





Lecture 11.5 - Kernel Methods Support Vector Machines - Kernel SVM

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(Bishop 7.1.0)

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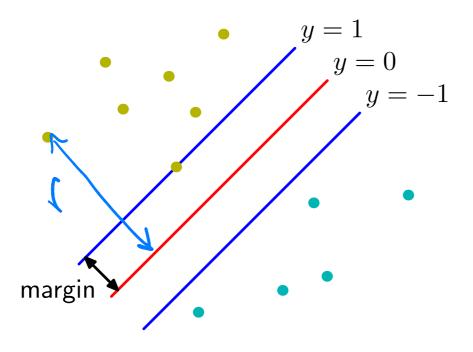
Maximizing the margin:

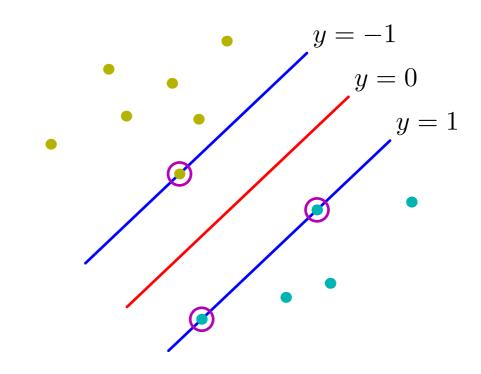
$$\underset{\mathbf{w},b}{\arg\min} \frac{1}{2} \|\mathbf{w}\|^2 \text{ subject to } N \text{ constraints } t_n(\mathbf{w}^T \mathbf{x}_n + b) \ge 1$$

- We decided to "calibrate" **w** s.t. for the nearest point $t_n(\mathbf{w}^T\mathbf{x}_n + b) = 1$
- Then the size of the margin is given by

$$\frac{1}{\|\mathbf{w}\|}$$

• And for all data points we have $t_n(\mathbf{w}^T\mathbf{x}_n + b) \ge 1$





Maximizing the margin:

$$\underset{\mathbf{w},b}{\operatorname{arg\,min}} \frac{1}{2} \|\mathbf{w}\|^2 \text{ subject to } N \text{ constraints } t_n(\mathbf{w}^T \mathbf{x}_n + b) \ge 1$$

Primal Lagrangian function:

agrangian function:
$$L(\mathbf{w},b,\mathbf{a}) = \frac{1}{2} ||\mathbf{w}||^2 - \sum_{n=1}^{N} a_n \{t_n(\mathbf{w}^T \mathbf{x}_n + b) - 1\}$$
T conditions:

With KKT conditions:

(primal feasibility)
$$t_n(\mathbf{w}^T\mathbf{x}_n+b)-1\geq 0$$
 for $n=1,\ldots,N$ (dual feasibility) $a_n\geq 0$ for $n=1,\ldots,N$ (complimentary slackness) $a_n(t_n(\mathbf{w}^T\mathbf{x}_n+b)-1)=0$ for $n=1,\ldots,N$

Dual Lagrangian obtained via (stationarity conditions) $\frac{\partial L}{\partial \mathbf{w}} = 0$, $\frac{\partial L}{\partial b} = 0$

$$\tilde{L}(\mathbf{a}) = \min_{\mathbf{x}, b} L(\mathbf{x}, b, \mathbf{a})$$

Solution:
$$\mathbf{a}^* = \underset{\mathbf{a}}{\operatorname{arg max}} \tilde{L}(\mathbf{a})$$
 $\mathbf{w}^*, b^* = \underset{\mathbf{w}, b}{\operatorname{arg min}} L(\mathbf{w}, b, \mathbf{a}^*)$

Primal Lagrangian function:

$$L(\mathbf{w}, b, \mathbf{a}) = \frac{1}{2} ||\mathbf{w}||^2 - \sum_{n=1}^{N} a_n \{ t_n(\mathbf{w}^T \mathbf{x}_n + b) - 1 \}$$

with Langrange multipliers: $a_n \ge 0$ for n = 1,...,N

First step towards dual Langrangian: obtain stationarity conditions

$$\frac{\partial L}{\partial \mathbf{w}} = \mathbf{w}^T - \sum_{n=1}^N a_n t_n \mathbf{x}_n^T = 0 \qquad \to \qquad \mathbf{w} = \sum_{n=1}^N a_n t_n \mathbf{x}_n$$

$$\frac{\partial L}{\partial b} = -\sum_{n=1}^N a_n t_n = 0 \qquad \to \qquad \sum_{n=1}^N a_n t_n = 0$$

ullet Eliminate ${f w}$ and b from L then gives the dual representation!

Stationarity conditions:

$$\frac{\partial L}{\partial \mathbf{w}} = \mathbf{w}^T - \sum_{n=1}^{N} a_n t_n \mathbf{x}_n^T = 0 \qquad \rightarrow \qquad \mathbf{w} = \sum_{n=1}^{N} a_n t_n \mathbf{x}_n$$

$$\frac{\partial L}{\partial b} = -\sum_{n=1}^{N} a_n t_n = 0 \qquad \rightarrow \qquad \sum_{n=1}^{N} a_n t_n = 0$$

lacktriangle Eliminate f w and b from L then gives the dual representation!

• Primal:
$$L(\mathbf{w}, b, \mathbf{a}) = \frac{1}{2} \mathbf{w}^T \mathbf{w} - \sum_{n=1}^N a_n \{t_n(\mathbf{w}^T \mathbf{x}_n + b) - 1\}$$
, with $a_n \ge 0$ for $n = 1, ..., N$
• Dual:
$$\tilde{L}(\mathbf{a}) = \mathbf{w}^T (\frac{1}{2} \mathbf{w} - \sum_{n=1}^N a_n t_n \mathbf{x}_n) - \sum_{n=1}^N a_n t_n \mathbf{x}_n + \sum_{n=1}^N a_n t_n \mathbf{x}_n + \sum_{n=1}^N a_n t_n \mathbf{x}_n + \sum_{n=1}^N a_n t_n \mathbf{x}_n \mathbf{x}_n + \sum_{n=1}^N a_n t_n t_n \mathbf{x}_n \mathbf{x}_n \mathbf{x}_n + \sum_{n=1}^N a_n t_n t_n \mathbf{x}_n \mathbf{x}_n$$

and with $\sum_{n=1}^{N} a_n t_n = 0$

The dual representation of the maximum margin, where we maximize w.r.t. a:

$$\tilde{L}(\mathbf{a}) = \sum_{n=1}^{N} a_n - \frac{1}{2} \sum_{n=1}^{N} \sum_{m=1}^{N} a_n a_m t_n t_m \mathbf{x}_n^T \mathbf{x}_m$$

with constraints:
$$a_n \ge 0$$
 for $n = 1,...,N$

$$\sum_{n=1}^{N} a_n t_n = 0$$

Apply the **KERNEL TRICK**: replace $\mathbf{x}_n^T \mathbf{x}_m$ with $k(\mathbf{x}_n, \mathbf{x}_m)$

$$\tilde{L}(\mathbf{a}) = \sum_{n=1}^{N} a_n - \frac{1}{2} \sum_{n=1}^{N} \sum_{m=1}^{N} a_n a_m t_n t_m k(\mathbf{x}_n, \mathbf{x}_m)$$

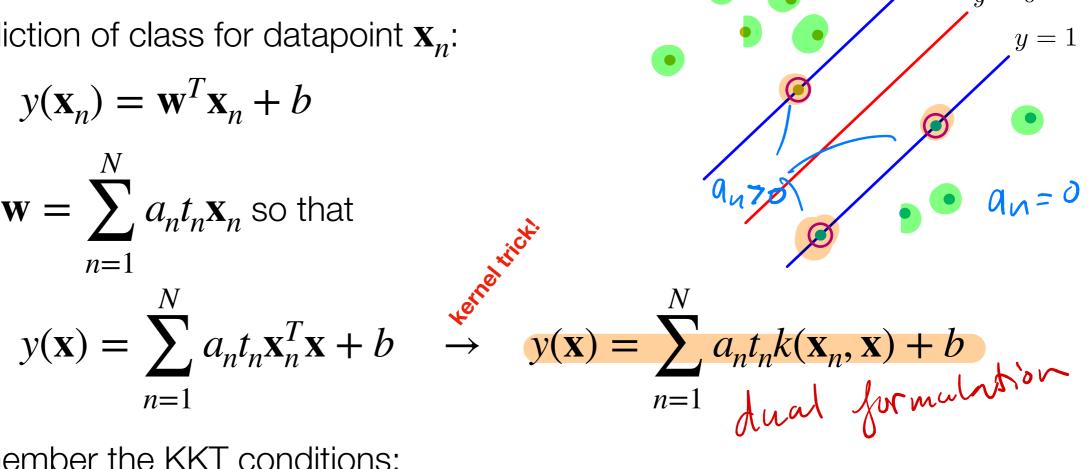
Advantage: can now learn complex nonlinear decision boundaries!

Prediction of class for datapoint \mathbf{X}_n :

$$y(\mathbf{x}_n) = \mathbf{w}^T \mathbf{x}_n + b$$

• Use
$$\mathbf{w} = \sum_{n=1}^{N} a_n t_n \mathbf{x}_n$$
 so that

$$y(\mathbf{x}) = \sum_{n=1}^{N} a_n t_n \mathbf{x}_n^T \mathbf{x} + b$$



Remember the KKT conditions:

(primal feasibility)
$$t_n(\mathbf{w}^T\mathbf{x}_n+b)-1\geq 0$$
 for $n=1,...,N$ (dual feasibility) $a_n\geq 0$ for $n=1,...,N$ (complimentary slackness) $a_n(t_n(\mathbf{w}^T\mathbf{x}_n+b)-1)=0$ for $n=1,...,N$

Support vectors lie on maximum margin hyperplanes

$$a_n > 0 \rightarrow t_n y(\mathbf{x}_n) = 1$$
 (support vectors)
 $a_n = 0 \leftarrow t_n y(\mathbf{x}_n) > 1$ (all other points)

Prediction of class for datapoint x:

$$y(\mathbf{x}) = \sum_{n=1}^{N} a_n t_n \mathbf{x}_n^T \mathbf{x} + \mathbf{b} \rightarrow y(\mathbf{x}) = \sum_{m \in S} a_m t_m k(\mathbf{x}_m, \mathbf{x}) + b$$

Find b by using that $t_n y_n(\mathbf{x}) = 1$ if \mathbf{x}_n lies on the margin boundary! (\mathbf{x}_n is a support vector)

Then
$$t_n\left(\sum_{m\in S}a_mt_mk(\mathbf{x}_m,\mathbf{x}_n)+b\right)=1$$
 by the solution $\sum_{m\in S}a_mt_mk(\mathbf{x}_m,\mathbf{x}_n)+b=t_n$ by $b=t_n-\sum_{m\in S}a_mt_mk(\mathbf{x}_m,\mathbf{x}_n)$

More stable to average over all support vectors (depending on optimizer, \mathbf{a}_n may not be perfect)

$$b = \frac{1}{N_S} \sum_{n \in S} \left(t_n - \sum_{m \in S} a_m t_m k(\mathbf{x}_m, \mathbf{x}_n) \right)$$

Maximum Margin Classifier with Gaussian Kernel

$$y(\mathbf{x}) = \sum_{m \in S} a_m t_m k(\mathbf{x}_m, \mathbf{x}) + b, \text{ with } k(\mathbf{x}_n, \mathbf{x}_m) = \exp\left(-\frac{1}{2\sigma^2} ||\mathbf{x}_n - \mathbf{x}_m||^2\right)$$

- Dataset is not linearly separable
- Nonlinear kernel can still separate the data perfectly!

