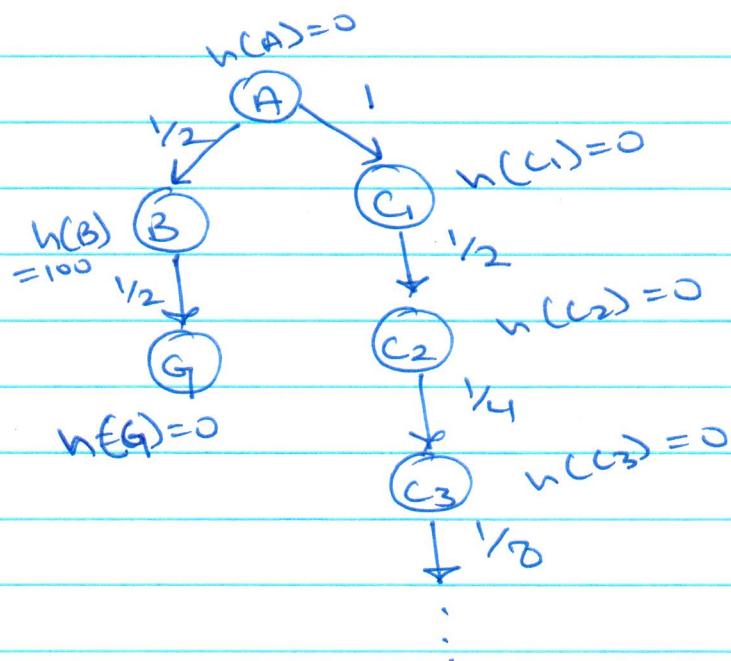


Hw 4Q1.

- i) As the cost of going from  $B \rightarrow G$  is equal to  $\frac{1}{2}$ , the range of  $h(B)$  that would be admissible would be  $[0, \frac{1}{2}]$ .

2)

Iteration 1

States in Closed = {A}

States in Open = {B, C}

A: ~~g(A)=0~~  $g(A)=0$ ,  $h(A)=0$ ,  $f(A)=0$ B:  $g(B)=\frac{1}{2}$ ,  $h(B)=100$ ,  $f(B)=100\frac{1}{2}$ , BackpointerC:  $g(C)=1$ ,  $h(C)=0$ ,  $f(C)=1$ , Backpointer to A

## Iteration 2.

States in Closed = { A, C<sub>1</sub> }

States in Open = { B, C<sub>2</sub> }

A : g(A) = 0, h(A) = 0, f(A) = 0

B : g(B) = 1/2, h(B) = 100, f(B) = 100 1/2, Backpointer to A

C<sub>1</sub> : g(C<sub>1</sub>) = 1, h(C<sub>1</sub>) = 0, f(C<sub>1</sub>) = 1, Backpointer to A

C<sub>2</sub> : g(C<sub>2</sub>) = 1 1/2, h(C<sub>2</sub>) = 0, f(C<sub>2</sub>) = 1 1/2, Backpointer to C<sub>1</sub>

## Iteration 3

States in Closed = { A, C<sub>1</sub>, C<sub>2</sub> }

States in Open = { B, ~~C<sub>2</sub>~~, C<sub>3</sub> }

A : g(A) = 0, h(A) = 0, f(A) = 0

B : g(B) = 1/2, h(B) = 100, f(B) = 100 1/2, Backpointer to A

C<sub>1</sub> : g(C<sub>1</sub>) = 1, h(C<sub>1</sub>) = 0, f(C<sub>1</sub>) = 1, Backpointer to A

C<sub>2</sub> : g(C<sub>2</sub>) = 1 1/2, h(C<sub>2</sub>) = 0, f(C<sub>2</sub>) = 1 1/2, Backpointer to C<sub>1</sub>

C<sub>3</sub> : g(C<sub>3</sub>) = 1 3/4, h(C<sub>3</sub>) = 0, f(C<sub>3</sub>) = 1 3/4, Backpointer to C<sub>2</sub>

### Iteration 4

States in Closed = { A, C<sub>1</sub>, C<sub>2</sub>, C<sub>3</sub> }

States in Open = { B, C<sub>4</sub> }

A: g(A) = 0, h(A) = 0, f(A) = 0

B: g(B) = 1/2, h(B) = 100, f(B) = 100 1/2, Backpointer to A

C<sub>1</sub>: g(C<sub>1</sub>) = 1, h(C<sub>1</sub>) = 0, f(C<sub>1</sub>) = 1, Backpointer to A

C<sub>2</sub>: g(C<sub>2</sub>) = 1 1/2, h(C<sub>2</sub>) = 0, f(C<sub>2</sub>) = 1 1/2, Backpointer to C<sub>1</sub>

C<sub>3</sub>: g(C<sub>3</sub>) = 1 3/4, h(C<sub>3</sub>) = 0, f(C<sub>3</sub>) = 1 3/4, Backpointer to C<sub>2</sub>

C<sub>4</sub>: g(C<sub>4</sub>) = 1 7/8, h(C<sub>4</sub>) = 0, f(C<sub>4</sub>) = 1 7/8, Backpointer to C<sub>3</sub>

### Iteration 5

States in Closed = { A, C<sub>1</sub>, C<sub>2</sub>, C<sub>3</sub>, C<sub>4</sub> }

States in Open = { B, C<sub>5</sub> }

A: g(A) = 0, h(A) = 0, f(A) = 0

B: g(B) = 1/2, h(B) = 100, f(B) = 100 1/2, Backpointer to A

C<sub>1</sub>: g(C<sub>1</sub>) = 1, h(C<sub>1</sub>) = 0, f(C<sub>1</sub>) = 1, Backpointer to A

C<sub>2</sub>: g(C<sub>2</sub>) = 1 1/2, h(C<sub>2</sub>) = 0, f(C<sub>2</sub>) = 1 1/2, Backpointer to C<sub>1</sub>

C<sub>3</sub>: g(C<sub>3</sub>) = 1 3/4, h(C<sub>3</sub>) = 0, f(C<sub>3</sub>) = 1 3/4, Backpointer to C<sub>2</sub>

C<sub>4</sub>: g(C<sub>4</sub>) = 1 7/8, h(C<sub>4</sub>) = 0, f(C<sub>4</sub>) = 1 7/8, Backpointer to C<sub>3</sub>

C<sub>5</sub>: g(C<sub>5</sub>) = 1 15/16, h(C<sub>5</sub>) = 0, f(C<sub>5</sub>) = 1 15/16, Backpointer to C<sub>4</sub>

3)  $f(C_i) = \frac{(1 - (1/2)^i)}{1 - 1/2}$  [Sum of a Geometric Progression with  $r = 1/2$ ]

$$\lim_{i \rightarrow \infty} \frac{1 - (1/2)^i}{1 - 1/2}$$

$$= \lim_{i \rightarrow \infty} \left(1 - \frac{1}{2^i}\right) \times 2$$

$$= 2$$

$$\left[ \lim_{i \rightarrow \infty} \frac{1}{2^i} \approx \frac{1}{\infty} \approx 0 \right]$$

- 4) The search will never find G because to get to G, we would have to expand node B which will only happen if B is popped out of open. B will never be popped out of open as its f value is  $100^{1/2}$  and the f value of all  $C_i$  will never even exceed 2. So nodes in the right branch will keep on being popped out of open and B will never be popped out.

5) For the A\* search to find G,

$$f(B) = h(B) + \frac{1}{2} \leq 2$$

$$h(B) \leq \frac{3}{2}$$

and for  $h(B)$  to be inadmissible,  
 $h(B) > \frac{1}{2}$ .

So, range for  $h(B)$  is

$$\frac{1}{2} \leq h(B) \leq \frac{3}{2}$$

6) An admissible  $h$  is a sufficient condition for A\* search to find the optimal goal. Like in this example, if  $\frac{1}{2} \leq h(B) \leq \frac{3}{2}$ , then  $h$  will be inadmissible but still find the optimal goal. Hence it is not a necessary condition.

## Q2 Iteration 1

Current point = 2 , Successor = 3

$$T(1) = 2(0.9)^1 = 1.8$$

$$P = \exp \left\{ - \frac{|f(x) - f(y)|}{T} \right\}$$

$$f(x) = \max \{ 4 - |x|, 2 - |x-6|, 2 - |x+6| \}$$

$$f(x) = \max \{ 4 - 2, 2 - |2-6|, 2 - |2+6| \}$$

$$= \max \{ 2, -2, -6 \}$$

$$= 2$$

$$f(y) = \max \{ 4 - 3, 2 - |3-6|, 2 - |3+6| \}$$

$$= \max \{ 1, -1, -7 \}$$

$$= 1$$

$$P = \exp \left\{ - \frac{|2-1|}{1.8} \right\}$$

$$= \exp \left\{ \frac{-1}{1.8} \right\} = 0.5737$$

As,  $0.102 < 0.5737$ , we move to point 3

## Iteration 2

Current point = 3, Successor = 1

$$T(2) = 2(0.9)^2 = 2 \times 0.81 = 1.62$$

$$f(x) = \max_{\text{P}} \quad 1$$

$$\begin{aligned} f(y) = f(1) &= \max \{ 4 - |1|, 2 - |1 - 6|, 2 - |1 + 6| \} \\ &= \max \{ 3, -3, -5 \} \\ &= 3. \end{aligned}$$

~~process~~ As  $f(y) > f(x)$ ,  
we move to point 1. Thus,  $p = 1$

## Iteration 3

Current point = 1, Successor = 1

$$T(3) = 2(0.9)^3 = 2 \times 0.729 = 1.458$$

$$f(x) = f(y) = 3$$

$$p = \exp \left\{ \frac{-0}{1.458} \right\} = e^{-0} = \frac{1}{e^0} = 1$$

### Iteration 4

Current point = 1, Successor = 4

$$T(4) = 2(0.9)^4 = \cancel{0.9} 1.3122$$

$$f(x) = 3$$

$$\begin{aligned} f(y) &= \max \{ 4 - 141, 2 - 14 - 61, 2 - 14 + 61 \} \\ &= \max \{ 0, 0, -8 \} \\ &= 0. \end{aligned}$$

$$p = \exp \left\{ \frac{-|3-0|}{1.3122} \right\}$$

$$= \exp \left\{ \frac{-3}{1.3122} \right\} = 0.101$$

As  $0.493 > 0.101$ , we do not move.

### Iteration

### Iteration 5

Current point = 1, Successor = 2

$$T(5) = 2 \log 5 = 1.181$$

$$f(x) = 3$$

$$\begin{aligned} f(y) = f(2) &= \max \{ 4 - |2|, 2 - |2 - 6|, 2 - |2 + 6| \} \\ &= \max \{ 2, -2, -6 \} \\ &= 2. \end{aligned}$$

$$p = \exp \left\{ \frac{-|3-2|}{1.181} \right\}$$

$$= \exp \left\{ \frac{-1}{1.181} \right\} = 0.4288$$

As  $0.312 < 0.4288$ ,

we move to 2.

### Iteration 6

Current = 2, Successor = 3

$$T(6) = 1.063$$

$$f(x) = 2$$

$$f(y) = f(3) = 1$$

$$p = \exp \left\{ - \frac{|2-1|}{1.063} \right\} = \exp \left\{ \frac{-1}{1.063} \right\} = 0.3903$$

### Iteration 7

Current = 2, Successor = 4

$$T(7) = 0.957$$

$$f(x) = 2$$

$$f(y) = f(4) = 0$$

$$p = \exp \left\{ - \frac{|2-0|}{0.957} \right\} = \exp \left\{ \frac{-2}{0.957} \right\} = 0.1237$$

### Iteration 8.

Current = 2, Successor = 3

$$T(\infty) = 0.861$$

$$f(x) = 2$$

$$f(y) = f(3) = 1$$

$$P = \exp \left\{ - \frac{|2-1|}{0.861} \right\} = \exp \left\{ - \frac{1}{0.861} \right\} = 0.313$$

As  $0.313 < 0.887$ ,

we stay at point 2. 2

Q3:

- The number of states for  $n$  trees is the same as the number of permutations of a string with  $n$  characters which is ~~no~~  $n!$

- There will be  $n-1$  possible successors as there are  $n-1$  values for  $j$  and each swap gives a unique successor.

The fraction of the state space covered is,

$$\frac{n-1}{n!} = \frac{n-1}{n(n-1)(n-2)!}$$

$$\frac{1}{n(n-2)!}$$

$$3) n = 112,511$$

$$\text{No. of states} = (112511)_b = 1.04 \times 10^{519455}$$
$$= 1 \times 10^{519455}$$

$$4) \text{Total distance} = d(0, t_1) + \sum_{i=1}^m d(t_i, t_{i+1}) + d(t_m, e)$$
$$= 10 + (112,511 - 1) \times 10 + 10$$
$$= 10 + (112,510) \times 10 + 10$$
$$= 20 + 1125100$$
$$= 1125120 \text{ Km}$$

$$1 \text{ LD} = 384,400 \text{ Km}$$

$$\text{Total distance} = \frac{1125120}{384400} \text{ LD} = 2.92 \text{ LD}$$

≈ 3 LD

$$5) \text{Best case} = 10 + (112,510) \times 10 + 10$$
$$= 1125120 \text{ m}$$
$$= \frac{1125,120}{1000} \text{ Km} = \boxed{1125.12 \text{ Km}}$$

$$6) 1125.12 \text{ Km} = 699.12 \text{ miles.}$$
$$\frac{699.12}{25} = 27.96 \text{ hours.}$$

→ Even in the best case, the inspector cannot finish in one day. //