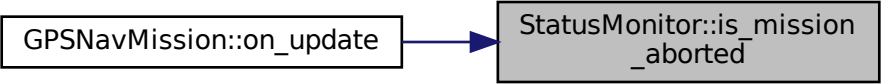


GPSNavMission::on_update



```
graph LR; A[GPSNavMission::on_update] --> B[StatusMonitor::is_mission_aborted]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is white with a black border and contains the text 'GPSNavMission::on_update'. The right box is gray with a black border and contains the text 'StatusMonitor::is_mission_aborted'. A blue arrow points from the right side of the left box to the left side of the right box.

StatusMonitor::is_mission
_aborted