

# code1 实验报告

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## 1 实验介绍

本次实验要求用 C++ 实现矩阵类 **matrix**：该类用一维数组和两个整数分别存储矩阵的元素、矩阵的行数及列数，能够调用赋值、加减乘（除）法运算、切片操作、输出矩阵元素等方法。

## 2 算法与实现

要求实现的功能并不复杂，主要有三大部分：

- 1 基础的赋值功能、重载等号运算符
- 2 '+'、'-'、'\*'、'/' 等运算
- 3 输出结果，如打印矩阵值，获取矩阵元素、子阵，输出错误信息等

其中矩阵的基础运算直接套用公式即可。需要注意几点：

1. 由于类中包含指针成员，需要对指针指向的内容进行拷贝，称为“深拷贝”，默认的等号运算符是“浅拷贝”。

2. 有时我们会在方法（操作符）中定义变量或者分配内存，然后需要返回变量值（类的实例）或者保留分配的内存。该情况下不能直接返回它们的引用，因为在跳出该方法时，在其中定义的变量（类的实例）生命周期结束，会被自动清理（析构），即无法返回有效内容。对于本次实验，应该返回 `Matrix<Tem>` 类的实例，这样实例就能被拷贝并带出（定义该实例的）方法。分配内存的指针同理，在跳出方法前，在方法中定义的指针不能指向要保留的内存空间。

## 3 测试结果

主要进行了正确性测试<sup>1</sup>和效率测试<sup>2</sup>，前者对编写的各方法以及不同模板进行了测试，后者对比了 `Matrix` 类与 `Eigen` 库的 `MatrixXd` 类在进行较大规模矩阵乘法的运算速度（矩阵乘法的时间复杂度最高，理论上应该用它来测试效率），实验结果如图所示，源代码详见附件或本文附录。

## 4 实验分析

本次实验完成了 `Matrix` 类的实现与测试。目标类在测试函数中正常运行。不难看出，在没有进行优化（debug）的情况下，`Matrix` 类明显快于 `Eigen::MatrixXd` 类，这是因为我们自己实现的

```

~~~~~
整型数据 准确性测试:
this matrix has size (4 x 3)
the entries are:
4      11      4
11     2       16
5      18      13
21     10      4
A: this matrix has size (3 x 4)
the entries are:
0      1       2       3
1      2       3       4
2      3       4       5
B: this matrix has size (4 x 3)
the entries are:
0      -1      -2
1      0       -1
2      1       0
3      2       1
R: this matrix has size (4 x 3)
the entries are:
4      12      6
10     2       17
3      17      13
18     8       3
C: this matrix has size (3 x 3)
the entries are:
14     8       2
20     10      0
26     12      -2
D: this matrix has size (4 x 4)
the entries are:
-5     -8      -11     -14
-2     -2      -2      -2
1      4       7       10
4      10      16      22
E: this matrix has size (1 x 3)
the entries are:
85     68      53
F: this matrix has size (3 x 2)
the entries are:
1      2
2      3
3      4

```

(a) 整型

```

~~~~~
双精度数据 准确性测试:
this matrix has size (4 x 3)
the entries are:
3.4     10.6    17.4
13.8    19.8    3.6
2       14.2    14.4
22.4    20      8.2
A: this matrix has size (3 x 4)
the entries are:
0      1       2       3
1      2       3       4
2      3       4       5
B: this matrix has size (4 x 3)
the entries are:
0      -1      -2
1      0       -1
2      1       0
3      2       1
R: this matrix has size (4 x 3)
the entries are:
3.4     11.6    19.4
12.8    19.8    4.6
0       13.2    14.4
19.4    18      7.2
C: this matrix has size (3 x 3)
the entries are:
14     8       2
20     10      0
26     12      -2
D: this matrix has size (4 x 4)
the entries are:
-5     -8      -11     -14
-2     -2      -2      -2
1      4       7       10
4      10      16      22
E: this matrix has size (1 x 3)
the entries are:
86     108.2    56
F: this matrix has size (3 x 2)
the entries are:
1      2
2      3
3      4

```

(b) 双精度型

图 1: 正确性测试

```

~~~~~
Matrix 效率测试:
My Matrix, runtime: 0.0894401
Eigen's Matrix, runtime: 0.0120396

```

(a) 优化 (Release)

```

~~~~~
Matrix 效率测试:
My Matrix, runtime: 2.03855
Eigen's Matrix, runtime: 3.73207

```

(b) 无优化 (Debug)

图 2: 效率测试

类会对数据直接操作；而在优化 (Release) 编译后，同一程序的运算速度都大幅提升，而且 Eigen 库的实现大幅反超了笔者自己的实现（情理之中）。

## 5 附件内容

本次作业附件为：

- 1 matrix\_main.cpp : 源代码
- 2 homework1/ : 用VS构建的项目，使用前需调整属性

## A 代码

包含 Matrix 类、Assert 函数 (检查与报错)、两个 test 函数、主函数 (测试用)、系数矩阵类 (To Be Done), 其中部分乱码应该是中文编码的问题, 暂未找到解决方法, 不过不影响查看 (详见附件)

---

```
//#include <cstdio>
#include <chrono>
#include <iostream>
#include <vector>

#include "Eigen/Dense"
//#include <Eigen/QR>

bool Assert(bool state);

// todo 5: change the class in to a template class
//#define Tem double
template<typename Tem>
class Matrix {
private:
    int rows, cols;
    Tem *data;

public:
    // default constructor
    // https://en.cppreference.com/w/cpp/language/constructor
    Matrix() :rows(1), cols(1), data(new Tem[1]) { data[0] = 0; } // Matrix() = delete;

    // constructor with initializer list
    Matrix(int r, int c)
    : rows(r), cols(c), data(new Tem[r*c]) {}
    Matrix(const Matrix& Mat) // 这里应该是中文乱码
    : rows(Mat.rows), cols(Mat.cols), data(new Tem[Mat.rows * Mat.cols])
    {
        // std::cout << "Created!" << std::endl;
        for (int n = 0; n < rows*cols; n++)
            data[n] = Mat[n];
    }

    // destructor
    // https://en.cppreference.com/w/cpp/language/destructor
    ~Matrix() { if(data!=nullptr)delete data; }

    int nrow() const {return rows;}
    int ncol() const {return cols;}

    // operator overloading
```

```

    Tem& operator()(int r, int c) {return data[r*cols + c]; } // i 1 g° á±
Tem& operator()(int r, int c) const { return data[r*cols + c]; } // ²»₁ μg° á±
Tem& operator[](int n) { return data[n]; /* todo 3: particular entry of the matrix*/ }
    Tem& operator[](int n) const {return data[n]; /* todo 3: particular entry of the matrix*/}

    Matrix col(int col)
    {
        /* todo 4: particular column of the matrix*/
        Matrix Mat_Col(rows, 1); // »» ú⁻ ½ ±» ¿²»» I · μ» , £⁻²»
        for (int i = 0; i < rows; i++)
            Mat_Col[i] = data[i*cols+col];
        return Mat_Col;
    }

    Matrix row(int row)
    {
        /* todo 4: particular row of the matrix*/
        Matrix Mat_Row = Matrix(1, cols);
        for (int i = 0; i < cols; i++)
            Mat_Row(0, i) = (*this)(row,i); // data[row*cols + i];
        return Mat_Row;
    }

    Matrix submat(int rowL, int rowU, int colL, int colU) const
    {
        /* todo 4: return a sub-matrix specified by the input parameters*/
        Assert((rowL<=rowU) && (colL<=colU));
        Matrix Mat_Sub(rowU-rowL+1, colU-colL+1);
        for (int i = 0; i < rowU - rowL + 1; i++)
        {
            for (int j = 0; j < colU - colL + 1; j++)
                Mat_Sub(i, j) = (*this)(i + rowL, j + colL); //data[(i + rowL)*cols + (j + colL)];
        }
        return Mat_Sub;
    }

    // constant alias
    Matrix& operator= (const Matrix& rhs)
    {
        // std::cout << "'=' called\n ~~~~~~" << std::endl;
        if(data!=nullptr) delete[] data;
        Tem* newData = new Tem[rhs.cols*rhs.rows];
        rows = rhs.rows; cols = rhs.cols;
        for (int i = 0; i < cols*rows; i++)
            newData[i] = rhs.data[i];

        data = newData;
        return *this;
    }

    /*      I · μ» μlô! ½± +=;¢⁻= μ μ
        ± (A*B).print()      İ · μ» Ø¿± μ */

```

```

    Matrix operator+ (const Matrix& rhs)
{
    Assert(cols == rhs.ncol() && rows == rhs.nrow());
    Matrix res(rows, cols);
    for (int n = 0; n < cols*rows; n++)
        res[n] = (*this)[n] + rhs[n];
    return res;
}

    Matrix operator- (const Matrix& rhs)
{
    Assert(cols == rhs.ncol() && rows == rhs.nrow());
    Matrix res(rows, cols);
    for (int n = 0; n < cols*rows; n++)
        res[n] = (*this)[n] - rhs[n];
    return res;
}

// %
    Matrix operator* (const Matrix& rhs)
{
    Assert(cols == rhs.nrow());
    Matrix res(rows, rhs.ncol());
    for(int i=0; i<rows; i++)
        for (int j = 0; j < rhs.ncol(); j++)
        {
            res(i, j) = 0;
            for (int k = 0; k < cols; k++)
                res(i, j) += (*this)(i, k) * rhs(k, j);
        }
    // res.print(); //test
    return res;
}

// ¶       $\mathbb{R}^n \times \mathbb{R}^m \rightarrow \mathbb{R}^n$ 
    Matrix operator/ (const Matrix& rhs)
{
    Assert(rows == rhs.nrow() && cols == rhs.ncol());
    Matrix res(rows, cols);
    for (int n = 0; n < cols*rows; n++)
        res[n] = (*this)[n] + rhs[n];
    return res;
}

    Matrix operator+= (const Matrix& rhs)
{
    Matrix res(*this + rhs);
    *this = res;
}

```

```

return *this;
}

    Matrix operator-= (const Matrix& rhs)
{
    Matrix res(*this - rhs);
    *this = res;
    return *this;
}

    Matrix operator*= (const Matrix& rhs)
{
    Matrix res(*this * rhs);
    *this = res;
    return *this;
}

    Matrix operator/= (const Matrix& rhs)
{
    Matrix res(*this / rhs);
    *this = res;
    return *this;
}

    Matrix operator+ (Tem v)
{
    Matrix res(rows, cols);
    for (int n = 0; n < cols*rows; n++)
        res[n] = (*this)[n] + v;
    return res;
}

    Matrix operator- (Tem v)
{
    Matrix res(rows, cols);
    for (int n = 0; n < cols*rows; n++)
        res[n] = (*this)[n] - v;
    return res;
}

    Matrix operator* (Tem v)
{
    Matrix res(rows, cols);
    for (int n = 0; n < cols*rows; n++)
        res[n] = (*this)[n] * v;
    return res;
}

    Matrix operator/ (Tem v)
{
    Assert(fabs(v) < 1e-10); //  $v^2 \gg \frac{1}{2} 0$ 

```

```

Matrix res(rows, cols);
for (int n = 0; n < cols*rows; n++)
    res[n] = (*this)[n] / v;
return res;
}

Matrix operator+= (Tem v)
{
    Matrix res(*this + v);
    *this = res;
    return *this;
}

Matrix operator-= (Tem v)
{
    Matrix res(*this - v);
    *this = res;
    return *this;
}

    Matrix operator*= (Tem v)
{
    Matrix res(*this * v);
    *this = res;
    return *this;
}

    Matrix operator/= (Tem v)
{
    Matrix res(*this / v);
    *this = res;
    return *this;
}

    void print () const {
        printf("this matrix has size (%d x %d)\n", rows, cols);
        printf("the entries are:\n");
        for (int i = 0; i < rows; i++)
        {
            for (int j = 0; j < cols; j++)
                std::cout << (*this)(i, j) << '\t';
            std::cout << std::endl;
        }
    }

};

bool Assert(bool state)
{
    if (state)

```

```

return true;
else
std::cout << "Err!" << std::endl;
exit(0);
}

// BONUS: write a sparse matrix class
template<typename R>
class SparseMatrix {

};

template<typename type>
void test_1()
{
std::cout << ": j " << std::endl; // ?<< static_cast<char*>(type)

Matrix<type> A(3, 4), B(4, 3), R(4, 3); // ¶ L11

for (int i = 0; i < A.nrow(); i++) // ·½· nrow(), ncol()
for (int j = 0; j < A.ncol(); j++)
A(i, j) = i + j; // ()''
for (int i = 0; i < B.nrow(); i++)
for (int j = 0; j < B.ncol(); j++)
{
B(i, j) = i - j;
R(i, j) = (rand() % 100) / static_cast<type>(5);
}

Matrix<type> C = A * B; // ¶ Matrix(const Matrix& Mat)
Matrix<type> D; D = B * A; // ¶ L11 L11 '='
Matrix<type> E(B.row(1)); // ¶ row(), col(), ¶
E += A.row(0)*(B + R); // '+' '-' 'p', '~
Matrix<type> F(A.submat(0, 2, 1, 2)); // ¶ submat() F=A[1:2, 0:3]

(B + R).print(); // '*' Matrix

std::cout << "A: "; A.print(); // ¶ print() L11
std::cout << "B: "; B.print();
std::cout << "R: "; R.print();
std::cout << "C: "; C.print();
std::cout << "D: "; D.print();
std::cout << "E: "; E.print();
std::cout << "F: "; F.print();
}

```



```

void test_2()
{
    std::cout << "    : " << std::endl;
    int n_rows = 300, n_cols = 200;
    auto start = std::chrono::steady_clock::now();
    {
        Matrix<double> A(n_rows, n_cols), B(n_cols, n_rows), R(n_cols, n_rows);

        for (int i = 0; i < A.nrow(); i++)
            for (int j = 0; j < A.ncol(); j++)
                A(i, j) = i + j;
        for (int i = 0; i < B.nrow(); i++)
            for (int j = 0; j < B.ncol(); j++)
            {
                B(i, j) = i - j;
                R(i, j) = (rand() % 100) / 9.7;
            }
        Matrix<double> C = A * B;
        Matrix<double> D; D = R * A;
    }

    auto end = std::chrono::steady_clock::now();
    std::chrono::duration<double> runTime = end - start;
    std::cout << "My Matrix, runtime: " << runTime.count() << std::endl;

    // todo 8: use Eigen and compare
    start = std::chrono::steady_clock::now();
    {
        Eigen::MatrixX<double> A(n_rows, n_cols), B(n_cols, n_rows), R(n_cols, n_rows);
        for (int i = 0; i < A.rows(); i++)
            for (int j = 0; j < A.cols(); j++)
                A(i, j) = i + j;
        for (int i = 0; i < B.rows(); i++)
            for (int j = 0; j < B.cols(); j++)
            {
                B(i, j) = i - j;
                R(i, j) = (rand() % 100) / 9.7;
            }

        Eigen::MatrixX<double> C = A * B;
        Eigen::MatrixX<double> D(n_cols, n_cols); D = R * A;
    }

    end = std::chrono::steady_clock::now();
    runTime = end - start;
    std::cout << "Eigen's Matrix, runtime: " << runTime.count() << std::endl;
}

int main()

```

```

{
    srand(time(0));
    /* test 1: j */
    std::cout << "\n~~~~~\n";
    std::cout << "    % "; test_1<int>();

    std::cout << "\n~~~~~\n";
    std::cout << "R%¶ % "; test_1<double>();

    /* test 2 */
    std::cout << "\n~~~~~\n";
    std::cout << "Matrix "; test_2();

    return 0;
}

```

---