Girsanov's Theorem & Solving SDEs 1. Solve the following SDE: dx = (B-logx)xtdt + 6xtdBt, X(0)=x0, B& or are constants let's try transforming the SDE using ito's lema we assume X DO for all t becaus log X must be defined let Yt = logxt, by Itôs lemma  $dY_t = 0.dt + \frac{1}{x_t} dX_t = \frac{1}{2(x_t)^2} dX_t dX_t$ but given, but given,  $dx_t = (\beta - \log x_t) \times_t dt + 6 \times_t d\beta_t$  $\frac{dx_t}{x_t} = (\beta - \log x_t)dt + \delta dB_t$ & dx, dxt = = 2(xt) dt (:dtdt=0, dBtdt=0)  $\frac{1}{(x_t)^2} = \int_0^2 dt$ i. en (1) be comes dy = (B-logx)dt + odBt - 1 o2.dt

: dy = (B-162-YE) dt + 6 dBE but this eq is in the form of Omstein-Unknbeck process dxt = O(n-xt)dt + 6dWt Solution to it is  $x_t = x_0e^{-Qt} + \mu(1-e^{-Qt}) + 6w - 20$  $Y_{t} = e^{-t}Y_{0} + (\beta - \frac{1}{2}e^{2})(1 - e^{t})$ t +6 ( e (t-s) dBs AL: Xt = e t  $= \exp \left\{ \frac{e^{\pm \log x_0} + (1 - e^{\pm t})(\beta - \frac{1}{2}e^2)}{t} \right\}$ +6 (= (t-s) dBs} 16 = 2xb. 3xb = are = (B-logxe)de + 6dBe-1 ofde

2. Let B<sub>t</sub> = (B<sub>t</sub>, B<sub>t</sub>)..., B<sub>t</sub>) be a d-dimensional Brownian motion and Rt = 11Bt11 = V(Bt)2 + ... + (Bt)2. What is the distribution of the process  $X_{t} = \sum_{i=1}^{d} \int_{0}^{t} \frac{B_{s}}{R_{s}} dB_{s}^{i}$ The integrand in each term of the sum, Bs , represents the i-th component of the brownian motion divided by the Radial distance from the origin in d-dimensional space. This can be seen as the projection of the d-dimensional Brownian motion on the unit sphere scaled by Rs. Quadratic variation of Xx.  $\langle x_{t}, x_{t} \rangle = \langle \sum_{i=1}^{\infty} \frac{B_{s}^{i}}{R_{s}^{i}} \frac{B_{s}^{i}}{E_{s}^{i}} \frac{B_{s}^{i}}{E_{s}^{i}} \frac{B_{s}^{i}}{R_{s}^{i}} \frac{B_{s}^{i}}{E_{s}^{i}} \frac{B_{s}^{i}}{E_{s}^$ Since the integrals are stochastic integrals with respect to orthogonal components ( independent B's) of the brownian motion the quadratic variation add up to

(x,x) = \( \)

 $(x,x)_t = \sum_{i=1}^{\infty} \left( \frac{B_5^i}{R_5} \right)^2 ds = \int_{i=1}^{\infty} \left( \frac{B_5^i}{R_5} \right) ds$ Notice that (B) is the guared component of the unit vector pointing in the direction of Bs The sum of the squares of these components 1 ( radius of mit sphere) d-dimensional (x,x) = | 1 ds = & each term (Bs) is continuous (as brownian motion) & xt is a continuous (or travers) and the second in the second continuous (or travers) and the second continuous (or trave X to has continuous paths by construction (3) Also each term in 2 (B's) ds is an (Stochastic) integral which are martingales (Property) - (4) From (1), (2), (3), (4) Xt is a continuous local martingale starting at a with quadratic variation t, by Levy's theorem, Xt is a standard Brownian motion. Therefore distribution of Xt is Normal i.C. Xt ~ N(0,t).

Find a Stochastic differential equation that Re satisfies.

To find a stochastic differential eq that R<sub>L</sub> = 11 B<sub>L</sub> 11 =  $\sqrt{(B_L^+)^2 + ... + (B_L^d)^2}$  satisfies,

 $B_t = (B_t, B_t, ..., B_t^d)$  is a d-dimensional Brownian motion, we can use Itô's formula The process Rt can be thought as the radial part of a multidimensional Brownian motion, and its dynamics can be analyzed by considering the square root of the sum of squares of the components of Bt.

1) We define Ry = f (By) Where f(x) = 1 x12 + ... >(2)

Using Itô formula for multidimensional case

 $df(x_t) = \sum_{i=1}^{n} \frac{\partial f}{\partial x_i} dx_i + \sum_{i=1}^{n} \frac{\partial^2 f}{\partial x_i} d(x_i, x_i)^{\frac{1}{n}}$ 

For Rt, Xi = Bt & d(Bi,Bi)t = Sij dt Cwhere Sij is the kronecker delta).

2) The first & second partial derivatives of

 $\frac{\partial f}{\partial x_i} = \frac{\alpha_i}{\left(\alpha_i^2 + \dots + \alpha_i^2\right)} = \frac{\beta_t}{R_t}$ 

The mixed partial derivatives for

$$\frac{3^{2}f}{3x;3x} = -\frac{3^{2}}{8^{2}}$$
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3. Applying itô's formula

$$\frac{dR_{t}}{dR_{t}} = \frac{2}{8^{2}} \frac{dS_{t}}{dS_{t}} + \frac{1}{2} \frac{(R_{t})^{2}}{(R_{t})^{3}}$$
As
$$\frac{d}{(R_{t})^{2}} = R_{t}^{2} \frac{(Radius of ol-dimensional)}{(R_{t})^{3}}$$

$$\frac{d}{(R_{t})^{3}} = \frac{2}{R_{t}} \frac{R_{t}^{2}}{(R_{t})^{3}}$$

$$\frac{d}{(R_{t})^{3}} = \frac{2}$$

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:. dR+ = dW+ + d-1 . d+ . This SDE reflects the behaviour of the radial part of a d-dimensional Brownian motion The term d-1 dt arises from the curvature effects in higher dimensions, effectively a mean-reverting force proportional to the inverse of the distance from origin