

Project – 2

ENPM 661

Utsav V Patel

UID - 115816756

Instructions to run the code.

- 1) Extract the folder “patel_project2” to any of your folders.
- 2) “patel_project2” contains following files
 - I. Main Code
 - a) code.m
 - II. Pre-defined functions
 - a) Constrains.m
 - b) moveleft.m
 - c) moveright.m
 - d) moveup.m
 - e) movedown.m
 - f) moveupleft.m
 - g) moveupright.m
 - h) movedownleft.m
 - i) movedownright.m
 - III. Information files
 - a) README
 - IV. Output folder which contains following files (Nodes, NodeInfo and Output_plot)
 - a) Output (It has all the generated x and y points and their parent info)
 - b) Output_plot (It has one example plot)
- 3) Open MATLAB
- 4) Locate the folder named “patel_project2” in MATLAB by providing the path of the folder “patel_project2”.
- 5) Now open the source code named code.m.
- 6) When the code.m script is run, it will ask for x and y co-ordinates of start and goal points.
- 7) It will start generating the nodes. The program will terminate when it reaches the goal point. I have ran the code for start point (158, 60) and goal point (188 ,60). Which are stored in “output” file in output folder, the plot is stored in “output_plot” file.
- 8) The information about any of the nodes can be accessed by running NodeInfo(p) code in command window. Here the p shows the node number. It will give [Parent node#,] as output. Any Nodeset can be accessed by typing x(p) and y(p) in command window, where p is the node number.