

# Matrix Reference Manual

## Matrix Calculus

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## Notation

- $d/dx$  ( $\mathbf{y}$ ) is a vector whose ( $i$ ) element is  $dy(i)/dx$
- $d/d\mathbf{x}$  ( $\mathbf{y}$ ) is a vector whose ( $i$ ) element is  $dy/dx(i)$
- $d/d\mathbf{x}$  ( $\mathbf{y}^T$ ) is a matrix whose ( $i,j$ ) element is  $dy(j)/dx(i)$
- $d/dx$  ( $\mathbf{Y}$ ) is a matrix whose ( $i,j$ ) element is  $dy(i,j)/dx$
- $d/d\mathbf{X}$  ( $\mathbf{y}$ ) is a matrix whose ( $i,j$ ) element is  $dy/dx(i,j)$

Note that the Hermitian transpose is not used because complex conjugates are not analytic.

In the expressions below matrices and vectors  $\mathbf{A}$ ,  $\mathbf{B}$ ,  $\mathbf{C}$  do not depend on  $\mathbf{X}$ .

## Derivatives of Linear Products

- $d/dx$  ( $\mathbf{AYB}$ ) =  $\mathbf{A} * d/dx$  ( $\mathbf{Y}$ ) \*  $\mathbf{B}$ 
  - $d/dx$  ( $\mathbf{Ay}$ ) =  $\mathbf{A} * d/dx$  ( $\mathbf{y}$ )
- $d/d\mathbf{x}$  ( $\mathbf{x}^T \mathbf{A}$ ) =  $\mathbf{A}$ 
  - $d/d\mathbf{x}$  ( $\mathbf{x}^T$ ) =  $\mathbf{I}$
  - $d/d\mathbf{x}$  ( $\mathbf{x}^T \mathbf{a}$ ) =  $d/d\mathbf{x}$  ( $\mathbf{a}^T \mathbf{x}$ ) =  $\mathbf{a}$
- $d/d\mathbf{X}$  ( $\mathbf{a}^T \mathbf{X} \mathbf{b}$ ) =  $\mathbf{ab}^T$ 
  - $d/d\mathbf{X}$  ( $\mathbf{a}^T \mathbf{X} \mathbf{a}$ ) =  $d/d\mathbf{X}$  ( $\mathbf{a}^T \mathbf{X}^T \mathbf{a}$ ) =  $\mathbf{aa}^T$
- $d/d\mathbf{X}$  ( $\mathbf{a}^T \mathbf{X}^T \mathbf{b}$ ) =  $\mathbf{ba}^T$
- $d/dx$  ( $\mathbf{YZ}$ ) =  $\mathbf{Y} * d/dx$  ( $\mathbf{Z}$ ) +  $d/dx$  ( $\mathbf{Y}$ ) \*  $\mathbf{Z}$

## Derivatives of Quadratic Products

- $d/dx$  ( $\mathbf{Ax+b}$ )<sup>T</sup>  $\mathbf{C}(\mathbf{Dx+e})$  =  $\mathbf{A}^T \mathbf{C}(\mathbf{Dx+e})$  +  $\mathbf{D}^T \mathbf{C}^T (\mathbf{Ax+b})$ 
  - $d/d\mathbf{x}$  ( $\mathbf{x}^T \mathbf{C} \mathbf{x}$ ) =  $(\mathbf{C} + \mathbf{C}^T) \mathbf{x}$ 
    - **[C: symmetric]:**  $d/d\mathbf{x}$  ( $\mathbf{x}^T \mathbf{C} \mathbf{x}$ ) =  $2\mathbf{C} \mathbf{x}$
    - $d/d\mathbf{x}$  ( $\mathbf{x}^T \mathbf{x}$ ) =  $2\mathbf{x}$
  - $d/d\mathbf{x}$  ( $\mathbf{Ax+b}$ )<sup>T</sup> ( $\mathbf{Dx+e}$ ) =  $\mathbf{A}^T (\mathbf{Dx+e})$  +  $\mathbf{D}^T (\mathbf{Ax+b})$

- $d/dx (\mathbf{Ax+b})^T (\mathbf{Ax+b}) = 2\mathbf{A}^T (\mathbf{Ax+b})$ 
    - **[C: symmetric]:**  $d/dx (\mathbf{Ax+b})^T \mathbf{C} (\mathbf{Ax+b}) = 2\mathbf{A}^T \mathbf{C} (\mathbf{Ax+b})$
- $d/d\mathbf{X} (\mathbf{a}^T \mathbf{X}^T \mathbf{Xb}) = \mathbf{X} (\mathbf{ab}^T + \mathbf{ba}^T)$ 
  - $d/d\mathbf{X} (\mathbf{a}^T \mathbf{X}^T \mathbf{Xa}) = 2\mathbf{Xaa}^T$
- $d/d\mathbf{X} (\mathbf{a}^T \mathbf{X}^T \mathbf{CXb}) = \mathbf{C}^T \mathbf{Xab}^T + \mathbf{CXba}^T$ 
  - $d/d\mathbf{X} (\mathbf{a}^T \mathbf{X}^T \mathbf{CXa}) = (\mathbf{C} + \mathbf{C}^T) \mathbf{Xaa}^T$
  - **[C:Symmetric]**  $d/d\mathbf{X} (\mathbf{a}^T \mathbf{X}^T \mathbf{CXa}) = 2\mathbf{CXaa}^T$
- $d/d\mathbf{X} ((\mathbf{Xa+b})^T \mathbf{C} (\mathbf{Xa+b})) = (\mathbf{C} + \mathbf{C}^T) (\mathbf{Xa+b}) \mathbf{a}^T$

## Derivatives of Cubic Products

- $d/dx (\mathbf{x}^T \mathbf{Axx}^T) = (\mathbf{A} + \mathbf{A}^T) \mathbf{xx}^T + \mathbf{x}^T \mathbf{AxI}$

## Derivatives of Inverses

- $d/dx (\mathbf{Y}^{-1}) = -\mathbf{Y}^{-1} d/dx (\mathbf{Y}) \mathbf{Y}^{-1}$

## Derivative of Trace

Note: matrix dimensions must result in an  $n*n$  argument for  $\text{tr}()$ .

- $d/d\mathbf{X} (\text{tr}(\mathbf{X})) = \mathbf{I}$
- $d/d\mathbf{X} (\text{tr}(\mathbf{X}^k)) = k(\mathbf{X}^{k-1})^T$
- $d/d\mathbf{X} (\text{tr}(\mathbf{AX}^k)) = \text{SUM}_{r=0:k-1} (\mathbf{X}^r \mathbf{A} \mathbf{X}^{k-r-1})^T$
- $d/d\mathbf{X} (\text{tr}(\mathbf{AX}^{-1} \mathbf{B})) = -(\mathbf{X}^{-1} \mathbf{B} \mathbf{A} \mathbf{X}^{-1})^T$ 
  - $d/d\mathbf{X} (\text{tr}(\mathbf{AX}^{-1})) = d/d\mathbf{X} (\text{tr}(\mathbf{X}^{-1} \mathbf{A})) = -\mathbf{X}^{-T} \mathbf{A}^T \mathbf{X}^{-T}$
- $d/d\mathbf{X} (\text{tr}(\mathbf{A}^T \mathbf{XB}^T)) = d/d\mathbf{X} (\text{tr}(\mathbf{BX}^T \mathbf{A})) = \mathbf{AB}$ 
  - $d/d\mathbf{X} (\text{tr}(\mathbf{XA}^T)) = d/d\mathbf{X} (\text{tr}(\mathbf{A}^T \mathbf{X})) = d/d\mathbf{X} (\text{tr}(\mathbf{X}^T \mathbf{A})) = d/d\mathbf{X} (\text{tr}(\mathbf{AX}^T)) = \mathbf{A}$
- $d/d\mathbf{X} (\text{tr}(\mathbf{AXBX}^T)) = \mathbf{A}^T \mathbf{XB}^T + \mathbf{AXB}$ 
  - $d/d\mathbf{X} (\text{tr}(\mathbf{XAX}^T)) = \mathbf{X}(\mathbf{A} + \mathbf{A}^T)$
  - $d/d\mathbf{X} (\text{tr}(\mathbf{X}^T \mathbf{AX})) = \mathbf{X}^T (\mathbf{A} + \mathbf{A}^T)$
  - $d/d\mathbf{X} (\text{tr}(\mathbf{AX}^T \mathbf{X})) = (\mathbf{A} + \mathbf{A}^T) \mathbf{X}$
- $d/d\mathbf{X} (\text{tr}(\mathbf{AXBX})) = \mathbf{A}^T \mathbf{X}^T \mathbf{B}^T + \mathbf{B}^T \mathbf{X}^T \mathbf{A}^T$
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- **[C:symmetric]**  $d/d\mathbf{X} (\text{tr}((\mathbf{X}^T \mathbf{CX})^{-1} \mathbf{A})) = d/d\mathbf{X} (\text{tr}(\mathbf{A} (\mathbf{X}^T \mathbf{CX})^{-1})) = -(\mathbf{CX}(\mathbf{X}^T \mathbf{CX})^{-1})(\mathbf{A} + \mathbf{A}^T)(\mathbf{X}^T \mathbf{CX})^{-1}$
- **[B,C:symmetric]**  $d/d\mathbf{X} (\text{tr}((\mathbf{X}^T \mathbf{CX})^{-1} (\mathbf{X}^T \mathbf{BX}))) = d/d\mathbf{X} (\text{tr}(\mathbf{X}^T \mathbf{BX})(\mathbf{X}^T \mathbf{CX})^{-1}) =$   
 $-2(\mathbf{CX}(\mathbf{X}^T \mathbf{CX})^{-1}) \mathbf{X}^T \mathbf{BX} (\mathbf{X}^T \mathbf{CX})^{-1} + 2\mathbf{BX} (\mathbf{X}^T \mathbf{CX})^{-1}$
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## Derivative of Determinant

Note: matrix dimensions must result in an  $n*n$  argument for  $\text{det}()$ .

- $d/d\mathbf{X} (\text{det}(\mathbf{X})) = d/d\mathbf{X} (\text{det}(\mathbf{X}^T)) = \text{det}(\mathbf{X}) * \mathbf{X}^{-T}$ 
  - $d/d\mathbf{X} (\text{det}(\mathbf{AXB})) = \text{det}(\mathbf{AXB}) * \mathbf{X}^{-T}$

- $d/d\mathbf{X} (\ln(\det(\mathbf{AXB}))) = \mathbf{X}^{-T}$
- $d/d\mathbf{X} (\det(\mathbf{X}^k)) = k \det(\mathbf{X}^k) \mathbf{X}^{-T}$ 
  - $d/d\mathbf{X} (\ln(\det(\mathbf{X}^k))) = k \mathbf{X}^{-T}$
- **[Real]**  $d/d\mathbf{X} (\det(\mathbf{X}^T \mathbf{C} \mathbf{X})) = \det(\mathbf{X}^T \mathbf{C} \mathbf{X}) * (\mathbf{C} + \mathbf{C}^T) \mathbf{X} (\mathbf{X}^T \mathbf{C} \mathbf{X})^{-1}$ 
  - **[C: Real, Symmetric]**  $d/d\mathbf{X} (\det(\mathbf{X}^T \mathbf{C} \mathbf{X})) = 2 \det(\mathbf{X}^T \mathbf{C} \mathbf{X}) * \mathbf{C} \mathbf{X} (\mathbf{X}^T \mathbf{C} \mathbf{X})^{-1}$
- **[C: Real, Symmetric]**  $d/d\mathbf{X} (\ln(\det(\mathbf{X}^T \mathbf{C} \mathbf{X}))) = 2 \mathbf{C} \mathbf{X} (\mathbf{X}^T \mathbf{C} \mathbf{X})^{-1}$

## Jacobian

If  $\mathbf{y}$  is a function of  $\mathbf{x}$ , then  $d\mathbf{y}^T/d\mathbf{x}$  is the Jacobian matrix of  $\mathbf{y}$  with respect to  $\mathbf{x}$ .

Its determinant,  $|d\mathbf{y}^T/d\mathbf{x}|$ , is the *Jacobian* of  $\mathbf{y}$  with respect to  $\mathbf{x}$  and represents the ratio of the hyper-volumes  $d\mathbf{y}$  and  $d\mathbf{x}$ . The Jacobian occurs when changing variables in an integration:  $\text{Integral}(f(\mathbf{y})d\mathbf{y}) = \text{Integral}(f(\mathbf{y}(\mathbf{x})) |d\mathbf{y}^T/d\mathbf{x}| d\mathbf{x})$ .

## Hessian matrix

If  $f$  is a function of  $\mathbf{x}$  then the symmetric matrix  $d^2f/d\mathbf{x}^2 = d/d\mathbf{x}^T(df/d\mathbf{x})$  is the *Hessian* matrix of  $f(\mathbf{x})$ . A value of  $\mathbf{x}$  for which  $df/d\mathbf{x} = \mathbf{0}$  corresponds to a minimum, maximum or saddle point according to whether the Hessian is positive definite, negative definite or indefinite.

- $d^2/d\mathbf{x}^2 (\mathbf{a}^T \mathbf{x}) = 0$
- $d^2/d\mathbf{x}^2 (\mathbf{Ax} + \mathbf{b})^T \mathbf{C} (\mathbf{Dx} + \mathbf{e}) = \mathbf{A}^T \mathbf{C} \mathbf{D} + \mathbf{D}^T \mathbf{C}^T \mathbf{A}$ 
  - $d^2/d\mathbf{x}^2 (\mathbf{x}^T \mathbf{C} \mathbf{x}) = \mathbf{C} + \mathbf{C}^T$ 
    - $d^2/d\mathbf{x}^2 (\mathbf{x}^T \mathbf{x}) = 2\mathbf{I}$
  - $d^2/d\mathbf{x}^2 (\mathbf{Ax} + \mathbf{b})^T (\mathbf{Dx} + \mathbf{e}) = \mathbf{A}^T \mathbf{D} + \mathbf{D}^T \mathbf{A}$ 
    - $d^2/d\mathbf{x}^2 (\mathbf{Ax} + \mathbf{b})^T (\mathbf{Ax} + \mathbf{b}) = 2\mathbf{A}^T \mathbf{A}$
  - **[C: symmetric]**:  $d^2/d\mathbf{x}^2 (\mathbf{Ax} + \mathbf{b})^T \mathbf{C} (\mathbf{Ax} + \mathbf{b}) = 2\mathbf{A}^T \mathbf{C} \mathbf{A}$

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