Digital Image Processing Project 2

Omar Rawashdeh Harshal Raut Utsav Shah

September 27, 2016

Contents

1	Inti	roduction	4		
	1.1	Image Enhancement	4		
2	Problem 1				
	2.1	Discussion and Objective	5		
	2.2	Filter and Parameter Used	5		
	2.3	Results and Remarks	6		
	2.4	MATLAB Source Code	7		
3	Problem 2				
	3.1	Discussion and Objective	9		
	3.2	Filter and Parameter Used	9		
	3.3	Results and Remarks	10		
	3.4	MATLAB Source Code	12		
4	Problem 3				
	4.1	Discussion and Objective	14		
	4.2	Filter and Parameter Used	14		
	4.3	Results and Remarks	15		
	4.4	MATLAB Source Code	19		
5	\mathbf{Pro}	blem 4	20		
	5.1	Discussion and Objective	20		
	5.2	Filter and Parameter Used	20		
	5.3	Results and Remarks	21		
	5.4	MATLAB Source Code	25		
6	Problem 5 26				
	6.1	Discussion and Objective	26		
	6.2	Filter and Parameter Used	26		
	6.3	Results and Remarks	27		
7	Ma	in Source Code	28		

List of Figures

1	Original Image	6
2	Gray Scale Logarithmic Transform Image	7
3	Blurred Image	10
4	Cleared Image Using Median Filter	11
5	Edge Extraction Noisy Image Without Scaling	15
6	Edge Extraction Noisy Image With Scaling	16
7	Edge Extraction No Noise Image Without Scaling	17
8	Edge Extraction No Noise Image With Scaling	18
9	Sharpened Gray Image using Sharp Mask	21
10	Sharpened Colored Image using Sharp Mask	22
11	Sharpened Gray Image using Unsharp Mask	23
12	Sharpened Colored Image using Unsharp Mask	24
13	Applying Two Sharpen Masks in Sequence	27
14	Applying One Sharpen Mask	28

1 Introduction

1.1 Image Enhancement

Image Enhancement falls into two categories:

- Enhancement in Spatial Domain: The term spatial domain refers to the Image Plane itself which is direct manipulation of pixels.
- Enhancement in Frequency Domain: Frequency Domain processing techniques are based on modifying the Fourier transform of an image.

The value of a pixel with coordinates (x,y) in the enhanced image is the result of performing some operation on the pixels in the neighbourhood of (x,y) in the input image, F. Neighbourhoods can be any shape, but usually they are rectangular.[1]

The term Spatial Domain refers to the aggregate of the pixels composing an image(1). The Spatial Domain methods are the procedures that operate directly on these pixels.

It is denoted by

$$g(x,y) = T[f(x,y)]$$

where

g(x,y): ProcessedImage; T: OperatoronImage; f(x,y): InputImage

Select a gray level transformation method and apply it to images and discuss your finding.

2.1 Discussion and Objective

The visual appearance of an image is generally characterized by two properties: brightness and contrast. Brightness refers to the overall intensity level and is therefore inuenced by the individual gray-level (intensity) values of all the pixels within an image. Since a bright image (or sub-image) has more pixel gray-level values closer to the higher end of the intensity scale, it is likely to have a higher average intensity value. Contrast in an image is indicated by the ability of the observer to distinguish separate neighboring parts within an image. This ability to see small details around an individual pixel and larger variations within a neighborhood is provided by the spatial intensity variations of adjacent pixels, between two neighboring sub-images, or within the entire image. Thus, an image may be bright (due to, for example, overexposure or too much illumination) with poor contrast if the individual target objects in the image have optical characteristics similar to the background. At the other end of the scale, a dark image may have high contrast if the background is signicantly different from the individual objects within the image, or if separate areas within the image have very different reectance properties.[2]

2.2 Filter and Parameter Used

A function is written to Logarthmic Transformation on the Grayscale Image.



Figure 1: Original Image



Figure 2: Gray Scale Logarithmic Transform Image

2.4 MATLAB Source Code

The following function was written to apply logarthmic transform

Gray Level Logarithmic Transform

```
\begin{array}{lll} & & \text{end} \\ & \text{11} & & \text{DoubleNewImage} = \text{mat2gray} \big( \text{NewImageMat} \,, & [0 \ 255] \big) \,; \\ & \text{12} & & \text{OutputImage} = \text{im2uint8} \big( \text{DoubleNewImage} \big) \,; \\ & \text{13} & \text{end} \end{array}
```

Select at least two spatial filters and apply them to noisy images and discuss your results.

3.1 Discussion and Objective

In blurring, an image is simply blurred using a low pass filter. An image looks more sharp or more detailed if humans are able to perceive all the objects and their shapes correctly in it. For example, an image with a face, looks clear when humans are able to identify eyes, ears nose, lips, forehead, etc. very clear. This shape of an object is due to its edges. So in blurring we simply reduce the edge content and makes the transition form one color to the other very smooth.[3]

Blurring can be achieved by many ways. The common type of filters that are used to perform blurring are.

- Mean filter
- Weighted average filter
- Gaussian filter

3.2 Filter and Parameter Used

Two methods used:

- Blurring image using low pass filter
- Clearing image using median filter to remove salt and pepper noise

Blurring Mask=
$$\begin{bmatrix} 1 & 2 & 1 \\ 2 & 3 & 2 \\ 1 & 2 & 1 \end{bmatrix}$$



Figure 3: Blurred Image



Figure 4: Cleared Image Using Median Filter

3.4 MATLAB Source Code

The following function was written to blur image

Spatial Filter 2 Blur Image

```
function BlurredImage = SpatialFilter2_BlurImage (Image,
                               Mask)
             %BLURIMAGE Summary of this function goes here
             %
                                    Detailed explanation goes here
  3
                                    if (\text{mod}(\text{size}(\text{Mask}, 1), 2) = 0) \mid | (\text{mod}(\text{size}(\text{Mask}, 2)) \mid | (\text{mod}(\text{size}(\text{Ma
  4
                                                      , 2) = 0
                                                        error ('it is recommended to use a mask with odd
                                                                          width and height');
                                   end
  6
                                   SumOfWeights = sum(Mask(:));
                                   NewMask = Mask/SumOfWeights;
10
                                 m = (size(Mask, 2)-1)/2;
                                   n = (size(Mask, 1)-1)/2;
12
                                   BlurredImageMat = Image;
14
                                    for j=m+1: size (Image, 2)-m
15
                                                        for i=n+1: size (Image, 1)-n
                                                                              Values_X_Weights = double(ReadImagePart(Image
17
                                                                                                , i, j, n, m)).*NewMask;
                                                                              BlurredImageMat(i, j) = fix(sum(
18
                                                                                               Values_X_Weights(:));
                                                        end
19
                                   end
20
21
                                   DoubleBlurredImage = mat2gray(BlurredImageMat, [0]
                                   BlurredImage = im2uint8(DoubleBlurredImage);
             end
24
```

The following function was written to remove noise

Spatial Filter 1 Remove Noise Statistical

```
function ClearedImage =
    SpatialFilter1_RemoveNoise_Statistical(NoiseImage, n)

%REMOVENOISE Summary of this function goes here

Detailed explanation goes here

ClearedImage = NoiseImage;

for j=n+1:size(NoiseImage, 2)-n

for i=n+1:size(NoiseImage, 1)-n

Values = ReadImagePart(NoiseImage, i, j, n, n

);

ClearedImage(i, j) = median(Values(:));

end
end
end
end
```

Select two edge extraction methods and apply them to both noise and no noise image and discuss your result.

4.1 Discussion and Objective

A high-pass filter can be used to make an image appear sharper. These filters emphasize fine details in the image – exactly the opposite of the low-pass filter. High-pass filtering works in exactly the same way as low-pass filtering; it just uses a different convolution kernel. In the example below, notice the minus signs for the adjacent pixels. If there is no change in intensity, nothing happens. But if one pixel is brighter than its immediate neighbors, it gets boosted.[4]

Unfortunately, while low-pass filtering smooths out noise, high-pass filtering does just the opposite: it amplifies noise. You can get away with this if the original image is not too noisy; otherwise the noise will overwhelm the image. High-pass filtering can also cause small, faint details to be greatly exaggerated. An over-processed image will look grainy and unnatural, and point sources will have dark donuts around them. So while high-pass filtering can often improve an image by sharpening detail, overdoing it can actually degrade the image quality significantly.

4.2 Filter and Parameter Used

$$\mathbf{M} = \begin{bmatrix} 0 & -1/4 & 0\\ 2 & -1/4 & -1/4\\ 0 & -1/4 & 0 \end{bmatrix}$$

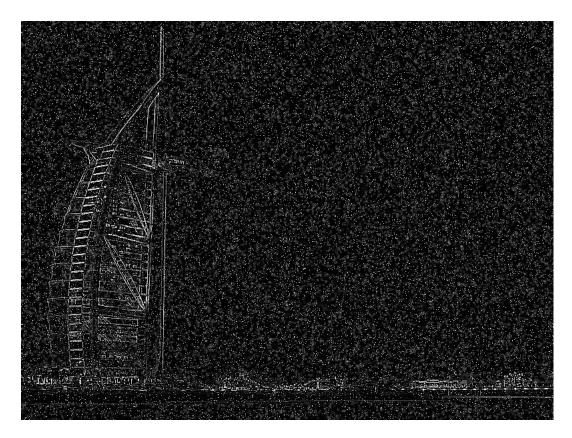


Figure 5: Edge Extraction Noisy Image Without Scaling

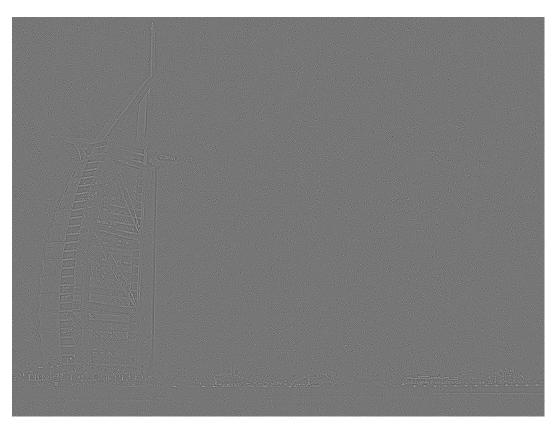


Figure 6: Edge Extraction Noisy Image With Scaling

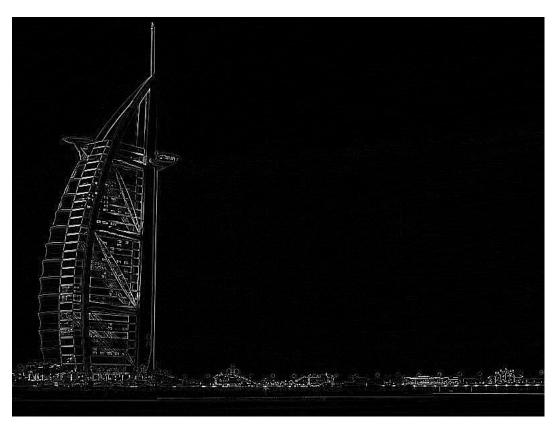


Figure 7: Edge Extraction No Noise Image Without Scaling

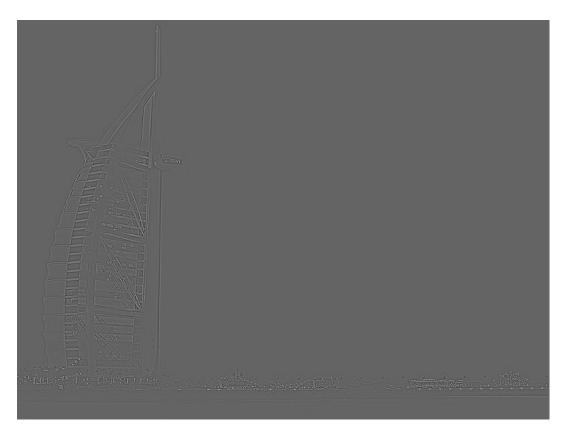


Figure 8: Edge Extraction No Noise Image With Scaling

4.4 MATLAB Source Code

Sharpen

```
function OutPutImage = Sharpen(Image, Mask, Add_X_Y)
            %SHARPEN Summary of this function goes here
                                  Detailed explanation goes here
                                  if (\text{mod}(\text{size}(\text{Mask}, 1), 2) = 0) \mid | (\text{mod}(\text{size}(\text{Mask}, 2)) \mid | (\text{mod}(\text{size}(\text{Ma
                                                   , 2) = 0
                                                     error ('it is recommended to use a mask with odd
                                                                      width and height');
                                 end
                               m = (size(Mask, 2)-1)/2;
                                 n = (size(Mask, 1)-1)/2;
10
                                 OutPutImageMat = zeros(size(Image, 1)-2*n, size(Image)
11
                                                   , 2)-2*m);
                                  for j=m+1: size (Image, 2)-m
12
                                                     for i=n+1: size (Image, 1)-n
13
                                                                          Values_X_Weights = double (ReadImagePart (Image
14
                                                                                           , i, j, n, m)).*Mask;
                                                                          if Add_X_Y
                                                                                             OutPutImageMat(i-n, j-m) = Image(i,j) +
16
                                                                                                               fix (sum(Values_X_Weights(:)));
                                                                          else
17
                                                                                             OutPutImageMat(i-n, j-m) = fix(sum(
18
                                                                                                              Values_X_Weights(:));
                                                                         end
19
                                                     end
20
                                 end
21
22
                                 DoubleImage = mat2gray(OutPutImageMat, [0 255]);
23
                                 OutPutImage = im2uint8(DoubleImage);
24
             end
25
```

Select two image sharpening methods and apply them to different kind of images and discuss your findings.

5.1 Discussion and Objective

- Sharpen grayscale image using sharp mask
- Sharpen colored image using sharp mask
- Sharpen grayscale image using unsharp mask
- Sharpen colored image using unsharp mask

5.2 Filter and Parameter Used

High pass filter is used to sharpen the image with sharp and unsharp masks.



Figure 9: Sharpened Gray Image using Sharp Mask



Figure 10: Sharpened Colored Image using Sharp Mask



Figure 11: Sharpened Gray Image using Unsharp Mask



Figure 12: Sharpened Colored Image using Unsharp Mask

5.4 MATLAB Source Code

Apply High Pass Filter

```
function OutPutImage = ApplyHighPassFilter(Image, Mask,
      Scale)
  %APPLYFILTER Summary of this function goes here
  %
       Detailed explanation goes here
       if (\text{mod}(\text{size}(\text{Mask}, 1), 2) = 0) \mid (\text{mod}(\text{size}(\text{Mask}, 2)))
           , 2) = 0
            error ('it is recommended to use a mask with odd
               width and height');
       end
6
       m = (size(Mask, 2)-1)/2;
       n = (size(Mask, 1)-1)/2;
10
       OutPutImageMat = zeros (size (Mask, 1)-n, size (Mask, 2)
11
          -m);
       for j=m+1: size (Image, 2)-m
12
            for i=n+1: size (Image, 1)-n
13
                Values_X_Weights = double (ReadImagePart (Image
14
                    , i, j, n, m)).*Mask;
                OutPutImageMat(i-n, j-m) = fix(sum(
15
                    Values_X_Weights(:));
            end
16
17
       end
18
       if Scale
19
            DoubleImage = mat2gray(OutPutImageMat, [min(
20
               OutPutImageMat(:)) max(OutPutImageMat(:))]);
       else
21
            DoubleImage = mat2gray(OutPutImageMat, [0 255]);
22
       end
23
24
       OutPutImage = im2uint8(DoubleImage);
25
  end
26
```

Demonstrate that in using two separate filters in a cascading operation, a single filter can be derived with the same resulting output

6.1 Discussion and Objective

Sharpen an image using two masks then sharpen it again using a mask made using both of the original masks

6.2 Filter and Parameter Used

$$\begin{aligned} \text{Mask1} &= \begin{bmatrix} 0 & -1 & 0 \\ -1 & 5 & -1 \\ 0 & -1 & 0 \end{bmatrix} \\ \text{Mask2} &= \begin{bmatrix} -1 & 0 & -1 \\ 0 & 5 & 0 \\ -1 & 0 & -1 \end{bmatrix}; \\ \text{Mask3} &= \begin{bmatrix} 0 & 1 & 0 & 1 & 0 \\ 1 & -5 & -3 & -5 & 1 \\ 0 & -3 & 25 & -3 & 0 \\ 1 & -5 & -3 & -5 & 1 \\ 0 & 1 & 0 & 1 & 0 \end{bmatrix} \end{aligned}$$



Figure 13: Applying Two Sharpen Masks in Sequence



Figure 14: Applying One Sharpen Mask

7 Main Source Code

MainSourceCodeFile

```
7 %
    Digital Image Processing HW2
  %##
                  ##
                     GrayScale & Spatial Filtering
                  ##
                        Matlab R2016a was used
                    ##
                           v9.0.0.341360
 %
    13 %
    %%
14
  %Read/Load example images
  Image1 = imread('Images/1.jpg');
  Image2 = imread('Images/2.jpg');
  % Image3 = imread('Images/3.jpg');
  Image4 = imread('Images/4.jpg');
  Image5 = imread('Images/5.jpg');
  Image6 = imread('Images/6.jpg');
  Image7 = imread('Images/7.jpg');
  Image8 = imread('Images/8.jpg');
  Image9 = imread('Images/9.jpg');
  Image10 = imread('Images/10.jpg');
  Image11 = imread('Images/11.jpg');
  Image12 = imread('Images/12.jpg');
27
28
  warning('off', 'MATLAB:MKDIR: DirectoryExists');
29
  mkdir('results');
  mkdir(fullfile(pwd, 'results'), 'Point1');
31
  mkdir(fullfile(pwd, 'results'), 'Point2');
  mkdir(fullfile(pwd, 'results'), 'Point3');
33
  mkdir(fullfile(pwd, 'results'), 'Point4');
  mkdir(fullfile(pwd, 'results'), 'Point5');
35
  warning('on', 'MATLAB:MKDIR: DirectoryExists');
37
  %<><< Preparing a grayscale Image and a noisy image
     >>>>>
  %convert colored image to grayscale
```

%

```
%parameters :
  %1) the colored image that we want to convert to gray
  GrayImage = Convert2Gray(Image6);
  imwrite (GrayImage, fullfile (pwd, 'results', 'GrayScale.jpg'
      ), 'jpg');
47
48
49
  %Add random noise to an image
  %parameters :
  %1) the image that we want to add noise to
  %2) amount/value/amplitude of noise
  %3) percentage of noise, if 0 no noise will be added if
      100 all pixel will
  %have noise added to them
  NoisyGrayImage = AddNoise(GrayImage, 150, 10);
57
  imwrite (NoisyGrayImage, fullfile (pwd, 'results', '
      NoisyGrayImage.jpg'), 'jpg');
  %
60
      <<<<<><<<><<<><<<><<<><<<><<<><<><<<><<<>><<>><<>><<<>><</><<>></><</><<>></><</><<>></><</><<>></><<>></><<>></><</><<>></><<>>
  %%
61
62
63
64
  %<<<<<<POINT
65
      1>>>>>>
  %%
66
  %=
  %apply the gray level Log Transformation on a grayscale
  %formula is: new level = constant*log(1+old level)
69
  %parameters :
  %1) the Gray scale image that we want to modify
  GrayTransformedImage = GrayLevelTransform_Log(GrayImage);
  imwrite (GrayTransformedImage, fullfile (pwd, 'results', '
      Point1', 'GrayLevelTransformedImage.jpg'), 'jpg');
  %
76
     <<<<<></></>
77 %
```

```
78
79
  %<<<<<<<<POINT
      2>>>>>>
  %%
  %
83
  %construct a mask then blur the Noisy image using a low
      pass filter (all weights are positive)
85
  MaskBlurring = [1 \ 2 \ 1;
86
                  2 3 2;
87
                  1 2 1];
  %parameters :
  %1) the noisy image that we want to blur
  %2) Blurring mask, all weights must be positive
   BlurredImage = SpatialFilter2_BlurImage (NoisyGrayImage,
      MaskBlurring);
93
   imwrite (BlurredImage, fullfile (pwd, 'results', 'Point2', '
94
      BlurredImage.jpg'), 'jpg');
95
  %Clear the noise from an image using statistical mask(
      median).
  %this function gives a better performance in removing the
       random noise
  %compared to just blurring or taking average
99
  %
100
  %parameters :
  %1) the noisy image that we want to remove the noise from
  %2) n value =>> if you want the mask size to be 3x3 then
      enter n as 1
   ClearedImage = SpatialFilter1_RemoveNoise_Statistical(
104
      NoisyGrayImage, 1);
105
  imwrite (ClearedImage, fullfile (pwd, 'results', 'Point2', '
106
      ClearedImageUsingMedianFilter.jpg'), 'jpg');
107
      %%
108
109
111
```

```
%%
113
   %
   %Edge Extraction using a Mask of values 0 -1 0; -1 4 -1;
       0 - 1 0
   %(highpass filter) with scaling
116
117
118
   MaskEdgeExtraction1 = [0 -1 0;
                            -1 \ 4 \ -1;
120
                            0 -1 0];
121
   %Parameters :
122
   %1) the GrayScale Image that we want to extract edges
123
       from using HighPass
   %filter
   %2) the Mask
   %3) Boolean Value indicating whether we want to scale
126
       values to 0 255 after
   %applying the filter
   EdgeExtractionNoNoiseImage1_WithScaling =
       ApplyHighPassFilter(GrayImage, MaskEdgeExtraction1,
       true);
   EdgeExtractionNoisyImage1_WithScaling =
       ApplyHighPassFilter (NoisyGrayImage,
       MaskEdgeExtraction1, true);
   imwrite (EdgeExtractionNoNoiseImage1_WithScaling, fullfile
131
       (pwd, 'results', 'Point3',
       EdgeExtractionNoNoiseWithScaling.jpg'), 'jpg');
   imwrite(EdgeExtractionNoisyImage1_WithScaling, fullfile(
       pwd, 'results', 'Point3', 'EdgeExtractionNoisyWithScaling
       .jpg'), 'jpg');
133
134
   %Edge Extraction using a Mask of values −1 −1 −1; −1 8
       -1; -1 -1 -1
   %(highpass filter) without scaling
137
   MaskEdgeExtraction2 = \begin{bmatrix} -1 & -1 & -1; \end{bmatrix}
138
                            -1 \ 8 \ -1;
139
                            -1 \ -1 \ -1;
   %Parameters :
   %1) the GrayScale Image that we want to extract edges
       from using a HighPass
143 %filter
```

```
144 \%2) the Mask
  %3) Boolean Value indicating whether we want to scale
       values to 0 255 after
  %applying the filter
  EdgeExtractionNoNoiseImage2_WithoutScaling =
      ApplyHighPassFilter(GrayImage, MaskEdgeExtraction2,
       false);
   EdgeExtractionNoisyImage2_WithoutScaling =
      ApplyHighPassFilter (NoisyGrayImage,
      MaskEdgeExtraction2, false);
149
   imwrite (EdgeExtractionNoNoiseImage2_WithoutScaling,
       fullfile (pwd, 'results', 'Point3',
      EdgeExtractionNoNoiseWithoutScaling.jpg'), 'jpg');
   imwrite (EdgeExtractionNoisyImage2_WithoutScaling,
      fullfile (pwd, 'results', 'Point3','
      EdgeExtractionNoisyWithoutScaling.jpg'), 'jpg');
  %
152
      %%
153
154
155
156
157
   %Sharpen GrayScale Image with a mask [-1 -1 -1; -1 9 -1;
159
       -1 -1 -1
  %Note: we use the same mask that we used for edge
160
      extraction \begin{bmatrix} -1 & -1 & -1; & -1 & 8 & -1; & -1 & -1 \end{bmatrix}
   Wwe just tell the sharping function to add the value of f
161
      (x,y) to the new image,
   %thus 8 will become 9
162
163
  %parameters :
  %1) GrayScale Image that we want to sharpen
165
  %2) Mask
   \%3) boolean to tell the function to add the f(x,y) (value
167
       of original
   %image) or not, if it is false, mask must have weights
168
      that sum up to a number
   %other than zero (1 if the middle is + and -1 if the
169
      middle is -)
   SharpenedGrayImage1 = Sharpen(GrayImage,
      MaskEdgeExtraction2, true);
```

```
\% \text{ S1} = \text{size} (\text{Image6}, 1) - 2;
172
   ColoredImageMatrix = zeros(size(Image6, 1)-2, size(Image6)
173
       , 2)-2, size (Image6, 3), 'uint8');
   %for the colored image sharpen each channel seperately
174
   ColoredImageMatrix(:,:,1) = Sharpen(Image6(:,:,1),
       MaskEdgeExtraction2, true);
   ColoredImageMatrix(:,:,2) = Sharpen(Image6(:,:,2)),
       MaskEdgeExtraction2, true);
   ColoredImageMatrix(:,:,3) = Sharpen(Image6(:,:,3),
       MaskEdgeExtraction2, true);
   SharpenedColorImage1 = im2uint8(ColoredImageMatrix);
178
179
   imwrite (Sharpened Gray Image1, fullfile (pwd, 'results', '
180
       Point4', 'SharpenedGrayImageConvolution.jpg'), 'jpg');
   imwrite (Sharpened Color Image 1, fullfile (pwd, 'results',
181
       Point4', 'SharpenedColoredImageConvolution.jpg'), 'jpg
       );
182
183
   %Sharpen GrayScale Image using unsharp masking
185
   Blurring_Mask = [1 \ 1 \ 1;
186
                      1 1 1;
187
                      1 1 1];
188
189
   BlurredImageToProduceUnSharpMask =
190
       SpatialFilter2_BlurImage(GrayImage, Blurring_Mask);
   Unsharp\_Mask = GrayImage -
191
       BlurredImageToProduceUnSharpMask;
   SharpenedGrayImage2 = GrayImage + Unsharp_Mask;
192
   %now do it for colored image
   ColoredImageMatrix2 = Image6;
194
   BlurredColoredChannels = Image6;
195
   Unsharp_Mask_Colored = Image6;
196
   BlurredColoredChannels(:,:,1) = SpatialFilter2\_BlurImage(
       Image6(:,:,1), Blurring\_Mask);
   BlurredColoredChannels(:,:,2) = SpatialFilter2_BlurImage(
       Image6(:,:,2), Blurring_Mask);
   BlurredColoredChannels(:,:,3) = SpatialFilter2_BlurImage(
199
       Image6(:,:,3), Blurring_Mask);
   Unsharp_Mask_Colored(:,:,1) = Image6(:,:,1) -
       BlurredColoredChannels(:,:,1);
   Unsharp_Mask_Colored(:,:,2) = Image6(:,:,2) -
       BlurredColoredChannels (:,:,2);
```

```
Unsharp_Mask_Colored(:,:,3) = Image6(:,:,3) -
       BlurredColoredChannels(:,:,3);
   SharpenedColorImage2 = Image6 + Unsharp_Mask_Colored;
203
   imwrite (SharpenedGrayImage2, fullfile (pwd, 'results', '
205
       Point4', 'SharpenedGrayImageUnsharpMasking.jpg'), 'jpg'
   imwrite (SharpenedColorImage2, fullfile (pwd, 'results', '
       Point4', 'SharpenedColoredImageUnsharpMasking.jpg'),
       jpg');
207
   %
208
   %%
209
210
211
212
       5>>>>>>
   %%
214
   %=
215
   %sharpen an image using two masks then sharpen it again
       using a mask made
   %using both of the original masks
217
218
   Mask1 = [0 -1 0;
219
            -1 \ 5 \ -1;
220
            0 -1 0;
221
   Mask2 = [-1 \ 0 \ -1;
222
             0 5 0;
223
            -1 \ 0 \ -1];
224
225
   Mask3 = [0]
               1
                   0
                       1 0:
226
             1 -5 -3 -5 1;
227
             0 -3 25 -3 0;
228
             1 -5 -3 -5 1;
229
                   0 \ 1 \ 0;
               1
231
   SequenceImage_Step1 = Sharpen(GrayImage, Mask1, false);
232
   SequenceImage_Step2 = Sharpen(SequenceImage_Step1, Mask2,
233
        false);
   SequenceImage = SequenceImage_Step2;
   OneMaskImage = Sharpen (GrayImage, Mask3, false);
236
```

References

- [1] Ehsan Khoramshahi. Image Enhancement in Spatial Domain.
- [2] P. K. Sinha. *Gray-Level Transformation*. Tech. rep. Image Acquisition and Pre-processing for Machine Vision Systems, 2012.
- [3] Concept of Blurring. Tech. rep. 2016. URL: https://www.tutorialspoint.com/dip/concept_of_blurring.htm.
- [4] Cyanogen Imaging $^{\mathrm{TM}}$ MaxIm DL. $\mathit{High-Pass\ Filtering}$. Diffraction Limited.