

# **Practice Set**

Vector Spaces, Subspaces, Independence, and Basis

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## 1 Vector Spaces and Subspaces

### Question 1 (Easy: Subspace Concept)

Let  $V = \mathbb{R}^2$ . Consider the subset  $U = \{(x, y) \in \mathbb{R}^2 \mid y = 2x + 1\}$ . Is  $U$  a subspace of  $V$ ? Justify your answer using the subspace criteria.

**Detailed Solution:**

To be a subspace,  $U$  must satisfy three conditions:

1. Contains the zero vector  $\mathbf{0}$ .
2. Closed under vector addition.
3. Closed under scalar multiplication.

**Step 1: Check for the zero vector.** The zero vector in  $\mathbb{R}^2$  is  $(0, 0)$ . Does  $(0, 0)$  satisfy the condition  $y = 2x + 1$ ? Substitute  $x = 0, y = 0$ :

$$0 = 2(0) + 1 \implies 0 = 1 \quad (\text{False})$$

Since  $\mathbf{0} \notin U$ ,  $U$  is **not** a subspace.

(Note: This represents a line that does not pass through the origin. As mentioned in the lecture, shifted lines are not subspaces).

### Question 2 (Moderate: Matrix Subspace)

Let  $V = M_{2 \times 2}$  be the vector space of all  $2 \times 2$  matrices. Let  $W$  be the set of all symmetric  $2 \times 2$  matrices (where  $A^T = A$ ). Is  $W$  a subspace of  $V$ ?

**Detailed Solution:**

The generic form of a symmetric  $2 \times 2$  matrix is  $A = \begin{pmatrix} a & b \\ b & c \end{pmatrix}$ .

**1. Zero Vector:** The zero matrix  $\mathbf{0} = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$  is symmetric ( $0 = 0$ ). So  $\mathbf{0} \in W$ .

**2. Closure under Addition:** Let  $A = \begin{pmatrix} a & b \\ b & c \end{pmatrix}$  and  $B = \begin{pmatrix} d & e \\ e & f \end{pmatrix}$  be in  $W$ .

$$A + B = \begin{pmatrix} a+d & b+e \\ b+e & c+f \end{pmatrix}$$

The off-diagonal elements are equal ( $b+e = b+e$ ). Thus,  $A + B$  is symmetric.

**3. Closure under Scalar Multiplication:** Let  $k \in \mathbb{R}$ .

$$kA = \begin{pmatrix} ka & kb \\ kb & kc \end{pmatrix}$$

The off-diagonal elements are equal ( $kb = kb$ ). Thus,  $kA$  is symmetric.

**Conclusion:** Since all conditions are met,  $W$  is a subspace of  $M_{2 \times 2}$ .

## 2 Linear Combinations and Span

### Question 3 (Easy: Checking Linear Combination)

Determine if the vector  $b = \begin{pmatrix} 4 \\ 3 \\ 12 \end{pmatrix}$  is a linear combination of vectors  $v_1 = \begin{pmatrix} 1 \\ 0 \\ 2 \end{pmatrix}$  and  $v_2 = \begin{pmatrix} 2 \\ 1 \\ 4 \end{pmatrix}$ .

**Detailed Solution:**

We want to find scalars  $c_1, c_2$  such that  $c_1v_1 + c_2v_2 = b$ . Augmented Matrix:

$$\begin{pmatrix} 1 & 2 & 4 \\ 0 & 1 & 3 \\ 2 & 4 & 12 \end{pmatrix}$$

**Row Reduction:**  $R_3 \rightarrow R_3 - 2R_1$ :

$$\begin{pmatrix} 1 & 2 & 4 \\ 0 & 1 & 3 \\ 0 & 0 & 4 \end{pmatrix}$$

Look at the last row:  $0c_1 + 0c_2 = 4 \implies 0 = 4$ . This is a contradiction. The system is inconsistent.

**Answer:** No,  $b$  is not a linear combination of  $v_1$  and  $v_2$ .

### Question 4 (Moderate: Determining Span Parameter)

For what value of  $k$  is the vector  $v = \begin{pmatrix} 1 \\ -2 \\ k \end{pmatrix}$  in the span of  $\left\{ \begin{pmatrix} 3 \\ 0 \\ 2 \end{pmatrix}, \begin{pmatrix} 2 \\ -1 \\ 5 \end{pmatrix} \right\}$ ?

**Detailed Solution:**

We set up the system  $c_1v_1 + c_2v_2 = v$ :

$$\begin{pmatrix} 3 & 2 & 1 \\ 0 & -1 & -2 \\ 2 & 5 & k \end{pmatrix}$$

**Step 1: Eliminate  $R_3$  using  $R_1$ .** Operation:  $R_3 \rightarrow 3R_3 - 2R_1$ .

$$\begin{pmatrix} 3 & 2 & 1 \\ 0 & -1 & -2 \\ 0 & 15 - 4 & 3k - 2 \end{pmatrix} = \begin{pmatrix} 3 & 2 & 1 \\ 0 & -1 & -2 \\ 0 & 11 & 3k - 2 \end{pmatrix}$$

**Step 2: Eliminate  $R_3$  using  $R_2$ .** Operation:  $R_3 \rightarrow R_3 + 11R_2$ .

$$\begin{pmatrix} 3 & 2 & 1 \\ 0 & -1 & -2 \\ 0 & 0 & (3k - 2) + 11(-2) \end{pmatrix} = \begin{pmatrix} 3 & 2 & 1 \\ 0 & -1 & -2 \\ 0 & 0 & 3k - 24 \end{pmatrix}$$

**Step 3: Condition for Consistency.** For the system to have a solution, the last row must not be a contradiction (like  $0 = 5$ ). Since the coefficient of variables is 0, the constant term must also be 0.

$$3k - 24 = 0 \implies 3k = 24 \implies k = 8$$

**Answer:**  $k = 8$ .

### 3 Linear Independence

#### Question 5 (Easy: Inspection)

Determine by inspection (without calculation) whether the set of vectors is linearly independent:

$$S = \left\{ \begin{pmatrix} 1 \\ 4 \\ 2 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} -1 \\ 5 \\ 3 \end{pmatrix} \right\}$$

**Detailed Solution:**

The set  $S$  contains the zero vector  $\mathbf{0} = (0, 0, 0)^T$ . According to the lecture (Slide 431), **any set containing the zero vector is linearly dependent**. (Reason:  $1 \cdot \mathbf{0} + 0 \cdot v_1 + 0 \cdot v_3 = \mathbf{0}$  is a non-trivial linear combination).

**Answer:** Linearly Dependent.

#### Question 6 (Moderate: Independence in $\mathbb{R}^3$ )

Determine if the following vectors are linearly independent. If dependent, find the dependency relation.

$$v_1 = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}, v_2 = \begin{pmatrix} 4 \\ 5 \\ 6 \end{pmatrix}, v_3 = \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix}$$

**Detailed Solution:**

We solve  $c_1 v_1 + c_2 v_2 + c_3 v_3 = 0$ . Augmented matrix:

$$\begin{pmatrix} 1 & 4 & 2 & 0 \\ 2 & 5 & 1 & 0 \\ 3 & 6 & 0 & 0 \end{pmatrix}$$

**Gaussian Elimination:**  $R_2 \rightarrow R_2 - 2R_1$  and  $R_3 \rightarrow R_3 - 3R_1$ :

$$\begin{pmatrix} 1 & 4 & 2 & 0 \\ 0 & -3 & -3 & 0 \\ 0 & -6 & -6 & 0 \end{pmatrix}$$

$R_3 \rightarrow R_3 - 2R_2$ :

$$\begin{pmatrix} 1 & 4 & 2 & 0 \\ 0 & -3 & -3 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

We have a row of zeros, implying a free variable ( $c_3$ ). Equation from  $R_2$ :  $-3c_2 - 3c_3 = 0 \implies c_2 = -c_3$ . Equation from  $R_1$ :  $c_1 + 4c_2 + 2c_3 = 0 \implies c_1 + 4(-c_3) + 2c_3 = 0 \implies c_1 = 2c_3$ .

Let  $c_3 = 1$ , then  $c_2 = -1$ ,  $c_1 = 2$ . Check:  $2v_1 - 1v_2 + 1v_3 = \begin{pmatrix} 2 \\ 4 \\ 6 \end{pmatrix} - \begin{pmatrix} 4 \\ 5 \\ 6 \end{pmatrix} + \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$ .

**Answer:** Vectors are Linearly Dependent. Relation:  $2v_1 - v_2 + v_3 = 0$ .

#### Question 7 (Tough: Matrix Space Independence)

Are the matrices  $A = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$ ,  $B = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$ , and  $C = \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix}$  linearly independent in  $M_{2 \times 2}$ ?

**Detailed Solution:**

We check  $c_1A + c_2B + c_3C = \mathbf{0}$ .

$$c_1 \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} + c_2 \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} + c_3 \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$$

This yields 4 equations (one per matrix position): 1.  $c_1 + 0 + c_3 = 0 \implies c_1 + c_3 = 0$  2.  $0 + c_2 + c_3 = 0 \implies c_2 + c_3 = 0$  3.  $0 + c_2 + c_3 = 0$  (Same as above) 4.  $0 + 0 + 0 = 0$  (Trivial)

From (1),  $c_1 = -c_3$ . From (2),  $c_2 = -c_3$ . This system has infinitely many solutions (one free variable  $c_3$ ). If we pick  $c_3 = 1$ , then  $c_1 = -1, c_2 = -1$ . Relation:  $-A - B + C = 0 \implies C = A + B$ .

**Answer:** Linearly Dependent.

## 4 Basis and Dimension

### Question 8 (Easy: Dimension Check)

Find the dimension of the subspace of  $\mathbb{R}^3$  spanned by the vectors:

$$v_1 = (1, 0, 0), \quad v_2 = (0, 1, 0), \quad v_3 = (1, 1, 0)$$

**Detailed Solution:**

We need to find the number of linearly independent vectors in this set. We observe that  $v_3 = v_1 + v_2$ . Thus,  $v_3$  is redundant.  $v_1$  and  $v_2$  are clearly independent (one has  $x$  component only, the other  $y$ ). The basis is  $\{v_1, v_2\}$ . The dimension is the count of basis vectors.

**Answer:** Dimension = 2.

### Question 9 (Moderate: Finding a Basis)

Find a basis for the subspace of  $\mathbb{R}^3$  spanned by  $S = \{(1, 1, 2), (2, 2, 4), (2, -1, 5)\}$ .

**Detailed Solution:**

**Step 1: Check for independence.** Notice that  $v_2 = 2 \cdot v_1$ .  $(2, 2, 4) = 2(1, 1, 2)$ . So,  $v_2$  is dependent on  $v_1$  and can be removed without changing the span.

**Step 2: Check remaining vectors.** We are left with  $v_1 = (1, 1, 2)$  and  $v_3 = (2, -1, 5)$ . Are they multiples of each other?  $2/1 = 2$ , but  $-1/1 \neq 2$ . No. They are linearly independent.

**Step 3: Form Basis.** The basis consists of the linearly independent vectors remaining in the set.

**Answer:** Basis =  $\{(1, 1, 2), (2, -1, 5)\}$ .

### Question 10 (Tough: Extending to a Basis)

The vector space  $V = M_{2 \times 2}$  has dimension 4. The set  $S = \left\{ \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \right\}$  is a linearly independent subset of  $V$ . Add two matrices to  $S$  to form a basis for  $V$ .

**Detailed Solution:**

The standard basis for  $M_{2 \times 2}$  is:

$$E_{11} = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, E_{12} = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, E_{21} = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}, E_{22} = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$$

The set  $S$  already contains  $E_{11}$  and  $E_{22}$ . To span the entire space  $M_{2 \times 2}$ , we need to be able to generate entries in the top-right ( $a_{12}$ ) and bottom-left ( $a_{21}$ ) positions. Currently, any linear combination of  $S$  looks like  $\begin{pmatrix} a & 0 \\ 0 & d \end{pmatrix}$ . We simply add the missing standard basis vectors.

**Answer:** Add  $\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$  and  $\begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}$ .