Advection equation

$$\partial_t f - \mathbf{E} \cdot \nabla_{\mathbf{v}} f = 0$$

In spherical coordinates

$$\nabla_{\boldsymbol{v}} = \hat{\boldsymbol{v}}_r \frac{\partial}{\partial v} + \hat{\boldsymbol{v}}_\theta \frac{1}{v} \frac{\partial}{\partial v_\theta} + \hat{\boldsymbol{v}}_\varphi \frac{1}{v \sin(v_\theta)} \frac{\partial}{\partial v_\varphi}$$

$$\boldsymbol{E} = E\hat{\boldsymbol{z}} = E\left(\cos(v_{\theta})\hat{\boldsymbol{v}}_r - \sin(v_{\theta})\hat{\boldsymbol{v}}_{\theta}\right)$$

$$\boldsymbol{E} \cdot \nabla_{\boldsymbol{v}} f = E \left(\cos(v_{\theta}) \frac{\partial f}{\partial v} - \sin(v_{\theta}) \frac{1}{v} \frac{\partial f}{\partial v_{\theta}} \right)$$

• Expansion in terms of Maxwell polynomials and spherical harmonics

$$f = A \exp\left(-\left(\frac{v}{v_{
m th}}\right)^2\right) \sum_{klm} h_{klm} P_k\left(\frac{v}{v_{
m th}}\right) Y_{lm}(v_{ heta}, v_{arphi})$$

Projection:

$$\int_{\mathbb{R}^3} \left(\partial_t f - \boldsymbol{E} \cdot \nabla_{\boldsymbol{v}} f = 0 \right) P_p \left(\frac{v}{v_{\text{th}}} \right) Y_{qs}(v_{\theta}, v_{\varphi}) \, \mathrm{d}\boldsymbol{v} \, \mathrm{d}v_{\omega}$$

Resulting system of ODEs:

$$\partial_t h_{pqs}(t) = \sum_{k.l.m} \epsilon_{pqsklm} h_{klm}(t)$$



Discretized operator

$$\epsilon_{pqsklm} = \left(d_{pk} - \frac{1}{2}l_{pk}\right)\Psi_{lmqs} + \frac{1}{2}\sum_{i=0}^{N_r} \left(d_{jk} - \frac{1}{2}l_{jk}\right)\left(d_{pj} - \frac{1}{2}l_{pj} + d_{jp}\right)\Phi_{lmqs}$$

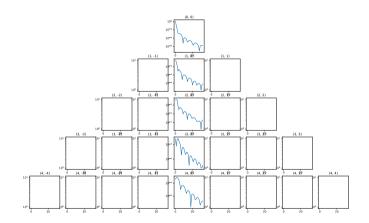
$$d_{jk}: P'_k(x) = \sum_{j=0}^{N_r} d_{jk} P_j(x)$$

$$l_{jk}: x P_k(x) = \sum_{j=0}^{N_r} l_{jk} P_k(x)$$

$$\Psi_{lmqs} = \int \cos(v_\theta) Y_{lm}(v_\theta, v_\varphi) Y_{qs}(v_\theta, v_\varphi) dv_\omega$$

$$\Phi_{lmqs} = \int \sin(v_\theta) Y_{qs}(v_\theta, v_\varphi) \frac{\partial}{\partial v_\theta} Y_{lm}(v_\theta, v_\varphi) dv_\omega$$

Sanity check: solution stays axisymmetric

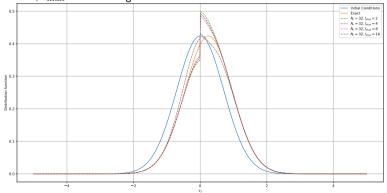






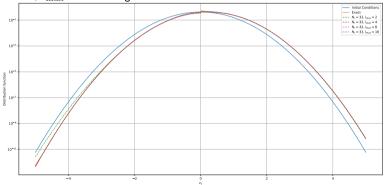
Convergence test: discontinuities at v = 0

- $E = \text{const} \rightarrow f(t, v) = f(0, v + Et)$
- $N_r=32$ is fixed, $l_{
 m max}$ is increasing



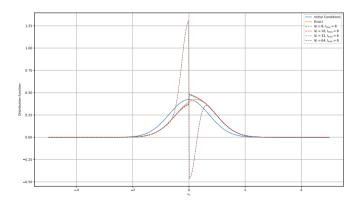
Convergence test: discontinuities at v = 0

- $E = const \rightarrow f(t, v) = f(0, v + Et)$
- $N_r=32$ is fixed, $l_{
 m max}$ is increasing



Convergence test: discontinuities at v = 0

- $E = \text{const} \rightarrow f(t, v) = f(0, v + Et)$
- N_r is increasing, $l_{\rm max}=8$ is fixed



• Kinda makes sense: generally singular at v=0

$$f = A \exp\left(-\left(\frac{v}{v_{
m th}}\right)^2\right) \sum_{lm} \left(\sum_k h_{klm} P_k\left(\frac{v}{v_{
m th}}\right)\right) Y_{lm}(v_{ heta}, v_{arphi})$$

Continuous if

$$\left(\sum_{k} h_{klm} P_k(0)\right) = 0$$

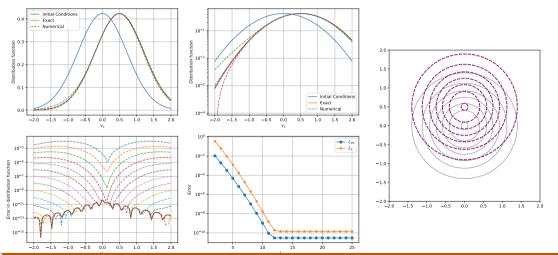
Possible fix (Following Gamba&Rjasanow 2018):

$$f = A \exp\left(-\left(\frac{v}{v_{\rm th}}\right)^2\right) \sum_{lm} \left(\sum_{k} h_{klm} \left(\frac{v}{v_{\rm th}}\right)^l P_{kl} \left(\frac{v}{v_{\rm th}}\right)\right) Y_{lm}(v_{\theta}, v_{\varphi})$$

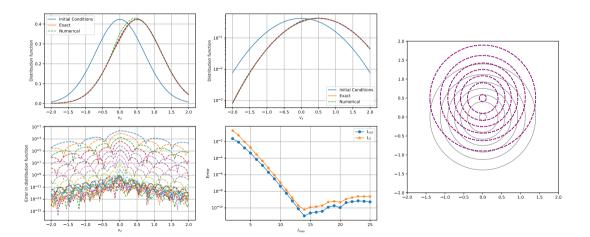
where (associated Maxwell polynomials?)

$$\int_{0}^{\infty} P_{kl}(x) P_{jl}(x) x^{2l+2} e^{-x^{2}} dx = \delta_{k,j}$$

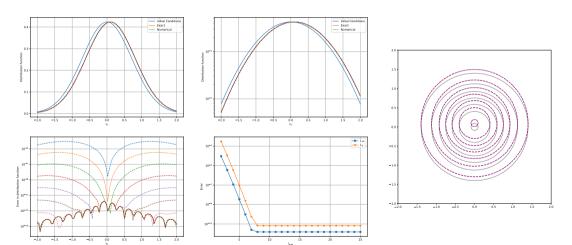
Convergence test ($N_r = 16$ is fixed, l_{max} is increasing)



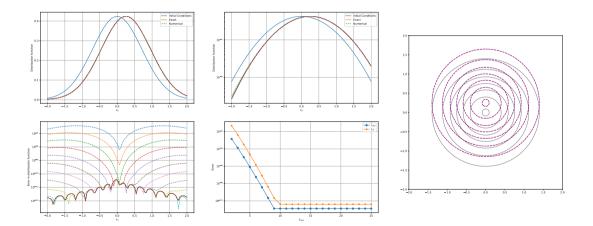
Convergence test (N_r is increasing, $l_{\text{max}} = 16$ is fixed)



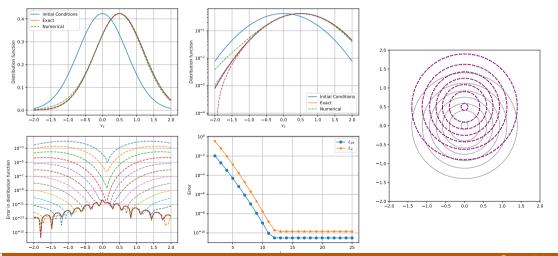
Convergence test ($N_r = 16$ is fixed, $l_{\rm max}$ is increasing)



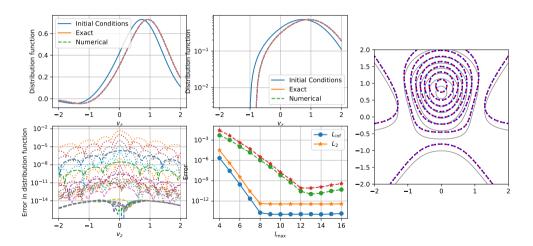
Convergence test ($N_r=16$ is fixed, $l_{\rm max}$ is increasing)



Convergence test ($N_r=16$ is fixed, $l_{\rm max}$ is increasing)



Convergence test: Maxwell vs Laguerre (N_r is increasing, $l_{max} = 16$ is fixed)



Dealing with advection term

Eulerian

$$\partial_t f - \mathbf{E} \cdot \nabla f = C[f]$$

- Might need more spherical harmonics

Lagrangian + operator splitting

$$\partial_t f - \mathbf{E} \cdot \nabla f = 0$$
$$\partial_t f = C[f]$$

- Have to reassemble collision operator
- Operator splitting error