

## Background

Dataset  $y_i \in \{\pm 1\}, x_i \in \mathbb{R}^d, i = 1, \dots, n, d > n$

Empirical risk  $\hat{L}(w) = \frac{1}{n} \sum_{i=1}^n \ln(1 + \exp(-y_i x_i^\top w))$   
 overparameterization  $\Rightarrow$  linear separability

Gradient descent  $w_{t+1} = w_t - \eta \nabla \hat{L}(w_t), w_0 = 0$

## Asymptotic implicit bias

max-margin direction  $\tilde{w} = \arg \max_{\|w\|=1} \min_i y_i x_i^\top w$

[Soudry et al, 2018; Ji & Telgarsky, 2018]

If  $\eta = \Theta(1)$ , then as  $t \rightarrow \infty$ ,

$$\|w_t\| \rightarrow \infty, \quad \frac{w_t}{\|w_t\|} \rightarrow \tilde{w}$$

max-margin is not the full story

## Data model

[Population distribution] For  $\text{tr}(\Sigma) \lesssim 1$  and  $\|w^*\|_\Sigma \lesssim 1$ ,

$$x \sim \mathcal{N}(0, \Sigma) \quad \Pr(y = 1 | x) = s(x^\top w^*)$$

Logistic risk  $L(w) = \mathbb{E} \ln(1 + \exp(-yx^\top w))$

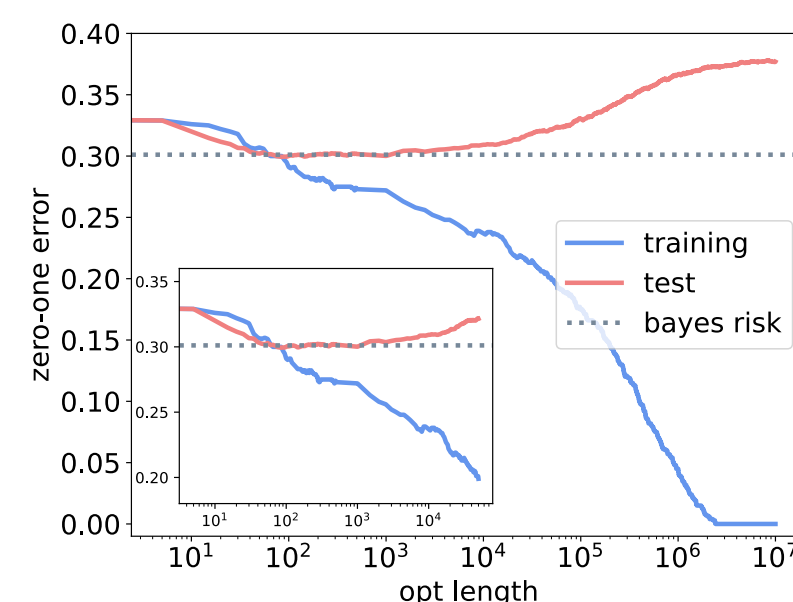
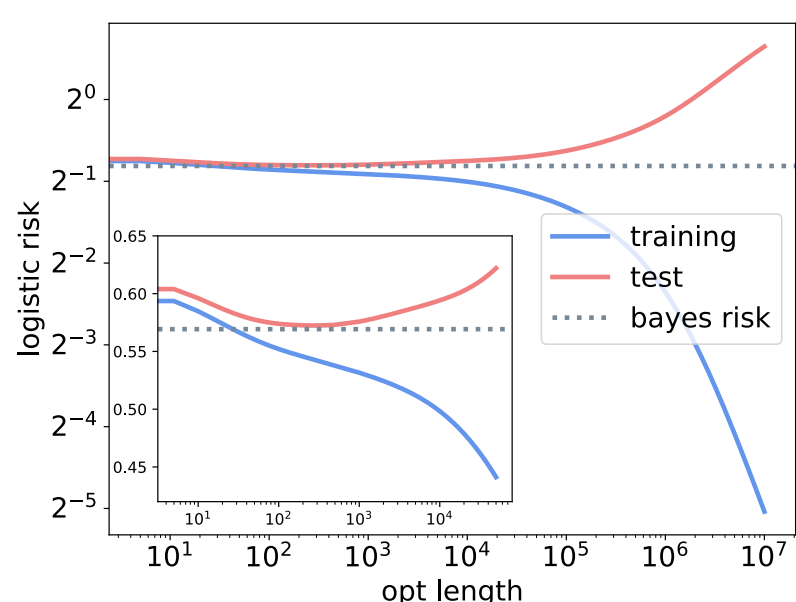
Zero-one risk  $Z(w) = \Pr(yx^\top w \leq 0)$

Calibration risk  $C(w) = \mathbb{E} |s(x^\top w) - \Pr(y = 1 | x)|^2$

[Consistency & calibration] An estimator  $w_n$  is

• logistic or 0-1 consistent if  $L(w_n) \rightarrow \min L$  or  $Z(w_n) \rightarrow \min Z$

• calibrated if  $C(w_n) \rightarrow 0$



[Simulations]  $d = 2000, n = 1000, \Sigma_{ii} = i^{-2}, w_{0:100}^* = 1, w_{100:d}^* = 0$

## Early-stopped GD

[Basic facts]

•  $w^*$  minimizes  $L, Z$ , and  $C$

•  $Z(w) - \min Z \leq 2\sqrt{C(w)} \leq \sqrt{2}\sqrt{L(w) - \min L}$

•  $\min L \gtrsim 1$  and  $\min Z \gtrsim 1$   $\leftarrow \Theta(1)$  noise  $\Rightarrow$  overfitting

logistic consistent  $\Rightarrow$  calibration  
 $\Rightarrow$  zero-one consistent

## Risk bounds

[Theorem] Let  $\eta \lesssim 1$  so GD is stable. Pick a stopping time  $t$

$$t(w^*, \Sigma, k_n) \rightarrow \hat{L}(w_t) \leq \hat{L}(w_{0:k}^*) \leq \hat{L}(w_{t-1})$$

Then with high probability

$$L(w_t) - \min L \lesssim \tilde{O}(1) \sqrt{\frac{\|w_{0:k}^*\|^2}{n} + \|w_{k:\infty}^*\|_\Sigma^2}$$

"best" rank- $k$  projection

[Examples] (rates are improvable)

• Finite norm:  $\|w^*\| \lesssim 1$

$$L(w_t) - \min L \leq \tilde{O}(n^{-1/2})$$

• Power laws:  $\lambda_i = i^{-a}, \lambda_i(w_i^*)^2 = i^{-b}, a, b > 1$

$$L(w_t) - \min L \leq \begin{cases} \tilde{O}(n^{-1/2}) & b > a + 1 \\ \tilde{O}(n^{\frac{1-b}{a+b-1}}) & b \leq a + 1 \end{cases}$$

GD passes through  $w^*$   
 but eventually diverges from it

## Key ideas

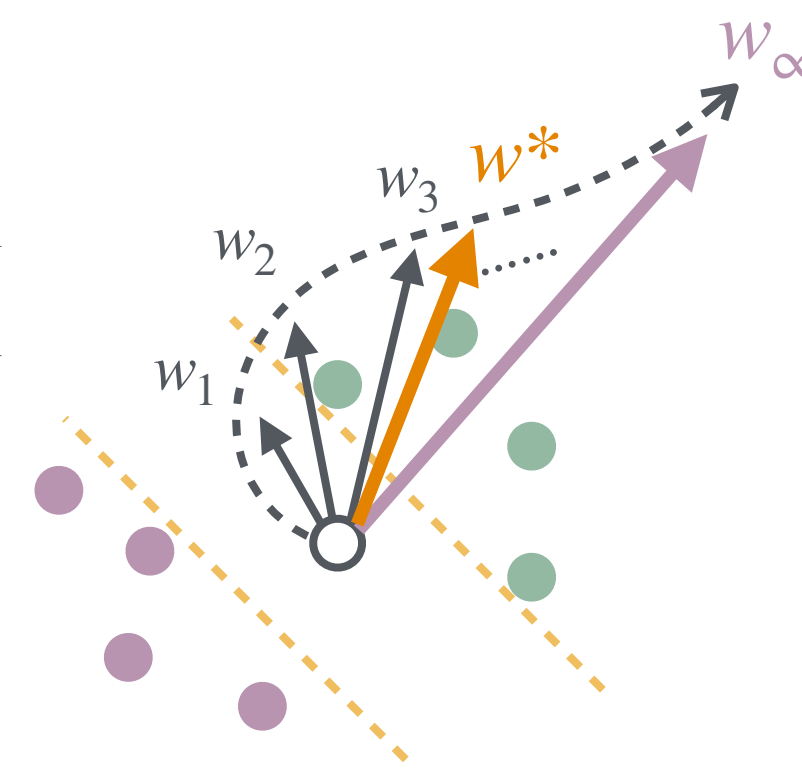
[Lemma (known)] For all convex-smooth  $\hat{L}$  and small  $\eta$ , we have

$$\forall u, t, \quad \frac{\|w_t - u\|^2}{2\eta t} + \hat{L}(w_t) \leq \hat{L}(u) + \frac{\|u\|^2}{2\eta t}$$

$$\hat{L}(w_t) \leq \hat{L}(u) \leq \hat{L}(w_{t-1})$$

(local) Rademacher complexity

$$\hat{L}(w_t) \leq \hat{L}(u) \quad \|w_{t-1} - u\| \leq \|u\|$$



## Interpolating estimators

### Issue of divergent norm

[Theorem] For all  $(w_t)_{t>0}$  such that

$$\lim \|w_t\| = \infty, \quad \lim \frac{w_t}{\|w_t\|} \text{ exists}$$

apply to GD when overparameterized

we have

inconsistent

poorly calibrated

$$L(w_\infty) = \infty, \quad C(w_\infty) \gtrsim 1$$

### Issue of interpolation

[Theorem] Assume that  $\|w^*\|_\Sigma \approx 1$  and  $\Sigma^{1/2}w^*$  is  $k$ -sparse. If

$$\min_i y_i x_i^\top \hat{w} > 0 \quad n \gtrsim k \ln k, \quad \text{rank}(\Sigma) \approx n \ln n$$

then for every interpolator  $\hat{w}$ , with high probability

$$Z(\hat{w}) - \min Z \gtrsim \frac{1}{\sqrt{\ln n}}$$

poly( $1/n$ ) for early stopping in "simple problems"

## Early stopping and $\ell_2$ -regularization

$$u_\lambda = \arg \min \hat{L}(u) + \frac{1}{2\lambda} \|u\|^2$$

[Theorem] For all convex-smooth  $\hat{L}$ , small  $\eta$ , and all  $t > 0$ ,

$$\|w_t - u_\lambda\| \leq \frac{1}{\sqrt{2}} \|w_t\| \quad \text{for } \lambda = \eta t$$

global, but relative

$$\text{As a result: } \angle(w_t, u_\lambda) \leq \frac{\pi}{4}, \quad 0.585 < \frac{\|w_t\|}{\|u_\lambda\|} < 3.415$$

[Theorem] For logistic regression

• If  $\text{rank}\{\text{support vectors}\} = \text{rank}\{\text{data}\}$ , then

$$\|w_t\|, \|u_\lambda\| \rightarrow \infty$$

$$\lambda \neq \eta t \rightarrow \exists \lambda(t) \rightarrow \infty, \quad \|w_t - u_\lambda\| \rightarrow 0$$

• For dataset  $x_1 = (\gamma, 0), x_2 = (\gamma, \gamma_2), y_1 = y_2 = 1$ , with  $0 < \gamma_2 < \gamma < 1$ , which violates the above condition, we have

$$\forall \lambda(t), \quad \|w_t - u_\lambda\| \gtrsim \ln \ln \|w_t\| \rightarrow \infty$$