

THEORY QUESTIONS

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Ans.1 The cost function is given as follows.

$$J(\theta) = \frac{1}{2} \sum_{i=1}^N (h_{\theta}(x_i') - y_i)^2$$

where $x_i' = \begin{bmatrix} 1 \\ x_i \end{bmatrix} \quad \forall i = 1 \text{ to } N.$

And,

$$h_{\theta}(x_i') = \sum_{j=0}^d \theta_j x_{ij} = \theta^T x_i'$$

Here, $x_{i0} = 1$, $x_i = \begin{bmatrix} x_{i1} \\ x_{i2} \\ \vdots \\ x_{id} \end{bmatrix}$

$$\theta = \begin{bmatrix} \theta_0 \\ \theta_1 \\ \vdots \\ \theta_d \end{bmatrix}$$

Given data can be written as

$$X = \begin{bmatrix} \text{---} (x_1')^T \text{---} \\ \text{---} (x_2')^T \text{---} \\ \vdots \\ \text{---} (x_N')^T \text{---} \end{bmatrix}, \quad y = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_N \end{bmatrix}$$

$$X\theta - y = \begin{bmatrix} (x_1')^T \theta \\ \vdots \\ (x_N')^T \theta \end{bmatrix} - \begin{bmatrix} y_1 \\ \vdots \\ y_N \end{bmatrix}$$

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$$= \begin{bmatrix} h_{\theta}(x_1) - y_1 \\ \vdots \\ h_{\theta}(x_N) - y_N \end{bmatrix}$$

Now, we will use the fact that for a given vector z , we have that $z^T z = \sum_i z_i^2$

$$\frac{1}{2} (X\theta - y)^T (X\theta - y) = \frac{1}{2} \sum_{i=1}^N (h_{\theta}(x_i) - y_i)^2$$

$$= J(\theta)$$

To minimize J , we need its derivative w.r.t. θ .

$$\nabla_{\theta} J(\theta) = \nabla_{\theta} \frac{1}{2} (X\theta - y)^T (X\theta - y)$$

$$= \frac{1}{2} \nabla_{\theta} ((X\theta)^T X\theta - (X\theta)^T y - y^T (X\theta) + y^T y)$$

$$= \frac{1}{2} \nabla_{\theta} (\theta^T (X^T X) \theta - y^T (X\theta) - y^T (X\theta))$$

$$= \frac{1}{2} \nabla_{\theta} (\theta^T (X^T X) \theta - 2 (X^T y)^T \theta)$$

$\because a^T b = b^T a$
where
 $a^T b$ is
a scalar

$$= \frac{1}{2} (2 X^T X \theta - 2 X^T y) \left[\nabla_x x^T A x = 2Ax \right] \left[\nabla_x b^T x = b \right]$$

for symmetric matrix A

$$= X^T X \theta - X^T y$$

To minimize J , its derivative w.r.t θ should be 0.

$$X^T X \theta = X^T y$$

$$\theta = (X^T X)^{-1} X^T y$$

θ exists under 'suitable conditions' given mentioned in Ans 2.

Ans. 2

$X^T X$ should be invertible

Ans-3

Closed form solution for a linear regression problem with ~~d~~ independent variables requires us to find inverse of the matrix $X^T X$.
Dimensions of $X^T X = (d+1) \times (d+1)$

The general algorithm that finds inverse has time complexity $O((d+1)^3) \sim O(d^3)$

~~Remember~~ 2

Also, forming the ~~equations~~ matrix $X^T X$ takes $O(d^2 N)$.

Gradient descent performs $O(dN)$ operations in 1 iteration.

We can decide how many iterations we want to perform based on ~~error~~ tolerance and time constraint. Gradient descent takes less time than closed normal form if no. of iterations are small.

When we have less time, we can use gradient descent.

Ans 4

$$(X^T X) \theta = X^T y$$

Since, we have simple linear regression,
 $d=1$.

$$X = \begin{bmatrix} 1 & x_{11} \\ 1 & x_{12} \\ \vdots & \vdots \\ 1 & x_{1N} \end{bmatrix}, \quad X^T = \begin{bmatrix} 1 & \dots & 1 \\ x_{11} & \dots & x_{1N} \end{bmatrix}$$

$$X^T X = \begin{bmatrix} 1 & \sum_{j=1}^N x_{1j} \\ \sum_{j=1}^N x_{1j} & \sum_{j=1}^N (x_{1j})^2 \end{bmatrix}$$

$$\begin{bmatrix} N & \sum_{j=1}^N x_{1j} \\ \sum_{j=1}^N x_{1j} & \sum_{j=1}^N (x_{1j})^2 \end{bmatrix} \begin{bmatrix} \theta_0 \\ \theta_1 \end{bmatrix} = \begin{bmatrix} 1 & \dots & 1 \\ x_{11} & \dots & x_{1N} \end{bmatrix} \begin{bmatrix} y_1 \\ \vdots \\ y_N \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} \theta_0 N + \theta_1 \sum_{j=1}^N x_{1j} \\ \theta_0 \sum_{j=1}^N x_{1j} + \theta_1 \sum_{j=1}^N (x_{1j})^2 \end{bmatrix} = \begin{bmatrix} \sum_{i=1}^N y_i \\ \sum_{i=1}^N x_{1i} y_i \end{bmatrix}$$

Equating the first rows,

$$\theta_0 N + \theta_1 \sum_{j=1}^N x_{1j} = \sum_{i=1}^N y_i$$

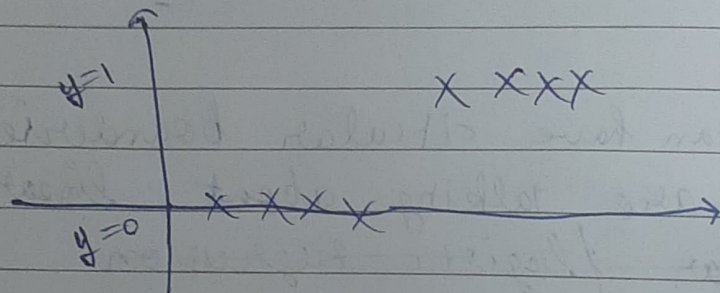
$$\theta_0 + \theta_1 \frac{\sum_{j=1}^N x_{1j}}{N} = \frac{\sum_{i=1}^N y_i}{N}$$

$$\Rightarrow \theta_0 + \theta_1 \bar{X} = \bar{Y}$$

All the notations have been defined in Ans.1

Ans. 5

We can use linear regression by fixing a threshold.
Consider this example of 8 datapoints, 4 of which



are having label 0 and ~~four~~ other rest 4 are having label 1.

we need to learn θ_0, θ_1 such that

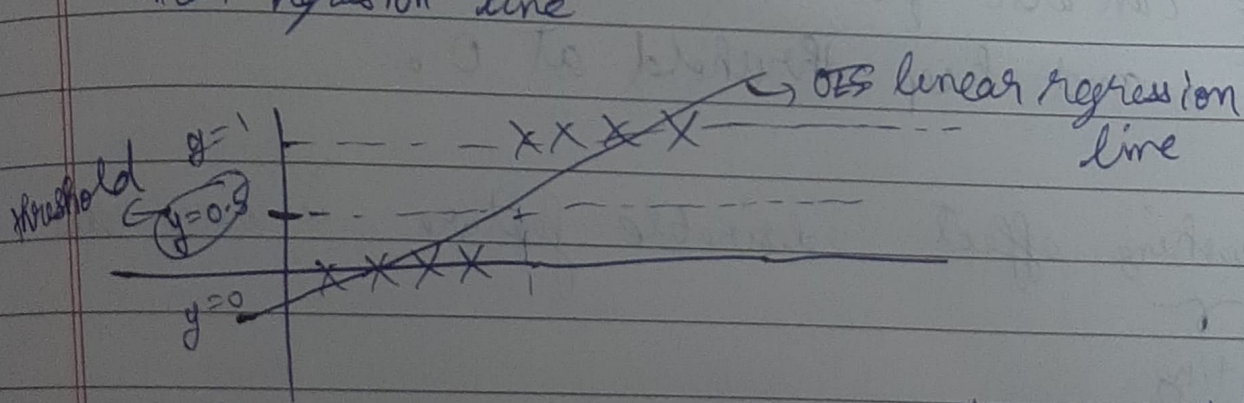
$$y = \theta_0 + x\theta_1.$$

We can set threshold at 0.5.

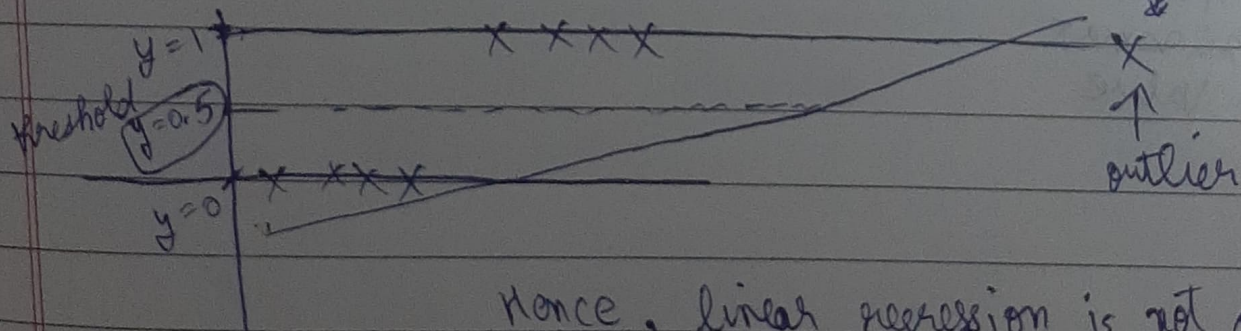
If $\hat{\theta}_0 + x\hat{\theta}_1 > 0.5$, then we classify the point as 1

else 0

But it does not perform well when outliers exist.



when there is an outlier, we classify many points ^{on} ~~outlier~~ $y=1$ wrongly



Hence, linear regression is not advisable to be used