Maths Basics Quick Sheet

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Derivatives

$$[f(u(x))]' = f'(u(x)) \times u'(x)$$
$$[e^{u(x)}]' = e^{u(x)} \times u'(x)$$
$$[u(x)^{\alpha}]' = \alpha u^{\alpha - 1}(x) \times u'(x)$$
$$[\ln(u(x))]' = \frac{u'(x)}{u(x)}$$
$$\cos(x)' = -\sin(x)$$
$$\sin(x)' = \cos(x)$$

Primitives

$$u'e^{u} \to e^{u}$$

$$u^{\alpha}u' \to \frac{u^{\alpha+1}}{\alpha+1}$$

$$\frac{u'}{u} \to \ln(u(x))$$

$$u'\sin(u) \to -\cos(u)$$

$$u'\cos(u) \to \sin(u)$$

Taylor Expansions in 0

Exponential:

$$e^x = 1 + x + \frac{x^2}{2!} + \frac{x^3}{3!} + \frac{x^4}{4!} + o(x^4)$$

$$(1+x)^{\alpha} = 1 + \alpha x + \frac{\alpha(\alpha-1)}{2!} x^2 + \frac{\alpha(\alpha-1)(\alpha-2)}{3!} x^3 + o(x^3)$$

$$\frac{1}{1+x} = (1+x)^{-1} = 1 - x + x^2 - x^3 + x^4 + o(x^4)$$

$$\frac{1}{1-x} = 1 + x + x^2 + x^3 + x^4 + o(x^4)$$

$$\ln(1+x) = x - \frac{x^2}{2} + \frac{x^3}{3} - \frac{x^4}{4} + o(x^4)$$

$$\cos(x) = 1 - \frac{x^2}{2!} + \frac{x^4}{4!} + \begin{vmatrix} o(x^4) \\ o(x^5) \end{vmatrix}$$

$$\sin(x) = x - \frac{x^3}{3!} + \frac{x^5}{5!} + \begin{vmatrix} o(x^5) \\ o(x^6) \end{vmatrix}$$

Manipulation of $o(x^{\alpha})$

- $o(x^{\alpha}) o(x^{\alpha}) = o(x^{\alpha})$
- $o(x^{\alpha}) o(x^{\alpha+1}) = o(x^{\alpha})$
- $o(\lambda x^{\alpha}) = o(x^{\alpha})$
- $x^n \times o(x^\alpha) = o(x^n \times x^\alpha) = o(x^{\alpha+n})$
- $\bullet \quad \frac{1}{x^n}o(x^2) = o\left(\frac{1}{x^n} \times x^2\right) = o(x^{2-n})$

Polynomials

Let r be a root of P

ullet r is a root of order of multiplicity at least m iff

$$(X-r)^m \mid P$$

• r is a root of order of multiplicity exactly m iff

$$\begin{cases} (X-r)^m & \mid P \\ (X-r)^{m+1} \nmid P \end{cases}$$

• r is a root of order of multiplicity at least m iff

$$P(r) = 0$$

$$P'(r) = 0$$

$$\vdots$$

$$P^{(m-1)}(r) = 0$$
 $m \text{ conditions}$

• r is a root of order of multiplicity exactly m iff

$$\begin{cases} (X-r)^m & | P \\ (X-r)^{m+1} \nmid P \end{cases}$$

Differential equations

Don't question these formulas. They Just Work™.

First order

With
$$ay' + by = c$$

$$y_0 = ke^{-\int \frac{b}{a}}$$
$$y_p = y_0 \int \frac{c}{ay_0}$$
$$y = y_0 + y_p$$

Second order (constant terms for a b c)

With
$$ay'' + by' + cy = d(t)$$

- 1. Compute root(s) of $ar^2 + br + c$
 - a. $\Delta > 0$: Two real roots r_1 and r_2

$$y_0 = k_1 e^{r_1 t} + k_2 e^{r_2 t}$$

b. $\Delta = 0$: One real root r_1

$$y_0 = (k_1 + k_2 t)e^{r_1 t}$$

c. $\Delta < 0$: Two complex roots $r_1 = \alpha i + \beta$ and $r_2 = \alpha i - \beta$ $v_0 = e^{\alpha t} (k_1 \cos(\beta t) + k_2 \sin(\beta t))$

- 2. Getting y_p
 - a. d(t) = P(t) (polynomial)

Then
$$y_p = Q(t)$$

$$c \neq 0$$
 $\rightarrow \deg(Q) = \deg(P)$

$$c = 0$$
, $b \neq 0 \rightarrow \deg(Q) = \deg(P) + 1$

$$c = 0, b = 0 \rightarrow \deg(Q) = \deg(P) + 2$$

We then know the expression of Q(t).

Compute the expressions of Q'(t) and Q''(t).

$$aQ''(t) + bQ'(t) + cQ(t) = d(t)$$

Use the coefficients of d(t) to deduce the coefficients of the left side of the equation

b. $d(t) = P(t)e^{mt}$ (polynomial times exponential) Then $y_n = Q(t)e^{mt}$

Derive y_p twice to get y_p' and y_p''

$$ay_p'' + by_p' + cy = P(t)e^{mt}$$

Factorize the left side by e^{mt} and divide both sides by e^{mt} .

You should find an equation

$$\alpha Q''(t) + \beta Q'(t) + \gamma Q(t) = P(t)$$

Once you get this, find Q(t) using the previous method (d(t) = P(t)).

c. For any other kind of d(t)

I'll quote Mehdi for this one:

"You either Taylor the shit out of it and try to solve for a polynomial, or send it back to the hell it comes from because it won't be on MCQ anyway"

3.
$$y = y_0 + y_p$$

Vector spaces

Direct sum/Supplementary subspaces

 $E = F \oplus G$ if both conditions are true:

- $F \cap G = \{0_F\}$
- -F+G=E

$$\circ$$
 $\forall w \in E$, $\exists u \in F$, $\exists v \in G$, $w = u + v$

Linear (in)dependence

A set $X = (x_1, \dots, x_n) \in E^n$ is linearly independent if

$$\forall (\lambda_i)_{i \in [\![1,n]\!]} \in \mathbb{K}^n, \left(\sum_{i=1}^n \lambda_i x_i = 0 \Rightarrow \forall i, \lambda_i = 0\right)$$

If it is not linearly independent, it is linearly dependent.

- Adding vectors to a linearly dependent set makes it remain dependent.
- Removing vectors from (i.e. taking a subset of) a linearly independent set makes it remain independent.

Span(X)

Let E be a \mathbb{R} vector space.

$$\begin{split} X &= \{u_1, u_2, \dots, u_n\} \subset E \\ Span(X) &= \{\lambda_1 u_1 + \dots + \lambda_n u_n \mid (\lambda_1, \dots, \lambda_n) \in \mathbb{R}^{\mathbb{N}}\} \\ &= \{\text{linear combinations of } u_1, \dots, u_n\} \end{split}$$

Span(X) is a \mathbb{R} -vs with $X \subset Span(X)$

Spanning set

Let $X \subset E$. We say that X is a spanning set of E if E = Span(X)

Base

A linearly independent spanning set of E is called a basis of E.

 $(e_1, ..., e_n)$ is a basis of $E \Leftrightarrow \forall u \in E$, there exists a unique decomposition of u as a linear combination of the basis $\left(u = \sum_{i=1}^n \lambda_i e_i\right)$

Linear maps

E and F two \mathbb{R} -vs.

$$f: E \to F$$

Then f is a linear map if $\forall (u, v) \in E^2, \forall \lambda \in \mathbb{R}$,

• $f(\lambda u + v) = \lambda f(u) + f(v)$

Or

• f(u+v) = f(u) + f(v)And $f(\lambda u) = \lambda f(u)$

Then:

• $f(0_E) = 0_F$ Proof: $f(-u+u) = -f(u) + f(u) \Rightarrow f(0_E) = 0_F$ All the linear maps $\mathbb{R}^n \to \mathbb{R}^p$ have the form

$$f\left(\begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix}\right) = \begin{pmatrix} a_{1,1}x_1 + \dots + a_{1,n}x_n \\ \vdots \\ a_{p,1}x_1 + \dots + a_{p,n}x_n \end{pmatrix}$$

Kernel and image

Let
$$f: E \to F$$
 be a linear map $(f \in \mathcal{L}(E, F))$

$$Ker(f) = \{ \text{preimages of } 0_F \text{ by } F \}$$

$$= \{ u \in E \text{ such that } f(u) = 0_F \}$$

$$= f^{-1}(\{0_F\})$$

$$Im(f) = f(E)$$

$$= \{ f(u), u \in E \}$$

$$= \{ v \in F \text{ such that } \exists v \in F, v = f(u) \}$$