

Half-Duplex, iCoupler Isolated RS-485 Transceiver

FEATURES

- ▶ RS-485 transceiver with electrical data isolation
- ▶ Complies with ANSI TIA/EIA RS-485-A and ISO 8482: 1987(E)
- ▶ 500 kbps data rate
- ▶ Slew rate-limited driver outputs
- ▶ Low power operation: 2.5 mA max
- ▶ Suitable for 5 V or 3 V operations (V_{DD1})
- ▶ High common-mode transient immunity: $>25\text{ kV}/\mu\text{s}$
- ▶ True fail-safe receiver inputs
- ▶ Chatter-free power-up/power-down protection
- ▶ 256 nodes on bus
- ▶ Thermal shutdown protection
- ▶ Safety and regulatory approvals
 - ▶ UL 1577
 - ▶ $V_{ISO} = 2500\text{ V}_{RMS}$ for 1 minute
 - ▶ IEC/CSA 62368-1
 - ▶ IEC/CSA 60601-1
 - ▶ IEC/CSA 61010-1
 - ▶ CQC GB4943.1
 - ▶ DIN EN IEC 60747-17 (VDE 0884-17)
 - ▶ $V_{IORM} = 565\text{ V}$ peak
- ▶ Operating temperature range: -40°C to $+85^\circ\text{C}$

APPLICATIONS

- ▶ Low power RS-485/RS-422 networks
- ▶ Isolated interfaces
- ▶ Building control networks
- ▶ Multipoint data transmission systems

FUNCTIONAL BLOCK DIAGRAM

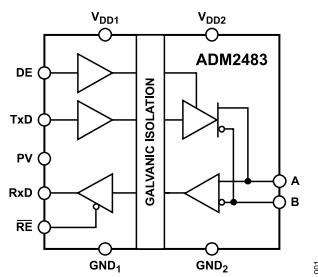


Figure 1.

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REVISION HISTORY**11/2024—Rev. F to Rev. G**

Changes to Features Section.....	1
Deleted Table 4; Renumbered Sequentially.....	5
Changes to Regulatory Information Section and Table 5.....	6
Changes to Table 6.....	6
Changed DIN V VDE V 0884-10 Insulation Characteristics Section to DIN EN IEC 60747-17 (VDE 0884-17) Insulation Characteristics Section.....	7
Changes to DIN EN IEC 60747-17 (VDE 0884-17) Insulation Characteristics Section and Table 7.....	7

SPECIFICATIONS

$2.7 \text{ V} \leq V_{DD1} \leq 5.5 \text{ V}$, $4.75 \text{ V} \leq V_{DD2} \leq 5.25 \text{ V}$, $T_A = T_{MIN}$ to T_{MAX} , unless otherwise noted.

Table 1.

Parameter	Min	Typ	Max	Unit	Test Conditions/Comments
DRIVER					
Differential Outputs					
Differential Output Voltage, V_{OD}			5	V	$R = \infty$, see Figure 3
	2.0	5	V		$R = 50 \Omega$ (RS-422), see Figure 3
	1.5	5	V		$R = 27 \Omega$ (RS-485), see Figure 3
	1.5	5	V		$V_{TST} = -7 \text{ V}$ to $+12 \text{ V}$, $V_{DD1} \geq 4.75$, see Figure 4
$\Delta V_{OD} $ for Complementary Output States			0.2	V	$R = 27 \Omega$ or 50Ω , see Figure 3
Common-Mode Output Voltage, V_{OC}			3	V	$R = 27 \Omega$ or 50Ω , see Figure 3
$\Delta V_{OC} $ for Complementary Output States			0.2	V	$R = 27 \Omega$ or 50Ω , see Figure 3
Output Short-Circuit Current, $V_{OUT} = \text{High}$	-250		+250	mA	$-7 \text{ V} \leq V_{OUT} \leq +12 \text{ V}$
Output Short-Circuit Current, $V_{OUT} = \text{Low}$	-250		+250	mA	$-7 \text{ V} \leq V_{OUT} \leq +12 \text{ V}$
Logic Inputs					
Input High Voltage	0.7 V_{DD1}			V	TxD, DE, \overline{RE} , PV
Input Low Voltage			0.25 V_{DD1}	V	TxD, DE, \overline{RE} , PV
CMOS Logic Input Current (TxD, DE, \overline{RE} , PV)	-10	+0.01	+10	μA	$TxD, DE, \overline{RE}, PV = V_{DD1}$ or 0 V
RECEIVER					
Differential Inputs					
Differential Input Threshold Voltage, V_{TH}	-200	-125	-30	mV	$-7 \text{ V} \leq V_{CM} \leq +12 \text{ V}$
Input Hysteresis		20		mV	$-7 \text{ V} \leq V_{CM} \leq +12 \text{ V}$
Input Resistance (A, B)	96	150		k Ω	$-7 \text{ V} \leq V_{CM} \leq +12 \text{ V}$
Input Current (A, B)			0.125	mA	$V_{IN} = +12 \text{ V}$
			-0.1	mA	$V_{IN} = -7 \text{ V}$
RxD Logic Output					
Output High Voltage	$V_{DD1} - 0.1$			V	$I_{OUT} = 20 \mu\text{A}$, $V_A - V_B = 0.2 \text{ V}$
	$V_{DD1} - 0.4$	$V_{DD1} - 0.2$		V	$I_{OUT} = 4 \text{ mA}$, $V_A - V_B = 0.2 \text{ V}$
Output Low Voltage			0.1	V	$I_{OUT} = -20 \mu\text{A}$, $V_A - V_B = -0.2 \text{ V}$
			0.4	V	$I_{OUT} = -4 \text{ mA}$, $V_A - V_B = -0.2 \text{ V}$
Output Short-Circuit Current	7	85		mA	$V_{OUT} = \text{GND}$ or V_{CC}
Three-State Output Leakage Current		± 1		μA	$0.4 \text{ V} \leq V_{OUT} \leq 2.4 \text{ V}$
POWER SUPPLY CURRENT					
Logic Side			2.5	mA	$4.5 \text{ V} \leq V_{DD1} \leq 5.5 \text{ V}$, outputs unloaded, $\overline{RE} = 0 \text{ V}$
			1.3	mA	$2.7 \text{ V} \leq V_{DD1} \leq 3.3 \text{ V}$, outputs unloaded, $\overline{RE} = 0 \text{ V}$
Bus Side			2.0	mA	Outputs unloaded, $DE = 5 \text{ V}$
			1.7	mA	Outputs unloaded, $DE = 0 \text{ V}$
COMMON-MODE TRANSIENT IMMUNITY¹					
	25			kV/ μs	$TxD = V_{DD1}$ or 0 V , $V_{CM} = 1 \text{ kV}$, transient magnitude = 800 V

¹ Common-mode transient immunity is the maximum common-mode voltage slew rate that can be sustained while maintaining specification-compliant operation. V_{CM} is the common-mode potential difference between the logic and bus sides. The transient magnitude is the range over which the common mode is slewed. The common-mode voltage slew rates apply to both rising and falling common-mode voltage edges.

TIMING SPECIFICATIONS

$2.7 \text{ V} \leq V_{DD1} \leq 5.5 \text{ V}$, $4.75 \text{ V} \leq V_{DD2} \leq 5.25 \text{ V}$, $T_A = T_{MIN}$ to T_{MAX} , unless otherwise noted.

Table 2.

Parameter	Min	Typ	Max	Unit	Test Conditions/Comments
DRIVER					
Maximum Data Rate	500			kbps	
Propagation Delay, t_{PLH}, t_{PHL}	250	620		ns	$R_{LDIFF} = 54 \Omega$, $C_{L1} = C_{L2} = 100 \text{ pF}$, see Figure 5 and Figure 9
Skew, t_{SKW}		40		ns	$R_{LDIFF} = 54 \Omega$, $C_{L1} = C_{L2} = 100 \text{ pF}$, see Figure 5 and Figure 9
Rise/Fall Time, t_R, t_F	200	600		ns	$R_{LDIFF} = 54 \Omega$, $C_{L1} = C_{L2} = 100 \text{ pF}$, see Figure 5 and Figure 9
Enable Time		1050		ns	$R_L = 500 \Omega$, $C_L = 100 \text{ pF}$, see Figure 6 and Figure 11
Disable Time		1050		ns	$R_L = 500 \Omega$, $C_L = 15 \text{ pF}$, see Figure 6 and Figure 11
RECEIVER					
Propagation Delay, t_{PLH}, t_{PHL}	400	1050		ns	$C_L = 15 \text{ pF}$, see Figure 7 and Figure 10
Differential Skew, t_{SKW}		250		ns	$C_L = 15 \text{ pF}$, see Figure 7 and Figure 10
Enable Time	25	70		ns	$R_L = 1 \text{ k}\Omega$, $C_L = 15 \text{ pF}$, see Figure 8 and Figure 12
Disable Time	40	70		ns	$R_L = 1 \text{ k}\Omega$, $C_L = 15 \text{ pF}$, see Figure 8 and Figure 12
POWER VALID INPUT					
Enable Time	1	2		μs	
Disable Time	3	5		μs	

ABSOLUTE MAXIMUM RATINGS

$T_A = 25^\circ\text{C}$, unless otherwise noted. All voltages are relative to their respective ground.

Table 3.

Parameter	Rating
V_{DD1}	-0.5 V to +7 V
V_{DD2}	-0.5 V to +6 V
Digital Input Voltage (DE, \overline{RE} , TxD)	-0.5 V to $V_{DD1} + 0.5$ V
Digital Output Voltage RXD	-0.5 V to $V_{DD1} + 0.5$ V
Driver Output/Receiver Input Voltage	-9 V to +14 V
ESD Rating: Contact Human Body Model (A, B Pins)	± 2 kV
Operating Temperature Range	-40°C to +85°C
Storage Temperature Range	-55°C to +150°C
Average Output Current per Pin	-35 mA to +35 mA
θ_{JA} Thermal Impedance	73°C/W
Lead Temperature Soldering (10 sec)	260°C
Vapor Phase (60 sec)	215°C
Infrared (15 sec)	220°C

Stresses at or above those listed under Absolute Maximum Ratings may cause permanent damage to the product. This is a stress rating only; functional operation of the product at these or any other conditions above those indicated in the operational section of this specification is not implied. Operation beyond the maximum operating conditions for extended periods may affect product reliability.

ESD CAUTION



ESD (electrostatic discharge) sensitive device. Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD. Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.

ABSOLUTE MAXIMUM RATINGS**PACKAGE CHARACTERISTICS****Table 4.**

Parameter	Symbol	Min	Typ	Max	Unit	Test Conditions
Resistance (Input-Output) ¹	R _{I-O}		10 ¹²		Ω	
Capacitance (Input-Output) ¹	C _{I-O}	3			pF	f = 1 MHz
Input Capacitance ²	C _I	4			pF	
Input IC Junction-to-Case Thermal Resistance	θ _{JCI}	33			°C/W	Thermocouple located at center of package underside
Output IC Junction-to-Case Thermal Resistance	θ _{JCO}	28			°C/W	Thermocouple located at center of package underside

¹ Device considered a 2-terminal device: Pins 1, 2, 3, 4, 5, 6, 7, and 8 shorted together, and Pins 9, 10, 11, 12, 13, 14, 15, and 16 shorted together.

² Input capacitance is from any input data pin to ground.

REGULATORY INFORMATION

The ADM2483 certification approvals are listed in **Table 5**.

Table 5. Regulatory Information

Regulatory Agency	Standard Certification/Approval	File
UL	1577 Single Protection, 2500 V _{RMS} ¹	File E214100
CSA	IEC/CSA 62368-1 Basic Insulation, 600 V Reinforced Insulation, 150 V _{RMS} IEC/CSA 60601-1 Reinforced Insulation (2MOPP), 150 V _{RMS} IEC/CSA 61010-1 Basic Insulation, 300 V _{RMS} Reinforced Insulation, 150 V _{RMS}	File No. 205078
CQC	GB4943.1 Basic Insulation, 415 V _{RMS}	Certificate No. CQC14001114898
VDE	DIN EN IEC 60747-17 (VDE 0884-17) Reinforced Insulation, 565 V peak ²	Certificate No. 40011599

¹ In accordance with UL 1577, each ADM2483 is proof tested by applying an insulation test voltage ≥ 3000 V_{RMS} for 1 second (current leakage detection limit = 5 μ A).

² In accordance with DIN EN IEC 60747-17 (VDE 0884-17), each ADM2483 is proof tested by applying an insulation test voltage ≥ 1059 V peak for 1 second (partial discharge detection limit = 5 pC).

INSULATION AND SAFETY-RELATED SPECIFICATIONS**Table 6.**

Parameter	Symbol	Value	Unit	Conditions
Rated Dielectric Insulation Voltage		2500	V rms	1-minute duration
Minimum External Air Gap (Clearance)	L(I01)	7.8	mm	Measured from input terminals to output terminals, shortest distance through air
Minimum External Tracking (Creepage)	L(I02)	7.8 ¹	mm	Measured from input terminals to output terminals, shortest distance along body
Minimum Clearance in the Plane of the Printed Circuit Board (PCB Clearance)	L(PCB)	8. ¹ ²	mm	
Minimum Internal Gap (Internal Clearance)		18	μ m	Insulation distance through insulation
Tracking Resistance (Comparative Tracking Index)	CTI	>600	V	DIN IEC 112/VDE 0303 Part 1

ABSOLUTE MAXIMUM RATINGS**Table 6. (Continued)**

Parameter	Symbol	Value	Unit	Conditions
Material Group		I		Material Group per IEC 60664-1

¹ In accordance with IEC 62368-1 / IEC 60601-1 guidelines for the measurement of creepage and clearance distances for a pollution degree of 2 and altitudes ≤ 2000 m.

² Consideration must be given to pad layout to ensure the minimum required distance for clearance is maintained.

DIN EN IEC 60747-17 (VDE 0884-17) INSULATION CHARACTERISTICS

This isolator is suitable for reinforced electrical isolation only within this safety limit data. Maintenance of this safety data shall be ensured by means of protective circuits.

An asterisk (*) on the physical package denotes DIN EN IEC 60747-17 (VDE 0884-17) approval.

Table 7.

Description	Test Conditions/Comments	Symbol	Characteristic	Unit
Overvoltage Category per IEC 60664-1				
For Rated Mains Voltage ≤ 150 V rms			I to IV	
For Rated Mains Voltage ≤ 300 V rms			I to III	
For Rated Mains Voltage ≤ 400 V rms			I to II	
Climatic Classification			40/100/21	
Pollution Degree per DIN VDE 0110, Table 1			2	
Maximum Repetitive Isolation Voltage		V_{IORM}	565	V_{PEAK}
Maximum Working Insulation Voltage		V_{IOWM}	400	V_{RMS}
Input to Output test Voltage, Method b1	$V_{IORM} \times 1.875 = V_{PR}$, 100% production tested, $t_{ini} = t_m = 1$ sec, partial discharge < 5 pC	V_{PR}	1059	V_{PEAK}
Input-to-Output Test Voltage, Method a				
After Environmental Tests, Subgroup 1	$V_{IORM} \times 1.6 = V_{PR}$, $t_{ini} = 60$ sec, $t_m = 10$ sec, partial discharge < 5 pC	V_{PR}	904	V_{PEAK}
After Input and/or Safety Test, Subgroup 2 and Subgroup 3	$V_{IORM} \times 1.2 = V_{PR}$, $t_{ini} = 60$ sec, $t_m = 10$ sec, partial discharge < 5 pC	V_{PR}	678	V_{PEAK}
Maximum Transient Isolation Voltage		V_{IOTM}	4200	V_{PEAK}
Maximum Impulse Voltage	Tested in air, 1.2 μ s/50 μ s waveform per IEC 61000-4-5	V_{IMP}	4200	V_{PEAK}
Maximum Surge Isolation Voltage	Tested in oil, 1.2 μ s/50 μ s waveform per IEC 61000-4-5, $V_{TEST} = V_{IMP} \times 1.3$ OR ≥ 10 kV	V_{IOSM}	10,000	V_{PEAK}
Safety-Limiting Values	Maximum value allowed in the event of a failure; see Figure 23			
Maximum Junction Temperature		T_S	150	°C
Input Current		$I_{S, INPUT}$	265	mA
Output Current		$I_{S, OUTPUT}$	335	mA
Insulation Resistance at T_S	$V_{IO} = 500$ V	R_S	$> 10^9$	Ω

PIN CONFIGURATION AND FUNCTION DESCRIPTIONS

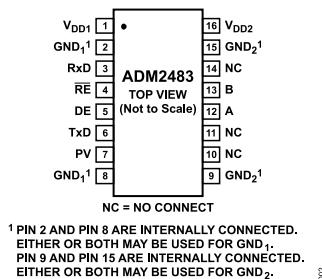
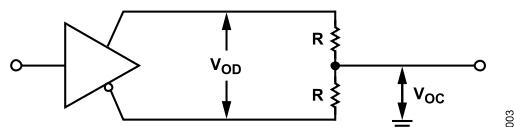


Figure 2. Pin Configuration

Table 8. Pin Function Descriptions

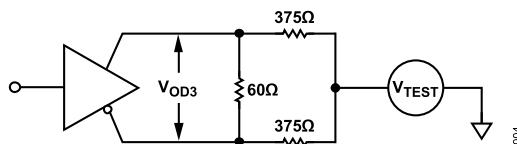
Pin No.	Mnemonic	Description
1	V _{DD1}	Power Supply (Logic Side).
2, 8	GND ₁	Ground (Logic Side).
3	RxD	Receiver Output Data. When enabled, if (A - B) ≥ -30 mV, then RxD = high. If (A - B) ≤ -200 mV, then RxD = low. This is a tristate output when the receiver is disabled, that is, when RE is driven high.
4	RE	Receiver Enable Input. This is an active-low input. Driving this input low enables the receiver, and driving it high disables the receiver.
5	DE	Driver Enable Input. Driving the input high enables the driver, and driving it low disables the driver.
6	TxD	Transmit Data Input. Data to be transmitted by the driver is applied to this input.
7	PV	Power_Valid. Used during power-up and power-down. See the Applications Information section.
9, 15	GND ₂	Ground (Bus Side).
10, 11, 14	NC	No Connect.
12	A	Noninverting Driver Output/Receiver Input. When the driver is disabled, or when V _{DD1} or V _{DD2} is powered down, Pin A is put into a high impedance state to avoid overloading the bus.
13	B	Inverting Driver Output/Receiver Input. When the driver is disabled, or when V _{DD1} or V _{DD2} is powered down, Pin B is put into a high impedance state to avoid overloading the bus.
16	V _{DD2}	Power Supply (Bus Side).

TEST CIRCUITS



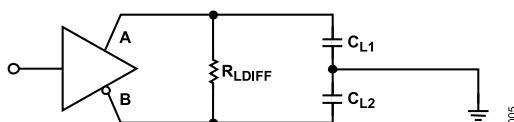
003

Figure 3. Driver Voltage Measurement



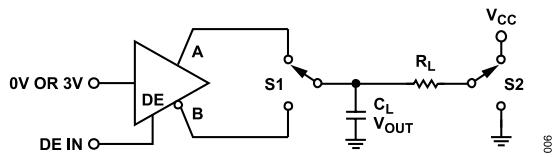
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Figure 4. Driver Voltage Measurement



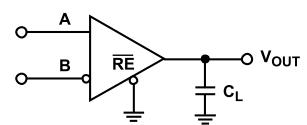
005

Figure 5. Driver Propagation Delay



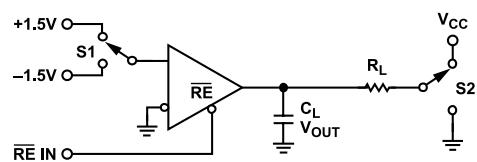
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Figure 6. Driver Enable/Disable



007

Figure 7. Receiver Propagation Delay



008

Figure 8. Receiver Enable/Disable

SWITCHING CHARACTERISTICS

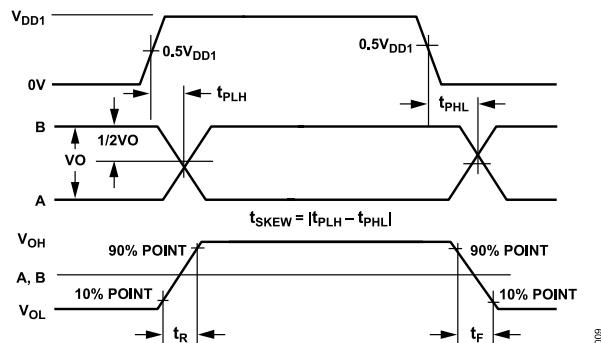


Figure 9. Driver Propagation Delay, Rise/Fall Timing

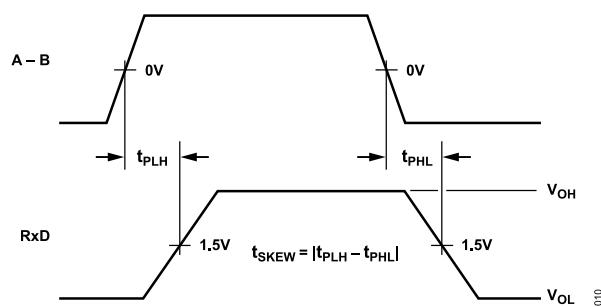


Figure 10. Receiver Propagation Delay

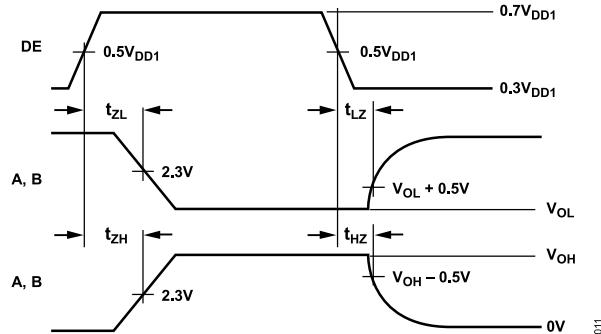


Figure 11. Driver Enable/Disable Timing

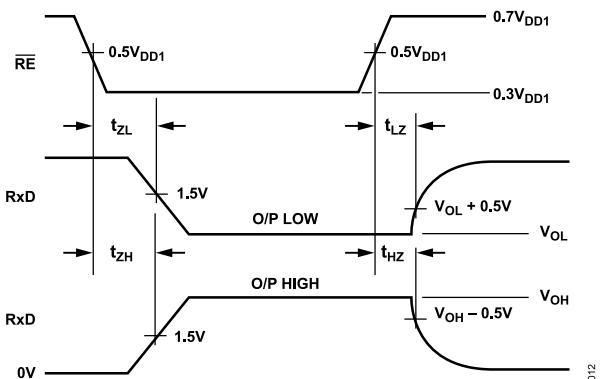


Figure 12. Receiver Enable/Disable Timing

TYPICAL PERFORMANCE CHARACTERISTICS

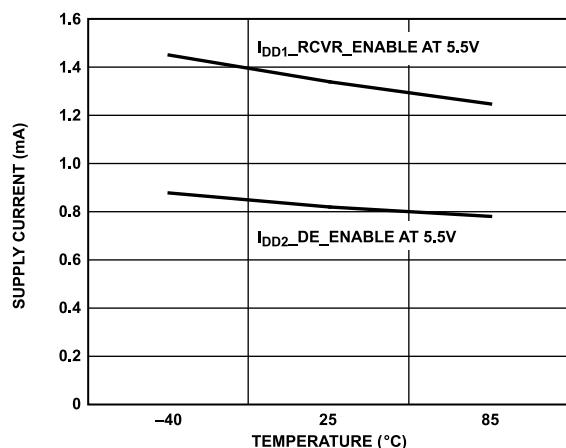
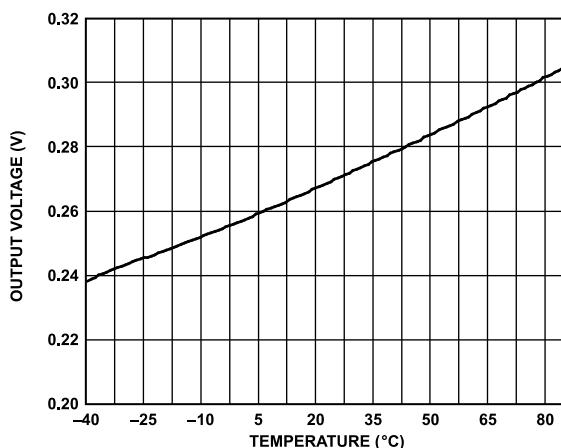


Figure 13. Unloaded Supply Current vs. Temperature

038

Figure 16. Receiver Output Low Voltage vs. Temperature, $I = -4\text{ mA}$

031

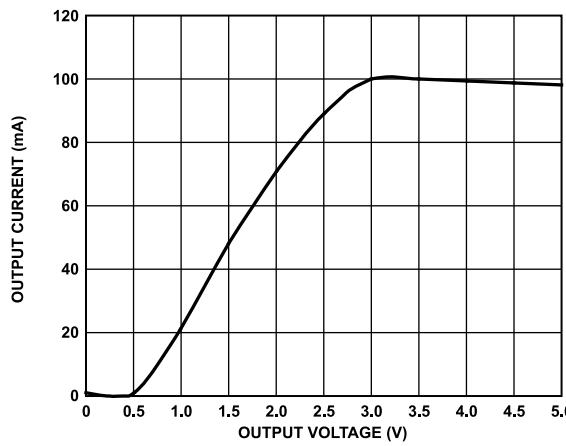
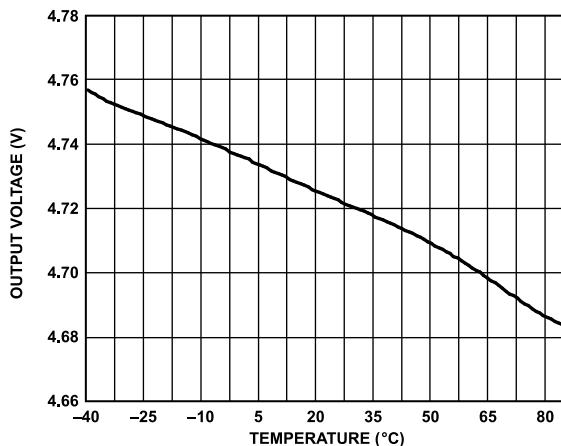
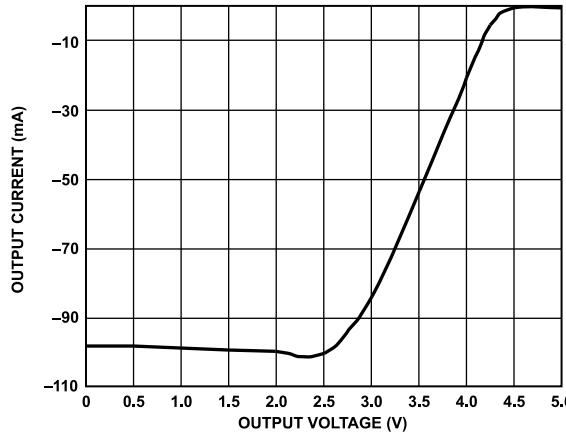


Figure 14. Output Current vs. Driver Output Low Voltage

014

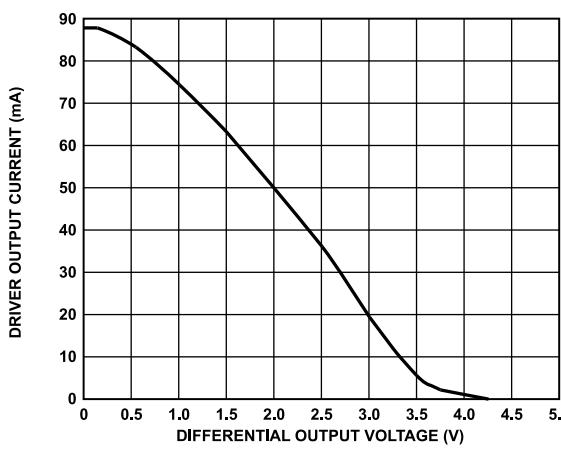
Figure 17. Receiver Output High Voltage vs. Temperature, $I = 4\text{ mA}$

032



015

Figure 15. Output Current vs. Driver Output High Voltage



013

Figure 18. Driver Output Current vs. Differential Output Voltage

TYPICAL PERFORMANCE CHARACTERISTICS

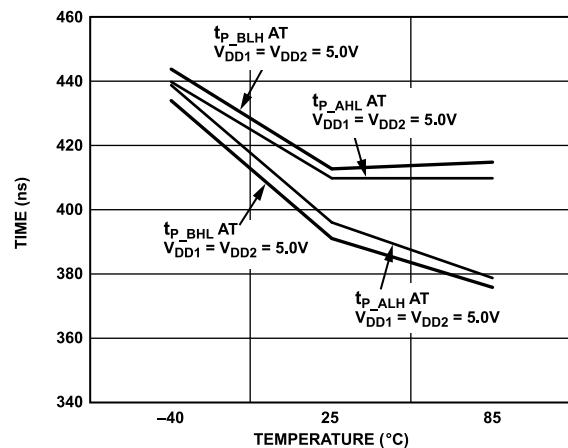


Figure 19. Driver Propagation Delay vs. Temperature

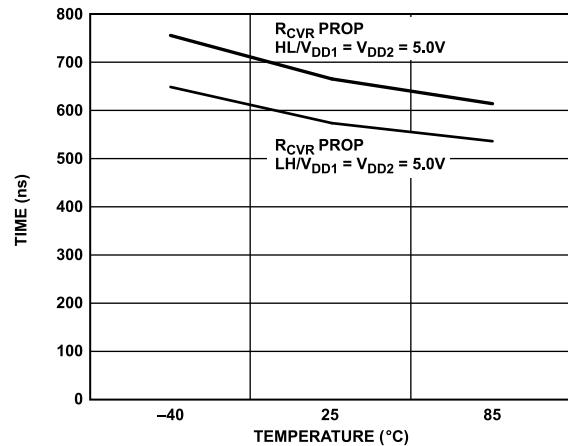


Figure 20. Receiver Propagation Delay vs. Temperature

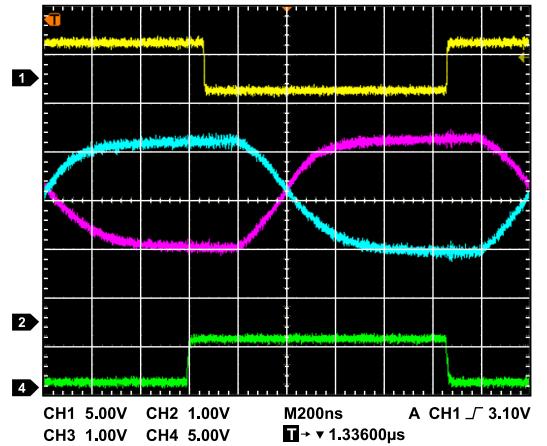


Figure 21. Driver/Receiver Propagation Delay High to Low

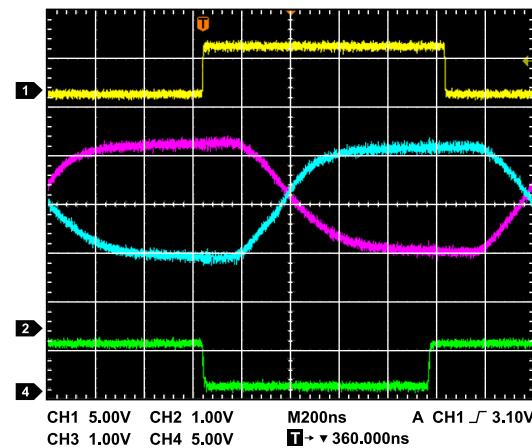


Figure 22. Driver/Receiver Propagation Delay Low to High

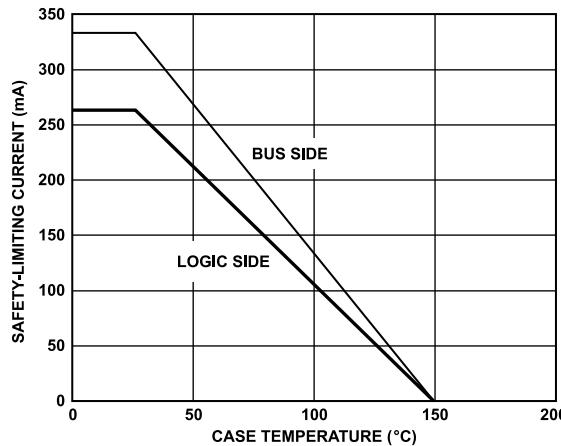


Figure 23. Thermal Derating Curve, Dependence of Safety-Limiting Values with Case Temperature per VDE V 0884

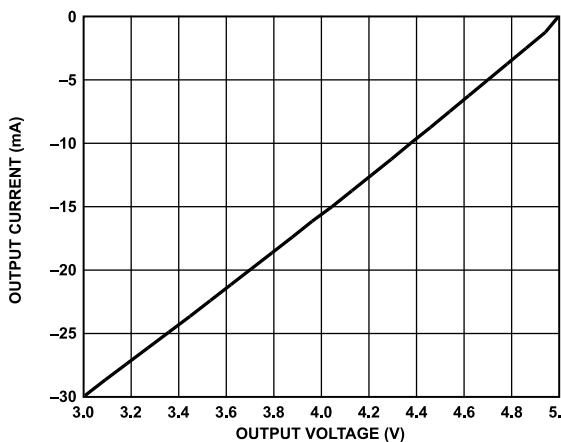


Figure 24. Output Current vs. Receiver Output High Voltage

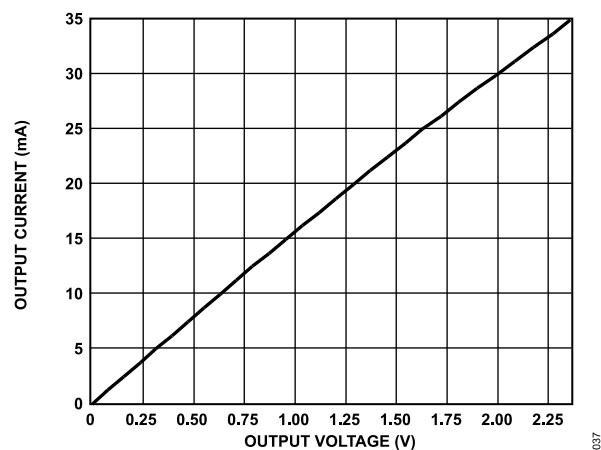
TYPICAL PERFORMANCE CHARACTERISTICS

Figure 25. Output Current vs. Receiver Output Low Voltage

CIRCUIT DESCRIPTION

ELECTRICAL ISOLATION

In the ADM2483, electrical isolation is implemented on the logic side of the interface. Therefore, the part has two main sections: a digital isolation section and a transceiver section (see [Figure 26](#)). Driver input and data enable signals, applied to the TxD and DE pins, respectively, and referenced to logic ground (GND_1), are coupled across an isolation barrier to appear at the transceiver section referenced to isolated ground (GND_2). Similarly, the receiver output, referenced to isolated ground in the transceiver section, is coupled across the isolation barrier to appear at the Rx_D pin referenced to logic ground.

iCoupler Technology

The digital signals are transmitted across the isolation barrier using iCoupler technology. This technique uses chip scale transformer windings to couple the digital signals magnetically from one side of the barrier to the other. Digital inputs are encoded into waveforms that are capable of exciting the primary transformer winding. At the secondary winding, the induced waveforms are then decoded into the binary value that was originally transmitted.

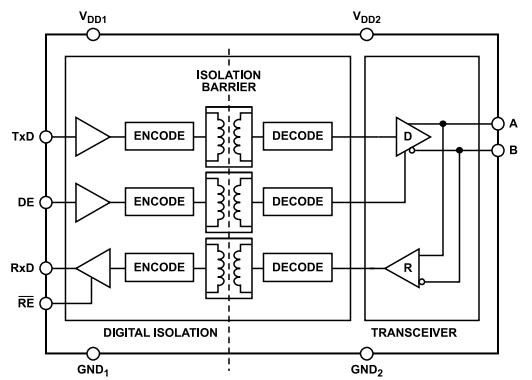


Figure 26. ADM2483 Digital Isolation and Transceiver Sections

CIRCUIT DESCRIPTION

TRUTH TABLES

The following truth tables use these abbreviations:

Letter	Description
H	High level
L	Low level
X	Irrelevant
Z	High impedance (off)
NC	Disconnected

Table 9. Transmitting

Supply Status		Inputs		Outputs	
V _{DD1}	V _{DD2}	DE	TxD	A	B
On	On	H	H	H	L
On	On	H	L	L	H
On	On	L	X	Z	Z
On	Off	X	X	Z	Z
Off	On	X	X	Z	Z
Off	Off	X	X	Z	Z

Table 10. Receiving

Supply Status		Inputs		Outputs	
V _{DD1}	V _{DD2}	A - B (V)	RE	RxD	
On	On	>-0.03	L or NC	H	
On	On	<-0.2	L or NC	L	
		-0.2 < A - B <			
On	On	-0.03	L or NC	Indeterminate	
On	On	Inputs open	L or NC	H	
On	On	X	H	Z	
On	Off	X	L or NC	H	
Off	On	X	L or NC	H	
Off	Off	X	L or NC	L	

POWER-UP/POWER-DOWN CHARACTERISTICS

The power-up/power-down characteristics of the ADM2483 are in accordance with the supply thresholds shown in Table 11. Upon power-up, the ADM2483 output signals (A, B, and RxD) reach their correct state once both supplies exceed their thresholds. Upon power-down, the ADM2483 output signals retain their correct state until at least one of the supplies drops below its power-down threshold. When the V_{DD1} power-down threshold is crossed, the ADM2483 output signals reach their unpowered states within 4 µs.

Table 11. Power-Up/Power-Down Thresholds

Supply	Transition	Threshold (V)
V _{DD1}	Power-up	2.0
V _{DD1}	Power-down	1.0
V _{DD2}	Power-up	3.3
V _{DD2}	Power-down	2.4

THERMAL SHUTDOWN

The ADM2483 contains thermal shutdown circuitry that protects the part from excessive power dissipation during fault conditions. Shorting the driver outputs to a low impedance source can result in high driver currents. The thermal sensing circuitry detects the increase in die temperature under this condition and disables the driver outputs. This circuitry is designed to disable the driver outputs when a die temperature of 150°C is reached. As the device cools, the drivers are re-enabled at a temperature of 140°C.

TRUE FAIL-SAFE RECEIVER INPUTS

The receiver inputs have a true fail-safe feature, which ensures that the receiver output is high when the inputs are open or shorted. During line-idle conditions, when no driver on the bus is enabled, the voltage across a terminating resistance at the receiver input decays to 0 V. With traditional transceivers, receiver input thresholds specified between -200 mV and +200 mV mean that external bias resistors are required on the A and B pins to ensure that the receiver outputs are in a known state. The true fail-safe receiver input feature eliminates the need for bias resistors by specifying the receiver input threshold between -30 mV and -200 mV. The guaranteed negative threshold means that when the voltage between A and B decays to 0 V, the receiver output is guaranteed to be high.

MAGNETIC FIELD IMMUNITY

Because iCougler use a coreless technology, no magnetic components are present, and the problem of magnetic saturation of the core material does not exist. Therefore, iCougler have essentially infinite dc field immunity. The analysis that follows defines the conditions under which this might occur. The 3 V operating condition of the ADM2483 is examined because it represents the most susceptible mode of operation.

The limitation on the iCougler's ac magnetic field immunity is set by the condition in which the induced error voltage in the receiving coil (the bottom coil in this case) is made sufficiently large, either to falsely set or reset the decoder. The voltage induced across the bottom coil is given by

$$V = \left(\frac{-d\beta}{dt} \right) \sum \pi r_n^2; \quad n = 1, 2, \dots, N \quad (1)$$

where if the pulses at the transformer output are greater than 1.0 V in amplitude:

β = magnetic flux density (gauss)

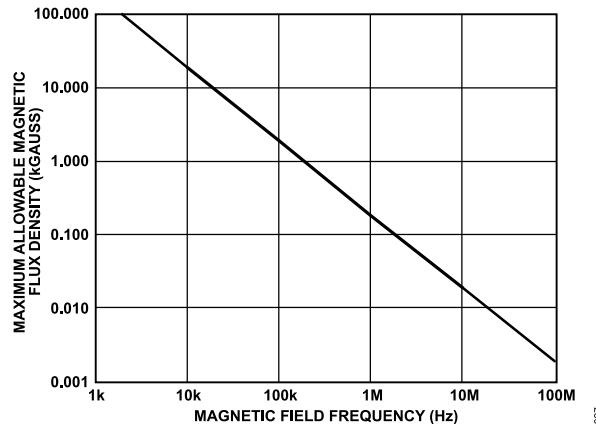
N = number of turns in receiving coil

r_n = radius of nth turn in receiving coil (cm)

The decoder has a sensing threshold of about 0.5 V; therefore, there is a 0.5 V margin in which induced voltages can be tolerated.

Given the geometry of the receiving coil and an imposed requirement that the induced voltage is, at most, 50% of the 0.5 V margin at the decoder, a maximum allowable magnetic field is calculated, as shown in Figure 27.

CIRCUIT DESCRIPTION

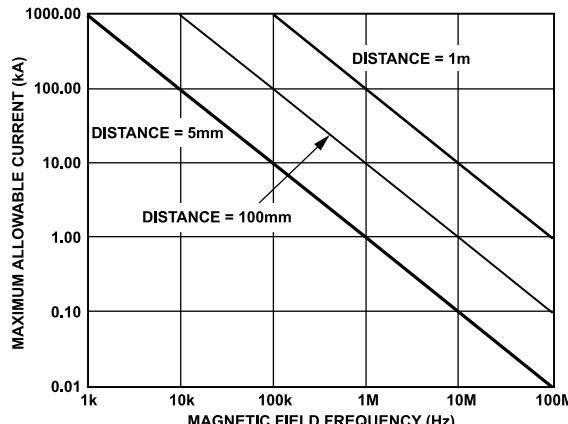


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Figure 27. Maximum Allowable External Magnetic Flux Density

For example, at a magnetic field frequency of 1 MHz, the maximum allowable magnetic field of 0.2 kGauss induces a voltage of 0.25 V at the receiving coil. This is about 50% of the sensing threshold and does not cause a faulty output transition. Similarly, if such an event occurs during a transmitted pulse and is the worst-case polarity, it reduces the received pulse from >1.0 V to 0.75 V. This is well above the 0.5 V sensing threshold of the decoder.

These magnetic flux density values are shown in Figure 28, using more familiar quantities such as maximum allowable current flow, at given distances away from the ADM2483 transformers.



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Figure 28. Maximum Allowable Current for Various Current-to-ADM2483 Spacings

At combinations of strong magnetic field and high frequency, any loops formed by printed circuit board traces could induce large enough error voltages to trigger the thresholds of succeeding circuitry. To avoid this possibility, care should be taken in the layout of such traces.

APPLICATIONS INFORMATION

POWER_VALID INPUT

To avoid chatter on the A and B outputs caused by slow power-up and power-down transients on V_{DD1} ($>100\ \mu s/V$), the ADM2483 features a power_valid (PV) digital input. This pin should be driven low until V_{DD1} exceeds 2.0 V. When V_{DD1} is greater than 2.0 V, the pin should be driven high. Conversely, upon power-down, the PV should be driven low before V_{DD1} reaches 2.0 V.

The power_valid input can be driven, for example, by the output of a system reset circuit such as the [ADM809Z](#), which has a threshold voltage of 2.32 V.

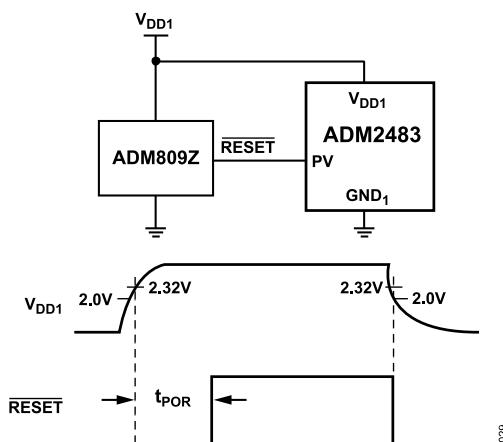


Figure 29. Driving PV with ADM809Z

ISOLATED POWER SUPPLY CIRCUIT

The ADM2483 requires isolated power capable of 5 V at 100 mA to be supplied between the V_{DD2} and GND_2 pins. If no suitable integrated power supply is available, a discrete circuit, such as the one in [Figure 30](#), can be used. A center-tapped transformer provides electrical isolation. The primary winding is excited with a pair of square waveforms that are 180° out of phase with each other. A pair of Schottky diodes and a smoothing capacitor are used to create a rectified signal from the secondary winding. The [ADP667](#) linear voltage regulator provides a regulated power supply to the ADM2483's bus-side circuitry.

To create the pair of square waves, a D-type flip-flop with complementary Q/\bar{Q} outputs is used. The flip-flop can be connected so that output Q follows the clock input signal. If no local clock signal is available, a simple digital oscillator can be implemented with a hex-inverting Schmitt trigger and a resistor and capacitor. In this case, values of 3.9 kΩ and 1 nF generate a 364 kHz square wave. A pair of discrete NMOS transistors, switched by the Q/\bar{Q} flip-flop outputs, conduct current through the center tap of the primary transformer, winding in an alternating fashion.

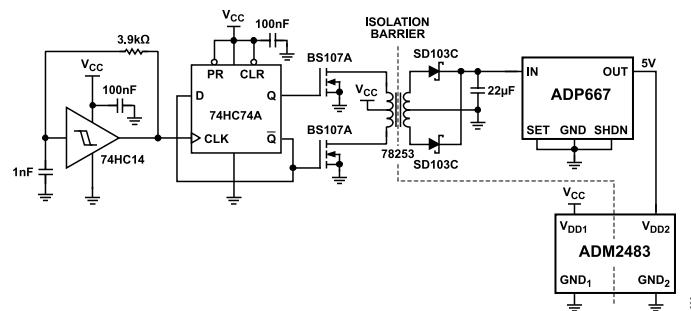


Figure 30. Isolated Power Supply Circuit

OUTLINE DIMENSIONS

Package Drawing (Option)	Package Type	Package Description
RW-16	SOIC_W	16-Lead Standard Small Outline Package

For the latest package outline information and land patterns (footprints), go to [Package Index](#).

ORDERING GUIDE

Model ^{1,2}	Data Rate (kbps)	Temperature Range	Package Description	Package Option
ADM2483BRW	500	-40°C to +85°C	16-Lead, Wide Body SOIC_W	RW-16
ADM2483BRW-REEL	500	-40°C to +85°C	16-Lead, Wide Body SOIC_W	RW-16
ADM2483BRWZ	500	-40°C to +85°C	16-Lead, Wide Body SOIC_W	RW-16
ADM2483BRWZ-REEL	500	-40°C to +85°C	16-Lead, Wide Body SOIC_W	RW-16

¹ Z = RoHS Compliant Part.

² -REEL suffix designates a 13-inch (1,000 units) tape-and-reel option.

EVALUATION BOARDS

Model ¹	Package Description
EVAL-ADM2483EBZ	ADM2483 Evaluation Board

¹ Z = RoHS Compliant Part.