Making High-Performance Robots Safe and Easy to Use for an Introduction to Computing

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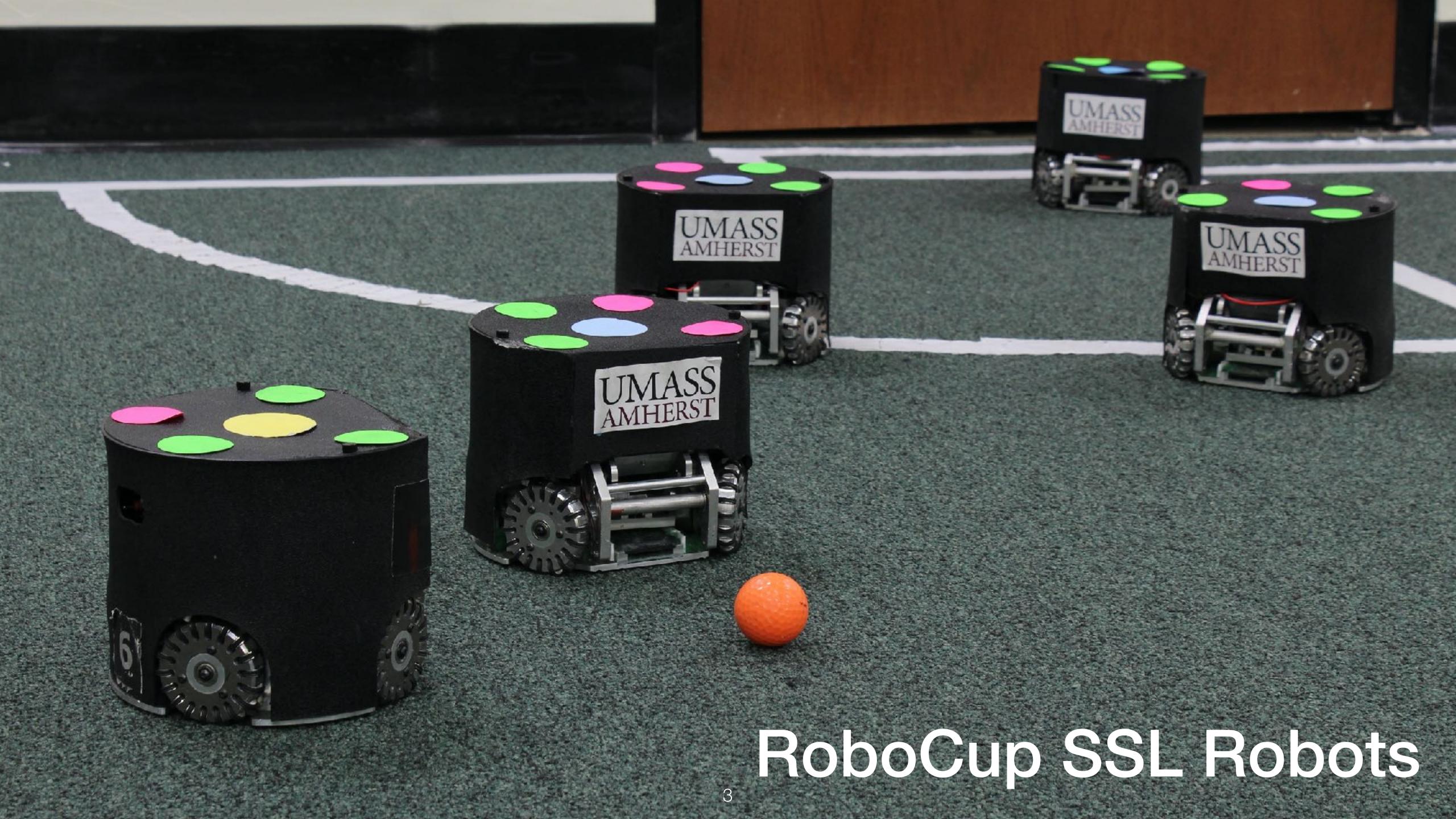
Robots for Education

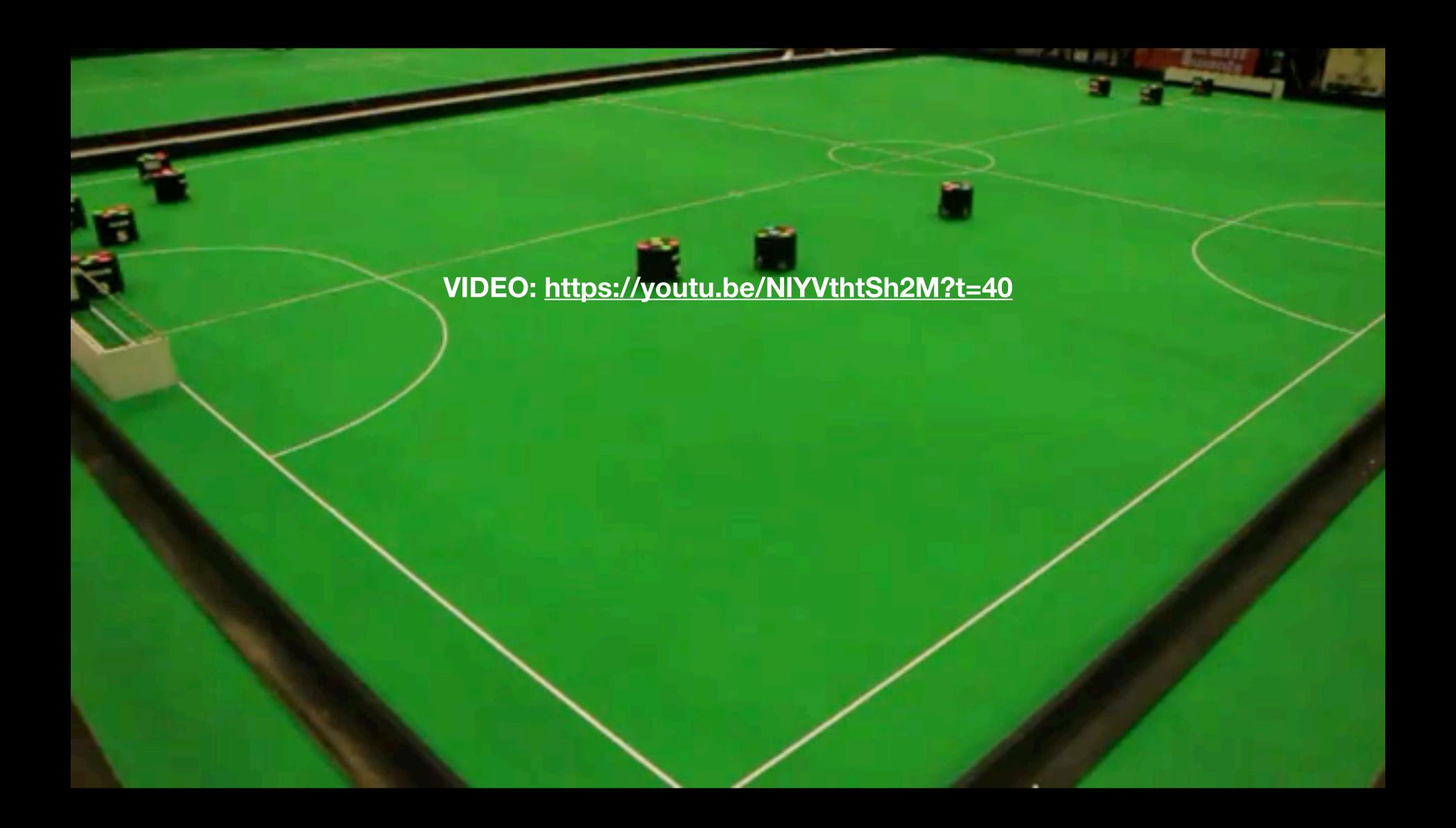
Robots serve as a popular medium to introduce computing:

Hands-on for increased engagement

A tool for teaching an array of STEM subjects







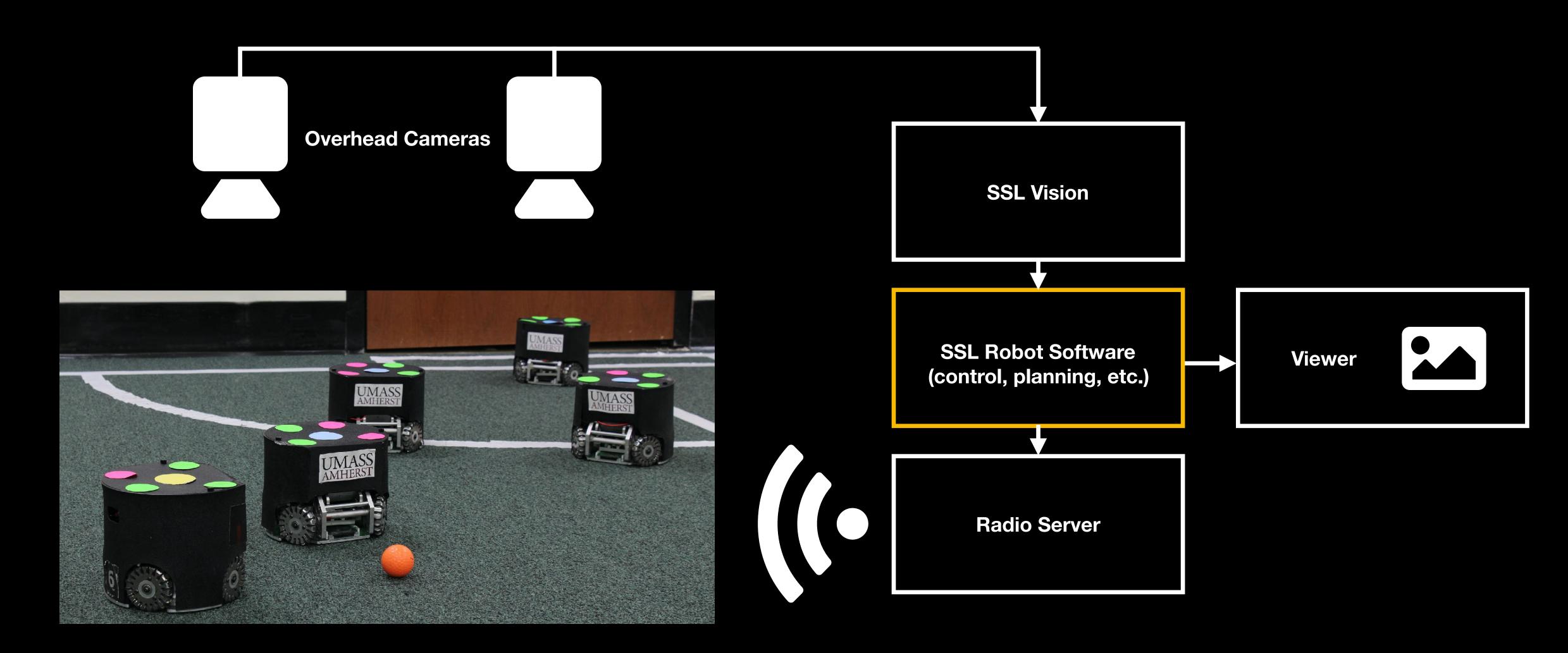
SSL Robot Software

- Optimized, high-performance C++
- Multi-threading and minimal dynamic memory allocation for speed

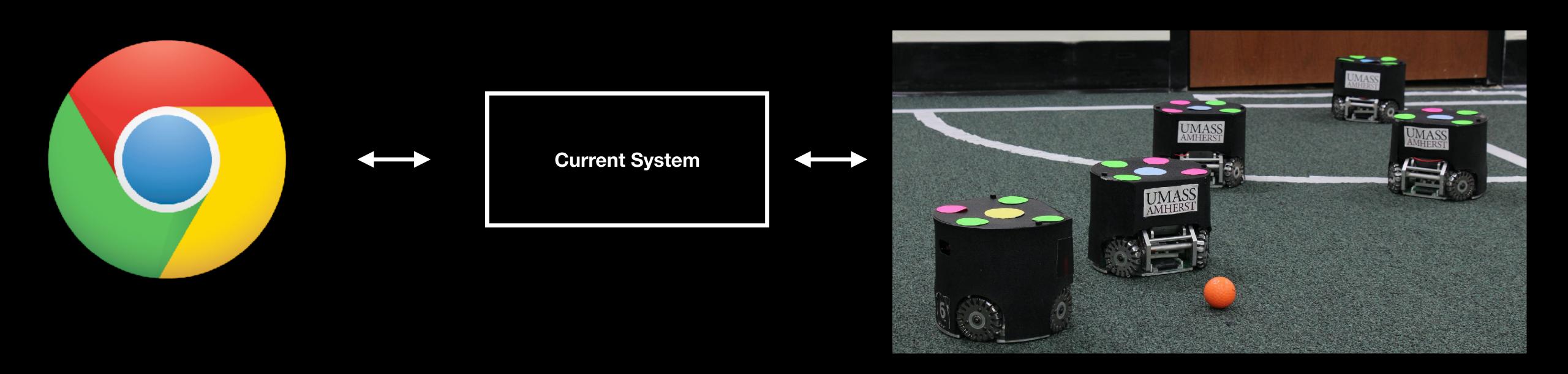
This presents a steep learning curve for even experienced programmers, and significantly more so for beginners.



Current System

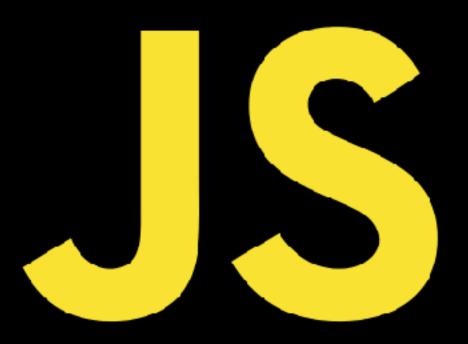


Ideal System



Why JavaScript?

- One of the most widely used languages
- Dynamic types
- Only needs a browser



Making SSL Robots Safe and Easy

Physical protection of the users and robots

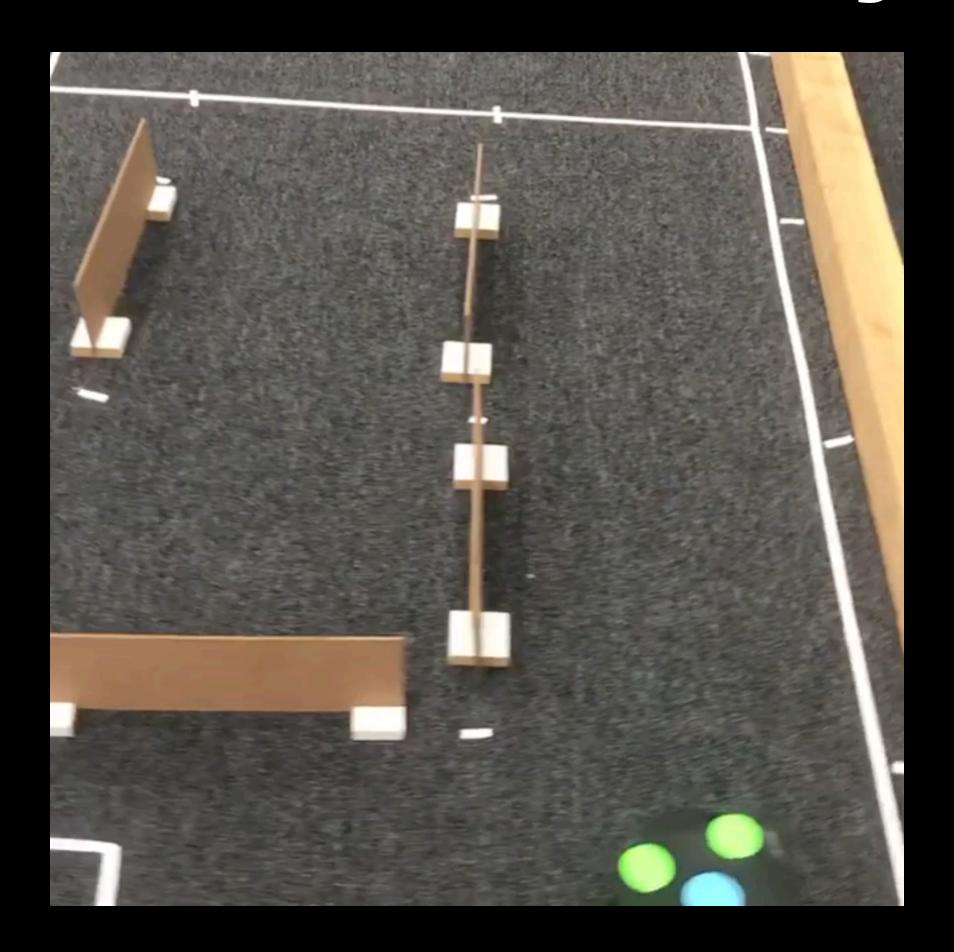
Making SSL Robots Safe and Easy

- Physical protection of the users and robots
- Simplification of the development experience

Robot Safety

- Reduced Motion Model: From in excess of 4m/s to at most 1m/s
- Crash Prevention Buffer: A uniform safety margin preventing collisions

Robot Safety



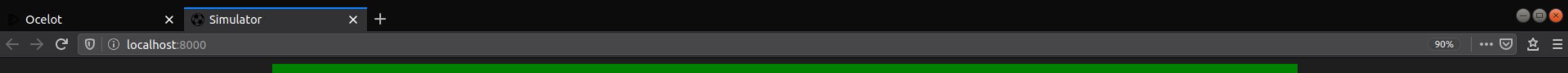
VIDEO: https://www.instagram.com/p/BzrYJI9hTBI/

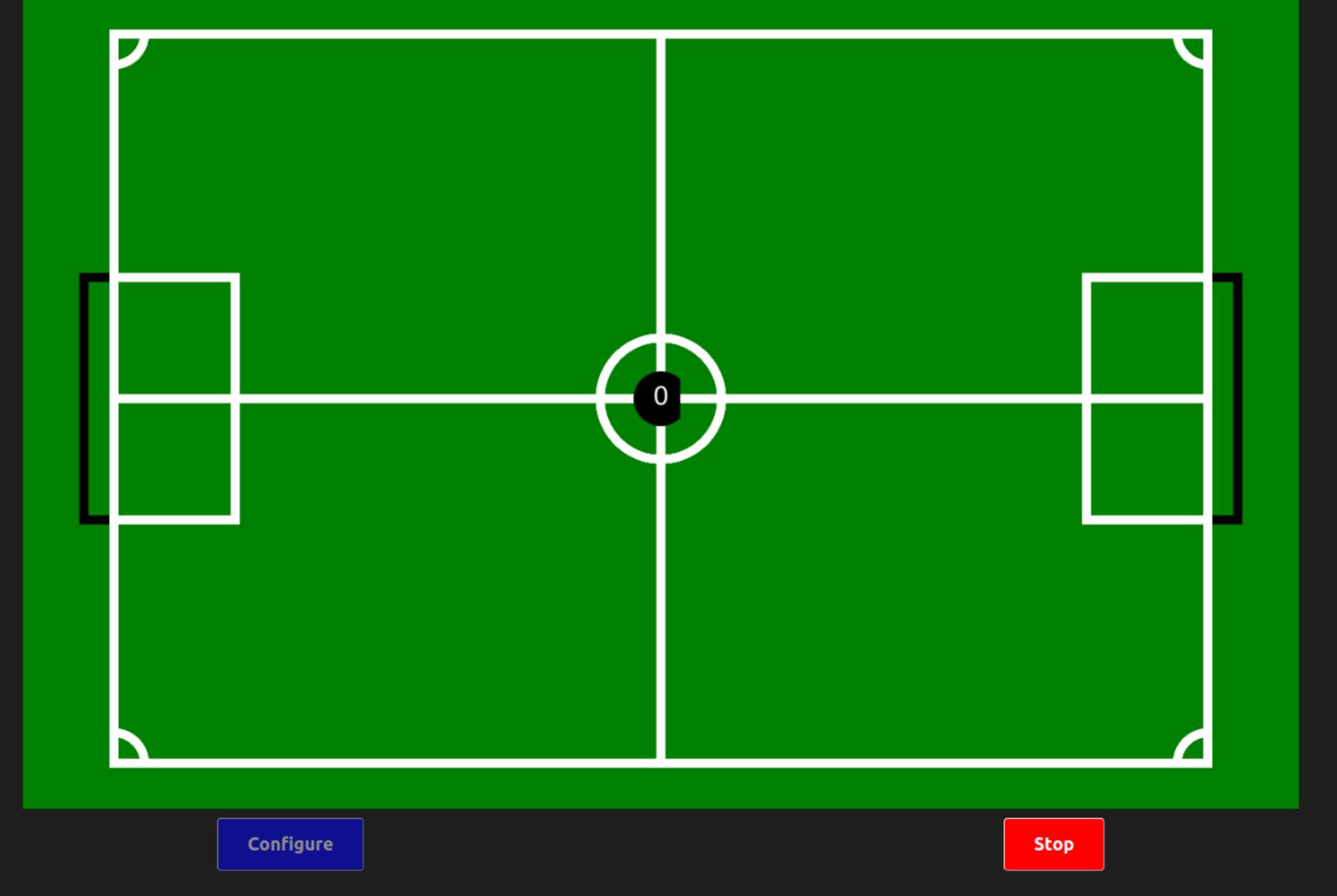
Robot Safety

- Command Timeouts: A sliding 5s window to complete an action
- Field Boundaries: Robots do not leave view of vision system

Extending SSL Software for Ease-of-Use

Publish the system state for external consumption





Extending SSL Software for Ease-of-Use

- Publish the system state for external consumption
- Have system receive external commands via the network:
 - Alleviates installation and configuration hassles

Extending SSL Software for Ease-of-Use

- Publish the system state for external consumption
- Have system to receive external commands via the network:
 - Alleviates installation and configuration hassles
 - Provide a simpler development environment (*Exclusively* in the browser!)

```
function add(a1, a2) {
  return a1 + a2;
}
add(1, 2); // 3
```

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add(1, 2, 3); // 3
add(1);
```

```
function add(a1, a2) {
  return a1 + a2;
}
add(1, 2); // 3
add(1, 2, 3); // 3
add(1); // NaN
```

- No function arity checks
- Implicit type conversions

```
function add(a1, a2) {
  return a1 + a2;
}
add(1, '2');
```

- No function arity checks
- Implicit type conversions

```
function add(a1, a2) {
  return a1 + a2;
}
add(1, '2'); // '12'
```

- No function arity
- Implicit type conversions

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A compiler implementing a "nice" subset of JavaScript, with a robotics library.

JavaScript-to-JavaScript Compilation Perform static checks checks

JavaScript-to-JavaScript Compilation Perform static checks Add runtime checks

Transparent to the user

Exemplary runtime check:

Function Arity

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function add(a1, a2) {
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Exemplary runtime check:

Function Arity

```
function add(a1, a2) {
  console.assert(arguments.length === 2);
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Exemplary runtime check:

Function Arity



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```

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Exemplary runtime check:

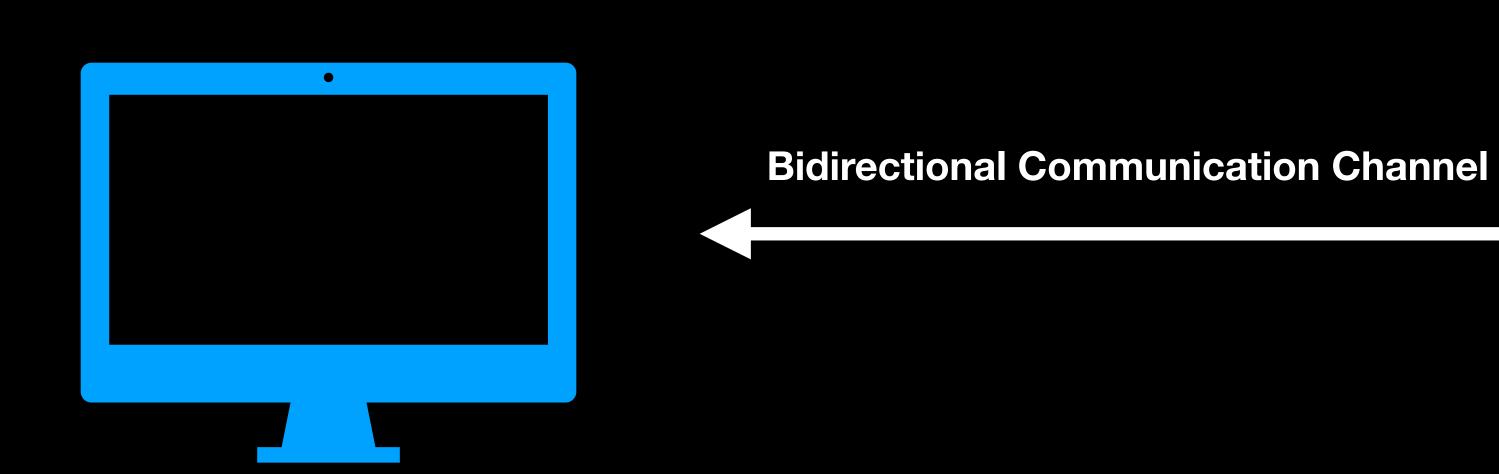
Function Arity

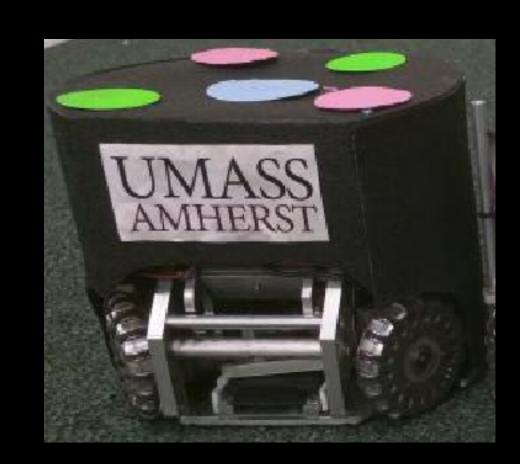


```
function add(a1, a2) {
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  return a1 + a2;
}
```

```
add(1, 2); // 3
add(1); // NaN
```

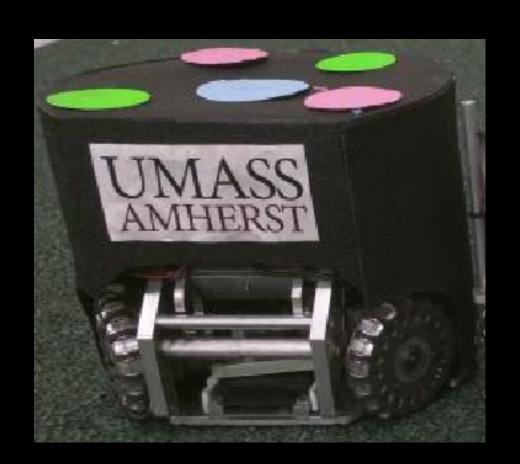
Programming Robots



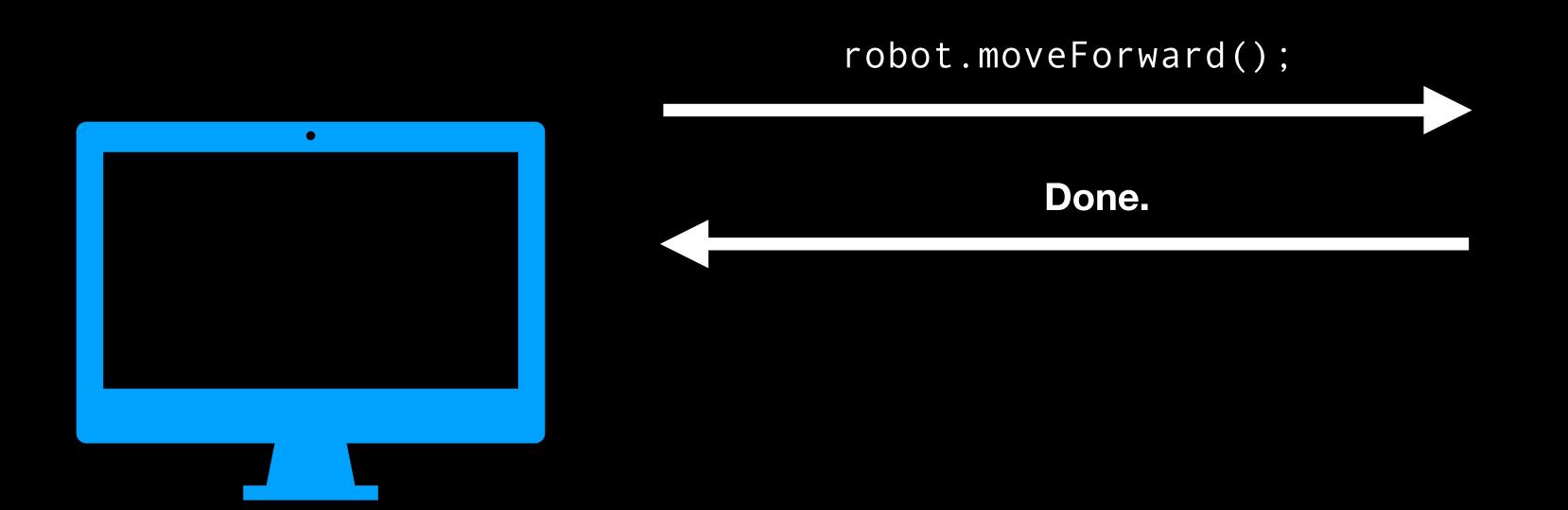


Programming Robots

```
robot.moveForward();
robot.turnLeft();
```

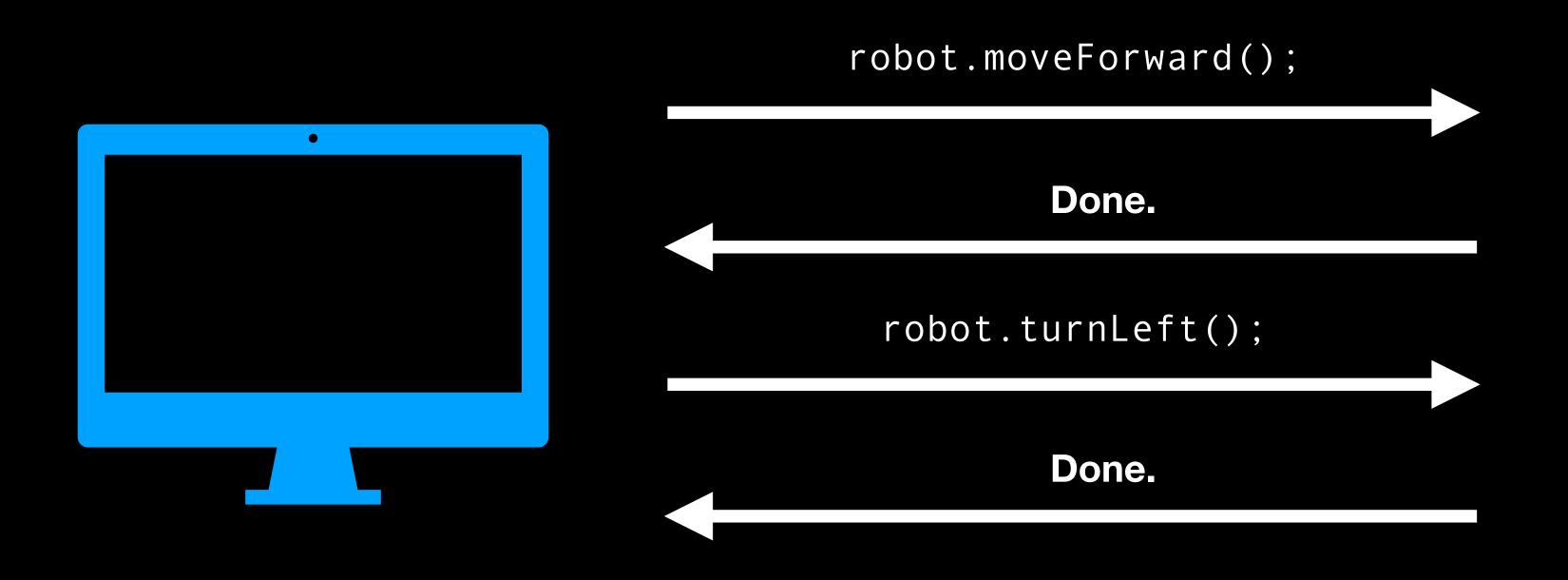


Programming Robots



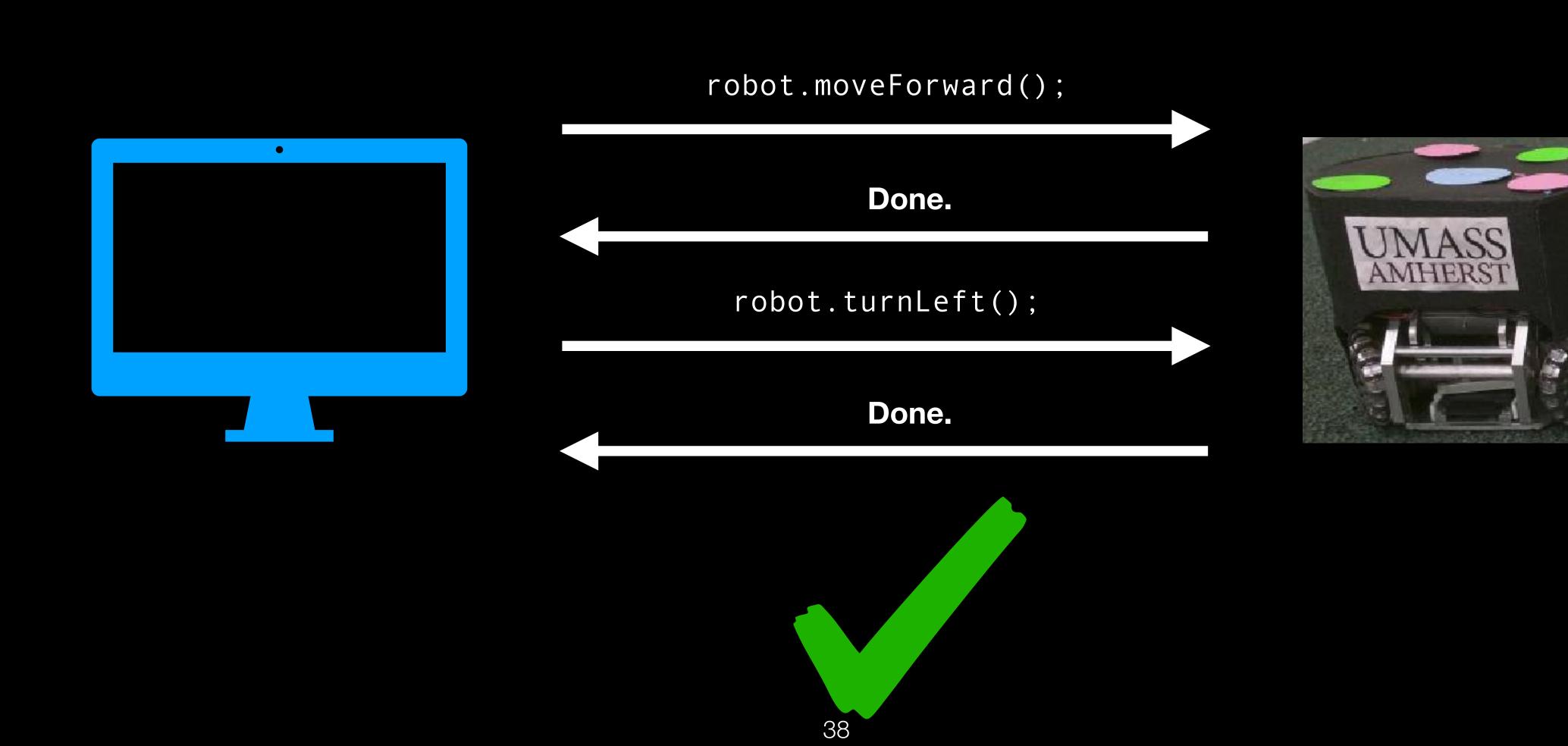


Programming Robots

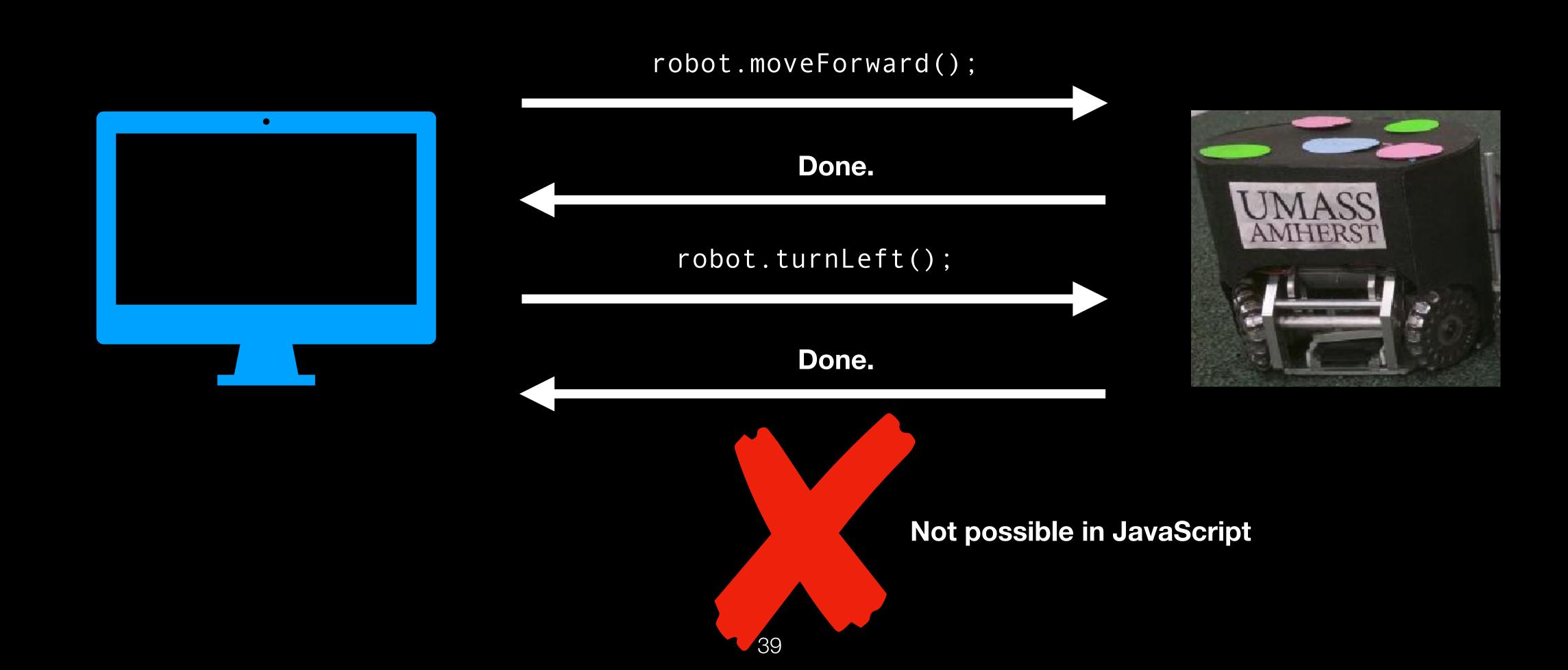




Programming Robots

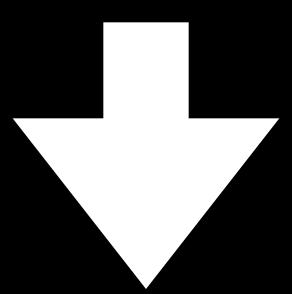


Programming Robots on the Web



Programming Robots on the Web

```
robot.moveForward();
robot.turnLeft();
```

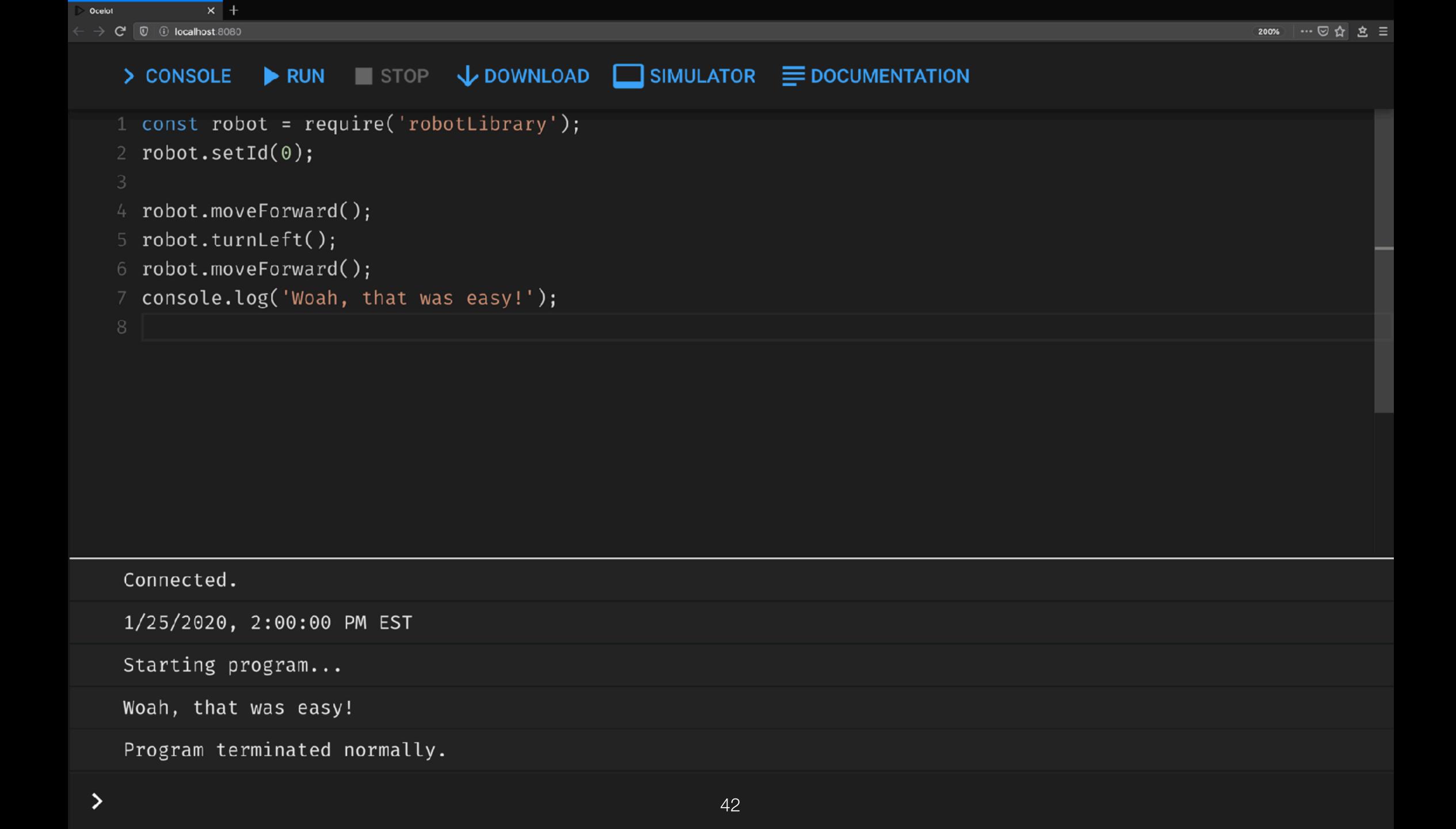


```
robot.moveForward(function() {
  robot.turnLeft();
});
```

Programming Robots on the Web with RoboJS

```
robot.moveForward();
robot.turnLeft();
```

RoboJS custom runtime makes all I/O blocking!



Workshop

Workshop Details

- 1 week; 6 hours/day
- 12 HS students; several had experience with Lego Mindstorms and block-based programming
- Lecture introduced a topic or activity, followed by student work time

Workshop Details

- Gradual introduction of more sophisticated concepts, supported by the layers of abstraction in the RoboJS API
- Programs were first written and tested in student's simulator before moving on to the real robots
- Later projects required more testing on real robots

Does RoboJS Help?

Data

- IDE saves a revision each time program is run (if changed)
- 3,230 student written revisions across 237 distinct files containing 106,168 lines
- ~10% of the revisions had JavaScript syntax errors
- Inspection of the remainder for RoboJS errors

Errors Caught by RoboJS

Pitfall

Count

Contrast

1. JS

2. Consequence 3. RoboJS

Errors Caught by RoboJS

Conditional assignment

Ex: if (x = 0)

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Coun	

28

Contrast 1

- 1. JS
- 3. RoboJS
- . Branches on value of RHS as a Boolean
- 2. Potential branching based on non-Boolean literals
- 2. Consequence 3. Same branch behavior, but only allowed if RHS evaluates to true/false

Errors Caught by RoboJS

Pitfall	Conditional assignment Ex: if(x = 0)	Operator type mismatch Ex: 'x' * 2
Count	28	42
1. JS	 Branches on value of RHS as a Boolean Potential branching based on non-Boolean literals Same branch behavior, but only allowed if RHS evaluates to true/false 	 NaN reference in the case of arithmetic/bit-wise operators and shorthand assignment Potential propagation of NaN Not allowed

Conclusion

- Extended the software stack of high-performance RoboCup Small-Size-League robots
- Ensured safety at various levels of abstraction
- Developed a rich robotics library in JS, targeted to newcomers RoboJS
- Packaged RoboJS into a browser IDE capable of blocking I/O
- Effectively leveraged the platform during a weeklong outreach workshop

Acknowledgments

- Students of the UT-AMRL & UMASS-PLASMA research labs
- Andrew Pasquale & Holyoke Codes

The following software has been modified from its original version. It has been formatted for personal use and edited for content:

https://github.com/ut-amrl/robo-js