Expectation-Maximization (EM)

Expectation-Maximization (EM) algorithm. Let X be a random variable distributed according to $p_X(x)$ and Y be a random variable distributed according to $p_Y(y)$. Let $\mathbf{D}_X = \{x_i\}_{i=1}^m$ be an i.i.d~sample from $p_X(x)$ and $\mathbf{D}_Y = \{y_i\}_{i=1}^n$ be an i.i.d.~sample from $p_Y(y)$. Finally, let $p_X(x)$ and $p_Y(y)$ be defined as follows

$$p_X(x) = \alpha N(\mu_1, \sigma_1^2) + (1 - \alpha) N(\mu_2, \sigma_2^2)$$

and

$$p_Y(y) = \beta N(\mu_1, \sigma_1^2) + (1 - \beta)N(\mu_2, \sigma_2^2),$$

where $N(\mu, \sigma^2)$ is a univariate Gaussian distribution with mean μ and variance σ^2 , $\alpha \in (0,1)$, $\beta \in (0,1)$, $\mu_1 \in \mathbb{R}$, $\mu_2 \in \mathbb{R}$, $\sigma_1 \in \mathbb{R}^+$ and $\sigma_2 \in \mathbb{R}^+$ are unknown parameters.

a) Derive update rules of the EM algorithm for estimating β , μ_1 , μ_2 , σ_1 , and σ_2 based only on data set D_Y .

Ans:

To solve this problem in more general way, now set

- 1. Y as observed variable: $Y|Z=C_k \sim \mathrm{N}(Y|\mu_k,\sigma_k^2)$
- 2. Z as latent variable: $\sum_{k=1}^{K} p_k = 1$

3. heta as parameters: $heta=\{p_1\dots p_k,\mu_1\dots \mu_k,\sigma_1\dots\sigma_k\}$

A. E-step:

$$Q(\theta, \theta^{(t)}) = E[logP(Y, Z|\theta)|Y, \theta^{(t)}]$$

Before calculating Q, first find several distributions:

$$P(Y|\theta) = \sum_{k=1}^{K} p_k N(Y|\mu_k, \sigma_k^2)$$

$$P(Y, Z|\theta) = P(Z|\theta)P(Y|Z, \theta)$$
$$= p_Z N(Y|\mu_Z, \sigma_Z^2)$$

$$\begin{split} P(Z|Y, \theta^{(t)}) &= \frac{P(Y, Z|\theta^{(t)})}{P(Y|\theta^{(t)})} \\ &= \frac{p_Z^{(t)} \mathcal{N}(Y|\mu_Z^{(t)}, \sigma_Z^{2(t)})}{\sum_{k=1}^K p_k^{(t)} \mathcal{N}(Y|\mu_k^{(t)}, \sigma_k^{2(t)})} \end{split}$$

Now the expectation is:

$$\begin{split} Q(\theta, \theta^{(t)}) &= E[log P(Y, Z|\theta)|Y, \theta^{(t)}] \\ &= \sum_{Z} \log \prod_{i=1}^{n} p(y_{i}, z_{i}|\theta) \prod_{i=1}^{n} p(z_{i}|y_{i}, \theta^{(t)}) \\ &= \sum_{Z} [\sum_{i=1}^{n} \log p(y_{i}, z_{i}|\theta)] \prod_{i=1}^{n} p(z_{i}|y_{i}, \theta^{(t)}) \\ &= \sum_{i=1}^{n} \sum_{z_{i}} \log(p(y_{i}, z_{i}|\theta)) p(z_{i}|y_{i}, \theta^{(t)}) \\ &= \sum_{i=1}^{n} \sum_{z_{i}} \log(p_{z_{i}} N(y_{i}|\mu_{z_{i}}, \sigma_{z_{i}}^{2})) p(z_{i}|y_{i}, \theta^{(t)}) \\ &= \sum_{k=1}^{K} \sum_{i=1}^{n} [\log(p_{k}) p(k|y_{i}, \theta^{(t)}) + \log(N(y_{i}|\mu_{k}, \sigma_{k}^{2}))] p(k|y_{i}, \theta^{(t)}) \end{split}$$

where

$$p(z_i|y_i, heta^{(t)}) = rac{p_{z_i}^{(t)} \mathrm{N}(y_i|\mu_{z_i}^{(t)}, \sigma_{z_i}^{2(t)})}{\sum_{k=1}^K p_k^{(t)} \mathrm{N}(y_i|\mu_k^{(t)}, \sigma_k^{2(t)})} \ p(z_i = k|y_i, heta^{(t)}) = rac{p_k^{(t)} \mathrm{N}(y_i|\mu_k^{(t)}, \sigma_k^{2(t)})}{\sum_{k=1}^K p_k^{(t)} \mathrm{N}(y_i|\mu_k^{(t)}, \sigma_k^{2(t)})}$$

B. M-step

1. To maximize $Q(\theta, \theta^{(t)})$ with respect to p, we observe that this is an instance of constrained optimization because it must hold that $\sum_{k=1}^K p_k = 1$ and $p_k \geq 0$. We will use the method of Lagrange multipliers:

$$L(p, \lambda) = \sum_{k=1}^{K} \sum_{i=1}^{n} \log(p_k) p(k|y_i, \theta^{(t)}) + \lambda(\sum_{k=1}^{K} p_k - 1)$$

$$\frac{\partial L(p,\lambda)}{\partial p_k} = \frac{\sum_{i=1}^n p(k|y_i,\theta^{(t)})}{p_k} + \lambda = 0$$

$$\sum_{i=1}^n p(k|y_i,\theta^{(t)}) + p_k\lambda = 0$$

$$\sum_{i=1}^n \underbrace{\sum_{k=1}^K p(k|y_i,\theta^{(t)})}_{1} + \underbrace{\sum_{k=1}^K p_k}_{1}\lambda = 0$$

$$\sum_{i=1}^n 1 + \lambda = 0$$

$$\lambda = -n$$

So that

$$p_k^{(t+1)} = rac{\sum_{i=1}^n p(k|y_i, heta^{(t)})}{n}$$

In this question, $p_1 = \beta$, so

$$\beta^{(t+1)} = \frac{\sum_{i=1}^{n} p(z_i = 1 | y_i, \theta^{(t)})}{n}$$

2. To maximize $Q(\theta, \theta^{(t)})$ with respect to μ :

$$\begin{split} L(\mu) &= \sum_{k=1}^{K} \sum_{i=1}^{n} [\log(\mathrm{N}(y_{i}|\mu_{k}, \sigma_{k}^{2})) p(k|y_{i}, \theta^{(t)})] \\ &= \sum_{k=1}^{K} \sum_{i=1}^{n} -[\frac{(y_{i} - \mu_{k})^{2}}{2\sigma_{k}^{2}} p(k|y_{i}, \theta^{(t)})] \end{split}$$

$$\frac{\partial L(\mu)}{\partial \mu_k} = \frac{1}{\sigma_k^2} \sum_{i=1}^n [(y_i - \mu_k) p(k|y_i, \theta^{(t)})] = 0$$

$$\mu_k^{(t+1)} = \frac{\sum_{i=1}^n y_i p(k|y_i, \theta^{(t)})}{\sum_{i=1}^n p(k|y_i, \theta^{(t)})}$$

In this question:

$$\mu_1^{(t+1)} = rac{\sum_{i=1}^n y_i p(z_i = 1 | y_i, heta^{(t)})}{\sum_{i=1}^n p(z_i = 1 | y_i, heta^{(t)})}
onumber \ \mu_2^{(t+1)} = rac{\sum_{i=1}^n y_i p(z_i = 2 | y_i, heta^{(t)})}{\sum_{i=1}^n p(z_i = 2 | y_i, heta^{(t)})}$$

3. To maximize $Q(\theta, \theta^{(t)})$ with respect to σ :

$$\begin{split} L(\sigma) &= \sum_{k=1}^{K} \sum_{i=1}^{n} [\log(\mathrm{N}(y_{i}|\mu_{k}, \sigma_{k}^{2})) p(k|y_{i}, \theta^{(t)})] \\ &= \sum_{k=1}^{K} \sum_{i=1}^{n} -[\frac{(y_{i} - \mu_{k})^{2}}{2\sigma_{k}^{2}} p(k|y_{i}, \theta^{(t)}) + \frac{1}{2} \log(2\pi\sigma_{k}^{2}) p(k|y_{i}, \theta^{(t)})] \end{split}$$

$$\frac{\partial L(\sigma)}{\partial \sigma_k^2} = \sum_{i=1}^n \{ [(y_i - \mu_k)^2 \sigma_k^{2-2} - \sigma_k^{2-1}] p(k|y_i, \theta^{(t)}) \} = 0$$

$$\sigma_k^{2(t+1)} = \frac{\sum_{i=1}^n [(y_i - \mu_k)^2 p(k|y_i, \theta^{(t)})]}{\sum_{i=1}^n p(k|y_i, \theta^{(t)})}$$

In this question:

$$\sigma_1^{2(t+1)} = rac{\sum_{i=1}^n [(y_i - \mu_1)^2 p(z_i = 1 | y_i, heta^{(t)})]}{\sum_{i=1}^n p(z_i = 1 | y_i, heta^{(t)})} \ \sigma_2^{2(t+1)} = rac{\sum_{i=1}^n [(y_i - \mu_2)^2 p(z_i = 2 | y_i, heta^{(t)})]}{\sum_{i=1}^n p(z_i = 2 | y_i, heta^{(t)})}$$

b) Derive update rules of an EM algorithm for estimating $\alpha, \beta, \mu_1, \mu_2, \sigma_1$, and σ_2 based on data sets D_X and D_Y .

Ans:

A. E-step:

$$Q(\theta, \theta^{(t)}) = E[logP(X, Z|\theta)|X, \theta^{(t)}] + E[logP(Y, Z|\theta)|Y, \theta^{(t)}]$$

Now the expectation is:

$$\begin{split} Q(\theta, \theta^{(t)}) &= E[log P(X, Z|\theta)|X, \theta^{(t)}] + E[log P(Y, Z|\theta)|Y, \theta^{(t)}] \\ &= \sum_{k=1}^{K} \sum_{i=1}^{m} [\log(\alpha_k) p(k|x_i, \theta^{(t)}) + \log(\mathrm{N}(x_i|\mu_k, \sigma_k^2)) p(k|x_i, \theta^{(t)})] + \\ &\sum_{k=1}^{K} \sum_{j=1}^{n} [\log(\beta_k) p(k|y_j, \theta^{(t)}) + \log(\mathrm{N}(y_j|\mu_k, \sigma_k^2)) p(k|y_j, \theta^{(t)})] \end{split}$$

where

$$p(z_{i} = k | x_{i}, \theta^{(t)}) = \frac{\alpha_{k}^{(t)} N(x_{i} | \mu_{k}^{(t)}, \sigma_{k}^{2(t)})}{\sum_{k=1}^{K} \alpha_{k}^{(t)} N(x_{i} | \mu_{k}^{(t)}, \sigma_{k}^{2(t)})}$$

$$p(z_{i} = k | y_{j}, \theta^{(t)}) = \frac{\beta_{k}^{(t)} N(y_{j} | \mu_{k}^{(t)}, \sigma_{k}^{2(t)})}{\sum_{k=1}^{K} \beta_{k}^{(t)} N(y_{j} | \mu_{k}^{(t)}, \sigma_{k}^{2(t)})}$$

$$\sum_{k=1}^{K} \alpha_{k} = 1$$

$$\sum_{k=1}^{K} \beta_{k} = 1$$

B. M-step

1. To maximize $Q(heta, heta^{(t)})$ with respect to lpha and eta. We will use the method of Lagrange multipliers:

$$lpha^{(t+1)} = rac{\sum_{i=1}^{m} p(z_i = 1 | x_i, heta^{(t)})}{m} \ eta^{(t+1)} = rac{\sum_{j=1}^{n} p(z_j = 1 | y_j, heta^{(t)})}{n}$$

2. To maximize $Q(heta, heta^{(t)})$ with respect to μ :

$$\begin{split} L(\mu) &= \sum_{k=1}^K \sum_{i=1}^m [\log(\mathrm{N}(x_i|\mu_k, \sigma_k^2)) p(k|x_i, \theta^{(t)})] + \sum_{k=1}^K \sum_{j=1}^n [\log(\mathrm{N}(y_j|\mu_k, \sigma_k^2)) p(k|y_j, \theta^{(t)})] \\ &= \sum_{k=1}^K \sum_{i=1}^m -[\frac{(x_i - \mu_k)^2}{2\sigma_k^2} p(k|x_i, \theta^{(t)})] + \sum_{k=1}^K \sum_{j=1}^n -[\frac{(y_j - \mu_k)^2}{2\sigma_k^2} p(k|y_j, \theta^{(t)})] \end{split}$$

$$\frac{\partial L(\mu)}{\partial \mu_k} = \frac{1}{\sigma_k^2} \sum_{i=1}^m [(x_i - \mu_k) p(k|x_i, \theta^{(t)})] + \frac{1}{\sigma_k^2} \sum_{j=1}^n [(y_j - \mu_k) p(k|y_j, \theta^{(t)})] = 0$$

$$\mu_k^{(t+1)} = \frac{\sum_{i=1}^m x_i p(k|x_i, \theta^{(t)}) + \sum_{j=1}^n y_j p(k|y_j, \theta^{(t)})}{\sum_{i=1}^m p(k|x_i, \theta^{(t)}) + \sum_{i=1}^n p(k|y_i, \theta^{(t)})}$$

In this question:

$$\mu_1^{(t+1)} = \frac{\sum_{i=1}^m x_i p(z_i = 1 | x_i, \theta^{(t)}) + \sum_{j=1}^n y_j p(z_i = 1 | y_j, \theta^{(t)})}{\sum_{i=1}^m p(z_i = 1 | x_i, \theta^{(t)}) + \sum_{j=1}^n p(z_i = 1 | y_j, \theta^{(t)})}$$

$$\mu_2^{(t+1)} = \frac{\sum_{i=1}^m x_i p(z_i = 2 | x_i, \theta^{(t)}) + \sum_{j=1}^n y_j p(z_i = 2 | y_j, \theta^{(t)})}{\sum_{i=1}^m p(z_i = 2 | x_i, \theta^{(t)}) + \sum_{j=1}^n p(z_i = 2 | y_j, \theta^{(t)})}$$

3. To maximize $Q(\theta, \theta^{(t)})$ with respect to σ :

$$\begin{split} L(\sigma) &= \sum_{k=1}^K \sum_{i=1}^m [\log(\mathrm{N}(x_i|\mu_k, \sigma_k^2)) p(k|x_i, \theta^{(t)})] + \sum_{k=1}^K \sum_{j=1}^n [\log(\mathrm{N}(y_j|\mu_k, \sigma_k^2)) p(k|y_j, \theta^{(t)})] \\ &= \sum_{k=1}^K \sum_{i=1}^m -[\frac{(x_i - \mu_k)^2}{2\sigma_k^2} p(k|x_i, \theta^{(t)}) + \frac{1}{2} \log(2\pi\sigma_k^2) p(k|x_i, \theta^{(t)})] + \\ &\sum_{k=1}^K \sum_{i=1}^n -[\frac{(y_j - \mu_k)^2}{2\sigma_k^2} p(k|y_j, \theta^{(t)}) + \frac{1}{2} \log(2\pi\sigma_k^2) p(k|y_j, \theta^{(t)})] \end{split}$$

$$\frac{\partial L(\sigma)}{\partial \sigma_k^2} = \sum_{i=1}^m \{ [(x_i - \mu_k)^2 \sigma_k^{2^{-2}} - \sigma_k^{2^{-1}}] p(k|x_i, \theta^{(t)}) \} + \sum_{i=1}^n \{ [(y_j - \mu_k)^2 \sigma_k^{2^{-2}} - \sigma_k^{2^{-1}}] p(k|y_j, \theta^{(t)}) \} = 0$$

$$\sigma_k^{2(t+1)} = \frac{\sum_{i=1}^n [(x_i - \mu_k)^2 p(k|x_i, \theta^{(t)})] + \sum_{j=1}^n [(y_j - \mu_k)^2 p(k|y_j, \theta^{(t)})]}{\sum_{i=1}^m p(k|x_i, \theta^{(t)}) + \sum_{j=1}^n p(k|y_j, \theta^{(t)})}$$

In this question:

$$\begin{split} \sigma_1^{2(t+1)} &= \frac{\sum_{i=1}^n [(x_i - \mu_k)^2 p(z_i = 1 | x_i, \theta^{(t)})] + \sum_{j=1}^n [(y_j - \mu_k)^2 p(z_j = 1 | y_j, \theta^{(t)})]}{\sum_{i=1}^m p(z_i = 1 | x_i, \theta^{(t)}) + \sum_{j=1}^n p(z_j = 1 | y_j, \theta^{(t)})} \\ \sigma_2^{2(t+1)} &= \frac{\sum_{i=1}^n [(x_i - \mu_k)^2 p(z_i = 2 | x_i, \theta^{(t)})] + \sum_{j=1}^n [(y_j - \mu_k)^2 p(z_j = 2 | y_j, \theta^{(t)})]}{\sum_{i=1}^m p(z_i = 2 | x_i, \theta^{(t)}) + \sum_{j=1}^n p(z_j = 2 | y_j, \theta^{(t)})} \end{split}$$

c) Implement both learning algorithms from above and evaluate them on simulated data when m, n = 100 and m, n = 1000. However, in each case repeat the experiment at least B = 100 times to estimate the expectation and variance of all parameters. To do so, repeatedly draw samples D_X and D_Y and then estimate the parameters based on these samples. Finally, average those B estimates and calculate their mean and variance. Document all experiments and discuss your findings.

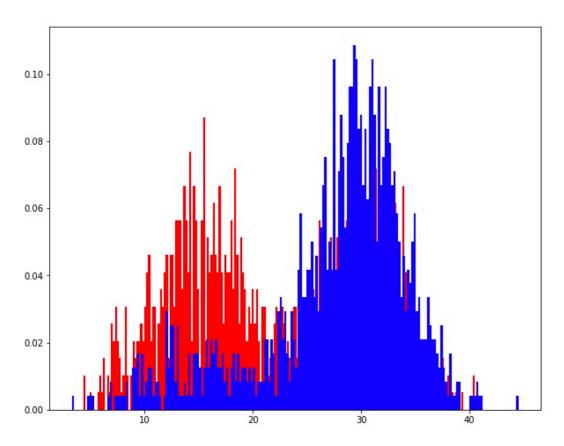
In my experience, the maximum iteration times is 300, and the tolerance level is 10^-9 . The stopping criteria are either reaching the max_iter or the sum of absolute difference between time t parameters and time t-1 parameters is less than tolerance level.

Experiment 1

$$m, n = 1000, 1000$$

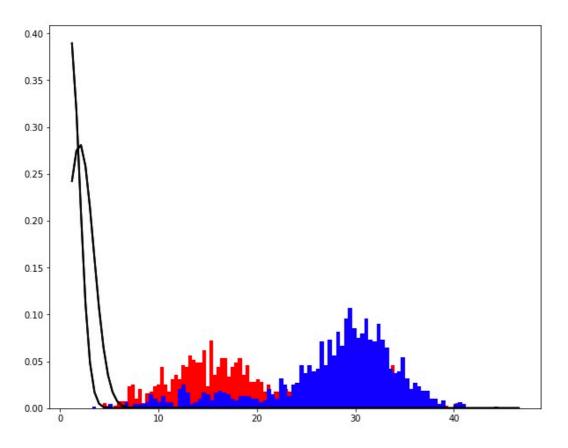
1.Generate Data

$$\alpha=0.6, \beta=0.2, \mu_1=15, \mu_2=30, \sigma_1^2=20, \sigma_2^2=15$$



2. Randomly initialize parameters

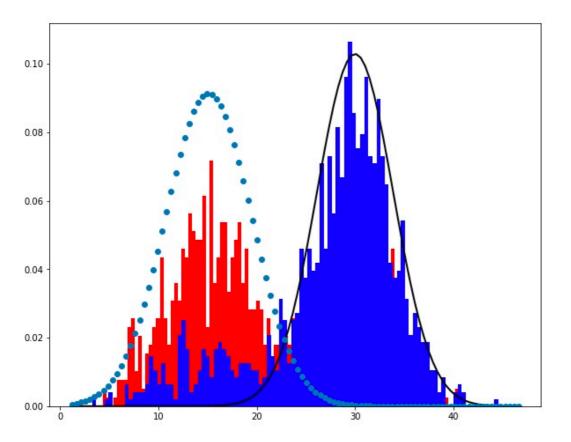
```
# Initialize alpha
Z_x = sorted([random.random(), 1-random.random()])
# Initialize beta
Z_y = sorted([random.random(), 1-random.random()])
# Initialize mu1 and mu2
means = [random.randint(1,30),random.randint(1,20)]
# Initialize sigma_square_1 and sigma_quare_2
S = [random.randint(1,30),random.randint(1,20)]
```



3. Iteratively find the optimal solution

```
for i in range(300):
   # Time t patameters
    Z_x_old = Z_x
   Z_y_old = Z_y
   means_old = means
    S_old = S
    # Updating
    gamma_x = update_gamma(data[0], means, S, Z_x)
    gamma_y = update_gamma(data[1], means, S, Z_y)
   Z_x = update_Z(gamma_x, data[0])
   Z_y = update_Z(gamma_y, data[1])
   means = update_mu(gamma_x, gamma_y, data)
    S = update_sigma(gamma_x, gamma_y, data, means)
    # Difference
    diff = np.nansum(abs(Z_x - Z_x_old)) + np.nansum(abs(Z_y - Z_y_old)) + np.nansum(abs(means - m))
eans_old)) + np.nansum(abs(S - S_old))
    # Stop criteria
    if diff <= eps and diff != 0:</pre>
        print('Early stopping at step {}, the diff is {}'.format(i+1, diff))
        break
```

Stop criteria are either imposing the maximum number of steps or when the difference of parameter at time t and t-1 is less than tolerance level.



4. Repeat the process for 100 times.

5.Evaluation

Evaluate lpha and eta

```
alpha = np.array(alphas)
beta = np.array(betas)

print('For the alpha: the true alpha = {}, mean = {}, variance = {}'.format(true_Z[0][0],np.nanmea
n(alpha), np.nanvar(alpha)))
print('For the beta: the true beta = {}, mean = {}, variance = {}'.format(true_Z[1][0],np.nanmean(
beta), np.nanvar(beta)))
```

For the alpha: the true alpha = 0.6, mean = 0.4988789381326482, variance = 0.0031406915499869476 For the beta: the true beta = 0.2, mean = 0.5066957332497739, variance = 0.1120372803102257

alphas[:10]

```
[0.5560530847590975,
0.44394691505850353,
0.4439469150990536,
0.5560530847083869,
0.5560530847370649,
0.5560530847396205,
0.4439469150344747,
0.5560530847367745,
0.4439469151592899]
```

```
[0.16521333176410535,
0.8347866681141207,
0.834786668141192,
0.16521333173025024,
0.1652133317511012,
0.16521333179486483,
0.8347866680980788,
0.16521333174920158,
0.8347866681814087]
```

Evaluate μ

betas[:10]

```
print('The true mean is {}'.format(true_means))
means = np.array(means_s)
print('For the first Gaussian distribution: mean = {}, variance = {}'.format(np.nanmean(means[:,0]
), np.nanvar(means[:,0])))
\#Z_i = 2
print('For the second Gaussian distribution: mean = {}, variance = {}'.format(np.nanmean(means[:,1
]), np.nanvar(means[:,1])))
The true mean is [15 30]
For the first Gaussian distribution: mean = 22.693785276494314, variance = 55.4044335440785
For the second Gaussian distribution: mean = 22.39598909508589, variance = 55.40443347492932
means_s[:10]
[array([15.09998261, 29.98979176]),
array([29.98979176, 15.09998261]),
array([29.98979176, 15.09998261]),
array([15.09998261, 29.98979176]),
array([15.09998261, 29.98979176]),
array([15.09998261, 29.98979176]),
 array([15.09998261, 29.98979176]),
```

Evalute Variance σ^2

array([29.98979176, 15.09998261]),
array([15.09998261, 29.98979176]),
array([29.98979176, 15.09998261])]

```
print('The true variance is {}'.format(true_S))
S = np.array(Ss)
#Z_i = 1
print('For the first Gaussian distribution: mean = {}, variance = {}'.format(np.nanmean(S[:,0]), n
p.nanvar(S[:,0])))
#Z_i = 2
print('For the second Gaussian distribution: mean = {}, variance = {}'.format(np.nanmean(S[:,1]),
np.nanvar(S[:,1])))
```

```
The true variance is [20 15]
For the first Gaussian distribution: mean = 17.0249963192281, variance = 4.139967455160417
For the second Gaussian distribution: mean = 17.106400270837593, variance = 4.1399675024860265
```

Ss[:10]

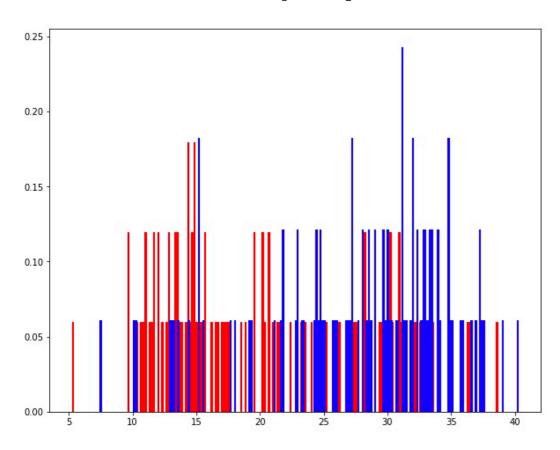
```
[array([19.10079634, 15.03060024]),
array([15.03060023, 19.10079636]),
array([15.03060023, 19.10079636]),
array([19.10079633, 15.03060024]),
array([19.10079634, 15.03060024]),
array([19.10079634, 15.03060024]),
array([19.10079634, 15.03060024]),
array([15.03060023, 19.10079636]),
array([19.10079634, 15.03060024]),
array([15.03060024, 19.10079635])]
```

Experiment 2

m, n = 100, 100

1.Generate Data

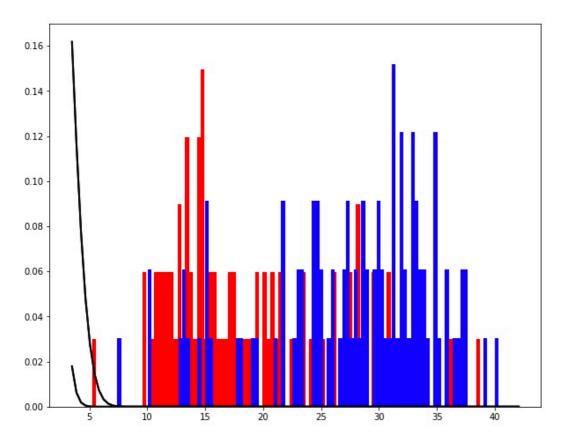
$$\alpha=0.6, \beta=0.2, \mu_1=15, \mu_2=30, \sigma_1^2=20, \sigma_2^2=15$$



2.Randomly initialize parameters

```
# Initialize alpha
Z_x = sorted([random.random(), 1-random.random()])
```

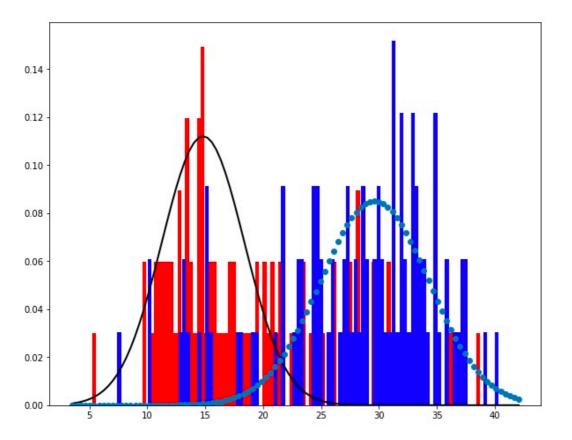
```
# Initialize beta
Z_y = sorted([random.random(), 1-random.random()])
# Initialize mu1 and mu2
means = [random.randint(1,30),random.randint(1,20)]
# Initialize sigma_square_1 and sigma_quare_2
S = [random.randint(1,30),random.randint(1,20)]
```



3. Iteratively find the optimal solution

```
for i in range(300):
   # Time t patameters
    Z_x_old = Z_x
    Z_y_old = Z_y
   means_old = means
    S_old = S
    # Updating
    gamma_x = update_gamma(data[0], means, S, Z_x)
    gamma_y = update_gamma(data[1], means, S, Z_y)
    Z_x = update_Z(gamma_x, data[0])
   Z_y = update_Z(gamma_y, data[1])
   means = update_mu(gamma_x, gamma_y, data)
    S = update_sigma(gamma_x, gamma_y, data, means)
    # Difference
    diff = np.nansum(abs(Z_x - Z_x_old)) + np.nansum(abs(Z_y - Z_y_old)) + np.nansum(abs(means - m))
eans_old)) + np.nansum(abs(S - S_old))
    # Stop criteria
   if diff <= eps and diff != 0:</pre>
        print('Early stopping at step {}, the diff is {}'.format(i+1, diff))
        break
```

Stop criteria are either imposing the maximum number of steps or when the difference of parameter at time t and t-1 is less than tolerance level.



4. Repeat the process for 100 times.

5.Evaluation

Evaluate lpha and eta

```
alpha = np.array(alphas)
beta = np.array(betas)

print('For the alpha: the true alpha = {}, mean = {}, variance = {}'.format(true_Z[0][0],np.nanmea
n(alpha), np.nanvar(alpha)))
print('For the beta: the true beta = {}, mean = {}, variance = {}'.format(true_Z[1][0],np.nanmean(
beta), np.nanvar(beta)))
```

For the alpha: the true alpha = 0.6, mean = 0.49111817912187017, variance = 0.005399169464344099 For the beta: the true beta = 0.2, mean = 0.5415401478080739, variance = 0.11810709036944107

alphas[:10]

0.4259861644026992]

```
[0.4259859546766435,

0.4259861564413597,

0.5740137163435277,

0.42598618959638784,

0.5740136991027822,

0.5740137049723929,

0.4259860550050301,

0.5740137032514985,

0.42598623279560804,
```

Evaluate μ

```
print('The true mean is {}'.format(true_means))
means = np.array(means_s)
#Z_i = 1
print('For the first Gaussian distribution: mean = {}, variance = {}'.format(np.nanmean(means[:,0]), np.nanvar(means[:,0])))
#Z_i = 2
print('For the second Gaussian distribution: mean = {}, variance = {}'.format(np.nanmean(means[:,1]), np.nanvar(means[:,1])))
```

The true mean is [15 30]

For the first Gaussian distribution: mean = 23.10218596083503, variance = 53.952352738894575For the second Gaussian distribution: mean = 21.326501219508685, variance = 53.95229965515634

```
means_s[:10]

[array([29.61303356, 14.8156572]),
    array([29.61303152, 14.81565453]),
    array([14.81565285, 29.61303023]),
    array([29.61303118, 14.8156541]),
    array([14.81565263, 29.61303006]),
    array([14.8156527, 29.61303012]),
    array([29.61303254, 14.81565588]),
    array([14.81565268, 29.6130301]),
    array([29.61303075, 14.81565353]),
    array([29.61303144, 14.81565443])]
```

Evalute Variance σ^2

```
print('The true variance is {}'.format(true_S))
S = np.array(Ss)
#Z_i = 1
print('For the first Gaussian distribution: mean = {}, variance = {}'.format(np.nanmean(S[:,0]), n
p.nanvar(S[:,0])))
#Z_i = 2
print('For the second Gaussian distribution: mean = {}, variance = {}'.format(np.nanmean(S[:,1]),
np.nanvar(S[:,1])))
```

The true variance is [20 15]

For the first Gaussian distribution: mean = 17.904541719480065, variance = 21.468705079403673For the second Gaussian distribution: mean = 16.784445432277, variance = 21.46869904786287

Ss[:10]

```
[array([22.01164038, 12.67734742]),
array([22.01165401, 12.6773294]),
array([12.67732381, 22.0116626]),
array([22.01165625, 12.67733056]),
array([12.67732257, 22.01166377]),
array([12.67732299, 22.01166337]),
array([22.01164716, 12.67734022]),
array([12.67732287, 22.01166349]),
array([22.01165917, 12.67732746]),
array([22.01165455, 12.67733237])]
```

The results shows that, when we have more data, the performance would be much better, and also the variance would be lower. For example, the variance of σ^2 is around 21 when sample size is 100, while around 4 when sample size is 1000.

But in this question, more interesting things happened:

For example, the original parameters are $\alpha=0.6, \beta=0.2, \mu_1=15, \mu_2=30, \sigma_1^2=20, \sigma_2^2=15$. One set of results from experiment is $\alpha=0.56, \beta=0.17, \mu_1=15.1, \mu_2=30.0, \sigma_1^2=19.1, \sigma_2^2=15.0$, another one is $\alpha=0.44, \beta=0.83, \mu_1=29.9, \mu_2=15.1, \sigma_1^2=15.0, \sigma_2^2=19.1$.

This shows that the algorithm does find the optimal solution, but may not as the same order as our initiative. Since in the question, there are only 2 distributions so that 2 groups of parameters. Parameters will switch because the algorithm can not determine the order of these parameters.

So the mean of α is 0.5, the average number of α and $1-\alpha$, so does β .

The mean of μ equals to the average number of μ_1 and μ_2 , so does σ_2 .