x>:PARallel:BIT<x>:SOUrce

Sets or returns the parallel bit source for  $B \le x >$ , where x is the bus number and  $Bit \le x >$  is the bit number.

**Group** Bus

Syntax BUS:B<x>:PARallel:BIT<x>:SOUrce {CH1|CH2|CH3|CH4|

D0|D1|D2|D3|D4|D5|D6|D7|D8|D9|D10|D11|D12|D13|D14|D15}

BUS:B<x>:PARallel:BIT<x>:SOurce?

**Arguments** CH1-CH4 or D0-D15 specifies the bit source B<x>. BIT<x> specifies the bit

number.

### BUS:B<x>:PARallel:CLOCK:EDGE

Sets or returns the parallel clock edge for bus  $\langle x \rangle$ , where x is the bus number.

**Group** Bus

Syntax BUS:B<x>:PARallel:CLOCK:EDGE {EITher|RISing|FALling}

BUS:B<x>:PARallel:CLOCK:EDGE?

**Arguments** EIther specifies either edge as the clock edge.

RISing specifies the rising edge as the clock edge.

FALling specifies the falling edge as the clock edge.

### BUS:B<x>:PARallel:CLOCK:ISCLOCKed

Sets or returns the parallel bus clock function for bus  $\langle x \rangle$ , where x is the bus number.

**Group** Bus

Syntax BUS:B<x>:PARallel:CLOCK:ISCLOCKed {YES|NO}

BUS:B<x>:PARallel:CLOCK:ISCLOCKed?

**Arguments** YES specifes that the Parallel bus is clocked.

NO specifes that the Parallel bus is not clocked.

#### BUS:B<x>:PARallel:CLOCK:SOUrce

Sets or returns the Parallel bus source  $\langle x \rangle$ , where x is the bus number.

**Group** Bus

Syntax BUS:B<x>:PARallel:CLOCK:SOUrce {CH1|CH2|CH3|CH4|

D0|D1|D2|D3|D4|D5|D6|D7|D8|D9|D10|D11|D12|D13|D14|D15}

BUS:B<x>:PARallel:CLOCK:SOurce?

**Arguments** CH1-CH4 or D0-D15 specifies the channel to use as the Parallel bit source.

#### BUS:B<x>:PARallel:WIDth

Sets or returns the number of bits used for the width of the Parallel bus  $\langle x \rangle$ , where x is the bus number.

**Group** Bus

Syntax BUS:B<x>:PARallel:WIDth <NR1>

BUS:B<x>:PARallel:WIDth?

**Arguments** <NR1> is the number of bits.

### BUS:B<x>:POSition

Sets or returns the position of the bus  $\leq x \geq$  waveform on the display, where x is

the bus number 1 through 4.

**Conditions** This command requires a serial bus analysis module.

**Group** Bus

Syntax BUS:B<x>:POSition <NR3>

BUS:B<x>:POSition?

**Arguments** <NR3> specifies the position.

#### BUS:B<x>:RS232C:BITRate

Sets or returns the RS-232 bit rate for bus <x>, where x is the bus number.

**Conditions** This command requires a DPO4COMP application module.

**Group** Bus

Syntax BUS:B<x>:RS232C:BITRate <NR1>

BUS:B<x>:RS232C:BITRate?

**Arguments** <NR1> is the bit rate in bits-per-second. You can enter any positive integer, and

the instrument will coerce the value to the closest supported bit rate.

#### BUS:B<x>:RS232C:DATABits

Sets or returns the number of RS-232 data bits for bus  $\langle x \rangle$ , where x is the bus

number.

**Conditions** This command requires a DPO4COMP application module.

**Group** Bus

Syntax BUS:B<x>:RS232C:DATABits {7|8}

BUS:B<x>:RS232C:DATABits?

**Arguments** 7 specifies seven bits in the RS-232 data frame.

8 specifies eight bits in the RS-232 data frame.

#### BUS:B<x>:RS232C:DELIMiter

Sets or returns the RS-232 delimiting value for a packet on bus  $\leq x >$ , where x

is the bus number.

**Conditions** This command requires a DPO4COMP application module.

Group Bus

Syntax BUS:B<x>:RS232C:DELIMiter {NULl|LF|CR|SPace|XFF}

BUS:B<x>:RS232C:DELIMiter?

**Arguments** NUL1 specifies 0x00.

LF specifies 0x0A.

CR specifies 0x0D.

XFF specifies 0xFF.

## BUS:B<x>:RS232C:DISplaymode

Sets or returns the display mode for the bus  $\leq x \geq$  display and event table, where x

is the bus number.

**Conditions** This command requires a DPO4COMP application module.

**Group** Bus

Syntax BUS:B<x>:RS232C:DISplaymode {FRAme|PACKET}

BUS:B<x>:RS232C:DISplaymode?

**Arguments** FRAme displays each frame as a single entity.

PACKET displays a group of frames terminated with a single frame defined by the

BUS:B<x>:RS232C:DELImiter command or the front panel.

## BUS:B<x>:RS232C:PARity

Sets or returns the RS-232C parity for bus <x>, where x is the bus number.

**Conditions** This command requires a DPO4COMP application module.

**Group** Bus

Syntax BUS:B<x>:RS232C:PARity {NONe|EVEN|ODD}

BUS:B<x>:RS232C:PARity?

**Arguments** NONe specifies no parity.

EVEN specifies even parity.

ODD specifies odd parity.

### BUS:B<x>:RS232C:POLarity

Sets or returns the RS-232C polarity for bus <x>, where x is the bus number.

**Conditions** This command requires a DPO4COMP application module.

**Group** Bus

Syntax BUS:B<x>:RS232C:POLarity {NORMal|INVERTed}

BUS:B<x>:RS232C:POLarity?

**Arguments** NORMal sets the RS-232C bus polarity to positive.

INVERTEd sets the RS-232C bus polarity to negative.

### BUS:B<x>:RS232C:RX:SOUrce

Sets or returns the RS-232 RX source for bus  $\langle x \rangle$ , where x is the bus number.

**Conditions** This command requires a DPO4COMP application module.

**Group** Bus

Syntax BUS:B<x>:RS232C:RX:SOUrce {CH1|CH2|CH3|CH4|

D0|D1|D2|D3|D4|D5|D6|D7|D8|D9|D10|D11|D12|D13|D14|D15|Off}

BUS:B<x>:RS232C:RX:SOUrce?

**Arguments** CH1-CH4 or D0-D15 specifies the channel to use for the RS-232 RX source.

Off sets the specified bus input to off.

### BUS:B<x>:RS232C:TX:SOUrce

Sets or returns the RS-232 TX Source for bus <x>, where x is the bus number.

**Conditions** This command requires a DPO4COMP application module.

**Group** Bus

Syntax BUS:B<x>:RS232C:TX:SOUrce {CH1|CH2|CH3|CH4|

D0|D1|D2|D3|D4|D5|D6|D7|D8|D9|D10|D11|D12|D13|D14|D15|Off}

BUS:B<x>:RS232C:TX:SOUrce?

**Arguments** CH1-CH4 or D0-D15 specifies the channel to use as the RS-232 TX source.

Off sets the specified bus input to off.

### BUS:B<x>:SPI:BITOrder

Sets or returns the bit order for the specified SPI bus. LSB is least significant bit

first; MSB is most significant bit first.

**Group** Bus

Syntax BUS:B<x>:SPI:BITOrder {LSB|MSB}

BUS:B<x>:SPI:BITOrder?

**Arguments** LSB sets the bit order to least significant bit first.

MSB sets the bit order to most significant bit first.

**Examples** BUS:B1:SPI:BITORDER LSB sets the bit order to least significant bit first.

BUS:B1:SPI:BITORDER? might return BUS:B1:SPI:BITORDER MSB

indicating the SPI bit order is set to most significant bit first.

## BUS:B<x>:SPI{:CLOCK|:SCLK}:POLARity

Sets or returns the SPI SCLK polarity for bus  $\langle x \rangle$ , where x is the bus number.

**Conditions** This command requires a DPO4EMBD application module.

**Group** Bus

Syntax BUS:B<x>:SPI{:CLOCK|:SCLK}:POLARity {FALL|RISe}

BUS:B<x>:SPI{:CLOCK|:SCLK}:POLARity?

**Arguments** FALL specifies the falling edge.

RISe specifies the rising edge.

## BUS:B<x>:SPI{:CLOCK|:SCLK}:SOUrce

Sets or returns the SPI SCLK source for bus <x>, where x is the bus number.

**Conditions** This command requires a DPO4EMBD application module.

Group Bus

Syntax BUS:B<x>:SPI{:CLOCK|:SCLK}:SOURCE {CH1|CH2|CH3|CH4|

D0|D1|D2|D3|D4|D5|D6|D7|D8|D9|D10|D11|D12|D13|D14|D15}

BUS:B<x>:SPI{:CLOCK|:SCLK}:SOUrce?

**Arguments** CH1-CH4 or D0-D15 is the channel to use as the SPI SCLK source.

## BUS:B<x>:SPI:DATA{:IN|:MISO}:POLARity

Sets or returns the SPI MISO polarity for bus  $\langle x \rangle$ , where x is the bus number.

**Conditions** This command requires a DPO4EMBD application module.

**Group** Bus

Syntax BUS:B<x>:SPI:DATA{:IN|:MISO}:POLARity {LOW|HIGH}

BUS:B<x>:SPI:DATA{:IN|:MISO}:POLARity?

**Arguments** LOW specifies an active low polarity.

HIGH specifies an active high polarity.

## BUS:B<x>:SPI:DATA{:IN|:MISO}:SOUrce

Sets or returns the SPI MISO source for bus <x, where x is the bus number.

**Conditions** This command requires a DPO4EMBD application module.

**Group** Bus

Syntax BUS:B<x>:SPI:DATA{:IN|:MISO}:SOUrce {CH1|CH2|CH3|CH4|

D0|D1|D2|D3|D4|D5|D6|D7|D8|D9|D10|D11|D12|D13|D14|D15}

BUS:B<x>:SPI:DATA{:IN|:MISO}:SOUrce?

**Arguments** CH1-CH4 or D0-D15 is the channel to use as the SPI MISO source.

# BUS:B<x>:SPI:DATA{:OUT|:MOSI}:POLARity

Sets or returns the SPI MOSI polarity for bus  $\langle x \rangle$ , where x is the bus number.

**Conditions** This command requires a DPO4EMBD application module.

**Group** Bus

Syntax BUS:B<x>:SPI:DATA{:OUT|:MOSI}:POLARity {LOW|HIGH}

BUS:B<x>:SPI:DATA{:OUT|:MOSI}:POLARity?

**Arguments** LOW specifies the active low polarity.

HIGH specifies the active high polarity.

# BUS:B<x>:SPI:DATA{:OUT|:MOSI}:SOUrce

Sets or returns the SPI MOSI source for bus <x, where x is the bus number>.

**Conditions** This command requires a DPO4EMBD application module.

**Group** Bus

Syntax BUS:B<x>:SPI:DATA{:OUT|:MOSI}:SOUrce {CH1|CH2|CH3|CH4|

D0|D1|D2|D3|D4|D5|D6|D7|D8|D9|D10|D11|D12|D13|D14|D15}

BUS:B<x>:SPI:DATA{:OUT|:MOSI}:SOUrce?

**Arguments** CH1-CH4 or D0-D15 is the channel to use as the SPI MISO source.

### BUS:B<x>:SPI:DATA:SIZe

Sets or returns the number of bits per word for the specified SPI bus.

**Group** Bus

Syntax BUS:B<x>:SPI:DATA:SIZe <NR1>

BUS:B<x>:SPI:DATA:SIZe?

**Arguments** NR1 is the data size of the specified bus.

**Examples** BUS:B1:SPI:DATA:SIZE 8 sets the data size for the specified bus to 8 bits

per word.

BUS:B1:SPI:DATA:SIZE? might return BUS:B1:SPI:DATA:SIZE 8

indicating the data size for the SPI B1 bus is 8 bits per word.

### BUS:B<x>:SPI:FRAMING

Sets or returns the type of SPI framing.

**Group** Bus

Syntax BUS:B<x>:SPI:FRAMING {SS|IDLEtime}

BUS:B<x>:SPI:FRAMING?

**Arguments** SS specifies framing by SS (non 2-wire).

IDLEtime specifies framing by Idle Time (2-wire).

**Examples** BUS:B1:SPI:FRAMING SS sets the SPI framing type to SS.

BUS:B1:SPI:FRAMING IDELTIME might return BUS:B1:SPI:FRAMING

IDELTIME indicating the SPI framing type is set to IDLETIME.

#### BUS:B<x>:SPI:IDLETime

Sets or returns the SPI bus idle time in seconds for the specified bus.

**Group** Bus

Syntax BUS:B<x>:SPI:IDLETime <NR3>

BUS:B<x>:SPI:IDLETime?

**Arguments** NR3 is the SPI bus idle time in seconds.

**Examples** BUS:B1:SPI:IDLETIME 100.0000E-9 sets the idle time to 100 ns.

BUS:B1:SPI:IDLETIME? might return BUS:B1:SPI:IDLETIME

100.0000E-9 indicating the idle time is set to 100 ns.

## BUS:B<x>:SPI{:SELect|:SS}:POLARity

Sets or returns the SPI SS polarity for bus  $\langle x \rangle$ , where x is the bus number.

**Conditions** This command requires a DPO4EMBD application module.

**Group** Bus

Syntax BUS:B<x>:SPI{:SELect|:SS}:POLARity {LOW|HIGH}

BUS:B<x>:SPI{:SELect|:SS}:POLARity?

**Arguments** LOW specifies an active low polarity.

HIGH specifies an active high polarity.

## BUS:B<x>:SPI{:SELect|:SS}:SOUrce

Sets or returns the SPI SS source for bus  $\langle x \rangle$ , where x is the bus number.

**Conditions** This command requires a DPO4EMBD application module.

**Group** Bus

Syntax BUS:B<x>:SPI{:SELect|:SS}:SOUrce {CH1|CH2|CH3|CH4|

D0|D1|D2|D3|D4|D5|D6|D7|D8|D9|D10|D11|D12|D13|D14|D15}

BUS:B<x>:SPI{:SELect|:SS}:SOUrce?

**Arguments** CH1-CH4 or D0-D15 is the channel to use as the SPI SS source.

### BUS:B<x>:STATE

Sets or returns the on/off state of bus  $\langle x \rangle$ , where x is the bus number.

**Group** Bus

Syntax BUS:B<x>:STATE {<NR1>|OFF|ON}

BUS:B<x>:STATE?

**Related Commands** SELect:BUS<x>

**Arguments** ON or  $\langle NR1 \rangle \neq 0$  turns on the bus.

OFF or  $\langle NR1 \rangle = 0$  turns off the bus.

#### BUS:B<x>:TYPE

Sets or returns the bus type for  $\langle x \rangle$ , where x is the bus number. The supported bus types are dependent on the oscilloscope model and the installed application keys.

**Group** Bus

Syntax BUS:B<x>:TYPE {I2C|SPI|CAN|RS232C|PARallel|USB}

BUS:B<x>:TYPE?

**Arguments** I2C specifies the Inter-IC bus.

SPI specifies the Serial Peripheral Interface bus (not available on two-channel

models).

CAN specifies the Controller Area Network bus.

RS232C specifies the RS-232C bus.

PARallel specifies the Parallel bus.

USB specifies the USB bus.

### BUS:B<x>:USB:BITRate

Sets or returns the bit rate for the USB signal.

**Group** Bus

Syntax BUS:B<x>:USB:BITRate {LOW|FULL|HIGH}

BUS:B<x>:USB:BITRate?

**Arguments** LOW indicates the bit rate is 1.5 Mbps.

FULL indicates the bit rate is 12 Mbps.

HIGH indicates the bit rate is 480 Mbps.

**Examples** BUS:B1:USB:BITRATE FULL sets the bit rate to 12 Mbps.

BUS:B1:USB:BITRATE? might return:BUS:B1:USB:BITRATE LOW, which

indicates that the bit rate is 1.5 Mbps.

### BUS:B<x>:USB:PRObe

Sets or returns the type of probe connected to the USB signal.

**Group** Bus

Syntax BUS:B<x>:USB:PRObe {DIFFerential|SINGleended}

BUS:B<x>:USB:PRObe?

**Arguments** DIFFerential indicates that the bus probe is a differential probe.

SINGleended indicates that the bus probe is not a differential probe.

**Examples** BUS:B1:USB:PROBE DIFFERENTIAL sets the bus probe to be a differential

probe.

BUS:B1:USB:PROBE? might return:BUS:B1:USB:PROBE SINGLEENDED, which indicates that the bus probe is not a differential probe.

#### BUS:B<x>:USB:SOUrce:DIFFerential

Sets or returns the USB Data Source when using a differential probe.

**Group** Bus

Syntax BUS:B<x>:USB:SOUrce:DIFFerential {CH1|CH2|CH3|CH4}

BUS:B<x>:USB:SOUrce:DIFFerential?

**Arguments** CH1-CH4 specifies the channel to use for data source for the USB bus. This

channel should have an attached differential probe.

**Examples** BUS:B1:USB:SOURCE:DIFFERENTIAL CH2 sets the source to channel 2. You

should have a differential probe attached to channel 2 and connect it to the USB

data signal.

BUS:B1:USB:SOURCE:DIFFERENTIAL? might return

:BUS:B1:USB:SOURCE:DIFFERENTIAL CH4 indicating that channel 4 is set to

be the differential input for USB data.

#### BUS:B<x>:USB:SOUrce:DMINus

Sets or returns the USB Data Source for D- input. If you are using single-ended probes, you need to set the sources for both the D+ and D- inputs.

**Group** Bus

Syntax BUS:B<x>:USB:SOUrce:DMINus

{CH1|CH2|CH3|CH4|D0|D1|D2|D3|D4|D5|D6|D7|D8

|D9|D10|D11|D12|D13|D14|D15} BUS:B<x>:USB:SOUrce:DMINus?

**Arguments** CH1-Ch4 or D0-D15 specifies the channel to use for D- data source for the

USB bus.

**Examples** BUS:B1:USB:SOURCE:DMINUS CH2 sets the D-source to channel 2.

BUS:B1:USB:SOURCE:DMINUS? might return:BUS:B1:USB:SOURCE:DMINUS

CH4 indicating that channel 4 is set to be the D- input for USB data.

#### BUS:B<x>:USB:SOUrce:DPLUs

Sets or returns the USB Data Source for D+ input. If you are using single-ended probes, you need to set the sources for both the D+ and D- inputs.

**Group** Bus

Syntax BUS:B<x>:USB:SOUrce:DPLUs

{CH1|CH2|CH3|CH4|D0|D1|D2|D3|D4|D5|D6|D7|D8

|D9|D10|D11|D12|D13|D14|D15} BUS:B<x>:USB:SOUrce:DPLUs?

Arguments CH1-Ch4 or D0-D15 specifies the channel to use for D+ data source for the

USB bus.

**Examples** BUS:B1:USB:SOURCE:DPLUS CH1 sets the D+ source to channel 1.

BUS:B1:USB:SOURCE:DPLUS? might return:BUS:B1:USB:SOURCE:DPLUS

CH3 indicating that channel 3 is set to be the D+ input for USB data.

### BUS:LOWerthreshold:CH<x>

Sets the lower threshold for each channel. This applies to all search and trigger types that use the channel. This command supersedes the :BUS:THReshold:CH<x> above.

Group Bus

Syntax BUS:LOWerthreshold:CH<x> {<NR3>|ECL|TTL}

BUS:LOWerthreshold:CH<x>?

**Arguments** <NR3> specifies the threshold in volts.

ECL specifies a preset ECL high level of -1.3V.

TTL specifies a preset TTL high level of 1.4V.

**Examples** BUS:LOWERTHRESHOLD:CH1 TTL sets the CH1 lower threshold to 800mV.

BUS:LOWERTHRESHOLD:CH1? might return:BUS:LOWERTHRESHOLD:CH1

-800.0000E-3 indicating the CH1 lower threshold is -800 mV.

#### BUS:THReshold:CH<x>

Sets or returns the threshold for analog channel <x>, where x is the channel number. This setting applies to all trigger types that use the channel.

**Conditions** This command requires a serial bus analysis module.

**Group** Bus

Syntax BUS:THReshold:CH<x> {ECL|TTL|<NR3>}

BUS:THReshold:CH<x>?

**Related Commands** TRIGger:A:LEVel:CH<x>

**Arguments** ECL specifies a preset ECL high level of -1.3V.

TTL specifies a TTL preset high level of 1.4V.

<NR3> specifies the threshold level in volts.

#### BUS:THReshold:D<x>

Sets or returns the threshold for digital channel  $\langle x \rangle$ , where x is the digital channel number. This will apply to all Search and Trigger Types that use the channel.

**Conditions** This command requires a DPO4COMP application module or RS-232C.

**Group** Bus

Syntax BUS:THReshold:D<x> {<NR3>|ECL|TTL}

BUS:THReshold:D<x>?

**Related Commands** TRIGger:A:LEVel:D<x>

**Arguments** ECL specifies a preset ECL high level of -1.3V.

TTL specifies a preset TTL high level of 1.4V.

<NR3> specifies the threshold level in volts.

### BUS:UPPerthreshold:CH<x>

Sets the upper threshold for each channel. This applies to all search and trigger types that use the channel.

**Group** Bus

Syntax BUS:UPPerthreshold:CH<x> {<NR3>|ECL|TTL}

BUS:UPPerthreshold:CH<x>?

**Arguments** <NR3> specifies the threshold in volts.

ECL specifies a preset ECL high level of -1.3V.

TTL specifies a preset TTL high level of 1.4V.

**Examples** BUS:UPPERTHRESHOLD:CH1 800.0000E-3 sets the CH1 upper threshold to

800 mV.

BUS: UPPERTHRESHOLD: CH1? might return: BUS: UPPERTHRESHOLD: CH1 -800.0000E-3 indicating that the CH1 upper threshold is set to -800 mV.

## **BUSY?** (Query Only)

Returns the status of the oscilloscope. This command allows you to synchronize the operation of the oscilloscope with your application program. (See page 3-7, *Synchronization Methods*.)

Certain oscilloscope operations can affect the BUSY? response. (See Table 3-3 on page 3-7.)

**Group** Status and Error

Syntax BUSY?

Related Commands \*OPC, \*WAI

Returns

<NR1> = 0 means the oscilloscope is not busy processing a command whose execution time is extensive.

<NR1> = 1 means the oscilloscope is busy processing a command whose execution time is extensive. (See Table 3-3 on page 3-7.)

**Examples** 

BUSY? might return: BUSY 1 indicating that the oscilloscope is currently busy.

## \*CAL? (Query Only)

Performs an internal self-calibration and returns the oscilloscope calibration status.

**NOTE**. Disconnect or otherwise remove all input signals prior to starting self-calibration. The self-calibration can take several minutes to complete.

No other commands are executed until calibration is complete.

Group

Calibration and Diagnostic

**Syntax** 

\*CAL?

Returns

<NR1> = 1 indicates the calibration did not complete successfully.

 $\langle NR1 \rangle = 0$  indicates the calibration completed without errors.

**Examples** 

\*CAL? starts the internal signal path calibration and might return 0 to indicate that

the calibration was successful.

## CALibrate:FACtory:STATus? (Query Only)

Returns the factory calibration status value saved in nonvolatile memory.

Group

Calibration and Diagnostic

**Syntax** 

CALibrate: FACtory: STATus?

**Examples** 

CALIBRATE: FACTORY: STATUS? might return CALIBRATE: FACTORY: STATUS

PASS indicating that factory calibration passed.

## **CALibrate:INTERNal (No Query Form)**

This command starts a signal path compensation.

**Group** Calibration and Diagnostic

Syntax CALibrate: INTERNal

**Arguments** None

**Examples** CALIBRATE: INTERNAL starts a serial path compensation cycle.

## CALibrate:INTERNal:STARt (No Query Form)

Starts the internal signal path calibration (SPC) of the oscilloscope. You can use the CALibrate:INTERNal:STATus? query to return the current status of the internal signal path calibration of the oscilloscope.

**Group** Calibration and Diagnostic

**Syntax** CALibrate:INTERNal:STARt

**Related Commands** CALibrate:RESults:SPC?

**Examples** CALIBRATE: INTERNAL: START initiates the internal signal path calibration of

the oscilloscope.

## CALibrate:INTERNal:STATus? (Query Only)

Returns the current status of the oscilloscope internal signal path calibration for the last SPC operation.

**Group** Calibration and Diagnostic

**Syntax** CALibrate:INTERNal:STATus?

Related Commands \*CAL?

#### Returns

This query will return one of the following:

- INIT indicates the oscilloscope has not had internal signal path calibration run.
- PASS indicates the signal path calibration completed successfully.
- FAIL indicates the signal path calibration did not complete successfully.
- RUNNING indicates the signal path calibration is currently running.

#### **Examples**

CALIBRATE: INTERNAL: STATUS? might return

:CALIBRATE:INTERNAL:STATUS INIT indicating that the current status of the internal signal path calibration is that it has not been run.

## **CALibrate:RESults? (Query Only)**

Returns the status of internal and factory calibrations, without performing any calibration operations. The results returned do not include the calibration status of attached probes. The CALibrate:RESults? query is intended to support GO/NoGO testing of the oscilloscope calibration readiness: all returned results should indicate PASS status if the oscilloscope is "fit for duty". It is quite common, however, to use uncalibrated probes (particularly when the oscilloscope inputs are connected into a test system with coaxial cables).

**Group** Calibration and Diagnostic

**Syntax** CALibrate:RESults?

Related Commands \*CAL?

# CALibrate:RESults:FACtory? (Query Only)

Returns the status of internal and factory calibration, without performing any calibration operations.

**Group** Calibration and Diagnostic

**Syntax** CALibrate:RESults:FACtory?

## **CALibrate:RESults:SPC? (Query Only)**

Returns the status of the SPC operation. This query does not initiate a SPC.

**Group** Calibration and Diagnostic

**Syntax** CALibrate:RESults:SPC?

Related Commands \*CAL?

**Returns** INIT indicates that SPC has never successfully completed.

PASS indicates that the last SPC operation passed.

FAIL indicates that the last SPC operation failed.

RUNNING indicates that the SPC operation is running.

**Examples** CALIBRATE: RESULTS: SPC? returns the results of the last SPC operation: either

PASS or FAIL.

## CH<x>? (Query Only)

Returns the vertical parameters for channel <x>, where x is the channel number.

**Group** Vertical

Syntax CH<x>?

### CH<x>:AMPSVIAVOLTs:ENAble

Sets or returns the state of the amps via volts feature for the specified channel. This feature supports measuring current via the voltage drop across a resistor.

**Group** Vertical

Syntax CH<x>:AMPSVIAVOLTs:ENAble {<NR1>|OFF|ON}

CH<x>:AMPSVIAVOLTs:ENAble?

**Arguments** OFF sets the amps via volts function for channel  $\langle x \rangle$  to off.

ON sets the amps via volts function for channel  $\langle x \rangle$  to on.

<NR1> = 0 sets the amps via volts function to off. Any other value sets the

function to on.

**Examples** CH1: AMSVIAVOLTS: ENABLE ON turns on the amps via volts feature for channel

1.

#### CH<x>:AMPSVIAVOLTs:FACtor

Sets or returns the amps via volts factor for the specified channel.

**Group** Vertical

Syntax CH<x>:AMPSVIAVOLTs:FACtor <NR3>

CH<x>:AMPSVIAVOLTs:FACtor?

**Arguments** <NR3> is a double-precision ASCII string that represents the amps via volts factor.

**Examples** CH1: AMPSVIAVOLTS: FACTOR 15.5 sets the amps via volts factor for channel 1

to 15.5.

#### CH<x>:BANdwidth

Sets or returns the selectable low-pass bandwidth limit filter for channel <x>,

where x is the channel number.

**Group** Vertical

Syntax CH<x>:BANdwidth {TWEnty|TWOfifty|FUL1|<NR3>}

CH<x>:BANdwidth?

**Arguments** Twenty sets the upper bandwidth limit of channel  $\leq x \geq to 20$  MHz.

Twofifty sets the upper bandwidth limit of channel <x> to 250 MHz.

FUL1 disables any optional bandwidth limiting. The specified channel operates

at its maximum attainable bandwidth.

<NR3> is a double-precision ASCII string. The oscilloscope rounds this value to an available bandwidth using geometric rounding, and then uses this value to set the upper bandwidth limit.

**NOTE.** Other values may be possible depending on the attached probes.

#### **Examples**

CH1: BANDWIDTH TWENTY sets the bandwidth of channel 1 to 20 MHz.

### CH<x>:COUPling

Sets or returns the input attenuator coupling setting for channel  $\langle x \rangle$ , where x is the channel number.

**Group** Vertical

**Syntax** CH<x>:COUPling {AC|DC|GND}

CH<x>:COUPling?

**Arguments** AC sets channel  $\langle x \rangle$  to AC coupling.

DC sets channel  $\langle x \rangle$  to DC coupling.

 $\mbox{GND}$  sets channel  $\mbox{<}x\mbox{>}$  to ground. Only a flat, ground-level waveform will be

displayed.

**Examples** CH2:COUPLING GND sets channel 2 to ground.

CH3:COUPling? might return :CH3:COUPling DC indicating that channel 3

is set to DC coupling.

### CH<x>:DESKew

Sets or returns the deskew time for channel <x>, where x is the channel number. You can adjust the deskew time to add an independent, channel-based delay time to the delay (set by the horizontal position control and common to all channels) from the common trigger point to first sample taken for each channel. This lets you compensate individual channels for different delays introduced by their individual input hook ups.

Syntax CH<x>:DESKew <NR3>

CH<x>:DESKew?

**Arguments** <NR3> is the deskew time for channel  $\langle x \rangle$ , ranging from -100 ns to +100 ns

with a resolution of 1 ps.

**Examples** CH4:DESKew 5.0E-9 sets the deskew time for channel 4 to 5 ns.

CH2:DESKew? might return: CH2:DESKEW 2.0000E-09 indicating that the

deskew time for channel 2 is set to 2 ns.

CH<x>:INVert

Sets or returns the invert function for channel <x>, where is the channel number. When on, the invert function inverts the waveform for the specified channel.

**NOTE**. This command inverts the waveform for display purposes only. The oscilloscope does not use an inverted waveform for triggers or trigger logic inputs.

**Group** Vertical

Syntax CH<x>:INVert {ON|OFF}

CH<x>:INVert?

**Arguments** OFF sets the invert function for channel  $\langle x \rangle$  to off.

ON sets the invert function for channel  $\langle x \rangle$  to on.

**Examples** CH4:INVert ON inverts the waveform on channel 4.

CH2:INVert? might return: CH2:INVERT 0 indicating that channel 2 is not

inverted.

CH<x>:LABel

Sets or returns the waveform label for channel  $\langle x \rangle$ , where x is the channel number.

Syntax CH<x>:LABel <Qstring>

CH<x>:LABel?

**Arguments** 

<Qstring> is an alphanumeric string of text, enclosed in quotes, that contains the text label information for the channel <x> waveform. The text string is limited to 30 characters.

#### CH<x>:OFFSet

Sets or returns the vertical offset for channel <x>, where x is the channel number.

This command offsets the vertical acquisition window (moves the level at the vertical center of the acquisition window) for the specified channel. Visualize offset as scrolling the acquisition window towards the top of a large signal for increased offset values, and scrolling towards the bottom for decreased offset values. The resolution of the vertical window sets the offset increment for this control.

Offset adjusts only the vertical center of the acquisition window for channel waveforms to help determine what data is acquired. The oscilloscope always displays the input signal minus the offset value.

The channel offset range depends on the vertical scale factor.

Table 2-38: Channel Offset Range

	Offset range	
V/Div Setting	1 MΩ Input	50 Ω Input
1 mV/div — 50 mV/div	±1 V	±1 V
50.5 mV/div — 99.5 mV/div	±0.5 V	±0.5 V
100 mV/div — 500 mV/div	±10 V	±5 V
505 mV/div — 995 mV/div	±5 V	±5 V
1 V/div — 5 V/div	±100 V	±5 V
5.05 V/div — 10 V/div 1	±50 V	N/A

For 50  $\Omega$  input, 1 V/div is the maximum setting.

**NOTE.** The above table describes oscilloscope behavior only when no probe is attached, and when the external attenuation factor is 1.0.

Syntax CH<x>:OFFSet <NR3>

CH<x>:OFFSet?

Related Commands CH<x>:POSition

**Arguments**  $\langle NR3 \rangle$  is the offset value for the specified channel  $\langle x \rangle$ .

**Examples** CH3:OFFSet 2.0E-3 sets the offset for channel 3 to 2 mV.

CH4:OFFSet? might return: CH4:OFFSET 1.0000E-03 indicating that the

offset for channel 4 is set to 1 mV.

#### CH<x>:POSition

Sets or returns the vertical position of channel <x>, where x is the channel number. The position value is applied to the signal before it is digitized.

Increasing the position value of a waveform causes the waveform to move up. Decreasing the position value causes the waveform to move down. The position value determines the vertical graticule coordinate at which input signal values, minus the present offset setting for that channel, are displayed. For example, if the position for Channel 3 is set to 2.0 and the offset is set to 3.0, then input signals equal to 3.0 units are displayed 2.0 divisions above the center of the screen

(at 1 V/div).

**Group** Vertical

Syntax CH<x>:POSition <NR3>

CH<x>:POSition?

**Related Commands** CH<x>:OFFSet, REF<x>:VERTical:POSition, MATH[1]:VERTical:POSition

**Arguments** <NR3> is the position value for channel <x>, in divisions, from the center

graticule. The range is 8 to -8 divisions.

**Examples** CH2: POSition 1.3 positions the Channel 2 input signal 1.3 divisions above the

center graticule.

CH1: POSition? might return: CH1: POSITION -1.3000 indicating that the

current position of Channel 1 is 1.3 divisions below the center graticule.

## CH<x>:PRObe? (Query Only)

Returns all information concerning the probe attached to channel  $\langle x \rangle$ , where x is the channel number.

**Group** Vertical

**Syntax** CH<x>: PRObe?

# CH<x>:PRObe:AUTOZero (No Query Form)

Sets the TekVPI probe attached to channel <x> to zero, where x is the channel number

**Group** Vertical

**Syntax** CH<x>:PRObe:AUTOZero EXECute

**Arguments** Execute auto zeros the probe.

### CH<x>:PRObe:COMMAND (No Query Form)

Sets the state of the probe control specified with the first argument to the state specified with the second argument. The commands and states are unique to the attached probe type. Only certain VPI probes support this command. See the probe documentation for how to set these string arguments.

**Group** Vertical

Syntax CH<x>:PRObe:COMMAND <QString>, <QString>

**Arguments** <QString> are quoted strings specifying the probe command and value to set in

the probe attached to the specified channel.

**Examples** CH1: PROBE: COMMAND "MODE", "4-4V1MHz" sets a Tektronix VPI-DPG probe

to the 4-4V1MHz mode.

CH1: PROBE: COMMAND "OUTPUT", "ON" turns the output of a Tektronix

VPI-DPG probe on.

CH1: PROBE: COMMAND? "MODE" might return CH1: PROBE: COMMAND "MODE", "4-4V1MHZ".

## CH<x>:PRObe:DEGAUss (No Query Form)

Starts a degauss auto-zero cycle on a TekVPI current probe attached to the input channel specified by  $\langle x \rangle$ , where x is the channel number.

Group Vertical

**Syntax** CH<x>:PRObe:DEGAUSS EXECute

**Arguments EXECute** initiates the degauss operation.

# CH<x>:PRObe:DEGAUss:STATE? (Query Only)

Returns the state of the probe degauss for the channel specified by  $\langle x \rangle$ , where is x is the channel number.

**NOTE.** This command will return PASSED for probes that do not support degauss operations.

Vertical Group

**Syntax** CH<x>:PRObe:DEGAUSS:STATE?

Returns NEEDED indicates the probe should be degaussed before taking measurements.

RECOMMENDED indicates the measurement accuracy might be improved by

degaussing the probe.

PASSED indicates the probe is degaussed.

FAILED indicates the degauss operation failed.

RUNNING indicates the probe degauss operation is currently in progress.

## CH<x>:PRObe:FORCEDRange

Sets or returns the range of a TekVPI probe attached to the channel specified by <x>, where x is the channel number.

**NOTE.** This command will return PASSED for probes that do not support degauss operations.

**Group** Vertical

**Syntax** CH<x>:PRObe:FORCEDRange <NR3>

CH<x>:PRObe:FORCEDRange?

**Arguments** <NR3> specifies the range, which is probe specific.

**Returns** This command returns 0.0 for probes that do no support forced range.

### CH<x>:PRObe:GAIN

Sets or returns the gain factor for the probe attached to the channel specified by  $\langle x \rangle$ , where x is the channel number. The "gain" of a probe is the output divided by the input transfer ratio. For example, a common 10x probe has a gain of 1V.

**Group** Vertical

Syntax CH<x>:PRObe:GAIN <NR3>

CH<x>:PRObe:GAIN?

Related Commands CH<x>:SCAle

**Arguments** <NR3> is the probe gain. Allowed values depend on the specific probe.

**Examples** CH2:PROBE:GAIN? might return :CH2:PROBE:GAIN 0.1000E+00 indicating

that the attached 10x probe delivers 1 V to the channel 2 BNC for every 10 V

applied to the probe input.

## CH<x>:PRObe:ID? (Query Only)

Returns the type and serial number of the probe attached to channel  $\langle x \rangle$ , where x is the channel number

**Syntax** CH<x>:PRObe:ID?

**Examples** CH

CH2:PROBE:ID? might return :CH2:PROBE:ID:TYPE "10X"; SERNUMBER "N/A" indicating that a passive 10x probe of unknown serial number is attached to channel 2.

### CH<x>:PRObe:ID:SERnumber? (Query Only)

Returns the serial number of the probe attached to channel  $\langle x \rangle$ , where x is the channel number.

**NOTE.** For Level 0 and 1 probes, the serial number will be "".

**Group** Vertical

**Syntax** CH<x>:PRObe:ID:SERnumber?

**Examples** 

CH1: PROBE: ID: SERNUMBER? might return: CH1: PROBE: ID: SERNUMBER "B010289" indicating that the serial number of the probe attached to channel 1 is B010289.

# CH<x>:PRObe:ID:TYPE? (Query Only)

Returns the type of probe attached to the channel specified by <x>, where x is the channel number. Level 2 (or higher) probes supply their exact product nomenclature; for Level 0 or 1 probes, a generic "No Probe Detected message is returned.

**Group** Vertical

**Syntax** CH<x>:PRObe:ID:TYPE?

**Examples** CH1:PROBE:ID:TYPE? might return :CH1:PROBE:ID:TYPE "P6203"

indicating that P6203-type probe is attached to channel 1.

#### CH<x>:PRObe:MODel

Sets or returns the probe model for the specified channel. If a coded probe is attached or the specified model is not recognized, an error event is set. The argument must be a supported probe.

To find the list of supported probes, push the front-panel channel 1, 2, 3, or 4 button, then push the lower-menu **More** item as many times as needed to select **Deskew**. Push **Probe Model** on the side menu and turn knob a to help you read from the resulting list. Alternatively, you can push **Test** > **Analysis** > **Deskew** > **Configure** > **Probe Model** and read from the resulting list.

**Group** Vertical

Syntax CH<x>:PRObe:MODel<String>

CH<x>:PRObe:MODel?

### CH<x>:PRObe:PROPDELay

Sets or returns the propagation delay for the probe connected to the specified channel.

**Group** Vertical

**Syntax** CH<x>:PRObe:PROPDELay<NR3>

CH<x>:PRObe:PROPDELay?

**Arguments** <NR3> specifies the propagation time delay for the connected probe.

**Examples** CH1: PROBE: PROPDELAY 100E-12 sets the CH1 propagation delay to 100 ps.

CH1:PROBE:PROPDELAY? might return :CH1:PROBE:PROPDELAY 1.1E-9

indicating that the CH1 propagation delay is set to 1.1 ns.

# CH<x>:PRObe:RECDESkew? (Query Only)

Returns the recommended deskew for the probe connected to the specified channel.

**Group** Vertical

**Syntax** CH<x>:PRObe:RECDESkew?

### CH<x>:PRObe:RESistance? (Query Only)

Returns the resistance factor of the probe attached to channel <x>, where x is the channel number.

**Group** Vertical

**Syntax** CH<x>:PRObe:RESistance?

**Examples** CH2:PRObe:RESistance? might return :CH2:PROBE:RESISTANCE

10.0000E+6 indicating that the input resistance of the probe attached to Channel

2 is 1 M $\Omega$ .

**NOTE**. This query will return 0.0 if no probe is attached or the attached probe does not report the input resistance.

#### CH<x>:PRObe:SIGnal

Sets or returns the input bypass setting of a TekVPI probe attached to channel <x>, where x is the channel number. The probe must support input bypass, for example TCP0001. This command is ignored if sent to an unsupported probe.

**Group** Vertical

Syntax CH<x>:PRObe:SIGnal {BYPass|PASS}

CH<x>:PRObe:SIGnal?

**Arguments** BYPass sets the probe to Bypass mode.

PASS sets the probe to Pass mode.

# CH<x>:PRObe:UNIts? (Query Only)

Returns a string describing the units of measure for the probe attached to channel  $\langle x \rangle$ , where x is the channel number.

**Group** Vertical

CH<x>:PRObe:UNIts? **Syntax** 

#### **Examples**

CH4: PROBE: UNITS? might return: CH4: PROBE: UNITS "V" indicating that the units of measure for the probe attached to channel 4 are volts.

#### CH<x>:SCAle

Sets or returns the vertical scale for the channel specified by  $\langle x \rangle$ , where x is the channel number.

Each waveform has a vertical scale parameter. For a signal with constant amplitude, increasing the Scale causes the waveform to be displayed smaller. Decreasing the scale causes the waveform to be displayed larger.

Scale affects all waveforms, but affects channel waveforms differently from other waveforms:

- For channel waveforms, this setting controls the vertical size of the acquisition window as well as the display scale. The range and resolution of scale values depends on the probe attached and any other external factors you have specified.
- For reference and math waveforms, this setting controls the display only, graphically scaling these waveforms and having no affect on the acquisition hardware.

Vertical Group

**Syntax** CH<x>:SCAle <NR3> CH<x>:SCAle?

**Related Commands** CH<x>:OFFSet, CH<x>:POSition, REF<x>:VERTical:SCAle,

MATH[1]:VERTical:SCAle

**Arguments** <NR3> is the vertical channel scale in units-per-division. The value entered here

is truncated to three significant digits.

CH4: SCALE 100E-03 sets the channel 4 scale to 100 mV per division. **Examples** 

CH2:SCALE? might return: CH2:SCALE 1.0000 indicating that the current scale

setting of channel 2 is 1 V per division.

#### CH<x>:TERmination

Sets the connected-disconnected status of a 50  $\Omega$  resistor, which may be connected between the specified channel's coupled input and oscilloscope ground. The channel is specified by <x>. There is also a corresponding query that requests the termination parameter and translates this enumeration into one of the two float values.

**Group** Vertical

Syntax CH<x>:TERmination {FIFty|MEG|<NR3>}

CH<x>:TERmination?

**Arguments** FIFty sets the channel  $\langle x \rangle$  input resistance to 50  $\Omega$ .

MEG sets the channel  $\langle x \rangle$  input resistance to 1 M $\Omega$ .

<NR3> specifies the channel <x> input resistance numerically.

**Examples** CH4:TERMINATION 50.0E+0 establishes 50  $\Omega$  impedance on channel 1.

CH2:TERMINATION? might return :CH2:TERMINATION 50.0E+0 indicating that channel 2 is set to  $50 \Omega$  impedance.

#### CH<x>:YUNits

Sets or returns the units for the channel specified by <x>, where x is the channel number. String arguments are case insensitive and any unsupported units will generate an error.

Supported units are:

%, /Hz, A, A/A, A/V, A/W, A/dB, A/s, AA, AW, AdB, As, B, Hz, IRE, S/s, V, V/A, V/V, V/W, V/dB, V/s, VV, VW, VdB, Volts, Vs, W, W/A, W/V, W/W, W/dB, W/s, WA, WV, WW, WdB, Ws, dB, dB/A, dB/V, dB/W, dB/dB, dBA, dBV, dBW, dBdB, day, degrees, div, hr, min, ohms, percent, s

**Group** Vertical

Syntax CH<x>:YUNits <QString>

CH<x>:YUNits?

**Arguments** QString is a string of text surrounded by quotes, specifying the supported units.

### **CLEARMenu (No Query Form)**

Clears the current menu from the display. This command is equivalent to pressing the front panel Menu off.

**Group** Miscellaneous

Syntax CLEARMenu

### \*CLS (No Query Form)

Clears the following:

- Event Queue
- Standard Event Status Register
- Status Byte Register (except the MAV bit)

If the \*CLS command immediately follows an <EOI>, the Output Queue and MAV bit (Status Byte Register bit 4) are also cleared. The MAV bit indicates that information is in the output queue. The device clear (DCL) GPIB control message will clear the output queue and thus MAV. \*CLS does not clear the output queue or MAV.

\*CLS can suppress a Service Request that is to be generated by an \*OPC. This will happen if a single sequence acquisition operation is still being processed when the \*CLS command is executed.

**Group** Status and Error

Syntax \*CLS

Related Commands DESE, \*ESE, \*ESR?, EVENT?, EVMsg?, \*SRE, \*STB?

**Examples** \*CLS clears the oscilloscope status data structures.

#### **CURSor?**

Returns all of the current cursor settings.

**Group** Cursor

Syntax CURSor?

**Examples** CURSOR? might return the following as the current cursor settings:

:CURSOR:FUNCTION SCREEN; HBARS:POSITION1 0.0000; POSITION2 0.0000; UNITS BASE; :CURSOR:MODE INDEPENDENT; VBARS:POSITION1

-19.0006E-6; POSITION2 -18.9994E-6; UNITS SECONDS

### CURSor:DDT? (Query Only)

Returns the cursor deltaY/deltaT (dY/dT) readout.

**Conditions** This command requires a DPO4PWR application module.

**Group** Cursor

Syntax CURSor: DDT?

**Examples** CURSOR:DDT? might return:CURSOR:DDT -166.6670 indicating that the

cursor dV/dt read out is -166.6670

**CURSor:FUNCtion** 

Sets or returns the cursor type. Cursors are attached to the selected waveform in

Waveform mode and are attached to the display area in Screen mode.

**Group** Cursor

Syntax CURSor:FUNCtion {OFF|SCREEN|WAVEform}

CURSor: FUNCtion?

**Arguments** OFF removes the cursors from the display but does not change the cursor type.

SCREEN specifies both horizontal and vertical bar cursors, which measure the selected waveform in horizontal and vertical units. Use these cursors to measure

anywhere in the waveform display area.

WAVEform specifies paired cursors in YT display format for measuring waveform amplitude and time. In XY and XYZ format, these cursors indicate the amplitude positions of an XY pair (Ch1 vs Ch2 voltage, where Ch1 is the X axis and Ch2 is

the Y axis) relative to the trigger.

**Examples** CURSOR: FUNCTION WAVEFORM selects the paired cursors for measuring waveform

amplitude and time.

CURSOR: FUNCTION? might return: CURSOr: FUNCtion SCREEN indicating that

the screen cursors are currently selected.

### **CURSor:HBArs? (Query Only)**

Returns the current settings for the horizontal bar cursors.

**Group** Cursor

**Syntax** CURSor: HBArs?

**Examples** CURSOR: HBARS? might return the horizontal

bar setting as :CURSOR:HBARS:POSITION1

320.0000E-03;POSITION2-320.0000E-03;UNITS BASE

# CURSor:HBArs:DELTa? (Query Only)

Returns the vertical difference between the two horizontal bar cursors.

**Group** Cursor

**Syntax** CURSor: HBArs: DELTa?

Related Commands CURSor:HBArs:UNIts

**Returns** A floating point value with an exponent.

**Examples** CURSOR:HBARS:DELTA? might return:CURSOR:HBARS:DELTA 5.0800E+00

indicating that the difference between the two cursors is 5.08.

#### CURSor:HBArs:POSITION<x>

Sets or returns the horizontal bar cursor position relative to ground, which is expressed in vertical units (usually volts). The cursor is specified by x, which can be 1 or 2.

**Group** Cursor

Syntax CURSor:HBArs:POSITION<x> <NR3>

CURSor: HBArs: POSITION<x>?

**Related Commands** CURSor:FUNCtion

**Arguments** <NR3> specifies the cursor position relative to ground.

**Examples** CURSOR: HBARS: POSITION1 25.0E-3 positions Cursor 1 of the horizontal

cursors at 25 mV.

CURSOR: HBARS: POSITION2? might return: CURSOR: HBARS: POSITION2 -64.0000E-03 indicating that Cursor 2 of the horizontal bar cursors is at -64 mV.

**CURSor:HBArs:UNIts** 

Sets or returns the units for the horizontal bar cursors.

**Group** Cursor

Syntax CURSor:HBArs:UNIts {BASE|PERcent}

CURSor: HBArs: UNIts?

**Arguments** BASE selects the vertical units for the selected waveform.

PERcent selects ratio cursors.

**Examples** CURSOR: HBARS: UNITS might return: CURSOR: HBARS: UNITS BASE indicating

that the units for the horizontal bar cursors are base.

CURSor:HBArs:USE (No Query Form)

Sets the horizontal bar cursor measurement scale. This command is only

applicable when ratio cursors are on.

**Group** Cursor

Syntax CURSor:HBArs:USE {CURrent|HALFgrat}

#### Related Commands CURSor:HBArs:UNIts

#### **Arguments**

CURrent sets the H Bar measurement scale so that 0% is the current position of the lowest H Bar cursor and 100% is the current position of the highest H Bar cursor.

HALFgrat sets H Bar measurement scale so that half the screen major divisions (five on the MSO/DPO4000) is 100%, where 0% is -2.5 divisions and 100% is +2.5 divisions from the center horizontal graticule.

#### **Examples**

CURSOR: HBARS: USE HALFGRAT sets the H Bar measurement scale so that five screen major divisions equals 100%.

#### **CURSor:MODe**

Sets or returns whether the two cursors move linked together in unison or separately. This command is equivalent to setting Linked to On or Off in the Cursor menu.

#### **Group** Cursor

Syntax CURSor:MODe {TRACk|INDependent}

CURSor:MODe?

#### **Arguments**

TRACk ties the navigational functionality of the two cursors together. For cursor 1 adjustments, this ties the movement of the two cursors together; however, cursor 2 continues to move independently of cursor 1. This mode only applies when the DISplay:FORMat is set to YT.

INDependent allows independent adjustment of the two cursors.

#### **Examples** CURSOR: MODE TRACK specifies that the cursor positions move in unison.

CURSOR: MODE? might return: CURSOR: MODE TRACK indicating that the two cursors move in unison.

# CURSor: VBArs? (Query Only)

Returns the current settings for the vertical bar cursors.

#### **Group** Cursor

Syntax CURSor: VBArs?

**Examples** CURSOR: VBARS? might return the following vertical bar settings

:CURSOR:VBARS:UNITS SECONDS; POSITION1 1.0000E-06; POSITION2

9.0000E-06

# CURSor:VBArs:ALTERNATE<x>? (Query Only)

Returns the alternate readout for the waveform (Vbar) cursors specified by <x>. This alternate readout is in effect when the selected waveform is a bus or digital channel.

**Group** Cursor

**Syntax** CURSor: VBArs: ALTERNATE < x>?

**Arguments** X = 1 specifies vertical bar cursor1.

X = 2 specifies vertical bar cursor2.

### CURSor: VBArs: DELTa? (Query Only)

Returns the horizontal difference between the two vertical bar cursors. The units are specified by the CURSor:VBArs:UNIts command.

This is equivalent to watching the cursor readout in the display while using the appropriate cursor mode.

**Group** Cursor

Syntax CURSor: VBArs: DELTa?

Related Commands CURSor: VBArs: UNIts

Returns <NR3>

**Examples** CURSOR: VBARS: DELTA? might return: CURSOR: VBARS: DELTa 1.0640E+00

indicating that the time between the vertical bar cursors is 1.064 s.

# CURSor:VBArs:HPOS<x>? (Query Only)

Returns the vertical value of the specified vertical bar ticks for cursor <x>.

**Group** Cursor

**Syntax** CURSor:VBArs:HPOS<x>?

Related Commands CURSor: VBArs: UNIts

**Arguments** <x> specifies the cursor. Valid values are 1 and 2.

**Returns** <NR3> indicates the value of one of the ticks. The units are the same as the

selected waveform.

**Examples** CURSOr: VBArs: HPOS2? might return CURSOR: VBARS: HPOS2 100E-3,

indicating the waveform value where the cursor intersects it is 0.100.

### CURSor: VBArs: POSITION < x >

Sets or returns the horizontal position for the specified vertical bar cursor. The cursor is specified by <x>, which can be 1 or 2. Values are with respect to trigger position or the zero reference point for the designated waveform (if horizontal units are not set to time). Use the CURSor:VBArs:UNIts command to specify units.

**Group** Cursor

Syntax CURSor:VBArs:POSITION<x> <NR3>

CURSor:VBArs:POSITION<x>?

**Related Commands** CURSor: VBArs: UNIts

**Arguments** <NR3> specifies the cursor position.

**Returns** A floating point value with an exponent.

**Examples** CURSor: VBArs: POSITION2 9.00E-6 positions the cursor2 vertical bar cursor

at 9 ms.

CURSOR: VBARS: POSITION1? this command might return :CURSOR: VBARS: POSITION1 1.0000E-06 indicating that the

cursor1 vertical bar is positioned at 1 µs.

CURSor: VBArs: UNIts

Sets or returns the units for the vertical bar cursors.

**Group** Cursor

Syntax CURSor:VBArs:UNIts {SEConds|HERtz|DEGrees|PERcent}

CURSor: VBArs: UNIts?

**Arguments** SEConds sets the units of the vertical bar cursors for the time domain (seconds).

HERtz sets the units of the vertical bar cursors for the frequency domain (Hertz).

**DEGrees** sets the units to degrees for measuring phase.

PERcent sets the units to percent for use with ratio cursors.

**Returns** SECONDS, HERTZ, DEGREES, or PERCENT, depending on the current vertical bar

cursor units.

**Examples** CURSOR: VBARS: UNITS HERtz sets the units of the VBArs cursors to 1/seconds.

CURSOR: VBARS: UNITS? might return: CURSOR: VBARS: UNITS SECONDS indicating that the units for the vertical bar cursor are currently set to seconds.

**CURSor:VBArs:USE (No Query Form)** 

Sets the vertical bar cursor measurement scale.

**Conditions** This command is only applicable when ratio cursors are on.

**Group** Cursor

Syntax CURSor:VBArs:USE {CURrent|HALFgrat|FIVEdivs}

Related Commands CURSor: VBArs: UNIts

**Arguments** CURrent sets the V Bar measurement scale so that 0% is the current position of

the left-most V Bar cursor and 100% is the current position of the right-most

V Bar cursor.

HALFgrat resets the ratio range to the default positions on the screen, half of the number of horizontal divisions (five on the MSO/DPO4000), from 25% to 75%

of the screen.

FIVEdivs sets V Bar measurement scale so that 5 screen major divisions is 100%, where 0% is -2.5 divisions and 100% is +2.5 divisions from the center

vertical graticule.

**Examples** CURSOR: VBARS: USE CURRENT sets the V Bar measurement scale to use the

current cursor positions as 0% and 100% of scale if units are set to %.

# CURSor: VBArs: VDELTa? (Query Only)

Returns the vertical difference between the two vertical bar cursor ticks.

**Group** Cursor

**Syntax** CURSor: VBArs: VDELTa?

**Related Commands** CURSor:HBArs:UNIts

**Returns** <NR3> indicates the vertical difference between the two vertical bar cursors' ticks.

**Examples** CURSOR: VBARS: VDELTA? might return CURSOR: VBARS: VDELTA 1.064E+0,

indicating that the vertical difference between the vertical bar cursors ticks is

1.064 units.

# CURSor:XY:POLar:RADIUS:DELta? (Query Only)

Returns the difference between the cursors X radius and the cursor Y radius ( $\Delta Y$ ,  $\Delta X$ ). The ratio is calculated as (cursor 2 Y - cursor 1 Y)  $\div$  (cursor 2 X - cursor 1 X).

**Group** Cursor

**Syntax** CURSor:XY:POLar:RADIUS:DELta?

# CURSor:XY:POLar:RADIUS:POSITION<x>? (Query Only)

Returns the polar radius for the specified cursor, where x can be either 1 or 2.

**Group** Cursor

Syntax CURSor:XY:POLar:RADIUS:POSITION<x>?

## CURSor:XY:POLar:RADIUS:UNIts? (Query Only)

Returns the polar radius units.

**Group** Cursor

Syntax CURSor:XY:POLar:RADIUS:UNIts?

# CURSor:XY:POLar:THETA:DELta? (Query Only)

Returns the XY cursor polar angle delta.

**Group** Cursor

**Syntax** CURSor:XY:POLar:THETA:DELta?

# CURSor:XY:POLar:THETA:POSITION<x>? (Query Only)

Returns the cursor X or cursor Y polar coordinate, where x is either 1 or 2.

**Group** Cursor

Syntax CURSor:XY:POLar:THETA:POSITION<x>?

# CURSor:XY:POLar:THETA:UNIts? (Query Only)

Returns the cursor coordinate units.

**Group** Cursor

**Syntax** CURSor:XY:POLar:THETA:UNIts?

### CURSor:XY:PRODUCT:DELta? (Query Only)

Returns the difference between the cursors X position and cursor Y position. The  $\Delta X \times \Delta Y$  value is calculated as  $(X2 - X1) \times (Y2 - Y1)$ .

**Group** Cursor

Syntax CURSor:XY:PRODUCT:DELta?

### CURSor:XY:PRODUCT:POSITION<x>? (Query Only)

Returns the position of the X or Y cursor used to calculate the  $X \times Y$  cursor measurement, Position  $1 = (X1 \times Y1)$ ; Position  $2 = (X2 \times Y2)$ . The cursor is specified by x, which can be 1 or 2.

**Group** Cursor

Syntax CURSor:XY:PRODUCT:POSITION<x>?

# CURSor:XY:PRODUCT:UNIts? (Query Only)

Returns the XY cursor product units.

**Group** Cursor

Syntax CURSor:XY:PRODUCT:UNIts?

### CURSor:XY:RATIO:DELta? (Query Only)

Returns the ratio of the difference between the cursors X position and cursor Y position ( $\Delta Y$ ,  $\Delta X$ ). The ratio is calculated as (Y2 - Y1) / (X2 - X1).

**Group** Cursor

**Syntax** CURSor:XY:RATIO:DELta?

### CURSor:XY:RATIO:POSITION<x>? (Query Only)

Returns the X (horizontal) or Y (vertical) position for the specified cursor, which can be 1 (X) or 2 (Y). The ratio is calculated as Position 1 = (Y1/X1); Position 2 = (Y2/X2).

**Group** Cursor

Syntax CURSor:XY:RATIO:POSITION<x>?

## CURSor:XY:RATIO:UNIts? (Query Only)

Returns the cursor X and cursor Y units for the ratio measurement.

**Group** Cursor

Syntax CURSor:XY:RATIO:UNIts?

#### **CURSor:XY:READOUT**

Sets or returns the XY cursor readout selection. This command is useful for oscilloscope models with limited display room. Oscilloscopes with sufficient display, such as the MSO4000 and DPO4000 series, show all the readouts simultaneously.

**Group** Cursor

**Syntax** CURSor:XY:READOUT {RECTangular|POLARCord|PRODuct|RATio}

CURSor: XY: READOUT?

**Arguments** RECTangular specifies the XY readout as rectangular coordinates.

POLARCORD specifies the XY readout as polar coordinates.

**PRODuct** specifies the XY readout in X\*Y format.

RATio specifies the XY readout in X:Y format.

### CURSor:XY:RECTangular:X:DELta? (Query Only)

Returns the cursor X delta value in rectangular coordinates.

**Group** Cursor

**Syntax** CURSor:XY:RECTangular:X:DELta?

### CURSor:XY:RECTangular:X:POSITION<x>

Sets or returns the X rectangular coordinate for cursor 1 or cursor 2. The cursor is specified by x and can be either 1 or 2.

**Group** Cursor

Syntax CURSor:XY:RECTangular:X:POSITION<x> <NR3>

CURSor:XY:RECTangular:X:POSITION<x>?

**Arguments** <NR3> is the coordinate in volts.

# CURSor:XY:RECTangular:X:UNIts? (Query Only)

Returns the cursor X rectangular units.

**Group** Cursor

**Syntax** CURSor:XY:RECTangular:X:UNIts?

# CURSor:XY:RECTangular:Y:DELta? (Query Only)

Returns The cursor Y delta value in rectangular coordinates.

**Group** Cursor

**Syntax** CURSor:XY:RECTangular:Y:DELta?

### CURSor:XY:RECTangular:Y:POSITION<x>

Sets or returns the Y rectangular coordinate for cursor 1 or cursor 2. The cursor is specified by x and can be either 1 or 2.

**Group** Cursor

Syntax CURSor:XY:RECTangular:Y:POSITION<x> <NR3>

CURSor:XY:RECTangular:Y:POSITION<x>?

**Arguments** <NR3> is the coordinate in volts.

### CURSor:XY:RECTangular:Y:UNIts? (Query Only)

Returns the cursor Y rectangular units.

**Group** Cursor

**Syntax** CURSor:XY:RECTangular:Y:UNIts?

#### **CURVe**

Transfers waveform data to and from the oscilloscope in binary or ASCII format. Each waveform transferred includes a waveform preamble which contains the data format, scale, and associated information.

For analog waveforms, the CURVe? query transfers data from the oscilloscope. The data source is specified by the DATa:SOUrce command. The first and last data points are specified by the DATa:STARt and DATa:STOP commands.

The oscilloscope returns data from the last acquisition if the source is a channel waveform that is being previewed. The data does not reflect the acquisition preview parameters. The user should always follow acquisition parameter changes with a single sequence OPC command prior to CURVe? to ensure the return data reflects the new acquisition parameters.

The CURVe command transfers waveform data to the oscilloscope. The data is stored in the reference memory location specified by DATa:DESTination, starting with the data point specified by DATa:STARt. Only one waveform can be transferred at a time. The waveform will only be displayed if the reference is displayed.

**NOTE.** Transferring large volumes of data to or from the oscilloscope takes time. ASCII waveform transfer is very inefficient.

Waveform Transfer Group

CURVe {<Block>|<asc curve>|DIGtal} **Syntax** CURVe?

**Related Commands** DATa: DESTination, DATa: SOUrce, DATa: STARt, DATa: STOP, WFMInpre?, WFMInpre:BYT Nr, WFMOutpre?, HEADer

<Block> is the waveform data in binary format. The waveform is formatted as: **Arguments** #<x><yyy><data><newline>, where:

<x> is the number of y bytes. For example, if <yyy>=500, then <x>=3)

<yyy> is the number of bytes to transfer. If width is 1, then all bytes on the bus are single data points. If width is 2, then all bytes on the bus are 2-bytes wide. Use the WFMInpre:BYT Nr command to set the width for waveforms transferred into the oscilloscope. Use WFMOutpre:BYT Nr to set the width for waveforms transferred out from the oscilloscope.

<data> is the curve data.

<newline> is a single byte new line character at the end of the data.

<asc curve> is the waveform data in ASCII format. The format for ASCII data is <NR1>[,<NR1>...], where each <NR1> represents a data point.

DIGital Sends the data to the specified reference waveform slot, as specified by the DATA: DESTINATION command. If the data encoding is a binary format, then depending upon the setting of HEADER, the binary block header is prepended to the output data. (MSO models only)

CURVE? with ASCII encoding, start and stop of 1 and 10 respectively, and a width **Examples** set to 1 might return: CURVE 61,62,61,60,60,-59,-59,-58,-59

**NOTE.** Curve data is transferred from the oscilloscope asynchronously, depending on the length of the curve record. Such transfers may require several seconds to complete. During this period, the oscilloscope will not respond to the user controls. You can interrupt these asynchronous data transfers by sending a device clear message to the oscilloscope or by interrupting the query with another command or query. In order to verify that curve data has been completely transferred, it is recommended that you follow such queries with an \*ESR? query to verify there are no error bits set. You can also check the event queue to determine the cause of the error. If the error was caused by an interrupted query, then the asynchronous data transfer was not complete when the \*ESR? query was sent. In such cases, it may be necessary to increase the program's time-out value to ensure that all data is transferred and read.

#### **DATa**

Sets or returns the format and location of waveform data transferred with the CURVe? query or CURVe command.

**Group** Waveform Transfer

Syntax DATa {INIT|SNAp}
DATa?

**Related Commands** CURVe, DATa:STARt, DATa:STOP, DATa:ENCdg, WFMInpre:NR\_Pt, WFMOutpre:NR\_Pt?

**Arguments** INIT initializes the waveform data parameters to their factory defaults except for DATa:STOP, which is set to the current acquisition record length.

SNAp sets DATa:STARt and DATa:STOP to match the current waveform cursor positions.

**Examples** DATA? might return : DATA: DESTINATION REF1: ENCDG RIBINARY; SOURCE CH1; START 1; STOP 500; WIDTH 1

DATA INIT initializes the waveform data parameters to their factory defaults.

#### **DATa: DESTination**

Sets or returns the reference memory location for storing waveform data transferred into the oscilloscope by the CURVe command.

**Group** Waveform Transfer

Syntax DATa: DESTination REF<x>

DATa: DESTination?

Related Commands CURVe

**Arguments** REF<x> is the reference location where the waveform will be stored.

**Examples** DATA: DESTINATION? might return: DATA: DESTINATION REF3 indicating that

reference 3 is the currently selected reference memory location for incoming waveform data. DATA: DESTINATION REF1 indicates that incoming waveform

data be stored in reference 1.

**DATa:ENCdg** 

Sets or returns the format of outgoing waveform data. This command is equivalent to setting WFMOutpre:ENCdg, WFMOutpre:BN\_Fmt, andWFMOutpre:BYT\_Or. Setting the DATa:ENGdg value causes the corresponding WFMOutpre values to be updated and conversley.

**NOTE.** This command and query does not apply to incoming waveform data.

**Group** Waveform Transfer

Syntax DATa: ENCdg

{ASCIi|FAStest|RIBinary|RPBinary|SRIbinary|SRPbinary}

DATa: ENCdg?

Related Commands WFMOutpre:ENCdg, WFMOutpre:BN Fmt, WFMOutpre:BYT Or

**Arguments** ASCIi specifies the ASCII representation for waveform data points. If ASCII is

the value, then :BN\_Fmt and :BYT\_Or are ignored.

FAStest specifies that the data be sent in the fastest possible manner consistent with maintaining accuracy and is interpreted with respect to the waveform

specified by DATa:SOUrce.

RIBINARY specifies signed integer data point representation with the most

significant byte transferred first.

When :BYT\_Nr is 1, the range is from -128 through 127. When :BYT\_Nr is 2, the range is from -32,768 through 32,767. Center screen is 0 (zero). The upper limit is the top of the screen and the lower limit is the bottom of the screen. This is the default argument.

RPBinary specifies the positive integer data-point representation, with the most significant byte transferred first.

When :BYT\_Nr is 1, the range from 0 through 255. When :BYT\_Nr is 2, the range is from 0 to 65,535. The center of the screen is 127. The upper limit is the top of the screen and the lower limit is the bottom of the screen.

SRIbinary is the same as RIBinary except that the byte order is swapped, meaning that the least significant byte is transferred first. This format is useful when transferring data to IBM compatible PCs.

SRPbinary is the same as RPBinary except that the byte order is swapped, meaning that the least significant byte is transferred first. This format is useful when transferring data to PCs.

Table 2-39: DATa and WFMOutpre Parameter Settings

DATa:ENCdg Setting	WFMOutpre Settings			
	:ENCdg	:BN_Fmt	:BYT_Or	:BYT_NR
ASCii	ASC	N/A	N/A	1,2
FAStest	BIN	RI	MSB	1,2
RIBinary	BIN	RI	MSB	1,2
RPBinary	BIN	RP	MSB	1,2
SRIbinary	BIN	RI	LSB	1,2
SRPbinary	BIN	RP	LSB	1,2

#### **Examples**

DATA: ENCDG? might return: DATa: ENCDG SRPBINARY for the format of the outgoing waveform data.

DATA: ENCDG RPBinary sets the data encoding format to be a positive integer where the most significant byte is transferred first.

#### **DATa:SOUrce**

Sets or returns the location of the waveform data transferred from the oscilloscope by the CURVe? query.

#### **Group** Waveform Transfer

Syntax DATa:SOUrce

{CH1|CH2|CH3|CH4|MATH|REF1|REF2|REF3|REF4|D0|D1|D2|D3|D4|D5|D6|D7|D8|D9

DATa:SOUrce?

Related Commands CURVe

**Arguments** CH1-CH4 specifies which analog channel data will be transferred from the

oscilloscope to the controller, channels 1 through 4.

MATH specifies that the Math waveform data will be transferred from the

oscilloscope to the controller.

REF1-REF4 specifies which Reference waveform data will be transferred from

the oscilloscope to the controller, waveforms, 1 through 4.

D0-D15 specifies which digital channel data will be transferred from the oscilloscope to the controller, channels 0 through 15. (MSO models only)

DIGital specifies that the Digital waveform data will be transferred from the

oscilloscope to the controller. (MSO models only)

**Examples** DATA: SOURCE? might return: DATA: SOURCE REF3 indicating that the source for

the waveform data which is transferred using a CURVe? query is reference 3.

DATA: SOURCE CH1 specifies that the CH1 waveform will be transferred in the

next CURVe? query.

**DATa:STARt** 

Sets or returns the starting data point for incoming or outgoing waveform transfer.

This command allows for the transfer of partial waveforms to and from the

oscilloscope.

**Group** Waveform Transfer

Syntax DATa:STARt <NR1>

DATa:STARt?

Related Commands CURVe, DATa, DATa:STOP, WFMInpre:NR\_Pt, WFMOutpre:NR\_Pt?

**Arguments** <NR1> is the first data point that will be transferred, which ranges from 1 to the

record length. Data will be transferred from <NR1> to DATa:STOP or the record length, whichever is less. If <NR1> is greater than the record length, the last

data point in the record is transferred.

DATa:STARt and DATa:STOP are order independent. When DATa:STOP is greater than DATa:STARt, the values will be swapped internally for the CURVE? query.

#### **Examples**

DATA: START? might return: DATA: START 214 indicating that data point 214 is the first waveform data point that will be transferred.

DATA: START 10 specifies that the waveform transfer will begin with data point 10.

#### DATa:STOP

Sets or returns the last data point that will be transferred when using the CURVe? query. This command allows for the transfer of partial waveforms from the oscilloscope.

Changes to the record length value are not automatically reflected in the DATa:STOP value. As record length is varied, the DATa:STOP value must be explicitly changed to ensure the entire record is transmitted. In other words, curve results will not automatically and correctly reflect increases in record length if the distance from DATa:STARt to DATa:STOP stays smaller than the increased record length.

**Group** Waveform Transfer

Syntax DATa:STOP <NR1>

DATa:STOP?

**Related Commands** 

CURVe, DATa, DATa:STARt, WFMInpre:NR Pt, WFMOutpre:NR Pt?

#### **Arguments**

<NR1> is the last data point that will be transferred, which ranges from 1 to the record length. If <NR1> is greater than the record length, then data will be transferred up to the record length. If both DATa:STARt and DATa:STOP are greater than the record length, the last data point in the record is returned.

DATa:STARt and DATa:STOP are order independent. When DATa:STOP is less than DATa:STARt, the values will be swapped internally for the CURVE? query.

If you always want to transfer complete waveforms, set DATa:STARt to 1 and DATa:STOP to the maximum record length, or larger.

**Examples** 

DATA: STOP? might return: DATA: STOP 14900 indicating that 14900 is the last waveform data point that will be transferred.

DATA: STOP 15000 specifies that the waveform transfer will stop at data point 15000

#### DATE

Sets or returns the date the oscilloscope displays.

**Group** Miscellaneous

Syntax DATE <QString>

DATE?

Related Commands TIME

**Arguments** <QString> is a date in the form "yyyy-mm-dd" where yyyy refers to a four-digit

year number, mm refers to a two-digit month number from 01 to 12, and dd refers

to a two-digit day number in the month.

**Examples** DATE "2006-01-24" specifies that the date is set to January 24, 2006.

DATE? might return: DATE 2006-01-24 indicating the current date is set to

January 24, 2006.

\*DDT

Allows you to specify a command or a list of commands that execute when the oscilloscope receives a \*TRG command or the GET IEEE488.2 interface message. Define Device Trigger (\*DDT) is a special alias that the \*TRG command uses.

**Group** Miscellaneous

Syntax \*DDT {<Block>|<QString>}

\*DDT?

Related Commands ALIas, \*TRG

**Arguments** <Block> is a complete sequence of program messages. The messages can contain

only valid commands that must be separated by semicolons and must follow all

rules for concatenating commands. The sequence must be less than or equal to 80 characters. The format of this argument is always returned as a query.

<QString> is a complete sequence of program messages. The messages can contain only valid commands that must be separated by semicolons and must follow all rules for concatenating commands. The sequence must be less than or equal to 80 characters.

#### **Examples**

\*DDT #OACQUIRE: STATE RUN specifies that the acquisition system will be started each time a \*TRG command is sent.

#### DESE

Sets or returns the bits in the Device Event Status Enable Register (DESER). The DESER is the mask that determines whether events are reported to the Standard Event Status Register (SESR), and entered into the Event Queue. For a detailed discussion of the use of these registers, see Registers.

**Group** Status and Error

Syntax DESE <NR1>
DESE?

**Related Commands** 

\*CLS, \*ESE, \*ESR?, EVENT?, EVMsg?, \*SRE, \*STB?

#### **Arguments**

<NR1> sets the binary bits of the DESER according to this value, which ranges from 1 through 255. For example, DESE 209 sets the DESER to the binary value 11010001 (that is, the most significant bit in the register is set to 1, the next most significant bit to 1, the next bit to 0, etc.).

The power-on default for DESER is all bits set if \*PSC is 1. If \*PSC is 0, the DESER maintains the previous power cycle value through the current power cycle.

**NOTE.** Setting the DESER and ESER to the same value allows only those codes to be entered into the Event Queue and summarized on the ESB bit (bit 5) of the Status Byte Register. Use the \*ESE command to set the ESER.

#### **Examples**

DESE 209 sets the DESER to binary 11010001, which enables the PON, URQ, EXE and OPC bits.

DESE? might return : DESE 186, showing that the DESER contains the binary value 10111010.

### **DESkew (No Query Form)**

Causes the deskew values for all channels to be set to the recommended values. Equivalent to pressing the "Set all deskews to recommended values" button in the application UI.

**NOTE.** The actual deskew values for each channel can be set or queried using the *CH*<*x*>:*DESKew* command.

**Group** Vertical

Syntax DESkew {SETALLtorec}

**Arguments** <SETALLtorec> sets the deskew for all channels to the recommended values.

### **DESkew:DISPlay**

Sets or returns the state of the deskew table display.

**Group** Vertical

**Syntax** DESkew:DISPlay {OFF|ON|0|1}

DESkew:DISPlay?

**Arguments** OFF or 0 turns off the deskew table display.

ON or 1 turns on the deskew table display.

# **DIAg:LOOP:OPTion**

Sets the self-test loop option.

**Group** Calibration and Diagnostic

Syntax DIAg:LOOP:OPTion {ALWAYS|FAIL|ONFAIL|ONCE|NTIMES}

**Arguments** ALWAYS continues looping until the self tests (diagnostics) are stopped via the

front panel or by an oscilloscope command.

FAIL causes looping until the first self test (diagnostic) failure or until self tests (diagnostics) are stopped.

ONFAIL causes looping on a specific test group as long as a FAIL status is returned from the test.

ONCE executes self test (diagnostics test) sequence once.

NTIMES runs "n" number of loops.

**Examples** DIAG: LOOP: OPTION ONCE runs one loop of self tests.

### DIAg:LOOP:OPTion:NTIMes

Sets the self-test loop option to run N times.

**Group** Calibration and Diagnostic

Syntax DIAg:LOOP:OPTion:NTIMes <NR1>

DIAg:LOOP:OPTion:NTIMes?

**Arguments** <NR1> is the number of self-test loops.

**Examples** DIAG:LOOP:OPTION:NTIMES 3 sets the self-test loop to run three times.

DIAG:LOOP:OPTION:NTIMES? might return:DIAG:LOOP:OPTION:NTIMES 5,

indicating the self-test loop is set to run five times.

# **DIAg:LOOP:STOP (No Query Form)**

Stops the self-test at the end of the current loop.

**Group** Calibration and Diagnostic

Syntax DIAg:LOOP:STOP

**Examples** DIAG: LOOP: STOP stops the self test at the end of the current loop.

# DIAg:RESUlt:FLAg? (Query Only)

Returns the pass/fail status from the last self-test sequence execution. Use this query to determine which test(s) has failed.

**Group** Calibration and Diagnostic

Syntax DIAg: RESUlt: FLAg?

**Related Commands** DIAg:RESUlt:LOG?

**Returns** PASS indicates that all of the selected self (diagnostic) tests have passed.

FAIL indicates that at least one of the selected self (diagnostic) tests has failed.

IN PROGRESS indicates that at least one of the selected self (diagnostic) tests is

ongoing.

NOT RUN indicates that the selected diagnostic test suite has not been run since

the instrument was powered on.

**Examples** DIAG: RESULT: FLAG? might return DIAG: RESULT: FLAG PASS.

### DIAg:RESUIt:LOG? (Query Only)

Returns the internal results log from the last self-test sequence execution. The list contains all modules and module interfaces that were tested along with the pass/fail status of each.

**Group** Calibration and Diagnostic

**Syntax** DIAg:RESUlt:LOG?

**Related Commands** DIAg:RESUlt:FLAg?

**Returns** <QString> in the following format:

<Status>--<Module name>[,<Status>--<Module name>...]

**Examples** DIAG:RESULT:LOG? might return :DIAG:RESULT:LOG "NOT RUN--CPU, NOT

RUN--DISPLAY, NOT RUN--FPANEL, NOT RUN--IO, NOT RUN--ACQ, NOT

RUN--RO M, NOT RUN--APPKEY"

### **DIAg:SELect (No Query Form)**

Sets the type of diagnostics grouping.

**Group** Calibration and Diagnostic

Syntax DIAg:SELect {ALL|APPKey|CPU|DISplay|FPAnel|IO|ROM|ACQ}

**Arguments** ALL runs all diagnostic groups.

APPKey runs just the application key diagnostic group.

CPU runs just the CPU diagnostic group.

DISplay runs just the display circuit diagnostic group.

FFPAnel runs just the front panel diagnostic group.

IO runs just the IO board diagnostic group.

ROM runs just the IO board diagnostic group.

ACQ runs just the acquisition system diagnostic group.

# **DIAg:SELect:<function> (No Query Form)**

Runs self-tests on the specified system subsystem.

**Group** Calibration and Diagnostic

Syntax DIAg:SELect:<function>

**Arguments** <function> specifies a single oscilloscope subsystem on which to run self tests

(diagnostics). Valid values are:

ACQ tests the acquisition system.

APPKey tests the application keys.

CPU tests the CPU.

DISplay tests the display.

FPAnel tests the front panel controls.

IO tests the IO ports.

ROM tests the system read only memory.

**Examples** DIAG: SELECT: CPU sets the oscilloscope to run just CPU tests.

### **DIAg:STATE (No Query Form)**

This command starts or stops the oscilloscope self-test. Depending on the

argument, self-test capabilities are either turned on or off.

**Group** Calibration and Diagnostic

Syntax DIAg:STATE {EXECute|ABORt}

**Arguments** EXECute starts diagnostics.

ABORt stops diagnostics at the end of the current loop.

**Examples** DIAG: STATE EXECute starts diagnostics.

# DISplay? (Query Only)

Returns the current display settings.

**Group** Display

Syntax DISplay?

### DISplay:CLOCk

Sets or returns whether the oscilloscope displays the date and time. The query form of this command returns an ON (1) or an OFF (0).

Syntax DISplay:CLOCk {ON|OFF|<NR1>}

DISplay:CLOCk?

Related Commands DATE, TIME

**Arguments** ON enables the display of date and time.

OFF disables the display of date and time.

<NR1> = 0 disables the display of date and time; any other value enables the

display of date and time.

**Examples** DISPLAY: CLOCK ON enables display of date and time.

DISPLAY: CLOCK? might return: DISPLAY: CLOCK 1 indicating that the display

of date and time is currently enabled.

### DISplay:DIGital:HElght

Sets or returns the number of available digital waveform position slots.

**NOTE.** If the number of live digital channels exceeds the number of slots, their height is reduced to a smaller size, allowing all digital channels to be displayed.

**Group** Display

**Syntax** DISplay:DIGital:HEIght {SMAll|MEDium|LARge}

DISplay:DIGital:HEIght?

**Arguments** SMA11 sets the height to 40.

MEDium sets the height to 20.

LARge sets the height to 10.

# DISplay:FORMat

Sets or returns the display format.

**Syntax** DISplay:FORMat {YT|XY}

DISplay: FORMat?

**Arguments** YT sets the display to a voltage versus time format and is the default mode.

XY argument displays one waveform against another. Selecting one source causes its corresponding source to be implicitly selected, producing a single trace from

the two input waveforms.

**Examples** DISPLAY: FORMAT XY sets the display format to XY.

DISPLAY: FORMAT? might return DISPLAY: FORMAT YT indicating the display

format is YT.

### **DISplay:GRAticule**

Selects or queries the type of graticule the oscilloscope displays.

**Group** Display

**Syntax** DISplay:GRAticule {CROSSHair|FRAme|FULl|GRId}

DISplay: GRAticule?

**Arguments** CROSSHair specifies a frame and cross hairs.

FRAme specifies a frame only.

FUL1 specifies a frame, a grid and cross hairs.

GRId specifies a frame and grid only.

**Examples** DISPLAY: GRATICULE FRAme sets the graticule type to display the frame only.

DISPLAY: GRATICULE? might return: DISPLAY: GRATICULE FULL indicating

that all graticule elements are selected.

### **DISplay:INTENSITy?** (Query Only)

Returns the display intensity settings.

**Syntax** DISplay:INTENSITY?

**Examples** DISPLAY:INTENSITY? might return: :DISPLAY:INTENSITY:WAVEFORM

30; GRATICULE 75; BACKLIGHT HIGH

### DISplay:INTENSITy:BACKLight

Sets and returns the waveform backlight intensity settings.

**Group** Display

**Syntax** DISplay:INTENSITy:BACKLight {LOW|MEDium|HIGH}

DISplay:INTENSITy:BACKLight?

**Examples** DISPLAY:INTENSITY:BACKLIGHT? might return

DISPLAY: INTENSITY: BACKLIGHT HIGH

### DISplay:INTENSITy:GRAticule

Sets and returns the display graticule intensity settings.

**Group** Display

Syntax DISplay:INTENSITy:GRAticule <NR1>

DISplay: INTENSITy: GRAticule?

**Arguments** <NR1> is the graticule intensity and ranges from 0 to 100 percent.

**Examples** DISPLAY: INTENSITY: GRATICULE? might return

DISPLAY: INTENSITY: GRATICULE 30

# DISplay:INTENSITy:WAVEform

Sets and returns the display waveform intensity settings.

Syntax DISplay:INTENSITy:WAVEform <NR1>

DISplay:INTENSITy:WAVEform?

**Arguments** <NR1> is the waveform intensity and ranges from 1 to 100 percent.

**Examples** DISPLAY:INTENSITY:WAVEFORM? might return

DISPLAY: INTENSITY: WAVEFORM 60

as the intensity of the waveforms.

### **DISplay:PERSistence**

Sets or returns the display persistence. This affects the display only.

**NOTE.** When Persistence is set to Infinite, it does not mean that the brightness of any pixel should never decrease. The brightness of a pixel is proportionally dependent on the ratio between its intensity (which does NOT decrease at Infinite Persistence) and the maximum value of intensity of any pixel on the screen. If a particular pixel get hit less often than others, its brightness will decrease over time. It will become less bright relative to the pixels that get hit often.

**Group** Display

Syntax DISplay:PERSistence {<NR3>|CLEAR|AUTO|MINImum|INFInite}

DISplay: PERSistence?

**Arguments** <NR3> specifies the time of the persistence.

CLEAR resets the persist time count down and clears the display of acquired points.

INFInite displays waveform points until a control change resets the acquisition system. When persistence is set to infinite, it does not mean that the brightness of any pixel should never decrease. The brightness of a pixel is proportionally dependent on the ratio between its intensity, which does NOT decrease at infinite persistence, and the maximum value of intensity of any pixel on the screen. Thus, if a particular pixel gets hit less often than others, its brightness will decrease over time. It will become less bright relative to the pixels that get hit often.

AUTO specifies that the oscilloscope automatically determines the best waveform persistence based on the value of waveform intensity (DISPLAY:INTEnsITY:WAVEFORM)

MINImum specifies that the waveform persistence is set to the minimum value of 0.0E0.

**Examples** DISPLAY: PERSISTENCE 3 specifies that the waveform points are displayed

fading for 3 seconds before they completely disappear.

## DISplay:STYle:DOTsonly

Turns on or off the dots-only mode for the waveform display.

**Group** Display

Syntax DISplay:STYle:DOTsonly {ON|OFF|<NR1>}

DISplay:STYle:DOTsonly?

**Arguments** ON or  $\langle NR1 \rangle \neq 0$  turns on the dots-only display.

OFF or  $\langle NR1 \rangle = 0$  turns off the dots-only display.

**D**<x>

Sets or returns parameters for digital channel  $\leq x >$ , where x is the channel number.

**Group** Vertical

Syntax D<X>

D<x>:LABel

Sets or returns the waveform label for digital channel <x>, where x is the channel number.

**Group** Vertical

Syntax D<x>:LABel <Qstring>

D<x>:LABel?

**Arguments** <Qstring> is an alphanumeric string of text, enclosed in quotes, that contains the

text label information for the digital channel <x> waveform. The text string is

limited to 30 characters.

**Examples** 

D4:LABEL? might return:D4:LABEL "Clk Wfm 4".

#### D<x>:POSition

Sets or returns the vertical position for digital channel  $\langle x \rangle$ , where x is the channel number.

**NOTE.** Unlike analog channels, which use the center baseline as the zero point, digital channels use the bottom logic level as the zero point. Because of the slot model used to describe digital channel position, the oscilloscope rounds off divisions to the nearest slot.

Group

Vertical

**Syntax** 

D<x>:POSition <NR3>
D<x>:POSition?

**Arguments** 

<NR3> is the position of the digital channel in slot units. Use the oscilloscope front-panel controls to place the channel; then query the channel to obtain an exact value for the position.

#### D<x>:THREshold

Sets or returns the logical threshold for digital channel <x>, where x is the channel number.

Group

Vertical

**Syntax** 

D<x>:THREshold {ECL|TTL|<NR3>}

D<x>:THREshold?

**Arguments** 

ECL sets the digital threshold for channel <x> to a preset ECL high level of -1.3V.

TTL sets the digital threshold for channel <x> to a preset TTL high level of 1.4V.

<NR3> specifies the digital threshold for channel  $\leq$ x> in volts.

**Examples** 

D5:THRESHOLD ECL sets the threshold for D5 digital channel to ECL levels.

D14: threshold? might return: D14: THRESHOLD 1.2500 indicating that the

threshold level for the D14 digital channel is 1.25 volts.

#### \*ESE

Sets and queries the bits in the Event Status Enable Register (ESER). The ESER prevents events from being reported to the Status Byte Register (STB). For a detailed discussion on how to use registers, see Registers.

Group Status and Error

\*ESE <NR1> **Syntax** \*ESE?

**Related Commands** 

\*CLS, DESE, \*ESR?, EVENT?, EVMsg?, \*SRE, \*STB?

**Arguments** <NR1> specifies the binary bits of the ESER according to this value, which ranges from 0 through 255.

> The power-on default for the ESER is 0 if \*PSC is 1. If \*PSC is 0, the ESER maintains the previous power cycle value through the current power cycle.

**NOTE.** Setting the DESER and the ESER to the same values allows only those codes to be entered into the Event Queue and summarized on the ESB bit (bit 5) of the Status Byte Register. Use the DESE command to set the DESER.

**Examples** 

\*ESE 209 sets the ESER to binary 11010001, which enables the PON, URQ, EXE, and OPC bits.

\*ESE? might return 186, showing that the ESER contains the binary value 10111010.

## \*ESR? (Query Only)

Returns the contents of the Standard Event Status Register (SESR). \*ESR? also clears the SESR (reading the SESR clears it). For a detailed discussion on how to use registers, see Registers.

Group Status and Error

**Syntax** \*ESR?

**Related Commands** ALLEV?, \*CLS, DESE, \*ESE, EVENT?, EVMsg?, \*SRE, \*STB? **Examples** \*ESR? might return 213, showing that the SESR contains the binary value

11010101.

#### ETHERnet:DHCPbootp

Sets or returns the network initialization search for a DHCP/BOOTP server.

**Group** Ethernet

**Syntax** ETHERnet:DHCPbootp {ON|OFF}

ETHERnet: DHCPbootp?

**Arguments** ON enables the oscilloscope to search the network for a DHCP or BOOTP server

in order to automatically assign a dynamic IP address to the oscilloscope.

**NOTE.** Do not use DHCP/BOOTP searching if your oscilloscope has been assigned a static address on a network. If you set this command to ON, the DHCP/BOOTP search will delete or change your static IP address information.

OFF disables the oscilloscope to search the network for a DHCP or BOOTP server.

**Examples** ETHERNET: DHCPBOOTP ON sets the oscilloscope to search for a DHCP or BOOTP

server and assign a dynamic IP address to the oscilloscope.

#### ETHERnet: DNS: IPADDress

Sets or returns the network Domain Name Server (Dns) IP address.

**Group** Ethernet

Syntax ETHERnet:DNS:IPADDress <QString>

ETHERnet: DNS: IPADDress?

**Arguments** <QString> is a standard IP address value, enclosed in quotes.

**Examples** ETHERNET: DNS: IPADDRESS "128.196.13.352" sets the Dns IP address that

the oscilloscope uses to communicate with the network.

#### **ETHERnet:DOMAINname**

Sets or returns the network domain name.

**Group** Ethernet

Syntax ETHERnet:DOMAINname <Qstring>

ETHERnet: DOMAINname?

**Arguments** <QString> is the network domain name, enclosed in quotes.

**Examples** ETHERNET: DOMAINNAME "Alpha1. Mycorp.com" sets the domain name that

the oscilloscope uses to communicate with the network.

# ETHERnet:ENET:ADDress? (Query Only)

Returns the Ethernet address value assigned to the oscilloscope. This is assigned at the factory and can not be changed.

**Group** Ethernet

Syntax ETHERnet:ENET:ADDress?

**Examples** ETHERNET: ENET: ADDRESS? returns an Ethernet address such as

08:00:11:01:02:03

#### ETHERnet:GATEWay:IPADDress

Sets or returns the remote interface gateway IP address.

**Group** Ethernet

Syntax ETHERnet:GATEWay:IPADDress <QString>

ETHERnet:GATEWay:IPADDress?

**Arguments** <QString> is a standard IP address value, enclosed in quotes.

**Examples** ETHERNET: GATEWAY: IPADDRESS "128.143.16.1" sets the gateway IP

address

#### ETHERnet:HTTPPort

Sets or returns the remote interface HTTP port value.

**Group** Ethernet

Syntax ETHERnet:HTTPPort <QString>

ETHERnet: HTTPPort?

**Arguments** <QString> is an integer port number, enclosed in quotes.

**NOTE.** Consider the following if you are using the  $e*Scope^{TM}$  control software. If you don't enter a port address in the URL, then the ETHERnet:HTTPPort value must be set to "80", which is the default port for HTTP protocol. If you use a URL with a port address (for example: http://DPO4104-04WKL4:1234), the port number is specified by the number after the colon. Set the ETHERnet:HTTPPort value to this same number.

**Examples** ETHERNET: HTTPPORT "80" sets the HTTP port value to 80.

#### ETHERnet: IPADDress

Sets or returns the IP address assigned to the oscilloscope.

**Group** Ethernet

Syntax ETHERnet:IPADDress <QString>

ETHERnet: IPADDress?

**Arguments** <QString> is a standard IP address value, enclosed in quotes.

**EXAMPLES** ETHERNET: IPADDRESS "123.121.13.214" sets the oscilloscope's IP address.

#### **ETHERnet:NAME**

Sets or returns the network name assigned to the oscilloscope.

**Group** Ethernet

Syntax ETHERnet:NAME <QString>

ETHERnet: NAME?

**Arguments** <QString> is the network name assigned to the oscilloscope, enclosed in quotes.

**Examples** ETHERNET: NAME "labscope1" sets the oscilloscope's network name.

#### ETHERnet:PASSWord

Sets or returns the HTTP Ethernet access password. If a password is set, the user must enter the password before the user's Web browser can access the

oscilloscope.

**Group** Ethernet

Syntax ETHERnet:PASSWord <new>

ETHERnet:PASSWord?

**Arguments** <new> is a new password, enclosed in quotes.

**Examples** ETHERNET: PASSWORD "ZEN53" replaces the current Ethernet password with the

new password ZEN53.

ETHERNET: PASSWORD? might return: ETHERNET: PASSWORD "ZEN53".

# ETHERnet:PING (No Query Form)

Causes the oscilloscope to ping the gateway IP address.

**Group** Ethernet

Syntax ETHERnet:PING EXECute

**Examples** ETHERNET: PING EXECUTE causes the oscilloscope to ping the gateway IP

address

# ETHERnet:PING:STATUS? (Query Only)

Returns the results from sending the ETHERnet:PING command to ping the gateway IP address.

**Group** Ethernet

Syntax ETHERnet:PING:STATUS?

**Returns** OK is returned if the computer at the gateway IP address answers.

NORESPONSE is returned if the computer at the gateway IP address does not

answer.

INPROGRESS is returned if the ping operation is still executing.

#### ETHERnet:SUBNETMask

Sets or returns the remote interface subnet mask value.

**Group** Ethernet

Syntax ETHERnet:SUBNETMask <QString>

ETHERnet:SUBNETMask?

**Arguments** <QString> is the subnet mask value, enclosed in quotes.

**Examples** ETHERNET: SUBNETMASK "255.255.0" sets the subnet mask value using

standard IP address notation format.

# **EVENT?** (Query Only)

Returns an event code from the Event Queue that provides information about the results of the last \*ESR? read. EVENT? also removes the returned value from the Event Queue.

**Group** Status and Error

Syntax EVENT?

Related Commands ALLEv?, \*CLS, DESE, \*ESE, \*ESR?, EVMsg?, \*SRE, \*STB?

**Examples** EVENT? might return: EVENT 110, showing that there was an error in a

command header. (See page 3-12, Messages.)

## **EVMsg?** (Query Only)

Removes a single event code from the Event Queue that is associated with the results of the last \*ESR? read and returns the event code along with an explanatory message. For information, see Event Handling.

**Group** Status and Error

Syntax EVMsg?

Related Commands ALLEv?

\*CLS, DESE, \*ESE, \*ESR?, EVENT?, \*SRE, \*STB?

**Returns** The event code and message in the following format:

<Event Code><Comma><QString>[<Event

Code><Comma><QString>...]<QString>::= <Message>;[<Command>] where <Command> is the command that caused the error and may be returned when a command error is detected by the oscilloscope. As much of the command will be returned as possible without exceeding the 60 character limit of the <Message> and <Command> string combined. The command string is right-justified.

**Examples** EVMSG? might return : EVMSG 110, "Command header error".

# **EVQty?** (Query Only)

Returns the number of event codes in the Event Queue. This is useful when using the ALLEV? query, which returns the exact number of events.

**Group** Status and Error

**Syntax** EVQty?

**Related Commands** ALLEv?, EVENT?, EVMsg?

**Examples** EVQTY? might return: EVQTY 3, indicating the number of event codes in the

Event Queue.

## **FACtory (No Query Form)**

Resets the oscilloscope to its factory default settings.

This command does the following:

- Clears the Event Status Enable Register
- Clears the Service Request Enable Register
- Sets the Device Event Status Enable Register to 255
- Purges all defined aliases
- Enables all Command Headers
- Sets the macro defined by \*DDT to a "zero-length field"
- Clears the pending operation flag and associated operations

This command does not reset the following:

- Communication settings
- Selected GPIB address.
- Sate of the VXI-11 (Ethernet IEEE Std 488.2) interface.
- Calibration data that affects device specifications
- Protected user data
- Stored settings
- Power On Status Clear Flag
- Oscilloscope password

**Group** Save and Recall

**Syntax** FACtory

Related Commands \*PSC, \*RCL, RECAll:SETUp, \*RST, \*SAV, SAVe:SETUp

**Arguments** None

**Examples** FACTORY resets the oscilloscope to its factory default settings.

#### FILESystem? (Query Only)

Returns the directory listing of the current working directory and the number of bytes of free space available. This query is the same as the FILESystem:DIR? query and the FILESystem:FREESpace? query.

**Group** File System

**Syntax** FILESystem?

Related Commands FILESystem: CWD, FILESystem: DELEte, FILESystem: DIR?,

FILESystem:REName

**Arguments** None.

**Examples** FILESYSTEM? might return

:FILESYSTEM:DIR

"tek00000.bmp", "elusiveGlitch1.png", "TEMP.TMP",

"file1.wfm","file2.wfm", "MATH1.wfm"," REF1.wfm","REF2.wfm";FREESPACE 30212096

#### FILESystem: CWD

Sets or returns the current working directory (CWD) for FILESystem commands. The default working directory is "D:/". Anytime you use this command to change the directory, the directory that you specify is retained as the current working directory until you either change the directory or you delete the directory. If you delete the current working directory, the oscilloscope resets current working directory to the default directory (D:) the next time the oscilloscope is powered on or the next time you execute a file system command.

This command supports the permutations of file and directory names supported by Microsoft Windows:

- Relative path names; for example, "./Temp"
- Absolute path names; for example, "D:/MyWaveform"
- Implied relative path names; for example "newfile.txt" becomes "D:/TekScope/newfile.txt" if the current working directory is "D:/TekScope"

**Group** File System

Syntax FILESystem:CWD {<new working directory path>}

**Arguments** < new working directory path> is a quoted string that defines the current

working; a directory name can be up to 128 characters.

**Examples** FILESYSTEM: CWD "D:/TekScope/images" sets the current working directory

to images.

FILESYSTEM: CWD? might return

:FILESYSTEM: CWD "D:/TekScope/Waveforms" indicating that the current

working directory is set to Waveforms.

### FILESystem: DELEte (No Query Form)

This command deletes a named file. If you specify a directory name, it will delete the directory and all of its contents, the same as the RMDir command. You can also specify the filename as \*.\* to delete all of the files in the current or specified directory.

**Group** File System

Syntax FILESystem:DELEte <file path>

**Related Commands** FILESystem:CWD

FILESystem:RMDir

**Arguments** <file path> is a quoted string that defines the file name and path. If the file

path is within the current working directory, you need only specify the file name.

The argument \*.\* will delete all files and subdirectories within the current working directory.

Examples

FILESYSTEM: DELETE "NOT\_MINE.SET" deletes the file named NOT MINE.SET from the current working directory.

#### FILESystem:DIR? (Query Only)

Returns a list of quoted strings. Each string contains the name of a file or directory in the current working directory.

**Group** File System

Syntax FILESystem:DIR?

Related Commands FILESystem: CWD, FILESystem: MKDir

**Arguments** None

**Returns** FILESystem: DIR? returns a list of files and directories in the current working

directory.

**Examples** FILESYSTEM: DIR? might return

:FILESYSTEM:DIR

"tek00000.png", "my\_CAN\_setup.set", "savedWfm1.isf", "myImages"

# FILESystem:FORMat (No Query Form)

Formats a mass storage device. This command should be used with extreme caution as it causes all data on the specified mass storage device to be lost. Drive letters (e.g., E:) are case sensitive and must be upper case. For all other FILESYSTEM commands, drives letters are not case sensitive. Example: FILES:FORMAT "E:/" Formats the USB flash drive installed in the oscilloscope's front panel USB port.

**Group** File System

**Syntax** FILESystem:FORMat

**Arguments** <drive name> is a quoted string that defines the disk drive to format.

Examples FILESYSTEM:FORMAT "E:/"

Formats the USB flash drive installed in the oscilloscope's front panel USB port.

# FILESystem:FREESpace? (Query Only)

Returns the number of bytes of free space on the current drive.

**Group** File System

**Syntax** FILESystem:FREESpace?

**Related Commands** FILESystem:FREESpace?, FILESystem:CWD

### FILESystem:LDIR? (Query Only)

Returns a semicolon separated list of every file and directory in the folder referred to by the FILESystem:CWD command. This is different than the FILESystem:DIR? query in that it provides a long output format with the file size, type, and modification date/time. Each entry is a semicolon separated list:

<file name>;<type DIR or FILE>;<size in bytes>;<date>;<time>

**Group** File System

Syntax FILESystem:LDIR?

**Related Commands** FILESystem:CWD, FILESystem:DIR?

**Returns** A string of the form: <file name>;<type DIR or FILE>;<size in

bytes>;<date>;<time>

**Examples** FILESYSTEM:LDIR? might return :FILESYSTEM:LDIR

"..;DIR;4096;2007-06-22;14:13:43";"tek0000CH1.isf;FILE;

20342;2009-05-21;13:58:24";"TEMP;DIR;4096;2009-09-15;06:20:44"

### FILESystem: MKDir (No Query Form)

Creates a new folder.

Group File System

FILESystem: MKDir < directory path> **Syntax** 

**Related Commands** FILESystem: CWD, FILESystem: DIR?

> **Arguments** <directory path> is a quoted string that specifies the directory to create

FILESYSTEM: MKDIR "D:/NewDirectory" creates the directory named **Examples** 

*NewDirectory* at the root of the D drive.

These two commands create the directory MyNewSubDirectory within the existing directory MyDirectory at the root of the D drive:

FILESYSTEM:CWD "D:/MyDirectory"; FILESYSTEM:MKDIR "MyNewSubDirectory"

This, of course, assumes that *D:/MyDirectory* already existed and was not a read-only directory.

### FILESystem: READFile (No Query Form)

Writes the contents of the specified file to the specified interface. If the specified file does not exist or is not readable, an appropriate error event is posted.

Group File System

Syntax FILESystem: READFile < QString>

**Related Commands** FILESystem: CWD

> **Arguments** <QString> is a quoted string that defines the file name and path. If the file path is

> > within the current working directory, specify only the file name.

**Examples** FILESYSTEM:READFILE "D:/test\_data/tek00016CH1.csv" reads the

content of the specified file, if the file exists and is readable, and sends the content

of the file to the current interface.

### FILESystem: REName (No Query Form)

Assigns a new name to an existing file.

**Group** File System

Syntax FILESystem:REName <old file path>,<new file path>

Related Commands FILESystem: CWD

**Arguments** <old file path> is a quoted string that defines the file name and path. If the file

path is within the current working directory, you need only specify the file name.

<new file path> is a quoted string that defines the file name and path. If the file path is within the current working directory, you need only specify the file name.

**Examples** FILESYSTEM:RENAME "D:/TEK00000.SET", "D:/MYSETTING.SET" gives the

file named TEK00000.SET the new name of MYSETTING.SET. The file remains

in the root directory on the D drive.

#### FILESystem: RMDir (No Query Form)

Deletes a named directory. This command deletes the specified directory and all

of its contents. The directory must not be a read-only directory.

**Group** File System

Syntax FILESystem:RMDir <directory path>

**Related Commands** FILESystem:CWD

**Arguments** <directory path> is a quoted string that defines the directory name and path.

If the file path is within the current working directory, you need only specify

the file name.

**Examples** FILESYSTEM:RMDIR "D:/OldDirectory" removes the directory named

OldDirectory from the root of the D drive.

### FILESystem: WRITEFile (No Query Form)

Writes the specified block data to a file in the oscilloscope current working directory. If the specified file does not exist or is not readable, an appropriate error event is posted.

**Group** File System

Syntax FILESystem:WRITEFile <file path>, <data>

Related Commands FILESystem: CWD

**Arguments** <file path> is the quoted string that defines the file name and path. If the path

is within the current working directory, specify the file name only.

<data> can be either DEFINITE LENGTH encoding or INDEFINITE LENGTH ARBITRARY BLOCK PROGRAM DATA encoding as described in IEEE488.2.

### FPAnel:PRESS (No Query Form)

Simulates the action of pressing a specified front-panel button.

When the front panel is locked, the front-panel button and multipurpose knob operations are suspended. The FPAnel:PRESS and the FPAnel:TURN commands will also not work. You can work around this by using the appropriate programmatic interface commands, instead of the front-panel commands.

**Group** Miscellaneous

Syntax FPAnel:PRESS <button>

**Arguments \*\* objective of a front-panel button. Most of the argument names** 

associate directly with their front panel buttons. For example, AUTOSet is for the Autoset button. The few commands that do not have obvious associations

are listed below.

Table 2-40: FPAnel:PRESS arguments

Argument	Description
ACQuire	Acquire button
AUTOset	Autoset button
BMENU <x></x>	Screen bottom menu buttons, where <x>=1 for the left-most bottom menu button and <x>=7 for the right-most bottom menu button</x></x>
B <x></x>	Bus select buttons, where $\langle x \rangle = 1$ through 4.
CH <x></x>	Channel select button, where <x>=1 for channel 1, <x>=2 for channel 2, and so on</x></x>
CURsor	Cursors button
D15D0	D0-D15 button
DEFaultsetup	Default Setup button
FINe	Fine button
FORCetrig	Force Trig button
HARDcopy	Hardcopy button
INTensity	Intensity button
MAGnify	Magnify (zoom) button (not the zoom/pan knob)
MARk	Mark Set/Clear button
MATh	M button
MENUOff	Menu Off button
MEASurement	Measure button
NEXt	Next arrow button
PAUse	Play/pause button
PREv	Previous arrow button
REF	R button
RMENU <x></x>	Screen side menu buttons, where <x>=1 for the top-most side menu button and <x>=5 for the bottom-most side menu button</x></x>
RUnstop	Run/Stop button
SAVEBUtton	Save button
SAVERecall	Save/Recall <b>Menu</b> button
SEArch	Search button
SELect	Select button
SETTO50	Set to 50% button
SINGleseq	Single button
TESt	Test button
TRIGger	Trigger <b>Menu</b> button
UTILity	Utility button

**Examples** FPANEL: PRESS AUTOSET executes the oscilloscope Autoset function.

#### FPAnel:TURN (No Query Form)

Simulates the action of turning a specified front-panel control knob.

When the front panel is locked, the front-panel button and multipurpose knob operations are suspended. The FPAnel:PRESS and FPAnel:TURN commands will also not work, and, they will not generate an error. You can work around this by using the appropriate programmatic interface commands, instead of the front-panel commands. For example, to set the trigger level to 50%, you could use TRIGger:A SETLevel. To force a trigger, you could use TRIGger FORCe.

**Group** Miscellaneous

Syntax FPAnel:TURN <knob>,<n>

#### Arguments

<knob> is the name of a rotating control.

A comma (,) separates the control knob argument from the numeric rotation value argument. You do not need a white space between the arguments and the comma.

<n> represents the rotation direction and magnitude of rotation. Negative values represent a counterclockwise knob rotation, and positive values represent a clockwise rotation. The magnitude of <n> specifies the amount of the turn, where <n> = 1 represents turning the knob one unit, <n> = 2 represents turning the knob two units, <n> = 4 represents turning the knob four units, and so on. The range of units depends on which front panel knob is specified.

Table 2-41: FPAnel:TURN arguments

Argument	Description
GPKNOB1	Multipurpose a knob
GPKNOB2	Multipurpose b knob
HORZPos	Horizontal <b>Position</b> knob
HORZScale	Horizontal <b>Scale</b> knob
PANKNOB1	Outer pan knob
TRIGLevel	Trigger <b>Level</b> knob
VERTPOS <n></n>	Vertical <b>Position</b> knob
VERTSCALE <n></n>	Vertical <b>Scale</b> knob
ZOOM	Inner zoom knob

**Examples** 

FPANEL: TURN TRIGLEVEL, 10 duplicates turning the front-panel Trigger Level knob clockwise by 10 units.

## **GPIBUsb:ADDress?** (Query Only)

Returns the current GPIB address setting for a connected TEK-USB-488 adaptor module.

**Group** Miscellaneous

**Syntax** GPIBUsb:ADDress?

### GPIBUsb:ID? (Query Only)

Returns the identification string of the connected TEK-USB-488 adaptor module and firmware version. If a TEK-USB-488.2 module is not connected, the system returns "Not detected".

**Group** Miscellaneous

Syntax GPIBUsb:ID?

### **HARDCopy** (No Query Form)

Sends a hard copy of the screen display to the currently active printer using the current palette and layout settings.

**Group** Hard Copy

**Syntax** HARDCopy {START}

HARDCopy?

Related Commands \*WAI, \*CLS

**Arguments** START sends a block of data representing the current screen image to

the requested port. The data sent is in the image format specified by the SAVe:IMAGe:FILEFormat command and the compression level is controlled by the selected format (BMP and TIFF are uncompressed where as PNG is

compressed). The SAVe:IMAGe:INKSaver determines whether the data sent is in InkSaver mode.

**NOTE.** The Hardcopy command with no arguments is equivalent to pressing the "HardCopy" button on the front panel, when the data is sent to the printer. As there is no front panel equivalent of the HARDCOPY START, you can choose to save the images to a different location using the "SAVE" button.

**Examples** 

HARDCOPY initiates a screen copy to the active printer.

### **HARDCopy:ACTIVeprinter**

Sets or returns the currently active printer. When a hard copy operation is performed, the output will be sent to this printer. One of two methods of specifying the printer can be used: specifying an index value obtained from looking at the list of attached printers or by specifying the printer name.

**Group** Hard Copy

Syntax HARDCopy:ACTIVeprinter {<NR1>|<name>}

HARDCopy: ACTIVeprinter?

**Arguments** <NR1> is the index of the desired printer as returned from HARDCopy:PRINTer:

LIST?

<name> is the name of the printer as specified in the printer list. This name is case sensitive and must be entered exactly as shown in the list.

### HARDCopy: INKSaver

Changes hard copy output to print traces and graticule on a white background while retaining waveform color information (except for channel 1, which prints as dark blue because yellow does not show up well and is difficult to see on a white background). This option can significantly reduce print time and quantities of ink required compared with WYSIWYG dark background images.

**Group** Hard Copy

**Syntax** HARDCopy:INKSaver?

**Arguments** ON or  $\langle NR1 \rangle \neq 0$  sets the ink saver mode on.

OFF or  $\langle NR1 \rangle = 0$  sets the ink saver mode off.

**Examples** HARDCOPY: INKSAVER ON will cause subsequent hard copy output to display the

screen on a white background.

#### HARDCopy:LAYout

Sets or returns the page orientation for hard copy. If you set the layout to LANdscape, the printer will print hard copies in landscape mode where the long edge of the screen will print to the long edge of the sheet of paper. If you set the layout to PORTRait, the printer will print hard copies in portrait mode.

This command is not applicable for PictBridge hardcopies.

**Group** Hard Copy

**Syntax** HARDCopy:LAYout {PORTRait|LANdscape}

HARDCopy:LAYout?

**Arguments** PORTRait orients the screen image vertically on the printed page.

LANdscape orients the screen image horizontally on the printed page.

**Examples** HARDCOPY: LAYOUT LANDSCAPE sets the hard copy page orientation to Landscape.

HARDCOPY: LAYOUT? might return: HARDCOPY: LAYOUT PORTRAIT indicating

that the hard copy page orientation is set to portrait.

#### HARDCopy:PREVIEW (No Query Form)

Displays a preview of the current screen contents with the InkSaver palette applied.

**Group** Hard Copy

Syntax HARDCopy:PREVIEW {ON|OFF|<NR1>}

**Arguments** ON or  $\langle NR1 \rangle \neq 0$  turns preview mode on.

OFF or  $\langle NR1 \rangle = 0$  turns preview mode off.

# HARDCopy:PRINTer:ADD (No Query Form)

Adds a network printer to the list of available printers. All three arguments must be present, but only one of server name or server IP address may be specified. An empty string can be used for blank arguments.

**Group** Hard Copy

Syntax HARDCopy:PRINTer:ADD <name>,<server>,<address>

**Arguments** < name > is the name of the network printer queue.

<server> is the host name of the print (LPR) server.

<address> is the IP address of the print server.

# **HARDCopy:PRINTer:DELete (No Query Form)**

Removes a network printer from the list of available printers. The printer name is case sensitive.

**Group** Hard Copy

Syntax HARDCopy:PRINTer:DELete <name>

**Arguments** < name > is the name of the printer to be deleted.

## HARDCopy:PRINTer:LIST? (Query Only)

Returns a list of currently attached printers.

**Group** Hard Copy

**Syntax** HARDCopy:PRINTer:LIST?

## HARDCopy:PRINTer:REName (No Query Form)

Renames a network printer on the list of available printers, replacing the currently stored settings with the settings specified in this command. Four arguments must

be present, but the arguments may be empty strings if the value for a field is to be deleted.

**Group** Hard Copy

Syntax HARDCopy:PRINTer:REName

<name>, <new\_name>, <new\_server>, <new\_address>

**Arguments** < name > is the name of the printer to be deleted.

<new\_name> is the new name for this printer.

<new\_server> is the new print server for this printer.

<new\_address> is the new IP address for the server.

#### **HEADer**

Sets or returns the Response Header Enable State that causes the oscilloscope to either include or omit headers on query responses.

**NOTE.** This command does not affect IEEE Std 488.2-1987 Common Commands (those starting with an asterisk); these commands never return headers. This command does affect the Response Header Enable State of both the USBTMC and VXI-11 interfaces. Refer to the Introduction for additional information.

**Group** Miscellaneous

Syntax HEADer {OFF|ON|<NR1>}

**HEADer?** 

Related Commands VERBose

**Arguments** OFF sets the Response Header Enable State to false. This causes the oscilloscope to omit headers on query responses, so that only the argument is returned.

ON sets the Response Header Enable State to true. This causes the oscilloscope to include headers on applicable query responses. You can then use the query

response as a command.

<NR1> = 0 sets the Response Header Enable State to false; any other value sets this state to true.

#### **Examples**

HEADER OFF specifies that the oscilloscope omits headers on query responses, so that only the argument is returned.

HEADER? might return: HEADER 1 indicating that the oscilloscope is including headers on applicable query responses.

## HIStogram? (Query Only)

This query-only command returns all histogram parameters; it queries the state of all histogram parameters that the user can set. This command is equivalent to selecting Waveform Histograms from the Measure menu.

**Group** Histogram

Syntax HIStogram?

Related Commands MEASUrement: METHod

**Examples** HISTOGRAM? might return the histogram parameters as :HISTOGRAM:BOXPCNT

30.0000,25.1000,70.0000,75.2000; DISPLAY LINEAR; STATE

1; FUNCTION VERTICAL; SIZE 2.0000; SOURCE CH1.

## **HIStogram:BOX**

This command sets or returns the histogram box coordinates in terms of source waveform vertical and horizontal units.

**Group** Histogram

Syntax HIStogram:BOX <NR3>, <NR3>, <NR3>, <NR3>

HIStogram: BOX?

Related Commands HIStogram: BOXPcnt

**Arguments** <NR3> specifies the left position of the histogram box in source waveform

horizontal units.

<NR3> specifies the top position of the histogram box in source waveform

vertical units.

<NR3> specifies the right position of the histogram box in source waveform horizontal units.

<NR3> specifies the bottom position of the histogram box in source waveform vertical units.

#### **Examples**

HISTOGRAM: BOX 1E-9, 0.250, 2E-9, 0.500 defines the coordinates of the histogram box in source waveform coordinates.

HISTOGRAM: BOX? might return: HISTOGRAM: BOX 1.0000E-09, 0.2500, 2.0000E-09, 0.5000, which identifies the coordinates of the histogram box in source waveform coordinates.

## HIStogram:BOXPcnt

This command sets or returns the histogram box coordinates in terms of percentages of the full screen extents of the source waveform. The arguments refer to the left (percent of the horizontal screen extent), top (percent of the vertical screen extent), right (percent of the horizontal screen extent), bottom (percent of the vertical screen extent). The valid range for these values is 0.0 to 100.0.

#### **Group** Hisstogram

Syntax HIStogram:BOXPcnt <NR2>, <NR2>, <NR2>, <NR2>

HIStogram:BOXPcnt?

#### Related Commands HIStogram:BOX

#### **Arguments**

<NR3> specifies the left position of the histogram box in percentage coordinates. The default value is 20%

<NR3> specifies the top position of the histogram box in percentage coordinates. The default value is 80%

<NR3> specifies the right position of the histogram box in percentage coordinates. The default value is 80%

<NR3> specifies the bottom position of the histogram box in percentage coordinates. The default value is 20%

#### **Examples**

HISTOGRAM: BOXPCNT 30.0,25.0,70.0,75.0 sets the left boundary of the histogram box to 30% of the graticule (3 divisions from the left edge); the top boundary to 25% of the graticule ( $0.25 \times 10 = 2.5$  divisions from the top edge); the right boundary to 70% of the graticule (7 divisions from the left edge); and

the bottom boundary to 75% of the graticule  $(0.75 \times 10 = 7.5 \text{ divisions from the top edge})$ .

HISTOGRAM: BOXPCNT? might return: HISTOGRAM: BOXPCNT 30.0000,25.1000,70.0000,75.2000.

### **HIStogram:COUNt (No Query Form)**

This command (no query form) clears the count and statistics for the histogram and the histogram source data. If the histogram is on, then counting restarts.

**Group** Histogram

Syntax HIStogram: COUNT RESET

Related Commands HIStogram:BOX

HIStogram:BOXPcnt

**Arguments** RESET

**Examples** HISTOGRAM: COUNT RESET clears the count and statistics for the histogram and

the histogram source data.

## **HIStogram:DATa? (Query Only)**

This query returns the histogram data when the :HIStogram:MODe is HORizontal or VERTical. If the mode is OFF, then no data is returned and an error event is set

The data values returned for this query represent the number of times the histogram source waveform samples were coincident with a particular histogram bin.

For vertical histograms, this query returns 256 values, representing the number of times the histogram source waveform samples were coincident with each of the 256 digitizing levels. Of these 256 values, the first 2 and last 3 are always 0, as they represent digitizing levels that fall above and beneath the waveform graticule, respectively.

For horizontal histograms, this query returns 1000 values, representing the number of times the histogram source waveform samples were coincident with each horizontal pixel column. The time of occurrence for each of the horizontal bins can be derived using the HIStogram:STARt? and HIStogram:END? queries.

**Group** Histogram

**Syntax** HIStogram: DATa?

Related Commands HIStogram:BOX

HIStogram:BOXPcnt

HIStogram: COUNt

HIStogram:DISplay

HIStogram:MODe

HIStogram:SOUrce

#### **Examples**

HISTOGRAM: DATA? might return : HISTOGRAM: DATA 0,0,0,0,0,0,1245,933,903,1003,838,782,764,697, 687,620,582,566,530,595,557,552,518,524,606, 503,526,470,498,554,534,487,546,548,504,554, 513,566,639,508,643,704,662,769,785,806,922, 960, 1153, 1336, 1478, 1960, 4515, 17598, 52184, 67040,50417,12885,4104,2382,1866,1699,1428, 1288, 1271, 1140, 975, 1024, 894, 841, 841, 678, 841, 804,685,713,746,729,644,640,787,768,668,671, 661,745,755,692,882,772,802,862,770,854,799, 969, 1102, 1080, 1040, 1272, 1329, 1394, 1760, 1428, 2418,3313,4475,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0 0,0,0,0,0,0,0,0,0,0,0.

### HIStogram: DISplay

This command sets the scaling of the histogram data display to be the count of each histogram bin or the log of that count. The default scaling is linear.

**Group** Histogram

**Syntax** HIStogram:DISplay {OFF|LOG|LINEAr}

HIStogram: DISplay?

**Related Commands** HIStogram:MODe

**Arguments** <LOG> sets the histogram display to logarithmic scaling

<LINEAr> sets the histogram display to linear scaling. This is the default setting.

**Examples** HISTOGRAM: DISPLAY LOG sets the histogram scaling to be the log count of

each histogram bin.

HISTOGRAM: DISPLAY? might return: HISTOGRAM: DISPLAY LOG indicating that the current histogram display scaling is the log count of each histogram bin.

### **HIStogram:END? (Query Only)**

Returns the time (horizontal) or vertical units value (vertical) of the last bin where the histogram data ends. The HIStogram:MODe must be either HORizontal or VERTical for a value to be returned. If the mode is OFF, an error event is set and nothing is returned.

If the HIStogram:MODe is HORizontal, the value returned is the time of the right bin. If the HIStogram:MODe is VERTical the value returned is the vertical units value of the bottom bin. The returned value is an <NR3>.

**Group** Histogram

**Syntax** HIStogram: END?

Related Commands HIStogram: MODe

HIStogram:STARt?

Returns <NR3>

**Examples** HISTOGRAM: END? might return: HISTOGRAM: END 1.6000E-05 indicating that

the last bin is at  $16 \mu s$ .

## HIStogram:MODe

This command selects the type of histogram to create or disables the histogram display. The query form either returns the current histogram type or that the histogram display is disabled.

**Group** Histogram

**Syntax** HIStogram: MODe {HORizontal|VERTical|OFF}

HIStogram: MODe?

**Related Commands** HIStogram:DISplay

**Arguments** HORizontal enables a horizontally positioned histogram that shows time

distribution.

VERTical enables a vertically positioned histogram that shows a voltage

distribution, or another distribution such as amperes.

OFF disables the collection of the histogram measurement.

**Examples** HISTOGRAM: MODE HORIZONTAL sets the type of histogram created to horizontal,

which displays a horizontally positioned histogram that shows time distribution.

HISTOGRAM: MODE? might return: HISTOGRAM: MODE OFF, indicating that the

histogram display is disabled.

HIStogram:SOUrce

This command sets or queries which source will be compared against the

histogram box when the histogram testing is enabled.

**Group** Histogram

Syntax HIStogram:SOUrce {CH<x>|MATH|REF<x>}

HIStogram: SOUrce?

Related Commands HIStogram: DISplay

**Arguments** CH<x> selects a channel waveform as the source for the histogram. The x variable

can be expressed as an integer ranging from 1 through 4.

MATH selects the math waveform as the source for the histogram.

REF<x> selects a reference waveform as the source for the histogram. The x

variable can be expressed as an integer ranging from 1 through 4.

**Examples** HISTOGRAM: SOURCE CH1 enables the Channel 1 waveform to be compared

against the histogram box.

HISTOGRAM: SOURCE? might return: HISTOGRAM: SOURCE CH1, indicating that the waveform for Channel 1 is the source for the histogram.

## HIStogram:STARt? (Query Only)

Returns the time (horizontal) or vertical units value (vertical) of the first bin where the histogram data starts. The HIStogram: MODe must be either HORizontal or VERTical for a value to be returned. If the mode is OFF, an error event is set and nothing is returned.

If the HIStogram: MODe is HORizontal, the value returned is the time of the left bin. If the HIStogram: MODe is VERTical the value returned is the vertical units value of the top bin. The returned value is an <NR3>.

**Group** Histogram

**Syntax** HIStogram: STARt?

Related Commands HIStogram: END?

HIStogram: MODe

**Returns** <NR3> showing the returned value.

Examples HISTOGRAM: START? might return: HISTOGRAM: START 2.0000E-06

indicating that the first bin is at 2  $\mu$ s.

## **HORizontal?** (Query Only)

Returns all settings for the horizontal commands.

**Group** Horizontal

Syntax HORizontal?

**Examples** HORIZONTAL? might return the following horizontal settings

:HORIZONTAL:DELAY:MODE 1;TIME 0.0000;:HORIZONTAL:MAIN:SCALE 20.0000E-9;SAMPLERATE 5.0000E+9;UNITS "s";UNITS:STRING "s";:HORIZONTAL:SAMPLERATE 5.0000E+9;RECORDLENGTH 1000000

### HORizontal:DELay:MODe

Sets or returns the horizontal delay mode.

**Group** Horizontal

Syntax HORizontal:DELay:MODe {OFF|ON|<NR1>}

HORizontal:DELay:MODe?

Related Commands HORizontal: POSition

**Arguments** OFF sets the Horizontal Delay Mode to off. This causes the HORizontal:POSition

command to operate like the HORIZONTAL POSITION knob on the front panel.

ON sets the Horizontal Delay Mode to on. This causes the

HORizontal:DELay:TIMe command to operate like the HORIZONTAL

POSITION knob on the front panel.

<NR1> = 0 sets the Horizontal Delay Mode to off; any other value sets this mode

to on.

**Examples** HORIZONTAL: DELAY: MODE OFF sets the Horizontal Delay Mode to off, allowing

the horizontal position command to operate like the HORIZONTAL POSITION

knob on the front panel.

HORIZONTAL: DELAY: MODE? might return HORIZONTAL: DELAY: MODE OFF indicating that the Horizontal Delay Mode is off and that the horizontal position command operates like the HORIZONTAL POSITION knob on the front panel.

HORizontal:DELay:TIMe

Sets or returns the horizontal delay time (position) that is used when delay is

on (the default mode).

**Group** Horizontal

Syntax HORizontal:DELay:TIMe <NR3>

HORizontal:DELay:TIMe?

Related Commands HORizontal:POSition

**Arguments** NR3 is the delay in seconds.

**Examples** HORizontal:DELay:TIME 0.3 sets the delay of acquisition data so that the

resulting waveform is centered 300 ms after the trigger occurs.

## HORizontal:DIGital:RECOrdlength:MAGnivu? (Query Only)

Returns the record length of the MagniVu digital acquisition.

**Group** Horizontal

**Syntax** HORizontal:DIGital:RECOrdlength:MAGnivu?

### **HORizontal:DIGital:RECOrdlength:MAIN? (Query Only)**

Returns the record length of the main digital acquisition.

**Group** Horizontal

**Syntax** HORizontal:DIGital:RECOrdlength:MAIN?

### HORizontal:DIGital:SAMPLERate:MAGnivu? (Query Only)

Returns the sample rate of the MagniVu digital acquisition.

**Group** Horizontal

**Syntax** HORizontal:DIGital:SAMPLERate:MAGnivu?

# **HORizontal:DIGital:SAMPLERate:MAIN? (Query Only)**

Returns the sample rate of the main digital acquisition.

**Group** Horizontal

**Syntax** HORizontal:DIGital:SAMPLERate:MAIN?

#### **HORizontal:POSition**

Sets or returns the horizontal position, in percent, that is used when delay if off. If Horizontal Delay Mode is turned off, this command is equivalent to adjusting the HORIZONTAL POSITION knob on the front panel. When Horizontal Delay Mode is on, this command stores a new horizontal position that is used when Horizontal Delay Mode is turned off.

**Group** Horizontal

Syntax HORizontal:POSition <NR3>

HORizontal: POSition?

Related Commands HORizontal:DELay:TIMe

**Arguments** <NR3> is the horizontal position expressed as the percentage of the waveform

acquired before the trigger.

**Examples** HORIZONTAL: POSITION 50 sets the horizontal position to 50%.

HORIZONTAL: POSITION? might return: HORIZONTAL: POSITION 100

indicating that the horizontal position is set to 100%.

# HORizontal:PREViewstate? (Query Only)

Returns a boolean value to indicate whether the display system is in the preview state.

**Group** Horizontal

**Syntax** HORizontal:PREViewstate?

**Returns**  $\langle NR1 \rangle = 1$  if the display system is in the preview state.

<NR1> = 0 if the display system is not in the preview state.

# HORizontal:RECOrdlength

Sets the horizontal record length. The query form of this command returns the current horizontal record length.

**Group** Horizontal

Syntax HORizontal:RECOrdlength <NR1>

HORizontal:RECOrdlength?

**Arguments** <NR1> represents the supported values for horizontal record lengths, which are:

1000, 10000, 100000, 1000000, or 10000000.

**Examples** HORIZONTAL: RECORDLENGTH 10000 specifies that 10000 data points will be

acquired for each record.

HORIZONTAL: RECORDLENGTH? might return: HORIZONTAL: RECOrdlength 1000 indicating that the horizontal record length is equal to 1000 data points.

#### **HORizontal:SAMPLERate**

Sets or returns the current horizontal sample rate.

**Group** Horizontal

Syntax HORizontal:SAMPLERate <NR3>

HORizontal:SAMPLERate?

**Arguments** <NR3> is the rate in samples per second.

**HORizontal:SCAle** 

Sets or returns the time base horizontal scale.

**Group** Horizontal

Syntax HORizontal:SCAle <NR3>

HORizontal:SCAle?

**Arguments** <NR3> specifies the range from 400 ps to 1000 s, depending on the record length.

**Examples** HORIZONTAL: SCALE 2E-6 sets the main scale to 2µs per division.

HORIZONTAL:SCALE? might return: HORIZONTAL:MAIN:SCALE 2.0000E-06

indicating that the main scale is currently set to 2 µs per division.

ID? (Query Only)

Returns identifying information about the oscilloscope and related firmware.

**Group** Miscellaneous

Syntax ID?

Related Commands \*IDN?

**Examples** ID? might return TEK/DPO4034, CF:91.1CT, FV:v1.0000. This indicates the

oscilloscope model number, configured format, and firmware version number.

\*IDN? (Query Only)

Returns the oscilloscope identification code.

**Group** Miscellaneous

Syntax \*IDN?

Related Commands ID?

**Examples** \*IDN? might return: TEKTRONIX, DPO4034, SN123456789, CF: 91.1CT

FV:v1.00000 indicating the oscilloscope model number, serial number,

configured number, and firmware version number.

**LANGuage** 

Sets or returns the user interface display language. This command only affects the oscilloscope displayed language. Remote commands and their responses

are always in English.

**Group** Miscellaneous

Syntax LANGuage

{ENGLish|FRENch|GERMan|ITALian|SPANish|PORTUguese|JAPAnese|

KOREan|RUSSian|SIMPlifiedchinese|TRADitionalchinese}

LANGuage?

**Examples** LANGUAGE? might return: LANGUAGE ENGLISH.

#### **LOCk**

Enables or disables all front-panel buttons and knobs. There is no front panel equivalent.

When the front panel is locked, neither the FPAnel: PRESS nor the FPAnel: TURN commands will work. They will not generate an error event either. You can work around this by using the appropriate programmatic interface commands, instead of the front-panel commands. For example, to set the trigger level to 50%, you could use TRIGger: A SETLevel. To force a trigger, you could use TRIGger FORCe.

**Group** Miscellaneous

**Syntax** LOCk {ALL|NONe}

LOCk?

Related Commands UNLock

**Arguments** ALL disables all front-panel controls.

NONe enables all front-panel controls. This is equivalent to the UNLock ALL

command.

**Examples** LOCK ALL locks the front-panel controls.

LOCK? might return: LOCK NONE indicating that the front-panel controls are

enabled by this command.

## \*LRN? (Query Only)

Returns the commands that list the oscilloscope settings except for configuration information for the calibration values, the WFMInpre? query, and the WFMOutpre? query. This query allows you to record or "learn" the current

oscilloscope settings. You can use these commands to return the oscilloscope to the state it was in when you made the \*LRN? query. This command is identical to the SET? Command.

**Group** Miscellaneous

Syntax \*LRN?

Related Commands SET?

#### **Examples**

\*LRN? might return a long response, part of which could be as follows: :ACQUIRE:STOPAFTER RUNSTOP;STATE 1;MODE SAMPLE;NUMENV INFINITE; NUMAVG 16; SAMPLINGMODE RT; : HEADER 1; : LOCK NONE;:LANGUAGE ENGLISH;:VERBOSE 1;:ALIAS:STATE O;:DISPLAY:COLOR:PALETTE NORMAL;:DISPLAY:STYLE:DOTSONLY 0;:DISPLAY:PERSISTENCE 0.0000;CLOCK 1;GRATICULE FULL; INTENSITY: WAVEFORM 30; GRATICULE 75; BACKLIGHT HIGH;:HARDCOPY :INKSAVER OFF;LAYOUT LANDSCAPE;PREVIEW 0;:SAVE:IMAGE:FILEFORMAT BMP;:SAVE:WAVEFORM:FILEFORMAT INTERNAL;:SAVE:ASSIGN:TYPE SETUP;:TRIGGER:A:MODE AUTO; TYPE EDGE; LE VEL 20.0000E-3; LEVEL: CH1 20.0000E-3;CH2 0.0000;CH3 0.0000;CH4 0.0000;:TRIGGER:A: UPPERTHRESHOLD:CH1 1.4000;CH2 800.0000E-3;CH3 800.0000E-3;CH4 800.0000E-3;:TRIGG ER:A:LOWERTHRESHOLD:CH1 20.0000E-3;CH2 0.0000;CH3 0.0000;CH4 0.0000;:TRIGGER:A:H OLDOFF:TIME 20.0000E-9;:TRIGGER:A:EDGE:SOURCE CH1; COUPLING DC; SLOPE RISE; :TRIGGER: A: LOGIC: CLASS SETHOLD; FUNCTION AND; THRESHOLD: CH1 20.0000E-3; CH2 0.0000; CH3 0.0 000; CH4 0.0000; :TRIGGER: A: LOGIC: INPUT: CH1 X;CH2 X;CH3 X;CH4 X;CLOCK:SOURCE NONE; EDGE RISE;:TRIGGER:A:LOGIC:PATTERN:INPUT:CH1 X;CH2 X;CH3 X;CH4 X;:TRIGGER:A:LOGIC:PATTERN:WHEN TRUE; WHEN: LESSLIMIT 4.0000E-9; LIMIT 4.0000E-9;:TRIGGER:A:SETHOLD:CLOCK:SOURCE CH1;EDGE RISE; THRESHOLD 20.0000E-3; :TRIGGER: A: SETHOLD: DATA: SOURCE CH2; THRESHOLD 0.0000; :TRIGGER: A: SETHOLD: HOLDTIME 4.0000E-9;SETTIME 4.0000E-9; :TRIGGER:A:PULSE:CLASS TRANSITION;:TRIGGER:A:PULSEWIDTH:SOURCE CH1; POLARITY POSITIVE; WHEN LESSTHAN; WIDTH 4.0000E-9;:TRIGGER:A:RUNT:SOURCE CH1;POLARITY POSITIVE; WHEN OCCURS; WIDTH 4.0000E-9; :TRIGGER: A:TRANSITION: SOURCE CH1

...

#### **MARK**

Moves to the next or previous reference mark on the waveform. Returns the

current mark position.

**Group** Mark

**Syntax** MARK {NEXT|PREVious}

MARK?

**Arguments** NEXT moves to the next reference mark on the right.

PREVious moves to the next reference mark on the left.

### MARK: CREATE (No Query Form)

Creates a mark on a specified waveform or all waveforms in a column.

**Group** Mark

Syntax MARK:CREATE {CH<x>|MATH|B<x>|REF<x>|DIGital|COLUMN}

**Arguments** CH<x> creates the mark on a channel waveform, where <x> is the channel number.

MATH creates the mark on the math waveform.

B<x> creates the mark on a bus waveform, where <x> is the bus number.

REF<x> creates the mark on a reference waveform, where  $\langle x \rangle$  is the reference

waveform number.

DIGital creates the mark on a digital waveform. (An error will result if no

digital channel is turned on.)

COLUMN creates marks on all waveforms in the current zoom pixel column.

# MARK:DELEte (No Query Form)

Deletes a mark on a particular waveform, all waveforms in a column, the selected mark, or all marks.

**Group** Mark

Syntax MARK:DELEte {CH<x>|MATH|B<x>|REF<x>|DIGital|COLUMN}

**Arguments** CH<x> deletes the mark on a channel waveform, where <x> is the channel number.

MATH deletes the mark on the math waveform.

B<x> deletes the mark on a bus waveform, where <x> is the bus number.

REF<x> deletes the mark on a reference waveform, where  $\langle x \rangle$  is the reference

waveform number.

DIGital deletes all marks on all digital channels.

COLUMN deletes marks on all waveforms in the current zoom pixel column.

## MARK:FREE? (Query Only)

Returns how many marks are available for use.

**Group** Mark

Syntax MARK: FREE?

## MARK:SELected:END? (Query Only)

Returns the end of the selected mark, 0 to 100% of the waveform.

**Group** Mark

**Syntax** MARK: SELected: END?

## MARK:SELected:FOCUS? (Query Only)

Returns the focus of the selected mark, 0 to 100% of the waveform.

**Group** Mark

**Syntax** MARK: SELected: FOCUS?

# MARK:SELected:MARKSINCOLumn? (Query Only)

Returns the number of marks in the current zoom pixel column.

**Group** Mark

**Syntax** MARK: SELected: MARKSINCOLumn?

## MARK:SELected:OWNer? (Query Only)

Returns the owner of the selected mark.

**Group** Mark

**Syntax** MARK: SELected: OWNer?

**Returns** <QString> is the owner of the mark.

**Examples** MARK: SELECTED: OWNER? might return: USER, SEARCH1

### MARK:SELected:SOURCE? (Query Only)

Returns the source waveform for the selected mark.

**Group** Mark

**Syntax** MARK: SELected: SOURCE?

## MARK:SELected:STARt? (Query Only)

Returns the starting point of the selected mark, 0 to 100% of the waveform.

**Group** Mark

**Syntax** MARK: SELected: STARt?

## MARK:SELected:STATe? (Query Only)

Returns the on or off state of the selected mark. The selected mark is at or near the center of the screen. If you press the front-panel Set/Clear button, this mark will disappear.

**Group** Mark

Syntax MARK:SELected:STATe?

## MARK:SELected:ZOOm:POSition? (Query Only)

Returns the position of the selected mark, 0 to 100% of the zoom overview window.

**Group** Mark

**Syntax** MARK:SELected:ZOOm:POSition?

## MARK:TOTal? (Query Only)

Returns how many marks are currently in use.

**Group** Mark

**Syntax** MARK: TOTal?

### {MATH|MATH1}:LABel

Sets or queries the waveform label for the math waveform.

**Group** Math

Syntax {MATH|MATH1}:LABel <QString>

{MATH|MATH1}:LABel?

**Arguments** <QString> is the quoted string used as the label for the math waveform.

**Examples** MATH: LABEL "Output" sets the label for the math waveform to Output.

MATH: LABEL? might return MATH: LABEL "Sum of channel 1 and channel 2" indicating the current label for the math waveform.

## MATH[1]? (Query Only)

Returns the definition of the math waveform. The returned data depends on the setting of the MATH[1]:TYPe command.

**Group** Math

Syntax MATH[1]?

**Related Commands** MATH[1]:TYPe

**Examples** MATH? or MATH1? might return :MATH:TYPE DUAL;DEFINE

"CH1+CH2"; VERTICAL: SCALE 100.0000E-3; POSITION 0.0000; UNITS "V"; :MATH: HORIZONTAL: SCALE 4.0000E-6; POSITION 50.0000; UNITS

"s";:MATH:SPECTRAL:MAG DB;WINDOW HANNING

### MATH[1]:DEFine

Sets or returns the current math function as a text string.

Dual math is defined if the string is of the form <wfm> <operation> <wfm>, where the <wfm>s are any combination of live channels or reference waveforms, <operation> is any of +, -, \* or /, and the MATH[1]:TYPe is DUAL.

FFT math is defined if the string is in the form FFT(<wfm>), where <wfm> is any live channel or reference waveform, and theMATH[1]:TYPe is FFT.

Advanced math is defined if the contents of the string can be parsed by the advanced math parser without errors and the MATH[1]:TYPe is ADVanced.

On the front panel, the Dual Wfm Math, FFT and Advanced Math menus contain controls that allow building equivalent math expressions to those described above.

**Group** Math

Syntax MATH[1]:DEFine <QString>

MATH[1]:DEFine?

#### **Related Commands**

#### MATHVAR:VAR<x>, MATH[1]:TYPe

#### **Arguments**

<QString> quoted string argument is the mathematical expression that defines the waveform.

Table 2-42: Advanced Math expression elements

Expression	Description
CH1-CH4, REF1-REF4	Specifies a waveform data source.
FFT( , INTG( , DIFF(	Executes a Fast Fourier Transform, integration, or differentiation operation on the expression that follows. The FFT operator must be the first (left-most) operator in an expression. All these operations must end with a right parenthesis.
AMPlitude(, AREa(, BURst(, CARea( CMEan(, CRMs(, DELay(, FALL(, FREQuency(, HIGH(, LOW(, MAXimum(, MEAN(, MINImum(, NDUty(, NOVershoot(, NWIdth(, PDUTy(, PERIod(, PHAse( PK2pk(, POVershoot(, PWIdth(, RISe(, RMS(,!(	Executes the selected measurement operation on the waveform (active or reference) that follows. All these operations must end with a right parenthesis.
LOG(, EXP(, SQRT(, SINE(, COSINE(, TANGENT(	Executes trigonometric and other functions. All these operations must end with a right parenthesis.
VAR1, VAR2	Adds the user-defined variable to the expression. Refer to the MATHVAR <x> command.</x>
+,-,*,/	Executes an addition, subtraction, multiplication, or division operation on the following expression. + and - are also unary; use - to negate the expression that follows.
<, >, <=, >=, ==, ≠,   , &&	Executes relational and logical operations.
<, >, <=, >=, ==, ≠,   , && ( ) ,	Parentheses provide a way to control evaluation order in an expression. The comma is used to separate the "from" and "to" waveforms in Delay and Phase measurement operations.
1-0 , . , E	Specifies a numeric value in (optional) scientific notation.

#### **Examples**

MATH1:DEFINE" CH1+CH2" adds the Ch 1 waveform and Ch 2 waveform, storing the results in Math 1.

MATH: DEFINE? might return: MATH1: DEFINE "CH2\*REF2" as the expression that defines Math 1.

### MATH[1]:HORizontal:POSition

Sets or returns the math horizontal display position for FFT or (non-live) math reference waveforms.

**Group** Math

Syntax MATH[1]:HORizontal:POSition <NR3>

MATH[1]:HORizontal:POSition?

**Arguments** <NR3> is the % of the math waveform that precedes center screen. It can vary

from 0.0 to 100.0.

**Examples** MATH: HORIZONTAL: POSITION 10 sets the horizontal position to 10% pretrigger

## MATH[1]:HORizontal:SCAle

Sets or returns the math horizontal display scale for FFT or for dual math waveforms that have source waveforms that are reference waveforms. The horizontal scale of a dual math waveform with a channel source waveform is set through the HORizontal:SCAle command.

**Group** Math

Syntax MATH[1]:HORizontal:SCAle <NR3>

MATH[1]:HORizontal:SCAle?

**Arguments** <NR3> is the math horizontal scale in seconds.

**Examples** MATH:HORIZONTAL:SCALE? might return MATH:HORIZONTAL:SCALE 2.0E-4

indicating that the math horizontal scale is 200  $\boldsymbol{\mu}$ 

### MATH[1]:HORizontal:UNIts

Returns the math waveform horizontal measurement unit value.

**Group** Math

**Syntax** MATH[1]:HORizontal:UNIts?

**Examples** MATH:HORIZONTAL:UNITS? might return MATH:HORIZONTAL:UNITS "?"

indicating that the math horizontal unit label for unknown values is the default

question mark unit.

### MATH[1]:SPECTral:MAG

Sets or returns the units of the Spectral Magnification function in the math string.

**Group** Math

**Syntax** MATH[1]:SPECTral:MAG {LINEAr|DB}

MATH[1]:SPECTral:MAG?

**Arguments** LINEAR sets the SpectralMag units to linear.

DB sets the SpectralMag units to decibels.

**Examples** MATH1: SPECTRAL: MAG DB sets the SpectralMag units for Math1 to decibels.

MATH1:SPECTRAL:MAG? might return:MATH1:SPECTRAL:MAG DB indicating

that the SpectralMag units for Math1 are set to decibels.

### MATH[1]:SPECTral:WINdow

Sets or returns the window function for the spectral analyzer input data for the specified math waveform. A spectral window determines what the filter shape of the spectral analyzer will be in the frequency domain. It can be described by a mathematical function that is multiplied point-by-point times the input data to the spectral analyzer.

**Group** Math

Syntax MATH[1]:SPECTral:WINdow

{RECTangular|HAMming|HANning|BLAckmanharris}

MATH[1]:SPECTral:WINdow?

**Arguments** RECTangular window function is equivalent to multiplying all gate data by one.

HAMming window function is based on a cosine series.

HANning window function is based on a cosine series.

BLAckmanharris window function is based on a cosine series.

**Examples** MATH1:SPECTRAL:WINDOW HANNING applies a Hanning window to the spectral

analyzer input data.

MATH1:SPECTRAL:WINDOW? might return:MATH1:SPECTRAL:WINDOW HAMMING indicating that the window function used to multiply the spectral

analyzer input data is the Hamming window.

## MATH[1]:TYPe

Sets or returns the math waveform mode type.

**Group** Math

Syntax MATH[1]:TYPe {ADVanced|DUAL|FFT}

MATH[1]:TYPe?

**Arguments** ADVanced sets the math waveform mode to advanced math.

DUAL sets the math waveform mode to dual waveform math.

FFT sets the math waveform mode to FFT math.

**Examples** MATH: TYPE FFT sets the math waveform mode to FFT.

MATH:TYPE FFT;:MATH:DEFINE "FFT( CH1 )" sets the math type to FFT and displays an FFT waveform of the channel 1 waveform, using the current

FFT scale and window settings.

MATH:TYPE ADVANCED;:MATH:DEFINE

"INTG(REF1\*CH3)+DELAY(CH1, CH2)" sets the math type to FFT and displays an advanced math waveform that is the integration of the product of REF1 and

CH3 plus the result of the delay measurement between channel 1 and 2.

## MATH[1]:VERTical:POSition

Sets or returns the vertical position of the currently selected math type.

**Group** Math

Syntax MATH[1]:VERTical:POSition <NR3>

MATH[1]: VERTical: POSition?

**Related Commands** CH<x>:POSition, REF<x>:VERTical:POSition

**Arguments** <NR3> is the desired position in divisions from the center graticule.

**Examples** MATH1: VERTICAL: POSITION 1.3E+00 positions the Math 1 input signal

1.3 divisions higher than a position of 0.

MATH1: VERTICAL: POSITION? might return: MATH1: VERTICAL: POSITION -1.3000E+00 indicating that the current position of Math 1 is 1.3 divisions

below the center graticule.

### MATH[1]:VERTical:SCAle

Sets or returns the vertical scale of the currently selected math type.

**Group** Math

Syntax MATH[1]:VERTical:SCAle <NR3>

MATH[1]:VERTical:SCAle?

**Related Commands** CH<x>:SCAle, REF<x>:VERTical:SCAle

**Arguments** <NR3> is the scale-per-division in the current math vertical units. The range is

from 1.0E-12 through 500.0E+12.

**Examples** MATH1: VERTICAL: SCALE 100E-03 sets the Math scale to 100 mV per division.

MATH: VERTICAL: SCALE? might return : MATH: VERTICAL: SCALE

1.0000E+00 indicating that the current scale setting of Math is 1 V per division.

## MATH[1]:VERTical:UNIts

Returns the math waveform vertical measurement unit value.

**Group** Math

**Syntax** MATH[1]:VERTical:UNIts?

**Examples** MATH: VERTICAL: UNITS? might return MATH: VERTICAL: UNITS "joules"

indicating that the math vertical unit label for unknown values is joules.

## MATHVAR? (Query Only)

Queries both numerical values you can use within math expressions.

**Group** Math

Syntax MATHVAR?

**Related Commands** MATHVAR:VAR<x>, MATH[1]:DEFine

**Returns** <NR3> are the stored numerical values.

**Examples** MATHVAR? returns the values of all variables stored in locations 1 through 2.

#### MATHVAR: VAR<x>

Sets or returns one of two different numerical values you can use within math expressions. These values can range from -10.0e-18 to 1.0e+15; the default values are 0.0. <x> specifies the location, 1 or 2, in which you can store values. Stored math variables can be referenced within math expressions as VAR1 and VAR2.

For example, the following command defines MATH1 as the product of Channel 1 and math variable 1: MATH1:DEFINE "CH1 \* VAR1".

**Group** Math

Syntax MATHVAR: VAR<x> <NR3>

MATHVAR: VAR<x>?

**Related Commands** MATHVAR:VAR<x>, MATH[1]:DEFine

**Arguments**  $\langle NR3 \rangle$  specifies the numerical value to be stored in location x <1 through 2>.

**Examples** MATHVAR: VAR2 -2.43E-5 stores the value -2.43e-5 in the second math variable

location.

MATHVAR: VAR2? might return : MATHVAR: VAR2 24.3000E-6 for the

expression stored in location 2.

### **MEASUrement? (Query Only)**

Returns all measurement parameters.

32;:MEASUREMENT:GATING SCREEN.

**Group** Measurement

**Syntax** MEASUrement?

#### **Examples**

MEASUREMENT? might return : MEASUREMENT: IMMED: DELAY: DIRECTION FORWARDS; EDGE1 RISE; EDGE2 RISE; :MEASUREMENT: IMMED: TYPE PERIOD; UNITS "s"; SOURCE1 CH1; SOURCE2 CH2;:MEASUREMENT:MEAS1:DELAY:DIRECTION FORWARDS;EDGE1 RISE; EDGE2 RISE; : MEASUREMENT: MEAS1: STATE 1; TYPE FREQUENCY; UNITS "Hz"; SOURCE1 CH1; SOURCE2 CH2; COUNT 0; MAXIMUM 0.0000; MEAN 0.0000; MINIMUM 0.0 000; STDDEV 0.0000;:MEASUREMENT:MEAS2:DELAY:DIRECTION FORWARDS;EDGE1 RISE; EDGE2 RISE; : MEASUREMENT: MEAS2: STATE 1; TYPE PERIOD; UNITS "s"; SOURCE1 CH1; SOURCE2 CH2; COUNT 0; MAXIMUM 0.0000; MEAN 0.0000; MINIMUM 0.0000; STDDEV 0.0000; :MEASUREMENT: MEAS3: DELAY: DIRECTION FORWARDS; EDGE1 RISE; EDGE2 RISE;:MEASUREMENT:MEAS3:STATE 1;TYPE PK2PK;UNITS "V";SOURCE1 CH1; SOURCE2 CH2; COUNT 0; MAXIMUM 0.0000; MEAN 0.0000; MINIMUM 0.0000; STDDEV 0.0000; :MEASUREMENT: MEAS4: DELAY: DIRECTION FORWARDS; EDGE1 RISE; EDGE2 RISE; :MEASUREMENT: MEAS4: STATE 0; TYPE PERIOD; UNITS "s"; SOURCE1 CH1; SOURCE2 CH2; COUNT 0; MAXIMUM 0.0000; MEAN 0.0000; MINIMUM 0.0000; STDDEV 0.0000;:MEASUREMENT:METHOD AUTO;REFLEVEL:METHOD PERCENT; ABSOLUTE: HIGH 0.0000; LOW 0.0000; MID1 0.0000;MID2 0.0000;:MEASUREMENT:REFLEVEL:PERCENT:HIGH 90.0000;LOW 10.0000;MID1 50.0000;MID2 50.0000;:MEASUREMENT:INDICATORS:STATE OFF; NUMHORZ 0; NUMVERT 0; HORZ1 99.0000E +36; HORZ2 99.0000E+36;HORZ3 99.0000E+36;HORZ4 99.0000E+36;VERT1 99.0000E+36; VERT2 99.0000E+36; VERT3 99.0000E+36; VERT4 99.0000E+36;:MEASUREMENT:STATISTICS:MODE OFF;WEIGHTING

### **MEASUrement:CLEARSNapshot (No Query Form)**

Removes the measurement snapshot display.

**Group** Measurement

Syntax MEASUrement:CLEARSNapshot

Related Commands CLEARMenu

## **MEASUrement: GATing**

Specifies or returns the measurement gating setting.

**Group** Measurement

Syntax MEASUrement:GATing {OFF|SCREen|CURSor}

MEASUrement:GATing?

**Arguments** OFF turns off measurement gating (full record).

SCREen turns on gating, using the left and right edges of the screen.

CURSor limits measurements to the portion of the waveform between the vertical

bar cursors, even if they are off screen.

**Examples** MEASUREMENT: GATING CURSOR turns on measurement gating using the cursors

as limits.

MEASUREMENT: GATING? might return: MEASUREMENT: GATING CURSOR indicating that measurements are limited to the portion of the waveform between

the vertical bar cursors.

## MEASUrement: IMMed? (Query Only)

Returns all immediate measurement setup parameters.

**Group** Measurement

**Syntax** MEASUrement:IMMed?

**Examples** MEASUREMENT: IMMED? might return

:MEASUREMENT:IMMED:DELAY:DIRECTION FORWARDS;EDGE1 RISE;EDGE2

RISE;:MEASUREMENT:IMMED:TYPE PERIOD;UNITS "s";SOURCE1

CH1; SOURCE2 CH2

### MEASUrement:IMMed:DELay? (Query Only)

Returns information about the immediate delay measurement. This command is equivalent to viewing the delay measurement settings on the measurement readout.

**Group** Measurement

**Syntax** MEASUrement:IMMed:DELay?

**Examples** MEASUREMENT: IMMED: DELAY? might return

:MEASUREMENT:IMMED:DELAY:DIRECTION FORWARDS; EDGE1

RISE; EDGE2 RISE

### MEASUrement:IMMed:DELay:DIRection

Sets or returns the starting point and direction that determines the delay "to" edge when taking an immediate delay measurement.

**NOTE.** Use the MEASUrement:IMMed:SOUrce<x> command to specify the delay "to" waveform.

**Group** Measurement

**Syntax** MEASUrement:IMMed:DELay:DIRection {BACKWards|FORWards}

MEASUrement:IMMed:DELay:DIRection?

Related Commands MEASUrement:IMMed:SOUrce<x>

**Arguments** BACKwards starts the search at the end of the waveform and looks for the last

rising or falling edge in the waveform.

FORwards starts the search at the beginning of the waveform and looks for the

first rising or falling edge in the waveform.

#### **Examples**

MEASUREMENT: IMMED: DELAY: DIRECTION FORWARDS starts searching from the beginning of the waveform record and looks for the first rising or falling edge.

MEASUREMENT: IMMED: DELAY: DIRECTION? might return

:MEASUREMENT:IMMED:DELAY:DIRECTION BACKWARDS indicating

that searching begins at the end of the waveform record and looks for the last

rising or falling edge.

### MEASUrement:IMMed:DELay:EDGE<x>

Sets or returns the slope of the edge the oscilloscope uses for the delay "from" or "to" waveform when taking an immediate delay measurement.

**Group** Measurement

Syntax MEASUrement:IMMed:DELay:EDGE<x> {FALL|RISe}

MEASUrement:IMMed:DELay:EDGE<x>?

Related Commands MEASUrement:IMMed:SOUrce<x>

**Arguments**  $\langle x \rangle$  specifies which waveform to use, where  $\langle x \rangle = 1$  is the "from" waveform, and

 $\langle x \rangle = 2$  is the "to" waveform.

FALL specifies the falling edge.

RISe specifies the rising edge.

**Examples** MEASUREMENT: IMMED: DELAY: EDGE1 RISE specifies that the "from" waveform

rising edge be used for the immediate delay measurement.

MEASUREMENT: IMMED: DELAY: EDGE1? returns either RISE or FALL.

#### MEASUrement:IMMed:SOUrce<x>

For SOURce1: Sets or returns the source for all single channel measurements. For delay or phase measurements, sets or returns the waveform to measure "from".

For SOUrce2: Sets or returns the waveform to measure "to" when taking a delay measurement or phase measurement.

**NOTE.** If you do not specify a numerical suffix, the source is assumed to be SOUrce1.

**Group** Measurement

Syntax MEASUrement:IMMed:SOUrce<x>

{CH1|CH2|CH3|CH4|MATH|D<x>|HIStogram}

MEASUrement:IMMed:SOUrce<x>?

**Arguments** CH1-CH4 or MATH is the source waveform.

MATH is the math waveform.

D<X> is a digital waveform. The x variable can be expressed as an integer, where x is the digital channel number. Digital channels are available only on MSO models.

HIStogram indicates the histogram as the object to be measured. HIStogram only applies to SOUrce1; it is not available for SOUrce2.

#### MEASUrement: IMMed: TYPe

Sets or returns the immediate measurement type.

Digital channel measurements do not have a user-settable midRef threshold. If you specify a digital channel measurement that is not available on MSO models, measurement error 2200: measurement system error occurs and 9.9e37 is returned.

**Group** Measurement

**Syntax** MEASUrement:IMMed:TYPe

{AMPlitude|AREa|BURst|CARea|CMEan|CRMs|DELay|FALL|FREQuency

| HIGH| HITS| LOW | MAXimum | MEAN | MEDian | MINImum | NDUty | NEDGECount | NOVershoot

|NPULSECount|NWIdth|PEAKHits|PEDGECount|PDUty

| PERIOd | PHASe | PK2Pk | POVershoot | PPULSECount | PWIdth | RISe | RMS

|SIGMA1|SIGMA2|SIGMA3|STDdev|WAVEFORMS}

MEASUrement: IMMed: TYPe?

#### Arguments

AMPlitude measures the amplitude of the selected waveform. In other words, it measures the high value less the low value measured over the entire waveform or gated region. This measurement is applicable only to the analog channels.

Amplitude = High - Low

AREa measures the voltage over time. The area is over the entire waveform or gated region and is measured in volt-seconds. The area measured above the ground is positive, while the area below ground is negative. This measurement is applicable only to the analog channels.

BURST measures the duration of a burst. The measurement is made over the entire waveform or gated region.

CARea (cycle area) measures the voltage over time. In other words, it measures, in volt-seconds, the area over the first cycle in the waveform or the first cycle in the gated region. The area measured above the common reference point is positive, while the area below the common reference point is negative. This measurement is applicable only to the analog channels.

CMEan (cycle mean) measures the arithmetic mean over the first cycle in the waveform or the first cycle in the gated region. This measurement is applicable only to the analog channels.

CRMs (cycle rms) measures the true Root Mean Square voltage over the first cycle in the waveform or the first cycle in the gated region. This measurement is applicable only to the analog channels.

DELay measures the time between the middle reference (default = 50%) amplitude point of the source waveform and the destination waveform.

FALL measures the time taken for the falling edge of the first pulse in the waveform or gated region to fall from a high reference value (default is 90%) to a low reference value (default is 10%). This measurement is applicable only to the analog channels.

FREQuency measures the first cycle in the waveform or gated region. Frequency is the reciprocal of the period and is measured in hertz (Hz), where 1 Hz = 1 cycle per second.

HIGH measures the High reference (100% level, sometimes called Topline) of a waveform. This measurement is applicable only to the analog channels.

HITS (histogram hits) measures the number of points in or on the histogram box.

LOW measures the Low reference (0% level, sometimes called Baseline) of a waveform. This measurement is applicable only to the analog channels.

MAXimum finds the maximum amplitude. This value is the most positive peak voltage found. It is measured over the entire waveform or gated region. This measurement is applicable only to the analog channels.

MEAN amplitude measurement finds the arithmetic mean over the entire waveform or gated region. This measurement is applicable only to the analog channels.

MEDian (histogram measurement) measures the middle point of the histogram box. Half of all acquired points within or on the histogram box are less than this value and half are greater than this value.

MINImum finds the minimum amplitude. This value is typically the most negative peak voltage. It is measured over the entire waveform or gated region. This measurement is applicable only to the analog channels.

NDUty (negative duty cycle) is the ratio of the negative pulse width to the signal period, expressed as a percentage. The duty cycle is measured on the first cycle in the waveform or gated region.

```
Negative Duty Cycle = ((Negative\ Width) / Period) \times 100\%
```

NEDGECount is the count of falling edges.

**NOVershoot** (negative overshoot) finds the negative overshoot value over the entire waveform or gated region. This measurement is applicable only to the analog channels.

```
Negative\ Overshoot = ((Low - Minimum) / Amplitude) \times 100\%)
```

NPULSECount is the count of negative pulses.

NWIdth (negative width) measurement is the distance (time) between the middle reference (default = 50%) amplitude points of a negative pulse. The measurement is made on the first pulse in the waveform or gated region.

PEAKHits measures the number of points in the largest bin of the histogram.

PDUty (positive duty cycle) is the ratio of the positive pulse width to the signal period, expressed as a percentage. It is measured on the first cycle in the waveform or gated region.

```
Positive Duty Cycle = ((Positive\ Width)/Period) \times 100\%
```

PEDGECount is the count of rising edges.

PERIod is the time required to complete the first cycle in a waveform or gated region. Period is the reciprocal of frequency and is measured in seconds.

PHAse measures the phase difference (amount of time a waveform leads or lags the reference waveform) between two waveforms. The measurement is made between the middle reference points of the two waveforms and is expressed in degrees, where 360° represents one waveform cycle.

PK2Pk (peak-to-peak) finds the absolute difference between the maximum and minimum amplitude in the entire waveform or gated region. This measurement is applicable only to the analog channels.

**POVershoot** is the positive overshoot value over the entire waveform or gated region. This measurement is applicable only to the analog channels.

```
Positive Overshoot = ((Maximum - High) / Amplitude) \times 100\%
```

PPULSECount is the count of positive pulses.

PWIdth (positive width) is the distance (time) between the middle reference (default = 50%) amplitude points of a positive pulse. The measurement is made on the first pulse in the waveform or gated region.

RISe timing measurement finds the rise time of the waveform. The rise time is the time it takes for the leading edge of the first pulse encountered to rise from a

low reference value (default is 10%) to a high reference value (default is 90%). This measurement is applicable only to the analog channels.

RMS amplitude measurement finds the true Root Mean Square voltage in the entire waveform or gated region. This measurement is applicable only to the analog channels.

SIGMA1 (histogram measurement) measures the percentage of points in the histogram that are within one standard deviation of the histogram mean.

SIGMA2 (histogram measurement) measures the percentage of points in the histogram that are within two standard deviations of the histogram mean.

SIGMA3 (histogram measurement) measures the percentage of points in the histogram that are within three standard deviations of the histogram mean.

STDdev measures the standard deviation (Root Mean Square (RMS) deviation) of all acquired points within or on the histogram box.

WAVEFORMS (waveform count) measures the number of waveforms used to calculate the histogram.

#### **Examples**

MEASUREMENT: IMMED: TYPE FREQUENCY defines the immediate measurement to be a frequency measurement.

MEASUREMENT: IMMED: TYPE? might return: MEASUREMENT: IMMED: TYPE RMS indicating that the immediate measurement is the true Root Mean Square voltage.

### MEASUrement: IMMed: UNIts? (Query Only)

Returns a string containing the units of the immediate measurement.

**Group** Measurement

**Syntax** MEASUrement:IMMed:UNIts?

**Returns** This query returns one of the following strings.

Unit string	Description
"%"	percent
"/Hz"	inverse hertz
"?"	indeterminate
"A"	amperes
"A/A"	amperes per ampere
"A/V"	amperes per volt

Unit string	Description
"A/W"	ampere per watt
"A/dB"	amperes per decibel
"A/s"	amperes per second
"AA"	amperes squared
"AW"	ampere-watts
"AdB"	ampere-decibels
"As"	ampere-seconds
"B"	bytes
"Hz"	hertz
"IRE"	Institute of Radio Engineers units
"S/s"	samples per second
"V"	volts
"V/A"	volts per ampere
"V/V"	volts per volt
"V/W"	volts per watt
"V/dB"	volts per decibel
"V/s"	volts per second
"VA"	volt-amperes
"VAR"	volt-amperes resistive
"VV"	volts squared
"VW"	volt-watts
"VdB"	volts-decibels
"Vs"	volt-seconds
"W"	watts
"W/A"	watts per ampere
"W/V"	watts per volt
"W/W"	watts per watt
"W/dB"	watt per decibel
"W/s"	watts per second
"WA"	watt-amperes
"WV"	watt-volts
"WW"	watts squared
"WdB"	watt-decibels
"Wfms"	waveforms
"Ws"	watt-seconds
"dB"	decibels
"dB/A"	decibels per ampere
"dB/V"	decibels per volt

Unit string	Description
"dB/W"	decibels per watt
"dB/dB"	decibels per decibel
"dBA"	decibel-amperes
"dBV"	decibel-volts
"dBW"	decibel-watts
"dBdB"	decibels squared
"day"	days
"degrees"	degrees
"div"	divisions
"edges"	edges
"hits"	hits
"hr"	hours
"joules"	joules
"min"	minutes
"ohms"	ohms
"percent"	percent
"pulses"	pulses
"s"	seconds
"unk"	unknown

#### **Examples**

MEASUREMENT: IMMED: UNITS? might return

:MEASUREMENT:IMMED:UNIts "s"

indicating that units for the immediate measurement are in seconds.

## MEASUrement:IMMed:VALue? (Query Only)

Returns the value of the measurement specified by the MEASUrement:IMMed: TYPe command. The measurement is immediately taken on the source(s) specified by a MEASUrement:IMMed:SOUrce<x> command.

**NOTE.** A change to HORizontal:MAIn:SCALe or CH<x>:SCALe will not necessarily have taken affect if immediately followed by this command.

**Group** Measurement

Syntax MEASUrement:IMMed:VALue?

**Related Commands** MEASUrement:IMMed:TYPe, MEASUrement:IMMed:SOUrce<x>, \*ESR?,

ALLEv?

**Examples** MEASUREMENT: IMMED: VALUE? might return: MEASUREMENT: IMMED: VALUE

9.9000E+37. If the measurement has an error or warning associated with it, then an item is added to the error queue. The error can be checked for with the

\*ESR? and ALLEv? commands.

## **MEASUrement:INDICators? (Query Only)**

Returns all measurement indicator parameters.

**Group** Measurement

**Syntax** MEASUrement:INDICators?

**Examples** MEASUREMENT: INDICATORS? might return

MEASUREMENT:INDICATORS:STATE MEAS1;NUMHORZ 0;NUMVERT 4;HORZ1 7.5E0;HORZ2 -3.400000095367E0;HORZ3 0.0E0;HORZ4 0.0E0;VERT1

-6.351123E-6; VERT2 -3.179753E-6; VERT3 -6.40943E-6; VERT4

-6.403E-6

## MEASUrement:INDICators:HORZ<x>? (Query Only)

Returns the position of the specified horizontal measurement indicator  $\langle x \rangle$ , where  $\langle x \rangle$  can be 1, 2, 3, or 4.

**Group** Measurement

Syntax MEASUrement:INDICators:HORZ<x>?

**Examples** MEASUREMENT: INDICATORS: HORZ1? might return

MEASUREMENT: INDICATORS: HORZ1 -2.0E-3 indicating that horizontal

indicator1 has a value of -2mV.

## MEASUrement:INDICators:NUMHORZ? (Query Only)

Returns the number of horizontal measurement indicators currently being displayed.

**Group** Measurement

Syntax MEASUrement:INDICators:NUMHORZ?

**Examples** MEASUREMENT: INDICATORS: NUMHORZ? might return

MEASUREMENT: INDICATORS: NUMHORZ 2 indicating there are currently 2 horizontal lines drawn on the graticule. The indicators show where the measurement specified by MEASUrement:INDICators:STATE is being

performed.

## MEASUrement:INDICators:NUMVERT? (Query Only)

Returns the number of vertical measurement indicators currently being displayed.

**Group** Measurement

Syntax MEASUrement:INDICators:NUMVERT?

**Examples** MEASUREMENT: INDICATORS: NUMVERT? might return

MEASUREMENT: INDICATORS: NUMVERT 2 indicating there are currently 2 vertical lines drawn on the graticule. The indicators show where the measurement

specified by MEASUrement:INDICators:STATE is being performed.

#### MEASUrement: INDICators: STATE

Sets or returns the state of visible measurement indicators.

**Group** Measurement

Syntax MEASUrement:INDICators:STATE {OFF|MEAS<x>}

MEASUrement:INDICators:STATE?

**Arguments** OFF turns the visible measurement indicators off.

MEAS<x> displays the visible measurement indicators for measurement <x>,

where  $\langle x \rangle$  can be 1 through 8.

**NOTE.** There must be an active measurement before you can activate an indicator for a specified measurement.

**Examples** MEASUREMENT: INDICATORS: STATE MEAS2 turns on the display of visible

measurement indicators for measurement 2.

MEASUREMENT: INDICATORS: STATE? might return

MEASUREMENT: INDICATORS: STATE OFF indicating that no measurement

indicators are active.

## MEASUrement:INDICators:VERT<x>? (Query Only)

Returns the value of the specified vertical measurement indicator  $\langle x \rangle$  from the trigger point, where  $\langle x \rangle$  can be 1 through 8. A negative value means that the indicator is positioned earlier in the waveform record than the trigger point.

**Group** Measurement

Syntax MEASUrement:INDICators:VERT<x>?

**Examples** MEASUREMENT:INDICATORS:VERT2? might return

MEASUREMENT: INDICATORS: VERT2 -3.724507E-6 indicating that the second measurement indicator is positioned 3.72 μs before the trigger point.

## **MEASUrement:MEAS<x>? (Query Only)**

Returns all measurement parameters for the specified active measurement <x>.

**Group** Measurement

Syntax MEASUrement:MEAS<x>?

## MEASUrement:MEAS<x>:COUNt? (Query Only)

Returns the number of values accumulated for this measurement since the last statistical reset. Values may be ignored if they generated an error. Measurements are specified by x, which ranges from 1 through 8.

**Group** Measurement

**Syntax** MEASUrement:MEAS<x>:COUNt?

**Examples** MEASUREMENT: MEAS3: COUNT? might return: MEASUREMENT: MEAS3: COUNT

3247.

### MEASUrement:MEAS<x>:DELay? (Query Only)

Returns the delay measurement parameters for the measurement specified by  $\langle x \rangle$ , which ranges from 1 through 8.

**Group** Measurement

**Syntax** MEASUrement:MEAS<x>:DELay?

**Examples** MEASUREMENT: MEAS1? might return

:MEASUREMENT:MEAS1:DELAY:DIRECTION FORWARDS; EDGE1 RISE; EDGE2

RISE.

## MEASUrement:MEAS<x>:DELay:DIRection

Sets or returns the starting point and direction that determines the delay "to" edge when taking a delay measurement. Use the MEASUrement:MEAS<x>: SOUrce<x> command to specify the waveform.

**Group** Measurement

**Syntax** MEASUrement:MEAS<x>:DELay:DIRection {BACKWards|FORWards}

MEASUrement:MEAS<x>:DELay:DIRection?

Related Commands MEASUrement:MEAS<x>:SOUrce<x>

**Arguments** BACKWards means the search starts at the end of the waveform and looks for the last rising or falling edge in the waveform. Use the

MEASUrement:MEAS<x>:DELay:EDGE<x> command to specify the slope

of the edge.

FORWards means the search starts at the beginning of the waveform and looks for the first rising or falling edge in the waveform. Use the MEASUrement:MEAS<x>:DELay:EDGE<x> command to specify the slope

of the edge.

**Examples** MEASUREMENT: MEAS3: DELAY: DIRECTION BACKWARDS starts searching from

the end of the waveform record.

MEASUREMENT: MEAS3: DELAY: DIRECTION? might return

:MEASUREMENT:MEAS3:DELAY:DIRECTION BACKWARDS indicating

that the current search direction is backwards.

## MEASUrement:MEAS<x>:DELay:EDGE<x>

Sets or returns the slope of the edge used for the delay "from" or "to" waveform when taking an immediate delay measurement. The waveform is specified by MEASUrement:MEAS<x>:SOUrce<x>.

**Group** Measurement

Syntax MEASUrement:MEAS<x>:DELay:EDGE<x> {FALL|RISe}

MEASUrement:MEAS<x>:DELay:EDGE<x>?

**Arguments**  $\langle x \rangle$  specifies which waveform to use, where  $\langle x \rangle = 1$  is the "from" waveform, and

 $\langle x \rangle = 2$  is the "to" waveform.

FALL specifies the falling edge.

RISe specifies the rising edge.

**Examples** MEASUREMENT: MEAS1: DELAY: EDGE1 RISE specifies that the "from" waveform

rising edge be used for the immediate delay measurement.

MEASUREMENT: MEAS1: DELAY: EDGE1? returns either RISE or FALL.

### MEASUrement:MEAS<x>:MAXimum? (Query Only)

Returns the maximum value found for this measurement since the last statistical reset. Measurements are specified by x, which ranges from 1 through 8.

**Group** Measurement

Syntax MEASUrement:MEAS<x>:MAXimum?

**Examples** MEASUREMENT: MEAS3: MAXIMUM? might return

:MEASUREMENT:MEAS3:MAXIMUM 4.18E-9.

### MEASUrement: MEAS<x>: MEAN? (Query Only)

Returns the mean value accumulated for this measurement since the last statistical reset. Measurements are specified by x, which ranges from 1 through 8.

**Group** Measurement

**Syntax** MEASUrement:MEAS<x>:MEAN?

**Examples** MEASUREMENT:MEAS1:MEAN? might return :MEASUREMENT:MEAS1:MEAN

514.71E-09.

### MEASUrement:MEAS<x>:MINImum? (Query Only)

Returns the minimum value for this measurement since the last statistical reset. Measurements are specified by  $\langle x \rangle$ , which ranges from 1 through 8.

**Group** Measurement

Syntax MEASUrement:MEAS<x>:MINImum?

**Examples** MEASUREMENT: MEAS1: MINIMUM? might return

:MEASUREMENT:MEAS1:MINIMUM 1.75E-09.

#### MEASUrement:MEAS<x>:SOUrce<x>

For SOURce1: Sets or returns the source for all single channel measurements. For delay or phase measurements, sets or returns the waveform to measure "from".

For SOUrce2: Sets or returns the waveform to measure "to" when taking a delay measurement or phase measurement.

Measurements are specified by  $\langle x \rangle$ , which ranges from 1 to 8.

**NOTE.** If you do not specify a numeric suffix, the source is assumed to be SOUrce1.

**Group** Measurement

Syntax MEASUrement:MEAS<x>:SOUrce<x> {CH<x>|MATH|D<x>|HIStogram}

MEASUrement:MEAS<x>:SOUrce<x>?

#### Related Commands MEASUrement:MEAS<x>:TYPe

**Arguments** CH<x> is an input channel waveform, where x is the channel number.

MATH is the math waveform.

REF<x> is a reference waveform, where x is the reference channel number.

D<x> is a digital waveform, where x is the digital channel number. Digital

channels are available only on MSO models.

HIStogram indicates the histogram is the object to be measured. HIStogram only

applies to SOUrce1; it is not allowed on SOUrce2.

**Examples** MEASUREMENT: MEAS4: SOURCE2 CH1 specifies CH1 as the delay "to" source

when making delay measurement.

MEASUREMENT: MEAS2: SOURCE2? might return

:MEASUREMENT:MEAS2:SOURCE2 MATH1 indicating that Math 1 is the

measurement 2 source.

#### MEASUrement:MEAS<x>:STATE

Sets or returns whether the specified measurement slot is computed and displayed. The measurement slot is specified by  $\langle x \rangle$ , which ranges from 1 through 8.

For a measurement to display, you must have selected a source waveform and defined the measurement you want to take and display. You select the measurement using the MEASUrement:MEAS<x>:SOUrce<x> command. You define the measurement type using the MEASUrement:MEAS<x>:TYPe command.

**Group** Measurement

Syntax MEASUrement:MEAS<x>:STATE {OFF|ON|<NR1>}

MEASUrement: MEAS<x>: STATE?

**Related Commands** MEASUrement:MEAS<x>:SOUrce<x>, MEASUrement:MEAS<x>:TYPe

**Arguments** OFF disables calculation and display of the specified measurement slot.

ON enables calculation and display of the specified measurement slot.

<NR1> = 0 disables calculation and display of the specified measurement slot; any other value enables calculation and display of the specified measurement slot.

**Examples** 

MEASUREMENT: MEAS2: STATE ON computes and displays the measurement defined as measurement 2.

MEASUREMENT: MEAS1: STATE? might return: MEASUREMENT: MEAS1: STATE 0 indicating that measurement defined for measurement slot 1 is disabled.

### MEASUrement:MEAS<x>:STDdev? (Query Only)

Returns the standard deviation of values accumulated for this measurement since the last statistical reset. Measurements are specified by <x>, the measurement slots, from 1 through 8.

Measurement Group

**Syntax** MEASUrement:MEAS<x>:STDdev?

MEASUREMENT: MEAS1: STDDEV? might return: MEASUREMENT: MEAS1: STDDEV **Examples** 

21.0E-12.

#### MEASUrement:MEAS<x>:TYPe

Sets or returns the measurement type defined for the specified measurement slot. The measurement slot is specified by  $\langle x \rangle$ , which ranges from 1 through 8.

Digital channel measurements do not have a user-settable midRef threshold. If you specify a digital channel measurement that is not available on MSO models, measurement error 2200: measurement system error occurs and 9.9e37 is returned.

Group Measurement

MEASUrement:MEAS<x>:TYPe **Syntax** 

{AMPlitude|AREa|BURst|CARea|CMEan|CRMs|DELay|FALL|FREQuency

|HIGH|HITS|LOW|MAXimum|MEAN|MEDian|MINImum|NDUty|NEDGECount|NOVersho

|NPULSECount|NWIdth|PEAKHits|PDUty|PEDGECount|PERIOd|PHAse|PK2Pk

| POVershoot | PPULSECount | PWIdth | RISe | RMS |SIGMA1|SIGMA2|SIGMA3|STDdev|WAVEFORMS}

MEASUrement:MEAS<x>:TYPe?

#### **Arguments**

AMPlitude measures the amplitude of the selected waveform. In other words, it measures the high value less the low value measured over the entire waveform or gated region. This measurement is applicable only to the analog channels.

Amplitude = High - Low

AREa measures the voltage over time. The area is over the entire waveform or gated region and is measured in volt-seconds. The area measured above the ground is positive, while the area below ground is negative. This measurement is applicable only to the analog channels.

BURST measures the duration of a burst. The measurement is made over the entire waveform or gated region.

CARea (cycle area) measures the voltage over time. In other words, it measures, in volt-seconds, the area over the first cycle in the waveform or the first cycle in the gated region. The area measured above the common reference point is positive, while the area below the common reference point is negative. This measurement is applicable only to the analog channels.

CMEan (cycle mean) measures the arithmetic mean over the first cycle in the waveform or the first cycle in the gated region. This measurement is applicable only to the analog channels.

CRMs (cycle rms) measures the true Root Mean Square voltage over the first cycle in the waveform or the first cycle in the gated region. This measurement is applicable only to the analog channels.

DELay measures the time between the middle reference (default = 50%) amplitude point of the source waveform and the destination waveform. This measurement is applicable only to the analog channels.

FALL measures the time taken for the falling edge of the first pulse in the waveform or gated region to fall from a high reference value (default is 90%) to a low reference value (default is 10%). This measurement is applicable only to the analog channels.

FREQuency measures the first cycle in the waveform or gated region. Frequency is the reciprocal of the period and is measured in hertz (Hz), where 1 Hz = 1 cycle per second.

HIGH measures the High reference (100% level, sometimes called Topline) of a waveform. This measurement is applicable only to the analog channels.

HITS (histogram hits) measures the number of points in or on the histogram box.

LOW measures the Low reference (0% level, sometimes called Baseline) of a waveform. This measurement is applicable only to the analog channels.

MAXimum finds the maximum amplitude. This value is the most positive peak voltage found. It is measured over the entire waveform or gated region. This measurement is applicable only to the analog channels.

MEAN amplitude measurement finds the arithmetic mean over the entire waveform or gated region. This measurement is applicable only to the analog channels.

MEDi an (histogram measurement) measures the middle point of the histogram box. Half of all acquired points within or on the histogram box are less than this value and half are greater than this value.

MINImum finds the minimum amplitude. This value is typically the most negative peak voltage. It is measured over the entire waveform or gated region. This measurement is applicable only to the analog channels.

NDUty (negative duty cycle) is the ratio of the negative pulse width to the signal period, expressed as a percentage. The duty cycle is measured on the first cycle in the waveform or gated region.

```
Negative Duty Cycle = ((Negative\ Width)/Period) \times 100\%
```

NEDGECount is the count of negative edges.

**NOVershoot** (negative overshoot) finds the negative overshoot value over the entire waveform or gated region. This measurement is applicable only to the analog channels.

```
Negative\ Overshoot = ((Low - Minimum) / Amplitude) \times 100\%)
```

NPULSECount is the count of negative pulses.

NWIdth (negative width) measurement is the distance (time) between the middle reference (default = 50%) amplitude points of a negative pulse. The measurement is made on the first pulse in the waveform or gated region.

PEAKHits measures the number of points in the largest bin of the histogram.

PDUty (positive duty cycle) is the ratio of the positive pulse width to the signal period, expressed as a percentage. It is measured on the first cycle in the waveform or gated region.

```
Positive Duty Cycle = ((Positive\ Width)/Period) \times 100\%
```

PEDGECount is the count of positive edges.

PERIOD is the time required to complete the first cycle in a waveform or gated region. Period is the reciprocal of frequency and is measured in seconds.

PHAse measures the phase difference (amount of time a waveform leads or lags the reference waveform) between two waveforms. The measurement is made between the middle reference points of the two waveforms and is expressed in degrees, where 360° represents one waveform cycle.

PK2Pk (peak-to-peak) finds the absolute difference between the maximum and minimum amplitude in the entire waveform or gated region. This measurement is applicable only to the analog channels.

**POVershoot** is the positive overshoot value over the entire waveform or gated region. This measurement is applicable only to the analog channels.

Positive Overshoot =  $((Maximum - High) / Amplitude) \times 100\%$ 

PPULSECount is the count of positive pulses.

PWIdth (positive width) is the distance (time) between the middle reference (default = 50%) amplitude points of a positive pulse. The measurement is made on the first pulse in the waveform or gated region.

RISe timing measurement finds the rise time of the waveform. The rise time is the time it takes for the leading edge of the first pulse encountered to rise from a low reference value (default is 10%) to a high reference value (default is 90%). This measurement is applicable only to the analog channels.

RMS amplitude measurement finds the true Root Mean Square voltage in the entire waveform or gated region. This measurement is applicable only to the analog channels.

SIGMA1 (histogram measurement) measures the percentage of points in the histogram that are within one standard deviation of the histogram mean.

SIGMA2 (histogram measurement) measures the percentage of points in the histogram that are within two standard deviations of the histogram mean.

SIGMA3 (histogram measurement) measures the percentage of points in the histogram that are within three standard deviations of the histogram mean.

STDdev measures the standard deviation (Root Mean Square (RMS) deviation) of all acquired points within or on the histogram box.

WAVEFORMS (waveform count) measures the number of waveforms used to calculate the histogram.

#### **Examples**

MEASUREMENT: MEAS2: TYPE FREQUENCY defines measurement 2 as a measurement of the frequency of a waveform.

MEASUREMENT: MEAS1: TYPE? might return: MEASUREMENT: MEAS1: TYPE RMS indicating that measurement 1 is defined to measure the RMS value of a waveform.

# MEASUrement:MEAS<x>:UNIts? (Query Only)

Returns the units associated with the specified measurement. The measurement slots are specified by  $\langle x \rangle$ , which ranges from 1 through 8.

**Group** Measurement

Syntax MEASUrement:MEAS<x>:UNIts?

**Related Commands** MEASUrement:MEAS<x>:TYPe

**Returns** This query returns one of the following strings.

Unit string	Description
"%"	percent
"/Hz"	inverse hertz
"?"	indeterminate
"A"	amperes
"A/A"	amperes per ampere
"A/V"	amperes per volt
"A/W"	ampere per watt
"A/dB"	amperes per decibel
"A/s"	amperes per second
"AA"	amperes squared
"AW"	ampere-watts
"AdB"	ampere-decibels
"As"	ampere-seconds
"B"	bytes
"Hz"	hertz
"IRE"	Institute of Radio Engineers units
"S/s"	samples per second
"V"	volts
"V/A"	volts per ampere
"V/V"	volts per volt
"V/W"	volts per watt
"V/dB"	volts per decibel
"V/s"	volts per second
"VA"	volt-amperes
"VAR"	volt-amperes resistive
"VV"	volts squared
"VW"	volt-watts
"VdB"	volts-decibels
"Vs"	volt-seconds
"W"	watts
"W/A"	watts per ampere
"W/V"	watts per volt
"W/W"	watts per watt
"W/dB"	watt per decibel
"W/s"	watts per second
"WA"	watt-amperes
"WV"	watt-volts
"WW"	watts squared
	·

Unit string	Description
"WdB"	watt-decibels
"Wfms"	waveforms
"Ws"	watt-seconds
"dB"	decibels
"dB/A"	decibels per ampere
"dB/V"	decibels per volt
"dB/W"	decibels per watt
"dB/dB"	decibels per decibel
"dBA"	decibel-amperes
"dBV"	decibel-volts
"dBW"	decibel-watts
"dBdB"	decibels squared
"day"	days
"degrees"	degrees
"div"	divisions
"edges"	edges
"hits"	hits
"hr"	hours
"joules"	joules
"min"	minutes
"ohms"	ohms
"percent"	percent
"pulses"	pulses
"s"	seconds
"unk"	unknown

#### **Examples**

MEASUREMENT: MEAS1: UNITS? might return: MEASUREMENT: MEAS1: UNITS % indicating units for measurement 1 are set to percent.

## MEASUrement:MEAS<x>:VALue? (Query Only)

Returns a calculate value for the measurement specified by <x>, which ranges from 1 through 8.

**NOTE.** This is the same value as displayed on-screen. If measurement statistics are enabled, a new value is calculated with every waveform. In addition, this value is updated approximately every 1/3 second. If you are acquiring a long acquisition record, the oscilloscope may take longer to update.

**Group** Measurement

**Syntax** MEASUrement:MEAS<x>:VALue?

**Related Commands** MEASUrement:MEAS<x>:UNIts?, \*ESR?, ALLEv?

**Examples** MEASUREMENT: MEAS1: VALUE? might return: MEASUREMENT: MEAS1: VALUE

2.8740E-06. If the measurement has an error or warning associated with it, then an item is added to the error queue. The error can be checked for with the

\*ESR? and ALLEv? commands.

#### **MEASUrement: METHod**

Sets or returns the method used to calculate the 0% and 100% reference level.

**Group** Measurement

Syntax MEASUrement:METHod {Auto|HIStogram|MINMax}

MEASUrement: METHod?

**Related Commands** MEASUrement:REFLevel:PERCent:HIGH, MEASUrement:REFLevel:PERCent:

LOW, MEASUrement:REFLevel:PERCent:MID, MEASUrement:REFLevel:

PERCent:MID2

**Arguments** Auto selects the best method for each data set.

HIStogram sets the high and low waveform levels statistically using a histogram

algorithm.

MINMax uses the highest and lowest values of the waveform record. This selection is best for examining waveforms with no large, flat portions of a common value,

such as sine waves and triangle waves.

**Examples** MEASUREMENT: METHOD? might return: MEASUREMENT: METHOD MINMAX

indicating that the reference levels are set to MIN and MAX.

## MEASUrement:REFLevel? (Query Only)

Returns the current reference level parameters.

**Group** Measurement

Syntax MEASUrement:REFLevel?

**Examples** MEASUREMENT: REFLEVEL? might return these reference

level settings :MEASUREMENT:REFLEVEL:METHOD

PERCENT; ABSOLUTE: HIGH 0.0000; LOW 0.0000; MID1 0.0000; MID2 0.0000; MEASUREMENT: REFLEVEL: PERCENT: HIGH 90.0000; LOW

10.0000; MID1 50.0000 ; MID2 50.0000

#### MEASUrement:REFLevel:ABSolute:HIGH

Sets or returns the high reference level, and is the upper reference level when MEASUrement:REFLevel:METHod is set to Absolute. This command affects the results of rise and fall measurements.

**NOTE**. this command affects the associated reference level parameter for all MEASurements: IMMed and the four periodic measurements.

**Group** Measurement

Syntax MEASUrement:REFLevel:ABSolute:HIGH <NR3>

MEASUrement:REFLevel:ABSolute:HIGH?

**Related Commands** MEASUrement:REFLevel:METHod, MEASUrement:IMMed:TYPe,

MEASUrement:MEAS<x>:TYPe

**Arguments** <NR3> is the high reference level, in volts. The default is 0.0 V.

**Examples** MEASUREMENT: REFLEVEL: ABSOLUTE: HIGH 1.71 sets the high reference level

to 1.71 V.

MEASUREMENT: REFLEVEL: ABSOLUTE: HIGH? might return

:MEASUREMENT: REFLEVEL: ABSOLUTE: HIGH 1.7100E+00 indicating that the

absolute high reference level is set to 1.71 V.

### MEASUrement:REFLevel:ABSolute:LOW

Sets or returns the low reference level, and is the lower reference level when MEASUrement; REFLevel; METHod is set to Absolute.

**NOTE**. this command affects the associated reference level parameter for all MEASurements: IMMed and the four periodic measurements.

**Group** Measurement

Syntax MEASUrement:REFLevel:ABSolute:LOW <NR3>

MEASUrement:REFLevel:ABSolute:LOW?

Related Commands MEASUrement:REFLevel:METHod, MEASUrement:IMMed:TYPe,

MEASUrement:MEAS<x>:TYPe

**Arguments** <NR3> is the low reference level, in volts. The default is 0.0 V.

**Examples** MEASUREMENT: REFLEVEL: ABSOLUTE: LOW 0.0 sets the low reference level

to 0.0 V.

MEASUREMENT: REFLEVEL: ABSOLUTE: LOW? might return

:MEASUREMENT:REFLEVEL:ABSOLUTE:LOW 0.0000E+00 indicating

that the absolute low reference level is set to 0.0 V.

### MEASUrement:REFLevel:ABSolute:MID[1]

Sets or returns the mid reference level, and is the 50% reference level when MEASUrement:REFLevel:METHod is set to Absolute. This command affects the results of period, frequency, delay, and all cyclic measurements.

**NOTE.** this command affects the associated reference level parameter for all MEASurements: IMMed and the four periodic measurements.

**Group** Measurement

Syntax MEASUrement:REFLevel:ABSolute:MID[1] <NR3>

MEASUrement:REFLevel:ABSolute:MID[1]?

Related Commands MEASUrement: REFLevel: METHod

**Arguments** <NR3> is the mid reference level, in volts. The default is 0.0 V.

**Examples** 

 ${\tt MEASUREMENT:REFLEVEL:ABSOLUTE:MID~1~.71~sets~the~mid~reference~level}$ 

to .71 V.

MEASUREMENT: REFLEVEL: ABSOLUTE: MID? might return

:MEASUREMENT:REFLEVEL:ABSOLUTE:MID 0.7100E+00 indicating

that the absolute mid1 reference level is set to .71 V.

#### MEASUrement:REFLevel:ABSolute:MID2

Sets or returns the mid reference level for the "to" waveform when taking a delay measurement, and is the 50% reference level when MEASUrement:REFLevel:METHod is set to Absolute. This command affects the results of delay measurements.

**NOTE.** this command affects the associated reference level parameter for all MEASurements: IMMed and the four periodic measurements.

Group

Measurement

**Syntax** 

MEASUrement:REFLevel:ABSolute:MID2 <NR3>

MEASUrement:REFLevel:ABSolute:MID2?

**Related Commands** 

MEASUrement:REFLevel:METHod

**Arguments** 

<NR3> is the mid reference level, in volts. The default is 0.0 V.

**Examples** 

MEASUREMENT: REFLEVEL: ABSOLUTE: MID2 0.5 sets the mid reference level for

the delay waveform to 0.5 V.

MEASUREMENT: REFLEVEL: ABSOLUTE: MID2? might return

:MEASUREMENT:REFLEVEL:ABSOLUTE:MID2 0.5000E+00 indicating that the

absolute mid2 reference level is set to 0.5 V.

# MEASUrement:REFLevel:ABSolute:MID<x>

Sets or returns the mid reference level for channel  $\langle x \rangle$ , where x is the measurement channel.

Group

Measurement

Syntax MEASUrement:REFLevel:ABSolute:MID<x> <NR3>

MEASUrement:REFLevel:ABSolute:MID<x>?

**Arguments** <NR3> is the mid reference level in volts.

#### MEASUrement:REFLevel:METHod

Specifies or returns the reference level units used for measurement calculations.

**NOTE.** this command affects the associated reference level parameter for all MEASurements:IMMed and the eight periodic measurements. To change the parameter for individual measurements, use the MEASUrement:MEAS<x>:REFLevel commands.

**Group** Measurement

Syntax MEASUrement:REFLevel:METHod {ABSolute|PERCent}

MEASUrement: REFLevel: METHod?

**Arguments** ABSolute specifies that the reference levels are set explicitly using the

MEASUrement:REFLevel:ABSolute commands. This method is useful when precise values are required (for example, when designing to published interface

specifications, such as RS-232-C).

PERCent specifies that the reference levels are calculated as a percent relative to HIGH and LOW. The percentages are defined using the

MEASUrement: REFLevel: PERCent commands.

**Examples** MEASUREMENT: REFLEVEL: METHOD ABSOLUTE specifies that explicit

user-defined values are used for the reference levels.

MEASUREMENT: REFLEVEL: METHOD? might return

:MEASUREMENT:REFLEVEL:METHOD PERCENT indicating that the reference

level units used are calculated as a percent relative to HIGH and LOW.

## MEASUrement:REFLevel:PERCent:HIGH

Sets or returns the percent (where 100% is equal to HIGH) used to calculate the high reference level when MEASUrement:REFLevel:METHod is set to Percent. This command affects the results of rise and fall measurements.

**NOTE**. This command affects the associated reference level parameter for all MEASurements: IMMed and the four periodic measurements.

**Group** Measurement

Syntax MEASUrement:REFLevel:PERCent:HIGH\_<NR3>

MEASUrement:REFLevel:PERCent:HIGH?

Related Commands MEASUrement:REFLevel:METHod, MEASUrement:IMMed:TYPe,

MEASUrement:MEAS<x>:TYPe

**Arguments** <NR3> is the high reference level, ranging from 0 to 100%. The default high

reference level is 90%.

**Examples** MEASUREMENT: REFLEVEL: PERCENT: HIGH 95 sets the high reference level

to 95% of HIGH.

MEASUREMENT: REFLEVEL: PERCENT: HIGH? might return

:MEASUREMENT:REFLEVEL:PERCENT:HIGH 90 indicating that the

percentage high reference level is set to 90% of HIGH.

#### MEASUrement:REFLevel:PERCent:LOW

Sets or returns the percent (where 100% is equal to HIGH) used to calculate the low reference level when MEASUrement:REFLevel:METHod is set to Percent. This command affects the results of rise and fall measurements.

**NOTE**. this command affects the associated reference level parameter for all MEASurements: IMMed and the four periodic measurements.

**Group** Measurement

Syntax MEASUrement:REFLevel:PERCent:LOW <NR3>

MEASUrement:REFLevel:PERCent:LOW?

Related Commands MEASUrement:REFLevel:METHod, MEASUrement:IMMed:TYPe,

MEASUrement:MEAS<x>:TYPe

**Arguments** <NR3> is the low reference level, ranging from 0 to 100%. The default low

reference level is 10%.

**Examples** MEASUREMENT: REFLEVEL: PERCENT: LOW 15 sets the high reference level to

15% of HIGH.

MEASUREMENT: REFLEVEL: PERCENT: LOW? might return

:MEASUREMENT:REFLEVEL:PERCENT:LOW 10 indicating that the

percentage high reference level is set to 10% of HIGH.

## MEASUrement:REFLevel:PERCent:MID[1]

Sets or returns the percent (where 100% is equal to HIGH) that is used to calculate the mid reference level when MEASUrement:REFLevel:METHod is set to Percent. This command affects the results of period, frequency, delay, and all cyclic measurements.

**NOTE.** this command affects the associated reference level parameter for all MEASurements: IMMed and the four periodic measurements.

**Group** Measurement

Syntax MEASUrement:REFLevel:PERCent:MID[1] <NR3>

MEASUrement:REFLevel:PERCent:MID[1]?

Related Commands MEASUrement: REFLevel: METHod

**Arguments** <NR3> is the mid reference level, ranging from 0 to 100%. The default mid

reference level is 50%.

**Examples** MEASUREMENT: REFLEVEL: PERCENT: MID 1 60 sets the mid reference level

to 60% of HIGH.

MEASUREMENT: REFLEVEL: PERCENT: MID? might return

:MEASUREMENT:REFLEVEL:PERCENT:MID 65 indicating that the

percentage mid reference level is set to 65% of HIGH.

### MEASUrement:REFLevel:PERCent:MID2

Sets or returns the percent (where 100% is equal to HIGH) that is used to calculate the mid reference level for the second waveform specified when

MEASUrement:REFLevel:METHod is set to Percent. This command affects the results of delay measurements.

**NOTE.** this command affects the associated reference level parameter for all MEASurements: IMMed and the four periodic measurements.

**Group** Measurement

Syntax MEASUrement:REFLevel:PERCent:MID2 <NR3>

MEASUrement:REFLevel:PERCent:MID2?

Related Commands MEASUrement:REFLevel:METHod

**Arguments** <NR3> is the mid reference level, ranging from 0 to 100%. The default mid

reference level is 50%.

**Examples** MEASUREMENT: REFLEVEL: PERCENT: MID2 40 sets the mid2 reference level

to 40% of HIGH.

MEASUREMENT: REFLEVEL: PERCENT: MID2? might return

:MEASUREMENT:REFLEVEL:PERCENT:MID2 45 indicating that the

percentage mid2 reference level is set to 45% of HIGH.

### MEASUrement:REFLevel:PERCent:MID<x>

Sets or returns the mid reference level for channel  $\langle x \rangle$ , where x is the measurement channel.

**Group** Measurement

Syntax MEASUrement:REFLevel:PERCent:MID<x> <NR3>

MEASUrement:REFLevel:PERCent:MID<x>?

**Arguments** <NR3> is the mid reference level in percent.

## **MEASUrement:SNAPShot (No Query Form)**

Displays the measurement snapshot list on the oscilloscope screen. The list contains the immediate values for all available measurements of the active signal.

**Group** Measurement

**Syntax** MEASUrement:SNAPShot

## **MEASUrement:STATIstics (No Query Form)**

Clears all of the statistics accumulated for all periodic measurements (MEAS1

through MEAS4).

The query form returns statistic settings.

**Group** Measurement

Syntax MEASUrement:STATIStics RESET

MEASUrement:STATIstics?

**Arguments** RESET clears the measurements.

### MEASUrement:STATIstics:MODE

Controls the operation and display of management statistics.

**Group** Measurement

Syntax MEASUrement:STATIstics:MODE {OFF|ON}

MEASUrement:STATIstics:MODE?

Related Commands MEASUrement: STATIstics

**Arguments** OFF turns all measurements off. This is the default value.

ON turns on statistics and displays all statistics for each measurement.

**Examples** MEASUREMENT: STATISTICS: MODE OFF turns statistic measurements off.

MEASUREMENT: STATISTICS: MODE? might return

:MEASUREMENT:STATISTICS:MODE ON indicating that measurement statistics

are turned on and all statistics are being displayed for each measurement.

## MEASUrement:STATIstics:WEIghting

Sets or returns the time constant for mean and standard deviation statistical accumulations.

**Group** Measurement

Syntax MEASUrement:STATIstics:WEIghting <NR1>

MEASUrement:STATIstics:WEIghting?

Related Commands MEASUrement:STATIstics:MODE

**Arguments** <NR1> is the number of samples used for the mean and standard deviation

statistical accumulations.

**Examples** MEASUREMENT: STATISTICS: WEIGHTING 4 sets statistical weighting to four

samples.

MEASUREMENT: STATISTICS: WEIGHTING? might return : MEASUREMENT: STATISTICS: WEIGHTING 4 indicating that measurement statistics weighting is currently set to 4 samples.

**MESSage** 

This command sets or queries message box (screen annotation) parameters.

**Group** Display

**Syntax** MESSage

MESSage?

**Examples** MESSAGE? might return MESSAGE: SHOW "TP401"; BOX

271,82,292,114; STATE 0 indicating the message parameters.

MESSage:BOX

Sets or returns the co-ordinates of the message box. This command does not

display the message unless MESSage:STATE is on.

X1 and Y1 are the screen coordinates of the top left corner of the message box. X2 and Y2 are the screen coordinates of the bottom right corner of the message box. All four coordinates are returned by the query.

Changing the text in the message box, using the MESSAGE:SHOW command, automatically resizes the message box. If you want a custom message box size, send the MESSAGE:BOX command after changing the text using the MESSAGE:SHOW command.

Message box settings and data are saved and restored in saved setups.

**Group** Display

**Syntax** MESSage: BOX <X1>, <Y1>[, <X2>, <Y2>]

MESSage:BOX?

Related Commands MESSage:STATE, MESSage:SHOW, MESSage:CLEAR

**Arguments** <X1> and <X2> = 0 to 1023, and are pixel positions along the horizontal axis.

<X1> defines the left and <X2> defines the right side of the window.

<Y1> and <Y2> = 0 to 767, and are pixel positions along the vertical axis. <Y1> defines the top and <Y2> defines the bottom of the window. The reserved height of all characters is 16 pixels so the window must be at least that high to fully display characters. <X2> and <Y2> are optional because the MESSAGE: SHOW command automatically sizes the box to fit the message. All four values are returned in a query.

## MESSage:CLEAR (No Query Form)

Clears the contents of the message box.

**Group** Display

Syntax MESSage: CLEAR

**Related Commands** MESSage:BOX, MESSage:SHOW, MESSage:STATE

**Examples** MESSage:CLEAR

removes the message from the message window.

## MESSage:SHOW

Sets or returns the contents of the message box. MESSage:SHOW <Qstring> defines the content of the message box. Change in string length causes automatic resize of the message box to fit the text. The box may be resized using the MESSage:BOX command. The MESSage:STATE command is used to turn on and off the message box display.

**Group** Display

**Syntax** MESSage:SHOW <QString>

MESSage: SHOW?

Related Commands MESSage:BOX, MESSage:CLEAR, MESSage:STATE

Arguments <QString> is the message and can include any of the characters shown in
the Character Set, Appendix A. The maximum length of the message is 1000

characters; the instrument ignores longer strings.

The message box size is set to fit the message. You can also set the message area height and width using the MESSage:BOX command. The length of the message that fits in the message area depends on the contents of the message because the width of characters varies.

If the message exceeds the limits of the message box, either horizontally or vertically, the portion of the message that exceeds the limits will not be displayed. The message string itself is not altered. The entire message can be returned as a query response regardless of what is displayed in the message box.

The message is left-justified, and is displayed on a single line starting with the top most line in the window. A new line character can be embedded in the string to position the message on multiple lines. You can also use white space and tab characters to position the message within a line. Text which does not fit within the message box is truncated. Defining a message box text string erases any previously displayed text within the message box.

You can send a tab by transmitting a tab character ( $\t$  or  $\t$ 09) followed characters representing the most significant eight bits followed by significant eight bits of a 16-bit number. The number specifies the position relative to the left margin of the message area. For example, to tab send TAB ( $\t$  or  $\t$ 09), NUL (decimal 0), and CR (decimal 13).

For example, using hexadecimal escape sequences, MESSAGE:SHOW '\x09\x01\x17Hello' when sent as a command would cause the 'Hello' to be displayed starting at pixel position 279 relative to the left margin set by the MESSAGE:BOX command. If you want to display characters starting at position

279, then 279 = 0x0117; split the hexadecimal number into two characters 0x01 and 0x17 and send x09x01x17.

Special characters which control decoration are two character sequences where the first character is an escape (0x1b) and the second character is as described below.

Bit 7	0	
Bit 6	If set, inverse video is toggled from current state and the following text is displayed in the new inverse state until the state is toggled again. Remaining bits are ignored	
Bit 5	If set, the color index in the four LSB's (bits 0 through 3) is applied to the foreground or background color depending on the fg/bg bit (bit 4).	
Bit 4	If set, color change is applied to the background, otherwise applies to the foreground.	
Bit 0 – 3	Specifies the color index (0 through 15) to change color as specified below:	
	Index 0	Black (background)
	Index 1	Yellow (Ch 1)
	Index 2	Cyan (Ch 2)
	Index 3	Magenta (Ch 3)
	Index 4	Green (Ch 4)
	Index 5	Red (math)
	Index 6	White (reference)
	Index 7	Orange
	Index 8	Gray (Graticule)
	Index 9	White (text)
	Index 10	Tek blue
	Index 11	Bright blue
	Index 12	Undefined
	Index 13	Blue
	Index 14	Undefined
	Index 15	Dark blue
Bit 4	If set, the foreground color is set to the default foreground color.	
Bit 3	If set, the background color is set to the default background color.	
Bit 2	Undefined	
Bit 1	Undefined	
Bit 0	Undefined	

The ESC (escape) character followed by the @ character turns inverse video on or off and can be embedded in the message string. Example: "abcESC@defESC@ghi" specifies the string "abcdefghi" where the "def" portion is displayed in inverse video.

Example: "abcESC#defESC)ESC@ghi" specifies the string "abcdefghi" where the "def" portion appears in the channel 3 color (magenta) and the "ghi" portion appears in the normal text color except it's in inverse video.

An alternate way to enter characters is octal escape sequences. This consists of a backslash followed by numerals in the standard C language printf fashion.

Another way to enter characters is \xnn where the nn is the hexadecimal value of the character to display.

An advantage of these methods is that any controller program can be used. Another advantage is it's easy to access characters with the high bit set, that is, those characters with a decimal value greater than 127.

An alternate way to enter certain characters is with a backslash followed by a single character (following "standard" Unix) as described in the table below.

n	Newline (carriage return and line feed)	
1	Backslash (\\ is required to get a backslash character)	
t	Horizontal tab; the next 2 characters specify the pixel column to tab to as explained earlier	

If a backslash is followed by an undefined special character, the backslash is ignored and the character following it is accepted as is.

**NOTE.** The use of any escape codes other than those described above may produce unpredictable results.

#### **Examples**

MESSage:SHOW "Hello World"

displays "Hello world" in the upper left corner of the box (you can define the box size with the MESSAGE BOX command).

MESSage:SHOW "←@Hello World←@ ... hello"

displays "Hello world ... hello" in the upper left corner of the box and the word "world" is displayed in inverse video. In this example,  $\leftarrow$  stands for the escape character. The escape character may appear differently for you depending on your controller program.

## MESSage:STATE

Controls the display of the message box.

**Group** Display

Syntax MESSage:STATE {OFF|ON|<NR1>}

MESSage: STATE?

Related Commands MESSage:BOX

MESSage:SHOW, MESSage:CLEAR

**Arguments** OFF or <NR1> = 0 removes the message window from the screen.

ON or  $\langle NR1 \rangle \neq 0$  displays the message window and its contents on the screen.

### **NEWpass (No Query Form)**

This command changes the password that enables access to password protected data. The PASSWord command must be successfully executed before using this command or an execution error will be generated.

**Group** Miscellaneous

Syntax NEWpass <QString>

Related Commands \*PUD

**PASSWord** 

**Arguments** <QString> is the new password, which can contain up to 16 characters.

**Examples** NEWPASS "mypassword" creates a new password (mypassword) for accessing

your protected data.

\*OPC

Generates the operation complete message in the Standard Event Status Register (SESR) when all pending commands that generate an OPC message are complete. The \*OPC? query places the ASCII character "1" into the output queue when all such OPC commands are complete. The \*OPC? response is not available to read until all pending operations finish. (See page 3-1, *Status and Events*.)

The \*OPC command allows you to synchronize the operation of the oscilloscope with your application program. (See page 3-7, *Synchronization Methods*.)

Certain oscilloscope operations can affect the \*OPC response. (See Table 3-3 on page 3-7.)

**Group** Status and Error

Syntax \*OPC

\*OPC?

Related Commands BUSY?, \*WAI

**Examples** \*OPC generates the operation complete message in the SESR at the completion of

all pending OPC operations.

\*OPC? might return 1 to indicate that all pending OPC operations are finished.

## PASSWord(No Query Form)

Enables the \*PUD and NEWpass set commands. Sending PASSWord without any arguments disables these same commands. Once the password is successfully entered, the \*PUD and NEWpass commands are enabled until the oscilloscope is powered off, or until the FACtory command or the PASSWord command with no arguments is issued.

To change the password, you must first enter the valid password with the PASSWord command and then change to your new password with the NEWpass command. Remember that the password is case sensitive.

**Group** Miscellaneous

Syntax PASSWord <QString>

Related Commands NEWpass, \*PUD

**Arguments** <QString> is the password and can include up to 10 characters. The factory

default password is "XYZZY" and is always valid.

**Examples** PASSWORD "XYZZY" enables the \*PUD and NEWpass set commands.

PASSWORD disables the \*PUB and NEWpass set commands. You can still use the

query version of \*PUD.

# PICTBridge:DATEPrint

Enables or disables printing the date on the print output

**Group** PictBridge

Syntax PICTBridge:DATEPrint {DEFLT|OFF|ON}

**Arguments** DEFLT is the default setting of the printer.

ON enables the date print on the print output.

OFF disables the date print on the print output.

**Examples** PICTBRIDGE: DATEPRINT ON enables the date print on the print output.

PICTBRIDGE: DATEPRINT? might return PICTBRIDGE: DATEPRINT DEFLT

indicating the default setting of the printer.

## PICTBridge: DEFault (No Query Form)

Sets the arguments for all PictBridge commands to their default values. The default values are same as printer default settings.

**Group** PictBridge

Syntax PICTBridge:DEFault

**Examples** PICTBRIDGE: DEFAULT sets all PICTBridge commands to their default values.

## PICTBridge:IDPrint

Enables or disables printing the oscilloscope model and serial number on the

print output.

**Group** PictBridge

Syntax PICTBridge:IDPrint {DEFLT|OFF|ON}

**Related Commands** 

**Arguments** DEFLT is the default setting of the printer.

ON enables the oscilloscope model and serial number print on the print output.

OFF disables the oscilloscope model and serial number print on the print output.

#### **Examples**

PICTBRIDGE: IDPRINT ON enables the printing of oscilloscope model and serial

number on the print output.

PICTBRIDGE: IDPRINT? might return PICTBRIDGE: IDPRINT OFF indicating

that the ID print is disabled on the print output.

## PICTBridge: IMAGESize

Sets or returns the image print size.

Group

PictBridge

**Syntax** 

PICTBridge: IMAGESize

{DEFLT|IN2P5BY3P25|L|IN4BY6|L2|IN8BY10|L4|E|CARD|HAGAKIPcard|CM6BY8|CM7

A4|LETTER}

**Arguments** 

DEFLT for a default image print size.

IN2P5BY3P25 for a 2 5\*3 25 image print size.

L for a 3\_5\*5 image print size.

IN4BY6 for a 4\*6 image print size.

L2 for a 5\*7 image print size.

IN8BY10 for a 8\*10 image print size.

L4 for a 254 MM\*178 MM image print size.

E for a 110 MM\*74 MM image print size.

CARD for a 89 MM\*55 MM image print size.

HAGAKIPcard for a 100 MM\*148 MM image print size.

CM6BY8 for a 6 CM\*8 CM image print size.

CM7BY10 for a 7 CM\*10 CM image print size.

CM9BY13 for a 9 CM\*13 CM image print size.

CM10BY15 for a 10 CM\*15 CM image print size.

CM13BY18 or a 13 CM\*18 CM image print size.

CM15BY21 for a 15 CM\*21 CM image print size.

CM18BY24 for a 18 CM\*24 CM image print size.

A4 for a A4 image print size.

LETTER for a Letter image print size.

**Examples** PICTBRIDGE: IMAGESIZE CARD sets the image print size to 89 MM\* 55 MM.

PICTBRIDGE: IMAGESIZE? might return PICTBRIDGE: IMAGESIZE DEFLT

indicating the default image print size.

### **PICTBridge:PAPERSize**

Sets the output print paper size.

Group PictBridge

**Syntax** PICTBridge: PAPERSize

DEFLT|L|L2|HAGAKIPCARD|MM54BY86|MM100BY150|IN4BY6|IN8BY10|LETTER|IN1

 $\verb|B4|B5|B6|B7|B8|B9|ROLL89MM|ROLL127MM|ROLL100MM|ROLL210MM|$ 

**Arguments** DEFLT for a default paper size.

L for a paper size L

L2 for a paper size 2L.

HAGAKIPCARD for a paper size Hagaki.

MM54BY86 for a card paper size.

MM100BY150 for paper size of 100\*150 MM.

IN4BY6 for a paper size of 4\*6.

IN8BY10 for a paper size of 8\*10.

LETTER for a letter paper size.

IN11BY17 for a paper size of 11\*17.

A0 for a A0 paper size.

A1 for a A1 paper size.

A2 for a A2 paper size.

A3 for a A3 paper size.

A4 for a A4 paper size.

A5 for a A5 paper size.

A6 for a A6 paper size.

A7 for a A7 paper size.

A8 for a A8 paper size..

A9 for a A9 paper size.

B0 for a B0 paper size.

**B1** for a B1 paper size.

B2 for a B2 paper size.

B3 for a B3 paper size.

B4 for a B4 paper size.

B5 for a B5 paper size.

B6 for a B6 paper size.

B7 for a B7 paper size.

B8 for a B8 paper size.

B9 for a B9 paper size.

ROLL89MM for a 89 MM Roll paper size.

ROLL127MM for a 127 MM Roll paper size.

ROLL100MM for a 100 MM Roll paper size.

ROLL210MM for a 210 MM Roll paper size.

#### Examples

PICTBRIDGE: PAPERSIZEL sets the paper size to L.

PICTBRIDGE: PAPERSIZE? might return PICTBRIDGE: PAPERSIZE DEFLT

indicating the paper size is set to Default.

## PICTBridge:PAPERType

Sets or returns the paper type.

Group PictBridge

Syntax PICTBridge:PAPERType {DEFLT|PLAIN|PHOTO|FASTPHOTO}

**Arguments** DEFLT for a default print paper type.

PLAIN for a plain print paper type.

PHOTO for a photo print paper type.

FASTPHOTO for a fastphoto print paper type.

**Examples** PICTBRIDGE: PAPERTYPE PLAIN sets the paper type to Plain.

PICTBRIDGE: PAPERTYPE? might return PICTBRIDGE: PAPERTYPE DEFLT

indicating the default paper type.

### PICTBridge:PRINTQual

Sets or returns the output print quality.

**Group** PictBridge

Syntax PICTBridge:PRINTQual {DEFLT|NRMAL|FINE|DRAFT}

**Arguments** DEFLT for the default quality print.

NRMAL for a normal quality print.

FINE for a fine quality print.

DRAFT for a draft quality print.

**Examples** PICTBRIDGE: PRINTQUAL FINE sets the print quality to Fine.

PICTBRIDGE: PRINTQUAL? might return PICTBRIDGE: PRINTQUAL DEFLT

indicating the default quality print.

#### **POWer:CURRENTSOurce**

Sets or returns the current source for the power application.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:CURRENTSOurce {CH1|CH2|CH3|CH4|REF1|REF2|REF3|REF4}

POWer: CURRENTSOurce?

**Arguments** CH1-CH4 sets an analog channel as the current source.

REF1-REF4 sets a reference as the current source.

**Examples** POWER: CURRENTSOURCE CH1 sets the current source as CH1.

POWER: CURRENTSOURCE? might return POWER: CURRENTSOURCE CH2 indicating

that CH2 is the current source.

**POWer:DISplay** 

Sets or returns the display state for the power application. This is the equivalent to pressing the **Test** button and then selecting the power application. The same

control is provided for each application.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

**Syntax** POWer:DISplay {OFF|ON|0|1}

POWer:DISplay?

**Arguments** OFF or 0 turns off the display settings.

ON or 1 turns on the display settings.

**Examples** POWER: DISPLAY 1 turns on the display.

POWER: DISPLAY? might return: POWER: DISPLAY 0 indicating that the display

is off.

**POWer: GATESOurce** 

Sets or returns the gate source for the power application.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:GATESOurce {CH1|CH2|CH3|CH4|REF1|REF2|REF3|REF4|NONe}

POWer: GATESOurce?

**Arguments** CH1-CH4 sets an analog channel as the gate source.

REF1-REF4 sets a reference as the gate source.

NONe is set when the gate source is not used in the application.

**Examples** POWER: GATESOURCE CH1 sets the gated source as CH1.

POWER: GATESOURCE? might return POWER: GATESOURCE CH2 indicating that

CH2 is the gated source.

**POWer: GATing** 

Sets or returns the power application gating.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:GATing {OFF|SCREen|CURSor}

POWer:GATing?

**Arguments** OFF turns off measurement gating (full record).

SCREEN turns on gating, using the left and right edges of the screen.

CURSor limits measurements to the portion of the waveform between the vertical

bar cursors, even if they are off screen.

**Examples** POWER: GATING CURSOr sets cursor gating on the oscilloscope.

POWER: GATING? might return POWER: GATING OFF indicating that gating is

turned off on the oscilloscope.

POWer: HARMonics: DISPlay: SELect

Sets or returns the harmonics to be displayed when the harmonics standard is

NONe.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:HARMonics:DISPlay:SELect {ODD|EVEN|ALL}

POWer: HARMonics: DISPlay: SELect?

**Arguments** ODD to display only odd harmonics.

EVEN to display only even harmonics.

ALL to display both odd and even harmonics.

**Examples** POWER: HARMONICS: DISPLAY: SELECT EVEN displays only even harmonics.

POWER: HARMONICS: DISPLAY: SELECT? might return

: POWER: HARMONICS: DISPLAY: SELECT ALL indicating that both odd and

even harmonics are displayed.

### POWer:HARMonics:DISPlay:TYPe

Sets or returns the display type for harmonics tests.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

**Syntax** POWer: HARMonics: DISPlay: TYPe {GRAph|TABle}

POWer: HARMonics: DISPlay: TYPe?

**Arguments** GRAph displays harmonic tests results in graphical format.

TABle displays harmonic tests results in tabular format.

**Examples** POWER: HARMONICS: DISPLAY: TYPE GRAph sets the display type to graphical.

POWER: HARMONICS: DISPLAY: TYPE? might return

:POWER:HARMONICS:DISPLAY:TYPE TAB indicating that the display type is

set to tabular.

### POWer: HARMonics: FREQRef

Sets or returns the frequency reference used when the harmonic standard is None.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer: HARMonics: FREQRef

{VOLTage|CURRent|HARMSOURce|FIXEDFREQuency}

POWer: HARMonics: FREQRef?

**Arguments** VOLTage to use a voltage waveform as the frequency reference.

CURRent to use a current waveform as the frequency reference.

HARMSOURce to use a harmonic source waveform as the frequency reference.

FIXEDFREQuency to use a fixed frequency value instead of a waveform for the

frequency reference.

**Examples** POWER: HARMONICS: FREQREF VOLTage sets voltage source as the frequency

reference.

POWER: HARMONICS: FREQREF? might return: POWER: HARMONICS: FREQREF

FIXEDFREQ indicating that the frequency reference is a fixed value.

#### POWer: HARMonics: FREQRef: FIXEDFREQValue

Sets or returns the frequency value when the :FREQRef selection is

FIXEDFREQuency.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:HARMonics:FREQRef:FIXEDFREQValue <NR3>

POWer: HARMonics: FREQRef: FIXEDFREQValue?

**Arguments** <NR3> is the fixed frequency value.

**Examples** POWER: HARMONICS: FREQREF: FIXEDFREQVALUE 100 sets the frequency to

100 Hz.

POWER: HARMONICS: FREQREF: FIXEDFREQVALUE? might return

:POWer:HARMonics:FREQREF:FIXEDFREQVALUE 60 indicating that the fixed

frequency value is set to 60 Hz.

#### POWer:HARMonics:IEC:CLAss

Sets or returns the equipment class for IEC harmonics.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

**Syntax** POWer: HARMonics: IEC: CLASS {A|B|C1|C2|C3|D}

POWer: HARMonics: IEC: CLAss?

**Arguments** A specifies Class A Equipment.

B specifies Class B Equipment.

C1 specifies Class C Equipment that use Table 1 limits of the IEC standard.

C2 specifies Class C Equipment that use Table 2 limits of the IEC standard.

C3 specifies Class C Equipment that use Table 3 limits of the IEC standard.

D specifies Class D Equipment.

**Examples** POWER: HARMONICS: IEC: CLASSB sets Equipment Class B for IEC harmonics.

POWER: HARMONICS: IEC: CLASS? might return

: POWER: HARMONICS: IEC: CLASS A indicating that the Equipment Class is A

for IEC harmonics.

#### POWer:HARMonics:IEC:FILter

Sets or returns the enabled state for filtering of IEC harmonics.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:HARMonics:IEC:FILter {OFF|ON|0|1}

POWer: HARMonics: IEC: FILter?

**Arguments** ON or 1 enables filtering of IEC harmonics.

OFF or 0 disables filtering of IEC harmonics.

**Examples** POWER: HARMONICS: IEC: FILTER OFF disables filtering of IEC harmonics.

POWER: HARMONICS: IEC: FILTER? might return

: POWER: HARMONICS: IEC: FILTER 1 indicating that the IEC harmonics are

filtered.

#### POWer: HARMonics: IEC: FUNDamental

Sets or returns the rated fundamental current for IEC harmonics. Valid values ranges from 0 to 16 in increments of 0.1. The unit is ampere.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:HARMonics:IEC:FUNDamental <NR3>

POWer:HARMonics:IEC:FUNDamental?

**Arguments** <NR3> is the fundamental current in amperes.

**Examples** POWER: HARMONICS: IEC: FUNDAMENTAL 1 sets the fundamental current to

1.0000 A.

POWER: HARMONICS: IEC: FUNDAMENTAL? might return

:POWER:HARMONICS:IEC:FUNDAMENTAL 16 indicating that the

fundamental current for IEC harmonics is set to 16.0000 A.

## POWer: HARMonics: IEC: GROUPing

Sets or returns the enabled state for grouping of IEC harmonics.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

**Syntax** POWer: HARMonics: IEC: GROUPing {OFF|ON|1|0}

POWer:HARMonics:IEC:GROUPing?

**Arguments** ON or 1 enables grouping of IEC harmonics.

OFF or 0 disables grouping of IEC harmonics.

**Examples** POWER: HARMONICS: IEC: GROUPING OFF disables grouping of IEC harmonics.

POWER: HARMONICS: IEC: GROUPING? might return

: POWER: HARMONICS: IEC: GROUPING 1 indicating that the grouping is enabled

for IEC harmonics.

#### POWer: HARMonics: IEC: INPUTPOWer

Sets or returns the class D rated input power for IEC harmonics.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:HARMonics:IEC:INPUTPOWer <NR3>

POWer: HARMonics: IEC: INPUTPOWer?

Arguments <NR3> is the class D input power. Valid values ranges from 0 to 600 in

increments of 10. The unit of measure is watt.

**Examples** POWER: HARMONICS: IEC: INPUTPOWER 600 sets the class D input power to

600 W.

POWER: HARMONICS: IEC: INPUTPOWER? might return

: POWER: HARMONICS: IEC: INPUTPOWER 100 indicating that the class D input

power is set to 100 W.

### POWer: HARMonics: IEC: LINEFREQuency

Sets or returns the line frequency for the IEC standard.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:HARMonics:IEC:LINEFREQuency <NR3>

POWer: HARMonics: IEC: LINEFREQuency?

**Arguments** <NR3> is the line frequency. The valid values are 50 and 60.

**Examples** POWER: HARMONICS: IEC: LINEFREQUENCY 50 sets the line frequency to 50 Hz.

POWER: HARMONICS: IEC: LINEFREQUENCY? might return

: POWER: HARMONICS: IEC: LINEFREQUENCY 60 indicating that the

line frequency value is set to 60 Hz.

#### POWer: HARMonics: IEC: OBSPERiod

Sets or returns the IEC observation period.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:HARMonics:IEC:OBSPERiod <NR3>

POWer: HARMonics: IEC: OBSPERiod?

**Arguments** <NR3> is the IEC observation period. Valid values ranges from 0.2 to 10 s.

**Examples** POWER: HARMONICS: IEC: OBSPERIOD 3 sets the IEC observation period to

3.0000 s.

POWER: HARMONICS: IEC: OBSPERIOD? might return

: POWER: HARMONICS: IEC: OBSPERIOD 10 indicating that the IEC observation

period is set to 10 s.

#### POWer: HARMonics: IEC: POWERFACtor

Sets or returns the rated power factor for IEC harmonics.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:HARMonics:IEC:POWERFACtor <NR3>

POWer: HARMonics: IEC: POWERFACtor?

**Arguments** <NR3> is the power factor. Valid values ranges from 0 to 1 in increments of 0.1.

**Examples** POWER: HARMONICS: IEC: POWERFACTOR 1 sets the power factor to 1.0000.

POWER: HARMONICS: IEC: POWERFACTOR? might return

:POWER:HARMONICS:IEC:POWERFACTOR 900.0000E-03 indicating

that the power factor is set to 0.9.

### POWer:HARMonics:MIL:FUNDamental:CALCmethod

Sets or returns the measurement method for the MIL harmonics fundamental current for use in calculating limits.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:HARMonics:MIL:FUNDamental:CALCmethod {MEAS|USER}

POWer: HARMonics: MIL: FUNDamental: CALCmethod?

**Arguments** MEAS specifies that the value of the fundamental current used in calculating limits

is measured.

USER specifies that the value of the fundamental current used in calculated limits

is user defined.

**Examples** POWER: HARMONICS: MIL: FUNDAMENTAL: CALCMETHOD USER sets the

measurement method to User.

POWER: HARMONICS: MIL: FUNDAMENTAL: CALCMETHOD? might return

:POWER:HARMONICS:MIL:FUNDAMENTAL:CALCMETHOD MEAS indicating that

the measurement method is set to Meas.

### POWer: HARMonics: MIL: FUNDamental: USER: CURRent

Sets or returns RMS amperes for USER CALCmethod.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:HARMonics:MIL:FUNDamental:USER:CURRent <NR3>

POWer: HARMonics: MIL: FUNDamental: USER: CURRent?

**Arguments** <NR3> is the current in amperes for USER CALCmethod.

**Examples** POWER: HARMONICS: MIL: FUNDAMENTAL: USER: CURRENT 2 sets the RMS

fundamental current to 2 A in calculating limits.

POWER: HARMONICS: MIL: FUNDAMENTAL: USER: CURRENT? might return: POWER: HARMONICS: MIL: FUNDAMENTAL: USER: CURRENT 1.0000 indicating that the RMS fundamental current for use in calculating limits is 1.0000 A.

## POWer: HARMonics: MIL: LINEFREQuency

Sets or returns the line frequency for MIL-STD-1399 harmonics tests. Valid values are 60 or 400 Hz.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:HARMonics:MIL:LINEFREQuency <NR3>

POWer: HARMonics: MIL: LINEFREQuency?

**Arguments** <NR3> is the line frequency for MIL standard.

**Examples** POWER: HARMONICS: MIL: LINEFREQUENCY 60 sets the MIL line frequency to

60 Hz.

POWER: HARMONICS: MIL: LINEFREQUENCY? might return

: POWER: HARMONICS: MIL: LINEFREQUENCY 400 indicating that the

MIL line frequency is set to 400 Hz.

#### POWer: HARMonics: MIL: POWERLEVel

Sets or returns the power level for calculating limits for MIL-STD-1399 harmonics tests.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:HARMonics:MIL:POWERLEVel {LOW|HIGH}

POWer: HARMonics: MIL: POWERLEVel?

**Arguments** LOW specifies low power level for MIL-STD-1399 harmonics tests.

HIGH specifies high power level for MIL-STD-1399 harmonics tests.

**Examples** POWER: HARMONICS: MIL: POWERLEVEL HIGH sets the MIL power level to High.

POWER: HARMONICS: MIL: POWERLEVEL? might return

: POWER: HARMONICS: MIL: POWERLEVEL LOW indicating that the MIL power

level is set to Low.

### POWer: HARMonics: NR\_HARMonics

Sets or returns the number of harmonics (value ranging from 20 to 400) when the

harmonics standard is NONe.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:HARMonics:NR\_HARMonics <NR3>

POWer: HARMonics: NR HARMonics?

**Arguments** <NR3> is the number of harmonics.

**Examples** POWER: HARMONICS: NR\_HARMONICS 100 sets the number of harmonics to 100.

POWER: HARMONICS: NR\_HARMONICS? might return

: POWer: HARMONICS: NR\_HARMONICS 40 indicating that the number of

harmonics is set to 40.

# POWer:HARMonics:RESults:HAR<1-400>:FREQuency? (Query Only)

Returns the frequency of the harmonic.

**NOTE.** The command returns NA, if the current harmonic standard is set to a new standard other than the returned query.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:HARMonics:RESults:HAR<1-400>:FREQuency?

**Examples** POWER: HARMONICS: RESULTS: HAR400: FREQUENCY? might return

:POWER:HARMONICS:RESULTS:HAR400:FREQUENCY 24000 indicating that

the harmonic frequency is set to 24000.

## POWer:HARMonics:RESults:HAR<1-400>:IECMAX? (Query Only)

The IEC Standard specifies harmonics measurements to be computed in time windows, with each time window being nominally 200 ms. This returns the maximum of the RMS magnitude of the harmonic, computed across successive 200 ms time windows within an observation period entered by the user.

**NOTE.** The command returns NA, if the current harmonic standard is set to a new standard other than the returned query.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:HARMonics:RESults:HAR<1-400>:IECMAX?

**Examples** POWER: HARMONICS: RESULTS: HAR400: IECMAX? might return

: POWER: HARMONICS: RESULTS: HAR400: IECMAX 1.0 indicating that the

maximum value is 1.0 A for the 400th harmonic.

## POWer:HARMonics:RESults:HAR<1-400>:LIMit? (Query Only)

The IEC and MIL standards specify a limit for each harmonic magnitude. Returns the limit in absolute units, or as a percentage of the fundamental as specified by

the standard. IEC Class C (Table 2) and MIL standards specify the limit as a

percentage of the fundamental.

**Conditions** This command requires a DPO4PWR application module.

Power Group

POWer: HARMonics: RESults: HAR<1-400>: LIMit? **Syntax** 

**Examples** POWER: HARMONICS: RESULTS: HAR3: LIMIT? might return

> :POWER:HARMONICS:RESULTS:HAR3:LIMIT 2.30 indicating that the harmonic magnitude limit for IEC standard for the 3rd harmonic is set to

2.30 A.

## POWer:HARMonics:RESults:HAR<1-400>:PHASe? (Query Only)

Returns the phase of the harmonic in degrees. The phase is measured relative to the zero-crossing of the reference waveform. When there is no reference waveform, the phase is relative to the fundamental component.

**Conditions** This command requires a DPO4PWR application module.

Power Group

POWer: HARMonics: RESults: HAR<1-400>: PHASe? **Syntax** 

**Examples** POWER: HARMONICS: RESULTS: HAR400: PHASE? might return

:POWER:HARMONICS:RESULTS:HAR400:PHASE 0 indicating that the harmonic

phase is set to 0 in degrees.

# POWer: HARMonics: RESults: HAR<1-400>: RMS: ABSolute? (Query Only)

Returns the RMS magnitude of the harmonic in absolute units.

Conditions This command requires a DPO4PWR application module.

Power Group

Syntax POWer:HARMonics:RESults:HAR<1-400>:RMS:ABSolute?

**Examples** POWER: HARMONICS: RESULTS: HAR400: RMS: ABSOLUTE? might return

: POWER: HARMONICS: RESULTS: HAR400: RMS: ABSOLUTE 1.0 indicating that

the RMS magnitude of the harmonic is set to 1.0 A.

## POWer:HARMonics:RESults:HAR<1-400>:RMS:PERCent? (Query Only)

Returns the RMS magnitude of the harmonic expressed as a percentage of the fundamental.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:HARMonics:RESults:HAR<1-400>:RMS:PERCent?

**Examples** POWER: HARMONICS: RESULTS: HAR400: RMS: PERCENT? might return

: POWER: HARMONICS: RESULTS: HAR400: RMS: PERCENT 33 indicating that the

RMS magnitude of the harmonic is set to 33%.

## POWer:HARMonics:RESults:HAR<1-400>:TEST:IEC:CLASSALIMit? (Query Only)

Specifies if the IEC Class A higher harmonic limit (and conditions) are met.

**NOTE.** The command returns NA if the standard does not specify a limit or the equipment is not class A.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:HARMonics:RESults:HAR<1-400>:TEST:IEC:CLASSALIMit?

Returns PASS, FAIL, or NA.

## POWer: HARMonics: RESults: HAR<1-400>: TEST: IEC: NORMAL? (Query Only)

Specifies if the Normal IEC harmonic limits are met.

**NOTE.** The command returns NA if the standard does not specify a limit.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:HARMonics:RESults:HAR<1-400>:TEST:IEC:NORMAL?

Returns PASS, FAIL, or NA.

# POWer: HARMonics: RESults: HAR<1-400>: TEST: IEC: POHCLIMit? (Query Only)

Specifies if the higher harmonic limit (and conditions) for the 21st and higher order odd harmonics are met.

**NOTE.** The command returns NA if the limit does not apply for a specific harmonic

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:HARMonics:RESults:HAR<1-400>:TEST:IEC:POHCLIMit?

Returns PASS, FAIL, or NA.

## POWer: HARMonics: RESults: HAR<1-400>: TEST: MIL: NORMAL? (Query Only)

Returns the test result for the specified harmonic for the MIL-STD-1399 testing standard.

This query is analogous to that for the IEC 61000-3-2 standard POWer:HARMonics:RESults:HAR<1-400>:TEST:IEC:NORMAL? command.

**NOTE.** The command returns NA if the standard does not specify a limit for the specific harmonic.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:HARMonics:RESults:HAR<1-400>:TEST:MIL:NORMAL?

Returns PASS, FAIL, or NA.

## POWer: HARMonics: RESults: IEC: FUNDamental? (Query Only)

Returns the IEC fundamental current used in calculating limits.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:HARMonics:RESults:IEC:FUNDamental?

**Examples** POWER: HARMONICS: RESULTS: IEC: FUNDAMENTAL? might return

:POWER:HARMONICS:RESULTS:IEC:FUNDAMENTAL 1.0 indicating that the

IEC fundamental frequency is set to 1.0 A.

## POWer: HARMonics: RESults: IEC: HARM3ALTernate? (Query Only)

Returns the IEC harmonics test result for the 3rd harmonic.

**NOTE.** The command returns NA if the limit does not apply.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

**Syntax** POWer: HARMonics: RESults: IEC: HARM3ALTernate?

Returns PASS, FAIL, or NA.

**Examples** POWER: HARMONICS: RESULTS: IEC: HARM3ALTERNATE? might return

POWER: HARMONICS: RESULTS: IEC: HARM3ALTERNATE PASS indicating the

test result.

### POWer: HARMonics: RESults: IEC: HARM5ALTernate? (Query Only)

Returns the overall harmonics test result for the 5th harmonic.

**NOTE.** The command returns NA the harmonic limit does not apply.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

**Syntax** POWer: HARMonics: RESults: IEC: HARM5ALTernate?

Returns PASS, FAIL, or NA.

**Examples** POWER: HARMONICS: RESULTS: IEC: HARM5ALTERNATE? might return

POWER: HARMONICS: RESULTS: IEC: HARM5ALTERNATE PASS indicating the

test result.

### POWer: HARMonics: RESults: IEC: POHC? (Query Only)

Returns the IEC POHC measurement.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

**Syntax** POWer: HARMonics: RESults: IEC: POHC?

**Examples** POWER: HARMONICS: RESULTS: IEC: POHC? might return

:POWER:HARMONICS:RESULTS:IEC:POHC 0.5 indicating that the

IEC POHC is set to 0.5 A.

# POWer:HARMonics:RESults:IEC:POHL? (Query Only)

Returns the IEC POHL measurement.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

**Syntax** POWer: HARMonics: RESults: IEC: POHL?

**Examples** POWER: HARMONICS: RESULTS: IEC: POHL? might return

:POWER:HARMONICS:RESULTS:IEC:POHL 0.5 indicating that the

IEC POHL is set to 0.5 A.

## POWer: HARMonics: RESults: IEC: POWer? (Query Only)

Returns the IEC input power that is used to calculate limits.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

**Syntax** POWer: HARMonics: RESults: IEC: POWer?

**Examples** POWER: HARMONICS: RESULTS: IEC: POWER? might return

:POWER:HARMONICS:RESULTS:IEC:POWER 5 indicating that the

IEC power is set to 5 W.

### POWer: HARMonics: RESults: IEC: POWERFactor? (Query Only)

Returns the IEC power factor measurement.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:HARMonics:RESults:IEC:POWERFactor?

**Examples** POWER: HARMONICS: RESULTS: IEC: POWERFACTOR? might return

:POWER:HARMONICS:RESULTS:IEC:POWERFACTOR 9.1900E+37 indicating

that the IEC power factor is set to 9.1900E+37.

## POWer: HARMonics: RESults: PASSFail? (Query Only)

Returns the overall harmonics test result: PASS, FAIL or NA.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:HARMonics:RESults:PASSFail?

**Examples** POWER: HARMONICS: RESULTS: PASSFAIL? might return

: POWER: HARMONICS: RESULTS: PASSFAIL PASS indicating that the

harmonics test passed.

## POWer: HARMonics: RESults: RMS? (Query Only)

Returns the root mean square value of the harmonics source waveform.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

**Syntax** POWer: HARMonics: RESults: RMS?

**Examples** POWER: HARMONICS: RESULTS: RMS? might return

: POWER: HARMONICS: RESULTS: RMS 1.0 indicating that the harmonics source

waveform RMS is set to 1.0.

# POWer: HARMonics: RESults: SAVe (No Query Form)

Saves the harmonic results to the specified file in CSV format.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:HARMonics:RESults:SAVe <String>

# POWer: HARMonics: RESults: THDF? (Query Only)

Returns the Total Harmonic Distortion (THD) in percentage, measured as a ratio to the RMS value of the fundamental component of the source waveform.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:HARMonics:RESults:THDF?

**Examples** POWER: HARMONICS: RESULTS: THDF? might return

: POWER: HARMONICS: RESULTS: THDF 40 indicating that the THDF is set to 40.

## POWer: HARMonics: RESults: THDR? (Query Only)

Returns the Total Harmonic Distortion (THD) in percentage, measured as a ratio to the RMS value of the source waveform.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:HARMonics:RESults:THDR?

**Examples** POWER: HARMONICS: RESULTS: THDR? might return

: POWER: HARMONICS: RESULTS: THDR 40 indicating that the THDR is set to 40.

#### POWer: HARMonics: SOURce

Sets or returns the source waveform for harmonics tests. The voltage source waveform is specified using the POWer:VOLTAGESOurce command and the current waveform is specified using the POWer:CURRENTSOurce command.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:HARMonics:SOURce {VOLTage|CURRent}

POWer: HARMonics: SOURce?

**Arguments** VOLTage specifies voltage source waveform for harmonic tests.

CURRent specifies current source waveform for harmonic tests.

**Examples** POWER: HARMONICS: SOURCE VOLTage sets voltage source for harmonic tests.

POWER: HARMONICS: SOURCE? might return: POWer: HARMOnics: SOURCE

CURRENT indicating that the harmonic source is set to current.

### POWer: HARMonics: STANDard

Sets or returns the standard for harmonics tests.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:HARMonics:STANDard {NONe|IEC|MIL}

POWer: HARMonics: STANDard?

**Arguments** NONe sets no standard for harmonic tests.

IEC sets IEC 610003-2 standard for harmonic tests.

MIL sets MIL1399 standard for harmonic tests.

**Examples** POWER: HARMONICS: STANDARD IEC sets IEC standard for harmonic tests.

POWER: HARMONICS: STANDARD? might return: POWer: HARMOnics: STANDard

NONe indicating that no standard is set.

### **POWer:INDICators**

Sets or returns the state of the measurement indicators for the power application.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:INDICators {OFF|ON|0|1}

POWer: INDICators?

**Arguments** OFF or 0 turns off the measurement indicators.

**ON** or 1 turns on the measurement indicators.

**Examples** POWER: INDICATORS 1 turns on the indicator.

POWER: INDICATORS? might return: POWER: INDICators 0 indicating that

the indicator is off.

### POWer: MODulation: SOUrce

Sets or returns the source waveform for modulation tests. The voltage source waveform is specified using the POWer:VOLTAGESOurce command and the current waveform is specified using the POWer:CURRENTSOurce command.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:MODulation:SOUrce {VOLTage|CURRent}

POWer: MODulation: SOUrce?

**Arguments** VOLTage specifies voltage source waveform for modulation tests.

CURRent specifies current source waveform for modulation tests.

**Examples** POWER: MODULATION: SOURCE CURRENT sets the modulation source to Current.

POWER: MODULATION: SOURCE? might return: POWER: MODULATION: SOURCE

VOLT indicating that the modulation source is set to Voltage.

#### POWer: MODulation: TYPe

Sets or returns the modulation type.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

**Syntax** POWer: MODulation: TYPe

{PWIdth|NWIdth|PERIod|PDUty|NDUty|FREQuency}

POWer: MODulation: TYPe?

#### **Arguments**

PWIdth (positive width) is the distance (time) between the middle reference (default = 50%) amplitude points of a positive pulse. The measurement is made on all the cycles in the waveform or gated region.

NWIdth (negative width) measurement is the distance (time) between the middle reference (default = 50%) amplitude points of a negative pulse. The measurement is made on all the cycles in the waveform or gated region.

PERIOd is the time required to complete the first cycle in a waveform or the gated region. The time is measured between the mid reference (default being 50%) amplitude points of the waveform.

PDUty (positive duty cycle) is the ratio of the positive pulse width to the signal period, expressed as a percentage. It is measured on all the cycles in the waveform or gated region.

Positive Duty Cycle =  $((Positive\ Width)/Period) \times 100\%$ 

NDUty (negative duty cycle) is the ratio of the negative pulse width to the signal period, expressed as a percentage. The duty cycle is measured on all the cycles in the waveform or gated region.

Negative Duty Cycle =  $((Negative\ Width) / Period) \times 100\%$ 

FREQuency measures all the cycles in the waveform or gated region. Frequency is the reciprocal of the period and is measured in hertz (Hz), where 1 Hz = 1 cycle per second.

Frequency = 1 / Period

#### **Examples**

POWER: MODULATION: TYPE NWIDTH sets the modulation type to Negative Width.

POWER: MODULATION: TYPE? might return: POWER: MODULATION: TYPE PWI indicating that the modulation type is set to Positive Width.

## POWer:QUALity:APPpwr? (Query Only)

Returns the apparent power measurement.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

**Syntax** POWer:QUALity:APPpwr?

**Examples** POWER:QUALITY:APPPWR? might return:POWER:QUALITY:APPpwr 100

indicating that the apparent power value is set to 100 VA.

## POWer:QUALity:DISplay:APPpwr

Sets or returns the display state for the apparent power readout.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

**Syntax** POWer:QUALity:DISplay:APPpwr {OFF|ON|0|1}

POWer:QUALity:DISplay:APPpwr?

**Arguments** OFF or 0 turns off the apparent power display.

ON or 1 turns on the apparent power display.

**Examples** POWER:QUALITY:DISPLAY:APPPWR 1 turns on the apparent power display.

POWER:QUALITY:DISPLAY:APPPWR? might return

:POWER:QUALITY:DISPLAY:APPPWR 0 indicating that the apparent power

display is off.

## POWer:QUALity:DISplay:FREQuency

Sets or returns the display state for the frequency readout.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

**Syntax** POWer:QUALity:DISplay:FREQuency {OFF|ON|0|1}

POWer:QUALity:DISplay:FREQuency?

**Arguments** OFF or 0 turns off the frequency display.

ON or 1 turns on the frequency display.

**Examples** POWER:QUALITY:DISPLAY:FREQUENCY 1 turns on the frequency readout

display.

POWER:QUALITY:DISPLAY:FREQUENCY? might return

:POWER:QUALITY:DISPLAY:FREQUENCY 0 indicating that the

frequency readout display is off.

## POWer:QUALity:DISplay:ICRESTfactor

Sets or returns the display state for the current crest factor readout.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

**Syntax** POWer:QUALity:DISplay:ICRESTfactor {OFF|ON|0|1}

POWer:QUALity:DISplay:ICRESTfactor?

**Arguments** OFF or 0 turns off the current crest factor display.

ON or 1 turns on the current crest factor display.

**Examples** POWER:QUALITY:DISPLAY:ICRESTFACTOR 1 turns on the current crest factor

display.

POWER:QUALITY:DISPLAY:ICRESTFACTOR? might return

:POWER:QUALITY:DISPLAY:ICRESTFACTOR 0 indicating that the

current crest factor display is off.

# POWer:QUALity:DISplay:IRMS

Sets or returns the display state for the rms current readout.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

**Syntax** POWer:QUALity:DISplay:IRMS {OFF|ON|0|1}

POWer:QUALity:DISplay:IRMS?

**Arguments** OFF or 0 turns off the rms current display.

**ON** or 1 turns on the rms current display.

**Examples** POWER:QUALITY:DISPLAY:IRMS 1 turns on the rms current display.

POWER:QUALITY:DISPLAY:IRMS? might return

:POWER:QUALITY:DISPLAY:IRMS 0 indicating that the rms current display

is off.

## POWer:QUALity:DISplay:PHASEangle

Sets or returns the display state for the phase angle readout.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

**Syntax** POWer:QUALity:DISplay:PHASEangle {OFF|ON|0|1}

POWer:QUALity:DISplay:PHASEangle?

**Arguments** OFF or 0 turns off the phase angle display.

ON or 1 turns on the phase angle display.

**Examples** POWER:QUALITY:DISPLAY:PHASEANGLE 1 turns on the phase angle display.

POWER:QUALITY:DISPLAY:PHASEANGLE? might return

:POWER:QUALITY:DISPLAY:PHASEANGLE 0 indicating that the

phase angle display is off.

# POWer:QUALity:DISplay:POWERFACtor

Sets or returns the display state for the power factor readout.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

**Syntax** POWer:QUALity:DISplay:POWERFACtor {OFF|ON|0|1}

POWer:QUALity:DISplay:POWERFACtor?

**Arguments** OFF or 0 turns off the power factor display.

ON or 1 turns on the power factor display.

**Examples** POWER:QUALITY:DISPLAY:POWERFACTOR 1 turns on the power factor display.

POWER:QUALITY:DISPLAY:POWERFACTOR? might return

:POWER:QUALITY:DISPLAY:POWERFACTOR 0 indicating that the

power factor display is off.

## POWer:QUALity:DISplay:REACTpwr

Sets or returns the display state for the reactor power readout.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

**Syntax** POWer:QUALity:DISplay:REACTpwr {OFF|ON|0|1}

POWer:QUALity:DISplay:REACTpwr?

**Arguments** OFF or 0 turns off the reactor power display.

ON or 1 turns on the reactor power display.

**Examples** POWER:QUALITY:DISPLAY:REACTPWR 1 turns on the reactor power display.

POWER:QUALITY:DISPLAY:REACTPWR? might return

: POWER: QUALITY: DISPLAY: REACTPWR 0 indicating that the reactor power

display is off.

## POWer:QUALity:DISplay:TRUEpwr

Sets or returns the display state for the true power readout.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

**Syntax** POWer:QUALity:DISplay:TRUEpwr {OFF|ON|0|1}

POWer:QUALity:DISplay:TRUEpwr?

**Arguments** OFF or 0 turns off the true power display.

**ON** or 1 turns on the true power display.

**Examples** POWER:QUALITY:DISPLAY:TRUEPWR 1 turns on the true power display.

POWER:QUALITY:DISPLAY:TRUEPWR? might return

:POWER:QUALITY:DISPLAY:TRUEPWR 0 indicating that the true power

display is off.

## POWer:QUALity:DISplay:VCRESTfactor

Sets or returns the display state for the voltage crest factor readout.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

**Syntax** POWer:QUALity:DISplay:VCRESTfactor {OFF|ON|0|1}

POWer:QUALity:DISplay:VCRESTfactor?

**Arguments** OFF or 0 turns off the voltage crest factor display.

ON or 1 turns on the voltage crest factor display.

**Examples** POWER:QUALITY:DISPLAY:VCRESTFACTOR 1 turns on the voltage crest factor

display.

POWER:QUALITY:DISPLAY:VCRESTFACTOR? might return :POWER:QUALITY:DISPLAY:VCRESTFACTOR 0 indicating that the voltage crest factor display is off.

## POWer:QUALity:DISplay:VRMS

Sets or returns the display state for the rms voltage readout.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

**Syntax** POWer:QUALity:DISplay:VRMS {OFF|ON|0|1}

POWer:QUALity:DISplay:VRMS?

**Arguments** OFF or 0 turns off the rms voltage display.

ON or 1 turns on the rms voltage display.

**Examples** POWER:QUALITY:DISPLAY:VRMSO turns off the rms voltage display.

POWER:QUALITY:DISPLAY:VRMS? might return

: POWER: QUALITY: DISPLAY: VRMS 1 indicating that the rms voltage display

is on.

## POWer:QUALity:FREQREFerence

Sets or returns the power quality frequency reference.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:QUALity:FREQREFerence {VOLTage|CURRent}

POWer:QUALity:FREQREFerence?

**Arguments** VOLTage sets voltage as the power quality frequency reference source.

CURRent sets current as the power quality frequency reference source.

**Examples** POWER:QUALITY: FREQREFERENCE CURRent sets current as the power quality

frequency reference source.

POWER:QUALITY:FREQREFERENCE? might return

: POWER: QUALITY: FREQREFERENCE VOLTAGE indicating that the power quality

frequency reference source is set to Voltage.

# POWer:QUALity:FREQuency? (Query Only)

Returns the frequency measurement.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

**Syntax** POWer:QUALity:FREQuency?

**Examples** POWER:QUALITY:FREQUENCY? might return:POWER:QUALITY:FREQUENCY

60 indicating that the frequency is set to 60 Hz.

# POWer:QUALity:ICRESTfactor? (Query Only)

Returns the current crest factor measurement.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

**Syntax** POWer:QUALity:ICRESTfactor?

**Examples** POWER:QUALITY:ICRESTFACTOR? might return

: POWER: QUALITY: ICREST factor 1.4 indicating that the current crest factor

value is set to 1.4.

# POWer:QUALity:IRMS? (Query Only)

Returns the RMS current measurement.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

**Syntax** POWer:QUALity:IRMS?

**Examples** POWER:QUALITY:IRMS? might return:POWER:QUALITY:IRMS 1.00

indicating that the RMS current value is set to 1.00 A.

# POWer:QUALity:PHASEangle? (Query Only)

Returns the phase angle measurement.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

**Syntax** POWer:QUALity:PHASEangle?

**Examples** POWER:QUALITY:PHASEANGLE? might return:POWER:QUALITY:PHASEANGLE

0 indicating that the phase angle is set to 0.

# POWer:QUALity:POWERFACtor? (Query Only)

Returns the power factor measurement.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

**Syntax** POWer:QUALity:POWERFACtor?

**Examples** POWER:QUALITY:POWERFACTOR? might return

: POWER: QUALITY: POWERFACTOR 1.0 indicating that the power factor is

set to 1.0.

# POWer:QUALity:REACTpwr? (Query Only)

Returns the reactive power measurement.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

**Syntax** POWer:QUALity:REACTpwr?

**Examples** POWER:QUALITY:REACTPWR? might return:POWER:QUALITY:REACTPWr 100

indicating that the reactor power value is set to 100 VAR.

# POWer:QUALity:TRUEpwr? (Query Only)

Returns the true power measurement.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

**Syntax** POWer:QUALity:TRUEpwr?

**Examples** POWER:QUALITY:TRUEPWR? might return:POWER:QUALITY:TRUEPWr 1000

W indicating that the true power value is set to 1000 W.

# POWer:QUALity:VRMS? (Query Only)

Returns the RMS voltage measurement.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

**Syntax** POWer:QUALity:VRMS?

**Examples** POWER:QUALITY:VRMS? might return:POWER:QUALITY:VRMS 115 indicating

that the rms voltage value is set to 115 V.

## POWer:REFLevel:ABSolute (No Query Form)

Sets the reference levels to their default unit values.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

**Syntax** POWer:REFLevel:ABSolute {SETTODEFaults}

**Arguments** SETTODEFaults sets the reference levels to their default values.

### POWer: REFLevel: ABSolute: HIGH

Sets or returns the top reference level for power measurements.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:REFLevel:ABSolute:HIGH <NR3>; Ranges={D,-1e6,+1E6}

POWer: REFLevel: ABSolute: HIGH?

**Arguments** <NR3> is the absolute high value in volts. Default value is 0.0E+0

**Examples** POWER: REFLEVEL: ABSOLUTE: HIGH 2 sets the absolute high value to 2.000.

POWER: REFLEVEL: ABSOLUTE: HIGH? might return

POWER: REFLEVEL: ABSOLUTE: HIGH 2 indicating that the absolute high

value is set to 2 V.

### POWer:REFLevel:ABSolute:LOW

Sets or returns the low reference level for power measurements.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:REFLevel:ABSolute:LOW <NR3>; Ranges={D,-1e6,+1E6}

POWer: REFLevel: ABSolute: LOW?

**Arguments** <NR3> is the absolute low value in volts. Default value is 0.0E+0.

**Examples** POWER:REFLEVEL:ABSOLUTE:LOW 1.0 sets the absolute high value to 1.0000.

POWER: REFLEVEL: ABSOLUTE: LOW? might return

POWER: REFLEVEL: ABSOLUTE: LOW 1.0000 indicating that the absolute low

value is set to 1 V.

#### POWer:REFLevel:ABSolute:MID<1-3>

Sets or returns the mid reference level for measurements. MID3 is specific to the power application.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

**Syntax** POWer:REFLevel:ABSolute:MID<1-3> <NR3>; Ranges={D,-1e6,+1E6}

POWer: REFLevel: ABSolute: MID<1-3>?

**Arguments** <NR3> is the absolute mid reference value.

**Examples** POWER: REFLEVEL: ABSOLUTE: MID1 1 sets the mid reference voltage to 1V.

POWER: REFLEVEL: ABSOLUTE: MID1? might return

POWER: REFLEVEL: ABSOLUTE: MID1 0.0E+0 indicating that the absolute

reference voltage level is set to 0.0E+0 V.

#### POWer: REFLevel: HYSTeresis

Sets or returns the measurement reference level hysteresis value.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:REFLevel:HYSTeresis <NR3>

POWer: REFLevel: HYSTeresis?

**Arguments** <NR3> is the hysteresis value.

**Examples** POWER: REFLEVEL: HYSTERESIS 30 sets the hysteresis value to 30.

POWER: REFLEVEL: HYSTERESIS? might return

POWER: REFLEVEL: HYSTERESIS 10 indicating that the hysteresis value is

set to 10.

### POWer:REFLevel:METHod

Sets or returns the method used to calculate the 0% and 100% reference level.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:REFLevel:METHod {ABSolute|PERCent}

POWer: REFLevel: METHod?

**Arguments** ABSolute specifies that the reference levels are set explicitly using the

MEASUrement: REFLevel: ABSolute commands. This method is useful when

precise values are required.

PERCent specifies that the reference levels are calculated as a percent

of the signal amplitude. The percentages are defined using the

MEASUrement: REFLevel: PERCent commands.

**Examples** POWER: REFLEVEL: METHOD ABSOLUTE specifies that explicit user-defined values

are used for the reference levels.

POWER: REFLEVEL: METHOD? might return POWER: REFLEVEL: METHOD

PERCENT indicating that the reference level units used are calculated as a percent

relative to HIGH and LOW.

## POWer:REFLevel:PERCent (No Query Form)

Sets the reference levels to the default percentage values.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:REFLevel:PERCent <SETTODEFaults>

**Arguments** SETTODEFaults sets the reference levels to their default percentage values.

### POWer:REFLevel:PERCent:HIGH

Sets or returns the top reference percent level for power measurements.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:REFLevel:PERCent:HIGH <NR3>; Ranges={D,0.0,100.0}

POWer: REFLevel: PERCent: HIGH?

**Arguments** <NR3> is the high value in percent.

**Examples** POWER: REFLEVEL: PERCENT: HIGH 95 sets the high reference level to 95% of

the signal amplitude.

POWER: REFLEVEL: PERCENT: HIGH? might return

:POWER:REFLEVEL:PERCENT:HIGH 90 indicating that the percentage high

reference level is set to 90% of the signal amplitude.

### POWer:REFLevel:PERCent:LOW

Sets or returns the low reference percent level for power measurements.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:REFLevel:PERCent:LOW <NR3>; Ranges={D,0.0,100.0}

POWer: REFLevel: PERCent: LOW?

**Arguments** <NR3> is the low value in percentage.

**Examples** POWER: REFLEVEL: PERCENT: LOW 15 sets the low reference level to 15% of the

signal amplitude.

POWER: REFLEVEL: PERCENT: LOW? might return

: POWER: REFLEVEL: PERCENT: LOW 10 indicating that the percentage low

reference level is set to 90% of the signal amplitude.

### POWer:REFLevel:PERCent:MID<1-3>

Sets or returns the mid reference percent level for waveform measurements. Mid3

is specific to the power application.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:REFLevel:PERCent:MID<1-3> <NR3>; Ranges={D,0.0,100.0}

POWer:REFLevel:PERCent:MID<1-3>?

**Arguments** <NR3> is the mid value in percentage.

**Examples** POWER:REFLEVEL:PERCENT:MID1 25 sets the mid reference voltage to 25%.

POWER: REFLEVEL: PERCENT: MID1? might return

POWER: REFLEVEL: PERCENT: MID1 50.0000 indicating that the mid reference

voltage level is set to 50%.

# POWer:RIPPle (No Query Form)

Does a vertical autoset for ripple measurements or sets the vertical offset to 0.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:RIPPle {VERTAUTOSet|VERTDEFault}

**Arguments** VERTAUTOSet automatically scales the source waveform to optimize ripple

measurements.

VERTDEFault sets the vertical offset of the source waveform to 0 volts (for

voltage source) or 0 amperes (for current source).

## POWer:RIPPle:RESults:AMPLitude? (Query Only)

Returns the peak-to-peak ripple measurement.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

**Syntax** POWer:RIPPle:RESults:AMPLitude?

**Examples** POWER:RIPPLE:RESULTS:AMPLITUDE? might return

:POWER:RIPPLE:RESULTS:AMPLITUDE 1 indicating that the peak-to-peak

amplitude is set to 1 V.

### POWer:RIPPle:RESults:MAX? (Query Only)

Returns the maximum of the peak-to-peak ripple measurements.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:RIPPle:RESults:MAX?

**Examples** POWER:RIPPLE:RESULTS:MAX? might return :POWER:RIPPLE:RESULTS:MAX

1.1 indicating that the maximum peak-to-peak amplitude is set to 1.1 V.

## POWer:RIPPle:RESults:MEAN? (Query Only)

Returns the mean of the peak-to-peak ripple measurements.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

**Syntax** POWer:RIPPle:RESults:MEAN?

**Examples** POWER:RIPPLE:RESULTS:MEAN? might return

: POWER: RIPPLE: RESULTS: MEAN 1.0 indicating that the mean peak-to-peak

amplitude is set to 1.0 V.

## POWer:RIPPle:RESults:MIN? (Query Only)

Returns the minimum of the peak-to-peak ripple measurement.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:RIPPle:RESults:MIN?

**Examples** POWER:RIPPLE:RESULTS:MIN? might return:POWER:RIPPLE:RESULTS:MIN

0.9 indicating that the minimum peak-to-peak amplitude is set to 0.9 V.

### POWer:RIPPle:RESults:STDdev? (Query Only)

Returns the standard deviation of the peak-to-peak ripple measurements.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

**Syntax** POWer:RIPPle:RESults:STDdev?

**Examples** POWER:RIPPLE:RESULTS:STDDEV? might return

:POWER:RIPPLE:RESULTS:STDDEV 0.14 indicating that the standard

deviation of the peak-to-peak amplitude is set to 0.14.

#### POWer:RIPPle:SOUrce

Sets or returns the source waveform for ripple tests. The voltage source waveform is specified using the POWer:VOLTAGESOurce command and the current waveform is specified using the POWer:CURRENTSOurce command.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:RIPPle:SOUrce {VOLTage|CURRent}

**Arguments** VOLTage specifies voltage source waveform for ripple tests.

CURRent specifies current source waveform for ripple tests.

**Examples** POWER:RIPPLE:SOURCE CURRent sets the ripple source to Current.

POWER:RIPPLE:SOURCE? might return :POWER:RIPPLE:SOURCE VOLT

indicating that the ripple source is set to Voltage.

#### POWer:SOA:LINear:XMAX

Sets or returns the user XMAX value for use in linear SOA calculations.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:SOA:LINear:XMAX <NR3>

POWer:SOA:LINear:XMAX?

**Arguments** <NR3> is the XMAX value used for linear SOA calculations.

**Examples** POWER: SOA: LINEAR: XMAX 700 sets the XMAX value to 700.0000.

POWER:SOA:LINEAR:XMAX ? might return :POWER:SOA:LINear:XMAX

500.0000 indicating that the XMAX value for linear plot type is set to 500.0000.

### POWer:SOA:LINear:XMIN

Sets or returns the user XMIN value for use in linear SOA calculations.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:SOA:LINear:XMIN <NR3>

POWer:SOA:LINear:XMIN?

**Arguments** <NR3> is the XMIN value used for linear SOA calculations.

**Examples** POWER: SOA: LINEAR: XMIN 2 sets the XMIN value to 2.0000.

POWER: SOA: LINEAR: XMIN? might return: POWER: SOA: LINEAR: XMIN 0.0E+0 indicating that the XMIN value for linear plot type is set to 0.0E+0.

### POWer:SOA:LINear:YMAX

Sets or returns the user YMAX value for use in linear SOA calculations.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:SOA:LINear:YMAX <NR3>

POWer:SOA:LINear:YMAX?

**Arguments** <NR3> is the YMAX value used for linear SOA calculations.

**Examples** POWER: SOA: LINEAR: YMAX 700 sets the YMAX value to 700.0000.

POWER: SOA: LINEAR: YMAX? might return: POWER: SOA: LINear: YMAX 50.0000 indicating that the YMAX value for linear plot type is set to 50.0000.

### POWer:SOA:LINear:YMIN

Sets or returns the user YMIN value for use in linear SOA calculations.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:SOA:LINear:YMIN <NR3>

POWer: SOA: LINear: YMIN?

**Arguments** <NR3> is the YMIN value used for linear SOA calculations.

**Examples** POWER: SOA: LINEAR: YMIN 2 sets the YMIN value to 2.0000.

POWER: SOA: LINEAR: YMIN? might return: POWER: SOA: LINEAR: YMIN 0.0E+0 indicating that the YMIN value for linear plot type is set to 0.0E+0.

### POWer:SOA:LOG:XMAX

Sets or returns the user XMAX value for use in Log SOA calculations.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:SOA:LOG:XMAX <NR3>

POWer:SOA:LOG:XMAX?

**Arguments** <NR3> is the XMAX value used for log SOA calculations.

**Examples** POWER: SOA: LOG: XMAX 1 sets the XMAX value to 1.0000.

POWER:SOA:LOG:XMAX ? might return :POWER:SOA:LOG:XMAX 1.0000E+3

indicating that the XMAX value for log plot type is set to 1.0000E+3.

#### POWer:SOA:LOG:XMIN

Sets or returns the user XMIN value for use in Log SOA calculations.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:SOA:LOG:XMIN <NR3>

POWer:SOA:LOG:XMIN?

**Arguments** <NR3> is the XMIN value used for log SOA calculations.

**Examples** POWER: SOA: LOG: XMIN 2 sets the XMIN value to 2.0000.

POWER:SOA:LOG:XMIN? might return:POWER:SOA:LOG:XMIN 100.0000E-3

indicating that the XMIN value for log plot type is set to 100.0000E-3.

### POWer:SOA:LOG:YMAX

Sets or returns the user YMAX value for use in Log SOA calculations.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:SOA:LOG:YMAX <NR3>

POWer:SOA:LOG:YMAX?

**Arguments** <NR3> is the YMAX value used for log SOA calculations.

**Examples** POWER: SOA: LOG: YMAX 10 sets the YMAX value to 10.0000.

POWER:SOA:LOG:YMAX ? might return :POWER:SOA:LOG:YMAX 100.0000

indicating that the YMAX value for log plot type is set to 100.0000.

#### POWer:SOA:LOG:YMIN

Sets or returns the user YMIN value for use in Log SOA calculations.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:SOA:LOG:YMIN <NR3>

POWer:SOA:LOG:YMIN?

**Arguments** <NR3> is the YMIN value used for log SOA calculations.

**Examples** POWER:SOA:LOG:YMIN 1 sets the YMIN value to 1.0000.

POWER:SOA:LOG:YMIN? might return:POWER:SOA:LOG:YMIN 100.0000E-3

indicating that the YMIN value for log plot type is set to 100.0000E-3.

#### POWer:SOA:MASK:DEFine

Sets or returns the X (Volts) and Y (Amps) coordinates of the current SOA mask. You can specify the number of points from 2 to 10, minimum being 2. Successive X values must be  $\geq$  the preceding X values. The number of XY points sent determines the value of NR PT.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:SOA:MASK:DEFine <NR3>

POWer:SOA:MASK:DEFine?

**Arguments** <NR3> represents SOA mask coordinates.

**Examples** POWER: SOA: MASK: DEFINE 10 specifies the SOA mask coordinates as

POWER:SOA:MASK:DEFINE ? might return :POWER:SOA:MASK:DEFINE

0.0E+0,30.0000,25.0000,30.0000,300.0000,2.5000,300.0000,0.0E+0

indicating that the SOA mask coordinates are set to

0.0E+0.30.0000.25.0000.30.0000.300.0000.2.5000.300.0000.0.0E+0.

# POWer:SOA:MASK:MAXAmps

Sets or returns the maximum current applied to SOA mask testing.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:SOA:MASK:MAXAmps <NR3>

POWer:SOA:MASK:MAXAmps?

**Arguments** <NR3> is the maximum current applied to SOA mask testing.

**Examples** POWER: SOA: MASK: MAXAMPS 40 sets the SOA mask testing current to 40 A.

POWER: SOA: MASK: MAXAMPS? might return: POWER: SOA: MASK: MAXAMPS 30.0000 indicating that the SOA mask testing maximum current is set to 30 A.

#### POWer:SOA:MASK:MAXVolts

Sets or returns the maximum voltage applied to SOA mask testing.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:SOA:MASK:MAXVolts <NR3>

POWer:SOA:MASK:MAXVolts?

**Arguments** <NR3> is the maximum voltage applied to SOA mask testing.

**Examples** POWER: SOA: MASK: MAXVOLTS 200 sets the SOA mask testing voltage to 200 V.

POWER: SOA: MASK: MAXVOLTS? might return: POWER: SOA: MASK: MAXVOLTS 300.0000 indicating that the SOA mask testing maximum voltage is set to 300 V.

#### POWer:SOA:MASK:MAXWatts

Sets or returns the maximum power applied to SOA mask testing.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:SOA:MASK:MAXWatts <NR3>

POWer:SOA:MASK:MAXWatts?

**Arguments** <NR3> is the maximum power applied to SOA mask testing.

**Examples** POWER:SOA:MASK:MAXWATTS 1000 sets the SOA mask testing power to

1.0000E+3 W.

POWER: SOA: MASK: MAXWATTS ? might return: POWER: SOA: MASK: MAXWATTS 750.0000 indicating that the SOA mask testing maximum power is set to 750 W.

## POWer:SOA:MASK:NR\_PT? (Query Only)

Returns the number of mask points defined.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:SOA:MASK:NR\_PT?

**Examples** POWER:SOA:MASK:NR\_PT? might return:POWER:SOA:MASK:NR\_PT 4

indicating that the number of mask points defined is 4.

#### POWer:SOA:MASK:STATe

Sets or returns the state of the mask for SOA calculations.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:SOA:MASK:STATE {OFF|LIMITS|POINTS}

POWer:SOA:MASK:STATe?

**Arguments** OFF disables mask testing.

LIMITS enables mask testing based on limits specified using

POWer:SOA:MASK:MAXAmps, POWer:SOA:MASK:MAXVolts, and

POWer:SOA:MASK:MAXWatts commands

POINTS enables mask testing based on masks points defined.

**Examples** POWER: SOA: MASK: STATEPOINTS enables mask testing power based on points

defined.

POWER:SOA:MASK:STATE? might return:POWER:SOA:MASK:STATE LIMITS

indicating that the mask testing is enabled based on limits.

#### POWer:SOA:MASK:STOPOnviol

Sets or returns the enabled state of the mask stop on violation condition.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:SOA:MASK:STOPOnviol {OFF|ON|0|1}

POWer:SOA:MASK:STOPOnviol?

**Arguments** OFF or 0 enables mask stop on violations.

ON or 1 disables mask stop on violations.

**Examples** POWER:SOA:MASK:STOPONVIOL 1 disables the state of the mask stop on

violation condition.

POWER:SOA:MASK:STOPONVIOL ? might return

: POWER: SOA: MASK: STOPONVIOL 0 indicating that the mask stop is enabled.

#### POWer:SOA:PLOTTYPe

Sets or returns the Safe Operating Area (SOA) plot type.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:SOA:PLOTTYPe {LOG|LINear}

POWer:SOA:PLOTTYPe?

**Arguments** LOG for logarithmic SOA plot type.

LINear for linear SOA plot type.

**Examples** POWER: SOA: PLOTTYPE LINear sets the SOA plot type to Linear.

POWER: SOA: PLOTTYPE? might return: POWER: SOA: PLOTTYPE LOG indicating

that the SOA plot type is set to Log.

# POWer:SOA:RESult:FAILures:QTY? (Query Only)

Returns the number of failures in the test.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

**Syntax** POWer:SOA:RESult:FAILures:QTY?

**Examples** POWER:SOA:RESULT:FAILURES:QTY? might return

: POWER: SOA: RESULT: FAILURES 0 indicating that the number of failures is 0.

# POWer:SOA:RESult:NUMACq? (Query Only)

Returns the number of acquisitions in the test.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

**Syntax** POWer:SOA:RESult:NUMACq?

**Examples** POWER:SOA:RESULT:NUMACQ? might return:POWER:SOA:RESULT:NUMACQ

10 indicating that the number of acquisitions is 10.

# POWer:SOA:RESult:STATe? (Query Only)

Returns the pass/fail state of the SOA test.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:SOA:RESult:STATe?

**Returns** PASS or FAIL.

**Examples** POWER:SOA:RESULT:STATE? might return:POWER:SOA:MASK:STATE PASS

indicating that the SOA test state is PASS.

### **POWer:STATIstics (No Query Form)**

Clears all the accumulated statistics of all measurements. Performs the same

function as the MEASUrement:STATIstics command.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

**Syntax** POWer:STATIStics {RESET}

**Arguments** RESET clears the measurement statistics.

### POWer:STATIstics:MODE

Enables or disables the display of the measurement statistics. Performs the same

function as the MEASUrement: STATIstics: MODE command.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:STATIStics:MODE {OFF|ALL}

POWer:STATIstics:MODE?

**Arguments** ALL turns on measurement statistics display.

OFF turns all measurements statistics off.

**Examples** POWER: STATISTICS: MODE OFF turns measurements statistics display off.

POWER: STATISTICS: MODE? might return: MEASUREMENT: STATISTICS: MODE ALL indicating that measurement statistics are turned on and all statistics are

being displayed for each measurement.

## POWer:STATIstics:WEIghting

Sets the number of samples which are included for the statistics computations for mean and the standard deviation. Performs the same function as the

MEASUrement:STATIstics:WEIghting command.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:STATIstics:WEIghting <NR1>;Ranges {L,2,1000}

POWer:STATIstics:WEIghting?

**Arguments** <NR1> is the number of samples used for the mean and standard deviation

statistical accumulations

**Examples** POWER: STATISTICS: WEIGHTING 4 sets statistical weighting to four samples.

POWER:STATISTICS:WEIGHTING ? might return

: POWER: STATISTICS: WEIGHTING 4 indicating that statistics weighting is

currently set to 4 samples.

### POWer:SWLoss:CONDCALCmethod

Sets or returns the power application switching loss conduction calculation

method.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:SWLoss:CONDCALCmethod {VOLTage|RDSon|VCEsat}

POWer: SWLoss: CONDCALCmethod?

**Arguments** VOLTage sets voltage as the conduction calculation method.

RDSon sets RDSon as the conduction calculation method.

VCEsat sets VCEsat as the conduction calculation method.

**Examples** POWER: SWLOSS: CONDCALCMETHOD RDSon sets the conduction calculation

method to RDSon.

POWER: SWLOSS: CONDCALCMETHOD? might return

: POWER: SWLOSS: CONDCALCMETHOD VOLT indicating that the conduction

calculation method is set to Voltage.

# POWer:SWLoss:CONDuction:ENERGY:MAX? (Query Only)

Returns the maximum conduction energy for switching loss calculation.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:SWLoss:CONDuction:ENERGY:MAX?

**Examples** POWER:SWLOSS:CONDUCTION:ENERGY:MAX? might return

:POWER:SWLOSS:CONDUCTION:ENERGY:MAX 1 indicating that the maximum conduction energy switching loss calculation is set to 1 J.

# POWer:SWLoss:CONDuction:ENERGY:MEAN? (Query Only)

Returns the mean conduction energy in the conduction period for the switching loss calculation.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:SWLoss:CONDuction:ENERGY:MEAN?

**Examples** POWER:SWLOSS:CONDUCTION:ENERGY:MEAN? might return

: POWER: SWLOSS: CONDUCTION: ENERGY: MEAN 1 indicating that the mean

conduction energy switching loss calculation is set to 1 J.

#### POWer:SWLoss:CONDuction:ENERGY:MIN? (Query Only)

Returns the minimum conduction energy for the switching loss calculation.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:SWLoss:CONDuction:ENERGY:MIN?

**Examples** POWER: SWLOSS: CONDUCTION: ENERGY: MIN? might return

: POWER: SWLOSS: CONDUCTION: ENERGY: MIN 1 indicating that the minimum conduction energy switching loss calculation is set to 1 J.

# POWer:SWLoss:CONDuction:POWER:MAX? (Query Only)

Returns the maximum conduction power for the switching loss calculation.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:SWLoss:CONDuction:POWER:MAX?

**Examples** POWER:SWLOSS:CONDUCTION:POWER:MAX? might return

: POWER: SWLOSS: CONDUCTION: POWER: MAX 1 indicating that the maximum conduction power switching loss calculation is set to 1 W.

### POWer:SWLoss:CONDuction:POWER:MEAN? (Query Only)

Returns the mean conduction power for the switching loss calculation.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

**Syntax** POWer: SWLoss: CONDuction: POWER: MEAN?

**Examples** POWER: SWLOSS: CONDUCTION: POWER: MEAN? might return

: POWER: SWLOSS: CONDUCTION: POWER: MEAN 1 indicating that the mean conduction power switching loss calculation is set to 1 W.

#### POWer:SWLoss:CONDuction:POWER:MIN? (Query Only)

Returns the minimum conduction power for the switching loss calculation.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:SWLoss:CONDuction:POWER:MIN?

**Examples** POWER:SWLOSS:CONDUCTION:POWER:MIN? might return

: POWER: SWLOSS: CONDUCTION: POWER: MIN 1 indicating that the minimum conduction power switching loss calculation is set to 1 W.

# POWer:SWLoss:DISplay

Sets or returns the display selection for switching loss results: All measurements,

energy loss measurements or power loss measurements.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:SWLoss:DISplay {ALL|ENERGYLoss|POWERLoss}

POWer:SWLoss:DISplay?

**Arguments** ALL displays both energy and power loss measurements in the results.

ENERGYLOSS displays only energy loss measurements in the results.

POWERLOSS displays only power loss measurements in the results.

**Examples** POWER: SWLOSS: DISPLAY ENERGYLOSS displays only energy loss measurements

in the results.

POWER: SWLOSS: DISPLAY? might return: POWER: SWLOSS: DISPLAY ALL indicating that the results displays both energy and power loss measurements.

# POWer:SWLoss:GATe:POLarity

Sets or returns the switching loss gate polarity.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

**Syntax** POWer:SWLoss:GATe:POLarity {FALL|RISe}

POWer: SWLoss: GATe: POLarity?

**Arguments** FALL sets falling edge as the switching loss gate polarity.

RISe sets rising edge as the switching loss gate polarity.

**Examples** POWER: SWLOSS: GATE: POLARITY FALL sets the gate polarity to Fall.

POWER:SWLOSS:GATE:POLARITY ? might return

: POWER: SWLOSS: GATE: POLARITY RISE indicating that the gate polarity

is set to Rise.

#### POWer:SWLoss:GATe:TURNON

Sets or returns the gate turn on level for switching loss power measurements.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:SWLoss:GATe:TURNON <NR3>

POWer:SWLoss:GATe:TURNON?

**Examples** POWER: SWLOSS: GATE: TURNON 3.5 sets the gate turn on level to 3.5000.

POWER: SWLOSS: GATE: TURNON? might return: POWER: SWLOSS: GATE: TURNON

1.5 indicating that the gating turn on level is set to 1.5.

#### POWer:SWLoss:NUMCYCles? (Query Only)

Returns the number of cycles counted for the switching loss calculation.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:SWLoss:NUMCYCles? <NR3>

**Examples** POWER: SWLOSS: NUMCYCLES? might return the number of cycles for

switching loss calculation, if the POWer: TYPe is set to Switching Loss (POWer: TYPe: SWITCHingLoss). If the query times out with the Switching

Loss power enabled, it indicates the possibility of incorrect settings and might return the following:

\*ESR? 20 ALLEV?

2202,"Measurement error, No period found;

:power:swloss:numcycles?",410,"Query INTERRUPTED"

#### POWer:SWLoss:RDSon

Sets or returns the user RDSON value for use in switching loss calculations when the conduction calculation method is RDSON.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:SWLoss:RDSon <NR3>

POWer:SWLoss:RDSon?

**Arguments** <NR3> is the RDSON switching loss calculation.

**Examples** POWER: SWLOSS: RDSON 30 sets the RDSon value to 30.0000.

POWER:SWLOSS:RDSON? might return:POWER:SWLOSS:RDSon 20.0000E-3

indicating that the RDSon value is set to 20.0000E-3.

#### POWer:SWLoss:REFLevel:ABSolute:GATEMid

Sets or returns the mid voltage reference level used in switching loss power measurements in volts.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:SWLoss:REFLevel:ABSolute:GATEMid <NR3>

POWer:SWLoss:REFLevel:ABSolute:GATEMid?

**Arguments** <NR3> is the mid voltage reference level in volts.

**Examples** POWER: SWLOSS: REFLEVEL: ABSOLUTE: GATEMID 100 sets the absolute gate

mid reference voltage to 100.0000 V.

POWER: SWLOSS: REFLEVEL: ABSOLUTE: GATEMID? might return

:POWER:SWLOSS:REFLEVEL:ABSOLUTE:GATEMID 50.0000 indicating that

the gate mid reference voltage is set to 50.0000 V.

#### POWer:SWLoss:REFLevel:ABSolute:LOWCurrent

Sets or returns the low current reference level used in switching loss power measurements in amperes.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:SWLoss:REFLevel:ABSolute:LOWCurrent <NR3>

POWer:SWLoss:REFLevel:ABSolute:LOWCurrent?

**Arguments** <NR3> is the low voltage current level in amperes.

**Examples** POWER: SWLOSS: REFLEVEL: ABSOLUTE: LOWCURRENT 2.8 sets the absolute

reference low current to 2.8000 A.

POWER: SWLOSS: REFLEVEL: ABSOLUTE: LOWCURRENT? might return

: POWER: SWLOSS: REFLEVEL: ABSOLUTE: LOWCURRENT 5.0000 indicating that

the absolute reference low current is set to 5.0000 A.

# POWer:SWLoss:REFLevel:ABSolute:LOWVoltage

Sets or returns the low voltage reference level used in switching loss power

measurements in volts.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:SWLoss:REFLevel:ABSolute:LOWVoltage <NR3>

POWer:SWLoss:REFLevel:ABSolute:LOWVoltage?

**Arguments** <NR3> is the low voltage reference level in volts.

**Examples** POWER: SWLOSS: REFLEVEL: ABSOLUTE: LOWVOLTAGE 2.5 sets the absolute

reference low voltage to 2.5000 V.

POWER: SWLOSS: REFLEVEL: ABSOLUTE: LOWVOLTAGE? might return

:POWER:SWLOSS:REFLEVEL:ABSOLUTE:LOWVOLTAGE 5.0000 indicating that

the absolute reference low voltage is set to 5.0000 V.

#### POWer:SWLoss:REFLevel:PERCent:GATEMid

Sets or returns the mid voltage reference level used in switching loss power

measurements in percent.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:SWLoss:REFLevel:PERCent:GATEMid <NR3>

POWer:SWLoss:REFLevel:PERCent:GATEMid?

**Arguments** <NR3> is the mid voltage reference level in volts.

**Examples** POWER: SWLOSS: REFLEVEL: PERCENT: GATEMID 30 sets the gate mid reference

voltage to 30%.

POWER:SWLOSS:REFLEVEL:PERCENT:GATEMID ? might return

:POWER:SWLOSS:REFLEVEL:PERCENT:GATEMID 50.0000 indicating that the

gate mid reference voltage is set to 50%.

#### POWer:SWLoss:REFLevel:PERCent:LOWCurrent

Sets or returns the low current reference level used in switching loss power measurements in percent.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:SWLoss:REFLevel:PERCent:LOWCurrent <NR3>

POWer:SWLoss:REFLevel:PERCent:LOWCurrent?

**Arguments** <NR3> is the low voltage reference level percent.

**Examples** POWER: SWLOSS: REFLEVEL: PERCENT: LOWCURRENT 15 sets the reference low

current to 15%.

POWER:SWLOSS:REFLEVEL:PERCENT:LOWCURRENT? might return

: POWER: SWLOSS: REFLEVEL: PERCENT: LOWCURRENT 5.0000 indicating that

the reference low current is set to 5%.

### POWer:SWLoss:REFLevel:PERCent:LOWVoltage

Sets or returns the low voltage reference level used in switching loss power

measurements in percent.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:SWLoss:REFLevel:PERCent:LOWVoltage <NR3>

POWer:SWLoss:REFLevel:PERCent:LOWVoltage?

**Arguments** <NR3> is the low voltage reference level in percent.

**Examples** POWER: SWLOSS: REFLEVEL: PERCENT: LOWVOLTAGE 10 sets the reference low

voltage to 10%.

POWER: SWLOSS: REFLEVEL: PERCENT: LOWVOLTAGE? might return

: POWER: SWLOSS: REFLEVEL: PERCENT: LOWVOLTAGE 5.0000 indicating that

the reference low voltage is set to 5%.

# POWer:SWLoss:TOFF:ENERGY:MAX? (Query Only)

Returns the maximum Toff energy for the switching loss calculation.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:SWLoss:TOFF:ENERGY:MAX?

**Examples** POWER:SWLOSS:TOFF:ENERGY:MAX? might return

: POWER: SWLOSS: TON: ENERGY: MAX 1 indicating that the maximum Toff energy

switching loss calculation is set to 1 J.

# POWer:SWLoss:TOFF:ENERGY:MEAN? (Query Only)

Returns the mean Toff energy for the switching loss calculation.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:SWLoss:TOFF:ENERGY:MEAN?

**Examples** POWER:SWLOSS:TOFF:ENERGY:MEAN? might return

: POWER: SWLOSS: TON: ENERGY: MEAN 1 indicating that the mean Toff energy

switching loss calculation is set to 1 J.

# POWer:SWLoss:TOFF:ENERGY:MIN? (Query Only)

Returns the minimum Toff energy for the switching loss calculation.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:SWLoss:TOFF:ENERGY:MIN?

**Examples** POWER:SWLOSS:TOFF:ENERGY:MIN? might return

: POWER: SWLOSS: TON: ENERGY: MIN 1 indicating that the minimum Toff energy

switching loss calculation is set to 1 J.

# POWer:SWLoss:TOFF:POWER:MAX? (Query Only)

Returns the maximum Toff power for the switching loss calculation.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:SWLoss:TOFF:POWER:MAX?

**Examples** POWER:SWLOSS:TOFF:POWER:MAX? might return

: POWER: SWLOSS: TON: POWER: MAX 1 indicating that the maximum Toff power

switching loss calculation is set to 1 W.

# POWer:SWLoss:TOFF:POWER:MEAN? (Query Only)

Returns the mean Toff power for the switching loss calculation.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:SWLoss:TOFF:POWER:MEAN?

**Examples** POWER:SWLOSS:TOFF:POWER:MEAN? might return

: POWER: SWLOSS: TON: POWER: MEAN 1 indicating that the mean Toff power

switching loss calculation is set to 1 W.

#### POWer:SWLoss:TOFF:POWER:MIN? (Query Only)

Returns the minimum Toff power for the switching loss calculation.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:SWLoss:TOFF:POWER:MIN?

**Examples** POWER:SWLOSS:TOFF:POWER:MIN? might return

: POWER: SWLOSS: TON: POWER: MIN 1 indicating that the minimum Toff power

switching loss calculation is set to 1 W.

#### POWer:SWLoss:TON:ENERGY:MAX? (Query Only)

Returns the maximum Ton energy for the switching loss calculation.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

**Syntax** POWer:SWLoss:TON:ENERGY:MAX?

**Examples** POWER:SWLOSS:TON:ENERGY:MAX? might return

: POWER: SWLOSS: TON: ENERGY: MAX 1 indicating that the maximum Ton energy

switching loss calculation is set to 1 J.

# POWer:SWLoss:TON:ENERGY:MEAN? (Query Only)

Returns the mean Ton energy for the switching loss calculation.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:SWLoss:TON:ENERGY:MEAN?

**Examples** POWER:SWLOSS:TON:ENERGY:MEAN? might return

:POWER:SWLOSS:TON:ENERGY:MEAN 1 indicating that the mean Ton energy

switching loss calculation is set to 1 J.

# POWer:SWLoss:TON:ENERGY:MIN? (Query Only)

Returns the minimum Ton energy for the switching loss calculation.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

**Syntax** POWer:SWLoss:TON:ENERGY:MIN?

**Examples** POWER:SWLOSS:TON:ENERGY:MIN? might return

: POWER: SWLOSS: TON: ENERGY: MIN 1 indicating that the minimum Ton energy

switching loss calculation is set to 1 J.

# POWer:SWLoss:TON:POWER:MAX? (Query Only)

Returns the maximum Ton power for the switching loss calculation.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

**Syntax** POWer:SWLoss:TON:POWER:MAX?

**Examples** POWER:SWLOSS:TON:POWER:MAX? might return

: POWER: SWLOSS: TON: POWER: MAX 1 indicating that the maximum Ton power

switching loss calculation is set to 1 W.

# POWer:SWLoss:TON:POWER:MEAN? (Query Only)

Returns the mean Ton power for the switching loss calculation.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:SWLoss:TON:POWER:MEAN?

**Examples** POWER:SWLOSS:TON:POWER:MEAN? might return

: POWER: SWLOSS: TON: POWER: MEAN 1 indicating that the mean Ton power

switching loss calculation is set to 1 W.

# POWer:SWLoss:TON:POWER:MIN? (Query Only)

Returns the minimum Ton power for the switching loss calculation.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

**Syntax** POWer:SWLoss:TON:POWER:MIN?

**Examples** POWER:SWLOSS:TON:POWER:MIN? might return

: POWER: SWLOSS: TON: POWER: MIN 1 indicating that the minimum Ton power

switching loss calculation is set to 1 W.

# POWer:SWLoss:TOTal:ENERGY:MAX? (Query Only)

Returns the maximum total energy for the switching loss calculation.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

**Syntax** POWer:SWLoss:TOTal:ENERGY:MAX?

**Examples** POWER:SWLOSS:TOTAL:ENERGY:MAX? might return

:POWER:SWLOSS:TOTAL:ENERGY:MAX 1 indicating that the maximum

conduction energy switching loss calculation is set to 1 J.

#### POWer:SWLoss:TOTal:ENERGY:MEAN? (Query Only)

Returns the mean total energy for the switching loss calculation.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

**Syntax** POWer:SWLoss:TOTal:ENERGY:MEAN?

**Examples** POWER:SWLOSS:TOTAL:ENERGY:MEAN? might return

:POWER:SWLOSS:TOTAL:ENERGY:MEAN 1 indicating that the mean conduction

energy switching loss calculation is set to 1 J.

### POWer:SWLoss:TOTal:ENERGY:MIN? (Query Only)

Returns the minimum total energy for the switching loss calculation.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:SWLoss:TOTal:ENERGY:MIN?

**Examples** POWER: SWLOSS: TOTAL: ENERGY: MIN? might return

: POWER: SWLOSS: TOTAL: ENERGY: MIN 1 indicating that the minimum

conduction energy switching loss calculation is set to 1 J.

#### POWer:SWLoss:TOTal:POWER:MAX? (Query Only)

Returns the maximum total power loss.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

**Syntax** POWer:SWLoss:TOTal:POWER:MAX?

**Examples** POWER:SWLOSS:TOTAL:POWER:MAX? might return

: POWER: SWLOSS: TOTAL: POWER: MAX 1 indicating that the maximum total

power switching loss calculation is set to 1 W.

# POWer:SWLoss:TOTal:POWER:MEAN? (Query Only)

Returns the mean total power loss.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

**Syntax** POWer:SWLoss:TOTal:POWER:MEAN?

**Examples** POWER:SWLOSS:TOTAL:POWER:MEAN? might return

: POWER: SWLOSS: TOTAL: POWER: MEAN 1 indicating that the mean total power

switching loss calculation is set to 1 W.

# POWer:SWLoss:TOTal:POWER:MIN? (Query Only)

Returns the minimum total power loss.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

**Syntax** POWer:SWLoss:TOTal:POWER:MIN?

**Examples** POWER:SWLOSS:TOTAL:POWER:MIN? might return

: POWER: SWLOSS: TOTAL: POWER: MIN 1 indicating that the minimum total

power switching loss calculation is set to 1 W.

### POWer:SWLoss:VCEsat

Sets or returns VCESAT value for use in switching loss calculations when the

conduction calculation method is VCESAT.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:SWLoss:VCEsat <NR3>

POWer: SWLoss: VCEsat?

**Arguments** <NR3> is the VCEsat switching loss calculation.

**Examples** POWER: SWLOSS: VCESAT 5 sets the VCEsat value to 5.0000.

POWER:SWLOSS:VCESAT ? might return :POWER:SWLOSS:VCEsat 2.0000

indicating that the VCEsat value is set to 2.0000.

POWer:TYPe

Sets or returns the power application measurement type.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer:TYPe {NONe|QUALity|SWITCHingloss|SOA

| HARMonics | RIPPle | MODULationanalysis | DESKew }

POWer:TYPe?

**Arguments** NONe Use to set the measurement type to None.

QUALity Use the power quality functions to obtain measurements and statistics about the general power quality in your test circuit

SWITCHingloss Use the switching loss functions to obtain the power loss and energy loss across the acquired waveform, including turn-on loss, turn-off loss, conduction loss, and total loss. Typically, use these functions to characterize losses in power supply switching devices, as they switch on and off.

SOA Use the safe operating functions to obtain an X-Y display of the switching device-under-test's voltage and current. Also use them to perform a mask test of the X-Y signal relative to the graphical X-Y description of the device specification table. The safe operating area is typically the voltage and current values that a semiconductor can operate without damaging itself.

HARMonics Use the harmonics functions to obtain the frequency spectrum of the source waveform and associated measurement values. Harmonic measurements can help one perform in-depth troubleshooting of power quality problems.

RIPPle Use the ripple functions to obtain measurements and statistics for the AC components of the acquired waveform. Ripples are often found on top of a large DC signal.

MODULationanalysis Use the modulation functions to obtain a trend plot of a measurement value across the acquired waveform. This is useful for showing the variations in the modulated switching signal.

DESKew Run the deskew procedure to match the delays through the probes. Different probes introduce different delays between the probe tip and the

oscilloscope. Many oscilloscope users do not have to worry about this because they use the same type of probe on all channels. Power measurement users, however, frequently use both a voltage probe and a current probe. A current probe typically has a larger delay than a voltage probe, so setting deskew values becomes important.

**Examples** POWER: TYPE HARMonics sets the measurement type to Harmonics.

POWER: TYPE? might return POWER: TYPE NON indicating that no measurement type is set.

#### POWer: VOLTAGESOurce

Sets or returns the voltage source for the power application.

**Conditions** This command requires a DPO4PWR application module.

**Group** Power

Syntax POWer: VOLTAGESOurce {CH1|CH2|CH3|CH4|REF1|REF2|REF3|REF4}

POWer: VOLTAGESOurce?

**Arguments** CH1-CH4 or REF1-REF4 sets channel or ref as the voltage source.

**Examples** POWER: VOLTAGESOURCE CH1 sets the voltage source as CH1.

POWER: VOLTAGESOURCE? might return POWER: VOLTAGESOURCE CH1 indicating

that the voltage source is set to CH1.

\*PSC

Sets or returns the power-on status flag that controls the automatic power-on handling of the DESER, SRER, and ESER registers. When \*PSC is true, the DESER register is set to 255 and the SRER and ESER registers are set to 0 at power-on. When \*PSC is false, the current values in the DESER, SRER, and ESER registers are preserved in nonvolatile memory when power is shut off and

are restored at power-on.

**Group** Status and Error

Syntax \*PSC {OFF|ON|NR1>}

\*PSC?

Related Commands DESE, \*ESE, FACtory, \*RST, \*SRE

**Arguments** OFF sets the power-on status clear flag to false.

ON sets the power-on status clear flag to true.

<NR1> = 0 sets the power-on status clear flag to false. This disables the power-on clear allowing the oscilloscope to possibly assert SRQ after power-on; any other value sets the power-on status clear flag to true, enabling the power-on status clear preventing any SRQ assertion after power on.

\*PSC 0 sets the power-on status clear flag to false.

\*PSC? might return 1 to indicate that the power-on status clear flag is set to true.

\*PUD

Sets or returns a string of Protected User Data. This data is protected by the PASSWord command. You can modify it only by first entering the correct password. This password is not necessary to query the data.

**Group** Status and Error

Syntax \*PUD {<Block>|<QString>}
 \*PUD?

Related Commands PASSWord

**Examples** 

**Arguments** <Block> is a block containing up to 300 ASCII characters.

<QString> is a string containing up to 300 ASCII characters.

**Examples** \*PUD #229This oscilloscope belongs to me stores the string "This

oscilloscope belongs to me" in the user protected data area.

\*PUD? might return #221PROPERTY OF COMPANY X

# \*RCL (No Query Form)

This command restores the state of the oscilloscope from a copy of the settings stored in memory (The settings are stored using the \*SAV command).

**Group** Save and Recall

Syntax \*RCL <NR1>

Related Commands FACtory, \*LRN?, RECAll:SETUp, \*RST, \*SAV, SAVe:SETUp

**Arguments** <NR1> is a value in the range from 1 to 10, which specifies a saved setup storage

location.

**Examples** \*RCL 3 restores the oscilloscope from a copy of the settings stored in memory

location 3.

### RECAII:SETUp (No Query Form)

Restores the state of the oscilloscope from a copy of the settings stored in memory. The settings are stored using the \*SAV command.

**Group** Save and Recall

Syntax RECAll:SETUP {FACtory|<NR1>|<file path>}

Related Commands FACtory, \*RCL, \*RST, \*SAV, SAVe:SETUp, FILESystem:CWD

**Arguments** FACtory restores the factory setup.

<NR1> is a value in the range from 1 to 10, which specifies a saved setup storage

location.

<file path> specifies a location for an oscilloscope setup file. <file path> is
a quoted string that defines the file name and path. Input the file path using the
form <drive>:/<dir>/<filename>.<extension> and one or <dir>s are
optional. If you do not specify them, the oscilloscope will read the file from the
default directory (see FILESystem:CWD). <filename> stands for a filename; the
use of wildcard characters in filenames is not supported. Filename extensions are
not required, but highly recommended.

**Examples** 

RECALL: SETUP FACTORY recalls (and makes current) the oscilloscope setup

to its factory defaults.

RECALL: SETUP 2 recalls the oscilloscope setup from setup storage location 2.

RECALL: SETUP "TEK00000 . SET" recalls the setup from the file TEK00000.SET

in the current working directory.

# **RECAII:WAVEform (No Query Form)**

This command (no query form) recalls a stored waveform to a reference location.

Group

Save and Recall

**Syntax** 

RECAll:WAVEform <file path>,REF<x>

**Related Commands** 

SAVe: WAVEform, FILESystem: CWD, FILESystem?

**Arguments** 

REF<x> specifies a location in internal reference memory. Reference memory location values range from 1 through 4.

<file path> specifies a location for an oscilloscope setup file. <file path> is
a quoted string that defines the file name and path. Input the file path using the
form <drive>:/<dir>/<filename>.<extension> and one or <dir>s are
optional. If you do not specify them, the oscilloscope will read the file from the
default directory (see FILESystem:CWD). <filename> stands for a filename; the
use of wildcard characters in filenames is not supported. Filename extensions are
not required, but highly recommended.

**Examples** 

RECALL: WAVEFORM "TEK00000.ISF", REF1 recalls the waveform stored in the file named TEK00000.ISF from the current directory for waveforms to the reference location 1.

### REF<x>? (Query Only)

Returns reference waveform data for the channel specified by  $\leq x >$ , where x is the reference channel number.

Group

Vertical

**Syntax** 

REF<x>?

# REF<x>:DATE? (Query Only)

Returns the date that reference waveform data for channel  $\langle x \rangle$  was copied into the internal reference memory, where x is the reference channel number.

**Group** Vertical

**Syntax** REF<x>:DATE?

### REF<x>:HORizontal:DELay:TIMe

Sets or returns the horizontal delay time for reference waveform  $\langle x \rangle$ , where x is the reference channel number. The delay time is expressed in seconds and is limited to  $\pm 5$  times the reference horizontal scale.

**Group** Vertical

Syntax REF<x>:HORizontal:DELay:TIMe <NR3>

REF<x>:HORizontal:DELay:TIMe?

**Arguments** <NR3> is the delay time in seconds.

**Examples** REF2:HORIZONTAL:DELAY:TIME 4.0E-6 sets the horizontal delay time for

the REF2 waveform to 4 µs.

#### REF<x>:HORizontal:SCAle

Sets or returns the horizontal scale for reference waveform  $\langle x \rangle$ , where x is the reference channel number.

**Group** Vertical

Syntax REF<x>:HORizontal:SCAle <NR3>

REF<x>:HORizontal:SCAle?

**Arguments** <NR3> is the horizontal scale in seconds.

**Examples** REF1:HORIZONTAL:SCALE? might return REF1:HORIZONTAL:SCALE 4.0E-4.

#### REF<x>:LABel

Sets or returns the reference waveform label for the channel specified by  $\langle x \rangle$ , where x is the reference channel number.

**Group** Vertical

Syntax REF<x>:LABel <Qstring>

REF<x>:LABel?

**Arguments** <Qstring> is an alphanumeric string of text, enclosed in quotes, that contains

the label text for the reference channel <x> waveform. The text string is limited

to 30 characters.

**Examples** REF4:LABEL? might return: REF4:LABEL "Clk wfm 2".

### REF<x>:TIMe? (Query Only)

Returns the time that reference waveform data was copied into the internal reference memory for reference channel <x>, where x is the reference channel number.

**Group** Vertical

**Syntax** REF<x>:TIMe?

**Examples** REF4:TIME? might return "16:54:05".

#### REF<x>:VERTical:POSition

Sets or returns the vertical position of the reference waveform specified by  $\langle x \rangle$ , where x is the reference channel number.

Increasing the position value of a waveform causes the waveform to move up, and decreasing the position value causes the waveform to move down. Position adjusts only the display position of a waveform. The position value determines the vertical graticule coordinate at which signal values are displayed. For example, if the position for Reference 3 is set to 2.0, the signal represented by that reference will be displayed at 2.0 divisions above the center of the screen.

**Group** Vertical

Syntax REF<x>:VERTical:POSition <NR3>

REF<x>:VERTical:POSition?

**Related Commands** CH<x>:POSition, MATH[1]:VERTical:POSition

**Arguments** <NR3> is the desired position, in divisions from the center horizontal graticule.

The range is from -5.0 to 5.0 divisions.

**Examples** REF2:VERTICAL:POSITION 1.3E+00 positions the Reference 2 input signal

1.3 divisions above the center horizontal graticule.

REF1: VERTICAL: POSITION? might return: REF1: VERTICAL: POSITION -1.3000E+00 indicating that the current position of Reference 1 is 1.3 divisions

below the center horizontal graticule.

#### REF<x>:VERTical:SCAle

Sets or returns the vertical scale for the reference waveform specified by  $\langle x \rangle$ , where x is the reference channel number.

Each waveform has a vertical scale parameter. For a signal with constant amplitude, increasing the Scale causes the waveform to be displayed smaller. Decreasing the scale causes the waveform to be displayed larger.

Scale affects all waveforms, but affects reference and math waveforms differently from channel waveforms:

- For reference and math waveforms, this setting controls the display only, graphically scaling these waveforms and having no affect on the acquisition hardware.
- For channel waveforms, this setting controls the vertical size of the acquisition window as well as the display scale. The range and resolution of scale values depends on the probe attached and any other external factors you have specified.

**Group** Vertical

Syntax REF<x>:VERTical:SCAle <NR3>

REF<x>:VERTical:SCAle?

**Related Commands** CH<x>:SCAle, MATH[1]:VERTical:SCAle

**Arguments** <NR3> is the gain in user units-per-division.

**Examples** REF4: VERTICAL: SCALE 100E-03 sets the Reference 4 scale to 100 mV per

division.

REF4:VERTICAL:SCALE? might return :REF2:VERTICAL:SCALE

1.0000e+00 indicating that the current vertical scale setting for Reference 2 is

1 V per division.

# **REM (No Query Form)**

Embeds a comment within programs as a means of internally documenting the programs. The oscilloscope ignores these embedded comment lines.

**Group** Miscellaneous

Syntax REM <QString>

**Arguments** <QString> is a string that can contain a maximum of 80 characters.

**Examples** REM "This is a comment" is a comment string that the oscilloscope will

ignore.

# \*RST (No Query Form)

Resets the oscilloscope to the factory default settings. The \*RST command does not alter the following:

- Calibration data that affect device specifications
- The Output Queue
- The Service Request Enable Register setting
- The Power-on status clear flag setting
- Alias definitions
- Stored settings
- The \*PUD? Response
- Any of the values associated with the DATA command.
- Oscilloscope password

**Group** Status and Error

Syntax \*RST

Related Commands FACtory, RECAll:SETUp, SAVe:SETUp, \*PSC, \*RCL, \*SAV

**Arguments** None

**Examples** \*RST resets the oscilloscope settings to factory defaults.

#### \*SAV (No Query Form)

Stores the state of the oscilloscope to a specified memory location. You can use the \*RCL command to restore the oscilloscope to this saved state at a later time.

**Group** Save and Recall

Syntax \*SAV <NR1>

Related Commands \*RCL, RECAll:SETUp, SAVe:SETUp

**Arguments** <NR1> specifies a location in which to save the state of the oscilloscope. Location

values range from 1 through 10. Using an out-of-range location value causes an execution error. Any settings that have been stored previously at this location

will be overwritten.

**Examples** \*SAV 2 saves the current oscilloscope state in memory location 2.

SAVe: ASSIgn: TYPe

Sets or returns the assignment of the data to be saved when the front-panel Save

button is pressed.

**Group** Save and Recall

Syntax SAVe:ASSIgn:TYPe {IMAGe|WAVEform|SETUp}

SAVe: ASSIgn: TYPe?

**Arguments** IMAGe assigns the Save button to save screen images.

WAVEform assigns the Save button to save waveforms.

SETUP assigns the Save button to save setups.

#### SAVe:EVENTtable:BUS<x> (No Query Form)

Saves the data from bus<x> to a specified file and location; where x is the bus number

**Group** Save and Recall

Syntax SAVe:EVENTtable:BUS<x> <file path>

**Arguments** <file path> is a quoted string that defines the file name and path location where the event table will be stored.

**NOTE.** <filename> stands for a filename of up to 125 characters, followed by a period (".") and the three-character extension. Waveform files should have a .csv extension for comma-separated spreadsheet format files.

# SAVe:IMAGe (No Query Form)

Saves a capture of the screen image into the specified file. Supported image formats are PNG, Windows Bitmap, and TIFF. If an extension for a supported file type is added to the file name, then the corresponding format will be used. If no supported extension is added to the file, the format to use will be determined by the value obtained from the :SAVe:IMAGe;FILEFormat? query.

**Group** Save and Recall

Syntax SAVe:IMAGe <file path>

**Related Commands** SAVe:ASSIgn:TYPe

**Arguments** <file path> is a filename, including path, where the image will be saved.

If you do not specify a directory, the oscilloscope will store the file in the current working directory. File name extensions are not required but are highly

recommended. The path "D:/foo.png" will save an image to the file "foo.png" on the Compact Flash card.

#### SAVe:IMAGe:FILEFormat

Sets or returns the file format to use for saving screen images.

**NOTE.** The file format is not automatically determined by the file name extension. You need to choose a file format with an extension which is consistent with the selected file format.

**Group** Save and Recall

Syntax SAVe:IMAGe:FILEFormat {PNG|BMP|TIFf}

SAVe: IMAGe: FILEFormat?

Related Commands SAVe:IMAGe

**Arguments** PNG saves the file in Portable Network Graphics format.

BMP saves the file in Microsoft Windows bitmap format.

TIFf saves the file in Tagged Image File Format.

#### SAVe:IMAGe:INKSaver

Sets or returns the current ink saver setting for the SAVe:IMAGe command. If set to "ON" or "1", images will be generated using the ink saver palette. If set to "OFF" or "0", images will be generated using the standard palette.

**Group** Save and Recall

**Syntax** SAVe:IMAGe:INKSaver {OFF|ON|0|1}

SAVe: IMAGe: INKSaver?

Related Commands SAVe:IMAGe

**Arguments** OFF or 0 generates images from the Inksaver palette.

ON or 1 generates images using the Standard palette.

#### SAVe:IMAGe:LAYout

Sets or returns the layout to use for saved screen images.

**Group** Save and Recall

Syntax SAVe:IMAGe:LAYout {LANdscape|PORTRait}

SAVe: IMAGe: LAYout?

**Arguments** LANdscape specifies that screen images are saved in landscape format.

PORTRait specifies that screen images are saved in portrait format.

#### SAVe:SETUp (No Query Form)

Stores the state of the oscilloscope to a specified memory location. You can later use the \*RCL command to restore the oscilloscope to this saved state.

**Group** Save and Recall

**Syntax** SAVe:SETUp {<file path>|<NR1>}

Related Commands \*RCL, RECAll:SETUp, \*SAV

**Arguments** 

<file path> is the target location for storing the setup file. <file path> is a quoted string that defines the file name and path. Input the file path using the form <driv>:<dir>/<filename>. <extension> and one or <dir>s are optional. If you do not specify them, the oscilloscope will store the file in the current working directory. <filename> stands for a filename. (Use of wildcard characters in filenames is not supported.) Filename extensions are not required but are highly recommended. For setups, use the extension ".SET".

<NR1> specifies a location for saving the current front-panel setup. The front-panel setup value ranges from 1 to 10. Using an out-of-range value causes an execution error. Any settings that have been stored previously at this location will be overwritten.

**Examples** SAVE: SETUP 5 saves the current oscilloscope setup in memory location 5.

SAVE: SETUP "TEK00000. SET" saves the current oscilloscope setup in the file TEK00000. SET in the current working directory.

### SAVe:WAVEform (No Query Form)

This command saves a specified waveform or all displayed waveforms (excluding serial bus waveforms). Only individual analog waveforms (CH<x>, MATH and REF<x>) can be saved to reference memory locations.

You can save all displayed waveforms, excluding serial bus waveforms, to a single CSV file when the SAVE: WAVEFORM: FILEFORMAT is set to SPREADSHEET.

You can save all displayed waveforms, excluding serial bus waveforms and digital channels (MSO models) to consecutive ISF (internal save format) files when the SAVE: WAVEFORM: FILEFORMAT is set to INTERNAL.

**Group** Save and Recall

Related Commands RECAll: WAVEform, SAVe: WAVEform: FILEFormat

#### **Arguments**

<wfm>, <REF<x>> saves the specified waveform to the specified reference memory location. <wfm> can be any live analog channel (where <x> is the channel number), the MATH1 waveform, or another reference waveform (such as REF1).

<wfm>, <QString> saves the specified waveform to the file specified in the quoted string argument. Any live channel (such as CH1), the MATH1 waveform, any reference waveform, and, for MSO models, digital waveforms (such as D0) can be saved to a file. Digital waveforms can only be saved when the SAVE: WAVEFORM: FILEFORMAT is set to SPREADSHEET.

ALL, <QString> saves all displayed waveforms, excluding serial bus waveforms, to a single CSV file specified by the quoted string argument when the SAVE:WAVEFORM:FILEFORMAT is set to SPREADSHEET, or saves all displayed waveforms, excluding serial bus waveforms and digital channel waveforms (MSO models), to individual ISF (internal save format) files with a file name prefix specified by the argument with an underscore (\_) and the waveform ID (such as CH1, REF1, MATH) appended to the file name(s).

#### **Examples**

SAVE: WAVEFORM CH1, REF1 saves the CH1 waveform in reference memory location 1.

:SAVE:WAVEFORM: FILEFORMAT SPREADSHEET; :SAVE:WAVEFORM ALL, "D:/test\_folder/test1\_all.csv" saves all displayed waveforms (excluding serial bus waveforms) to D:/test\_folder/test1\_all.csv.

:SAVe:WAVEform:FILEFormat INTERNal; :SAVe:WAVEform ALL,
"D:/test\_folder/test1" saves all displayed waveforms (excluding serial
bus waveforms and digital channels for MSO models) to individual files named
D:/test\_folder/test1\_<wfm>.isf (for example test1\_CH1.isf).

#### SAVe:WAVEform:FILEFormat

Specifies or returns the file format for saved waveforms. Waveform header and timing information is included in the resulting file of non-internal formats. The oscilloscope saves DPO waveforms as a 500 x 200 matrix, with the first row corresponding to the most recently acquired data. The values specified by DATa:STARt and DATa:STOP determine the range of waveform data to output. In the event that DATa:STOP value is greater than the current record length, the current record length determines the last output value.

**Group** Save and Recall

Syntax

SAVe:WAVEform:FILEFormat {INTERNal|SPREADSheet}

SAVe: WAVEform: FILEFormat?

Related Commands CURVe, DATa, DATa:STARt, DATa:STOP, SAVe:WAVEform,

WFMInpre:NR Pt, WFMOutpre:NR Pt?

Arguments INTERNal specifies that waveforms are saved in an internal format, using a .isf

filename extension. These files can be recalled as reference waveforms. When this argument is specified, the settings specified via the DATa:STARt and DATa:STOP

commands have no meaning as the entire waveform is saved.

SPREADSheet specifies that waveform data is saved in a format that contains comma delimited values. These waveform data files are named using the .csv filename extension. Saving waveforms in CSV format enables spreadsheet

programs to import the data.

**Examples** SAVE: WAVEFORM: FILEFORMAT INTERNAL specifies that the internal file format

is the format used for saving waveforms.

SAVE: WAVEFORM: FILEFORMAT? might return: SAVE: WAVEFORM: FILEFORMAT

INTERNAL indicating that waveforms are saved using the internal format.

# SAVe:WAVEform:GATIng

Specifies whether save waveform operations should save the entire waveform (NONe) or a specified portion of the waveform.

**Group** Save and Recall

Syntax SAVe:WAVEform:GATIng {NONe|CURSors|SCREEN}

SAVe: WAVEform: GATIng?

**Arguments** CURSors turns on cursors and the gates are the waveform record points at the

cursor positions.

NONe saves the entire waveform.

SCREEN, if zoom is on, the gates are the start and end waveform record points of the zoom (upper) graticule, otherwise the gates are the start and end waveform

record points of the main graticule.

**Examples** SAVE: WAVEFORM: GATING CURSOrs specifies that, when the waveform gating

is set to cursors, save waveform operations should save the waveform points between the cursors. If cursors are turned off, waveform gating automatically

reverts to NONE.

### **SEARCH?** (Query Only)

Returns all search-related settings.

**Group** Search

Syntax SEARCH?

**Examples** SEARCH? might return:

:SEARCH:SEARCH1:TRIG:A:BUS:B1:SPI:COND SS;DAT:MOSI:VAL

"XXXXXXXX";:SEARCH:SEARCH1:TRIG:A:BUS:B1:SPI: DAT:MISO:VAL

"XXXXXXXX";:SEARCH:SEARCH1:TRIG:A:BUS:B1:SPI:DAT:SIZ

1;:SEARCH:SEARCH1:TRIG:A:BUS:B1:I2C:COND

STAR; DAT: VAL "XXXXXXXXX"; SIZ 1; DIR

NOCARE;:SEARCH:SEARCH1:TRIG:A:BUS:B1:I2C:ADDR:MOD ADDR7;TYP USER;VAL "XXXXXXX";:SEARCH:SEARCH1:TRIG:A:BUS:B1:CAN:COND

SOF; FRAME DATA; DAT: VAL "XXXXXXXX"; SIZ 1; D IR

NOCARE; QUAL EQU; :SEARCH: SEARCH1: TRIG: A:BUS: B1: CAN: ID: MOD

ST; VAL "XXXXXXXXXXX"; : SEARCH: SEARCH1: TRI

G:A:BUS:B2:SPI:COND SS;DAT:MOSI:VAL

"XXXXXXXX";:SEARCH:SEARCH1:TRIG:A:BUS:B2:SPI:DAT:MISO:VAL

"XXXXX XXX";:SEARCH:SEARCH1:TRIG:A:BUS:B2:SPI:DAT:SIZ

1;:SEARCH:SEARCH1:TRIG:A:BUS:B2:I2C:COND

STAR; DAT: VAL "XXXXXXXXX"; SIZ 1; DIR NOCARE;:SEARCH:SEARCH1:TRIG:A:BUS:B2:I2C:ADDR:MOD ADDR7;TYP USER; VAL "XXXXXXX" ;: SEARCH: SEARCH1: TRIG: A: BUS: B2: CAN: COND SOF; FRAME DATA; DAT: VAL "XXXXXXXX"; SIZ 1; DIR NOCARE; QUAL EQU; :SEARCH:SEARCH1:TRIG:A:BUS:B2:CAN:ID:MOD ST;VAL "XXXXXXXXXXX";:SEARCH:SEARCH1:TRIG:A:BUS:SOU B1;:SEA RCH:SEARCH1:TRIG:A:TYP EDG;LEV 0.0000;LEV:CH1 0.0000;CH2 0.0000;CH3 0.0000;CH4 0.0000;MATH 0.0000; RE F1 0.0000; REF2 0.0000; REF3 0.0000; REF4 0.0000;:SEARCH:SEARCH1:TRIG:A:UPP:CH1 800.0000E-3;CH2 800.000 0E-3;CH3 800.0000E-3;CH4 800.0000E-3;MATH 800.0000E-3;REF1 800.0000E-3;REF2 800.0000E-3;REF3 800.000 0E-3; REF4 800.0000E-3;: SEARCH: SEARCH1: TRIG: A:LOW: CH1 0.0000; CH2 0.0000; CH3 0.0000; CH4 0.0000; MATH 0. 0000; REF1 0.0000; REF2 0.0000; REF3 0.0000; REF4 0.0000;:SEARCH:SEARCH1:TRIG:A:EDGE:SOU CH1;SL0 RIS;:SE ARCH:SEARCH1:TRIG:A:LOGI:FUNC AND;THR:CH1 0.0000; CH2 0.0000; CH3 0.0000; CH4 0.0000; MATH 0.0000; REF1 0 .0000; REF2 0.0000; REF3 0.0000; REF4 0.0000;:SEARCH:SEARCH1:TRIG:A:LOGI:INP:CH1 X;CH2 X;CH3 X;CH4 X;MA TH X;REF1 X;REF2 X;REF3 X;REF4 X;CLOC:SOU NONE; EDGE RIS; :SEARCH: SEARCH1: TRIG: A:LOGI: PAT: INP: CH1 X;CH 2 X;CH3 X;CH4 X;MATH X;REF1 X;REF2 X;REF3 X;REF4 X;:SEARCH:SEARCH1:TRIG:A:LOGI:PAT:WHE TRU;WHE:LESSL 8.0000E-9;L 8.0000E-9;:SEARCH:SEARCH1:TRIG:A:PULSEW:SOU CH1; POL POS; WHE LESS; WID 8.0000E-9; SEA RCH:SEARCH1:TRIG:A:RUNT:SOU CH1;POL POS;WHE OCCURS;WID 8.0000E-9;:SEARCH:SEARCH1:TRIG:A:TRAN:SOU CH1 ;POL POS;WHE SLOW; DELT 8.0000E-9;: SEARCH: SEARCH1: TRIG: A: SETH: CLOC: SOU CH1; EDGE RIS; THR 0.0000; :SEARC H:SEARCH1: TRIG: A:SETH:DAT:SOU CH2; THR 0.0000; :SEARCH: SEARCH1: TRIG: A: SETH: HOLDT 8.0000E-9;SETT 8.0000 E-9;:SEARCH:SEARCH1:STATE 0

### SEARCH:SEARCH<x>:COPy (No Query Form)

Copies the search criteria to the trigger, or the trigger criteria to a search. <x> is the search number.

**Group** Search

Syntax SEARCH:SEARCH<x>:COPy {SEARCHtotrigger|TRIGgertosearch}

**Arguments** SEARCHtotrigger copies the search criteria to the trigger

TRIGgertosearch copies the trigger criteria to the search

#### SEARCH:SEARCH<x>:STATE

Sets the search state to on or off. <x> is the search number, which is always 1. The query form returns the search state.

**Group** Search

Syntax SEARCH:SEARCH<x>:STATE {<NR1>|OFF|ON}

SEARCH: SEARCH<x>: STATE?

**Arguments** OFF or  $\langle NR1 \rangle = 0$  sets the search state to off.

ON or  $\langle NR1 \rangle \neq 0$  sets the search state to on.

### SEARCH:SEARCH<x>:TOTAL? (Query Only)

Returns the total number of matches for the search. The total number of matches may be than the number of marks placed. <x> is the search number, which is always 1.

**Group** Search

Syntax SEARCH:SEARCH<x>:TOTAL?

**Returns** <NR1> is the total number of matches.

### SEARCH:SEARCH<x>:TRIGger:A:BUS? (Query Only)

Returns the serial search type. <x> is the search number, which is always 1. There are four serial buses, B1 through B4.

**Conditions** This command requires a DPO4AUTO or DPO4EMBD application module.

**Group** Search

**Syntax** SEARCH:SEARCH<x>:TRIGger:A:BUS?

**Returns** I2C specifies the Inter-IC bus.

SPI specifies the Serial Peripheral Interface bus.

CAN specifies the Controller Area Network bus.

**Examples** SEARCH:SEARCH1:TRIGGER:A:BUS? might return

SEARCH:SEARCH1:TRIGGER:A:BUS:B1:SPI:CONDITION SS;:SEARCH:SEARCH1:TRIGGER:A:BUS:B2:SPI:CONDITION SS;:SEARCH:SEARCH1:TRIGGER:A:BUS:B3:SPI:CONDITION SS;:SEARCH:SEARCH1:TRIGGER:A:BUS:B4:SPI:CONDITION

SS;:SEARCH:SEARCH1:TRIGGER:A:BUS:B1:SPI:DATA:MOSI:VALUE "XX".

# SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:AUDio:CONDition

Sets or returns the search trigger condition for the AUDIO bus: Start of Frame or Data.

**Conditions** This command requires DPO4AUDIO application module.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:AUDio:CONDition

{SOF|DATA}

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:AUDio:CONDition?

**Arguments** SOF enables triggering at the start of frame for the audio bus.

DATA enables triggering on matching data for the audio bus.

#### SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:AUDio:DATa:HIVALue

Sets or returns the search trigger data upper word for the AUDIO bus.

**Conditions** This command requires DPO4AUDIO application module.

**Group** Search

**Syntax** SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:AUDio:DATa:HIVALue

<String>

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:AUDio:DATa:HIVALue?

**Arguments** <String> specifies the search data trigger data upper word.

# SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:AUDio:DATa:OFFSet

Sets or returns the search trigger data offset for the AUDIO bus.

**Conditions** This command requires DPO4AUDIO application module.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:AUDio:DATa:OFFSet <NR1>

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:AUDio:DATa:OFFSet?

**Arguments** <NR1> is the search trigger data offset value.

#### SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:AUDio:DATa:QUALifier

Sets or returns the search trigger data qualifier for the AUDIO bus.

**Conditions** This command requires DPO4AUDIO application module.

**Group** Search

**Syntax** SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:AUDio:DATa:QUALifier

{LESSThan|MOREThan|EQUal|UNEQual|LESSEQual|MOREEQual|INrange|OUTrang

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:AUDio:DATa:QUALifier?

**Arguments** LESSThan sets the search trigger data qualifier to less than.

MOREThan sets the search trigger data qualifier to greater than.

EQUal sets the search trigger data qualifier to equal.

UNEQual sets the search trigger data qualifier to not equal.

LESSEQual sets the search trigger data qualifier to less than or equal.

MOREEQual sets the search trigger data qualifier to greater than or equal.

Inrange sets the search trigger data qualifier to in range.

OUTrange sets the search trigger data qualifier to out of range.

# SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:AUDio:DATa:VALue

Sets or returns the search trigger data lower word for the AUDIO bus.

**Conditions** This command requires DPO4AUDIO application module.

**Group** Search

**Syntax** SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:AUDio:DATa:VALue

<String>

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:AUDio:DATa:VALue?

**Arguments** <String> is the search trigger data lower word.

### SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:AUDio:DATa:WORD

Sets or returns the search trigger data alignment for the AUDIO bus.

**Conditions** This command requires DPO4AUDIO application module.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:AUDio:DATa:WORD

{EITher|LEFt|RIGht}

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:AUDio:DATa:WORD?

**Arguments** EITher aligns the search trigger data to either left or right.

LEFt aligns the search trigger data to the left.

RIGht aligns the search trigger data to the right.

# SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:CAN:CONDition

Sets or returns the search condition for a CAN trigger search. SEARCH<x> is the

search number and B<x> is the bus number.

**Conditions** This command requires a DPO4AUTO application module.

**Group** Search

**Syntax** SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:CAN:CONDition

{SOF|FRAMEtype|IDentifier|DATA|IDANDDATA|EOF|ACKMISS}
SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:CAN:CONDition?

**Arguments** SOF specifies a search based on the start of frame.

FRAMEtype specifies a search based on the frame type.

IDentifier specifies a search based on the frame identifier.

DATA specifies a search based on the frame data.

IDANDDATA specifies a search based on the frame identifier and data.

EOF specifies a search base on the end of frame.

ACKMISS specifies a search based on the missing ACK field.

# SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:CAN:DATa:DIRection

Sets or returns the CAN search to be valid for Read, Write, or Either condition if the criteria is IDentifier. SEARCH<x> is the search number and B<x> is the bus number. This only applies if the search condition is IDentifier.

**Conditions** This command requires a DPO4AUTO application module.

**Group** Search

**Syntax** SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:CAN:DATa:DIRection

{READ|WRITE|NOCARE}

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:CAN:DATa:DIRection?

**Related Commands** SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:CAN:CONDition

**Arguments** READ specifies the read condition.

WRITE specifies the write condition.

NOCARE specifies either a read or write condition.

### SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:CAN:DATa:QUALifier

Sets or returns the CAN data qualifier for a search. SEARCH<x> is the search number and B<x> is the bus number. This only applies if the trigger condition is IDANDDATA or DATA.

**Conditions** This command requires a DPO4AUTO application module.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:CAN:DATa:QUALifier

{LESSThan|Than|EQUal|UNEQual|LESSEQual|EQual}

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:CAN:DATa:QUALifier?

**Related Commands** SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:CAN:DATa:VALue

**Arguments** LESSThan searches for bus data less than the value specified by

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:CAN:DATa:VALue.

Than searches for bus data greater than the value specified by SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:CAN:DATa:VALue.

EQUal searches for bus data equal to the value specified by SEARCH:

SEARCH<x>:TRIGger:A:BUS:B<x>:CAN:DATa:VALue.

UNEQual searches for bus data not equal to the value specified by SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:CAN:DATa:VALue.

LESSEQual searches for bus data less equal to the value specified by SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:CAN:DATa:VALue.

EQual searches for bus data equal to the value specified by SEARCH:

SEARCH<x>:TRIGger:A:BUS:B<x>:CAN:DATa:VALue.

#### SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:CAN:DATa:SIZe

Sets or returns the length of the data string in bytes to be used for a CAN search if the search condition is DATA or IDANDDATA. SEARCH<x> is the search number and B<x> is the bus number.

**Conditions** This command requires a DPO4AUTO application module.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:CAN:DATa:SIZe <NR1>

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:CAN:DATa:SIZe?

**Arguments** <NR1> is the data string length in bytes.

#### SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:CAN:DATa:VALue

Sets or returns the binary data string to be used for a CAN search if the search condition is ID or IDANDDATA. SEARCH<x> is the search number and B<x>

is the bus number.

**Conditions** This command requires a DPO4AUTO application module.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:CAN:DATa:VALue <bin>

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:CAN:DATa:VALue?

**Related Commands** SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:CAN:DATa:QUALifier

**Arguments** <br/> <br/> <br/> <br/> is the data in binary format.

# SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:CAN:FRAMEtype

Sets or returns the CAN Frame Type to be used if the trigger search condition is Frame Type. SEARCH<x> is the search number and B<x> is the bus number.

**Conditions** This command requires a DPO4AUTO application module.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:CAN:FRAMEtype

{DATA|REMote|ERRor|OVERLoad}

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:CAN:FRAMEtype?

**Arguments** DATA specifies a data frame.

REMote specifies a remote frame.

ERROr specifies an error frame.

OVERLoad specifies an overload frame.

# SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:CAN{:IDentifier|:ADDRess}:MODe

Sets or returns the CAN addressing mode for a trigger search to a standard or extended format. SEARCH<x> is the search number and B<x> is the bus number.

**Conditions** This command requires a DPO4AUTO application module.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:CAN{:IDentifier|:

ADDRess}:MODe {STandard|EXTended}

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:CAN{:IDentifier|:

ADDRess}:MODe?

**Arguments** STandard specifies an 11-bit identifier field.

EXTended specifies a 29-bit identifier field.

# SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:CAN{:IDentifier|:ADDRess}:VALue

Sets or returns the binary address string to be used for a CAN trigger search if the search condition is ID or IDANDDATA. SEARCH<x> is the search number and B<x> is the bus number.

**Conditions** This command requires a DPO4AUTO application module.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:CAN{:IDentifier|:

ADDRess}: VALue <bin>

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:CAN{:IDentifier|:

ADDRess}: VALue?

**Arguments** <br/> <br/> <br/> <br/> is the address in binary format.

# SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:FLEXray:CONDition

Sets or returns the trigger condition for FLEXRAY.

**Group** Search

**Syntax** SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:FLEXray:CONDition

{SOF|FRAMETypeid|CYCLEcount|HEADer|DATA|IDANDDATA|EOF|ERROR}

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:FLEXray:CONDition?

**Arguments** SOF sets the FLEXRAY trigger condition to start of frame.

FRAMETypeid sets the FLEXRAY trigger condition to a frame type id.

CYCLEcount sets the FLEXRAY trigger condition to cycle count.

**HEADer** sets the FLEXRAY trigger condition to header.

DATA sets the FLEXRAY trigger condition to data.

IDANDDATA sets the FLEXRAY trigger condition to ID and data.

EOF sets the FLEXRAY trigger condition to EOF.

ERROR sets the FLEXRAY trigger condition to an error.

Examples SEARCH: TRIGGER: A:BUS: B1:FLEXRAY: CONDITION ERROR sets

the FLEXRAY condition to ERROR

SEARCH:SEARCH1:TRIGGER:A:BUS:B1:FLEXRAY:CONDITION? might return SEARCH:SEARCH1:TRIGGER:A:BUS:B1:FLEXRAY:CONDITION SOF

indicating the FLEXRAY condition is start of frame.

# SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:FLEXray:CYCLEcount:HIVALue

Sets or returns the binary data string to be used for FLEXRAY cycle count high value.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:FLEXray:CYCLEcount:

HIVALue <QString>

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:FLEXray:CYCLEcount:

HIVALue?

**Arguments** <QString> is a quoted string that is the cycle count high value.

**Examples** SEARCH:SEARCH1:TRIGGER:A:BUS:B1:FLEXRAY:CYCLECOUNT:HIVALUE

"110010" sets the cycle count high value to 110010.

SEARCH: SEARCH1: TRIGGER: A: BUS: B1: FLEXRAY: CYCLECOUNT: HIVALUE?

might return

SEARCH:SEARCH1:TRIGGER:A:BUS:B1:FLEXRAY:CYCLECOUNT:HIVALUE

"XXXXXX" indicating the cycle count high value is set to don't cares.

#### SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:FLEXray:CYCLEcount:QUALifier

Sets or returns the FLEXRAY cycle count qualifier.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:BUS:

B<x>:FLEXray:CYCLEcount:QUALifier

 $\{ \texttt{LESSThan} | \texttt{MOREThan} | \texttt{EQUal} | \texttt{UNEQual} | \texttt{LESSEQual} | \texttt{MOREEQual} | \texttt{INrange} | \texttt{OUTrange} \}$ 

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:FLEXray:CYCLEcount:

QUALifier?

**Arguments** LESSThan sets the cycle count qualifier to less than.

MOREThan sets the cycle count qualifier to greater than.

EQUal sets the cycle count qualifier to equal.

UNEQual sets the cycle count qualifier to not equal.

LESSEQual sets the cycle count qualifier to less than or equal.

MOREEQual sets the cycle count qualifier to greater than or equal.

INrange sets the cycle count qualifier to in range.

OUTrange sets the cycle count qualifier to out of range.

Examples SEARCH:SEARCH1:TRIGGER:A:BUS:B1:FLEXRAY:CYCLECOUNT:QUALIFIER

LESSTHANsets the cycle count qualifier to LESSTHAN.

SEARCH:SEARCH1:TRIGGER:A:BUS:B1:FLEXRAY:CYCLECOUNT:QUALIFIER?

might return

SEARCH:SEARCH1:TRIGGER:A:BUS:B1:FLEXRAY:CYCLECOUNT:QUALIFIER

EQUAL indicating the cycle count qualifier is set to EQUAL.

# SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:FLEXray:CYCLEcount:VALue

Sets or returns the binary data string to be used for FLEXRAY cycle count low value.

**Group** Search

**Syntax** SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:FLEXray:CYCLEcount:VALue

<QString>

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:FLEXray:CYCLEcount:

VALue?

**Arguments** <QString> is a quoted string that is the binary cycle count value.

**Examples** SEARCH:SEARCH1:TRIGGER:A:BUS:B1:FLEXRAY:CYCLECOUNT:VALUE

"110010" sets the cycle count value to 110010.

SEARCH:SEARCH1:TRIGGER:A:BUS:B1:FLEXRAY:CYCLECOUNT:VALUE?

might return

SEARCH:SEARCH1:TRIGGER:A:BUS:B1:FLEXRAY:CYCLECOUNT:VALUE

"XXXXXX" indicating the cycle count value is don't cares.

### SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:FLEXray:DATa:HIVALue

Sets or returns the high binary data string used for FLEXRAY trigger if trigger condition is ID or IDANDDATA.

**Group** Search

**Syntax** SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:FLEXray:DATa:HIVALue

OStrina>

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:FLEXray:DATa:HIVALue?

**Arguments** <QString> is a quoted string that is the binary high value.

**Examples** SEARCH: TRIGGER: A: BUS: B1: FLEXRAY: DATA: HIVALUE

"11001010" sets the high value 11001010.

SEARCH:SEARCH1:TRIGGER:A:BUS:B1:FLEXRAY:DATA:HIVALUE? might return SEARCH:SEARCH1:TRIGGER:A:BUS:B1:FLEXRAY:DATA:HIVALUE

"XXXXXXX" indicating the high value is don't cares.

### SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:FLEXray:DATa:OFFSet

Sets or returns the offset of the data string in bytes to be used for FLEXRAY trigger.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:FLEXray:DATa:OFFSet

<NR1>

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:FLEXray:DATa:OFFSet?

**Arguments** <NR1> is the FLEXRAY data offset in bytes. A byte offset of -1 signifies don't

care, and no byte offset is used. The instrument will trigger or match any byte

value that fits.

**Examples** SEARCH:SEARCH1:TRIGGER:A:BUS:B1:FLEXRAY:DATA:OFFSET 10 sets

the FLEXRAY data offset to 10 bytes.

SEARCH: SEARCH1: TRIGGER: A: BUS: B1: FLEXRAY: DATA: OFFSET? might

return SEARCH:SEARCH1:TRIGGER:A:BUS:B1:FLEXRAY:DATA:OFFSET 0

indicating the offset is set to 0 bytes.

# SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:FLEXray:DATa:QUALifier

Sets or returns the FLEXRAY data qualifier.

**Group** Search

**Syntax** SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:FLEXray:DATa:QUALifier

{LESSThan|MOREThan|EQUal|UNEQual|LESSEQual|MOREEQual|

INrange|OUTrange}

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:FLEXray:DATa:QUALifier?

**Arguments** LESSThan sets the FLEXRAY data qualifier to less than.

MOREThan sets the FLEXRAY data qualifier to greater than.

EQUal sets the FLEXRAY data qualifier to equal.

UNEQual sets the FLEXRAY data qualifier to not equal.

LESSEQual sets the FLEXRAY data qualifier to less than or equal.

MOREEQual sets the FLEXRAY data qualifier to greater than or equal.

INrange sets the FLEXRAY data qualifier to in range.

OUTrange sets the FLEXRAY data qualifier to out of range.

**Examples** 

SEARCH:SEARCH1:TRIGGER:A:BUS:B1:FLEXRAY:DATA:QUALIFIER

LESSTHAN sets the data qualifier to LESSTHAN.

SEARCH:SEARCH1:TRIGGER:A:BUS:B1:FLEXRAY:DATA:QUALIFIER? might return SEARCH:SEARCH1:TRIGGER:A:BUS:B1:FLEXRAY:DATA:QUALIFIER

EQUAL indicating the data qualifier is EQUAL.

# SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:FLEXray:DATa:SIZe

Sets or returns the length of the data string in bytes to be used for FLEXRAY trigger.

Group

Search

**Syntax** 

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:FLEXray:DATa:SIZe\_<NR1>

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:FLEXray:DATa:SIZe?

**Arguments** 

<NR1> is the length of the data string in bytes. Length range is 1 to 8.

**Examples** 

SEARCH:SEARCH1:TRIGGER:A:BUS:B1:FLEXRAY:DATA:SIZE 8 sets the

data size to 8 bytes.

SEARCH: SEARCH1: TRIGGER: A: BUS: B1: FLEXRAY: DATA: SIZE? might return SEARCH: SEARCH1: TRIGGER: A: BUS: B1: FLEXRAY: DATA: SIZE 1 indicating

the data size is 1 byte.

# SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:FLEXray:DATa:VALue

Sets or returns the low binary data string used for FLEXRAY trigger condition if trigger condition is ID or IDANDDATA.

Group

Search

**Syntax** 

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:FLEXray:DATa:VALue

<QString>

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:FLEXray:DATa:VALue?

**Arguments** <QString> is a quoted string that is the low binary data string to be used for

FLEXRAY trigger condition if trigger condition is ID or IDANDDATA.

Examples SEARCH:SEARCH1:TRIGGER:A:BUS:B1:FLEXRAY:DATA:VALUE

"11001010" sets the binary data string to 11001010.

SEARCH:SEARCH1:TRIGGER:A:BUS:B1:FLEXRAY:DATA:VALUE? might return SEARCH:SEARCH1:TRIGGER:A:BUS:B1:FLEXRAY:DATA:VALUE

"XXXXXXXX" indicates the binary data string is don't cares.

# SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:FLEXray:EOFTYPE

Sets or returns the end of frame type used for FLEXRAY trigger.

**Group** Search

**Syntax** SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:FLEXray:E0FTYPE

{STATic|DYNAMic|ANY}

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:FLEXray:EOFTYPE?

**Arguments** STATIC sets the FLEXRAY end of frame type to STATIC.

DYNAMic sets the FLEXRAY end of frame type to DYNAMIC.

ANY sets the FLEXRAY end of frame type to ANY type.

**Examples** SEARCH:SEARCH1:TRIGGER:A:BUS:B1:FLEXRAY:E0FTYPE ANY sets the

FLEXRAY end of frame type to any type.

SEARCH: SEARCH1: TRIGGER: A: BUS: B1: FLEXRAY: EOFTYPE? might return

SEARCH:SEARCH1:TRIGGER:A:BUS:B1:FLEXRAY:EOFTYPE STATIC

indicating the FLEXRAY end of frame type is static.

#### SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:FLEXray:ERRTYPE

Sets or returns the error type be used for FLEXRAY trigger.

**Group** Search

**Syntax** SEARCH:SEARCH<X>:TRIGger:A:BUS:B<X>:FLEXray:ERRTYPE

{CRCHeader|CRCTrailer|SYNCFrame|STARTupnosync|NULLFRStatic|

NULLFRDynamic}

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:FLEXray:ERRTYPE?

**Arguments** CRCHeader sets the FLEXRAY error type to CRC header.

CRCTrailer sets the FLEXRAY error type to CRC trailer.

SYNCFrame sets the FLEXRAY error type to SYNC frame.

STARTupnosync sets the FLEXRAY error type to start up with no sync.

NULLFRStatic sets the FLEXRAY error type to null frame static.

NULLFRDynamic sets the FLEXRAY error type to null frame dynamic.

**Examples** 

SEARCH:SEARCH1:TRIGGER:A:BUS:B1:FLEXRAY:ERRTYPE SYNCFRAME sets

the FLEXRAY error type SYNCFRAME

SEARCH:SEARCH1:TRIGGER:A:BUS:B1:FLEXRAY:ERRTYPE? might return SEARCH:SEARCH1:TRIGGER:A:BUS:B1:FLEXRAY:ERRTYPE CRCHEADER

indicating the FLEXRAY error type is CRCHEADER

### SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:FLEXray:FRAMEID:HIVALue

Sets or returns the binary data string used for FLEXRAY frame ID high value.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:FLEXray:FRAMEID:HIVALue

<QString>

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:FLEXray:FRAMEID:HIVALue?

**Arguments** <QString> is a quoted string representing the binary data string used for

FLEXRAY frame ID high value.

**Examples** SEARCH:SEARCH1:TRIGGER:A:BUS:B1:FLEXRAY:FRAMEID:HIVALUE

"00101100101" sets the frame id high value to 00101100101.

SEARCH:SEARCH1:TRIGGER:A:BUS:B1:FLEXRAY:FRAMEID:HIVALUE?

might return

SEARCH:SEARCH1:TRIGGER:A:BUS:B1:FLEXRAY:FRAMEID:HIVALUE

"XXXXXXXXXX" indicating the frame id high value is don't cares.

# SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:FLEXray:FRAMEID:QUALifier

Sets or returns the FLEXRAY frame ID qualifier.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:BUS:

B<x>:FLEXray:FRAMEID:QUALifier

{LESSThan|MOREThan|EQUal|UNEQual|LESSEQual|MOREEQual|

INrange|OUTrange}

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:FLEXray:FRAMEID:

QUALifier?

**Arguments** LESSThan sets the frame id qualifier to LESSThan

MOREThan sets the frame id qualifier to MOREThan

QUal sets the frame id qualifier to QUal

UNEQual sets the frame id qualifier to UNEQual

LESSEQual sets the frame id qualifier to LESSEQual

MOREEQual sets the frame id qualifier to MOREEQual

INrange sets the frame id qualifier to INrange

OUTrange sets the frame id qualifier to OUTrange

Examples SEARCH:SEARCH1:TRIGGER:A:BUS:B1:FLEXRAY:FRAMEID:QUALIFIER

OUTRANGE sets the frame id qualifier to out of range.

SEARCH:SEARCH1:TRIGGER:A:BUS:B1:FLEXRAY:FRAMEID:QUALIFIER?

might return

SEARCH: SEARCH1: TRIGGER: A: BUS: B1: FLEXRAY: FRAMEID: QUALIFIER

EQUAL indicating the frame id qualifier is EQUAL.

## SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:FLEXray:FRAMEID:VALue

Sets or returns the binary data string to be used for FLEXRAY frame ID low value.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:FLEXray:FRAMEID:VALue

<QString>

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:FLEXray:FRAMEID:VALue?

**Arguments** <QString> is a quoted string representing the binary data string used for

FLEXRAY frame ID low value.

**Examples** SEARCH: SEARCH1: TRIGGER: A: BUS: B1: FLEXRAY: FRAMEID: VALUE

"11001101010" sets the value of the frame id is 11001101010.

SEARCH: SEARCH1: TRIGGER: A: BUS: B1: FLEXRAY: FRAMEID: VALUE? might return SEARCH:SEARCH1:TRIGGER:A:BUS:B1:FLEXRAY:FRAMEID:VALUE

"10110010101" indicating the value of the frame id is 10110010101.

### SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:FLEXray:FRAMEType

Sets or returns the frame type for FLEXRAY.

Search Group

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:FLEXray:FRAMEType **Syntax** 

{NORMal|PAYLoad|NULL|SYNC|STARTup}

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:FLEXray:FRAMEType?

**Arguments** NORMal sets the FLEXRAY frame type to normal.

PAYLoad sets the FLEXRAY frame type to payload.

NULL sets the FLEXRAY frame type to NULL.

SYNC sets the FLEXRAY frame type to sync.

STARTup sets the FLEXRAY frame type to start up.

SEARCH:SEARCH1:TRIGGER:A:BUS:B1:FLEXRAY:FRAMETYPE STARTUP **Examples** 

sets the flexray frame type to startup.

SEARCH: SEARCH1: TRIGGER: A: BUS: B1: FLEXRAY: FRAMETYPE? might return

SEARCH:SEARCH1:TRIGGER:A:BUS:B1:FLEXRAY:FRAMETYPE NORMAL

indicating the flexray frame type is normal.

# SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:FLEXray:HEADER:CRC

Sets or returns the CRC portion of the binary header string to be used for FLEXRAY trigger.

Search Group

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:FLEXray:HEADER:CRC **Syntax** 

SEARCH:SEARCH<X>:TRIGGer:A:BUS:B<X>:FLEXray:HEADER:CRC?

**Arguments** <QString> is a quoted string representing the CRC portion of the binary header

string used for FLEXRAY trigger.

**Examples** SEARCH:SEARCH1:TRIGGER:A:BUS:B1:FLEXRAY:HEADER:CRC

"00110010101" sets the CRC protion of the binary header string 00110010101.

SEARCH:SEARCH1:TRIGGER:A:BUS:B1:FLEXRAY:HEADER:CRC? might return SEARCH:SEARCH1:TRIGGER:A:BUS:B1:FLEXRAY:HEADER:CRC "XXXXXXXXXX" indicating the CRC protion of the binary header string is don't

cares.

# SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:FLEXray:HEADER:CYCLEcount

Sets or returns the cycle count portion of the binary header string used for FLEXRAY trigger.

**Group** Search

**Syntax** SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:FLEXray:HEADER:

CYCLEcount <QString>

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:FLEXray:HEADER:

CYCLEcount?

**Arguments** <QString> is a quoted string representing the cycle count portion of the binary

header String used for FLEXRAY trigger.

**Examples** SEARCH:SEARCH1:TRIGGER:A:BUS:B1:FLEXRAY:HEADER:CYCLECOUNT

"001101" sets the cycle count to 001101.

SEARCH:SEARCH1:TRIGGER:A:BUS:B1:FLEXRAY:HEADER:CYCLECOUNT?

might return

SEARCH:SEARCH1:TRIGGER:A:BUS:B1:FLEXRAY:HEADER:CYCLECOUNT

"XXXXXX" indicating the cycle count is don't cares.

# SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:FLEXray:HEADER:FRAMEID

Sets or returns the frame id portion of the binary header string used for FLEXRAY trigger.

**Group** Search

**Syntax** SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:FLEXray:HEADER:FRAMEID

<QString>

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:FLEXray:HEADER:FRAMEID?

**Arguments** <QString> is a quoted string representing the frame id portion of the binary

header string used for FLEXRAY trigger.

Examples SEARCH:SEARCH1:TRIGGER:A:BUS:B1:FLEXRAY:HEADER:FRAMEID

"10110010101" sets the frame id portion of the binary header string to

10110010101.

SEARCH: SEARCH1: TRIGGER: A: BUS: B1: FLEXRAY: HEADER: FRAMEID? might return SEARCH: SEARCH1: TRIGGER: A: BUS: B1: FLEXRAY: HEADER: FRAMEID "XXXXXXXXXXX" indicating the frame id portion of the binary header string is

don't cares.

#### SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:FLEXray:HEADER:INDBits

Sets or returns the indicator bits portion of the binary header string used for FLEXRAY trigger.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:FLEXray:HEADER:INDBits

<QString>

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:FLEXray:HEADER:INDBits?

**Arguments** <QString> is a quoted string representing the indicator bits portion of the binary

header string used for FLEXRAY trigger.

**Examples** SEARCH:SEARCH1:TRIGGER:A:BUS:B1:FLEXRAY:HEADER:INDBITS

"10100" sets the indicator bits of the header to 10100.

SEARCH:SEARCH1:TRIGGER:A:BUS:B1:FLEXRAY:HEADER:INDBITS? might

return SEARCH:SEARCH1:TRIGGER:A:BUS:B1:FLEXRAY:HEADER:INDBITS

"XXXXX" indicating the indicator bits of the header are don't cares.

## SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:FLEXray:HEADER:PAYLength

Sets or returns the payload length portion of the binary header string used for FLEXRAY trigger.

**Group** Search

**Syntax** SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:FLEXray:HEADER:PAYLength

<QString>

SEARCH: SEARCH<x>:TRIGger:A:BUS:B<x>:FLEXray:HEADER:

PAYLength?

**Arguments** <QString> is a quoted string representing the payload length portion of the

binary header string used for FLEXRAY trigger.

**Examples** SEARCH:SEARCH1:TRIGGER:A:BUS:B1:FLEXRAY:HEADER:PAYLENGTH

"1001101" sets the payload length portion of the binary header string to 1001101.

SEARCH:SEARCH1:TRIGGER:A:BUS:B1:FLEXRAY:HEADER:PAYLENGTH?

might return

SEARCH: SEARCH1: TRIGGER: A: BUS: B1: FLEXRAY: HEADER: PAYLENGTH "XXXXXXX" indicating the payload length portion of the binary header string

is don't cares.

### SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:I2C:ADDRess:MODe

Sets or returns the I2C address mode to 7 or 10-Bit. SEARCH<x> is the search number and B<x> is the bus number.

**Conditions** This command requires a DPO4EMBD application module.

**Group** Search

**Syntax** SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:I2C:ADDRess:MODe

{ADDR7|ADDR10}

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:I2C:ADDRess:MODe?

**Arguments** ADDR7 specifies 7-bit addresses.

ADDR10 specifies 10-bit addresses.

# SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:I2C:ADDRess:TYPe

Sets or returns the I2C address type. SEARCH<x> is the search number and B<x> is the bus number.

**Conditions** This command requires a DPO4EMBD application module.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:I2C:ADDRess:TYPe

{GENeralcall|STARtbyte|HSmode|EEPROM|USER}

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:I2C:ADDRess:TYPe?

**Arguments** GENeral call specifies the GENeral call address type.

STARtbyte specifies the STARtbyte address type.

HSmode specifies the HSmode address type

EEPROM specifies the EEPROM address type.

USER specifies a user address.

# SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:I2C:ADDRess:VALue

Sets or returns the binary address string to be used for an I2C trigger search if the search condition is ADDR or ADDRANDDATA. SEARCH<x> is the search number and B<x> is the bus number.

**Conditions** This command requires a DPO4EMBD application module.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:I2C:ADDRess:VALue <bin>

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:I2C:ADDRess:VALue?

**Arguments** <br/> <br/> <br/> is the address in binary format.

### SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:I2C:CONDition

Sets or returns the search condition for an I2C trigger search. SEARCH<x> is the search number and B<x> is the bus number.

**Conditions** This command requires a DPO4EMBD application module.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:I2C:CONDition

{STARt|STOP|REPEATStart|ACKMISS|ADDRess|DATA|ADDRANDDATA}

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:I2C:CONDition?

**Arguments** STARt specifies a search based on a start condition.

STOP specifies a search based on a stop condition.

REPEATstart specifies a search based on a repeat of start condition.

ACKMISS specifies a search based on a missing acknowledgement condition.

ADDRess specifies a search based on an address.

DATA specifies a search based on a data condition.

ADDRANDDATA specifies a search based on an address and data condition.

## SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:I2C:DATa:DIRection

Sets or returns the I2C search condition to be valid on a Read, Write, or Either condition. SEARCH<x> is the search number and B<x> is the bus number.

**Conditions** This command requires a DPO4EMBD application module.

**Group** Search

**Syntax** SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:I2C:DATa:DIRection

{READ|WRITE|NOCARE}

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:I2C:DATa:DIRection?

**Arguments** READ specifies a read condition.

WRITE specifies a write condition.

NOCARE specifies either a read or write condition.

#### SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:I2C:DATa:SIZe

Sets or returns the length of the data string in bytes to be used for an I2C trigger search if the search condition is DATA or ADDRANDDATA. SEARCH<x> is the search number and B<x> is the bus number.

**Conditions** This command requires a DPO4EMBD application module.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:I2C:DATa:SIZe <NR1>

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:I2C:DATa:SIZe?

**Arguments** <NR1> is the data string length in bytes.

#### SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:I2C:DATa:VALue

Sets or returns the binary data string to be used for an I2C trigger search if the search condition is DATA or ADDRANDDATA. SEARCH<x> is the search

number and B<x> is the bus number.

**Conditions** This command requires a DPO4EMBD application module.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:I2C:DATa:VALue <bin>

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:I2C:DATa:VALue?

**Arguments** <br/> <br/> <br/> <br/> is the data in binary format.

# SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:LIN:CONDition

Sets or returns the search condition for a LIN search.

**Group** Search

**Syntax** SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:LIN:CONDition

{SYNCField|IDentifier|DATA|IDANDDATA|WAKEup|SLEEP|ERROR}

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:LIN:CONDition?

**Arguments** SYNCField specifies to search on the sync field.

IDentifier specifies to search on the identifier.

DATA specifies to search on the data.

IDANDDATA specifies to search on the identifier and the data.

WAKEup specifies to search on wake up.

SLEEP specifies to search on sleep.

ERROR specifies to search on errors.

**Examples** SEARCH

SEARCH:SEARCH1:TRIGGER:A:BUS:B1:LIN:CONDITION? might return SEARCH:SEARCH1:TRIGGER:A:BUS:B1:LIN:CONDITION SYNCFIELD

indicating a search on the sync field.

#### SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:LIN:DATa:HIVALue

Sets or returns the binary data string to be used for LIN searches if the search condition is ID or IDANDDATA.

Group

Search

**Syntax** 

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:LIN:DATa:HIVALue

<QString>

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:LIN:DATa:HIVALue?

**Arguments** 

<QString> is a quoted string of 1s, 0s, or Xs representing the binary data string to be used for LIN searches if the search condition is ID or IDANDDATA.

**Examples** 

#### SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:LIN:DATa:QUALifier

Sets or returns the LIN data qualifier. This only applies if the trigger condition is IDANDDATA or DATA.

Group

Search

**Syntax** 

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:LIN:DATa:QUALifier
{LESSThan|MOREThan|EQUal|UNEQual|LESSEQual|MOREEQual|

INrange|OUTrange}

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:LIN:DATa:QUALifier?

**Arguments** LESSThan sets the LIN data qualifier to less than.

MOREThan sets the LIN data qualifier to greater than.

EQUal sets the LIN data qualifier to equal.

UNEQual sets the LIN data qualifier to not equal.

LESSEQual sets the LIN data qualifier to less than or equal.

MOREEQual sets the LIN data qualifier to greater than or equal.

INrange sets the LIN data qualifier to in range.

OUTrange sets the LIN data qualifier to out of range.

Examples SEARCH:SEARCH1:TRIGGER:A:BUS:B1:LIN:DATA:QUALIFIER LESSThan

sets the data qualifier to lessthan.

SEARCH:SEARCH1:TRIGGER:A:BUS:B1:LIN:DATA:QUALIFIER? might return

SEARCH:SEARCH1:TRIGGER:A:BUS:B1:LIN:DATA:QUALIFIER EQUAL

indicating the data qualifier is equal.

# SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:LIN:DATa:SIZe

Sets or returns the length of the data string in bytes to be used for LIN Search, if search condition is DATA or IDANDDATA.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:LIN:DATa:SIZe <NR1>

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:LIN:DATa:SIZe?

**Arguments** <NR1> is the length of the data in bytes.

**Examples** SEARCH:SEARCH1:TRIGGER:A:BUS:B1:LIN:DATA:SIZE 8 sets the LIN data

size is 8 bytes.

SEARCH:SEARCH1:TRIGGER:A:BUS:B1:LIN:DATA:SIZE? might return SEARCH:SEARCH1:TRIGGER:A:BUS:B1:LIN:DATA:SIZE 1 indicating that

the LIN data size is 1 byte.

## SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:LIN:DATa:VALue

Sets or returns the binary data string used for a LIN search if the search condition is ID or IDANDDATA.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:LIN:DATa:VALue <QString>

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:LIN:DATa:VALue?

**Arguments** <QString> is the binary data string for the search.

**Examples** SEARCH:SEARCH1:TRIGGER:A:BUS:B1:LIN:DATA:VALUE? might

return SEARCH:SEARCH1:TRIGGER:A:BUS:B1:LIN:DATA:VALUE

"XXXXXXXX" indicating the data value is don't care.

#### SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:LIN:ERRTYPE

Sets or returns the error type used for a LIN Search.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:LIN:ERRTYPE

{SYNC|PARity|CHecksum|HEADertime|RESPtime|FRAMetime} SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:LIN:ERRTYPE?

**Arguments** SYNC specifies a sync error type.

PARity specifies a parity error type.

CHecksum specifies a checksum error type.

**HEADertime** specifies a header time error type.

RESPtime specifies a response time error type.

RAMetime specifies a frame time error type.

**Examples** SEARCH:SEARCH1:TRIGGER:A:BUS:B1:LIN:ERRTYPE? might return

SEARCH: SEARCH1: TRIGGER: A: BUS: B1: LIN: ERRTYPE SYNC indicating a

SYNC error type.

## SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:LIN:IDentifier:VALue

Sets or returns the binary address string used for LIN search if search condition is ID or IDANDDATA.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:LIN:IDentifier:VALue

<QString>

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:LIN:IDentifier:VALue?

**Arguments** <QString> is a quoted string specifying the binary address string to be used for

LIN search if search condition is ID or IDANDDATA.

**Examples** SEARCH:SEARCH1:TRIGGER:A:BUS:B1:LIN:IDENTIFIER:VALUE? might

return SEARCH:SEARCH1:TRIGGER:A:BUS:B1:LIN:IDENTIFIER:VALUE

"XXXXXX" indicating the binary address is undefined.

### SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:PARallel:VALue

Sets or returns the binary data string to be used for a Parallel trigger search. SEARCH<x> is the search number and B<x> is the bus number.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:PARallel:VALue <QString>

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:PARallel:VALue?

**Arguments** <QString> is the binary data string.

# SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:RS232C:CONDition

Sets or returns the condition for an RS-232 trigger search. SEARCH<x> is the

search number and B<x> is the bus number.

**Conditions** This command requires a DPO4COMP application module.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:RS232C:CONDition

{RXSTArt|RXDATA|RXENDPacket|TXSTArt|TXDATA|TXENDPacket}
SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:RS232C:CONDition?

**Arguments** RXSTArt specifies a search based on the RX Start Bit.

RXDATA specifies a search based on RX Data.

RXENDPacket specifies a search based on the RX End of Packet condition.

TXSTArt specifies a search base on the TX Start Bit.

TXDATA specifies a search based on TX Data.

TXENDPacket specifies a search based on the TX End of Packet condition.

### SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:RS232C:RX:DATa:SIZe

Sets or returns the length of the data string for an RS-232 trigger search if the trigger condition is RX. SEARCH<x> is the search number and B<x> is the bus number.

**Conditions** This command requires a DPO4COMP application module.

**Group** Search

**Syntax** SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:RS232C:RX:DATa:SIZe

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:RS232C:RX:DATa:SIZe?

**Arguments** <NR1> is the length of the data string in Bytes.

# SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:RS232C:RX:DATa:VALue

Sets or returns the binary data string for an RS-232 trigger search if the condition involves RX. SEARCH<x> is the search number and B<x> is the bus number.

**Conditions** This command requires a DPO4COMP application module.

**Group** Search

**Syntax** SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:RS232C:RX:DATa:VALue

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:RS232C:RX:DATa:VALue?

### SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:RS232C:TX:DATa:SIZe

Sets or returns the length of the data string to be used for an RS-232 trigger search if the Trigger condition is TX. SEARCH<x> is the search number and B<x> is the bus number.

**Conditions** This command requires a DPO4COMP application module.

**Group** Search

Syntax SEARCH:SEARCH<a>x>:TRIGger:A:BUS:B<a>:RS232C:TX:DATa:SIZe

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:RS232C:TX:DATa:SIZe?

**Arguments** <NR1> is the length of the data string in Bytes.

#### SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:RS232C:TX:DATa:VALue

Sets or returns the binary data string to be used for an RS-232 trigger search if the condition involves RX. SEARCH<x> is the search number and B<x> is the bus number.

**Conditions** This command requires a DPO4COMP application module.

**Group** Search

**Syntax** SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:RS232C:TX:DATa:VALue

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:RS232C:TX:DATa:VALue?

#### SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:SPI:CONDition

Sets or returns the search condition for a SPI trigger search. SEARCH<x> is the search number and B<x> is the bus number.

**Conditions** This command requires a DPO4EMBD application module.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:SPI:CONDition

{SS|STARTofframe|MISO|MOSI|MISOMOSI}

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:SPI:CONDition?

**Related Commands** BUS:B<x>:SPI:IDLETime, BUS:B<x>:SPI:FRAMING

**Arguments** SS specifies a search based on the Slave Selection condition.

STARTofframe is applicable when BUS:B<x>:SPI:FRAMING is set to IDLEtime. When the trigger condition is set to STARTofframe, the instrument triggers on the first SPI clock after an idle time when there are no clocks.

MISO specifies a search based on the Master-In Slave-Out condition.

MOSI specifies a search based on the Master-Out Slave-In condition.

MISOMOSI specifies a search based on the Master-In Slave-Out and Master-Out

Slave-In conditions.

### SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:SPI:DATa{:MISO|:IN}:VALue

Sets or returns the binary data string for an SPI trigger search if the search condition is MISO or MISOMOSI. SEARCH<x> is the search number and B<x> is the bus number.

**Conditions** This command requires a DPO4EMBD application module.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:SPI:DATa{:MISO|:IN}:

VALue <bin>

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:SPI:DATa{:MISO|:IN}:

VALue?

**Arguments** <br/> <br/> <br/> <br/> is the data string in binary format.

# SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:SPI:DATa{:MOSI|:OUT}:VALue

Sets or returns the binary data string for an SPI trigger search if search the condition is MOSI, or MISOMOSI. SEARCH<x> is the search number and B<x> is the bus number.

**Conditions** This command requires a DPO4EMBD application module.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:SPI:DATa{:MOSI|:OUT}:

VALue <bin>

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:SPI:DATa{:MOSI|:OUT}:

VALue?

**Arguments** <br/> <br/> <br/> <br/> is the data in binary format.

### SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:SPI:DATa:SIZe

Sets or returns the length of the data string for an SPI trigger search if the search condition is MISO, MOSI, or MISOMOSI. SEARCH<x> is the search number and B<x> is the bus number.

**Conditions** This command requires a DPO4EMBD application module.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:SPI:DATa:SIZe <NR1>

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:SPI:DATa:SIZe?

**Arguments** <NR1> is the data string length in bytes.

#### SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:ADDRess:HIVALue

Sets or returns the binary address string for the upper limit for inside-of-range and outside-of-range qualifiers for the USB search trigger. Use the command SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:ADDRess:VALue to set the lower limit.

**Conditions** This command requires the DPO4USB application module.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:ADDRess:HIVALue

<QString>

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:ADDRess:HIVALue?

**Related Commands** SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:CONDition,

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:ADDRess:VALue

**Arguments** <QString> within the range 0000000 to 1111111 (00 hex to 7F hex).

Examples SEARCH:SEARCH1:TRIGGER:A:BUS:B1:USB:ADDRESS:HIVALUE

"0001000" sets the upper limit to binary 0001000 (08 hex).

SEARCH:SEARCH1:TRIGGER:A:BUS:B1:USB:ADDRESS:HIVALUE? might return:SEARCH:SEARCH1:TRIGGER:A:BUS:B1:USB:ADDRESS:HIVALUE

"111111", which indicates that the upper limit is 1111111 (7F hex).

#### SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:ADDRess:VALue

Sets or returns the binary address string to be used for the USB search trigger.

This command also sets or returns the binary address string for the lower limit for inside-of-range and outside-of-range qualifiers for the USB search trigger.

**Conditions** This command requires the DPO4USB application module.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:ADDRess:VALue

<QString>

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:ADDRess:VALue?

**Related Commands** SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:CONDition

**Arguments** <QString> within the range 0000000 to 1111111 (00 hex to 7F hex).

**Examples** SEARCH: TRIGGER: A:BUS: B1:USB: ADDRESS: VALUE "0001000"

sets the binary address to 0001000 (08 hex).

SEARCH:SEARCH1:TRIGGER:A:BUS:B1:USB:ADDRESS:VALUE? might return:SEARCH:SEARCH1:TRIGGER:A:BUS:B1:USB:ADDRESS:VALUE "1000000",

which indicates that the binary address is 100000 (40 hex).

### SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:CONDition

Sets or returns the trigger condition for the USB search.

**Conditions** This command requires the DPO4USB application module.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:CONDition

{SYNC|RESET|SUSPEND|RESUME|EOP|TOKENPacket|DATAPacket

|HANDSHAKEPacket|SPECIALPacket|ERRor}

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:CONDition?

**Arguments** SYNC indicates triggering on a Sync field of a packet.

RESET sets triggering on a reset condition.

SUSPEND sets triggering on a suspend condition.

RESUME sets triggering on a resume condition.

EOP indicates triggering on an end-of-packet signal.

TOKENPacket indicates triggering on a token packet.

DATAPacket indicates triggering on a data packet

HANDSHAKEPacket indicates triggering on a handshake packet.

SPECIALPacket indicates triggering on a special status packet.

ERROr indicates triggering on an error condition.

Examples SEARCH:SEARCH1:TRIGGER:A:BUS:B1:USB:CONDITION TOKENPACKET sets

the trigger condition to be a token packet.

SEARCH:SEARCH1:TRIGGER:A:BUS:B1:USB:CONDITION? might return:SEARCH:SEARCH1:TRIGGER:A:BUS:B1:USB:CONDITION SYNC, which

indicates that the trigger condition is a sync field.

# SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:DATa:HIVALue

Sets or returns the binary data string for the upper limit for inside-of-range and outside-of-range qualifiers for the USB search trigger when trigger search condition is DATAPacket. Use the command SEARCH:SEARCH<x>:TRIGger: A:BUS:B<x>:USB:DATa:VALue to set the lower limit.

**Conditions** This command requires the DPO4USB application module.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:DATa:HIVALue

<QString>

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:DATa:HIVALue?

**Related Commands** SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:CONDition,

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:DATa:VALue

**Arguments** <QString> within the range 00000000 to 11111111 (00 hex to FF hex).

Examples SEARCH:SEARCH1:TRIGGER:A:BUS:B1:USB:DATA:HIVALUE "00001000"

sets the upper limit to binary 00001000 (08 hex).

SEARCH:SEARCH1:TRIGGER:A:BUS:B1:USB:DATA:HIVALUE? might return :SEARCH:SEARCH1:TRIGGER:A:BUS:B1:USB:DATA:HIVALUE "01111111",

which indicates that the upper limit is 01111111 (7F hex).

#### SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:DATa:OFFSet

Sets or returns the data offset in bytes to trigger the search on. The minimum and

default values are 0 and the maximum is 1024.

**Conditions** This command requires the DPO4USB application module.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:DATa:OFFSet <NR1>

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:DATa:OFFSet?

**Arguments** <NR1> is number in the range 0 to 1024.

**Examples** SEARCH: TRIGGER: A:BUS: B1:USB: DATA: OFFSET 36 sets the data

offset to 36.

SEARCH:SEARCH1:TRIGGER:A:BUS:B1:USB:DATA:OFFSET? might return:SEARCH:SEARCH1:TRIGGER:A:BUS:B1:USB:DATA:OFFSET 0, indicating

that the data offset is the default value, 0.

### SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:DATa:SIZe

Sets or returns the number of contiguous data bytes to trigger the search on. The minimum and default values are 1 and the maximum value is 16.

**Conditions** This command requires the DPO4USB application module.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:DATa:SIZe <NR1>

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:DATa:SIZe?

**Arguments** <NR1> is number in the range 1 to 16.

**Examples** SEARCH:SEARCH1:TRIGGER:A:BUS:B1:USB:DATA:SIZE 4 sets the

oscilloscope to trigger on four contiguous data bytes.

SEARCH:SEARCH1:TRIGGER:A:BUS:B1:USB:DATA:SIZE? might return, :SEARCH:SEARCH1:TRIGGER:A:BUS:B1:USB:DATA:SIZE 6 indicating that

the oscilloscope will trigger on 6 contiguous data bytes.

#### SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:DATa:TYPe

Sets or returns the data type for the search trigger when the search trigger

condition is set to DATAPacket.

**Conditions** This command requires the DPO4USB application module.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:DATa:TYPe

{ANY | DATA0 | DATA1}

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:DATa:TYPe?

**Related Commands** SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:CONDition

**Arguments** ANY indicates either a DATA0 or DATA1 data packet type.

DATA0 indicates a DATA0 data packet type.

DATA1 indicates a DATA1 data packet type.

Examples SEARCH: SEAF

SEARCH:SEARCH1:TRIGGER:A:BUS:B1:USB:DATA:TYPE DATAO sets the

oscilloscope to trigger on a DATA0 data packet type.

SEARCH:SEARCH1:TRIGGER:A:BUS:B1:USB:DATA:TYPE? might return

:SEARCH:SEARCH1:TRIGGER:A:BUS:B1:USB:DATA:TYPE DATA1, indicating

that the data packet type is set to DATA1.

### SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:DATa:VALue

Sets or returns the binary data string to be used for the USB search trigger when the search trigger condition is DATAPacket.

This command also sets or returns the binary data string for the lower limit for inside-of-range and outside-of-range qualifiers for USB search trigger when the

trigger search condition is DATAPacket.

**Conditions** 

This command requires the DPO4USB application module.

Group

Search

**Syntax** 

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:DATa:VALue <QString>

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:DATa:VALue?

**Related Commands** 

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:CONDition

**Arguments** 

<QString> within the range 00000000 to 11111111 (00 hex to FF hex).

**Examples** 

SEARCH:SEARCH1:TRIGGER:A:BUS:B1:USB:DATA:VALUE "00001000" sets

the binary address to 00001000 (08 hex).

SEARCH:SEARCH1:TRIGGER:A:BUS:B1:USB:DATA:VALUE? might return :SEARCH:SEARCH1:TRIGGER:A:BUS:B1:USB:DATA:VALUE "01000000",

which indicates that the binary address is 0100000 (40 hex).

## SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:ENDPoint:VALue

Sets or returns the binary endpoint string to be used for the USB search trigger.

**Conditions** 

This command requires the DPO4USB application module.

Group

Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:ENDPoint:VALue

<QString>

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:ENDPoint:VALue?

**Related Commands** SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:CONDition

**Arguments** <QString> within the range 0000 to 1111 (00 hex to 0F hex).

Examples SEARCH:SEARCH1:TRIGGER:A:BUS:B1:USB:ENDPOINT:VALUE "1000" sets

the binary address to 1000 (08 hex).

SEARCH: SEARCH1: TRIGGER: A: BUS: B1: USB: ENDPOINT: VALUE? might return: SEARCH: SEARCH1: TRIGGER: A: BUS: B1: USB: ENDPOINT: VALUE "1001",

which indicates that the binary address is 1001 (09 hex).

#### SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:ERRORTYPe

Sets or returns the error type used when the search trigger condition is set to

ERRor.

**Conditions** This command requires the DPO4USB application module.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:ERRORTYPe

{PID|CRC5|CRC16|BITSTUFFing}

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:ERRORTYPe?

**Related Commands** SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:CONDition

**Arguments** PID indicates the error type is set to packet ID.

CRC5 indicates the error type is set to 5-bit CRC.

CRC16 indicates the error type is set to 16-bit CRC.

BITSTUFFing indicates the error type is set to bit stuffing.

**Examples** SEARCH:SEARCH1:TRIGGER:A:BUS:B1:USB:CONDITION PID sets the error

trigger condition to packet ID.

SEARCH:SEARCH1:TRIGGER:A:BUS:B1:USB:CONDITION? might return :SEARCH:SEARCH1:TRIGGER:A:BUS:B1:USB:CONDITION PID, indicating

the error trigger condition is packet ID.

### SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:HANDSHAKEType

Sets or returns the handshake type for the USB search trigger.

**Conditions** This command requires the DPO4USB application module.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:HANDSHAKEType

{ANY | NAK | ACK | STALL}

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:HANDSHAKEType?

**Related Commands** SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:CONDition

**Arguments** ANY indicates the oscilloscope will trigger on any handshake type.

NAK indicates the oscilloscope will trigger when a device cannot send or receive

data.

ACK indicates the oscilloscope will trigger when a packet is successfully received.

STALL indicates the oscilloscope will trigger when a device requires intervention

from the host.

**Examples** SEARCH:SEARCH1:TRIGGER:A:BUS:B1:USB:HANDSHAKETYPE ACK sets the

handshake type to acknowledgement.

SEARCH: SEARCH1: TRIGGER: A: BUS: B1: USB: HANDSHAKETYPE? might return

:SEARCH:SEARCH1:TRIGGER:A:BUS:B1:USB:HANDSHAKETYPE STALL,

indicating that the handshake type is set to stall.

### SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:QUALifier

Sets or returns the USB search trigger qualifier for address, endpoint and data.

**Conditions** This command requires the DPO4USB application module.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:QUALifier

{LESSThan|MOREThan|EQUal|UNEQual|LESSEQual

|MOREEQual|INrange|OUTrange|

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:QUALifier?

**Related Commands** SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:CONDition

**Arguments** LESSThan triggers the search on an value that is less than a set value.

MOREThan triggers the search on an value that is greater than a set value.

EQUal triggers the search on an value that is to a set value.

UNEQual triggers the search on an value that is not equal to a set value.

LESSEQual triggers the search on an value that is less than or equal to a set value.

MOREEQual triggers the search on an value that is that is more than or equal to a set value.

INrange triggers the search on an value that is within a range set by two values.

OUTrange triggers the search on an value that is outside of a range set by two values.

**Examples** SEARCH:SEARCH1:TRIGGER:A:BUS:B1:USB:QUALIFIER LESSTHAN sets the

oscilloscope to trigger when an address, data, or endpoint value is less than a

set value.

SEARCH:SEARCH1:TRIGGER:A:BUS:B1:USB:QUALIFIER? might return :SEARCH:SEARCH1:TRIGGER:A:BUS:B1:USB:QUALIFIER EQUAL indicating that the trigger condition is to trigger when an address, data, or endpoint is equal

to a set value.

#### SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:SOFFRAMENUMber

Sets or returns the binary data string to be used for start of frame number, when the search trigger condition is Token Packet and the token type is Start of Frame.

**Conditions** This command requires the DPO4USB application module.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:SOFFRAMENUMber

<QString>

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:SOFFRAMENUMber?

**Related Commands** SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:CONDition

**Arguments** <QString> within the range 000 0000 0000 to 111 1111 1111 (000 hex to 7FF

hex).

**Examples** SEARCH:SEARCH1:TRIGGER:A:BUS:B1:USB:SOFFRAMENUMBER

"0000001000" sets the start of frame number to 00000001000 (008 hex).

SEARCH: SEARCH1: TRIGGER: A: BUS: B1: USB: SOFFRAMENUMBER? might return: SEARCH: SEARCH1: TRIGGER: A: BUS: B1: USB: SOFFRAMENUMBER "0000001001", which indicates that the start of frame number is 00000001001

(009 hex).

## SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:SPECIALType

Sets or returns the packet ID (PID) for the special packet.

**Conditions** This command requires the DPO4USB application module.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:SPECIALType

{ANY|PREamble|RESERVed}

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:SPECIALType?

**Arguments** ANY indicates any type of special packet.

PREamble indicates a preamble special packet.

RESERVed indicates a reserved special packet.

**Examples** SEARCH:SEARCH1:TRIGGER:A:BUS1:USB:SPECIALTYPE PREAMBLE sets

the special packet type to preamble.

SEARCH:SEARCH1:TRIGGER:A:BUS1:USB:SPECIALTYPE? might return :SEARCH:SEARCH1:TRIGGER:A:BUS1:USB:SPECIALTYPE PREAMBLE,

indicating that the special type is set to preamble.

# SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:TOKENType

Sets or returns the token type for the USB search trigger.

**Conditions** This command requires the DPO4USB application module.

**Group** Search

**Syntax** SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:TOKENType

{ANY|SOF|OUT|IN|SETUP}

SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:USB:TOKENType?

**Arguments** ANY indicates any of the token types.

SOF indicates a SOF (start-of-frame) token type

OUT indicates an OUT token type.

IN indicates an IN token type.

SETUP indicates a SETUP token type.

**Examples** SEARCH:SEARCH1:TRIGGER:A:BUS:B1:USB:TOKENTYPE SETUP sets the

token type to SETUP.

SEARCH:SEARCH1:TRIGGER:A:BUS:B1:USB:TOKENTYPE? might return :SEARCH:SEARCH1:TRIGGER:A:BUS:B1:USB:TOKENTYPE SOF if the token

type is SOF.

# SEARCH:SEARCH<x>:TRIGger:A:BUS:SOUrce

Sets or returns a bus serial search. <x> is the search number.

**Conditions** This command requires a DPO4AUTO or DPO4EMBD application module.

**Group** Search

**Syntax** SEARCH:SEARCH<x>:TRIGger:A:BUS:SOUrce {B1|B2|B3|B4}

SEARCH:SEARCH<x>:TRIGger:A:BUS:SOUrce?

**Arguments** B1 specifies the Bus 1 source.

B2 specifies the Bus 2 source.

B3 specifies the Bus 3 source.

B4 specifies the Bus 4 source.

### SEARCH:SEARCH<x>:TRIGger:A:EDGE:SLOpe

Sets or returns the slope for an edge trigger search to determine where to place a mark. <x> is the search number.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:EDGE:SLOpe {RISe|FALL}

SEARCH:SEARCH<x>:TRIGger:A:EDGE:SLOpe?

**Arguments** RISe specifies a rising edge.

FALL specifies a falling edge.

### SEARCH:SEARCH<x>:TRIGger:A:EDGE:SOUrce

Sets or returns the source waveform for an edge trigger search to determine where to place a mark.  $\langle x \rangle$  is the search number.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:EDGE:SOUrce

{CH1|CH2|CH3|CH4|MATH}

SEARCH:SEARCH<x>:TRIGger:A:EDGE:SOUrce?

**Arguments** CH<x> specifies one input channel as the edge source, where <x> is the channel

number.

MATH specifies the math waveform as the search source.

#### SEARCH:SEARCH<x>:TRIGger:A:LEVel

Sets or returns the level for an edge trigger search to determine where to place a mark. <x> is the search number.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:LEVel {<NR3>|TTL}

SEARCH:SEARCH<x>:TRIGger:A:LEVel?

**Arguments** <NR3> specifies the trigger level, in volts.

TTL specifies a preset TTL high level of 1.4V.

### SEARCH:SEARCH<x>:TRIGger:A:LEVel:CH<x>

Sets or returns the level for an edge trigger search to determine where to place a mark. SEARCH<x> is the search number and CH<x> is the channel number. Each channel can have an independent level.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:LEVel:CH<x> {<NR3>|TTL}

SEARCH:SEARCH<x>:TRIGger:A:LEVel:CH<x>?

**Arguments** <NR3> specifies the trigger level in volts.

TTL specifies a preset TTL high level of 1.4 V.

# SEARCH:SEARCH<x>:TRIGger:A:LEVel:MATH[1]

Sets or returns the math waveform level for an edge trigger search to determine where to place a mark. <x> is the search number. The value of MATH is 1 for all oscilloscopes.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:LEVel:MATH {TTL}

SEARCH:SEARCH<x>:TRIGger:A:LEVel:MATH?

**Arguments** TTL specifies a preset TTL high level of 1.4 V.

# SEARCH:SEARCH<x>:TRIGger:A:LEVel:REF<x>

Sets or returns the specified reference waveform level for an edge trigger search to determine where to place a mark. SEARCH<x> is the search number and REF<x> is the reference channel number.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:LEVe]:REF<x> {TTL}

SEARCH:SEARCH<x>:TRIGger:A:LEVel:REF<x>?

**Arguments** TTL specifies a preset TTL high level of 1.4 V.

# SEARCH:SEARCH<x>:TRIGger:A:LOGIc:FUNCtion

Sets or returns the logic operator for a logic trigger search to determine where to place a mark. <x> is the search number.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:LOGIc:FUNCtion {AND|NANd|NOR|OR}

SEARCH:SEARCH<x>:TRIGger:A:LOGIc:FUNCtion?

**Arguments** AND places a mark if all conditions are true.

NANd places a mark if any of the conditions are false.

NOR places a mark if all conditions are false.

OR places a mark if any of the conditions are true.

# SEARCH:SEARCH<x>:TRIGger:A:LOGIc:INPut:CH<x>

Sets or returns the Boolean logic criteria for a logic trigger search to determine where to place a mark. SEARCH<x> is the search number and CH<x> is the channel number.

Group Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:LOGIc:INPut:CH<x> {HIGH|LOW|X}

SEARCH:SEARCH<x>:TRIGger:A:LOGIc:INPut:CH<x>?

**Arguments** HIGH specifies the logic high.

LOW specifies the logic low.

X specifies a "don't care" state.

# SEARCH:SEARCH<x>:TRIGger:A:LOGIc:INPut:CLOCk:EDGE

Sets or returns whether the clock edge is a rising or falling for a logic search to determine where to place a mark. <x> is the search number.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:LOGIc:INPut:CLOCk:EDGE

{FALL|RISe}

SEARCH:SEARCH<x>:TRIGger:A:LOGIc:INPut:CLOCk:EDGE?

**Arguments** RISe specifies a rising edge.

FALL specifies a falling edge.

### SEARCH:SEARCH<x>:TRIGger:A:LOGIc:INPut:CLOCk:SOUrce

Sets or returns the clock source definition for a logic trigger search.  $\langle x \rangle$  is the search number. If a clock source is defined, then the logic search is determined by the state of the other inputs at the clock transition. If no clock source is defined, then the logic search is determined only by the state of the inputs.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:LOGIc:INPut:CLOCk:SOUrce

{CH1|CH2|CH3|CH4|MATH|REF|NONe}

SEARCH:SEARCH<x>:TRIGger:A:LOGIc:INPut:CLOCk:SOUrce?

**Arguments** CH<x> specifies a channel input as the clock source, where <x> = 1, 2, 3, or 4.

MATH specifies the math waveform as the clock source.

REF specifies the reference waveform as the clock source.

NONe specifies no clock source.

# SEARCH:SEARCH<x>:TRIGger:A:LOGIc:INPut:D<x>

Sets or returns the waveform logic criteria for a trigger search. SEARCH<x> is the search number and D<x> is the digital channel number.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:LOGIc:INPut:D<x> {HIGH|LOW|X}

SEARCH:SEARCH<x>:TRIGger:A:LOGIc:INPut:D<x>?

**Arguments** HIGH specifies a high logic level.

LOW specifies a low logic level.

X specifies a "don't care" condition.

# SEARCH:SEARCH<x>:TRIGger:A:LOGIc:INPut:MATH

Sets or returns the Boolean logic criteria for a logic trigger search to determine where to place a mark. <x> is the search number.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:LOGIc:INPut:MATH {HIGH|LOW|X}

SEARCH:SEARCH<x>:TRIGger:A:LOGIc:INPut:MATH?

**Arguments** HIGH specifies a high logic level.

LOW specifies a low logic level.

X specifies a "don't care" condition.

# SEARCH:SEARCH<x>:TRIGger:A:LOGIc:INPut:REF<x>

Sets or returns the Boolean logic criteria for a logic trigger search to determine where to place a mark. SEARCH<x> is the search number and REF<x> is the reference channel number.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGGer:A:LOGIC:INPut:REF<x> {HIGH|LOW|X}

SEARCH:SEARCH<x>:TRIGger:A:LOGIc:INPut:REF<x>?

**Arguments** HIGH specifies a high logic level.

LOW specifies a low logic level.

X specifies a "don't care" condition.

# SEARCH:SEARCH<x>:TRIGger:A:LOGIc:PATtern:INPut:CH<x>

Sets or returns the logic criteria for a logic pattern trigger search to determine where to place a mark. SEARCH<x> is the search number and CH<x> is the channel number.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:LOGIc:PATtern:INPut:CH<x>

{HIGH|LOW|X}

SEARCH:SEARCH<x>:TRIGger:A:LOGIc:PATtern:INPut:CH<x>?

**Arguments** HIGH specifies a high logic level.

LOW specifies a low logic level.

X specifies a "don't care" condition.

#### SEARCH:SEARCH<x>:TRIGger:A:LOGIc:PATtern:INPut:D<x>

Sets or returns the logic criteria for a logic pattern search to determine where to place a mark. SEARCH<x> is the search number and D<x> is the digital channel number

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:LOGIc:PATtern:INPut:D<x>

{HIGH|LOW|X}

SEARCH:SEARCH<x>:TRIGger:A:LOGIc:PATtern:INPut:D<x>?

**Arguments** HIGH specifies a high logic level.

LOW specifies a low logic level.

X specifies a "don't care" condition.

# SEARCH:SEARCH<x>:TRIGger:A:LOGIc:PATtern:INPut:MATH

Sets or returns the Boolean logic criteria for a logic pattern trigger search to determine where to place a mark. <x> is the search number.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:LOGIc:PATtern:INPut:MATH

{HIGH|LOW|X}

SEARCH:SEARCH<x>:TRIGger:A:LOGIc:PATtern:INPut:MATH?

**Arguments** HIGH specifies a high logic level.

LOW specifies a low logic level.

X specifies a "don't care" condition.

# SEARCH:SEARCH<x>:TRIGger:A:LOGIc:PATtern:INPut:REF<x>

Sets or returns the Boolean logic criteria for a pattern trigger search to determine where to place a mark. SEARCH<x> is the search number and REF<x> is the reference channel number.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:LOGIc:PATtern:INPut:REF<x>

{HIGH|LOW|X}

SEARCH:SEARCH<x>:TRIGger:A:LOGIc:PATtern:INPut:REF<x>?

**Arguments** HIGH specifies a high logic level.

LOW specifies a low logic level.

X specifies a "don't care" condition.

# SEARCH:SEARCH<x>:TRIGger:A:LOGIc:PATtern:WHEn

Sets or returns the condition for generating a logic pattern trigger search to determine where to place a mark.  $\langle x \rangle$  is the search number.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:LOGIc:PATtern:WHEn

{TRUe|FALSe|LESSThan|Than|EQUal|UNEQual}

SEARCH:SEARCH<x>:TRIGger:A:LOGIc:PATtern:WHEn?

**Arguments** TRUe places a mark when the pattern becomes true.

FALSe places a mark when the pattern becomes false.

LESSThan places a mark if the specific pattern is true less than the time set by the SEARCH:SEARCH<x>:TRIGger:A:LOGIc:PATtern:WHEn:LESSLimit command.

Than places a mark if the specific pattern is true longer than the specified time set by the SEARCH:SEARCH<x>:TRIGger:A:LOGIc:PATtern:WHEn:MORELimit command.

EQUal places a mark if the specific pattern is true longer than the time set by the SEARCH:SEARCH<x>:TRIGger:A:LOGIc:PATtern:WHEn:LESSLimit command, but less than the specified time set by the SEARCH:SEARCH<x>:TRIGger:A:LOGIc:PATtern:WHEn:MORELimit command.

UNEQual places a mark if the specific pattern is true less than the time set by the SEARCH:SEARCH<x>:TRIGger:A:LOGIc:PATtern:WHEn:LESSLimit command, or longer than the specified time set by the SEARCH:SEARCH<x>:TRIGger:A:LOGIc:PATtern:WHEn:MORELimit command.

# SEARCH:SEARCH<x>:TRIGger:A:LOGIc:PATtern:WHEn:LESSLimit

Sets or returns the maximum time that the selected pattern may be true and still generate an A logic pattern search to place a mark. <x> is the search number.

**Group** Search

**Syntax** SEARCH:SEARCH<x>:TRIGger:A:LOGIC:PATtern:WHEn:LESSLimit

<NR3>

SEARCH:SEARCH<x>:TRIGger:A:LOGIc:PATtern:WHEn:LESSLimit?

**Arguments** <NR3> specifies the maximum amount of time to hold the pattern true.

#### SEARCH:SEARCH<x>:TRIGger:A:LOGIc:PATtern:WHEn:MORELimit

Sets or returns the minimum time that the selected pattern may be true and still generate an A logic pattern search to place a mark. <x> is the search number.

**Group** Search

**Syntax** SEARCH:SEARCH<x>:TRIGger:A:LOGIC:PATtern:WHEn:MORELimit

<NR3>

SEARCH:SEARCH<x>:TRIGger:A:LOGIc:PATtern:WHEn:MORELimit?

**Arguments** <NR3> specifies the minimum amount of time to hold the pattern true.

# SEARCH:SEARCH<x>:TRIGger:A:LOGIc:THReshold:CH<x>

Sets or returns the channel threshold level for a logic trigger search to determine where to place a mark. SEARCH<x> is the search number and CH<x> is the channel number.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:LOGIc:THReshold:CH<x> {<NR3>|TTL}

SEARCH:SEARCH<x>:TRIGger:A:LOGIc:THReshold:CH<x>?

**Arguments** <NR3> specifies the trigger level, in volts.

TTL specifies a preset TTL high level of 1.4 V.

### SEARCH:SEARCH<x>:TRIGger:A:LOGIc:THReshold:MATH

Sets or returns the math waveform threshold level for a logic trigger search to determine where to place a mark. <x> is the search number.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:LOGIc:THReshold:MATH {TTL}

SEARCH:SEARCH<x>:TRIGger:A:LOGIc:THReshold:MATH?

**Arguments** TTL specifies a preset TTL high level of 1.4 V.

### SEARCH:SEARCH<x>:TRIGger:A:LOGIc:THReshold:REF<x>

Sets or returns the reference waveform threshold level for a logic trigger search to determine where to place a mark. SEARCH<x> is the search number and REF<x> is the reference channel number.

Group Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:LOGIc:THReshold:REF<x> {TTL}

SEARCH:SEARCH<x>:TRIGger:A:LOGIc:THReshold:REF<x>?

**Arguments** TTL specifies a preset TTL high level of 1.4 V.

# SEARCH:SEARCH<x>:TRIGger:A:LOWerthreshold:CH<x>

Sets or returns the channel waveform lower threshold to determine where to place a mark. This setting is applied to all channel searches that use a lower threshold. SEARCH<x> is the search number and CH<x> is the channel number.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:LOWerthreshold:CH<x> {TTL}

SEARCH:SEARCH<x>:TRIGger:A:LOWerthreshold:CH<x>?

**Arguments** TTL specifies a preset TTL high level of 1.4 V.

#### SEARCH:SEARCH<x>:TRIGger:A:LOWerthreshold:MATH

Sets or returns the math waveform lower threshold to determine where to place a mark. This setting is applied to all math searches that use a lower threshold. <x> is the search number.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:LOWerthreshold:MATH {TTL}

SEARCH:SEARCH<x>:TRIGger:A:LOWerthreshold:MATH?

**Arguments** TTL specifies a preset TTL high level of 1.4 V.

#### SEARCH:SEARCH<x>:TRIGger:A:LOWerthreshold:REF<x>

Sets or returns the reference waveform lower threshold to determine where to place a mark. This setting is applied to all reference searches that use a lower threshold.

SEARCH<x> is the search number and REF<x> is the reference channel number.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:LOWerthreshold:REF<x> {TTL}

SEARCH:SEARCH<x>:TRIGger:A:LOWerthreshold:REF<x>?

**Arguments** TTL specifies a preset TTL high level of 1.4 V.

#### SEARCH:SEARCH<x>:TRIGger:A:PULSEWidth:POLarity

Sets or returns the polarity for a pulse trigger search to determine where to place a

mark.  $\langle x \rangle$  is the search number.

**Group** Search

**Syntax** SEARCH:SEARCH<x>:TRIGger:A:PULSEWidth:POLarity

{NEGative|POSitive}

SEARCH:SEARCH<x>:TRIGger:A:PULSEWidth:POLarity?

**Arguments** POSITIVE places a mark only when the polarity of the pulse is positive.

NEGative places a mark only when the polarity of the pulse is negative.

# SEARCH:SEARCH<x>:TRIGger:A:PULSEWidth:SOUrce

Sets or returns the source waveform for a pulse trigger search to determine where

to place a mark. <x> is the search number.

**Group** Search

**Syntax** SEARCH:SEARCH<x>:TRIGger:A:PULSEWidth:SOUrce

{CH1|CH2|CH3|CH4|MATH|REF}

SEARCH:SEARCH<x>:TRIGger:A:PULSEWidth:SOurce?

**Arguments** CH<x> specifies one input channel as the edge source, where  $\langle x \rangle = 1, 2, 3$  or 4.

MATH specifies the math waveform as the search source.

REF specifies the reference waveform as the search source.

# SEARCH:SEARCH<x>:TRIGger:A:PULSEWidth:WHEn

Sets or returns the condition for generating a pulse width search to determine where to place a mark.  $\langle x \rangle$  is the search number.

Search Group

**Syntax** SEARCH:SEARCH<x>:TRIGger:A:PULSEWidth:WHEn

{LESSthan|than|EQual|UNEQual}

SEARCH: SEARCH<x>:TRIGger:A:PULSEWidth:WHEn?

**Arguments** LESSThan places a mark if the pulse width is less than the time set by the

SEARCH:SEARCH<x>:TRIGger:A:PULSEWidth:WIDth command.

Than places a mark if the pulse width is true longer than the specified time set by the SEARCH:SEARCH<x>:TRIGger:A:PULSEWidth:WIDth command.

EQUal places a mark if the pulse width is equal to the time set by the SEARCH:SEARCH<x>:TRIGger:A:PULSEWidth:WIDth command within a tolerance of  $\pm 5\%$ .

UNEQual places a mark if the pulse width is unequal to the time the time set by the SEARCH:SEARCH<x>:TRIGger:A:PULSEWidth:WIDth command within a tolerance of  $\pm 5\%$ .

# SEARCH:SEARCH<x>:TRIGger:A:PULSEWidth:WIDth

Sets or returns the pulse width setting for a pulse width trigger search to determine where to place a mark.  $\langle x \rangle$  is the search number.

Search Group

**Syntax** SEARCH:SEARCH<x>:TRIGger:A:PULSEWidth:WIDth <NR3>

SEARCH:SEARCH<x>:TRIGger:A:PULSEWidth:WIDth?

**Arguments** <NR3> is the pulse width.

# SEARCH:SEARCH<x>:TRIGger:A:RUNT:POLarity

Sets or returns the polarity setting for a runt trigger search to determine where to

place a mark. <x> is the search number.

Group Search

SEARCH:SEARCH<x>:TRIGger:A:RUNT:POLarity **Syntax** 

{EITher|NEGative|POSitive}

SEARCH:SEARCH<x>:TRIGger:A:RUNT:POLarity?

#### **Arguments**

POSitive places a mark when the rising edge crosses the low threshold and the falling edge re-crosses the low threshold without either edge ever crossing the high threshold.

NEGative places a mark when the falling edge crosses the high threshold and the rising edge re-crosses the high threshold without either edge ever crossing the low threshold.

EITher places a mark on a runt of either polarity.

# SEARCH:SEARCH<x>:TRIGger:A:RUNT:SOUrce

Sets or returns the source setting for a runt trigger search to determine where to place a mark.  $\langle x \rangle$  is the search number.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:RUNT:SOUrce

{CH1|CH2|CH3|CH4|MATH|REF}

SEARCH:SEARCH<x>:TRIGger:A:RUNT:SOUrce?

**Arguments** CH1-CH4 specifies an input channel as the edge source.

MATH specifies the math waveform as the search source.

REF specifies the reference waveform as the search source.

#### SEARCH:SEARCH<x>:TRIGger:A:RUNT:WHEn

Sets or returns the condition setting for a runt trigger search to determine where to place a mark.  $\langle x \rangle$  is the search number.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:RUNT:WHEn

{LESSthan|than|EQual|UNEQual|OCCURS} SEARCH:SEARCH<x>:TRIGger:A:RUNT:WHEn?

**Arguments** OCCURS argument specifies a trigger event if a runt of any detectable width occurs.

LESSthan argument sets the oscilloscope to trigger if the a runt pulse is detected with width less than the time set by the SEARCH:SEARCH<x>:TRIGger:A:

**RUNT: WIDth command.** 

than argument sets the oscilloscope to trigger if the a runt pulse is detected with width than the time set by the SEARCH:SEARCH<x>:TRIGger:A:RUNT:WIDth command.

EQUal argument sets the oscilloscope to trigger when the pattern is true for a time period equal to the time period specified in SEARCH:SEARCH<x>:TRIGger:A: RUNT:WIDth within a ±5% tolerance.

NOTEQual argument sets the oscilloscope to trigger when the pattern is true for a time period greater than or less than (but not equal) the time period specified in SEARCH:SEARCH<x>:TRIGger:A:RUNT:WIDth within a  $\pm 5\%$  tolerance.

# SEARCH:SEARCH<x>:TRIGger:A:RUNT:WIDth

Sets or returns the width setting for a runt trigger search to determine where to place a mark. <x> is the search number.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:RUNT:WIDth <NR3>

SEARCH:SEARCH<x>:TRIGger:A:RUNT:WIDth?

**Arguments** <NR3> specifies the minimum width, in seconds.

# SEARCH:SEARCH<x>:TRIGger:A:SETHold:CLOCk:EDGE

Sets or returns the clock slope setting for a setup/hold trigger search to determine where to place a mark.  $\langle x \rangle$  is the search number.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:SETHold:CLOCk:EDGE {FALL|RISe}

SEARCH:SEARCH<x>:TRIGger:A:SETHold:CLOCk:EDGE?

**Arguments** FALL specifies polarity as the clock falling edge.

RISe specifies polarity as the clock rising edge.

# SEARCH:SEARCH<x>:TRIGger:A:SETHold:CLOCk:SOUrce

Sets or returns the clock source setting for an setup/hold trigger search to determine where to place a mark. <x> is the search number.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:SETHold:CLOCk:SOurce

{CH1|CH2|CH3|CH4|MATH|REF}

SEARCH:SEARCH<x>:TRIGger:A:SETHold:CLOCk:SOurce?

Related Commands SEARCH:SEARCH<x>:TRIGger:A:SETHold:DATa:SOUrce

**Arguments** CH1-CH4 specifies an input channel as the edge source.

MATH specifies the math waveform as the search source.

REF specifies the reference waveform as the search source.

# SEARCH:SEARCH<x>:TRIGger:A:SETHold:CLOCk:THReshold

Sets or returns the clock threshold setting for an setup/hold trigger search to determine where to place a mark. <x> is the search number.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:SETHold:CLOCk:THReshold

{<NR3>|TTL|ECL}

SEARCH:SEARCH<x>:TRIGger:A:SETHold:CLOCk:THReshold?

**Arguments** TTL specifies a preset TTL high level of 1.4 V.

ECL specifies a preset ECL high level of -1.3V.

<NR3> is the clock level, in volts.

# SEARCH:SEARCH<x>:TRIGger:A:SETHold:DATa:SOUrce

Sets or returns the data source setting for an setup/hold trigger search to determine where to place a mark.  $\langle x \rangle$  is the search number. You cannot specify the same source for both clock and data.

**Group** Search

Syntax DPO Models:

SEARCH:SEARCH<x>:TRIGger:A:SETHold:DATa:SOurce

{CH1|CH2|CH3|CH4|MATH|REF}

MSO Models:

SEARCH:SEARCH<x>:TRIGger:A:SETHold:DATa:SOUrce <wfm>[,<wfm>]

[,<wfm>] [,<wfm] [,<wfm>] [,<wfm>] [,<wfm>] [,<wfm] [,<wfm

[, <wfm>] [, <wfm>] [, <wfm>]

SEARCH:SEARCH<x>:TRIGger:A:SETHold:DATa:SOUrce?

Related Commands SEARCH:SEARCH<x>:TRIGger:A:SETHold:CLOCk:SOUrce

**Arguments** DPO Models:

CH1-CH4 specifies an input channel as the search source.

MATH specifies the math waveform as the search source.

REF specifies the reference waveform as the search source.

MSO Models:

<wfm> can be any combination of the channel, math, reference, and digital

waveforms.

### SEARCH:SEARCH<x>:TRIGger:A:SETHold:DATa:THReshold

Sets or returns the data threshold setting for an setup/hold trigger search to determine where to place a mark.  $\langle x \rangle$  is the search number.

**Group** Search

**Syntax** SEARCH:SEARCH<x>:TRIGger:A:SETHold:DATa:THReshold

{<NR3>|TTL}

SEARCH:SEARCH<x>:TRIGger:A:SETHold:DATa:THReshold?

**Arguments** TTL specifies a preset TTL high level of 1.4 V.

<NR3> is the clock level, in volts.

### SEARCH:SEARCH<x>:TRIGger:A:SETHold:HOLDTime

Sets or returns the hold time setting for an setup/hold trigger search to determine where to place a mark. <x> is the search number.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:SETHold:HOLDTime <NR3>

SEARCH:SEARCH<x>:TRIGger:A:SETHold:HOLDTime?

**Arguments** <NR3> specifies the hold time setting in seconds. Positive values for hold time

occur after the clock edge. Negative values occur before the clock edge.

#### SEARCH:SEARCH<x>:TRIGger:A:SETHold:SETTime

Sets or returns the setup time setting for an setup/hold trigger search to determine where to place a mark.  $\langle x \rangle$  is the search number.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:SETHold:SETTime <NR3>

SEARCH:SEARCH<x>:TRIGger:A:SETHold:SETTime?

**Arguments** <NR3> specifies the setup time for setup and hold violation triggering.

#### SEARCH:SEARCH<x>:TRIGger:A:SETHold:THReshold:CH<x>

Sets or returns the trigger search setup and hold lower threshold for the selected channel. This helps determine where to place search marks. Search<x> is the search number, which is always 1. CH<x> is the channel number.

**Conditions** MSO oscilloscopes only.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:SETHold:THReshold:CH<x> <NR3>

SEARCH:SEARCH<x>:TRIGger:A:SETHold:THReshold:CH<x>?

**Arguments** <NR3> is the lower threshold in volts.

#### SEARCH:SEARCH<x>:TRIGger:A:SETHold:THReshold{:MATH|:MATH1}

Sets or returns the trigger search setup and hold threshold for the math waveform. This helps to determine where to place search marks. Search<x> is the search number, which is always 1.

**Conditions** MSO oscilloscopes only.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:SETHold:THReshold{:MATH|:MATH1}

<NR3>

SEARCH:SEARCH<x>:TRIGger:A:SETHold:THReshold{:MATH|:MATH1}?

**Arguments** <NR3> is the lower threshold in volts.

### SEARCH:SEARCH<x>:TRIGger:A:SETHold:THReshold:REF<x>

Sets or returns the trigger search setup and hold threshold for the selected reference waveform. This helps to determine where to place search marks. Search<x> is the search number, which is always 1. REF<x> is the reference waveform number.

**Conditions** MSO oscilloscopes only.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:SETHold:THReshold:REF<x> <NR3>

SEARCH:SEARCH<x>:TRIGger:A:SETHold:THReshold:REF<x>?

**Arguments** <NR3> is the lower threshold in volts.

### SEARCH:SEARCH<x>:TRIGger:A{:TRANsition|:RISEFall}:DELTatime

Sets or returns the transition time setting for an transition trigger search to determine where to place a mark.<x> is the search number.

**Group** Search

**Syntax** SEARCH:SEARCH<x>:TRIGger:A{:TRANsition|:RISEFall}:DELTatime

<NR3>

SEARCH:SEARCH<x>:TRIGger:A{:TRANsition|:RISEFall}:DELTatime?

**Arguments** <NR3> specifies the transition time, in seconds.

### SEARCH:SEARCH<x>:TRIGger:A{:TRANsition|:RISEFall}:POLarity

Sets or returns the polarity setting for an transition trigger search to determine where to place a mark. <x> is the search number.

Group Search

**Syntax** SEARCH:SEARCH<x>:TRIGger:A{:TRANsition|:RISEFall}:POLarity

{EITher|NEGative|POSitive}

SEARCH:SEARCH<x>:TRIGger:A{:TRANsition|:RISEFall}:POLarity?

**Arguments** POSitive specifies that a pulse edge must traverse from the lower (most

negative) to higher (most positive) level for transition triggering to occur.

NEGative specifies that a pulse edge must traverse from the upper (most positive)

to lower (most negative) level for transition triggering to occur.

EITher specifies either positive or negative polarity.

# SEARCH:SEARCH<x>:TRIGger:A{:TRANsition|:RISEFall}:SOUrce

Sets or returns the source setting for an transition trigger search to determine where to place a mark. <x> is the search number.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A{:TRANsition|:RISEFall}:SOurce

{CH1|CH2|CH3|CH4|MATH}

SEARCH:SEARCH<x>:TRIGger:A{:TRANsition|:RISEFall}:SOurce?

**Arguments** CH1-CH4 specifies one input channel as the edge source.

MATH specifies the math waveform as the search source.

### SEARCH:SEARCH<x>:TRIGger:A{:TRANsition|:RISEFall}:WHEn

Sets or returns the condition setting for an transition trigger search to determine where to place a mark.  $\langle x \rangle$  is the search number.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A{:TRANsition|:RISEFall}:WHEn

{SLOWer|FASTer|EQual|UNEQual}

SEARCH:SEARCH<x>:TRIGger:A{:TRANsition|:RISEFall}:WHEn?

**Arguments** FASTer sets the trigger to occur when the transitioning signal is faster than the set

volts/second rate.

SLOWer sets the trigger to occur when the transitioning signal is slower than

the set volts/second rate.

EQual sets the trigger to occur when the transitioning signal is equal to the set

volts/second rate within a  $\pm 5\%$  tolerance.

UNEQual sets the trigger to occur when the transitioning signal is not equal to

the set volts/second rate  $\pm 5\%$ .

### SEARCH:SEARCH<x>:TRIGger:A:TYPe

Sets or returns the trigger type setting for a search to determine where to place a mark. <x> is the search number.

**Group** Search

**Syntax** SEARCH:SEARCH<x>:TRIGger:A:TYPe

{EDGe|SETHold|PULSEWidth|RUNt|TRANsition|LOGIc|BUS (with the

appropriate application module installed)}

SEARCH:SEARCH<x>:TRIGger:A:TYPe?

**Arguments** RUNt triggers when a pulse crosses the first preset voltage threshold but does not

cross the second preset threshold before recrossing the first. The thresholds are set with the SEARCH:SEARCH<x>:TRIGger:A:LOWerthreshold:CH<x> and SEARCH:SEARCH<x>:TRIGger:A:UPPerthreshold:CH<x> commands.

PULSEWIdth triggers when a pulse is found that has the specified polarity and is either inside or outside the limits as specified by

SEARCH:SEARCH<x>:TRIGger:A:LOGIc:PATtern:WHEn:LESSLimit and SEARCH:SEARCH<x>:TRIGger:A:LOGIc:PATtern:WHEn:MORELimit.

The polarity is selected using the SEARCH:SEARCH<x>:TRIGger:A:RUNT: POLarity command.

TRANsition triggers when a pulse crosses both thresholds in the same direction as the specified polarity and the transition time between the two threshold crossings is greater or less than the specified time delta.

# SEARCH:SEARCH<x>:TRIGger:A:UPPerthreshold:CH<x>

Sets or returns the channel waveform upper threshold to determine where to place a mark. This setting is applied to all channel searches that uses an upper threshold.SEARCH<x> is the search number and CH<x> is the channel number.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:UPPerthreshold:CH<x> {TTL}

SEARCH:SEARCH<x>:TRIGger:A:UPPerthreshold:CH<x>?

**Arguments** TTL specifies a preset TTL high level of 1.4 V.

#### SEARCH:SEARCH<x>:TRIGger:A:UPPerthreshold:MATH

Sets or returns the math waveform upper threshold to determine where to place a mark. This setting is applied to all math waveform searches that uses an upper threshold. <x> is the search number.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:UPPerthreshold:MATH {TTL}

SEARCH:SEARCH<x>:TRIGger:A:UPPerthreshold:MATH?

**Arguments** TTL specifies a preset TTL high level of 1.4 V.

# SEARCH:SEARCH<x>:TRIGger:A:UPPerthreshold:REF<x>

Sets or returns the reference waveform upper threshold to determine where to place a mark. This setting is applied to all reference waveform searches that uses an upper threshold. SEARCH<x> is the search number and REF<x> is the reference channel number.

**Group** Search

Syntax SEARCH:SEARCH<x>:TRIGger:A:UPPerthreshold:REF<x> {TTL}

SEARCH:SEARCH<x>:TRIGger:A:UPPerthreshold:REF<x>?

**Arguments** TTL specifies a preset TTL high level of 1.4 V.

**SELect** 

Sets or returns the selected waveform display (controlled by the front-panel)

on or off.

**Group** Vertical

**Syntax** SELect {ON|OFF}

**Arguments** ON turns the selected waveform display on.

OFF turns the selected waveform display off.

**Examples** SELECT might return the following

:SELECT:BUS1 0;BUS2 0;CH1 1;CH2 0;CH3 0;CH4 0;MATH 0;REF1

0; REF2 0; REF3 0; REF4 0; CONTROL CH1

SELect:BUS<x>

This command turns on and off the display of the waveform for  $\langle x \rangle$ , where x is the bus number. The query returns whether the channel is on or off but does not

indicate whether it is the selected waveform.

**Group** Vertical

Syntax SELect:BUS<x> {<NR1>|OFF|ON}

SELect:BUS<x>?

#### SELect:CH<x>

Turns the display of the channel  $\langle x \rangle$  waveform on or off, where  $\langle x \rangle$  is the channel number. This command also resets the acquisition. The query returns whether the channel is on or off but does not indicate whether it is the selected waveform.

**Group** Vertical

Syntax SELect:CH<x> {ON|OFF|<NR1>}

SELect:CH<x>?

**Arguments** ON turns on the display of the specified waveform. This waveform also becomes

the selected waveform.

OFF turns off the display of the specified waveform.

<NR1> = 0 turns off the display of the specified waveform; any other value turns

on the display of the specified waveform.

**Examples** SELECT: CH2 ON turns the channel 2 waveform display on, and selects channel 2.

SELECT: CH1? might return: SELECT: CH1 1 indicating that channel 1 is being

displayed.

#### SELect:CONTROL

Sets or returns the waveform that is the recipient of future channel-related commands, for example, the cursor commands. The command form also performs the equivalent of a SELect:CH<x> ON command, as well as the Math, Reference, and Bus variations of that command.

**Group** Vertical

Syntax SELect:CONTROl {CH<x>|MATH|BUS<x>}

SELect: CONTROl?

**Arguments** CH<x> specifies a channel waveform as the waveform affected by the front-panel

controls. <x> is the channel number.

MATH specifies the math waveform as the waveform that is affected by the

front-panel controls.

BUS<x> specifies a bus waveform as the waveform affected by the front-panel controls. <x> specifies the bus number.

Returns

NONE if all the channels are turned off. NONE is ignored on input.

**Examples** 

SELECT: CONTROL CH2 resets acquisition displays on channel 2, and causes the selected waveform to be the implied object of waveform commands.

SELECT: CONTROL? might return: SELECT: CONTROL MATH indicating that math is the implied object of waveform commands.

#### SELect:D<x>

Turns on the display of the digital channel <x> and resets the acquisition. <x> is the channel number. The query returns whether the channel is on or off but does not indicate whether it is the selected waveform.

**Group** Vertical

Syntax SELect:D<x> {<NR1>|OFF|ON}

SELect:D<x>?

Arguments

ON turns on the display of the specified waveform. This waveform also becomes the selected waveform.

OFF turns off the display of the specified waveform.

<NR1> = 0 turns off the display of the specified waveform; any other value turns on the display of the specified waveform.

**Examples** 

SELECT: D2 ON turns the digital channel 2 waveform display on, and selects digital channel 2.

SELECT:D2? might return:SELECT:D2 1 indicating that digital channel 2 is being displayed.

# SELect:MATH[1]

Turns on and off the display of the math waveform. The query returns whether the math waveform is on or off but does not indicate whether it is the selected waveform.

**Group** Vertical

Syntax SELect:MATH[1] {ON|OFF|<NR1>}

SELect:MATH[1]?

**Arguments** ON turns on the display of the specified waveform. This waveform also becomes

the selected waveform.

OFF turns off the display of the specified waveform.

<NR1> = 0 turns off the display of the specified waveform; any other value turns

on the display of the specified waveform.

**Examples** SELECT: MATH ON turns the math waveform display on, and selects it.

SELECT: MATH? might return: SELECT: MATH 1 indicating that the math

waveform is being displayed.

#### SELect:REF<x>

Turns on and off the display of the reference waveform <x>. The <x> variable represents the reference channel number. The query returns whether the channel is on or off.

**Group** Vertical

Syntax SELect:REF<x> {ON|OFF|<NR1>}

SELect:REF<x>?

**Arguments** ON turns on the display of the specified waveform. This waveform also becomes

the selected waveform.

OFF turns off the display of the specified waveform.

<NR1> = 0 turns off the display of the specified waveform; any other value turns

on the display of the specified waveform.

**Examples** SELECT: REF2 ON turns the channel 2 waveform display on, and selects reference

waveform 2.

SELECT: REF2? might return: SELECT: REF2 1 indicating that reference

waveform 2 is being displayed.

#### **SET?** (Query Only)

Returns the commands that list the oscilloscope settings except for configuration information for the calibration values, the WFMInpre? query, and the WFMOutpre? query. This query allows you to record or "learn" the current oscilloscope settings. You can use these commands to return the oscilloscope to the state it was in when you made the SET? query. The SET? query always returns command headers, regardless of the setting of the HEADer command. This is because the returned commands are intended to be sent back to the oscilloscope as a command string. The VERBose command can still be used to specify whether the returned headers should be abbreviated or full-length.

This command is identical to the \*LRN? command.

**Group** Miscellaneous

Syntax SET?

Related Commands HEADer, \*LRN?, VERBose

#### **Examples**

SET? returns a long response, part of which could be as follows: :SET :ACQUIRE:STOPAFTER RUNSTOP;STATE 1;MODE SAMPLE;NUMENV INFINITE;NUMAVG 16;SAMPLINGMODE RT;:HEADER 1;:LOCK NONE;:LANGUAGE ENGLISH;:VERBOSE 1;:ALIAS:STATE 0;: DISPLAY:COLOR:PALETTE NORMAL;:DISPLAY:STYLE:DOTSONLY 0;:DISPLAY:PERSISTENCE 0.0000;CLOCK 1;GRATICULE FULL; INTERSITY: WAVEFORM 30; GRATICULE 75; BACKLIGHT HIGH;:HARDCOPY:INKSAVER OFF;LAYOUT LANDSCAPE;PREVIEW 0; :SAVE:IMAGE:FILEFORMAT BMP;:SAVE:WAVEFORM:FILEFORMAT INTERNAL;:SAVE:ASSIGN:TYPE SETUP;:TRIGGER:A:MODE AUTO; TYPE EDGE; LEVEL 20.0000E-3; LEVEL: CH1 20.0000E-3; CH2 0.0000;CH3 0.0000;CH4 0.0000;:TRIGGER:A:UPPERTHRESHOLD:CH1 1.4000; CH2 800.0000E-3; CH3 800.0000E-3; CH4 800.0000E-3;: TRIGGER: A:LOWERTHRESHOLD: CH1 20.0000E-3; CH2 0.0000;CH3 0.0000;CH4 0.0000;:TRIGGER:A:HOLDOFF:TIME 20.0000E-9;:TRIGGER:A:EDGE:SOURCE CH1;COUPLING DC;SLOPE RISE;:TRIGGER:A:LOGIC:CLASS SETHOLD;FUNCTION AND; THRESHOLD: CH1 20.0000E-3; CH2 0.0000; CH3 0.0000; CH4 0.0000; :TRIGGER: A: LOGIC: INPUT: CH1 X;CH2 X;CH3 X;CH4 X;CLOCK:SOURCE NONE;EDGE RISE;:TRIGGER:A:LOGIC:PATTERN:INPUT:CH1 X;CH2 X;CH3 X;CH4 X;:TRIGGER:A :LOGIC:PATTERN:WHEN TRUE; WHEN: LESSLIMIT 4.0000E-9; LIMIT 4.0000E-9; :TRIGGER: A :SETHOLD:CLOCK:SOURCE CH1; EDGE RISE; THRESHOLD 20.0000E-3;:TRIGGER:A:SETHOLD:DATA:SOURCE CH2;

### **SETUP**<x>:DATE? (Query Only)

Returns the date when the oscilloscope setup was saved for the specified channel  $\langle x \rangle$ .

**Group** Save and Recall

**Syntax** SETUP<x>:DATE?

**Examples** SETUP4: DATE? might return SETUP4: DATE: 04–18–06 which is the setup

date for channel 4.

#### SETUP<x>:LABEL

Sets or returns the setup label for the specified channel  $\langle x \rangle$ , where x can be 1 through 10.

**Group** Save and Recall

Syntax SETUP<x>:LABEL <Qstring>

**Arguments** <Qstring> is an alphanumeric string of characters, enclosed in quotes, that

defines the label text for SETUP<x>. The length of the string is limited to 30

characters.

**Examples** SETUP:LABEL? might return SETUP1:LABEL: TEST 2 which is the label setup

for channel 1.

# SETUP<x>:TIME? (Query Only)

Returns the time when the oscilloscope setup was saved for the specified channel  $\langle x \rangle$ .

**Group** Save and Recall

Syntax SETUP<x>:TIME?

**Examples** 

SETUP2:TIME? might return "SETUP2:TIME: 15:24:07 which is the setup time for channel 2.

\*SRE

The \*SRE (Service Request Enable) command sets or returns the bits in the Service Request Enable Register. For information, refer to Registers.

**Group** Status and Error

Syntax \*SRE <NR1> \*SRE?

Related Commands \*CLS, DESE, \*ESE, \*ESR?, EVENT?, EVMsg?, FACtory, \*STB?

**Arguments** <NR1> is a value in the range from 0 through 255. The binary bits of the SRER

are set according to this value. Using an out-of-range value causes an execution error. The power-on default for SRER is 0 if \*PSC is 1. If \*PSC is 0, the SRER maintains the previous power cycle value through the current power cycle.

**Examples** \*SRE 48 sets the bits in the SRER to binary 00110000.

\*SRE? might return 32, showing that the bits in the SRER have the binary value

of 00100000.

\*STB? (Query Only)

\*STB? (Read Status Byte) returns the contents of the Status Byte Register (SBR) using the Master Summary Status (MSS) bit. For information, refer to Registers.

**Group** Status and Error

Syntax \*STB?

Related Commands \*CLS, DESE, \*ESE, \*ESR?, EVENT?, EVMsg?, FACtory, \*SRE

Returns <NR1>

#### **Examples**

\*STB? might return 96, showing that the SBR contains the binary value 01100000.

#### **TEKSecure (No Query Form)**

This command initializes both waveform and setup memories, overwriting any previously stored data. These are the WFMInpre?, WFMOutpre?, and DATa command values after the TEKSecure operation.

```
:WFMOUTPRE:BYT_NR 1 :WFMOUTPRE:BIT_NR 8 :WFMOUTPRE:ENCDG
BIN :WFMOUTPRE:BN_FMT RI :WFMOUTPRE:BYT_OR MSB
:WFMOUTPRE:WFID "Ch1, DC coupling, 100.0mV/div,
4.000us/div, 10000 points, Sample mode": WFMOUTPRE:NR_PT
10000 :WFMOUTPRE:PT_FMT Y :WFMOUTPRE:XUNIT "s"
:WFMOUTPRE:XINCR 4.0000E-9 :WFMOUTPRE:XZERO -20.0000E-6
:WFMOUTPRE:PT_OFF 0 :WFMOUTPRE:YUNIT "V" :WFMOUTPRE:YMULT
4.0000E-3 :WFMOUTPRE:YOFF 0.0000 :WFMOUTPRE:YZERO 0.0000
:WFMINPRE:BYT_NR 1 :WFMINPRE:BIT_NR 8 :WFMINPRE:ENCDG
BIN :WFMINPRE:BN_FMT RI :WFMINPRE:BYT_OR MSB
:WFMINPRE:NR_PT 10000 :WFMINPRE:PT_FMT Y :WFMINPRE:XUNIT
"s" :WFMINPRE:XINCR 4.0000E-9 :WFMINPRE:XZERO 0.0000
:WFMINPRE:PT OFF 0 :WFMINPRE:YUNIT "V" :WFMINPRE:YMULT
4.0000E-3 :WFMINPRE:YOFF 0.0000 :WFMINPRE:YZERO 0.0000
DATA: DESTINATION REF1 DATA: ENCDG RIBINARY DATA: SOURCE CH1
DATA:START 1 DATA:STOP 10000 DATA:WIDTH 1
```

**NOTE.** The TEKSecure command can take up to five minutes to complete. The oscilloscope is inoperable during this period.

#### **Group** Miscellaneous

#### **Syntax** TEKSecure

#### **Examples**

TEKSECURE initializes both waveform and setup memories.

This is a program example of how to generate an SRQ when TEKSECURE completes:

```
# Bit 0 of the DESE (Device Event Status Enable Register)
# enables OPC to be reported to the SESR (Standard Event
# Status Register)
DESE 255
# Bit 0 of the ESER (Event Status Enable Register)
# enables OPC to be summarized in the ESB (Event Status # Bit) of the SBR (Status Byte Register)
*ESE 255
```

```
# Bit 5 of the SRE (Service Request Enable Register)
enables
# the generation of SRQ when the ESB bit of the SBR
becomes # TRUE
*SRE 32
TEKSECURE;*OPC
```

When the TEKSECURE operation has completed, the OPC bit of the SESR will be TRUE and SRQ will have been generated.

#### TIME

Sets or returns the time that the oscilloscope displays.

**Group** Miscellaneous

Syntax TIME <QString>

TIME?

Related Commands DATE

**Arguments** <QString> is a time in the form "hh:mm:ss" where hh refers to a two-digit hour

number, mm refers to a two-digit minute number from 00 to 59, and ss refers to a

two-digit second number from 00 to 59.

**Examples** TIME "14:00:00" sets the time to exactly 2:00 p.m.

TIME? might return: TIME "14:05:17" indicating the current time is set to 2:05

p.m. and 17 seconds.

#### **TOTaluptime?** (Query Only)

This command returns the total number of hours that the oscilloscope has been powered on since the nonvolatile memory was last programmed (usually since the initial manufacturing process).

**Group** Miscellaneous

Syntax TOTaluptime?

### \*TRG (No Query Form)

Performs a group execute trigger on commands defined by \*DDT.

**Group** Miscellaneous

Syntax \*TRG

Related Commands \*DDT

**Examples** \*TRG immediately executes all commands that have been defined by \*DDT.

### **TRIGger (No Query Form)**

Forces a trigger event to occur.

**Group** Trigger

Syntax TRIGger FORCe

TRIGger?

**Arguments** FORCe creates a trigger event. If TRIGger:STATE is set to READy, the acquisition

will complete. Otherwise, this command will be ignored.

**Examples** TRIGGER FORCE forces a trigger event to occur.

## TRIGger:A

Sets the A trigger level automatically to 50% of the range of the minimum and maximum values of the trigger input signal. The query returns current A trigger parameters. The trigger level is the voltage threshold through which the trigger source signal must pass to generate a trigger event. This command works for the following cases: Edge Trigger (when source is Not Line), Logic Trigger (when Clock Source is not Off or Logic Pattern is Don't Care), and Pulse Width Trigger.

**Group** Trigger

**Syntax** TRIGger: A SETLevel

TRIGger:A?

**Related Commands** TRIGger:A:EDGE?, TRIGger:A:LOGIc?, TRIGger:A:PULse?

**Arguments** SETLevel sets the A trigger level to 50% of the range of the minimum and

maximum values of the trigger input signal.

**Examples** TRIGGER: A SETLEVEL sets the A trigger level to 50% of the range of the

minimum and maximum values of the trigger input signal.

TRIGGER: A? might return a long response with A trigger parameters, some of which could be as follows: :TRIGGER: A:MODE AUTO; TYPE

EDGE; LEVEL 20.0000E-3; LEVEL: CH1 20.0000E-3; CH2 0.0000; CH3 0.0000; CH4 0.0000; :TRIGGER: A: UPPERTHRESHOLD: CH1

1.4000; CH2 800.0000E-3; CH3 8 00.0000E-3; CH4

800.0000E-3;:TRIGGER:A:LOWERTHRESHOLD:CH1 20.0000E-3;CH2

0.0000;CH3 0.0000;CH4 0.0000;:TRIGGER:A:HOLDOFF:TIME

20.0000E-9;:TRIGGER:A:EDGE:SOURCE CH1;COUPLING

DC;SLOPE RISE;:TRIGGER:A:LOGIC:CLASS SETHOLD;FUNCTION

AND; THRESHOLD: CH1 20.0000E-3; CH2 0.0000; CH3

0.0000;CH4 0.0000;:TRIGGER:A:LOGIC:INPUT:CH1

X;CH2 X;CH3 X;CH4 X;CLOCK:SOURCE NONE;EDGE

RISE;:TRIGGER:A:LOGIC:PATTERN:INPUT:CH1 X; CH2

X;CH3 X;CH4 X;:TRIGGER:A:LOGIC:PATTERN:WHEN

TRUE; WHEN: LESSLIMIT 4.0000E-9; MO RELIMIT

4.0000E-9;:TRIGGER:A:SETHOLD:CLOCK:SOURCE CH1;EDGE

RISE; THRESHOLD 20.000 0E-3; :TRIGGER: A: SETHOLD: DATA: SOURCE

CH2; THRESHOLD 0.0000; :TRIGGER: A: SETHOLD: HOLD TIME

4.0000E-9;SETTIME 4.0000E-9;:TRIGGER:A:PULSE:CLASS

TRANSITION;:TRIGGER:A:PULSEWIDTH:SOURCE

CH1; POLARITY POSITIVE; WHEN LESSTHAN; WIDTH

4.0000E-9;:TRIGGER:A:RUNT:SOURCE CH1;POLARITY POSITIVE;WHEN

OCCURS; WIDTH 4.0000E-9; :TRIGGER: A: TRANSITION: SOURCE

CH1; POLARITY POSITIVE; WHEN SLOWER; DELTATIME

4.0000E-9;:TRIGGER:A:VIDEO :POLARITY POSITIVE;SOURCE

CH1; STANDARD NTSC; SYNC ALLLINES; HOLDOFF: FIELD 0.0000;:

TRIGGER: A: VIDEO: CUSTOM: FORMAT PROGRESSIVE; SCAN

RATE15K;:TRIGGER:A:VIDEO:LINE 1;H DTV:FORMAT

HD1080I60;:TRIGGER:A:BUS:SOURCE B1;B1:I2C:CONDITION

START; DATA: VALUE "XXXXXXXXX"; SIZE 1; START 0.0000; DIRECTION

NOCARE;:TRIGGER:A:BUS:B1:I2C:ADDRESS:MODE

ADDR7; TYPE USER; VALUE

"XXXXXXX";:TRIGGER:A:BUS:B1:SPI:CONDITION MOSI;DATA:OUT:VALUE "XXXXXXXX";:TRIGGER:A:BUS:B1:SPI:DATA:IN:VALUE

"XXXXXXXX";:TRIGGER:A:BUS: B1:SPI:DATA:SIZE 1;START 0.0000;:

#### TRIGger:A:BUS

Sets or returns the trigger type: I2C, CAN, SPI, RS-232, or Parallel. There are up to four serial buses, B1–B4, depending on your instrument model. Each can be independently set to one of the serial trigger types. The serial parameters related to the trigger are broken into two sections: Trigger:A:SERIAL xxx, consisting of parameters the user will change frequently, and BUS:B1:xxx, consisting of parameters the user will specify once (bus definition).

**Conditions** Requires a DPO4AUTO, DPO4EMBD, or DPO4COMP application module.

**Group** Trigger

Syntax TRIGger:A:BUS {I2C|SPI|CAN|RS232|PARallel}

TRIGger:A:BUS?

**Arguments** I2C specifies the Inter-IC bus.

SPI specifies the Serial Peripheral Interface bus.

CAN specifies the Controller Area Network bus.

PARallel specifies the Parallel bus.

**NOTE.** Parallel bus commands work with MSO4000 Series oscilloscopes only.

### TRIGger:A:BUS:B<x>:AUDio:CONDition

Sets or returns the trigger condition for the AUDIO bus: Start of Frame or Data.

**Conditions** This command requires DPO4AUDIO application module.

**Group** Trigger

Syntax TRIGger:A:BUS:B<x>:AUDio:CONDition {SOF|DATA}

TRIGger:A:BUS:B<x>:AUDio:CONDition?

**Arguments** SOF enables triggering on the start of frame.

DATA enables triggering on matching data.

# TRIGger:A:BUS:B<x>:AUDio:DATa:HIVALue

Sets or returns the trigger data upper word for the AUDIO bus.

**Conditions** This command requires DPO4AUDIO application module.

**Group** Trigger

Syntax TRIGger:A:BUS:B<x>:AUDio:DATa:HIVALue <String>

TRIGger:A:BUS:B<x>:AUDio:DATa:HIVALue?

#### TRIGger:A:BUS:B<x>:AUDio:DATa:OFFSet

Sets or returns the trigger data offset for the AUDIO bus.

**Conditions** This command requires DPO4AUDIO application module.

**Group** Trigger

Syntax TRIGger:A:BUS:B<x>:AUDio:DATa:OFFSet <NR1>

TRIGger:A:BUS:B<x>:AUDio:DATa:OFFSet?

**Arguments** <NR1> is the trigger data offset value.

#### TRIGger:A:BUS:B<x>:AUDio:DATa:QUALifier

Sets or returns the trigger data qualifier for the AUDIO bus.

**Conditions** This command requires DPO4AUDIO application module.

**Group** Trigger

Syntax TRIGger:A:BUS:B<x>:AUDio:DATa:QUALifier

{LESSThan|MOREThan|EQUal|UNEQual|LESSEQual|MOREEQual|INrange|OUTrang

TRIGger:A:BUS:B<x>:AUDio:DATa:QUALifier?

**Arguments** LESSThan sets the Audio data qualifier to less than.

MOREThan sets the Audio data qualifier to greater than.

EQUal sets the Audio data qualifier to equal.

UNEQual sets the Audio data qualifier to not equal.

LESSEQual sets the Audio data qualifier to less than or equal.

MOREEQual sets the Audio data qualifier to greater than or equal.

INrange sets the Audio data qualifier to in range.

OUTrange sets the Audio data qualifier to out of range.

### TRIGger:A:BUS:B<x>:AUDio:DATa:VALue

Sets or returns the trigger data lower word for the AUDIO bus.

**Conditions** This command requires DPO4AUDIO application module.

**Group** Trigger

Syntax TRIGger:A:BUS:B<x>:AUDio:DATa:VALue <String>

TRIGger:A:BUS:B<x>:AUDio:DATa:VALue?

**Arguments** <String> specifies the trigger data lower word.

### TRIGger:A:BUS:B<x>:AUDio:DATa:WORD

Sets or returns the trigger data alignment for the AUDIO bus.

**Conditions** This command requires DPO4AUDIO application module.

**Group** Trigger

Syntax TRIGger:A:BUS:B<x>:AUDio:DATa:WORD {EITher|LEft|RIGht}

TRIGger:A:BUS:B<x>:AUDio:DATa:WORD?

**Arguments** EITher aligns the trigger data to either left or right.

LEFt aligns the trigger data to the left.

RIGht aligns the trigger data to the right.

# TRIGger:A:BUS:B<x>:CAN:CONDition

Sets or returns the CAN trigger condition for bus <x>, where x is the bus number.

**Conditions** Requires a DPO4AUTO application module.

**Group** Trigger

**Syntax** TRIGger:A:BUS:B<x>:CAN:CONDition

{SOF|FRAMEtype|IDentifier|DATA|IDANDDATA|EOF|ACKMISS}

TRIGger:A:BUS:B<x>:CAN:CONDition?

**Arguments** SOF enables triggering on the start of frame.

FRAMEtype enables triggering on the type of frame.

IDentifier enables triggering on a matching identifier.

DATA enables triggering on matching data.

IDANDDATA enables triggering on a matching identifier and matching data.

EOF enables triggering on the end of frame.

ACKMISS enables triggering on a missing acknowledge.

**Examples** TRIGGER:A:BUS:B1:CAN:CONDITION? might return:TRIGGER:A:BUS:B1:

CAN: CONDITION EOF indicating an end of file condition.

TRIGGER: A: BUS: B1: CAN: CONDITION DATA enables triggering on matching

CAN data.

# TRIGger:A:BUS:B<x>:CAN:DATa:DIRection

Sets or returns the CAN trigger data direction to be valid on a Read, Write, or Either condition for bus  $\langle x \rangle$ , where x is the bus number. This applies only, if the trigger condition is ID.

**Conditions** Requires a DPO4AUTO application module.

**Group** Trigger

Syntax TRIGger:A:BUS:B<x>:CAN:DATa:DIRection {READ|WRITE|NOCARE}

TRIGger:A:BUS:B<x>:CAN:DATa:DIRection?

**Arguments** READ sets the CAN data direction to READ.

WRITE sets the CAN data direction to WRITE.

NOCARE sets the CAN data direction to either.

**Examples** TRIGGER:A:BUS:B1:CAN:DATA:DIRECTION WRITE sets the CAN data

direction to Write.

# TRIGger:A:BUS:B<x>:CAN:DATa:QUALifier

Sets or returns the CAN data qualifier for bus <x>, where x is the bus number. This applies only, if the trigger condition is IDANDDATA or DATA.

**Conditions** Requires a DPO4AUTO application module.

**Group** Trigger

Syntax TRIGger:A:BUS:B<x>:CAN:DATa:QUALifier

{LESSThan|Than|EQUal|UNEQual|LESSEQual|EQual}

TRIGger:A:BUS:B<x>:CAN:DATa:QUALifier?

**Arguments** LESSThan sets the oscilloscope to trigger when the data is less than the qualifier

value.

Than sets the oscilloscope to trigger when the data is than the qualifier value.

EQUal sets the oscilloscope to trigger when the data is equal to the qualifier value.

UNEQual sets the oscilloscope to trigger when the data is not equal to the qualifier

value.

LESSEQual sets the oscilloscope to trigger when the data is less than or equal

to the qualifier value.

EQual sets the oscilloscope to trigger when the data is than or equal to the

qualifier value.

**Examples** TRIGGER:A:BUS:B1:CAN:DATA:QUALIFIER LESSTHAN sets the oscilloscope

to trigger when the data is less than the qualifier value.

TRIGGER:A:BUS:B1:CAN:DATA:QUALIFIER? might return :TRIGGER:A:BUS:B1:CAN:DATA:QUALIFIER THAN, indicating that the oscilloscope is set to trigger when the data is than the qualifier value.

### TRIGger:A:BUS:B<x>:CAN:DATa:SIZe

Sets or returns the length of the data string in bytes for a CAN trigger if the condition is DATA or IDANDDATA. Applies to bus <x>, where x is the bus number

**Conditions** This command requires a DPO4AUTO application module.

**Group** Trigger

Syntax TRIGger:A:BUS:B<x>:CAN:DATa:SIZe <NR1>

TRIGger:A:BUS:B<x>:CAN:DATa:SIZe?

**Arguments** <NR1> is the length of the data string in bytes.

# TRIGger:A:BUS:B<x>:CAN:DATa:VALue

Sets or returns the binary data string to be used for a CAN trigger if the trigger condition is ID or IDANDDATA. Applies to bus <x>, where x is the bus number.

**Conditions** This command requires a DPO4AUTO application module.

**Group** Trigger

Syntax TRIGger:A:BUS:B<x>:CAN:DATa:VALue <QString>

TRIGger:A:BUS:B<x>:CAN:DATa:VALue?

**Arguments** <QString> is the CAN data value in binary format. The only allowed characters

in the QString are 0, 1, and X.

**Examples** TRIGGER: A:BUS: B1: CAN: DATA: VALUE 1011 sets the CAN data value to 1011.

# TRIGger:A:BUS:B<x>:CAN:FRAMEtype

Sets or returns the frame type for a CAN FRAMEType trigger. Applies to bus  $\langle x \rangle$ , where x is the bus number.

**Conditions** This command requires a DPO4AUTO application module. This command is

only valid when the TRIGger: A:BUS:B<x>:CAN:CONDition is FRAMETYPE.

**Group** Trigger

**Syntax** TRIGger:A:BUS:B<x>:CAN:FRAMEtype

{DATA|REMote|ERROr|OVERLoad}
TRIGger:A:BUS:B<x>:CAN:FRAMEtype?

**Arguments** DATA specifies a data frame type.

REMote specifies a remote frame type.

ERRor specifies an error frame type.

OVERLold specifies an overload frame type.

**Examples** TRIGGER:A:BUS:B1:CAN:FRAMETYPE DATA sets the CAN trigger frame type

to DATA.

# TRIGger:A:BUS:B<x>:CAN{:IDentifier|:ADDRess}:MODe

Sets or returns the CAN addressing mode for bus  $\langle x \rangle$ , where x is the bus number. Use this command to do the following:

Trigger on ID

Trigger in IDANDDATA

**Conditions** This command requires a DPO4AUTO application module.

**Group** Trigger

Syntax TRIGger:A:BUS:B<x>:CAN{:IDentifier|:ADDRess}:MODe

{STandard|EXTended}

TRIGger:A:BUS:B<x>:CAN{:IDentifier|:ADDRess}:MODe?

**Arguments** STandard specifies the standard addressing mode.

EXTended specifies the extended addressing mode.

### TRIGger:A:BUS:B<x>:CAN{:IDentifier|:ADDRess}:VALue

Sets or returns the binary address string used for a CAN trigger if the trigger condition is ID or IDANDDATA. Applies to bus <x>, where x is the bus number.

**Conditions** This command requires a DPO4AUTO application module.

**Group** Trigger

Syntax TRIGger:A:BUS:B<x>:CAN{:IDentifier|:ADDRess}:VALue <QString>

TRIGger:A:BUS:B<x>:CAN{:IDentifier|:ADDRess}:VALue?

**Arguments** <QString> is up to 29 bits specifying the binary CAN identifier value. The only

allowed characters in the QString are 0, 1, and X.

**Examples** TRIGGER:A:BUS:B1:CAN:IDENTIFIER:VALUE 1011 sets the CAN trigger

identifier value to 1011.

# TRIGger:A:BUS:B<x>:FLEXray:CONDition

Sets or returns the trigger condition for FLEXRAY.

**Group** Trigger

**Syntax** TRIGger:A:BUS:B<x>:FLEXray:CONDition

{SOF|FRAMEType|IDentifier|CYCLEcount|HEADer|DATA|IDANDDATA|EOF|ERROR

TRIGger: A: BUS: B < x > : FLEX ray: CONDition?

**Arguments** SOF sets the FLEXRAY trigger condition to start of frame.

FRAMEType sets the FLEXRAY trigger condition to frame type.

IDentifier sets the FLEXRAY trigger condition to identifier.

CYCLEcount sets the FLEXRAY trigger condition to cycle count.

HEADer sets the FLEXRAY trigger condition to header.

DATA sets the FLEXRAY trigger condition to data.

IDANDDATA sets the FLEXRAY trigger condition to id and data.

**EOF** sets the FLEXRAY trigger condition to end of frame.

ERROR sets the FLEXRAY trigger condition to error.

#### **Examples**

TRIGGER:A:BUS:B1:FLEXRAY:CONDITION? might return TRIGGER:A:BUS:B1:FLEXRAY:CONDITION SOF indicating the

GLEXRAY condition is start of frame.

TRIGGER:A:BUS:B1:FLEXRAY:CONDITION? might return
TRIGGER:A:BUS:B1:FLEXRAY:CONDITION SOF indicating the

GLEXRAY condition is start of frame.

# TRIGger:A:BUS:B<x>:FLEXray:CYCLEcount:HIVALue

Sets or returns the binary data string to be used for FLEXRAY cycle count high value.

**Group** Trigger

Syntax TRIGger:A:BUS:B<x>:FLEXray:CYCLEcount:HIVALue <QString>

TRIGger:A:BUS:B<x>:FLEXray:CYCLEcount:HIVALue?

**Arguments** <QString> is a quoted string that is the cycle count high value.

**Examples** TRIGGER:A:BUS:B1:FLEXRAY:CYCLECOUNT:HIVALUE "110010" sets the

cycle count high value to 110010.

TRIGGER: A: BUS: B1: FLEXRAY: CYCLECOUNT: HIVALUE? might return

TRIGGER: A:BUS: B1: FLEXRAY: CYCLECOUNT: HIVALUE "XXXXXX" indicating

the cycle count high value is don't care.

### TRIGger:A:BUS:B<x>:FLEXray:CYCLEcount:QUALifier

Sets or returns the FLEXRAY cycle count qualifier.

**Group** Trigger

**Syntax** TRIGger:A:BUS:B<x>:FLEXray:CYCLEcount:QUALifier

{LESSThan|MOREThan|EQUal|UNEQual|LESSEQual|MOREEQual|

INrange|OUTrange}

TRIGger:A:BUS:B<x>:FLEXray:CYCLEcount:QUALifier?

**Arguments** LESSThan sets the FLEXRAY cycle count qualifier to less than.

MOREThan sets the FLEXRAY cycle count qualifier to more than.

EQUal sets the FLEXRAY cycle count qualifier to equal.

UNEQual sets the FLEXRAY cycle count qualifier to not equal.

LESSEQual sets the FLEXRAY cycle count qualifier to less than or equal.

MOREEQual sets the FLEXRAY cycle count qualifier to greater than or equal.

INrange sets the FLEXRAY cycle count qualifier to in range.

OUTrange sets the FLEXRAY cycle count qualifier to out of range.

**Examples** TRIGGER:A:BUS:B1:FLEXRAY:CYCLECOUNT:QUALIFIER LESSTHAN sets the

cycle count qualifier to LESSTHAN.

TRIGGER:A:BUS:B1:FLEXRAY:CYCLECOUNT:QUALIFIER? might return
TRIGGER:A:BUS:B1:FLEXRAY:CYCLECOUNT:QUALIFIER EQUAL indicating

that the cycle count qualifier is set to EQUAL.

# TRIGger:A:BUS:B<x>:FLEXray:CYCLEcount:VALue

Sets or returns the binary data string to be used for FLEXRAY cycle count low value

**Group** Trigger

Syntax TRIGger:A:BUS:B<x>:FLEXray:CYCLEcount:VALue <QString>

TRIGger:A:BUS:B<x>:FLEXray:CYCLEcount:VALue?

**Arguments** <QString> is a quoted string that is the FLEXRAY binary data string that is the

cycle count low value.

**Examples** TRIGGER:A:BUS:B1:FLEXRAY:CYCLECOUNT:VALUE "11001101" sets the

cycle count value to 11001101.

TRIGGER:A:BUS:B1:FLEXRAY:CYCLECOUNT:VALUE? might return
TRIGGER:A:BUS:B1:FLEXRAY:CYCLECOUNT:VALUE "XXXXXX" indicating the
cycle count value is don't care.

### TRIGger:A:BUS:B<x>:FLEXray:DATa:HIVALue

Sets or returns the high binary data string to be used for FLEXRAY trigger if trigger condition is ID or IDANDDATA.

**Group** Trigger

Syntax TRIGger:A:BUS:B<x>:FLEXray:DATa:HIVALue <QString>

TRIGger:A:BUS:B<x>:FLEXray:DATa:HIVALue?

**Arguments** <QString> is a quoted string that is the FLEXRAY binary data high value.

Examples TRIGGER:A:BUS:B1:FLEXRAY:DATA:HIVALUE

XXXXXXX1" sets the binary data string high value to

XXXXXXX1".

TRIGGER:A:BUS:B1:FLEXRAY:DATA:HIVALUE? might return TRIGGER:A:BUS:B1:FLEXRAY:DATA:HIVALUE

XXXXXXXX" indicating the binary data string high value is don't care.

# TRIGger:A:BUS:B<x>:FLEXray:DATa:OFFSet

Sets or returns the offset of the data string in bytes to be used for FLEXRAY trigger.

**Group** Trigger

Syntax TRIGger:A:BUS:B<x>:FLEXray:DATa:OFFSet <NR1>

TRIGger:A:BUS:B<x>:FLEXray:DATa:OFFSet?

**Arguments** <NR1> is the offset of the data string in bytes. A byte offset of -1 signifies don't

care, and no byte offset is used. The instrument will trigger or match any byte

value that fits.

**Examples** TRIGGER:A:BUS:B1:FLEXRAY:DATA:OFFSET? might return

TRIGGER: A: BUS: B1: FLEXRAY: DATA: OFFSET 0 indicating that a data offset

of 0.

TRIGGER: A: BUS: B1: FLEXRAY: DATA: OFFSET? might return

TRIGGER: A: BUS: B1: FLEXRAY: DATA: OFFSET 0 indicating that a data offset

of 0.

### TRIGger:A:BUS:B<x>:FLEXray:DATa:QUALifier

Sets or returns the FLEXRAY data qualifier.

**Group** Trigger

**Syntax** TRIGger:A:BUS:B<x>:FLEXray:DATa:QUALifier

{LESSThan|MOREThan|EQUal|UNEQual|LESSEQual|MOREEQual|

INrange|OUTrange}

TRIGger:A:BUS:B<x>:FLEXray:DATa:QUALifier?

**Arguments** LESSThan sets the FLEXRAY data qualifier to less than.

MOREThan sets the FLEXRAY data qualifier to greater than.

**EQUal** sets the FLEXRAY data qualifier to equal.

UNEQual sets the FLEXRAY data qualifier to not equal.

LESSEQual sets the FLEXRAY data qualifier to less than or equal.

MOREEQual sets the FLEXRAY data qualifier to greater than or equal.

INrange sets the FLEXRAY data qualifier to in range.

OUTrange sets the FLEXRAY data qualifier to out of range.

**Examples** TRIGGER:A:BUS:B1:FLEXRAY:DATA:QUALIFIER LESSTHAN sets the data

qualifier to LESSTHAN.

TRIGGER: A: BUS: B1: FLEXRAY: DATA: QUALIFIER? might return

TRIGGER: A: BUS: B1: FLEXRAY: DATA: QUALIFIER EQUAL indicating the data

qualifier is EQUAL.

# TRIGger:A:BUS:B<x>:FLEXray:DATa:SIZe

Sets or returns the length of the data string in bytes to be used for FLEXRAY trigger.

**Group** Trigger

Syntax TRIGger:A:BUS:B<x>:FLEXray:DATa:SIZe <NR1>

TRIGger:A:BUS:B<x>:FLEXray:DATa:SIZe?

**Arguments** <NR1> is the FLEXRAY data string length in bytes.

**Examples** TRIGGER:A:BUS:B1:FLEXRAY:DATA:SIZE 8 sets the data string size to 8

bytes.

TRIGGER: A: BUS: B1: FLEXRAY: DATA: SIZE? might return

TRIGGER:A:BUS:B1:FLEXRAY:DATA:SIZE 1 indicating the data

size is 1 byte.

## TRIGger:A:BUS:B<x>:FLEXray:DATa:VALue

Sets or returns the low binary data string to be used for FLEXRAY trigger condition if trigger condition is ID or IDANDDATA.

**Group** Trigger

Syntax TRIGger:A:BUS:B<x>:FLEXray:DATa:VALue <QString>

TRIGger:A:BUS:B<x>:FLEXray:DATa:VALue?

**Arguments** <QString> is a quoted string that is the binary data string for a FLEXRAY

trigger if the trigger condition is ID or IDANDDATA.

**Examples** TRIGGER:A:BUS:B1:FLEXRAY:DATA:VALUE "11001101" sets the FLEXRAY

data value for triggering to 11001101.

TRIGGER:A:BUS:B1:FLEXRAY:DATA:VALUE? might return

TRIGGER: A: BUS: B1: FLEXRAY: DATA: VALUE "XXXXXXXX" indicating the

FLEXRAY data value is don't care.

# TRIGger:A:BUS:B<x>:FLEXray:EOFTYPE

Sets or returns the end of file type used for FLEXRAY trigger.

**Group** Trigger

Syntax TRIGger:A:BUS:B<x>:FLEXray:EOFTYPE {STATic|DYNAMic|ANY}

TRIGger:A:BUS:B<x>:FLEXray:EOFTYPE?

**Arguments** STATic specifies triggering on the STATIC end of file type.

DYNAMic specifies triggering on the DYNAMIC end of file type.

ANY specifies triggering on a STATIC or DYNAMIC end of file type.

**Examples** TRIGGER:A:BUS:B1:FLEXRAY:EOFTYPE ANY sets the FLEXRAY end of file

type to ANY.

TRIGGER: A: BUS: B1: FLEXRAY: EOFTYPE? might return

TRIGGER: A: BUS: B1: FLEXRAY: EOFTYPE STATIC indicating the

FLEXRAY end of file type is STATIC

### TRIGger:A:BUS:B<x>:FLEXray:ERRTYPE

Sets or returns the error type be used for FLEXRAY trigger.

**Group** Trigger

**Syntax** TRIGger:A:BUS:B<x>:FLEXray:ERRTYPE

{CRCHeader|CRCTrailer|SYNCFrame|STARTupnosync|NULLFRStatic|

NULLFRDynamic}

TRIGger:A:BUS:B<x>:FLEXray:ERRTYPE?

**Arguments** CRCHeader sets the FLEXRAY error type for a trigger to CRCHeader.

CRCTrailer sets the FLEXRAY error type for a trigger to CRCTrailer.

SYNCFrame sets the FLEXRAY error type for a trigger to SYNCFrame.

STARTupnosync sets the FLEXRAY error type for a trigger to STARTupnosync.

NULLFRStatic sets the FLEXRAY error type for a trigger to NULLFRStatic.

NULLFRDynamic sets the FLEXRAY error type for a trigger to NULLFRDynamic.

**Examples** TRIGGER:A:BUS:B1:FLEXRAY:ERRTYPE SYNCFRAME sets the FLEXRAY

trigger type is SYNCFRAME.

TRIGGER: A: BUS: B1: FLEXRAY: ERRTYPE? might return

TRIGGER: A: BUS: B1: FLEXRAY: ERRTYPE CRCHEADER indicating the

FLEXRAY trigger type is CRCHeader.

## TRIGger:A:BUS:B<x>:FLEXray:FRAMEID:HIVALue

Sets or returns the binary data string to be used for FLEXRAY frame ID high value.

**Group** Trigger

Syntax TRIGger:A:BUS:B<x>:FLEXray:FRAMEID:HIVALue <QString>

TRIGger:A:BUS:B<x>:FLEXray:FRAMEID:HIVALue?

**Arguments** <QString> is a quoted string that is the binary frame id high value.

**Examples** TRIGGER:A:BUS:B1:FLEXRAY:FRAMEID:HIVALUE "11001100101" sets the

frame id high value to 11001100101.

indicating the frame id high value is don't care.

## TRIGger:A:BUS:B<x>:FLEXray:FRAMEID:QUALifier

Sets or returns the FLEXRAY frame ID qualifier.

**Group** Trigger

**Syntax** TRIGger:A:BUS:B<x>:FLEXray:FRAMEID:QUALifier

{LESSThan|MOREThan|EQUal|UNEQual|LESSEQual|MOREEQual|

INrange|OUTrange}

TRIGger:A:BUS:B<x>:FLEXray:FRAMEID:QUALifier?

**Arguments** LESSThan sets the frame id qualifier to less than.

MOREThan sets the frame id qualifier to greater than.

EQUal sets the frame id qualifier to equal.

UNEQual sets the frame id qualifier to not equal.

LESSEQual sets the frame id qualifier to less than or equal.

MOREEQual sets the frame id qualifier to greater than or equal.

INrange sets the frame id qualifier to in range.

OUTrange sets the frame id qualifier to out of range.

**Examples** TRIGGER:A:BUS:B1:FLEXRAY:FRAMEID:QUALIFIER LESSTHAN sets the

frame id qualifier to less than.

TRIGGER: A: BUS: B1: FLEXRAY: FRAMEID: QUALIFIER? might return

TRIGGER: A: BUS: B1: FLEXRAY: FRAMEID: QUALIFIER EQUAL indicating the

frame id qualifier is set to equal.

### TRIGger:A:BUS:B<x>:FLEXray:FRAMEID:VALue

Sets or returns the binary data string to be used for FLEXRAY frame ID low value.

**Group** Trigger

Syntax TRIGger:A:BUS:B<x>:FLEXray:FRAMEID:VALue <QString>

TRIGger:A:BUS:B<x>:FLEXray:FRAMEID:VALue?

**Arguments** <QString> is a quoted string that is the FLEXRAY frame ID low value.

**Examples** TRIGGER: A: BUS: B1: FLEXRAY: FRAMEID: VALUE "11001100101" sets the

frame id value to 11001100101.

TRIGGER: A:BUS: B1: FLEXRAY: FRAMEID: VALUE? might return

TRIGGER: A: BUS: B1: FLEXRAY: FRAMEID: VALUE "XXXXXXXXXXXX" indicating

the frame id value is don't care.

## TRIGger:A:BUS:B<x>:FLEXray:FRAMEType

Sets or returns the frame type for FLEXRAY.

**Group** Trigger

**Syntax** TRIGger:A:BUS:B<x>:FLEXray:FRAMEType

{NORMal|PAYLoad|NULL|SYNC|STARTup}
TRIGger:A:BUS:B<x>:FLEXray:FRAMEType?

**Arguments** NORMal specifies the normal frame type.

PAYLoad specifies the payload frame type.

NULL specifies the null frame type.

SYNC specifies the sync frame type.

STARTup specifies the startup frame type.

**Examples** TRIGGER:A:BUS:B1:FLEXRAY:FRAMETYPE PAYLOAD sets the frame type to

payload.

TRIGGER:A:BUS:B1:FLEXRAY:FRAMETYPE? might return

TRIGGER: A: BUS: B1: FLEXRAY: FRAMETYPE NORMAL indicating the

frame type is set to normal.

## TRIGger:A:BUS:B<x>:FLEXray:HEADER:CRC

Sets or returns the CRC portion of the binary header string to be used for FLEXRAY trigger.

**Group** Trigger

Syntax TRIGger:A:BUS:B<x>:FLEXray:HEADER:CRC <QString>

TRIGger:A:BUS:B<x>:FLEXray:HEADER:CRC?

**Arguments** <QString> is a quoted string that is the CRC portion of the binary header string.

**Examples** TRIGGER:A:BUS:B1:FLEXRAY:HEADER:CRC "11001100101" sets the CRC

portion of the binary header string to 11001100101.

TRIGGER:A:BUS:B1:FLEXRAY:HEADER:CRC? might return

TRIGGER:A:BUS:B1:FLEXRAY:HEADER:CRC "XXXXXXXXXXX" indicating the

CRC portion of the binary header string is don't care.

# TRIGger:A:BUS:B<x>:FLEXray:HEADER:CYCLEcount

Sets or returns the cycle count portion of the binary header string to be used for

FLEXRAY trigger.

**Group** Trigger

Syntax TRIGger:A:BUS:B<x>:FLEXray:HEADER:CYCLEcount <QString>

TRIGger:A:BUS:B<x>:FLEXray:HEADER:CYCLEcount?

**Arguments** <QString> is a quoted string that is the cycle count portion of the binary header

string.

**Examples** TRIGGER:A:BUS:B1:FLEXRAY:HEADER:CYCLECOUNT "110010" sets the

cycle count to 110010.

TRIGGER: A: BUS: B1: FLEXRAY: HEADER: CYCLECOUNT? might return

TRIGGER: A: BUS: B1: FLEXRAY: HEADER: CYCLECOUNT "XXXXXX" indicating

the cycle count is don't care.

# TRIGger:A:BUS:B<x>:FLEXray:HEADER:FRAMEID

Sets or returns the frame id portion of the binary header string to be used for FLEXRAY trigger.

**Group** Trigger

Syntax TRIGger:A:BUS:B<x>:FLEXray:HEADER:FRAMEID <QString>

TRIGger:A:BUS:B<x>:FLEXray:HEADER:FRAMEID?

**Arguments** <QString> is a quoted string that is the frame id portion of the binary header

string.

**Examples** TRIGGER:A:BUS:B1:FLEXRAY:HEADER:FRAMEID "11001100101" sets the

frame id portion of the binary header string to 11001100101.

TRIGGER:A:BUS:B1:FLEXRAY:HEADER:FRAMEID? might return
TRIGGER:A:BUS:B1:FLEXRAY:HEADER:FRAMEID "XXXXXXXXXXXX"
indicating the frame id portion of the binary header string are don't cares.

## TRIGger:A:BUS:B<x>:FLEXray:HEADER:INDBits

Sets or returns the indicator bits portion of the binary header string to be used for FLEXRAY trigger.

**Group** Trigger

Syntax TRIGger:A:BUS:B<x>:FLEXray:HEADER:INDBits <QString>

TRIGger:A:BUS:B<x>:FLEXray:HEADER:INDBits?

**Arguments** <QString> is a quoted string that is the indicator bits portion of the binary

header string.

**Examples** TRIGGER:A:BUS:B1:FLEXRAY:HEADER:INDBITS "11001 sets the indicator

bits portion of the header string to 11001.

TRIGGER: A: BUS: B1: FLEXRAY: HEADER: INDBITS? might return

TRIGGER: A: BUS: B1: FLEXRAY: HEADER: INDBITS "XXXXX" indicating that

the indicator bits portion of the header string are don't cares.

## TRIGger:A:BUS:B<x>:FLEXray:HEADER:PAYLength

Sets or returns the payload length portion of the binary header string to be used for FLEXRAY trigger.

**Group** Trigger

Syntax TRIGger:A:BUS:B<x>:FLEXray:HEADER:PAYLength <QString>

TRIGger:A:BUS:B<x>:FLEXray:HEADER:PAYLength?

**Arguments** <QString> is the length of the payload portion of the Binary header string.

**Examples** TRIGGER:A:BUS:B1:FLEXRAY:HEADER:PAYLENGTH "1100101" sets the

FLEXRAY header paylength to 1100101.

TRIGGER:A:BUS:B1:FLEXRAY:HEADER:PAYLENGTH? might return

TRIGGER: A: BUS: B1: FLEXRAY: HEADER: PAYLENGTH "XXXXXXX" indicating

the FLEXRAY header paylength is don't care.

## TRIGger:A:BUS:B<x>:I2C:ADDRess:MODe

Sets or returns the I<sup>2</sup>C address mode to 7 or 10-bit. Applies to bus  $\langle x \rangle$ , where x is the large number.

is the bus number.

**Conditions** This command requires a DPO4EMBD application module.

**Group** Trigger

Syntax TRIGger:A:BUS:B<x>:I2C:ADDRess:MODe {ADDR7|ADDR10}

TRIGger:A:BUS:B<x>:I2C:ADDRess:MODe?

**Arguments** ADDR7 specifies the 7-bit I<sup>2</sup>C address mode.

ADDR10 specifies the 10-bit I<sup>2</sup>C address mode.

**Examples** TRIGGER:A:BUS:B1:I2C:ADDRESS:MODE ADDR10 sets the I2C address mode

to 10-bit.

### TRIGger:A:BUS:B<x>:I2C:ADDRess:TYPe

Sets or returns the I<sup>2</sup>C address type. The only supported address type is USER.

Applies to bus  $\langle x \rangle$ , where x is the bus number.

**Conditions** This command requires a DPO4EMBD application module.

**Group** Trigger

Syntax TRIGger:A:BUS:B<x>:I2C:ADDRess:TYPe

{GENeralcall|STARtbyte|HSmode|EEPROM|USER}

TRIGger:A:BUS:B<x>:I2C:ADDRess:TYPe?

**Arguments** GENeral call specifies a general call address.

STARtbyte specifies a start byte address.

HSmode specifies a high-speed mode address.

**EEPROM** specifies an EEPROM address.

USER specifies a user address.

### TRIGger:A:BUS:B<x>:I2C:ADDRess:VALue

Sets or returns the binary address string used for the I<sup>2</sup>C trigger if the trigger condition is ADDRESS or ADDRANDDATA. Applies to bus <x>, where x is the

bus number.

**Conditions** This command requires a DPO4EMBD application module.

**Group** Trigger

Syntax TRIGger:A:BUS:B<x>:I2C:ADDRess:VALue <QString>

TRIGger:A:BUS:B<x>:I2C:ADDRess:VALue?

**Arguments** <QString> is up to 7 or 10-bits depending on the address mode that specifies the

address. The only allowed characters in the QString are 0, 1, and X.

**Examples** TRIGGER: A:BUS: B1:I2C: ADDRESS: VALUE 1011 sets the I<sup>2</sup>C address value

to XXX1011.

# TRIGger:A:BUS:B<x>:I2C:CONDition

Sets or returns the trigger condition for an I<sup>2</sup>C trigger. Applies to bus <x>, where

x is the bus number.

**Conditions** This command requires a DPO4EMBD application module.

**Group** Trigger

**Syntax** TRIGger:A:BUS:B<x>:I2C:CONDition

{START|STOP|REPEATSTART|ACKMISS|ADDRess|DATA|ADDRANDDATA}

TRIGger:A:BUS:B<x>:I2C:CONDition?

**Arguments** STARt specifies a search based on start condition.

STOP specifies a search based on stop condition.

REPEATstart specifies a search based on repeat of start condition.

ACKMISS specifies a search based on missing acknowledgement condition.

ADDRess specifies a search based on address.

DATA specifies a search based on data.

ADDRANDDATA specifies a search based on address and data.

**Examples** TRIGGER: A:BUS: B1:I2C: CONDITION START specifies start as the I<sup>2</sup>C trigger

condition.

### TRIGger:A:BUS:B<x>:I2C:DATa:DIRection

Sets or returns the I<sup>2</sup>C trigger type to be valid on a Read, Write, or Either condition. Read or write is indicated by the R/W bit in the I<sup>2</sup>C protocol. Applies

to bus  $\langle x \rangle$ , where x is the bus number.

**Conditions** This command requires a DPO4EMBD application module.

**Group** Trigger

Syntax TRIGger:A:BUS:B<x>:I2C:DATa:DIRection {READ|WRITE|NOCARE}

TRIGger:A:BUS:B<x>:I2C:DATa:DIRection?

**Arguments** READ specifies read as the data direction.

WRITE specifies write as the data direction.

NOCARE specifies either as the data direction.

**Examples** TRIGGER: A: BUS: B1: I2C: DATA: DIRECTION WRITE specifies write as the

I<sup>2</sup>C data direction.

### TRIGger:A:BUS:B<x>:I2C:DATa:SIZe

Sets or returns the length of the data string in bytes to be used for an I2C trigger if the trigger condition is DATA or ADDRANDDATA. Applies to bus <x>, where x is the bus number.

**Conditions** This command requires a DPO4EMBD application module.

**Group** Trigger

Syntax TRIGger:A:BUS:B<x>:I2C:DATa:SIZe <NR1>

TRIGger:A:BUS:B<x>:I2C:DATa:SIZe?

**Arguments** <NR1> is the length of the data string in bytes.

# TRIGger:A:BUS:B<x>:I2C:DATa:VALue

Sets or returns the binary data string used for I2C triggering if the trigger condition is DATA or ADDRANDDATA. Applies to bus <x>, where x is the bus number.

**Conditions** This command requires a DPO4EMBD application module.

**Group** Trigger

Syntax TRIGger:A:BUS:B<x>:I2C:DATa:VALue <QString>

TRIGger:A:BUS:B<x>:I2C:DATa:VALue?

#### **Arguments**

<QString> is the binary data string, where the number of bits is 8 times the number of bytes specified. The only allowed characters in the string are 0, 1, and X.

## TRIGger:A:BUS:B<x>:LIN:CONDition

Sets or returns the trigger condition for LIN.

**Group** Trigger

**Syntax** TRIGger:A:BUS:B<x>:LIN:CONDition

{SYNCField|IDentifier|DATA|IDANDDATA|WAKEup|SLEEP|ERROR}

TRIGger:A:BUS:B<x>:LIN:CONDition?

**Arguments** SYNCField sets the LIN trigger condition to sync field.

IDentifier sets the LIN trigger condition to identifier.

DATA sets the LIN trigger condition to data.

IDANDDATA sets the LIN trigger condition to id and data.

WAKEup sets the LIN trigger condition to wake up.

SLEEP sets the LIN trigger condition to sleep.

ERROR sets the LIN trigger condition to error.

**Examples** TRIGGER:A:BUS:B1:LIN:CONDITION ERROR sets the LIN trigger condition

to error.

TRIGGER: A: BUS: B1: LIN: CONDITION? might return

TRIGGER: A: BUS: B1: LIN: CONDITION SYNCFIELD indicating the LIN trigger

condition is sync field.

### TRIGger:A:BUS:B<x>:LIN:DATa:HIVALue

Sets or returns the binary data string to be used for LIN trigger if trigger condition

is ID or IDANDDATA.

**Group** Trigger

Syntax TRIGger:A:BUS:B<x>:LIN:DATa:HIVALue <QString>

TRIGger:A:BUS:B<x>:LIN:DATa:HIVALue?

**Arguments** <QString> is a quoted string that is the binary data string used for LIN trigger if

the trigger condition is ID or IDANDDATA.

**Examples** TRIGGER: A: BUS: B1: LIN: DATA: HIVALUE "11001010" sets the high value

to 11001010.

TRIGGER:A:BUS:B1:LIN:DATA:HIVALUE? might return

TRIGGER: A: BUS: B1: LIN: DATA: HIVALUE "XXXXXXXX" indicating

the high value is don't care.

# TRIGger:A:BUS:B<x>:LIN:DATa:QUALifier

Sets or returns the LIN data qualifier. This only applies if the trigger condition is IDANDDATA or DATA.

**Group** Trigger

**Syntax** TRIGger:A:BUS:B<x>:LIN:DATa:QUALifier

{LESSThan|MOREThan|EQUal|UNEQual|LESSEQual|MOREEQual|

INrange|OUTrange}

TRIGger:A:BUS:B<x>:LIN:DATa:QUALifier?

**Arguments** LESSThan sets the LIN data qualifier to less than.

MOREThan sets the LIN data qualifier to greater than.

EQUal sets the LIN data qualifier to equal.

UNEQual sets the LIN data qualifier to not equal.

LESSEQual sets the LIN data qualifier to less than or equal.

MOREEQual sets the LIN data qualifier to greater than or equal.

INrange sets the LIN data qualifier to in range.

OUTrange sets the LIN data qualifier to out of range.

**Examples** TRIGGER:A:BUS:B1:LIN:DATA:QUALIFIER OUTRANGE sets the data qualifier

to out of range.

TRIGGER: A: BUS: B1: LIN: DATA: QUALIFIER? might return

TRIGGER: A: BUS: B1: LIN: DATA: QUALIFIER EQUAL indicating the data

qualifier is set to equal.

## TRIGger:A:BUS:B<x>:LIN:DATa:SIZe

Sets or returns the length of the data string in bytes to be used for LIN trigger.

**Group** Trigger

Syntax TRIGger:A:BUS:B<x>:LIN:DATa:SIZe <NR1>

TRIGger:A:BUS:B<x>:LIN:DATa:SIZe?

**Arguments** <NR1> is the size of the data string in bytes.

**Examples** TRIGGER:A:BUS:B1:LIN:DATA:SIZE 8 sets the data size to 8 bytes.

TRIGGER:A:BUS:B1:LIN:DATA:SIZE? might return

TRIGGER: A:BUS: B1: LIN: DATA: SIZE 1 indicating the data size is 1 byte.

# TRIGger:A:BUS:B<x>:LIN:DATa:VALue

Sets or returns the binary data string to be used for LIN trigger condition if trigger condition is ID or IDANDDATA.

**Group** Trigger

Syntax TRIGger:A:BUS:B<x>:LIN:DATa:VALue <QString>

TRIGger:A:BUS:B<x>:LIN:DATa:VALue?

**Arguments** <QString> is a quoted string that is the LIN trigger data value.

**Examples** TRIGGER:A:BUS:B1:LIN:DATA:VALUE "11001101" sets the data value to

11001101.

TRIGGER: A: BUS: B1: LIN: DATA: VALUE? might return

TRIGGER:A:BUS:B1:LIN:DATA:VALUE "XXXXXXXX" indicating the

data value is don't care.

## TRIGger:A:BUS:B<x>:LIN:ERRTYPE

Sets or returns the error type be used for LIN trigger.

**Group** Trigger

Syntax TRIGger:A:BUS:B<x>:LIN:ERRTYPE

{SYNC|PARity|CHecksum|HEADertime|RESPtime|FRAMetime}

TRIGger:A:BUS:B<x>:LIN:ERRTYPE?

**Arguments** SYNC sets the LIN error type to SYNC.

PARity sets the LIN error type to parity.

CHecksum sets the LIN error type to checksum.

**HEADertime** sets the LIN error type to header time.

RESPtime sets the LIN error type to response time.

FRAMetime sets the LIN error type to frame time.

**Examples** TRIGGER: A:BUS: B1: LIN: ERRTYPE CHECKSUM sets the LIN error type to

checksum.

TRIGGER: A: BUS: B1: LIN: ERRTYPE? might return

TRIGGER: A: BUS: B1: LIN: ERRTYPE SYNC indicating the LIN error type

is SYNC.

### TRIGger:A:BUS:B<x>:LIN:IDentifier:VALue

Sets or returns the binary address string used for LIN trigger if the trigger

condition is ID or IDANDDATA.

**Group** Trigger

Syntax TRIGger:A:BUS:B<x>:LIN:IDentifier:VALue <QString>

TRIGger:A:BUS:B<x>:LIN:IDentifier:VALue?

**Arguments** <QString> is the binary address string used for LIN trigger if the trigger

condition is ID or IDANDDATA.

**Examples** TRIGGER:A:BUS:B1:LIN:IDENTIFIER:VALUE "110010" sets the identifier

value to 110010.

TRIGGER: A: BUS: B1: LIN: IDENTIFIER: VALUE? might return

TRIGGER: A: BUS: B1: LIN: IDENTIFIER: VALUE "XXXXXX" indicating the

identifier value is XXXXXX.

## TRIGger:A:BUS:B<x>:PARallel:VALue

Sets or returns the binary data string to be used for a Parallel trigger. Applies to bus  $\langle x \rangle$ , where x is the bus number.

**Group** Trigger

Syntax TRIGger:A:BUS:B<x>:PARallel:VALue <QString>

TRIGger:A:BUS:B<x>:PARallel:VALue?

**Arguments** <QString> is the binary data string.

### TRIGger:A:BUS:B<x>:RS232C:CONDition

Sets or returns the condition for an RS-232C trigger, where x is the bus number.

**Conditions** This command requires a DPO4COMP application module.

**Group** Trigger

**Syntax** TRIGger:A:BUS:B<x>:RS232C:CONDition

{RXSTArt|RXDATA|RXENDPacket|TXSTArt|TXDATA|TXENDPacket}

TRIGger:A:BUS:B<x>:RS232C:CONDition?

**Arguments** RXSTArt specifies a search based on the RX Start Bit.

RXDATA specifies a search based on RX Data.

**RXENDPacket** specifies a search based on the RX End of Packet condition.

TXSTArt specifies a search base on the TX Start Bit.

TXDATA specifies a search based on TX Data.

TXENDPacket specifies a search based on the TX End of Packet condition.

# TRIGger:A:BUS:B<x>:RS232C:RX:DATa:SIZe

Sets or returns the length of the data string in Bytes for an RS-232 Trigger if the trigger condition is RXDATA. Applies to bus <x>, where x is the bus number.

**Conditions** This command requires a DPO4COMP application module.

**Group** Trigger

Syntax TRIGger:A:BUS:B<x>:RS232C:RX:DATa:SIZe <NR1>

TRIGger:A:BUS:B<x>:RS232C:RX:DATa:SIZe?

**Arguments** <NR1> is the length of the data string in bytes.

### TRIGger:A:BUS:B<x>:RS232C:RX:DATa:VALue

Sets or returns the binary data string for an RS-232 trigger if the trigger condition involves RX. Applies to bus <x>, where x is the bus number.

This command requires a DPO4COMP application module.

**Group** Trigger

**Conditions** 

**Syntax** TRIGger:A:BUS:B<x>:RS232C:RX:DATa:VALue

TRIGger:A:BUS:B<x>:RS232C:RX:DATa:VALue?

**Arguments** <Qstring> is the binary data string to be used for the trigger.

### TRIGger:A:BUS:B<x>:RS232C:TX:DATa:SIZe

Sets or returns the length of the data string for an RS-232 trigger if the trigger condition is TXDATA. Applies to bus <x>, where x is the bus number.

**Conditions** This command requires a DPO4COMP application module.

**Group** Trigger

Syntax TRIGger:A:BUS:B<x>:RS232C:TX:DATa:SIZe <NR1>

TRIGger:A:BUS:B<x>:RS232C:TX:DATa:SIZe?

**Arguments** <NR1> is the length of the data string in Bytes.

# TRIGger:A:BUS:B<x>:RS232C:TX:DATa:VALue

Sets or returns the binary data string for an RS-232 trigger if the condition involves TX. Applies to bus <x>, where x is the bus number.

**Conditions** This command requires a DPO4COMP application module.

**Group** Trigger

Syntax TRIGger:A:BUS:B<X>:RS232C:TX:DATa:VALue

TRIGger:A:BUS:B<x>:RS232C:TX:DATa:VALue?

**Arguments** <Qstring> is the binary data string to be used for the trigger.

### TRIGger: A:BUS:B<x>:SPI:CONDition

Sets or returns the trigger condition for a SPI trigger. Applies to bus  $\langle x \rangle$ , where x is the bus number.

**Conditions** This command requires a DPO4EMBD application module.

**Group** Trigger

**Syntax** TRIGger:A:BUS:B<x>:SPI:CONDition

{SS|STARTofframe|MISO|MOSI|MISOMOSI}
TRIGger:A:BUS:B<x>:SPI:CONDition?

**Related Commands** BUS:B<x>:SPI:IDLETime, BUS:B<x>:SPI:FRAMING

**Arguments** SS specifies the Slave Selection condition.

STARTofframe is applicable when BUS:B<x>:SPI:FRAMING is set to IDLEtime. When the trigger condition is set to STARTofframe, the instrument triggers on the first SPI clock after an idle time when there are no clocks.

MISO specifies the Master-In Slave-Out condition.

MOSI specifies the Master-Out Slave-In condition.

MISOMOSI specifies the Master-In Slave-Out and Master-Out Slave-In conditions.

# TRIGger:A:BUS:B<x>:SPI:DATa{:IN|:MISO}:VALue

Sets or returns the binary data string to be used for a SPI trigger if the trigger condition is MISO or MISOMOSI. Applies to bus <x>, where x is the bus number.

**Conditions** This command requires a DPO4EMBD application module.

**Group** Trigger

Syntax TRIGger:A:BUS:B<x>:SPI:DATa{:IN|:MISO}:VALue <QString>

TRIGger:A:BUS:B<x>:SPI:DATa{:IN|:MISO}:VALue?

**Arguments** <QString> is the binary data string, where the number of bits is 8 times the

number of bytes specified. The only allowed characters in the string are 0, 1,

and X.

# TRIGger:A:BUS:B<x>:SPI:DATa{:OUT|:MOSI}:VALue

Sets or returns the binary data string to be used for a SPI trigger if the trigger condition is MOSI or MISOMOSI. Applies to bus <x>, where x is the bus number.

**Conditions** This command requires a DPO4EMBD application module.

**Group** Trigger

Syntax TRIGger:A:BUS:B<x>:SPI:DATa{:OUT|:MOSI}:VALue <QString>

TRIGger:A:BUS:B<x>:SPI:DATa{:OUT|:MOSI}:VALue?

**Arguments** <QString> is the binary data string with the number of bits specified by the

TRIGger; A:BUS:B<x>:SPI:DATa:SIZe command. The only allowed characters

in the QString are 0, 1, and X.

### TRIGger:A:BUS:B<x>:SPI:DATa:SIZe

Sets or returns the length of the data string to be used for a SPI trigger if the trigger condition is MISO, MOSI, or MISOMOSI. Applies to bus <x>, where x is the bus number.

**Conditions** This command requires a DPO4EMBD application module.

**Group** Trigger

Syntax TRIGger:A:BUS:B<x>:SPI:DATa:SIZe <NR1>

TRIGger:A:BUS:B<x>:SPI:DATa:SIZe?

**Arguments** <NR1> is the length of the data string in bytes.

### TRIGger:A:BUS:B<x>:USB:ADDRess:HIVALue

Sets or returns the binary address string for the upper limit for inside-of-range and outside-of-range qualifiers for the USB trigger. Use the command TRIGger:A:BUS:B<x>:USB:ADDRess:VALue to set the lower limit.

**Conditions** This command requires the DPO4USB application module.

**Group** Trigger

Syntax TRIGger:A:BUS:B<x>:USB:ADDRess:HIVALue <QString>

TRIGger:A:BUS:B<x>:USB:ADDRess:HIVALue?

**Related Commands** TRIGger:A:BUS:B<x>:USB:CONDition, TRIGger:A:BUS:B<x>:USB:

ADDRess:VALue

**Arguments** <QString> within the range 0000000 to 1111111 (00 hex to 7F hex).

**Examples** TRIGGER:A:BUS:B1:USB:ADDRESS:HIVALUE "0001000" sets the upper limit

to binary 0001000 (08 hex).

TRIGGER:A:BUS:B1:USB:ADDRESS:HIVALUE? might return

:TRIGGER:A:BUS:B1:USB:ADDRESS:HIVALUE "1111111", which indicates

that the upper limit is 1111111 (7F hex).

# TRIGger:A:BUS:B<x>:USB:ADDRess:VALue

Sets or returns the binary address string to be used for USB trigger.

This command also sets or returns the binary address string for the lower limit for inside-of-range and outside-of-range qualifiers for the USB trigger.

**Conditions** This command requires the DPO4USB application module.

**Group** Trigger

Syntax TRIGger:A:BUS:B<x>:USB:ADDRess:VALue <Qstring>

TRIGger:A:BUS:B<x>:USB:ADDRess:VALue?

**Related Commands** TRIGger:A:BUS:B<x>:USB:CONDition

**Arguments** <QString> within the range 0000000 to 1111111 (00 hex to 7F hex).

**Examples** TRIGGER:A:BUS:B1:USB:ADDRESS:VALUE "0001000" sets the binary

address to 0001000 (08 hex).

TRIGGER: A: BUS: B1: USB: ADDRESS: VALUE? might return

:TRIGGER:A:BUS:B1:USB:ADDRESS:VALUE "1000000", which

indicates that the binary address is 100000 (40 hex).

### TRIGger:A:BUS:B<x>:USB:CONDition

Sets or returns the trigger condition for the USB trigger.

**Conditions** This command requires the DPO4USB application module.

**Group** Trigger

**Syntax** TRIGger:A:BUS:B<x>:USB:CONDition

{SYNC|RESET|SUSPEND|RESUME|EOP|TOKENPacket|DATAPacket

|HANDSHAKEPacket|SPECIALPacket|ERRor}
TRIGger:A:BUS:B<x>:USB:CONDition?

**Arguments** SYNC indicates triggering on a Sync field of a packet.

RESET sets triggering on a reset condition.

SUSPEND sets triggering on a suspend condition.

RESUME sets triggering on a resume condition.

EOP indicates triggering on an end-of-packet signal.

TOKENPacket indicates triggering on a token packet.

DATAPacket indicates triggering on a data packet

HANDSHAKEPacket indicates triggering on a handshake packet.

SPECIALPacket indicates triggering on a special status packet.

ERROr indicates triggering on an error condition.

**Examples** 

TRIGGER:A:BUS:B1:USB:CONDITION TOKENPACKET sets the trigger condition to be a token packet.

TRIGGER: A: BUS: B1: USB: CONDITION? might return

:TRIGGER:A:BUS:B1:USB:CONDITION SYNC, which indicates that the trigger

condition is a sync field.

# TRIGger:A:BUS:B<x>:USB:DATa:HIVALue

Sets or returns the binary data string for the upper limit for inside-of-range and outside-of-range qualifiers for the USB trigger when the trigger condition is DATAPacket. Use the command TRIGger:A:BUS:B<x>:USB:DATa:VALue to set the lower limit.

**Conditions** 

This command requires the DPO4USB application module.

Group

Trigger

**Syntax** 

TRIGger:A:BUS:B<x>:USB:DATa:HIVALue\_<QString>

TRIGger:A:BUS:B<x>:USB:DATa:HIVALue?

**Related Commands** 

TRIGger:A:BUS:B<x>:USB:CONDition, TRIGger:A:BUS:B<x>:USB:DATa:

VALue

**Arguments** 

**QString>** within the range 00000000 to 11111111 (00 hex to FF hex).

**Examples** 

TRIGGER:A:BUS:B1:USB:DATA:HIVALUE "00001000" sets the upper limit

to binary 00001000 (08 hex).

TRIGGER:A:BUS:B1:USB:DATA:HIVALUE? might return

:TRIGGER:A:BUS:B1:USB:DATA:HIVALUE "01111111", which

indicates that the upper limit is 01111111 (7F hex).

# TRIGger:A:BUS:B<x>:USB:DATa:OFFSet

Sets or returns the data offset in bytes to trigger on. The minimum and default values are 0 and the maximum is 1024.

**Conditions** This command requires the DPO4USB application module.

**Group** Trigger

Syntax TRIGger:A:BUS:B<x>:USB:DATa:OFFSet <NR1>

TRIGger:A:BUS:B<x>:USB:DATa:OFFSet?

**Related Commands** TRIGger:A:BUS:B<x>:USB:CONDition

**Arguments** <NR1> is number in the range 0 to 1024.

**Examples** TRIGGER: A:BUS: B1: USB: DATA: OFFSET 36 sets the data offset to 36.

TRIGGER: A: BUS: B1: USB: DATA: OFFSET? might return

:TRIGGER:A:BUS:B1:USB:DATA:OFFSET 0, indicating that the

data offset is the default value, 0.

### TRIGger:A:BUS:B<x>:USB:DATa:SIZe

Sets or returns the number of contiguous data bytes to trigger on. The minimum

and default values are 1 and maximum is 16.

**Conditions** This command requires the DPO4USB application module.

**Group** Trigger

Syntax TRIGger:A:BUS:B<x>:USB:DATa:SIZe <NR1>

TRIGger:A:BUS:B<x>:USB:DATa:SIZe?

**Arguments** <NR1> is number in the range 1 to 16.

**Examples** TRIGGER:A:BUS:B1:USB:DATA:SIZE 4 sets the oscilloscope to trigger on four

contiguous data bytes.

TRIGGER: A: BUS: B1: USB: DATA: SIZE? might return

:TRIGGER:A:BUS:B1:USB:DATA:SIZE 6 indicating that the oscilloscope will

trigger on 6 contiguous data bytes.

## TRIGger:A:BUS:B<x>:USB:DATa:TYPe

Sets or returns the data type for when the trigger condition is set to DATAPacket.

**Conditions** This command requires the DPO4USB application module.

**Group** Trigger

Syntax TRIGger:A:BUS:B<x>:USB:DATa:TYPe {ANY|DATA0|DATA1}

TRIGger:A:BUS:B<x>:USB:DATa:TYPe?

**Related Commands** TRIGger:A:BUS:B<x>:USB:CONDition

**Arguments** ANY indicates either a DATA0 or DATA1 data packet type.

DATA0 indicates a DATA0 data packet type.

DATA1 indicates a DATA1 data packet type.

**Examples** TRIGGER:A:BUS:B1:USB:DATA:TYPE DATA0 sets the oscilloscope to trigger

on a DATA0 data packet type.

TRIGGER: A: BUS: B1: USB: DATA: TYPE? might return

:TRIGGER:A:BUS:B1:USB:DATA:TYPE DATA1, indicating that the data packet

type is set to DATA1.

### TRIGger:A:BUS:B<x>:USB:DATa:VALue

Sets or returns the binary data string to be used for the USB trigger when the trigger condition is DATAPacket.

This command also sets or returns the binary data string for the lower limit for inside-of-range and outside-of-range qualifiers for the USB trigger when trigger condition is DATAPacket.

**Conditions** This command requires the DPO4USB application module.

**Group** Trigger

Syntax TRIGger:A:BUS:B<x>:USB:DATa:VALue <QString>

TRIGger:A:BUS:B<x>:USB:DATa:VALue?

**Related Commands** TRIGger:A:BUS:B<x>:USB:CONDition

**Arguments** <QString> within the range 00000000 to 11111111 (00 hex to FF hex).

**Examples** TRIGGER: A:BUS: B1: USB: DATA: VALUE "00001000" sets the binary address

to 00001000 (08 hex).

TRIGGER: A: BUS: B1: USB: DATA: VALUE? might return

:TRIGGER:A:BUS:B1:USB:DATA:VALUE "01000000", which

indicates that the binary address is 0100000 (40 hex).

### TRIGger:A:BUS:B<x>:USB:ENDPoint:VALue

Sets or returns the binary endpoint string to be used for the USB trigger.

**Conditions** This command requires the DPO4USB application module.

**Group** Trigger

Syntax TRIGger:A:BUS:B<x>:USB:ENDPoint:VALue <QString>

TRIGger:A:BUS:B<x>:USB:ENDPoint:VALue?

**Related Commands** TRIGger:A:BUS:B<x>:USB:CONDition

**Arguments** <QString> within the range 0000 to 1111 (00 hex to 0F hex).

**Examples** TRIGGER:A:BUS:B1:USB:ENDPOINT:VALUE "1000" sets the binary address

to 1000 (08 hex).

TRIGGER: A: BUS: B1: USB: ENDPOINT: VALUE? might return

:TRIGGER:A:BUS:B1:USB:ENDPOINT:VALUE "1001", which indicates that

the binary address is 1001 (09 hex).

# TRIGger:A:BUS:B<x>:USB:ERRORTYPe

Sets or returns the error type used when the trigger condition is set to ERRor.

**Conditions** This command requires the DPO4USB application module.

**Group** Trigger

Syntax TRIGger:A:BUS:B<x>:USB:ERRORTYPe

{PID|CRC5|CRC16|BITSTUFFing}
TRIGger:A:BUS:B<x>:USB:ERRORTYPe?

**Related Commands** TRIGger:A:BUS:B<x>:USB:CONDition

**Arguments** PID indicates the error type is set to packet ID.

CRC5 indicates the error type is set to 5-bit CRC.

CRC16 indicates the error type is set to 16-bit CRC.

BITSTUFFing indicates the error type is set to bit stuffing.

**Examples** TRIGGER:A:BUS:B1:USB:CONDITION PID sets the error trigger condition

to packet ID.

TRIGGER: A: BUS: B1: USB: CONDITION? might return

:TRIGGER:A:BUS:B1:USB:CONDITION PID, indicating the error trigger

condition is packet ID.

TRIGger:A:BUS:B<x>:USB:HANDSHAKEType

Sets or returns the handshake type for the USB trigger.

**Conditions** This command requires the DPO4USB application module.

**Group** Trigger

Syntax TRIGger:A:BUS:B<x>:USB:HANDSHAKEType {ANY|NAK|ACK|STALL}

TRIGger:A:BUS:B<x>:USB:HANDSHAKEType?

**Related Commands** TRIGger:A:BUS:B<x>:USB:CONDition

**Arguments** ANY indicates the oscilloscope will trigger on any handshake type.

NAK indicates the oscilloscope will trigger when a device cannot send or receive

data.

ACK indicates the oscilloscope will trigger when a packet is successfully received.

STALL indicates the oscilloscope will trigger when a device requires intervention from the host.

**Examples** 

TRIGGER:A:BUS:B1:USB:HANDSHAKETYPE ACK sets the handshake type to acknowledgement.

TRIGGER: A: BUS: B1: USB: HANDSHAKETYPE? might return

:TRIGGER:A:BUS:B1:USB:HANDSHAKETYPE STALL, indicating that

the handshake type is set to stall.

# TRIGger:A:BUS:B<x>:USB:QUALifier

Sets or returns the USB trigger qualifier for address, endpoint and data.

**Conditions** This command requires the DPO4USB application module.

**Group** Trigger

Syntax TRIGger:A:BUS:B<x>:USB:QUALifier

{LESSThan|MOREThan|EQUal|UNEQual|LESSEQual

|MOREEQual|INrange|OUTrange|
TRIGger:A:BUS:B<x>:USB:QUALifier?

**Related Commands** TRIGger:A:BUS:B<x>:USB:CONDition

**Arguments** LESSThan triggers on an input value that is less than a set value.

MOREThan triggers on an input value that is greater than a set value.

EQUal triggers on an input value that is equal to a set value.

UNEQual triggers on an input value that is not equal to a set value.

LESSEQual triggers on an input value that is less than or equal to a set value.

MOREEQual triggers on an input value that is more than or equal to a set value.

INrange triggers on an input value that is within a range set by two values.

OUTrange triggers on an input value that is outside of a range set by two values.

**Examples** TRIGGER:A:BUS:B1:USB:QUALIFIER LESSTHAN sets the oscilloscope to

trigger when an address, data, or endpoint value is less than a set value.

TRIGGER:A:BUS:B1:USB:QUALIFIER? might return

:TRIGGER:A:BUS:B1:USB:QUALIFIER EQUAL indicating that the trigger condition is to trigger when an address, data, or endpoint is equal to a set value.

### TRIGger:A:BUS:B<x>:USB:SOFFRAMENUMber

Sets or returns the binary data string to be used for start of frame number, when the trigger condition is Token Packet and the token type is Start of Frame.

**Conditions** This command requires the DPO4USB application module.

**Group** Trigger

Syntax TRIGger:A:BUS:B<x>:USB:SOFFRAMENUMber <QString>

TRIGger:A:BUS:B<x>:USB:SOFFRAMENUMber?

**Related Commands** TRIGger:A:BUS:B<x>:USB:CONDition

**Arguments** <QString> within the range 000 0000 0000 to 111 1111 1111 (000 hex to 7FF

hex).

**Examples** TRIGGER:A:BUS:B1:USB:SOFFRAMENUMBER "00000001000" sets the start of

frame number to 00000001000 (008 hex).

TRIGGER:A:BUS:B1:USB:SOFFRAMENUMBER? might return

:TRIGGER:A:BUS:B1:USB:SOFFRAMENUMBER "0000001001", which

indicates that the start of frame number is 00000001001 (009 hex).

# TRIGger:A:BUS:B<x>:USB:SPECIALType

Sets or returns the packet ID (PID) for the special packet.

**Conditions** This command requires the DPO4USB application module.

**Group** Trigger

Syntax TRIGger:A:BUS:B<x>:USB:SPECIALType {ANY|PREamble|RESERVed}

TRIGger:A:BUS:B<x>:USB:SPECIALType?

**Related Commands** TRIGger:A:BUS:B<x>:USB:CONDition

**Arguments** ANY indicates any type of special packet.

PREamble indicates a preamble special packet.

RESERVed indicates a reserved special packet.

**Examples** TRIGGER: A: BUS1: USB: SPECIALTYPE PREAMBLE sets the special packet type

to preamble.

TRIGGER: A: BUS1: USB: SPECIALTYPE? might return

:TRIGGER:A:BUS1:USB:SPECIALTYPE PREAMBLE, indicating that the special

type is set to preamble.

### TRIGger:A:BUS:B<x>:USB:TOKENType

Sets or returns the token type for the USB trigger.

**Conditions** This command requires the DPO4USB application module.

**Group** Trigger

Syntax TRIGger:A:BUS:B<x>:USB:TOKENType {ANY|SOF|OUT|IN|SETUP}

TRIGger:A:BUS:B<x>:USB:TOKENType?

**Related Commands** TRIGger:A:BUS:B<x>:USB:CONDition

**Arguments** ANY

indicates any of the token types.

SOF indicates a SOF (start-of-frame) token type

OUT indicates an OUT token type.

IN indicates an IN token type.

SETUP indicates a SETUP token type.

**Examples** TRIGGER:A:BUS:B1:USB:TOKENTYPE SETUP sets the token type to SETUP.

TRIGGER: A: BUS: B1: USB: TOKENTYPE? might return

:TRIGGER:A:BUS:B1:USB:TOKENTYPE SOF if the token type is SOF.

### TRIGger:A:BUS:SOUrce

Sets or returns the source for a Serial bus trigger.

**Conditions** This command requires a DPO4AUTO or DPO4EMBD application module.

**Group** Trigger

Syntax TRIGger:A:BUS:SOUrce {B1|B2|B3|B4}

TRIGger: A: BUS: SOUrce?

**Arguments** B1 specifies the Bus 1 source.

B2 specifies the Bus 2 source.

B3 specifies the Bus 3 source.

B4 specifies the Bus 4 source.

### TRIGger:A:EDGE? (Query Only)

Returns the trigger source, coupling, and slope for the A edge trigger.

**Group** Trigger

Syntax TRIGger:A:EDGE?

**Related Commands** TRIGger:A:PULse?, TRIGger:A:LOGIc?

**Examples** TRIGGER: A: EDGE? might return: TRIGGER: A: EDGE: SOURCE CH1; COUPLING

DC; SLOPE RISE indicating the trigger source, coupling, and slope for the A

edge trigger.

## TRIGger: A: EDGE: COUPling

Sets or returns the type of coupling for the A edge trigger.

**Group** Trigger

Syntax TRIGger:A:EDGE:COUPling {DC|HFRej|LFRej|NOISErej}

TRIGger:A:EDGE:COUPling?

Related Commands TRIGger:A:EDGE:SOUrce, TRIGger:A:EDGE:SLOpe

**Arguments** DC specifies DC trigger coupling, which passes all input signals to the trigger

circuitry.

HFRej specifies high-frequency rejection coupling, which attenuates signals

above 50 kHz before passing the signals to the trigger circuitry.

LFRej specifies low-frequency rejection coupling, which attenuates signals below

50 kHz before passing the signals to the trigger circuitry.

NOISErej specifies noise-rejection coupling, which provides stable triggering

by increasing the trigger hysteresis. Increased hysteresis reduces the trigger sensitivity to noise but may require greater trigger signal amplitude.

**Examples** TRIGGER: A: EDGE: COUPLING DC sets the A edge trigger coupling to DC.

TRIGGER: A: EDGE: COUPLING? might return: TRIGGER: A: EDGE: COUPLING

DC indicating that the A edge trigger coupling is set to DC.

TRIGger: A: EDGE: SLOpe

Sets or returns the slope for the A edge trigger.

**Group** Trigger

Syntax TRIGger:A:EDGE:SLOpe {RISe|FALL}

TRIGger:A:EDGE:SLOpe?

Related Commands TRIGger: A:EDGE: SOUrce, TRIGger: A:EDGE: COUPling

**Arguments** RISe specifies to trigger on the rising or positive edge of a signal.

FALL specifies to trigger on the falling or negative edge of a signal.

**Examples** TRIGGER: A: EDGE: SLOPE RISE sets the A edge trigger slope to positive, which

triggers on the rising edge of the signal.

TRIGGER: A: EDGE: SLOPE? might return: TRIGGER: A: EDGE: SLOPE FALL

indicating that the A edge trigger slope is negative.

## TRIGger:A:EDGE:SOUrce

Sets or returns the source for the A edge trigger.

**Group** Trigger

Syntax TRIGger:A:EDGE:SOUrce {CH1|CH2|CH3|CH4|

D0|D1|D2|D3|D4|D5|D6|D7|D8|D9|D10|D11|D12|D13|D14|D15|

EXT|LINE|AUX}

TRIGger:A:EDGE:SOUrce?

Related Commands TRIGger: A:EDGE: SLOpe, TRIGger: A:EDGE: COUPling

**Arguments** CH1-CH4 specifies an analog input channel as the A edge trigger source.

D0-D15 specifies a digital channel as the source (MSO models only).

EXT specifies an external trigger using the Aux In connector located on the front

panel of the oscilloscope.

LINE specifies the AC line as the trigger source.

AUX specifies the Auxiliary Input as the trigger source (if available on your

oscilloscope).

**Examples** TRIGGER: A: EDGE: SOURCE CH1 sets channel 1 as the A edge trigger source.

TRIGGER: A: EDGE: SOURCE? might return: TRIGGER: A: EDGE: SOURCE CH1

indicating that channel 1 is the A edge trigger source.

TRIGger: A: HOLDoff? (Query Only)

Returns the A trigger holdoff parameters. These parameters specify the time period during which the trigger circuitry is not looking to generate a trigger event.

**Group** Trigger

**Syntax** TRIGger:A:HOLDoff?

**Related Commands** TRIGger: A:HOLDoff: TIMe

**Examples** TRIGGER:A:HOLDOFF? might return :TRIGGER:A:HOLDOFF:TIME

900.0000E-09; BY DEFAULT indicating that the A edge trigger holdoff time

(by default) is 900 ns.

#### TRIGger: A: HOLDoff: TIMe

Sets or returns the A trigger holdoff time.

**Group** Trigger

Syntax TRIGger:A:HOLDoff:TIMe <NR3>

TRIGger:A:HOLDoff:TIMe?

**Arguments** <NR3> specifies the holdoff time in seconds. The range is from 20 ns through 8.0 s.

**Examples** TRIGGER:A:HOLDOFF:TIME ? might return :TRIGGER:A:HOLDOFFTIME

1.2000E-06 indicating that the A trigger holdoff time is set to 1.2  $\mu$ s.

TRIGGER: A: HOLDOFF: TIME 10 sets the A trigger holdoff time to 10 s.

TRIGger:A:LEVel

Sets or returns the trigger level for the A trigger.

**Group** Trigger

Syntax TRIGger:A:LEVel {ECL|TTL|<NR3>}

TRIGger:A:LEVel?

**Arguments** ECL specifies a preset ECL high level of -1.3V.

TTL specifies a preset TTL high level of 1.4V.

<NR3> specifies the trigger level in user units (usually volts).

**Examples** TRIGGER:A:LEVEL? might return :TRIGGER:A:LEVel 1.3000E+00

indicating that the A edge trigger is set to 1.3 V.

TRIGGER: A: LEVEL TTL sets the A edge trigger to TTL high level, which is 1.4 V.

### TRIGger: A: LEVel: AUXin

Sets or returns the trigger level for the AUXIN port.

**Group** Trigger

Syntax TRIGger:A:LEVel:AUXin {<NR3>|ECL|TTL}

TRIGger: A: LEVel: AUXin?

**Arguments** <NR3> specifies the trigger level, in volts.

ECL specifies a preset ECL trigger level of -1.3V.

TTL specifies a preset TTL trigger level of 1.4V.

**Examples** TRIGGER: A: LEVEL: AUXIN ECL sets the auxiliary input trigger level to -1.3

volts.

TRIGGER: A: LEVEL: AUXIN? might return TRIGGER: A: LEVEL: AUXIN 0.0E+0

indicating the auxiliary input trigger level is 0.0 volts.

#### TRIGger:A:LEVel:CH<x>

Sets or returns the trigger level for the specified channel. Each channel can have

an independent level.

**Group** Trigger

Syntax TRIGger:A:LEVel:CH<x> {<NR3>|TTL|ECL}

TRIGger:A:LEVel:CH<x>?

**Arguments** <NR3> specifies the trigger level in user units (usually volts).

TTL specifies a preset TTL high level of 1.4V.

ECL specifies a preset ECL high level of -1.3V.

**Examples** TRIGGER:A:LEVEL:CH2? might return :TRIGGER:A:LEVEL:CH2

1.3000E+00 indicating that the A edge trigger is set to 1.3 V for channel 2.

TRIGGER: A: LEVEL: CH3 TTL sets the A edge trigger to TTL high level for

channel 3.

### TRIGger:A:LEVel:D<x>

Sets or returns the trigger level for the specified digital channel <x>, where x is the channel number. Each digital channel can have an independent level.

**Group** Trigger

Syntax TRIGger:A:LEVel:D<x> {<NR3>|ECL|TTL}

TRIGger:A:LEVel:D<x>?

**Arguments** ECL specifies a preset ECL high level of –1.3V.

TTL specifies a preset TTL high level of 1.4V.

<NR3> specifies the trigger level in volts.

## TRIGger:A:LOGIc? (Query Only)

Returns all of the A logic trigger parameters.

**Group** Trigger

Syntax TRIGger:A:LOGIc?

Related Commands TRIGger: A:LOGIc: CLAss

**Examples** TRIGGER:A:LOGIC? might return :TRIGGER:A:LOGIC:CLASS

SETHOLD; FUNCTION AND; THRESHOLD: CH1 20.0000E-3; CH2 0.0000;

CH3 0.0000; CH4 0.0000; :TRIGGER: A: LOGIC: INPUT: CH1

X;CH2 X;CH3 X;CH4 X;CLOCK:SOURCE NONE;EDGE

RISE;:TRIGGER:A:LOGIC:PATTERN:INPUT:CH1 X;CH2 X;CH3

X;CH4 X;:TRIGGER :A:LOGIC:PATTERN:WHEN TRUE;WHEN:LESSLIMIT 4.0000E-9;LIMIT 4.0000E-9;:TRIGGER:A:LOGIC:PATTERN:DELTATIME

4.0000E-9

## TRIGger:A:LOGIc:CLAss

Sets or returns the class of the Logic Trigger. This command is used in conjunction with the TRIGger:A:TYPe command.

**Group** Trigger

Syntax TRIGger:A:LOGIc:CLAss {LOGIC|SETHold}

TRIGger:A:LOGIc:CLAss?

**Related Commands** TRIGger:A:TYPe, TRIGger:A:PULse:CLAss

**Arguments** LOGIC sets the oscilloscope to trigger on logical combinations of the channels.

When the TRIGger: A:LOGIc: INPut: CLOCk: SOUrce is NONE, LOGIC sets the oscilloscope to trigger when the specified logical combinations of channels 1, 2, 3, and 4 are met on four-channel oscilloscopes. On two-channel oscilloscopes,

only channel 1 and channel 2 are available.

When the TRIGger:A:LOGIc:INPut:CLOCk:SOUrce is set to one of the channels, LOGIC sets the oscilloscope to trigger when the specified logical combinations of the remaining channels is true during a transition on the clock channel.

SETHold sets the oscilloscope to trigger on setup and hold violations between a data source and a clock source. Use one channel input as the clock signal and a second channel input as the data input. The clocking and data levels are used to determine if a clock or data transition has occurred.

**Examples** TRIGGER:A:LOGIC:CLASS? might return :TRIGGER:A:LOGIC:CLASS LOGIC

TRIGGER:A:LOGIC:CLASS LOGIC sets the trigger A logic class to LOGIc, which causes the oscilloscope to trigger when the specified logical combinations of

channels 1, 2, 3, and 4 are met.

## TRIGger: A: LOGIc: FUNCtion

Sets or returns the logical combination of the input channels for the A pattern and A state logic triggers.

**Group** Trigger

Syntax TRIGger:A:LOGIc:FUNCtion {AND|NANd|NOR|OR}

TRIGger:A:LOGIc:FUNCtion?

**Related Commands** TRIGger: A:LOGIc:INPut:CH<x>

**Arguments** AND specifies to trigger if all conditions are true.

NANd specifies to trigger if any of the conditions is false.

NOR specifies to trigger if all conditions are false.

OR specifies to trigger if any of the conditions is true.

**Examples** TRIGGER:A:LOGIC:FUNCTION? might return:TRIGGER:A:LOGIC:FUNCTION

NAND

which indicates that the oscilloscope will trigger if the AND logic conditions

are false.

TRIGGER: A: LOGIC: FUNCTION AND sets the logical combination of channels to

be true when all conditions are true.

## TRIGger:A:LOGIc:INPut? (Query Only)

Returns the logic input values for all channels. If a clock channel is defined, it returns the clock source and edge.

**Group** Trigger

Syntax TRIGger:A:LOGIc:INPut?

**Examples** TRIGGER:A:LOGIC:INPUT? might return :TRIGGER:A:LOGIC:INPUT:CH1

HIGH; CH2 X; CH3 X indicating that a logic high is expected on channel 1 while

channel 2 and channel three are "don't care."

## TRIGger:A:LOGIc:INPut:CH<x>

Sets or returns the logical input condition for the channel specified by  $\langle x \rangle$ .

**Group** Trigger

Syntax TRIGger:A:LOGIc:INPut:CH<x> {HIGH|LOW|X}

TRIGger:A:LOGIc:INPut:CH<x>?

**Arguments** HIGH specifies the logic high.

LOW specifies the logic low.

X specifies a "don't care" state.

#### **Examples**

TRIGGER:A:LOGIC:INPUT:CH1? might return:TRIGGER:LOGIC:INPUT:CH1 X indicating that the setting for the A logic trigger input to channel 1 does not

matter.

TRIGGER:A:LOGIC:INPUT:CH2 HIGH sets the A logic trigger input to logic HIGH for channel 2.

#### TRIGger: A:LOGIc: INPut: CLOCk: EDGE

Sets the polarity of the clock channel.

**Group** Trigger

Syntax TRIGger:A:LOGIc:INPut:CLOCk:EDGE {FALL|RISe}

TRIGger:A:LOGIc:INPut:CLOCk:EDGE?

**Arguments** RISe specifies to trigger on the rising or positive edge of a signal.

FALL specifies to trigger on the falling or negative edge of a signal.

## TRIGger:A:LOGIc:INPut:CLOCk:SOUrce

Sets or returns the channel to use as the clock source. The clock can be selected as NONE. A selection of None implies pattern trigger. Any other selection implies state trigger.

**Group** Trigger

Syntax TRIGger:A:LOGIc:INPut:CLOCk:SOUrce {CH1|CH2|CH3|CH4|

D0|D1|D2|D3|D4|D5|D6|D7|D8|D9|D10|D11|D12|D13|D14|D15|NONE}

TRIGger:A:LOGIc:INPut:CLOCk:SOUrce?

**Arguments** CH1–CH4 specifies the analog input channel source.

D0-D15 specifies the digital input channel source.

NONE specifies a Pattern trigger.

### TRIGger:A:LOGIc:INPut:D<x>

Sets or returns the logic pattern for a trigger on digital channel <x>, where x is the channel number.

**Group** Trigger

Syntax TRIGger:A:LOGIc:INPut:D<x> {HIGH|LOW|X}

TRIGger:A:LOGIc:INPut:D<x>?

**Arguments** High specifies the logic high state.

Low specifies the logic low state.

X specifies a "don't care" state.

# TRIGger:A:LOGIc:PATtern? (Query Only)

Returns the conditions used for generating an A logic pattern trigger, with respect to the defined input pattern, and identifies the time that the selected pattern may be true and still generate the trigger.

**Group** Trigger

**Syntax** TRIGger:A:LOGIc:PATtern?

**Examples** TRIGGER:A:LOGIC:PATTERN? might return

:TRIGGER:A:LOGIC:PATTERN:INPUT:CH1 HIGH;CH2 LOW;CH3 X;CH4 X;:TRIGGER:A:LOGIC:PATTERN:WHEN LESSTHAN;WHEN:LESSLIMIT 16.0000E-9;LIMIT

16.0000e-9;:TRIGGER:A:LOGIC:PATTERN:DELTATIME 16.0000e-9

## TRIGger: A:LOGIc: PATtern: DELTatime

Sets or returns the pattern trigger delta time value. The time value is used as part of the pattern trigger condition to determine if the duration of a logic pattern meets the specified time constraints.

**Group** Trigger

Syntax TRIGger:A:LOGIc:PATtern:DELTatime <NR3>

TRIGger: A: LOGIc: PATtern: DELTatime?

**Arguments** <NR3> is a floating point value with exponent that sets the pattern trigger time

value. This argument has a range of 39.6E–9 (39.6 ns) to 10.0E0 (10 s), in increments of 13.2 ns. Values that are not an increment of 13.2 ns are rounded to

the nearest correct value.

**Examples** TRIGGER: A:LOGIC: PATTERN: DELTATIME 71.28E-8 sets the pattern trigger

delta time value to 712.8 ns.

#### TRIGger:A:LOGIc:PATtern:INPut:D<x>

Sets or returns the A logic trigger input for the specified digital channel <x>, where x is the channel number. This command species the logic value used when the pattern trigger detects the threshold level.

**Group** Trigger

Syntax TRIGger:A:LOGIc:PATtern:INPut:D<x> {HIGH|LOW|X}

TRIGger:A:LOGIc:PATtern:INPut:D<x>?

**Arguments** HIGH specifies a logic high.

LOW specifies a logic low.

X specifies a "do not care" state.

#### TRIGger: A: LOGIc: PATtern: WHEn

Sets or returns the pattern logic condition on which to trigger the oscilloscope.

**Group** Trigger

**Syntax** TRIGger:A:LOGIc:PATtern:WHEn

{TRUe|FALSe|LESSThan|MOREThan|EQUal|UNEQual}

TRIGger:A:LOGIc:PATtern:WHEn?

**Arguments** TRUE triggers the oscilloscope when the pattern becomes true.

FALSE triggers the oscilloscope when the pattern becomes false.

LESSTHAN triggers the oscilloscope when the input pattern is true for a time period less than the time period specified in TRIGGER:A:LOGIC:PATTERN:DELTATIME.

MORETHAN triggers the oscilloscope when the input pattern is true for a time period more (greater) than the time period specified in TRIGGER:A:LOGIC:PATTERN:DELTATIME.

EQUAL triggers the oscilloscope when the input pattern is true for a time period equal to the time period specified in TRIGGER: A:LOGIC: PATTERN: DELTATIME, within a  $\pm 5\%$  tolerance.

UNEQUAL triggers the oscilloscope when the input pattern is true for a time period greater than or less than (not equal to) the time period specified in TRIGGER:A:LOGIC:PATTERN:DELTATIME, within a  $\pm 5\%$  tolerance.

#### **Examples**

TRIGGER:A:LOGIC:PATTERN:WHEN LESSTHAN sets the oscilloscope to trigger when the pattern is true for a time period less than the pattern trigger delta time setting.

#### TRIGger:A:LOGIc:PATtern:WHEn:LESSLimit

Sets or returns the maximum time that the selected pattern may be true and still generate an A logic pattern trigger.

**Group** Trigger

Syntax TRIGger:A:LOGIc:PATtern:WHEn:LESSLimit <NR3>

TRIGger: A: LOGIc: PATtern: WHEn: LESSLimit?

**Arguments** <NR3> specifies the maximum amount of time to hold the pattern true.

**Examples** TRIGGER:A:LOGIC:PATTERN:WHEN:LESSLIMIT 10.0E+00 sets the

maximum time that the selected pattern may hold true (and generate an A logic

pattern trigger) to 10 s.

TRIGGER: A: LOGIC: PATTERN: WHEN: LESSLIMIT? might return

TRIGGER: A: LOGIC: PATTERN: WHEN: LESSLIMIT 8.0000E-9 indicating that the selected pattern may hold true for up to 8 ns and still generate an A logic

pattern trigger.

## TRIGger: A: LOGIc: PATtern: WHEn: MORELimit

Sets or returns the minimum time that the selected pattern may be true and still generate an A logic pattern trigger.

**Group** Trigger

Syntax TRIGger:A:LOGIc:PATtern:WHEn:MORELimit <NR3>

TRIGger: A: LOGIc: PATtern: WHEn: MORELimit?

**Arguments** <NR3> specifies the minimum amount of time to hold the pattern true.

**Examples** TRIGGER:A:LOGIC:PATTERN:WHEN:MORELIMIT 10.0E+00 sets the minimum

time that the selected pattern may hold true (and generate an A logic pattern

trigger) to 10 s.

TRIGGER: A: LOGIC: PATTERN: WHEN: MORELIMIT? might return

TRIGGER:A:LOGIC:PATTERN:WHEN:MORELIMIT 8.0000E-9 indicating that the selected pattern must hold true for at least 8 ns to generate an A logic pattern

trigger.

## TRIGger:A:LOGIc:THReshold:CH<x>

This command sets or queries the trigger A logic threshold voltage for the specified channel x.

**Group** Trigger

Syntax TRIGger:A:LOGIc:THReshold:CH<x> {<NR3>|ECL|TTL}

TRIGger:A:LOGIc:THReshold:CH<x>?

**Arguments** <NR3> specifies the threshold voltage, in volts.

ECL specifies a preset ECL high level of -1.3V.

TTL specifies a preset TTL high level of 1.4V.

**Examples** TRIGGER:A:LOGIC:THRESHOLD:CH2 3.0E-3 sets the A logic trigger threshold

voltage for Channel 2 to 3 mV.

TRIGGER: A: LOGIC: THRESHOLD: CH3? might return

:TRIGGER:A:LOGIC:THRESHOLD:CH3 1.2000E+00, indicating that the A

logic trigger threshold voltage for Channel 3 is 1.2 V.

## TRIGger:A:LOGIc:THReshold:D<x>

Sets or returns the trigger A logic threshold level for the specified digital channel <x>. This commands affects all trigger types using the digital channel.

**Group** Trigger

Syntax TRIGger:A:LOGIc:THReshold:D<x> {<NR3>|ECL|TTL}

TRIGger:A:LOGIc:THReshold:D<x>?

**Related Commands** TRIGger:A:LEVel:D<x>

**Arguments** <NR3> specifies the threshold level in volts.

ECL specifies a preset ECL high level of -1.3V.

TTL specifies a preset TTL high level of 1.4V.

## TRIGger:A:LOWerthreshold:CH<x>

Sets or returns the lower threshold for the channel selected. Each channel can have an independent level. Used in Runt and Slew Rate triggers as the lower threshold. Used for all other trigger types as the single level/threshold.

**Group** Trigger

Syntax TRIGger:A:LOWerthreshold:CH<x> {ECL|TTL|<NR3>}

TRIGger: A: LOWerthreshold: CH<x>?

**Related Commands** TRIGger:A:LEVel:CH<x>

**Arguments** ECL specifies a preset ECL high level of -1.3V.

TTL specifies a preset TTL high level of 1.4V.

<NR3> is the clock level, in volts.

**Examples** TRIGGER:A:LOWERTHRESHOLD:CH2 50E-3 sets the lower limit threshold for

CH2 of the pulse runt trigger to 50 mV.

TRIGGER:A:LOWERTHRESHOLD:CH2? might return:TRIGGER:A:LOWERTHRESHOLD:CH2 1.2000E-01 indicating that the lower limit threshold for CH2 of the pulse runt trigger is set to 120 mV.

#### TRIGger:A:LOWerthreshold:D<x>

Sets the lower threshold for the digital channel selected. Each channel can have an independent level. Used in runt and slew rate as the lower threshold. Used for all other trigger types as the single level/threshold.

**Group** Trigger

Syntax TRIGger:A:LOWerthreshold:D<x> {<NR3>|ECL|TTL}

TRIGger:A:LOWerthreshold:D<x>?

**Arguments** <NR3> specifies the threshold voltage, in volts.

ECL specifies a preset ECL high level of -1.3V.

TTL specifies a preset TTL high level of 1.4V.

**Examples** TRIGGER:A:LOWERTHRESHOLD:D1 0.5 sets the lower threshold to 0.5 volts.

TRIGGER: A: LOWERTHRESHOLD: D1? might return

TRIGGER: A: LOWERTHRESHOLD: D1 -1.3000 indicating the lower threshold

is set to -1.3 volts.

#### TRIGger:A:LOWerthreshold{:EXT|:AUX}

Sets or returns the lower threshold for the Auxiliary Input. Used for the following trigger types: Runt, Slew Rate.

**Group** Trigger

Syntax TRIGger:A:LOWerthreshold{:EXT|:AUX} {<NR3>|ECL|TTL}

TRIGger:A:LOWerthreshold{:EXT|:AUX}?

**Arguments** ECL specifies a preset ECL high level of –1.3V.

TTL specifies a preset TTL high level of 1.4V.

<NR3> specifies the threshold level in volts.

### TRIGger: A: MODe

Sets or returns the A trigger mode.

**Group** Trigger

**Syntax** TRIGger:A:MODe {AUTO|NORMal}

TRIGger:A:MODe?

Related Commands TRIGger: A:LEVel

**Arguments** AUTO generates a trigger if one is not detected within a specified time period.

NORMal waits for a valid trigger event.

**Examples** TRIGGER: A: MODE NORMAL specifies that a valid trigger event must occur before

a trigger is generated.

TRIGGER: A: MODE ? might return : TRIGGER: A: MODE NORMAL indicating that a

valid trigger event must occur before a trigger is generated.

## TRIGger:A:PULse? (Query Only)

Returns the A pulse trigger parameters.

**Group** Trigger

**Syntax** TRIGger:A:PULse?

Related Commands TRIGger: A:EDGE?, TRIGger: A:LOGIc?

Examples TRIGGER:A:PULSE? might return :TRIGGER:A:PULSE:CLASS TRANSITION

## TRIGger:A:PULse:CLAss

Sets or returns the type of pulse on which to trigger.

**Group** Trigger

Syntax TRIGger:A:PULse:CLAss {RUNt|WIDth|TRANsition}

TRIGger:A:PULse:CLAss?

**Related Commands** TRIGger:A:RUNT?, TRIGger:A:PULSEWIDth?, TRIGger:A{:TRANsition|:

RISEFall}?, TRIGger:A:TYPe

**Arguments** RUNt triggers when a pulse crosses the first preset voltage threshold but does not

cross the second preset threshold before recrossing the first.

WIDth triggers when a pulse is found that has the specified polarity and is either

inside or outside the specified time limits.

TRANsition triggers when a pulse crosses both thresholds in the same direction

as the specified polarity and the transition time between the two threshold

crossings is greater or less than the specified time delta.

**Examples** TRIGGER: A: PULSE: CLASS WIDTH specifies a width pulse for the A trigger.

TRIGGER: A: PULSE: CLASS? might return: TRIGGER: A: PULSE: CLASS WIDTH

indicating that a pulse was found that is of the specified polarity and width.

## TRIGger: A:PULSEWIDth? (Query Only)

Returns the width parameters for the pulse width trigger.

**Group** Trigger

**Syntax** TRIGger:A:PULSEWIDth?

**Examples** TRIGGER:A:PULSEWIDTH? might return

:TRIGGER:A:PULSEWIDTH:POLARITY POSITIVE;WHEN LESSTHAN;WIDTH

8.0000E-9

### TRIGger: A: PULSEWidth: POLarity

Sets or returns the polarity for the width trigger.

**Group** Trigger

Syntax TRIGger:A:PULSEWidth:POLarity {NEGative|POSitive}

TRIGger: A: PULSEWidth: POLarity?

**Arguments** NEGative specifies a negative pulse.

POSitive specifies a positive pulse.

**Examples** TRIGGER:A:PULSEWIDTH:POLARITY NEGATIVE sets the pulse polarity to

negative.

TRIGGER: A: PULSEWIDTH: POLARITY? might return

:TRIGGER:A:WIDTH:POLARITY POSITIVE indicating a positive pulse.

#### TRIGger: A: PULSEWidth: SOUrce

Sets or returns the source for the pulse-width trigger.

**Group** Trigger

Syntax TRIGger:A:PULSEWidth:SOUrce {CH1|CH2|CH3|CH4|LINE|EXT}

TRIGger: A: PULSEWidth: SOUrce?

**Arguments** CH1-CH4 specifies an analog input channel as the A edge trigger source.

EXT specifies an external trigger using the Aux In connector located on the front

panel of the oscilloscope.

LINE specifies AC line voltage.

**Examples** TRIGGER:A:PULSEWIDTH:SOURCE CH1 sets channel 1 as the pulse width source.

TRIGGER: A: PULSEWIDTH: SOURCE? might return: TRIGGER: A: PULSEWIDTH:

SOURCE CH1 indicating that channel 1 is the pulse width source.

#### TRIGger: A: PULSEWidth: WHEn

Sets or returns whether to trigger on a pulse that meets, falls outside, or within

the specified range of limits.

**Group** Trigger

Syntax TRIGger:A:PULSEWidth:WHEn {LESSthan|than|EQual|UNEQual}

TRIGger: A: PULSEWidth: WHEn?

**Related Commands** TRIGger:A:PULSEWidth:WIDth

#### **Arguments**

LESSthan argument sets the oscilloscope to trigger if a pulse is detected with width less than the time set by the TRIGger:A:PULSEWidth:WIDth command.

than argument sets the oscilloscope to trigger if a pulse is detected with width than the time set by the TRIGger:A:PULSEWidth:WIDth command.

EQUal argument sets the oscilloscope to trigger if a pulse is detected with width equal to the time period specified in TRIGger:A:PULSEWidth:WIDth within a  $\pm 5\%$  tolerance.

NOTEQual argument sets the oscilloscope to trigger if a pulse is detected with width greater than or less than (but not equal) the time period specified in TRIGger:A:PULSEWidth:WIDth within a ±5% tolerance.

#### **Examples**

TRIGGER: A: PULSEWIDTH: WHEN LESSTHAN specifies that the duration of the A pulse will fall within defined high and low limits.

TRIGGER:A:PULSEWIDTH:WHEN? might return:TRIGGER:A:PULSEWIDTH:WHEN THAN indicating the conditions for generating a width trigger.

#### TRIGger: A: PULSEWidth: WIDth

Sets or returns the width setting for the pulse width trigger.

**Group** Trigger

Syntax TRIGger:A:PULSEWidth:WIDth <NR3>

TRIGger:A:PULSEWidth:WIDth?

Related Commands TRIGger: A:PULSEWidth: WHEn

**Arguments** <NR3> specifies the pulse width in seconds.

**Examples** TRIGGER:A:PULSEWIDTH:WIDTH 5.0E-6 sets the pulse width to 5 µs.

TRIGGER: A: PULSEWIDTH: WIDTH? might return: TRIGGER: A: PULSEWIDTH:

WIDTH 2.0000E-9 indicating that the pulse width is set to 2 ns.

## TRIGger:A:RUNT? (Query Only)

Returns the current A runt trigger parameters.

**Group** Trigger

**Syntax** TRIGger:A:RUNT?

**Examples** TRIGGER: A:RUNT? might return: TRIGGER: A:RUNT: SOURCE CH1; POLARITY

POSITIVE; WHEN OCCURS; WIDTH 4.0000E-9.

### TRIGger: A: RUNT: POLarity

Sets or returns the polarity for the runt trigger.

**Group** Trigger

Syntax TRIGger:A:RUNT:POLarity {EITher|NEGative|POSitive}

TRIGger: A: RUNT: POLarity?

**Arguments** POSitive indicates that the rising edge crosses the low threshold and the falling

edge recrosses the low threshold without either edge ever crossing the high

threshold.

NEGative indicates that the falling edge crosses the high threshold and the rising edge recrosses the high threshold without either edge ever crossing the

low threshold.

EITher triggers on a runt of either polarity.

**Examples** TRIGGER: A: RUNT: POLARITY NEGATIVE specifies that the polarity of the A

pulse runt trigger is negative.

TRIGGER: A: RUNT: POLARITY? might return: TRIGGER: A: RUNT: POLARITY

POSITIVE indicating that the polarity of the A pulse runt trigger is positive.

## TRIGger: A: RUNT: SOUrce

Sets or returns the source for the A runt trigger.

**Group** Trigger

Syntax TRIGger:A:RUNT:SOUrce {CH1|CH2|CH3|CH4}

TRIGger: A: RUNT: SOUrce?

**Arguments** CH1-CH4 specifies the input channel number, depending on the model of the

oscilloscope.

**Examples** TRIGGER:A:RUNT:SOURCE CH4 sets channel 4 as the source for the A pulse

trigger.

TRIGGER:A:RUNT:SOURCE? might return:TRIGGER:A:RUNT:SOURCE CH2

indicating that channel 2 is the source for the A pulse trigger.

#### TRIGger: A: RUNT: WHEn

Sets or returns the type of pulse width the trigger checks for when it detects a runt.

**Group** Trigger

**Syntax** TRIGger:A:RUNT:WHEn {LESSthan|than|EQual|UNEQual|OCCURS}

TRIGger:A:RUNT:WHEn?

Related Commands TRIGger: A:RUNT: WIDth

**Arguments** OCCURS argument specifies a trigger event if a runt of any detectable width occurs.

LESSthan argument sets the oscilloscope to trigger if the a runt pulse is detected with width less than the time set by the TRIGger:A:RUNT:WIDth command.

than argument sets the oscilloscope to trigger if the a runt pulse is detected with width than the time set by the TRIGger:A:RUNT:WIDth command.

EQUal argument sets the oscilloscope to trigger if a runt pulse is detected with width equal to the time period specified in TRIGger:A:RUNT:WIDth within a  $\pm 5\%$  tolerance.

NOTEQual argument sets the oscilloscope to trigger if a runt pulse is detected with width greater than or less than (but not equal to) the time period specified in TRIGger:A:RUNT:WIDth within a  $\pm 5\%$  tolerance.

**Examples** TRIGGER: A: RUNT: WHEN THAN sets the runt trigger to occur when the oscilloscope detects a runt in a pulse wider than the specified width.

TRIGGER:A:RUNT:WHEN? might return :TRIGGER:A:PULSE:RUNT:WHEN OCCURS indicating that a runt trigger will occur if the oscilloscope detects a runt of any detectable width.

# TRIGger: A: RUNT: WIDth

Sets or returns the width for a runt trigger.

**Group** Trigger

Syntax TRIGger:A:RUNT:WIDth <NR3>

TRIGger:A:RUNT:WIDth?

Related Commands TRIGger: A:RUNT: WHEn

**Arguments** <NR3> specifies the minimum width, in seconds.

**Examples** TRIGGER: A: RUNT: WIDTH 15E-6 sets the minimum width of the pulse runt

trigger to 15 µs.

TRIGGER:A:RUNT:WIDTH? might return :TRIGGER:A:PULSE:RUNT:WIDTH 2.0000E-09 indicating that the minimum width of a pulse runt trigger is 2 ns.

## TRIGger: A:SETHold? (Query Only)

Returns the clock edge polarity, voltage threshold and source input; data voltage threshold and source; and both setup and hold times for setup and hold violation triggering.

**Group** Trigger

**Syntax** TRIGger:A:SETHold?

**Examples** TRIGGER:A:SETHOLD? might return

:TRIGGER:A:SETHOLD:CLOCK:SOURCE CH1;EDGE RISE;THRESHOLD 100.0000E-3;:TRIGGER:A:SETHOLD:DATA:SOURCE CH2;THRESHOLD 80.0000E-3;:TRIGGER:A:SETHOLD:HOLDTIME 20.0000E-9;SETTIME

8.0000E-9

## TRIGger:A:SETHold:CLOCk? (Query Only)

Returns the clock edge polarity, voltage threshold, and source input for setup and hold triggering.

**Group** Trigger

Syntax TRIGger:A:SETHold:CLOCk?

**Examples** TRIGGER:A:SETHOLD:CLOCK? might return

:TRIGGER:A:SETHOLD:CLOCK:SOURCE EXT;EDGE FALL;THRESHOLD

1.4000

## TRIGger: A: SETHold: CLOCk: EDGE

Sets or returns the clock edge polarity for setup and hold triggering.

**Group** Trigger

Syntax TRIGger:A:SETHold:CLOCk:EDGE {FALL|RISe}

TRIGger:A:SETHold:CLOCk:EDGE?

**Arguments** FALL specifies polarity as the clock falling edge.

RISe specifies polarity as the clock rising edge.

**Examples** TRIGGER: A: SETHOLD: CLOCK: EDGE RISE specifies the polarity as the clock

rising edge.

TRIGGER:A:SETHOLD:CLOCK:EDGE? might return:TRIGGER:A:SETHOLD:CLOCK:EDGE RISE indicating that polarity is specified as the clock rising edge.

#### TRIGger: A: SETHold: CLOCk: SOUrce

Sets or returns the clock source for the setup and hold triggering.

**Group** Trigger

**Syntax** TRIGger:A:SETHold:CLOCk:SOUrce

{CH1|CH2|CH3|CH4|D0|D1|D2|D3|D4|D5|D6|D7|D8|D9|D10|D11|D12|D13|D14|D15|

TRIGger:A:SETHold:CLOCk:SOUrce?

Related Commands TRIGger: A:SETHold: DATa: SOUrce

**Arguments** CH1-CH4 or D0-D15 specifies the input channel number. D0-D15 is only for

MSO models.

AUX or EXT specifies an external trigger using the Aux Input connector located

on the front panel of the oscilloscope.

**Examples** TRIGGER: A: SETHOLD: CLOCK: SOURCE CH1 specifies channel 1 as the clock

input for setup and hold input.

TRIGGER: A: SETHOLD: CLOCK: SOURCE? might return: TRIGGER: A: SETHOLD: CLOCK: SOURCE CH4 indicating that channel 4 is the clock source for the setup

and hold trigger input.

### TRIGger: A: SETHold: CLOCk: THReshold

Sets or returns the clock voltage threshold for the setup and hold trigger.

**Group** Trigger

Syntax TRIGger:A:SETHold:CLOCk:THReshold {<NR3>|TTL}

TRIGger:A:SETHold:CLOCk:THReshold?

**Arguments** TTL specifies a preset TTL high level of 1.4 V.

<NR3> is the clock level, in volts.

**Examples** TRIGGER: A: SETHOLD: CLOCK: THRESHOLD TTL specifies the preset TTL value

of 1.4 V as the clock threshold for the setup and hold trigger.

TRIGGER: A: SETHOLD: CLOCK: THRESHOLD? might return

:TRIGGER:A:LOGIC:SETHOLD:CLOCK:THRESHOLD 1.2000E+00 indicating that the clock threshold for the setup and hold trigger is 1.2 V.

## TRIGger:A:SETHold:DATa? (Query Only)

Returns the voltage threshold and data source for the setup and hold trigger.

**Group** Trigger

**Syntax** TRIGger:A:SETHold:DATa?

#### Related Commands TRIGger: A:SETHold: CLOCk?

**Examples** TRIGGER:A:SETHOLD:DATA? might return

:TRIGGER:A:SETHOLD:DATA:SOURCE CH2;THRESHOLD 80.0000E-3

#### TRIGger: A: SETHold: DATa: SOUrce

Sets or returns the data source for the setup and hold trigger. You cannot specify the same source for both clock and data.

For DPO models, you can specify only a single data source. Data sources for DPO models may be one of CH1-CH4 or the Auxin port (EXT or AUX).

For MSO models, you can specify any combination of CH1-CH4 and D0-D15 as the data sources.

#### **Group** Trigger

#### **Syntax** DPO Models:

TRIGger:A:SETHold:DATa:SOUrce <wfm>

MSO Models:

TRIGger:A:SETHold:DATa:SOUrce <wfm>[,<wfm>] [,<wfm>] [,<wfm] [,<

[,<wrm>] [,<wrm>] [,<wrm>]
TRIGger:A:SETHold:DATa:SOUrce?

#### Related Commands TRIGger: A:SETHold: CLOCk: SOUrce

#### **Arguments** DPO Models:

<wfm> specifies the source channel number and is one of CH1-CH4, EXT or AUX. You can specify only one waveform on a DPO.

#### MSO Models:

<wfm> specifies the source channel numbers. Each <wfm> can be one of CH1-CH4 or D0-D15. Auxin (EXT or AUX) is not valid as a data source.

#### Examples

TRIGGER:A:SETHOLD:DATA:SOURCE CH1 sets channel 1 as the data source for the setup and hold trigger.

TRIGGER: A: SETHOLD: DATA: SOURCE? might return

:TRIGGER:A:LOGIC:SETHOLD:DATA:SOURCE CH2 indicating that channel 2 is

the current data source for the setup and hold trigger.

### TRIGger: A: SETHold: DATa: THReshold

Sets or returns the data voltage threshold for setup and hold trigger.

**Group** Trigger

Syntax TRIGger:A:SETHold:DATa:THReshold {<NR3>|TTL}

TRIGger:A:SETHold:DATa:THReshold?

**Arguments** TTL specifies the preset TTL high level of 1.4 V.

<NR3> is the setup and hold data level, in V.

**Examples** TRIGGER: A: SETHOLD: DATA: THRESHOLD TTL specifies the preset high level of

1.4 V as the current data voltage level for the setup and hold trigger.

TRIGGER: A: SETHOLD: DATA: THRESHOLD? might return

:TRIGGER:A:SETHOLD:DATA:THRESHOLD 1.2000E+00 indicating that 1.2 V is the current data voltage level for the setup and hold trigger.

#### TRIGger: A: SETHold: HOLDTime

Sets or returns the hold time for setup and hold violation triggering.

**Group** Trigger

Syntax TRIGger:A:SETHold:HOLDTime <NR3>

TRIGger: A: SETHold: HOLDTime?

**Arguments** <NR3> specifies the hold time setting in seconds. Positive values for hold time

occur after the clock edge. Negative values occur before the clock edge.

**Examples** TRIGGER:A:SETHOLD:HOLDTIME 3.0E-3 sets the hold time for the setup and

hold trigger to 3 ms.

TRIGGER: A: SETHOLD: HOLDTIME? might return

:TRIGGER:A:SETHOLD:HOLDTIME 2.0000E-09 indicating that the current

hold time for the setup and hold trigger is 2 ns.

## TRIGger: A: SETHold: SETTime

Sets or returns the setup time for setup and hold violation triggering.

**Group** Trigger

Syntax TRIGger:A:SETHold:SETTime <NR3>

TRIGger:A:SETHold:SETTime?

**Arguments** <NR3> specifies the setup time for setup and hold violation triggering.

**Examples** TRIGGER: A: SETHOLD: SETTIME 3.0E-6 specifies that the current setup time for

setup and hold trigger is 3 μs.

TRIGGER: A: SETHOLD: SETTIME? might return

:TRIGGER:A:LOGIC:SETHOLD:SETTIME 2.0000E-09 indicating that the

current setup time for setup and hold trigger is 2 ns.

## TRIGger:A:SETHold:THReshold:CH<x>

Sets or queries the threshold for the channel specified by x. Affects all trigger types using the channel.

**Group** Trigger

Syntax TRIGger:A:SETHold:THReshold:CH<x> {<NR3>|ECL|TTL}

TRIGger:A:SETHold:THReshold:CH<x>?

**Arguments** <NR3> specifies the threshold voltage, in volts.

ECL specifies a preset ECL high level of -1.3V.

TTL specifies a preset TTL high level of 1.4V.

**Examples** TRIGGER: A: SETHOLD: THRESHOLD: CH1 1.5 sets the channel 1 threshold

to 1.5 volts.

TRIGGER: A: SETHOLD: THRESHOLD: CH1? might return

TRIGGER: A: SETHOLD: THRESHOLD: CH1 0.0E+0 indicating the

channel 1 threshold is set to 0.0 volts.

## TRIGger:A:SETHold:THReshold:D<x>

Sets the threshold for the selected digital channel. Affects all trigger types using the digital channel.

**Group** Trigger

Syntax TRIGger:A:SETHold:THReshold:D<x> {<NR3>|ECL|TTL}

TRIGger:A:SETHold:THReshold:D<x>?

**Arguments** <NR3> specifies the threshold voltage, in volts.

ECL specifies a preset ECL high level of -1.3V. TTL specifies a preset TTL high level of 1.4V.

**Examples** TRIGGER:A:SETHOLD:THRESHOLD:D1 ECL sets the threshold to ECL levels.

TRIGGER: A: SETHOLD: THRESHOLD: D1? might return

TRIGGER: A: SETHOLD: THRESHOLD: D1 -1.3000 indicating the

threshold is set to -1.3 volts.

#### TRIGger:A{:TRANsition|:RISEFall}? (Query Only)

Returns transition time trigger parameters.

**Group** Trigger

Syntax TRIGger:A{:TRANsition|:RISEFall}?

**Related Commands** TRIGger:A:UPPerthreshold:CH<x>, TRIGger:A:LOWerthreshold:CH<x>

**Examples** TRIGGER: A:: TRANSITION? might return

:TRIGGER:A:TRANSITION:POLARITY POSITIVE;WHEN

SLOWER; DELTATIME 8.0000E-9

## TRIGger:A{:TRANsition|:RISEFall}:DELTatime

Sets or returns the delta time used in calculating the transition value for the transition trigger.

**Group** Trigger

Syntax TRIGger:A{:TRANsition|:RISEFall}:DELTatime <NR3>

TRIGger:A{:TRANsition|:RISEFall}:DELTatime?

**Arguments** <NR3> specifies the delta time, in seconds.

**Examples** TRIGGER: A:TRANSITION: DELTATIME 15E-6 sets the delta time of the

transition trigger to 15 µs.

TRIGGER: A: TRANSITION: DELTATIME? might return: TRIGGER: A

:TRANSITION:DELTATIME 2.0000E-09 indicating that the delta time of the

transition trigger is set to 2 ns.

# TRIGger:A{:TRANsition|:RISEFall}:POLarity

Sets or returns the polarity for the transition trigger.

**Group** Trigger

Syntax TRIGger:A{:TRANsition|:RISEFall}:POLarity

{EITher|NEGative|POSitive}

TRIGger:A{:TRANsition|:RISEFall}:POLarity?

**Arguments** POSitive indicates that a pulse edge must traverse from the lower (most

negative) to higher (most positive) level for transition triggering to occur.

NEGative indicates that a pulse edge must traverse from the upper (most positive)

to lower (most negative) level for transition triggering to occur.

EITher indicates either positive or negative polarity.

**Examples** TRIGGER: A:TRANSITION: POLARITY NEGATIVE sets the transition polarity to

negative.

TRIGGER:A:TRANSITION:POLARITY? might return :TRIGGER:A:

TRANSITION: POLARITY EITHER indicating that the polarity can be either

positive or negative.

## TRIGger:A{:TRANsition|:RISEFall}:SOUrce

Sets or returns the source for transition trigger.

**Group** Trigger

Syntax TRIGger:A{:TRANsition|:RISEFall}:SOUrce {CH1|CH2|CH3|CH4}

TRIGger:A{:TRANsition|:RISEFall}:SOurce?

**Arguments** CH1-CH4 specifies one of the input channels.

**Examples** TRIGGER: A:TRANSITION: SOURCE CH4 sets channel 4 as the source for the

transition trigger.

TRIGGER: A: TRANSITION: SOURCE? might return: TRIGGER: A: TRANSITION: SOURCE CH2 indicating that channel 2 is the source for the A transition trigger.

### TRIGger:A{:TRANsition|:RISEFall}:WHEn

Sets or returns whether to check for a transitioning signal that is faster or slower than the specified delta time.

**Group** Trigger

Syntax TRIGger:A{:TRANsition|:RISEFall}:WHEn

{SLOWer|FASTer|EQual|UNEQual}

TRIGger:A{:TRANsition|:RISEFall}:WHEn?

**Arguments** FASTer sets the trigger to occur when the signal transition time is faster than the

time set by TRIGger:A{:TRANsition|:RISEFall}:DELTatime.

SLOWer sets the trigger to occur when the signal transition time is slower than the

time set by.TRIGger:A{:TRANsition|:RISEFall}:DELTatime.

EQual sets the trigger to occur when the signal transition time is equal to the time

set by TRIGger:A{:TRANsition|:RISEFall}:DELTatime.

UNEQual sets the trigger to occur when the signal transition time is not equal to

the time set by TRIGger:A{:TRANsition|:RISEFall}:DELTatime.

**Examples** TRIGGER: A:TRANSITION: WHEN SLOWER sets the trigger to occur

when the signal transition time is slower than the time set by the TRIGGer:A{:TRANsition|:RISEFall}:DELTatime command.

TRIGGER: A: TRANSITION: WHEN? might return: TRIGGER: A: TRANSITION:

WHEN FASTER

## TRIGger:A:TYPe

Sets or returns the type of A trigger. Once you have set the trigger type, you may also need to identify the associated trigger class. For details on selecting Logic and Pulse trigger classes, see TRIGger:A:LOGIc:CLAss and TRIGger:A:PULse:CLAss respectively.

**Group** Trigger

Syntax TRIGger:A:TYPe {EDGe|LOGic|PULSe|BUS|VIDeo}

TRIGger:A:TYPe?

**Related Commands** TRIGger:A:EDGE?, TRIGger:A:LOGIc:CLAss, TRIGger:A:PULse:CLAss

**Arguments** EDGe is the default trigger. A trigger event occurs when a signal passes through a specified voltage level in a specified direction and is controlled by the

TRIGger: A:EDGE? commands.

LOGic specifies that a trigger occurs when specified conditions are met and is controlled by the TRIGger:A:LOGIc? commands. This trigger type is equivalent to the logic trigger and to the setup and hold trigger found in the user interface.

PULSe specifies that a trigger occurs when a specified pulse is found and is controlled by the TRIGger:A:PULse? commands. This trigger type is equivalent to the pulse width, runt, and rise/fall time triggers found in the user interface.

BUS specifies that a trigger occurs when a communications signal is found. Supports CAN, I<sup>2</sup>C, SPI, and RS-232 communications signals.

VIDeo specifies that the trigger occurs when a video signal is found.

**Examples** TRIGGER: A: TYPE EDGE sets the A trigger type to EDGE.

TRIGGER:A:TYPE? might return:TRIGGER:A:TYPE PULSE indicating that the A trigger type is a pulse trigger.

TRIGger: A: UPPerthreshold: CH<x>

Sets the upper threshold for channel <x>, where x is the channel number. Each channel can have an independent level. Used only for runt and slew rate trigger types.

**Group** Trigger

Syntax TRIGger:A:UPPerthreshold:CH<x> {<NR3>|ECL|TTL}

TRIGger:A:UPPerthreshold:CH<x>?

**Arguments** <NR3> is the threshold level in volts.

ECL specifies a preset ECL high level of -1.3V.

TTL specifies a preset TTL high level of 1.4V.

**Examples** TRIGGER:A:UPPERTHRESHOLD:CH2 50E-3 sets the upper limit of the pulse

runt trigger to 50 mV for channel 2.

TRIGGER: A: UPPERTHRESHOLD: CH2? might return: TRIGGER: A:

UPPERTHRESHOLD: CH2 1.2000E-01 indicating that the upper limit of the pulse

runt trigger is set to 120 mV.

## TRIGger:A:VIDeo? (Query Only)

Returns the A trigger video parameters.

**Group** Trigger

**Syntax** TRIGger:A:VIDeo?

**Examples** TRIGGER:A:VIDEO? might return :TRIGGER:A:VIDEO:POLARITY

POSITIVE; SOURCE CH1; STANDARD NTSC; SYNC

ALLLINES; HOLDOFF: FIELD 0.0000; :TRIGGER: A: VIDEO: CUSTOM: FORMAT PROGRESSIVE; SCANRATE15K; :TRIGGER: A: VIDEO: LINE 1; HDTV: FORMAT

HD1080I60

#### TRIGger:A:VIDeo:CUSTom{:FORMat|:TYPE}

Sets or returns the video trigger format. Use this command only when the video

format is set to custom.

**Conditions** This command requires a DPO4VID application module.

**Group** Trigger

Syntax TRIGger:A:VIDeo:CUSTom{:FORMat|:TYPE}

{INTERLAced|PROGressive}

TRIGger:A:VIDeo:CUSTom{:FORMat|:TYPE}?

**Arguments** INTERLACED argument sets the format for interlaced video lines.

PROGressive argument sets the format for progressive video lines.

**Examples** TRIGGER:A:VIDEO:CUSTOM:FORMAT PROGRESSIVE sets the custom format for

the A video trigger to progressive lines.

TRIGGER:A:VIDEO:CUSTOM:FORMAT? might return:TRIGGER:A:VIDEO:CUSTOM:FORMAT INTERLACED indicating that interlaced is selected as the

custom format for the A video trigger.

## TRIGger: A: VIDeo: CUSTom: LINEPeriod

Sets or queries the line period for the standard under test. Use this command only when the video format is set to custom.

**Conditions** This command requires a DPO4VID application module.

**Group** Trigger

Syntax TRIGger:A:VIDeo:CUSTom:LINEPeriod <NR3>

TRIGger:A:VIDeo:CUSTom:LINEPeriod?

**Arguments** <NR3> is the custom video line period.

**Examples** TRIGGER:A:VIDEO:CUSTOM:LINEPERIOD 50.5E-6 sets the video line period

to 50.5 µs.

TRIGGER: A: VIDEO: CUSTOM: LINEPERIOD? might return

TRIGGER: A: VIDEO: CUSTOM: LINEPERIOD 63.5600E-6 indicating

the video line period is set to 63.56 µs.

#### TRIGger: A: VIDeo: CUSTom: SCAN

Sets or returns the horizontal line scan rate of the A video trigger. Use this command only when the video format is set to custom.

**Conditions** This command requires a DPO4VID application module.

**Group** Trigger

Syntax TRIGger:A:VIDeo:CUSTom:SCAN

{RATE15K|RATE20K|RATE25K|RATE35K|RATE50K}

TRIGger:A:VIDeo:CUSTom:SCAN?

**Arguments** RATE15 sets the range of the video line scan rate to 15 kHz through 20 kHz. This

is the standard broadcast rate.

RATE20 sets the range of the video line scan rate to 20 kHz through 25 kHz.

RATE25 sets the range of the video line scan rate to 25 kHz through 35 kHz

RATE35 sets the range of the video line scan rate to 35 kHz through 50 kHz

RATE50 sets the range of the video line scan rate to 50 kHz through 65 kHz

**Examples** TRIGGER: A: VIDEO: CUSTOM: SCAN RATE15 sets the scan rate of the A trigger

custom video to Rate 1, which is 15 kHz to 20 kHz (standard broadcast rate).

TRIGGER: A: VIDEO: CUSTOM: SCAN? might return: TRIGGER: A: VIDEO:

CUSTOM: SCAN RATE 20 indicating that the video line rate for the A trigger custom

video is set to Rate20, which is 20 kHz to 25 kHz.

TRIGger: A: VIDeo: CUSTom: SYNCInterval

Sets or queries the sync interval for the standard under test. This is only required for BiLevel Custom. Use this command only when the video format is set to

custom.

**Conditions** This command requires a DPO4VID application module.

**Group** Trigger

Syntax TRIGger:A:VIDeo:CUSTom:SYNCInterval <NR3>

TRIGger:A:VIDeo:CUSTom:SYNCInterval?

**Arguments** <NR3> is the sync interval.

**Examples** TRIGGER:A:VIDEO:CUSTOM:SYNCINTERVAL 4.0E-6 sets the sync interval is

set to 4.0 µs.

TRIGGER:A:VIDEO:CUSTOM:SYNCINTERVAL? might return

TRIGGER: A: VIDEO: CUSTOM: SYNCINTERVAL 4.7200E-6 indicating the sync

interval is set to 4.72 µs.

## TRIGger: A: VIDeo: HDtv: FORMat

Sets or returns the HDTV video signal format on which to trigger.

**Conditions** This command requires a DPO4VID application module.

**Group** Trigger

**Syntax** TRIGger:A:VIDeo:HDtv:FORMat

{HD1080P24|HD720P60|HD480P60|HD1080I50|HD1080P25|

HD1080I60|HD1080PSF24}

TRIGger:A:VIDeo:HDtv:FORMat?

#### **Arguments** Table 2-43: Available HDTV formats

HDTV format	Description
1080i50	1125 Lines (1080 active), 1920 x 1080 pixel, interlaced, 60 fps
1080i60	1125 lines (1080 active), 1920 x 1080 pixel, interlaced, 50 fps
1080p24	1125 lines (1080 active), 1920 x 1080 pixel, progressive, 24 fps
1080p25	1125 lines (1080 active), 1920 x 1080 pixel, progressive, 25 fps
1080sf24	1125 Lines (1080 active), 1920 x 1080 pixel, progressive (sF), 24 fps
720p60	750 lines (720 active), 1280 x 720 pixel, progressive, 60 fps
480p60	525 lines (480 active), 640 or 704 x 480 pixel, progressive, 60 fps

## TRIGger: A: VIDeo: HOLDoff: FIELD

Sets or returns the video trigger holdoff in terms of video fields.

**Conditions** This command requires a DPO4VID application module.

Syntax TRIGger:A:VIDeo:HOLDoff:FIELD <NR3>

TRIGger:A:VIDeo:HOLDoff:FIELD?

**Arguments** <NR3> argument is a real number from 0.0 to 8.5 in increments of 0.5. The

argument sets the number of fields that the oscilloscope waits before rearming

the video trigger.

**Examples** TRIGGER:A:VIDEO:HOLDOFF:FIELD? might return

:TRIGger:A:VIDeo:HOLdoff:FIELD 5 indicating that the oscilloscope is set

to wait 5 video fields before rearming the trigger.

TRIGGER: A: VIDEO: HOLDOFF: FIELD 4.5 sets the oscilloscope to wait 4.5 video

fields before rearming the trigger.

### TRIGger: A: VIDeo: LINE

Sets or returns the video line number on which the oscilloscope triggers. Use the TRIGger:A:VIDeo{:SYNC|:FIELD} command to actually trigger the oscilloscope on the line that you specify with this command.

**Conditions** This command requires a DPO4VID application module.

**Group** Trigger

Syntax TRIGger:A:VIDeo:LINE <NR1>

TRIGger:A:VIDeo:LINE?

Related Commands TRIGger: A: VIDeo {:SYNC|:FIELD}

Arguments <NR

<NR1> argument is an integer that sets the video line number on which the oscilloscope triggers. The following table lists the valid choices, depending on the active video standard.

Table 2-44: Video Line Numbering Ranges

Video Standard	Line Number Range
525/NTSC	1–525
625/PAL, SECAM	1–625
SECAM	1–625

TRIGGER: A: VIDEO: LINE 23 sets the oscilloscope to trigger on the line 23. **Examples** 

TRIGGER: A: VIDEO: LINE? might return: TRIGGER: A: VIDEO: LINE 10

indicating that the oscilloscope is set to trigger on line 10.

# TRIGger: A: VIDeo: POLarity

Sets or returns the polarity of the A video trigger.

**Conditions** This command requires a DPO4VID application module.

Trigger Group

TRIGger:A:VIDeo:POLarity {NEGative|POSitive} **Syntax** 

TRIGger:A:VIDeo:POLarity?

**Arguments** POSitive argument sets the oscilloscope to trigger on a positive video sync pulse.

NEGative argument sets the oscilloscope to trigger on a negative video sync

pulse.

**Examples** TRIGGER: A: VIDEO: POLARITY NEGATIVE sets the oscilloscope to trigger on a

negative video pulse.

TRIGGER: A: VIDEO: POLARITY? might return: TRIGGEr: A: VIDEO: POLARITY

POSITIVE indicating that the oscilloscope is set to trigger on a positive video

sync pulse.

## TRIGger: A: VIDeo: SOUrce

Sets or returns the source for the A video trigger.

Group Trigger

TRIGger:A:VIDeo:SOUrce {CH1|CH2|CH3|CH4| **Syntax** 

D0|D1|D2|D3|D4|D5|D6|D7|D8|D9|D10|D11|D12|D13|D14|D15}

TRIGger: A: VIDeo: SOUrce?

**Arguments** CH1-CH4 or D0-D15 specifies the input channel to use as the A video trigger. **Examples** TRIGGER: A: VIDEO: SOURCE CH1 sets the source for A video trigger to Channel 1.

TRIGGER:A:VIDEO:SOURCE? might return :TRIGGEr:A:VIDeo:SOURCE CH2

indicating that the source for the A video trigger is set to Channel 2.

### TRIGger: A: VIDeo: STANdard

Sets or returns the standard for the video trigger.

**Group** Trigger

Syntax TRIGger:A:VIDeo:STANdard {NTSc|PAL|SECAM|CUSTom|HDtv}

TRIGger:A:VIDeo:STANdard?

**Arguments** NTSc sets the oscilloscope to trigger on video signals that meet the NTSC

525/60/2:1 standard (a line rate of 525 lines per frame and a field rate of 60 Hz).

PAL sets the oscilloscope to trigger on video signals that meet the NTSC 625/50/2:1 standard (a line rate of 625 lines per frame and a field rate of 50 Hz).

SECAM sets the oscilloscope to trigger on video signals that meet the SECAM

standard.

CUSTom sets the oscilloscope to trigger on video horizontal scan rate parameters

defined by TRIGger: A: VIDeo: CUSTom: SCAN command.

HDtv sets the oscilloscope to trigger on HDTV video signals that meet standards

defined by the TRIGger: A: VIDeo: HDtv: FORMat command.

**Examples** TRIGGER: A: VIDEO: STANDARD NTSC sets the oscilloscope to trigger on

NTSC-standard video signals.

TRIGGER: A: VIDEO: STANDARD? might return :TRIGGER: A: VIDEO: STANDARD

HDTV indicating that the oscilloscope is set to trigger on an HDTV format.

# TRIGger:A:VIDeo{:SYNC|:FIELD}

Sets or returns the video field or line that the trigger detects.

**Group** Trigger

Syntax TRIGger:A:VIDeo{:SYNC|:FIELD}

{ODD|EVEN|ALLFields|ALLLines|NUMERic}

TRIGger:A:VIDeo{:SYNC|:FIELD}?

**Arguments** ODD argument sets the oscilloscope to trigger on interlaced video odd fields.

EVEN argument sets the oscilloscope to trigger on interlaced video even fields.

ALLFields argument sets the oscilloscope to trigger on all fields.

ALLLines argument sets the oscilloscope to trigger on all video lines.

NUMERic argument sets the oscilloscope to trigger on the video signal line specified by the TRIGger: A: VIDeo: LINE command.

**Examples** 

TRIGGER:A:VIDEO:FIELD EVEN sets the A video trigger so that it will trigger

on even fields.

TRIGGER:A:VIDEO:FIELD? might return :TRIGGER:A:VIDEO:FIELD ALLFIELDS indicating that the A video will trigger on all video fields.

TRIGger:B

Sets the B trigger level to 50% of minimum and maximum. The query form of this command returns the B trigger parameters. This command is similar to selecting B Event (Delayed) Trigger Setup from the Trig menu and then viewing

the current setups.

**Group** Trigger

Syntax TRIGger:B SETLevel

TRIGger:B?

Related Commands TRIGger:A

**Arguments** SETLevel sets the B trigger level to 50% of MIN and MAX.

**Examples** TRIGGER: B SETLEVEL sets the B trigger level to 50% of MIN and MAX.

TRIGGER:B? might return the following B trigger parameters: :TRIGGER:B:STATE 0;TYPE EDGE; LEVEL -220.0000E-3;BY

TIME; EDGE: SOURCE CH1; SLOPE RISE; COUPLING DC; :TRIGGER: B:TIME

16.0000E-9; EVENTS: COUNT 2

TRIGger:B:BY

Selects or returns whether the B trigger occurs after a specified number of events

or a specified period of time after the A trigger.

Syntax TRIGger:B:BY {EVENTS|TIMe}

TRIGger:B:BY?

Related Commands TRIGger:B:EVENTS:COUNt, TRIGger:B:TIMe, ,

**Arguments** EVENTS sets the B trigger to take place following a set number of trigger

events after the A trigger occurs. The number of events is specified by

TRIGger:B:EVENTS:COUNt.

TIMe sets the B trigger to occur a set time after the A trigger event. The time

period is specified by TRIGger:B:TIMe.

**Examples** TRIGGER:B:BY TIME sets the B trigger to occur at a set time after the A trigger

event.

TRIGGER:B:BY? might return:TRIGGER:B:BY EVENTS indicating that the B trigger takes place following a set number of trigger events after the A trigger

occurs.

### TRIGger:B:EDGE? (Query Only)

Returns the source, slope, and coupling for B trigger.

**Group** Trigger

**Syntax** TRIGger:B:EDGE?

Related Commands TRIGger:B:EDGE:COUPling, TRIGger:B:EDGE:SLOpe, TRIGger:B:EDGE:

**SOUrce** 

**Examples** TRIGGER:B:EDGE? might return :TRIGGER:B:EDGE:SOURCE CH1; SLOPE

RISE; COUPLING DC

## TRIGger:B:EDGE:COUPling

Sets or returns the type of coupling for the B trigger.

**Group** Trigger

**Syntax** TRIGger:B:EDGE:COUPling {DC|HFRej|LFRej|NOISErej}

TRIGger:B:EDGE:COUPling?

**Related Commands** TRIGger:B:EDGE?

**Arguments** DC selects DC trigger coupling.

HFRej selects high-frequency reject coupling.

LFRej selects low-frequency reject coupling.

NOISErej selects DC low sensitivity.

**Examples** TRIGGER:B:EDGE:COUPLING DC selects DC for the B trigger coupling.

TRIGGER:B:EDGE:COUPLING? might return:TRIGGER:B:EDGE:COUPLING

ATRIGGER for the B trigger coupling.

### TRIGger:B:EDGE:SLOpe

Sets or returns the slope for the B trigger.

**Group** Trigger

Syntax TRIGger:B:EDGE:SLOpe {RISe|FALL}

TRIGger:B:EDGE:SLOpe?

**Related Commands** TRIGger:B:EDGE?

**Arguments** RISe triggers on the rising or positive edge of a signal.

FALL triggers on the falling or negative edge of a signal.

**Examples** TRIGGER:B:EDGE:SLOPE FALL sets the B edge trigger to occur on the falling

slope.

TRIGGER:B:EDGE:SLOPE? might return :TRIGGER:B:EDGE:SLOPE RISE

indicating that the B edge trigger occurs on the rising slope.

# TRIGger:B:EDGE:SOUrce

Sets or returns the source for the B trigger.

Syntax TRIGger:B:EDGE:SOUrce {CH<x>|EXT|LINE}

TRIGger:B:EDGE:SOUrce?

**Related Commands** TRIGger:B:EDGE?

**Arguments** CH<x> specifies one of the input channels as the B trigger source.

EXT specifies an external trigger (using the Aux In connector, located on the front

panel of the oscilloscope) as the B trigger source.

LINE specifies the power line as the B trigger source.

**Examples** TRIGGER:B:EDGE:SOURCE CH4 sets channel 4 as the input source for the B

trigger.

TRIGGER:B:EDGE:SOURCE? might return :TRIGGER:B:EDGE:SOURCE CH1

indicating that the current input source for the B trigger is channel 1.

## TRIGger:B:EVENTS? (Query Only)

Returns the current B trigger events parameter.

**Group** Trigger

**Syntax** TRIGger:B:EVENTS?

Related Commands TRIGger:B:EVENTS:COUNt

**Examples** TRIGGER:B:EVENTS? might return

:TRIGGER:B:EVENTS:COUNT 2

indicating that 2 events must occur before the B trigger occurs.

## TRIGger:B:EVENTS:COUNt

Sets or returns the number of events that must occur before the B trigger (when TRIG:DELay:BY is set to EVENTS).

Syntax TRIGger:B:EVENTS:COUNT <NR1>

TRIGger:B:EVENTS:COUNt?

**Related Commands** TRIGger:B:EVENTS?

**Arguments** <NR1> is the number of B trigger events, which can range from 1 to 10,000,000.

**Examples** TRIGGER:B:EVENTS:COUNT 4 specifies that the B trigger will occur four trigger

events after the A trigger.

TRIGGER:B:EVENTS:COUNT? might return:TRIGGER:B:EVENTS:COUNT 2 indicating that two events must occur after the A trigger before the B trigger

can occur.

TRIGger:B:LEVel

Sets or returns the level for the B trigger.

**Group** Trigger

Syntax TRIGger:B:LEVel {TTL|<NR3>}

TRIGger:B:LEVel?

Related Commands TRIGger:A:LEVel, TRIGger:B; TRIGger:B:EDGE:SOUrce

**Arguments** TTL specifies a preset TTL high level of 1.4 V.

<NR3> is the B trigger level, in volts.

**Examples** TRIGGER: B: LEVEL TTL sets the B trigger level to 1.4 V.

TRIGGER:B:LEVEL? might return:TRIGGER:B:LEVEL 173.0000E-03

indicating that the B trigger level is currently set at 173 mV.

TRIGger:B:LEVel:CH<x>

Sets or returns the B trigger level for channel <x>, where x is the channel number. Each Channel can have an independent Level.

Syntax TRIGger:B:LEVel:CH<x> {ECL|TTL|<NR3>}

TRIGger:B:LEVel:CH<x>?

**Arguments** ECL specifies a preset ECL high level of -1.3V.

TTL specifies a preset TTL high level of 1.4V.

<NR3> specifies the trigger level in user units (usually volts).

**Examples** TRIGGER:B:LEVEL:CH2? might return :TRIGGER:B:LEVEL:CH2

1.3000E+00 indicating that the B edge trigger is set to 1.3 V for channel 2.

TRIGGER:B:LEVEL:CH3 TTL sets the B edge trigger to TTL high level for

channel 3.

## TRIGger:B:LEVel:D<x>

Sets or returns the B trigger level for digital channel <x>, where x is the channel

number. Each channel can have an independent level.

**Group** Trigger

Syntax TRIGger:B:LEVel:D<x> {ECL|TTL|<NR3>}

TRIGger:B:LEVel:D<x>?

**Arguments** ECL specifies a preset ECL high level of -1.3V.

TTL specifies a preset TTL high level of 1.4V.

<NR3> specifies the trigger level in user units (usually volts).

### TRIGger:B:LOWerthreshold:CH<x>

Sets or returns the B trigger lower threshold for the channel <x>, where x is the channel number. Each channel can have an independent level. Used in runt and slew rate triggers as the lower threshold. Used for all other trigger types as the single level/threshold.

**Group** Trigger

Syntax TRIGger:B:LOWerthreshold:CH<x> {ECL|TTL|<NR3>}

TRIGger:B:LOWerthreshold:CH<x>?

**Arguments** ECL specifies a preset ECL high level of -1.3V.

TTL specifies a preset TTL high level of 1.4V.

<NR3> is the threshold level, in volts.

## TRIGger:B:LOWerthreshold:D<x>

Sets or queries the lower threshold for the digital channel selected. Each channel can have an independent level. Used in runt and slew rate as the lower threshold. Used for all other trigger types as the single level/threshold.

**Group** Trigger

Syntax TRIGger:B:LOWerthreshold:D<x> {<NR3>|ECL|TTL}

TRIGger:B:LOWerthreshold:D<x>?

**Arguments** <NR3> specifies the threshold in volts.

ECL specifies a preset ECL high level of -1.3V.

TTL specifies a preset TTL high level of 1.4V.

**Examples** TRIGGER:B:LOWERTHRESHOLD:D1? might return

TRIGGER:B:LOWERTHRESHOLD:D1 1.4000 indicating the threshold is set to

1.4 volts.

## TRIGger:B:STATE

Sets or returns the state of B trigger activity. If the B trigger state is on, the B trigger is part of the triggering sequence. If the B trigger state is off, then only

the A trigger causes the trigger event.

**Group** Trigger

Syntax TRIGger:B:STATE {ON|OFF|<NR1>}

TRIGger:B:STATE?

**Related Commands** TRIGger:A:MODe

**Arguments** ON specifies that the B trigger is active and in causes trigger events conjunction

with the A trigger.

OFF specifies that only the A trigger causes trigger events.

<NR1> a 0 turns off the B trigger; any other value activates the B trigger.

**Examples** TRIGGER: B: STATE ON sets the B trigger to active, making it capable of causing

trigger events.

TRIGGER:B:STATE? might return:TRIGGER:B:STATE Oindicating that the B

trigger is inactive and that only the A trigger causes trigger events.

TRIGger:B:TIMe

Sets or returns B trigger delay time. The B Trigger time applies only if

TRIGger:B:BY is set to TIMe.

**Group** Trigger

Syntax TRIGger:B:TIMe <NR3>

TRIGger:B:TIMe?

Related Commands TRIGger:B:BY, TRIGger:B:EVENTS:COUNt

**Arguments** <NR3> is the B trigger delay time in seconds.

**Examples** TRIGGER: B:TIME 4E-6 sets the B trigger delay time to 4 µs.

TRIGGER:B:TIME? might return:TRIGGER:B:TIME 16.0000E-9 indicating

that the B trigger time is set to 16 ns.

TRIGger:B:TYPe

Sets or returns the type of B trigger. The only supported B trigger type is EDGE.

**Group** Trigger

Syntax TRIGger:B:TYPe EDGE

TRIGger:B:TYPe?

Related Commands TRIGger: A:TYPe

**Arguments** EDGE sets the B trigger type to edge.

**Examples** TRIGGER:B:TYPE EDGE sets the B trigger type to edge.

TRIGGER:B:TYPE? might return :TRIGGER:B:TYPE EDGE.

### TRIGger:B:UPPerthreshold:CH<x>

Sets the upper threshold for the channel selected. Each channel can have an

independent level.

**Group** Trigger

Syntax TRIGger:B:UPPerthreshold:CH<x> {<NR3>|TTL}

TRIGger:B:UPPerthreshold:CH<x>?

**Arguments** TTL specifies a preset TTL high level of 1.4 V.

<NR3> is the clock level, in volts.

# TRIGger: EXTernal? (Query Only)

Returns all external trigger parameters.

**Group** Trigger

**Syntax** TRIGger: EXTernal?

# TRIGger: EXTernal: PRObe

Sets or returns the attenuation factor value of the external probe connector.

**Group** Trigger

Syntax TRIGger:EXTernal:PRObe <NR3>

TRIGger:EXTernal:PRObe?

**Arguments** <NR3> is the attenuation factor of the probe.

**Examples** TRIGGER: EXTERNAL: PROBE? might return: TRIGGER: EXTERNAL: PROBE

1.0E1 for a 10X probe.

## TRIGger:EXTernal:YUNIts? (Query Only)

Returns the external trigger vertical (Y) units value.

**Group** Trigger

**Syntax** TRIGger:EXTernal:YUNIts?

**Examples** TRIGGER: EXTERNAL: YUNITS? might return TRIGGER: EXTERNAL: YUNITS

"V" if the vertical unit is volts.

# TRIGger:FREQuency? (Query Only)

Returns the trigger frequency in hertz if available. If the trigger frequency is not currently available, the IEEE Not A Number (NaN = 99.10E+36) value is returned. The maximum precision of the returned frequency is 12 digits.

**Group** Trigger

Syntax TRIGger: FREQuency?

**Examples** TRIGGER: FREQUENCY? might return TRIGGER: FREQUENCY 99.10+36

indicating that the trigger frequency is not available.

# TRIGger:STATE? (Query Only)

Returns the current state of the triggering system.

**Group** Trigger

**Syntax** TRIGger:STATE?

Related Commands TRIGger:A:MODe

**Returns** ARMED indicates that the oscilloscope is acquiring pretrigger information.

AUTO indicates that the oscilloscope is in the automatic mode and acquires data even in the absence of a trigger.

READY indicates that all pretrigger information has been acquired and that the oscilloscope is ready to accept a trigger.

SAVE indicates that the oscilloscope is in save mode and is not acquiring data.

TRIGGER indicates that the oscilloscope triggered and is acquiring the post trigger

information.

**Examples** TRIGGER: STATE? might return: TRIGGER: STATE ARMED indicating that the

pretrigger data is being acquired.

\*TST? (Query Only)

Tests (self-test) the interface and returns a 0.

**Group** Miscellaneous

Syntax \*TST?

**Examples** \*TST? always returns 0.

**UNLock (No Query Form)** 

Unlocks the front panel. The command is equivalent to LOCk NONe.

**Group** Miscellaneous

Syntax UNLock ALL

Related Commands LOCk

**Arguments** ALL specifies that all front-panel buttons and knobs are unlocked.

**Examples** UNLOCK ALL unlocks all front-panel buttons and knobs.

## **USBDevice:CONFigure**

Enables or disables the rear USB port for use with Pictbridge printers.

Group PictBridge

Syntax USBDevice:CONFigure {DISabled|IMAge|USBTmc}

USBDevice: CONFigure?

**Arguments** DISabled disables the rear USB port.

IMAge enables the rear USB port as an SIC device.

USBTmc enables the rear USB port as a USBTMC device.

**Examples** USBDEVICE: CONFIGURE IMAGE enables the rear USB port as an SIC device

USBDEVICE: CONFIGURE? might return USBDEVICE: CONFIGURE USBT

indicating a USBTMC device.

## **USBTMC?** (Query Only)

Returns the USBTMC information used by the USB hosts to determine the

instrument interfaces.

**Group** Miscellaneous

Syntax USBTMC?

## **USBTMC:PRODUCTID:DECimal? (Query Only)**

This query to returns the USBTMC product ID. The product ID numbers vary

for each instrument family and model.

**Group** Miscellaneous

**Syntax** USBTMC:PRODUCTID:DECimal?

Related Commands USBTMC:PRODUCTID:HEXadecimal?, USBTMC:SERIALnumber?,

USBTMC:VENDORID:DECimal?, USBTMC:VENDORID:HEXadecimal?

**Examples** USBTMC: PRODUCTID: DECIMAL? might return USBTMC: PRODUCTID: DECIMAL

1025, indicating the product ID in decimal is 1025.

### **USBTMC:PRODUCTID:HEXadecimal? (Query Only)**

This query to returns the USBTMC product ID. The product ID numbers vary for each instrument family and model.

**Group** Miscellaneous

**Syntax** USBTMC:PRODUCTID:HEXadecimal?

Related Commands USBTMC:PRODUCTID:DECimal?, USBTMC:SERIALnumber?,

USBTMC: VENDORID: DECimal?, USBTMC: VENDORID: HEXadecimal?

**Examples** USBTMC:PRODUCTID:HEXADECIMAL? might return

USBTMC: PRODUCTID: HEXADECIMAL 0x0401, indicating the product ID

in hexadecimal is 0x0401.

# **USBTMC:SERIALnumber?** (Query Only)

This query returns the instrument serial number.

**Group** Miscellaneous

**Syntax** USBTMC:SERIALnumber?

Related Commands USBTMC:PRODUCTID:DECimal?, USBTMC:PRODUCTID:HEXadecimal?,

USBTMC: VENDORID: DECimal?, USBTMC: VENDORID: HEXadecimal?

**Examples** USBTMC:SERIALNUMBER? might return USBTMC:SERIALNUMBER PQ30003,

indicating the product serial number is PQ30003.

# **USBTMC:VENDORID:DECimal? (Query Only)**

This query returns the USBTMC vendor ID. The Vendor ID for Tektronix is 0x699 or 1689 decimal.

**Group** Miscellaneous

Syntax USBTMC: VENDORID: DECimal?

Related Commands USBTMC:PRODUCTID:DECimal?, USBTMC:PRODUCTID:HEXadecimal?,

USBTMC:SERIALnumber?, USBTMC:VENDORID:HEXadecimal?

Examples USBTMC: VENDORID: DECIMAL? might return USBTMC: VENDORID: DECIMAL

1689, indicating the vendor ID in decimal is 1689.

### **USBTMC:VENDORID:HEXadecimal? (Query Only)**

This query returns the USBTMC vendor ID. The Vendor ID for Tektronix is 0x699 or 1689 decimal.

Group

Miscellaneous

Syntax USBTMC: VENDORID: HEXadecimal?

Related Commands USBTMC:PRODUCTID:DECimal?, USBTMC:PRODUCTID:HEXadecimal?,

USBTMC:SERIALnumber?, USBTMC:VENDORID:DECimal?

**Examples** USBTMC:VENDORID:HEXADECIMAL? might return

USBTMC: VENDORID: HEXADECIMAL 0x0699, indicating the vendor ID in

hexadecimal is 0x0699.

### **VERBose**

Sets or returns the Verbose state that controls the length of keywords on query

responses. Keywords can be both headers and arguments.

**NOTE.** This command does not affect IEEE Std 488.2-1987 Common Commands (those starting with an asterisk). This command does affect the verbose state of both the USBTMC and VXI-11 interfaces. Refer to the Introduction for information.

**Group** Miscellaneous

Syntax VERBose {OFF|ON|<NR1>}

Related Commands HEADer, \*LRN?, SET?

**Arguments** OFF sets the Verbose state to false, which returns minimum-length keywords

for applicable setting queries.

ON sets the Verbose state to true, which returns full-length keywords for applicable

setting queries.

<NR1> a 0 returns minimum-length keywords for applicable setting queries; any

other value returns full-length keywords.

**Examples** VERBOSE ON enables the Verbose state.

VERBOSE? might return: VERB 0 indicating that the Verbose state is disabled.

## \*WAI (No Query Form)

Prevents the oscilloscope from executing further commands or queries until all pending commands that generate an OPC message are complete. This command allows you to synchronize the operation of the oscilloscope with your application program. (See page 3-7, *Synchronization Methods*.)

The \*WAI command will stop execution until certain oscilloscope operations are complete. (See Table 3-3 on page 3-7.)

**Group** Status and Error

Syntax \*WAI

Related Commands BUSY?, \*OPC

#### **Examples**

\*WAI prevents the oscilloscope from executing any further commands or queries until all pending commands that generate an OPC message are complete.

# WAVFrm? (Query Only)

Returns WFMOutpre? and CURVe? data for the waveform as specified by the DATA:SOUrce command. This command is equivalent to sending both WFMOutpre? and CURVe?, with the additional provision that the response to WAVFrm? is guaranteed to provide a synchronized preamble and curve. The source waveform, as specified by :DATA:SOURCE, must be active or the query will not return any data and will generate an error indicator.

**Group** Waveform Transfer

Syntax WAVFrm?

Related Commands CURVe, DATa: SOUrce, WFMOutpre?

**Examples** 

WAVFRM? might return the waveform data as: :WFMOUTPRE:BYT\_NR 1;BIT\_NR 8;ENCDG ASCII;BN\_FMT RI;BYT\_OR MSB;WFID "Ch1, DC coupling, 100.0mV/div, 4.000us/div, 10000 points, Sample mode";NR\_PT 20;PT\_FMT Y;XUNIT "s";XINCR 4.0000E-9;XZERO -20.0000E-6;PT\_OFF 0;YUNIT "V";YMULT 4.0000E-3;YOFF 0.0000;YZERO 0.0000;:CURVE 2,1,4,2,4,3,0,3,3,3,3,3,3,4,3,5,6,6,7,3

# WFMInpre? (Query Only)

Returns the waveform formatting and scaling specifications to be applied to the next incoming CURVe command data.

**Group** Waveform Transfer

**Syntax** WFMInpre?

Related Commands WFMOutpre?

**Examples** WFMINPRE? might return the waveform formatting as :WFMINPRE:BIT\_NR

8;BN\_FMT RI;BYT\_NR 1; BYT\_OR MSB;ENCDG BIN;NR\_PT 500;PT\_FMT

Y; PT\_OFF 0;XINCR 2.0000E-6;XZERO 1.7536E-6; XUNIT "s";YMULT 1.0000E-3;YOFF 0.0000; YZERO 0.0000;YUNIT "V"

## WFMInpre:BIT\_Nr

Sets or returns the number of bits per binary waveform point for the incoming waveform. Changing the value of WFMInpre:BIT\_Nr also changes the value of WFMInpre:BYT\_Nr.

**Group** Waveform Transfer

Syntax WFMInpre:BIT\_Nr <NR1>
 WFMInpre:BIT\_Nr?

**Related Commands** WFMInpre:BYT\_Nr

**Arguments** <NR1> number of bits per data point can be 8 or 16.

**Examples** WFMINPRE: BIT\_NR 16 sets the number of bits per waveform point to 16, for

incoming data.

WFMINPRE:BIT\_NR? might return: WFMINPRE:BIT\_NR 8 indicating that

incoming waveform data uses 8 bits per waveform point.

WFMInpre:BN\_Fmt

Sets or returns the format of binary data for incoming waveforms.

**Group** Waveform Transfer

Syntax WFMInpre:BN\_Fmt {RI|RP}

WFMInpre:BN\_Fmt?

Related Commands WFMOutpre:BN\_Fmt

**Arguments** RI specifies signed integer data point representation.

RP specifies positive integer data point representation.

**Examples** WFMINPRE:BN\_FMT RP specifies positive integer data point representation.

WFMINPRE:BN\_FMT? might return:WFMINPRE:BN\_FMT RI indicating that the

incoming data is currently interpreted as signed integers.

# WFMInpre:BYT\_Nr

Sets or returns the data width for the incoming waveform. Changing the value of WFMInpre:BYT Nr also changes the value of WFMInpre:BIT Nr.

**Group** Waveform Transfer

Syntax WFMInpre:BYT\_Nr <NR1>

WFMInpre:BYT\_Nr?

Related Commands WFMInpre:BIT\_Nr

**Arguments** <NR1> is the number of bytes per data point and can be 1 or 2.

**Examples** WFMINPRE:BYT\_NR 1 sets the number of bytes per incoming waveform data

point to 1, which is the default setting.

WFMINPRE:BYT\_NR? might return:WFMINPRE:BYT\_NR 2 indicating that there

are 2 bytes per incoming waveform data point.

# WFMInpre:BYT\_Or

Sets or returns which byte of binary waveform data is expected first for incoming waveform data when data points require than one byte. This specification only has meaning when WFMInpre:ENCdg is set to BIN and WFMInpre:BYT Nr is 2.

**Group** Waveform Transfer

Syntax WFMInpre:BYT\_Or {LSB|MSB}

WFMInpre:BYT\_Or?

Related Commands WFMInpre:ENCdg, WFMInpre:BYT Nr, WFMOutpre:BYT Or

**Arguments** LSB specifies that the least significant byte will be expected first.

MSB specifies that the most significant byte will be expected first.

**Examples** WFMINPRE: BYT\_OR MSB sets the most significant incoming byte of incoming

waveform data to be expected first.

WFMINPRE:BYT\_OR? might return: WFMINPRE:BYT\_OR LSB indicating that the

least significant incoming CURVe data byte will be expected first.

# WFMInpre:ENCdg

Sets or returns the type of encoding for incoming waveform data.

**Group** Waveform Transfer

**Syntax** WFMInpre:ENCdg {ASCii|BINary}

WFMInpre: ENCdg?

Related Commands WFMOutpre:ENCdg

**Arguments** ASCii specifies that the incoming data is in ASCII format.

BINary specifies that the incoming data is in a binary format whose further interpretation requires knowledge of BYT NR, BIT NR, BN FMT, and

BYT OR.

**Examples** WFMINPRE: ENCDG ASC sets the format of incoming waveform data to ASCII

format.

WFMINPRE: ENCDG? might return: WFMINPRE: ENCDG BIN indicating that the

incoming waveform data is in binary format.

WFMInpre:NR\_Pt

Sets or returns the number of data points that are in the incoming waveform record.

**Group** Waveform Transfer

Syntax WFMInpre:NR\_Pt <NR1>

WFMInpre:NR\_Pt?

#### **Related Commands**

CURVe, DATa, DATa:STARt, DATa:STOP, SAVe:WAVEform, SAVe:WAVEform:FILEFormat, WFMOutpre:NR Pt?

#### **Arguments**

<NR1> is the number of data points if WFMInpre:PT\_Fmt is set to Y. It is the number of min-max pairs if WFMInpre:PT Fmt is set to ENV.

#### **Examples**

WFMINPRE: NR\_PT 10000 specifies that 10000 data points will be expected.

WFMINPRE:NR\_PT ? might return :WFMINPRE:NR\_PT 10000 indicating that there are 10000 data points in the expected incoming waveform record.

# WFMInpre:PT\_Fmt

Sets or returns the point format of the incoming waveform data. Regardless of the argument used, the scale, offset, and so on are interpreted similarly. When ENV is used, waveform data is interpreted over the min-max pair; when Y is used, it is interpreted over a single point.

### Group

Waveform Transfer

### **Syntax**

WFMInpre:PT\_Fmt {ENV|Y}
WFMInpre:PT\_Fmt?

#### **Related Commands**

WFMOutpre:PT Fmt?

#### **Arguments**

ENV specifies that the waveform is transmitted in envelope mode as maximum and minimum point pairs. Only Y values are explicitly transmitted. Absolute coordinates are given by:

$$Xn = XZEro + XINcr (n - PT_Off)$$

$$Ynmax = YZEro + YMUlt (ynmax - YOFf)$$

$$Ynmin = YZEro + YMUlt (ynmin - YOFf)$$

Y specifies a normal waveform where one ASCII or binary data point is transmitted for each point in the waveform record. Only Y values are explicitly transmitted. Absolute coordinates are given by:

$$Xn = XZEro + XINcr (n - PT Off)$$

$$Yn = YZEro + YMUlt (yn - YOFf)$$

**Examples** WFMINPRE: PT\_FMT ENV sets the incoming waveform data point format to

enveloped.

WFMINPRE: PT\_FMT? might return: WFMINPRE: PT\_FMT ENV indicating that the

waveform is transmitted as maximum and minimum point pairs.

WFMInpre:PT\_Off

The set form of this command is ignored. The query form always returns a 0. This

command is listed for compatibility with other Tektronix oscilloscopes.

**Group** Waveform Transfer

Syntax WFMInpre:PT\_Off <NR1>

WFMInpre:PT\_Off?

**Arguments** Arguments are ignored.

WFMInpre:XINcr

Sets or returns the horizontal interval between incoming waveform points in

units specified by WFMInpre:XUNit.

**Group** Waveform Transfer

Syntax WFMInpre:XINcr <NR3>

WFMInpre:XINcr?

**Related Commands** WFMInpre:XUNit, WFMOutpre:XINcr?

**Arguments** <NR3> is the horizontal interval representation.

**Examples** WFMINPRE:XINCR 3E-3 sets the interval between incoming waveform points

to 3 ms.

WFMINPRE:XINCR ? might return :WFMINPRE:XINCR 1.0000E-3 indicating that if WFMInpre:XUNit is set to "s", there is a 1 ms interval between incoming

waveform points.

### WFMInpre:XUNit

Sets or returns the horizontal units of the incoming waveform.

Supported units are:

%, /Hz, A, A/A, A/V, A/W, A/dB, A/s, AA, AW, AdB, As, B, Hz, IRE, S/s, V, V/A, V/V, V/W, V/dB, V/s, VV, VW, VdB, Volts, Vs, W, W/A, W/V, W/W, W/dB, W/s, WA, WV, WW, WdB, Ws, dB, dB/A, dB/V, dB/W, dB/dB, dBA, dBV, dBW, dBdB, day, degrees, div, hr, min, ohms, percent, s

Waveform Transfer

Syntax WFMInpre:XUNit <QString>

WFMInpre:XUNit?

Related Commands WFMOutpre:XUNit?

Group

**Arguments** <QString> contains a maximum of three alpha characters that represent the

horizontal unit of measure for the incoming waveform.

**Examples** WFMINPRE: XUNIT "HZ" specifies that the horizontal units for the incoming

waveform are hertz.

WFMINPRE:XUNIT? might return: WFMINPRE:XUNIT "s" indicating that the

horizontal units for the incoming waveform are seconds.

WFMInpre:XZEro

Sets or returns the position value, in XUNits, of the first sample of the incoming

waveform.

**Group** Waveform Transfer

Syntax WFMInpre:XZEro <NR3>

WFMInpre:XZEro?

**Related Commands** WFMInpre:XINcr, WFMInpre:XUNit, WFMOutpre:XZEro?

**Arguments** <NR3> argument is the floating point value of the position, in XUNits, of the first

sample in the incoming waveform. If XUNits is "s", <NR3> is the time of the

first sample in the incoming waveform.

#### **Examples**

WFMINPRE: XZERO 5.7E-6, which indicates the trigger occurred 5.7 μs before the first sample in the waveform.

WFMINPRE: XZERO? might return: WFMINPRE: XZEro -7.5000E-6 indicating that the trigger occurs 7.5 μs after the first sample in the waveform.

### WFMInpre:YMUIt

Sets or returns the vertical scale factor of the incoming waveform, expressed in YUNits per waveform data point level. For one byte waveform data, there are 256 data point levels. For two byte waveform data there are 65,536 data point levels.

YMUlt, YOFf, and YZEro are used to convert waveform record values to YUNit values using the following formula (where dl is the data level; curve\_in\_dl is a data point in CURVe):

value in units = ((curve in dl - YOFf in dl) \* YMUlt) + YZEro in units

**NOTE.** For a given waveform record, YMUlt, YOFf, and YZEro have to be a consistent set, otherwise vertical cursor readouts and vertical measurements may give incorrect results.

#### Group

Waveform Transfer

### **Syntax**

WFMInpre:YMUlt <NR3>
WFMInpre:YMUlt?

#### **Related Commands**

DATa:DESTination, WFMInpre:BYT Nr, WFMInpre:YUNit

### Arguments

<NR3> is the vertical scale factor per digitizing level of the incoming waveform points.

### **Examples**

WFMINPRE: YMULT? might return: WFMINPRE: YMULT 40.0000E-3, which (if YUNit is "V") indicates that the vertical scale is 40 mV/digitizing level (1V/div for 8-bit data).

WFMINPRE: YMULT 20E-3 specifies that (if WFMInpre: YUNit is "V" and WFMInpre: BYT\_Nr is 1), the vertical scale is 20 mV/digitizing level (500 mV/div).

### WFMInpre:YOFf

Sets or returns the vertical position of the incoming waveform in digitizing levels. Variations in this number are analogous to changing the vertical position of the waveform.

YMUlt, YOFf, and YZEro are used to convert waveform record values to YUNit values using the following formula (where dl is the data level; curve\_in\_dl is a data point in CURVe):

value\_in\_units = ((curve\_in\_dl - YOFf\_in\_dl) \* YMUlt) + YZEro\_in\_units

**NOTE.** For a given waveform record, YMUlt, YOFf, and YZEro have to be a consistent set, otherwise vertical cursor readouts and vertical measurements may give incorrect results.

**Group** Waveform Transfer

Syntax WFMInpre:YOFf <NR3>

WFMInpre:YOFf?

Related Commands WFMInpre:BYT Nr, WFMInpre:YMUlt, WFMOutpre:YOFf?

**Arguments** <NR3> is the vertical offset in digitizing levels.

**Examples** WFMINPRE: YOFF 50 specifies that the zero reference point for the incoming

waveform is 50 digitizing levels (2 divisions, for 8-bit data) above the center

of the data range.

WFMINPRE:YOFF? might return: WFMINPRE:YOFF 25 indicating the vertical

position of the incoming waveform in digitizing levels.

# WFMInpre:YUNit

Sets or returns the vertical units of the incoming waveform.

Supported units are: %, /Hz, A, A/A, A/V, A/W, A/dB, A/s, AA, AW, AdB, As, B, Hz, IRE, S/s, V, V/A, V/V, V/W, V/dB, V/s, VV, VW, VdB, Volts, Vs, W, W/A, W/V, W/W, W/dB, W/s, WA, WV, WW, WdB, Ws, dB, dB/A, dB/V, dB/W, dB/dB, dBA, dBV, dBW, dBdB, day, degrees, div, hr, min, ohms, percent, s

**Group** Waveform Transfer

Syntax WFMInpre:YUNit <QString>

WFMInpre:YUNit?

**Related Commands** WFMOutpre:YUNit?

Arguments <QString> contains a maximum of three alpha characters that represent the

vertical unit of measure for the incoming waveform.

**Examples** WFMINPRE:YUNIT? might return:WFMINPRE:YUNIT "V" indicating the vertical

units for the incoming waveform are volts.

WFMINPRE: YUNIT "A" specifies that the vertical units for the incoming waveform

are Amperes.

WFMInpre:YZEro

Sets or returns the vertical offset of the incoming waveform in units specified by WFMInpre:YUNit. Variations in this number are analogous to changing the vertical offset of the waveform.

vertical offset of the waveform.

YMUlt, YOFf, and YZEro are used to convert waveform record values to YUNit values using the following formula (where dl is the data level; curve\_in\_dl is a

data point in CURVe):

value in units = ((curve in dl - YOFf in dl) \* YMUlt) + YZEro in units

**NOTE.** For a given waveform record, YMUlt, YOFf, and YZEro have to be a consistent set, otherwise vertical cursor readouts and vertical measurements may

give incorrect results.

**Group** Waveform Transfer

Syntax WFMInpre:YZEro <NR3>

WFMInpre: YZEro?

**Related Commands** WFMInpre:YUNit, WFMOutpre:YZEro?

**Arguments** <NR3> is the offset in YUNits.

#### **Examples**

WFMINPRE:YZERO 1.5E+0 specifies that the zero reference point for the incoming waveform is 1.5 V below the center of the data range (given that WFMInpre:YUNit is set to V).

WFMINPRE:YZERO? might return:WFMINPRE:YZEro 7.5000E-6 indicating that the zero reference for the incoming waveform is 7.5  $\mu$ V below the center of the data range (given that WFMInpre:YUNit is set to V).

## WFMOutpre? (Query Only)

Returns waveform transmission and formatting parameters for the waveform specified by DATa:SOUrce command. If the waveform specified by the DATa:SOUrce command is not displayed, the oscilloscope returns only the waveform transmission parameters (BYT\_Nr, BIT\_Nr, ENCdg, BN\_Fmt, BYT\_Or).

**Group** Waveform Transfer

Syntax WFMOutpre?

#### **Examples**

WFMOUTPRE?? might return the waveform formatting data as: :WFMOUTPRE:BYT\_NR 2;BIT\_NR 16;ENCDG ASCII;BN\_FMT RI;BYT\_OR MSB;WFID "Ch1, DC coupling, 100.0mV/div, 4.000us/div, 10000 points, Sample mode";NR\_PT 10000;PT\_FMT Y;XUNIT "s";XINCR 4.0000E-9;XZERO - 20.0000E-6;PT\_OFF 0;YUNIT "V";YMULT 15.6250E-6;YOFF :"6.4000E+3;YZERO 0.0000

# WFMOutpre:BIT\_Nr

Sets and returns the number of bits per waveform point that outgoing waveforms contain, as specified by the DATa:SOUrce command. Changing the value of WFMOutpre:BIT Nr also changes the values of WFMOutpre:BYT Or and .

**Group** Waveform Transfer

Syntax WFMOutpre:BIT\_Nr <NR1>

WFMOutpre:BIT\_Nr?

Related Commands DATa:SOUrce, , WFMOutpre:BN\_Fmt

**Arguments** <NR1> is the number of bits per data point and can be 8 or 16.

**Examples** WFMOUTPRE:BIT\_NR 16 sets the number of bits per waveform point to 16 for

outgoing waveforms.

WFMOUTPRE:BIT\_NR? might return: WFMOUTPRE:BIT\_NR 8 indicating that

outgoing waveforms use 8 bits per waveform point.

### WFMOutpre:BN\_Fmt

Sets or returns the format of binary data for outgoing waveforms specified by the DATa:SOUrce command. Changing the value of WFMOutpre:BN\_Fmt also

changes the value of DATa:ENCdg.

**Group** Waveform Transfer

Syntax WFMOutpre:BN\_Fmt {RI|RP}

WFMOutpre:BN\_Fmt?

Related Commands DATa:ENCdg, DATa:SOUrce

**Arguments** RI specifies signed integer data point representation.

RP specifies positive integer data point representation.

**Examples** WFMOUTPRE: BN\_FMT RP specifies that outgoing waveform data will be in positive

integer format.

WFMOUTPRE:BN\_FMT? might return:WFMOUTPRE:BN\_FMT RI indicating that

the outgoing waveform data is currently in signed integer format.

WFMOutpre:BYT\_Nr

Sets or returns the data width for the outgoing waveform specified by the DATa:SOUrce command. Changing WFMOutpre:BYT Nr also changes

WFMOutpre:BIT Nr and .

**Group** Waveform Transfer

Syntax WFMOutpre:BYT\_Nr <NR1>

WFMOutpre:BYT\_Nr?

Related Commands DATa:SOUrce, , WFMOutpre:BIT Nr

**Arguments** <NR1> is the number of bytes per data point and can be 1 or 2.

**Examples** WFMOUTPRE:BYT\_NR 1 sets the number of bytes per outgoing waveform data

point to 1, which is the default setting.

WFMOUTPRE:BYT\_NR? might return: WFMOUTPRE:BYT\_NR 2 indicating that

there are 2 bytes per outgoing waveform data point.

### WFMOutpre:BYT\_Or

Sets or returns which byte of binary waveform data is transmitted first, during a waveform data transfer, when data points require than one byte. This specification only has meaning when WFMOutpre:ENCdg is set to BIN and WFMOutpre:BYT\_Nr is 2. Changing WFMOutpre:BYT\_Or also changes DATa:ENCdg (if DATa:ENCdg is not ASCIi).

**Group** Waveform Transfer

**Syntax** WFMOutpre:BYT\_Or {LSB|MSB}

WFMOutpre:BYT\_Or?

**Related Commands** WFMOutpre:ENCdg, WFMOutpre:BYT\_Nr

**Arguments** LSB specifies that the least significant byte will be transmitted first.

MSB specifies that the most significant byte will be transmitted first.

**Examples** WFMOUTPRE: BYT\_OR MSB sets the most significant outgoing byte of waveform

data to be transmitted first.

WFMOUTPRE:BYT\_OR? might return: WFMOUTPRE:BYT\_OR LSB indicating that

the least significant data byte will be transmitted first.

WFMOutpre:ENCdg

Sets and queries the type of encoding for outgoing waveforms.

**Group** Waveform Transfer

**Syntax** WFMOutpre:ENCdg {ASCii|BINary}

WFMOutpre: ENCdg?

Related Commands DATa:ENCdg, WFMOutpre:BYT\_Nr, WFMOutpre:BYT\_Or,

WFMOutpre:BIT Nr, WFMOutpre:BN Fmt

**Arguments** ASCii specifies that the outgoing data is to be in ASCII format. Waveforms

will be sent as <NR1> numbers.

BINary specifies that outgoing data is to be in a binary format whose further specification is determined by WFMOutpre:BYT\_Nr, WFMOutpre:BIT\_Nr,

WFMOutpre:BN Fmt and WFMOutpre:BYT Or.

**Examples** WFMOUTPRE: ENCDG? might return: WFMOUTPRE: ENCDG BIN indicating that

outgoing waveform data will be sent in binary format.

WFMOUTPRE: ENCDG ASC specifies that the outgoing waveform data will be sent

in ASCII format.

# WFMOutpre:FRACTional? (Query Only)

The set form of this command is ignored. The query form always returns a 0, if the waveform specified by DATA:SOUrce is on or displayed. If the waveform is not displayed, the query form generates an error and returns event code 2244. This command is for compatibility with other Tektronix oscilloscopes.

**Group** Waveform Transfer

**Syntax** WFMOutpre:FRACTional?

Related Commands DATa:SOUrce

**Arguments** Arguments are ignored.

### WFMOutpre:NR\_Pt? (Query Only)

Returns the number of points for the DATa:SOUrce waveform that will be transmitted in response to a CURVe? query. The query command will time out and an error will be generated if the waveform specified by DATa:SOUrce is not turned on.

**Group** Waveform Transfer

Syntax WFMOutpre:NR\_Pt?

Related Commands CURVe, DATa, DATa:STARt, DATa:STOP, SAVe:WAVEform,

SAVe: WAVEform: FILEFormat, WFMInpre: NR Pt

**Examples** WFMOUTPRE:NR\_PT? might return:WFMOUTPRE:NR\_PT 10000 indicating that

there are 10000 data points to be sent.

## WFMOutpre:PT\_Fmt? (Query Only)

Returns the point format for the outgoing waveform specified by the DATa:SOUrce command. Returned values are either ENV, which indicates envelope mode format in which the data is returned as a series of min/max pairs, or Y, which indicates normal waveform points. The query command will time out and an error will be generated if the waveform specified by DATa:SOUrce is not turned on.

**Group** Waveform Transfer

**Syntax** WFMOutpre:PT\_Fmt?

Related Commands CURVe, DATa:SOUrce

**Examples** WFMOUTPRE:PT\_FMT? might return:WFMOutpre:PT\_Fmt ENV indicating that

the waveform data is a series of min-max pairs.

### WFMOutpre:PT\_Off? (Query Only)

The set form of this command is ignored. The query form always returns a 0, if the waveform specified by DATA:SOUrce is on or displayed. If the waveform is not displayed, the query form generates an error and returns event code 2244. This command is for compatibility with other Tektronix oscilloscopes.

**Group** Waveform Transfer

**Syntax** WFMOutpre:PT\_Off?

Related Commands DATa:SOUrce

**Arguments** Arguments are ignored.

**Examples** WFMOUTPRE: PT\_OFF? might return WFMOUTPRE: PT\_OFF 0 indicating that the

waveform specified by DATA: SOURCE is on or displayed.

## WFMOutpre:PT\_ORder? (Query Only)

This query is for compatibility with other Tektronix oscilloscopes and always returns LINEAR.

**Group** Waveform Transfer

Syntax WFMOutpre:PT\_ORder?

Related Commands DATa:SOUrce

**Examples** WFMOUTPRE:PT\_ORDER? returns:WFMOUTPRE:PT\_ORDER LINEAR.

# WFMOutpre:WFld? (Query Only)

Returns a string describing several aspects of the acquisition parameters for the waveform specified by the DATa:SOUrce command. The query command will time out and an error will be generated if the waveform specified by DATa:SOUrce is not turned on.

**Group** Waveform Transfer

**Syntax** WFMOutpre:WFId?

Related Commands DATa:SOUrce

**Returns** <QString> comprises the following comma-separated fields documented in

the tables below:

Table 2-45: Waveform Suffixes

Field	Description	Examples
Source	The source identification string as it appears in the front-panel scale factor readouts.	"CH1-4" "Math1 "Ref1-4"
Coupling	A string describing the vertical coupling of the waveform (the Source1 waveform in the case of Dual Waveform Math).	"AC coupling" "DC couplng" "GND coupling"
Vert Scale	A string containing the vertical scale factor of the unzoomed waveform. The numeric portion will always be four digits. The examples cover all known internal units.	"100.0 mV/div" "20.00 dB/div" "45.00 deg/div" "785.4 mrad/div"
		"500.0 µVs/div" "10.00 kV/s/div" "200.0 mV/div" "50.00 unk/div"
Horiz Scale	A string containing the horizontal scale factor of the unzoomed waveform. The numeric portion will always be four digits. The examples cover all known internal units.	"100 ms/div" "10.00 kHz/div"
Record Length	A string containing the number of waveform points available in the entire record. The numeric portion is given as an integer.	"1000 points" "1000000 points"
Acquisition Mode	A string describing the mode used to acquire the waveform.	"Sample mode" "Pk Detect mode" "Envelope mode" "Average mode"

### **Examples**

WFMOUTPRE:WFID? might return :WFMOUTPRE:WFID "Ch1, DC coupling,100.0mVolts/div,500.0 $\mu$ s/div, 1000 points, Sample mode"

# WFMOutpre:XINcr? (Query Only)

Returns the horizontal point spacing in units of WFMOutpre:XUNit for the waveform specified by the DATa:SOUrce command. This value corresponds to the sampling interval. The query command will time out and an error will be generated if the waveform specified by DATa:SOUrce is not turned on.

**Group** Waveform Transfer

**Syntax** WFMOutpre:XINcr?

Related Commands DATa:SOUrce, WFMOutpre:XUNit?

**Examples** WFMOUTPRE:XINCR? might return:WFMOUTPRE:XINCR 10.0000E-6

indicating that the horizontal sampling interval is 10 µs/point.

## WFMOutpre:XUNit? (Query Only)

Returns the horizontal units for the waveform specified by the DATa:SOUrce command. The query command will time out and an error will be generated if the waveform specified by DATa:SOUrce is not turned on.

**Group** Waveform Transfer

Syntax WFMOutpre:XUNit?

Related Commands DATa:SOUrce

**Examples** WFMOUTPRE:XUNIT? might return:WFMOUTPRE:XUNIT "HZ" indicating that

the horizontal units for the waveform are in Hertz.

### WFMOutpre:XZEro? (Query Only)

Returns the time coordinate of the first point in the outgoing waveform.

This value is in units of WFMOutpre:XUNit?. The query command will time out and an error will be generated if the waveform specified by DATa:SOUrce

is not turned on.

**Group** Waveform Transfer

**Syntax** WFMOutpre:XZEro?

**Related Commands** DATa:SOUrce, WFMOutpre:XUNit?

**Examples** WFMOUTPRE:XZERO? might return:WFMOUTPRE:XZERO 5.6300E-9 indicating

that the trigger occurred 5.63 ns before the first sample in the waveform record.

# WFMOutpre:YMUIt? (Query Only)

Returns the vertical scale factor per digitizing level in units specified by WFMOutpre:YUNit for the waveform specified by the DATa:SOUrce command. The query command will time out and an error is generated if the waveform specified by DATa:SOUrce is not turned on.

See the description of WFMInpre:YMUlt to see how this scale factor is used to convert waveform sample values to volts.

**Group** Waveform Transfer

**Syntax** WFMOutpre:YMUlt?

Related Commands DATa: SOUrce, WFMInpre: YMUlt

**Examples** WFMOUTPRE: YMULT? might return: WFMOUTPRE: YMULT 4.0000E-3 indicating

that the vertical scale for the corresponding waveform is 100 mV/div (for 8-bit

waveform data).

### WFMOutpre:YOFf? (Query Only)

Returns the vertical position in digitizing levels for the waveform specified by the DATa:SOUrce command. The query command will time out and an error will be generated if the waveform specified by DATa:SOUrce is not turned on.

See the description of WFMInpre:YOFf to see how this position is used to convert waveform sample values to volts.

**Group** Waveform Transfer

**Syntax** WFMOutpre:YOFf?

Related Commands DATa: SOUrce, WFMOutpre: BYT Nr

**Examples** WFMOUTPRE:YOFF? might return:WFMOUTPRE:YOFF -50.0000E+0 indicating

that the position indicator for the waveform was 50 digitizing levels (2 divisions)

below center screen (for 8-bit waveform data).

## WFMOutpre:YUNit? (Query Only)

Returns the vertical units for the waveform specified by the DATa:SOUrce command. The query command will time out and an error will be generated if the waveform specified by DATa:SOUrce is not turned on.

**Group** Waveform Transfer

**Syntax** WFMOutpre:YUNit?

Related Commands DATa:SOUrce

**Examples** WFMOUTPRE:YUNIT? might return:WFMOUTPRE:YUNIT "dB" indicating that

the vertical units for the waveform are measured in decibels.

## WFMOutpre:YZEro? (Query Only)

Returns the vertical offset in units specified by WFMOutpre:YUNit? for the waveform specified by the DATa:SOUrce command. The query command will time out and an error will be generated if the waveform specified by DATa:SOUrce is not turned on.

See the description of WFMInpre:YZEro to see how this offset is used to convert waveform sample values to volts.

**Group** Waveform Transfer

Syntax WFMOutpre:YZEro?

Related Commands DATa: SOUrce, WFMOutpre: YUNit?

Examples WFMOUTPRE:YZERO? might return:WFMOUTPRE:YZERO -100.0000E-3

indicating that vertical offset is set to -100 mV.

### ZOOm? (Query Only)

Returns the current vertical and horizontal positioning and scaling of the display.

Group Zoom

Syntax ZOOm?

**Examples** ZOOM? might return : ZOOM: MODE 1; GRATICULE: SIZE

80; SPLIT EIGHTYTWENTY; : ZOOM: ZOOM1: STATE

1; SCALE 400. 0000E-12; POSITION 46.8986; FACTOR

50.0000E+3; HORIZONTAL: POSITION 46.8986; SCALE 40 0.0000E-12

### ZOOm:MODe

Turns Zoom mode on or off. The Zoom query returns the current state of Zoom mode. This command is equivalent to pressing the zoom button located on the front panel.

**Group** Zoom

Syntax ZOOm:MODe {ON|OFF|<NR1>}

ZOOm:MODe

**Arguments** ON turns on Zoom mode.

OFF turns off Zoom mode.

<NR1> = 0 turns off Zoom mode; any other value turns on Zoom mode.

**Examples** ZOOM: MODE OFF turns off Zoom mode.

ZOOM: MODE? might return: ZOOM: MODE 1 indicating that Zoom mode is

currently turned on.

## ZOOm:ZOOM<x>? (Query Only)

Returns the current vertical and horizontal positioning and scaling of the display. <x> can only be 1.

Group Zoom

Syntax ZOOm: ZOOM<x>?

**Examples** ZOOM:ZOOM1? might return :ZOOM:ZOOM1:STATE 1;SCALE

400.0000E-12; POSITION 46.8986; FACTOR 50.0000E+3; HORIZO

NTAL: POSITION 46.8986; SCALE 400.0000E-12.

# ZOOm:ZOOM<x>:FACtor? (Query Only)

Returns the zoom factor of a particular zoom box. <x> can only be 1.

Group Zoom

Syntax ZOOm:ZOOM<x>:FACtor?

**Returns** <NR1> is the zoom factor of a zoom box.

### ZOOm:ZOOM<x>:POSition

Sets the horizontal position of the zoom box, in terms of 0 to 100.0% of upper window. <x> can only be 1.

Group Zoom

Syntax ZOOm:ZOOM<x>:POSition <NR3>

ZOOm:ZOOM<x>:POSition?

**Arguments** <NR3> is the horizontal position as a percent of the upper window.

### ZOOm:ZOOM<x>:SCAle

Sets or returns the horizontal scale of the zoom box. <x> can only be 1.

**Group** Zoom

Syntax ZOOm:ZOOM<x>:SCAle <NR3>

ZOOm:ZOOM<x>:SCAle?

**Arguments** <NR3> is the horizontal scale of the zoom box.

### ZOOm:ZOOM<x>:STATE

Sets or returns the specified zoom on or off, where x is the integer 1 representing

the single zoom window.  $\langle x \rangle$  can only be 1.

Zoom Group

ZOOm:ZOOM<x>:STATE {ON|OFF|<NR1>} **Syntax** 

ZOOm:ZOOM<x>:STATE?

ON turns Zoom 1 on. **Arguments** 

OFF turns Zoom 1 off.

<NR1> = 0 disables the specified zoom; any other value enables the specified

zoom.

**Examples** ZOOM: ZOOM1: STATE ON turns Zoom1 on.

ZOOM: ZOOM1: STATE? might return: ZOOM: ZOOM1: STATE 1 indicating that

Zoom1 is on.

# **Status and Events**

The oscilloscope provides a status and event reporting system for the Ethernet, GPIB (with the TEK-USB-488 Adapter), and USB interfaces. This system informs you of certain significant events that occur within the oscilloscope.

The oscilloscope status handling system consists of five 8-bit registers and two queues for each interface. The remaining Status subtopics describe these registers and components. They also explain how the event handling system operates.

### Registers

#### Overview

The registers in the event handling system fall into two functional groups:

- Status Registers contain information about the status of the oscilloscope. They include the Standard Event Status Register (SESR).
- Enable Registers determine whether selected types of events are reported to the Status Registers and the Event Queue. They include the Device Event Status Enable Register (DESER), the Event Status Enable Register (ESER), and the Service Request Enable Register (SRER).

#### Status Registers

The Standard Event Status Register (SESR) and the Status Byte Register (SBR) record certain types of events that may occur while the oscilloscope is in use. IEEE Std 488.2-1987 defines these registers.

Each bit in a Status Register records a particular type of event, such as an execution error or message available. When an event of a given type occurs, the oscilloscope sets the bit that represents that type of event to a value of one. (You can disable bits so that they ignore events and remain at zero. See Enable Registers). Reading the status registers tells you what types of events have occurred.

The Standard Event Status Register (SESR). The SESR records eight types of events that can occur within the oscilloscope. Use the \*ESR? query to read the SESR register. Reading the register clears the bits of the register so that the register can accumulate information about new events.

**NOTE.** TekVISA applications use SESR bit 6 to respond to any of several events, including some front panel actions.

7	6	5	4	3	2	1	0
PON	URQ	CME	EXE	DDE	QYE	RQC	OPC

Figure 3-1: The Standard Event Status Register (SESR)

Table 3-1: SESR Bit Functions

Bit	Function	
7 (MSB)	PON	Power On. Shows that the oscilloscope was powered on. On completion, the diagnostic self tests also set this bit.
6	URQ	User Request. Indicates that an application event has occurred. *See note.
5	CME	Command Error. Shows that an error occurred while the oscilloscope was parsing a command or query.
4	EXE	Execution Error. Shows that an error executing a command or query.
3	DDE	Device Error. Shows that a device error occurred.
2	QYE	Query Error. Either an attempt was made to read the Output Queue when no data was present or pending, or that data in the Output Queue was lost.
1	RQC	Request Control. This is not used.
0 (LSB)	OPC	Operation Complete. Shows that the operation is complete. This bit is set when all pending operations complete following an *OPC command.

**The Status Byte Register (SBR).** Records whether output is available in the Output Queue, whether the oscilloscope requests service, and whether the SESR has recorded any events.

Use a Serial Poll or the \*STB? query to read the contents of the SBR. The bits in the SBR are set and cleared depending on the contents of the SESR, the Event Status Enable Register (ESER), and the Output Queue. When you use a Serial Poll to obtain the SBR, bit 6 is the RQS bit. When you use the \*STB? query to obtain the SBR, bit 6 is the MSS bit. Reading the SBR does not clear the bits.

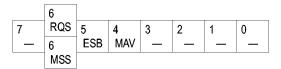


Figure 3-2: The Status Byte Register (SBR)

Table 3-2: SBR Bit Functions

Bit	Function	
7 (MSB)		Not used.
6	RQS	Request Service. Obtained from a serial poll. Shows that the oscilloscope requests service from the GPIB controller.
6	MSS	Master Status Summary. Obtained from *STB? query. Summarizes the ESB and MAV bits in the SBR.
5	ESB	Event Status Bit. Shows that status is enabled and present in the SESR.

Table 3-2: SBR Bit Functions (cont.)

Bit	Function	
4	MAV Message Available. Shows that output is available in the Output Queue.	
3	Not used.	
2	Not used.	
1–0	Not used.	

#### **Enable Registers**

DESER, ESER, and SRER allow you to select which events are reported to the Status Registers and the Event Queue. Each Enable Register acts as a filter to a Status Register (the DESER also acts as a filter to the Event Queue) and can prevent information from being recorded in the register or queue.

Each bit in an Enable Register corresponds to a bit in the Status Register it controls. In order for an event to be reported to a bit in the Status Register, the corresponding bit in the Enable Register must be set to one. If the bit in the Enable Register is set to zero, the event is not recorded.

Various commands set the bits in the Enable Registers. The Enable Registers and the commands used to set them are described below.

**The Device Event Status Enable Register (DESER).** This register controls which types of events are reported to the SESR and the Event Queue. The bits in the DESER correspond to those in the SESR.

Use the DESE command to enable and disable the bits in the DESER. Use the DESE? query to read the DESER.

7	6	5	4	3	2	1	0
PON	URQ	CME	EXE	DDE	QYE	RQC	OPC

Figure 3-3: The Device Event Status Enable Register (DESER)

**The Event Status Enable Register (ESER).** This register controls which types of events are summarized by the Event Status Bit (ESB) in the SBR. Use the \*ESE command to set the bits in the ESER. Use the \*ESE? query to read it.

7	6	5	4	3	2	1	0
PON	URQ	CME	EXE	DDE	QYE	RQC	OPC

Figure 3-4: The Event Status Enable Register (ESER)

The Service Request Enable Register (SRER). This register controls which bits in the SBR generate a Service Request and are summarized by the Master Status Summary (MSS) bit.

Use the \*SRE command to set the SRER. Use the \*SRE? query to read the register. The RQS bit remains set to one until either the Status Byte Register is read with a Serial Poll or the MSS bit changes back to a zero.

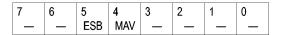


Figure 3-5: The Service Request Enable Register (SRER)

#### \*PSC Command

The \*PSC command controls the Enable Registers contents at power-on. Sending \*PSC 1 sets the Enable Registers at power on as follows:

- DESER 255 (equivalent to a DESe 255 command)
- ESER 0 (equivalent to an \*ESE 0 command)
- SRER 0 (equivalent to an \*SRE 0 command)

Sending \*PSC 0 lets the Enable Registers maintain their values in nonvolatile memory through a power cycle.

**NOTE.** To enable the PON (Power On) event to generate a Service Request, send \*PSC 0, use the DESe and \*ESE commands to enable PON in the DESER and ESER, and use the \*SRE command to enable bit 5 in the SRER. Subsequent power-on cycles will generate a Service Request.

### Queues

The \*PSC command controls the Enable Registers contents at power-on. Sending \*PSC 1 sets the Enable Registers at power on as follows:

### **Output Queue**

The oscilloscope stores query responses in the Output Queue and empties this queue each time it receives a new command or query message after an <EOM>. The controller must read a query response before it sends the next command (or query) or it will lose responses to earlier queries.



**CAUTION.** When a controller sends a query, an <EOM>, and a second query, the oscilloscope normally clears the first response and outputs the second while reporting a Query Error (QYE bit in the ESER) to indicate the lost response. A fast controller, however, may receive a part or all of the first response as well. To avoid this situation, the controller should always read the response immediately after sending any terminated query message or send a DCL (Device Clear) before sending the second query.

#### **Event Queue**

The Event Queue stores detailed information on up to 33 events. If than 32 events stack up in the Event Queue, the 32nd event is replaced by event code 350, "Queue Overflow."

Read the Event Queue with the EVENT? query (which returns only the event number), with the EVMSG? query (which returns the event number and a text description of the event), or with the ALLEV? query (which returns all the event numbers along with a description of the event). Reading an event removes it from the queue.

Before reading an event from the Event Queue, you must use the \*ESR? query to read the summary of the event from the SESR. This makes the events summarized by the \*ESR? read available to the EVENT? and EVMSG? queries, and empties the SESR.

Reading the SESR erases any events that were summarized by previous \*ESR? reads but not read from the Event Queue. Events that follow an \*ESR? read are put in the Event Queue but are not available until \*ESR? is used again.

## **Event Handling Sequence**

The figure below shows how to use the status and event handling system. In the explanation that follows, numbers in parentheses refer to numbers in the figure.

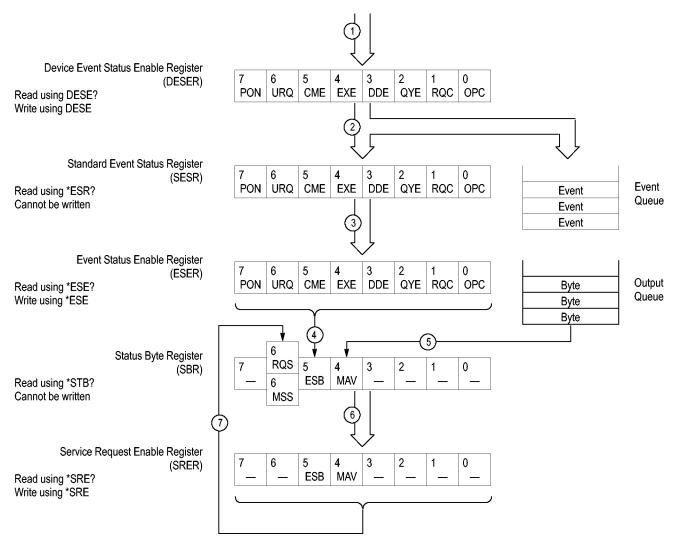


Figure 3-6: Status and Event Handling Process

When an event occurs, a signal is sent to the DESER (1). If that type of event is enabled in the DESER (that is, if the bit for that event type is set to 1), the appropriate bit in the SESR is set to one, and the event is recorded in the Event Queue (2). If the corresponding bit in the ESER is also enabled (3), then the ESB bit in the SBR is set to one (4).

When output is sent to the Output Queue, the MAV bit in the SBR is set to one (5).

When a bit in the SBR is set to one and the corresponding bit in the SRER is enabled (6), the MSS bit in the SBR is set to one and a service request is generated (7).

# **Synchronization Methods**

#### Overview

Although most commands are completed almost immediately after being received by the oscilloscope, some commands start a process that requires time. For example, once a single sequence acquisition command is executed, depending upon the applied signals and trigger settings, it may take an extended period of time before the acquisition is complete. Rather than remain idle while the operation is in process, the oscilloscope will continue processing other commands. This means that some operations will not be completed in the order that they were sent.

Sometimes the result of an operation depends on the result of an earlier operation. A first operation must complete before the next one is processed. The oscilloscope status and event reporting system is designed to accommodate this process.

The Operation Complete (OPC) bit of the Standard Event Status Register (SESR) can be programmed to indicate when certain oscilloscope operations have completed and, by setting the Event Status Enable Register (ESER) to report OPC in the Event Status Bit (ESB) of the Status Byte Register (SBR) and setting the Service Request Enable Register (SRER) to generate service request upon a positive transition of the ESB, a service request (SRQ) interrupt can be generated when certain operations complete as described in this section.

The following oscilloscope operations can generate an OPC:

Table 3-3: Oscilloscope operations that can generate OPC

Command	Conditions
ACQuire:STATE <non-zero nr1="">   ON</non-zero>	Only when in single sequence acquisition mode
CALibrate:FACtory STARt	
CALibrate:FACtory CONTinue	
CALibrate:FACtory PREVious	
CH <x>:PRObe:DEGAUss EXECute</x>	
AUXin:PRObe:DEGAUss EXECute	
DIAg:STATE EXECute	
FACtory	
HARDCopy	
HARDCopy START	
RECAll:SETUp <file as="" quoted="" string=""></file>	
RECAll:WAVEform <file as="" quoted="" string=""></file>	
*RST	
SAVe:IMAGe <file as="" quoted="" string=""></file>	
SAVe:SETUp <file as="" quoted="" string=""></file>	
SAVe:WAVEform <file as="" quoted="" string=""></file>	

Table 3-3: Oscilloscope operations that can generate OPC (cont.)

Command	Conditions
SAVe:WAVEform REF1 REF2 REF3 REF4	
TEKSecure	

For example, a typical application might involve acquiring a single-sequence waveform and then taking a measurement on the acquired waveform. You could use the following command sequence to do this:

```
/** Set up conditional acquisition **/
ACQUIRE:STATE OFF
SELECT:CH1 ON
HORIZONTAL:RECORDLENGTH 1000
ACQUIRE:MODE SAMPLE
ACQUIRE:STOPAFTER SEQUENCE
/** Acquire waveform data **/
ACQUIRE:STATE ON
/** Set up the measurement parameters **/
MEASUREMENT:IMMED:TYPE AMPLITUDE
MEASUREMENT: IMMED:SOURCE CH1
/** Take amplitude measurement **/
MEASUREMENT: MEAS1:VALUE?
```

The acquisition of the waveform requires extended processing time. It may not finish before the oscilloscope takes an amplitude measurement (see the following figure). This can result in an incorrect amplitude value.

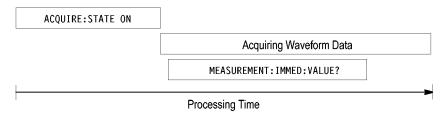


Figure 3-7: Command Processing Without Using Synchronization

To ensure the oscilloscope completes waveform acquisition before taking the measurement on the acquired data, you can synchronize the program.

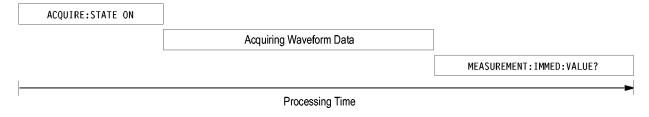


Figure 3-8: Processing Sequence With Synchronization

You can use four commands to synchronize the operation of the oscilloscope with your application program: \*WAI, BUSY, \*OPC, and \*OPC?

### **Using the \*WAI Command**

The \*WAI command forces completion of previous commands that generate an OPC message. No commands after the \*WAI are processed before the OPC message(s) are generated

The same command sequence using the \*WAI command for synchronization looks like this:

```
/* Set up conditional acquisition */
ACQUIRE:STATE OFF
SELECT: CH1 ON
HORIZONTAL: RECORDLENGTH 1000
ACOUIRE: MODE SAMPLE
ACQUIRE:STOPAFTER SEQUENCE
/* Acquire waveform data */
ACQUIRE:STATE ON
/* Set up the measurement parameters */
MEASUREMENT: IMMED: TYPE AMPLITUDE
MEASUREMENT: IMMED: SOURCE CH1
/* Wait until the acquisition is complete before taking
the measurement*/
*/
*WAI
/* Take amplitude measurement */
MEASUREMENT: TMMED: VALUE?
```

The controller can continue to write commands to the input buffer of the oscilloscope, but the commands will not be processed by the oscilloscope until all in-process OPC operations are complete. If the input buffer becomes full, the controller will be unable to write commands to the buffer. This can cause a time-out.

#### **Using the BUSY Query**

The BUSY? query allows you to find out whether the oscilloscope is busy processing a command that has an extended processing time such as single-sequence acquisition.

The same command sequence, using the BUSY? query for synchronization, looks like this:

```
/* Set up conditional acquisition */
ACQUIRE:STATE OFF
SELECT:CH1 ON
HORIZONTAL:RECORDLENGTH 1000
ACQUIRE:MODE SAMPLE
ACQUIRE:STOPAFTER SEQUENCE
/* Acquire waveform data */
```

```
ACQUIRE:STATE ON

/* Set up the measurement parameters */

MEASUREMENT:IMMED:TYPE AMPLITUDE

MEASUREMENT:IMMED:SOURCE CH1

/* Wait until the acquisition is complete before taking the measurement */

While BUSY? keep looping

/* Take amplitude measurement */

MEASUREMENT:IMMED:VALUE?
```

This sequence lets you create your own wait loop rather than using the \*WAI command. The BUSY? query helps you avoid time-outs caused by writing too many commands to the input buffer. The controller is still tied up though, and the repeated BUSY? query will result in bus traffic.

#### **Using the \*OPC Command**

If the corresponding status registers are enabled, the \*OPC command sets the OPC bit in the Standard Event Status Register (SESR) when an operation is complete. You achieve synchronization by using this command with either a serial poll or service request handler.

**Serial Poll Method:** Enable the OPC bit in the Device Event Status Enable Register (DESER) and the Event Status Enable Register (ESER) using the DESE and \*ESE commands.

When the operation is complete, the OPC bit in the Standard Event Status Register (SESR) will be enabled and the Event Status Bit (ESB) in the Status Byte Register will be enabled.

The same command sequence using the \*OPC command for synchronization with serial polling looks like this:

```
/* Set up conditional acquisition */
ACQUIRE:STATE OFF
SELECT: CH1 ON
HORIZONTAL: RECORDLENGTH 1000
ACQUIRE: MODE SAMPLE
ACQUIRE:STOPAFTER SEQUENCE
/* Enable the status registers */
DESE 1
*ESE 1
*SRE 0
/* Acquire waveform data */
ACQUIRE:STATE ON
/* Set up the measurement parameters */
MEASUREMENT: IMMED: TYPE AMPLITUDE
MEASUREMENT: IMMED: SOURCE CH1
/* Wait until the acquisition is complete before taking the
measurement.*/
*OPC
```

```
while serial poll = 0, keep looping
/* Take amplitude measurement */
MEASUREMENT:IMMED:VALUE?
```

This technique requires less bus traffic than did looping on BUSY.

**Service Request Method:** Enable the OPC bit in the Device Event Status Enable Register (DESER) and the Event Status Enable Register (ESER) using the DESE and \*ESE commands.

You can also enable service requests by setting the ESB bit in the Service Request Enable Register (SRER) using the \*SRE command. When the operation is complete, the oscilloscope will generate a Service Request.

The same command sequence using the \*OPC command for synchronization looks like this

```
/* Set up conditional acquisition */
ACQUIRE:STATE OFF
SELECT: CH1 ON
HORIZONTAL: RECORDLENGTH 1000
ACQUIRE: MODE SAMPLE
ACQUIRE:STOPAFTER SEQUENCE
/* Enable the status registers */
DESE 1
*ESE 1
*SRE 32
/* Acquire waveform data */
ACQUIRE:STATE ON
/* Set up the measurement parameters */
MEASUREMENT: IMMED: TYPE AMPLITUDE
MEASUREMENT: IMMED: SOURCE CH1
/* Wait until the acquisition is complete before taking the
measurement*/
*OPC
```

The program can now do different tasks such as talk to other devices. The SRQ, when it comes, interrupts those tasks and returns control to this task.

```
/* Take amplitude measurement */
MEASUREMENT:IMMED:VALUE?
```

### Using the \*OPC? Query

The \*OPC? query places a 1 in the Output Queue once an operation that generates an OPC message is complete. The \*OPC? query does not return until all pending OPC operations have completed. Therefore, your time-out must be set to a time at least as long as the longest expected time for the operations to complete.

The same command sequence using the \*OPC? query for synchronization looks like this:

```
/* Set up single sequence acquisition */
```

ACQUIRE:STATE OFF SELECT:CH1 ON

HORIZONTAL: RECORDLENGTH 1000

ACQUIRE:MODE SAMPLE

ACQUIRE:STOPAFTER SEQUENCE
/\* Acquire waveform data \*/

ACQUIRE:STATE ON

/\* Set up the measurement parameters \*/

MEASUREMENT: IMMED: TYPE AMPLITUDE MEASUREMENT: IMMED: SOURCE CH1

/\* Wait until the acquisition is complete before taking the

measurement\*/

\*OPC?

Wait for read from Output Queue.

/\* Take amplitude measurement \*/

MEASUREMENT: IMMED: VALUE?

This is the simplest approach. It requires no status handling or loops. However, you must set the controller time-out for longer than the acquisition operation.

#### Messages

The information contained in the topic tabs above covers all the programming interface messages the oscilloscope generates in response to commands and queries.

For most messages, a secondary message from the oscilloscope gives detail about the cause of the error or the meaning of the message. This message is part of the message string and is separated from the main message by a semicolon.

Each message is the result of an event. Each type of event sets a specific bit in the SESR and is controlled by the equivalent bit in the DESER. Thus, each message is associated with a specific SESR bit. In the message tables, the associated SESR bit is specified in the table title, with exceptions noted with the error message text.

#### No Event

The following table shows the messages when the system has no events or status to report. These have no associated SESR bit.

Table 3-4: No Event Messages

Code	Message
0	No events to report; queue empty
1	No events to report; new events pending *ESR?

#### **Command Error**

The following table shows the command error messages generated by improper syntax. Check that the command is properly formed and that it follows the rules in the section on command Syntax.

Table 3-5: Command Error Messages (CME Bit 5)

Message
Command error
Invalid character
Syntax error
Invalid separator
Data type error
GET not allowed
Parameter not allowed
Missing parameter
Command header error
Program mnemonic too long
Undefined header
Numeric data error
Invalid character in numeric
Exponent too large
Too many digits
Suffix error
Invalid suffix
Suffix too long
Character data error
Invalid character data
Character data too long
String data error
Invalid string data
String data too long
Block data error
Invalid block data
Command expression error
Invalid expression

### **Execution Error**

The following table lists the execution errors that are detected during execution of a command.

Table 3-6: Execution Error Messages (EXE Bit 4)

Code	Message	
200	Execution error	
221	Settings conflict	
222	Data out of range	

Table 3-6: Execution Error Messages (EXE Bit 4) (cont.)

Code	Message
224	Illegal parameter value
241	Hardware missing
250	Mass storage error
251	Missing mass storage
252	Missing media
253	Corrupt media
254	Media full
255	Directory full
256	File name not found
257	File name error
258	Media protected
259	File name too long
270	Hardcopy error
271	Hardcopy device not responding
272	Hardcopy is busy
273	Hardcopy aborted
274	Hardcopy configuration error
280	Program error
282	Insufficient network printer information
283	Network printer not responding
284	Network printer server not responding
286	Program runtime error
287	Print server not found
2200	Measurement error, Measurement system error
2201	Measurement error, Zero period
2202	Measurement error, No period, second waveform
2203	Measurement error, No period, second waveform
2204	Measurement error, Low amplitude, second waveform
2205	Measurement error, Low amplitude, second waveform
2206	Measurement error, Invalid gate
2207	Measurement error, Measurement overflow
2208	Measurement error, No backwards Mid Ref crossing
2209	Measurement error, No second Mid Ref crossing
2210	Measurement error, No Mid Ref crossing, second waveform
2211	Measurement error, No backwards Mid Ref crossing
2212	Measurement error, No negative crossing
2213	Measurement error, No positive crossing

Table 3-6: Execution Error Messages (EXE Bit 4) (cont.)

Code	Message
2214	Measurement error, No crossing, target waveform
2215	Measurement error, No crossing, second waveform
2216	Measurement error, No crossing, target waveform
2217	Measurement error, Constant waveform
2219	Measurement error, No valid edge - No arm sample
2220	Measurement error, No valid edge - No arm cross
2221	Measurement error, No valid edge - No trigger cross
2222	Measurement error, No valid edge - No second cross
2223	Measurement error, Waveform mismatch
2224	Measurement error, WAIT calculating
2225	Measurement error, No waveform to measure
2226	Measurement error, Null Waveform
2227	Measurement error, Positive and Negative Clipping
2228	Measurement error, Positive Clipping
2229	Measurement error, Negative Clipping
2230	Measurement error, High Ref < Low Ref
2231	Measurement error, No statistics available
2233	Requested waveform is temporarily unavailable
2235	Math error, invalid math description
2240	Invalid password
2241	Waveform requested is invalid
2244	Source waveform is not active
2245	Saveref error, selected channel is turned off
2250	Reference error, the reference waveform file is invalid
2253	Reference error, too many points received
2254	Reference error, too few points received
2259	File too big
2270	Alias error
2271	Alias syntax error
2273	Illegal alias label
2276	Alias expansion error
2277	Alias redefinition not allowed
2278	Alias header not found
2285	TekSecure(R) Pass
2286	TekSecure(R) Fail
2500	Setup error, file does not look like a setup file
2501	Setup warning, could not recall all values from external setup

Table 3-6: Execution Error Messages (EXE Bit 4) (cont.)

Code	Message
2620	Mask error, too few points received
2760	Mark limit reached
2761	No mark present
2762	Search copy failed

### **Device Error**

The following table lists the device errors that can occur during oscilloscope operation. These errors may indicate that the oscilloscope needs repair.

Table 3-7: Device Error Messages (DDE Bit 3)

Code	Message
310	System error
311	Memory error
312	PUD memory lost
314	Save/recall memory lost

### **System Event**

The following table lists the system event messages. These messages are generated whenever certain system conditions occur.

**Table 3-8: System Event Messages** 

Code	Message
400	Query event
401	Power on (PON bit 7 set)
402	Operation complete (OPC bit 0 set)
403	User request (URQ bit 6 set)
404	Power fail (DDE bit 3 set)
405	Request control
410	Query INTERRUPTED (QYE bit 2 set)
420	Query UNTERMINATED (QYE bit 2 set)
430	Query DEADLOCKED (QYE bit 2 set)
440	Query UNTERMINATED after indefinite response (QYE bit 2 set)
468	Knob/Keypad value changed
472	Application variable changed

### **Execution Warning**

The following table lists warning messages that do not interrupt the flow of command execution. They also notify you of a possible unexpected results.

Table 3-9: Execution Warning Messages (EXE Bit 4)

Code	Message
528	Parameter out of range
532	Curve data too long, Curve truncated
533	Curve error, Preamble values are inconsistent
540	Measurement warning, Uncertain edge
541	Measurement warning, Low signal amplitude
542	Measurement warning, Unstable histogram
543	Measurement warning, Low resolution
544	Measurement warning, Uncertain edge
545	Measurement warning, Invalid in minmax
546	Measurement warning, Need 3 edges
547	Measurement warning, Clipping positive/negative
548	Measurement warning, Clipping positive
549	Measurement warning, Clipping negative

Table 3-10: Execution Warning Messages (EXE Bit 4)

Message
Measurement warning
Measurement warning, Low signal amplitude
Measurement warning, Unstable histogram
Measurement warning, Low resolution
Measurement warning, Uncertain edge
Measurement warning, Invalid min max
Measurement warning, Need 3 edges
Measurement warning, Clipping positive/negative
Measurement warning, Clipping positive
Measurement warning, Clipping negative

### **Internal Warning**

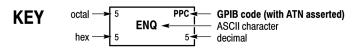
The following table shows internal errors that indicate an internal fault in the oscilloscope.

**Table 3-11: Internal Warning Messages** 

Code	Message
630	Internal warning, $50\Omega$ overload

# **Appendix A: Character Set**

B7	0 0	0 0	0 1	0 1	1 0 1 0	1 1 1
B6 B5	0	1	. 0	1	0 1	0 1
BITS B4 B3 B2 B1	CON	TROL	NUME SYME		UPPER CASE	LOWER CASE
0 0 0 0	0 NUL	20 DLE	40 LAO SP	60 <b>LA16</b>	100 TA0 120 TA16	140 SA0 160 SA16
0 0 0 0	0 0	10 16	20 32	<b>0</b> 30 48	<b>@ P 8</b> 0	60 96 70 p
	1 GTL	21 <b>LL0</b>	41 <b>LA1</b>	61 <b>LA17</b>	101 TA1 121 TA17	141 <b>SA1</b> 161 <b>SA17</b>
0 0 0 1	<b>SOH</b> 1	<b>DC1</b>	! 21 33	<b>1</b> 31 49	<b>A Q</b> 41 65 51 81	<b>a q</b> 61 97 71 113
	2	22	42 <b>LA2</b>	62 <b>LA18</b>	102 TA2 122 TA18	142 <b>SA2</b> 162 <b>SA18</b>
0 0 1 0	<b>STX</b> 2	DC2 12 18	22 34	<b>2</b> 32 50	<b>B R</b> 42 66 52 82	<b>b r</b> 62 98 72 114
	3	23	43 <b>LA3</b>	63 LA19	103 TA3 123 TA19	143 <b>SA3</b> 163 <b>SA19</b>
0 0 1 1	3 ETX 3	DC3	# 23 35	<b>3</b> 33 51	C S 83	63 99 73 115
	4 SDC	24 DCL	44 <b>LA4</b>	64 <b>LA20</b>	104 <b>TA4</b> 124 <b>TA20</b>	144 <b>SA4</b> 164 <b>SA20</b>
0 1 0 0	<b>EOT</b> 4	DC4	<b>\$</b> 24 36	<b>4</b> 34 52	<b>D T</b>	<b>d t</b> 100 74 116
	5 PPC	25 <b>PPU</b>	45 <b>LA5</b>	65 <b>LA21</b>	105 <b>TA5</b> 125 <b>TA21</b>	145 <b>SA5</b> 165 <b>SA21</b>
0 1 0 1	<b>ENQ</b> 5	<b>NAK</b> 15 21	<b>%</b> 25 37	<b>5</b> 35 53	<b>E U</b> 45 69 55 85	<b>e u</b> 65 101 75 117
	6	26	46 <b>LA6</b>	66 <b>LA22</b>	106 <b>TA6</b> 126 <b>TA22</b>	146 SA6 166 SA22
0 1 1 0	6 ACK	SYN 16 22	<b>&amp;</b> 26 38	<b>6</b> 36 54	F V 56 86	<b>f v</b> 66 102 76 118
	7	27	47 <b>LA7</b>	67 <b>LA23</b>	107 <b>TA7</b> 127 <b>TA23</b>	147 <b>SA7</b> 167 <b>SA23</b>
0 1 1 1	<b>BEL</b> 7	ETB 17 23	27 39	<b>7</b> 37 55	G W 87	<b>g w</b> 103 77 119
	10 <b>GET</b>	30 <b>SPE</b>	50 <b>LA8</b>	70 <b>LA24</b>	110 TA8 130 TA24	150 SA8 170 SA24
1 0 0 0	8 BS 8	CAN 18 24	<b>(</b> 28 40	<b>8</b> 38 56	H X X 88	<b>h x</b> 120
	11 TCT	31 <b>SPD</b>	51 <b>LA9</b>	71 <b>LA25</b>	111 TA9 131 TA25	151 SA9 171 SA25
1 0 0 1	HT 9 9	EM 19 25	) 29 41	<b>9</b> 39 57	Y   Y   89	i y 105 79 121
	12	32	52 <b>LA10</b>	72 <b>LA26</b>	112 <b>TA10</b> 132 <b>TA26</b>	152 <b>SA10</b> 172 <b>SA26</b>
1 0 1 0	<b>LF</b> A 10	SUB 1A 26	<b>*</b> 2A 42	<b>:</b> 3A 58	J Z Z 4A 74 5A 90	j z 6A 106 7A 122
-	13	33	53 <b>LA11</b>	73 <b>LA27</b>	113 <b>TA11</b> 133 <b>TA27</b>	153 <b>SA11</b> 173 <b>SA27</b>
1 0 1 1	B VT	1B 27	<b>+</b> 2B 43	; 3B 59	<b>K</b> [ [ 4B 75 5B 91	<b>k</b>   {   107   7B   123
	14	34	54 <b>LA12</b>	74 <b>LA28</b>	114 TA12 134 TA28	154 <b>SA12</b> 174 <b>SA28</b>
1 1 0 0	<b>FF</b> C 12	FS 1C 28	<b>,</b> 2C 44	<b>C C C C C C C C C C</b>	L   \ 4C	6C 108 7C 124
	15	35	55 <b>LA13</b>	75 <b>LA29</b>	115 TA13 135 TA29	155 <b>SA13</b> 175 <b>SA29</b>
1 1 0 1	<b>CR</b> D 13	<b>GS</b> 1D 29	<b>–</b> 2D 45	= 3D 61	M   ] 4D 77 5D 93	<b>m</b>   }   6D   109   7D   125
	16	36	56 <b>LA14</b>	76 <b>LA30</b>	116 <b>TA14</b> 136 <b>TA30</b>	156 <b>SA14</b> 176 <b>SA30</b>
1 1 1 0	<b>SO</b> E 14	1E 30	• 2E 46	> 3E 62	N 78 5E 94	n ~ 110 7E 126
	17	37	57 <b>LA15</b>	77 UNL	117 <b>TA15</b> 137 <b>UNT</b>	157 <b>SA15</b> 177
1 1 1 1	<b>SI</b> F 15	<b>US</b> 1F 31	/ 2F 47	<b>?</b> 3F 63	<b>O</b> 79 5F 95	6F 111 7F (DEL) 127
	ADDRESSED	<u>I</u> UNIVERSAL	LIST	EN	TALK	SECONDARY ADDRESSES
	COMMANDS	COMMANDS	ADDRE		ADDRESSES	OR COMMANDS



**Tektronix** REF: ANSI STD X3.4-1977 IEEE STD 488.1-1987 ISO STD 646-2973

# **Appendix B: Reserved Words**

This is a list of reserved words for your instrument. Capital letters identify the required minimum spelling.

*641	1D) (an and	DITOrdor	CM1 OBV 1 F
*CAL	ADVanced	BITOrder	CM10BY15
*CLS	ALIas	BITRate	CM13BY18
*DDT	ALL	BITSTUFFing	CM15BY21
*ESE	ALLEV	BIT_Nr	CM18BY24
*ESR	ALLFields	BIT	СМ6ВҮ8
*IDN	ALLLines	BLAckmanharris	CM7BY10
*LRN	ALLQString	BM	CM9BY13
*OPC	ALTERNATE	BMP	CMEan
*PSC	ALWAYS	BN_Fmt	COLUMN
*PUD	AMPLitude	BOTh	COMMAND
*RCL	AMPSVIAVOLTS	BOX	CONDCALCmethod
*RST			CONDITION
	AND	BOXPCnt	
*SAV	ANY	BTRIGger	CONDuction
*SRE	APPKey	BURst	CONFigure
*STB	APPpwr	BUS	CONTRO
*TRG	AREa	BUSY	CONTinue
*TST	ASCII	BY	СОРУ
*WAI	ASSIgn	BYPass	COUNT
1CHx	ATRIGger	BYT_Nr	COUPling
1NR3	AUDio	BYT_Or	CPU
Α	AUTO	Block	CR
Α0	AUTOSet	C1	CRC
A1	AUTOZero	c2	CRC16
A2	AUX	C3	CRC5
A3	AUXOut	CALCmethod	CRCHeader
A4	AUXin	CALibrate	CRCTrailer
A5	AVErage	CAN	CREATE
A6			CRMS
	Auto	CANH	CROSSHair
A7	B	CANL	
A8	B0	CARD	CURRENTSOurce
Α9	B1	CARea	CURRent
ABORt	B2	CATalog	CURSor
ABOrt	в3	CH1	CURSors
ABSolute	В4	CH2	CURVe
AC	В5	CH3	CUSTom
ACK	в6	CH4	CWD
ACKMISS	В7	CHANnel	CYCLEcount
ACQ	в8	CHecksum	D
ACQLENGTH	в9	CLASSALIMit	D0
ACQuire	BACKLight	CLASS	D1
ACTIVeprinter	BACKWards	CLEAR	D10
ADD	BANdwidth	CLEARMenu	D11
ADDR10	BASE	CLEARSNapshot	D12
ADDR7	BDIFFBP	CLEar	D13
ADDRANDDATA		CLOCK	D13
	BINary	CLOCK	
ADDRess	BITDelay	CLUCK	D15

D2	DYNAMic	FIRST	HARM5ALTernate
D3	DX	FIVEdivs	HARMSOURce
D4	E	FIXEDFREQValue	HARMonics
D5	ECL	FIXEDFREQuency	HBArs
D6	EDGE	FLAg	HD1080I50
D7	EEPROM	FLEXray	HD1080I60
D8	EITher	FOCUS	HD1080P24
D9	ENAble	FOLder	HD1080P25
DATA	ENCdg	FORCEDRange	HD1080PSF24
DATA0	END	FORCe	HD480P60
DATA1	ENDPoint	FORMAt	HD720P60
DATABits	ENERGY	FORWards	HDtv
DATAPacket	ENERGYLOSS	FPAnel	HEADER
DATE	ENET	FRACTional	HEADer
DATEPrint	ENGLish	FRAME	HEADertime
DAll	ENV	FRAMEID	HEIght
DB	ENVelope	FRAMESync	HERtz
DC	EOF	FRAMEType	HEXadecimal
DDT	EOFTYPE	FRAMETypeid	HFRej
DECimal	EOP	FRAMEtype	HIGH
DEFLT	EQUal	FRAMING	HIGHLimit
DEFault	ERROR	FRAMetime	HIRes
DEFine	ERRORTYPe	FREE	HIStogram
DEGAUSS	ERRTYPE	FREESpace	HIVALue
DEGrees	ERRlog	FRENCh	HOLDTime
DELEte	ETHERnet	FREQREFerence	HOLDoff
DELIMiter	EVEN	FREQRef	HORizontal
DELTa	EVENT	FREQuency	HSmode
DELTatime	EVENTS	FULL	HTTPPort
DELay	EVENTtable	FUNCtion	HYSTeresis
DELayed	EVMsg	FUNDamental	I2C
DESE	EVQty	GAIN	I2S
DESKew	EXECute	GATEMid	ICRESTfactor
DESTination	EXT	GATESOurce	ID
DHCPbootp	EXTended	GATEWay	IDANDDATA
DIAg	EXTernal	GATIng	IDFORmat
DIFFerential	FACtor	GATe	IDLETime
DIGital	FACtory	GENeralcall	IDLEtime
DIR	FAIL	GERMan	IDPrint
DIRection	FAILures	GND	IDentifier
DISPlay	FALL	GPIBUsb	IEC
DISabled	FALSe	GRAph	IECMAX
DISplay	FALling	GRAticule	IMAGESize
DISplaymode	FASTPHOTO	GRId .	IMAGe
DMINUS	FASTer	GROUPing	IMAge
DNS	FAStest	HAGAKIPCARD	IMMed
DOMAINname	FFT	HALFġrat	IMPedance
DOTsonly	FIELD	HAMming .	IN
DPLUS	FIFty	HANDSHAKEPacket	IN11BY17
DPOModels	FILEFormat	HANDSHAKEType	IN2P5BY3P25
DRAFT	FILESystem	HANning	IN4BY6
DUAL	FILter	HARDCopy	IN8BY10
DUmp	FINE	HARM3ALTernate	INDBits

INDICators	LOW	NAK	PARity
INDIvidual	LOWCurrent	NAME	PASS
INDependent	LOWLimit	NANd	PASSFail
INFInite	LOWVoltage	NDUty	PASSWord
INIT	LOWerthreshold	NEGative	PATtern
INKSaver	LSB	NEWpass	PAYLength
INPUTPOWer	MAG	NEXT	PAYLoad
INPut	MAGnivu	NEXT	PDUty
INTENSITY	MAIN	NO	PEAKdetect
INTERLACED	MARK	NOCARE	PERCent
INTERNAT			PERIOD
	MARKSINCOLumn	NOISErej	PERSistence
INVERTed	MASK	NONE	
INVert	MATH	NONe	PERcent
INVerted	MATH1	NOPARity	PHASEangle
INrange	MATHVAR	NOR	PHASe
IO	MAX	NORMAL .	PHOTO
IPADDress	MAXAmps	NOTCOMPuted	PICTBridge
IRMS	MAXBytedelim	NRMAL .	PID
ISCLOCKed	MAXSamplerate	NR_HARMonics	PING
ITALian	MAXVolts	NR_PT	PLAIN
JAPAnese	MAXWatts	NTIMES	PLOTTYPe
KOREan	MAXimum	NTSC	PNG
L	MEAN	NULL	POHC
L2	MEAS	NULLFRDynamic	POHCLIMit
L4	MEASUrement	NULLFRStatic	POHL
LABEL	MEDium	NUMACq	POINTS
LANGuage	MEG	NUMAVg	POLARCord
LANdscape	MESSage	NUMCYCles	POLARity
LARge	METHOd	NUMENTries	POLar
LAYout	MID	NUMERic	PORTRait
LDIR	MID2	NUMEnv	PORTUguese
LEFt	MIL	NUMHORZ	POSition
LESSEQual	MIN	NUMVERT	POSitive
LESSLimit	MINImum	NWIdth	POWER
LESSThan	MINMax	OBSPERiod	POWERFACtor
LETTER	MISO	OCCURS	POWERFactor
LEVel			
	MISOMOSI MIXed	ODD	POWERLEVe1
LF		OFF OFF OFF	POWERLOSS
LFRej	MIXED2	OFFSet	POWer
LIMITS	MKD1r	ON	POWerupstatus
LIMit	MM100BY150	ONCE	PRESS
LIN	MM54BY86	ONFAIL	PREVIEW
LINE	MODE	OPTion	PREViewstate
LINEAr	MODULationanalysis	OR	PREVious
LINEFREQuency	MODe_	OUT	PREamble_
LINEPeriod	MODel	OUTrange	PRINTQual
LINear	MODulation	OVERLoad	PRINTer
LIST	MOREEQual	OWNer	PRODDELta
LJ	MORELimit	PACKET	PRODUCT
LOCk	MOREThan	PAL	PRODUCTID
LOG	MOREthan	PAPERSize	PROGressive
LOGIC	MOSI	PAPERType	PROPDELay
LOOP	MSB	PARallel	PRObe

PT_Fmt	RI	SETTime	STandard
PT_ORder	RIBinary	SETUP	SUBNETMask
PT_ORGET PT_Off	RIGht	SETUP	SUSPEND
PULSEWIDth	RIPPle	SHOW	SWITCHingloss
PULSEWIDTH	RISEFall	SIGMA1	_
	RISE	SIGMA2	SWLOSS SYNC
PULSE		~ - ~	
PULSE	RISing	SIGMA3	SYNCField
PWIdth	RJ	SIGNEDDECimal	SYNCFrame
QTY	RMDir	SIGnal SIMPlifiedchinese	SYNCInterval
QUALifier	RMS	SIMPTITTEGENTHESE SINGleended	TABle
QUALity	ROLL100MM		TDM
RADIUS	ROLL127MM	SIZe	TEKSecure
RATDELta	ROLL210MM	SLEEP	TEMPerature
RATE10K	ROLL89MM	SLEWRate	TERmination
RATE15K	ROM	SLOWer	TEST
RATE1M	RP	SLOpe	TESTnumber
RATE20K	RPBinary	SMAll.	THDELta
RATE25K	RS232	SNAPShot	THDF
RATE33K	RS232C	SNAp	THDR
RATE35K	RUN	SOA	THETA
RATE37K	RUNSTop	SOF .	THREshold
RATE50K	RUNT	SOFFRAMENUMber	TIFf
RATE62K	RUNT	SOURCE	TIME
RATE800K	RUSSian	SOURCE2	TOFF
RATIO	RWINClude	SPANish	TOKENPacket
RDELta	RX	SPC	TOKENType
RDSon	RXDATA	SPECIALPacket	TON
REACTpwr	RXENDPacket	SPECIALType	TOTAL
READ	RXSTArt	SPECTral	TOTaluptime
READFile	SAMPLERate	SPI	TRACk
READOUT	SAMPLEpoint	SPREADSheet	TRADitionalchinese
RECAll	SAMple	SPace	TRANsition
RECDESkew	SAVe	SRIbinary	TRIGger
RECOrdlength	SCAN	SRPbinary	TRIGgertosearch
RECTangular	SCAle	SS	TRUEpwr
REF	SCLK	STALL	TRUe
REF1	SCREEN	STANDard	TTL
REF2	SCREen	STANdard	TURN
REF3	SDATA	START	TURNON
REF4	SEARCH	STARTofframe	TWEnty
REFLevel	SEARCHtotrigger	STARTup	TWOfifty
REM	SECAM	STARTupnosync	TX
REMote	SEConds	STARt	TXDATA
REName	SELect	STARtbyte	TXENDPacket
REPEATstart	SELected	STATE	TXRX
RESERVed	SEQuence	STATIstics	TXSTArt
RESET	SERIALnumber	STATUS	TYPE
RESOlution	SERnumber	STATic	Than
RESPtime	SET	STDdev	UNDO
RESUME	SETALLtorec	STOP	UNEQual
RESUlt	SETHold	STOPAfter	UNITS
RESistance	SETLevel	STOPOnviol	UNLock
RESults	SETTODEFaults	STYle	UPPerthreshold

USB	VERTAUTOset	WFMOutpre	XY
USBDevice	VERTDEFault	WHEn	XZEro
USBTMC	VERTical	WIDth	Υ
USBTmc	VIDeo	WINdow	YDELta
USE	VOLTAGESOurce	WORD	YES
USER	VOLTage	WORDSel	YMAX
V1X	VOLts	WRITE	YMIN
V2X	VRMS	WRITEFile	YMUlt
VALue	WAKEup	X	YOFf
VBArs	WAVEFORMS	XDELta	YT
VCEsat	WAVEform	XFF	YUNIts
VCRESTfactor	WAVFrm	XINCr	YUNit
VDELTa	WEIghting	XMAX	YUNits
VENDORID	WFId	XMIN	YZEro
VERBose	WFMInpre	XUNit	ZOOm

# **Appendix C: Factory Defaults**

# **Default Setup**

The following table lists the default values for each command.

**NOTE.** Find the most up-to-date default values for your instrument and software by performing a TekSecure command, saving the instrument setup and looking at the instrument or setup file.

Table C-1: Default values

Command	Default value
ACQ:MAG	0
ACQ:MOD	SAM
ACQ:NUMAV	16
ACQ:NUME	INFI
ACQ:STATE	1
ACQ:STOPA	RUNST
ALI	0
AUX:PRO:FORCEDR	0.0E+0
AUX:PRO:GAIN	1.0000
BUS:B1:CAN:BITR	500000
BUS:B1:CAN:PRO	CANH
BUS:B1:CAN:SAMPLE	50
BUS:B1:CAN:SOU	CH1
BUS:B1:DIS:FORM	HEX
BUS:B1:DIS:TYP	BUS
BUS:B1:I2C:ADDR:RWINC	0
BUS:B1:I2C:CLOC:SOU	CH1
BUS:B1:I2C:DAT:SOU	CH2
BUS:B1:LAB	"Parallel"
BUS:B1:LIN:BITR	19200
BUS:B1:LIN:IDFOR	NOPAR
BUS:B1:LIN:POL	NORM
BUS:B1:LIN:SAMPLE	50
BUS:B1:LIN:SOU	CH1
BUS:B1:LIN:STAND	V2X
BUS:B1:PAR:BIT0:SOU	D0
BUS:B1:PAR:BIT10:SOU	D10

Table C-1: Default values (cont.)

BUS:B1:PAR:BIT11:SOU         D11           BUS:B1:PAR:BIT12:SOU         D12           BUS:B1:PAR:BIT13:SOU         D13           BUS:B1:PAR:BIT14:SOU         D14	
BUS:B1:PAR:BIT13:SOU D13	
BUS:B1:PAR:BIT14:SOU D14	
BUS:B1:PAR:BIT15:SOU D15	
BUS:B1:PAR:BIT16:SOU CH1	
BUS:B1:PAR:BIT17:SOU CH2	
BUS:B1:PAR:BIT18:SOU CH3	
BUS:B1:PAR:BIT19:SOU CH4	
BUS:B1:PAR:BIT1:SOU D1	_
BUS:B1:PAR:BIT2:SOU D2	_
BUS:B1:PAR:BIT3:SOU D3	
BUS:B1:PAR:BIT4:SOU D4	_
BUS:B1:PAR:BIT5:SOU D5	_
BUS:B1:PAR:BIT6:SOU D6	_
BUS:B1:PAR:BIT7:SOU D7	
BUS:B1:PAR:BIT8:SOU D8	_
BUS:B1:PAR:BIT9:SOU D9	_
BUS:B1:PAR:CLOC:EDGE RIS	_
BUS:B1:PAR:CLOC:ISCLOCK NO	_
BUS:B1:PAR:CLOC:SOU CH1	
BUS:B1:PAR:WID 16	
BUS:B1:POS 0.0E+	-0
BUS:B1:RS232C:BITR 9600	
BUS:B1:RS232C:DATAB 8	_
BUS:B1:RS232C:DELIM LF	
BUS:B1:RS232C:DIS FRA	
BUS:B1:RS232C:PAR NON	
BUS:B1:RS232C:POL NORI	M
BUS:B1:RS232C:RX:SOU OFF	
BUS:B1:RS232C:TX:SOU CH1	
BUS:B1:SPI:BITO MSB	
BUS:B1:SPI:CLOC:POL RIS	
BUS:B1:SPI:CLOC:SOU CH1	
BUS:B1:SPI:DAT:IN:POL HIGH	
BUS:B1:SPI:DAT:IN:SOU OFF	
BUS:B1:SPI:DAT:OUT:POL HIGH	

Table C-1: Default values (cont.)

Command	Default value
BUS:B1:SPI:DAT:OUT:SOU	CH3
BUS:B1:SPI:DAT:SIZ	8
BUS:B1:SPI:FRAMING	SS
BUS:B1:SPI:IDLET	5.0000E-6
BUS:B1:SPI:SEL:POL	LOW
BUS:B1:SPI:SEL:SOU	CH2
BUS:B1:STATE	0
BUS:B1:TYP	PAR
BUS:B1:USB:BITR	FULL
BUS:B1:USB:PRO	DIFF
BUS:B1:USB:SOU:DIFF	CH1
BUS:B1:USB:SOU:DMIN	CH2
BUS:B1:USB:SOU:DPLU	CH1
BUS:B2:CAN:BITR	500000
BUS:B2:CAN:PRO	CANH
BUS:B2:CAN:SAMPLE	50
BUS:B2:CAN:SOU	CH1
BUS:B2:DIS:FORM	HEX
BUS:B2:DIS:TYP	BUS
BUS:B2:I2C:ADDR:RWINC	0
BUS:B2:I2C:CLOC:SOU	CH1
BUS:B2:I2C:DAT:SOU	CH2
BUS:B2:LAB	"Parallel"
BUS:B2:LIN:BITR	19200
BUS:B2:LIN:IDFOR	NOPAR
BUS:B2:LIN:POL	NORM
BUS:B2:LIN:SAMPLE	50
BUS:B2:LIN:SOU	CH1
BUS:B2:LIN:STAND	V2X
BUS:B2:PAR:BIT0:SOU	D0
BUS:B2:PAR:BIT10:SOU	D10
BUS:B2:PAR:BIT11:SOU	D11
BUS:B2:PAR:BIT12:SOU	D12
BUS:B2:PAR:BIT13:SOU	D13
BUS:B2:PAR:BIT14:SOU	D14
BUS:B2:PAR:BIT15:SOU	D15
BUS:B2:PAR:BIT16:SOU	CH1

Table C-1: Default values (cont.)

Command	Default value
BUS:B2:PAR:BIT17:SOU	CH2
BUS:B2:PAR:BIT18:SOU	CH3
BUS:B2:PAR:BIT19:SOU	CH4
BUS:B2:PAR:BIT1:SOU	D1
BUS:B2:PAR:BIT2:SOU	D2
BUS:B2:PAR:BIT3:SOU	D3
BUS:B2:PAR:BIT4:SOU	D4
BUS:B2:PAR:BIT5:SOU	D5
BUS:B2:PAR:BIT6:SOU	D6
BUS:B2:PAR:BIT7:SOU	D7
BUS:B2:PAR:BIT8:SOU	D8
BUS:B2:PAR:BIT9:SOU	D9
BUS:B2:PAR:CLOC:EDGE	RIS
BUS:B2:PAR:CLOC:ISCLOCK	NO
BUS:B2:PAR:CLOC:SOU	CH1
BUS:B2:PAR:WID	16
BUS:B2:POS	0.0E+0
BUS:B2:RS232C:BITR	9600
BUS:B2:RS232C:DATAB	8
BUS:B2:RS232C:DELIM	LF
BUS:B2:RS232C:DIS	FRA
BUS:B2:RS232C:PAR	NON
BUS:B2:RS232C:POL	NORM
BUS:B2:RS232C:RX:SOU	OFF
BUS:B2:RS232C:TX:SOU	CH1
BUS:B2:SPI:BITO	MSB
BUS:B2:SPI:CLOC:POL	RIS
BUS:B2:SPI:CLOC:SOU	CH1
BUS:B2:SPI:DAT:IN:POL	HIGH
BUS:B2:SPI:DAT:IN:SOU	OFF
BUS:B2:SPI:DAT:OUT:POL	HIGH
BUS:B2:SPI:DAT:OUT:SOU	CH3
BUS:B2:SPI:DAT:SIZ	8
BUS:B2:SPI:FRAMING	SS
BUS:B2:SPI:IDLET	5.0000E-6
BUS:B2:SPI:SEL:POL	LOW
BUS:B2:SPI:SEL:SOU	CH2

Table C-1: Default values (cont.)

Command	Default value
BUS:B2:STATE	0
BUS:B2:TYP	PAR
BUS:B2:USB:BITR	FULL
BUS:B2:USB:PRO	DIFF
BUS:B2:USB:SOU:DIFF	CH1
BUS:B2:USB:SOU:DMIN	CH2
BUS:B2:USB:SOU:DPLU	CH1
BUS:B3:CAN:BITR	500000
BUS:B3:CAN:PRO	CANH
BUS:B3:CAN:SAMPLE	50
BUS:B3:CAN:SOU	CH1
BUS:B3:DIS:FORM	HEX
BUS:B3:DIS:TYP	BUS
BUS:B3:I2C:ADDR:RWINC	0
BUS:B3:I2C:CLOC:SOU	CH1
BUS:B3:I2C:DAT:SOU	CH2
BUS:B3:LAB	"Parallel"
BUS:B3:LIN:BITR	19200
BUS:B3:LIN:IDFOR	NOPAR
BUS:B3:LIN:POL	NORM
BUS:B3:LIN:SAMPLE	50
BUS:B3:LIN:SOU	CH1
BUS:B3:LIN:STAND	V2X
BUS:B3:PAR:BIT0:SOU	D0
BUS:B3:PAR:BIT10:SOU	D10
BUS:B3:PAR:BIT11:SOU	D11
BUS:B3:PAR:BIT12:SOU	D12
BUS:B3:PAR:BIT13:SOU	D13
BUS:B3:PAR:BIT14:SOU	D14
BUS:B3:PAR:BIT15:SOU	D15
BUS:B3:PAR:BIT16:SOU	CH1
BUS:B3:PAR:BIT17:SOU	CH2
BUS:B3:PAR:BIT18:SOU	CH3
BUS:B3:PAR:BIT19:SOU	CH4
BUS:B3:PAR:BIT1:SOU	D1
BUS:B3:PAR:BIT2:SOU	D2
BUS:B3:PAR:BIT3:SOU	D3

Table C-1: Default values (cont.)

Command	Default value
BUS:B3:PAR:BIT4:SOU	D4
BUS:B3:PAR:BIT5:SOU	D5
BUS:B3:PAR:BIT6:SOU	D6
BUS:B3:PAR:BIT7:SOU	D7
BUS:B3:PAR:BIT8:SOU	D8
BUS:B3:PAR:BIT9:SOU	D9
BUS:B3:PAR:CLOC:EDGE	RIS
BUS:B3:PAR:CLOC:ISCLOCK	NO
BUS:B3:PAR:CLOC:SOU	CH1
BUS:B3:PAR:WID	16
BUS:B3:POS	0.0E+0
BUS:B3:RS232C:BITR	9600
BUS:B3:RS232C:DATAB	8
BUS:B3:RS232C:DELIM	LF
BUS:B3:RS232C:DIS	FRA
BUS:B3:RS232C:PAR	NON
BUS:B3:RS232C:POL	NORM
BUS:B3:RS232C:RX:SOU	OFF
BUS:B3:RS232C:TX:SOU	CH1
BUS:B3:SPI:BITO	MSB
BUS:B3:SPI:CLOC:POL	RIS
BUS:B3:SPI:CLOC:SOU	CH1
BUS:B3:SPI:DAT:IN:POL	HIGH
BUS:B3:SPI:DAT:IN:SOU	OFF
BUS:B3:SPI:DAT:OUT:POL	HIGH
BUS:B3:SPI:DAT:OUT:SOU	CH3
BUS:B3:SPI:DAT:SIZ	8
BUS:B3:SPI:FRAMING	SS
BUS:B3:SPI:IDLET	5.0000E-6
BUS:B3:SPI:SEL:POL	LOW
BUS:B3:SPI:SEL:SOU	CH2
BUS:B3:STATE	0
BUS:B3:TYP	PAR
BUS:B3:USB:BITR	FULL
BUS:B3:USB:PRO	DIFF
BUS:B3:USB:SOU:DIFF	CH1
BUS:B3:USB:SOU:DMIN	CH2

Table C-1: Default values (cont.)

Command	Default value
BUS:B3:USB:SOU:DPLU	CH1
BUS:B4:CAN:BITR	500000
BUS:B4:CAN:PRO	CANH
BUS:B4:CAN:SAMPLE	50
BUS:B4:CAN:SOU	CH1
BUS:B4:DIS:FORM	HEX
BUS:B4:DIS:TYP	BUS
BUS:B4:I2C:ADDR:RWINC	0
BUS:B4:I2C:CLOC:SOU	CH1
BUS:B4:I2C:DAT:SOU	CH2
BUS:B4:LAB	"Parallel"
BUS:B4:LIN:BITR	19200
BUS:B4:LIN:IDFOR	NOPAR
BUS:B4:LIN:POL	NORM
BUS:B4:LIN:SAMPLE	50
BUS:B4:LIN:SOU	CH1
BUS:B4:LIN:STAND	V2X
BUS:B4:PAR:BIT0:SOU	D0
BUS:B4:PAR:BIT10:SOU	D10
BUS:B4:PAR:BIT11:SOU	D11
BUS:B4:PAR:BIT12:SOU	D12
BUS:B4:PAR:BIT13:SOU	D13
BUS:B4:PAR:BIT14:SOU	D14
BUS:B4:PAR:BIT15:SOU	D15
BUS:B4:PAR:BIT16:SOU	CH1
BUS:B4:PAR:BIT17:SOU	CH2
BUS:B4:PAR:BIT18:SOU	CH3
BUS:B4:PAR:BIT19:SOU	CH4
BUS:B4:PAR:BIT1:SOU	D1
BUS:B4:PAR:BIT2:SOU	D2
BUS:B4:PAR:BIT3:SOU	D3
BUS:B4:PAR:BIT4:SOU	D4
BUS:B4:PAR:BIT5:SOU	D5
BUS:B4:PAR:BIT6:SOU	D6
BUS:B4:PAR:BIT7:SOU	D7
BUS:B4:PAR:BIT8:SOU	D8
BUS:B4:PAR:BIT9:SOU	D9

Table C-1: Default values (cont.)

Command	Default value
BUS:B4:PAR:CLOC:EDGE	RIS
BUS:B4:PAR:CLOC:ISCLOCK	NO
BUS:B4:PAR:CLOC:SOU	CH1
BUS:B4:PAR:WID	16
BUS:B4:POS	0.0E+0
BUS:B4:RS232C:BITR	9600
BUS:B4:RS232C:DATAB	8
BUS:B4:RS232C:DELIM	LF
BUS:B4:RS232C:DIS	FRA
BUS:B4:RS232C:PAR	NON
BUS:B4:RS232C:POL	NORM
BUS:B4:RS232C:RX:SOU	OFF
BUS:B4:RS232C:TX:SOU	CH1
BUS:B4:SPI:BITO	MSB
BUS:B4:SPI:CLOC:POL	RIS
BUS:B4:SPI:CLOC:SOU	CH1
BUS:B4:SPI:DAT:IN:POL	HIGH
BUS:B4:SPI:DAT:IN:SOU	OFF
BUS:B4:SPI:DAT:OUT:POL	HIGH
BUS:B4:SPI:DAT:OUT:SOU	CH3
BUS:B4:SPI:DAT:SIZ	8
BUS:B4:SPI:FRAMING	SS
BUS:B4:SPI:IDLET	5.0000E-6
BUS:B4:SPI:SEL:POL	LOW
BUS:B4:SPI:SEL:SOU	CH2
BUS:B4:STATE	0
BUS:B4:TYP	PAR
BUS:B4:USB:BITR	FULL
BUS:B4:USB:PRO	DIFF
BUS:B4:USB:SOU:DIFF	CH1
BUS:B4:USB:SOU:DMIN	CH2
BUS:B4:USB:SOU:DPLU	CH1
BUS:LOW:CH1	0.0E+0
BUS:LOW:CH2	0.0E+0
BUS:LOW:CH3	0.0E+0
BUS:LOW:CH4	0.0E+0
BUS:UPP:CH1	800.0000E-3

Table C-1: Default values (cont.)

Command	Default value
BUS:UPP:CH2	800.0000E-3
BUS:UPP:CH3	800.0000E-3
BUS:UPP:CH4	800.0000E-3
CH1:AMPSVIAVOLT:ENA	0
CH1:AMPSVIAVOLT:FAC	10.0000
CH1:BAN	500.0000E+6
CH1:COUP	DC
CH1:DESK	0.0E+0
CH1:INV	0
CH1:LAB	IIII
CH1:OFFS	0.0E+0
CH1:POS	0.0E+0
CH1:PRO:FORCEDR	0.0E+0
CH1:PRO:GAIN	1.0000
CH1:PRO:MOD	"Other"
CH1:PRO:PROPDEL	0.0E+0
CH1:SCA	100.0000E-3
CH1:TER	1.0000E+6
CH1:YUN	"V"
CH1:YUN CH2:AMPSVIAVOLT:ENA	"V" 0
CH2:AMPSVIAVOLT:ENA	0
CH2:AMPSVIAVOLT:ENA CH2:AMPSVIAVOLT:FAC	10.0000
CH2:AMPSVIAVOLT:ENA CH2:AMPSVIAVOLT:FAC CH2:BAN	0 10.0000 500.0000E+6
CH2:AMPSVIAVOLT:ENA CH2:AMPSVIAVOLT:FAC CH2:BAN CH2:COUP	0 10.0000 500.0000E+6 DC
CH2:AMPSVIAVOLT:ENA CH2:BAN CH2:COUP CH2:DESK	0 10.0000 500.0000E+6 DC 0.0E+0
CH2:AMPSVIAVOLT:ENA CH2:AMPSVIAVOLT:FAC CH2:BAN CH2:COUP CH2:DESK CH2:INV	0 10.0000 500.0000E+6 DC 0.0E+0
CH2:AMPSVIAVOLT:ENA CH2:BAN CH2:COUP CH2:DESK CH2:INV CH2:LAB	0 10.0000 500.0000E+6 DC 0.0E+0 0
CH2:AMPSVIAVOLT:ENA CH2:AMPSVIAVOLT:FAC CH2:BAN CH2:COUP CH2:DESK CH2:INV CH2:LAB CH2:OFFS	0 10.0000 500.0000E+6 DC 0.0E+0 0
CH2:AMPSVIAVOLT:ENA CH2:BAN CH2:COUP CH2:DESK CH2:INV CH2:LAB CH2:OFFS CH2:POS	0 10.0000 500.0000E+6 DC 0.0E+0 0 "" 0.0E+0
CH2:AMPSVIAVOLT:ENA CH2:AMPSVIAVOLT:FAC CH2:BAN CH2:COUP CH2:DESK CH2:INV CH2:LAB CH2:OFFS CH2:POS CH2:PRO:FORCEDR	0 10.0000 500.0000E+6 DC 0.0E+0 0 "" 0.0E+0 0.0E+0
CH2:AMPSVIAVOLT:ENA CH2:BAN CH2:COUP CH2:DESK CH2:INV CH2:LAB CH2:OFFS CH2:POS CH2:PRO:FORCEDR CH2:PRO:GAIN	0 10.0000 500.0000E+6 DC 0.0E+0 0 "" 0.0E+0 0.0E+0 1.0000 "Other" 0.0E+0
CH2:AMPSVIAVOLT:ENA CH2:AMPSVIAVOLT:FAC CH2:BAN CH2:COUP CH2:DESK CH2:INV CH2:LAB CH2:OFFS CH2:POS CH2:PR0:FORCEDR CH2:PR0:GAIN CH2:PRO:MOD	0 10.0000 500.0000E+6 DC 0.0E+0 0 "" 0.0E+0 0.0E+0 1.0000 "Other"
CH2:AMPSVIAVOLT:ENA CH2:BAN CH2:COUP CH2:DESK CH2:INV CH2:LAB CH2:OFFS CH2:POS CH2:PRO:FORCEDR CH2:PRO:MOD CH2:PRO:PROPDEL	0 10.0000 500.0000E+6 DC 0.0E+0 0 "" 0.0E+0 0.0E+0 1.0000 "Other" 0.0E+0 100.0000E-3 1.0000E+6
CH2:AMPSVIAVOLT:ENA CH2:BAN CH2:COUP CH2:DESK CH2:INV CH2:LAB CH2:OFFS CH2:POS CH2:POS CH2:PRO:GAIN CH2:PRO:PROPDEL CH2:PRO:PROPDEL CH2:SCA	0 10.0000 500.0000E+6 DC 0.0E+0 0 "" 0.0E+0 0.0E+0 1.0000 "Other" 0.0E+0 100.0000E-3
CH2:AMPSVIAVOLT:ENA CH2:AMPSVIAVOLT:FAC CH2:BAN CH2:COUP CH2:DESK CH2:INV CH2:LAB CH2:OFFS CH2:POS CH2:PRO:FORCEDR CH2:PRO:GAIN CH2:PRO:DESC CH2:PRO:PROPDEL CH2:SCA CH2:TER	0 10.0000 500.0000E+6 DC 0.0E+0 0 "" 0.0E+0 0.0E+0 1.0000 "Other" 0.0E+0 100.0000E-3 1.0000E+6

Table C-1: Default values (cont.)

Command	Default value
CH3:BAN	500.0000E+6
CH3:COUP	DC
CH3:DESK	0.0E+0
CH3:INV	0
CH3:LAB	III
CH3:OFFS	0.0E+0
CH3:POS	0.0E+0
CH3:PRO:FORCEDR	0.0E+0
CH3:PRO:GAIN	1.0000
CH3:PRO:MOD	"Other"
CH3:PRO:PROPDEL	0.0E+0
CH3:SCA	100.0000E-3
CH3:TER	1.0000E+6
CH3:YUN	"V"
CH4:AMPSVIAVOLT:ENA	0
CH4:AMPSVIAVOLT:FAC	10.0000
CH4:BAN	500.0000E+6
CH4:COUP	DC
CH4:DESK	0.0E+0
CH4:INV	0
CH4:LAB	mii
CH4:OFFS	0.0E+0
CH4:POS	0.0E+0
CH4:PRO:FORCEDR	0.0E+0
CH4:PRO:GAIN	1.0000
CH4:PRO:MOD	"Other"
CH4:PRO:PROPDEL	0.0E+0
CH4:SCA	100.0000E-3
CH4:TER	1.0000E+6
CH4:YUN	"V"
CURS:FUNC	OFF
CURS:HBA:POSITION1	0.0E+0
CURS:HBA:POSITION2	0.0E+0
CURS:HBA:UNI	BAS
CURS:MOD	IND
CURS:VBA:POSITION1	0.0E+0
CURS:VBA:POSITION2	0.0E+0

Table C-1: Default values (cont.)

Command	Default value
CURS:VBA:UNI	SEC
CURS:XY:READOUT	RECT
CURS:XY:RECT:X:POSITION1	0.0E+0
CURS:XY:RECT:X:POSITION2	0.0E+0
CURS:XY:RECT:Y:POSITION1	0.0E+0
CURS:XY:RECT:Y:POSITION2	0.0E+0
D0:LAB	ни
D0:POS	60.0000E-3
D0:THRE	1.4000
D10:LAB	1111
D10:POS	60.0000E-3
D10:THRE	1.4000
D11:LAB	1111
D11:POS	60.0000E-3
D11:THRE	1.4000
D12:LAB	""
D12:POS	60.0000E-3
D12:THRE	1.4000
D13:LAB	""
D13:POS	60.0000E-3
D13:THRE	1.4000
D14:LAB	""
D14:POS	60.0000E-3
D14:THRE	1.4000
D15:LAB	nn
D15:POS	60.0000E-3
D15:THRE	1.4000
D1:LAB	nn
D1:POS	60.0000E-3
D1:THRE	1.4000
D2:LAB	1111
D2:POS	60.0000E-3
D2:THRE	1.4000
D3:LAB	nn
D3:POS	60.0000E-3
D3:THRE	1.4000
D4:LAB	""

Table C-1: Default values (cont.)

Command	Default value
D4:POS	60.0000E-3
D4:THRE	1.4000
D5:LAB	""
D5:POS	60.0000E-3
D5:THRE	1.4000
D6:LAB	""
D6:POS	60.0000E-3
D6:THRE	1.4000
D7:LAB	""
D7:POS	60.0000E-3
D7:THRE	1.4000
D8:LAB	111
D8:POS	60.0000E-3
D8:THRE	1.4000
D9:LAB	111
D9:POS	60.0000E-3
D9:THRE	1.4000
DAT:DEST	REF1
DAT:ENC	RIB
DAT:SOU	CH1
DAT:STAR	1
DAT:STOP	10000
DES:DISP	1
DIS:CLOC	1
DIS:DIG:HEI	MED
DIS:FORM	YT
DIS:GRA	FUL
DIS:INTENSIT:BACKL	HIGH
DIS:INTENSIT:GRA	75
DIS:INTENSIT:WAVE	35
DIS:PERS	0.0E+0
DIS:STY:DOT	0
DIS:TRIGF	0
HARDC:INKS	1
HARDC:LAY	LAN
HARDC:PREVIEW	0
HEAD	0

Table C-1: Default values (cont.)

Command	Default value
HIS:BOXP	20.0000,20.0000,80.0000,80.0000
HIS:DIS	LINEA
HIS:MOD	OFF
HIS:SOU	CH1
HOR:DEL:MOD	1
HOR:DEL:TIM	0.0E+0
HOR:POS	50.0000
HOR:RECO	10000
HOR:SCA	4.0000E-6
LOC	NON
MATH:DEF	"CH1+CH2"
MATH:HOR:POS	50.0000
MATH:HOR:SCA	4.0000E-6
MATH:HOR:UNI	"s"
MATH:LAB	111
MATH:SPECT:MAG	DB
MATH:SPECT:WIN	HAN
MATH:TYP	DUAL
MATH:VERT:POS	0.0E+0
MATH:VERT:SCA	100.0000E-3
MATH:VERT:UNI	"V"
MATHVAR:VAR1	0.0E+0
MATHVAR:VAR2	0.0E+0
MEASU:GAT	SCRE
MEASU:IMM:DEL:DIR	FORW
MEASU:IMM:DEL:EDGE1	RIS
MEASU:IMM:DEL:EDGE2	RIS
MEASU:IMM:SOU1	CH1
MEASU:IMM:SOU2	CH2
MEASU:IMM:TYP	PERI
MEASU:INDIC:STATE	OFF
MEASU:MEAS1:DEL:DIR	FORW
MEASU:MEAS1:DEL:EDGE1	RIS
MEASU:MEAS1:DEL:EDGE2	RIS
MEASU:MEAS1:SOU1	CH1
MEASU:MEAS1:SOU2	CH2
MEASU:MEAS1:STATE	0

Table C-1: Default values (cont.)

MEASU:MEAS2:DEL:DIR	
	IS IS
MEASU:MEAS2:DEL:EDGE1	IS
MEASU:MEAS2:DEL:EDGE2	111
MEASU:MEAS2:SOU1 C	:H1
MEASU:MEAS2:SOU2 C	H2
MEASU:MEAS2:STATE 0	
MEASU:MEAS2:TYP PI	ERI
MEASU:MEAS3:DEL:DIR	ORW
MEASU:MEAS3:DEL:EDGE1 R	IS
MEASU:MEAS3:DEL:EDGE2	IS
MEASU:MEAS3:SOU1 C	H1
MEASU:MEAS3:SOU2 C	H2
MEASU:MEAS3:STATE 0	
MEASU:MEAS3:TYP PI	ERI
MEASU:MEAS4:DEL:DIR FO	ORW
MEASU:MEAS4:DEL:EDGE1 R	IS
MEASU:MEAS4:DEL:EDGE2	IS
MEASU:MEAS4:SOU1 C	H1
MEASU:MEAS4:SOU2 C	H2
MEASU:MEAS4:STATE 0	
MEASU:MEAS4:TYP PI	ERI
MEASU:MEAS5:DEL:DIR FO	ORW
MEASU:MEAS5:DEL:EDGE1	IS
MEASU:MEAS5:DEL:EDGE2	IS
MEASU:MEAS5:SOU1 C	H1
MEASU:MEAS5:SOU2 C	H2
MEASU:MEAS5:STATE 0	
MEASU:MEAS5:TYP PI	ERI
MEASU:MEAS6:DEL:DIR FO	ORW
MEASU:MEAS6:DEL:EDGE1 R	IS
MEASU:MEAS6:DEL:EDGE2	IS
MEASU:MEAS6:SOU1 C	H1
MEASU:MEAS6:SOU2 C	H2
MEASU:MEAS6:STATE 0	
MEASU:MEAS6:TYP PI	ERI
MEASU:MEAS7:DEL:DIR FO	ORW

Table C-1: Default values (cont.)

Command	Default value
MEASU:MEAS7:DEL:EDGE1	RIS
MEASU:MEAS7:DEL:EDGE2	RIS
MEASU:MEAS7:SOU1	CH1
MEASU:MEAS7:SOU2	CH2
MEASU:MEAS7:STATE	0
MEASU:MEAS7:TYP	PERI
MEASU:MEAS8:DEL:DIR	FORW
MEASU:MEAS8:DEL:EDGE1	RIS
MEASU:MEAS8:DEL:EDGE2	RIS
MEASU:MEAS8:SOU1	CH1
MEASU:MEAS8:SOU2	CH2
MEASU:MEAS8:STATE	0
MEASU:MEAS8:TYP	PERI
MEASU:METH	A
MEASU:REFL:ABS:HIGH	0.0E+0
MEASU:REFL:ABS:LOW	0.0E+0
MEASU:REFL:ABS:MID1	0.0E+0
MEASU:REFL:ABS:MID2	0.0E+0
MEASU:REFL:METH	PERC
MEASU:REFL:PERC:HIGH	90.0000
MEASU:REFL:PERC:LOW	10.0000
MEASU:REFL:PERC:MID1	50.0000
MEASU:REFL:PERC:MID2	50.0000
MEASU:STATI:MODE	ALL
MEASU:STATI:WEI	32
MESS:BOX	271,82,271,98
MESS:SHOW	""
MESS:STATE	0
PICTB:DATEP	DEFLT
PICTB:IDP	OFF
PICTB:IMAGES	DEFLT
PICTB:PAPERS	DEFLT
PICTB:PAPERT	DEFLT
PICTB:PRINTQ	DEFLT
REF1:HOR:DEL:TIM	0.0E+0
REF1:HOR:SCA	4.0000E-6
REF1:VERT:POS	0.0E+0

Table C-1: Default values (cont.)

Command	Default value
REF1:VERT:SCA	100.0000E-3
REF2:HOR:DEL:TIM	0.0E+0
REF2:HOR:SCA	4.0000E-6
REF2:VERT:POS	0.0E+0
REF2:VERT:SCA	100.0000E-3
REF3:HOR:DEL:TIM	0.0E+0
REF3:HOR:SCA	4.0000E-6
REF3:VERT:POS	0.0E+0
REF3:VERT:SCA	100.0000E-3
REF4:HOR:DEL:TIM	0.0E+0
REF4:HOR:SCA	4.0000E-6
REF4:VERT:POS	0.0E+0
REF4:VERT:SCA	100.0000E-3
SAV:ASSI:TYP	IMAG
SAV:IMAG:FILEF	PNG
SAV:IMAG:INKS	1
SAV:IMAG:LAY	LAN
SAV:WAVE:FILEF	SPREADS
SAV:WAVE:GATI	NON
SEARCH:SEARCH1:STATE	0
SEARCH:SEARCH1:TRIG:A:BUS:B1:CAN:COND	SOF
SEARCH:SEARCH1:TRIG:A:BUS:B1:CAN:DAT:DIR	NOCARE
SEARCH:SEARCH1:TRIG:A:BUS:B1:CAN:DAT:QUAL	EQU
SEARCH:SEARCH1:TRIG:A:BUS:B1:CAN:DAT:SIZ	1
SEARCH:SEARCH1:TRIG:A:BUS:B1:CAN:DAT:VAL	"XXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B1:CAN:FRAME	DATA
SEARCH:SEARCH1:TRIG:A:BUS:B1:CAN:ID:MOD	ST
SEARCH:SEARCH1:TRIG:A:BUS:B1:CAN:ID:VAL	"XXXXXXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B1:I2C:ADDR:MOD	ADDR7
SEARCH:SEARCH1:TRIG:A:BUS:B1:I2C:ADDR:TYP	USER
SEARCH:SEARCH1:TRIG:A:BUS:B1:I2C:ADDR:VAL	"XXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B1:I2C:COND	STAR
SEARCH:SEARCH1:TRIG:A:BUS:B1:I2C:DAT:DIR	NOCARE
SEARCH:SEARCH1:TRIG:A:BUS:B1:I2C:DAT:SIZ	1
SEARCH:SEARCH1:TRIG:A:BUS:B1:I2C:DAT:VAL	"XXXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B1:LIN:COND	SYNCF
SEARCH:SEARCH1:TRIG:A:BUS:B1:LIN:DAT:HIVAL	"XXXXXXXX"

Table C-1: Default values (cont.)

Command	Default value
SEARCH:SEARCH1:TRIG:A:BUS:B1:LIN:DAT:QUAL	EQU
SEARCH:SEARCH1:TRIG:A:BUS:B1:LIN:DAT:SIZ	1
SEARCH:SEARCH1:TRIG:A:BUS:B1:LIN:DAT:VAL	"XXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B1:LIN:ERRTYPE	SYNC
SEARCH:SEARCH1:TRIG:A:BUS:B1:LIN:ID:VAL	"XXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B1:PAR:VAL	"XXXXXXXXXXXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B1:RS232C:COND	TXSTA
SEARCH:SEARCH1:TRIG:A:BUS:B1:RS232C:RX:DAT:SIZ	1
SEARCH:SEARCH1:TRIG:A:BUS:B1:RS232C:RX:DAT:VAL	"XXXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B1:RS232C:TX:DAT:SIZ	1
SEARCH:SEARCH1:TRIG:A:BUS:B1:RS232C:TX:DAT:VAL	"XXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B1:SPI:COND	SS
SEARCH:SEARCH1:TRIG:A:BUS:B1:SPI:DAT:MISO:VAL	"XXXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B1:SPI:DAT:MOSI:VAL	"XXXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B1:SPI:DAT:SIZ	1
SEARCH:SEARCH1:TRIG:A:BUS:B1:USB:ADDR:HIVAL	"XXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B1:USB:ADDR:VAL	"XXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B1:USB:COND	SYNC
SEARCH:SEARCH1:TRIG:A:BUS:B1:USB:DAT:HIVAL	"XXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B1:USB:DAT:OFFS	-1
SEARCH:SEARCH1:TRIG:A:BUS:B1:USB:DAT:SIZ	1
SEARCH:SEARCH1:TRIG:A:BUS:B1:USB:DAT:TYP	ANY
SEARCH:SEARCH1:TRIG:A:BUS:B1:USB:DAT:VAL	"XXXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B1:USB:ENDP:VAL	"XXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B1:USB:ERRTYPE	PID
SEARCH:SEARCH1:TRIG:A:BUS:B1:USB:HANDSHAKET	ANY
SEARCH:SEARCH1:TRIG:A:BUS:B1:USB:QUAL	EQU
SEARCH:SEARCH1:TRIG:A:BUS:B1:USB:SOFFRAMENUM	"XXXXXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B1:USB:SPECIALT	ANY
SEARCH:SEARCH1:TRIG:A:BUS:B1:USB:TOKENT	ANY
SEARCH:SEARCH1:TRIG:A:BUS:B2:CAN:COND	SOF
SEARCH:SEARCH1:TRIG:A:BUS:B2:CAN:DAT:DIR	NOCARE
SEARCH:SEARCH1:TRIG:A:BUS:B2:CAN:DAT:QUAL	EQU
SEARCH:SEARCH1:TRIG:A:BUS:B2:CAN:DAT:SIZ	1
SEARCH:SEARCH1:TRIG:A:BUS:B2:CAN:DAT:VAL	"XXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B2:CAN:FRAME	DATA
SEARCH:SEARCH1:TRIG:A:BUS:B2:CAN:ID:MOD	ST

Table C-1: Default values (cont.)

Command	Default value
SEARCH:SEARCH1:TRIG:A:BUS:B2:CAN:ID:VAL	"XXXXXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B2:I2C:ADDR:MOD	ADDR7
SEARCH:SEARCH1:TRIG:A:BUS:B2:I2C:ADDR:TYP	USER
SEARCH:SEARCH1:TRIG:A:BUS:B2:I2C:ADDR:VAL	"XXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B2:I2C:COND	STAR
SEARCH:SEARCH1:TRIG:A:BUS:B2:I2C:DAT:DIR	NOCARE
SEARCH:SEARCH1:TRIG:A:BUS:B2:I2C:DAT:SIZ	1
SEARCH:SEARCH1:TRIG:A:BUS:B2:I2C:DAT:VAL	"XXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B2:LIN:COND	SYNCF
SEARCH:SEARCH1:TRIG:A:BUS:B2:LIN:DAT:HIVAL	"XXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B2:LIN:DAT:QUAL	EQU
SEARCH:SEARCH1:TRIG:A:BUS:B2:LIN:DAT:SIZ	1
SEARCH:SEARCH1:TRIG:A:BUS:B2:LIN:DAT:VAL	"XXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B2:LIN:ERRTYPE	SYNC
SEARCH:SEARCH1:TRIG:A:BUS:B2:LIN:ID:VAL	"XXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B2:PAR:VAL	"XXXXXXXXXXXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B2:RS232C:COND	TXSTA
SEARCH:SEARCH1:TRIG:A:BUS:B2:RS232C:RX:DAT:SIZ	1
SEARCH:SEARCH1:TRIG:A:BUS:B2:RS232C:RX:DAT:VAL	"XXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B2:RS232C:TX:DAT:SIZ	1
SEARCH:SEARCH1:TRIG:A:BUS:B2:RS232C:TX:DAT:VAL	"XXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B2:SPI:COND	SS
SEARCH:SEARCH1:TRIG:A:BUS:B2:SPI:DAT:MISO:VAL	"XXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B2:SPI:DAT:MOSI:VAL	"XXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B2:SPI:DAT:SIZ	1
SEARCH:SEARCH1:TRIG:A:BUS:B2:USB:ADDR:HIVAL	"XXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B2:USB:ADDR:VAL	"XXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B2:USB:COND	SYNC
SEARCH:SEARCH1:TRIG:A:BUS:B2:USB:DAT:HIVAL	"XXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B2:USB:DAT:OFFS	-1
SEARCH:SEARCH1:TRIG:A:BUS:B2:USB:DAT:SIZ	1
SEARCH:SEARCH1:TRIG:A:BUS:B2:USB:DAT:TYP	ANY
SEARCH:SEARCH1:TRIG:A:BUS:B2:USB:DAT:VAL	"XXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B2:USB:ENDP:VAL	"XXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B2:USB:ERRTYPE	PID
SEARCH:SEARCH1:TRIG:A:BUS:B2:USB:HANDSHAKET	ANY
SEARCH:SEARCH1:TRIG:A:BUS:B2:USB:QUAL	EQU

Table C-1: Default values (cont.)

Command	Default value
SEARCH:SEARCH1:TRIG:A:BUS:B2:USB:SOFFRAMENUM	"XXXXXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B2:USB:SPECIALT	ANY
SEARCH:SEARCH1:TRIG:A:BUS:B2:USB:TOKENT	ANY
SEARCH:SEARCH1:TRIG:A:BUS:B3:CAN:COND	SOF
SEARCH:SEARCH1:TRIG:A:BUS:B3:CAN:DAT:DIR	NOCARE
SEARCH:SEARCH1:TRIG:A:BUS:B3:CAN:DAT:QUAL	EQU
SEARCH:SEARCH1:TRIG:A:BUS:B3:CAN:DAT:SIZ	1
SEARCH:SEARCH1:TRIG:A:BUS:B3:CAN:DAT:VAL	"XXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B3:CAN:FRAME	DATA
SEARCH:SEARCH1:TRIG:A:BUS:B3:CAN:ID:MOD	ST
SEARCH:SEARCH1:TRIG:A:BUS:B3:CAN:ID:VAL	"XXXXXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B3:I2C:ADDR:MOD	ADDR7
SEARCH:SEARCH1:TRIG:A:BUS:B3:I2C:ADDR:TYP	USER
SEARCH:SEARCH1:TRIG:A:BUS:B3:I2C:ADDR:VAL	"XXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B3:I2C:COND	STAR
SEARCH:SEARCH1:TRIG:A:BUS:B3:I2C:DAT:DIR	NOCARE
SEARCH:SEARCH1:TRIG:A:BUS:B3:I2C:DAT:SIZ	1
SEARCH:SEARCH1:TRIG:A:BUS:B3:I2C:DAT:VAL	"XXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B3:LIN:COND	SYNCF
SEARCH:SEARCH1:TRIG:A:BUS:B3:LIN:DAT:HIVAL	"XXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B3:LIN:DAT:QUAL	EQU
SEARCH:SEARCH1:TRIG:A:BUS:B3:LIN:DAT:SIZ	1
SEARCH:SEARCH1:TRIG:A:BUS:B3:LIN:DAT:VAL	"XXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B3:LIN:ERRTYPE	SYNC
SEARCH:SEARCH1:TRIG:A:BUS:B3:LIN:ID:VAL	"XXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B3:PAR:VAL	"XXXXXXXXXXXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B3:RS232C:COND	TXSTA
SEARCH:SEARCH1:TRIG:A:BUS:B3:RS232C:RX:DAT:SIZ	1
SEARCH:SEARCH1:TRIG:A:BUS:B3:RS232C:RX:DAT:VAL	"XXXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B3:RS232C:TX:DAT:SIZ	1
SEARCH:SEARCH1:TRIG:A:BUS:B3:RS232C:TX:DAT:VAL	"XXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B3:SPI:COND	SS
SEARCH:SEARCH1:TRIG:A:BUS:B3:SPI:DAT:MISO:VAL	"XXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B3:SPI:DAT:MOSI:VAL	"XXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B3:SPI:DAT:SIZ	1
SEARCH:SEARCH1:TRIG:A:BUS:B3:USB:ADDR:HIVAL	"XXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B3:USB:ADDR:VAL	"XXXXXXX"

Table C-1: Default values (cont.)

Command	Default value
SEARCH:SEARCH1:TRIG:A:BUS:B3:USB:COND	SYNC
SEARCH:SEARCH1:TRIG:A:BUS:B3:USB:DAT:HIVAL	"XXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B3:USB:DAT:OFFS	-1
SEARCH:SEARCH1:TRIG:A:BUS:B3:USB:DAT:SIZ	1
SEARCH:SEARCH1:TRIG:A:BUS:B3:USB:DAT:TYP	ANY
SEARCH:SEARCH1:TRIG:A:BUS:B3:USB:DAT:VAL	"XXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B3:USB:ENDP:VAL	"XXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B3:USB:ERRTYPE	PID
SEARCH:SEARCH1:TRIG:A:BUS:B3:USB:HANDSHAKET	ANY
SEARCH:SEARCH1:TRIG:A:BUS:B3:USB:QUAL	EQU
SEARCH:SEARCH1:TRIG:A:BUS:B3:USB:SOFFRAMENUM	"XXXXXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B3:USB:SPECIALT	ANY
SEARCH:SEARCH1:TRIG:A:BUS:B3:USB:TOKENT	ANY
SEARCH:SEARCH1:TRIG:A:BUS:B4:CAN:COND	SOF
SEARCH:SEARCH1:TRIG:A:BUS:B4:CAN:DAT:DIR	NOCARE
SEARCH:SEARCH1:TRIG:A:BUS:B4:CAN:DAT:QUAL	EQU
SEARCH:SEARCH1:TRIG:A:BUS:B4:CAN:DAT:SIZ	1
SEARCH:SEARCH1:TRIG:A:BUS:B4:CAN:DAT:VAL	"XXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B4:CAN:FRAME	DATA
SEARCH:SEARCH1:TRIG:A:BUS:B4:CAN:ID:MOD	ST
SEARCH:SEARCH1:TRIG:A:BUS:B4:CAN:ID:VAL	"XXXXXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B4:I2C:ADDR:MOD	ADDR7
SEARCH:SEARCH1:TRIG:A:BUS:B4:I2C:ADDR:TYP	USER
SEARCH:SEARCH1:TRIG:A:BUS:B4:I2C:ADDR:VAL	"XXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B4:I2C:COND	STAR
SEARCH:SEARCH1:TRIG:A:BUS:B4:I2C:DAT:DIR	NOCARE
SEARCH:SEARCH1:TRIG:A:BUS:B4:I2C:DAT:SIZ	1
SEARCH:SEARCH1:TRIG:A:BUS:B4:I2C:DAT:VAL	"XXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B4:LIN:COND	SYNCF
SEARCH:SEARCH1:TRIG:A:BUS:B4:LIN:DAT:HIVAL	"XXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B4:LIN:DAT:QUAL	EQU
SEARCH:SEARCH1:TRIG:A:BUS:B4:LIN:DAT:SIZ	1
SEARCH:SEARCH1:TRIG:A:BUS:B4:LIN:DAT:VAL	"XXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B4:LIN:ERRTYPE	SYNC
SEARCH:SEARCH1:TRIG:A:BUS:B4:LIN:ID:VAL	"XXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B4:PAR:VAL	"XXXXXXXXXXXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B4:RS232C:COND	TXSTA

Table C-1: Default values (cont.)

Command	Default value
SEARCH:SEARCH1:TRIG:A:BUS:B4:RS232C:RX:DAT:SIZ	1
SEARCH:SEARCH1:TRIG:A:BUS:B4:RS232C:RX:DAT:VAL	"XXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B4:RS232C:TX:DAT:SIZ	1
SEARCH:SEARCH1:TRIG:A:BUS:B4:RS232C:TX:DAT:VAL	"XXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B4:SPI:COND	SS
SEARCH:SEARCH1:TRIG:A:BUS:B4:SPI:DAT:MISO:VAL	"XXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B4:SPI:DAT:MOSI:VAL	"XXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B4:SPI:DAT:SIZ	1
SEARCH:SEARCH1:TRIG:A:BUS:B4:USB:ADDR:HIVAL	"XXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B4:USB:ADDR:VAL	"XXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B4:USB:COND	SYNC
SEARCH:SEARCH1:TRIG:A:BUS:B4:USB:DAT:HIVAL	"XXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B4:USB:DAT:OFFS	-1
SEARCH:SEARCH1:TRIG:A:BUS:B4:USB:DAT:SIZ	1
SEARCH:SEARCH1:TRIG:A:BUS:B4:USB:DAT:TYP	ANY
SEARCH:SEARCH1:TRIG:A:BUS:B4:USB:DAT:VAL	"XXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B4:USB:ENDP:VAL	"XXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B4:USB:ERRTYPE	PID
SEARCH:SEARCH1:TRIG:A:BUS:B4:USB:HANDSHAKET	ANY
SEARCH:SEARCH1:TRIG:A:BUS:B4:USB:QUAL	EQU
SEARCH:SEARCH1:TRIG:A:BUS:B4:USB:SOFFRAMENUM	"XXXXXXXXXXX"
SEARCH:SEARCH1:TRIG:A:BUS:B4:USB:SPECIALT	ANY
SEARCH:SEARCH1:TRIG:A:BUS:B4:USB:TOKENT	ANY
SEARCH:SEARCH1:TRIG:A:BUS:SOU	B1
SEARCH:SEARCH1:TRIG:A:EDGE:SLO	RIS
SEARCH:SEARCH1:TRIG:A:EDGE:SOU	CH1
SEARCH:SEARCH1:TRIG:A:LEV	0.0E+0
SEARCH:SEARCH1:TRIG:A:LEV:CH1	0.0E+0
SEARCH:SEARCH1:TRIG:A:LEV:CH2	0.0E+0
SEARCH:SEARCH1:TRIG:A:LEV:CH3	0.0E+0
SEARCH:SEARCH1:TRIG:A:LEV:CH4	0.0E+0
SEARCH:SEARCH1:TRIG:A:LEV:MATH	0.0E+0
SEARCH:SEARCH1:TRIG:A:LEV:REF1	0.0E+0
SEARCH:SEARCH1:TRIG:A:LEV:REF2	0.0E+0
SEARCH:SEARCH1:TRIG:A:LEV:REF3	0.0E+0
SEARCH:SEARCH1:TRIG:A:LEV:REF4	0.0E+0
SEARCH:SEARCH1:TRIG:A:LOGI:FUNC	AND

Table C-1: Default values (cont.)

Command	Default value
SEARCH:SEARCH1:TRIG:A:LOGI:INP:CH1	X
SEARCH:SEARCH1:TRIG:A:LOGI:INP:CH2	X
SEARCH:SEARCH1:TRIG:A:LOGI:INP:CH3	X
SEARCH:SEARCH1:TRIG:A:LOGI:INP:CH4	X
SEARCH:SEARCH1:TRIG:A:LOGI:INP:CLOC:EDGE	RIS
SEARCH:SEARCH1:TRIG:A:LOGI:INP:CLOC:SOU	NON
SEARCH:SEARCH1:TRIG:A:LOGI:INP:D0	X
SEARCH:SEARCH1:TRIG:A:LOGI:INP:D1	X
SEARCH:SEARCH1:TRIG:A:LOGI:INP:D10	X
SEARCH:SEARCH1:TRIG:A:LOGI:INP:D11	X
SEARCH:SEARCH1:TRIG:A:LOGI:INP:D12	X
SEARCH:SEARCH1:TRIG:A:LOGI:INP:D13	X
SEARCH:SEARCH1:TRIG:A:LOGI:INP:D14	X
SEARCH:SEARCH1:TRIG:A:LOGI:INP:D15	X
SEARCH:SEARCH1:TRIG:A:LOGI:INP:D2	X
SEARCH:SEARCH1:TRIG:A:LOGI:INP:D3	X
SEARCH:SEARCH1:TRIG:A:LOGI:INP:D4	X
SEARCH:SEARCH1:TRIG:A:LOGI:INP:D5	X
SEARCH:SEARCH1:TRIG:A:LOGI:INP:D6	X
SEARCH:SEARCH1:TRIG:A:LOGI:INP:D7	X
SEARCH:SEARCH1:TRIG:A:LOGI:INP:D8	X
SEARCH:SEARCH1:TRIG:A:LOGI:INP:D9	Х
SEARCH:SEARCH1:TRIG:A:LOGI:INP:MATH	X
SEARCH:SEARCH1:TRIG:A:LOGI:INP:REF1	X
SEARCH:SEARCH1:TRIG:A:LOGI:INP:REF2	X
SEARCH:SEARCH1:TRIG:A:LOGI:INP:REF3	X
SEARCH:SEARCH1:TRIG:A:LOGI:INP:REF4	X
SEARCH:SEARCH1:TRIG:A:LOGI:PAT:INP:CH1	X
SEARCH:SEARCH1:TRIG:A:LOGI:PAT:INP:CH2	X
SEARCH:SEARCH1:TRIG:A:LOGI:PAT:INP:CH3	X
SEARCH:SEARCH1:TRIG:A:LOGI:PAT:INP:CH4	X
SEARCH:SEARCH1:TRIG:A:LOGI:PAT:INP:D0	X
SEARCH:SEARCH1:TRIG:A:LOGI:PAT:INP:D1	X
SEARCH:SEARCH1:TRIG:A:LOGI:PAT:INP:D10	X
SEARCH:SEARCH1:TRIG:A:LOGI:PAT:INP:D11	X
SEARCH:SEARCH1:TRIG:A:LOGI:PAT:INP:D12	X
SEARCH:SEARCH1:TRIG:A:LOGI:PAT:INP:D13	X

Table C-1: Default values (cont.)

Command	Default value
SEARCH:SEARCH1:TRIG:A:LOGI:PAT:INP:D14	X
SEARCH:SEARCH1:TRIG:A:LOGI:PAT:INP:D15	X
SEARCH:SEARCH1:TRIG:A:LOGI:PAT:INP:D2	X
SEARCH:SEARCH1:TRIG:A:LOGI:PAT:INP:D3	X
SEARCH:SEARCH1:TRIG:A:LOGI:PAT:INP:D4	X
SEARCH:SEARCH1:TRIG:A:LOGI:PAT:INP:D5	X
SEARCH:SEARCH1:TRIG:A:LOGI:PAT:INP:D6	X
SEARCH:SEARCH1:TRIG:A:LOGI:PAT:INP:D7	X
SEARCH:SEARCH1:TRIG:A:LOGI:PAT:INP:D8	X
SEARCH:SEARCH1:TRIG:A:LOGI:PAT:INP:D9	X
SEARCH:SEARCH1:TRIG:A:LOGI:PAT:INP:MATH	X
SEARCH:SEARCH1:TRIG:A:LOGI:PAT:INP:REF1	X
SEARCH:SEARCH1:TRIG:A:LOGI:PAT:INP:REF2	X
SEARCH:SEARCH1:TRIG:A:LOGI:PAT:INP:REF3	X
SEARCH:SEARCH1:TRIG:A:LOGI:PAT:INP:REF4	X
SEARCH:SEARCH1:TRIG:A:LOGI:PAT:WHE	TRU
SEARCH:SEARCH1:TRIG:A:LOGI:PAT:WHE:LESSL	8.0000E-9
SEARCH:SEARCH1:TRIG:A:LOGI:PAT:WHE:MOREL	8.0000E-9
SEARCH:SEARCH1:TRIG:A:LOGI:THR:CH1	0.0E+0
SEARCH:SEARCH1:TRIG:A:LOGI:THR:CH2	0.0E+0
SEARCH:SEARCH1:TRIG:A:LOGI:THR:CH3	0.0E+0
SEARCH:SEARCH1:TRIG:A:LOGI:THR:CH4	0.0E+0
SEARCH:SEARCH1:TRIG:A:LOGI:THR:MATH	0.0E+0
SEARCH:SEARCH1:TRIG:A:LOGI:THR:REF1	0.0E+0
SEARCH:SEARCH1:TRIG:A:LOGI:THR:REF2	0.0E+0
SEARCH:SEARCH1:TRIG:A:LOGI:THR:REF3	0.0E+0
SEARCH:SEARCH1:TRIG:A:LOGI:THR:REF4	0.0E+0
SEARCH:SEARCH1:TRIG:A:LOW:CH1	0.0E+0
SEARCH:SEARCH1:TRIG:A:LOW:CH2	0.0E+0
SEARCH:SEARCH1:TRIG:A:LOW:CH3	0.0E+0
SEARCH:SEARCH1:TRIG:A:LOW:CH4	0.0E+0
SEARCH:SEARCH1:TRIG:A:LOW:MATH	0.0E+0
SEARCH:SEARCH1:TRIG:A:LOW:REF1	0.0E+0
SEARCH:SEARCH1:TRIG:A:LOW:REF2	0.0E+0
SEARCH:SEARCH1:TRIG:A:LOW:REF3	0.0E+0
SEARCH:SEARCH1:TRIG:A:LOW:REF4	0.0E+0
SEARCH:SEARCH1:TRIG:A:PULSEW:POL	POS

Table C-1: Default values (cont.)

Command	Default value
SEARCH:SEARCH1:TRIG:A:PULSEW:WHE	LESS
SEARCH:SEARCH1:TRIG:A:PULSEW:WID	8.0000E-9
SEARCH:SEARCH1:TRIG:A:RUNT:POL	POS
SEARCH:SEARCH1:TRIG:A:RUNT:WHE	OCCURS
SEARCH:SEARCH1:TRIG:A:RUNT:WID	8.0000E-9
SEARCH:SEARCH1:TRIG:A:SETH:CLOC:EDGE	RIS
SEARCH:SEARCH1:TRIG:A:SETH:CLOC:SOU	CH1
SEARCH:SEARCH1:TRIG:A:SETH:CLOC:THR	0.0E+0
SEARCH:SEARCH1:TRIG:A:SETH:DAT:SOU	NONE
SEARCH:SEARCH1:TRIG:A:SETH:DAT:THR	9.9100E+37
SEARCH:SEARCH1:TRIG:A:SETH:HOLDT	8.0000E-9
SEARCH:SEARCH1:TRIG:A:SETH:SETT	8.0000E-9
SEARCH:SEARCH1:TRIG:A:SETH:THR:CH1	0.0E+0
SEARCH:SEARCH1:TRIG:A:SETH:THR:CH2	0.0E+0
SEARCH:SEARCH1:TRIG:A:SETH:THR:CH3	0.0E+0
SEARCH:SEARCH1:TRIG:A:SETH:THR:CH4	0.0E+0
SEARCH:SEARCH1:TRIG:A:SETH:THR:MATH	0.0E+0
SEARCH:SEARCH1:TRIG:A:SETH:THR:REF1	0.0E+0
SEARCH:SEARCH1:TRIG:A:SETH:THR:REF2	0.0E+0
SEARCH:SEARCH1:TRIG:A:SETH:THR:REF3	0.0E+0
SEARCH:SEARCH1:TRIG:A:SETH:THR:REF4	0.0E+0
SEARCH:SEARCH1:TRIG:A:TRAN:DELT	8.0000E-9
SEARCH:SEARCH1:TRIG:A:TRAN:POL	POS
SEARCH:SEARCH1:TRIG:A:TRAN:WHE	SLOW
SEARCH:SEARCH1:TRIG:A:TYP	EDG
SEARCH:SEARCH1:TRIG:A:UPP:CH1	800.0000E-3
SEARCH:SEARCH1:TRIG:A:UPP:CH2	800.0000E-3
SEARCH:SEARCH1:TRIG:A:UPP:CH3	800.0000E-3
SEARCH:SEARCH1:TRIG:A:UPP:CH4	800.0000E-3
SEARCH:SEARCH1:TRIG:A:UPP:MATH	800.0000E-3
SEARCH:SEARCH1:TRIG:A:UPP:REF1	800.0000E-3
SEARCH:SEARCH1:TRIG:A:UPP:REF2	800.0000E-3
SEARCH:SEARCH1:TRIG:A:UPP:REF3	800.0000E-3
SEARCH:SEARCH1:TRIG:A:UPP:REF4	800.0000E-3
SEL:BUS1	0
SEL:BUS2	0
SEL:BUS3	0

Table C-1: Default values (cont.)

Command	Default value
SEL:BUS4	0
SEL:CH1	1
SEL:CH2	0
SEL:CH3	0
SEL:CH4	0
SEL:CONTRO	CH1
SEL:D0	0
SEL:D1	0
SEL:D10	0
SEL:D11	0
SEL:D12	0
SEL:D13	0
SEL:D14	0
SEL:D15	0
SEL:D2	0
SEL:D3	0
SEL:D4	0
SEL:D5	0
SEL:D6	0
SEL:D7	0
SEL:D8	0
SEL:D9	0
SEL:MATH	0
SEL:REF1	0
SEL:REF2	0
SEL:REF3	0
SEL:REF4	0
SELECT:DALL	0
TRIG:A:BUS:B1:CAN:COND	SOF
TRIG:A:BUS:B1:CAN:DAT:DIR	NOCARE
TRIG:A:BUS:B1:CAN:DAT:QUAL	EQU
TRIG:A:BUS:B1:CAN:DAT:SIZ	1
TRIG:A:BUS:B1:CAN:DAT:STAR	0.0E+0
TRIG:A:BUS:B1:CAN:DAT:VAL	"XXXXXXX"
TRIG:A:BUS:B1:CAN:FRAME	DATA
TRIG:A:BUS:B1:CAN:ID:MOD	ST
TRIG:A:BUS:B1:CAN:ID:VAL	"XXXXXXXXXX"

Table C-1: Default values (cont.)

Command	Default value
TRIG:A:BUS:B1:I2C:ADDR:MOD	ADDR7
TRIG:A:BUS:B1:I2C:ADDR:TYP	USER
TRIG:A:BUS:B1:I2C:ADDR:VAL	"XXXXXXX"
TRIG:A:BUS:B1:I2C:COND	STAR
TRIG:A:BUS:B1:I2C:DAT:DIR	NOCARE
TRIG:A:BUS:B1:I2C:DAT:SIZ	1
TRIG:A:BUS:B1:I2C:DAT:STAR	0.0E+0
TRIG:A:BUS:B1:I2C:DAT:VAL	"XXXXXXXX"
TRIG:A:BUS:B1:LIN:COND	SYNCF
TRIG:A:BUS:B1:LIN:DAT:HIVAL	"XXXXXXX"
TRIG:A:BUS:B1:LIN:DAT:QUAL	EQU
TRIG:A:BUS:B1:LIN:DAT:SIZ	1
TRIG:A:BUS:B1:LIN:DAT:VAL	"XXXXXXXX"
TRIG:A:BUS:B1:LIN:ERRTYPE	SYNC
TRIG:A:BUS:B1:LIN:ID:VAL	"XXXXXX"
TRIG:A:BUS:B1:PAR:VAL	"XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX
TRIG:A:BUS:B1:RS232C:COND	TXSTA
TRIG:A:BUS:B1:RS232C:RX:DAT:SIZ	1
TRIG:A:BUS:B1:RS232C:RX:DAT:VAL	"XXXXXXXX"
TRIG:A:BUS:B1:RS232C:TX:DAT:SIZ	1
TRIG:A:BUS:B1:RS232C:TX:DAT:VAL	"XXXXXXX"
TRIG:A:BUS:B1:SPI:COND	SS
TRIG:A:BUS:B1:SPI:DAT:IN:VAL	"XXXXXXXX"
TRIG:A:BUS:B1:SPI:DAT:OUT:VAL	"XXXXXXXX"
TRIG:A:BUS:B1:SPI:DAT:SIZ	1
TRIG:A:BUS:B1:SPI:DAT:STAR	0.0E+0
TRIG:A:BUS:B1:USB:ADDR:HIVAL	"XXXXXXX"
TRIG:A:BUS:B1:USB:ADDR:VAL	"XXXXXXX"
TRIG:A:BUS:B1:USB:COND	SYNC
TRIG:A:BUS:B1:USB:DAT:HIVAL	"XXXXXXXX"
TRIG:A:BUS:B1:USB:DAT:OFFS	-1
TRIG:A:BUS:B1:USB:DAT:SIZ	1
TRIG:A:BUS:B1:USB:DAT:TYP	ANY
TRIG:A:BUS:B1:USB:DAT:VAL	"XXXXXXX"
TRIG:A:BUS:B1:USB:ENDP:VAL	"XXXX"
TRIG:A:BUS:B1:USB:ERRTYPE	PID
TRIG:A:BUS:B1:USB:HANDSHAKET	ANY

Table C-1: Default values (cont.)

Command	Default value
TRIG:A:BUS:B1:USB:QUAL	EQU
TRIG:A:BUS:B1:USB:SOFFRAMENUM	"XXXXXXXXXX"
TRIG:A:BUS:B1:USB:SPECIALT	ANY
TRIG:A:BUS:B1:USB:TOKENT	ANY
TRIG:A:BUS:B2:CAN:COND	SOF
TRIG:A:BUS:B2:CAN:DAT:DIR	NOCARE
TRIG:A:BUS:B2:CAN:DAT:QUAL	EQU
TRIG:A:BUS:B2:CAN:DAT:SIZ	1
TRIG:A:BUS:B2:CAN:DAT:STAR	0.0E+0
TRIG:A:BUS:B2:CAN:DAT:VAL	"XXXXXXX"
TRIG:A:BUS:B2:CAN:FRAME	DATA
TRIG:A:BUS:B2:CAN:ID:MOD	ST
TRIG:A:BUS:B2:CAN:ID:VAL	"XXXXXXXXXX"
TRIG:A:BUS:B2:I2C:ADDR:MOD	ADDR7
TRIG:A:BUS:B2:I2C:ADDR:TYP	USER
TRIG:A:BUS:B2:I2C:ADDR:VAL	"XXXXXXX"
TRIG:A:BUS:B2:I2C:COND	STAR
TRIG:A:BUS:B2:I2C:DAT:DIR	NOCARE
TRIG:A:BUS:B2:I2C:DAT:SIZ	1
TRIG:A:BUS:B2:I2C:DAT:STAR	0.0E+0
TRIG:A:BUS:B2:I2C:DAT:VAL	"XXXXXXXX"
TRIG:A:BUS:B2:LIN:COND	SYNCF
TRIG:A:BUS:B2:LIN:DAT:HIVAL	"XXXXXXXX"
TRIG:A:BUS:B2:LIN:DAT:QUAL	EQU
TRIG:A:BUS:B2:LIN:DAT:SIZ	1
TRIG:A:BUS:B2:LIN:DAT:VAL	"XXXXXXXX"
TRIG:A:BUS:B2:LIN:ERRTYPE	SYNC
TRIG:A:BUS:B2:LIN:ID:VAL	"XXXXXX"
TRIG:A:BUS:B2:PAR:VAL	"XXXXXXXXXXXXXXXXXX"
TRIG:A:BUS:B2:RS232C:COND	TXSTA
TRIG:A:BUS:B2:RS232C:RX:DAT:SIZ	1
TRIG:A:BUS:B2:RS232C:RX:DAT:VAL	"XXXXXXXX"
TRIG:A:BUS:B2:RS232C:TX:DAT:SIZ	1
TRIG:A:BUS:B2:RS232C:TX:DAT:VAL	"XXXXXXXX"
TRIG:A:BUS:B2:SPI:COND	SS
TRIG:A:BUS:B2:SPI:DAT:IN:VAL	"XXXXXXXX"
TRIG:A:BUS:B2:SPI:DAT:OUT:VAL	"XXXXXXX"

Table C-1: Default values (cont.)

TRIG:A:BUS:B2:SPI:DAT:SIZ         1           TRIG:A:BUS:B2:SPI:DAT:STAR         0.0E+0           TRIG:A:BUS:B2:USB:ADDR:HIVAL         "XXXXXXX"           TRIG:A:BUS:B2:USB:ADDR:VAL         "XXXXXXXX"           TRIG:A:BUS:B2:USB:COND         SYNC           TRIG:A:BUS:B2:USB:DAT:HIVAL         "XXXXXXXXX"           TRIG:A:BUS:B2:USB:DAT:OFFS         -1           TRIG:A:BUS:B2:USB:DAT:SIZ         1           TRIG:A:BUS:B2:USB:DAT:TYP         ANY           TRIG:A:BUS:B2:USB:DAT:VAL         "XXXXXXXXX"           TRIG:A:BUS:B2:USB:ENDP:VAL         "XXXXXXXXX"           TRIG:A:BUS:B2:USB:ENDP:VAL         "XXXXXXXXX"           TRIG:A:BUS:B2:USB:HANDSHAKET         ANY           TRIG:A:BUS:B2:USB:HANDSHAKET         ANY           TRIG:A:BUS:B2:USB:SOFFRAMENUM         "XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX	
TRIG:A:BUS:B2:USB:ADDR:HIVAL "XXXXXXX"  TRIG:A:BUS:B2:USB:ADDR:VAL "XXXXXXX"  TRIG:A:BUS:B2:USB:COND SYNC  TRIG:A:BUS:B2:USB:DAT:HIVAL "XXXXXXXX"  TRIG:A:BUS:B2:USB:DAT:HIVAL "XXXXXXXX"  TRIG:A:BUS:B2:USB:DAT:OFFS -1  TRIG:A:BUS:B2:USB:DAT:SIZ 1  TRIG:A:BUS:B2:USB:DAT:TYP ANY  TRIG:A:BUS:B2:USB:DAT:VAL "XXXXXXXX"  TRIG:A:BUS:B2:USB:ENDP:VAL "XXXXXXXX"  TRIG:A:BUS:B2:USB:ENDP:VAL "XXXXXXXX"  TRIG:A:BUS:B2:USB:ENDP:VAL "XXXXXXXX"  TRIG:A:BUS:B2:USB:ENDP:VAL "XXXXXXXX"  TRIG:A:BUS:B2:USB:HANDSHAKET ANY  TRIG:A:BUS:B2:USB:QUAL EQU  TRIG:A:BUS:B2:USB:SOFFRAMENUM "XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX	
TRIG:A:BUS:B2:USB:ADDR:VAL "XXXXXXX"  TRIG:A:BUS:B2:USB:COND SYNC  TRIG:A:BUS:B2:USB:DAT:HIVAL "XXXXXXXX"  TRIG:A:BUS:B2:USB:DAT:OFFS -1  TRIG:A:BUS:B2:USB:DAT:TYP ANY  TRIG:A:BUS:B2:USB:DAT:TYP ANY  TRIG:A:BUS:B2:USB:DAT:VAL "XXXXXXXX"  TRIG:A:BUS:B2:USB:ENDP:VAL "XXXXXXXX"  TRIG:A:BUS:B2:USB:ENDP:VAL "XXXXXXX"  TRIG:A:BUS:B2:USB:ERRTYPE PID  TRIG:A:BUS:B2:USB:HANDSHAKET ANY  TRIG:A:BUS:B2:USB:QUAL EQU  TRIG:A:BUS:B2:USB:SOFFRAMENUM "XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX	
TRIG:A:BUS:B2:USB:COND  TRIG:A:BUS:B2:USB:DAT:HIVAL  TRIG:A:BUS:B2:USB:DAT:OFFS  TRIG:A:BUS:B2:USB:DAT:SIZ  TRIG:A:BUS:B2:USB:DAT:TYP  TRIG:A:BUS:B2:USB:DAT:VAL  TRIG:A:BUS:B2:USB:DAT:VAL  TRIG:A:BUS:B2:USB:ENDP:VAL  TRIG:A:BUS:B2:USB:ERRTYPE  TRIG:A:BUS:B2:USB:HANDSHAKET  TRIG:A:BUS:B2:USB:QUAL  TRIG:A:BUS:B2:USB:QUAL  TRIG:A:BUS:B2:USB:SOFFRAMENUM  "XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX	
TRIG:A:BUS:B2:USB:DAT:HIVAL "XXXXXXXX"  TRIG:A:BUS:B2:USB:DAT:OFFS -1  TRIG:A:BUS:B2:USB:DAT:SIZ 1  TRIG:A:BUS:B2:USB:DAT:TYP ANY  TRIG:A:BUS:B2:USB:DAT:VAL "XXXXXXXX"  TRIG:A:BUS:B2:USB:ENDP:VAL "XXXXXXXX"  TRIG:A:BUS:B2:USB:ERRTYPE PID  TRIG:A:BUS:B2:USB:HANDSHAKET ANY  TRIG:A:BUS:B2:USB:QUAL EQU  TRIG:A:BUS:B2:USB:SOFFRAMENUM "XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX	
TRIG:A:BUS:B2:USB:DAT:OFFS  TRIG:A:BUS:B2:USB:DAT:SIZ  TRIG:A:BUS:B2:USB:DAT:TYP  ANY  TRIG:A:BUS:B2:USB:DAT:VAL  TRIG:A:BUS:B2:USB:ENDP:VAL  TRIG:A:BUS:B2:USB:ENDP:VAL  TRIG:A:BUS:B2:USB:ERRTYPE  PID  TRIG:A:BUS:B2:USB:HANDSHAKET  ANY  TRIG:A:BUS:B2:USB:QUAL  TRIG:A:BUS:B2:USB:QUAL  TRIG:A:BUS:B2:USB:SOFFRAMENUM  "XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX	
TRIG:A:BUS:B2:USB:DAT:SIZ  TRIG:A:BUS:B2:USB:DAT:TYP  ANY  TRIG:A:BUS:B2:USB:DAT:VAL  TRIG:A:BUS:B2:USB:ENDP:VAL  TRIG:A:BUS:B2:USB:ENDP:VAL  TRIG:A:BUS:B2:USB:ERRTYPE  PID  TRIG:A:BUS:B2:USB:HANDSHAKET  ANY  TRIG:A:BUS:B2:USB:QUAL  TRIG:A:BUS:B2:USB:SOFFRAMENUM	
TRIG:A:BUS:B2:USB:DAT:TYP  TRIG:A:BUS:B2:USB:DAT:VAL  TRIG:A:BUS:B2:USB:ENDP:VAL  TRIG:A:BUS:B2:USB:ENDP:VAL  TRIG:A:BUS:B2:USB:ERRTYPE  PID  TRIG:A:BUS:B2:USB:HANDSHAKET  ANY  TRIG:A:BUS:B2:USB:QUAL  TRIG:A:BUS:B2:USB:SOFFRAMENUM  "XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX	
TRIG:A:BUS:B2:USB:DAT:VAL "XXXXXXXX"  TRIG:A:BUS:B2:USB:ENDP:VAL "XXXX"  TRIG:A:BUS:B2:USB:ERRTYPE PID  TRIG:A:BUS:B2:USB:HANDSHAKET ANY  TRIG:A:BUS:B2:USB:QUAL EQU  TRIG:A:BUS:B2:USB:SOFFRAMENUM "XXXXXXXXXXXX"	
TRIG:A:BUS:B2:USB:ENDP:VAL "XXXX"  TRIG:A:BUS:B2:USB:ERRTYPE PID  TRIG:A:BUS:B2:USB:HANDSHAKET ANY  TRIG:A:BUS:B2:USB:QUAL EQU  TRIG:A:BUS:B2:USB:SOFFRAMENUM "XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX	
TRIG:A:BUS:B2:USB:ERRTYPE PID TRIG:A:BUS:B2:USB:HANDSHAKET ANY TRIG:A:BUS:B2:USB:QUAL EQU TRIG:A:BUS:B2:USB:SOFFRAMENUM "XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX	
TRIG:A:BUS:B2:USB:HANDSHAKET ANY TRIG:A:BUS:B2:USB:QUAL EQU TRIG:A:BUS:B2:USB:SOFFRAMENUM "XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX	
TRIG:A:BUS:B2:USB:QUAL EQU TRIG:A:BUS:B2:USB:SOFFRAMENUM "XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX	
TRIG:A:BUS:B2:USB:SOFFRAMENUM "XXXXXXXXXXX"	
TRIG:A:BUS:B2:USB:SPECIALT ANY	
TRIG:A:BUS:B2:USB:TOKENT ANY	
TRIG:A:BUS:B3:CAN:COND SOF	
TRIG:A:BUS:B3:CAN:DAT:DIR NOCARE	
TRIG:A:BUS:B3:CAN:DAT:QUAL EQU	
TRIG:A:BUS:B3:CAN:DAT:SIZ 1	
TRIG:A:BUS:B3:CAN:DAT:STAR 0.0E+0	
TRIG:A:BUS:B3:CAN:DAT:VAL "XXXXXXXX"	
TRIG:A:BUS:B3:CAN:FRAME DATA	
TRIG:A:BUS:B3:CAN:ID:MOD ST	
TRIG:A:BUS:B3:CAN:ID:VAL "XXXXXXXXXXX"	
TRIG:A:BUS:B3:I2C:ADDR:MOD ADDR7	
TRIG:A:BUS:B3:I2C:ADDR:TYP USER	
TRIG:A:BUS:B3:I2C:ADDR:VAL "XXXXXXX"	
TRIG:A:BUS:B3:I2C:COND STAR	
TRIG:A:BUS:B3:I2C:DAT:DIR NOCARE	
TRIG:A:BUS:B3:I2C:DAT:SIZ	
TRIG:A:BUS:B3:I2C:DAT:STAR 0.0E+0	
TRIG:A:BUS:B3:I2C:DAT:VAL "XXXXXXX"	
TRIG:A:BUS:B3:LIN:COND SYNCF	
TRIG:A:BUS:B3:LIN:DAT:HIVAL "XXXXXXX"	
TRIG:A:BUS:B3:LIN:DAT:QUAL EQU	

Table C-1: Default values (cont.)

Command	Default value
TRIG:A:BUS:B3:LIN:DAT:SIZ	1
TRIG:A:BUS:B3:LIN:DAT:VAL	"XXXXXXX"
TRIG:A:BUS:B3:LIN:ERRTYPE	SYNC
TRIG:A:BUS:B3:LIN:ID:VAL	"XXXXXX"
TRIG:A:BUS:B3:PAR:VAL	"XXXXXXXXXXXXXXXX"
TRIG:A:BUS:B3:RS232C:COND	TXSTA
TRIG:A:BUS:B3:RS232C:RX:DAT:SIZ	1
TRIG:A:BUS:B3:RS232C:RX:DAT:VAL	"XXXXXXX"
TRIG:A:BUS:B3:RS232C:TX:DAT:SIZ	1
TRIG:A:BUS:B3:RS232C:TX:DAT:VAL	"XXXXXXX"
TRIG:A:BUS:B3:SPI:COND	SS
TRIG:A:BUS:B3:SPI:DAT:IN:VAL	"XXXXXXX"
TRIG:A:BUS:B3:SPI:DAT:OUT:VAL	"XXXXXXX"
TRIG:A:BUS:B3:SPI:DAT:SIZ	1
TRIG:A:BUS:B3:SPI:DAT:STAR	0.0E+0
TRIG:A:BUS:B3:USB:ADDR:HIVAL	"XXXXXX"
TRIG:A:BUS:B3:USB:ADDR:VAL	"XXXXXX"
TRIG:A:BUS:B3:USB:COND	SYNC
TRIG:A:BUS:B3:USB:DAT:HIVAL	"XXXXXXX"
TRIG:A:BUS:B3:USB:DAT:OFFS	-1
TRIG:A:BUS:B3:USB:DAT:SIZ	1
TRIG:A:BUS:B3:USB:DAT:TYP	ANY
TRIG:A:BUS:B3:USB:DAT:VAL	"XXXXXXX"
TRIG:A:BUS:B3:USB:ENDP:VAL	"XXXX"
TRIG:A:BUS:B3:USB:ERRTYPE	PID
TRIG:A:BUS:B3:USB:HANDSHAKET	ANY
TRIG:A:BUS:B3:USB:QUAL	EQU
TRIG:A:BUS:B3:USB:SOFFRAMENUM	"XXXXXXXXX"
TRIG:A:BUS:B3:USB:SPECIALT	ANY
TRIG:A:BUS:B3:USB:TOKENT	ANY
TRIG:A:BUS:B4:CAN:COND	SOF
TRIG:A:BUS:B4:CAN:DAT:DIR	NOCARE
TRIG:A:BUS:B4:CAN:DAT:QUAL	EQU
TRIG:A:BUS:B4:CAN:DAT:SIZ	1
TRIG:A:BUS:B4:CAN:DAT:STAR	0.0E+0
TRIG:A:BUS:B4:CAN:DAT:VAL	"XXXXXXX"
TRIG:A:BUS:B4:CAN:FRAME	DATA

Table C-1: Default values (cont.)

TRIG:A:BUS:B4:CAN:ID:MOD	ST
THOM: DOOD TOMINION	O1
TRIG:A:BUS:B4:CAN:ID:VAL	"XXXXXXXXXXX"
TRIG:A:BUS:B4:I2C:ADDR:MOD	ADDR7
TRIG:A:BUS:B4:I2C:ADDR:TYP	USER
TRIG:A:BUS:B4:I2C:ADDR:VAL	"XXXXXXX"
TRIG:A:BUS:B4:I2C:COND	STAR
TRIG:A:BUS:B4:I2C:DAT:DIR	NOCARE
TRIG:A:BUS:B4:I2C:DAT:SIZ	1
TRIG:A:BUS:B4:I2C:DAT:STAR	0.0E+0
TRIG:A:BUS:B4:I2C:DAT:VAL	"XXXXXXX"
TRIG:A:BUS:B4:LIN:COND	SYNCF
TRIG:A:BUS:B4:LIN:DAT:HIVAL	"XXXXXXX"
TRIG:A:BUS:B4:LIN:DAT:QUAL	EQU
TRIG:A:BUS:B4:LIN:DAT:SIZ	1
TRIG:A:BUS:B4:LIN:DAT:VAL	"XXXXXXX"
TRIG:A:BUS:B4:LIN:ERRTYPE	SYNC
TRIG:A:BUS:B4:LIN:ID:VAL	"XXXXXX"
TRIG:A:BUS:B4:PAR:VAL	"XXXXXXXXXXXXXXXXX
TRIG:A:BUS:B4:RS232C:COND	TXSTA
TRIG:A:BUS:B4:RS232C:RX:DAT:SIZ	1
TRIG:A:BUS:B4:RS232C:RX:DAT:VAL	"XXXXXXXX"
TRIG:A:BUS:B4:RS232C:TX:DAT:SIZ	1
TRIG:A:BUS:B4:RS232C:TX:DAT:VAL	"XXXXXXXX"
TRIG:A:BUS:B4:SPI:COND	SS
TRIG:A:BUS:B4:SPI:DAT:IN:VAL	"XXXXXXXX"
TRIG:A:BUS:B4:SPI:DAT:OUT:VAL	"XXXXXXXX"
TRIG:A:BUS:B4:SPI:DAT:SIZ	1
TRIG:A:BUS:B4:SPI:DAT:STAR	0.0E+0
TRIG:A:BUS:B4:USB:ADDR:HIVAL	"XXXXXXX"
TRIG:A:BUS:B4:USB:ADDR:VAL	"XXXXXXX"
TRIG:A:BUS:B4:USB:COND	SYNC
TRIG:A:BUS:B4:USB:DAT:HIVAL	"XXXXXXXX"
TRIG:A:BUS:B4:USB:DAT:OFFS	-1
TRIG:A:BUS:B4:USB:DAT:SIZ	1
TRIG:A:BUS:B4:USB:DAT:TYP	ANY
TRIG:A:BUS:B4:USB:DAT:VAL	"XXXXXXXX"
TRIG:A:BUS:B4:USB:ENDP:VAL	"XXXX"

Table C-1: Default values (cont.)

Command	Default value
TRIG:A:BUS:B4:USB:ERRTYPE	PID
TRIG:A:BUS:B4:USB:HANDSHAKET	ANY
TRIG:A:BUS:B4:USB:QUAL	EQU
TRIG:A:BUS:B4:USB:SOFFRAMENUM	"XXXXXXXXXX"
TRIG:A:BUS:B4:USB:SPECIALT	ANY
TRIG:A:BUS:B4:USB:TOKENT	ANY
TRIG:A:BUS:SOU	B1
TRIG:A:EDGE:COUP	DC
TRIG:A:EDGE:SLO	RIS
TRIG:A:EDGE:SOU	CH1
TRIG:A:HOLD:TIM	20.0000E-9
TRIG:A:LEV	0.0E+0
TRIG:A:LEV:AUX	0.0E+0
TRIG:A:LEV:CH1	0.0E+0
TRIG:A:LEV:CH2	0.0E+0
TRIG:A:LEV:CH3	0.0E+0
TRIG:A:LEV:CH4	0.0E+0
TRIG:A:LEV:D0	1.4000
TRIG:A:LEV:D1	1.4000
TRIG:A:LEV:D10	1.4000
TRIG:A:LEV:D11	1.4000
TRIG:A:LEV:D12	1.4000
TRIG:A:LEV:D13	1.4000
TRIG:A:LEV:D14	1.4000
TRIG:A:LEV:D15	1.4000
TRIG:A:LEV:D2	1.4000
TRIG:A:LEV:D3	1.4000
TRIG:A:LEV:D4	1.4000
TRIG:A:LEV:D5	1.4000
TRIG:A:LEV:D6	1.4000
TRIG:A:LEV:D7	1.4000
TRIG:A:LEV:D8	1.4000
TRIG:A:LEV:D9	1.4000
TRIG:A:LOGI:CLA	LOGIC
TRIG:A:LOGI:FUNC	AND
TRIG:A:LOGI:INP:CH1	X
TRIG:A:LOGI:INP:CH2	X

Table C-1: Default values (cont.)

Command	Default value
TRIG:A:LOGI:INP:CH3	X
TRIG:A:LOGI:INP:CH4	Χ
TRIG:A:LOGI:INP:CLOC:EDGE	RIS
TRIG:A:LOGI:INP:CLOC:SOU	NON
TRIG:A:LOGI:INP:D0	X
TRIG:A:LOGI:INP:D1	X
TRIG:A:LOGI:INP:D10	X
TRIG:A:LOGI:INP:D11	X
TRIG:A:LOGI:INP:D12	Х
TRIG:A:LOGI:INP:D13	Х
TRIG:A:LOGI:INP:D14	X
TRIG:A:LOGI:INP:D15	Х
TRIG:A:LOGI:INP:D2	Х
TRIG:A:LOGI:INP:D3	Х
TRIG:A:LOGI:INP:D4	Х
TRIG:A:LOGI:INP:D5	Χ
TRIG:A:LOGI:INP:D6	Х
TRIG:A:LOGI:INP:D7	Х
TRIG:A:LOGI:INP:D8	X
TRIG:A:LOGI:INP:D9	Х
TRIG:A:LOGI:PAT:DELT	8.0000E-9
TRIG:A:LOGI:PAT:WHE	TRU
TRIG:A:LOGI:PAT:WHE:LESSL	8.0000E-9
TRIG:A:LOGI:PAT:WHE:MOREL	8.0000E-9
TRIG:A:LOGI:THR:CH1	0.0E+0
TRIG:A:LOGI:THR:CH2	0.0E+0
TRIG:A:LOGI:THR:CH3	0.0E+0
TRIG:A:LOGI:THR:CH4	0.0E+0
TRIG:A:LOGI:THR:D0	1.4000
TRIG:A:LOGI:THR:D1	1.4000
TRIG:A:LOGI:THR:D10	1.4000
TRIG:A:LOGI:THR:D11	1.4000
TRIG:A:LOGI:THR:D12	1.4000
TRIG:A:LOGI:THR:D13	1.4000
TRIG:A:LOGI:THR:D14	1.4000
TRIG:A:LOGI:THR:D15	1.4000
TRIG:A:LOGI:THR:D2	1.4000

Table C-1: Default values (cont.)

TRIG-ALOGI-THR.D3	Command	Default value
TRIGALOGITHR:D5	TRIG:A:LOGI:THR:D3	1.4000
TRIGALOGITHR:D6	TRIG:A:LOGI:THR:D4	1.4000
TRIGALOGITHR:D7	TRIG:A:LOGI:THR:D5	1.4000
TRIGALOGI:THR:D8	TRIG:A:LOGI:THR:D6	1.4000
TRIGALOW:CH1	TRIG:A:LOGI:THR:D7	1.4000
TRIG-ALOW:CH1	TRIG:A:LOGI:THR:D8	1.4000
TRIG-ALOW-CH2	TRIG:A:LOGI:THR:D9	1.4000
TRIG:A:LOW:CH3         0.0E+0           TRIG:A:LOW:CH4         0.0E+0           TRIG:A:LOW:D0         1.4000           TRIG:A:LOW:D1         1.4000           TRIG:A:LOW:D10         1.4000           TRIG:A:LOW:D11         1.4000           TRIG:A:LOW:D12         1.4000           TRIG:A:LOW:D13         1.4000           TRIG:A:LOW:D14         1.4000           TRIG:A:LOW:D15         1.4000           TRIG:A:LOW:D2         1.4000           TRIG:A:LOW:D2         1.4000           TRIG:A:LOW:D3         1.4000           TRIG:A:LOW:D4         1.4000           TRIG:A:LOW:D5         1.4000           TRIG:A:LOW:D6         1.4000           TRIG:A:LOW:D7         1.4000           TRIG:A:LOW:D8         1.4000           TRIG:A:LOW:D9         1.4000           TRIG:A:LOW:D9         1.4000           TRIG:A:LOW:D9         1.4000           TRIG:A:LOW:D9         1.4000           TRIG:A:LOW:EXT         0.0E+0           TRIG:A:PUL:CLA         WID           TRIG:A:PULSEW:POL         POS           TRIG:A:PULSEW:WHE         LESS           TRIG:A:PULSEW:WHE         LESS           TRIG:A:PULSEW	TRIG:A:LOW:CH1	0.0E+0
TRIG:A:LOW:CH4         0.0E+0           TRIG:A:LOW:D0         1.4000           TRIG:A:LOW:D1         1.4000           TRIG:A:LOW:D10         1.4000           TRIG:A:LOW:D11         1.4000           TRIG:A:LOW:D12         1.4000           TRIG:A:LOW:D13         1.4000           TRIG:A:LOW:D14         1.4000           TRIG:A:LOW:D15         1.4000           TRIG:A:LOW:D2         1.4000           TRIG:A:LOW:D2         1.4000           TRIG:A:LOW:D3         1.4000           TRIG:A:LOW:D4         1.4000           TRIG:A:LOW:D5         1.4000           TRIG:A:LOW:D6         1.4000           TRIG:A:LOW:D7         1.4000           TRIG:A:LOW:D8         1.4000           TRIG:A:LOW:D8         1.4000           TRIG:A:LOW:D9         1.4000           TRIG:A:LOW:D9         1.4000           TRIG:A:LOW:EXT         0.0E+0           TRIG:A:LOW:EXT         0.0E+0           TRIG:A:PUL:SCLA         WID           TRIG:A:PULSEW:POL         POS           TRIG:A:PULSEW:WHE         LESS           TRIG:A:PULSEW:WID         8.0000E-9           TRIG:A:RUNT:WIE         OCCURS           TRIG:	TRIG:A:LOW:CH2	0.0E+0
TRIG:A:LOW:D0         1.4000           TRIG:A:LOW:D1         1.4000           TRIG:A:LOW:D10         1.4000           TRIG:A:LOW:D11         1.4000           TRIG:A:LOW:D12         1.4000           TRIG:A:LOW:D13         1.4000           TRIG:A:LOW:D14         1.4000           TRIG:A:LOW:D15         1.4000           TRIG:A:LOW:D2         1.4000           TRIG:A:LOW:D2         1.4000           TRIG:A:LOW:D3         1.4000           TRIG:A:LOW:D4         1.4000           TRIG:A:LOW:D5         1.4000           TRIG:A:LOW:D6         1.4000           TRIG:A:LOW:D7         1.4000           TRIG:A:LOW:D8         1.4000           TRIG:A:LOW:D8         1.4000           TRIG:A:LOW:D9         1.4000           TRIG:A:LOW:EXT         0.0E+0           TRIG:A:PUL:CLA         WID           TRIG:A:PULSEW:POL         POS           TRIG:A:PULSEW:WID         8.0000E-9           TRIG:A:PULSEW:WID         8.0000E-9           TRIG:A:RUNT:WID         8.0000E-9	TRIG:A:LOW:CH3	0.0E+0
TRIG:A:LOW:D1         1.4000           TRIG:A:LOW:D10         1.4000           TRIG:A:LOW:D11         1.4000           TRIG:A:LOW:D12         1.4000           TRIG:A:LOW:D13         1.4000           TRIG:A:LOW:D14         1.4000           TRIG:A:LOW:D15         1.4000           TRIG:A:LOW:D2         1.4000           TRIG:A:LOW:D3         1.4000           TRIG:A:LOW:D4         1.4000           TRIG:A:LOW:D5         1.4000           TRIG:A:LOW:D6         1.4000           TRIG:A:LOW:D7         1.4000           TRIG:A:LOW:D8         1.4000           TRIG:A:LOW:D8         1.4000           TRIG:A:LOW:D8         1.4000           TRIG:A:LOW:EXT         0.0E+0           TRIG:A:LOW:EXT         0.0E+0           TRIG:A:PUL:CLA         WID           TRIG:A:PULSEW:WHE         LESS           TRIG:A:PULSEW:WHE         LESS           TRIG:A:PULSEW:WID         8.0000E-9           TRIG:A:RUNT:WHE         OCCURS           TRIG:A:RUNT:WID         8.0000E-9	TRIG:A:LOW:CH4	0.0E+0
TRIG:A:LOW:D10         1.4000           TRIG:A:LOW:D11         1.4000           TRIG:A:LOW:D12         1.4000           TRIG:A:LOW:D13         1.4000           TRIG:A:LOW:D14         1.4000           TRIG:A:LOW:D15         1.4000           TRIG:A:LOW:D2         1.4000           TRIG:A:LOW:D3         1.4000           TRIG:A:LOW:D4         1.4000           TRIG:A:LOW:D5         1.4000           TRIG:A:LOW:D6         1.4000           TRIG:A:LOW:D7         1.4000           TRIG:A:LOW:D8         1.4000           TRIG:A:LOW:D8         1.4000           TRIG:A:LOW:D8         1.4000           TRIG:A:LOW:D9         1.4000           TRIG:A:LOW:EXT         0.0E+0           TRIG:A:LOW:EXT         0.0E+0           TRIG:A:PUL:CLA         WID           TRIG:A:PULSEW:WHE         LESS           TRIG:A:PULSEW:WHE         LESS           TRIG:A:PULSEW:WID         8.0000E-9           TRIG:A:RUNT:WHE         OCCURS           TRIG:A:RUNT:WID         8.0000E-9	TRIG:A:LOW:D0	1.4000
TRIG:A:LOW:D11         1.4000           TRIG:A:LOW:D12         1.4000           TRIG:A:LOW:D13         1.4000           TRIG:A:LOW:D14         1.4000           TRIG:A:LOW:D15         1.4000           TRIG:A:LOW:D2         1.4000           TRIG:A:LOW:D3         1.4000           TRIG:A:LOW:D4         1.4000           TRIG:A:LOW:D5         1.4000           TRIG:A:LOW:D6         1.4000           TRIG:A:LOW:D7         1.4000           TRIG:A:LOW:D8         1.4000           TRIG:A:LOW:D8         1.4000           TRIG:A:LOW:D9         1.4000           TRIG:A:LOW:EXT         0.0E+0           TRIG:A:MOD         AUTO           TRIG:A:PULSEW:POL         POS           TRIG:A:PULSEW:WHE         LESS           TRIG:A:PULSEW:WID         8.0000E-9           TRIG:A:RUNT:POL         POS           TRIG:A:RUNT:WHE         OCCURS           TRIG:A:RUNT:WID         8.0000E-9	TRIG:A:LOW:D1	1.4000
TRIG:A:LOW:D12         1,4000           TRIG:A:LOW:D13         1,4000           TRIG:A:LOW:D14         1,4000           TRIG:A:LOW:D15         1,4000           TRIG:A:LOW:D2         1,4000           TRIG:A:LOW:D3         1,4000           TRIG:A:LOW:D4         1,4000           TRIG:A:LOW:D5         1,4000           TRIG:A:LOW:D6         1,4000           TRIG:A:LOW:D7         1,4000           TRIG:A:LOW:D8         1,4000           TRIG:A:LOW:D9         1,4000           TRIG:A:LOW:EXT         0,0E+0           TRIG:A:MOD         AUTO           TRIG:A:PUL:CLA         WID           TRIG:A:PULSEW:POL         POS           TRIG:A:PULSEW:WHE         LESS           TRIG:A:PULSEW:WID         8,0000E-9           TRIG:A:RUNT:WHE         OCCURS           TRIG:A:RUNT:WID         8,0000E-9	TRIG:A:LOW:D10	1.4000
TRIG:A:LOW:D13       1,4000         TRIG:A:LOW:D14       1,4000         TRIG:A:LOW:D15       1,4000         TRIG:A:LOW:D2       1,4000         TRIG:A:LOW:D3       1,4000         TRIG:A:LOW:D4       1,4000         TRIG:A:LOW:D5       1,4000         TRIG:A:LOW:D6       1,4000         TRIG:A:LOW:D7       1,4000         TRIG:A:LOW:D8       1,4000         TRIG:A:LOW:D8       1,4000         TRIG:A:LOW:EXT       0,0E+0         TRIG:A:LOW:EXT       0,0E+0         TRIG:A:MOD       AUTO         TRIG:A:PUL:CLA       WID         TRIG:A:PULSEW:POL       POS         TRIG:A:PULSEW:WHE       LESS         TRIG:A:PULSEW:WID       8,0000E-9         TRIG:A:RUNT:POL       POS         TRIG:A:RUNT:WHE       OCCURS         TRIG:A:RUNT:WID       8,0000E-9	TRIG:A:LOW:D11	1.4000
TRIG:A:LOW:D14       1.4000         TRIG:A:LOW:D15       1.4000         TRIG:A:LOW:D2       1.4000         TRIG:A:LOW:D3       1.4000         TRIG:A:LOW:D4       1.4000         TRIG:A:LOW:D5       1.4000         TRIG:A:LOW:D6       1.4000         TRIG:A:LOW:D7       1.4000         TRIG:A:LOW:D8       1.4000         TRIG:A:LOW:D9       1.4000         TRIG:A:LOW:EXT       0.0E+0         TRIG:A:MOD       AUTO         TRIG:A:PUL:CLA       WID         TRIG:A:PULSEW:POL       POS         TRIG:A:PULSEW:WHE       LESS         TRIG:A:PULSEW:WID       8.0000E-9         TRIG:A:RUNT:WHE       OCCURS         TRIG:A:RUNT:WID       8.0000E-9	TRIG:A:LOW:D12	1.4000
TRIG:A:LOW:D15       1.4000         TRIG:A:LOW:D2       1.4000         TRIG:A:LOW:D3       1.4000         TRIG:A:LOW:D4       1.4000         TRIG:A:LOW:D5       1.4000         TRIG:A:LOW:D6       1.4000         TRIG:A:LOW:D7       1.4000         TRIG:A:LOW:D8       1.4000         TRIG:A:LOW:D9       1.4000         TRIG:A:LOW:EXT       0.0E+0         TRIG:A:MOD       AUTO         TRIG:A:PUL:CLA       WID         TRIG:A:PULSEW:POL       POS         TRIG:A:PULSEW:WHE       LESS         TRIG:A:PULSEW:WID       8.0000E-9         TRIG:A:RUNT:POL       POS         TRIG:A:RUNT:WHE       OCCURS         TRIG:A:RUNT:WID       8.0000E-9	TRIG:A:LOW:D13	1.4000
TRIG:A:LOW:D2       1.4000         TRIG:A:LOW:D3       1.4000         TRIG:A:LOW:D4       1.4000         TRIG:A:LOW:D5       1.4000         TRIG:A:LOW:D6       1.4000         TRIG:A:LOW:D7       1.4000         TRIG:A:LOW:D8       1.4000         TRIG:A:LOW:D9       1.4000         TRIG:A:LOW:EXT       0.0E+0         TRIG:A:MOD       AUTO         TRIG:A:PUL:CLA       WID         TRIG:A:PULSEW:POL       POS         TRIG:A:PULSEW:WHE       LESS         TRIG:A:PULSEW:WID       8.0000E-9         TRIG:A:RUNT:POL       POS         TRIG:A:RUNT:WHE       OCCURS         TRIG:A:RUNT:WID       8.0000E-9	TRIG:A:LOW:D14	1.4000
TRIG:A:LOW:D3       1.4000         TRIG:A:LOW:D4       1.4000         TRIG:A:LOW:D5       1.4000         TRIG:A:LOW:D6       1.4000         TRIG:A:LOW:D7       1.4000         TRIG:A:LOW:D8       1.4000         TRIG:A:LOW:D9       1.4000         TRIG:A:LOW:EXT       0.0E+0         TRIG:A:MOD       AUTO         TRIG:A:PUL:CLA       WID         TRIG:A:PULSEW:POL       POS         TRIG:A:PULSEW:WHE       LESS         TRIG:A:PULSEW:WID       8.0000E-9         TRIG:A:RUNT:POL       POS         TRIG:A:RUNT:WHE       OCCURS         TRIG:A:RUNT:WID       8.0000E-9	TRIG:A:LOW:D15	1.4000
TRIG:A:LOW:D4         1.4000           TRIG:A:LOW:D5         1.4000           TRIG:A:LOW:D6         1.4000           TRIG:A:LOW:D7         1.4000           TRIG:A:LOW:D8         1.4000           TRIG:A:LOW:D9         1.4000           TRIG:A:LOW:EXT         0.0E+0           TRIG:A:MOD         AUTO           TRIG:A:PUL:CLA         WID           TRIG:A:PULSEW:POL         POS           TRIG:A:PULSEW:WHE         LESS           TRIG:A:PULSEW:WID         8.0000E-9           TRIG:A:RUNT:POL         POS           TRIG:A:RUNT:WHE         OCCURS           TRIG:A:RUNT:WID         8.0000E-9	TRIG:A:LOW:D2	1.4000
TRIG:A:LOW:D5       1.4000         TRIG:A:LOW:D6       1.4000         TRIG:A:LOW:D7       1.4000         TRIG:A:LOW:D8       1.4000         TRIG:A:LOW:D9       1.4000         TRIG:A:LOW:EXT       0.0E+0         TRIG:A:MOD       AUTO         TRIG:A:PUL:CLA       WID         TRIG:A:PULSEW:POL       POS         TRIG:A:PULSEW:WHE       LESS         TRIG:A:PULSEW:WID       8.0000E-9         TRIG:A:RUNT:POL       POS         TRIG:A:RUNT:WHE       OCCURS         TRIG:A:RUNT:WID       8.0000E-9	TRIG:A:LOW:D3	1.4000
TRIG:A:LOW:D6         1.4000           TRIG:A:LOW:D7         1.4000           TRIG:A:LOW:D8         1.4000           TRIG:A:LOW:EXT         0.0E+0           TRIG:A:MOD         AUTO           TRIG:A:PUL:CLA         WID           TRIG:A:PULSEW:POL         POS           TRIG:A:PULSEW:WHE         LESS           TRIG:A:PULSEW:WID         8.0000E-9           TRIG:A:RUNT:POL         POS           TRIG:A:RUNT:WHE         OCCURS           TRIG:A:RUNT:WID         8.0000E-9	TRIG:A:LOW:D4	1.4000
TRIG:A:LOW:D7       1.4000         TRIG:A:LOW:D8       1.4000         TRIG:A:LOW:D9       1.4000         TRIG:A:LOW:EXT       0.0E+0         TRIG:A:MOD       AUTO         TRIG:A:PUL:CLA       WID         TRIG:A:PULSEW:POL       POS         TRIG:A:PULSEW:WHE       LESS         TRIG:A:PULSEW:WID       8.0000E-9         TRIG:A:RUNT:POL       POS         TRIG:A:RUNT:WHE       OCCURS         TRIG:A:RUNT:WID       8.0000E-9	TRIG:A:LOW:D5	1.4000
TRIG:A:LOW:D8       1.4000         TRIG:A:LOW:EXT       0.0E+0         TRIG:A:MOD       AUTO         TRIG:A:PUL:CLA       WID         TRIG:A:PULSEW:POL       POS         TRIG:A:PULSEW:WHE       LESS         TRIG:A:PULSEW:WID       8.0000E-9         TRIG:A:RUNT:POL       POS         TRIG:A:RUNT:WHE       OCCURS         TRIG:A:RUNT:WID       8.0000E-9	TRIG:A:LOW:D6	1.4000
TRIG:A:LOW:D9       1.4000         TRIG:A:LOW:EXT       0.0E+0         TRIG:A:MOD       AUTO         TRIG:A:PUL:CLA       WID         TRIG:A:PULSEW:POL       POS         TRIG:A:PULSEW:WHE       LESS         TRIG:A:PULSEW:WID       8.0000E-9         TRIG:A:RUNT:POL       POS         TRIG:A:RUNT:WHE       OCCURS         TRIG:A:RUNT:WID       8.0000E-9	TRIG:A:LOW:D7	1.4000
TRIG:A:LOW:EXT         0.0E+0           TRIG:A:MOD         AUTO           TRIG:A:PUL:CLA         WID           TRIG:A:PULSEW:POL         POS           TRIG:A:PULSEW:WHE         LESS           TRIG:A:PULSEW:WID         8.0000E-9           TRIG:A:RUNT:POL         POS           TRIG:A:RUNT:WHE         OCCURS           TRIG:A:RUNT:WID         8.0000E-9	TRIG:A:LOW:D8	1.4000
TRIG:A:MOD         AUTO           TRIG:A:PUL:CLA         WID           TRIG:A:PULSEW:POL         POS           TRIG:A:PULSEW:WHE         LESS           TRIG:A:PULSEW:WID         8.0000E-9           TRIG:A:RUNT:POL         POS           TRIG:A:RUNT:WHE         OCCURS           TRIG:A:RUNT:WID         8.0000E-9	TRIG:A:LOW:D9	1.4000
TRIG:A:PUL:CLA         WID           TRIG:A:PULSEW:POL         POS           TRIG:A:PULSEW:WHE         LESS           TRIG:A:PULSEW:WID         8.0000E-9           TRIG:A:RUNT:POL         POS           TRIG:A:RUNT:WHE         OCCURS           TRIG:A:RUNT:WID         8.0000E-9	TRIG:A:LOW:EXT	0.0E+0
TRIG:A:PULSEW:POL         POS           TRIG:A:PULSEW:WHE         LESS           TRIG:A:PULSEW:WID         8.0000E-9           TRIG:A:RUNT:POL         POS           TRIG:A:RUNT:WHE         OCCURS           TRIG:A:RUNT:WID         8.0000E-9	TRIG:A:MOD	AUTO
TRIG:A:PULSEW:WHE         LESS           TRIG:A:PULSEW:WID         8.0000E-9           TRIG:A:RUNT:POL         POS           TRIG:A:RUNT:WHE         OCCURS           TRIG:A:RUNT:WID         8.0000E-9	TRIG:A:PUL:CLA	WID
TRIG:A:PULSEW:WID         8.0000E-9           TRIG:A:RUNT:POL         POS           TRIG:A:RUNT:WHE         OCCURS           TRIG:A:RUNT:WID         8.0000E-9	TRIG:A:PULSEW:POL	POS
TRIG:A:RUNT:POL POS TRIG:A:RUNT:WHE OCCURS TRIG:A:RUNT:WID 8.0000E-9	TRIG:A:PULSEW:WHE	LESS
TRIG:A:RUNT:WHE OCCURS TRIG:A:RUNT:WID 8.0000E-9	TRIG:A:PULSEW:WID	8.0000E-9
TRIG:A:RUNT:WID 8.0000E-9	TRIG:A:RUNT:POL	POS
	TRIG:A:RUNT:WHE	OCCURS
TRIG:A:SETH:CLOC:EDGE RIS	TRIG:A:RUNT:WID	8.0000E-9
	TRIG:A:SETH:CLOC:EDGE	RIS

Table C-1: Default values (cont.)

Command	Default value
TRIG:A:SETH:CLOC:SOU	CH1
TRIG:A:SETH:CLOC:THR	0.0E+0
TRIG:A:SETH:DAT:SOU	NONE
TRIG:A:SETH:DAT:THR	9.9100E+37
TRIG:A:SETH:HOLDT	8.0000E-9
TRIG:A:SETH:SETT	8.0000E-9
TRIG:A:SETH:THR:CH1	0.0E+0
TRIG:A:SETH:THR:CH2	0.0E+0
TRIG:A:SETH:THR:CH3	0.0E+0
TRIG:A:SETH:THR:CH4	0.0E+0
TRIG:A:SETH:THR:D0	1.4000
TRIG:A:SETH:THR:D1	1.4000
TRIG:A:SETH:THR:D10	1.4000
TRIG:A:SETH:THR:D11	1.4000
TRIG:A:SETH:THR:D12	1.4000
TRIG:A:SETH:THR:D13	1.4000
TRIG:A:SETH:THR:D14	1.4000
TRIG:A:SETH:THR:D15	1.4000
TRIG:A:SETH:THR:D2	1.4000
TRIG:A:SETH:THR:D3	1.4000
TRIG:A:SETH:THR:D4	1.4000
TRIG:A:SETH:THR:D5	1.4000
TRIG:A:SETH:THR:D6	1.4000
TRIG:A:SETH:THR:D7	1.4000
TRIG:A:SETH:THR:D8	1.4000
TRIG:A:SETH:THR:D9	1.4000
TRIG:A:TRAN:DELT	8.0000E-9
TRIG:A:TRAN:POL	POS
TRIG:A:TRAN:WHE	SLOW
TRIG:A:TYP	EDG
TRIG:A:UPP:CH1	800.0000E-3
TRIG:A:UPP:CH2	800.0000E-3
TRIG:A:UPP:CH3	800.0000E-3
TRIG:A:UPP:CH4	800.0000E-3
TRIG:A:VID:HOLD:FIELD	0.0E+0
TRIG:A:VID:LINE	1
TRIG:A:VID:POL	POS

Table C-1: Default values (cont.)

Command	Default value
TRIG:A:VID:STAN	NTS
TRIG:A:VID:SYNC	ALLL
TRIG:B:BY	TIM
TRIG:B:EDGE:COUP	DC
TRIG:B:EDGE:SLO	RIS
TRIG:B:EDGE:SOU	CH1
TRIG:B:EVENTS:COUN	1
TRIG:B:LEV	0.0E+0
TRIG:B:LEV:CH1	0.0E+0
TRIG:B:LEV:CH2	0.0E+0
TRIG:B:LEV:CH3	0.0E+0
TRIG:B:LEV:CH4	0.0E+0
TRIG:B:LEV:D0	1.4000
TRIG:B:LEV:D1	1.4000
TRIG:B:LEV:D10	1.4000
TRIG:B:LEV:D11	1.4000
TRIG:B:LEV:D12	1.4000
TRIG:B:LEV:D13	1.4000
TRIG:B:LEV:D14	1.4000
TRIG:B:LEV:D15	1.4000
TRIG:B:LEV:D2	1.4000
TRIG:B:LEV:D3	1.4000
TRIG:B:LEV:D4	1.4000
TRIG:B:LEV:D5	1.4000
TRIG:B:LEV:D6	1.4000
TRIG:B:LEV:D7	1.4000
TRIG:B:LEV:D8	1.4000
TRIG:B:LEV:D9	1.4000
TRIG:B:LOW:CH1	0.0E+0
TRIG:B:LOW:CH2	0.0E+0
TRIG:B:LOW:CH3	0.0E+0
TRIG:B:LOW:CH4	0.0E+0
TRIG:B:LOW:D0	1.4000
TRIG:B:LOW:D1	1.4000
TRIG:B:LOW:D10	1.4000
TRIG:B:LOW:D11	1.4000
TRIG:B:LOW:D12	1.4000

Table C-1: Default values (cont.)

Command	Default value
TRIG:B:LOW:D13	1.4000
TRIG:B:LOW:D14	1.4000
TRIG:B:LOW:D15	1.4000
TRIG:B:LOW:D2	1.4000
TRIG:B:LOW:D3	1.4000
TRIG:B:LOW:D4	1.4000
TRIG:B:LOW:D5	1.4000
TRIG:B:LOW:D6	1.4000
TRIG:B:LOW:D7	1.4000
TRIG:B:LOW:D8	1.4000
TRIG:B:LOW:D9	1.4000
TRIG:B:STATE	0
TRIG:B:TIM	8.0000E-9
TRIG:B:TYP	EDG
TRIG:B:UPP:CH1	800.0000E-3
TRIG:B:UPP:CH2	800.0000E-3
TRIG:B:UPP:CH3	800.0000E-3
TRIG:B:UPP:CH4	800.0000E-3
TRIG:EXT:PRO	1.0000
VERB	0
ZOO:MOD	0
ZOO:ZOOM1:HOR:POS	50.0000
ZOO:ZOOM1:HOR:SCA	4.0000E-6
ZOO:ZOOM1:POS	50.0000
ZOO:ZOOM1:SCA	4.0000E-6
ZOO:ZOOM1:STATE	0

## **Appendix D: Programming Example**

The following series of commands and queries illustrate many of the most common commands and techniques. In this example, data sent from the controller computer to the oscilloscope is prefaced with the > symbol. Replies from the oscilloscope have no preface.

```
> rem "Check for any messages, and clear them from the queue."
> *esr?
128
> allev?
:ALLEV 401,"Power on; "
> rem "Set the scope to the default state."
> factory
> rem "Set the scope parameters that differ from the defaults."
> ch1:scale 2.0
> hor:m:scale 100e-6
> trig:a:level 2.4
> rem "Start a single sequence acquisition."
> acquire:stopafter sequence
> acquire:state on
> rem "Wait for the acquisition to complete."
> rem "Note: your controller program time-out must be set long enough to handle
the wait."
> *opc?
> rem "Use the oscilloscope built-in measurements to measure the waveform
you acquired."
> measu:immed:type mean
> measu:immed:value?
:MEASUREMENT:IMMED:VALUE 1.2767
```

```
> rem "Be sure to use the *esr? query to check for measurement errors."
> measu:immed:type freq
> measu:immed:value
:MEASUREMENT:IMMED:VALUE 9.9100E+37
> *esr?
16
> alley?
:ALLEV 2202,"Measurement error, No period found "
> rem "Query out the waveform points, for later analysis on your controller
computer."
> data:encdg ascii
> curve?
:CURVE 7,6,5,5,5,6,6,6,8 [...]
> rem "Query out the parameters used for calculating the times and voltages of
the waveform points."
> wfmpre?
:WFMPRE:BYT_NR 1;BIT_NR 8;ENCDG ASCII;BN_FMT RI;BYT_OR
MSB;NR PT 10000; [...]
```

# Index

A	BUS:B <x>:AUDio:DATa:SOUrce, 2-89</x>
ACQuire:MAXSamplerate?, 2-72	BUS:B <x>:AUDio:DISplay:FORMat, 2-89</x>
ACQuire?, 2-71	BUS:B <x>:AUDio:FRAME:SIZe, 2-90</x>
ACQuire:MAGnivu, 2-71	BUS:B <x>:AUDio:FRAMESync:POLarity, 2-90</x>
ACQuire:MODe, 2-72	BUS:B <x>:AUDio:FRAMESync:SOUrce, 2-91</x>
ACQuire:NUMACq?, 2-73	BUS:B <x>:AUDio:TYPe, 2-91</x>
ACQuire:NUMAVg, 2-73	BUS:B <x>:AUDio:WORDSel:POLarity, 2-92</x>
ACQuire:STATE, 2-74	BUS:B <x>:AUDio:WORDSel:SOUrce, 2-92</x>
ACQuire:STOPAfter, 2-75	BUS:B <x>:CAN:BITRate, 2-93</x>
Acquisition Command Group, 2-11	BUS:B <x>:CAN:PRObe, 2-94</x>
Acquisition Command Group, 2-11 Alias Command Group, 2-12	BUS:B <x>:CAN:SAMPLEpoint, 2-94</x>
ALIas, 2-75	BUS:B <x>:CAN:SOUrce, 2-94</x>
ALIas, 2-73 ALIas[:STATE], 2-78	BUS:B <x>:DISplay:FORMAt, 2-95</x>
ALIas[.STATE], 2-76 ALIas:CATalog?, 2-76	BUS:B <x>:DISplay:TYPe, 2-96</x>
ALIas:DEFine, 2-76	BUS:B <x>:FLEXray:BITRate, 2-96</x>
· · · · · · · · · · · · · · · · · · ·	BUS:B <x>:FLEXray:CHannel, 2-97</x>
ALIas:DELEte, 2-77	BUS:B <x>:FLEXray:SIGnal, 2-97</x>
ALIas:DELEte[:NAMe], 2-78	BUS:B <x>:FLEXray:SOUrce, 2-98</x>
ALLE: 2.2.70	BUS:B <x>:I2C:ADDRess:RWINClude, 2-98</x>
ALLEV?, 2-79	BUS:B <x>:I2C{:CLOCK :SCLK}:SOUrce, 2-99</x>
AUTOSet, 2-79	BUS:B <x>:I2C{:DATA :SDATA}:SOUrce, 2-99</x>
AUTOSet:ENAble, 2-80	BUS:B <x>:LIN:BITRate, 2-100</x>
AUXin:PRObe:AUTOZero, 2-81	BUS:B <x>:LIN:IDFORmat, 2-100</x>
AUXin:PRObe:DEGAUss:STATE?, 2-82	BUS:B <x>:LIN:POLARity, 2-101</x>
AUXin:PRObe:FORCEDRange, 2-82	BUS:B <x>:LIN:SAMPLEpoint, 2-101</x>
AUXin:PRObe:ID:SERnumber?, 2-83	BUS:B <x>:LIN:SOUrce, 2-102</x>
AUXin:PRObe:ID:TYPE?, 2-83	BUS:B <x>:LIN:STANDard, 2-102</x>
AUXin:PRObe:RESistance?, 2-83	BUS:B <x>:PARallel:BIT<x>:SOUrce, 2-103</x></x>
AUXin?, 2-80	BUS:B <x>:PARallel:CLOCK:EDGE, 2-103</x>
AUXin:PRObe, 2-80	BUS:B <x>:PARallel:CLOCK:ISCLOCKed, 2-103</x>
AUXin:PRObe:COMMAND, 2-81	BUS:B <x>:PARallel:CLOCK:SOUrce, 2-104</x>
AUXin:PRObe:DEGAUss, 2-82	BUS:B <x>:PARallel:WIDth, 2-104</x>
AUXin:PRObe:GAIN, 2-83	BUS:B <x>:POSition, 2-104</x>
AUXin:PRObe:SIGnal, 2-84	BUS:B <x>:RS232C:BITRate, 2-105</x>
AUXin:PRObe:UNIts?, 2-84	,
	BUS:B <x>:RS232C:DATABits, 2-105</x>
В	BUS:B <x>:RS232C:DELIMiter, 2-106</x>
BUS:B <x>:AUDio:BITDelay, 2-85</x>	BUS:B <x>:RS232C:DISplaymode, 2-106</x>
BUS:B <x>:AUDio:BITOclay, 2-85</x>	BUS:B <x>:RS232C:PARity, 2-106</x>
BUS:B <x>:AUDio:CHANnel:SIZe, 2-86</x>	BUS:B <x>:RS232C:POLarity, 2-107</x>
BUS:B <x>:AUDio:CHANIei:SiZe, 2-80 BUS:B<x>:AUDio:CLOCk:POLarity, 2-86</x></x>	BUS:B <x>:RS232C:RX:SOUrce, 2-107</x>
BUS:B <x>:AUDio:CLOCk:POLanty, 2-80 BUS:B<x>:AUDio:CLOCk:SOUrce, 2-87</x></x>	BUS:B <x>:RS232C:TX:SOUrce, 2-108</x>
	BUS:B <x>:SPI:BITOrder, 2-108</x>
BUS:B <x>:AUDio:DATa:POLarity, 2-88 BUS:B<x>:AUDio:DATa:SIZe, 2-88</x></x>	BUS:B <x>:SPI:DATA:SIZe, 2-111 BUS:B<x>:SPI:DATA:FINI-MISO:POLARity 2-10</x></x>
DU3.D^X/.AUDI0.DATa.3D/だ. 2-88	RUS:R <v>:SPI:DATAJ:INU:MUSOU:POLARity/7_10</v>

BUS:B <x>:SPI:DATA {:IN :MISO}:SOUrce, 2-110</x>	CH <x>:PRObe:RESistance?, 2-133</x>
BUS:B <x>:SPI:DATA{:OUT :MOSI}:</x>	CH <x>:PRObe:SIGnal, 2-133</x>
POLARity, 2-110	CH <x>:PRObe:UNIts?, 2-133</x>
BUS:B <x>:SPI:DATA{:OUT :MOSI}:SOUrce, 2-110</x>	CH <x>:TERmination, 2-135</x>
BUS:B <x>:SPI:FRAMING, 2-111</x>	CH <x>?, 2-122</x>
BUS:B <x>:SPI:IDLETime, 2-112</x>	CH <x>:BANdwidth, 2-123</x>
BUS:B <x>:SPI{:CLOCK :SCLK}:POLARity, 2-109</x>	CH <x>:COUPling, 2-124</x>
BUS:B <x>:SPI{:CLOCK :SCLK}:SOUrce, 2-109</x>	CH <x>:DESKew, 2-124</x>
BUS:B <x>:SPI{:SELect :SS}:POLARity, 2-112</x>	CH <x>:INVert, 2-125</x>
BUS:B <x>:SPI{:SELect :SS}:SOUrce, 2-112</x>	CH <x>:LABel, 2-125</x>
BUS:B <x>:USB:BITRate, 2-114</x>	CH <x>:OFFSet, 2-126</x>
BUS:B <x>:USB:PRObe, 2-114</x>	CH <x>:POSition, 2-127</x>
BUS:B <x>:USB:SOUrce:DIFFerential, 2-115</x>	CH <x>:PRObe?, 2-128</x>
BUS:B <x>:USB:SOUrce:DMINus, 2-115</x>	CH <x>:PRObe:GAIN, 2-130</x>
BUS:B <x>:USB:SOUrce:DPLUs, 2-116</x>	CH <x>:PRObe:ID?, 2-130</x>
BUS:LOWerthreshold:CH <x>, 2-116</x>	CH <x>:SCAle, 2-134</x>
BUS:THReshold:CH <x>, 2-117</x>	CH <x>:YUNits, 2-135</x>
BUS:THReshold:D <x>, 2-117</x>	CLEARMenu, 2-136
BUS:UPPerthreshold:CH <x>, 2-118</x>	*CLS, 2-136
BUS?, 2-85	Command Groups, 2-11
BUS:B <x>:LABel, 2-99</x>	Cursor Command Group, 2-17
BUS:B <x>:STATE, 2-113</x>	CURSor:HBArs:POSITION <x>, 2-138</x>
BUS:B <x>:TYPE, 2-113</x>	CURSor:VBArs:ALTERNATE <x>?, 2-141</x>
BUSY?, 2-118	CURSor:VBArs:HPOS <x>?, 2-142</x>
	CURSor:VBArs:POSITION <x>, 2-142</x>
C	CURSor:VBArs:VDELTa?, 2-144
	CURSor:XY:POLar:RADIUS:DELta?, 2-144
*CAL?, 2-119	CURSor:XY:POLar:RADIUS:POSITION <x>?, 2-145</x>
CALibrate:FACtory:STATus?, 2-119	CURSor:XY:POLar:RADIUS:UNIts?, 2-145
CALibrate:INTERNal:STARt, 2-120 CALibrate:INTERNal:STATus?, 2-120	CURSor:XY:POLar:THETA:DELta?, 2-145
CALibrate:RESults:FACtory?, 2-121	CURSor:XY:POLar:THETA:POSITION <x>?, 2-145</x>
CALibrate:RESults:SPC?, 2-122	CURSor:XY:POLar:THETA:UNIts?, 2-146
CALibrate:INTERNal, 2-120	CURSor:XY:PRODUCT:DELta?, 2-146
CALibrate:RESults?, 2-121	CURSor:XY:PRODUCT:POSITION <x>?, 2-146</x>
Calibration and Diagnostic Command Group, 2-17	CURSor:XY:PRODUCT:UNIts?, 2-146
CH <x>:AMPSVIAVOLTs:ENAble, 2-122</x>	CURSor:XY:RATIO:DELta?, 2-147
CH <x>:AMPSVIAVOLTS:FACtor, 2-123</x>	CURSor:XY:RATIO:POSITION <x>?, 2-147</x>
CH <x>:AWI SVIAVOLIS.FACIOI, 2-123 CH<x>:PRObe:AUTOZero, 2-128</x></x>	CURSor:XY:RATIO:UNIts?, 2-147
CH <x>:PRObe:COMMAND, 2-128</x>	CURSor:XY:RECTangular:X:DELta?, 2-148
CH <x>:PRObe:DEGAUss, 2-129</x>	CURSor:XY:RECTangular:X:POSITION <x>, 2-148</x>
CH <x>:PRObe:DEGAUss; 2-129 CH<x>:PRObe:DEGAUss:STATE?, 2-129</x></x>	CURSor:XY:RECTangular:X:UNIts?, 2-148
CH <x>:PRObe:FORCEDRange, 2-129</x>	CURSor:XY:RECTangular:Y:DELta?, 2-148
CH <x>:PRObe:PORCEDRange, 2-129 CH<x>:PRObe:ID:SERnumber?, 2-131</x></x>	CURSor:XY:RECTangular:Y:POSITION <x>, 2-149</x>
CH <x>:PRObe:ID:TYPE?, 2-131</x>	CURSor:XY:RECTangular:Y:UNIts?, 2-149
CH <x>:PRObe:ID:14PE?, 2-131 CH<x>:PRObe:MODel, 2-132</x></x>	CURSor?, 2-136
CH <x>:PRObe:PROPDELay, 2-132</x>	CURSor:DDT?, 2-137
CH <x>:PRObe:RECDESkew?, 2-132</x>	CURSor:FUNCtion, 2-137

DISplay:INTENSITy?, 2-164 CURSor: HBArs?, 2-138 CURSor:HBArs:DELTa?, 2-138 DISplay:PERSistence, 2-166 CURSor: HBArs: UNIts, 2-139 CURSor:HBArs:USE, 2-139 Ε CURSor: MODe, 2-140 \*ESE, 2-169 CURSor: VBArs?, 2-140 \*ESR?, 2-169 CURSor: VBArs: DELTa?, 2-141 Ethernet Command Group, 2-20 CURSor: VBArs: UNIts, 2-143 ETHERnet:DNS:IPADDress, 2-170 CURSor: VBArs: USE, 2-143 ETHERnet:ENET:ADDress?, 2-171 CURSor:XY:READOUT, 2-147 ETHERnet: GATEWay: IPADDress, 2-171 CURVe, 2-149 ETHERnet:PING:STATUS?, 2-174 ETHERnet:DHCPbootp, 2-170 D ETHERnet:DOMAINname, 2-171 D < x > , 2-167ETHERnet:HTTPPort, 2-172 D < x > : LABel, 2-167ETHERnet: IPADDress, 2-172 ETHERnet:NAME, 2-173 D < x >: POSition, 2-168D<x>:THREshold, 2-168 ETHERnet:PASSWord, 2-173 DATa, 2-151 ETHERnet:PING, 2-173 ETHERnet:SUBNETMask, 2-174 DATa: DESTination, 2-151 DATa:ENCdg, 2-152 EVENT?, 2-174 DATa:SOUrce, 2-153 EVMsg?, 2-175 EVQty?, 2-175 DATa:STARt, 2-154 DATa:STOP, 2-155 DATE, 2-156 F \*DDT, 2-156 FACtory, 2-176 DESE, 2-157 File System Command Group, 2-21 DESkew, 2-158 FILESystem:FREESpace?, 2-180 DESkew:DISPlay, 2-158 FILESystem: WRITEFile, 2-183 DIAg:LOOP:OPTion:NTIMes, 2-159 FILESystem?, 2-177 DIAg:SELect:<function>, 2-161 FILESystem: CWD, 2-177 DIAg:LOOP:OPTion, 2-158 FILESystem: DELEte, 2-178 DIAg:LOOP:STOP, 2-159 FILESystem:DIR?, 2-179 DIAg:RESUlt:FLAg?, 2-160 FILESystem: FORMat, 2-179 DIAg:RESUlt:LOG?, 2-160 FILESystem:LDIR?, 2-180 DIAg:SELect, 2-161 FILESystem: MKDir, 2-181 DIAg:STATE, 2-162 FILESystem: READFile, 2-181 Display Command Group, 2-19 FILESystem: REName, 2-182 DISplay:DIGital:HEIght, 2-163 FILESystem: RMDir, 2-182 DISplay:INTENSITy:BACKLight, 2-165 FPAnel:PRESS, 2-183 DISplay: INTENSITy: GRAticule, 2-165 FPAnel:TURN, 2-185 DISplay:INTENSITy:WAVEform, 2-165 DISplay:STYle:DOTsonly, 2-167 G DISplay?, 2-162 DISplay:CLOCk, 2-162 GPIBUsb:ADDress?, 2-186 DISplay:FORMat, 2-163 GPIBUsb:ID?, 2-186

DISplay: GRAticule, 2-164

H	M
Hard copy Command Group, 2-22	Mark Command Group, 2-25
HARDCopy, 2-186	MARK, 2-205
HARDCopy: ACTIVeprinter, 2-187	MARK:SELected:FOCUS?, 2-206
HARDCopy:PRINTer:ADD, 2-189	MARK:SELected:MARKSINCOLumn?, 2-207
HARDCopy:PRINTer:DELete, 2-189	MARK:SELected:OWNer?, 2-207
HARDCopy:PRINTer:LIST?, 2-189	MARK:SELected:SOURCE?, 2-207
HARDCopy:PRINTer:REName, 2-189	MARK:SELected:STARt?, 2-207
HARDCopy:INKSaver, 2-187	MARK:SELected:STATe?, 2-208
HARDCopy:LAYout, 2-188	MARK:SELected:ZOOm:POSition?, 2-208
HARDCopy:PREVIEW, 2-188	MARK:CREATE, 2-205
HEADer, 2-190	MARK:DELEte, 2-205
Histogram Command Group, 2-24	MARK:FREE?, 2-206
HIStogram?, 2-191	MARK:SELected:END?, 2-206
HIStogram:BOX, 2-191	MARK:TOTal?, 2-208
HIStogram:BOXPcnt, 2-192	Math Command Group, 2-26
HIStogram: COUNt, 2-193	MATH[1]:HORizontal:POSition, 2-211
HIStogram: DATa?, 2-193	MATH[1]:HORizontal:SCAle, 2-211
HIStogram:DISplay, 2-194	MATH[1]:HORizontal:UNIts, 2-211
HIStogram: END?, 2-195	MATH[1]:SPECTral:MAG, 2-212
HIStogram:MODe, 2-195	MATH[1]:SPECTral:WINdow, 2-212
HIStogram:SOUrce, 2-196	MATH[1]:VERTical:POSition, 2-213
HIStogram:STARt?, 2-197	MATH[1]:VERTical:SCAle, 2-214
Horizontal Command Group, 2-24	MATH[1]:VERTical:UNIts, 2-214
HORizontal:DELay:MODe, 2-198	MATH[1]?, 2-209
HORizontal:DELay:TIMe, 2-198	MATH[1]:DEFine, 2-209
HORizontal:DIGital:RECOrdlength:	MATH[1]:TYPe, 2-213
MAGnivu?, 2-199	{MATH MATH1}:LABel, 2-208
HORizontal:DIGital:RECOrdlength:MAIN?, 2-199	MATHVAR?, 2-215
HORizontal:DIGital:SAMPLERate:MAGnivu?, 2-199	MATHVAR:VAR <x>, 2-215</x>
HORizontal:DIGital:SAMPLERate:MAIN?, 2-199	Measurement Command Group, 2-27
HORizontal:PREViewstate?, 2-200	MEASUrement: CLEARSNapshot, 2-217
HORizontal:RECOrdlength, 2-200	MEASUrement:IMMed:DELay:DIRection, 2-218
HORizontal:SAMPLERate, 2-201	MEASUrement:IMMed:DELay:EDGE <x>, 2-219</x>
HORizontal?, 2-197	MEASUrement:IMMed:DELay?, 2-218
HORizontal:POSition, 2-200	MEASUrement:IMMed:SOUrce <x>, 2-219</x>
HORizontal:SCAle, 2-201	MEASUrement:IMMed:TYPe, 2-220
	MEASUrement:IMMed:UNIts?, 2-223
	MEASUrement:IMMed:VALue?, 2-225
ID?, 2-202	MEASUrement:INDICators:HORZ <x>?, 2-226</x>
*IDN?, 2-202	MEASUrement:INDICators:NUMHORZ?, 2-226
*	MEASUrement:INDICators:NUMVERT?, 2-227
L	MEASUrement:INDICators:VERT 2.227
	MEASUrement:INDICators:VERT <x>?, 2-228 MEASUrement:INDICators?, 2-226</x>
LANGuage, 2-202	MEASUrement:MEAS <x>:COUNt?, 2-228</x>
LOCk, 2-203	MEASUrement:MEAS <x>:COUNT?, 2-228 MEASUrement:MEAS<x>:DELay:DIRection, 2-229</x></x>
*LRN?, 2-203	MEASUICHICHUMEAS N. DELay DINCCHOII, 2-229

MEASUrement:MEAS <x>:DELay:EDGE<x>, 2-230</x></x>	P
MEASUrement:MEAS <x>:DELay?, 2-229</x>	PASSWord, 2-254
MEASUrement:MEAS <x>:MAXimum?, 2-230</x>	PICTBridge:DATEPrint, 2-254
MEASUrement:MEAS <x>:MEAN?, 2-231</x>	PICTBridge:IMAGESize, 2-256
MEASUrement:MEAS <x>:MINImum?, 2-231</x>	PICTBridge:PAPERSize, 2-257
MEASUrement:MEAS <x>:SOUrce<x>, 2-231</x></x>	PICTBridge:PAPERType, 2-258
MEASUrement:MEAS <x>:STATE, 2-232</x>	PICTBridge:PRINTQual, 2-259
MEASUrement:MEAS <x>:STDdev?, 2-233</x>	PICTBridge:DEFault, 2-255
MEASUrement:MEAS <x>:TYPe, 2-233</x>	PICTBridge:IDPrint, 2-255
MEASUrement:MEAS <x>:UNIts?, 2-236</x>	POWer:HARMonics:DISPlay:SELect, 2-261
MEASUrement:MEAS <x>:VALue?, 2-238</x>	POWer:HARMonics:DISPlay:TYPe, 2-262
MEASUrement:MEAS <x>?, 2-228</x>	POWer:HARMonics:FREQRef, 2-262
MEASUrement:REFLevel:ABSolute:HIGH, 2-240	POWer:HARMonics:FREQRef:
MEASUrement:REFLevel:ABSolute:LOW, 2-240	FIXEDFREQValue, 2-263
MEASUrement:REFLevel:ABSolute:MID, 2-241	POWer:HARMonics:IEC:CLAss, 2-264
MEASUrement:REFLevel:ABSolute:MID <x>, 2-242</x>	POWer:HARMonics:IEC:ELAss, 2-204
MEASUrement:REFLevel:ABSolute:MID2, 2-242	POWer:HARMonics:IEC:FUNDamental, 2-265
MEASUrement:REFLevel:METHod, 2-243	POWer:HARMonics:IEC:GROUPing, 2-265
MEASUrement:REFLevel:PERCent:HIGH, 2-243	POWer:HARMonics:IEC:INPUTPOWer, 2-266
MEASUrement:REFLevel:PERCent:LOW, 2-244	POWer:HARMonics:IEC:HNF 0 17 0 Wei, 2-200
MEASUrement:REFLevel:PERCent:MID, 2-245	POWer:HARMonics:IEC:OBSPERiod, 2-267
MEASUrement:REFLevel:PERCent:MID <x>, 2-246</x>	POWer:HARMonics:IEC:POWERFACtor, 2-267
MEASUrement:REFLevel:PERCent:MID2, 2-245	POWer:HARMonics:MIL:FUNDamental:
MEASUrement:REFLevel?, 2-239	CALCmethod, 2-268
MEASUrement:SNAPShot, 2-246	POWer:HARMonics:MIL:FUNDamental:USER:
MEASUrement: STATIstics, 2-247	
MEASUrement:STATIstics:MODE, 2-247	CURRent, 2-268
MEASUrement:STATIstics:WEIghting, 2-248	POWer:HARMonics:MIL:LINEFREQuency, 2-269 POWer:HARMonics:MIL:POWERLEVel, 2-269
MEASUrement?, 2-216	
MEASUrement:GATing, 2-217	POWer:HARMonics:NR_HARMonics, 2-270 POWer:HARMonics:RESults:HAR<1-400>:
MEASUrement:IMMed?, 2-217	
MEASUrement:METHod, 2-239	FREQuency?, 2-270
MESSage, 2-248	POWer:HARMonics:RESults:HAR<1-400>:
MESSage:BOX, 2-248	IECMAX?, 2-271
MESSage:CLEAR, 2-249	POWer:HARMonics:RESults:HAR<1-400>:
MESSage:SHOW, 2-250	LIMit?, 2-271
MESSage:STATE, 2-252	POWer:HARMonics:RESults:HAR<1-400>:
Miscellaneous Command Group, 2-30	PHASe?, 2-272
Wilsonanous Commana Group, 2 50	POWer:HARMonics:RESults:HAR<1-400>:RMS: ABSolute?, 2-272
N	POWer:HARMonics:RESults:HAR<1-400>:RMS:
	PERCent?, 2-273
NEWpass, 2-253	POWer:HARMonics:RESults:HAR<1-400>:TEST:
	IEC:CLASSALIMit?, 2-273
0	POWer:HARMonics:RESults:HAR<1-400>:TEST:
*OPC, 2-253	IEC:NORMAL?, 2-274
0. 0, <b>- 2</b> 00	POWer:HARMonics:RESults:HAR<1-400>:TEST:
	IFC·POHCI IMit? 2-274

POWer: HARMonics: RESults: HAR<1-400>: TEST: POWer:REFLevel:PERCent:HIGH. 2-295 MIL:NORMAL?. 2-274 POWer:REFLevel:PERCent:LOW, 2-295 POWer:REFLevel:PERCent:MID<1-3>, 2-296 POWer:HARMonics:RESults:IEC: FUNDamental?, 2-275 POWer:RIPPle:RESults:AMPLitude?, 2-297 POWer:HARMonics:RESults:IEC: POWer:RIPPle:RESults:MAX?, 2-297 HARM3ALTernate?, 2-275 POWer:RIPPle:RESults:MEAN?, 2-298 POWer:HARMonics:RESults:IEC: POWer:RIPPle:RESults:MIN?, 2-298 HARM5ALTernate?, 2-276 POWer:RIPPle:RESults:STDdev?, 2-298 POWer: HARMonics: RESults: IEC: POHC?, 2-276 POWer:SOA:LINear:XMAX, 2-299 POWer:HARMonics:RESults:IEC:POHL?, 2-277 POWer:SOA:LINear:XMIN, 2-300 POWer:HARMonics:RESults:IEC:POWer?. 2-277 POWer:SOA:LINear:YMAX. 2-300 POWer:HARMonics:RESults:IEC: POWer:SOA:LINear:YMIN, 2-301 POWERFactor?, 2-277 POWer:SOA:MASK:DEFine, 2-303 POWer: HARMonics: RESults: PASSFail?, 2-278 POWer:SOA:MASK:MAXAmps, 2-304 POWer:HARMonics:RESults:RMS?, 2-278 POWer:SOA:MASK:MAXVolts, 2-304 POWer:HARMonics:RESults:SAVe, 2-278 POWer:SOA:MASK:MAXWatts, 2-305 POWer: HARMonics: RESults: THDF?, 2-279 POWer:SOA:MASK:NR PT?, 2-305 POWer:HARMonics:RESults:THDR?, 2-279 POWer:SOA:MASK:STATe, 2-306 POWer: HARMonics: SOURce, 2-279 POWer:SOA:MASK:STOPOnviol, 2-306 POWer: HARMonics: STANDard, 2-280 POWer:SOA:RESult:FAILures:QTY?, 2-307 POWer: MODulation: SOUrce, 2-281 POWer:SOA:RESult:NUMACq?, 2-308 POWer: MODulation: TYPe, 2-282 POWer:SOA:RESult:STATe?, 2-308 POWer:QUALity:APPpwr?, 2-283 POWer:STATIstics:MODE, 2-309 POWer:QUALity:DISplay:APPpwr, 2-283 POWer: STATIstics: WEIghting, 2-309 POWer:QUALity:DISplay:FREQuency, 2-283 POWer:SWLoss:CONDCALCmethod, 2-310 POWer:QUALity:DISplay:ICRESTfactor, 2-284 POWer:SWLoss:CONDuction:ENERGY: POWer: OUALity: DISplay: IRMS, 2-284 MAX?, 2-310 POWer:QUALity:DISplay:PHASEangle, 2-285 POWer:SWLoss:CONDuction:ENERGY: POWer:QUALity:DISplay:POWERFACtor, 2-285 MEAN?, 2-311 POWer:QUALity:DISplay:REACTpwr, 2-286 POWer:SWLoss:CONDuction:ENERGY: POWer:QUALity:DISplay:TRUEpwr, 2-287 MIN?, 2-311 POWer:QUALity:DISplay:VCRESTfactor, 2-287 POWer:SWLoss:CONDuction:POWER:MAX?, 2-312 POWer:QUALity:DISplay:VRMS, 2-288 POWer:SWLoss:CONDuction:POWER: POWer:QUALity:FREQREFerence, 2-288 MEAN?, 2-312 POWer:QUALity:FREQuency?, 2-289 POWer:SWLoss:CONDuction:POWER:MIN?, 2-312 POWer: OUALity: ICREST factor?, 2-289 POWer:SWLoss:DISplay, 2-313 POWer:QUALity:PHASEangle?, 2-290 POWer:SWLoss:GATe:POLarity, 2-313 POWer:QUALity:POWERFACtor?, 2-290 POWer:SWLoss:GATe:TURNON, 2-314 POWer:QUALity:REACTpwr?, 2-291 POWer:SWLoss:NUMCYCles?, 2-314 POWer:QUALity:TRUEpwr?, 2-291 POWer:SWLoss:REFLevel:ABSolute: POWer:REFLevel:ABSolute, 2-292 GATEMid, 2-315 POWer:SWLoss:REFLevel:ABSolute: POWer:REFLevel:ABSolute:HIGH, 2-292 POWer:REFLevel:ABSolute:LOW, 2-292 LOWCurrent, 2-316 POWer:REFLevel:ABSolute:MID<1-3>, 2-293 POWer:SWLoss:REFLevel:ABSolute: POWer:REFLevel:HYSTeresis, 2-293 LOWVoltage, 2-316 POWer:SWLoss:REFLevel:PERCent: POWer:REFLevel:METHod, 2-294 POWer:REFLevel:PERCent, 2-295 GATEMid, 2-317

POWer:SWLoss:REFLevel:PERCent:	RECAll:WAVEform, 2-330
LOWCurrent, 2-317	REF <x>:HORizontal:DELay:TIMe, 2-331</x>
POWer:SWLoss:REFLevel:PERCent:	REF <x>:HORizontal:SCAle, 2-331</x>
LOWVoltage, 2-318	REF <x>:VERTical:POSition, 2-332</x>
POWer:SWLoss:TOFF:ENERGY:MAX?, 2-318	REF <x>:VERTical:SCAle, 2-333</x>
POWer:SWLoss:TOFF:ENERGY:MEAN?, 2-319	REF <x>?, 2-330</x>
POWer:SWLoss:TOFF:ENERGY:MIN?, 2-319	REF <x>:DATE?, 2-331</x>
POWer:SWLoss:TOFF:POWER:MAX?, 2-320	REF <x>:LABel, 2-332</x>
POWer:SWLoss:TOFF:POWER:MEAN?, 2-320	REF <x>:TIMe?, 2-332</x>
POWer:SWLoss:TOFF:POWER:MIN?, 2-320	REM, 2-334
POWer:SWLoss:TON:ENERGY:MAX?, 2-321	*RST, 2-334
POWer:SWLoss:TON:ENERGY:MEAN?, 2-321	,
POWer:SWLoss:TON:ENERGY:MIN?, 2-321	S
POWer:SWLoss:TON:POWER:MAX?, 2-322	_
POWer:SWLoss:TON:POWER:MEAN?, 2-322	*SAV, 2-335
POWer:SWLoss:TON:POWER:MIN?, 2-323	Save and Recall Command Group, 2-40
POWer:SWLoss:TOTal:ENERGY:MAX?, 2-323	SAVe:EVENTtable:BUS <x>, 2-336</x>
POWer:SWLoss:TOTal:ENERGY:MEAN?, 2-323	SAVe:IMAGe:FILEFormat, 2-337
POWer:SWLoss:TOTal:ENERGY:MIN?, 2-324	SAVe: WAVEform: FILEFormat, 2-340
POWer:SWLoss:TOTal:POWER:MAX?, 2-324	SAVe:WAVEform:GATIng, 2-340
POWer:SWLoss:TOTal:POWER:MEAN?, 2-324	SAVe:ASSIgn:TYPe, 2-335
POWer:SWLoss:TOTal:POWER:MIN?, 2-325	SAVe:IMAGe, 2-336
POWer:CURRENTSOurce, 2-259	SAVe:IMAGe:INKSaver, 2-337
POWer:DISplay, 2-260	SAVe:IMAGe:LAYout, 2-338
POWer:GATESOurce, 2-260	SAVe:SETUp, 2-338
POWer:GATing, 2-261	SAVe:WAVEform, 2-339
POWer:INDICators, 2-280	Search Commands Group, 2-41
POWer:QUALity:IRMS?, 2-289	SEARCH:SEARCH <x>:COPy, 2-342</x>
POWer:QUALity:VRMS?, 2-291	SEARCH:SEARCH <x>:STATE, 2-343</x>
POWer:RIPPle, 2-296	SEARCH:SEARCH <x>:TOTAL?, 2-343</x>
POWer:RIPPle:SOUrce, 2-299	SEARCH:SEARCH <x>:TRIGger:A:BUS:B<x>:</x></x>
POWer:SOA:LOG:XMAX, 2-301	AUDio:CONDition, 2-344
POWer:SOA:LOG:XMIN, 2-302	SEARCH:SEARCH <x>:TRIGger:A:BUS:B<x>:</x></x>
POWer:SOA:LOG:YMAX, 2-302	AUDio:DATa:HIVALue, 2-344
POWer:SOA:LOG:YMIN, 2-303	SEARCH:SEARCH <x>:TRIGger:A:BUS:B<x>:</x></x>
POWer:SOA:PLOTTYPe, 2-307	AUDio:DATa:OFFSet, 2-345
POWer:STATIstics, 2-308	SEARCH:SEARCH <x>:TRIGger:A:BUS:B<x>:</x></x>
POWer:SWLoss:RDSon, 2-315	AUDio:DATa:QUALifier, 2-345
POWer:SWLoss:VCEsat, 2-325	SEARCH:SEARCH <x>:TRIGger:A:BUS:B<x>:</x></x>
POWer:TYPe, 2-326	AUDio:DATa:VALue, 2-346
POWer:VOLTAGESOurce, 2-327	SEARCH:SEARCH <x>:TRIGger:A:BUS:B<x>:</x></x>
*PSC, 2-327	AUDio:DATa:WORD, 2-346
*PUD, 2-328	SEARCH:SEARCH <x>:TRIGger:A:BUS:B<x>:</x></x>
100,200	CAN:CONDition, 2-346
D	SEARCH:SEARCH <x>:TRIGger:A:BUS:B<x>:</x></x>
R	CAN:DATa:DIRection, 2-347
*RCL, 2-329	SEARCH:SEARCH <x>:TRIGger:A:BUS:B<x>:</x></x>
RECAll:SETUp, 2-329	CAN:DATa:QUALifier, 2-348

- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>: CAN:DATa:SIZe, 2-348
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>: CAN:DATa:VALue, 2-349
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>: CAN:FRAMEtype, 2-349
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>: CAN{:IDentifier|:ADDRess}:MODe, 2-350
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>: CAN{:IDentifier|:ADDRess}:VALue, 2-350
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>: FLEXray:CONDition, 2-351
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>: FLEXray:CYCLEcount:HIVALue, 2-351
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>: FLEXray:CYCLEcount:QUALifier, 2-352
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>: FLEXray:CYCLEcount:VALue, 2-353
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>: FLEXray:DATa:HIVALue, 2-353
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>: FLEXray:DATa:OFFSet, 2-354
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>: FLEXray:DATa:QUALifier, 2-354
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>: FLEXray:DATa:SIZe, 2-355
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>: FLEXray:DATa:VALue, 2-355
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>: FLEXray:EOFTYPE, 2-356
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>: FLEXray:ERRTYPE, 2-356
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>: FLEXray:FRAMEID:HIVALue, 2-357
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>: FLEXray:FRAMEID:QUALifier, 2-357
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>: FLEXray:FRAMEID:VALue, 2-358
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>: FLEXray:FRAMEType, 2-359
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>: FLEXray:HEADER:CRC, 2-359
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>: FLEXray:HEADER:CYCLEcount, 2-360
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>: FLEXray:HEADER:FRAMEID, 2-360

- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>: FLEXray:HEADER:INDBits, 2-361
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>: FLEXray:HEADER:PAYLength, 2-361
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:I2C: ADDRess:MODe, 2-362
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:I2C: ADDRess:TYPe, 2-362
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:I2C: ADDRess:VALue, 2-363
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:I2C: CONDition, 2-363
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:I2C: DATa:DIRection, 2-364
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:I2C: DATa:SIZe, 2-364
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:I2C: DATa:VALue, 2-365
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:LIN: CONDition, 2-365
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:LIN: DATa:HIVALue, 2-366
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:LIN: DATa:QUALifier, 2-366
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:LIN: DATa:SIZe, 2-367
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:LIN: DATa:VALue, 2-367
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:LIN: ERRTYPE, 2-368
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:LIN: IDentifier:VALue, 2-368
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>: PARallel:VALue, 2-369
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>: RS232C:CONDition, 2-369
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>: RS232C:RX:DATa:SIZe, 2-370
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>: RS232C:RX:DATa:VALue, 2-370
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>: RS232C:TX:DATa:SIZe, 2-371
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>: RS232C:TX:DATa:VALue, 2-371
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:SPI: CONDition, 2-371

- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:SPI: DATa:SIZe, 2-373
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:SPI: DATa{:MISO|:IN}:VALue, 2-372
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>:SPI: DATa{:MOSI|:OUT}:VALue, 2-372
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>: USB:ADDRess:HIVALue, 2-373
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>: USB:ADDRess:VALue, 2-374
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>: USB:CONDition, 2-375
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>: USB:DATa:HIVALue, 2-375
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>: USB:DATa:OFFSet, 2-376
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>: USB:DATa:SIZe, 2-377
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>: USB:DATa:TYPe, 2-377
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>: USB:DATa:VALue, 2-378
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>: USB:ENDPoint:VALue, 2-378
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>: USB:ERRORTYPe, 2-379
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>: USB:HANDSHAKEType, 2-380
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>: USB:QUALifier, 2-380
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>: USB:SOFFRAMENUMber, 2-381
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>: USB:SPECIALType, 2-382
- SEARCH:SEARCH<x>:TRIGger:A:BUS:B<x>: USB:TOKENType, 2-382
- SEARCH:SEARCH<x>:TRIGger:A:BUS: SOUrce, 2-383
- SEARCH:SEARCH<x>:TRIGger:A:BUS?, 2-343
- SEARCH:SEARCH<x>:TRIGger:A:EDGE: SLOpe, 2-384
- SEARCH:SEARCH<x>:TRIGger:A:EDGE: SOUrce, 2-384
- SEARCH:SEARCH<x>:TRIGger:A:LEVel, 2-384
- SEARCH:SEARCH<x>:TRIGger:A:LEVel: CH<x>, 2-385

- SEARCH:SEARCH<x>:TRIGger:A:LEVel: MATH, 2-385
- SEARCH:SEARCH<x>:TRIGger:A:LEVel: REF<x>, 2-385
- SEARCH:SEARCH<x>:TRIGger:A:LOGIc: FUNCtion, 2-386
- SEARCH:SEARCH<x>:TRIGger:A:LOGIc:INPut: CH<x>, 2-386
- SEARCH:SEARCH<x>:TRIGger:A:LOGIc:INPut: CLOCk:EDGE, 2-387
- SEARCH:SEARCH<x>:TRIGger:A:LOGIc:INPut: CLOCk:SOUrce, 2-387
- SEARCH:SEARCH<x>:TRIGger:A:LOGIc:INPut: D<x>, 2-387
- SEARCH:SEARCH<x>:TRIGger:A:LOGIc:INPut: MATH, 2-388
- SEARCH:SEARCH<x>:TRIGger:A:LOGIc:INPut: REF<x>, 2-388
- SEARCH:SEARCH<x>:TRIGger:A:LOGIc:PATtern: INPut:CH<x>, 2-389
- SEARCH:SEARCH<x>:TRIGger:A:LOGIc:PATtern: INPut:D<x>, 2-389
- SEARCH:SEARCH<x>:TRIGger:A:LOGIc:PATtern: INPut:MATH, 2-389
- SEARCH:SEARCH<x>:TRIGger:A:LOGIc:PATtern: INPut:REF<x>, 2-390
- SEARCH:SEARCH<x>:TRIGger:A:LOGIc:PATtern: WHEn, 2-390
- SEARCH:SEARCH<x>:TRIGger:A:LOGIc:PATtern: WHEn:LESSLimit, 2-391
- SEARCH:SEARCH<x>:TRIGger:A:LOGIc:PATtern: WHEn:MORELimit, 2-391
- SEARCH:SEARCH<x>:TRIGger:A:LOGIc: THReshold:CH<x>, 2-392
- SEARCH:SEARCH<x>:TRIGger:A:LOGIc: THReshold:MATH, 2-392
- SEARCH:SEARCH<x>:TRIGger:A:LOGIc: THReshold:REF<x>, 2-392
- SEARCH:SEARCH<x>:TRIGger:A: LOWerthreshold:CH<x>, 2-393
- SEARCH:SEARCH<x>:TRIGger:A: LOWerthreshold:MATH, 2-393
- SEARCH:SEARCH<x>:TRIGger:A: LOWerthreshold:REF<x>, 2-393
- SEARCH:SEARCH<x>:TRIGger:A:PULSEWidth: POLarity, 2-394

SEARCH:SEARCH <x>:TRIGger:A:PULSEWidth:</x>	SEARCH:SEARCH <x>:TRIGger:A{:TRANsition :</x>
SOUrce, 2-394	RISEFall}:WHEn, 2-403
SEARCH:SEARCH <x>:TRIGger:A:PULSEWidth:</x>	SEARCH?, 2-341
WHEn, 2-394	SELect, 2-405
SEARCH:SEARCH <x>:TRIGger:A:PULSEWidth:</x>	SELect:BUS $<$ x $>$ , 2-405
WIDth, 2-395	SELect:CH $<$ x $>$ , 2-406
SEARCH:SEARCH <x>:TRIGger:A:RUNT:</x>	SELect:CONTROl, 2-406
POLarity, 2-395	SELect:D <x>, 2-407</x>
SEARCH:SEARCH <x>:TRIGger:A:RUNT:</x>	SELect:MATH[1], 2-407
SOUrce, 2-396	SELect:REF <x>, 2-408</x>
SEARCH:SEARCH <x>:TRIGger:A:RUNT:</x>	SET?, 2-409
WHEn, 2-396	SETUP <x>:DATE?, 2-410</x>
SEARCH:SEARCH <x>:TRIGger:A:RUNT:</x>	SETUP <x>:LABEL, 2-410</x>
WIDth, 2-397	SETUP <x>:TIME?, 2-410</x>
SEARCH:SEARCH <x>:TRIGger:A:SETHold:</x>	*SRE, 2-411
CLOCk:EDGE, 2-397	Status and Error Command Group, 2-48
SEARCH:SEARCH <x>:TRIGger:A:SETHold:</x>	*STB?, 2-411
CLOCk:SOUrce, 2-398	,
SEARCH:SEARCH <x>:TRIGger:A:SETHold:</x>	T
CLOCk:THReshold, 2-398	•
SEARCH:SEARCH <x>:TRIGger:A:SETHold:DATa:</x>	TEKSecure, 2-412
SOUrce, 2-398	TIME, 2-413
SEARCH:SEARCH <x>:TRIGger:A:SETHold:DATa:</x>	TOTaluptime?, 2-413
THReshold, 2-399	*TRG, 2-414
SEARCH:SEARCH <x>:TRIGger:A:SETHold:</x>	Trigger Command Group, 2-49
HOLDTime, 2-400	TRIGger, 2-414
SEARCH:SEARCH <x>:TRIGger:A:SETHold:</x>	TRIGger: A:BUS:B <x>:AUDio:CONDition, 2-416</x>
SETTime, 2-400	TRIGger:A:BUS:B <x>:AUDio:DATa:</x>
SEARCH:SEARCH <x>:TRIGger:A:SETHold:</x>	HIVALue, 2-417
THReshold:CH <x>, 2-400</x>	TRIGger:A:BUS:B <x>:AUDio:DATa:OFFSet, 2-417</x>
SEARCH:SEARCH <x>:TRIGger:A:SETHold:</x>	TRIGger:A:BUS:B <x>:AUDio:DATa:</x>
THReshold:REF <x>, 2-401</x>	QUALifier, 2-417
SEARCH:SEARCH <x>:TRIGger:A:SETHold:</x>	TRIGger: A:BUS:B <x>:AUDio:DATa:VALue, 2-418</x>
THReshold{:MATH :MATH1}, 2-401	TRIGger: A:BUS:B <x>:AUDio:DATa:WORD, 2-418</x>
SEARCH:SEARCH <x>:TRIGger:A:TYPe, 2-403</x>	TRIGger: A:BUS:B <x>:CAN:CONDition, 2-419</x>
SEARCH:SEARCH <x>:TRIGger:A:UPPerthreshold:</x>	TRIGger:A:BUS:B <x>:CAN:DATa:DIRection, 2-419</x>
CH < x > , 2-404	TRIGger: A:BUS:B <x>:CAN:DATa:QUALifier, 2-420</x>
SEARCH:SEARCH <x>:TRIGger:A:UPPerthreshold:</x>	TRIGger: A:BUS:B <x>:CAN:DATa:SIZe, 2-421</x>
MATH, 2-404	TRIGger: A:BUS:B <x>:CAN:DATa:VALue, 2-421</x>
SEARCH:SEARCH <x>:TRIGger:A:UPPerthreshold:</x>	TRIGger: A:BUS:B <x>:CAN:FRAMEtype, 2-422</x>
REF < x > , 2-404	TRIGger:A:BUS:B <x>:CAN{:IDentifier :ADDRess}:</x>
SEARCH:SEARCH <x>:TRIGger:A{:TRANsition :</x>	MODe, 2-422 TRIC gorr A. PUS. P. S. C. A.N. (.IDontiford): A.D.D.R. ogg).
RISEFall}:DELTatime, 2-401	TRIGger:A:BUS:B <x>:CAN{:IDentifier :ADDRess}: VALue, 2-423</x>
SEARCH:SEARCH <x>:TRIGger:A{:TRANsition :</x>	TRIGger:A:BUS:B <x>:FLEXray:CONDition, 2-423</x>
RISEFall}:POLarity, 2-402	TRIGger:A:BUS:B <x>:FLEXIay:CONDition, 2-423 TRIGger:A:BUS:B<x>:FLEXIay:CYCLEcount:</x></x>
SEARCH:SEARCH <x>:TRIGger:A{:TRANsition :</x>	HIVALue, 2-424
RISEFall\:SOUrce, 2-402	111 VALUE, 2-424

```
TRIGger: A:BUS:B<x>:FLEXray:CYCLEcount:
                                                  TRIGger: A:BUS:B<x>:PARallel:VALue, 2-442
   QUALifier, 2-424
                                                  TRIGger: A:BUS:B<x>:RS232C:CONDition, 2-442
TRIGger: A:BUS:B<x>:FLEXray:CYCLEcount:
                                                  TRIGger: A:BUS:B<x>:RS232C:RX:DATa:
   VALue, 2-425
                                                     SIZe, 2-442
TRIGger:A:BUS:B<x>:FLEXray:DATa:
                                                  TRIGger: A:BUS:B<x>:RS232C:RX:DATa:
   HIVALue, 2-426
                                                     VALue, 2-443
TRIGger: A:BUS:B<x>:FLEXray:DATa:
                                                  TRIGger: A:BUS:B<x>:RS232C:TX:DATa:
   OFFSet, 2-426
                                                     SIZe, 2-443
TRIGger: A:BUS:B<x>:FLEXray:DATa:
                                                  TRIGger: A:BUS:B<x>:RS232C:TX:DATa:
                                                     VALue, 2-444
   QUALifier, 2-427
TRIGger: A:BUS:B<x>:FLEXray:DATa:SIZe, 2-427
                                                  TRIGger: A:BUS:B<x>:SPI:CONDition, 2-444
TRIGger:A:BUS:B<x>:FLEXray:DATa:
                                                  TRIGger: A:BUS:B<x>:SPI:DATa:SIZe, 2-445
   VALue, 2-428
                                                  TRIGger:A:BUS:B<x>:SPI:DATa{:IN|:MISO}:
TRIGger: A:BUS:B<x>:FLEXray:EOFTYPE, 2-428
                                                     VALue, 2-445
TRIGger: A:BUS:B<x>:FLEXray:ERRTYPE, 2-429
                                                  TRIGger:A:BUS:B<x>:SPI:DATa{:OUT|:MOSI}:
TRIGger:A:BUS:B<x>:FLEXray:FRAMEID:
                                                     VALue, 2-445
   HIVALue, 2-430
                                                  TRIGger: A:BUS:B<x>:USB:ADDRess:
TRIGger: A:BUS:B<x>:FLEXray:FRAMEID:
                                                     HIVALue, 2-446
   QUALifier, 2-430
                                                  TRIGger:A:BUS:B<x>:USB:ADDRess:
TRIGger: A:BUS:B<x>:FLEXray:FRAMEID:
                                                     VALue, 2-446
   VALue, 2-431
                                                  TRIGger: A:BUS:B<x>:USB:CONDition, 2-447
TRIGger: A:BUS:B<x>:FLEXray:
                                                  TRIGger: A:BUS:B<x>:USB:DATa:HIVALue, 2-448
   FRAMEType, 2-431
                                                  TRIGger:A:BUS:B<x>:USB:DATa:OFFSet, 2-448
TRIGger: A:BUS:B<x>:FLEXray:HEADER:
                                                  TRIGger: A:BUS:B<x>:USB:DATa:SIZe, 2-449
   CRC, 2-432
                                                  TRIGger: A:BUS:B<x>:USB:DATa:TYPe, 2-450
TRIGger: A:BUS:B<x>:FLEXray:HEADER:
                                                  TRIGger: A:BUS:B<x>:USB:DATa:VALue, 2-450
   CYCLEcount, 2-432
                                                  TRIGger:A:BUS:B<x>:USB:ENDPoint:
                                                     VALue, 2-451
TRIGger: A:BUS:B<x>:FLEXray:HEADER:
   FRAMEID, 2-433
                                                  TRIGger: A:BUS:B<x>:USB:ERRORTYPe, 2-451
TRIGger:A:BUS:B<x>:FLEXray:HEADER:
                                                  TRIGger:A:BUS:B<x>:USB:
   INDBits, 2-433
                                                     HANDSHAKEType, 2-452
TRIGger: A:BUS:B<x>:FLEXray:HEADER:
                                                  TRIGger: A:BUS:B<x>:USB:QUALifier, 2-453
   PAYLength, 2-434
                                                  TRIGger: A:BUS:B<x>:USB:
TRIGger: A:BUS:B<x>:I2C:ADDRess:MODe, 2-434
                                                     SOFFRAMENUMber, 2-454
TRIGger:A:BUS:B<x>:I2C:ADDRess:TYPe, 2-435
                                                  TRIGger: A:BUS:B<x>:USB:SPECIALType, 2-454
TRIGger: A:BUS:B<x>:I2C:ADDRess: VALue, 2-435
                                                  TRIGger: A:BUS:B<x>:USB:TOKENType, 2-455
TRIGger: A:BUS:B<x>:I2C:CONDition, 2-436
                                                  TRIGger: A:BUS: SOUrce, 2-456
TRIGger:A:BUS:B<x>:I2C:DATa:DIRection, 2-436
                                                  TRIGger: A:EDGE: COUPling, 2-456
TRIGger:A:BUS:B<x>:I2C:DATa:SIZe, 2-437
                                                  TRIGger: A:EDGE: SLOpe, 2-457
TRIGger: A:BUS:B<x>:I2C:DATa:VALue, 2-437
                                                  TRIGger: A:EDGE:SOUrce, 2-458
TRIGger: A:BUS:B<x>:LIN:CONDition, 2-438
                                                  TRIGger: A:HOLDoff: TIMe, 2-459
TRIGger:A:BUS:B<x>:LIN:DATa:HIVALue, 2-438
                                                  TRIGger: A:LEVel: AUXin, 2-460
TRIGger: A:BUS:B<x>:LIN:DATa:QUALifier, 2-439
                                                  TRIGger: A:LEVel: CH<x>, 2-460
TRIGger: A:BUS:B<x>:LIN:DATa:SIZe, 2-440
                                                  TRIGger: A:LEVel: D<x>, 2-461
TRIGger: A:BUS:B<x>:LIN:DATa:VALue, 2-440
                                                  TRIGger: A:LOGIc:CLAss, 2-461
TRIGger: A:BUS:B<x>:LIN:ERRTYPE, 2-440
                                                  TRIGger: A:LOGIc: FUNCtion, 2-462
TRIGger: A:BUS:B<x>:LIN:IDentifier:VALue, 2-441
                                                  TRIGger: A:LOGIc:INPut:CH<x>, 2-463
```

TRIGger: A:LOGIc: INPut: CLOCk: EDGE, 2-464 TRIGger: A: VIDeo: POLarity, 2-492 TRIGger: A: VIDeo: SOUrce, 2-492 TRIGger: A:LOGIc: INPut: CLOCk: SOUrce, 2-464 TRIGger: A:LOGIc:INPut:D<x>, 2-465 TRIGger: A: VIDeo: STANdard, 2-493 TRIGger: A:LOGIc: INPut?, 2-463 TRIGger: A: VIDeo {: SYNC|: FIELD}, 2-493 TRIGger: A:LOGIc: PATtern: DELTatime, 2-465 TRIGger:A{:TRANsition|:RISEFall}: TRIGger: A:LOGIc:PATtern:INPut:D<x>, 2-466 DELTatime, 2-483 TRIGger: A:LOGIc:PATtern: WHEn, 2-466 TRIGger: A {: TRANsition |: RISEFall }: POLarity, 2-484 TRIGger: A:LOGIc:PATtern: WHEn: TRIGger: A {:TRANsition|:RISEFall}:SOUrce, 2-484 LESSLimit, 2-467 TRIGger: A {:TRANsition|:RISEFall}:WHEn, 2-485 TRIGger: A:LOGIc: PATtern: WHEn: TRIGger: A {: TRANsition |: RISEFall }?, 2-483 MORELimit, 2-467 TRIGger:B:EDGE:COUPling, 2-495 TRIGger: A:LOGIc: PATtern?, 2-465 TRIGger:B:EDGE:SLOpe, 2-496 TRIGger: A:LOGIc:THReshold:CH<x>, 2-468 TRIGger:B:EDGE:SOUrce, 2-496 TRIGger: A:LOGIc: THReshold: D<x>, 2-469 TRIGger:B:EVENTS:COUNt, 2-497 TRIGger: A:LOWerthreshold: CH<x>, 2-469 TRIGger:B:LEVel:CH<x>, 2-498 TRIGger: A:LOWerthreshold: D<x>, 2-470 TRIGger:B:LEVel:D<x>, 2-499 TRIGger: A:LOWerthreshold {: EXT|: AUX}, 2-470 TRIGger:B:LOWerthreshold:CH<x>, 2-499 TRIGger: A: PULse: CLAss, 2-471 TRIGger:B:LOWerthreshold:D<x>, 2-500 TRIGger: A:PULSEWidth: POLarity, 2-472 TRIGger:B:UPPerthreshold:CH<x>, 2-502 TRIGger: A:PULSEWidth: SOUrce, 2-473 TRIGger: EXTernal: PRObe, 2-502 TRIGger: A:PULSEWidth: WHEn, 2-473 TRIGger: EXTernal: YUNIts?, 2-503 TRIGger: A: PULSEWidth: WIDth, 2-474 TRIGger: A, 2-414 TRIGger: A: PULSEWIDth?, 2-472 TRIGger: A:BUS, 2-416 TRIGger: A:RUNT: POLarity, 2-475 TRIGger: A:EDGE?, 2-456 TRIGger: A:RUNT: SOUrce, 2-475 TRIGger: A:HOLDoff?, 2-458 TRIGger: A:RUNT: WIDth, 2-477 TRIGger: A:LEVel, 2-459 TRIGger: A:SETHold: CLOCk: EDGE, 2-478 TRIGger: A:LOGIc?, 2-461 TRIGger: A:SETHold: CLOCk: SOUrce, 2-478 TRIGger: A:MODe, 2-471 TRIGger: A:SETHold: CLOCk: THReshold, 2-479 TRIGger: A: PULse?, 2-471 TRIGger: A: SETHold: CLOCk?, 2-477 TRIGger: A:RUNT?, 2-474 TRIGger: A:SETHold: DATa: SOUrce, 2-480 TRIGger: A:RUNT: WHEn, 2-476 TRIGger: A:SETHold: DATa: THReshold, 2-481 TRIGger: A:SETHold?, 2-477 TRIGger: A:SETHold: DATa?, 2-479 TRIGger: A:TYPe, 2-486 TRIGger: A: SETHold: HOLDTime, 2-481 TRIGger: A: VIDeo?, 2-487 TRIGger: A:SETHold: SETTime, 2-482 TRIGger:B, 2-494 TRIGger: A:SETHold: THReshold: CH<x>, 2-482 TRIGger:B:BY, 2-494 TRIGger: A:SETHold: THReshold: D<x>, 2-483 TRIGger:B:EDGE?, 2-495 TRIGger: A: UPPerthreshold: CH<x>, 2-486 TRIGger:B:EVENTS?, 2-497 TRIGger: A: VIDeo: CUSTom: LINEPeriod, 2-488 TRIGger:B:LEVel, 2-498 TRIGger: A: VIDeo: CUSTom: SCAN, 2-488 TRIGger:B:STATE, 2-500 TRIGger: A: VIDeo: CUSTom: SYNCInterval, 2-489 TRIGger:B:TIMe, 2-501 TRIGger:A:VIDeo:CUSTom{:FORMat|: TRIGger:B:TYPe, 2-501 TYPE}, 2-487 TRIGger: EXTernal?, 2-502 TRIGger: A: VIDeo: HDtv: FORMat, 2-490 TRIGger:FREQuency?, 2-503 TRIGger: A: VIDeo: HOLDoff: FIELD, 2-490 TRIGger:STATE?, 2-503 TRIGger: A: VIDeo: LINE, 2-491 \*TST?, 2-504

#### U

UNLock, 2-504 USBDevice:CONFigure, 2-505 USBTMC:PRODUCTID:DECimal?, 2-505 USBTMC:PRODUCTID:HEXadecimal?, 2-506 USBTMC:SERIALnumber?, 2-506 USBTMC:VENDORID:DECimal?, 2-507 USBTMC:VENDORID:HEXadecimal?, 2-507 USBTMC?, 2-505

#### ٧

VERBose, 2-507 Vertical Command Group, 2-60

#### W

\*WAI, 2-508 Waveform Transfer Command Group, 2-63 WAVFrm?, 2-509 WFMInpre?, 2-509 WFMInpre:BIT Nr, 2-510 WFMInpre:BN Fmt, 2-510 WFMInpre:BYT Nr, 2-511 WFMInpre:BYT Or, 2-511 WFMInpre:ENCdg, 2-512 WFMInpre:NR Pt, 2-512 WFMInpre:PT Fmt, 2-513 WFMInpre:PT Off, 2-514 WFMInpre:XINcr, 2-514 WFMInpre:XUNit, 2-515 WFMInpre:XZEro, 2-515 WFMInpre: YMUlt, 2-516 WFMInpre:YOFf, 2-517

WFMInpre: YUNit, 2-517 WFMInpre: YZEro, 2-518 WFMOutpre:FRACTional?, 2-522 WFMOutpre?, 2-519 WFMOutpre:BIT Nr, 2-519 WFMOutpre:BN Fmt, 2-520 WFMOutpre:BYT Nr, 2-520 WFMOutpre:BYT Or, 2-521 WFMOutpre:ENCdg, 2-521 WFMOutpre:NR Pt?, 2-522 WFMOutpre:PT Fmt?, 2-523 WFMOutpre:PT Off?, 2-523 WFMOutpre:PT ORder?, 2-524 WFMOutpre:WFId?, 2-524 WFMOutpre:XINcr?, 2-525 WFMOutpre:XUNit?, 2-526 WFMOutpre: XZEro?, 2-526 WFMOutpre: YMUlt?, 2-527 WFMOutpre: YOFf?, 2-527 WFMOutpre: YUNit?, 2-528 WFMOutpre: YZEro?, 2-528

### Z

Zoom Command Group, 2-68 ZOOm:ZOOM<x>:FACtor?, 2-530 ZOOm:ZOOM<x>:POSition, 2-530 ZOOm:ZOOM<x>:SCAle, 2-530 ZOOm:ZOOM<x>:STATE, 2-531 ZOOm?, 2-528 ZOOm:MODe, 2-529 ZOOm:ZOOM<x>?, 2-529