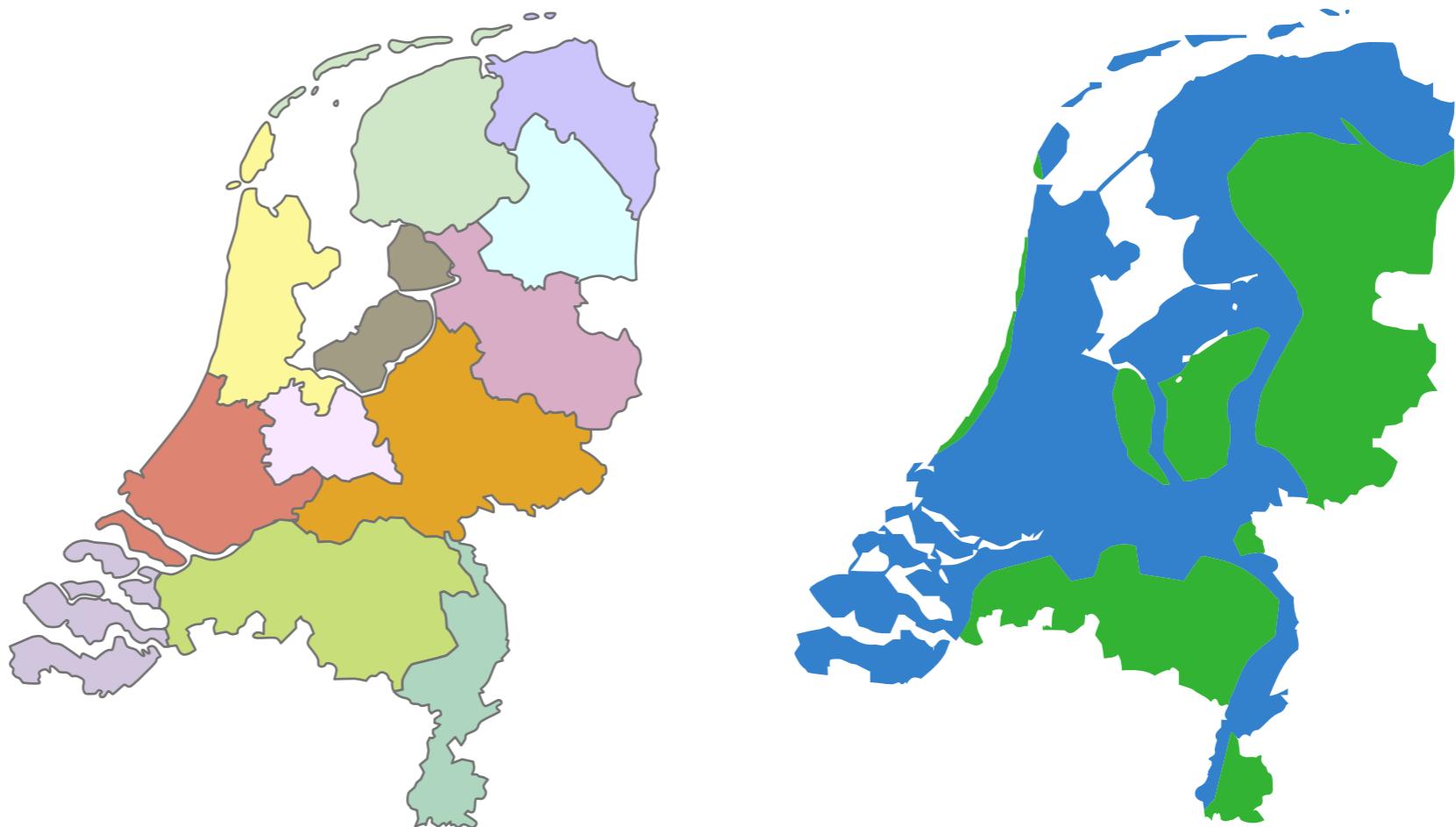


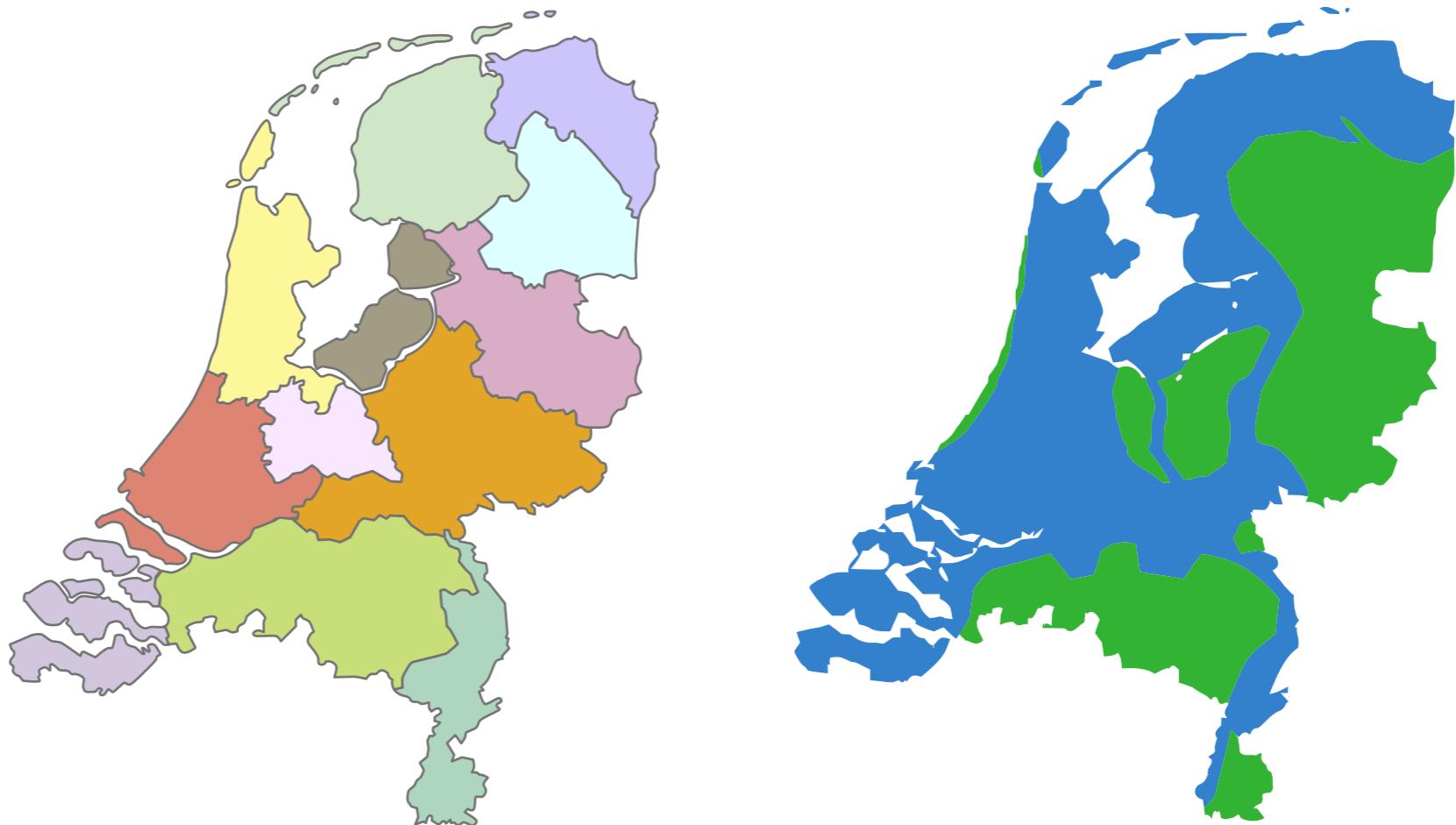
Introduction



Introduction



Introduction



What percentage of Utrecht is in danger of floods?

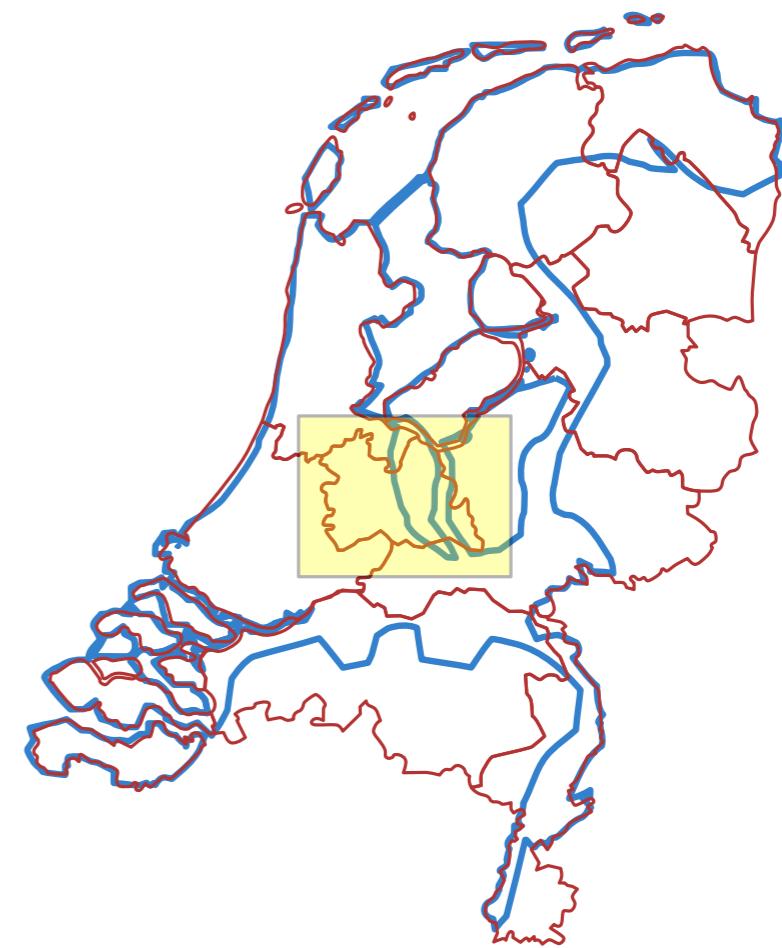
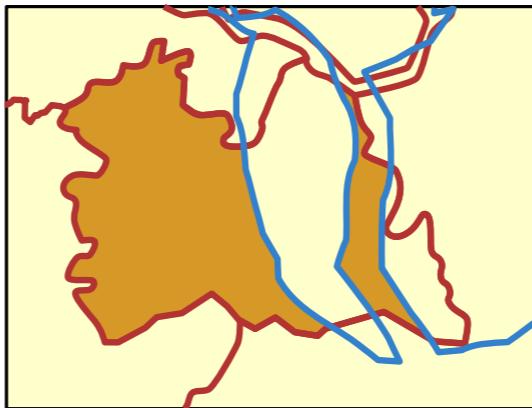
Introduction



Introduction



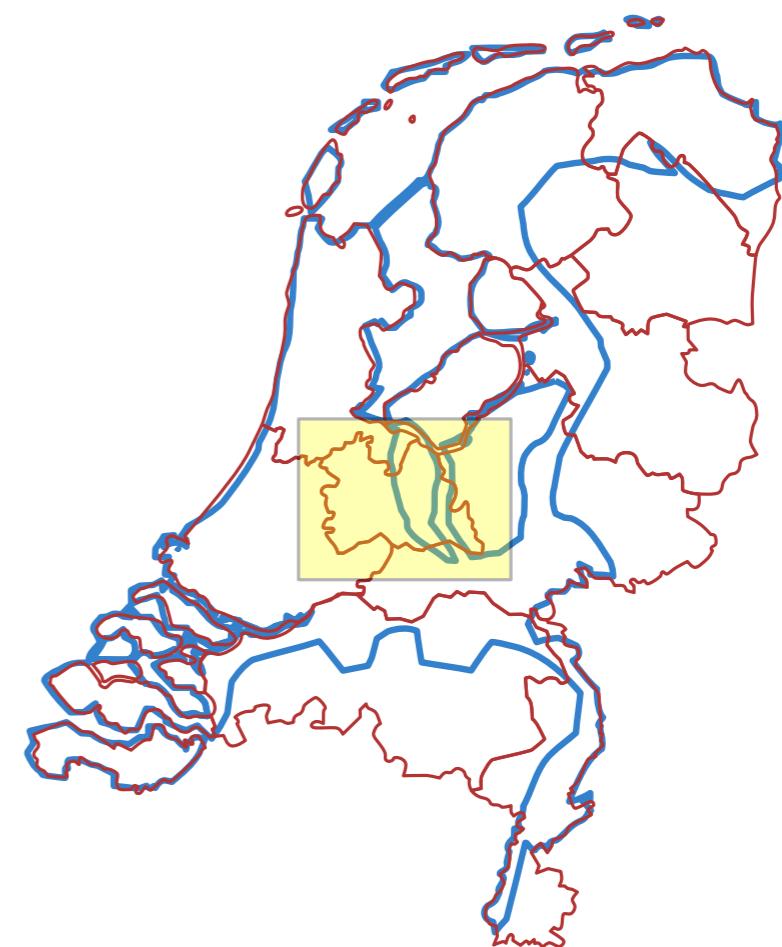
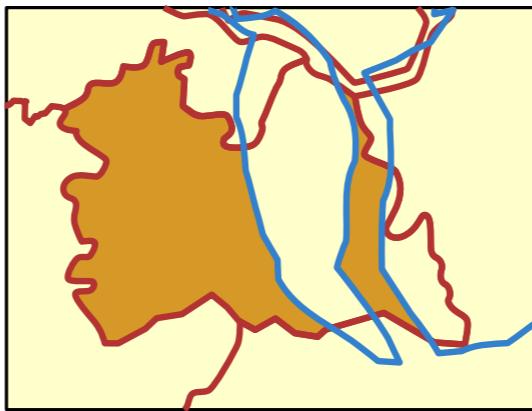
Introduction



Map Overlay

Problem:

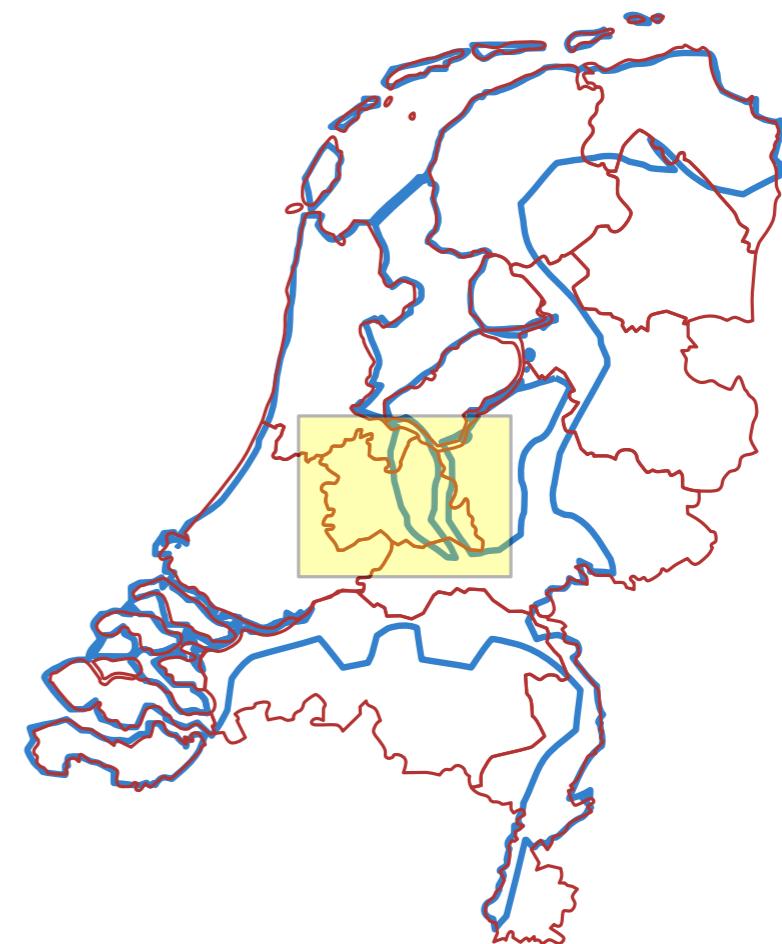
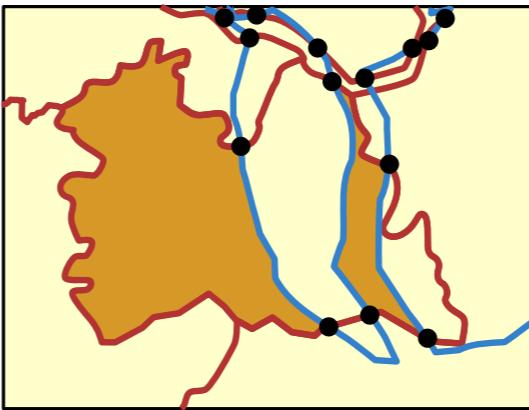
Given two maps M_1 and M_2 , compute the overlay of M_1 and M_2 .



Map Overlay

Problem:

Given two maps M_1 and M_2 , compute the overlay of M_1 and M_2 .

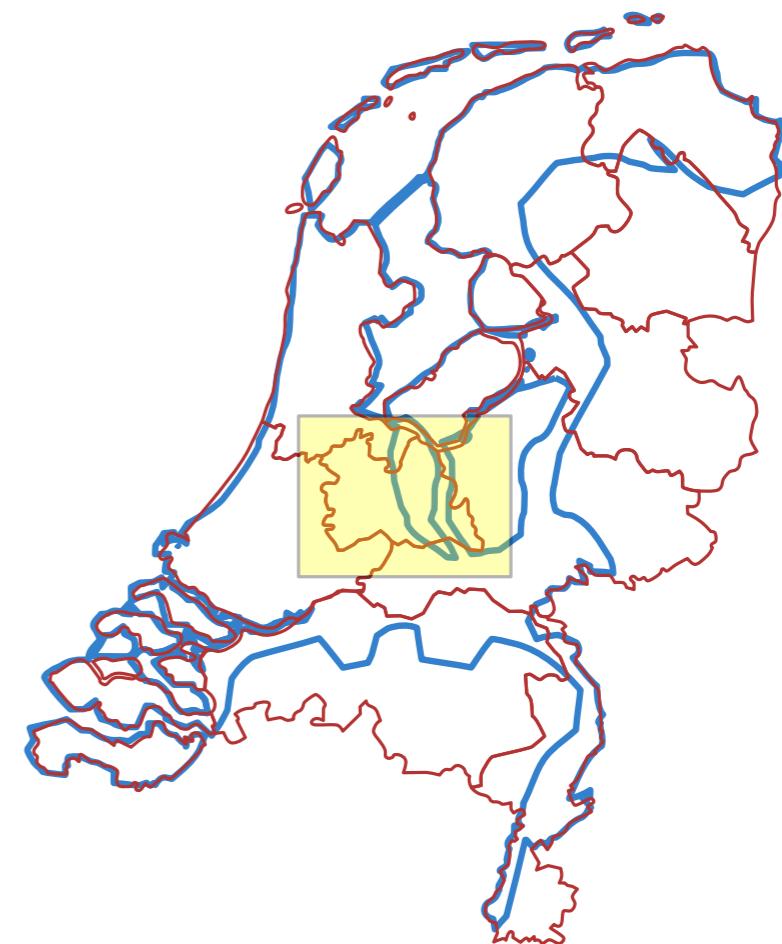
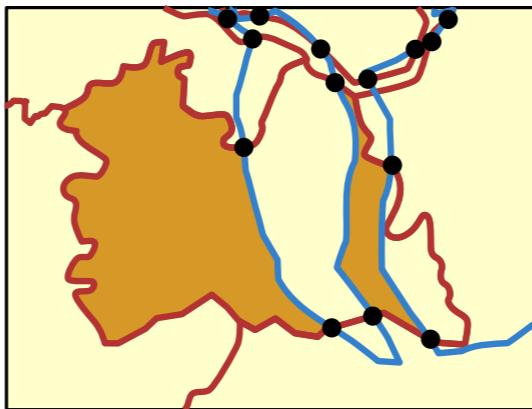


- How to compute all intersection points?

Map Overlay

Problem:

Given two maps M_1 and M_2 , compute the overlay of M_1 and M_2 .

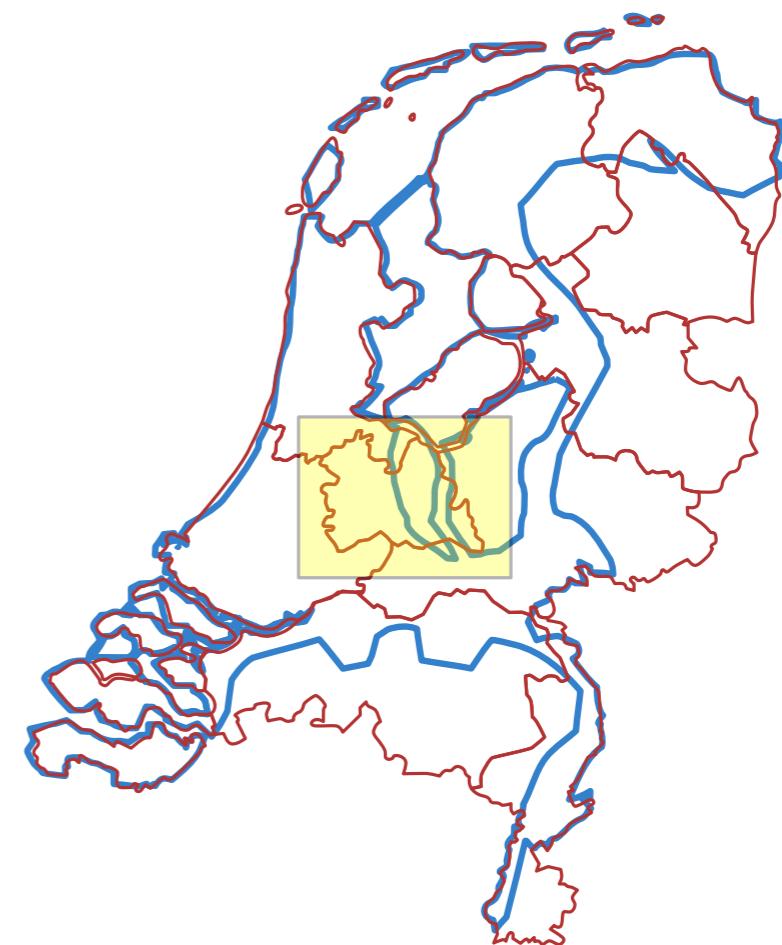
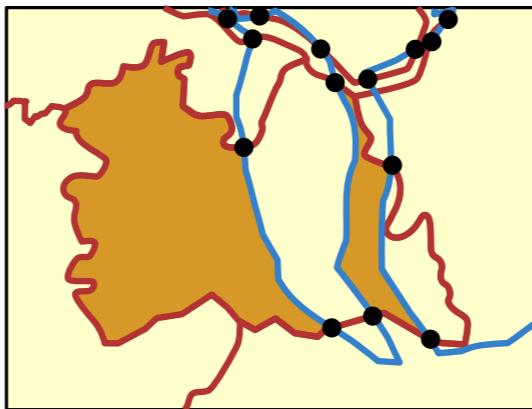


- How to compute all intersection points?
- How to represent (the overlay of) a map?

Map Overlay

Problem:

Given two maps M_1 and M_2 , compute the overlay of M_1 and M_2 .



- How to compute all intersection points?
- How to represent a planar subdivision?

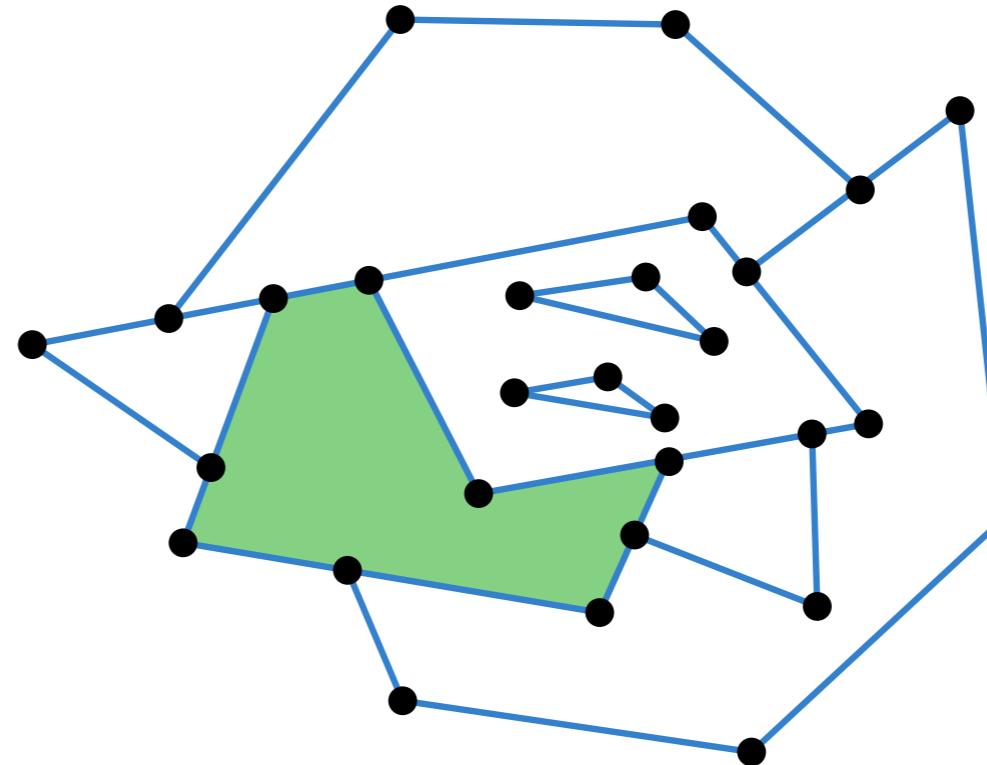
Representing a planar subdivision

A planar subdivision is an embedded planar graph, consisting of:

Vertices

Edges

Faces



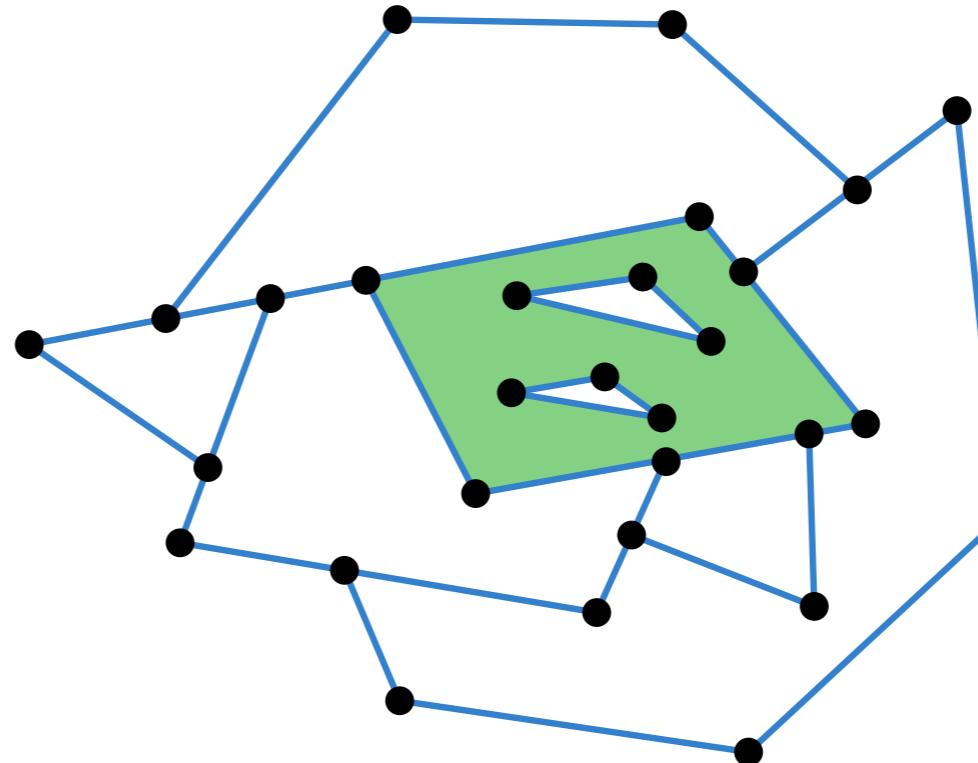
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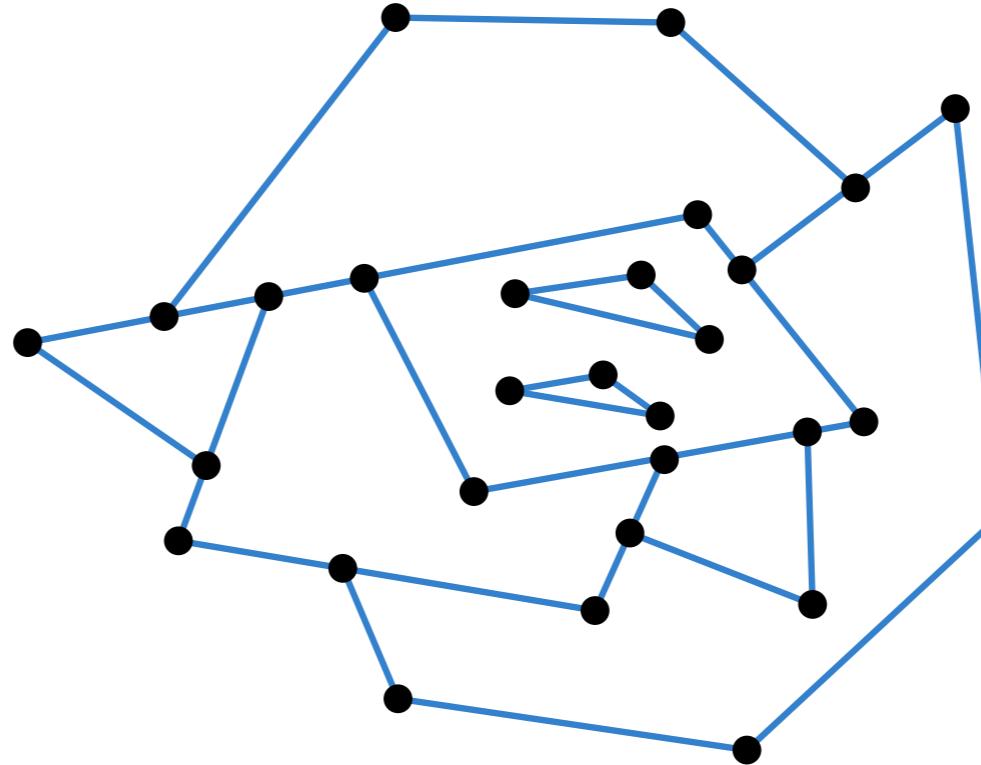
Edges

Faces



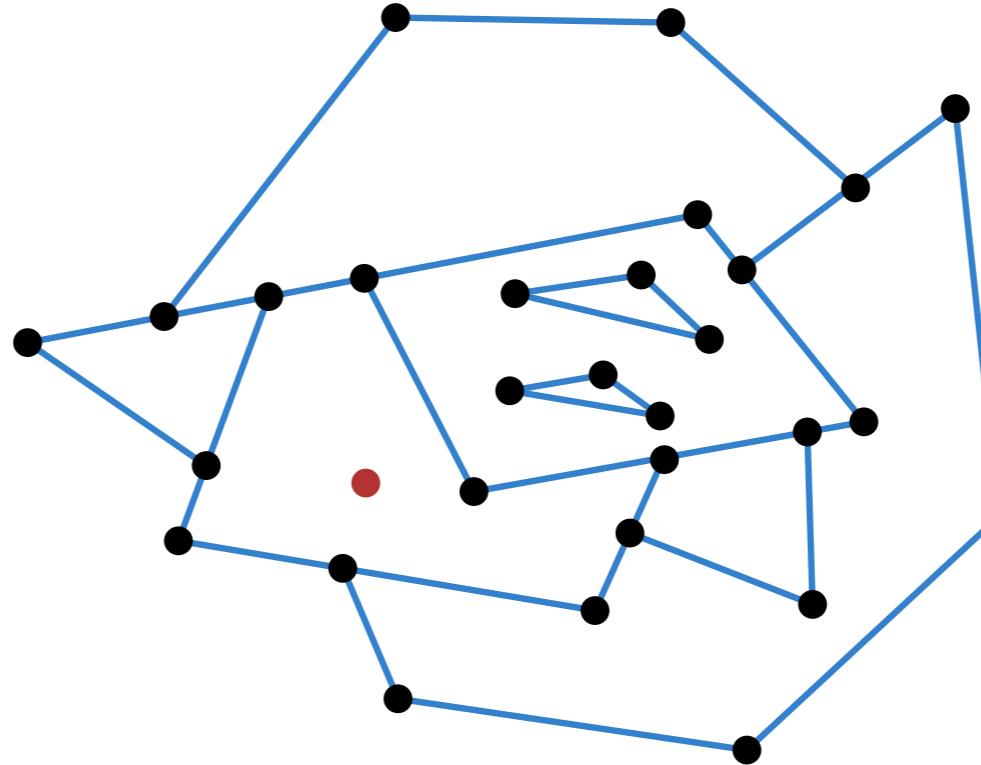
Representing a planar subdivision

What operations should are representation support?



Representing a planar subdivision

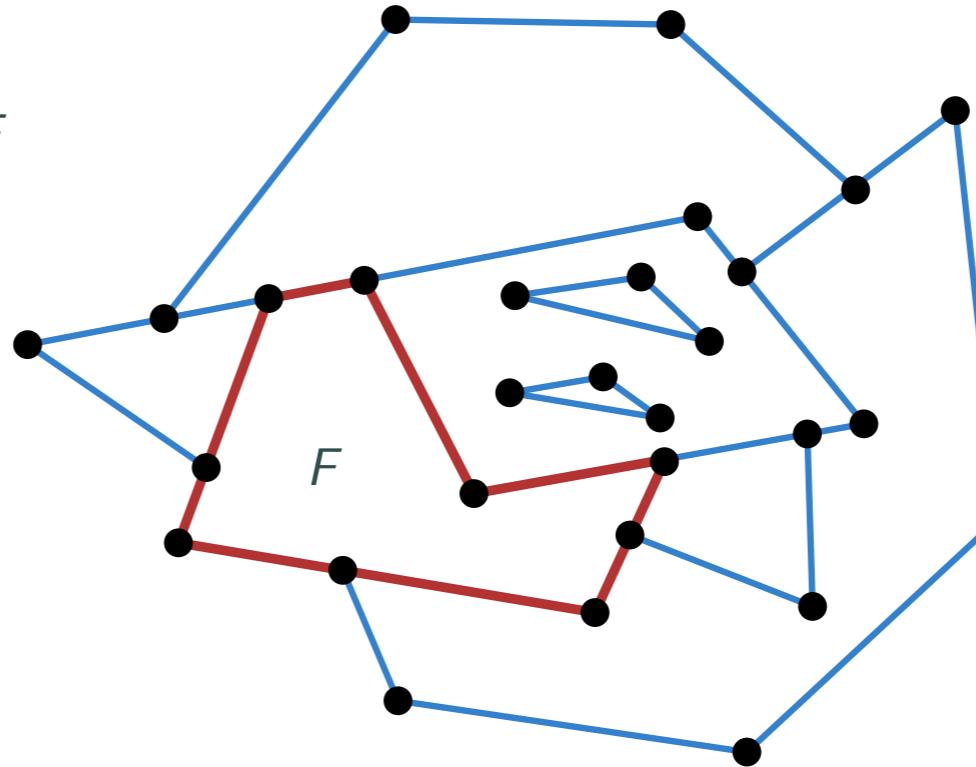
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Representing a planar subdivision

What operations should are representation support?

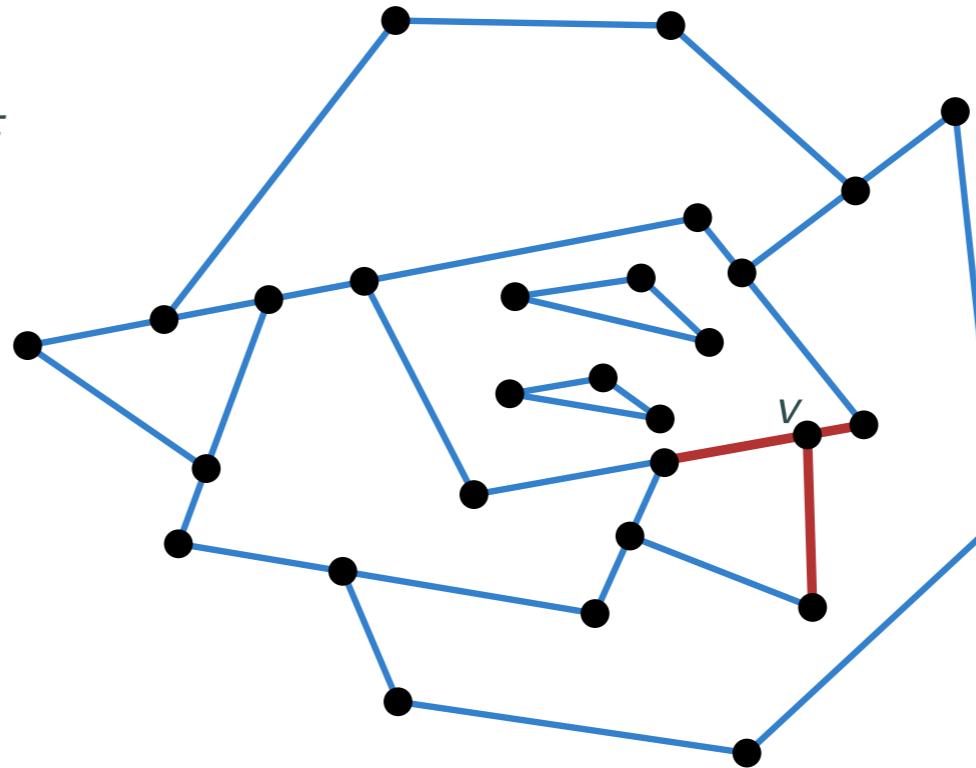
- List edges or vertices bounding a face F



Representing a planar subdivision

What operations should are representation support?

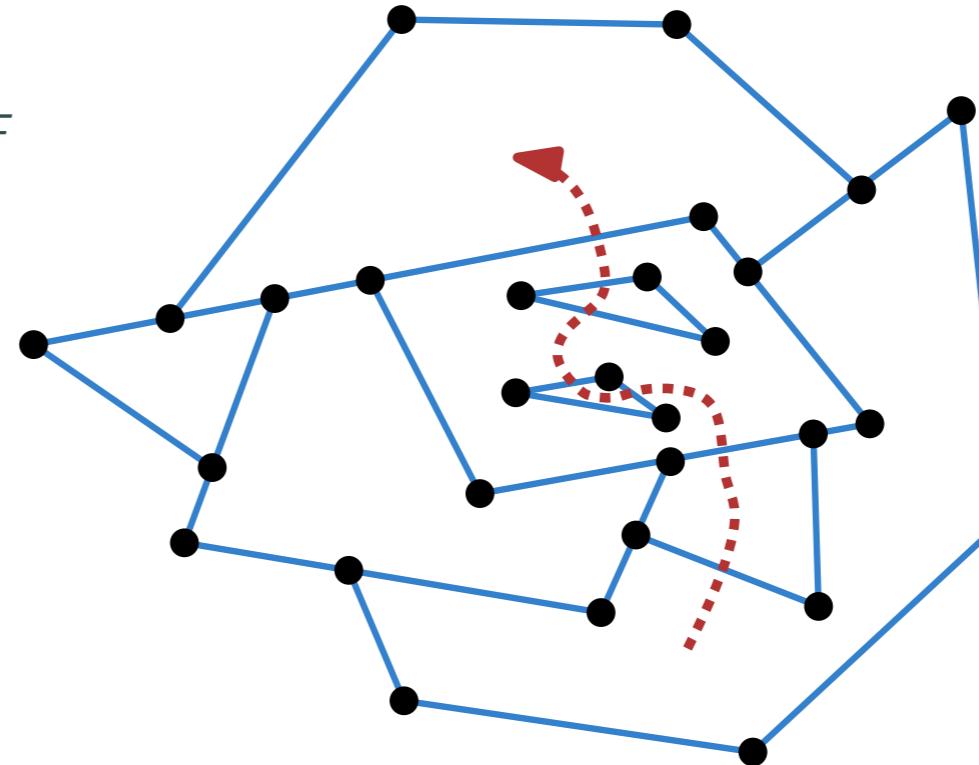
- List edges or vertices bounding a face F
- List edges incident to a vertex v



Representing a planar subdivision

What operations should a representation support?

- List edges or vertices bounding a face F
- List edges incident to a vertex v
- Efficiently "walk" in the subdivision
- ...



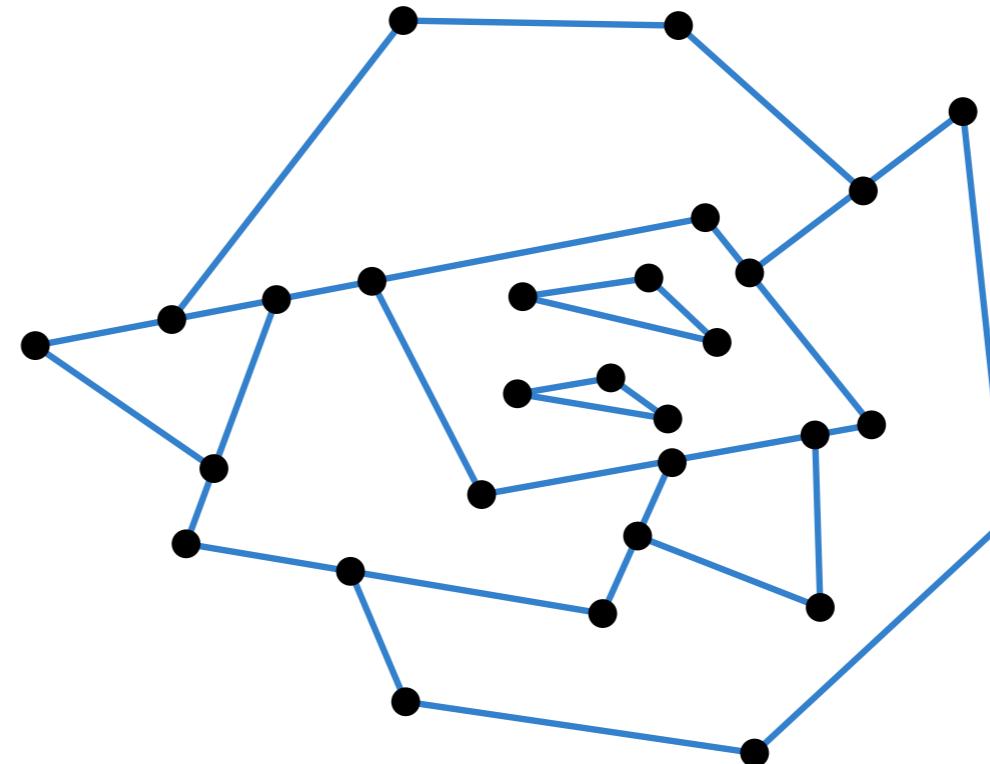
The Doubly-Connected Edge List (DCEL)

We store the planar subdivision in a
doubly-connected edge list (DCEL)

Vertices

Edges

Faces



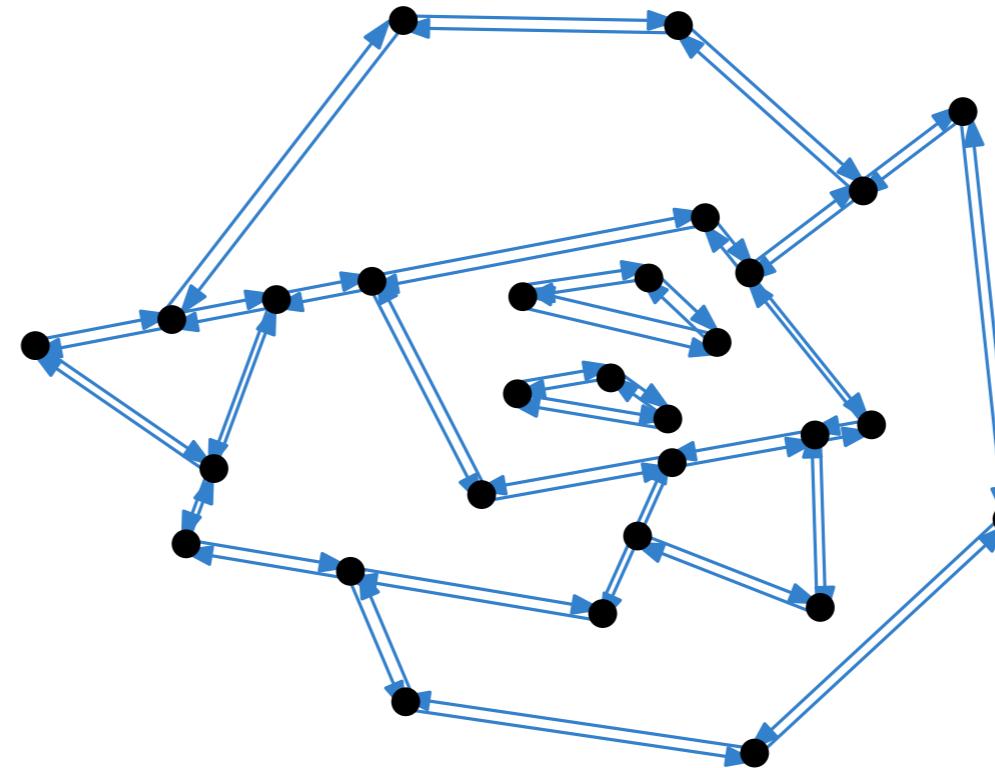
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Vertices

Half-edges

Faces



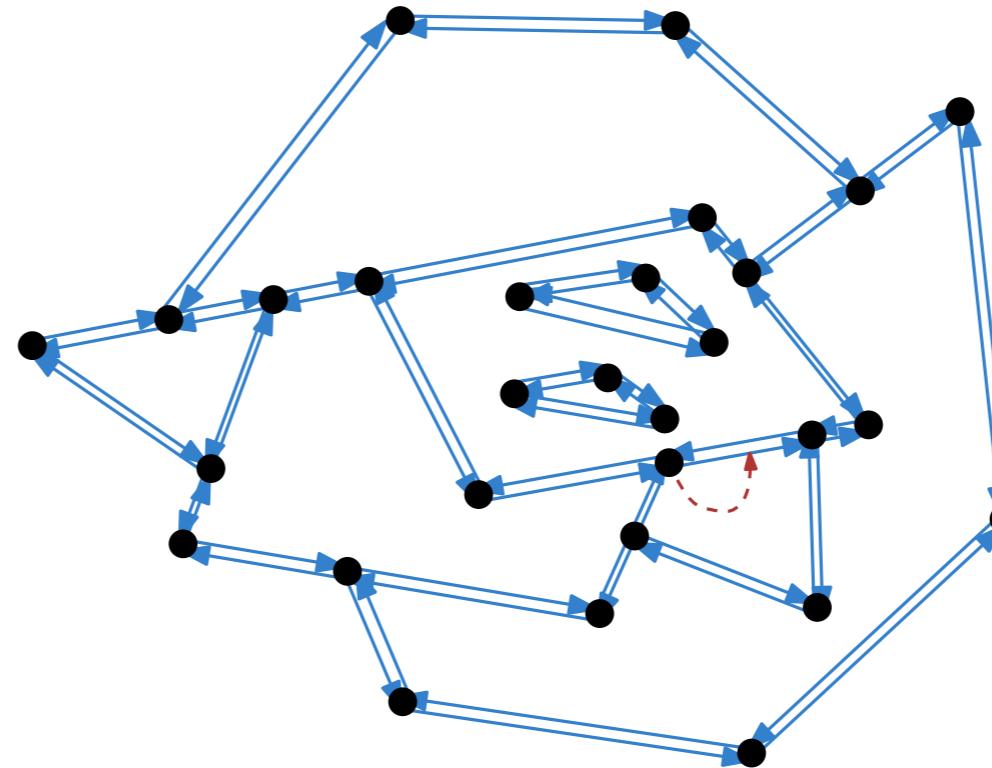
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Vertices
Coordinates
An arbitrary outgoing half-edge

Half-edges

Faces



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We store the planar subdivision in a
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Vertices

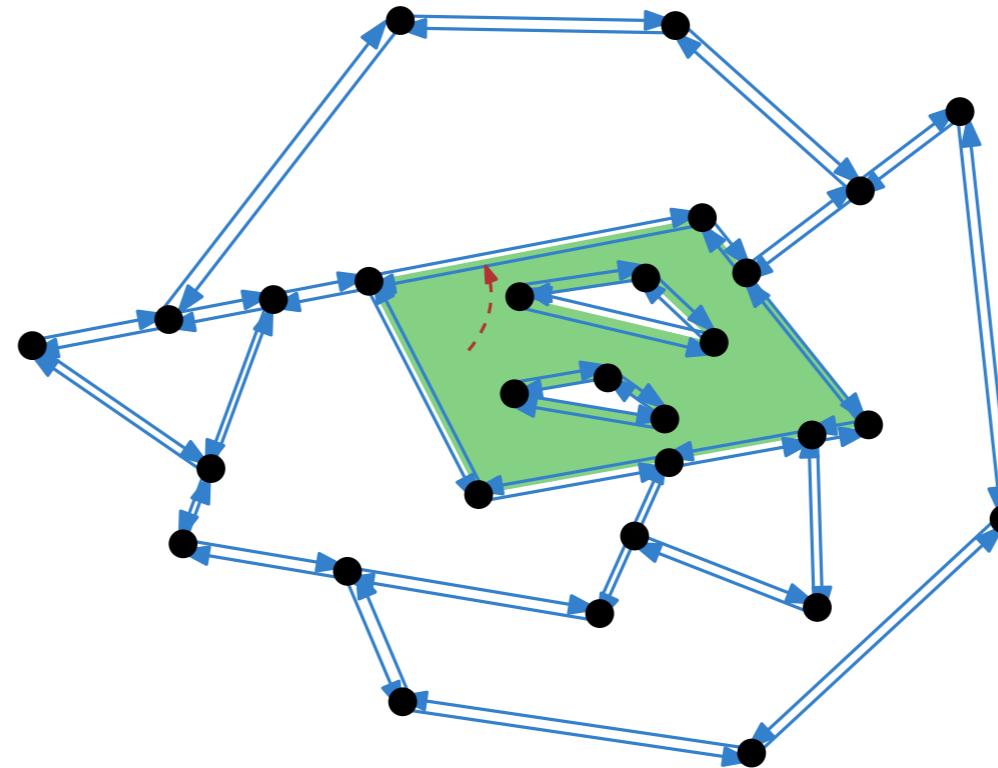
Coordinates

An arbitrary outgoing half-edge

Half-edges

Faces

An arbitrary half-edge on its outer boundary



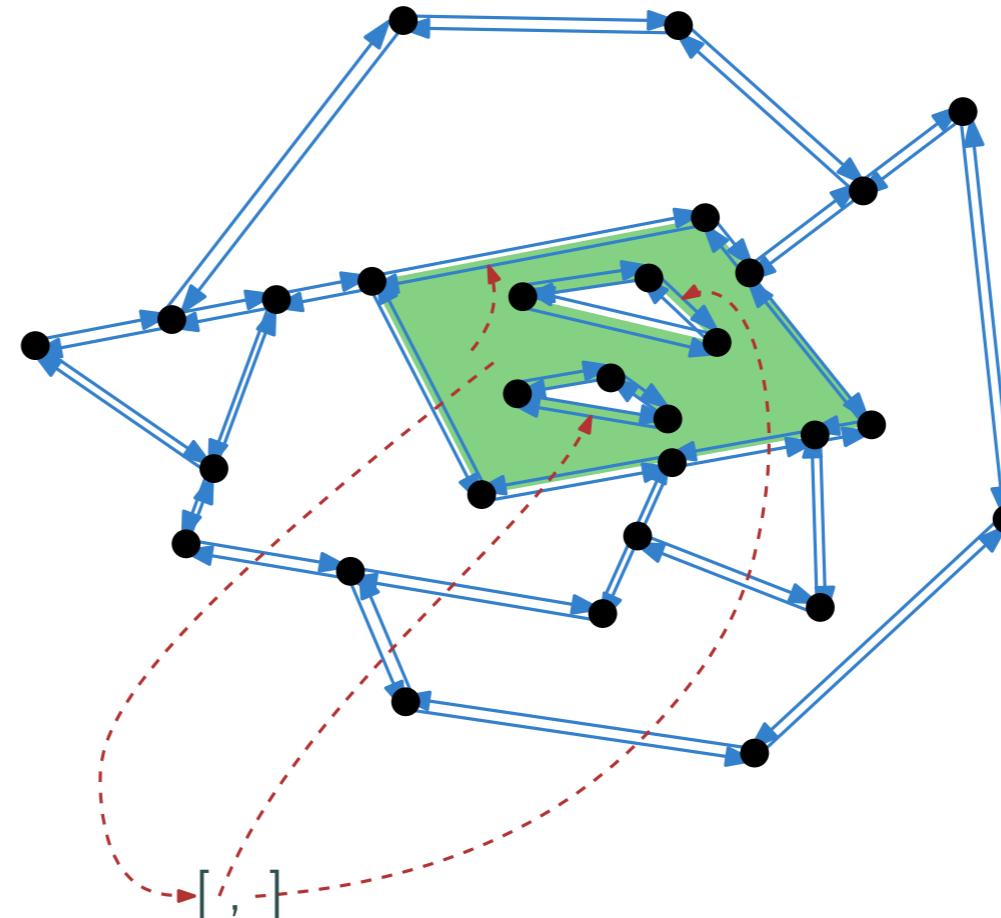
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Vertices
Coordinates
An arbitrary outgoing half-edge

Half-edges

Faces
An arbitrary half-edge on its outer boundary
A list of holes in the face;
for each hole an arbitrary half-edge.



The Doubly-Connected Edge List (DCEL)

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Vertices

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An arbitrary outgoing half-edge

Half-edges

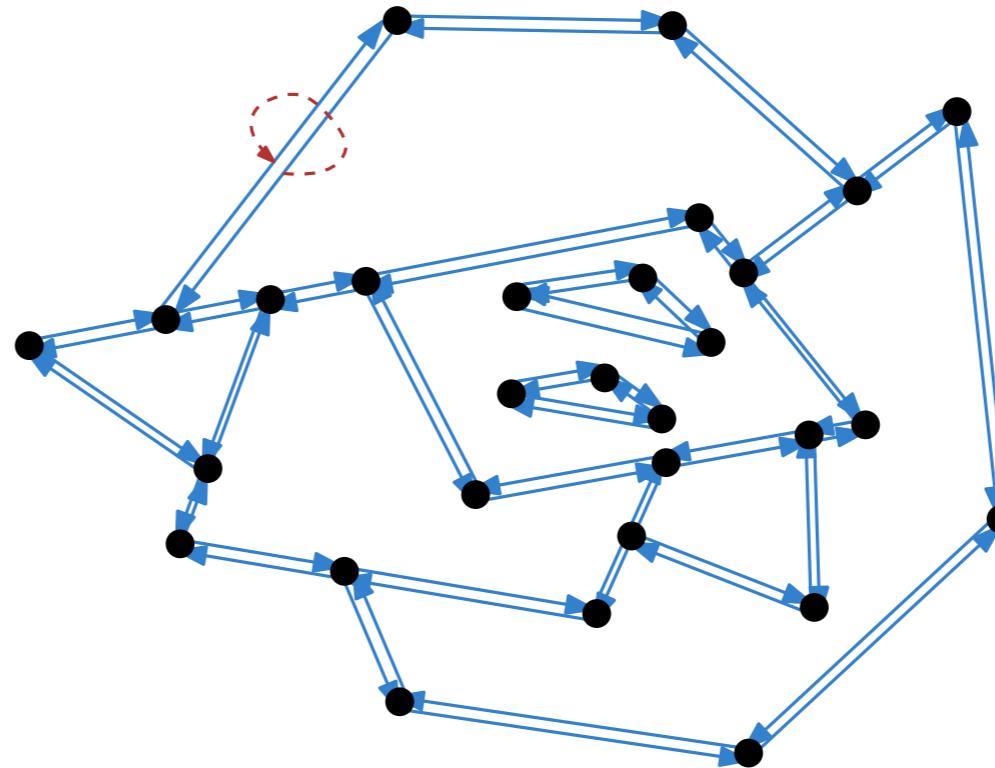
Twin

Faces

An arbitrary half-edge on its outer boundary

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An arbitrary outgoing half-edge

Half-edges

Twin

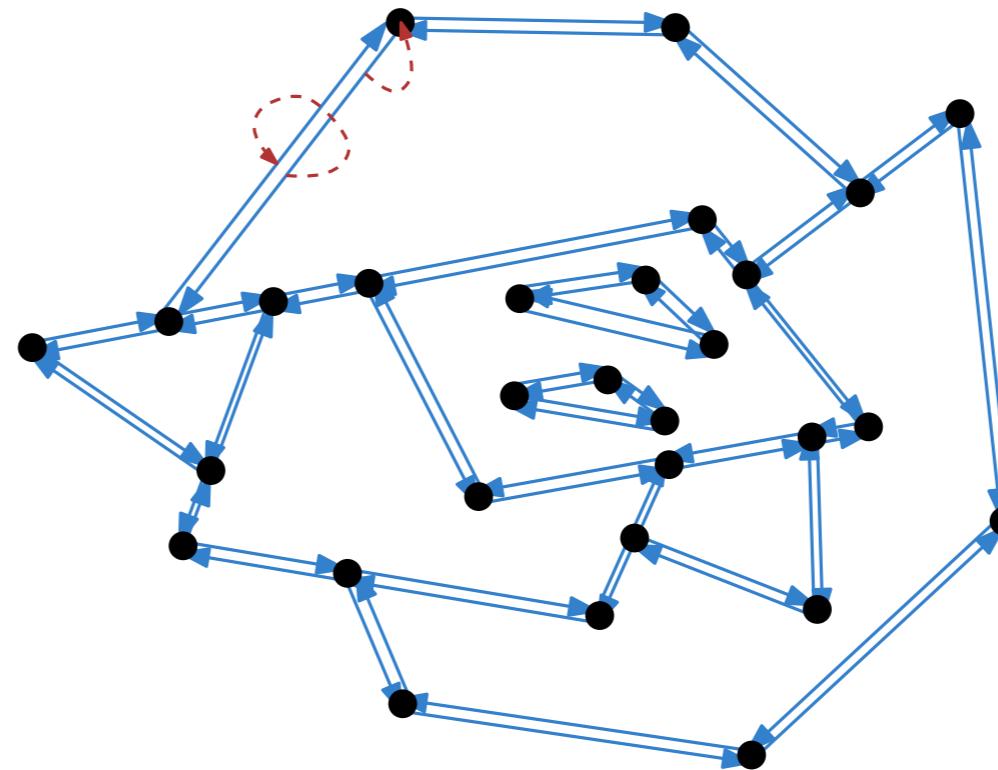
Origin

Faces

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Vertices

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An arbitrary outgoing half-edge

Half-edges

Twin

Origin

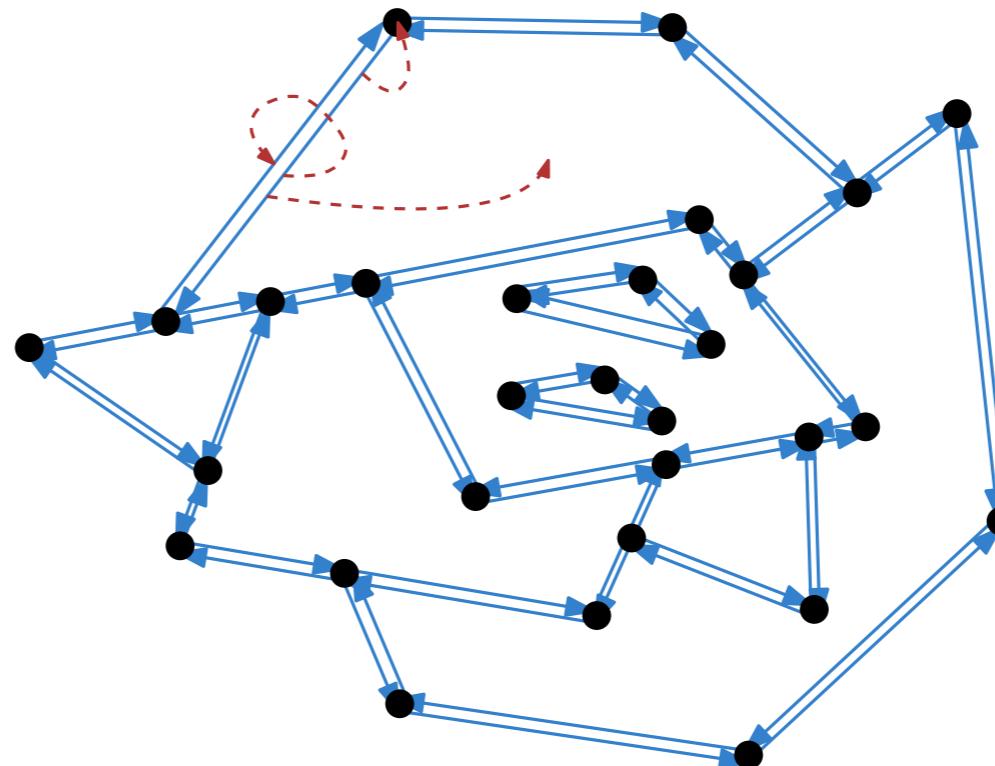
Incident face

Faces

An arbitrary half-edge on its outer boundary

A list of holes in the face;

for each hole an arbitrary half-edge.



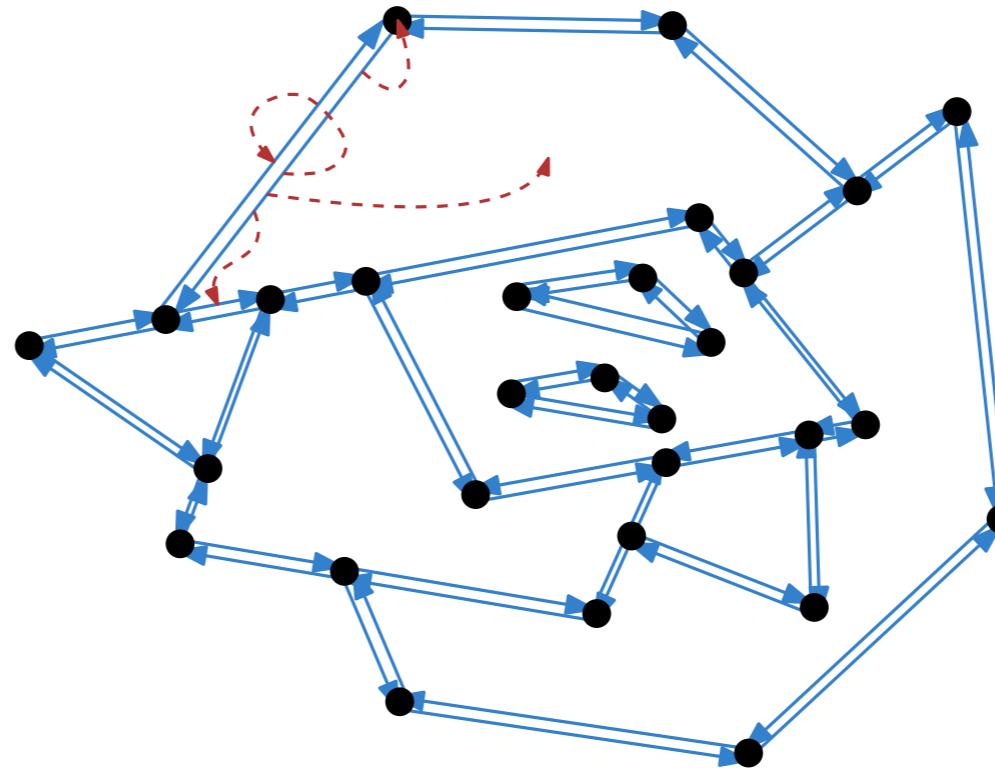
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Vertices
Coordinates
An arbitrary outgoing half-edge

Half-edges
Twin
Origin
Incident face
Next

Faces
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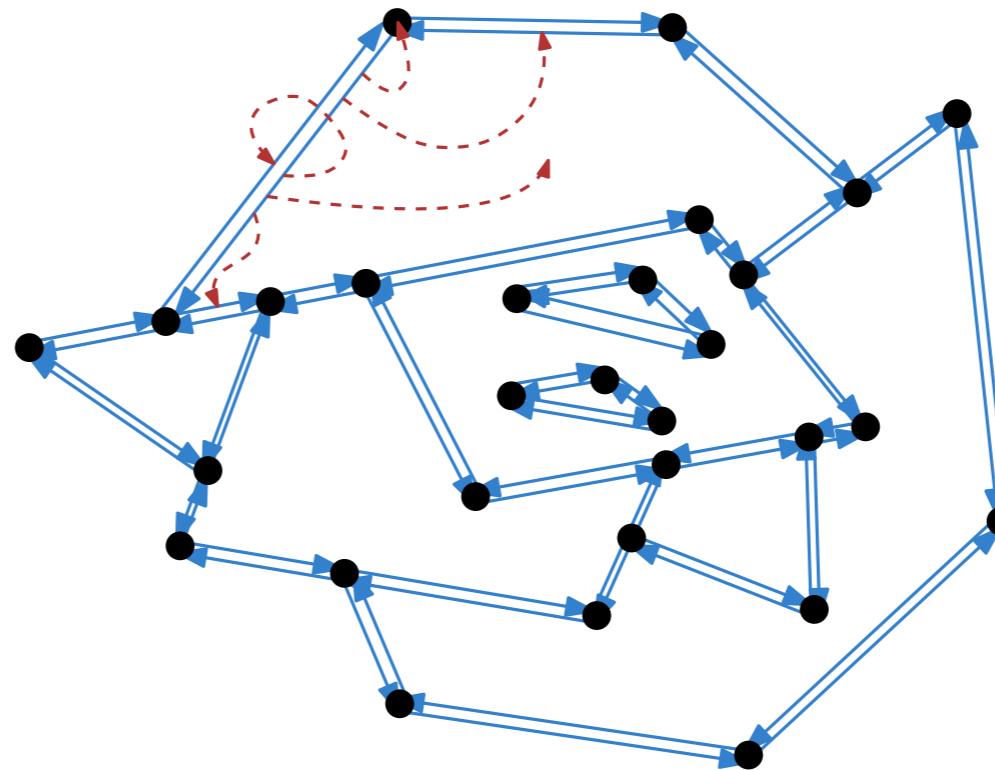
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The Doubly-Connected Edge List (DCEL)

We store the planar subdivision in a
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Vertices

Coordinates

An arbitrary outgoing half-edge

Label

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Twin

Origin

Incident face

Next

Prev

Label

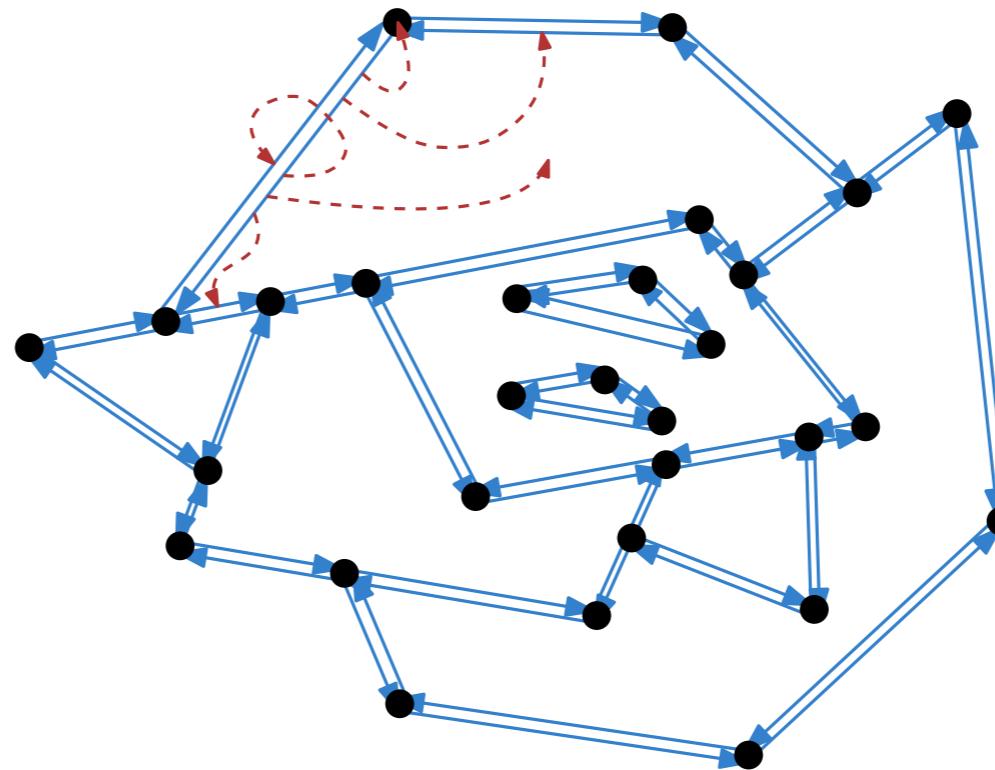
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Label



Map Overlay

Compute the overlay of M_1 and M_2 :

Use a sweep line algorithm to compute the intersection points and maintain the vertex and half-edge information above the sweep line.



Map Overlay

Compute the overlay of M_1 and M_2 :

Use a sweep line algorithm to compute the intersection points and maintain the vertex and half-edge information above the sweep line.

Use a second sweep to compute the face information.

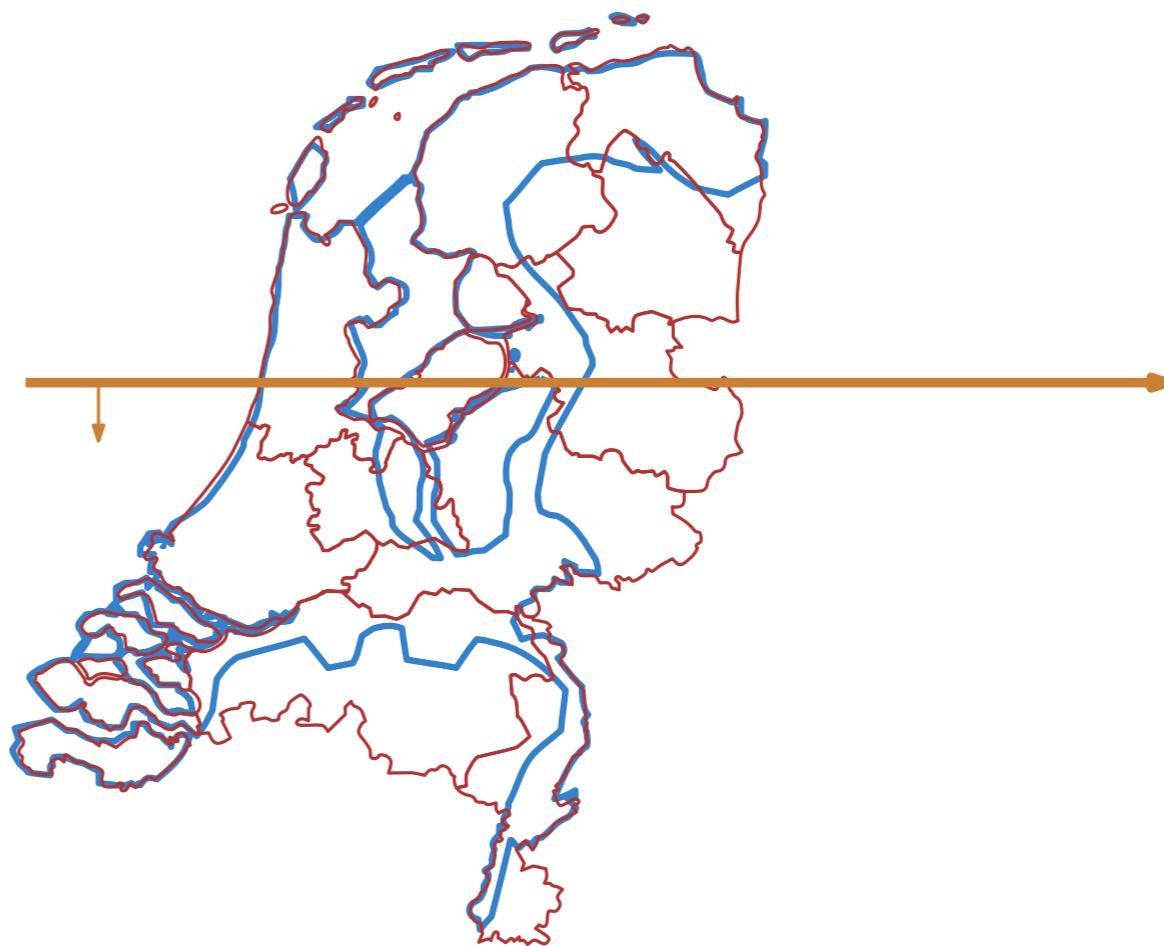


Map Overlay

Compute the overlay of M_1 and M_2 :

Use a sweep line algorithm to compute the intersection points and maintain the vertex and half-edge information above the sweep line.

Use a second sweep to compute the face information.



Theorem. We can compute the overlay of M_1 and M_2 in $O((n + k) \log n)$ time, where n is the total number of line segments in M_1 and M_2 , and k is the number of line segments in the output.