



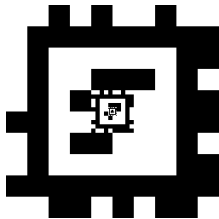
Autonomous Drone Landing with Fiducial Markers and a Gimbal-Mounted Camera for Active Tracking

Joshua Springer

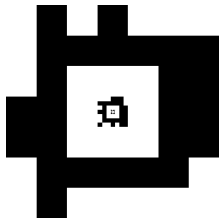
25 November 2022

Reykjavik University

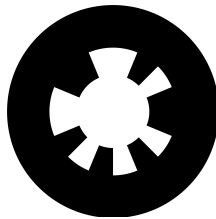
Department of Computer Science



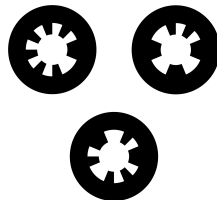
(a) April Tag 48h12



(b) April Tag 24h10



(c) WhyCode (Orig)



(d) WhyCode Multi

The Downward-facing Camera Axiom



DJI Mobile SDK

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- ▶ Orientation ambiguity, discontinuities → pose estimation is harder.
- ▶ Autonomous precision landing still possible but can be improved.