

The Blueprint For Formalizing Geometric Algebra in Lean

Eric Wieser, Utensil Song

November 1, 2023

Introduction

The goal of this document is to provide a detailed account of the formalization of Geometric Algebra (GA) a.k.a. Clifford Algebra [Hestenes and Sobczyk(1984)] in the Lean 4 theorem prover and programming language [Moura and Ullrich(2021), de Moura et al.(2015), Ullrich(2023)] and using its Mathematical Library Mathlib [The mathlib Community(2020)].

The web version of this blueprint is available [here](#).

1 Preliminaries

This section introduces the algebraic environment of Clifford Algebra, covering vector spaces, groups, algebras, representations, modules, multilinear algebras, quadratic forms, filtrations and graded algebras.

The material in this section should be familiar to the reader, but it is worth reading through it to become familiar with the notation and terminology that is used, as well as their counterparts in Lean, which usually require some additional treatment, both mathematically and technically (probably applicable to other formal proof verification systems).

Details can be found in the references in corresponding section, or you may hover a definition/theorem, then click on "L \forall N" for the Lean 4 code.

1.1 Basics

In this section, we follow [Jadczyk(2019)], with supplements from [Garling(2011), Chen(2016)], and modifications to match the counterparts in Lean's Mathlib .

Remark 1.1.1 — We unify the informal mathematical language for a definition to:

Let A be a *concept* A . A *concept* B is a set/pair/triple/tuple (B, op, \dots) , satisfying:

1. B is a *concept* C over A under op .
2. *formula* for all *elements in concept* B (*property*).
3. for each *element in concept* A there exists *element* such that *formula* for all *elements in concept* B .
4. op is called *op name*, for all *elements in concept* B , we have
 - (i) *formula*
 - (ii) *formula*

(*property*).

By default, A is a set, op is a binary operation on A .

Definition 1.1.2 (Group). A **group** is a pair $(G, *)$, satisfying:

1. $(a * b) * c = a * (b * c)$ for all $a, b, c \in G$ (**associativity**).
2. there exists $1 \in G$ such that $1 * a = a * 1 = a$ for all $a \in G$.
3. for each $a \in G$ there exists $a^{-1} \in G$ such that $a * a^{-1} = a^{-1} * a = 1$.

Remark 1.1.3 — It then follows that e , the **identity element**, is unique, and that for each $g \in G$ the **inverse** g^{-1} is unique.

A group G is abelian, or **commutative**, if $g * h = h * g$ for all $g, h \in G$.

Remark 1.1.4 — In literatures, the binary operation are usually denoted by juxtaposition, and is understood to be a mapping $(g, h) \mapsto g * h$ from $G \times G$ to G .

Mathlib uses a slightly different way to encode this, $G \rightarrow G \rightarrow G$ is understood to be $G \rightarrow (G \rightarrow G)$, that sends $g \in G$ to a mapping that sends $h \in G$ to $g * h \in G$.

Further more, a mathematical construct is represented by a "type", as Lean has a dependent type theory foundation, see [Carneiro(2019)] and [Ullrich(2023), section 3.2].

It can be denoted multiplicatively as $*$ in **Group** or additively as $+$ in **AddGroup**, where e will be denoted by 1 or 0, respectively.

Sometimes we use notations with subscripts (e.g. $*_G, 1_G$) to indicate where they are.

We will use the corresponding notation in Mathlib for future operations without further explanation.

Definition 1.1.5 (Monoid). A **monoid** is a pair $(R, *)$, satisfying:

1. $(a * b) * c = a * (b * c)$ for all $a, b, c \in R$ (**associativity**).
2. there exists an element $1 \in R$ such that $1 * a = a * 1 = a$ for all $a \in R$
i.e. 1 is the multiplicative identity (**neutral element**).

Definition 1.1.6 (Ring). A **ring** is a triple $(R, +, *)$, satisfying:

1. R is a **commutative group** under $+$.
2. R is a **monoid** under $*$.
3. for all $a, b, c \in R$, we have

(i) $a * (b + c) = a * b + a * c$

(ii) $(a + b) * c = a * c + b * c$

(left and right **distributivity** over $+$).

Remark 1.1.7 — In applications to Clifford algebras R will be always assumed to be **commutative**.

Definition 1.1.8 (Division ring). A **division ring** is a ring $(R, +, *)$, satisfying:

1. R contains at least 2 elements.
2. for all $a \neq 0$ in R , there exists a multiplicative inverse $a^{-1} \in R$ such that

$$a * a^{-1} = a^{-1} * a = 1$$

Definition 1.1.9 (Module). Let R be a commutative ring. A **module** over R (in short **R -module**) is a pair (M, \bullet) , satisfying:

1. M is a group under $+$.
2. $\bullet : R \rightarrow M \rightarrow M$ is called **scalar multiplication**, for every $a, b \in R, x, y \in M$, we have

- (i) $a \bullet (x + y) = a \bullet x + b \bullet y$
- (ii) $(a + b) \bullet x = a \bullet x + b \bullet x$
- (iii) $a * (b \bullet x) = (a * b) \bullet x$
- (iv) $1_R \bullet x = x$

Remark 1.1.10 — The notation of scalar multiplication is generalized as heterogeneous scalar multiplication **HMul** in Mathlib :

$$\bullet : \alpha \rightarrow \beta \rightarrow \gamma$$

where α, β, γ are different types.

Definition 1.1.11 (Vector space). If R is a **division ring**, then a module M over R is called a **vector space**.

Remark 1.1.12 — For generality, Mathlib uses **Module** throughout for vector spaces, particularly, for a vector space V , it's usually declared as

```
variable [DivisionRing K] [AddCommGroup V] [Module K V]
```

for definitions/theorems about it, and most of them can be found under `Mathlib.LinearAlgebra` e.g. **LinearIndependent**.

Remark 1.1.13 — A **submodule** N of M is a module N such that every element of N is also an element of M .

If M is a vector space then N is called a **subspace**.

Definition 1.1.14 (Ring homomorphism). Let $(\alpha, +_\alpha, *_\alpha)$, and $(\beta, +_\beta, *_\beta)$ be rings.

A **ring homomorphism**, from α to β is a function $f : \alpha \rightarrow_{+*} \beta$ such that

- (i) $f(x +_\alpha y) = f(x) +_\beta f(y)$ for each $x, y \in \alpha$.

- (ii) $f(x *_\alpha y) = f(x) *_\beta f(y)$ for each $x, y \in \alpha$.
- (iii) $f(1_\alpha) = 1_\beta$.

Definition 1.1.15 (Algebra). Let R be a commutative ring. An **algebra** A over R is a pair (A, \bullet) , satisfying:

1. A is a **ring** under $*$.
2. there exists a **ring homomorphism** from R to A , denoted $\iota : R \rightarrow_{+*} A$.
3. $\bullet : R \rightarrow M \rightarrow M$ is a **scalar multiplication**
4. for every $r \in R, x \in A$, we have
 - (i) $r * x = x * r$ (commutativity between R and A)
 - (ii) $r \bullet x = r * x$ (definition of scalar multiplication)

where we omitted that the ring homomorphism ι is applied to r before each multiplication, while they are explicitly written as `toRingHom(r)` in `Mathlib`.

Remark 1.1.16 — The definition above (adopted in `Mathlib`) is more general than the definition in literature:

Let R be a commutative ring. An **algebra** A over R is a pair $(M, *)$, satisfying:

1. A is a **module** M over R under $+$ and \bullet .
2. A is a **ring** under $*$.
3. For $x, y \in A, a \in R$, we have

$$a \bullet (x * y) = (a \bullet x) * y = x * (a \bullet y)$$

See *Implementation notes* in [Algebra](#) for details.

Remark 1.1.17 — What's simply called algebra is actually associative algebra with identity, a.k.a. **associative unital algebra**. See [the red herring principle](#) for more about such phenomenon for naming, particularly the example of (possibly) **nonassociative algebra**.

Definition 1.1.18 (Free algebra). Let X be an arbitrary set. An **free R -algebra** A on X (or "generated by X ") is the **ring quotient** of the following inductively constructed set A_{pre}

1. for all x in X , there exists a map $X \rightarrow A_{pre}$.
2. for all r in R , there exists a map $R \rightarrow A_{pre}$.
3. for all a, b in A_{pre} , $a + b$ is in A_{pre} .
4. for all a, b in A_{pre} , $a * b$ is in A_{pre} .

by that equivalence relation that makes A an **R -algebra**, namely:

1. there exists a **ring homomorphism** from R to A_{pre} , denoted $R \rightarrow_{+*} A_{pre}$.

2. A is a **commutative group** under $+$.
3. A is a **monoid** under $*$.
4. left and right **distributivity** under $*$ over $+$.
5. $0 * a \sim a * 0 \sim 0$.
6. for all a, b, c in A , if $a \sim b$, we have

- (i) $a + c = b + c$
- (ii) $c + a = c + b$
- (iii) $a * c = b * c$
- (iv) $c * a = c * b$

(**compatibility** with the ring operations $+$ and $*$)

Remark 1.1.19 — What we defined here is the free (associative, unital) R -algebra on X , it can be denoted $R\langle X \rangle$, expressing that it's freely generated by R and X , where X is the set of generators.

Definition 1.1.20 (Linear map). Let R, S be rings, M an R -module, N an S -module. A **linear map** from M to N is a function $f : M \rightarrow_l N$ over a ring homomorphism $\sigma : R \rightarrow_{+*} S$, satisfying:

1. $f(x + y) = f(x) + f(y)$ for all $x, y \in M$.
2. $f(r \bullet x) = \sigma(r) \bullet f(x)$ for all $r \in R, x \in M$.

Definition 1.1.21 (Quotient of non-commutative ring). Let R be a non-commutative ring, r an arbitrary equivalence relation on R . The **ring quotient** of R by r is by the strengthen equivalence relation of r such that for all a, b, c in R :

1. $a + c \sim b + c$ if $a \sim b$
2. $a * c \sim b * c$ if $a \sim b$
3. $a * b \sim a * c$ if $b \sim c$

i.e. the equivalence relation is compatible with the ring operations $+$ and $*$.

Remark 1.1.22 — As ideals haven't been formalized for the non-commutative case, **Mathlib** uses **RingQuot** in places where the quotient of non-commutative rings by ideal is needed.

The universal properties of the quotient are proven, and should be used instead of the definition that is subject to change.

Definition 1.1.23 (Tensor algebra relation). Let A be a free R -algebra on module M , let $\iota : M \rightarrow A$ denote the map from M to A .

The **tensor algebra relation** on M is the equivalence relation satisfying:

1. for all a, b in M , $\iota(a + b) \sim \iota(a) + \iota(b)$.
2. for all r in R , a in M , $\iota(r \bullet a) \sim r * \iota(a)$.

i.e. making the inclusion of M into an R -linear map.

Definition 1.1.24 (Tensor algebra). Let M be a module over R .

An **tensor algebra** over M (or "of M ") T is the **ring quotient** of the **free R -algebra** generated by M , by the **tensor algebra relation** on M 1.1.23.

Remark 1.1.25 — The definition above is equivalent to the following definition in literature:

Let M be a module over R . An algebra T is called a **tensor algebra** over M (or "of M ") if it satisfies the following universal property

1. T is an algebra containing M as a **submodule**, and it is **generated by** M ,
2. Every linear mapping λ of M into an algebra A over R , can be extended to a **homomorphism** θ of T into A .

2 Foundations

2.1 Clifford algebras - definition

Throughout this section:

Let M be a module over a commutative ring R , equipped with a quadratic form $Q : M \rightarrow R$.

Let $\iota : M \rightarrow_{l[R]} T(M)$ be the canonical R -linear map for the tensor algebra $T(M)$.

Let $\iota_a : R \rightarrow_{+*} T(M)$ be the canonical map from R to $T(M)$, as a ring homomorphism.

Definition 2.1.1 (Clifford relation). $\forall m \in M, \iota(m)^2 \sim \iota_a(Q(m))$

We say that ι is **Clifford** if this relation holds.

Definition 2.1.2 (Clifford algebra). A **Clifford algebra** over M , denoted $\mathcal{C}\ell(M)$, is the quotient of the **tensor algebra** $T(M)$ by **Clifford relation 2.1.1**.

Remark 2.1.3 — In literatures, M is often written V , and the quotient is taken by the two-sided ideal I_Q generated from the set $\{v \otimes v - Q(v) \mid v \in V\}$.

As of writing, Mathlib does not have direct support for two-sided ideals, but it does support the equivalent operation of taking the quotient by a suitable closure of a relation like $v \otimes v \sim Q(v)$.

Hence the definition above.

Example 2.1.4 (Clifford algebra over a vector space)

Let V be a vector space \mathbb{R}^n over \mathbb{R} , equipped with a quadratic form Q .

Since \mathbb{R} is a commutative ring and V is a module, definition 2.1.2 of Clifford algebra applies.

2.1.1 Involutions

2.2 Structure of Clifford algebras

2.3 Classifying Clifford algebras

2.4 Representing Clifford algebras

2.5 Spin

3 Geometric Algebra

3.1 Axioms

3.2 Operations and properties

4 Concrete algebras - definition

4.1 CGA

4.2 PGA

4.3 STA

5 Applications

5.1 Geometry

References

- [Carneiro(2019)] Mario Carneiro. 2019. The type theory of Lean. *preparation* (<https://github.com/digama0/lean-type-theory/releases>) (2019).
- [Chen(2016)] Evan Chen. 2016. An infinitely large napkin.
- [de Moura et al.(2015)] Leonardo de Moura, Soonho Kong, Jeremy Avigad, Floris van Doorn, and Jakob von Raumer. 2015. The Lean Theorem Prover (System Description). In *Automated Deduction - CADE-25*, Amy P. Felty and Aart Middeldorp (Eds.). Lecture Notes in Computer Science, Vol. 9195. Springer International Publishing, Cham, 378–388. https://doi.org/10.1007/978-3-319-21401-6_26
- [Garling(2011)] David JH Garling. 2011. *Clifford algebras: an introduction*. Vol. 78. Cambridge University Press.
- [Hestenes and Sobczyk(1984)] David Hestenes and Garret Sobczyk. 1984. *Clifford Algebra to Geometric Calculus: A Unified Language for Mathematics and Physics*. Vol. 5. Springer Science & Business Media. <https://www.springer.com/gp/book/9789027716736>
- [Jadczyk(2019)] Arkadiusz Jadczyk. 2019. Notes on Clifford Algebras. (2019).
- [Moura and Ullrich(2021)] Leonardo de Moura and Sebastian Ullrich. 2021. The lean 4 theorem prover and programming language. In *Automated Deduction—CADE 28: 28th International Conference on Automated Deduction, Virtual Event, July 12–15, 2021, Proceedings 28*. Springer, 625–635.

- [The mathlib Community(2020)] The mathlib Community. 2020. The Lean Mathematical Library. In *Proceedings of the 9th ACM SIGPLAN International Conference on Certified Programs and Proofs* (New Orleans, LA, USA, 2020-01-20) (*CPP 2020*). Association for Computing Machinery, 367–381. <https://doi.org/10.1145/3372885.3373824>
- [Ullrich(2023)] Sebastian Andreas Ullrich. 2023. *An Extensible Theorem Proving Frontend*. Ph.D. Dissertation. Dissertation, Karlsruhe, Karlsruher Institut für Technologie (KIT), 2023.