


IdleMission::on_exit



```
graph LR; A[IdleMission::on_exit] --> B[StatusMonitor::reset_gps_fix]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains the text 'IdleMission::on_exit'. The right box is white and contains the text 'StatusMonitor::reset' on the top line and '_gps_fix' on the bottom line. A blue arrow points from the right side of the gray box to the left side of the white box.

StatusMonitor::reset
_gps_fix