

# Acme AI Test Case

Full Stack Developer

# Setting up the configuration tool

**Step 1:** Download [Docker Desktop](#) for free (choose the download according to your operating system)

Set up as required

**Step 2:** Open your IDE (PyCharm, VSCode, ...)

**Step 3:** Clone the “configuration-tool” repository from: <https://github.com/trackbox-ai/configuration-tool.git>

**Step 4:** Open as a project in your IDE

**Step 5:** Build the application

Step 5.1: Open Docker Desktop

Step 5.2: Open the terminal in your IDE and put “docker-compose build”

Step 5.3: Run the file “docker-compose.yml”

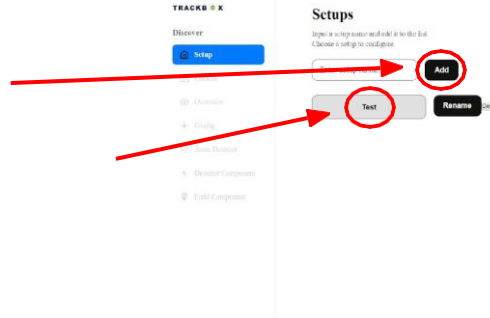
**Step 6:** Navigate to <http://localhost:3000/> in your browser

# Test the configuration tool

## Setup Page

### Objective of this page:

- Add a camera configuration to be made
- Select an already existing camera configuration to adjust



### Workflow:

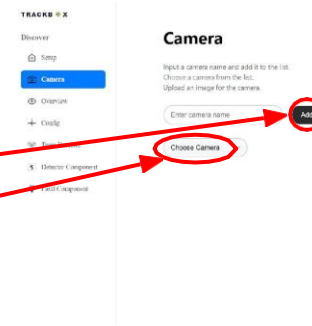
- Put a name in the textbox, before adding the camera configuration
- Select for example camera configuration “Test” if you want to adjust this one instead of creating a new one

# Test the configuration tool

## Camera page

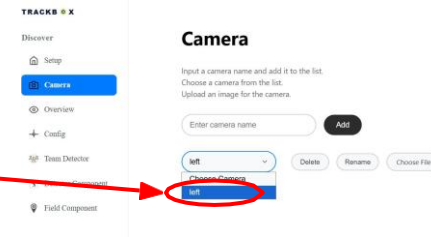
### Objective of this page:

- Add camera(s) to a selected configuration
- Select a camera of a selected configuration



### Workflow:

- Put a name in the textbox, before adding a camera
- Click “Choose Camera” and select the camera you want to adjust



# Test the configuration tool

Camera page: Configuration - Camera

## Objective of this page:

Just input text, so these values are not used anywhere in the tool

**TRACKER 3.0**

Discover

- Setup
- Camera**
- Operator
- Config
- Setup Database
- Database Component
- Field Component

**Camera**

Insert a camera name and add it to the list.  
Click on camera from the list.  
Upload an image for the camera.

Enter camera name  **ADD**

**ALL** **+** **REMOVE** **PREVIEW** **DELETE (X)**

**Setup Configuration**

Barcode label:

API:

Enable event stream for camera output: ☐

Barcode output:

Image resolution for camera output:

Rotation:

Physical position or location of camera:

Physical type:

Dynamic:

Type of mapping algorithm applied:

Line connection: ☐

RT:

Base address connection or network:

Area:

Camera ID:

File system path for camera data storage:

# Test the configuration tool

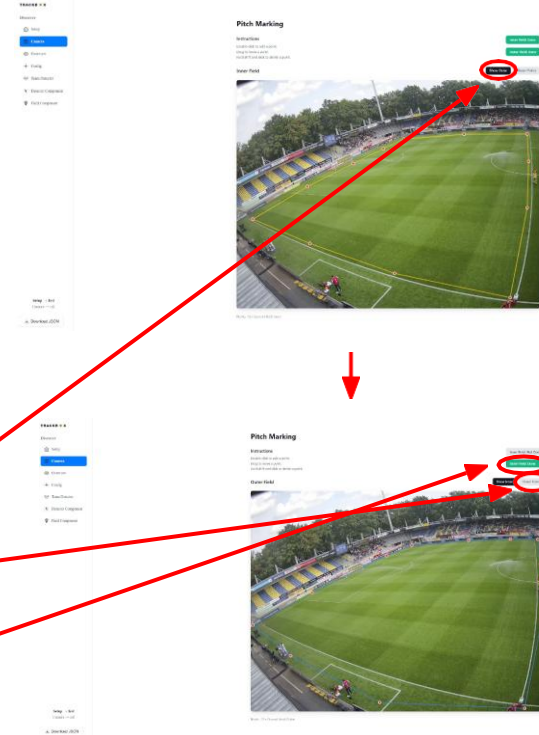
## Camera page: Pitch Marking

### Objective of this page:

- Add inner and outer field points

### Workflow:

- Double click to place a point
- Drag if you want to replace the point
- Functionality: add point between other points and it will be easily integrated
- Switch to outer field points by clicking “Show Outer”
- Reset points by clicking “Reset Points”
- After putting 4 points on the image – it will be marked as done



# Test the configuration tool

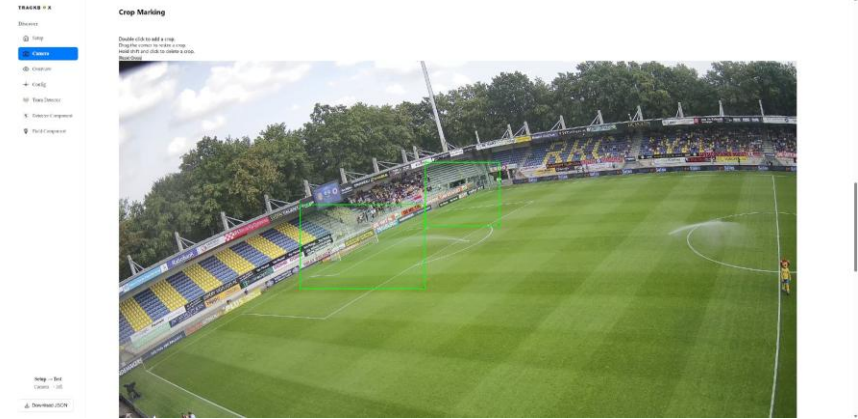
## Camera page: Crop Marking

### Objective of this page:

- Add inner and outer field points

### Workflow:

- Double click to place a crop
- Adjust the crop by dragging the right bottom corner
- Shift + click to remove a crop
- Remove all the crops by clicking “Reset Crops”



# Test the configuration tool

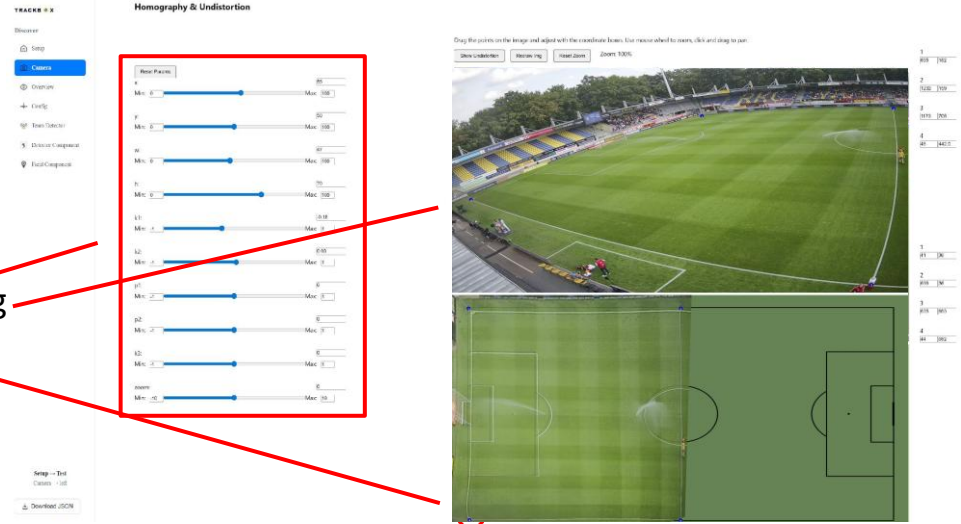
## Camera page: Homography & Undistortion

### Objective of this page:

- Project the image on the 2D map

### Workflow:

- Drag the 4 blue points to keypoints on the image
- Do the same for the 4 points on the 2D map
- Adjust the params to project the image on the 2D map





# Test case

## Context:

The version you tested is the current status of our configuration tool. It's not fully operational yet, so we want to start using it as soon as possible and are looking for a full stack developer to take on this project, next to other exciting things to work on in the space of Sports Tech.

FYI: Only the "camera-page" is fully working. The other pages are not yet functional and should not be investigated.

### Part 1: Investigation

Make an overview of the following:

- **Problems to be solved for v1:** these are things that need to be adjusted because otherwise the "camera-page" won't work properly.
  - **Optimization for v2:** these are things that are "nice-to-haves" or "how it should be"
- ☐ List them, so we can use it as some sort of blueprint / planning board on what to develop, how and why!

### Part 2: Implementation

Make an overview of the following:

- **Add functionality** to allow one camera to have multiple homography & undistortion combinations. We call this projections.
- **Add a drop down** (or something similar) to easily add and select projections for this camera. No need to be able to work on multiple projections at the same time.