### Finite-Sample Analysis of Learning High-Dimensional Single ReLU Neuron

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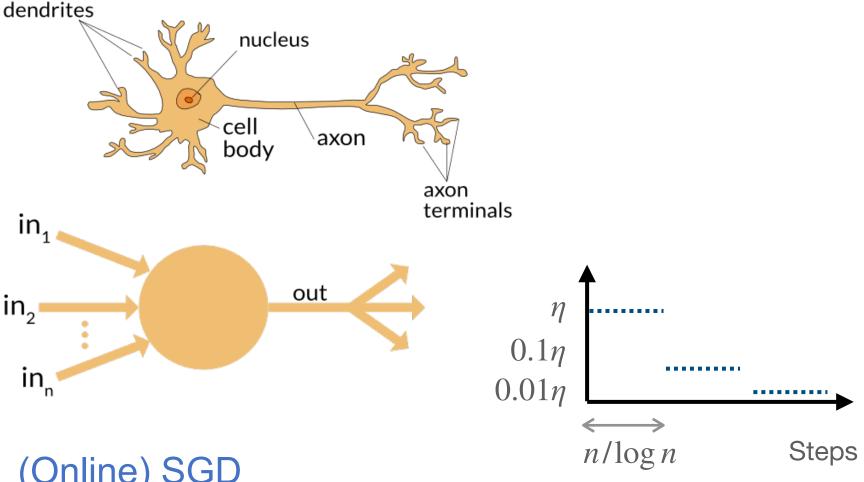
#### **ReLU Regression**

if removed => linear regression

$$Minimize R(\mathbf{w}) = \mathbb{E}\left(\widetilde{ReLU}(\mathbf{x}^{\mathsf{T}}\mathbf{w}) - y\right)^{2}, \quad \mathbf{w} \in \mathbb{R}^{d}$$

With n samples (iid):  $(\mathbf{x}_1, y_1), \dots, (\mathbf{x}_n, y_n)$ 

overparameterization: d > n



#### (Online) SGD

$$\begin{aligned} \mathbf{w}_t &= \mathbf{w}_{t-1} - \eta_t \cdot \left( \text{ReLU}(\mathbf{x}_t^\top \mathbf{w}_{t-1}) - y_t \right) \cdot \mathbf{x}_t \cdot \mathbf{1}_{\left[\mathbf{x}_t^\top \mathbf{w}_{t-1} > 0\right]} \\ t &= 1, \dots, n \end{aligned}$$

#### (Online) GLM-tron [KKSK'11]

$$\mathbf{w}_{t} = \mathbf{w}_{t-1} - \eta_{t} \cdot \left( \text{ReLU}(\mathbf{x}_{t}^{\top} \mathbf{w}_{t-1}) - y_{t} \right) \cdot \mathbf{x}_{t}$$
$$t = 1, ..., n$$

#### Notation

$$\begin{aligned}
\mathsf{OPT} &:= \min R(\,\cdot\,) \\
\mathbf{w}^* &\in \arg\min R(\,\cdot\,)
\end{aligned}$$

 $\mathbf{H} := \mathbb{E} \mathbf{x} \mathbf{x}^{\mathsf{T}}$ , eigenvalues denoted by  $(\lambda_i)_{i \geq 1}$ 

#### **Prior Works on Linear Regression**

#### Simplified Bounds of SGD [ZWBGK'21, WZBGK'22]

SGD 
$$\mathbf{w}_t = \mathbf{w}_{t-1} - \eta_t \cdot (\mathbf{x}_t^{\mathsf{T}} \mathbf{w}_{t-1} - y_t) \cdot \mathbf{x}_t, \quad t = 1, ..., n$$

Distribution 
$$y = \mathbf{x}^{\mathsf{T}} \mathbf{w}_* + \mathcal{N}(0,1), \quad \|\mathbf{w}_*\|_2 \le 1, \quad \mathbf{x} \sim \mathcal{N}(0,\mathbf{H})$$

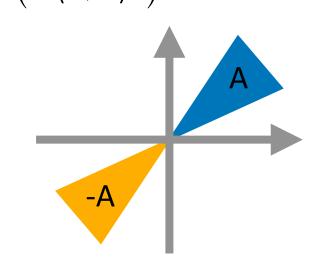
Bounds 
$$\frac{D_{\rm eff}}{N_{\rm eff}} \lesssim \mathbb{E} R(\mathbf{w}_n) - \mathrm{OPT} \lesssim \frac{D_{\rm eff}}{N_{\rm eff}}$$

#### Result 1: Well-Specified Case

#### Distributional Assumptions

- 1. Well-specified noise  $y = \text{ReLU}(\mathbf{x}^{\mathsf{T}}\mathbf{w}_*) + \mathcal{N}(0, \sigma^2)$
- 2. Hypercontractivity  $\mathbb{E}\langle \mathbf{v}, \mathbf{x} \rangle^4 \leq \alpha \big( \mathbb{E}\langle \mathbf{v}, \mathbf{x} \rangle^2 \big)^2$
- 3. Symmetric moments

$$\mathbb{E}f(\mathbf{x})\mathbf{1}[\mathbf{x} \in A] = \mathbb{E}f(\mathbf{x})\mathbf{1}[\mathbf{x} \in -A]$$
for  $f(\mathbf{x}) = \mathbf{x}^{\otimes 2}$  or  $\mathbf{x}^{\otimes 4}$ 



#### Risk Bound of GLM-tron

Suppose  $\eta_0 < 1 / (4\alpha \operatorname{tr}(\mathbf{H}))$ . Then

$$\mathbb{E}R(\mathbf{w}_n) - \text{OPT} \lesssim \left\| \prod_{t=1}^n \left( \mathbf{I} - \frac{\eta_t}{2} \cdot \mathbf{H} \right) (\mathbf{w}_0 - \mathbf{w}^*) \right\|_{\mathbf{H}}^2 + (1 + \text{SNR}) \cdot \sigma^2 \cdot \frac{D_{\text{eff}}}{N_{\text{off}}}$$

where

$$\mathtt{SNR} := \|\mathbf{w}_0 - \mathbf{w}^*\|_{\mathbf{H}}^2 / \sigma^2$$

$$N_{\text{eff}} := n / \log(n)$$

$$D_{\text{eff}} := \# \left\{ \lambda_i \geq \frac{1}{\eta_0 N_{\text{eff}}} \right\} + \eta_0^2 N_{\text{eff}}^2 \cdot \sum_{\lambda_i < \frac{1}{\eta_0 N_{\text{eff}}}} \lambda_i^2$$

#### Applications

Suppose that  $\sigma^2 \lesssim 1$ ,  $\lambda_1 \lesssim 1$ ,  $\|\mathbf{w}_0 - \mathbf{w}_*\|_2 \lesssim 1$ .

1. If  $tr(\mathbf{H}) \lesssim 1$ , then by choosing  $\eta_0 \approx 1 / \sqrt{N_{\rm eff}}$ , we have

$$\mathbb{E}R(\mathbf{w}_n) - \text{OPT} \lesssim 1 / \sqrt{N_{\text{eff}}}$$

2. If d is finite, then by choosing  $\eta_0 \approx 1$  /  $\mathrm{tr}(\mathbf{H})$ , we have

$$\mathbb{E}R(\mathbf{w}_n) - \text{OPT} \lesssim d / N_{\text{eff}}$$

- Linear reg. bounds port over to ReLU reg.
- Point-wise tight, dim-free, ...
- Recover existing bound  $\tilde{\mathcal{O}}(1/\sqrt{n})$  [KKSK'2011]
- ReLU isn't harder!

#### **Result 2: Misspecified Case**

#### **Distributional Assumptions**

- 1. Well-specified noise  $\mathbb{E}\left[\left(y \text{ReLU}(\mathbf{x}^{\mathsf{T}}\mathbf{w}_*)\right)^2 \mathbf{x} \mathbf{x}^{\mathsf{T}}\right] \leq \sigma^2 \cdot \mathbf{H}$
- 2. Hypercontractivity
- 3. Symmetric moments

#### Risk Bound of GLM-tron

Suppose  $\eta_0 < 1 / (8\alpha tr(\mathbf{H}))$ . Then

$$\begin{split} \mathbb{E}R(\mathbf{w}_n) &\lesssim \mathsf{OPT} + \left\| \prod_{t=1}^n \left( \mathbf{I} - \frac{\eta_t}{2} \cdot \mathbf{H} \right) (\mathbf{w}_0 - \mathbf{w}^*) \right\|_{\mathbf{H}}^2 \\ &+ (1 + \mathsf{SNR}) \cdot \sigma^2 \cdot \frac{D_{\mathsf{eff}}}{N_{\mathsf{eff}}} \end{split}$$

Here,  $D_{\rm eff}$  and  $N_{\rm eff}$  are as before but

$$\mathtt{SNR} := \left(\mathtt{OPT} + \|\mathbf{w}^*\|_{\mathbf{H}}^2 + \|\mathbf{w}_0 - \mathbf{w}^*\|_{\mathbf{H}}^2\right) / \sigma^2$$

#### **Applications**

Suppose that  $\sigma^2 \lesssim 1$ ,  $\lambda_1 \lesssim 1$ ,  $\|\mathbf{w}_0 - \mathbf{w}_*\|_2 \lesssim 1$ ,  $\|\mathbf{w}_*\|_2 \lesssim 1$ .

If d is finite, then by choosing  $\eta_0 \approx 1$  / tr(**H**), we have

$$\mathbb{E}R(\mathbf{w}_n) \lesssim \text{OPT} + d / N_{\text{eff}}$$

- $\mathbb{E}R(\mathbf{w}) \leq \mathsf{OPT} + o(1)$  bound is believed to be "impossible" [GKK'19]
- Previously, best known bound  $\mathcal{O}(\mathsf{OPT} + \sqrt{d/n})$  [DGKKS'20]
- A dim-free, const. factor approx.

#### Result 3: GLM-tron vs. SGD

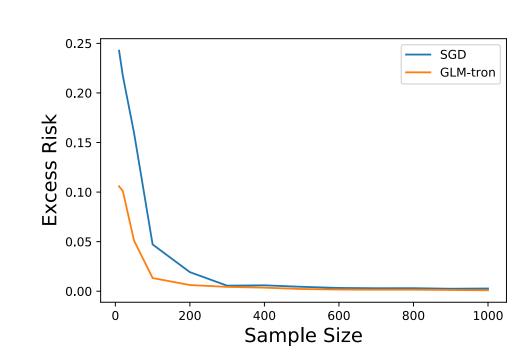
$$y = \text{ReLU}(\mathbf{x}^{\top}\mathbf{w}_*) + \mathcal{N}(0, \sigma^2), \qquad \|\mathbf{w}_*\|_2 \le 1$$

$$\mathbb{P}\{\mathbf{x} = \mathbf{e}_i\} = \mathbb{P}\{\mathbf{x} = -\mathbf{e}_i\} = \frac{\lambda_i}{2}$$

- SGD no better than GLM-tron when noise is well-specified
- SGD suffers constant error if noiseless

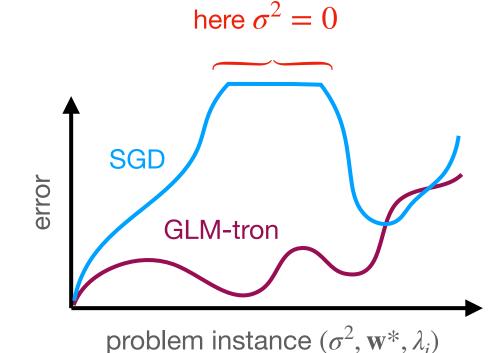
# Sample Size

Well-specified noise + Gaussian data



Well-specified noise + Bernoulli data

## 1D non-convex risk landscape Noiseless + Bernoulli data



References

- [KKSK'11] Kakade, S., Kanade, V., Shamir, O. and Kalai, A. Efficient learning of generalized linear and single index models with isotonic regression. In NeurIPS 2011.
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  - [WZBGK'22] Wu, J., Zou, D., Braverman, V., Gu, Q. and Kakade, S. Last iterate risk bounds of sgd with decaying stepsize for overparameterized linear regression. In ICML 2022.