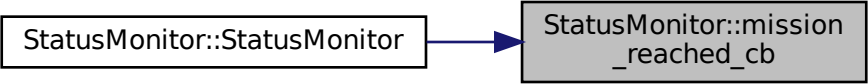


StatusMonitor::StatusMonitor



```
graph LR; A[StatusMonitor::StatusMonitor] --> B[StatusMonitor::mission_reached_cb]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is white with a black border and contains the text 'StatusMonitor::StatusMonitor'. The right box is light gray with a black border and contains the text 'StatusMonitor::mission_reached_cb' on two lines. A dark blue arrow points from the right side of the left box to the left side of the right box.

StatusMonitor::mission
_reached_cb