



Vehicular Ad-Hoc Networks



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**Dr. Debasis Das
IIT Jodhpur**

Mobility Modeling for Future Mobile Network Design and Simulation



Mobility Modeling for Future Mobile Network Design and Simulation

Outline

- Mobile Ad Hoc Networks & Mobility Classification
 - Synthetic and Trace-based Mobility Models
 - The Need for Systematic Mobility Framework
- Survey of the Major Mobility Models
 - Random models - Group mobility models – Vehicular (Manhattan/Freeway) models - Obstacle models
- Characterizing the Mobility Space
 - Mobility Dimensions (spatial and temporal dependency, geographic restrictions)
 - Mobility Metrics (spatio-temporal correlations, path and link duration)

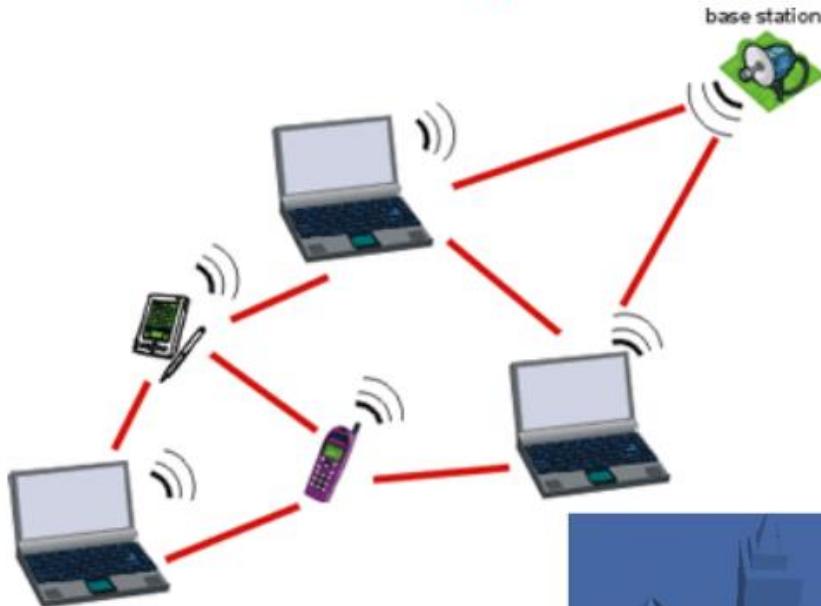
Outline (contd.)

- Mobility-centric framework to analyze ad hoc networks
 - The *IMPORTANT* mobility framework
 - Case Studies: *BRICS*, *PATHS*, *MAID*
- Trace-based mobility modeling
 - Analyzing wireless network measurements and traces
 - The *TVC* model, and *profile-cast*
- Mobility simulation and analysis tools
 - Software packages and tools
 - Resources and related projects

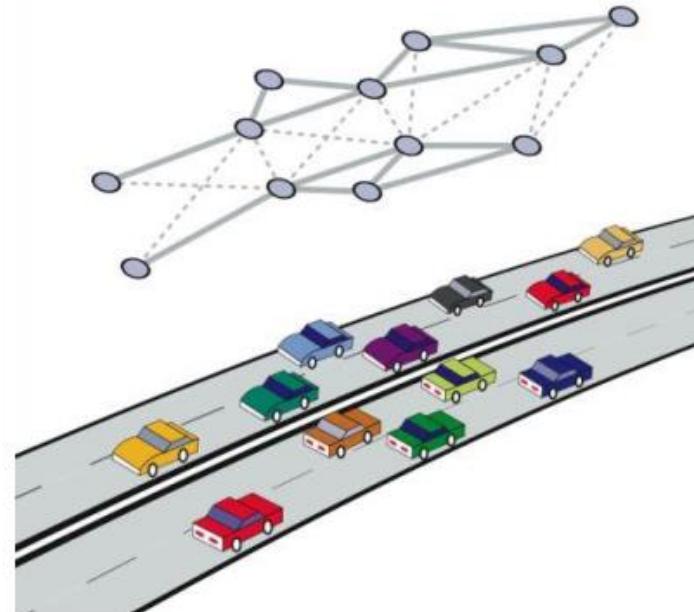
Wireless Mobile Ad hoc Networks (MANETs)

- A Mobile Ad hoc Network (*MANET*) is a collection of mobile devices forming a multi-hop wireless network with minimal (or no) infrastructure
- To evaluate/study adhoc networks mobility and traffic patterns are two significant factors affecting protocol performance.
- Wireless network performance evaluation uses:
 - Mobility Patterns: usually, uniformly and randomly chosen destinations (random waypoint model)
 - Traffic Patterns: usually, uniformly and randomly chosen communicating nodes with long-lived connections
- **Impact of mobility** on wireless networks and ad hoc routing protocols is significant

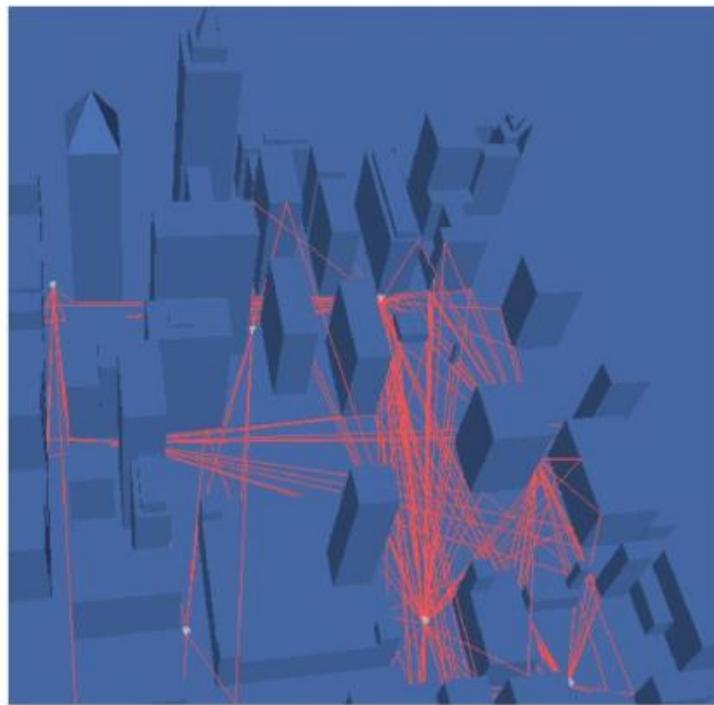
Example Ad hoc Networks



Mobile devices (laptop, PDAs)



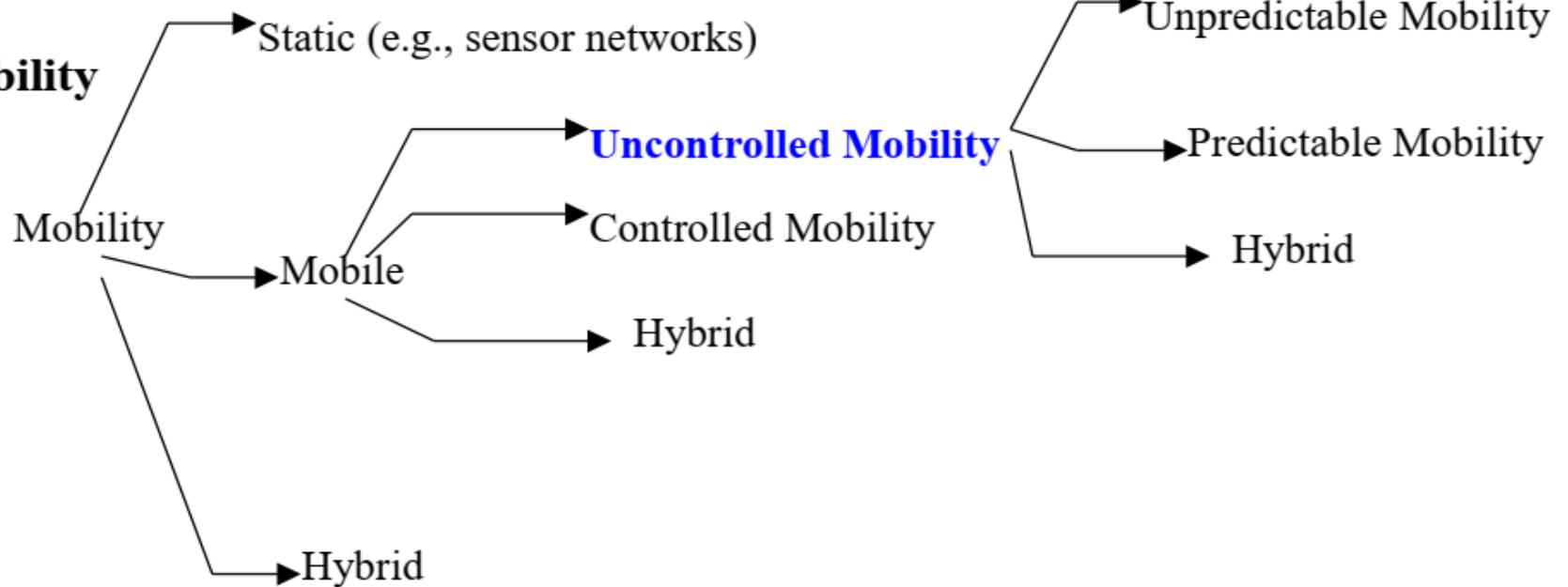
Vehicular Networks on Highways



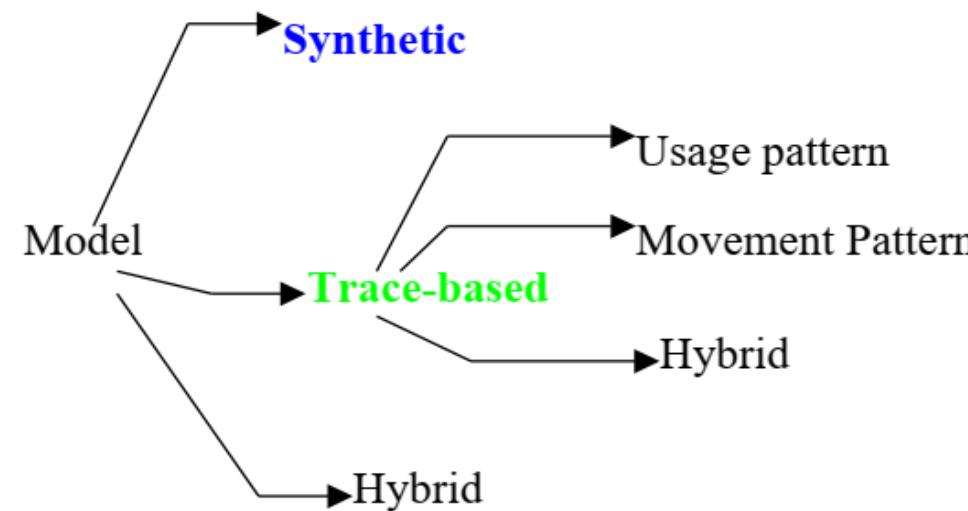
Hybrid urban ad hoc network (vehicular, pedestrian, hot spots,...)

Classification of Mobility and Mobility Models

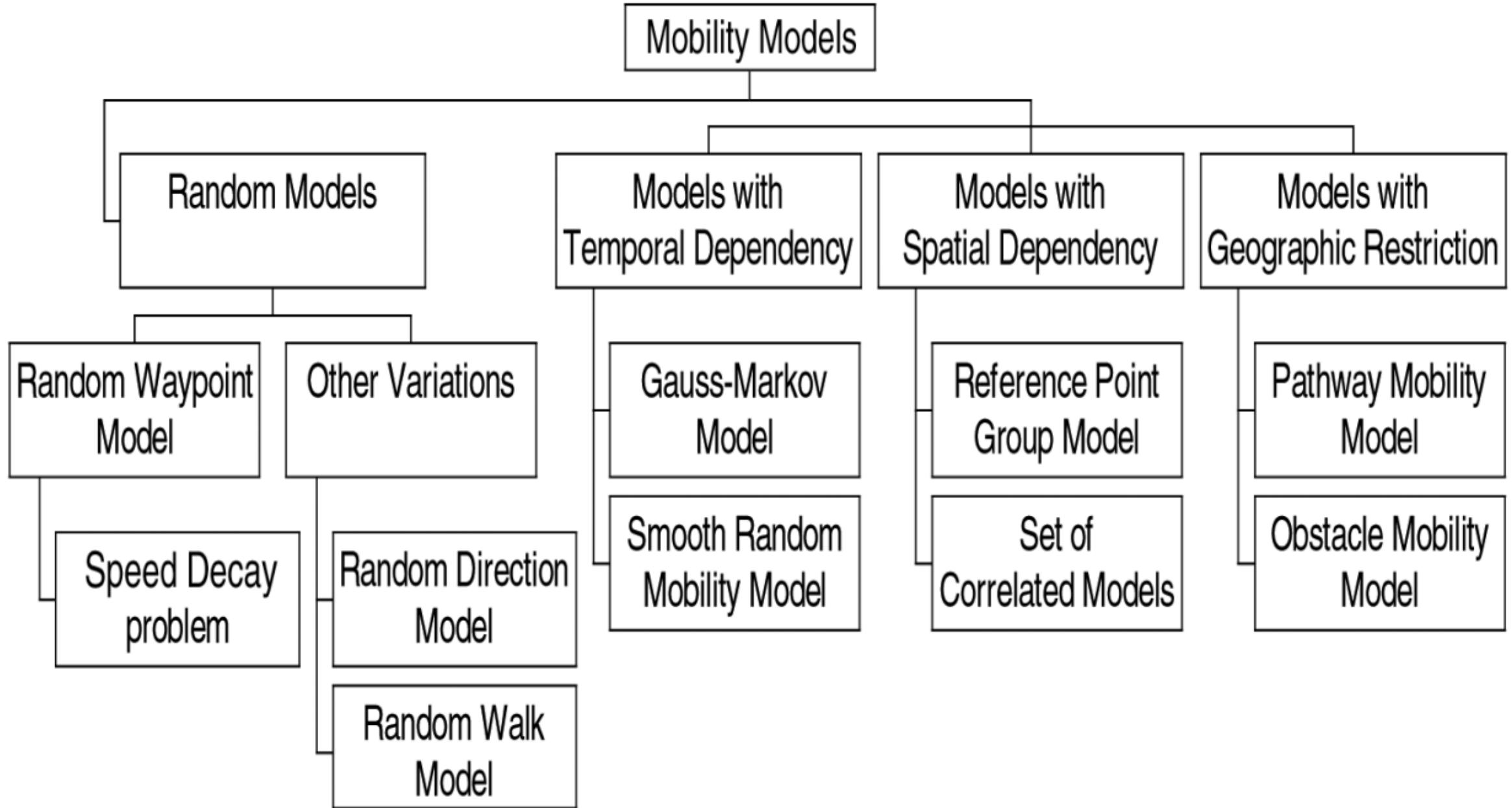
I- Based on Controllability



II- Based on Model Construction



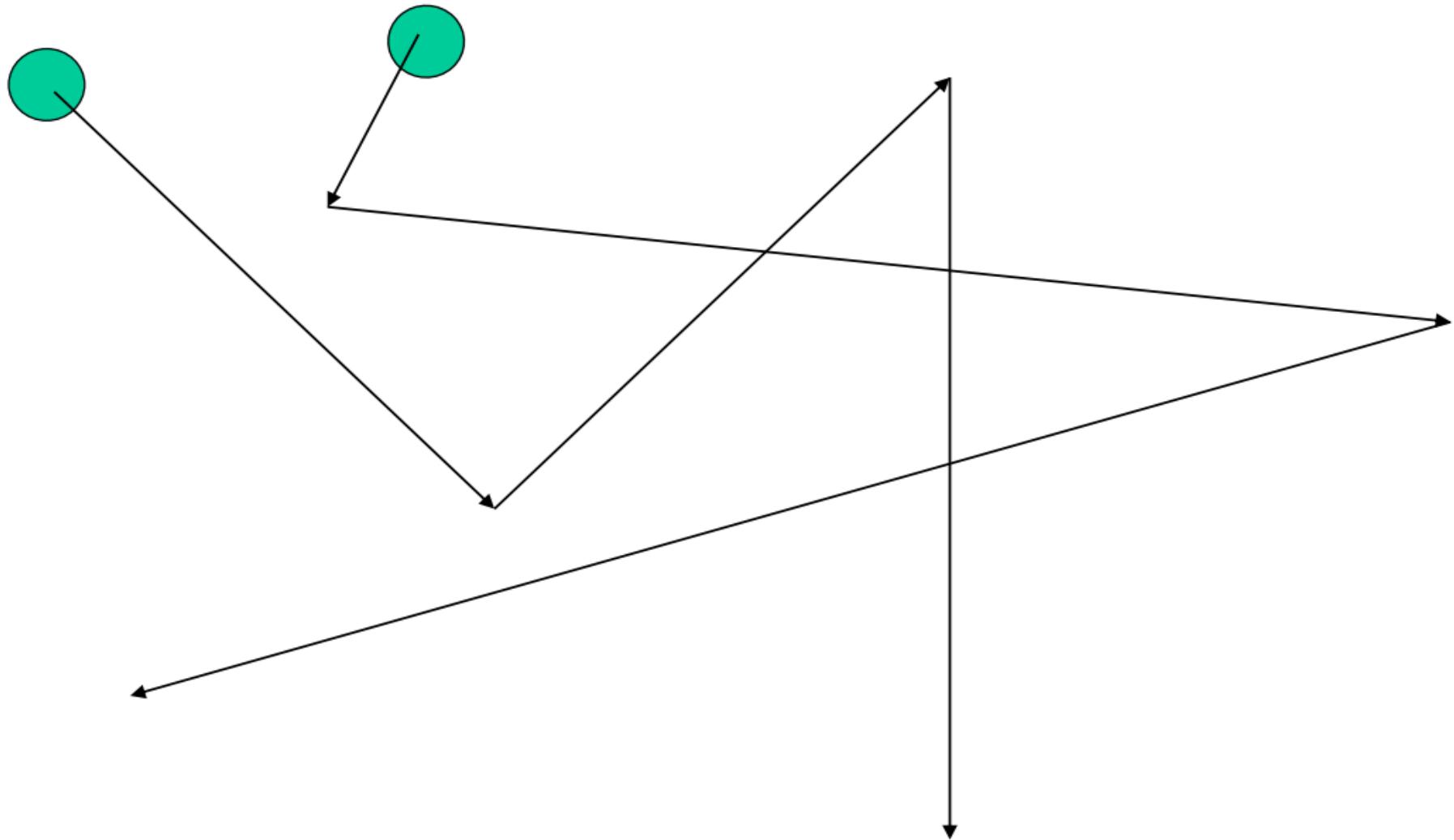
Mobility Dimensions & Classification of Synthetic Uncontrolled Mobility Models



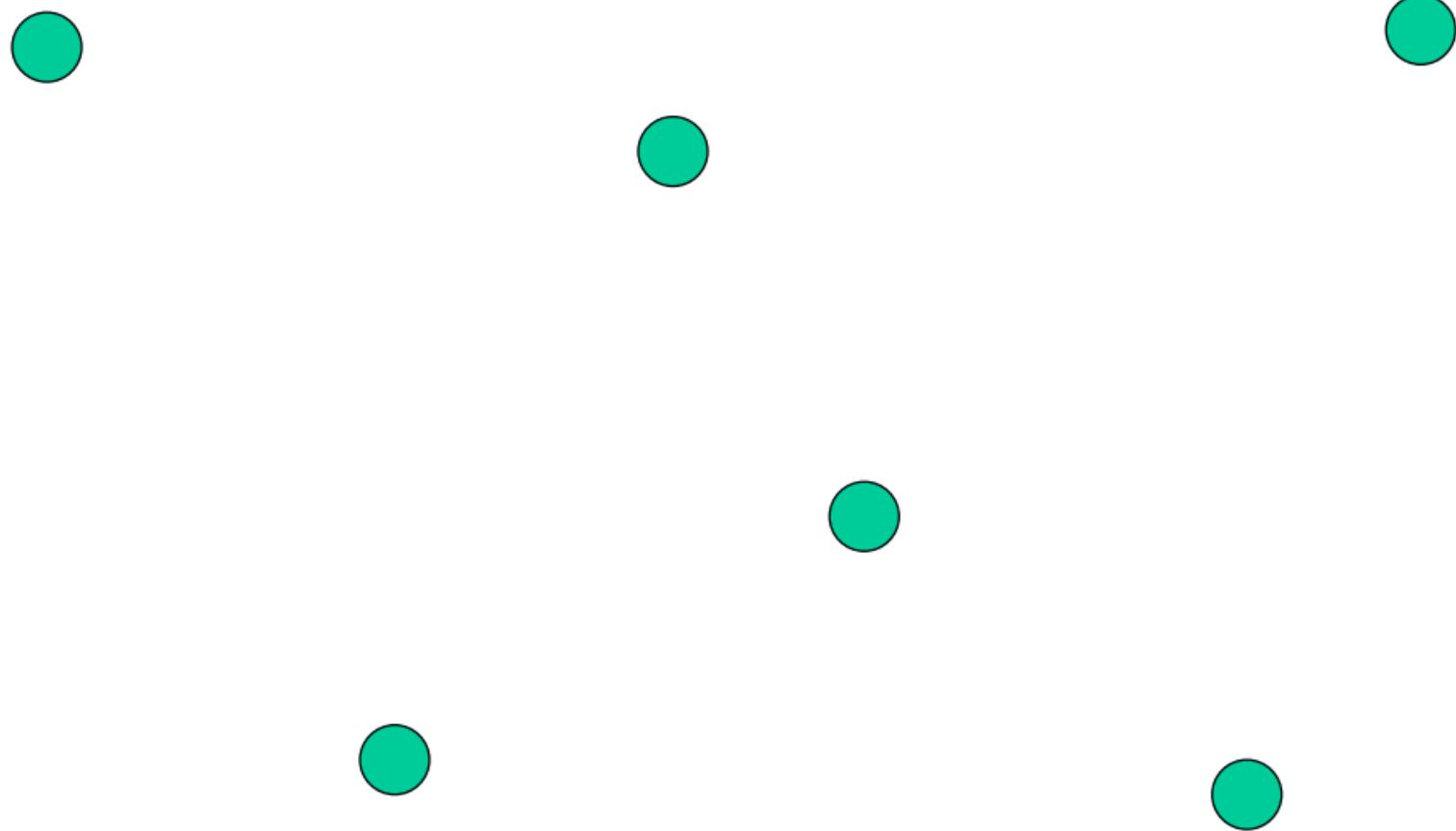
I. Random Waypoint (*RWP*) Model

1. A node chooses a random destination anywhere in the network field
2. The node moves towards that destination with a velocity chosen randomly from $[0, V_{max}]$
3. After reaching the destination, the node stops for a duration defined by the “pause time” parameter.
4. This procedure is repeated until the simulation ends
 - Parameters: Pause time T , max velocity V_{max}
 - Comments:
 - Speed decay problem, non-uniform node distribution
 - Variants: random walk, random direction, smooth random, ...

Random Way Point: Basics



Random Way Point: Example



II. Random (*RWK*) Walk Model

- Similar to RWP but
 - Nodes change their speed/direction every time slot
 - New direction θ is chosen randomly between $(0, 2\pi]$
 - New speed chosen from uniform (or Gaussian) distribution
 - When node reaches boundary it bounces back with $(\pi - \theta)$

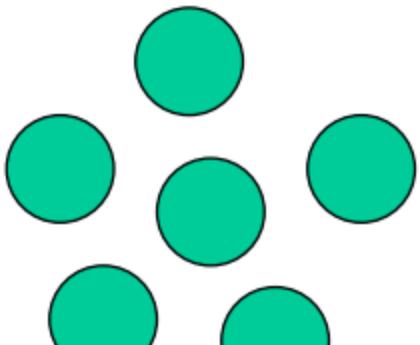
Random Walk



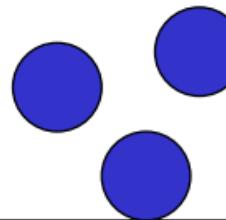
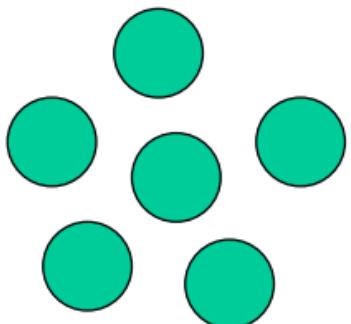


III. Reference Point Group Mobility (*RPGM*)

- Nodes are divided into groups
- Each group has a leader
- The leader's mobility follows random way point
- The members of the group follow the leader's mobility closely, with some deviation
- Examples:
 - Group tours, conferences, museum visits
 - Emergency crews, rescue teams
 - Military divisions/platoons

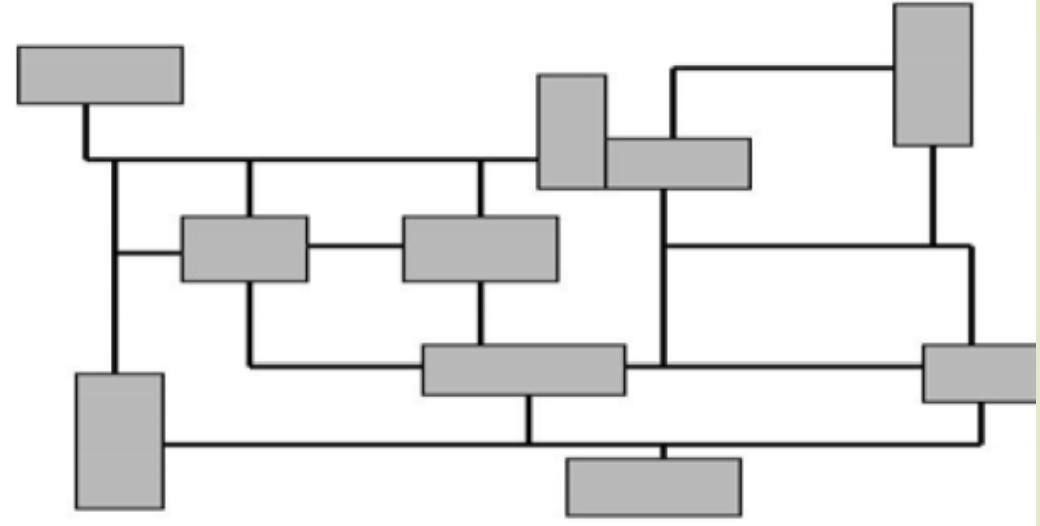


Group Mobility: Multiple Groups



IV. Obstacle/Pathway Model

- Obstacles/bldgs map
- Nodes move on pathways between obstacles
- Nodes may enter/exit buildings
- Pathways constructed by computing Voronoi graph (i.e., pathways equidistant to nearby buildings)
- Obstacles affect communication
 - Nodes on opposite sides (or in/outside) of a building cannot communicate



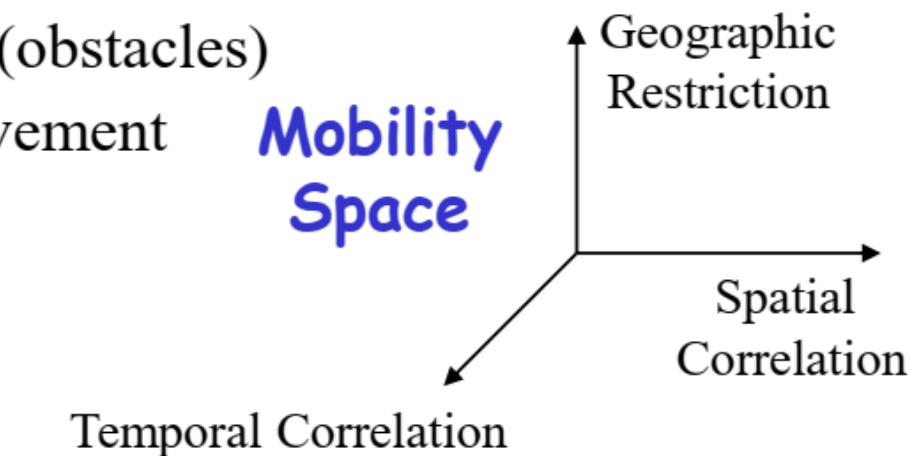
(c) Pathway Graph on a Campus

V. Related Real-world Mobility Scenarios

- Pedestrian Mobility
 - University or business campuses
 - Usually mixes group and RWP models, with obstacles and pathways
- Vehicular Mobility
 - Urban streets (Manhattan-like)
 - Freeways
 - Restricted to streets, involves driving rules

Motivation

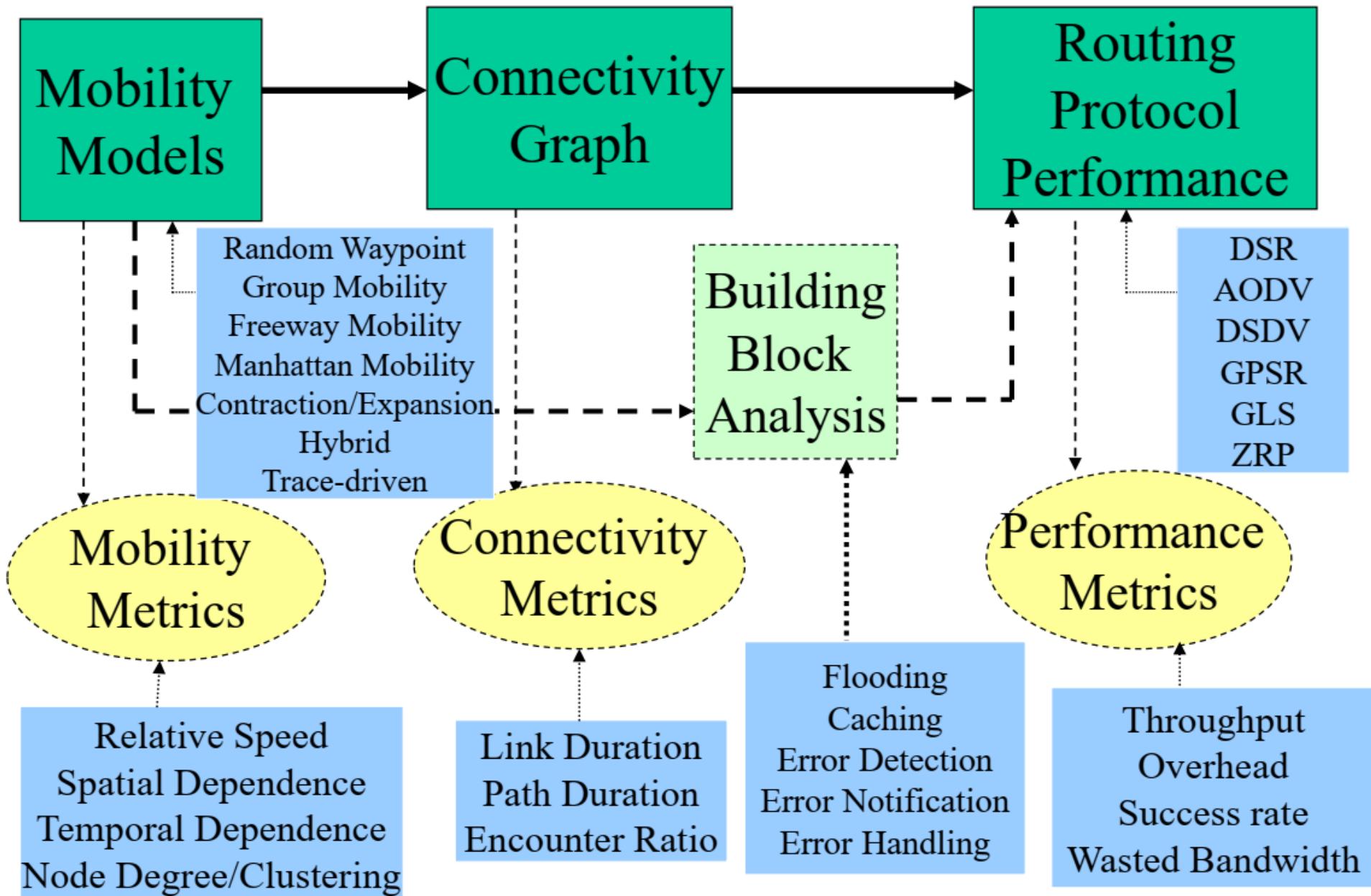
- Randomized models (e.g., random waypoint) do not capture
 - (I) Existence of geographic restriction (obstacles)
 - (II) Temporal dependence of node movement (correlation over history)
 - (III) Spatial dependence (correlation) of movement among nodes
- A systematic framework is needed to investigate the impact of various mobility models on the performance of different routing protocols for MANETs
- This study attempts to answer
 - What are key characteristics of the mobility space?
 - Which metrics can compare mobility models in a meaningful way?
 - Whether mobility matters? To what degree?
 - If the answer is yes, why? How?



Framework Goals (Questions to Answer)

- Whether mobility matters? and How much does it matter?
 - Rich set of mobility models that capture characteristics of different types of movement
 - Protocol independent metrics such as mobility metrics and connectivity graph metrics to capture the above characteristics
- Why?
 - Analysis process to relate performance with a specific characteristic of mobility via connectivity metrics
- How?
 - Systematic process to study the performance of protocol mechanistic building blocks (*BRICS*) across various mobility characteristics

The IMPORTANT Framework Overview



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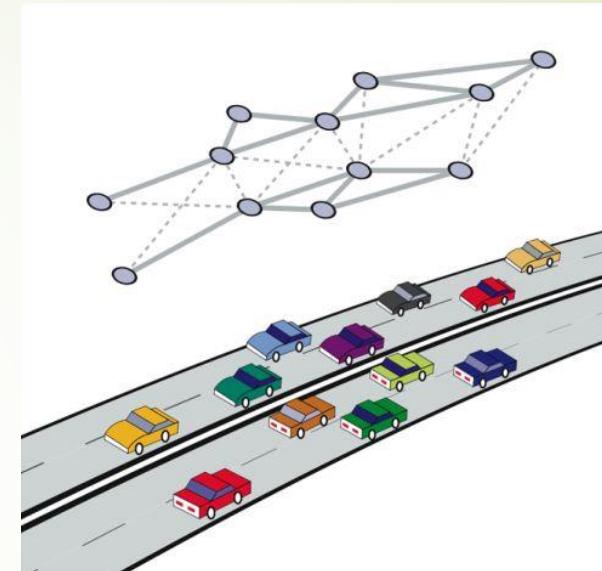
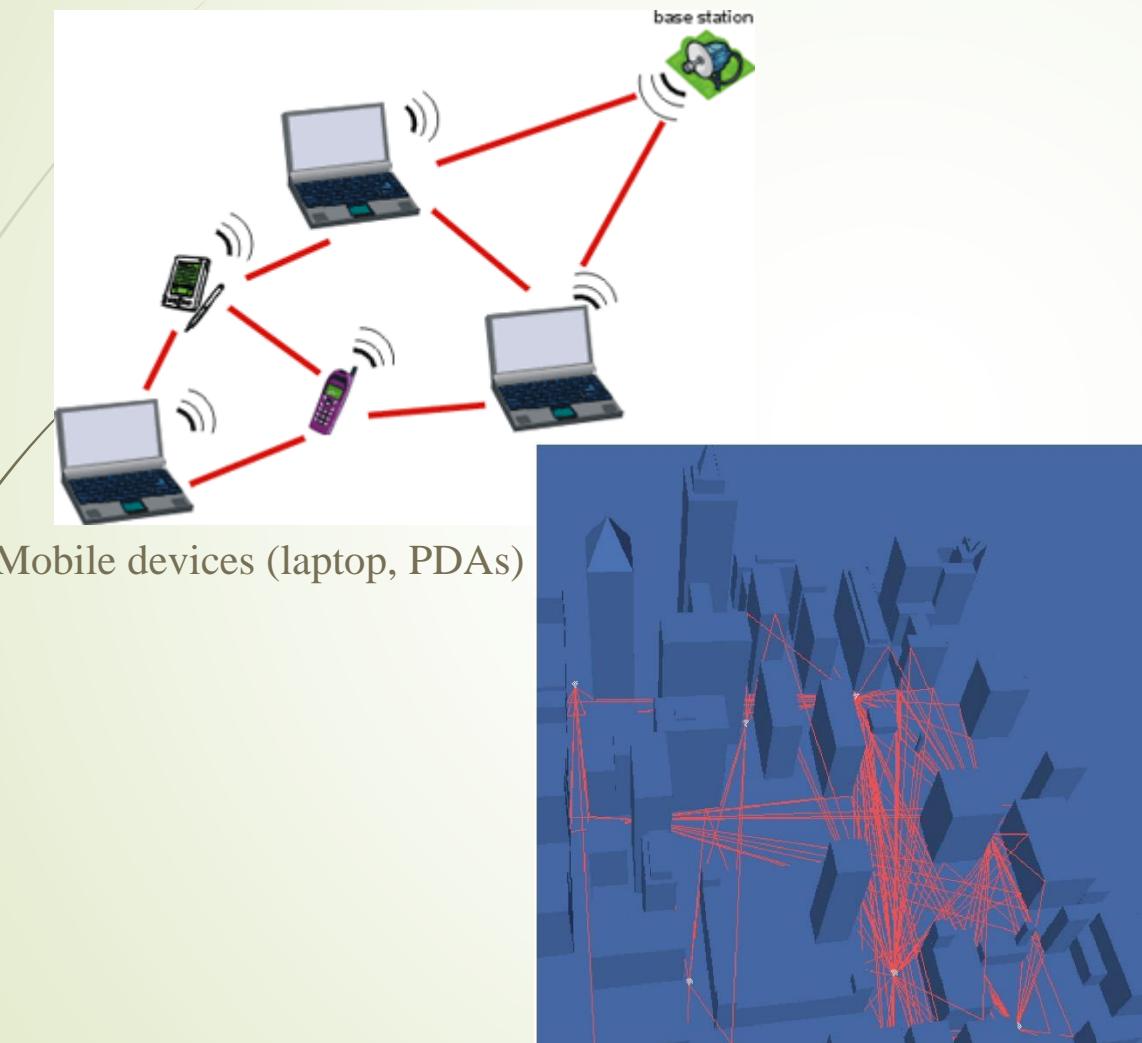
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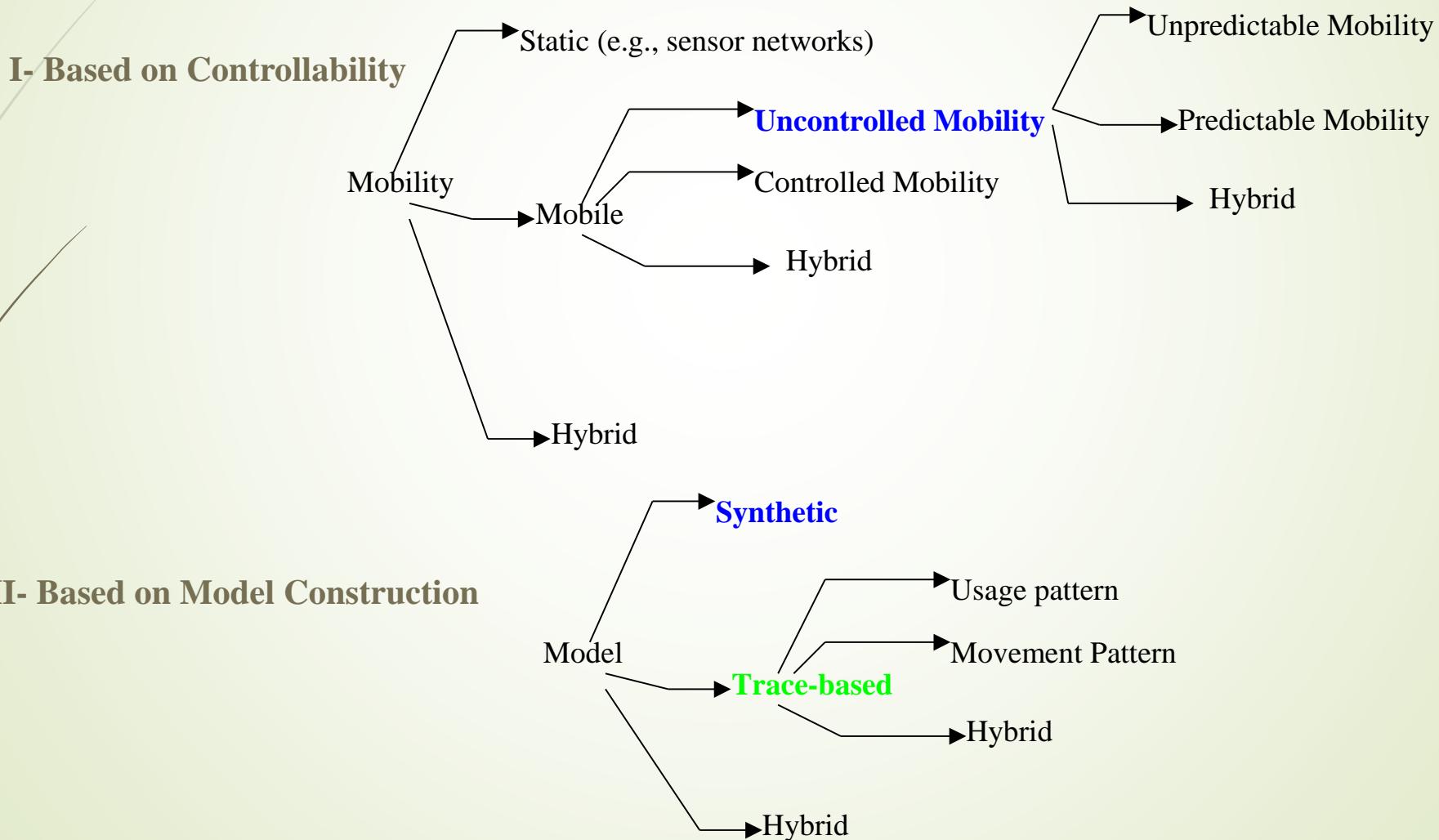
Example Ad hoc Networks



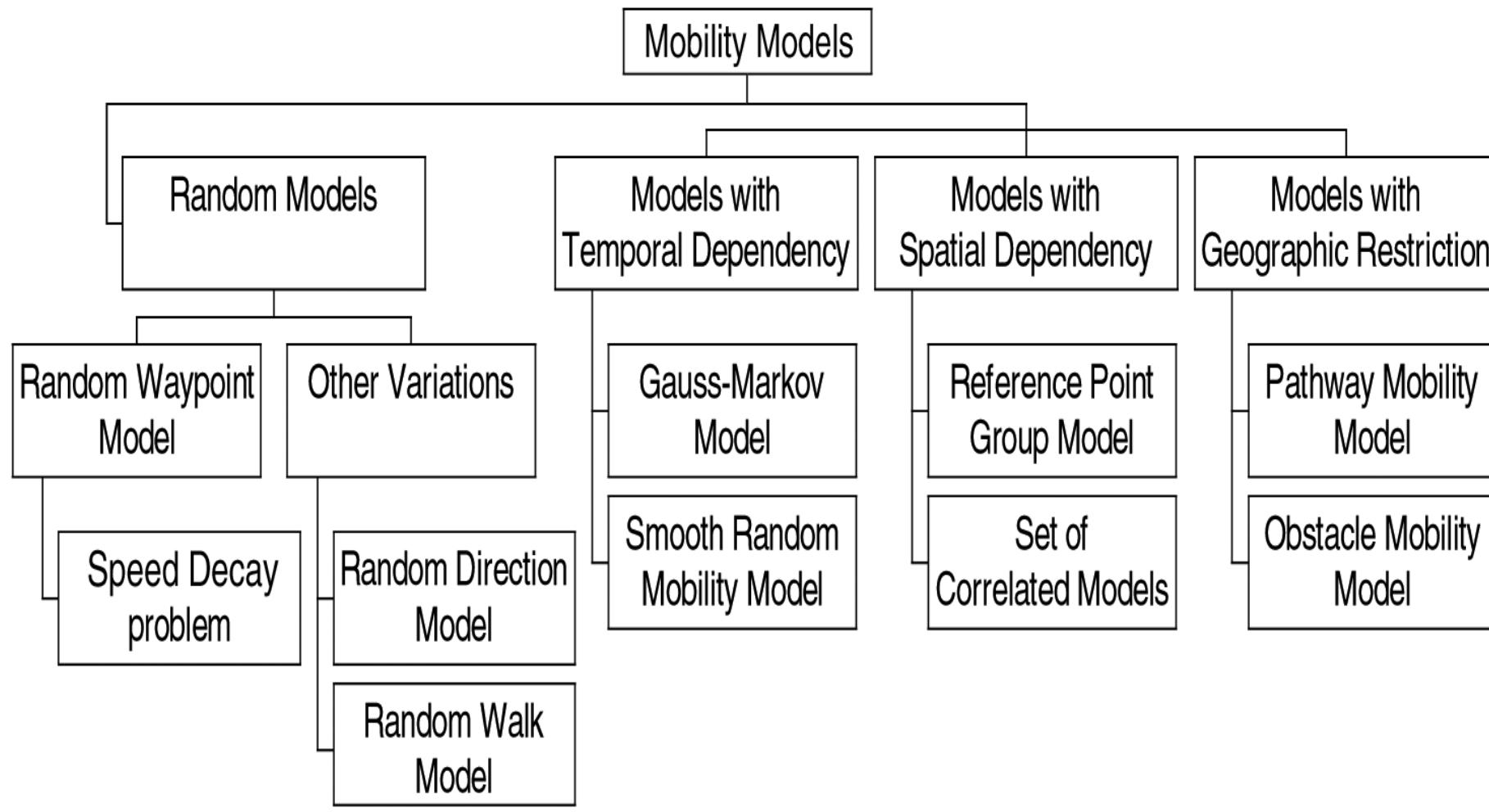
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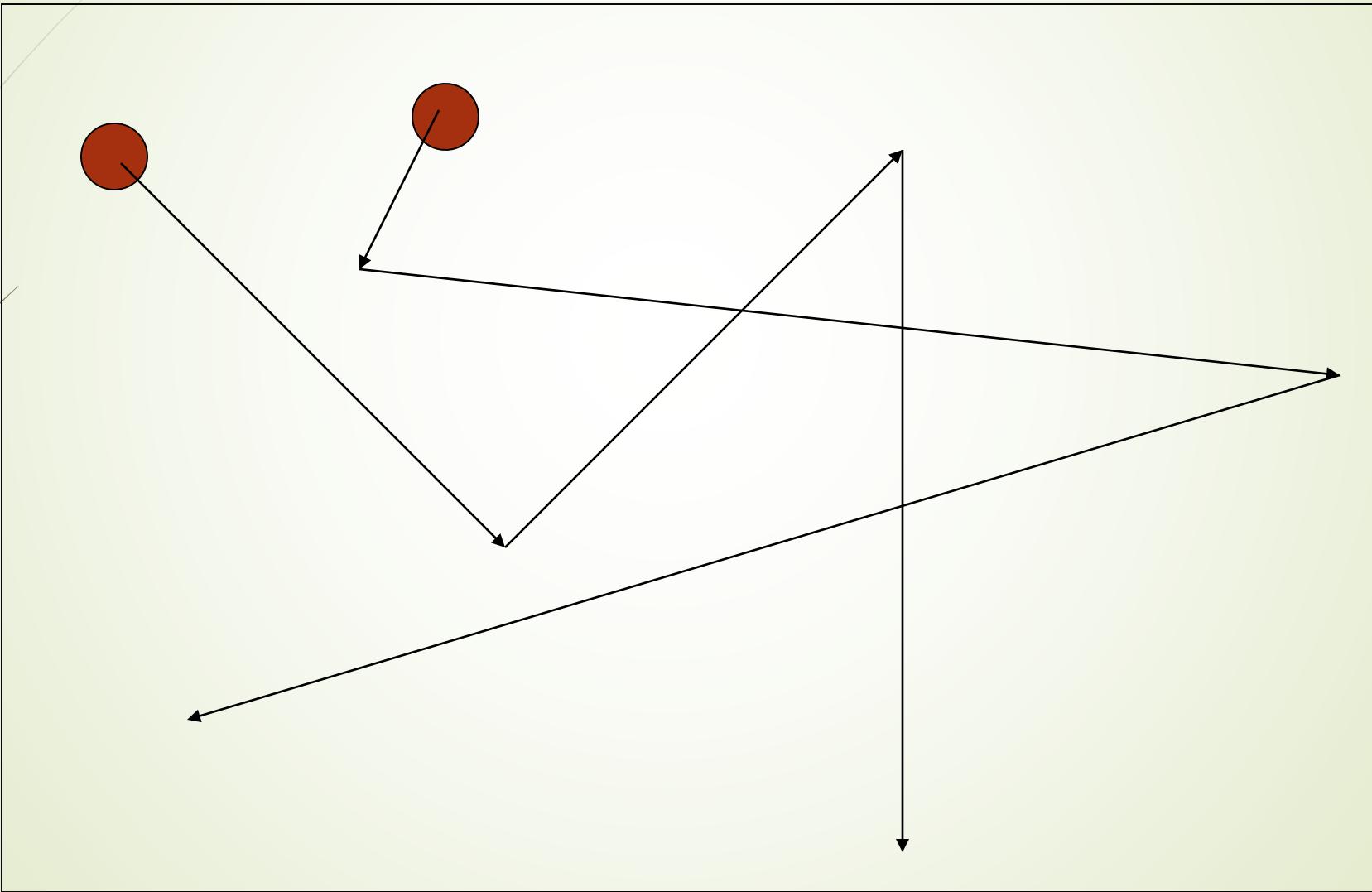


* F. Bai, A. Helmy, "A Survey of Mobility Modeling and Analysis in Wireless Adhoc Networks", Book Chapter in the book "Wireless Ad Hoc and Sensor Networks", Kluwer Academic Publishers, June 2004.

I. Random Waypoint (RWP) Model

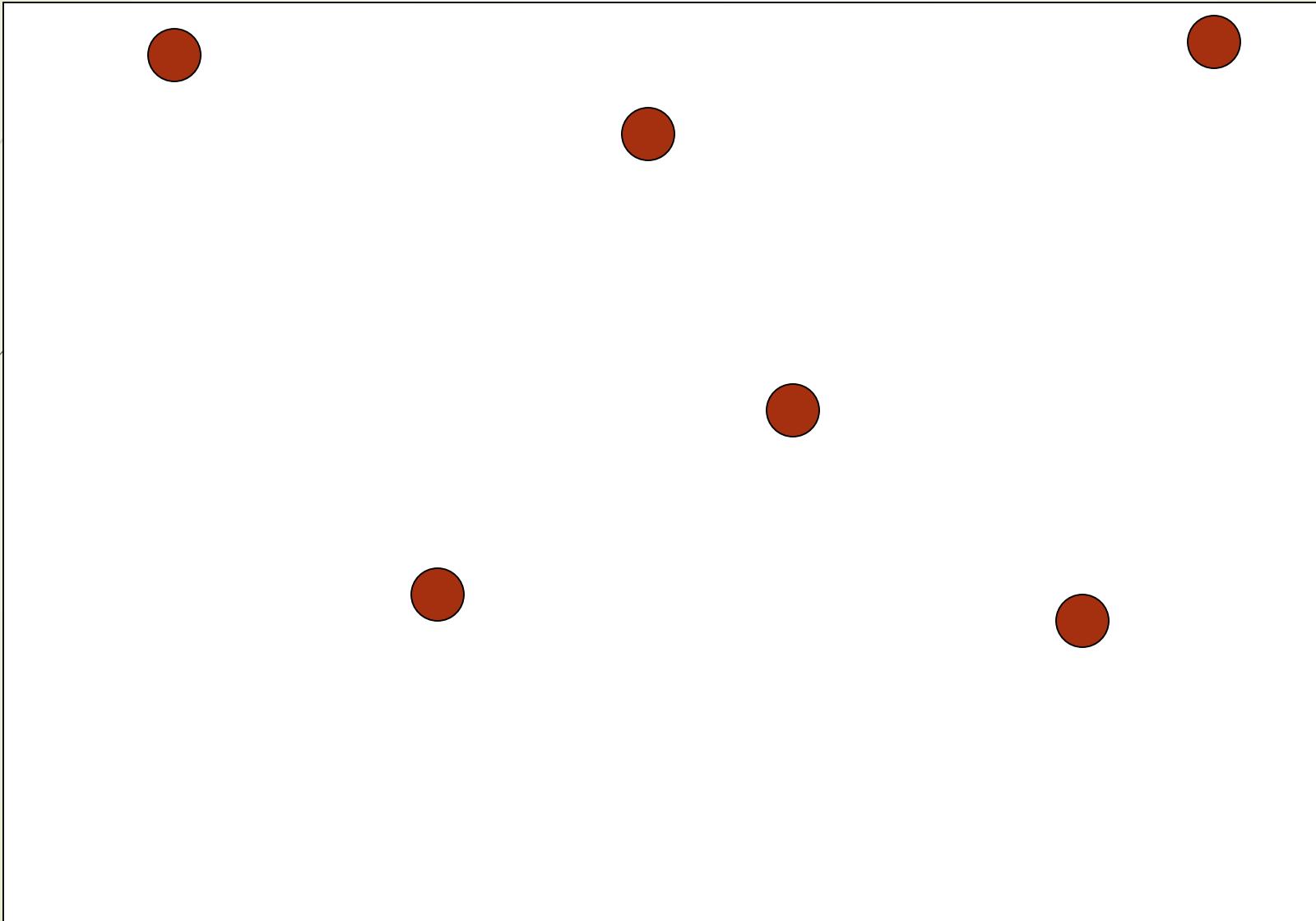
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4. This procedure is repeated until the simulation ends
 - ▶ Parameters: Pause time T , max velocity V_{max}
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 - ▶ non-uniform node distribution
 - ▶ Variants: random walk, random direction, smooth random, ...

Random Way Point: Basics





Random Way Point: Example



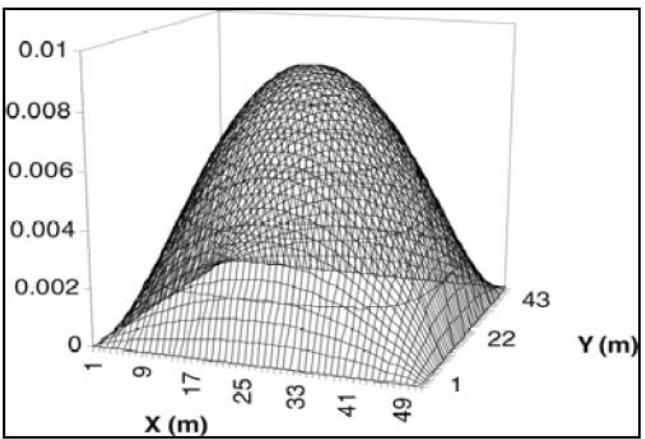


Figure 1-3. Node Spatial Distribution (Square Area)

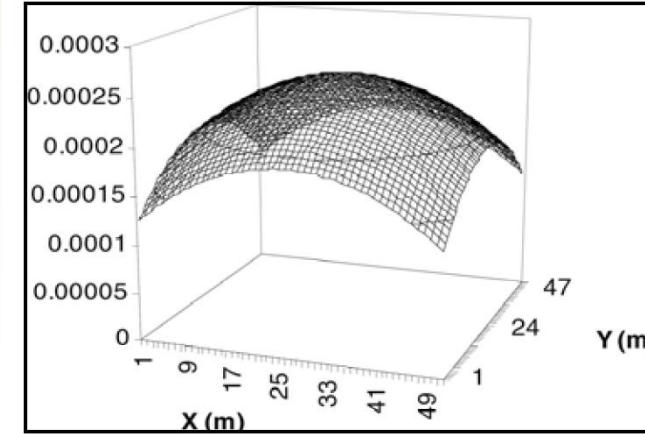


Figure 1-4. Node Spatial Distribution (Circular Area)

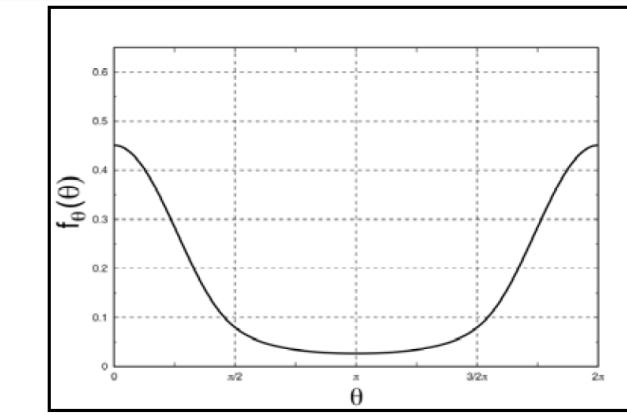


Figure 1-5. The probability distribution of movement direction

- 1- RWP leads to non-uniform distribution of nodes due to bias towards the center of the area, due to non-uniform direction selection. To remedy this the “random direction” mobility model can be chosen.
- 2- Average speed decays over time due to nodes getting ‘stuck’ at low speeds

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 - ▶ Nodes change their **speed/direction every time slot**
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Random Walk

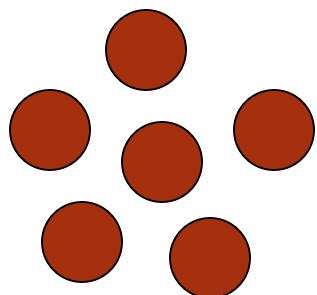




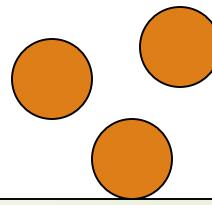
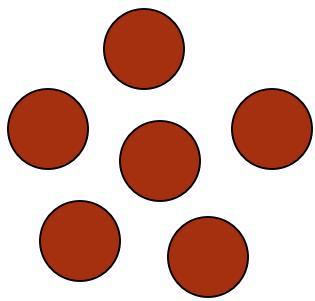
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Group Mobility: Single Group

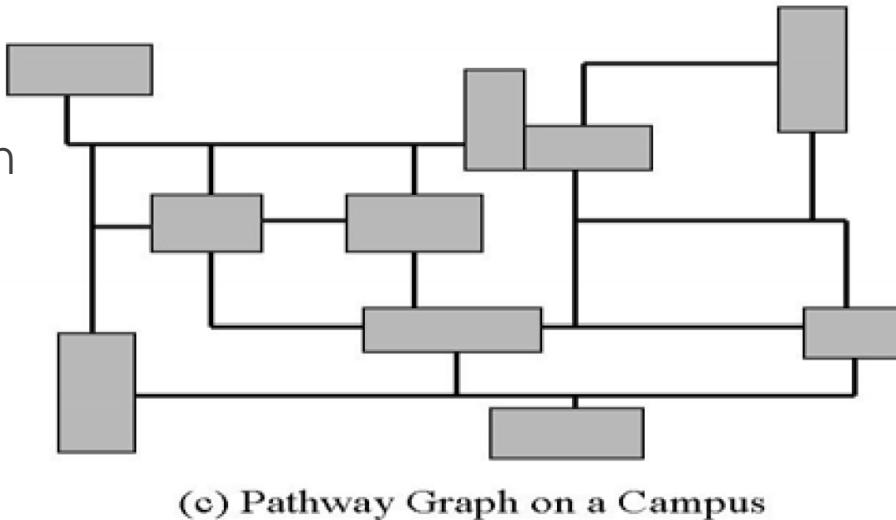


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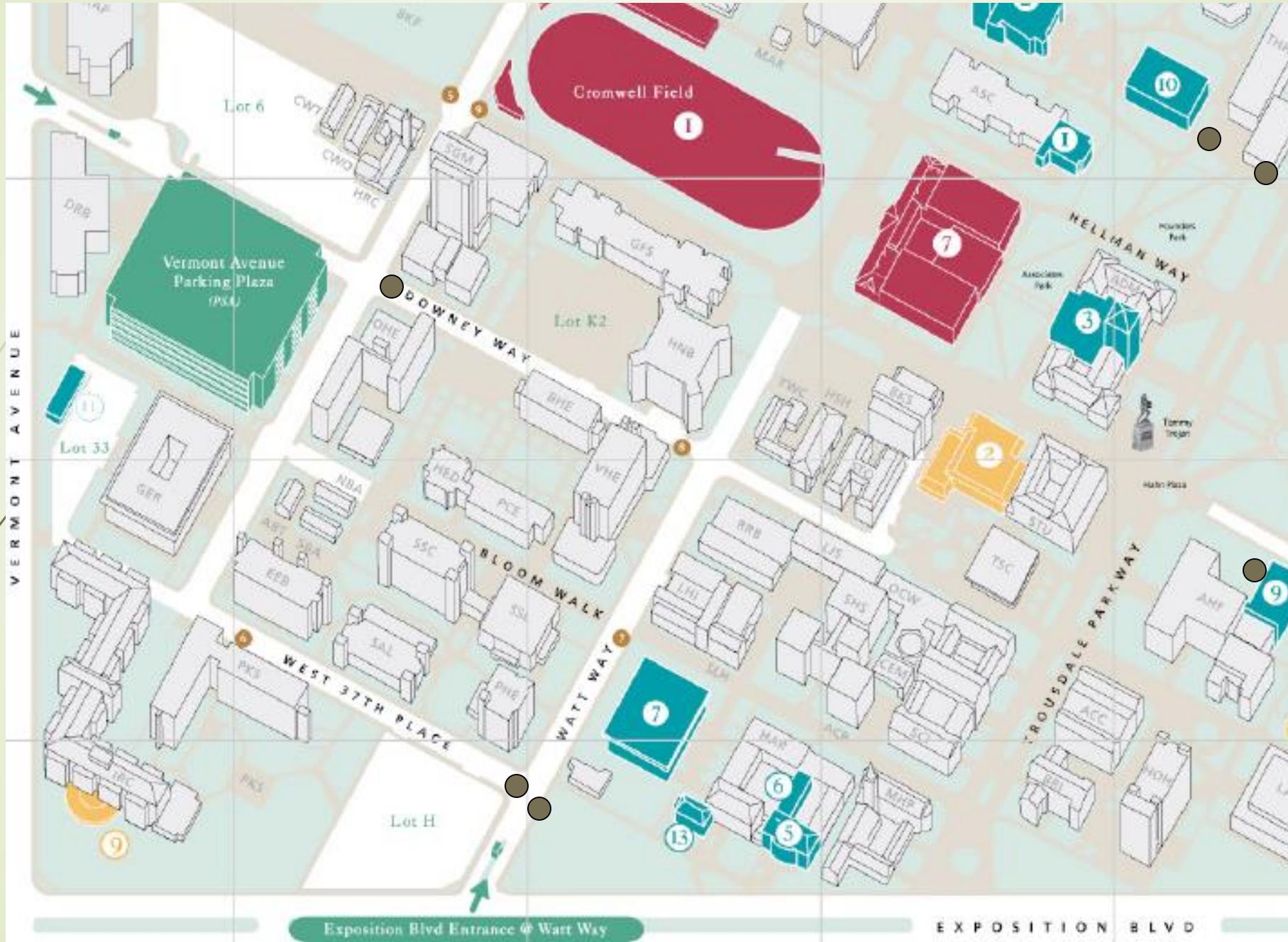
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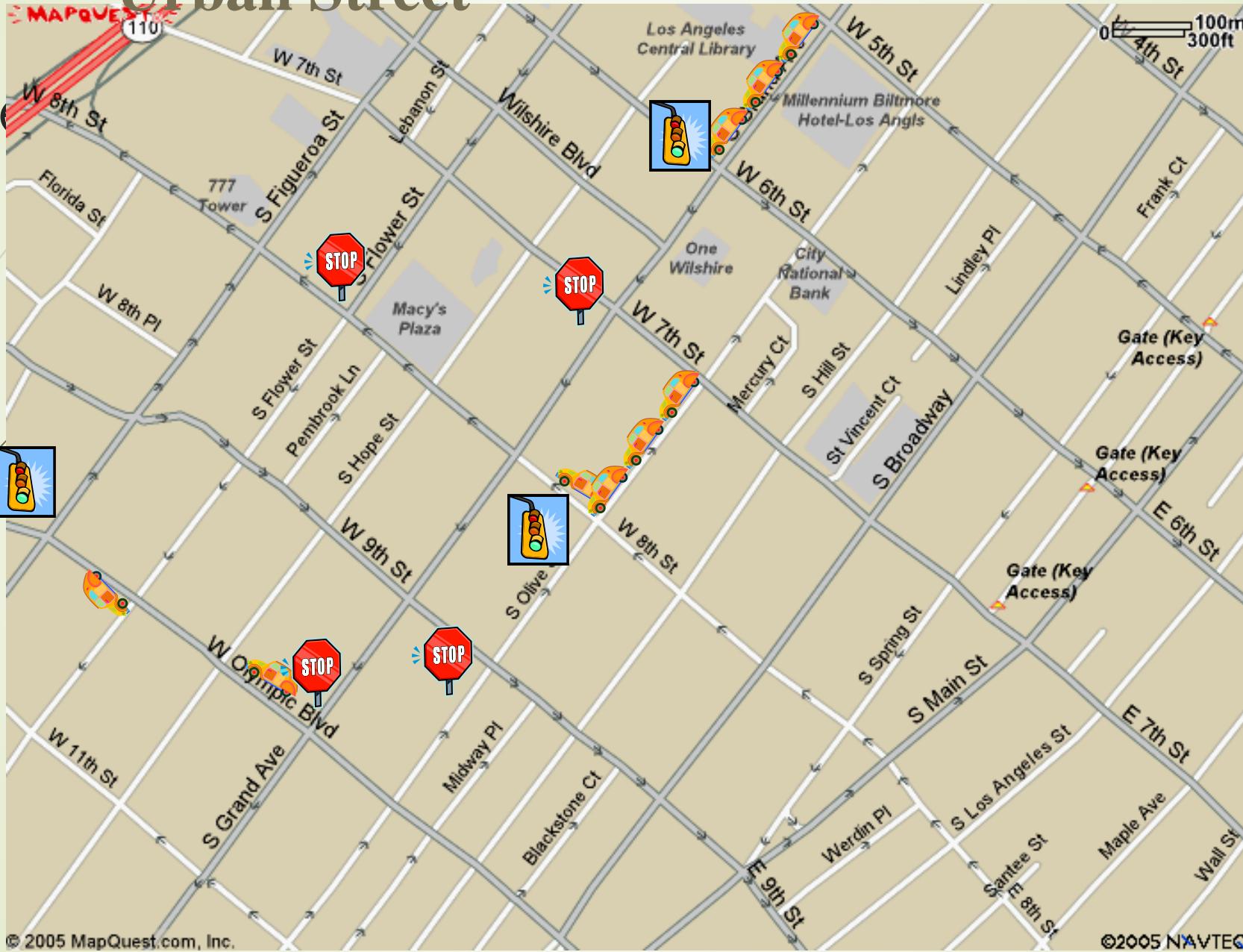
► **Vehicular Mobility**

- Urban streets (Manhattan-like)
- Freeways
- Restricted to streets, involves driving rules

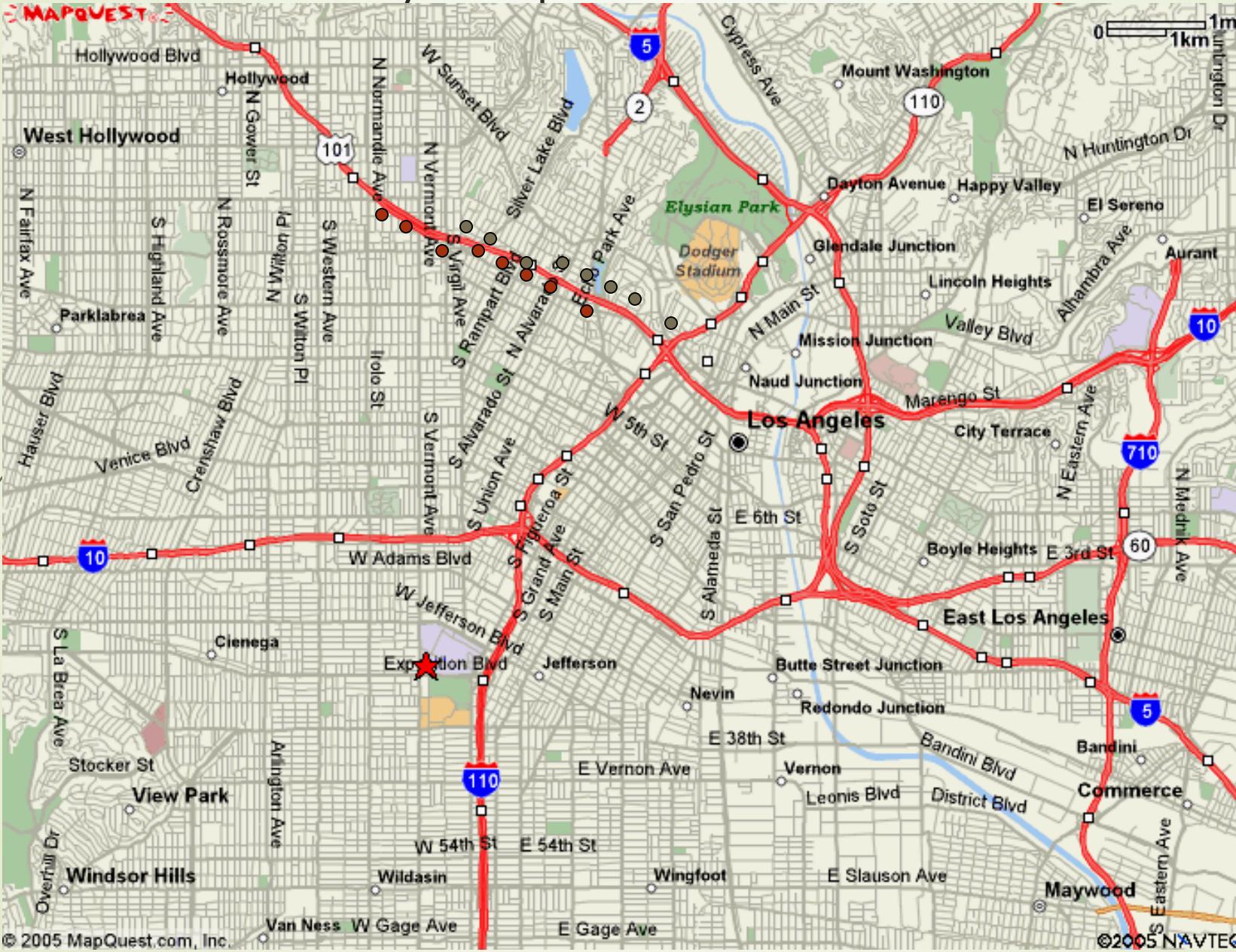


Urban Street

Street

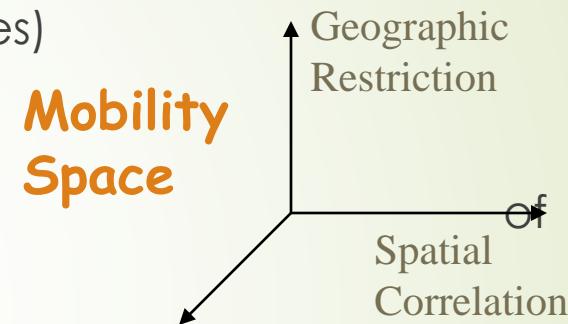


Freeway Map



Motivation

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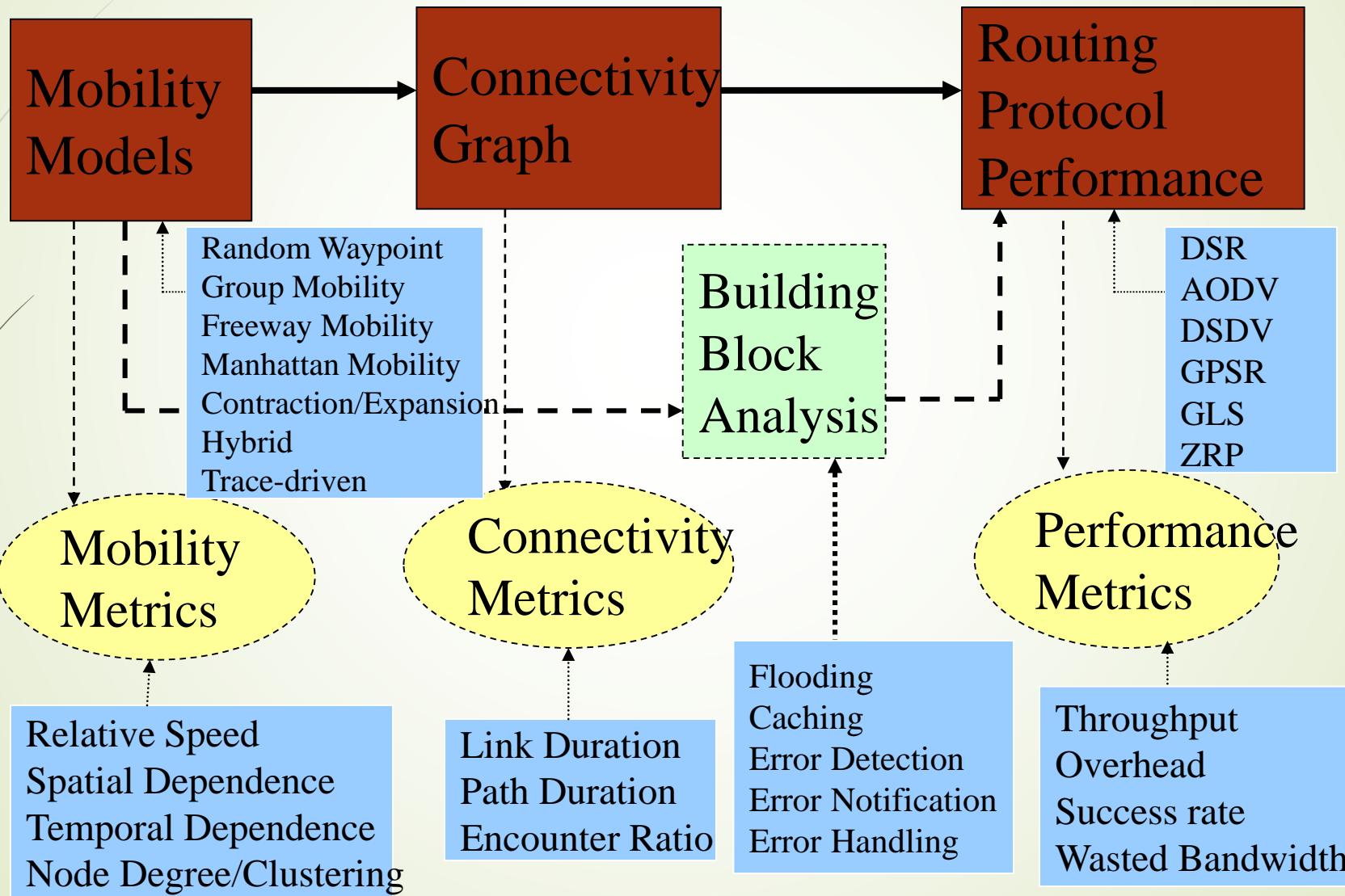


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The **IMPORTANT** Framework Overview



Mobility Metrics

► Relative Speed (mobility metric I)

- The magnitude of relative speed of two nodes, averaged over all neighborhood pairs and all time

$$\overline{RS} = \frac{1}{P} \sum_{t=0}^T \sum_{i=1}^N \sum_{\substack{j=1 \\ j \neq i}}^N |\vec{v}(i,t) - \vec{v}(j,t)| \quad \text{if } dist((x_i, y_i), (x_j, y_j)) \leq 2R$$

► Spatial Dependence (mobility metric II)

- The value of extent of similarity of the velocities/dir of two nodes that are not too far apart, averaged over all neighborhood pairs and all time

$$\overline{D}_{spatial} = \frac{1}{P} \sum_{t=0}^T \sum_{i=1}^N \sum_{\substack{j=1 \\ j \neq i}}^N \frac{\min(\vec{v}(i,t), \vec{v}(j,t))}{\max(\vec{v}(i,t), \vec{v}(j,t))} \times \frac{\vec{v}(i,t) \bullet \vec{v}(j,t)}{|\vec{v}(i,t)| |\vec{v}(j,t)|} \quad \text{if } dist((x_i, y_i), (x_j, y_j)) \leq 2R$$

For example, RWP model, Vmax=30m/s, RS=12.6m/s, D_{spatial}=0.03

Connectivity Graph Metrics

- ▶ Average link duration (connectivity metric I)
 - ▶ The value of link duration, averaged over all nodes pairs

$$\overline{LD} = \frac{1}{P} \sum_{i=1}^N \sum_{\substack{j=1 \\ j \neq i}}^N LD(i, j) \quad \text{if there is a link between } i \text{ and } j$$

- ▶ Link/Path duration distributions (PATHS study)

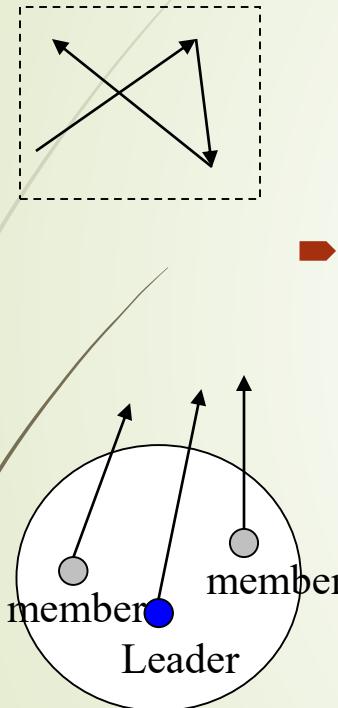
Protocol Performance Metrics

- Throughput: delivery ratio
- Overhead: number of routing control packets sent

Mobility Models Summary

	Application	Spatial Dependence	Geographic Restriction
Random Waypoint Model	General (uncorrelated straight lines)	No	No
Group Mobility Model	Conventions, Campus	Yes	No
Freeway Mobility Model	Metropolitan Traffic/Vehicular	Yes	Yes
Manhattan Mobility Model	Urban Traffic/Vehicular	No	Yes

Parameterized Mobility Models



► Random Waypoint Model (RWP)

- Each node chooses a random destination and moves towards it with a random velocity chosen from $[0, V_{max}]$. After reaching the destination, the node stops for a duration defined by the “pause time” parameter. This procedure is repeated until simulation ends
- Parameters: Pause time T , max velocity V_{max}

► Reference Point Group Model (RPGM)

- Each group has a logical center (group leader) that determines the group’s motion behavior
- Each nodes within group has a speed and direction that is derived by randomly deviating from that of the group leader

$$|\vec{V}_{member}(t)| = |\vec{V}_{leader}(t)| + \text{random}() \times SDR \times V_{max}$$

$$\theta_{member}(t) = \theta_{leader}(t) + \text{random}() \times ADR \times \theta_{max}$$

- Parameters: Angle Deviation Ratio(ADR) and Speed Deviation Ratio(SDR), number of groups, max velocity V_{max} . In our study, $ADR=SDR=0.1$
- In our study, we use two scenarios: Single Group (SG) and Multiple Group (MG)

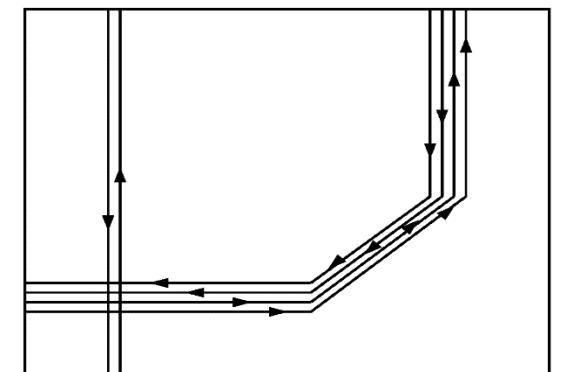
Parameterized Mobility Models

► Freeway Model (FW)

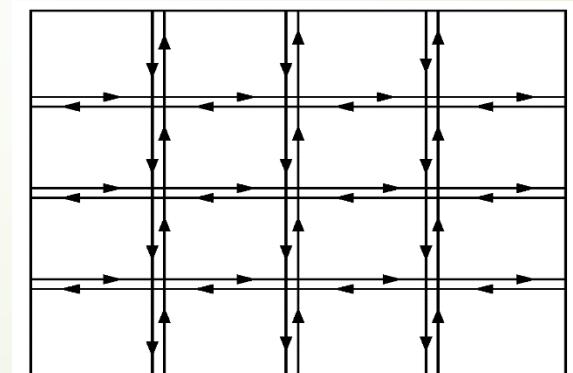
- Each mobile node is restricted to its lane on the freeway
- The velocity of mobile node is temporally dependent on its previous velocity
- If two mobile nodes on the same freeway lane are within the Safety Distance (SD), the velocity of the following node cannot exceed the velocity of preceding node
- Parameter: Map layout, V_{max}

► Manhattan Model (MH)

- Similar to Freeway model, but it allows node to make turns at each corner of street
- Parameter: Map layout, V_{max}



Map for FW



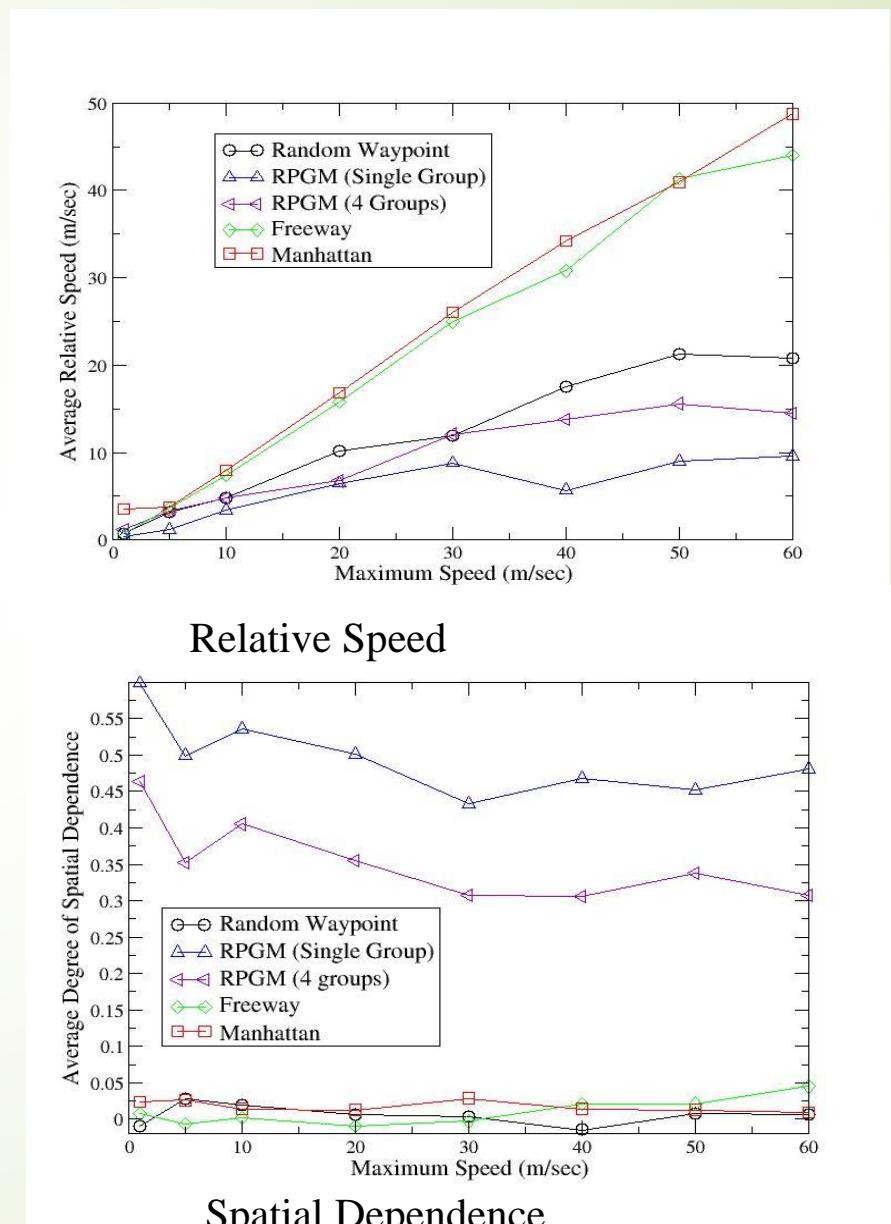
Map for MH

Experiment I: Analysis of mobility characteristics

- IMPORTANT mobility tool
 - integrated with NS-2 (released Jan '04, Aug '05)
 - <http://nile.cise.ufl.edu/important>
- Simulation done using our mobility generator and analyzer
 - Number of nodes(N) = 40, Simulation Time(T) = 900 sec
 - Area = 1000m x 1000m
 - Vmax set to 1,5,10,20,30,40,50,60 m/sec across simulations
 - RWP, pause time T=0
 - SG/MG, ADR=0.1, SDR=0.1
 - FW/MH, map layout in the previous slide

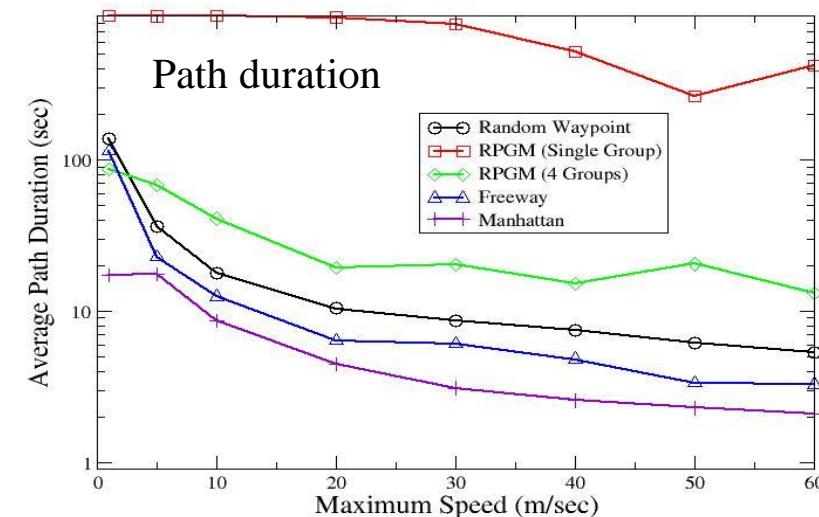
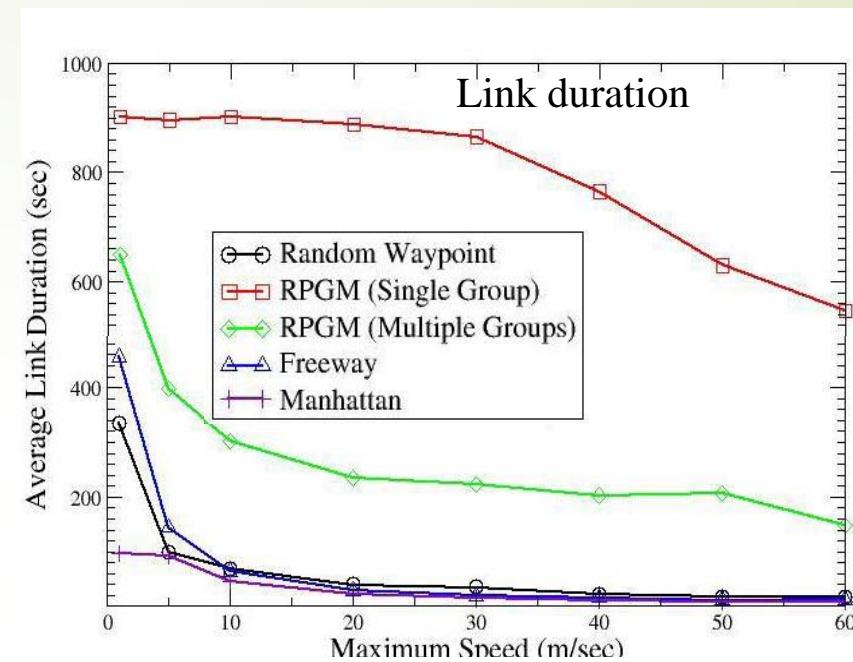
Mobility metrics

- ▶ Objective:
 - ▶ validate whether proposed mobility models span the mobility space we explore
- ▶ Relative speed
 - ▶ For same Vmax, MH/FW is higher than RWP, which is higher than SG/MG
- ▶ Spatial dependence
 - ▶ For SG/MG, strong degree of spatial dependence
 - ▶ For RWP/FW/MH, no obvious spatial dependence is observed



Connectivity Graph Metrics

- ▶ Link duration
 - ▶ For same Vmax, SG/MG is higher than RWP, which is higher than FW, which is higher than MH
- ▶ Summary
 - ▶ Freeway and Manhattan model exhibits a high relative speed
 - ▶ Spatial Dependence for group mobility is high, while it is low for random waypoint and other models
 - ▶ Link Duration for group mobility is higher than Freeway, Manhattan and random waypoint for Path duration



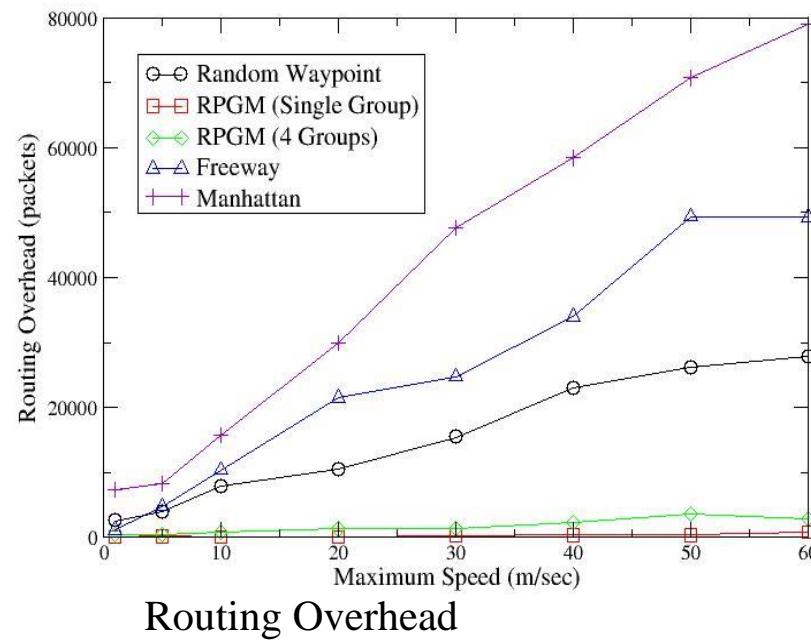
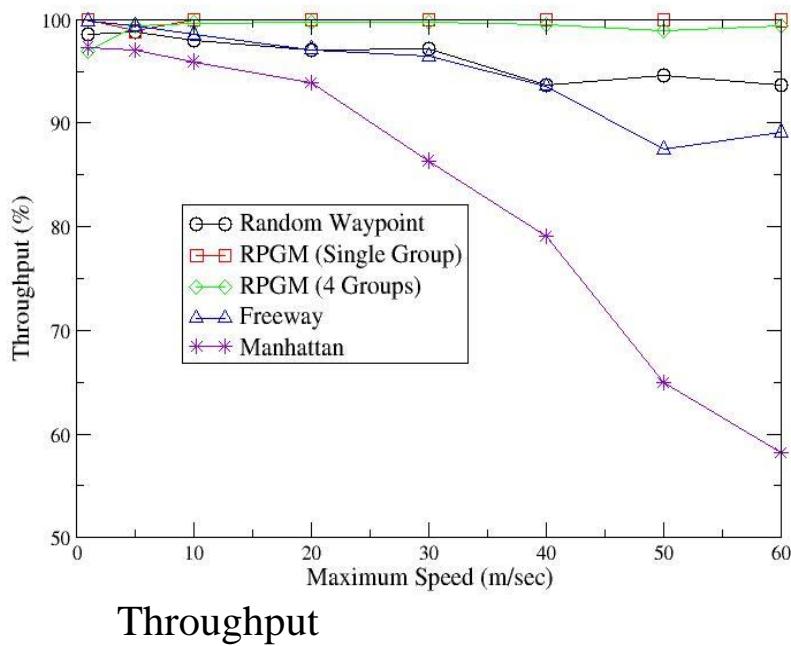
Experiment II: Protocol Performance across Mobility Models

Simulations done in ns-2:

- Routing protocols: DSR, AODV, DSDV
- Same set of mobility trace files used in experiment1
- Traffic pattern consists of source-destination pairs chosen at random
- 20 source, 30 connections, CBR traffic
- Data rate is 4packets/sec (low data rate to avoid congestion)
- For each mobility trace file, we vary traffic patterns and run the simulations for 3 times

Results and Observations

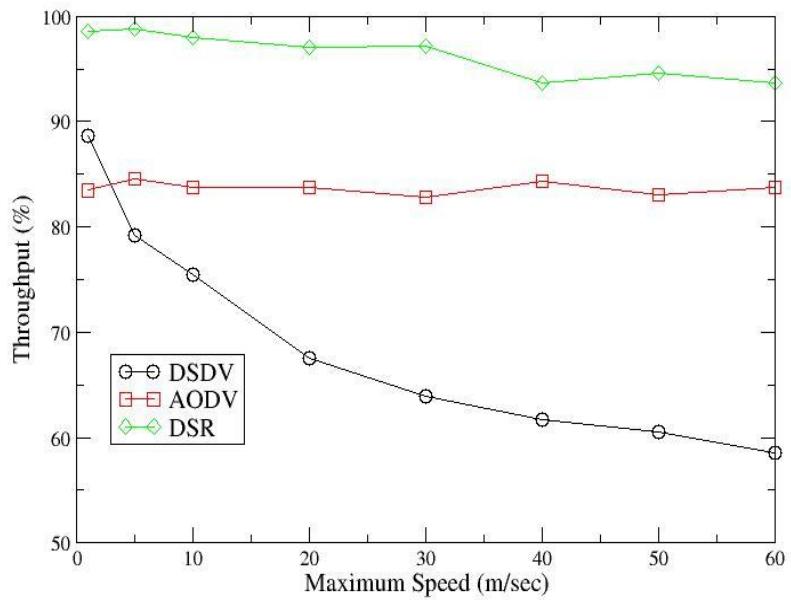
- Performance of routing protocols may vary drastically across mobility patterns (Example for DSR)



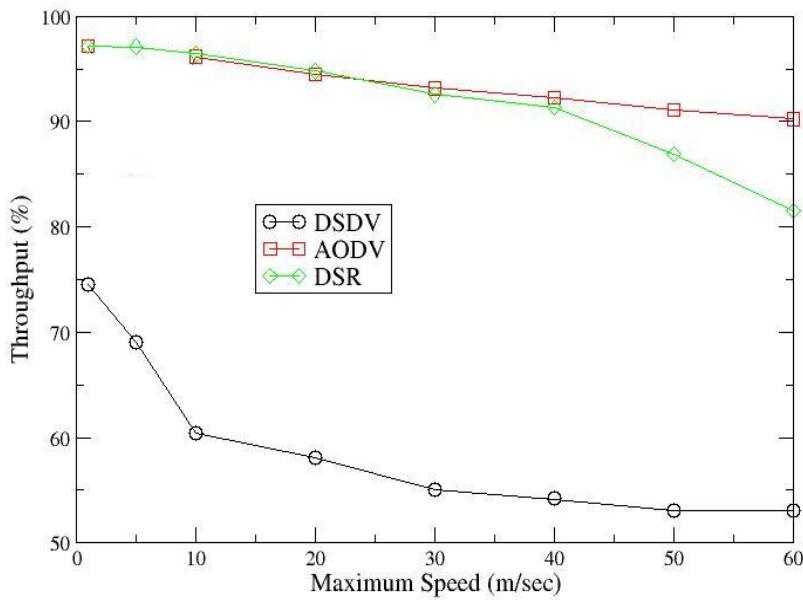
- There is a difference of 40% for throughput and an order of magnitude difference for routing overhead across mobility models!

Which Protocol Has the Highest Throughput ?

- We observe that using different mobility models may alter the ranking of protocols in terms of the throughput!



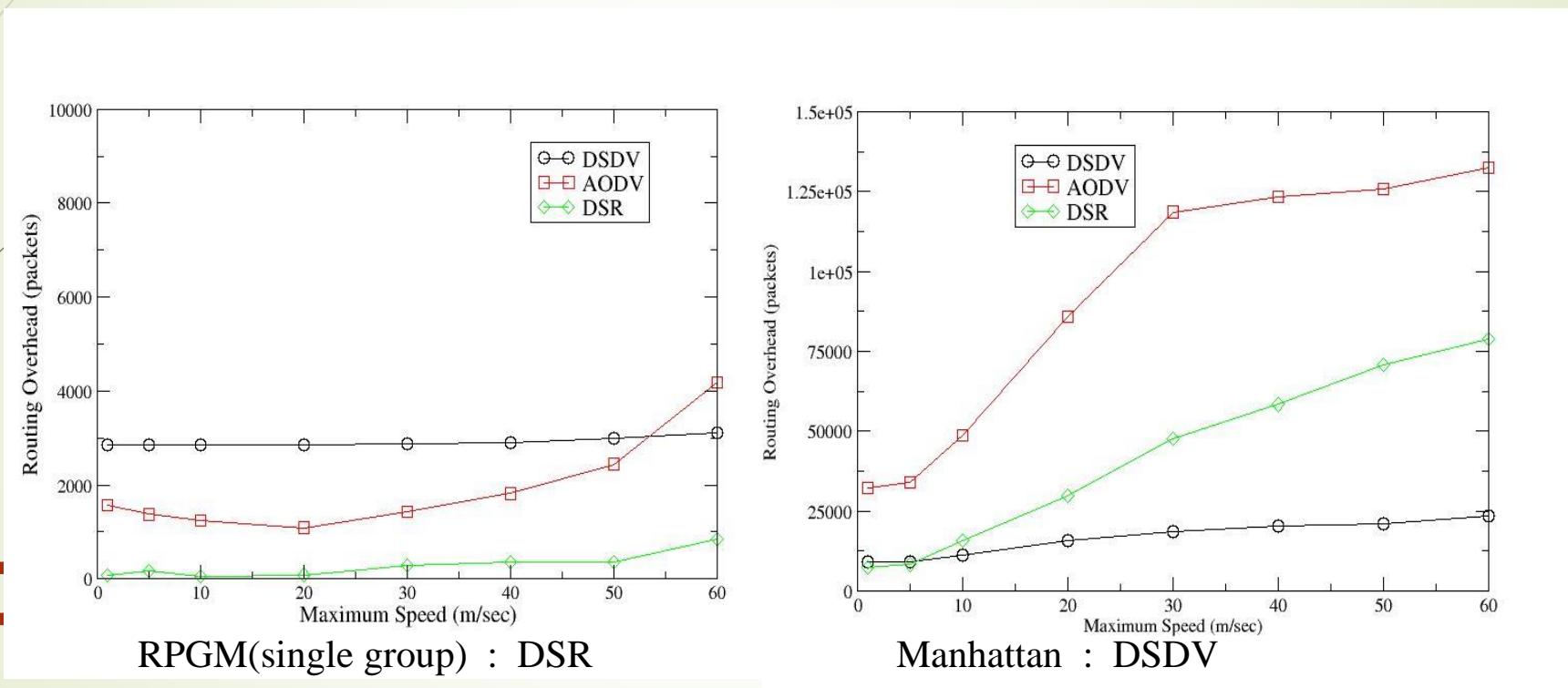
Random Waypoint : DSR



Manhattan : AODV !

Which Protocol Has the Lowest Overhead ?

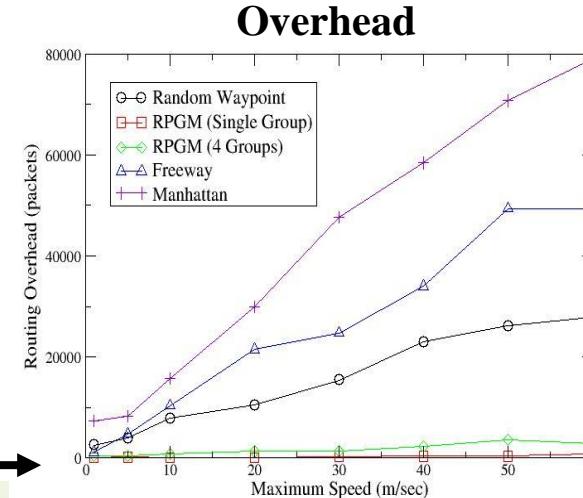
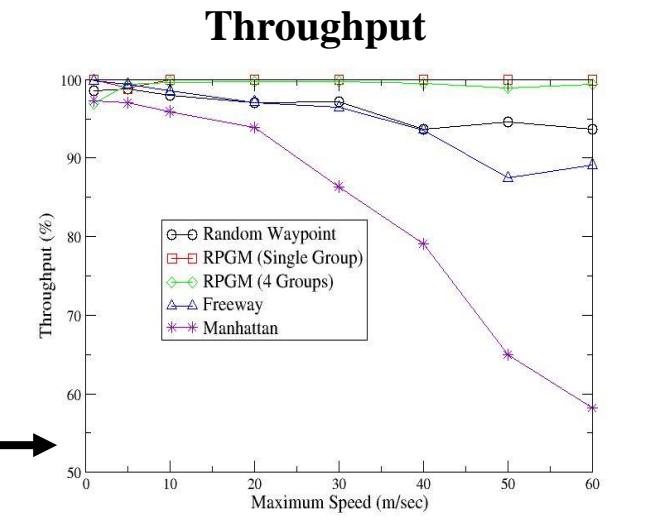
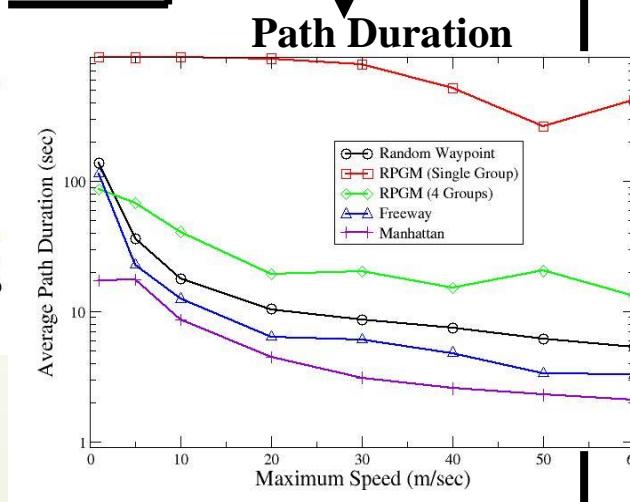
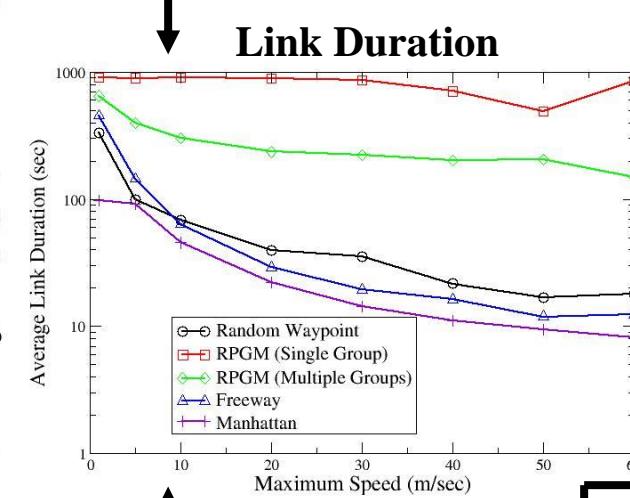
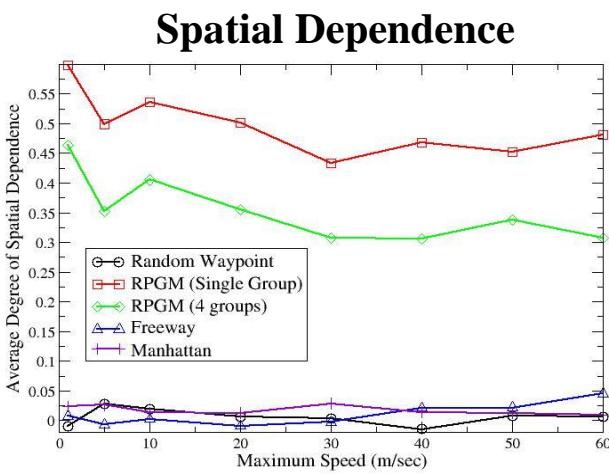
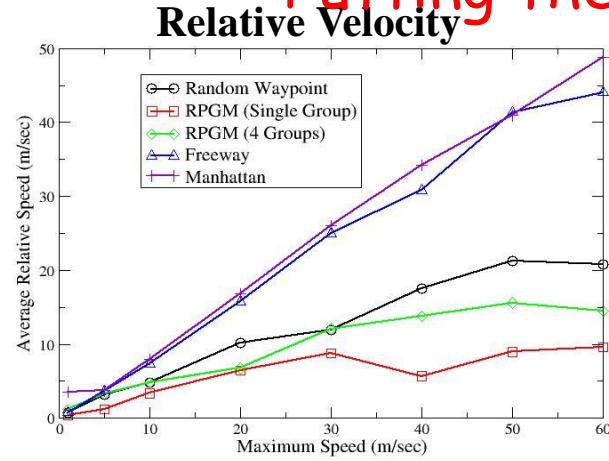
- We observe that using different mobility models may alter the ranking of protocols in terms of the routing overhead!



Putting the Pieces Together

- ▶ Why does mobility affect protocol performance?
- ▶ We observe a very clear trend between mobility metric, connectivity and performance
 - ▶ With similar average spatial dependency
 - ▶ Relative Speed increases → Link Duration decreases → Routing Overhead increases and throughput decreases
 - ▶ With similar average relative speed
 - ▶ Spatial Dependence increase → Link Duration increases → Throughput increases and routing overhead decreases
- ▶ Conclusion: **Mobility Metrics influence Connectivity Metrics which in turn influence protocol performance metrics !**

Putting the Pieces Together

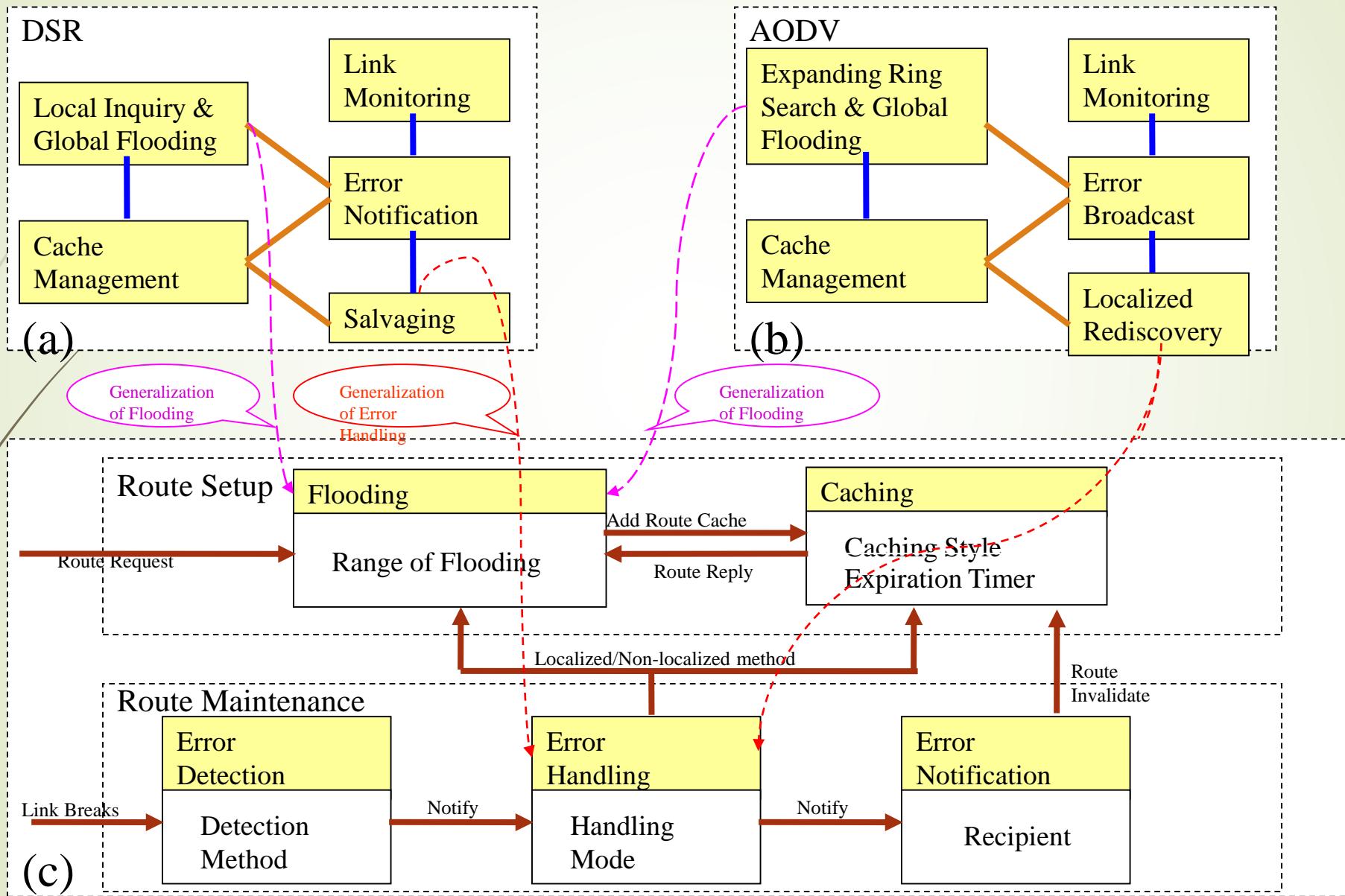


Mechanistic Building Blocks (BRICS) *

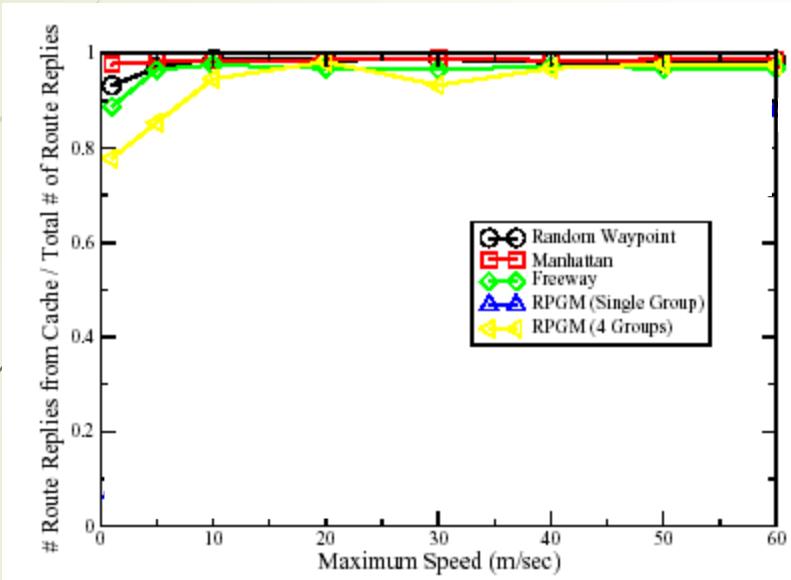
- How does mobility affect the protocol performance?
- Approach:
 - ▶ The protocol is decomposed into its constituent mechanistic, parameterized building block, each implements a well-defined functionality
 - ▶ Various protocols choose different parameter settings for the same building block. For a specific mobility scenario, the building block with different parameters behaves differently, affecting the performance of the protocol
- We are interested in the contribution of building blocks to the overall performance in the face of mobility
- Case study:
 - ▶ Reactive protocols (e.g., DSR and AODV)

* F. Bai, N. Sadagopan, A. Helmy, "BRICS: A Building-block approach for analyzing RoutIng protoCols in Ad Hoc Networks - A Case Study of Reactive Routing Protocols", *IEEE International Conference on Communications (ICC)*, June 2004.

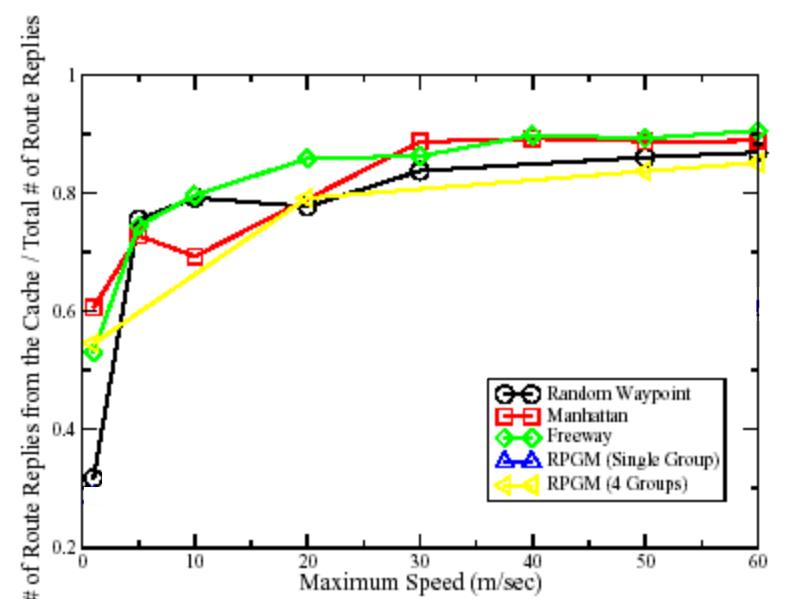
Building Block Diagram for reactive protocols



How useful is caching?



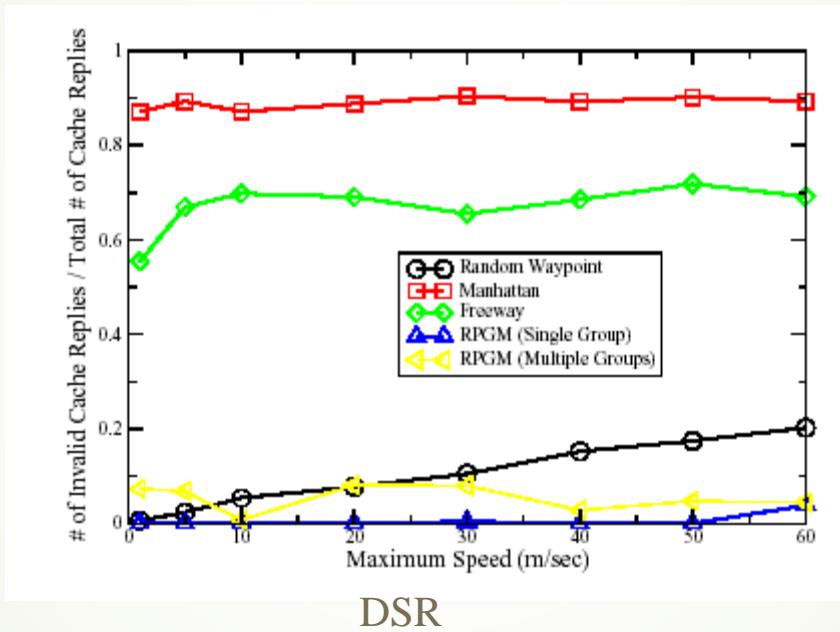
DSR



AODV

- In RW, FW and MH model, most of route replies come from the cache, rather than destination (>80% for DSR, >60% for AODV in most cases)
- The difference in the route replies coming from cache between DSR and AODV is greater than 20% for all mobility models, maybe because of caching mode

Is aggressive caching always good?



- The invalid cached routes increase from RPGM to RW to FW to MH mobility models
- Aggressive Caching may have adverse effect at high mobility scenarios!

Conclusions

- ▶ Mobility patterns are very **IMPORTANT** in evaluating performance of ad hoc networks
- ▶ A rich set of mobility models is needed for a good evaluation framework.
- ▶ Richness of those models should be evaluated using quantitative mobility metrics.

- ▶ Observation
 - ▶ In the previous study only 'average' link duration was considered.
 - ▶ Are we missing something by looking only at averages?
 - ▶ Next: We conduct the PATHS study to investigate statistics and distribution of link and path duration.

Duration Statistics and their Impact on Reactive MANET Routing Protocols

Fan Bai, Narayanan Sadagopan,

Bhaskar Krishnamachari, Ahmed Helmy

{fbai, nsadagop, brksihna, helmy}@usc.edu

* F. Bai, N. Sadagopan, B. Krishnamachari, A. Helmy, "Modeling Path Duration Distributions in MANETs and their Impact on Routing Performance", *IEEE Journal on Selected Areas in Communications (JSAC), Special Issue on Quality of Service in Variable Topology Networks*, Vol. 22, No. 7, pp. 1357-1373, Sept 2004.

•N. Sadagopan, F. Bai, B. Krishnamachari, A. Helmy, "PATHS: analysis of PATH duration Statistics and their impact on reactive MANET routing protocols", *ACM MobiHoc*, pp. 245-256, June 2003.

Motivation and Goal

- ▶ Mobility affects connectivity (i.e., links), and in turn protocol mechanisms and performance
- ▶ It is essential to understanding effects of mobility on link and path characteristics

- ▶ In this study:

- ▶ Closer look at the mobility effects on connectivity metrics (statistics of link duration (LD) and path duration (PD))
- ▶ Develop approximate expressions for LD & PD distributions
(Is it really exponential? When is it exponential?)
- ▶ Develop first order models for Tput & Overhead as $f(PD)$

Protocol Mechanisms

Performance
(Throughput,
Overhead)

(Is it really

~~Mobility~~ → ~~Connectivity~~

~~Statistics of link~~

Connectivity Metrics

- ▶ Link Duration (LD):
 - ▶ For nodes i, j , the duration of link $i-j$ is the longest interval in which i & j are directly connected
 - ▶ $LD(i,j,t_1) = t_2 - t_1$
 - ▶ iff $\forall t, t_1 \leq t \leq t_2, \exists \epsilon > 0 : X(i,j,t) = 1, X(i,j,t_1-\epsilon) = 0, X(i,j,t_2+\epsilon) = 0$
- ▶ Path Duration (PD):
 - ▶ Duration of path $P = \{n_1, n_2, \dots, n_k\}$ is the longest interval in which all $k-1$ links exist

$$PD(P, t_1) = \min_{1 \leq z \leq k-1} LD(n_z, n_{z+1}, t_1)$$

Simulation Scenarios in NS-2

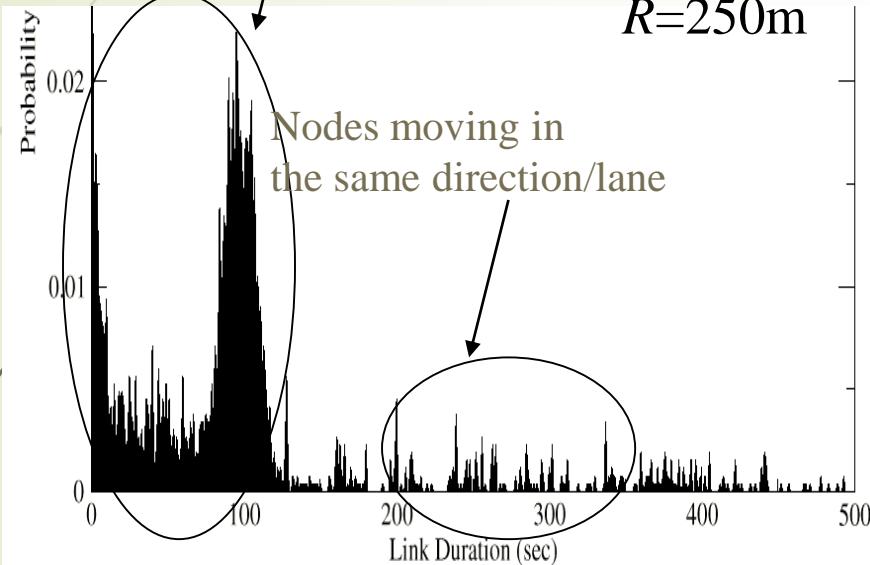
- ▶ Path duration computed for the shortest path, at the graph and protocol levels, until it breaks.
- ▶ Used the *IMPORTANT* mobility tool:
 - ▶ nile.usc.edu/important
- ▶ Mobility Parameters
 - ▶ $V_{max} = 1, 5, 10, 20, 30, 40, 50, 60 \text{ m/s}$,
 - ▶ RPGM: 4 groups (RPGM4), Speed/Angle Deviation Ratio=0.1
- ▶ 40 nodes, in $1000\text{m} \times 1000\text{m}$ area
- ▶ Radio range (R)= $50, 100, 150, 200, 250\text{m}$
- ▶ Simulation time 900sec

Link Duration (LD) PDFs

- ▶ At low speeds ($V_{max} < 10m/s$) link duration has multi-modal distribution for FW and RPGM4
 - ▶ In FW due to geographic restriction of the map
 - ▶ Nodes moving in same direction have *high* link duration
 - ▶ Nodes moving in opposite directions have *low* link duration
 - ▶ In RPGM4 due to correlated node movement
 - ▶ Nodes in *same* group have *high* link duration
 - ▶ Nodes in *different* groups have *low* link duration
- ▶ At higher speeds ($V_{max} > 10m/s$) link duration does *not* exhibit multi-modal distribution
- ▶ Link duration distribution is *NOT* exponential

Nodes moving in opposite directions

FW model
 $V_{max}=5\text{m/s}$
 $R=250\text{m}$

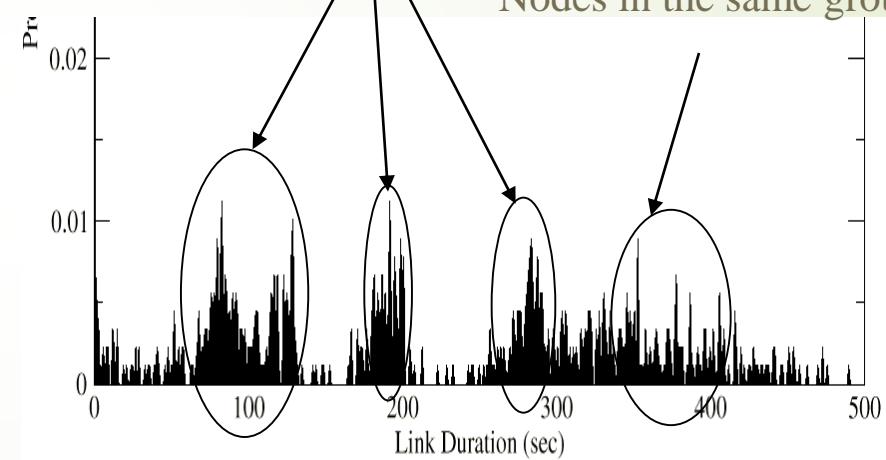


Multi-modal Distribution of Link Duration for Freeway model at low speeds

RPGM w/ 4 groups
 $V_{max}=5\text{m/s}$
 $R=250\text{m}$

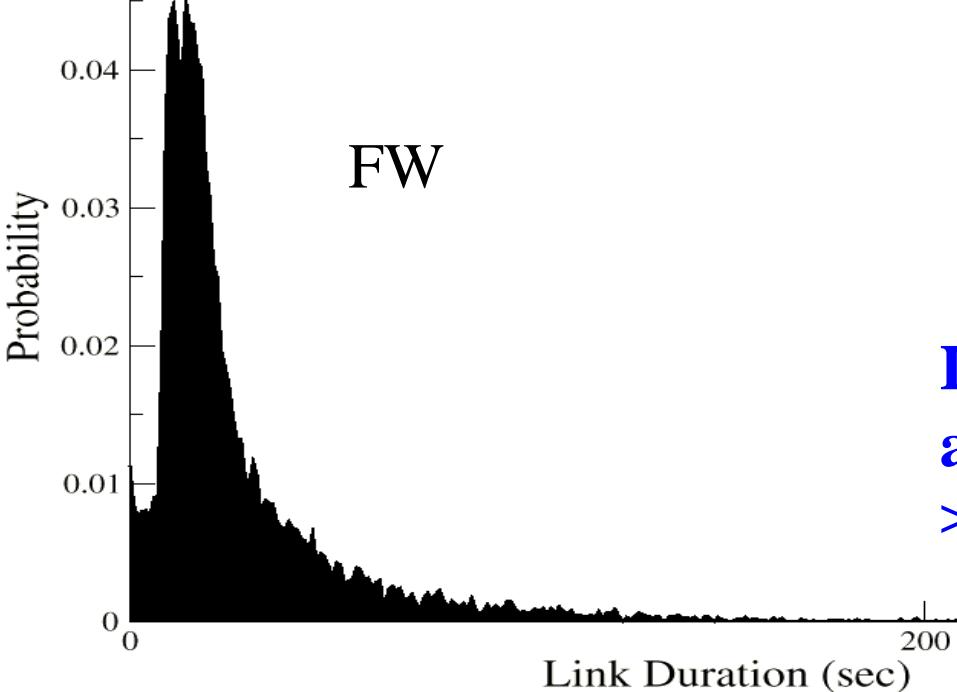
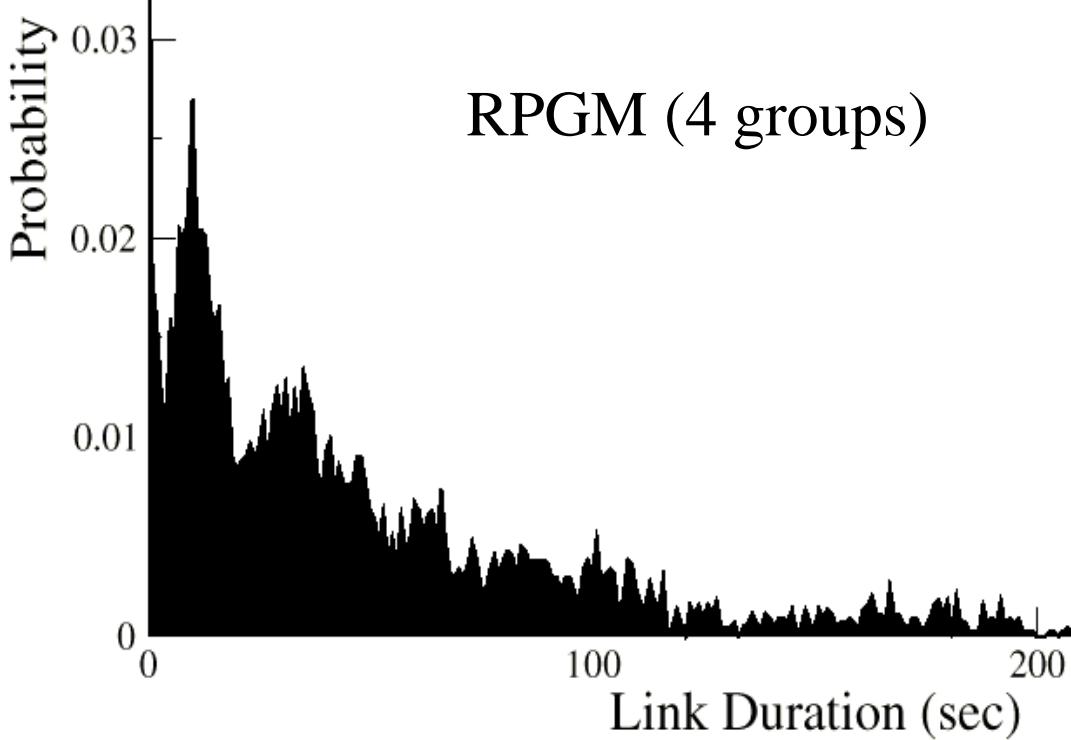
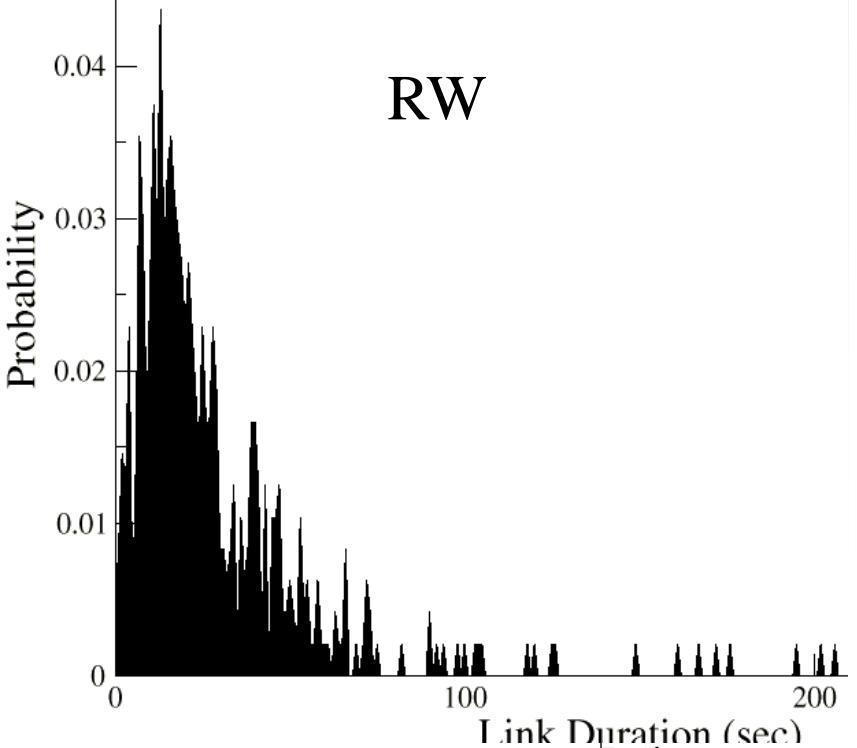
Nodes in different groups

Nodes in the same group



Multi-modal Distribution of Link Duration for RPGM4 model at low speeds

Link Duration (LD) distribution at low speeds < 10m/s



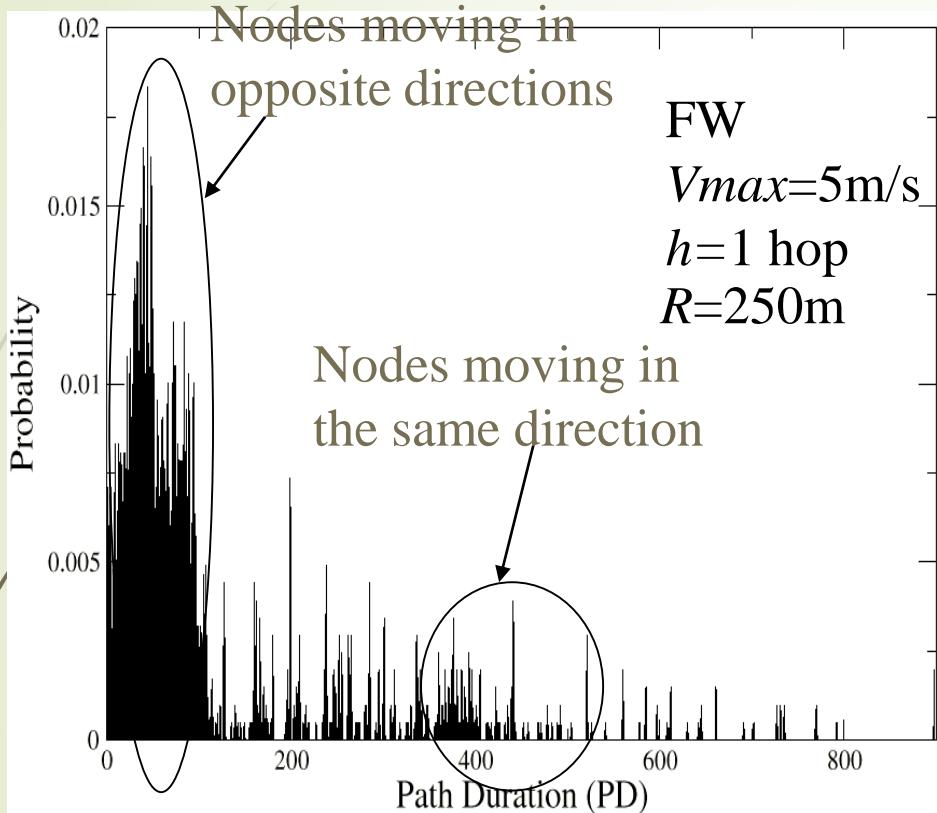
$V_{max}=30\text{m/s}$
 $R=250\text{m}$

**Link Duration
at high speeds
> 10m/s**

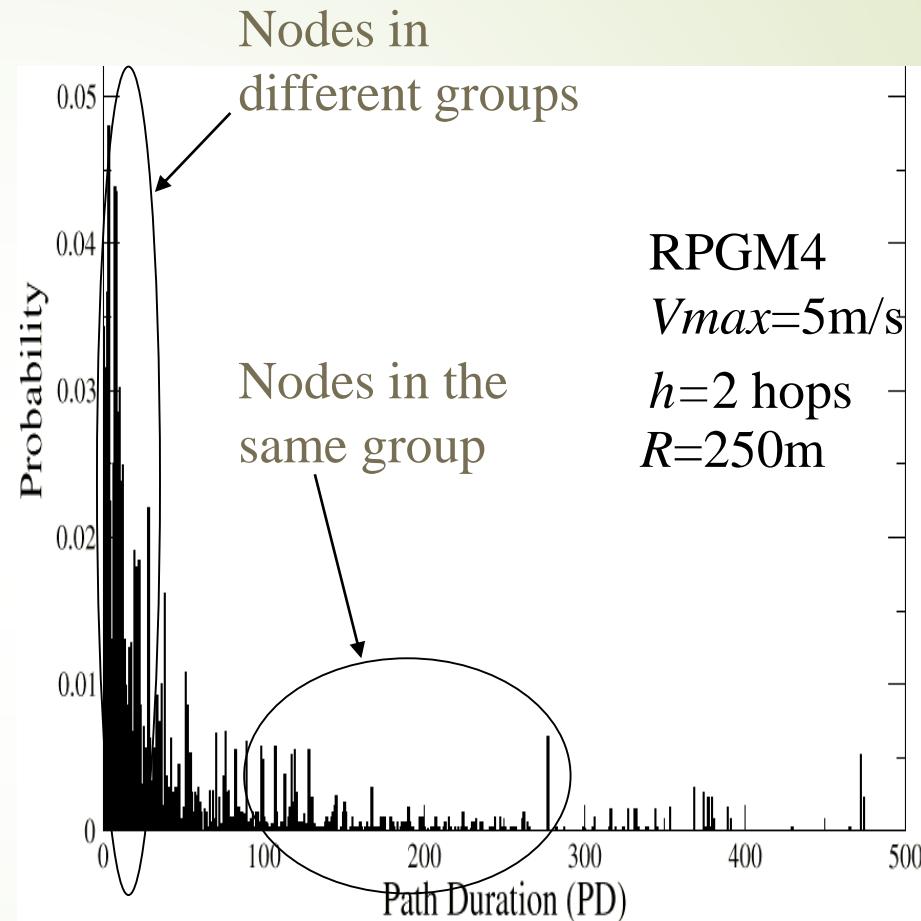
Not Exponential !!

Path Duration (PD) PDFs

- ▶ At low speeds ($V_{max} < 10m/s$) and for short paths ($h \leq 2$) path duration has multi-modal for FW and RPGM4
- ▶ At higher speeds ($V_{max} > 10m/s$) and longer path length ($h \geq 2$) path duration can be reasonably approximated using exponential distribution for RW, FW, MH, RPGM4.

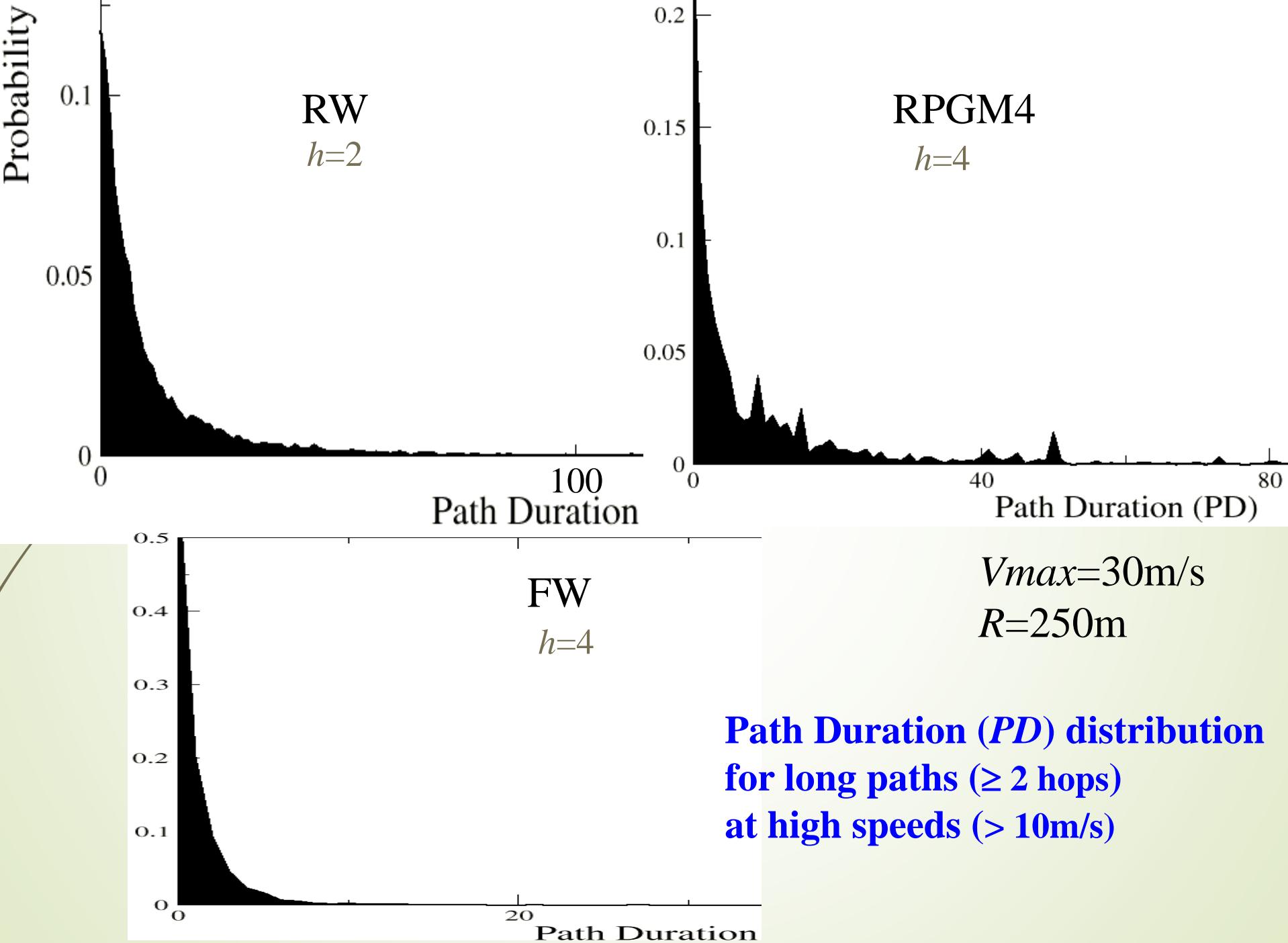


Multi-modal Distribution of Path Duration for Freeway model at low speeds, low hops



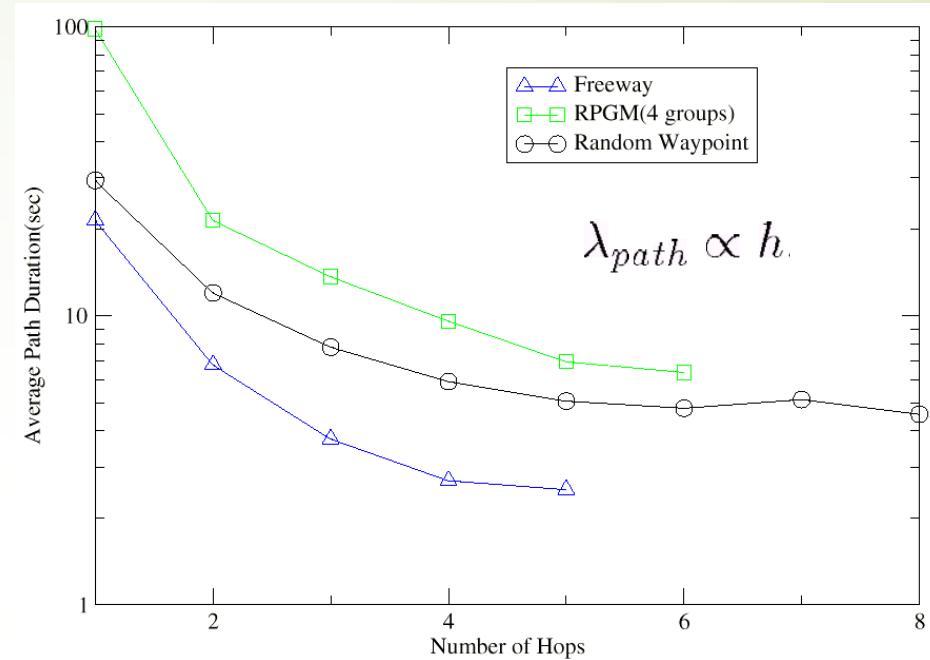
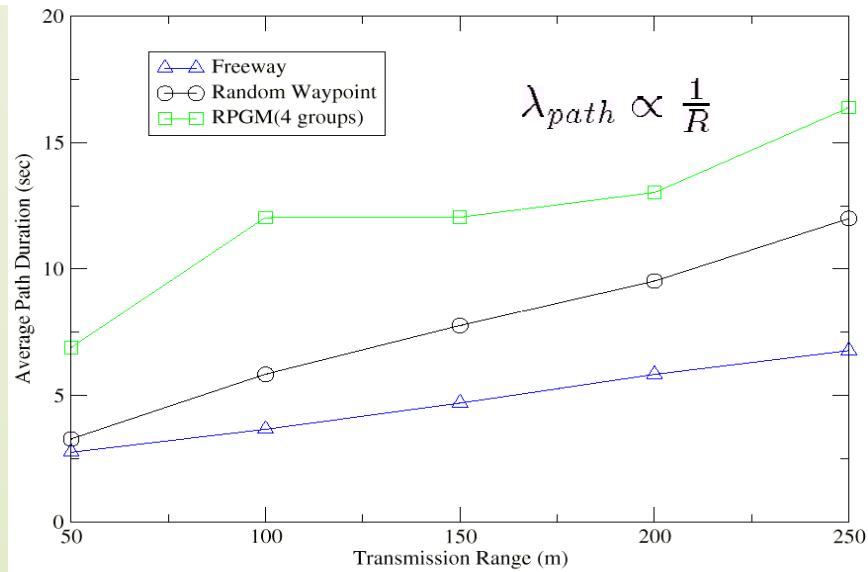
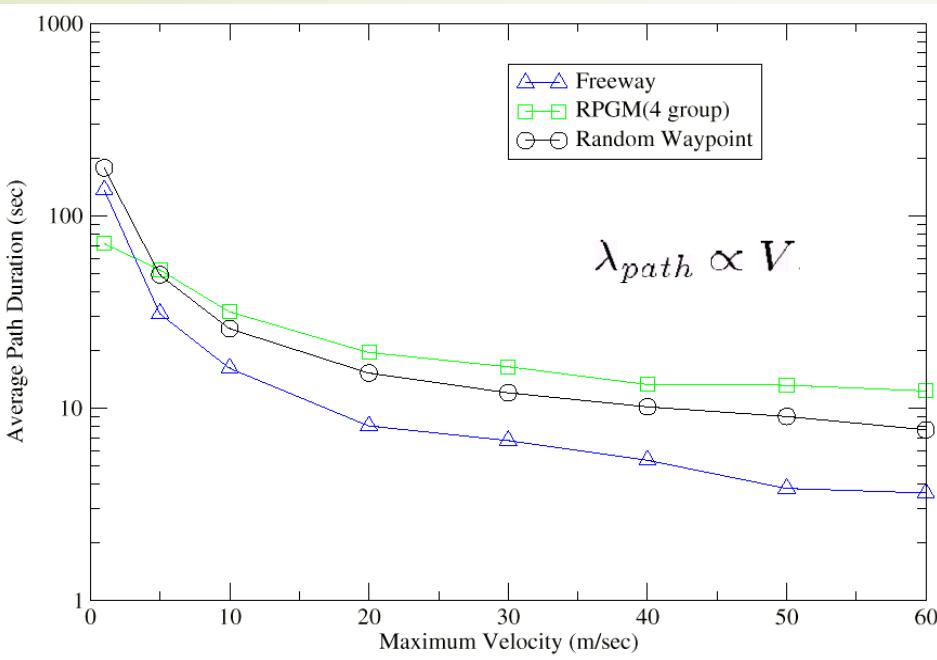
Multi-modal Distribution of Path Duration for RPGM4 model at low speeds, low hops

Path Duration (*PD*) distribution for short paths at low speeds < 10m/s



Exponential Model for Path Duration (PD)

- ▶ Let λ_{path} be the parameter for exponential PD distribution:
 - ▶ PD PDF $f(x) = \lambda_{path} e^{-\lambda_{path} x}$
 - ▶ As λ_{path} increases average PD decreases (and vice versa)
- ▶ Intuitive qualitative analysis:
 - ▶ $PD = f(V, h, R)$; V is relative velocity, h is path hops & R is radio range
 - ▶ As V increases, average PD decreases, i.e., λ_{path} increases
 - ▶ As h increases, average PD decreases, i.e., λ_{path} increases
 - ▶ As R increases, average PD increases, i.e., λ_{path} decreases
- ▶ Validate intuition through simulations



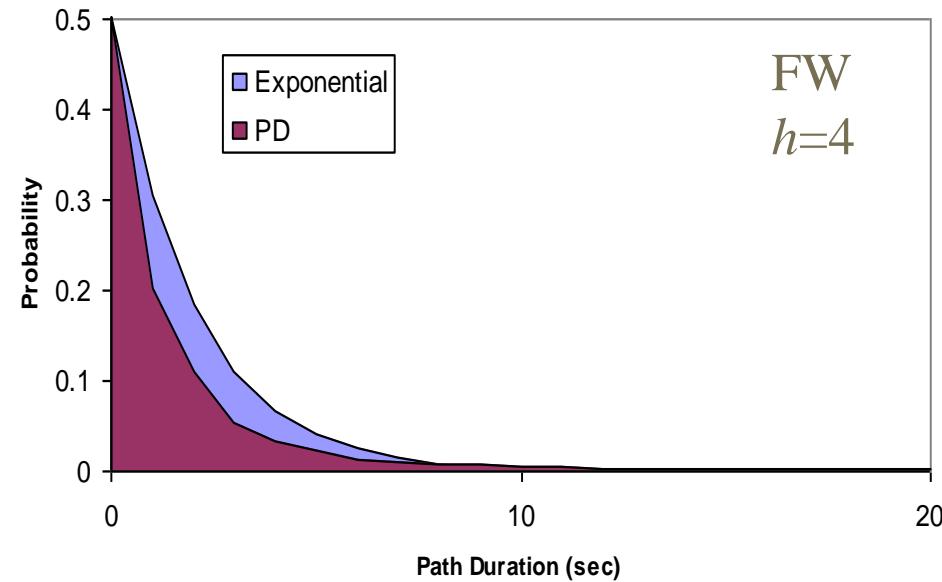
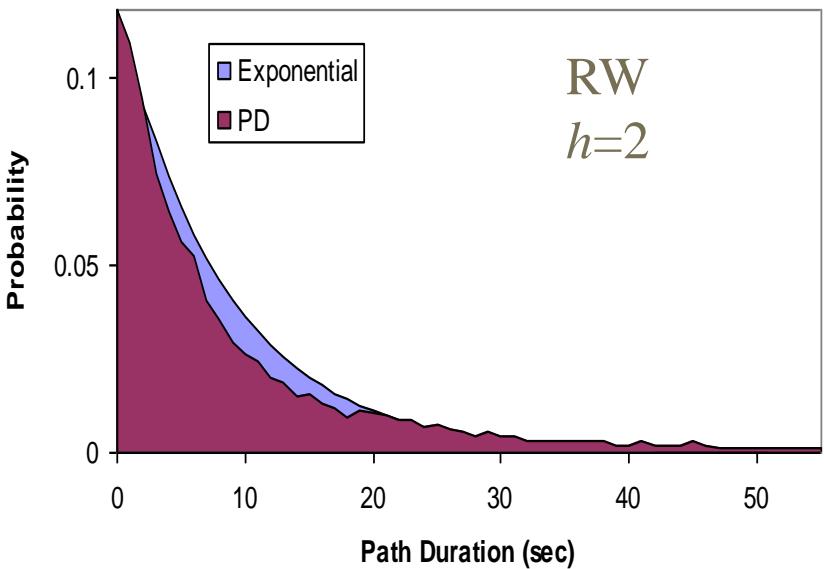
Exponential Model for PD

$$\lambda_{path} \propto h \quad \lambda_{path} \propto V \quad \lambda_{path} \propto \frac{1}{R}$$

$$\lambda_{path} = \lambda_0 \frac{hV}{R}$$

But, PD PDF $f(x) = \lambda_{path} e^{-\lambda_{path} x}$

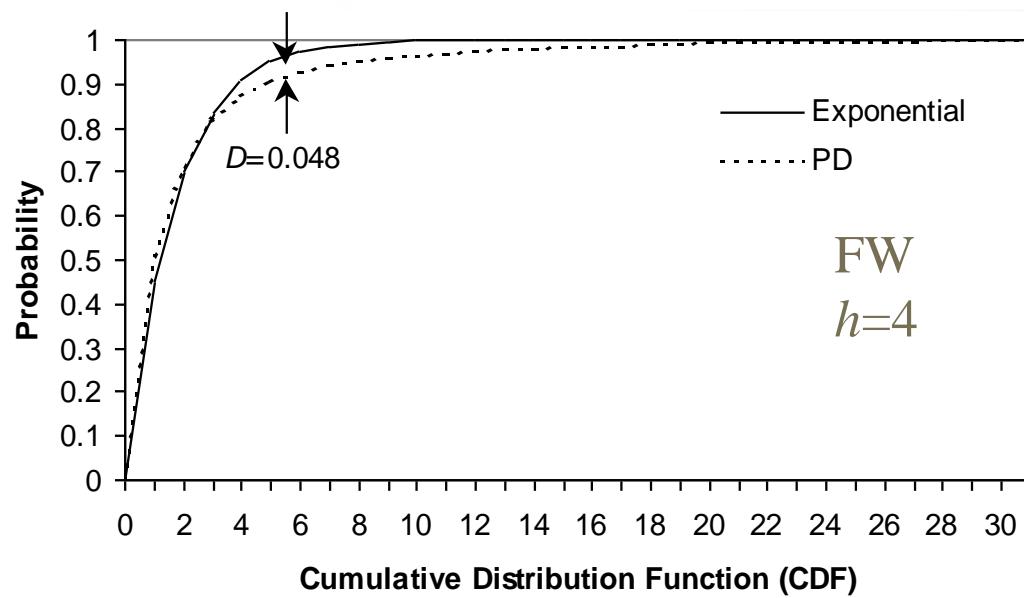
$$f(x) = \frac{\lambda_0 h V}{R} e^{-\frac{\lambda_0 h V}{R} x}$$



- Correlation:
94.1-99.8%

- Goodness-of-fit Test

	K-S test
RW	0.04-0.065
FW	0.045-0.085
RPGM	0.09-0.12



$V_{max}=30\text{m/s}$
 $R=250\text{m}$

Effect of Path Duration (PD) on Performance: Case Study for DSR

- PD observed to have significant effect on performance
- (I) Throughput: First order model
 - ▶ T : simulation time, D : data transferred, T_{flow} : data transfer time, T_{repair} : total path repair time, t_{repair} : av. path repair time, f : path break frequency

$$\text{Throughput} = \frac{D}{T}$$

$$T = T_{flow} + T_{repair} = T_{flow} + t_{repair} \cdot f \cdot T = T_{flow} + t_{repair} \cdot \frac{1}{PD} \cdot T \quad \Rightarrow \quad T = \frac{T_{flow}}{\left(1 - \frac{t_{repair}}{PD}\right)}$$

$$\boxed{\text{Throughput} = \left(1 - \frac{t_{repair}}{PD}\right) \frac{D}{T_{flow}} = \left(1 - \frac{t_{repair}}{PD}\right).rate}$$

⇒

$$\boxed{\text{Throughput} \propto \left(-\frac{1}{PD}\right)}$$

Effect of PD on Performance (contd.)

- ▶ (II) Overhead: First order model
 - ▶ Number of DSR route requests = $\frac{T}{PD}$
 - ▶ p : non-propagating cache hit ratio, N : number of nodes

- ▶ Evaluation through NS2 simulations for DSR

$$\text{Overhead} = \frac{T}{PD}((p)1 + (1 - p)N) \Rightarrow \text{Overhead} \propto \frac{1}{PD}$$

	Random Waypoint (RW)	Freeway (FW)	Manhattan (MH)
Throughput	-0.9165	-0.9597	-0.9132
Overhead	0.9753	0.9812	0.9978

- ▶ Pearson coefficient of correlation (ρ) with $\frac{1}{PD}$
RPGM exhibits low ρ , due to relatively low path changes/route requests

Conclusions

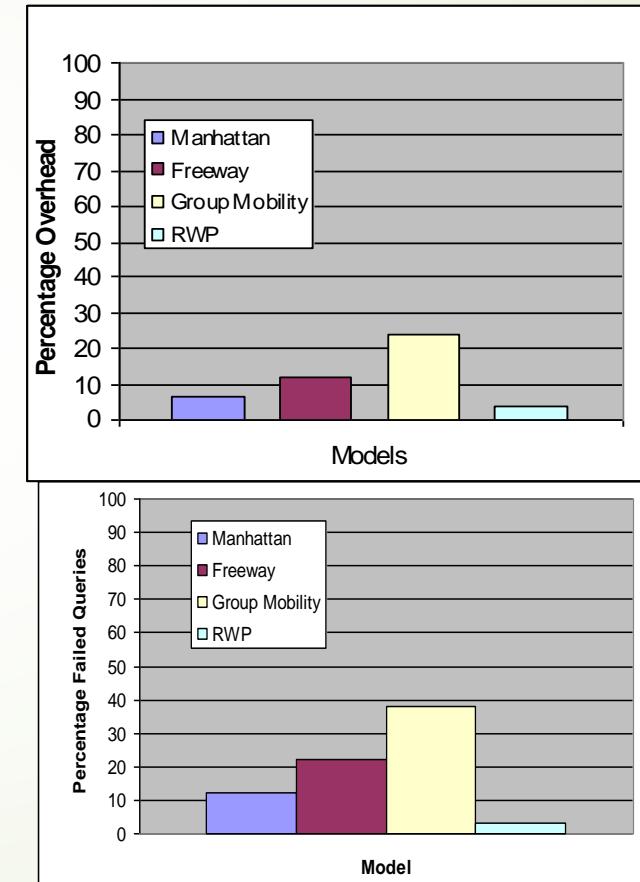
- ▶ Detailed statistical analysis of link and path duration for multiple mobility models (RW, FW, MH, RPGM4):
 - ▶ Link Duration: multi-modal FW and RPGM4 at low speeds
 - ▶ Path Duration PDF:
 - ▶ Multi-modal FW and RPGM4 at low speeds and hop count
 - ▶ Exponential-like at high speeds & med/high hop count for all models
- ▶ Developed parametrized exponential model for *PD* PDF, as function of relative velocity V , hop count h and radio range R
- ▶ Proposed simple analytical models for throughput & overhead that show strong correlation with reciprocal of average *PD*
- ▶ Open Issues:
 - ▶ Can we prove this mathematically? Yes
 - ▶ Is it general for random and correlated mobility? Yes



Case Studies Utilizing Mobility Modeling

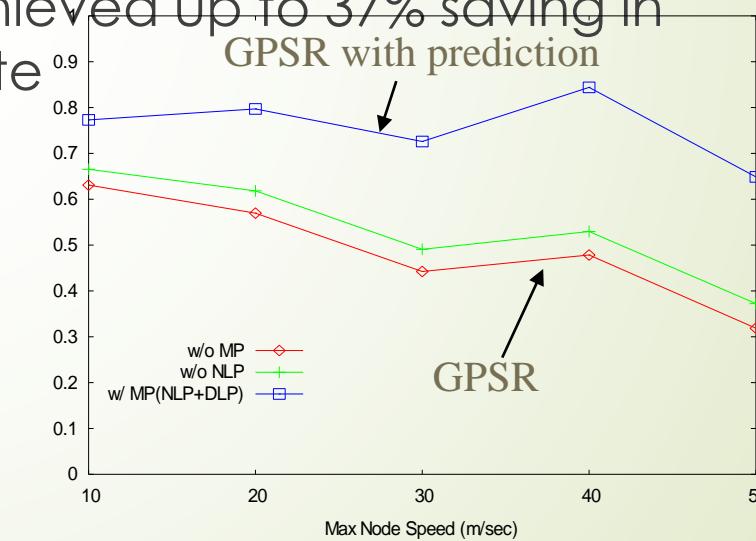
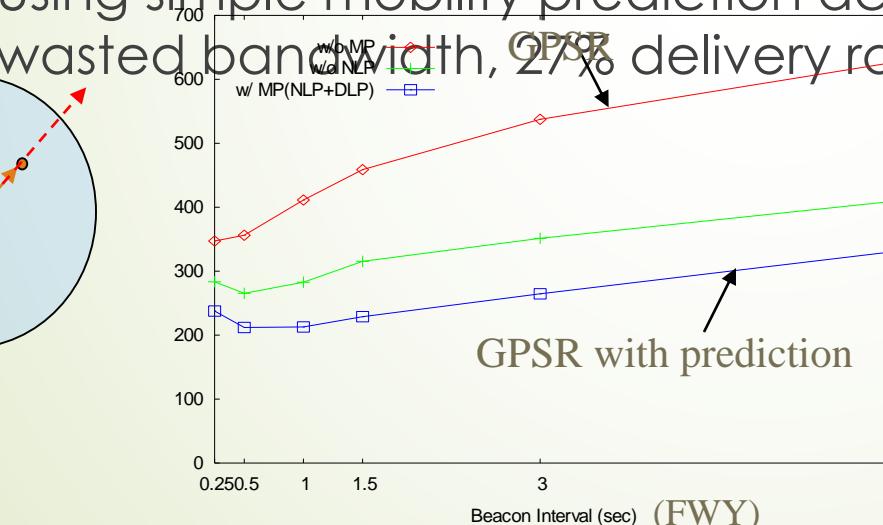
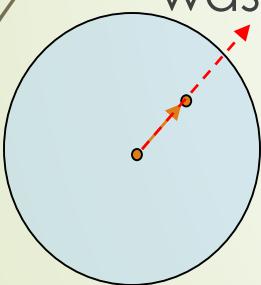
Case Study on Effects of Mobility on the Grid Location Service (GLS)

- ▶ Group mobility:
 - prolongs protocol convergence
 - incurs max overhead
 - incurs max query failure rate
- * Subtle Coupling between
 - ▶ (1) Mobility
 - ▶ (2) The Grid Topology
 - ▶ (3) Protocol Mechanisms



Case Study on Geo-routing across Mobility Models

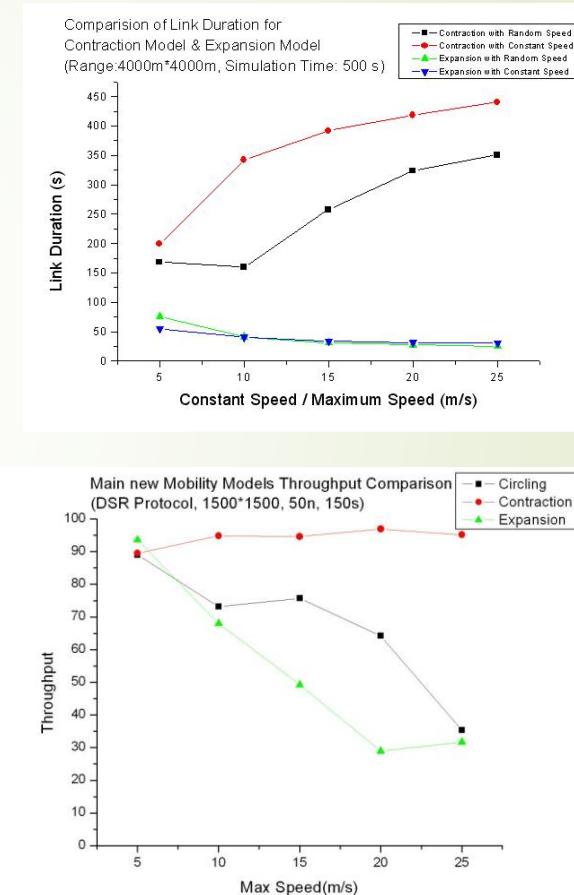
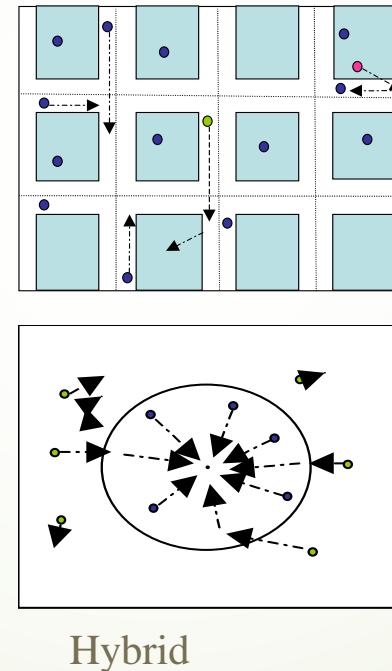
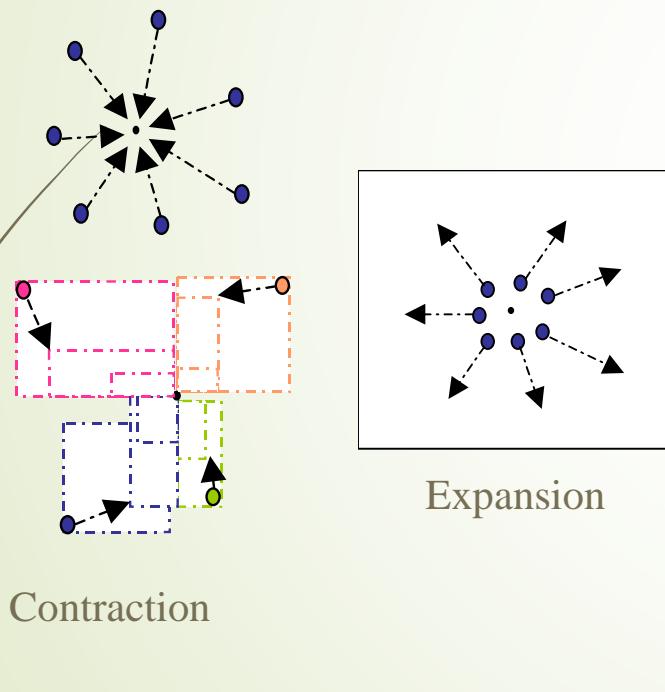
- Depending on beacon frequency location info may be out of date
- Nodes chosen by geographic routing may move out of range before next beacon update.
- Increasing beacon updates does not always help!
- Using simple mobility prediction achieved up to 37% saving in wasted bandwidth, 27% delivery rate



* D. Son, A. Helmy, B. Krishnamachari, "The Effect of Mobility-induced Location Errors on Geographic Routing in Ad Hoc Networks: Analysis and Improvement using Mobility Prediction", *IEEE WCNC*, March 2004, and *IEEE Transactions on Mobile Computing, Special Issue on Mobile Sensor Networks*, 3rd quarter 2004.

Contraction, Expansion and Hybrid Models

- ▶ May be useful for sensor networks
- ▶ Contraction models show 'improved' performance (e.g., Tput, link duration) with increased velocity

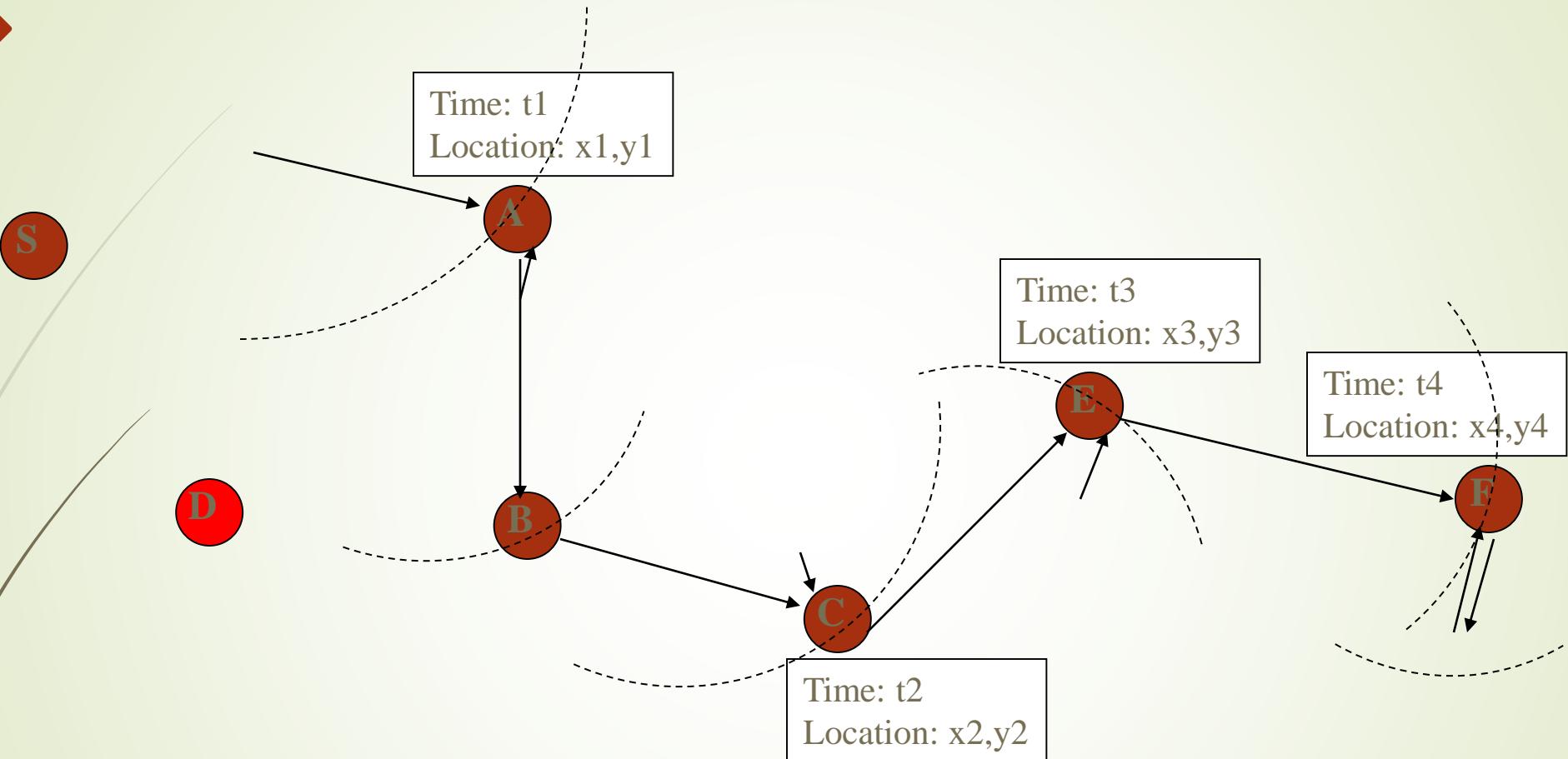


* Y. Lu, H. Lin, Y. Gu, A. Helmy, "Towards Mobility-Rich Performance Analysis of Routing Protocols in Ad Hoc Networks: Using Contraction, Expansion and Hybrid Models", IEEE ICC, June 2004.

MAID Case Study: Utilizing Mobility

- ▶ MAID: Mobility Assisted Information Diffusion
- ▶ May be used for: resource discovery, routing, node location applications
- ▶ MAID uses 'encounter' history to create age-gradients towards the target/destination
- ▶ MAID uses (and depends on) mobility to diffuse information, hence its performance may be quite sensitive to mobility degree and patterns
- ▶ Unlike conventional adhoc routing, link/path duration may not be the proper metrics to analyze
- ▶ The 'Age gradient tree' and its characteristics determine MAID's performance

* F. Bai, A. Helmy, "Impact of Mobility on Mobility-Assisted Information Diffusion (*MAID*) Protocols", IEEE SECON, 2007.

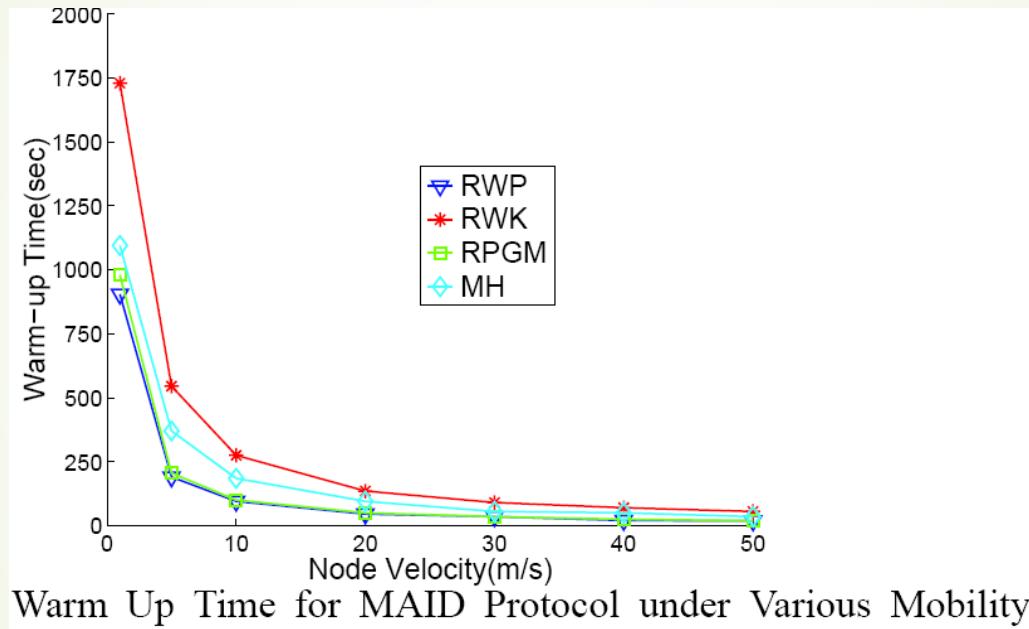


Basic Operation of MAID: Encounter history, search and age gradient tree

MAID protocol phases and metrics

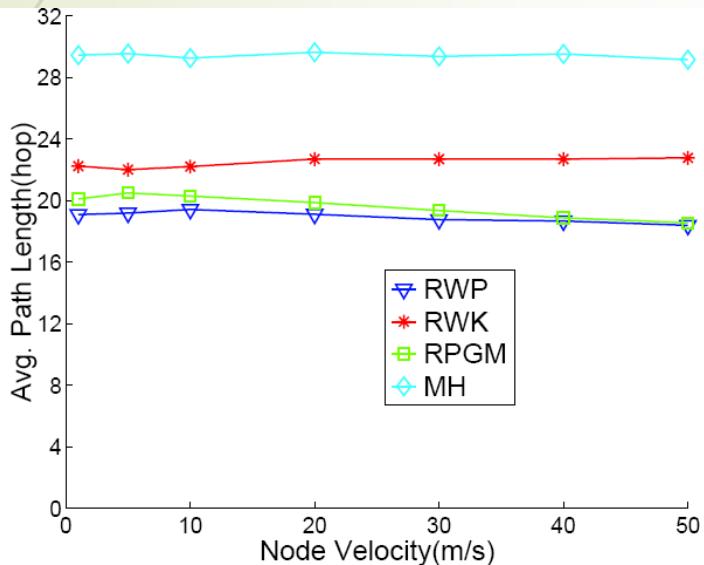
- ▶ Cold cache (initial, transient, phase):
 - ▶ Encounter cache is empty
 - ▶ More encounters ‘warm up’ the cache by increasing the entries
- ▶ Warm cache (steady state phase) :
 - ▶ Average encounter ratio reaches ~30% of network nodes
 - ▶ Age gradient trees are established
- ▶ Metrics:
 - ▶ Warm up time
 - ▶ Average path length to a destination
 - ▶ Cost of search to establish the route to the destination

Warm Up Phase

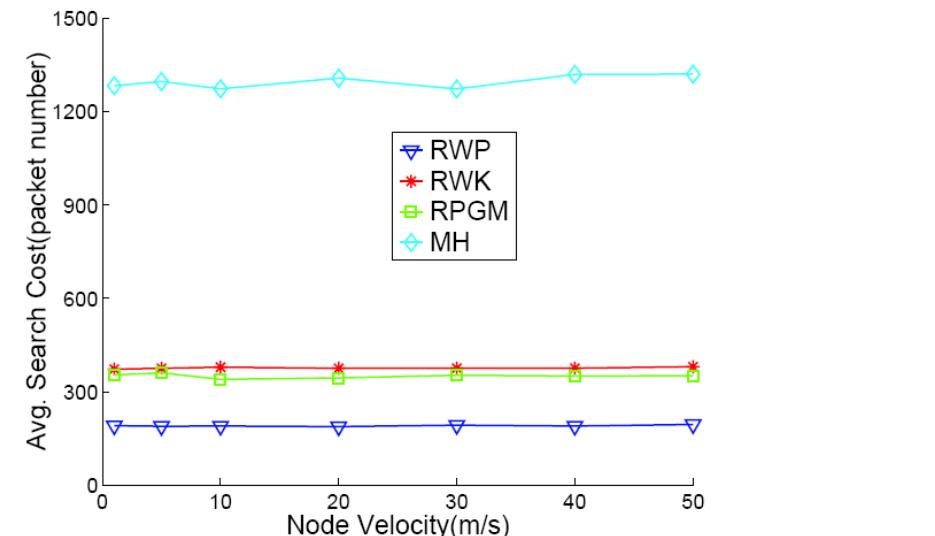


The Warm Up Time depends heavily on the Mobility model and the Velocity

Steady State Phase



Average Path Length for MAID Protocol under Various Mobility

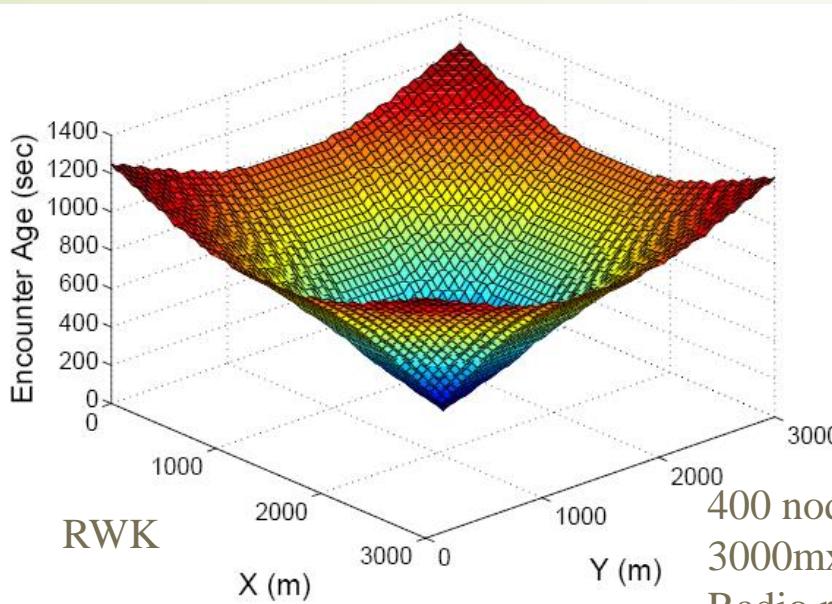


Average Search Cost for MAID Protocol under Various Mobility

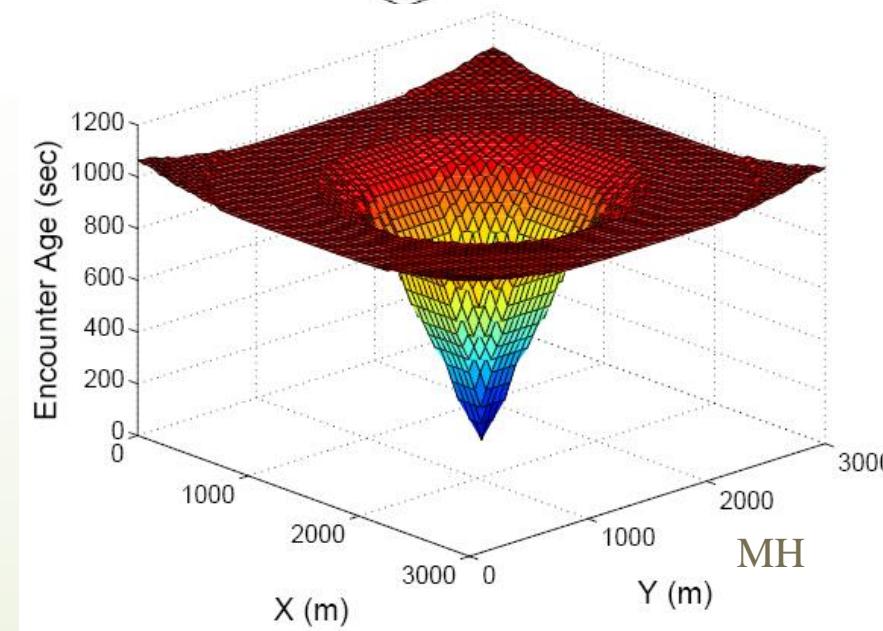
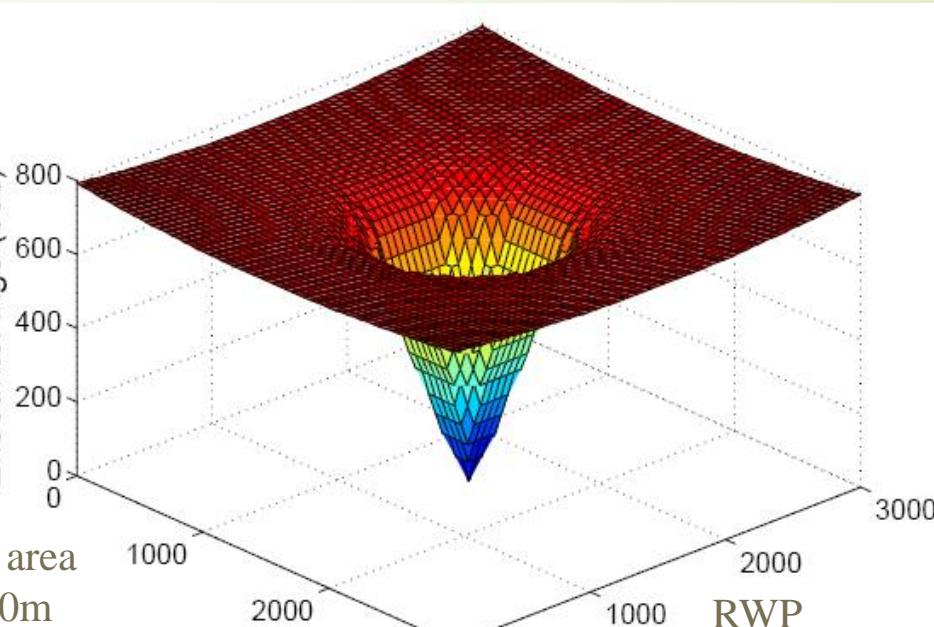
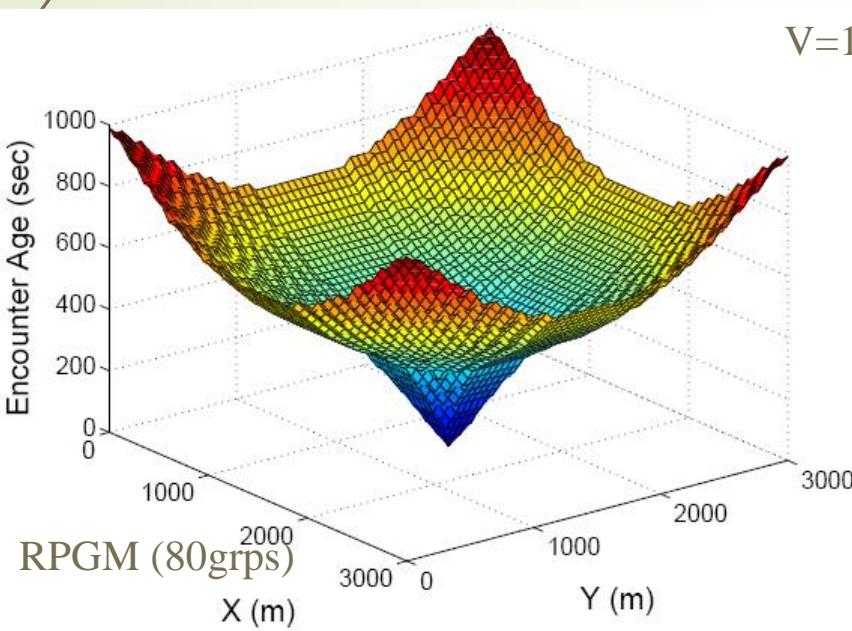
Steady State Performance depends only on the Mobility model but NOT on the Velocity

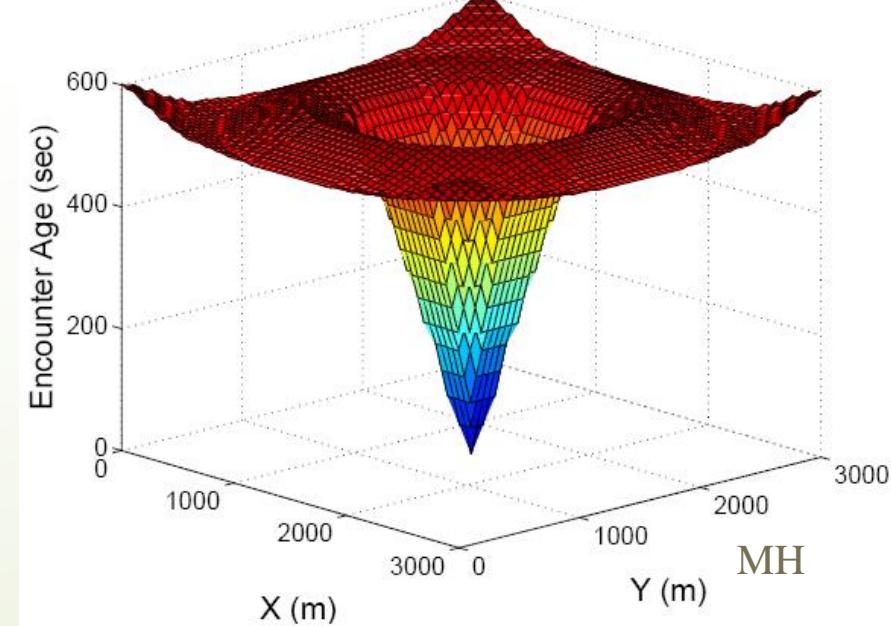
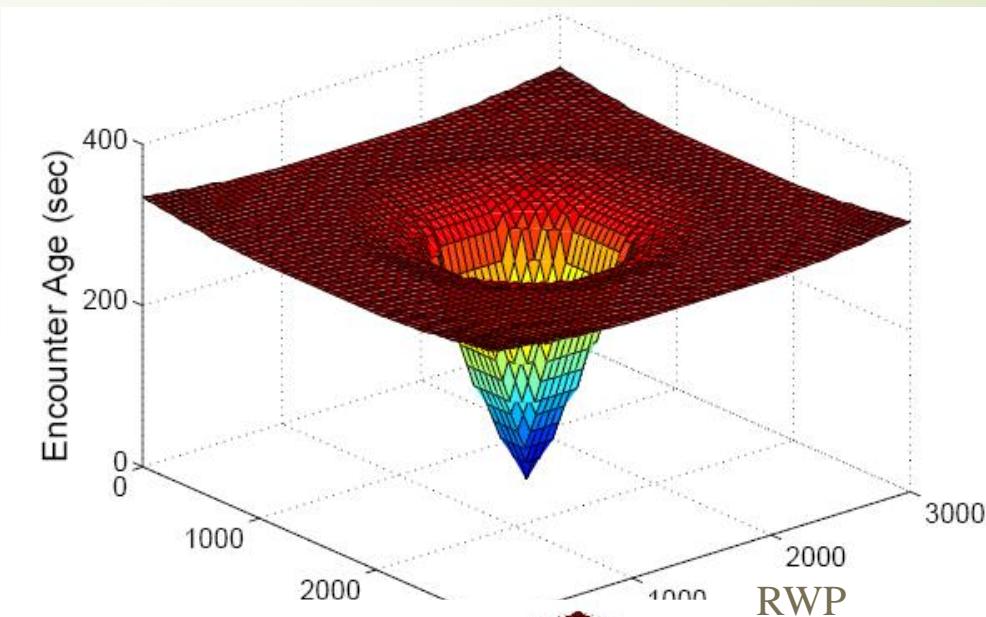
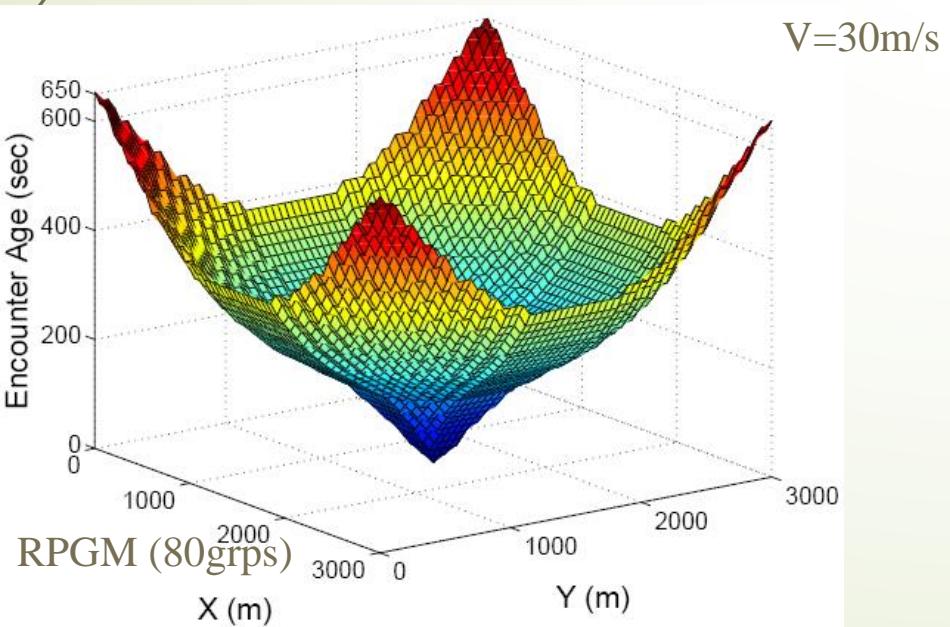
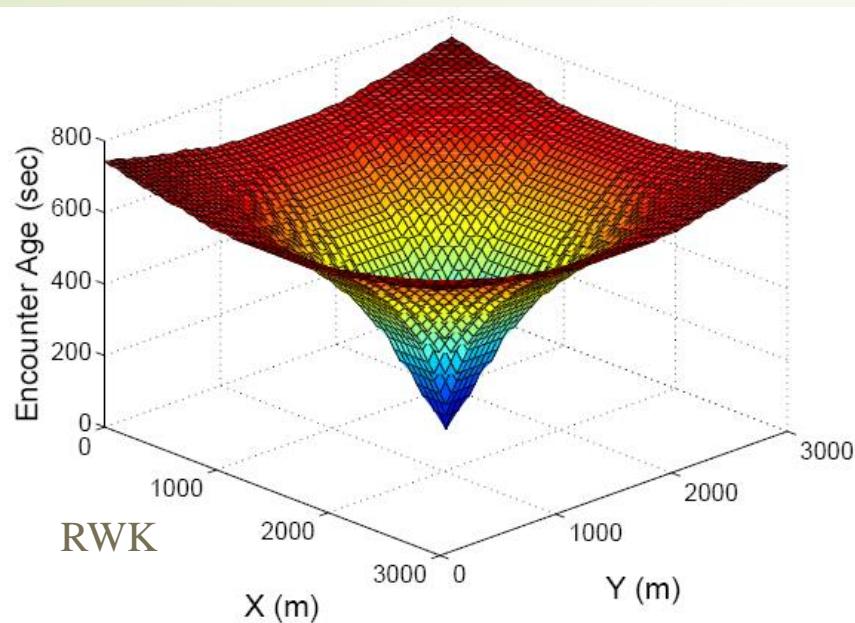
- These metrics reflect the structure of the age-gradient trees (AGTs).
- Hence, MAID leads to stable characteristics of the AGTs.

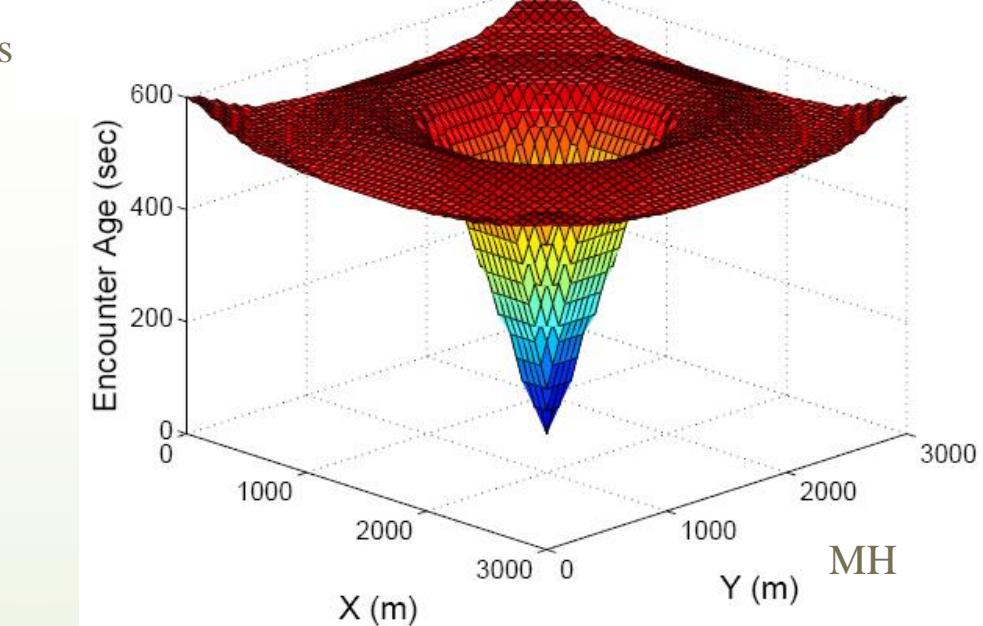
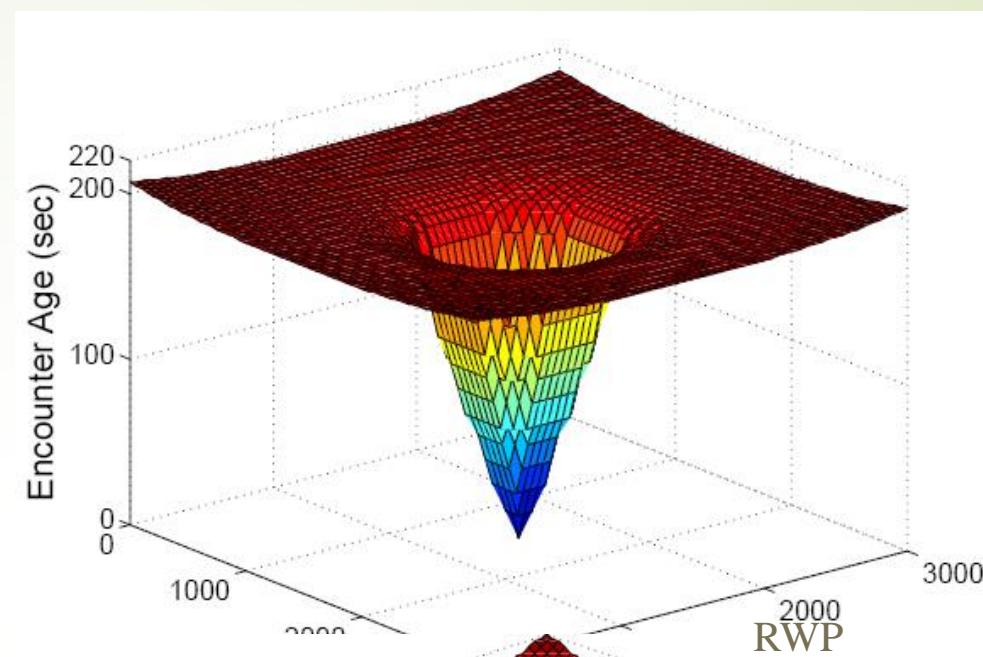
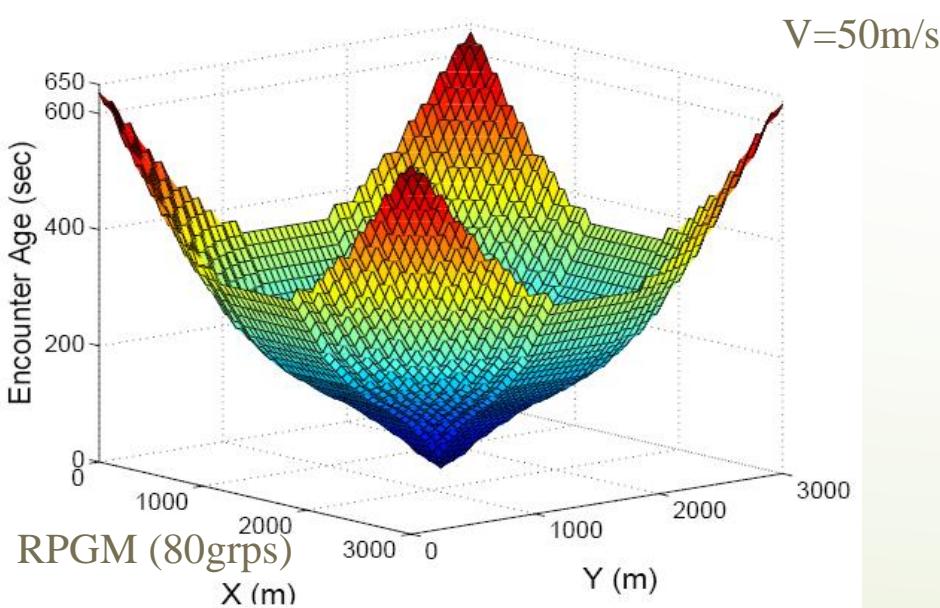
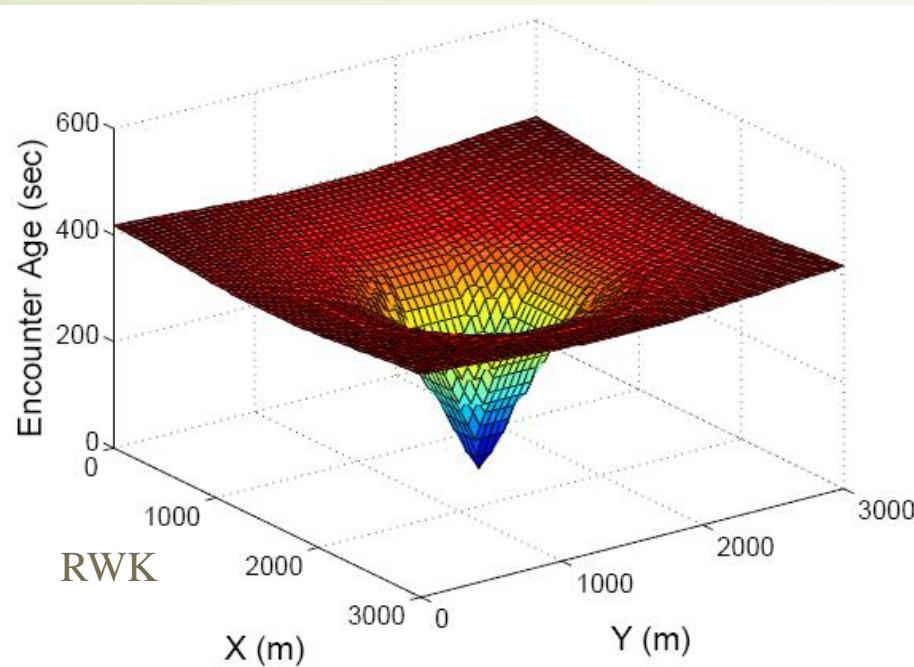
Spatio-Temporal Correlations in the AGT



400 nodes
3000mx3000m area
Radio range 250m







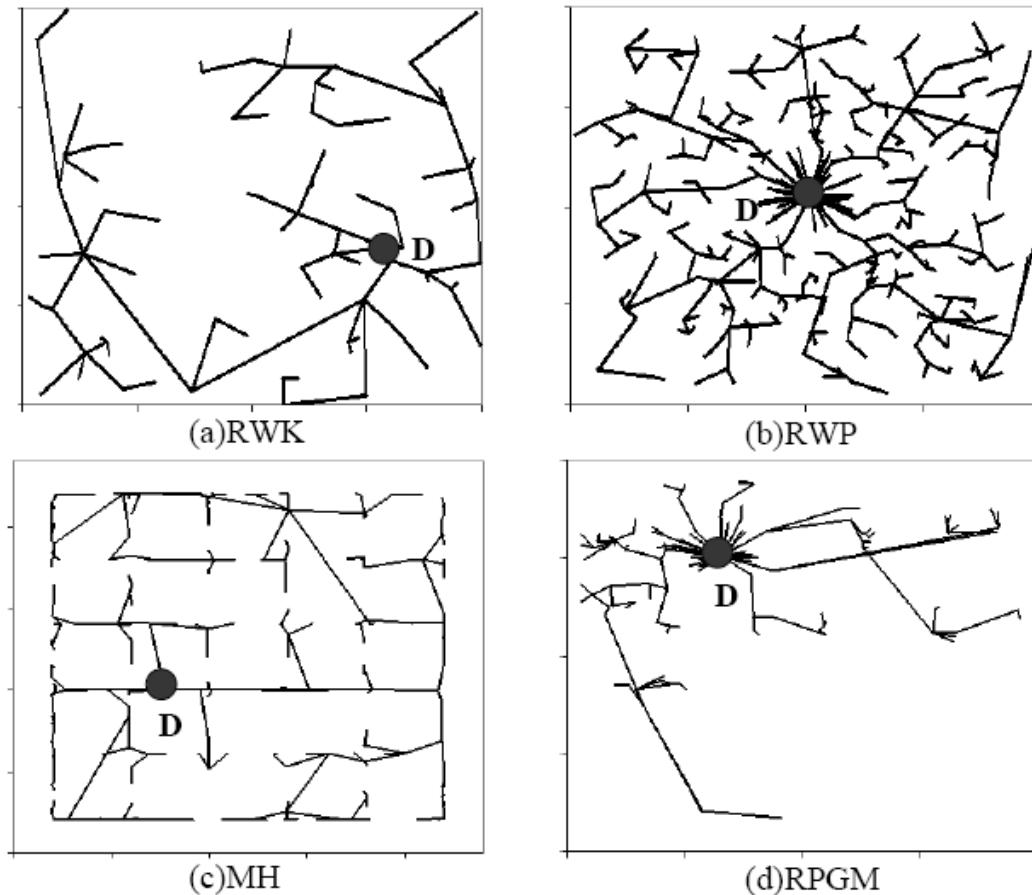


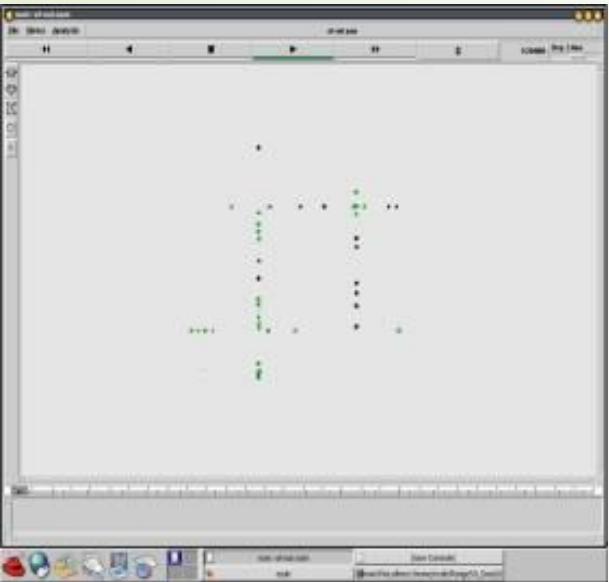
Fig. 13. The Age Gradient Tree (AGT) for RWP, RWK, MH and RPGM models ($v=20\text{m/s}$, $t=400\text{sec}$). Here, D is the destination (also, the root of AGT).

Mobility Simulation Tools

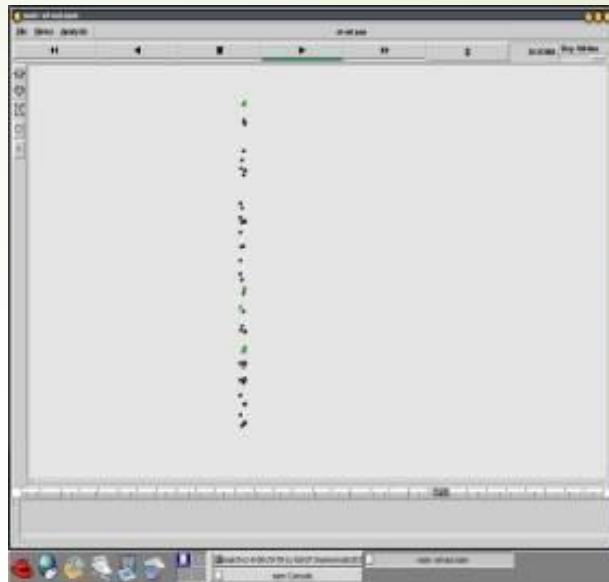
- ▶ The Network Simulator (NS-2) (USC/ISI, UCB, Xerox Parc)
[wireless extensions CMU/Rice]
 - ▶ www.isi.edu/nsnam
- ▶ The GloMoSim Simulator (UCLA)/QualNet (Commercial)
- ▶ The IMPORTANT Mobility Tool (USC/UF)
 - ▶ nile.cise.ufl.edu/important
- ▶ Time Variant Community (TVC) (UF/USC)
 - ▶ nile.cise.ufl.edu/~helmy (click on TVC model)
- ▶ The Obstacle Mobility simulator (UCSB)
 - ▶ moment.cs.ucsb.edu/mobility
- ▶ The CORSIM Simulator
- ▶ OPNET (commercial)

IMPORTANT

- ▶ Includes:
 - ▶ Mobility generator tools for FWY, MH, RPGM, RWP, RWK (future release), City Section (Rel. Sp 05)
 - ▶ Acts as a pre-processing phase for simulations, currently supports NS-2 formats (can extend to other formats)
 - ▶ Analysis tools for mobility metrics (link duration, path duration) and protocol performance
 - ▶ (throughput, overhead, age gradient tree chars)
 - ▶ Acts as post-processing phase of simulations
 - ▶ nile.cise.ufl.edu/important



Manhattan

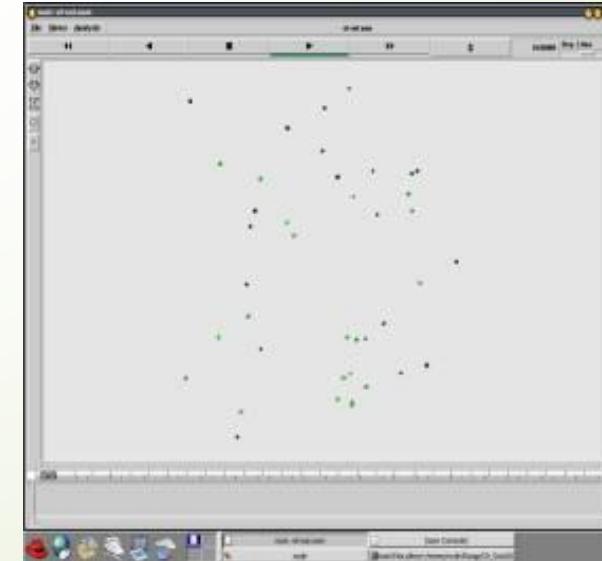


Freeway

IMPORTANT



Group

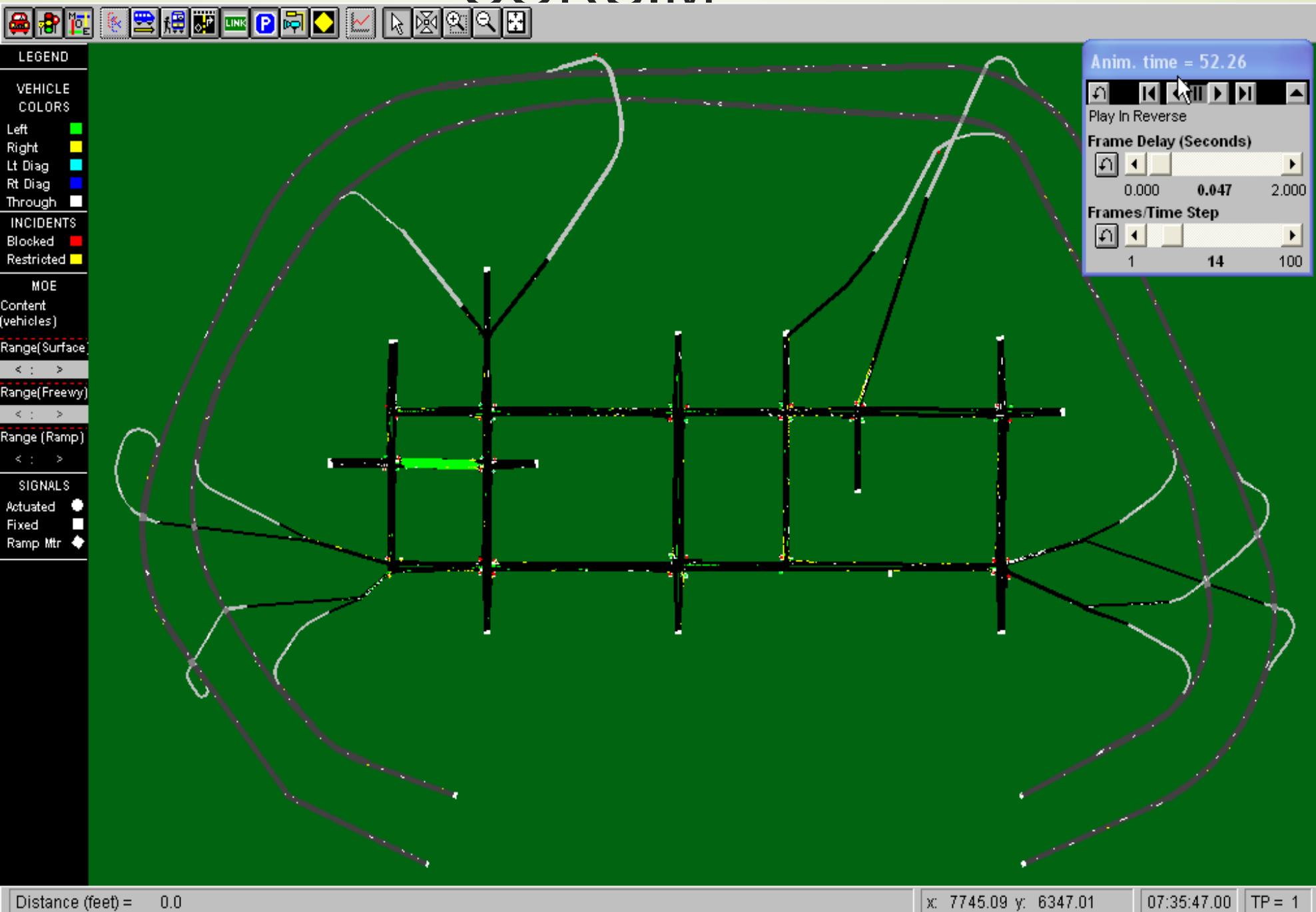


RWP

CORSIM (Corridor Traffic Simulator)

- ▶ Simulates vehicles on highways/streets
- ▶ Micro-level traffic simulator
 - ▶ Simulates intersections, traffic lights, turns, etc.
 - ▶ Simulates various types of cars (trucks, regular)
 - ▶ Used mainly in transportation literature (and recently for vehicular networks)
 - ▶ Does not incorporate communication or protocols
 - ▶ Developed through FHWA (federal highway administration)
<http://ops.fhwa.dot.gov>
 - ▶ Need to buy license

CORSIM

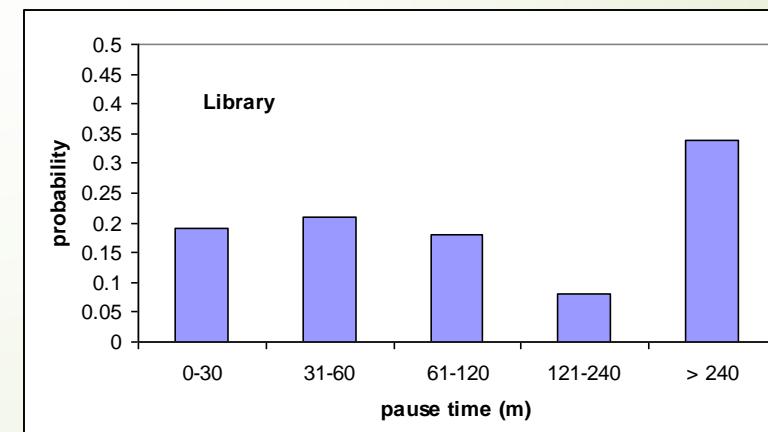
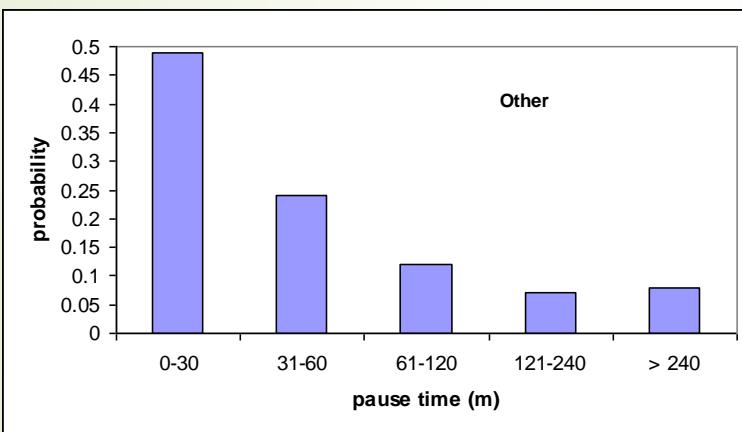
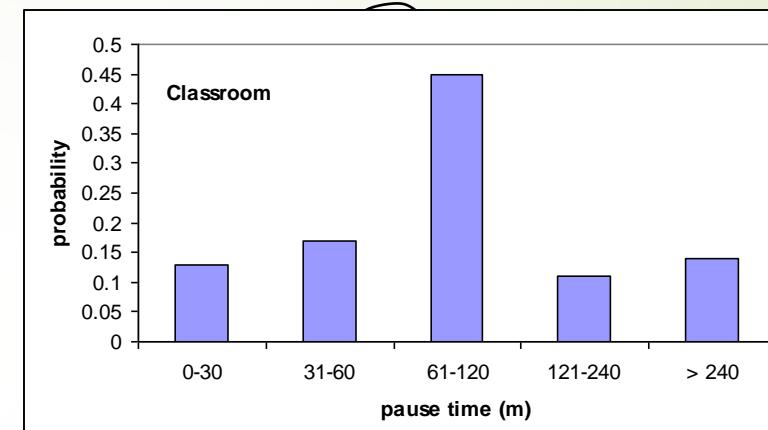
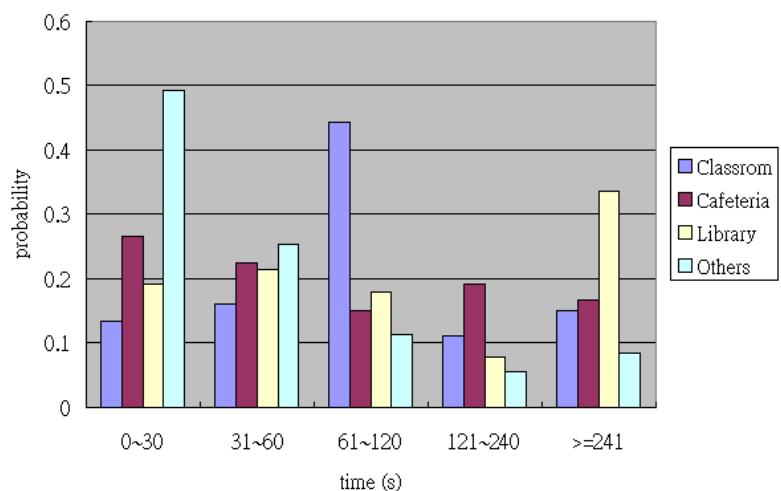


Trace-based Mobility Modeling

- ▶ Extend the *IMPORTANT* mobility tool:
 - ▶ URL: <http://nile.cise.ufl.edu/important>
- ▶ Trace-based mobility models nile.cise.ufl.edu/MobiLib
 - ▶ Pedestrians on campus
 - ▶ Usage pattern (WLAN traces)
 - ▶ USC, MIT, UCSD, Dartmouth,...
 - ▶ Student tracing (survey, observe)
 - ▶ Vehicular mobility
 - ▶ Transportation literature
 - ▶ Parametrized hybrid models
 - ▶ Integrate Weighted Group mobility with...
 - ▶ Derive the parameters based on the traces



Survey based: Weighted Way Point (WWP) Model [ACM MC²R 04]





Q1. What is the computational cost and performance metrics of V2V Mobility Modeling and Simulation using Periodic Broadcast (PBC) Messages for Traffic Congestion Control (i.e., Mitigation)? Explain your answer.

The ETSI standardized message set for vehicular communication is Cooperative Awareness Messages (CAM). CAM is a set of VANETs application that intended for the intelligent transportation system using the periodically messaging services that can be used to send and receive notification. The traffic congestion is significant factor in disrupting traffic flows. The CAM notifications are utilized to enhance traffic flow by mitigating traffic congestion through Vehicle to Vehicle (V2V) communication System. The using of CAM notification can parse congestion at high traffic density points.



Q2. Importance of vehicle discovery for V2V (or V2I) communication in VANETs? Explain your answer based on mobility patterns and routing.



