```
Arithmetic;
Q1 : Add two numbers 1 and 2;
1 + 2
3
Q2 : Subtruct two numbers 7 and 3;
7 – 3
Q3 : Multiply two numbers 2 and 3;
Note: For multiplication of two numbers we
   use sign \star or by using space between the two multiplied numbers;
2 * 3
\mathbf{2} \times \mathbf{3}
Q4 : Divide two numbers 2 & 3;
Note: for division we use sign /
2/3
_
3
Note:
  to get the answer in fraction we use . with any number. or use N for get the answer in fraction;
7./3
2.33333
N[7/3]
2.33333
Q5 : Factorial of number 5;
Note: for finding the factorial we can use sign! or Factorial;
5!
120
Factorial[5]
120
Q6: calculate 10 digits in 2/7;
Note: to get the number of digit by given question we can use the following form to get the
   number of digits of any number N[2/7, n] where n is number of required digits;
```

```
N[2/7, 10]
     0.2857142857
     Note: this also be done by use = ing post version symbol which used for only one
         input. but this not give the required number of digit of required question; // N \,
     2/7//N
     0.285714
     Q7 : Calculate 10 digits in Pi;
     N[Pi, 10]
     3.141592654
     Q8: calculate the square root 5 and 4 power 3.1;
     Note : to show or find the power of any number we use the hat operator \ensuremath{\,^{\wedge}}
     power;
     4^3.1
     73.5167
     5^(1/2)
     \sqrt{5}
     note: to show these square root to follow the BODMAS rule;
     N[5^(1/2), 10]
     2.236067977
     5^(1/2)//N
     2.23607
     Note: to shoe the squure root we can use the command Sqrt[x] where x is any given number;
     Q9: to show the numbers in the form of sqaure roor;
     Sqrt[Pi]
     \sqrt{\pi}
     note: to find the log or anti - log we use the command;
     ? Log
Log[z] gives the natural logarithm of z (logarithm to base e).
Log[b, z] gives the logarithm to base b. \gg
     Q10 : calculate ln3 .1 and log [3, 9];
     Log[3.1]
     1.1314
     Log[3, 9]
     Q11: calculate the log;
```

```
7^Log[7, 11]
11
Log[5, 5<sup>19</sup>]
19
Note: to find the answer for trignometirx functions we use the built in fucntions,
like Cos[30 Degree] or Cos[Pi/6] where Degree = Pi/180;
Q12 : find the answer ;
Cos[30 * Pi / 180]
Cos[Pi / 6]
\frac{\sqrt{3}}{2}
Cos[30 * Degree]
? Degree
```

Degree gives the number of radians in one degree. It has a numerical value of  $\frac{\pi}{180}$ .  $\gg$ 

```
Q13 : find inverse trignometric functions in degree;
Note : we use the command ArcSin[x] where x is any given value;
ArcCos[1/2]/Degree
 π
3 °
Q14 : find inverse trignometric functions in degree and in decimal points;
N[ArcCos[1/2]/Degree]
60.
N[ArcSin[1/2]/Degree]
30.
ArcCos[1/2]/Degree // N
60.
Topic: Order of operations;
note : to BODMAS rules;
Pi^(2/3)
\pi^{2/3}
```

6

9

4

```
5^(3 Ie)
5<sup>3 Ie</sup>
I^((3/2) + Pi)
1^{\frac{3}{2}+\pi}
Pi^(3/2I)
12 Pi * I / (((Pi + 2) ^I / (4 Pi)) + 5 I)
  12 i π
5 i + \frac{(2+\pi)^{i}}{4\pi}
-\sin[2 + Pi * I] / ((Pi + 1)^2 / (8e) + 2e^3)^(3/2)
Topic : Expression;
x = 2
2
Q15: what is output;
x = 2; y = 3; ab = 5
x = 2; y = 3; xy = 5
x = 2; y = 3; x * y
x = 2
y = 4
2
x = 2; y = 3; x * y; Print[x * y]
x = 2; y = 3; x * y; x = 3; Print[x * y]
x = 2; y = 3; x * y; x = 4; Print[x]
Topic : Loops;
```

Note: for loops we use the command Do and For and to display the values of the lop we use the command Print[x] where x is any number whose we want to print the value;

```
? Do
```

```
Do[expr, \{i_{max}\}] evaluates expr\ i_{max} times.
Do[expr, \{i, i_{max}\}] evaluates expr with the variable i successively taking on the values 1 through i_{max} (in steps of 1).
Do[expr, {i, i_{min}, i_{max}}] starts with i = i_{min}.
Do[expr, {i, i_{min}, i_{max}, di}] uses steps di.
Do[expr, \{i, \{i_1, i_2, ...\}\}] uses the successive values i_1, i_2, ...
Do[expr, \{i, i_{min}, i_{max}\}, \{j, j_{min}, j_{max}\}, \dots] evaluates expr looping over different values of j, etc. for each i. \gg
```

? For

For[start, test, incr, body] executes start, then repeatedly evaluates body and incr until test fails to give True. >>

```
Do[2i, \{i, 1, 4\}] // in this example we cant disply
          the number of this loop because we not use commadn Print[x] here;
      Do[Print[2i], {i, 1, 4}]
2
4
6
8
      Q16: generate all elements of the sequence a1 = 2.1, a2 = 6, a3 = 5,
      and the sequence is that a1 = i^2 + i for i = 1, 2, 3, \ldots, 12;
      a[1] = 2.1; a[2] = 6; a[3] = 5; Do[Print[i^2 + i], {i, 1, 12}]
2
6
12
20
30
42
56
72
90
110
132
156
      Q17 : generate all elements of the sequence a1 = 2.1,
      a2 = 6, a3 = 5, and the sequence is that a[i] for i = 1, 2, 3;
      a[1] = 2.1; a[2] = 6; a[3] = 5; Do[Print[a[i]], {i, 1, 3}]
```

```
5
      {\tt Q18} : generate all elements of the sequence given by the starter formula a1 =
       2 and the recursion formula a[i+1] = 2 ai - 3 for i = 1, 2, 3, ... .12;
      a[1] = 2
      Do[Print[2a[i]-3], {i, 1, 12}]
1
-1
- 5
-13
-29
-61
-125
-253
-509
-1021
-2045
-4093
      this question also be done by;
      a[1] = 2
      a[i+1] = 2a[i] - 3; Do[Print[a[i+1]], {i, 1, 12}]
1
-1
- 5
-13
-29
-61
-125
-253
-509
-1021
-2045
-4093
      Topic : Genrating a list and a list of lists; rows, columns and matrices;
      Note: to generate a list of numbers we use the commnad Table,
      which represent each number separated by commas in {}; you can check the command Table and Do;
```

```
? Do
```

 $\begin{pmatrix} -1 & 6.7 \\ -\pi & i \end{pmatrix}$ 

```
Do[expr, \{i_{max}\}] evaluates expr\ i_{max} times.
Do[expr, \{i, i_{max}\}] evaluates expr with the variable i successively taking on the values 1 through i_{max} (in steps of 1).
Do[expr, {i, i_{min}, i_{max}}] starts with i = i_{min}.
Do[expr, {i, i_{min}, i_{max}, di}] uses steps di.
Do[expr, {i, {i<sub>1</sub>, i<sub>2</sub>, ...}}] uses the successive values i<sub>1</sub>, i<sub>2</sub>, ....
Do[expr, \{i, i_{min}, i_{max}\}, \{j, j_{min}, j_{max}\}, ...] evaluates expr looping over different values of j, etc. for each i. \gg
      ? Table
Table[expr, \{i_{max}\}] generates a list of i_{max} copies of expr.
Table[expr, \{i, i_{max}\}] generates a list of the values of expr when i runs from 1 to i_{max}.
Table[expr, \{i, i_{min}, i_{max}\}] starts with i = i_{min}.
Table[expr, \{i, i_{min}, i_{max}, di\}] uses steps di.
Table[expr, \{i, \{i_1, i_2, ...\}\}] uses the successive values i_1, i_2, ...
Table[expr, \{i, i_{min}, i_{max}\}, \{j, j_{min}, j_{max}\}, \ldots] gives a nested list. The list associated with i is outermost. \gg
      you can see that comnands are same in
        patterns but the more efficient for lists are Table command;
     Q19: generate a list containing 2.1, 6 and 5;
      {2.1, 6, 5}
      \{2.1, 6, 5\}
      Q20 : generate a list containing all elements of the sequence a[i] = i^2 + i for i = 1,
      2, ....12;
      Table[i^2+1, {i, 1, 12}]
      {2, 5, 10, 17, 26, 37, 50, 65, 82, 101, 122, 145}
      Q21 : generate a list of all elements of the sequence given by the starter formula a1 =
       2 and the recursion formula a[i+1] = 2ai - 3 for i = 1, 2, 3, \ldots .12;
      note: to add the starter formula as the output value
          we use the another command with tyhe table are Append or Prepend;
      a[1] = 2; Prepend[Table[2 a[i] - 3, {i, 1, 12}], a[1]]
      \{2, 1, -1, -5, -13, -29, -61, -125, -253, -509, -1021, -2045, -4093\}
      Note: a matrix is a list of lists, i.e. a list of rows with each row being a list as above;
      Q22 : type in the matrix and display normally;
      to display the list in the form of matrix we use the commands TraditionalForm [],
      MatrixForm[], both commands yield same result;
      TraditionalForm [{{-1, 6.7}, {-Pi, I}}]
```

```
MatrixForm[{{-1, 6.7}, {-Pi, I}}]
      (-1 6.7)
      | -π i
     multiplying rows, columns and matrices;
     Q23 : multiply a column with a row;
     Note: In mathematica,
     if you have assigned the list say r (row) and assigned a list to c (coloumn),
     for this multiplication you have to type in r.c after these multiplication;
     r = \{\{5\}, \{0\}, \{-1\}\}; c = \{\{2, 7, 3\}\}; TraditionalForm[r.c]
     \begin{bmatrix} 0 & 0 & 0 \\ -2 & -7 & -3 \end{bmatrix}
     Q24 : multiply the matrix with column and row;
     Note: when we multiply a matrix with another list,
     the list appearing to the left of a dot becomes a row (multiply the matrix with row) r.m and the
       list appearing to the right of a dot becomes a column (multiply the matrix with column) m.c;
     m = \{\{1, 0, Pi\}, \{8, 3, 2\}, \{I, -5, 1.5\}\}; r = \{\{2, 7, 3\}\}; c = \{\{5\}, \{0\}, \{-1\}\}; \}
     "matirx with row"
     TraditionalForm [r.m]
     "matrix with column"
     TraditionalForm [m.c]
     matirx with row
     (58. + 3. i \quad 6. + 0. i \quad 24.7832 + 0. i)
     matrix with column
      (1.85841 + 0.i)
      38. + 0. i
     matrices with rules for elements;
     Q25 : generate a matrix containing all the elements given by a[i][j] =
      (i-1)^2j^3s[i][j] for i, j=1, 2,
     3 and display it normally where s = [i][j] is kroneckerDelta;
     to solve this question we use the command Table and put in the
        commnad TraditionalForm (first make the list and then display it normally);
     ? KroneckerDelta
KroneckerDelta[n_1, n_2, ...] gives the Kronecker delta \delta_{n_1 n_2 \dots n_r}, equal to 1 if all the n_i are equal, and 0 otherwise. \gg
      A = Table[(i-1)^2 * j^3 KroneckerDelta[i, j], \{i, 1, 3\}, \{j, 1, 3\}]; TraditionalForm[A]
```

```
0 8 0
```

Q26: generate a matrix containing all the elements given by a[i][j] = i^2 SinjPi for i, j = 1, 2, 3 and display it normally;

```
\mathtt{T} = \mathtt{Table}\left[\mathtt{i^2Sin}\left[\mathtt{j*Pi}\right],\, \{\mathtt{i},\, 1,\, 3\},\, \{\mathtt{j},\, 1,\, 3\}\right];\, \mathtt{TraditionalForm}\left[\mathtt{T}\right]
(0 \ 0 \ 0)

\left[ 
\begin{array}{ccc}
0 & 0 & 0 \\
0 & 0 & 0
\end{array}
\right]

Q27 : Generate an identity matrix of 5 cross 5;
to generate the n cross identity matrix we use the commnad
   ? IdentityMatrix
```

IdentityMatrix[n] gives the  $n \times n$  identity matrix.  $\gg$ 

```
iden = IdentityMatrix[3]; TraditionalForm[iden]
      0 1 0
      Q : geometric sequence;
      a[1] = 4
      r = 3; Do[Print[a[1] *r^i], {i, 1, 9}]
12
36
108
324
972
2916
8748
26244
78 732
      Q : Arithmetic sequence;
      a[1] = 3; r = 2
     Do[Print[a[i+1] = a[i] + r], \{i, 1, 9\}]
```

```
5
7
9
11
13
15
17
19
21
       piecewise function;
       f[x_] := 2/x/; x < 1
       f[x_{-}] := x /; 1 <= x <= 2
       f[x_] := x^2/; x > 2
       x = 2.5; f[x]
       6.25
       f[x_] := x^2; f[t]
       t<sup>2</sup>
       f[x_, y_] := x^y; f[b, 2]
       m1 = 3; m2 = 5; x1 = 2*10^-2; xc := (m1*x1+m2*x2) / (m1+m2)
       x2 = 4 * 10^{-2};
       хc
       "after repeat"
       x2 = 3 * 10^{-2};
       хc
        13
        400
       after repeat
        21
        800
       topic : symbolic representation;
       Expand [ (a + b) ^3]
       a^3 + 3 a^2 b + 3 a b^2 + b^3
       {\tt Q}: {\tt by} \ {\tt using} \ {\tt coloumb} \ {\tt '} \ {\tt s} \ {\tt law} \ {\tt total} \ {\tt flux} \ {\tt through} \ {\tt surface}
           of radius r with a charge q at its centre in terms of permitivity z;
       F = 1 / (4 Piz) (q1 q/r^2); ef = F/q1; fl = ef 4 Pir^2 Cos[0]
       f[x_] := x^2; f[x]
       x^2
```

```
f[x_] := x^2; f[3]
?_
```

or Blank[] is a pattern object that can stand for any Mathematica expression.  $\_h$  or Blank[h] can stand for any expression with head h.  $\gg$ 

?/;

patt /; test is a pattern which matches only if the evaluation of test yields True. lhs:> rhs /; test represents a rule which applies only if the evaluation of test yields True. lhs := rhs /; test is a definition to be used only if test yields True.  $\gg$ 

?If

If [condition, t, f] gives t if condition evaluates to True, and f if it evaluates to False. If [condition, t, f, u] gives u if condition evaluates to neither True nor False.  $\gg$ 

```
discussion;
x = 2; f = x^2; x = 3; f
x = 2; f := x^2; x = 3; f
c1 = 0.5 * 10^-6; c2 = 1.3 * 10^-6; ct = 1/c1 + 1/c2; 1/ct
3.61111 \times 10^{-7}
{\tt Q} : Total number of electrons passing through circuit in 2 minutes if current is 3 mA;
we use formulas is n (total number of elctrons) = I * t / e;
t = 120; i = 3 * 10^{-3}; e = 1.67 * 10^{-19}; n = i * t/e
2.15569 \times 10^{18}
functions;
?_
```

\_ or Blank[] is a pattern object that can stand for any Mathematica expression.  $\_h$  or Blank[h] can stand for any expression with head h.  $\gg$ 

?/;

patt /; test is a pattern which matches only if the evaluation of test yields True. lhs:> rhs /; test represents a rule which applies only if the evaluation of test yields True. lhs := rhs /; test is a definition to be used only if test yields True.  $\gg$ 

?If

```
If [condition, t, f] gives t if condition evaluates to True, and f if it evaluates to False.
If [condition, t, f, u] gives u if condition evaluates to neither True nor False. \gg
```

Abs[z] gives the absolute value of the real or complex number z.  $\gg$ 

```
f[x_] := x /; x >= 0
f[x_] := -x /; x < 0
f[-2] - Abs[-2]
0
? Simplify</pre>
```

Simplify[expr] performs a sequence of algebraic

and other transformations on expr, and returns the simplest form it finds.

Simplify[expr, assum] does simplification using assumptions. >>

```
calculate square root x square if x is negative;
Simplify[Sqrt[x^2], x < 0]
-x
topic: limit, differentiation and replacment rule;
? Limit</pre>
```

Limit[expr,  $x \rightarrow x_0$ ] finds the limiting value of expr when x approaches  $x_0$ .  $\gg$ 

```
? D
```

```
D[f, x] gives the partial derivative \partial f/\partial x.
D[f, \{x, n\}] gives the multiple derivative \partial^n f / \partial x^n.
D[f, x, y, ...] differentiates f successively with respect to x, y, ....
D[f, {{x_1, x_2, ...}}}] for a scalar f gives the vector derivative (\partial f/\partial x_1, \partial f/\partial x_2, ...). \gg
      \mathtt{Q1}: \mathtt{Differentiate} \ \mathtt{sin[x]} \ \mathtt{by} \ \mathtt{using} \ \mathtt{the} \ \mathtt{defination} \ \mathtt{and} \ \mathtt{built} \ \mathtt{in} \ \mathtt{commnad} \ \mathtt{differentiate} \ ;
      f[x_] := Sin[x];
       "by defination"
      \texttt{Limit}[(f[x+h]-f[x])/h, h \rightarrow 0]
      "by commnad"
      D[f[x], x]
      by defination
      Cos[x]
      by commnad
      Cos[x]
      f[x_] := -7 x^3 + 5 x^2 + 11 x - 9;
      "by definition"
      Limit[(f[x+h]-f[x])/h, h \rightarrow 0]
       "by commnad"
      D[f[x], x]
      by definition
      11 + 10 x - 21 x^2
      by commnad
      11 + 10 x - 21 x^2
      Q3 : Diffierentiate lnx at x = 1;
      D[Log[x], x]
      D[Log[x], x] /. x \rightarrow 1
      {\tt Q4}:{\tt Find} the expression as well as SI values of angular velocity,
      angular accelration, tangentional velocity, tangentional accelration,
```

and radial accelration for given equation, with r = 2 (meter) and t = 3 (sec);

```
th = 4 t^3 - 2 t^2 + 5 t - 9;
"w expression"
w = D[th, t]
"w value"
w/.t\rightarrow 3
"alpha expression"
alpha = D[w, t]
"alpha value"
alpha /. t \rightarrow 3
"tang speed expression"
vt = rw
"tang speed value"
vt/.r \rightarrow 2/.t \rightarrow 3
"tang alpha expression"
at = ralpha
"tang alpha value"
at /. r \rightarrow 2 /. t \rightarrow 3
"radial accel expression"
ar = vt^2/r
"radial accel value"
ar/.r \rightarrow 2/.t \rightarrow 3
w expression
5 - 4 t + 12 t^2
w value
101
alpha expression
-4 + 24 t
alpha value
tang speed expression
r (5 - 4 t + 12 t^2)
tang speed value
202
tang alpha expression
r(-4 + 24 t)
tang alpha value
136
radial accel expression
r (5 - 4 t + 12 t^2)^2
radial accel value
20 402
```

```
Q5 : find limit;
      Limit[x/x, x \rightarrow 0]
      1
      Q6 : Q : Use lagrane and Euler lagrange 's;
      note: to solve this question we use the command ?D and ?';
       L = 1/2m * x'[t]^2 - V[x[t]]; D[L, x[t]] - D[D[L, x'[t]], t]/. x''[t] \rightarrow a/. -V'[x[t]] \rightarrow F
      F - a m
      ? D
D[f, x] gives the partial derivative \partial f/\partial x.
D[f, \{x, n\}] gives the multiple derivative \partial^n f / \partial x^n.
D[f, x, y, ...] differentiates f successively with respect to x, y, ....
D[f, \{\{x_1, x_2, ...\}\}] for a scalar f gives the vector derivative (\partial f/\partial x_1, \partial f/\partial x_2, ...). \gg
      note: to solve the question 1 we use the 2 nd property
          of Do command D[f, {x, n}] gives the multiple derivative \partial^n f / \partial x^n;
      Q: Demonstrate that both x =
         ACos[wt] + BSin[wt] and x = cSin[wt] are solution of D[x, \{t, 2\}] + w^2 * t;
      x = c * Sin[w * t + phi]; D[x, {t, 2}] + x * (w^2)
      0
      "there was a small mistake in following program do yourself";
      x = A * Cos[w*t] + B * Sin[w*t]; D[x, {t, 2}] + x * (w^2)
      -Aw^2 Cos[tw] - Bw^2 Sin[tw] + w^2 (A Cos[tw] + B Sin[tw])
      topic : graphing function;
      ? D
D[f, x] gives the partial derivative \partial f/\partial x.
D[f, \{x, n\}] gives the multiple derivative \partial^n f / \partial x^n.
D[f, x, y, ...] differentiates f successively with respect to x, y, ....
D[f, {{x_1, x_2, ...}}}] for a scalar f gives the vector derivative (\partial f/\partial x_1, \partial f/\partial x_2, ...). \gg
      Q1 : Demonstarte psi = ACos[kx - w * t + phi] is a solution
```

of classical wave equation and make its graph and simulate its graph;

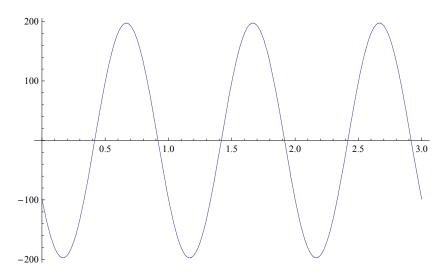
 $10 \pi \cos [30 \circ + 2 \pi t]$  "velocity plot"

```
w = k * v; psi = ACos[k * x - w * t + phi]; D[psi, {x, 2}] - 1 / v^2 D[psi, {t, 2}]
0
note: to solve the question 1 we use the 2 nd property
   of Do command D[f, {x, n}] gives the multiple derivative \partial^n \mathbf{f} / \partial \mathbf{x}^n;
Q2 : graph the position,
velocity and accelration for a one - dimensional SHO for the interval 0 \leq
 t \leq 3\,. take the amplitude of the motion to be 5 units,
angular frequency 2 Pi radians adn the phase constant phi to be 30 Degree;
c = 5; w = 2 Pi; phi = 30 Degree;
"position"
x = c * Sin[w * t + phi]
"position plot"
Plot[x, {t, 0, 3}]
"velocity"
v = D[x, t]
"velocity plot"
Plot[a, {t, 0, 3}]
"accelration"
a = D[x, \{t, 2\}]
"accelration plot"
Plot[a, {t, 0, 3}]
"position"
5 \sin[30^{\circ} + 2\pi t]
"position plot"
 2
                                            2.0
                                                                  3.0
            0.5
                       1.0
                                  1.5
                                                       2.5
-4
"velocity"
```

"accelration"

 $-20 \pi^2 \sin[30 \circ + 2 \pi t]$ 

"accelration plot"



? Plot

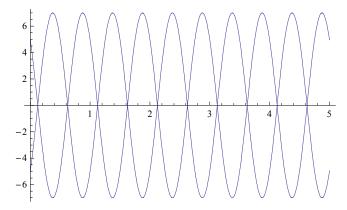
Plot[f, {x,  $x_{min}$ ,  $x_{max}$ }] generates a plot of f as a function of x from  $x_{min}$  to  $x_{max}$ . Plot[{ $f_1$ ,  $f_2$ , ...}, {x,  $x_{min}$ ,  $x_{max}$ }] plots several functions  $f_i$ .  $\gg$ 

A = 5; w = 2 Pi; phi = 30 Degree;  $Animate[Plot[ACos[k*x-w*t+phi], {x, 0, 3}], {t, 0, 3}]$ 

Q4 : for 0  $\leq$  x  $\leq$  5 meters and a wave with amplitude 7 units, wave number 2 Pi radians / meter, angular frequuency Pi radian / sec and phase constant 45 Degree for t =

1 and t = 2 seconds. Disply bothe the graphs together;

```
 t = 1; A = 7; k = 2 Pi; w = Pi; phi = 45 Degree; g1 = Plot[A * Cos[k * x - w * t + phi], \{x, 0, 5\}]; \\ t = 2; g2 = Plot[A * Cos[k * x - w * t + phi], \{x, 0, 5\}]; Show[g1, g2]
```



note : to show the both graphs we use the command ?Show;

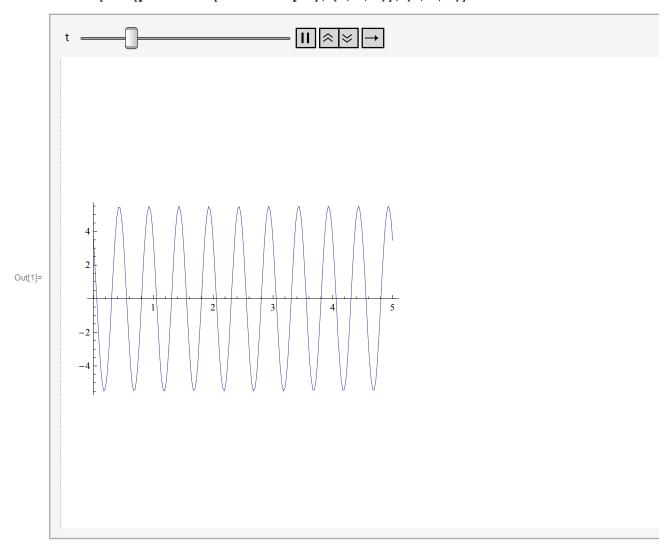
? Show

Show[graphics, options] shows graphics with the specified options added. Show[ $g_1, g_2, ...$ ] shows several graphics combined.  $\gg$ 

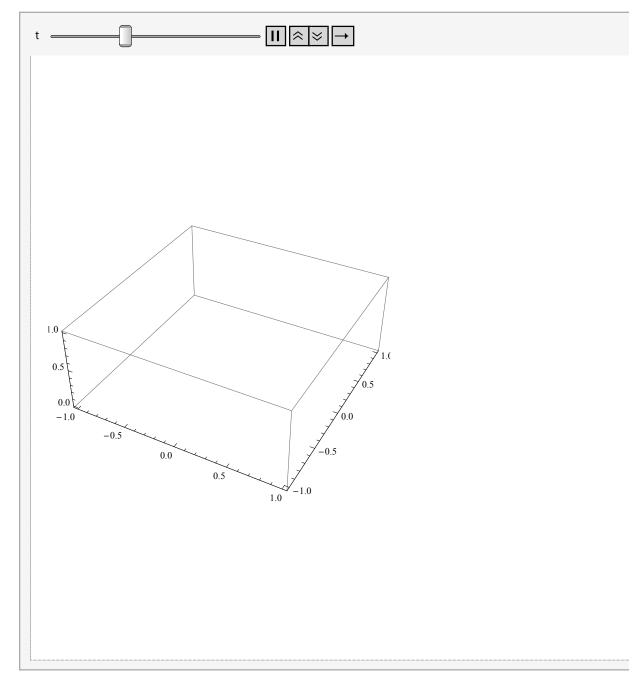
topic : Simulations;

to simulate the graph we use the command  ${\tt Animate}\:;$ 

ln[1]:= w = Pi; k = 4 Pi; A = 5.5; phi = 0;Animate[Plot[psi =  $A * Cos[k * x - w * t + phi], \{x, 0, 5\}], \{t, 1, 5\}]$ 

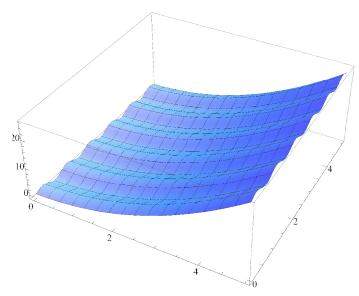


 $w = 3 \text{ Pi; } kx = 2; ky = 3; A = 7; phi = 45; \\ \text{Animate}[\text{Plot3D}[\sin[kx * x + ky * y - w * t + phi], {x, 1, 3}, {y, 0, 4}], {t, 0, 2}]$ 



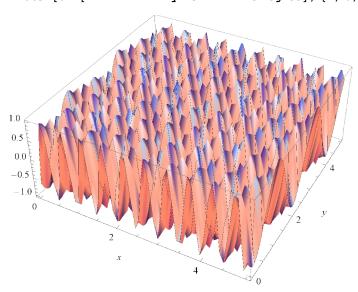
Q : for 0  $\leq$  x <= 5; 0  $\leq$  y <= 5; graph x62 + Sin7y;

 ${\tt Plot3D}\,[\,x\,{}^{\smallfrown}2\,+\,{\tt Sin}\,[\,7\,\,y\,]\,\,,\,\,\{\,x\,,\,\,0\,,\,\,5\,\}\,\,,\,\,\{\,y\,,\,\,0\,,\,\,5\,\}\,]$ 

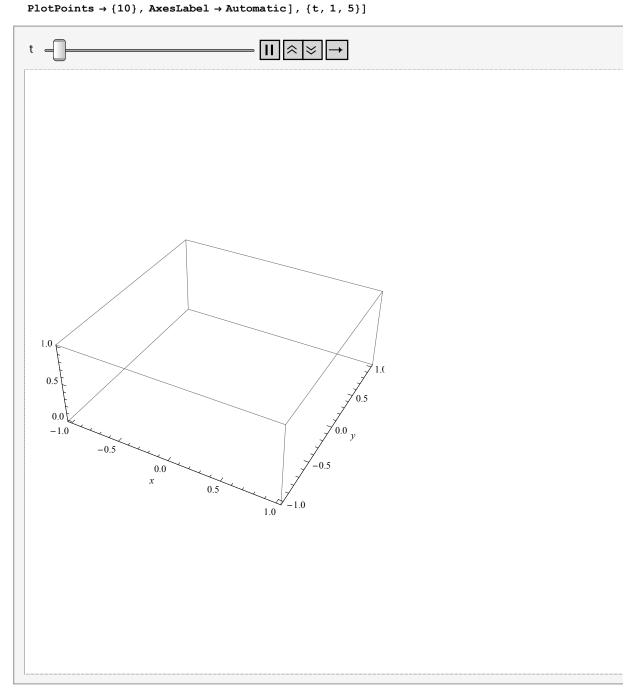


Q: for  $0 \le x \le 5$ ;  $0 \le y \le 5$ ; graph a wave function with amplitude 7 units, wave vector - 4 Pii + Pij radians / meter, angular frequency 3 Pi radians / s and phase constant 45 degree . label  ${\bf x}$  and  ${\bf y}$  axis.

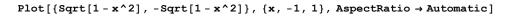
 $\texttt{Plot3D}\left[\texttt{Sin}\left[-4\ \texttt{Pi} \star \texttt{x} + \texttt{Pi} \star \texttt{y} - 3\ \texttt{Pi} \star \texttt{1} + 45\ \texttt{Degree}\right], \ \{\texttt{x},\ \texttt{0},\ \texttt{5}\},\ \{\texttt{y},\ \texttt{0},\ \texttt{5}\},\ \texttt{AxesLabel} \rightarrow \texttt{Automatic}\right]$ 

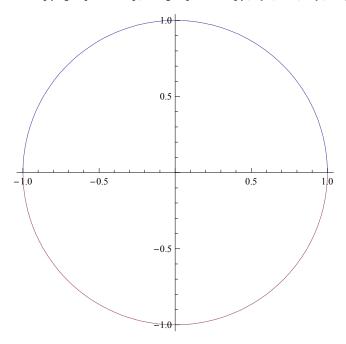


**Q**:

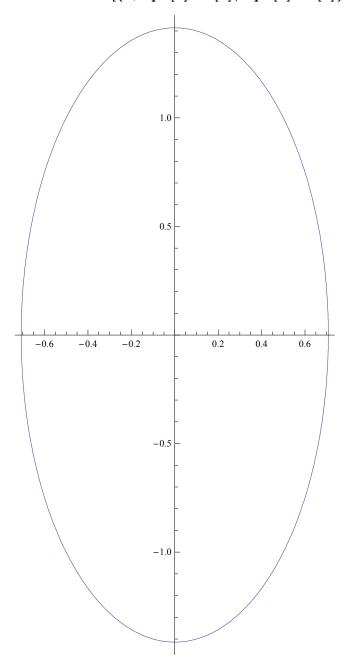


```
Q1 : Demonstarte psi = ACos[kx - w * t + phi] is a solution
    of classical wave equation and make its graph and simulate its graph;
w = k * v; psi = ACos[k * x - w * t + phi]; D[psi, {x, 2}] - 1/v^2 D[psi, {t, 2}]
0
topic : parametric equations and plots;
Q : manually solve for y and graph x^2 + y^2 = 1;
```



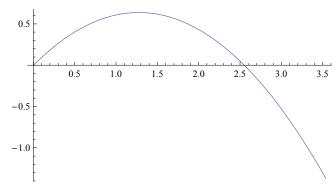


Q : use a parameter and parametric equations to graph 2  $x^2 + 1/2 y^2 = 1$ ;



 ${\tt Q} : {\tt parametric\ plot\ for\ projectile\ motion}\,;$ 

v = 5; thi = 45 Degree; g = 9.8;  $Parametric Plot \, [\, \{v * t * Cos[thi]\,,\, v * t * Sin[thi]\, - 1\,/\, 2\, g * t^2\}\,,\, \{t,\, 0\,,\, 1\}\,]$ 



topic : contourPlot;

? ContourPlot

?Plot3D

ContourPlot[f, {x,  $x_{min}$ ,  $x_{max}$ }, {y,  $y_{min}$ ,  $y_{max}$ }] generates a contour plot of f as a function of x and y.  $\mathsf{ContourPlot}[f == g, \{x, \, x_{\min}, \, x_{\max}\}, \, \{y, \, y_{\min}, \, y_{\max}\}] \; \mathsf{plots} \; \mathsf{contour} \; \mathsf{lines} \; \mathsf{for} \; \mathsf{which} \; f = g.$  $\mathsf{ContourPlot}[\{f_1 == g_1, \ f_2 == g_2, \ \ldots\}, \ \{x_i, \ x_{\mathit{min}}, \ x_{\mathit{max}}\}, \ \{y_i, \ y_{\mathit{min}}, \ y_{\mathit{max}}\}] \ \mathsf{plots} \ \mathsf{several} \ \mathsf{contour} \ \mathsf{lines}. \ \gg$ 

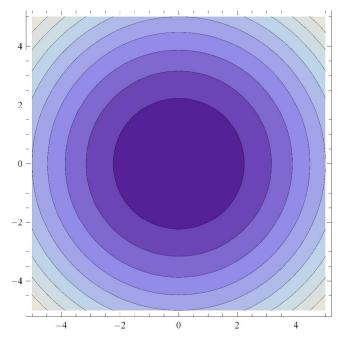
Note: ContourPlot commnad is exactly is same as that of Plot3D commnad which is used for two variables. to do the questions  $% \left( 1\right) =\left( 1\right) \left( 1\right) \left($ for ContourPlot we just replace the Plot3D comad with the ContourPlot;

Plot3D[f, {x,  $x_{min}$ ,  $x_{max}$ }, {y,  $y_{min}$ ,  $y_{max}$ }] generates a three-dimensional plot of f as a function of x and y. Plot3D[ $\{f_1, f_2, ...\}$ ,  $\{x_i, x_{min}, x_{max}\}$ ,  $\{y_i, y_{min}, y_{max}\}$ ] plots several functions.  $\gg$ 

Q1 : draw a regions / curves in  $\{x, -5, 5\}$ ,  $\{y, -5, 5\}$  oor the surface  $x^2 + y^2$ ;

Hint: to solve this question we use the first help from the ContourPlot commnad;

ContourPlot  $[x^2 + y^2, \{x, -5, 5\}, \{y, -5, 5\}]$ 



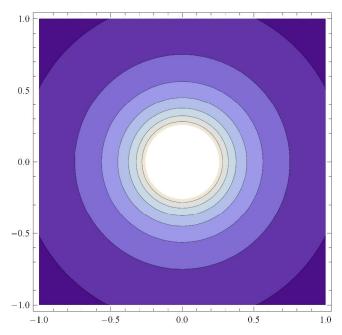
Q2 : Show regions in  $\{x, -1, 1\}$ ,

 $\{y, -1, 1\}$  of different values of electric potential around a static charge of  $5*10^-9$  C;

## Hint

to solve this question we use the formula of electric potential which related the given data;

 $k = 9*10^9; \ q = 5*10^-9; \ ContourPlot[1/Sqrt[x^2+y^2] \ k*q, \ \{x, -1, 1\}, \ \{y, -1, 1\}]$ 

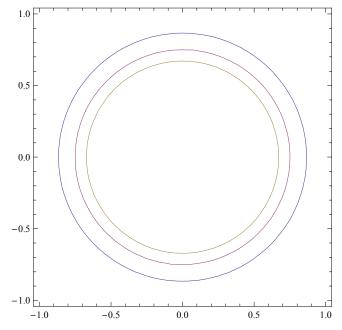


Q3 : draw in  $\{x, -1, 1\}$ ,  $\{y, -1, 1\}$  lines of magnitudes of electric field as 60, 80 and 100 N/C around a static charge of  $5*10^-9$  C;

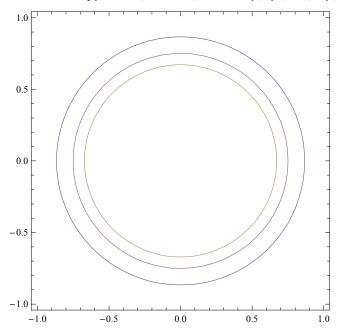
Hint: to solve this question for the different

values of electric field we use the third help of ContourPlot commnad;

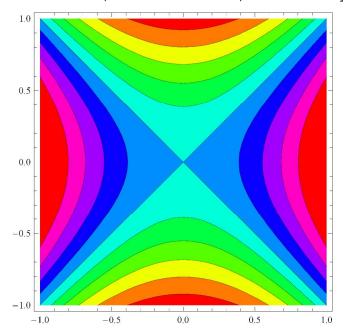
 $k = 9 * 10^9; q = 5 * 10^-9;$  $\texttt{ContourPlot}\left[\left\{1 \; / \; (\textbf{x}^2 + \textbf{y}^2) \; k * q == 60 \; , \; 1 \; / \; (\textbf{x}^2 + \textbf{y}^2) \; k * q == 80 \; , \; 1 \; / \; (\textbf{x}^2 + \textbf{y}^2) \; k * q == 100 \right\} \; ,$ {x, -1, 1}, {y, -1, 1}]



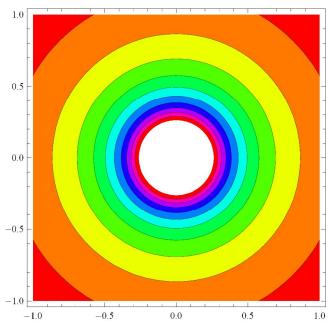
 $f = 1 / (x^2 + y^2) k * q; k = 9 * 10^9; q = 5 * 10^-9;$ ContourPlot[ $\{f == 60, f == 80, f == 100\}, \{x, -1, 1\}, \{y, -1, 1\}$ ]



 ${\tt HInt: to increase \ the \ number \ of \ contours \ ,}$ colour the contrours and points we use the following typings; ContourPlot[ $Sin[x^2 - y^2]$ ,  $\{x, -1, 1\}$ ,  $\{y, -1, 1\}$ , Contours  $\rightarrow$  10, ColorFunction  $\rightarrow$  Hue, PlotPoints  $\rightarrow$  5]



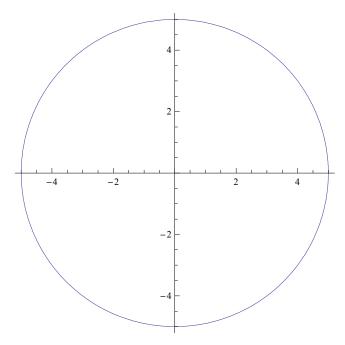
 $k = 9*10^9; \; q = 5*10^-9; \; ContourPlot[1/Sqrt[x^2+y^2] \; k*q,$  $\{x, -1, 1\}, \{y, -1, 1\}, Contours \rightarrow 10, ColorFunction \rightarrow Hue]$ 



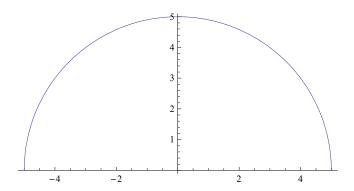
Topic : PolarPlot;

 ${\tt Q}: {\tt using polar coordinates graph \ the \ circle \ and \ half \ of \ the \ circle \ radius \ of \ 5 \ meters};$ 

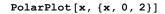
## ${\tt PolarPlot[5, \{\theta, 0, 2\,Pi\}]}$

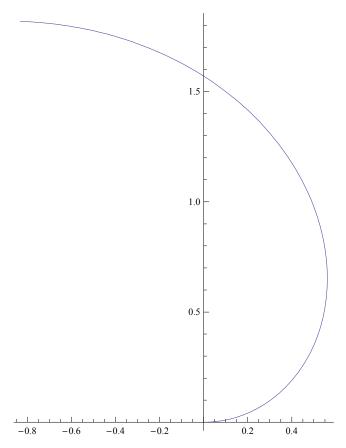


## PolarPlot[5, {thi, 0, Pi}]



Topic : LogPlot;





Topic : grphic data;

Note: to show the data like points we sue the commnad ListPlot[]; to join the points we use the commnad ListLinePlot[];

?ListPlot

ListPlot[ $\{y_1, y_2, ...\}$ ] plots points corresponding to a list of values, assumed to correspond to x coordinates 1, 2, .... ListPlot[ $\{\{x_1, y_1\}, \{x_2, y_2\}, ...\}$ ] plots a list of points with specified x and y coordinates. ListPlot[ $\{list_1, list_2, ...\}$ ] plots several lists of points.  $\gg$ 

## ?ListLinePlot

ListLinePlot[ $\{y_1, y_2, ...\}$ ] plots a line through a list of values, assumed to correspond to x coordinates 1, 2, .... ListLinePlot[ $\{x_1, y_1\}, \{x_2, y_2\}, ...\}$ ] plots a line through specific x and y positions. ListLinePlot[ $\{list_1, list_2, ...\}$ ] plots several lines.  $\gg$ 

Q1 : graph  $(0.1,\,2.3)$  ,  $(0.7,\,3.1)$  ,  $(1.1,\,2.7)$  , and also a set of line joining them. display both graphs together;

```
{\tt g1 = ListPlot[\{\{0.1,\,2.3\},\,\{0.7,\,3.1\},\,\{1.1,\,2.7\}\}]\,;}
\tt g2 = ListLinePlot[\{\{0.1,\,2.3\}\,,\,\{0.7,\,3.1\}\,,\,\{1.1,\,2.7\}\}]\,;\,Show[g1,\,g2]
```

