Neural networks

10.1 Draw a neural network

Draw the graph corresponding to a two-layer dense neural network for regression with p input variables x_1, \ldots, x_p , one hidden layer with U units, activation function $h : \mathbb{R} \to \mathbb{R}$ in the layer, and output $\widehat{y} \in \mathbb{R}$. How many parameters does the model have (including offsets)?

10.2 Vectorization over units

Mathematically, the model above can be described as

$$q_i = h\left(b_i^{(1)} + \sum_{j=1}^p W_{ij}^{(1)} x_j\right), \qquad i = 1, \dots, U$$
 (10.1a)

$$\widehat{y} = b^{(2)} + \sum_{\ell=1}^{U} W_{\ell}^{(2)} q_{\ell}$$
(10.1b)

where each node contains a linear regression model, and where each node in the hidden layer is squeezed through an activation function h. When we implement this in code, we prefer to use a *vectorized* version of these equations since it runs faster than loops and explicit sums. Vectorize the equations in (10.1) by introducing the variables

$$\mathbf{x} = \begin{bmatrix} x_1 \\ \vdots \\ x_p \end{bmatrix}, \quad \mathbf{q} = \begin{bmatrix} q_1 \\ \vdots \\ q_U \end{bmatrix}, \quad \mathbf{b}^{(1)} = \begin{bmatrix} b_1^{(1)} \\ \vdots \\ b_U^{(1)} \end{bmatrix}, \quad \mathbf{W}^{(1)} = \begin{bmatrix} W_{11}^{(1)} & \dots & W_{1p}^{(1)} \\ \vdots & & \vdots \\ W_{U1}^{(1)} & \dots & W_{Up}^{(1)} \end{bmatrix}, \quad \mathbf{b}^{(2)} = \begin{bmatrix} b^{(2)} \end{bmatrix}, \quad \mathbf{W}^{(2)} = \begin{bmatrix} W_1^{(2)} & \dots & W_U^{(2)} \\ \vdots & & \vdots \\ W_U^{(1)} & \dots & W_U^{(1)} \end{bmatrix},$$

i.e. write (10.1) on a matrix form

$$\widehat{y} = f(\mathbf{x}),\tag{10.2}$$

which does not include any explicit summation \sum or looping over $\ell = 1, \dots, U$.

10.3 Vectorization over data points

When processing many data points $\{\mathbf{x}_i\}_{i=1}^n$, we have the relation (10.2) for each data point $i=1,\ldots,n$

$$\widehat{\mathbf{y}}_i = f(\mathbf{x}_i), \qquad i = 1, \dots, n. \tag{10.3}$$

Vectorize the equations in (10.3) by introducing the variables

$$\mathbf{X} = \begin{bmatrix} \mathbf{x}_1^\mathsf{T} \\ \vdots \\ \mathbf{x}_n^\mathsf{T} \end{bmatrix}, \quad \widehat{\mathbf{Y}} = \begin{bmatrix} \widehat{\mathbf{y}}_1^\mathsf{T} \\ \vdots \\ \widehat{\mathbf{y}}_n^\mathsf{T} \end{bmatrix}, \quad \text{and} \quad \mathbf{Q} = \begin{bmatrix} \mathbf{q}_1^\mathsf{T} \\ \vdots \\ \mathbf{q}_n^\mathsf{T} \end{bmatrix}, \tag{10.4}$$

i.e. write (10.3) on a matrix form

$$\widehat{\mathbf{Y}} = f(\mathbf{X}),\tag{10.5}$$

which does not include any explicit looping $i = 1, \ldots, n$.

10.4 Linear activation function

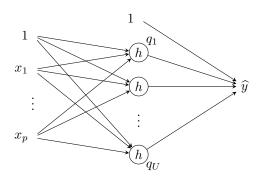
Show that the model in the (10.1) reduces to a linear regression model if h(x) = x. Specifically, show how the parameters of the entire neural network relate to the parameters of the single linear regression model

$$\widehat{y} = \theta_0 + \sum_{j=1}^p \theta_j x_j.$$

Solutions

10.1 A dense neural network for regression with one hidden layer can be illustrated as

Input variables Hidden units Output



Each link represents a multiplication of its incoming unit with a parameter. The parameters are different for each link. The number of links in the graph (=number of parameters in the model) is consequently $(p+1) \cdot U + 1 + U$.

10.2 By stacking the equations in (10.1a) as rows in vectors we get

$$\begin{bmatrix} q_1 \\ \vdots \\ q_U \end{bmatrix} = \begin{bmatrix} h \left(b_1^{(1)} + \sum_{j=1}^p W_{1j}^{(1)} x_j \right) \\ \vdots \\ h \left(b_U^{(1)} + \sum_{j=1}^p W_{Uj}^{(1)} x_j \right) \end{bmatrix}$$
(10.6a)

$$\widehat{y} = b^{(2)} + \sum_{i=1}^{U} W_i^{(2)} q_i$$
(10.6b)

Further, by replacing the summations with matrix-vector multiplications we can write this as

$$\underbrace{\begin{bmatrix} q_1 \\ \vdots \\ q_U \end{bmatrix}}_{\mathbf{q}} = h \underbrace{\begin{bmatrix} W_{11}^{(1)} & \dots & W_{1p}^{(1)} \\ \vdots & & \vdots \\ W_{U1}^{(1)} & \dots & W_{Up}^{(1)} \end{bmatrix}}_{\mathbf{W}^{(1)}} \underbrace{\begin{bmatrix} x_1 \\ \vdots \\ x_p \end{bmatrix}}_{\mathbf{x}} + \underbrace{\begin{bmatrix} b_1^{(1)} \\ \vdots \\ b_U^{(1)} \end{bmatrix}}_{\mathbf{b}^{(1)}}, \tag{10.7a}$$

$$\widehat{y} = \underbrace{\begin{bmatrix} W_1^{(2)} & \dots & W_U^{(2)} \end{bmatrix}}_{\mathbf{W}^{(2)}} \underbrace{\begin{bmatrix} q_1 \\ \vdots \\ q_U \end{bmatrix}}_{\mathbf{g}} + \underbrace{\begin{bmatrix} b^{(2)} \end{bmatrix}}_{\mathbf{b}^{(2)}}.$$
(10.7b)

By identifying all the matrices and vectors, we can in a more compact and vectorized manner write these equations as

$$\mathbf{q} = h\left(\mathbf{W}^{(1)}\mathbf{x} + \mathbf{b}^{(1)}\right),\tag{10.8a}$$

$$\widehat{y} = \mathbf{W}^{(2)}\mathbf{q} + \mathbf{b}^{(2)} \tag{10.8b}$$

Note that the activation function h acts element-wise here.

10.3 Following the solutions from the previous exercise, the equations we are about to vecotrize are

$$\mathbf{q}_i = h\left(\mathbf{W}^{(1)}\mathbf{x}_i + \mathbf{b}^{(1)}\right), \qquad i = 1, \dots, n,$$
(10.9a)

$$\widehat{\mathbf{y}}_i = \mathbf{W}^{(2)} \mathbf{q}_i + \mathbf{b}^{(2)}, \qquad i = 1, \dots, n. \tag{10.9b}$$

We start by taking the transpose of these equations

$$\mathbf{q}_i^{\mathsf{T}} = h\left(\mathbf{x}_i^{\mathsf{T}}\mathbf{W}^{(1)\mathsf{T}} + \mathbf{b}^{(1)\mathsf{T}}\right), \qquad i = 1, \dots, n,$$
 (10.10a)

$$\widehat{\mathbf{y}}_i^{\mathsf{T}} = \mathbf{q}_i^{\mathsf{T}} \mathbf{W}^{(2)\mathsf{T}} + \mathbf{b}^{(2)\mathsf{T}}, \qquad i = 1, \dots, n.$$
(10.10b)

We continue by stacking these equations in rows

$$\begin{bmatrix} \mathbf{q}_{1}^{\mathsf{T}} \\ \vdots \\ \mathbf{q}_{n}^{\mathsf{T}} \end{bmatrix} = \begin{bmatrix} h \left(\mathbf{x}_{1}^{\mathsf{T}} \mathbf{W}^{(1)\mathsf{T}} + \mathbf{b}^{(1)\mathsf{T}} \right) \\ \vdots \\ h \left(\mathbf{x}_{n}^{\mathsf{T}} \mathbf{W}^{(1)\mathsf{T}} + \mathbf{b}^{(1)\mathsf{T}} \right) \end{bmatrix}, \tag{10.11a}$$

$$\begin{bmatrix} \widehat{\mathbf{y}}_{1}^{\mathsf{T}} \\ \vdots \\ \widehat{\mathbf{y}}_{n}^{\mathsf{T}} \end{bmatrix} = \begin{bmatrix} \mathbf{q}_{1}^{\mathsf{T}} \mathbf{W}^{(2)\mathsf{T}} + \mathbf{b}^{(2)\mathsf{T}} \\ \vdots \\ \mathbf{q}_{n}^{\mathsf{T}} \mathbf{W}^{(2)\mathsf{T}} + \mathbf{b}^{(2)\mathsf{T}} \end{bmatrix}.$$
(10.11b)

By bringing the weight matrices and offset vectors outside we get

$$\begin{bmatrix} \mathbf{q}_1^\mathsf{T} \\ \vdots \\ \mathbf{q}_n^\mathsf{T} \end{bmatrix} = h \begin{pmatrix} \begin{bmatrix} \mathbf{x}_1^\mathsf{T} \\ \vdots \\ \mathbf{x}_n^\mathsf{T} \end{bmatrix} \mathbf{W}^{(1)\mathsf{T}} + \mathbf{b}^{(1)\mathsf{T}} \end{pmatrix}, \tag{10.12a}$$

$$\begin{bmatrix} \widehat{\mathbf{y}}_{1}^{\mathsf{T}} \\ \vdots \\ \widehat{\mathbf{y}}_{n}^{\mathsf{T}} \end{bmatrix} = \begin{bmatrix} \mathbf{q}_{1}^{\mathsf{T}} \\ \vdots \\ \mathbf{q}_{n}^{\mathsf{T}} \end{bmatrix} \mathbf{W}^{(2)\mathsf{T}} + \mathbf{b}^{(2)\mathsf{T}}.$$
 (10.12b)

Note that in these equations we add $+\mathbf{b}^{(1)\mathsf{T}}$ and $+\mathbf{b}^{(2)\mathsf{T}}$ to each row. In python-language we call that *broadcasting* and is heavily used in deep learning implementations.

Now we can identify the matrices in the problem description and write these equations as

$$\mathbf{Q} = h\left(\mathbf{X}\mathbf{W}^{(1)\mathsf{T}} + \mathbf{b}^{(1)\mathsf{T}}\right),\tag{10.13a}$$

$$\widehat{\mathbf{Y}} = \mathbf{Q}\mathbf{W}^{(2)\mathsf{T}} + \mathbf{b}^{(2)\mathsf{T}},\tag{10.13b}$$

which now is in a format suitable for efficient vectorized implementation in code. For the implementation you might want to consider using the transposed version of $\mathbf{W}^{(1)}$, $\mathbf{W}^{(2)}$, $\mathbf{b}^{(1)}$ and $\mathbf{b}^{(2)}$ as your weight matrices and offset vectors to avoid taking transpose in each layer.

10.4 Alternative 1

The mathematical model corresponding to the neural network above is

$$q_{i} = h \left(b_{i}^{(1)} + \sum_{j=1}^{p} W_{ij}^{(1)} x_{j} \right), \qquad i = 1, \dots, U$$
$$\widehat{y} = b^{(2)} + \sum_{\ell=1}^{U} W_{\ell}^{(2)} q_{\ell}$$

If we consider a linear activation function h(x) = x in (10.1) we get

$$\widehat{y} = b^{(2)} + \sum_{\ell=1}^{U} W_{\ell}^{(2)} \left(b_{\ell}^{(1)} + \sum_{j=1}^{p} W_{\ell j}^{(1)} x_{j} \right)$$

$$= b^{(2)} + \sum_{\ell=1}^{U} W_{\ell}^{(2)} b_{\ell}^{(1)} + \sum_{j=1}^{p} \sum_{\ell=1}^{U} W_{\ell}^{(2)} W_{\ell j}^{(1)} x_{j},$$

which is a linear regression model

$$\widehat{y} = \theta_0 + \sum_{j=1}^p \theta_j x_j$$

where

$$\theta_0 = b^{(2)} + \sum_{\ell=1}^{U} W_{\ell}^{(2)} b_{\ell}^{(1)}$$
 and $\theta_j = \sum_{\ell=1}^{U} W_{\ell}^{(2)} W_{\ell j}^{(1)}$. (10.14)

Alternative 2

We can also solve the exercise by starting from the vectorized version of the model in (10.2). With h(x) = x we get

$$\mathbf{q} = \mathbf{W}^{(1)}\mathbf{x} + \mathbf{b}^{(1)},\tag{10.15a}$$

$$\widehat{y} = \mathbf{W}^{(2)}\mathbf{q} + \mathbf{b}^{(2)} \tag{10.15b}$$

which gives us

$$\widehat{y} = \mathbf{W}^{(2)} \mathbf{W}^{(1)} \mathbf{x} + \mathbf{W}^{(2)} \mathbf{b}^{(1)} + \mathbf{b}^{(2)}$$
(10.16)

This can be compared with the linear regression model

$$\widehat{y} = \theta_0 + \sum_{j=1}^p \theta_j x_j$$

$$= \boldsymbol{\theta}_{-0}^\mathsf{T} \mathbf{x} + \theta_0$$
(10.17)

where $\boldsymbol{\theta}_{-0} = [\theta_1, \dots, \theta_p]^\mathsf{T}$. By comparing (10.16) and (10.17) we get that

$$\theta_{-0} = \mathbf{W}^{(1)\mathsf{T}} \mathbf{W}^{(2)\mathsf{T}}, \quad \text{and} \quad \theta_0 = \mathbf{W}^{(2)} \mathbf{b}^{(1)} + \mathbf{b}^{(2)}$$
 (10.18)

and by using the definitions in Exercise 10.2 this is

$$\begin{bmatrix} \theta_1 \\ \vdots \\ \theta_p \end{bmatrix} = \begin{bmatrix} W_{11}^{(1)} & \dots & W_{U1}^{(1)} \\ \vdots & & \vdots \\ W_{1p}^{(1)} & \dots & W_{Up}^{(1)} \end{bmatrix} \begin{bmatrix} W_{1}^{(2)} \\ \vdots \\ W_{U}^{(2)} \end{bmatrix}, \quad \text{and} \quad \theta_0 = \begin{bmatrix} W_{1}^{(2)} & \dots & W_{U}^{(2)} \end{bmatrix} \begin{bmatrix} b_1^{(1)} \\ \vdots \\ b_U^{(1)} \end{bmatrix} + b^{(2)}$$

$$(10.19)$$

which is equivalent with the solution in (10.14).