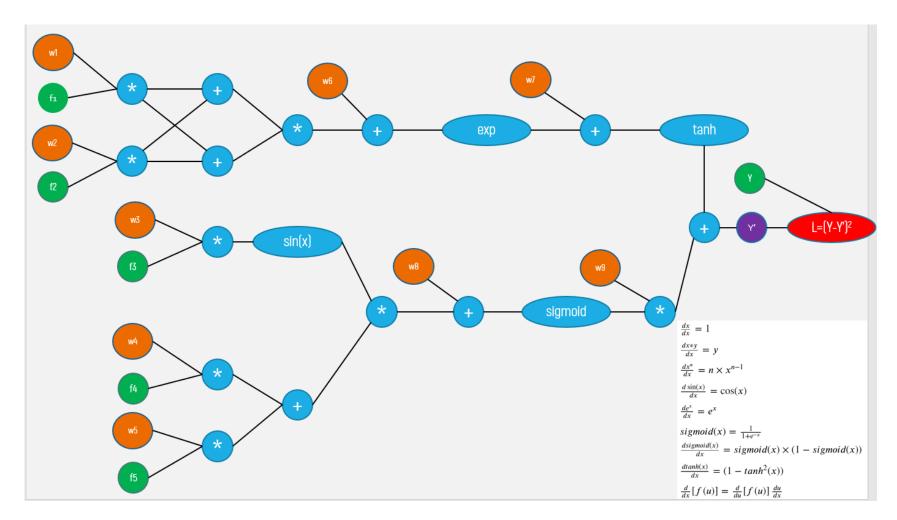
The Neural Network ,That i'll implement is Shown Bellow in Image



What It Need's To Implement a Neural Network.

• Implemnting A Neural Network Mailny Consists 3 Parts :::

- 1. Implement ForWard Propagation.
- 2. Implemnt BackWord Propagation.
- 3. Implement The Optimizers For Your Neural Network. Here We will Implement 3 types of Optimizers.
 - * Gradient Descent
 - * Gradient Descent With Momentum
 - * Adam Optimizer

Let's Load the Data First:

```
In []: ▶ import pickle
            import numpy as np
            from tqdm.notebook import tqdm
            import matplotlib.pyplot as plt
            import pandas as pd
            with open('data.pkl', 'rb') as f:
                data = pickle.load(f)
            print(data.shape)
            X = data[:, :5]
            y = data[:, -1]
            print(X.shape, y.shape)
```

Part-1: Forward propagation

```
    def sigmoid(z):

In [22]:
                  return 1 / (1+ np.exp(-z))
```

```
In [23]: \bigvee def forward propagation(x,y,w):
                 a = w[0]*x[0]
                 b = w[1]*x[1]
                 c = a+b
                 d = a+b
                 e = c*d
                 f = w[5] + e
                 exp = np.exp(f)
                 g = exp + w[6]
                 tanh = np.tanh(g)
                 h = np.sin((w[2]*x[2]))
                 i = (w[3]*x[3]) + (w[4]*x[4])
                 j = h*i
                 k = (w[7]+j)
                 sigh = sigmoid(k)
                 # y^ computation
                 1 = w[8]*sigh
                 y_hat = tanh + 1
                 # Computing loss
                 loss = (y_hat - y)**2
                 # compute derivative of L w.r.to Y' and storing it in dl
                 dl = 2*(y_hat - y)
                 # Creating dictionary
                 dict_ = {"dl": dl , "loss":loss , "exp":exp , "tanh":tanh , "sigmoid":sigh}
                 return dict
```

Part-2: Backward Propagation

```
In [26]:

    def backward propagation(x, W, dict ):

                                                                                                    dw9 = ((dict .get("dl"))*dict .get("sigmoid")*1)
                                                                                                    dw8 = ((dict_.get("dl"))*(w[8])*(dict_.get("sigmoid")*(1-(dict_.get("sigmoid")))))
                                                                                                    dw7 = ((dict_.get("dl"))*(1-(dict_.get("tanh")**2)))
                                                                                                    dw6 = ((dict_.get("dl"))*(1-(dict_.get("tanh")**2)))*(dict_.get("exp"))
                                                                                                    dw5 = ((dw8)*(np.sin((w[2]*x[2])))*(x[4]))
                                                                                                    dw4 = ((dw8)*(np.sin((w[2]*x[2])))*(x[3]))
                                                                                                    dw3 = ((dw8)*((x[3]*w[3])+(x[4]*w[4]))*(np.cos((w[2]*x[2])))*(x[2]))
                                                                                                    dw2 = ((dict_.get("dl")*(1-((dict_.get("tanh"))**2))*(dict_.get("exp"))*(2*((w[0]*x[0])+(w[1]*x[1])))*(x)
                                                                                                    dw1 = ((dict .get("dl")*(1-((dict .get("tanh"))**2))*(dict .get("exp"))*(2*((w[0]*x[0])+(w[1]*x[1])))*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[0])*(x[
                                                                                                    dervt \ dict = \{ "dw1": dw1 , "dw2": dw2, "dw3": dw3, "dw4": dw4, "dw5": dw5 , dw5": dw5
                                                                                                                                                                                                              "dw6":dw6 , "dw7":dw7 , "dw8":dw8 , "dw9":dw9 }
                                                                                                    return dervt dict
```

Part-3: Implementing Diffrent Deep Learning Optimizers.

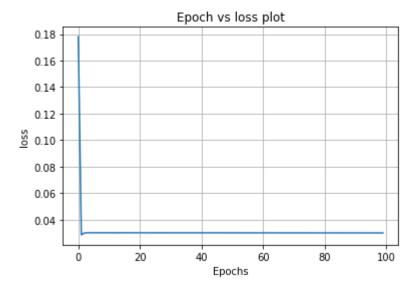
1. Gradient Decent.

```
I from tadm import tadm
In [31]:
             learning rate = 0.01
             W = np.random.normal(loc=0.0, scale=0.1, size=9)
             epochs = list(i for i in range(100))
             epoch losses = []
             for epoch in tqdm(epochs):
                 loss = 0
                 for data point index in range(len(X)):
                     dict1 = forward propagation(X[data point index],y[data point index],W)
                     dws dict = backward propagation(X[data point index],W,dict1)
                     old weights derivatives = [dws dict.get(i) for i in dws dict]
                     # getting loss with current weights
                     loss = loss + (dict1.get("loss"))
                     # updating weights
                     w1 = ((W[0]) - (learning rate*(old weights derivatives[0])))
                     w2 = ((W[1]) - (learning rate*(old weights derivatives[1])))
                     w3 = ((W[2]) - (learning rate*(old weights derivatives[2])))
                     w4 = ((W[3]) - (learning rate*(old weights derivatives[3])))
                     w5 = ((W[4]) - (learning rate*(old weights derivatives[4])))
                     w6 = ((W[5]) - (learning rate*(old weights derivatives[5])))
                     w7 = ((W[6]) - (learning rate*(old weights derivatives[6])))
                     w8 = ((W[7]) - (learning rate*(old weights derivatives[7])))
                     w9 = ((W[8]) - (learning rate*(old weights derivatives[8])))
                     W = [w1, w2, w3, w4, w5, w6, w7, w8, w9]
                 epoch losses.append((loss/len(X)))
```

```
100%
                                                                           100/100 [00:04<00:0
0, 20.07it/s]
```

```
In [32]:
          # Plot between epochs and loss
             import matplotlib.pyplot as plt
             plt.grid()
             plt.plot(epochs,epoch_losses)
             plt.title("Epoch vs loss plot")
             plt.xlabel("Epochs")
             plt.ylabel("loss")
             plt.show
```

Out[32]: <function matplotlib.pyplot.show(*args, **kw)>



2. Gradient Decent with Momentum.

```
In [33]:
          def get_vt(old_derivative_list):
                 learning_rate = 0.01
                 lambdaa = 0.9
                 old_derivative_list.reverse()
                 vt = 0
                 for i in range(len(old_derivative_list)):
                     vt = vt + ((lambdaa**i)* (learning_rate*old_derivative_list[i]))
                 return vt
```

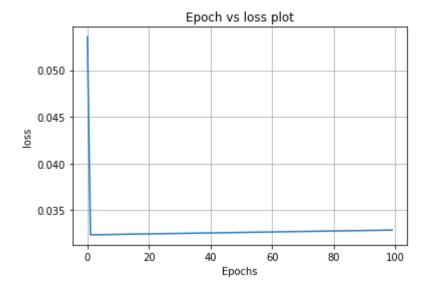
```
I from tadm import tadm
In [34]:
             learning rate = 0.01
             W = np.random.normal(loc=0.0, scale=0.1, size=9)
             epochs = list(i for i in range(100))
             epoch losses = []
             for epoch in tqdm(epochs):
                 loss = 0
                 old weights derivatives of w1 = []
                 old weights derivatives of w2 = []
                 old weights derivatives of w3 = []
                 old weights derivatives of w4 = []
                 old weights derivatives of w5 = []
                 old weights derivatives of w6 = []
                 old weights derivatives of w7 = []
                 old weights derivatives of w8 = []
                 old weights derivatives of w9 = []
                 for data point index in range(len(X)):
                     dict1 = forward propagation(X[data point index],y[data point index],W)
                     dws dict = backward propagation(X[data point index],W,dict1)
                     old weights derivatives = [dws dict.get(i) for i in dws dict]
                     # getting loss with current weights
                     loss = loss + (dict1.get("loss"))
                     # storing old derivatives weights
                     old weights derivatives of w1.append(old weights derivatives[0])
                     old weights derivatives of w2.append(old weights derivatives[1])
                     old weights derivatives of w3.append(old weights derivatives[2])
                     old weights derivatives of w4.append(old weights derivatives[3])
                     old weights derivatives of w5.append(old weights derivatives[4])
                     old weights derivatives of w6.append(old weights derivatives[5])
                     old weights derivatives of w7.append(old weights derivatives[6])
                     old weights derivatives of w8.append(old weights derivatives[7])
                     old weights derivatives of w9.append(old weights derivatives[8])
                     # updating weights
                     w1 = ((W[0]) - (get vt(old weights derivatives of w1)))
                     w2 = ((W[1]) - (get vt(old weights derivatives of w2)))
                     w3 = ((W[2]) - (get vt(old weights derivatives of w3)))
                     w4 = ((W[3]) - (get vt(old weights derivatives of w4)))
                     w5 = ((W[4]) - (get vt(old weights derivatives of w5)))
                     w6 = ((W[5]) - (get vt(old weights derivatives of w6)))
                     w7 = ((W[6]) - (get vt(old weights derivatives of w7)))
```

```
w8 = ((W[7]) - (get_vt(old_weights_derivatives_of_w8)))
    w9 = ((W[8]) - (get_vt(old_weights_derivatives_of_w9)))
    W = [w1, w2, w3, w4, w5, w6, w7, w8, w9]
epoch_losses.append((loss/len(X)))
```

100% 100/100 [02:43<00:0 0, 1.64s/it]

```
In [35]:
            # Plot between epochs and loss
             import matplotlib.pyplot as plt
             plt.grid()
             plt.plot(epochs,epoch_losses)
             plt.title("Epoch vs loss plot")
             plt.xlabel("Epochs")
             plt.ylabel("loss")
             plt.show
```

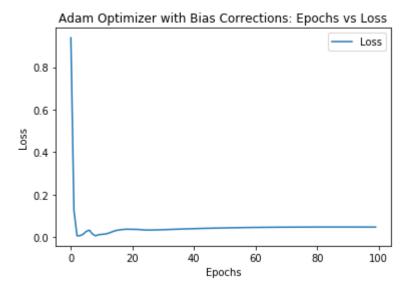
Out[35]: <function matplotlib.pyplot.show(*args, **kw)>



3. Implementing Adam Optimizer.

```
In [20]:

    def Adam(X data, y data, learning rate=0.001):
                 N = 9 #No of Weight parameters
                 w = initilize randomly gaussian(N)
                 epochs = list(range(0,100))
                 epoch loss = np.zeros(len(epochs))
                 Beta1 = 0.9
                 Beta2 = 0.999
                 epsilon = 1e-7
                 for epoch in epochs:
                     # print("Epoch - ",epoch+1,"/100",end=" ")
                     loss = 0
                     Mt = np.zeros(N)
                     Vt = np.zeros(N)
                     for t, (X,y) in enumerate(zip(X data,y data)):
                         dict loss=forward propagation(X,y,w)
                         dict Weights=backward propagation(X,w,dict loss)
                         grad = gradients to vector(dict Weights)
                         Mt = Beta1*Mt + (1-Beta1)*grad
                         Vt = Beta2*Vt + (1-Beta2)*np.square(grad)
                         Mt hat = Mt /(1 - np.power(Beta1, t+1))
                         Vt hat = Vt /(1 - np.power(Beta2,t+1))
                         w = w - learning rate*Mt hat/(np.sqrt(Vt hat) + epsilon)
                         loss += np.square(dict loss["loss"])
                     epoch loss[epoch] = loss/len(y data)
                     # print("Loss - ",'%.4e' % MSELoss[epoch])
                 plt.xlabel("Epochs")
                 plt.ylabel("Loss")
                 plt.grid()
                 plt.title("Adam Optimizer : Epochs vs Loss")
                 plt.plot(epochs,epoch loss)
                 plt.legend(["Loss"])
                 return MSEloss
             Adam loss = Adam(X,y)
```



Thanks For Coming..!!:)