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LINEAR EQUATION

- A **linear equation** in the variables x_1, \dots, x_n is an equation that can be written in the form

$$a_1x_1 + a_2x_2 + \cdots + a_nx_n = b ,$$

where b and the coefficients a_1, \dots, a_n are real or complex numbers that are usually known in advance.

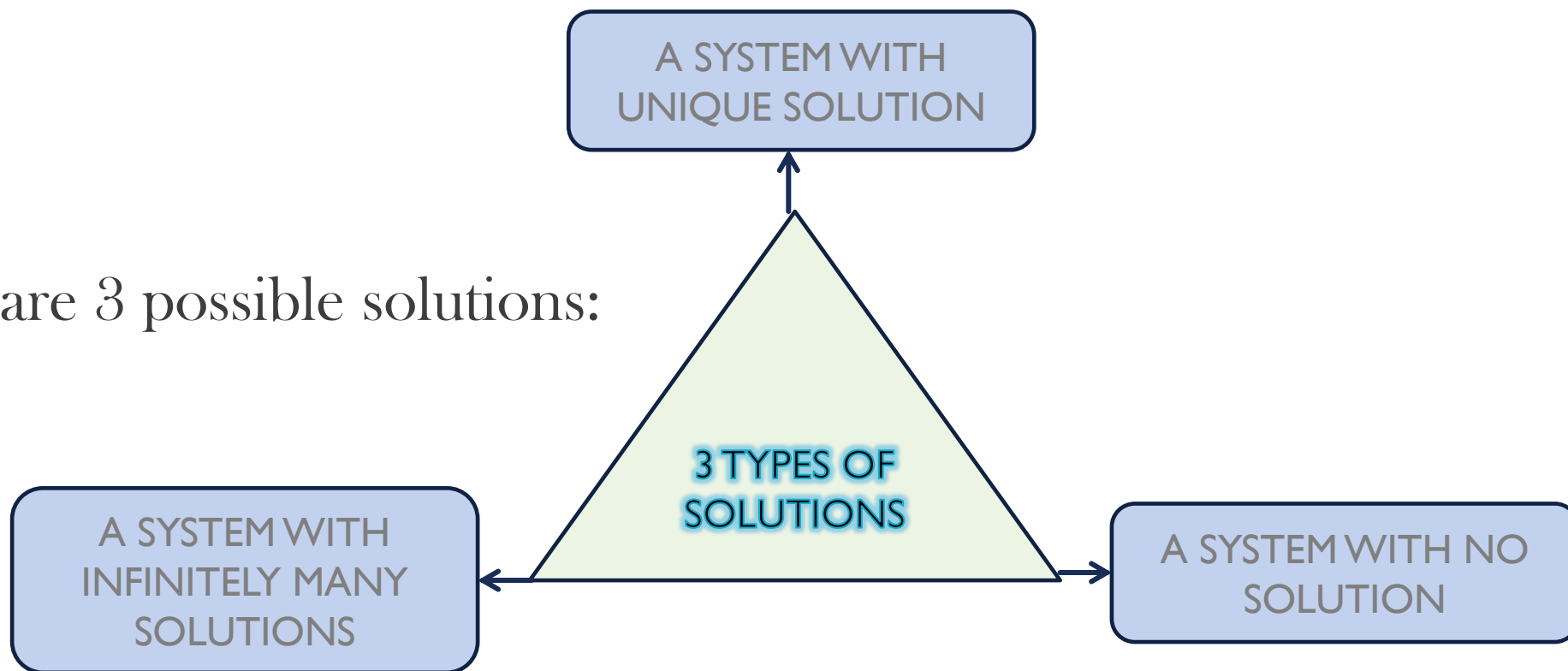
- A **system of linear equations** (or a **linear system**) is a collection of one or more linear equations involving the same variables — say, x_1, \dots, x_n .

LINEAR EQUATION

- A **solution** of the system is a list (s_1, s_2, \dots, s_n) of numbers that makes each equation a true statement when the values s_1, \dots, s_n are substituted for x_1, \dots, x_n , respectively.
- The set of all possible solutions is called the **solution set** of the linear system.
- Two linear systems are called **equivalent** if they have the same solution set.

TYPES OF SOLUTIONS TO SYSTEMS OF LINEAR EQUATIONS

There are 3 possible solutions:



A SYSTEMS WITH UNIQUE SOLUTION

Consider the system:

$$\begin{aligned}x_1 + 2x_2 &= 3 \\ 0x_1 + x_2 &= 2\end{aligned}$$

Augmented matrix:

$$\left[\begin{array}{cc|c} 1 & 2 & 3 \\ 0 & \boxed{1} & 2 \end{array} \right]$$

The system has unique solution:

$$\boxed{x_2 = 2, \quad x_1 = -1}$$

\downarrow \downarrow
 s_2 s_1

$$u_1 + 2u_2 = 3$$

$$u_1 + 2 \cdot 2 = 3$$

$$u_1 + 4 = 3$$

$$\begin{aligned}u_1 &= 3 - 4 \\ &= -1\end{aligned}$$

A SYSTEMS WITH INFINITELY MANY SOLUTION

Consider the system:

$$x_1 + 2x_2 = 3$$
$$0x_1 + 0x_2 = 0$$

$$u_1 + 2s = 3$$

$$u_1 = 3 - 2s$$

Augmented matrix:

$$\left[\begin{array}{cc|c} 1 & 2 & 3 \\ 0 & 0 & 0 \end{array} \right]$$

$$u_2 = 0$$

The system has many solutions: let $x_2 = s$, where s is called a free variable.
Then, $x_1 = 3 - 2s$,

A SYSTEMS WITH NO SOLUTION

- Consider the system:
$$\begin{aligned}x_1 + 2x_2 &= 3 \\ 0x_1 + 0x_2 &= 2\end{aligned}$$
- Augmented matrix:
$$\left[\begin{array}{cc|c} 1 & 2 & 3 \\ 0 & 0 & 2 \end{array} \right]$$
- The system has no solution, since coefficient of x_2 is '0'.
$$(0x_2 \neq 2)$$

SOLVING SYSTEMS OF EQUATIONS

Systems of linear equations :

$$a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1$$

$$a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2$$

$$\vdots$$

$$a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n = b_m$$

$$\left[\begin{array}{cccc|c} a_{11} & a_{12} & \dots & a_{1n} & b_1 \\ a_{21} & a_{22} & \dots & a_{2n} & b_2 \\ \vdots & \vdots & & \vdots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} & b_m \end{array} \right]$$

SOLVING SYSTEMS OF EQUATIONS

4 methods used to solve systems of equations.

- 1) The Inverse of the Coefficient Matrix
- 2) Gauss Elimination
- 3) Gauss-Jordan Elimination
- 4) Cramer's Rule



THE INVERSE OF THE COEFFICIENT MATRIX



SOLVING SYSTEMS OF EQUATIONS

Matrix Form: $AX = B$

$$A^{-1} A \cdot X = A^{-1} B$$

$$\begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix}$$

$$a_{11}x_1 + a_{12}x_2 + \cdots + a_{1n}x_n = b_1$$

$$a_{21}x_1 + a_{22}x_2 + \cdots + a_{2n}x_n = b_2$$

\vdots

$$a_{m1}x_1 + a_{m2}x_2 + \cdots + a_{mn}x_n = b_n$$

To find X : $X = A^{-1} B$

System

THE INVERSE OF THE COEFFICIENT MATRIX

Method : $X = A^{-1} B$

Example:

Solve the system by using A^{-1} , the inverse of the coefficient matrix:

$$\begin{aligned}x + y + z &= 0 \\2x - y + z &= -1 \\-x + 3y - z &= -8\end{aligned}$$

$$A = \begin{bmatrix} 1 & 1 & 1 \\ 2 & -1 & 1 \\ -1 & 3 & -1 \end{bmatrix} \quad B = \begin{bmatrix} 0 \\ -1 \\ -8 \end{bmatrix}$$

\downarrow
 $A^{-1} ?$

THE INVERSE OF THE COEFFICIENT MATRIX

Solution:

$$A = \begin{bmatrix} 1 & 1 & 1 \\ 2 & -1 & 1 \\ -1 & 3 & -1 \end{bmatrix} \quad X = \begin{bmatrix} x \\ y \\ z \end{bmatrix} \quad B = \begin{bmatrix} 0 \\ -1 \\ -8 \end{bmatrix}$$

$$AX = B:$$

$$\begin{bmatrix} 1 & 1 & 1 \\ 2 & -1 & 1 \\ -1 & 3 & -1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ -1 \\ -8 \end{bmatrix}$$

THE INVERSE OF THE COEFFICIENT MATRIX

Find A^{-1} :

$$A^{-1} = \frac{1}{|A|} \text{adj}[A]$$

Cofactor of A :

$$\begin{bmatrix} -2 & 1 & 5 \\ 4 & 0 & -4 \\ 2 & 1 & -3 \end{bmatrix}$$

Therefore:

$$\text{adj}[A] = \begin{bmatrix} -2 & 4 & 2 \\ 1 & 0 & 1 \\ 5 & -4 & -3 \end{bmatrix}, \quad |A| = 4$$

$$A = \begin{bmatrix} 1 & 1 & 1 \\ 2 & -1 & 1 \\ 4 & 3 & -1 \end{bmatrix}$$

$$|A| = a_{11} \cdot A_{11} + a_{12} \cdot A_{12} + a_{13} \cdot A_{13}$$

$$= 1 \cdot (-2) + 1 \cdot 1 + 1 \cdot 5$$

$$= -2 + 1 + 5 = 4$$

$$A_{11} = (-1)^{1+1} \begin{vmatrix} -1 & 1 \\ 3 & -1 \end{vmatrix} = (-1)^2 ((-1) \cdot (-1) - (3 \cdot 1))$$

$$= 1(1 - 3) = -2$$

$$A_{21} = (-1)^{2+1} \begin{vmatrix} 1 & 1 \\ 3 & -1 \end{vmatrix} = (-1)^3 (1 \cdot (-1) - (3 \cdot 1))$$

$$= (-1)(-1 - 3) = (-1)(-4) = 4$$

THE INVERSE OF THE COEFFICIENT MATRIX

Find X :

$$X = A^{-1}B$$

$$\begin{aligned} \begin{bmatrix} x \\ y \\ z \end{bmatrix} &= \frac{1}{4} \begin{bmatrix} -2 & 4 & 2 \\ 1 & 0 & 1 \\ 5 & -4 & -3 \end{bmatrix} \begin{bmatrix} 0 \\ -1 \\ -8 \end{bmatrix} = \frac{1}{4} \begin{bmatrix} -2 \cdot 0 + 4 \cdot (-1) + 2 \cdot (-8) \\ 1 \cdot 0 + 0 \cdot (-1) + 1 \cdot (-8) \\ 5 \cdot 0 + (-4) \cdot (-1) + (-3) \cdot (-8) \end{bmatrix} = \frac{1}{4} \begin{bmatrix} -20 \\ -8 \\ 28 \end{bmatrix} \\ &= \begin{bmatrix} -5 \\ -2 \\ 7 \end{bmatrix} \checkmark \checkmark \checkmark \quad \therefore x = -5, y = -2, z = 7 \end{aligned}$$

THE INVERSE OF THE COEFFICIENT MATRIX

Example 2:

Solve the system by using A^{-1} , the inverse of the coefficient matrix:

$$x - 3y + z = 1$$

$$2x - y + 2z = 2$$

$$x + 2y - 3z = -1$$

Answer :

$$x = \frac{1}{2}, y = 0, z = \frac{1}{2}$$



GAUSS ELIMINATION



GAUSS ELIMINATION

- Consider the systems of linear eq:

$$a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1$$

$$a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2$$

\vdots

$$a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n = b_m$$

GAUSS ELIMINATION

Write in augmented form : $[A | B]$

$$\begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} & b_1 \\ a_{21} & a_{22} & \cdots & a_{2n} & b_2 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} & b_n \end{bmatrix}$$

Using ERO (ELEMENTARY ROW OPERATION), such that A may be reduce in REF (ROW ECHELON FORM)/Upper Triangular

GAUSS ELIMINATION

Example:

Solve the system by using Gauss Elimination method:

$$x + y + z = 0$$

$$2x - y + z = -1$$

$$-x + 3y - z = -8$$

$$\left[\begin{array}{ccc|c} 1 & 1 & 1 & 0 \\ 2 & -1 & 1 & -1 \\ -1 & 3 & -1 & -8 \end{array} \right]$$

GAUSS ELIMINATION

Solution:

Write in augmented form:

$$\begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & | & 0 \\ 2 & -1 & 1 & | & -1 \\ -1 & 3 & -1 & | & -8 \end{bmatrix}$$

Reduce to REF : (Diagonal = 1)

$$\begin{aligned}
 \begin{bmatrix} x \\ y \\ z \end{bmatrix} &= \begin{bmatrix} 1 & 1 & 1 & | & 0 \\ 2 & -1 & 1 & | & -1 \\ -1 & 3 & -1 & | & -8 \end{bmatrix} \xrightarrow{H_{21}(-2)} \begin{bmatrix} 1 & 1 & 1 & | & 0 \\ 0 & -3 & -1 & | & -1 \\ 0 & 4 & 0 & | & -8 \end{bmatrix} \xrightarrow{H_{31}(1)} \begin{bmatrix} 1 & 1 & 1 & | & 0 \\ 0 & -3 & -1 & | & -1 \\ 0 & 4 & 0 & | & -8 \end{bmatrix} \xrightarrow{H_{32}(\frac{4}{3})} \begin{bmatrix} 1 & 1 & 1 & | & 0 \\ 0 & -3 & -1 & | & -1 \\ 0 & 0 & -\frac{4}{3} & | & -\frac{28}{3} \end{bmatrix} \xrightarrow{H_{2(-\frac{1}{3})}} \begin{bmatrix} 1 & 1 & 1 & | & 0 \\ 0 & 1 & \frac{1}{3} & | & \frac{1}{3} \\ 0 & 0 & -\frac{4}{3} & | & -\frac{28}{3} \end{bmatrix} \xrightarrow{H_{3(-\frac{3}{4})}} \begin{bmatrix} 1 & 1 & 1 & | & 0 \\ 0 & 1 & \frac{1}{3} & | & \frac{1}{3} \\ 0 & 0 & 1 & | & 7 \end{bmatrix}
 \end{aligned}$$

Handwritten annotations for the first three matrices:

- Red arrows and text: $1 + (-2) \cdot 1$, $(-1) + (-2) \cdot 1$, $1 + (-2) \cdot 1$, $(-1) + (-2) \cdot 1$
- Blue arrows and text: $4 + (-4)$, $0 + (-1) \cdot \frac{4}{3}$

$$\therefore \boxed{z = 7}$$

$$\boxed{y + \frac{1}{3}z = \frac{1}{3}}$$

$$y + \frac{1}{3} \cdot 7 = \frac{1}{3}$$

$$y = \frac{1}{3} - \frac{7}{3}$$

$$y = -2$$

$$\boxed{x + y + z = 0}$$

$$x - 2 + 7 = 0$$

$$x + 5 = 0$$

$$x = -5 \quad \checkmark$$

$$-8 + (-1) \cdot \left(\frac{4}{3}\right)$$



GAUSS JORDAN ELIMINATION



GAUSS JORDAN ELIMINATION

Written in augmented form : $[A \mid B]$

$$\begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix} \left| \begin{array}{c} b_1 \\ b_2 \\ \vdots \\ b_n \end{array} \right.$$

- Using ERO (ELEMENTARY ROW OPERATION), such that A may be reduce in RREF (REDUCED ROW ECHELON FORM)/IDENTITY (***DIAGONAL = 1, OTHER ENTRIES = 0***)

Reduce to RREF : (Diagonal = 1, Other entries = 0)

$$\begin{bmatrix} x \\ y \\ z \end{bmatrix} = \left[\begin{array}{ccc|c} 1 & 1 & 1 & 0 \\ 2 & -1 & 1 & -1 \\ -1 & 3 & -1 & -8 \end{array} \right] \xrightarrow{H_{21}(-2)} \left[\begin{array}{ccc|c} 1 & 1 & 1 & 0 \\ 0 & -3 & -1 & -1 \\ 0 & 4 & 0 & -8 \end{array} \right] \xrightarrow{H_{31}(1)} \left[\begin{array}{ccc|c} 1 & 1 & 1 & 0 \\ 0 & -3 & -1 & -1 \\ 0 & 4 & 0 & -8 \end{array} \right] \xrightarrow{H_{32}(\frac{4}{3})} \left[\begin{array}{ccc|c} 1 & 1 & 1 & 0 \\ 0 & -3 & -1 & -1 \\ 0 & 0 & -\frac{4}{3} & -\frac{28}{3} \end{array} \right] \xrightarrow{H_{2(-\frac{1}{3})}} \left[\begin{array}{ccc|c} 1 & 1 & 1 & 0 \\ 0 & 1 & \frac{1}{3} & \frac{1}{3} \\ 0 & 0 & -\frac{4}{3} & -\frac{28}{3} \end{array} \right] \xrightarrow{H_{3(-\frac{3}{4})}} \left[\begin{array}{ccc|c} 1 & 1 & 1 & 0 \\ 0 & 1 & \frac{1}{3} & \frac{1}{3} \\ 0 & 0 & 1 & 7 \end{array} \right]$$

$$\begin{array}{l} \xrightarrow{H_{23}(-\frac{1}{3})} \left[\begin{array}{ccc|c} 1 & 1 & 0 & -7 \\ 0 & 1 & 0 & -2 \\ 0 & 0 & 1 & 7 \end{array} \right] \xrightarrow{H_{12}(-1)} \left[\begin{array}{ccc|c} 1 & 0 & 0 & -5 \\ 0 & 1 & 0 & -2 \\ 0 & 0 & 1 & 7 \end{array} \right] \end{array}$$

$\xrightarrow{H_{13}(-1)} \left[\begin{array}{ccc|c} 1 & 0 & 0 & -5 \\ 0 & 1 & 0 & -2 \\ 0 & 0 & 1 & 7 \end{array} \right]$

$1 + (-1) \cdot 1 = 0$
 $-7 + (-1)(-2) = -5$
 $1 + (-1) \cdot 1$
 $0 + (-1) \cdot 7$
 $z = 7$
 $y = -2$
 $x = -5$

Example 2:

Solve the system by Gauss elimination and Gauss Jordan Elimination.

$$x - 3y + z = 1$$

$$2x - y + 2z = 2$$

$$x + 2y - 3z = -1$$

Answer : $x = \frac{1}{2}, y = 0, z = \frac{1}{2}$

GAUSS JORDAN ELIMINATION

Example 4:

Solve the system by Gauss Jordan elimination.

$$x + y + z = 4$$

$$x - y - z = 0$$

$$x - y + z = 0$$

Answer : $x = 2, y = 2, z = 0$



CRAMMER RULES



CRAMER'S RULE

Theorem 5

Cramer's Rule for 3x3 system

Given the system:

$$\begin{aligned} a_{11}x_1 + a_{12}x_2 + a_{13}x_3 &= b_1 \\ a_{21}x_1 + a_{22}x_2 + a_{23}x_3 &= b_2 \\ a_{31}x_1 + a_{32}x_2 + a_{33}x_3 &= b_3 \end{aligned}$$

with :

$$D = \begin{vmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{vmatrix} \neq 0$$

CRAMER'S RULE

If :

$$D_{x_1} = \begin{vmatrix} b_1 & a_{12} & a_{13} \\ b_2 & a_{22} & a_{23} \\ b_3 & a_{32} & a_{33} \end{vmatrix} \quad D_{x_2} = \begin{vmatrix} a_{11} & b_1 & a_{13} \\ a_{21} & b_2 & a_{23} \\ a_{31} & b_3 & a_{33} \end{vmatrix} \quad D_{x_3} = \begin{vmatrix} a_{11} & a_{12} & b_1 \\ a_{21} & a_{22} & b_2 \\ a_{31} & a_{32} & b_3 \end{vmatrix}$$

Then :

$$x = \frac{D_{x_1}}{D} \quad y = \frac{D_{x_2}}{D} \quad z = \frac{D_{x_3}}{D}$$

CRAMER'S RULE

$$D_{x_1} = \begin{vmatrix} b_1 & a_{12} & a_{13} \\ b_2 & a_{22} & a_{23} \\ b_3 & a_{32} & a_{33} \end{vmatrix} \quad D_{x_2} = \begin{vmatrix} a_{11} & b_1 & a_{13} \\ a_{21} & b_2 & a_{23} \\ a_{31} & b_3 & a_{33} \end{vmatrix} \quad D_{x_3} = \begin{vmatrix} a_{11} & a_{12} & b_1 \\ a_{21} & a_{22} & b_2 \\ a_{31} & a_{32} & b_3 \end{vmatrix}$$

Step to solve n linear inhomogeneous equations in n variables proceed as follows:

- i. Compute $|D|$, the determinant of the coefficient matrix, and, if $|D| \neq 0$, proceed to the next step.
- ii. Compute the modified coefficient determinants $|D_i|, i = 1, 2, \dots, n$ where D_i is derived from D by replacing the i -th column of D by the inhomogeneous vector B ;
- iii. The solutions x_1, x_2, \dots, x_n are given by $x_i = \frac{|D_i|}{|D|}$ for $i = 1, 2, \dots, n$.
- iv. If $|D| = 0$ the Cramer's rule cannot be applied. In such a case, either a unique solution to the system does not exist or there is no solution.

CRAMER'S RULE

Example 5:

Solve the system by using the Cramer's Rule.

$$x + y + z = 4$$

$$x - y - z = 0$$

$$x - y + z = 0$$

CRAMER'S RULE

Solution

$$A = \begin{bmatrix} 1 & 1 & 1 \\ 1 & -1 & -1 \\ 1 & -1 & 1 \end{bmatrix}$$

$$B = \begin{bmatrix} 4 \\ 0 \\ 0 \end{bmatrix}$$

$$X = \begin{bmatrix} x \\ y \\ z \end{bmatrix}$$

$$|D| = (a_{11}) \cdot A_{11} + (a_{12}) \cdot A_{12} + (a_{13}) \cdot A_{13}$$

$$(-1)^{1+1} \begin{vmatrix} -1 & -1 \\ -1 & 1 \end{vmatrix}$$

$$(-1)^{1+2} \begin{vmatrix} 1 & -1 \\ 1 & 1 \end{vmatrix}$$

$$(-1)^{1+3} \begin{vmatrix} 1 & -1 \\ 1 & -1 \end{vmatrix}$$

Determinant of A :

$$|A| = D = 1 \begin{vmatrix} -1 & -1 \\ -1 & 1 \end{vmatrix} - \begin{vmatrix} 1 & -1 \\ 1 & 1 \end{vmatrix} + \begin{vmatrix} 1 & -1 \\ 1 & -1 \end{vmatrix} = -4$$

$-1 - (-1) = -2$ $-(1 - (-1)) = -2$ $-1 - (-1) = 0$

CRAMER'S RULE

$$D_x = \begin{vmatrix} 4 & 1 & 1 \\ 0 & -1 & -1 \\ 0 & -1 & 1 \end{vmatrix} = 4 \begin{vmatrix} -1 & -1 \\ -1 & 1 \end{vmatrix} = -8 \rightarrow x = \frac{-8}{-4} = 2$$

$$D_y = \begin{vmatrix} 1 & 4 & 1 \\ \underline{1} & 0 & \underline{-1} \\ \underline{1} & 0 & \underline{1} \end{vmatrix} = -4 \begin{vmatrix} 1 & -1 \\ 1 & 1 \end{vmatrix} = -8 \rightarrow y = \frac{-8}{-4} = 2$$

$$D_z = \begin{vmatrix} 1 & 1 & 4 \\ 1 & -1 & 0 \\ 1 & -1 & 0 \end{vmatrix} = 4 \begin{vmatrix} 1 & -1 \\ 1 & -1 \end{vmatrix} = 0 \rightarrow z = \frac{0}{-4} = 0$$

CRAMER'S RULE

Example 6:

Solve the system by using Cramer's Rule. $x + 2y = z - 1$

$$x = 4 + y - z$$

$$x + y - 3z = -2$$

Answer :

$$x = 2, y = -1, z = 1$$