

Astr 511: Galaxies as galaxies

University of Washington

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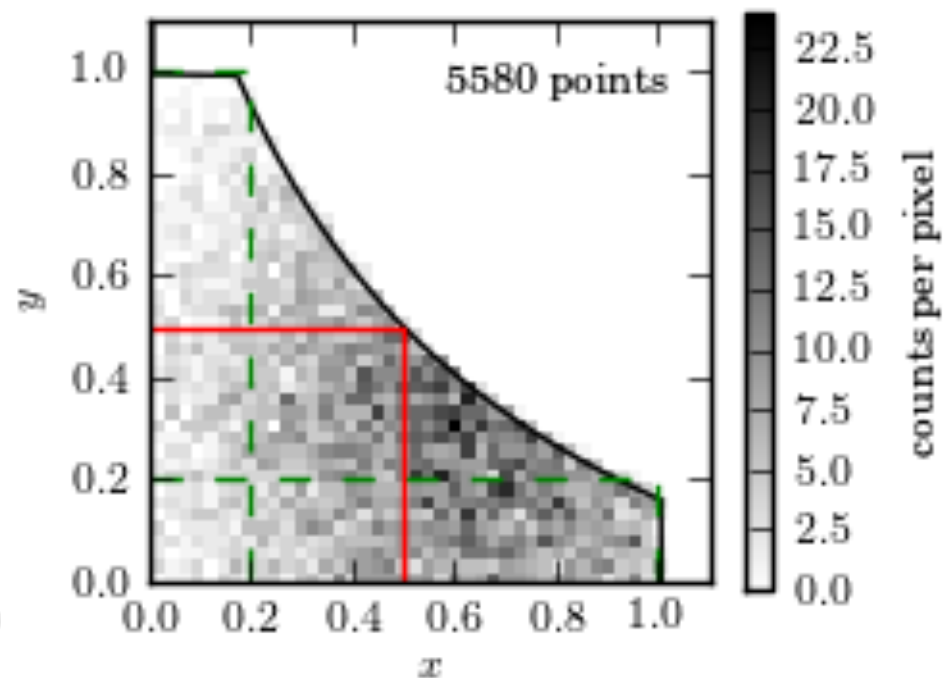
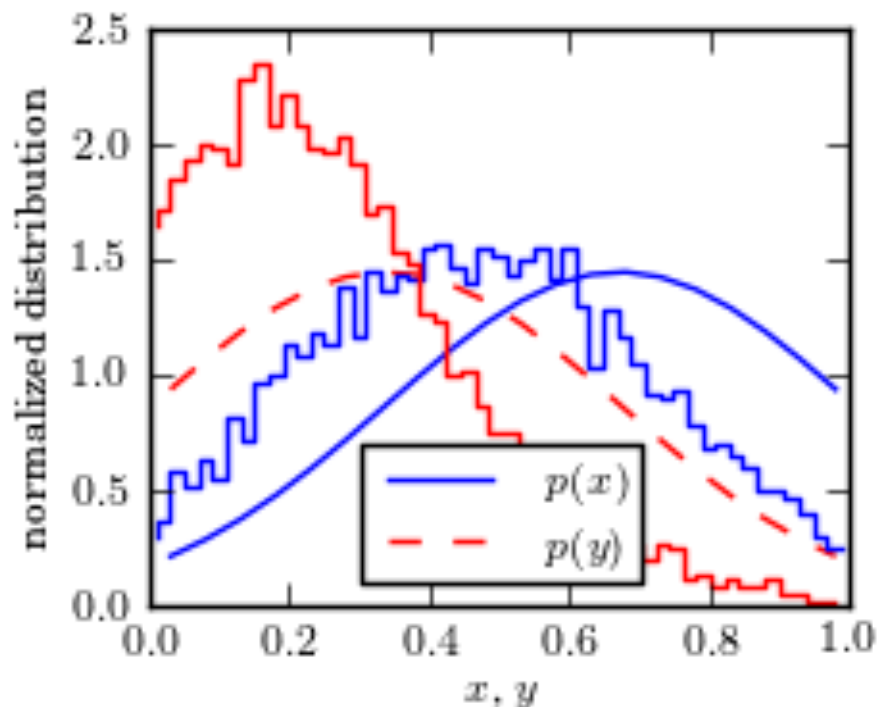
Lecture 5:

Luminosity and mass functions of galaxies: II

Outline

- Luminosity function: basic concepts
- Stellar mass function in the Milky Way
- **Methods for estimating LF from data**

- Toy example: the x-y “measurements” are truncated (similar to a flux-limited sample in astronomy).
- Histograms of measured quantities are biased for a truncated sample.
- Unbiased distributions can be obtained using various methods (V/V_{max} method, C^- method, maximum likelihood method)

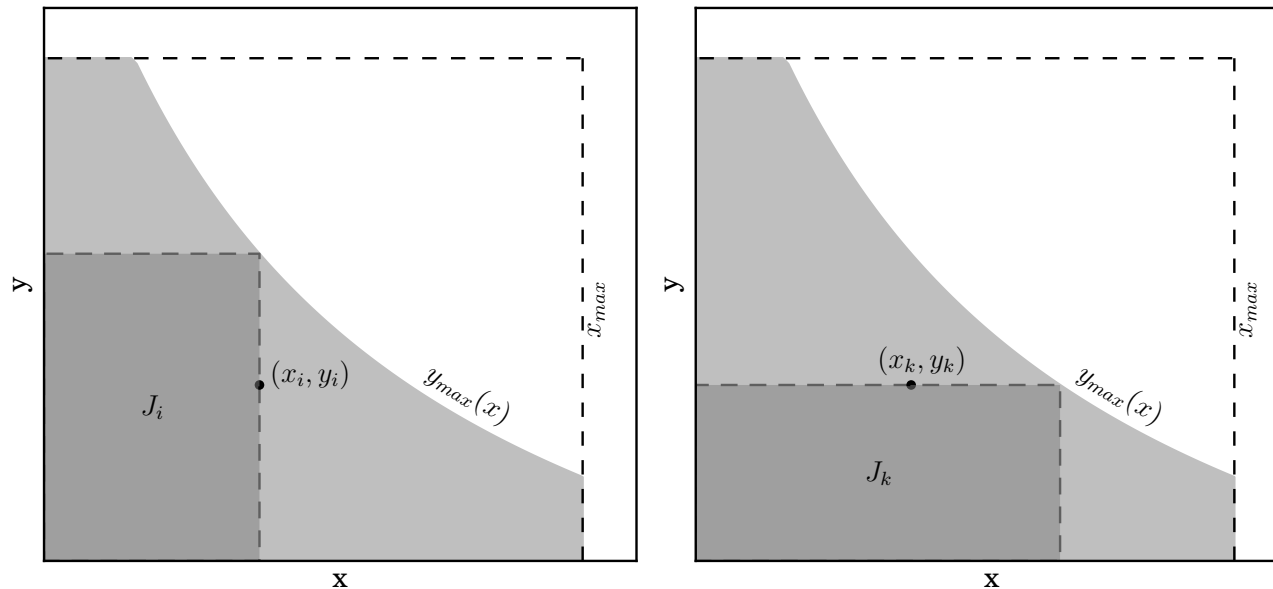


The C^- method for estimating LF

- Lynden-Bell (1971, MNRAS 155, 95); a non-parametric method that works for separable LFs, $\Psi(L, z) = \Phi(L)n(z)$
- practically all non-parametric methods can be reduced to the C^- method (Petrosian 1992)
- parametric methods are usually based on maximizing likelihood (e.g. Marshall 1985)
- the simplest and most famous method, the V_{max} method (Schmidt 1968), requires binning in two axes simultaneously, while with the C^- method data is binned only one axis at a time (e.g. Fan et al. 2001)
- How do we know that separable LF is a good guess for our data?

C⁻ method

- Given a set of measured pairs (x_i, y_i) , with $i = 1 \dots N$, and *known* relation $y_{max}(x)$, estimate the two-dimensional distribution, $n(x, y)$, from which the sample was drawn. Assume that measurement errors for both x and y are negligible compared to their observed ranges, that x is measured within a range defined by x_{min} and x_{max} , and that the selection function is 1 for $0 \leq y \leq y_{max}(x)$ and $x_{min} \leq x \leq x_{max}$, and 0 otherwise.

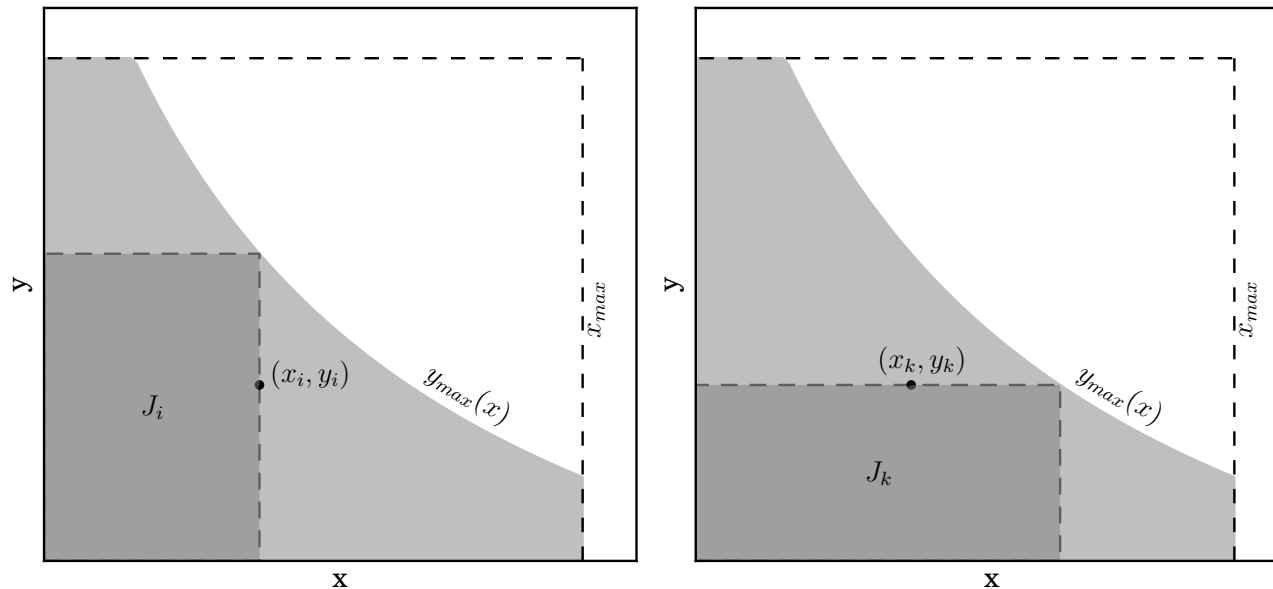


C^- method

- C^- method is applicable when the distributions along the two coordinates x and y are uncorrelated, that is, when we can assume that the bivariate distribution $n(x, y)$ is separable

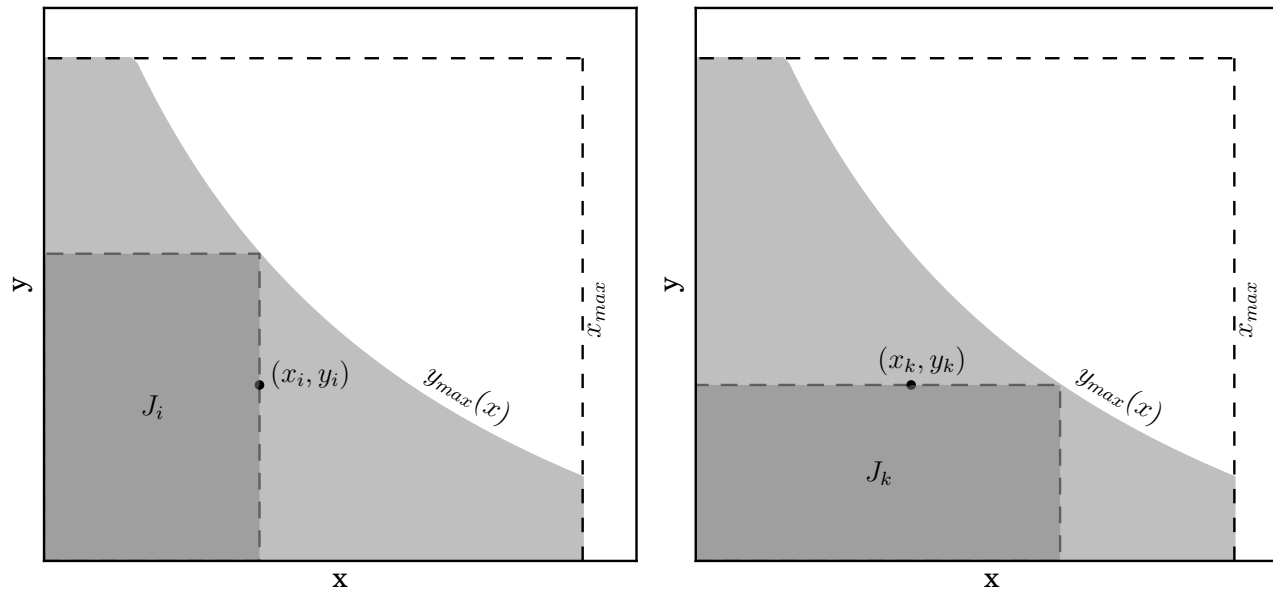
$$n(x, y) = \psi(x) \rho(y). \quad (1)$$

Therefore, before using the C^- method we need to demonstrate that this assumption is valid.



C⁻ method

- Define a *comparable* or *associated* set for each object i such that $J_i = \{j : x_j < x_i, y_j < y_{\max}(x_i)\}$; this is the largest x -limited and y -limited data subset for object i , with N_i elements (see the left panel).
- Sort the set J_i by y_j ; this gives us the rank R_j for each object (ranging from 1 to N_i)



C⁻ method

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- Sort the set J_i by y_j ; this gives us the rank R_j for each object (ranging from 1 to N_i)
- Define the rank R_i for object i in *its* associated set: this is essentially the number of objects with $y < y_i$ in set J_i .
- If x and y are truly independent, R_i must be distributed *uniformly* between 0 and N_i .

C⁻ method

- If x and y are truly independent, R_i must be distributed *uniformly* between 0 and N_i .
- In this case, it is trivial to determine the expectation value and variance for R_i : $E(R_i) = E_i = N_i/2$ and $V(R_i) = V_i = N_i^2/12$. We can define the statistic

$$\tau = \frac{\sum_i (R_i - E_i)}{\sqrt{\sum_i V_i}} \quad (2)$$

If $\tau < 1$, then x and y are uncorrelated at $\sim 1\sigma$ level.

- A quiz question for in-class discussion: how would the above expression for τ look like if the uniform distribution were replaced by a Gaussian (normal) distribution?

C⁻ method

Assuming that $\tau < 1$, it is straightforward to show using relatively simple probability integral analysis (e.g., see Appendix in Fan et al. 2001), as well as the original Lynden-Bell's paper, how to determine cumulative distribution functions. The cumulative distributions are defined as

$$\Phi(x) = \int_{-\infty}^x \Psi(x') dx', \quad (3)$$

and

$$\Sigma(y) = \int_{-\infty}^y \rho(y') dy'. \quad (4)$$

Then,

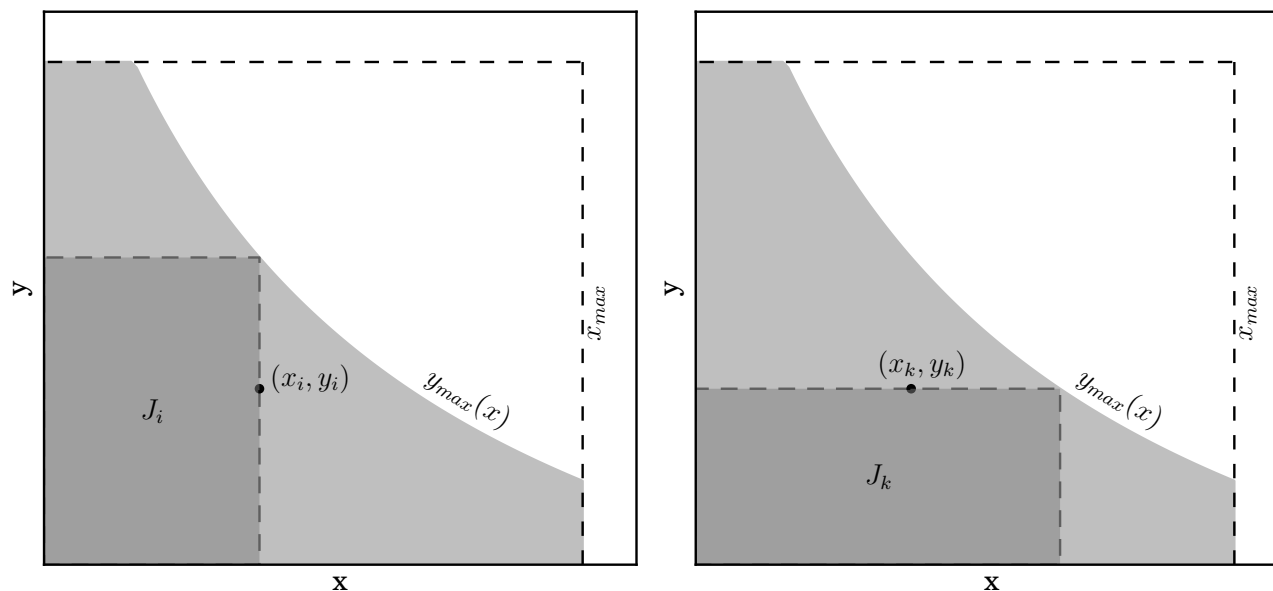
$$\Phi(x_i) = \Phi(x_1) \prod_{k=2}^i (1 + 1/N_k) \quad (5)$$

where it is assumed that x_i are sorted ($x_1 \leq x_k \leq x_N$).

C⁻ method

Analogously, if M_k is the number of objects in a set defined by $J_k = \{j : y_j < y_k, y_{\max}(x_j) > y_k\}$ (see the right panel of figure below), then

$$\Sigma(y_j) = \Sigma(y_1) \prod_{k=2}^j (1 + 1/M_k). \quad (6)$$

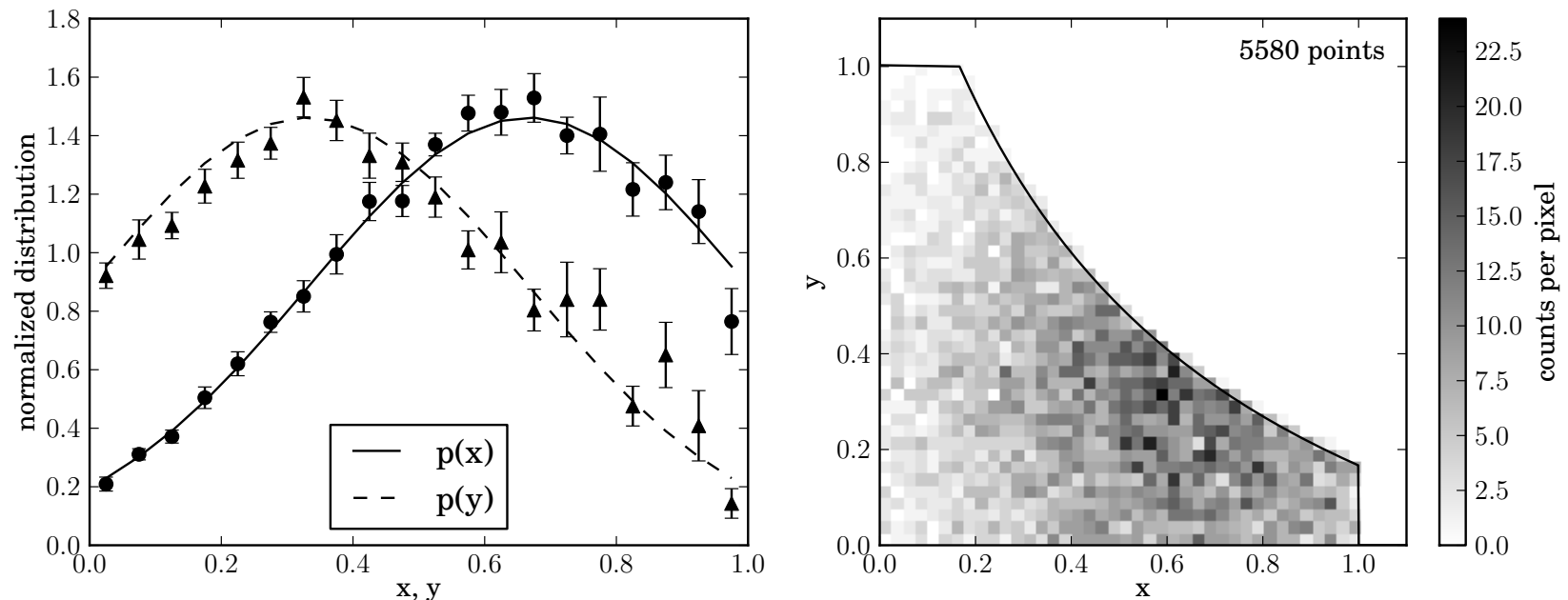


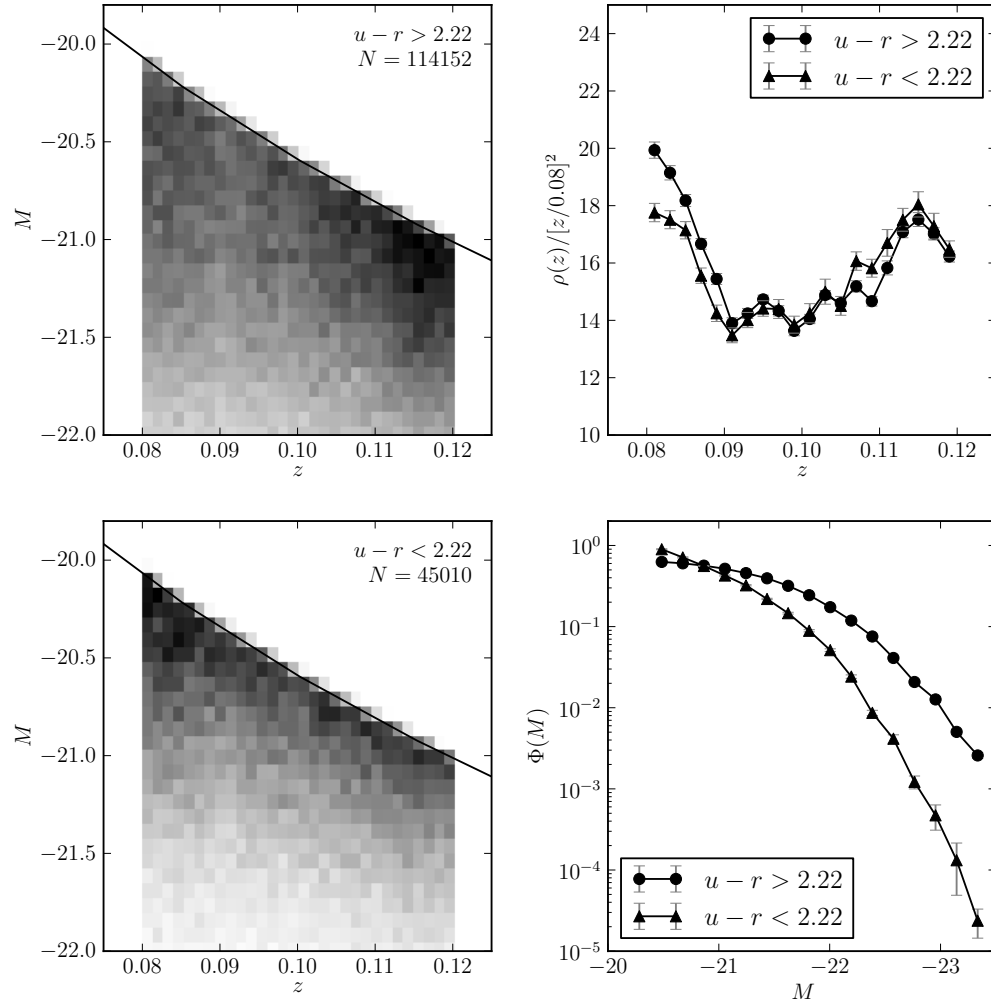
astroML implementation of the C^- method

- Note that both $\Phi(x_j)$ and $\Sigma(y_j)$ are defined on non-uniform grids with N values, corresponding to the N measured values.
- Essentially, the C^- method assumes a piece-wise constant model for $\Phi(x)$ and $\Sigma(y)$ between data points (equivalently, differential distributions are modeled as Dirac's δ functions at the position of each data point).
- As shown by Petrosian (1992), $\Phi(x)$ and $\Sigma(y)$ represent an optimal data summary.
- The differential distributions $\Psi(x)$ and $\rho(y)$ can be obtained by differentiating cumulative distributions in the relevant axis; an approximate normalization can be obtained by requiring that the total predicted number of objects is equal to their observed number.

- **astroML Book Figure 4.9:** The right panel shows a realization of truncated separable two-dimensional Gaussian distribution (with the truncation given by the solid line). The lines in the left panel show the true one-dimensional distributions of x and y , and the points are computed from the truncated data set using the C^- method (with error bars from 20 bootstrap resamples).

https://www.astroml.org/book_figures/chapter4/fig_lyndenbell_toy.html





- **astroML Book Figure 4.10:** The luminosity function for two $u-r$ color-selected subsamples of SDSS galaxies from the spectroscopic sample, with redshift in the range $0.08 < z < 0.12$ and flux limited to $r < 17.7$.
- The left panels show the distribution of sources as a function of redshift and absolute magnitude. The distribution $p(z, M) = \rho(z)\Phi(m)$ is obtained using Lynden-Bell's method, with errors determined by 20 bootstrap resamples, and shown in the right panels.

https://www.astroml.org/book_figures/chapter4/fig_lyndenbell_gals.html

Test of L-z Correlation. II

- In reality, the selection function is typically complex: $s(L, z|SED, \dots)$ (no sharp faint limit!)
- First define a generalized comparable set (Fan et al. 2001; AJ 121, 54) $J_i = \{j : L_j > L_i\}$; this is a luminosity limited data subset for object i
- Then generalize N_i to

$$T_i = \sum_{j=1}^{N_i} \frac{s(L_i, z_j|SED_j)}{s(L_j, z_j|SED_j)}, \quad (7)$$

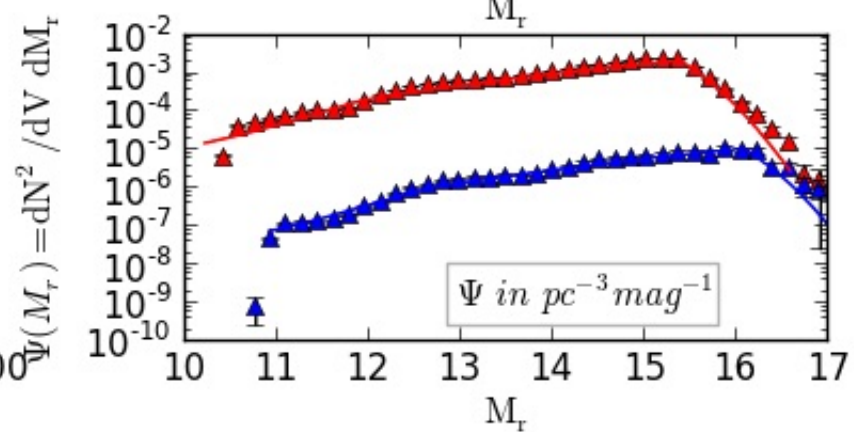
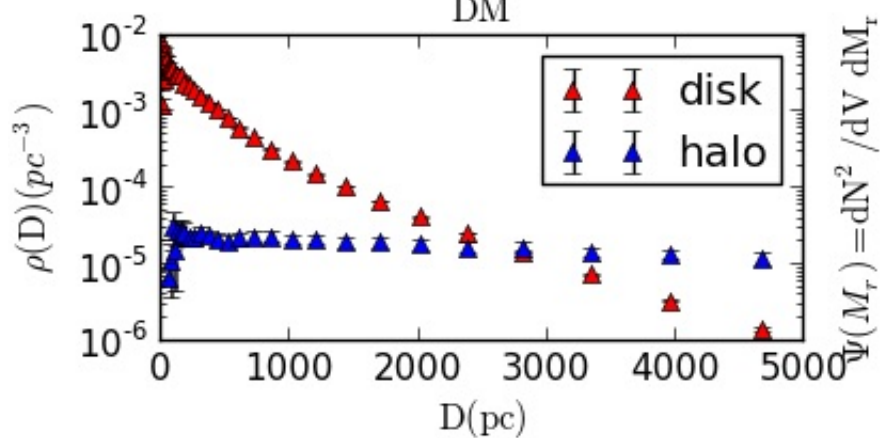
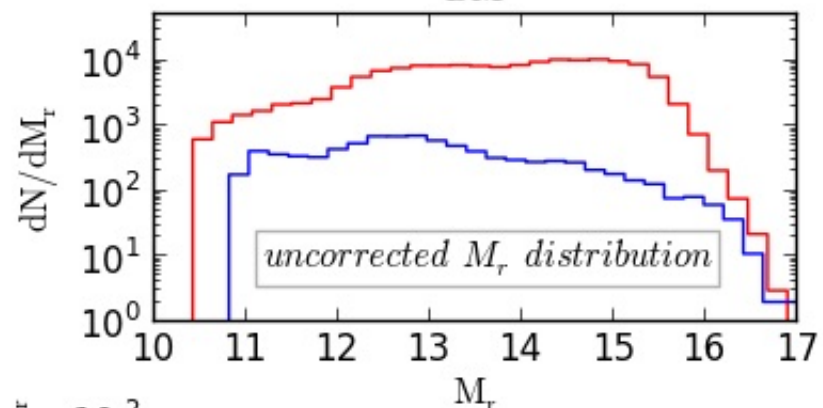
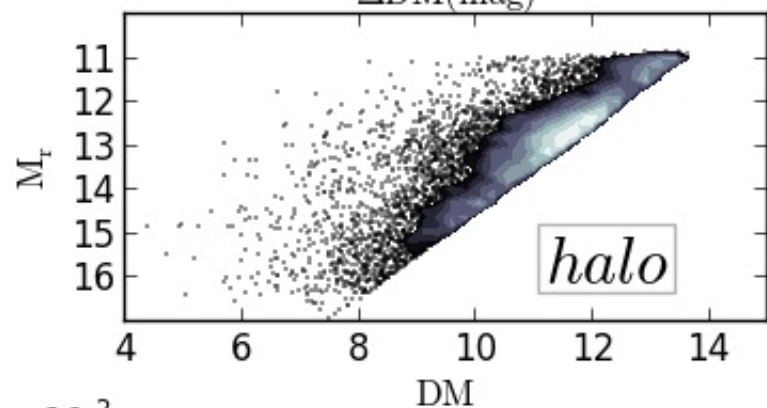
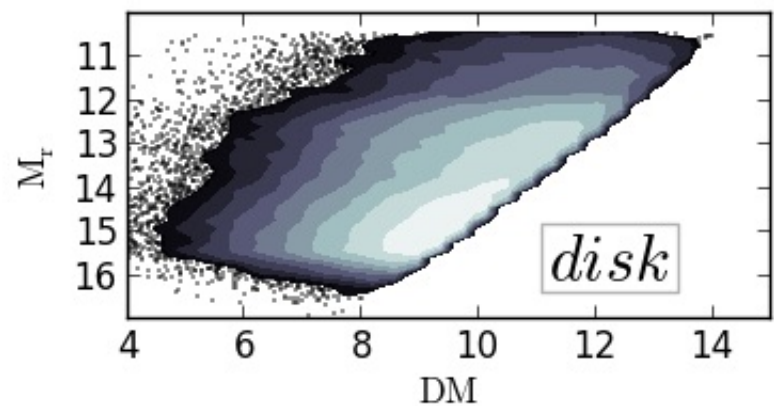
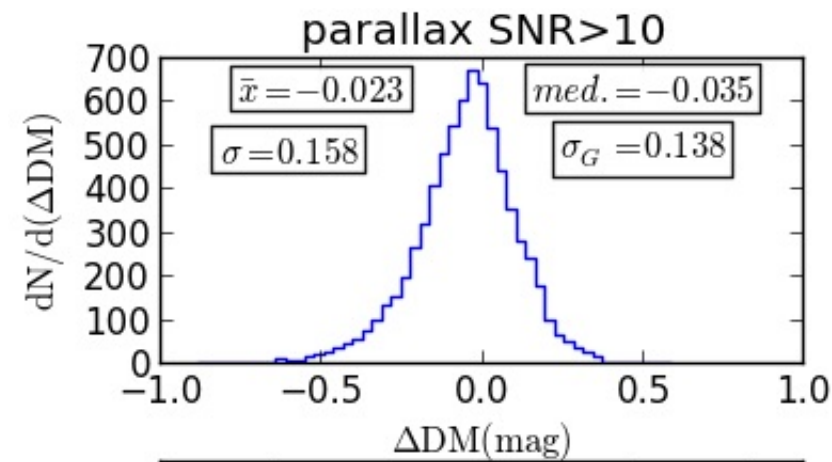
and redefine the rank accordingly

$$R_i = \sum_{j=1}^{N_i} \frac{s(L_i, z_j|SED_j)}{s(L_j, z_j|SED_j)}, \quad (8)$$

for $z_j < z_i$. It follows that $E(R_i) = T_i/2$ and $V(R_i) = T_i^2/12$.

Evolving Luminosity Function

- The C^- method is simple and optimal, but it is valid only for uncorrelated variables (separable luminosity function). What do we do when the τ test suggests correlated variables?
- Kelly, Fan and Vestergaard (2008, ApJ 682, 874) described a powerful and completely general Bayesian approach (see their Appendix A for a nice introduction to Bayesian methodology). While too complex for homework, this is a fantastic method – if you ever come again across the problem of estimating a general multi-dimensional distribution that is sampled with non-negligible and possibly complex selection function, remember that paper!
- ...and let's now say a few words to help you with HW # 2



LF normalization

- The C^- method does not know (or need) details about our sample; in particular, it cannot give us the overall LF normalization!
- We will use HW#2 problem to discuss normalization in more detail; we can talk about three levels of normalization in this case:
 1. **The sample normalization:** if we didn't have the selection effects, how many objects would our sample contain?
 2. **Normalization to the full sky:** we need to know the sky coverage for our sample (and have arguments why we can extrapolate to the whole sky).
 3. **Extrapolation** from the volume probed by the sample **to some other position**; here, we want to know LF at $z = 0$.

LF normalization: the sample normalization

If we didn't have the selection effects, how many objects would our sample contain?

- To recap, the cumulative luminosity (absolute magnitude) function is $\Phi_c(M_j)$ and the cumulative distance distribution is $n_c(D_j)$ where $j = 1 \dots N$.
- Both $\Phi_c(M_j)$ and $n_c(D_j)$ are **direct outputs** from the C^- method; **let us renormalize them** as $\Phi_c(M_N) = 1$ and $n_c(D_N) = 1$, where it is assumed that M_j and D_j arrays are sorted so that M_N and D_N are their maxima (btw, C^- would return $\Phi_c(M_N) = N$ and $n_c(D_N) = N$).
- The number of points, n , brighter than some arbitrary M^* and closer than some arbitrary D^* is then

$$n(M < M^* \text{ and } D < D^*) = C \Phi_c(M^*) n_c(D^*). \quad (9)$$

where we (still) don't know C (n.b. C is dimensionless).

LF normalization: the sample normalization

- Now, if make sure that M^* and D^* are within our selection volume (the implied apparent mag must be above our cutoff) and thus unaffected by selection effects, then we get C from

$$N^o(M < M^o \text{ and } D < D^o) = C \Phi_c(M^o) n_c(D^o), \quad (10)$$

which is almost the same expression as on the previous page, except that here $n(M < M^* \text{ and } D < D^*)$ is replaced by $N^o(M < M^o \text{ and } D < D^o)$: the actual number of objects in our sample that satisfy this condition.

- This is not mathematically optimal solution for C because N^o is a random variable, but with modern large samples this is nit-picking; the optimal procedure would integrate over the full sample, but nevertheless would still need to adopt an interpolation procedure for $\Phi_c(M)$ and $n_c(D)$...
- Given the real sample size, N , that is affected by selection effects, the “corrected” sample size is C !

LF normalization: the sample normalization

- The number of points per unit two-dimensional area, $dA = dM dD$, is then

$$\frac{d^2 N}{dM dD} = C \left(\frac{d\Phi_c(M)}{dM} \right) \left(\frac{dn_c(D)}{dD} \right), \quad (11)$$

where we now know C and can easily take (numerical) derivatives $d\Phi_c(M)/dM$ and $dn_c(D)/dD$ (where $\Phi_c(M)$ and $n_c(D)$ came from C^- and are normalized to 1).

- The quantities in parenthesis are differential distribution functions.
- When normalizing to the full sky (step #2), we need to know the fraction of sky, f_{sky} , covered by our sample; if justified, we need to multiply C by $1/f_{sky}$: $C_{sky} = C/f_{sky}$.

LF normalization: extrapolation

How do we go from $d^2N/(dM dD)$ to volume density?

$$\Phi(M, D) \equiv \frac{d^2N}{dM dV} = \frac{d^2N}{dM dD} \frac{dD}{dV}, \quad (12)$$

where $dV = 4\pi D^2 dD$. We have two cases of interest:

- **Case 1:** We seek the volume density vs. D , $\rho(D)$, and we don't care about M distribution:

$$\rho(D) = \int \Phi(M, D) dM = \frac{C_{sky}}{4\pi D^2} \left(\frac{dn_c(D)}{dD} \right), \quad (13)$$

where we used the fact that $\int_{-\infty}^{\infty} \left(\frac{d\Phi_c(M)}{dM} \right) dM = \Phi_c(M_N) = 1$.

- Unit for $\rho(D)$ is the number of objects per (distance unit)³ (remember that $n_c(D)$ was dimensionless and normalized to unity at $D = D_N$; the unit comes from taking derivative with respect to D , $dn_c(D)/dD$, and from the $1/D^2$ term).

LF normalization: extrapolation

- Given $\rho(D)$, we can fit some function to it and **extrapolate** to get $\rho(D = D_0)$ (and thus the ratio $\rho(D)/\rho(D = D_0)$ for any D_0 , including $\rho(D_0)/\rho(D_N)$).
- **Case 2:** We want to know the M distribution at some $D = D_0$, call it $\psi(M|D = D_0)$ (e.g. $D_0 = 0$ corresponding to solar neighborhood, as discussed in this HW). First, at $D = D_N$ (recall $n_c(D_N) = 1$)

$$\psi(M|D = D_N) = \int \Phi(M, D) dD = C_{sky} \left(\frac{d\Phi_c(M)}{dM} \right). \quad (14)$$

- Then, extrapolating to D_0 (unit for ψ is the number of objects per mag; this is what we compare to the “true” LF)

$$\psi(M|D = D_0) = \psi(M|D = D_N) \frac{\rho(D_0)}{\rho(D_N)}. \quad (15)$$