

DroneControl::register
_missions



```
graph LR; A[DroneControl::register_missions] --> B[NodeMachine::register_node]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is light gray with a black border and contains the text 'DroneControl::register_missions'. The right box is white with a black border and contains the text 'NodeMachine::register_node'. A dark blue arrow points from the right side of the left box to the left side of the right box.

NodeMachine::register_node