

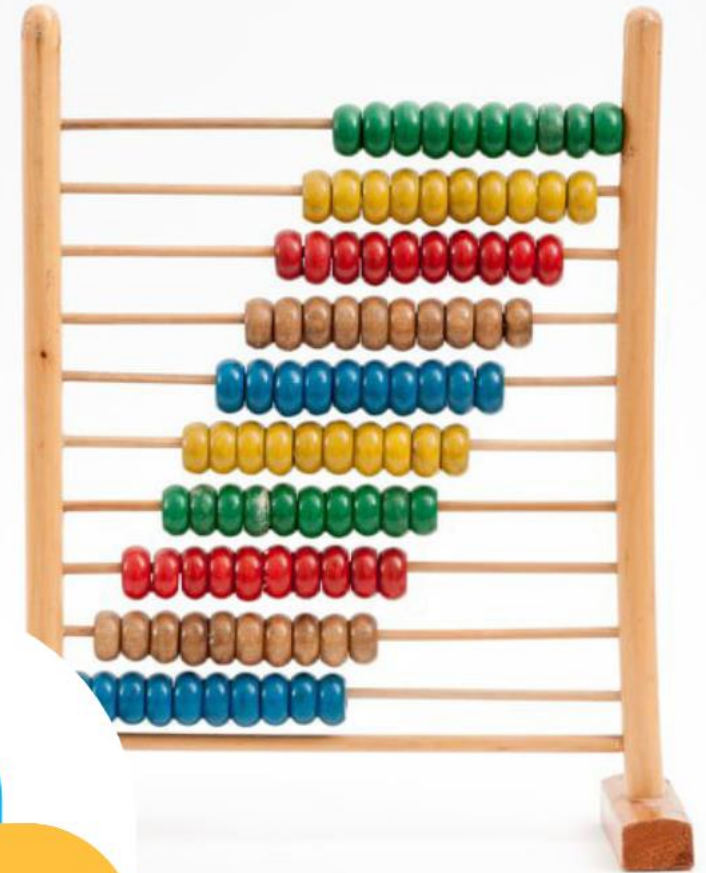
# Fast Key Access with Hashing

Why hash tables solve exact-match performance

Map arbitrary keys to fixed indices for expected  $O(1)$  lookup, insert, delete;  
focus on algorithmic hashing, not cryptography.

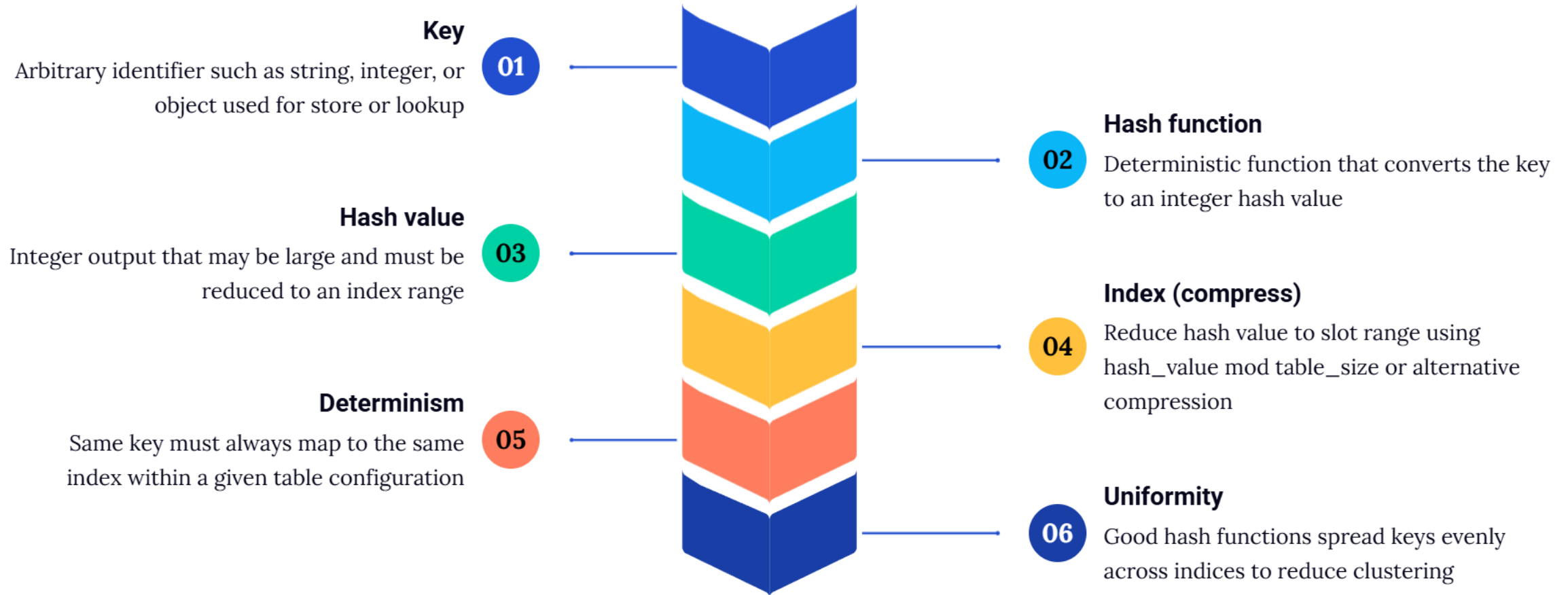
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# Hashing Basics: Keys, Functions, Values, and Indices

How keys map deterministically and uniformly into table slots

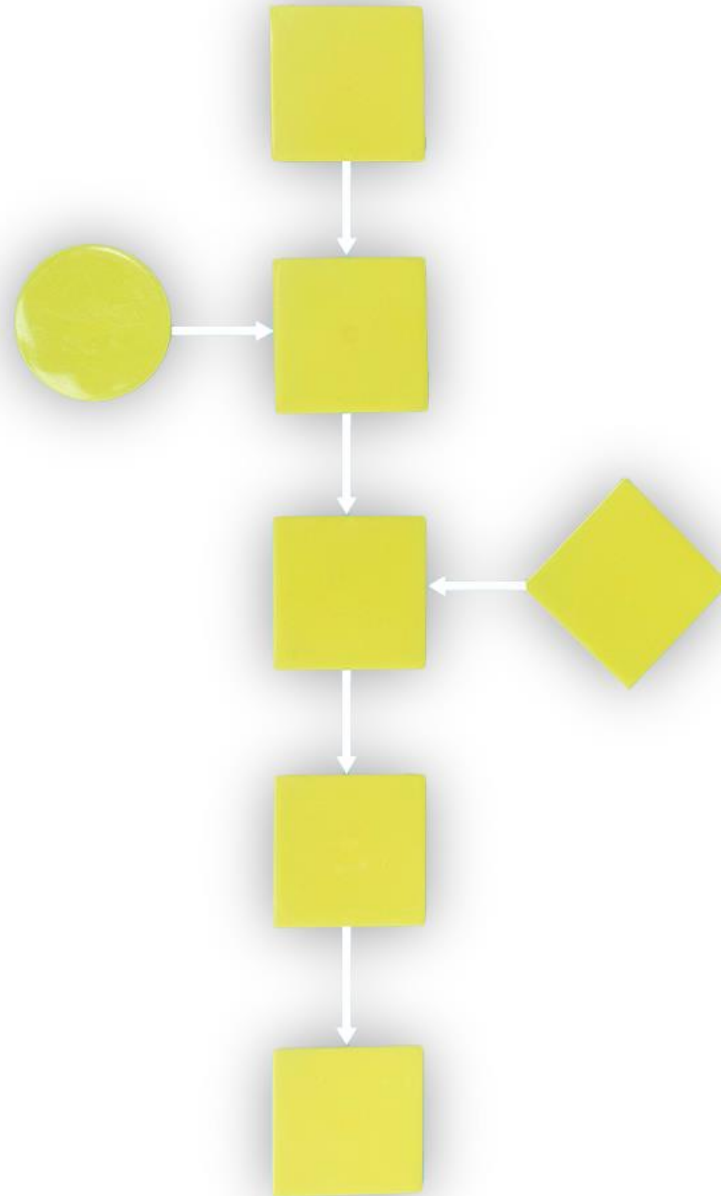


# Hash tables

	0	1	2	3	4	5
Values →	Ahmed	Ali	John	Jane	Mehmed	Ali
Keys →	a10	a11	a12	a13	a14	a15

# Collisions in Hash Tables: why they happen and why they matter

Pigeonhole inevitability and measurable performance cost



## Why they happen

Pigeonhole principle: finite table slots vs unlimited keys guarantees collisions



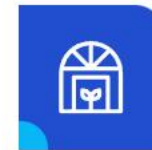
## Immediate implication

Distinct keys map to same index; extra work needed to remain correct



## Performance impact

Longer probes or larger buckets push average time from  $O(1)$  toward  $O(n)$



## Practical note

Small load factor increases sharply raise collision rate and latency

# Memory Layout and Cache Trade-offs for Hash Tables

Compare separate chaining versus open addressing for in-memory performance



## Separate Chaining

- Memory: pointers per entry increase footprint
- Cache: poor locality because of pointer chasing
- Use when: bucket sizes remain small or deletions frequent

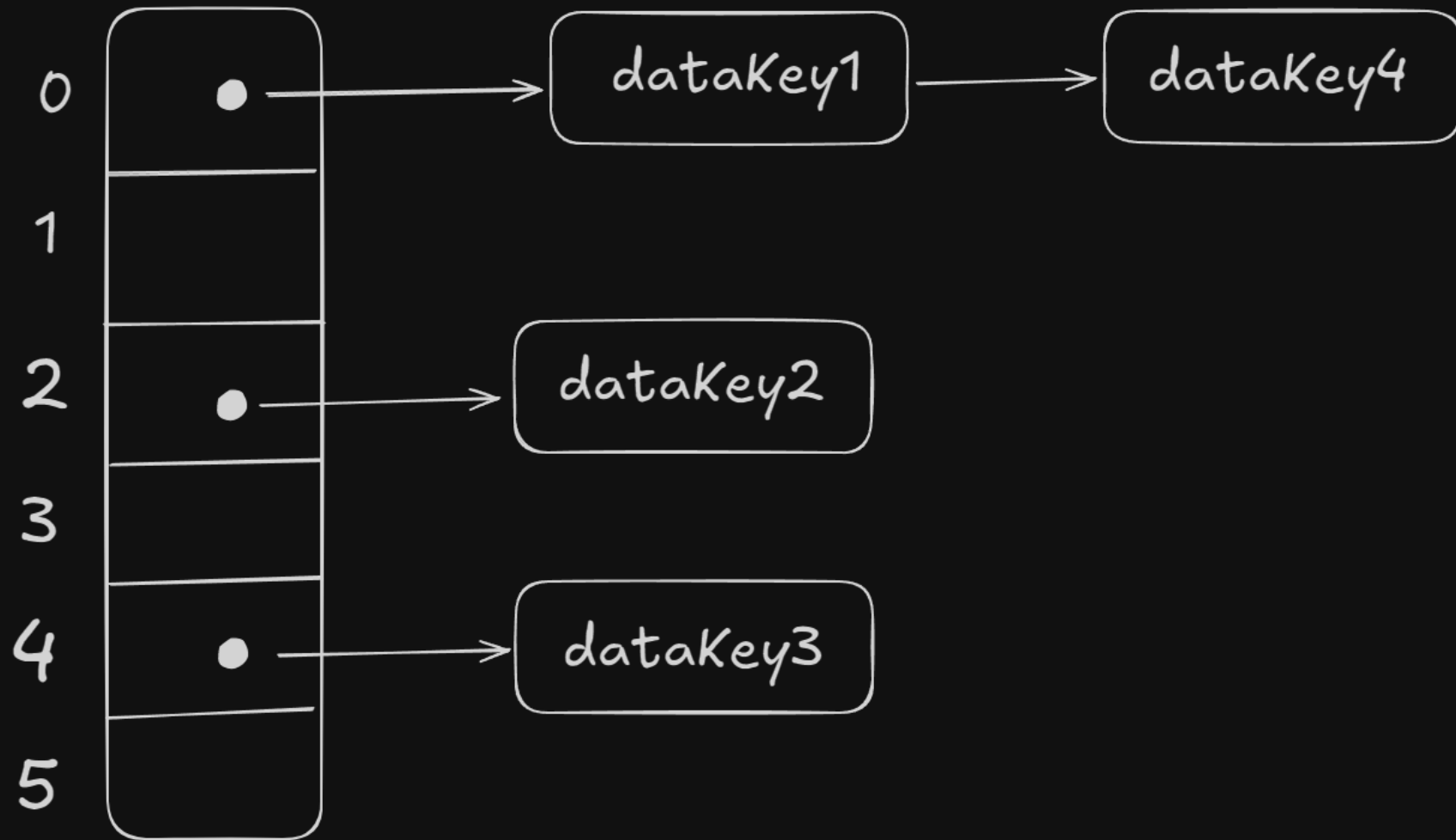
# vs




## Open Addressing

- Memory: compact contiguous array lowers overhead
- Cache: better locality and fewer cache misses at moderate load
- Use when: read-heavy workloads and load factor controlled

# Chaining example



# Code example




```
1  #include <stdio.h>
2  #include <stdlib.h>
3
4  #define TABLE_SIZE 10
5
6  // Node structure for chaining
7  struct Node {
8      int key;
9      struct Node* next;
10 };
11
12 // Hash table (array of pointers)
13 struct Node* hashTable[TABLE_SIZE];
14
```

# Code example


```
1  int hashFunction(int key) {
2      return key % TABLE_SIZE;
3  }
4
5  // Insert key into hash table
6  void insert(int key) {
7      int index = hashFunction(key);
8
9      struct Node* newNode = (struct Node*)malloc(sizeof(struct Node));
10     newNode->key = key;
11     newNode->next = hashTable[index];
12
13     hashTable[index] = newNode;
14 }
15
16 // Search key in hash table
17 int search(int key) {
18     int index = hashFunction(key);
19     struct Node* current = hashTable[index];
20
21     while (current != NULL) {
22         if (current->key == key)
23             return 1; // Found
24         current = current->next;
25     }
26     return 0; // Not found
27 }
```



# Collision



```
1
2 // Main function
3 int main() {
4     insert(15);
5     insert(25);
6     insert(35); // collision with 15 and 25
7
8     if (search(25))
9         printf("Key 25 found in hash table.\n");
10    else
11        printf("Key 25 not found.\n");
12
13    return 0;
14 }
```



# Thanks for Listening — Key Takeaways on Hashmaps

Questions about hashing or performance?

