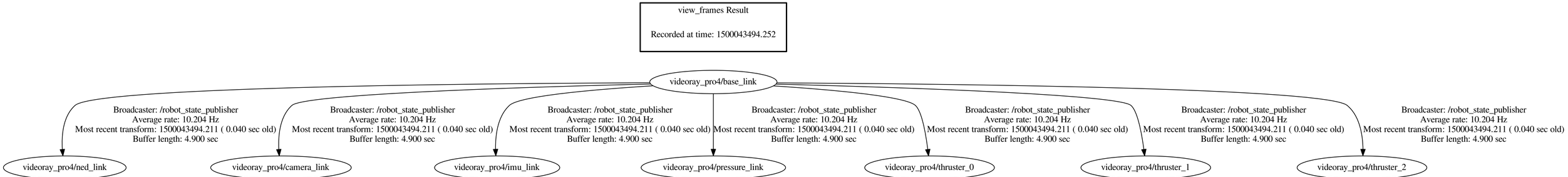
view_frames Result
Recorded at time: 1500043494.252
videoray_pro4/base_link
Broadcaster: /robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1500043494.211 (0.040 sec old)
Buffer length: 4.900 sec
videoray_pro4/ned_link
videoray_pro4/camera_link
videoray_pro4/imu_link
videoray_pro4/pressure_link
videoray_pro4/thruster_0
videoray_pro4/thruster_1
videoray_pro4/thruster_2