



# Smallest enclosing circles and more

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Computational Geometry

Utrecht University

# Introduction

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# Introduction

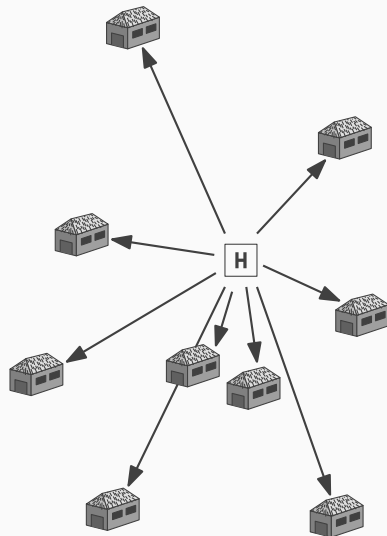
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## Facility location

## Facility location

Given a set of houses and farms in an isolated area.  
Can we place a helicopter ambulance post so that  
each house and farm can be reached within 15  
minutes?

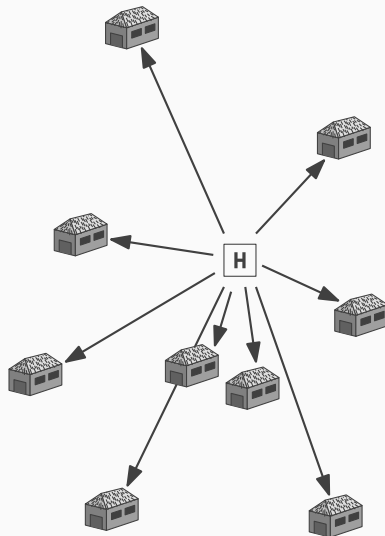
Where should we place an antenna so that a  
number of locations have maximum reception?



## Facility location in geometric terms

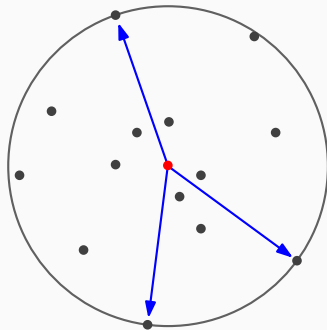
Given a set of points in the plane. Is there any point that is within a certain distance of these points?

Where do we place a point that minimizes the maximum distance to a set of points?



## Facility location in geometric terms

Given a set of points in the plane, compute the smallest enclosing circle



# Introduction

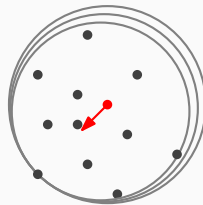
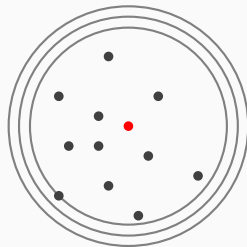
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## Properties of the smallest enclosing circle

## Smallest enclosing circle

**Observation:** It must pass through some points, or else it cannot be smallest

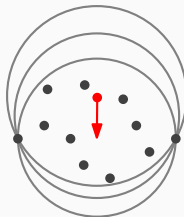
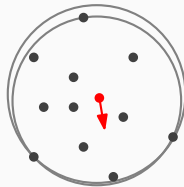
- Take any circle that encloses the points, and reduce its radius until it contains a point  $p$
- Move center towards  $p$  while reducing the radius further, until the circle contains another point  $q$





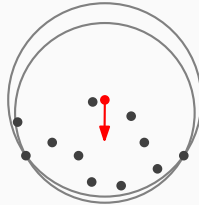
## Smallest enclosing circle

- Move center on the bisector of  $p$  and  $q$  towards their midpoint, until:
  - (i) the circle contains a third point, or
  - (ii) the center reaches the midpoint of  $p$  and  $q$



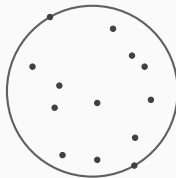
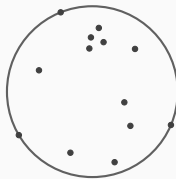
## Smallest enclosing circle

**Question:** Does the “algorithm” of the previous slide work?



## Smallest enclosing circle

**Observe:** A smallest enclosing circle has (at least) three points on its boundary, or only two in which case they are diametrically opposite



## **Smallest enclosing circle algorithm**

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# **Smallest enclosing circle algorithm**

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**Randomized incremental construction**

Construction by randomized incremental construction

*incremental construction*: Add points one by one and maintain the solution so far

*randomized*: Use a random order to add the points

## Adding a point

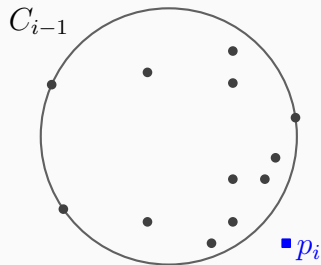
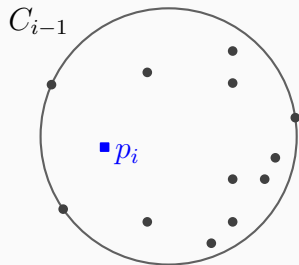
Let  $p_1, \dots, p_n$  be the points in random order

Let  $C_i$  be the smallest enclosing circle for  $p_1, \dots, p_i$

Suppose we know  $C_{i-1}$  and we want to add  $p_i$

- If  $p_i$  is inside  $C_{i-1}$ , then  $C_i = C_{i-1}$
- If  $p_i$  is outside  $C_{i-1}$ , then  $C_i$  will have  $p_i$  on its boundary

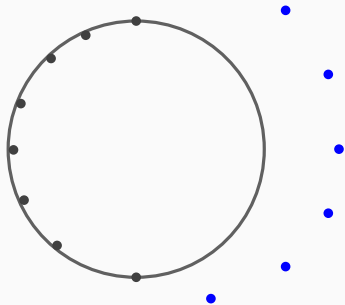
## Adding a point





**Question:** Suppose we remembered not only  $C_{i-1}$ , but also the two or three points defining it. It looks like if  $p_i$  is outside  $C_{i-1}$ , the new circle  $C_i$  is defined by  $p_i$  and some points that defined  $C_{i-1}$ . Why is this false?

## Adding a point



# **Smallest enclosing circle algorithm**

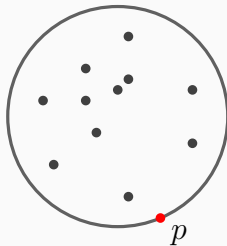
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**A more restricted problem**

## Adding a point

How do we find the smallest enclosing circle of  $p_1 \dots, p_{i-1}$  with  $p_i$  on the boundary?

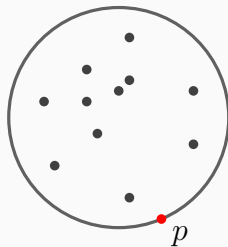
We study the *new(!)* geometric problem of computing the smallest enclosing circle with a given point  $p$  on its boundary



## Smallest enclosing circle with point

Given a set  $P$  of points and one special point  $p$ , determine the smallest enclosing circle of  $P$  that must have  $p$  on the boundary

**Question:** How do we solve it?



Construction by randomized incremental construction

*incremental construction:* Add points one by one and maintain the solution so far

*randomized:* Use a random order to add the points

## Adding a point

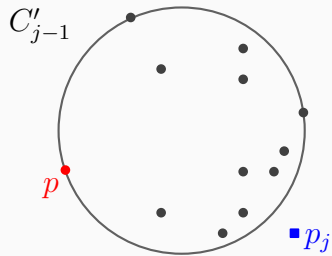
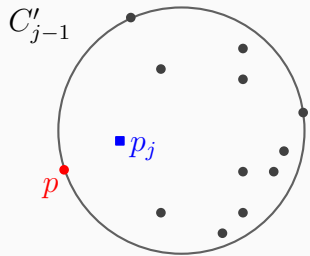
Let  $p_1, \dots, p_{i-1}$  be the points in random order

Let  $C'_j$  be the smallest enclosing circle for  $p_1, \dots, p_j$  ( $j \leq i-1$ ) and with  $p$  on the boundary

Suppose we know  $C'_{j-1}$  and we want to add  $p_j$

- If  $p_j$  is inside  $C'_{j-1}$ , then  $C'_j = C'_{j-1}$
- If  $p_j$  is outside  $C'_{j-1}$ , then  $C'_j$  will have  $p_j$  on its boundary (and also  $p$  of course!)

## Adding a point





## **Smallest enclosing circle algorithm**

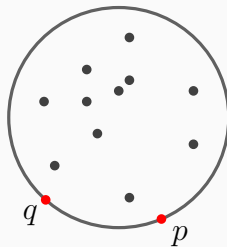
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**A yet more restricted problem**

## Adding a point

How do we find the smallest enclosing circle of  $p_1 \dots, p_{j-1}$  with  $p$  and  $p_j$  on the boundary?

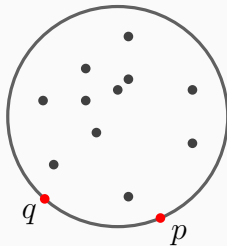
We study the *new(!)* geometric problem of computing the smallest enclosing circle with two given points on its boundary



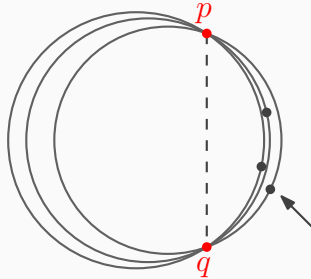
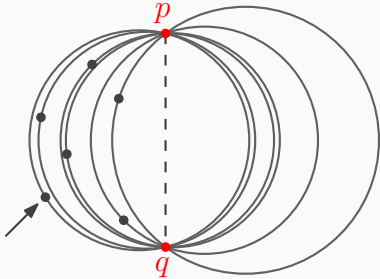
## Smallest enclosing circle with two points

Given a set  $P$  of points and two special points  $p$  and  $q$ , determine the smallest enclosing circle of  $P$  that must have  $p$  and  $q$  on the boundary

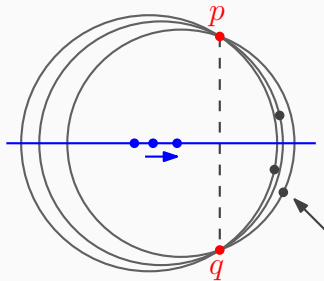
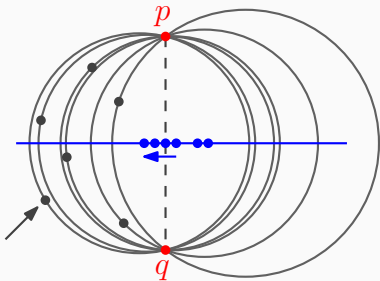
**Question:** How do we solve it?



## Two points known



## Two points known



## Two points known

Assume w.l.o.g. that  $p$  and  $q$  lie on a vertical line. Let  $\ell$  be the line through  $p$  and  $q$  and let  $\ell'$  be their bisector

Let  $P^-$  be the set of all points left of  $\ell$ . Every point  $p_j \in P^-$  defines a circle  $C(p_j, p, q)$  with center  $c_j$ . Let  $p_l \in P^-$  be the point whose center  $c_l$  is leftmost.

**Lemma.** For any two points  $p_i, p_j \in P^-$ , if  $p_i \in C(p_j, p, q)$  then  $p_i \in C(p_l, p, q)$ .

**Corollary.**  $C(p_l, p, q)$  is the only circle with  $p_l \in P^-$  that encloses all points in  $P^-$ .

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**Corollary.**  $C(p_l, p, q)$  is the only circle with  $p_l \in P^-$  that encloses all points in  $P^-$ .

$\implies p_l$  is the only point from  $P^-$  that we have to consider to define a smallest enclosing circle of  $P \supseteq P^-$ .

## Algorithm: two points known

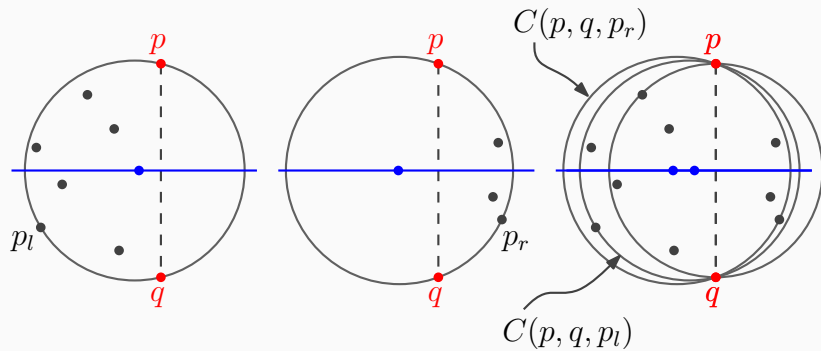
Find the point  $p_l \in P^-$  whose center  $c_l$  is leftmost.

Find the point  $p_r \in P \setminus P^-$  whose center  $c_r$  is rightmost.

Decide if  $C(p, q, p_l)$  or  $C(p, q, p_r)$  or  $C(p, q)$  is the smallest enclosing circle



## Two points known



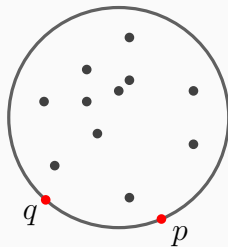
# **Smallest enclosing circle algorithm**

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**Efficiency analysis**

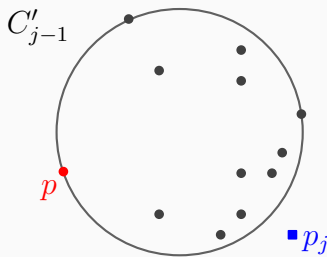
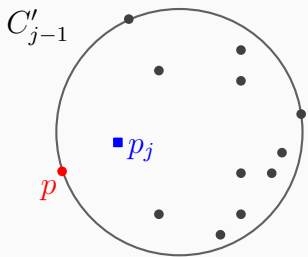
## Analysis: two points known

Smallest enclosing circle for  $n$  points with two points already known takes  $O(n)$  time, worst case



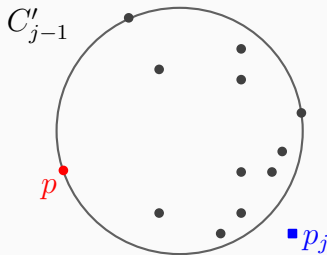
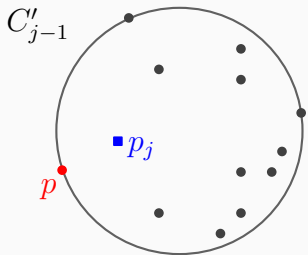
## Algorithm: one point known

- Use a random order for  $p_1, \dots, p_n$ ; start with  $C_1 = C(p, p_1)$
- **for**  $j \leftarrow 2$  **to**  $n$  **do**  
    If  $p_j$  in or on  $C_{j-1}$  then  $C_j = C_{j-1}$ ; otherwise, solve smallest enclosing circle for  $p_1, \dots, p_{j-1}$  with two points known ( $p$  and  $p_j$ )



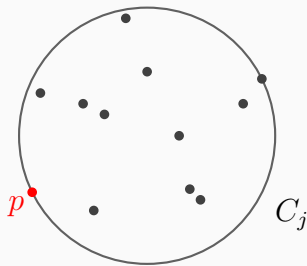
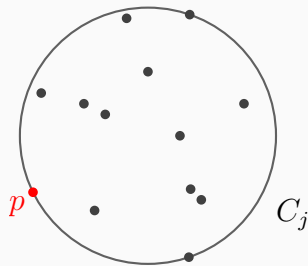
## Analysis: one point known

If only one point is known, we used randomized incremental construction, so we need an *expected time analysis*



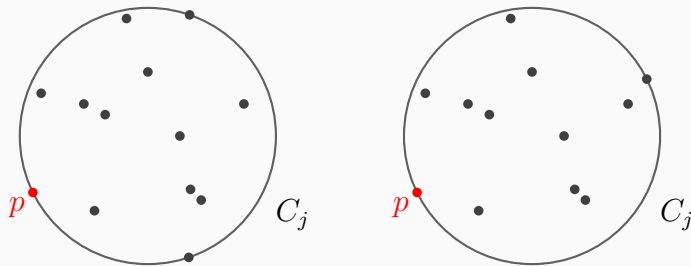
## Analysis: one point known

**Backwards analysis:** Consider the situation *after* adding  $p_j$ , so we have computed  $C_j$



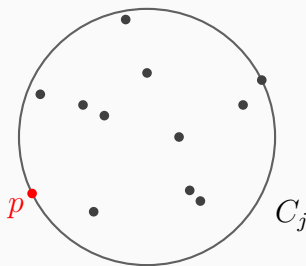
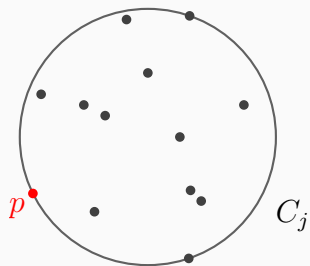
## Analysis: one point known

The probability that the  $j$ -th addition was expensive is the same as the probability that the smallest enclosing circle changes (decreases in size) if we remove a random point from the  $j$  points



## Analysis: one point known

This probability is  $2/j$  in the left situation and  $1/j$  in the right situation





## Analysis: one point known

The expected time for the  $j$ -th addition of a point is

$$\frac{j-2}{j} \cdot \Theta(1) + \frac{2}{j} \cdot \Theta(j) = O(1)$$

or

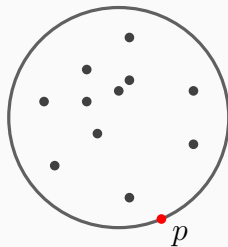
$$\frac{j-1}{j} \cdot \Theta(1) + \frac{1}{j} \cdot \Theta(j) = O(1)$$

The expected running time of the algorithm for  $n$  points is:

$$\Theta(n) + \sum_{j=2}^n \Theta(1) = \Theta(n)$$

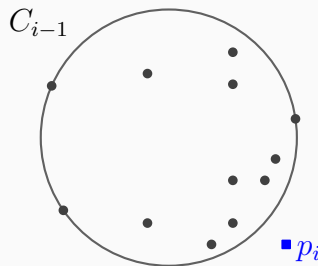
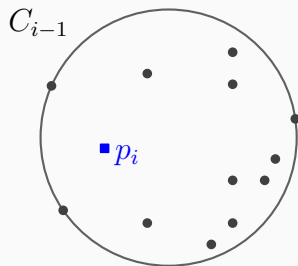
## Analysis: one point known

Smallest enclosing circle for  $n$  points with one point already known takes  $\Theta(n)$  time, expected



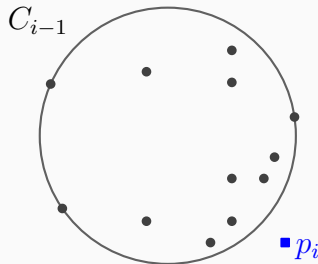
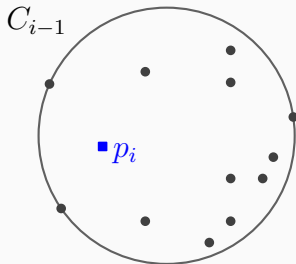
## Algorithm: smallest enclosing circle

- Use a random order for  $p_1, \dots, p_n$ ; start with  $C_2 = C(p_1, p_2)$
- **for**  $i \leftarrow 3$  **to**  $n$  **do**  
  If  $p_i$  in or on  $C_{i-1}$  then  $C_i = C_{i-1}$ ; otherwise, solve smallest enclosing circle for  $p_1, \dots, p_{i-1}$  with one point known ( $p_i$ )



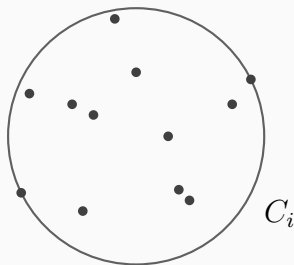
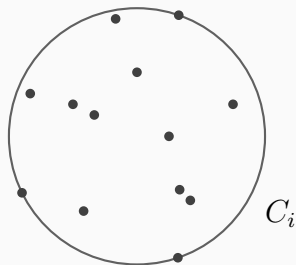
## Analysis: smallest enclosing circle

For smallest enclosing circle, we used randomized incremental construction, so we need an *expected time analysis*



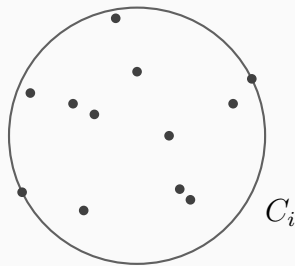
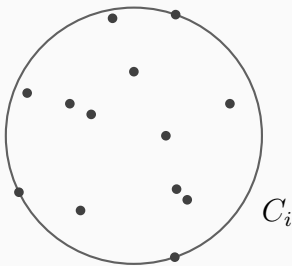
## Analysis: smallest enclosing circle

**Backwards analysis:** Consider the situation *after* adding  $p_i$ , so we have computed  $C_i$



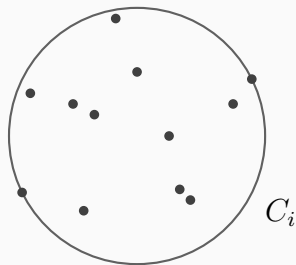
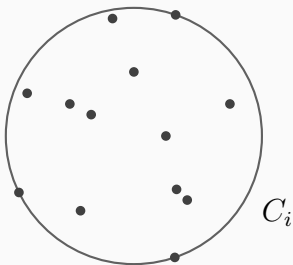
## Analysis: smallest enclosing circle

The probability that the  $i$ -th addition was expensive is the same as the probability that the smallest enclosing circle changes (decreases in size) if we remove a random point from the  $i$  points



## Analysis: smallest enclosing circle

This probability is  $3/i$  in the left situation and  $2/i$  in the right situation



## Analysis: smallest enclosing circle

The expected time for the  $i$ -th addition of a point is

$$\frac{i-3}{i} \cdot \Theta(1) + \frac{3}{i} \cdot \Theta(i) = O(1)$$

or

$$\frac{i-2}{i} \cdot \Theta(1) + \frac{2}{i} \cdot \Theta(i) = O(1)$$

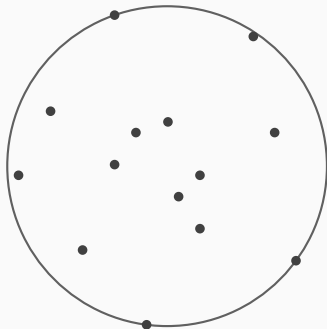
The expected running time of the algorithm for  $n$  points is:

$$\Theta(n) + \sum_{i=3}^n \Theta(1) = \Theta(n)$$



## Result: smallest enclosing circle

**Theorem** The smallest enclosing circle for  $n$  points in plane can be computed in  $O(n)$  expected time



## Randomized incremental construction

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# **Randomized incremental construction**

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## **Conditions**

## When does it work?

Randomized incremental construction algorithms of this sort (compute an 'optimal' thing) work if:

- The test whether the next input object violates the current optimum must be possible and fast
- If the next input object violates the current optimum, finding the new optimum must be an *easier* problem than the general problem
- The thing must already be defined by  $O(1)$  of the input objects
- Ultimately: the analysis must work out

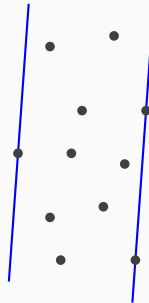
## **Randomized incremental construction**

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**Width?**

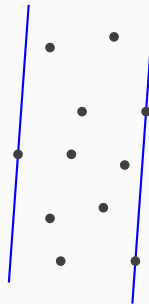
# Width

**Width:** Given a set of  $n$  points in the plane, compute the smallest distance between two parallel lines that contain the points (narrowest strip)



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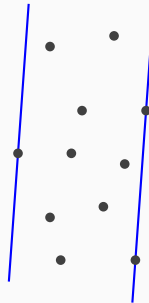
**Theorem:** The width of a set of  $n$  points can be computed in  $O(n \log n)$  time.



## Width by RIC?

**Property:** The width is always determined by three points of the set

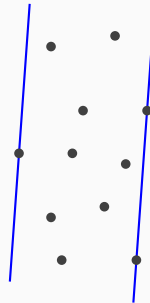
**Idea:** Maintain the two lines defining the width to have a fast test for violation.



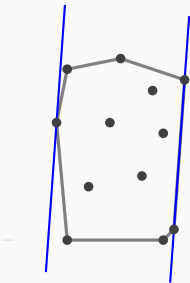


## Adding a point

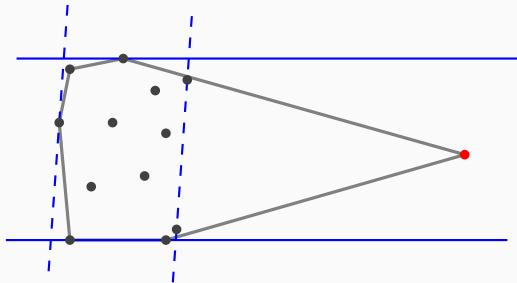
**Question:** How about adding a point? If the new point lies inside the narrowest strip we are fine, but what if it lies outside?



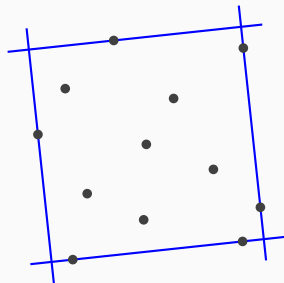
## Adding a point



## Adding a point



A good reason to be very suspicious of randomized incremental construction as a working approach is *non-uniqueness* of a solution



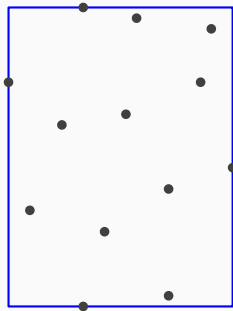
## **Randomized incremental construction**

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**More examples**

## Minimum bounding box

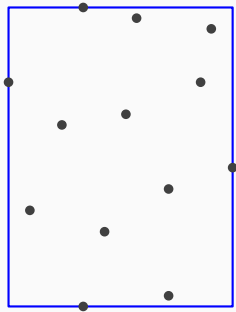
**Question:** Can we compute the minimum axis-parallel bounding box by randomized incremental construction?



## Minimum bounding box

Yes, in  $O(n)$  expected time

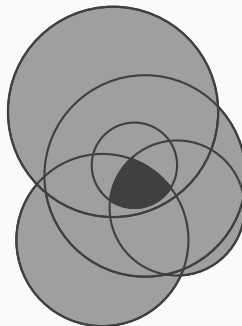
... but a normal incremental algorithm does it in  
 $O(n)$  worst case time



## Lowest point in circles

**Problem 1:** Given  $n$  disks in the plane, can we compute the lowest point in their common intersection efficiently by randomized incremental construction?

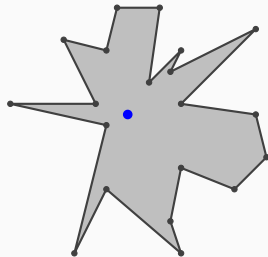
**Problem 2:** Given  $n$  disks in the plane, can we compute the lowest point in their union efficiently by randomized incremental construction?





## One-guardable polygons

**Problem:** Given a simple polygon with  $n$  vertices, can we decide efficiently if one guard is enough?



## One-guardable polygons

It can easily happen that a problem is an instance of linear programming

Then don't devise a new algorithm, just explain how to transform it, and show that it is correct (that your problem is really solved that way)

