

# Estimating Euler's Number (e) Using Probability Theory

## Introduction

Euler's number  $e$  is a fundamental mathematical constant. In this report, we estimate using two probabilistic approaches.

## Method 1: Geometric Mean of Uniform Samples

### Concept

If we take a large number of samples from a uniform distribution, compute their geometric mean, and take its inverse, we obtain an estimate for  $e$ . Repeating this process multiple times and averaging the results improves accuracy.

### Implementation

```
n= 1e6      ## No.of observation from U(0,1) by each individual.

k= 1e2      ## No. of observer..

vec<- numeric(length = k)## Vector that will store the estimated value of e from each

for( i in 1:k){
  uni<- runif(n,0,1)      ##generation of 1e6 samples from U(0,1)

  yn<- prod(uni^(1/n))    ## Taking geometric mean of all samples
```

```

    vec[i]<- 1/yn
  }

e <- mean(vec)  ## mean of the values estimated by every individual.

cat("The value of e :",e)      ## Value of estimated e..

```

The value of e : 2.718274

## Mathematical Proof of Method 1

Let  $X_1, X_2, \dots, X_n$  be independent and identically distributed (i.i.d.) random variables drawn from the uniform distribution  $U(0, 1)$ . We define their geometric mean as:

$$Y_n = \left( \prod_{i=1}^n X_i \right)^{\frac{1}{n}}$$

Taking the natural logarithm on both sides:

$$\log Y_n = \frac{1}{n} \sum_{i=1}^n \log X_i$$

Since  $X_i \sim U(0, 1)$ , we use the known expectation result:

$$\mathbb{E}[\log X] = \int_0^1 \log x \, dx = -1$$

By the Law of Large Numbers, as  $n \rightarrow \infty$ , the sample mean of  $\log X_i$  converges to its expected value:

$$\mathbb{E}[\log Y_n] \approx -1$$

which implies:

$$\mathbb{E}[Y_n] \approx e^{-1}$$

Taking the reciprocal gives our estimator for  $e$ :

$$\hat{e} = \frac{1}{Y_n}$$

Thus, as  $n$  grows large,  $\hat{e}$  provides an approximation to Euler's number  $e$ .

## Explanation

- The geometric mean of a large number of independent uniform variables approximates  $e$ , so taking its inverse gives an estimate of  $1/e$ .
- By repeating the experiment 100 times, we mitigate randomness and improve accuracy.

## Method 2: Estimation Using Derangements of a Deck of Cards

### Concept

- A derangement is a permutation where no element appears in its original position.
- The probability of a derangement of objects converges to  $1/e$ , so the estimate of  $e$  is given by the inverse of this probability.

### Implementation

```
is_derangement <- function(permutation) {  
  all(permutation != seq_along(permutation))  
  ## Check if the permutation is deranged  
}  
  
estimate_e <- function(deck_size, trials) {  
  derangements <- 0  
  cumulative_e <- numeric(trials)  
  ## Store e estimates at each trial  
  
  for (i in 1:trials) {  
    deck <- sample(1:deck_size)  
    ## Shuffle the cards  
  
    if (is_derangement(deck)) {  
      derangements <- derangements + 1  
    }  
  
    cumulative_e[i] <- ifelse(derangements > 0, i / derangements, Inf)  
    #inverse of probability after each trial  
  }  
}
```

```

    return(cumulative_e) #e estimates after each trial
}

cards <- 52 ## Standard 52 deck of cards (numbered 1 to 52)
trials <- 2*1e4 ## Number of trials
repeats <-100; ## Repetitions for accuracy

vec_e<-numeric(length = repeats); #vector that stores e estimates

for(i in 1:repeats){
  cumulative_e <- estimate_e(cards,trials)
  vec_e[i] <- cumulative_e[length(cumulative_e)]
}

final_estimate <- mean(vec_e)

cat("The value of e:", final_estimate)

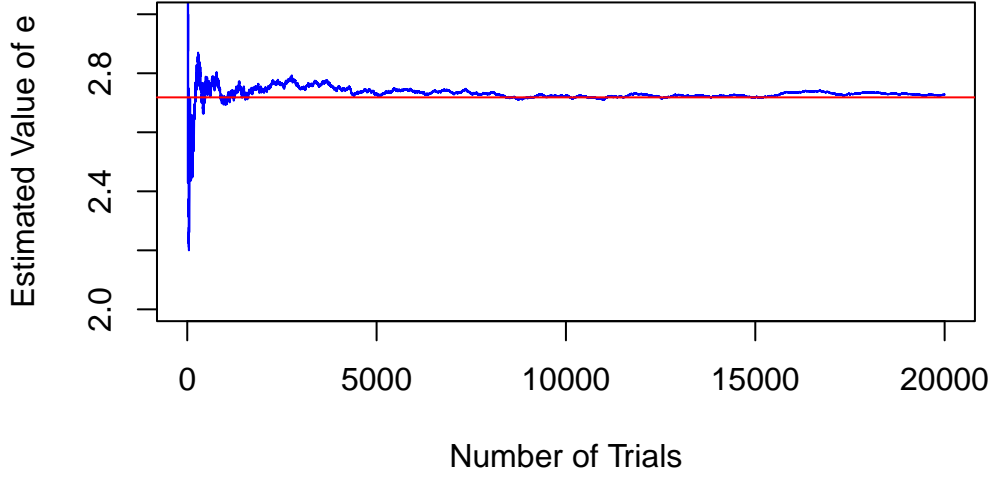
```

The value of e: 2.718365

```

## Plot how estimate gets closer to real value
plot(1:trials, cumulative_e, type = "l", col = "blue",
     , ylim = c(2, 3), xlab = "Number of Trials", ylab = "Estimated Value of e")
abline(h = exp(1), col = "red")

```



### Mathematical Proof of Method 2

A derangement is a permutation where no element appears in its original position. We define:

- $D_n$  as the number of derangements of an  $n$ -element set.
- $n!$  as the total number of permutations.

The probability of a random permutation being a derangement is:

$$P(D_n) = \frac{D_n}{n!}$$

Using the recurrence relation:

$$D_n = (n-1)(D_{n-1} + D_{n-2})$$

it follows that:

$$D_n = \left(\frac{n!}{e}\right) \sum_{k=0}^n \frac{(-1)^k}{k!}$$

Taking the limit:

$$\lim_{n \rightarrow \infty} \frac{D_n}{n!} = \frac{1}{e}$$

Thus, the probability of a derangement approaches  $(\frac{1}{e})$ . Given  $k$  independent trials and  $p$  observed derangements, the estimate of  $e$  is:

$$\hat{e} = \frac{k}{p}$$

which converges to  $e$  as  $k \rightarrow \infty$ .

### Explanation

- The experiment repeatedly shuffles a deck of 52 cards and checks if it is a derangement.
- The probability of derangement  $D_n/n!$  so the inverse of the observed probability provides an estimate of  $e$ .
- The red line in the plot represents the true value of  $e$  showing convergence.

### Conclusion

Both methods successfully estimate  $e$ . The geometric mean method relies on properties of uniform distributions, while the derangement method leverages combinatorial probabilities. The results illustrate how fundamental mathematical constants emerge naturally in probability theory.