

1. Consider the following elliptic PDE

$$-\nabla \cdot (p(\vec{x}) \nabla u) = q(\vec{x}) \quad \text{for } \vec{x} \in \Omega \subset \mathbb{R}^2,$$

$$u(\vec{x}) = 0 \quad \text{when } \vec{x} \in \partial\Omega,$$

with $p(\vec{x}) \geq m > 0$.

(a) Write the weak formulation of this problem in the form,

Find $u \in V$, such that

$$a(u, v) = G(v), \text{ for all } v \in V.$$

What is $a(\cdot, \cdot)$? What is $G(\cdot)$? What is V ? Why are u and v in the same space? Is $a(\cdot, \cdot)$ symmetric?

(b) Define the energy functional,

$$J(u) = \frac{1}{2} a(u, u) - G(u),$$

and show that the weak formulation above is equivalent to finding the “critical” or “stationary” point of J , by computing

$$\left. \frac{d}{d\tau} J(u + \tau v) \right|_{\tau=0} = 0.$$

What is the second directional-derivative of J ?

$$\left. \frac{d^2}{d\tau^2} J(u + \tau v) \right|_{\tau=0}$$

What can we conclude about the stationary point and what should we assume about $a(\cdot, \cdot)$?

(c) Suppose the domain is a disjoint union of M triangles, E_1, E_2, \dots, E_M , with shared vertices. Further suppose that there are a total of N vertices with $\vec{x} = (x, y)$ coordinates given by $\vec{x}_1, \vec{x}_2, \dots, \vec{x}_N$.

Show that the bilinear form, $a(\cdot, \cdot)$, and linear functional, $G(v)$, derived in the previous part can be written as a sum of integrals over each triangle (element).

- (d) Consider approximating the solution to the weak formulation by restricting the solution space to a subspace spanned by N basis functions, $\{\phi_1, \dots, \phi_N\}$. Write the (approximate) solution as a linear combination of these basis functions,

$$u(\vec{x}) = \sum_{i=1}^N u_i \phi_i,$$

where $\phi_i \in V$ and $\text{span}(\phi_1, \dots, \phi_N) \subset V$.

Show that the minimizer of the energy, $J(u)$, over the subspace $\text{span}(\phi_1, \dots, \phi_N)$, solves

$$\sum_{j=1}^N u_j a(\phi_j, \phi_i) = G(\phi_i), \quad \forall i = 1 \dots N.$$

- (e) Suppose we modified the PDE to include nonhomogeneous Dirichlet boundary conditions,

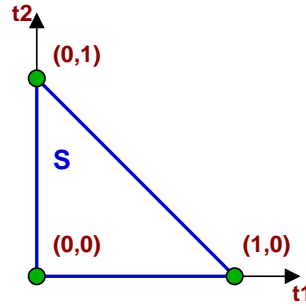
$$-\nabla \cdot (p(\vec{x}) \nabla u) = q(\vec{x}) \quad \text{for } \vec{x} \in \Omega \subset \mathbb{R}^2,$$

$$u(\vec{x}) = g(\vec{x}) \quad \text{when } \vec{x} \in \partial\Omega,$$

with $p(\vec{x}) \geq m > 0$. Let $\hat{u} \in V$ and $u := u^0 + \hat{u}$ with u^0 satisfying the boundary conditions.

What problem does \hat{u} solve?

2. Here we derive the analytical formulae necessary for implementation of the finite element method using piecewise linear finite elements on a triangulated domain.



- (a) Suppose $\lambda_1(\alpha, \beta)$ is the piecewise linear nodal basis function on the standard element (triangle), with $\lambda_1(0, 0) = 1$ and $\lambda_1(1, 0) = \lambda_1(0, 1) = 0$. Show that when restricted to the standard triangle with vertices $(0, 0), (1, 0), (0, 1) \in \mathbb{R}^2$, this basis function can be written as

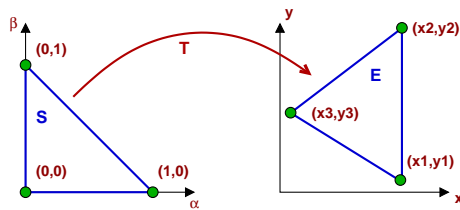
$$\lambda_1(\alpha, \beta) = 1 - \alpha - \beta$$

and conclude that the gradient of λ_1 is

$$\nabla \lambda_1 = \begin{bmatrix} -1 \\ -1 \end{bmatrix}.$$

Derive a similar result for λ_2 which satisfies $\lambda_2(1, 0) = 1$ and $\lambda_2(0, 0) = \lambda_2(0, 1) = 0$.

Derive a similar result for λ_3 which satisfies $\lambda_3(0, 1) = 1$ and $\lambda_3(0, 0) = \lambda_3(1, 0) = 0$.



- (b) Given three vertices of a general triangle, $\vec{x}_1, \vec{x}_2, \vec{x}_3 \in \mathbb{R}^2$,

write down an affine transformation, T , that maps the vertices of the “standard triangle” $(0, 0), (1, 0), (0, 1) \in \mathbb{R}^2$ to the “general triangle”.

Show that the Jacobian (derivative) of this transformation is

$$J_T = \begin{bmatrix} (\vec{x}_2 - \vec{x}_1) & (\vec{x}_3 - \vec{x}_1) \end{bmatrix} \in \mathbb{R}^{2 \times 2},$$

where $\vec{x} = (x, y)$.

- (c) Suppose ϕ_r is the piecewise linear nodal basis function for a general triangulation with $\phi_r(\vec{x}_r) = 1$ and $\phi_r(\vec{x}_s) = 0$ if $r \neq s$.

Using the results of the prior two parts show that when restricted to the “general triangle” that ϕ_r can be written as a composition of λ_r and T^{-1} ,

$$\phi_r(\vec{x}) = \lambda_r(T^{-1}(\vec{x}))$$

and the gradient of ϕ_r is

$$\nabla \phi_r|_{\vec{x}} = J_T^{-T} \nabla \lambda_r$$

where $\nabla \lambda_r$ is constant.

- (d) Let $\vec{x} = (x, y) \in \mathbb{R}^2$, $\vec{\alpha} = (\alpha, \beta) \in \mathbb{R}^2$, E the region defined by the general triangle, S the region defined by the standard triangle, T the affine transformation defined above, and $|J_T|$ the determinant of the Jacobian of the transformation. Using the change of variables formula

$$\iint_E h(\vec{x}) \, d\vec{x} = \iint_S h(T(\vec{\alpha})) \, |J_T| \, d\vec{\alpha}$$

,

show that

$$\langle p(\vec{x}) \nabla \phi_s, \nabla \phi_r \rangle_E = (J_T^{-T} \nabla \lambda_r)^T (J_T^{-T} \nabla \lambda_s) |J_T| \iint_S p(T(\vec{\alpha})) \, d\vec{\alpha}$$

and

$$\langle q(\vec{x}), \phi_r \rangle_E = |J_T| \iint_S q(T(\vec{\alpha})) \lambda_r(\vec{\alpha}) \, d\vec{\alpha}$$