view_frames Result Recorded at time: 4136.643 odom Broadcaster: /gazebo Average rate: 10.217 Hz Most recent transform: 4136.559 (0.084 sec old) Buffer length: 4.600 sec chassis Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /lane_laser_broadcaster Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10.217 Hz Average rate: 10.217 Hz Average rate: 10.220 Hz Most recent transform: 0.000 (4136.643 sec old) Most recent transform: 0.000 (4136.643 sec old) Most recent transform: 4136.556 (0.087 sec old) Most recent transform: 4136.556 (0.087 sec old) Most recent transform: 4136.559 (0.084 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 4.600 sec Buffer length: 4.600 sec Buffer length: 4.599 sec hokuyo left_wheel right_wheel lane_laser_frame camera