

## GAN for celebrity faces



Off-manifold

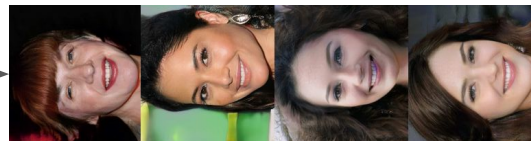
## GAN for **children** faces



TRANSFER  
LEARNING

On-manifold

## GAN for **women** faces



# MineGAN: effective knowledge transfer from GANs to target domains with few images

(Wang et al., 2020)

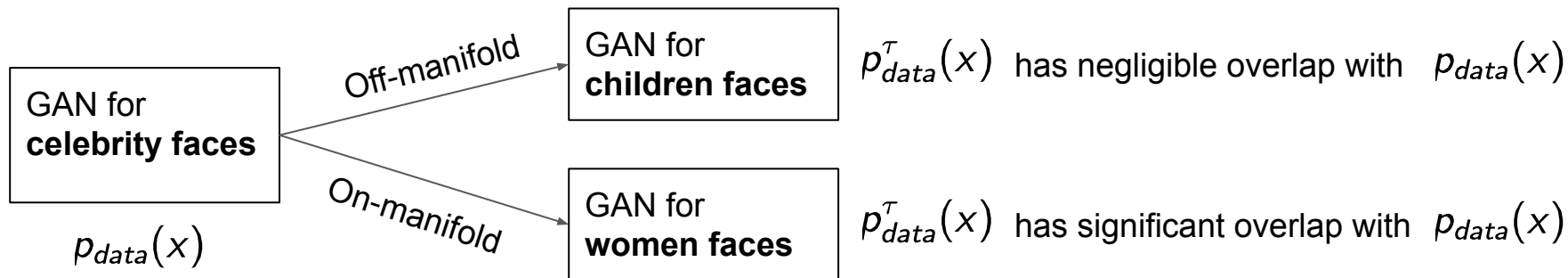
**Vladimir Fedoseev**  
Computer Vision Seminar SS 2020

# Problem - transfer from single GAN

Given:

- a target real images distribution  $p_{data}^{\tau}(x)$  from which a small set  $\mathcal{D}_{\mathcal{T}}$  is sampled
- D and G trained to approximate a source real images distribution  $p_{data}(x)$  with generative  $p_g(x)$

Produce a new model to approximate  $p_{data}^{\tau}(x)$  with new  $p_g^{\tau}(x)$  using G, D, and  $\mathcal{D}_{\mathcal{T}}$



# Problem - transfer from multiple GANs

Given:

- a target real images distribution  $p_{data}^{\tau}(x)$  from which a small set  $\mathcal{D}_{\mathcal{T}}$  is sampled
- N generators  $\{G_i\}$  and N discriminators  $\{D_i\}$  pretrained

Produce a new model to approximate  $p_{data}^{\tau}(x)$  with new  $p_g^{\tau}(x)$  using  $\{G_i\}$ ,  $\{D_i\}$ , and  $\mathcal{D}_{\mathcal{T}}$

# Contributions

1. New method of knowledge transfer for GANs for target distributions represented by a small training set
2. First method to transfer knowledge from several GANs to one GAN
3. Outperforming other approaches in transfer for different GANs

# Motivation - GANs

Generative models to induce  
**complex, high-dimensional data distribution**  
(e.g. a set of images) and generate new samples

Variety of other tasks: super-resolution, style transfer,  
image inpainting, text to image, ...

# Motivation - GANs



images from [thispersondoesnotexist.com](https://thispersondoesnotexist.com) (Karras et al, 2020)

# Motivation - knowledge transfer for GANs

1. Training GANs from scratch require a lot of time and images  
(Progressive GANs - 30K images, a month on an NVIDIA Tesla V100)



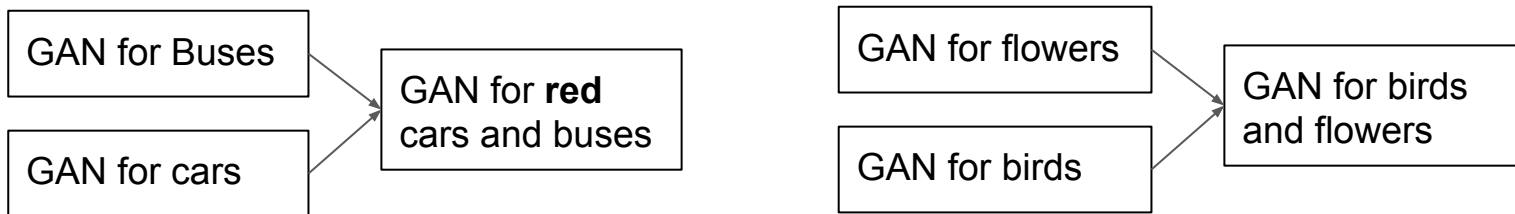
- Sometimes images from target distribution are rare or costly to obtain
- Applications might require fast training on a specific target distribution

2. GAN training is prone to overfitting, mode collapse, not stable gradients ...

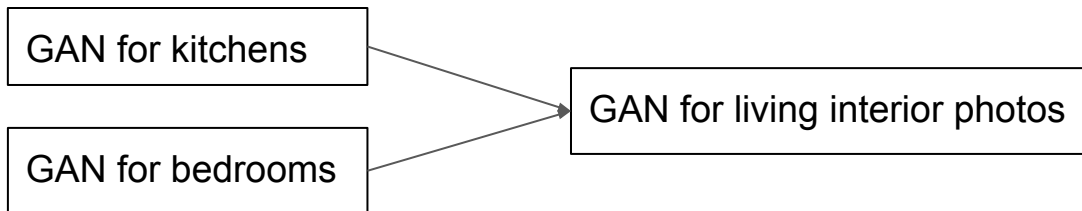
**=> Need to quickly retrain well-trained GANs for new distributions represented by small sets**

# Motivation - knowledge transfer from several GANs

- Target distribution is a mixture or intersection of (parts of) distributions of available pre-trained GANs



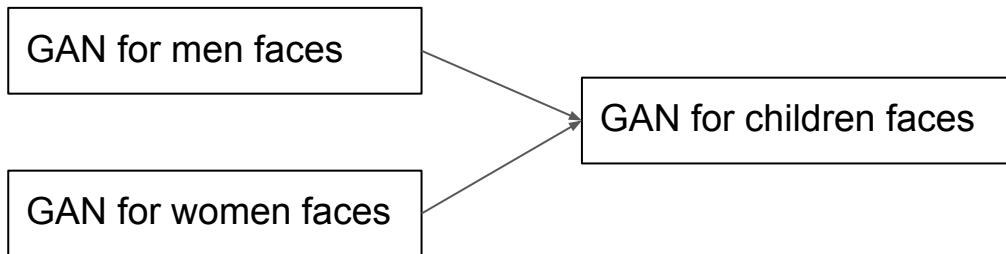
- Target distribution includes distributions of pre-trained GANs



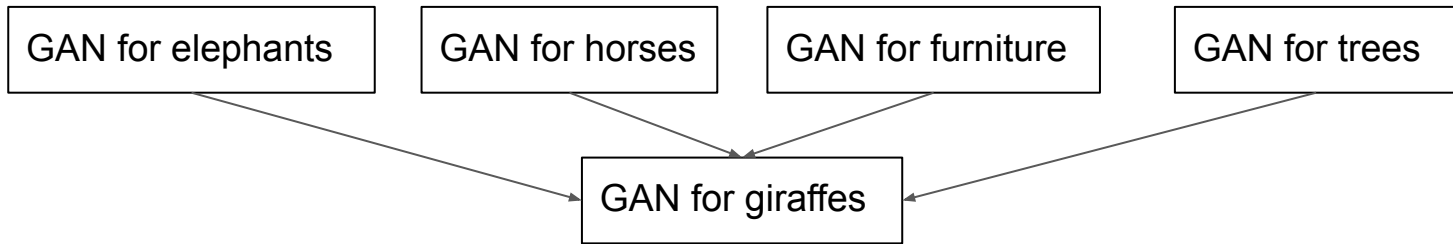


# Motivation - knowledge transfer from several GANs

- Target distribution is off-manifold for pre-trained GANs, but close



- Target distribution is mainly off-manifold for pre-trained GANs, but mixing them will increase the amount of potentially relevant knowledge



# GAN - original formulation

expectations over minibatches

D score for train image

D score for generated image

$$\min_G \max_D \mathbb{E}_{x \sim \mathbb{P}_r} [\log (D(x))] + \mathbb{E}_{\tilde{x} \sim \mathbb{P}_g} [\log (1 - D(\tilde{x}))]$$

generator network

discriminator network

image drawn from training ones

image drawn from generated ones

$\tilde{x} = G(z, \theta^g), z \sim \mathbb{P}_z$

latent noise vector drawn from some distribution

$G(z, \theta^g)$

$D(x) = A(f(x, \theta^d))$

function to map to (0, 1), like sigmoid

# GAN - original formulation

$$\min_G \max_D \mathbb{E}_{x \sim \mathbb{P}_r} [\log (D(x))] + \mathbb{E}_{\tilde{x} \sim \mathbb{P}_g} [\log (1 - D(\tilde{x}))]$$

$$G(z, \theta^g)$$

find parameters  $\theta^g$  to maximize  $D(\tilde{x})$

$$D(x) = A(f(x, \theta^d))$$

find parameters  $\theta^d$  to minimize  $D(\tilde{x})$  and maximize  $D(x)$

# GAN - WGAN-GP used by MineGAN

$$\min_G \max_D \mathbb{E}_{x \sim \mathbb{P}_r} [\log(D(x))] + \mathbb{E}_{\tilde{x} \sim \mathbb{P}_g} [\log(1 - D(\tilde{x}))]$$



$$\lim_{\|D - D^*\| \rightarrow 0} \nabla_{\theta} \mathbb{E}_{z \sim p(z)} [\log(1 - D(\tilde{x}))] = 0 \quad (\text{Arjovsky \& Bottou, 2017})$$

$$L = \mathbb{E}_{\tilde{x} \sim \mathbb{P}_g} [D(\tilde{x})] - \mathbb{E}_{x \sim \mathbb{P}_r} [D(x)] + \lambda \mathbb{E}_{\hat{x} \sim \mathbb{P}_{\hat{x}}} [(\|\nabla_{\hat{x}} D(\hat{x})\|_2 - 1)^2]$$

“Critic”: not [0, 1] output, no logs

Critic gradient penalty  
to enforce Lipschitz-1 constraint

Arjovsky, M., & Bottou, L. (2017). Towards principled methods for training generative adversarial networks.

Gulrajani et al. (2017). Improved training of wasserstein gans

# GAN - WGAN-GP used by MineGAN

$$L = \mathbb{E}_{\tilde{x} \sim \mathbb{P}_g}[D(\tilde{x})] - \mathbb{E}_{x \sim \mathbb{P}_r}[D(x)] + \lambda \mathbb{E}_{\hat{x} \sim \mathbb{P}_{\hat{x}}}[(\|\nabla_{\hat{x}} D(\hat{x})\|_2 - 1)^2]$$

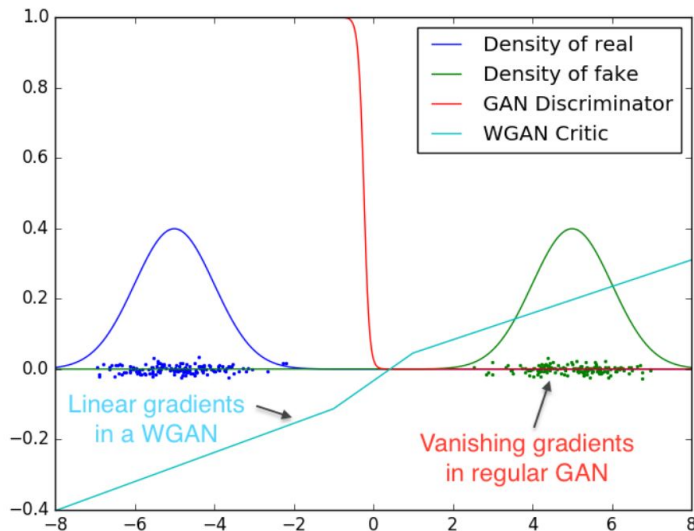
- Soft, two-sided penalty (not necessarily below 1)
- $\hat{x} \sim \mathbb{P}_{\hat{x}}$  is sampled uniformly along straight lines between pairs of points  $\tilde{x} \sim \mathbb{P}_g$  ———  $x \sim \mathbb{P}_r$
- Penalizing w.r.t each input individually, so no batch normalization in D (e.g. layer normalization instead)

# GAN - WGAN-GP used by MineGAN

WGAN:

Less gradient vanishing/exploding

No mode collapse

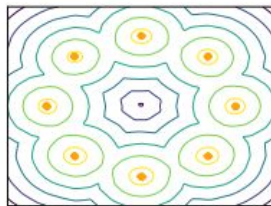
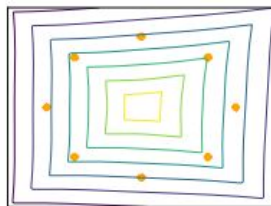


WGAN-GP:

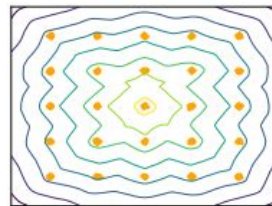
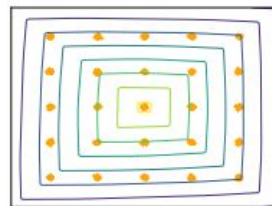
Learning more complex functions

Even less gradient vanishing/exploding

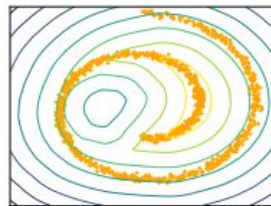
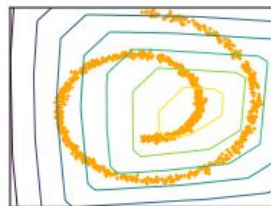
8 Gaussians



25 Gaussians



Swiss Roll



Arjovsky, Chintala, & Bottou. (2017). Wasserstein gan

Gulrajani et al. (2017). Improved training of wasserstein gans

## Other GANs - BigGAN (MineGAN is also applied to)

- Increase batch size (i.e. 8 times)
- Increase number of channels in each layer by 50%
- If conditional, project label embedding (and skip-z) to each BN layer
- “Truncation trick”: trained with  $\mathbf{z} \sim \mathbf{N}(\mathbf{0}, \mathbf{I})$ , during inference resample  $\mathbf{z}$  if it falls outside a thresholded range.  
It increases image quality, but reduces variety.  
Threshold maintains the trade-off

↓  
need to make  $\mathbf{G}$  smooth, so  $\mathbf{z}$   
maps to good output everywhere

↗ Add regularizer to loss:

$$R_{\beta}(W) = \beta \|W^T W \odot (1 - I)\|_F^2$$

# Other GANs - Progressive GAN (MineGAN is also applied to)

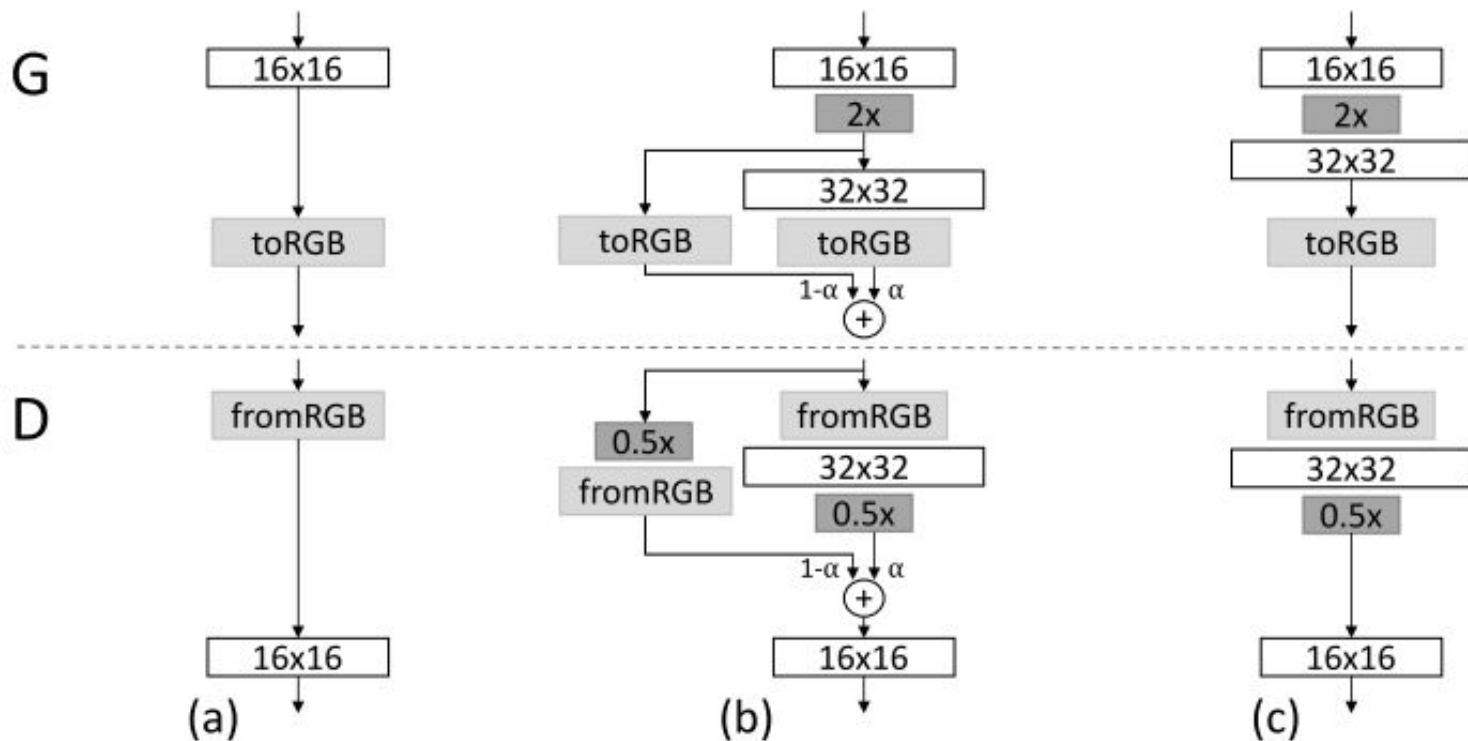
- WGAN loss
- Start training with small res, iteratively add larger layers
- To increase variation, at the end of the D:
  - compute SD over a minibatch for every channel and location
  - average all these values to a single one
  - add one more channel with this mean SD in all locations
- For magnitudes of G and D not to grow out of control, normalize across features at each pixel in G after each conv layer:

$$b_{x,y} = \frac{a_{x,y}}{\sqrt{\frac{1}{N} \sum_{j=0}^{N-1} (a_{x,y}^j)^2 + \epsilon}}$$

features original feature vector  $10^{-8}$



# Other GANs - Progressive GAN (MineGAN is also applied to)



## Other GANs - SNGAN (MineGAN is also applied to)

- Spectral normalization to enforce Lipschitz-1 constraint on **D** and to improve the image quality (better than weight normalization and gradient penalty)

Normalized **D** weight matrix  $\bar{W}_{SN}(W) = \frac{W}{\sigma(W)}$  **D** weight matrix

$$\max_{\|h\|_2 \leq 1} \|Wh\|_2$$

spectral norm, largest singular value

# Related works - TransferGAN

- First knowledge transfer for GANs - **plainly fine-tune all parameters**
- Uses WGAN-GP
- Needs 2-5 times less images than scratch to get same scores
- GANs pretrained on narrow but dense domains perform better even when they are not so related to target domain
- Conditional: **D** has an 'auxiliary classifier', outputs  $P(C = y|x)$

$$\mathcal{L}_{AC-GAN}(G) = \mathcal{L}_{GAN}(G) - \alpha_G \mathbb{E} [\log (P (C = y' | G(z, y')))]$$

$$\mathcal{L}_{AC-GAN}(D) = \mathcal{L}_{GAN}(D) - \alpha_D \mathbb{E} [\log (P (C = y | x))]$$

log likelihoods of the correct class

# Related works - BSA

- To adapt prior knowledge, **fine-tune only these G parameters:**  
BN + introduced scale and shift on all channels of all conv layers

$$G_{Adapt}^{(l)} = G^{(l)} \cdot \gamma^{(l)} + \beta^{(l)}$$

$$\text{conv}(x; W) \cdot \gamma + \beta \quad \text{———} \quad \text{applying scale and shift on the convolution result}$$

$$= \text{conv}(x; W \cdot \gamma + \beta)$$

$$= \text{conv}(x; \{\gamma_1 W_1 + \beta_1, \dots, \gamma_{c_{out}} W_{c_{out}} + \beta_{c_{out}}\})$$

activation strength

activation threshold

Different filters of the layer

# Related works - BSA

- Supervised, estimating  $\mathbf{z}$  of sparse training samples + updating parameters

$$\begin{aligned}
 L = & \sum_i \frac{1}{c_x h_x w_x} \|x_i - G_{Adapt}(z_i + \epsilon)\|_1 \quad \text{Pixelwise MSE} \\
 & + \sum_i \sum_{l \in layers} \frac{\lambda_C^l}{c_l h_l w_l} \|C^{(l)}(x_i) - C^{(l)}(G_{Adapt}(z_i + \epsilon))\| \quad \text{Perceptual loss} \\
 & + \lambda_z \left( \sum_j^k \frac{1}{d_z} \min_i \|z_i - r_j\|_2^2 + \sum_i^b \frac{1}{d_z} \min_j \|z_i - r_j\|_2^2 \right) \quad \text{Regularize } \mathbf{z} \text{ to } \mathcal{N}(0, 1) \\
 & + \lambda_{\gamma, \beta} \sum_l \frac{1}{d_{\gamma, \beta}^l} (\|\gamma_l - 1\|_2^2 + \|\beta_l\|_2^2) \quad \text{Regularize parameters}
 \end{aligned}$$

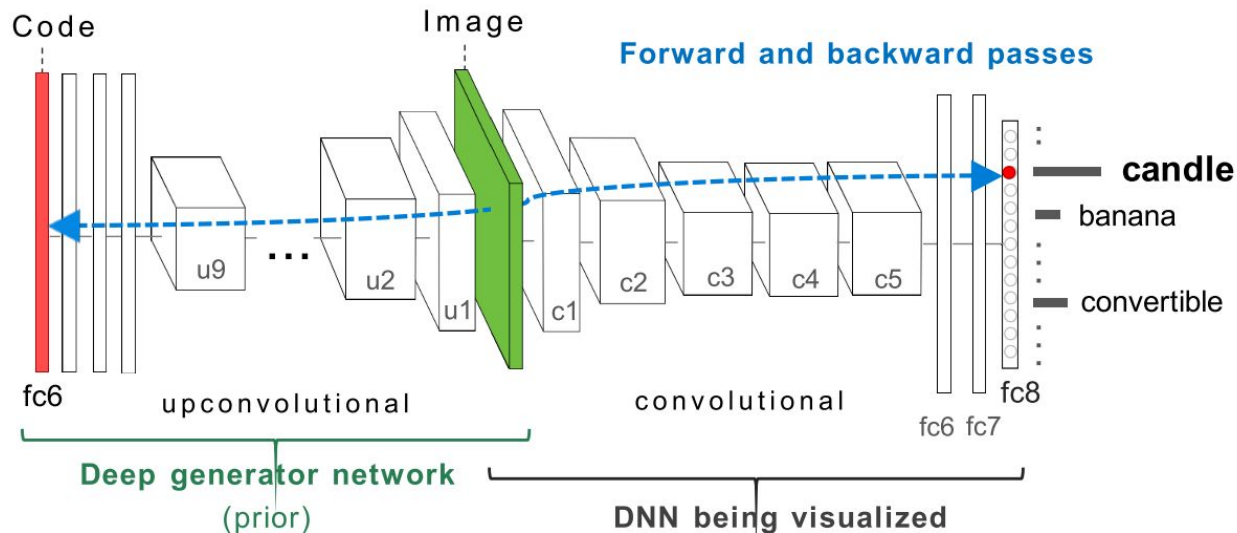
Diagram annotations:
 

- $x_i$ : train image
- $G_{Adapt}(z_i + \epsilon)$ : G output
- $C^{(l)}(x_i)$  and  $C^{(l)}(G_{Adapt}(z_i + \epsilon))$ : classifier CNN
- $r_j$ :  $\sim \mathcal{N}(0, 1)$

# Related works - BSA

- Generator learns sparse  $\mathbf{z}_i - \mathbf{x}_i$  relationships.  
During inference - sample from truncated  $\mathbf{z}$
- Small number of parameters avoids overfitting,  
suitable for very small (<100 images) target sets
- Blurred images because of MSE loss

# Related works - iterative - DGN-AM, PPGN



$$\hat{\mathbf{y}}^l = \arg \max_{\mathbf{y}^l} (\Phi_h(G_l(\mathbf{y}^l)) - \lambda \|\mathbf{y}^l\|)$$

DNN target neuron output      Generated image      Optimised code

Nguyen et al. (2017). Plug & play generative networks: Conditional iterative generation of images in latent space

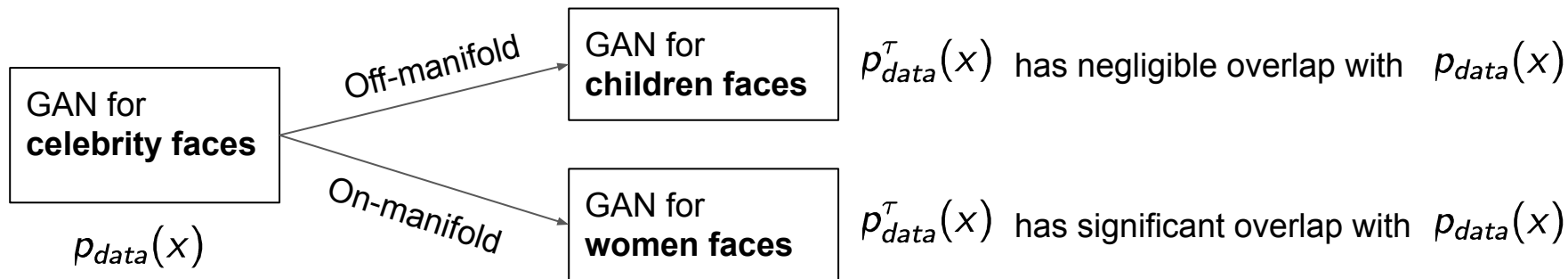
Nguyen et al. (2016). Synthesizing the preferred inputs for neurons in neural networks via deep generator networks<sup>23</sup>

# Problem - transfer from single GAN

Given:

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- D and G trained to approximate a source real images distribution  $p_{data}(x)$  with generative  $p_g(x)$

Produce a new model to approximate  $p_{data}^{\tau}(x)$  with new  $p_g^{\tau}(x)$  using G, D, and  $\mathcal{D}_{\mathcal{T}}$





# MineGAN (w/o FT) - mining

W/o loss of generality, assume  $\mathbf{z} \sim \mathcal{N}(0, 1)$

Learn  $p_g^\tau(x)$  by finding the regions in  $p_g(x)$  that better approximate  $p_{data}^\tau(x)$

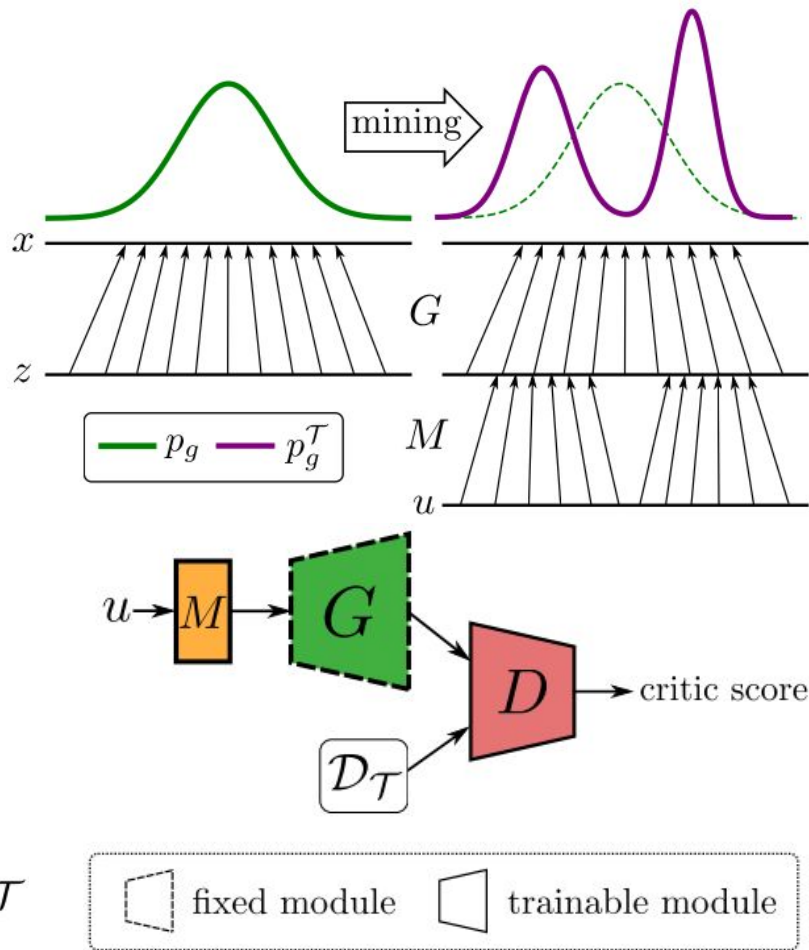


Find new prior  $p_z^\tau(z)$  by transforming  $p_z(z)$  with a miner  $M$  (MLP), training on  $\mathcal{D}_T$ ,  $G$  fixed



Sampling  $\mathbf{z}$  from promising regions of  $\mathbf{z}$  with new learned multimodal distribution

Same for images from  $p_g(x)$ , will be closer to  $\mathcal{D}_T$



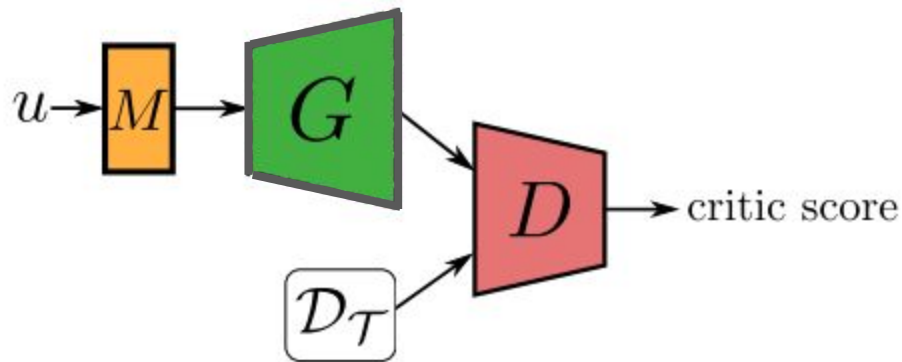
## MineGAN (w/o FT) - mining

$$L_D^M = \mathbb{E}_{u \sim p_z(u)} [D(G(M(u)))] - \mathbb{E}_{x \sim p_{data}^\tau(x)} [D(x)]$$

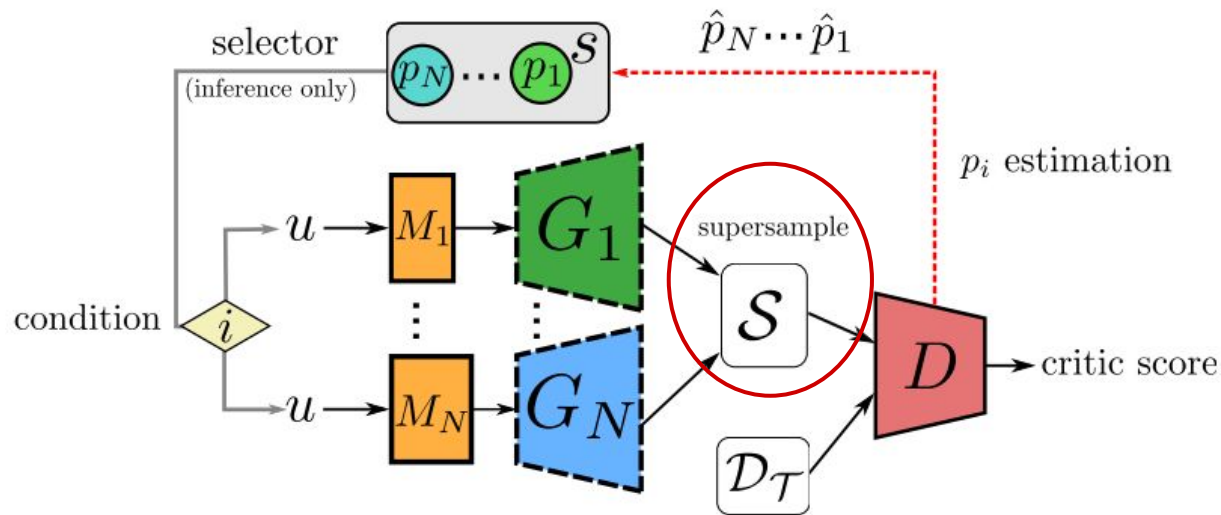
$$L_G^M = -\mathbb{E}_{u \sim p_z(u)} [D(G(M(u)))]$$

# MineGAN - fine-tuning

Since mining step made output closer to  $\mathcal{D}_T$ ,  $G$  can be released and fine-tuned more efficiently and with more stable gradient and lower variance

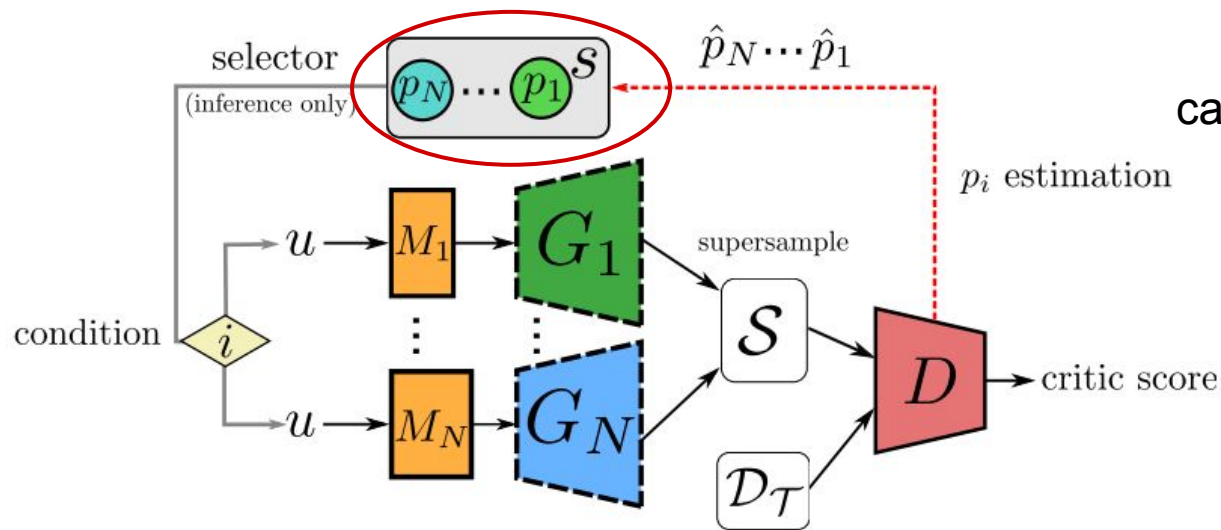


# MineGAN - mining multiple GANs - supersample



a set of samples, 1 per  $G_i$ :  $S = \{G_i(z) | z \sim p_z^i(z); i = 1, \dots, N\}$

# MineGAN - mining multiple GANs - selector



**Training:**

categorical distribution  $p_1 \dots p_N$

$\hat{p}_i$ : for each  $S$  in minibatch,

acc. over  $K$  samples by  $i$

$\operatorname{argmax}_i D(G_i(z))$

normalize by  $K$

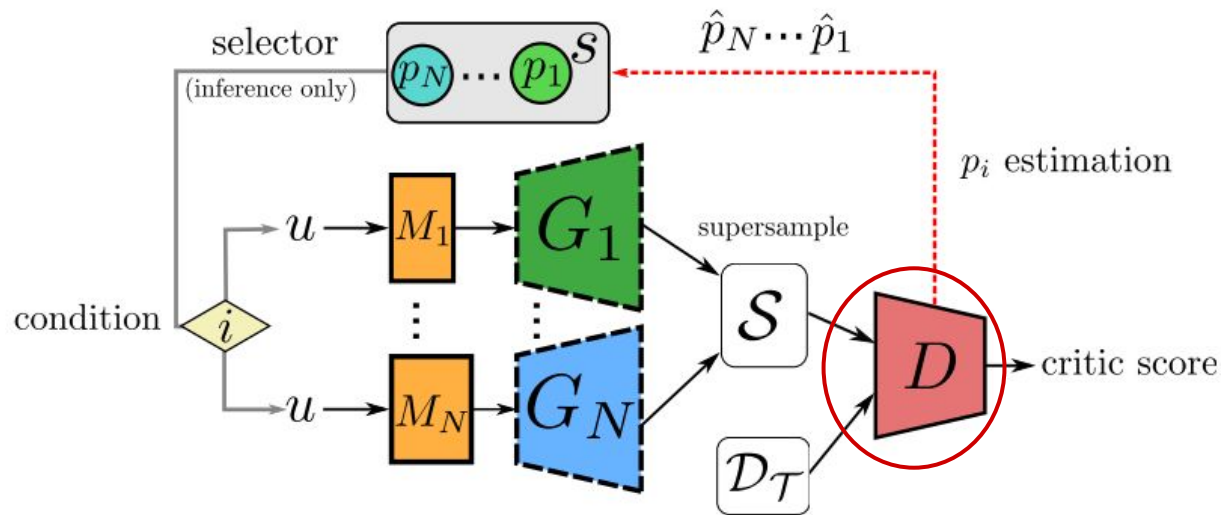
$$p_i = \frac{1}{1000} \sum_{\text{last 1000 batches}} \hat{p}_i$$

$$p_i > 0, \sum p_i = 1$$

**Inference:**

fix  $s$ , sample to get the index of the  $G$  to be used

# MineGAN - mining multiple GANs - critic



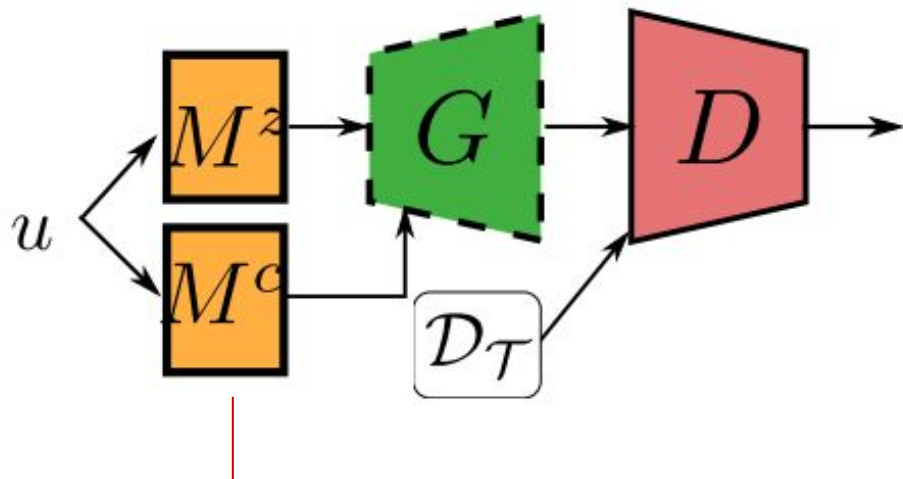
weights from 1 random pretrained critic

## MineGAN - mining multiple GANs - loss

$$L_D^M = \mathbb{E}_{\{u^i \sim p_z^i(u)\}} [\max_i \{ D(G_i(M_i(u^i))) \}] - \mathbb{E}_{x \sim p_{data}^\tau(x)} [D(x)]$$

$$L_G^M = -\mathbb{E}_{\{u^i \sim p_z^i(u)\}} [\max_i \{ D(G_i(M_i(u^i))) \}]$$

# MineGAN - conditional GANs



During mining and FT  
correspondence between  
 $\mathbf{c}$  and  $\mathbf{z}$  is implicitly learned!  
(since both are mapped from  $u$ )

Second miner, maps  $\mathbf{u}$  to a class embedding  $\mathbf{c}$  (any label in target dataset)  
 $\mathbf{c}$  is projected to scale and shift parameters of each BN layer



# MineGAN - overview

Mining - reducing the divergence between source and target distributions

- Less parameters (only  $M$ ) to learn during mining - less overfitting
- Less adaptation during fine-tuning - less overfitting
- Fake images closer to target - more efficient training
- Transfer for conditional GANs does not need target labels
- Does not optimize  $\mathbf{z}$ , but finds more relevant regions

# Evaluation measures - FID

sets of images embedded w/ a CNN to some layer

$$FID(\chi_1, \chi_2) = \underbrace{\|\mu_1 - \mu_2\|_2^2}_{\text{precision}} + \underbrace{Tr(\Sigma_1 + \Sigma_2 - 2(\Sigma_1 \Sigma_2)^{\frac{1}{2}})}_{\text{mutual variance}}$$

- The **lower** the better
- Easy to compute
- Correlates with human perception
- Unstable on small datasets

Wang et al. (2018). Transferring GANs: generating images from limited data

Wang et al. (2020). MineGAN: effective knowledge transfer from GANs to target domains with few images <sup>34</sup>

# Evaluation measures - KMMD w/ Gaussian kernel

- Distance between means of CNN features of images from the 2 sets
- The **lower** the better

as in Noguchi & Harada (2019)

Noguchi & Harada. (2019). Image generation from small datasets via batch statistics adaptation

Wang et al. (2020). MineGAN: effective knowledge transfer from GANs to target domains with few images

# Evaluation measures - MV

- The **higher** the better
- Indicates the variety in the generated images  
(since high variety is challenging for GANs)

## Experiments: 1. MNIST, w/o FT, off-manifold



**5**

**8**

**9**

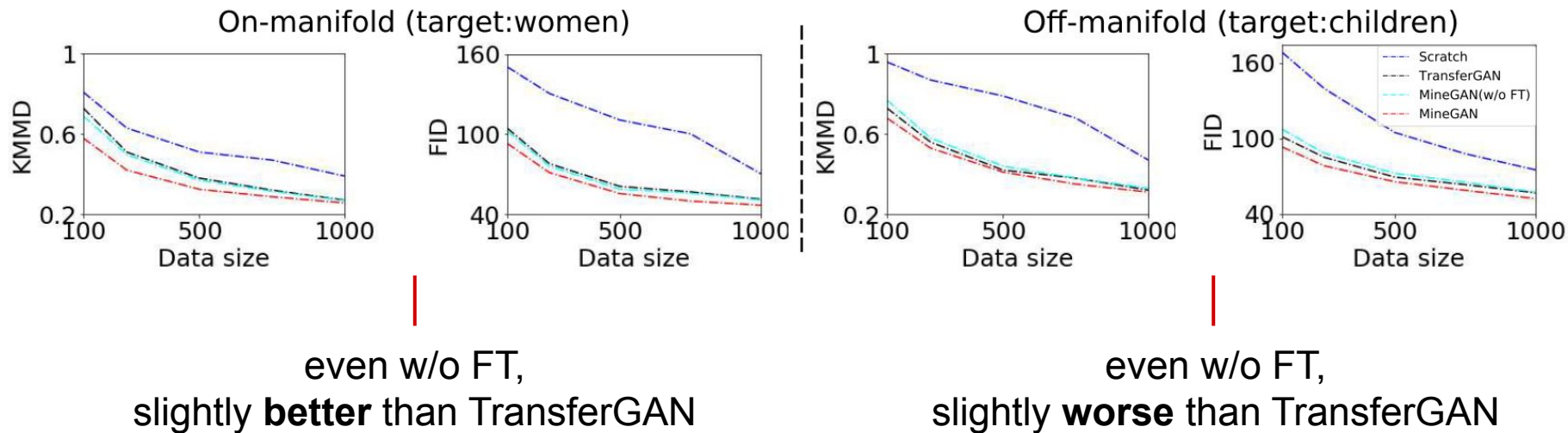
G is pre-trained to synthesize all *MNIST* digits except for the target one

target set: 1000 images 28x28

# Experiments: 2. On- and off-manifold faces, 1 GAN

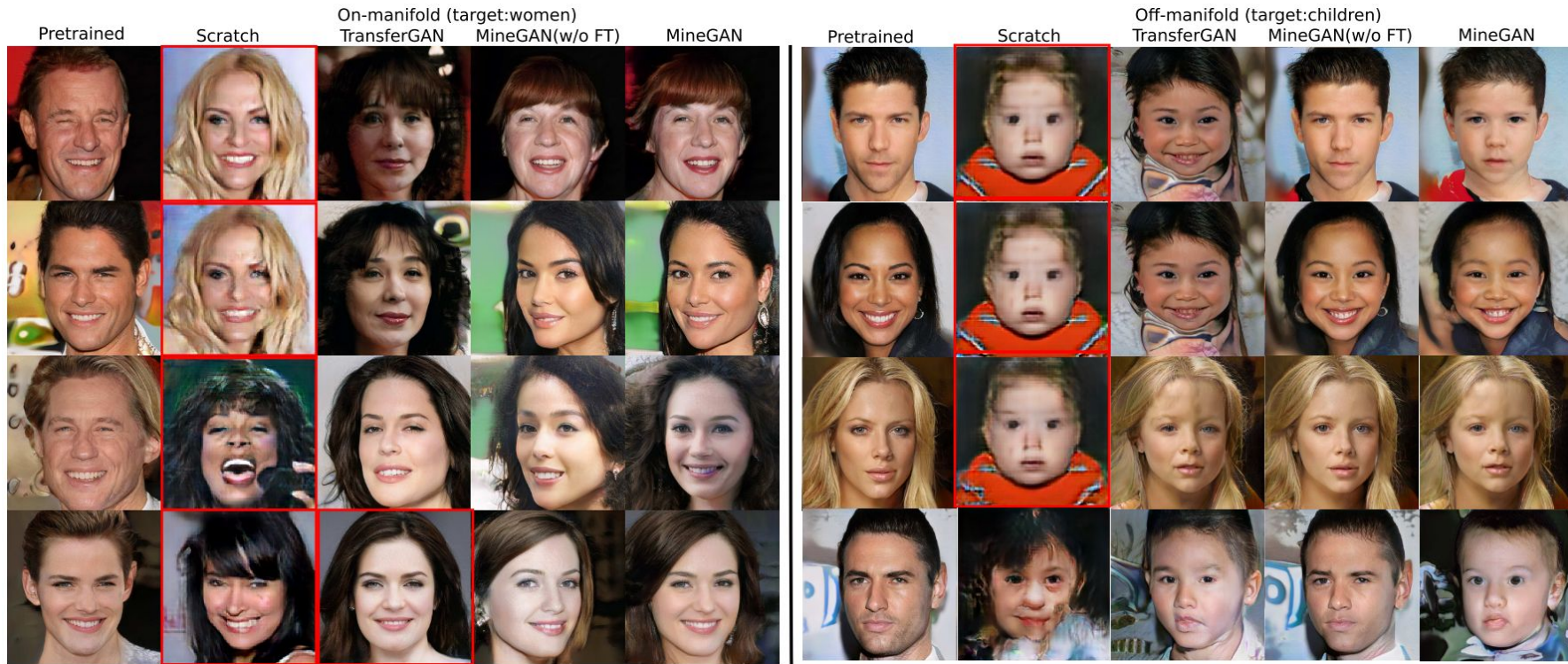
1024 x 1024 images, varying target set size

Progressive GAN pre-trained on *CelebA* -> *FFHQ* women, *FFHQ* children



# Experiments: 2. on- and off-manifold faces, 1 GAN

Target set size - 100 images



## Experiments: 3. Far off-manifold faces, small dataset, 1 GAN

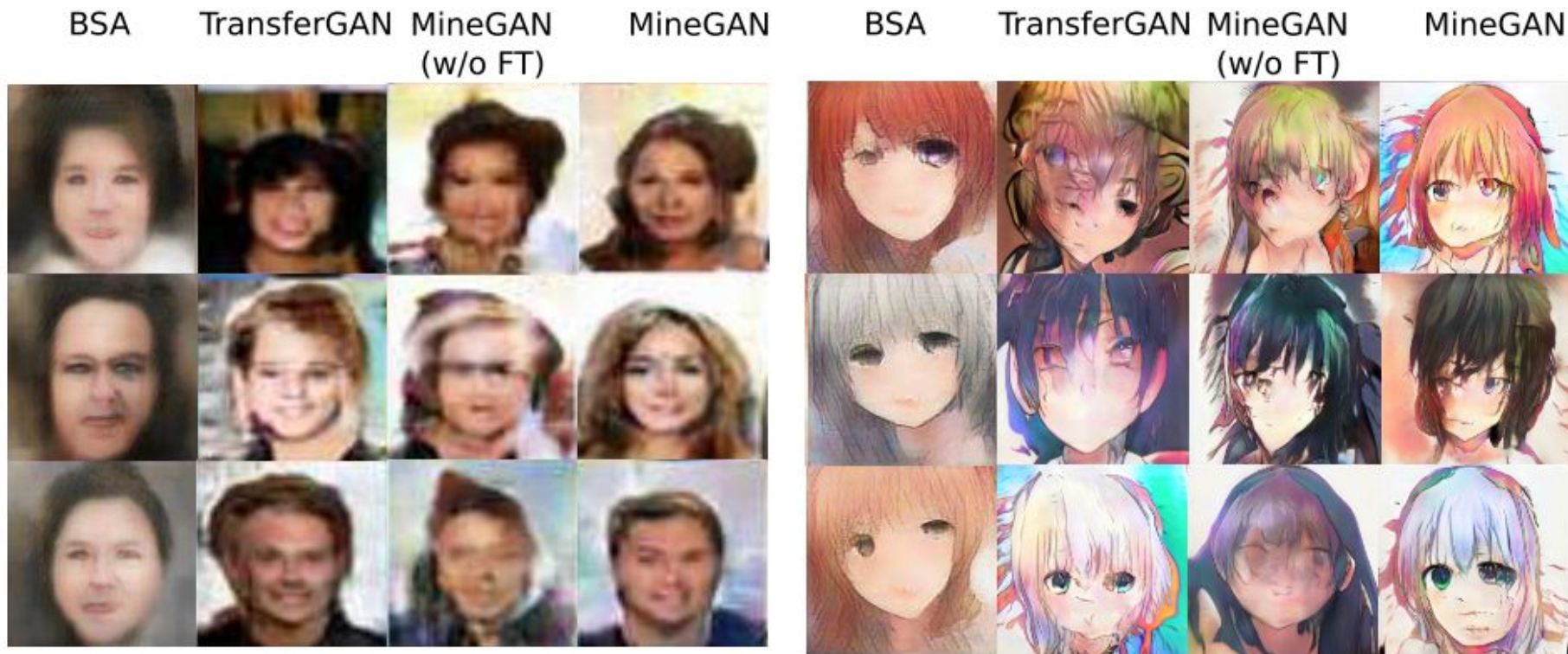
128 x 128 images, target sets sizes - 25 images

SNGAN pre-trained on *ImageNet* -> *FFHQ*, *Anime Face*

	FFHQ		Anime Face	
	KMMD	MV	KMMD	MV
Scratch	0.890	-	0.753	-
TransferGAN	0.346	0.506	0.347	0.785
BSA	0.345	0.785	0.342	0.908
MineGAN (w/o FT)	0.349	0.774	0.347	0.891
MineGAN	<b>0.337</b>	<b>0.812</b>	<b>0.334</b>	<b>0.934</b>



# Experiments: 3. Far off-manifold faces, small dataset, 1 GAN



# Experiments: 4. 2 GANs, target is a mix of subsets from both

256 x 256 images, target set size - 200 images

2 Progressive GANs pre-trained on *LSUN*: 1 on *cars*, 1 on *buses*

-> *Red Vehicles* (red buses + red cars). 3 sets with cars/buses: 3/7, 1, 7/3

	FID	
Scratch	190 / 185 / 196	
TransferGAN (car)	76.9 / 72.4 / 75.6	Estimated Pi:
TransferGAN (bus)	72.8 / 71.3 / 73.5	car: 0.34 / 0.48 / 0.64
MineGAN (w/o FT)	67.3 / 65.9 / 65.8	bus: 0.66 / 0.52 / 0.36
MineGAN	<b>61.2 / 59.4 / 61.5</b>	

# Experiments: 4. 2 GANs, target is a mix of subsets from both

256 x 256  
200 target images



# Experiments: 5. 4 GANs, 2 off-manifold targets

256 x 256 images, target sets sizes - 200 images

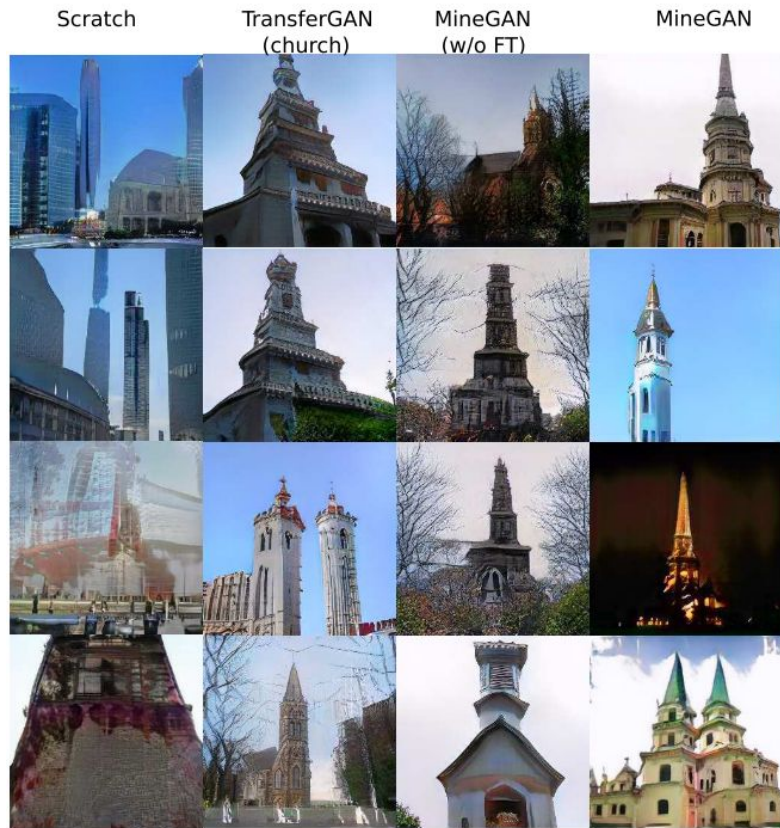
4 Progressive GANs pre-trained on *LSUN: Livingroom, Kitchen, Church, Bridge*  
-> 2 separate *LSUN* targets: *Bedroom, Tower*

	Tower FID	Bedroom FID	Estimated Pi		
				Tower	Bedroom
Scratch	176	181			
TransferGAN (livingroom)	78.9	65.4	livingroom	0.07	0.45
TransferGAN (church)	73.8	71.5	kitchen	0.06	0.40
MineGAN (w/o FT)	69.2	58.9	bridge	0.42	0.08
MineGAN	<b>62.4</b>	<b>54.7</b>	church	0.45	0.07



# Experiments: 5. 4 GANs, 2 off-manifold targets

256 x 256  
target - 200 images



# Experiments: 6. Conditional GANs, off- and on-manifold

Target sets sizes - 500 images per category

BigGAN pre-trained on *ImageNet*

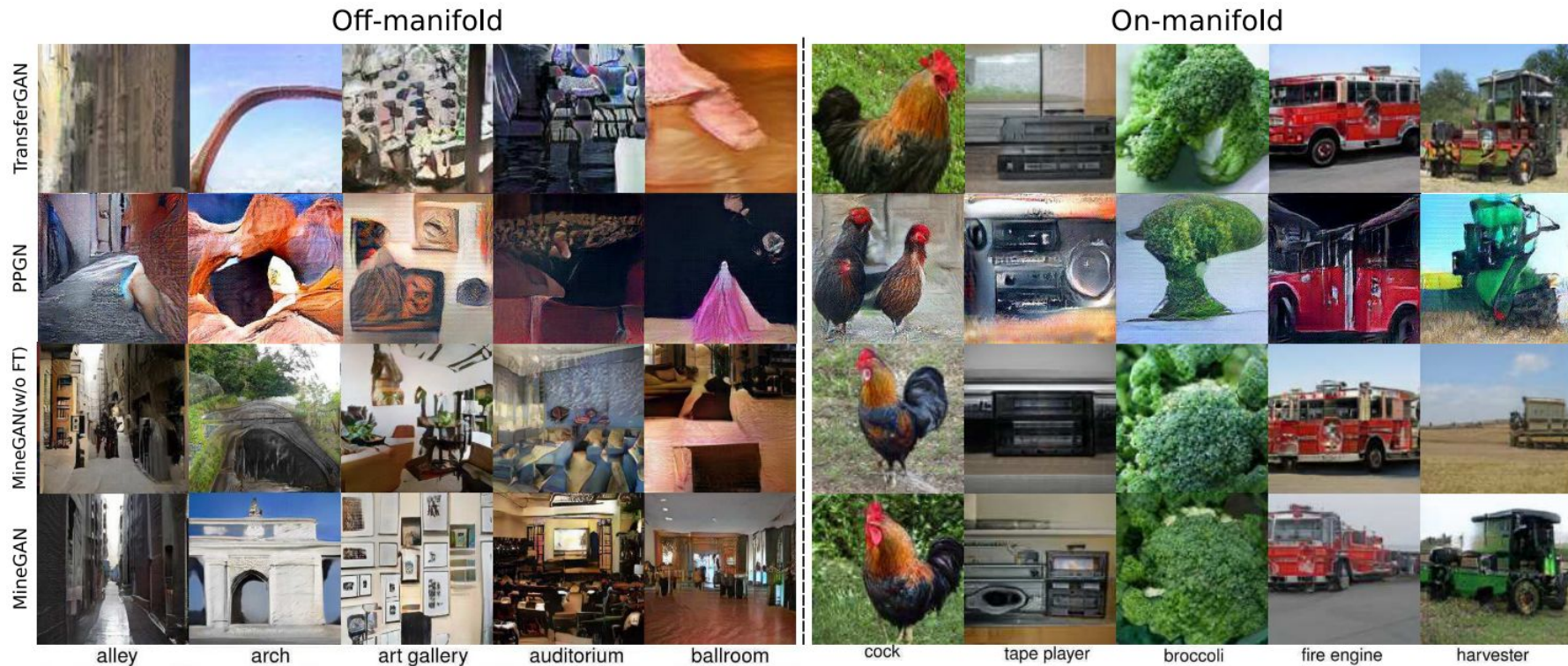
-> (on-manifold) *ImageNet: cock, tape player, broccoli, fire engine, harvester*

-> (off-manifold) *Places365: alley, arch, art gallery, auditorium, ballroom*

## Experiments: 6. Conditional GANs, off- and on-manifold

	Label	Off-manifold FID / KMMD	On-manifold FID / KMMD	Time
Scratch	N/N	190 / 0.96	187 / 0.93	5.1
TransferGAN	N/Y	89.2 / 0.53	58.4 / 0.39	5.1
DGN-AM	Y/Y	214 / 0.98	180 / 0.95	3020
PPGN	Y/Y	139 / 0.56	127 / 0.47	3830
MineGAN (w/o FT)	N/N	<b>82.3 / 0.47</b>	61.8 / <b>0.32</b>	5.2
MineGAN	N/N	<b>78.4 / 0.41</b>	<b>52.3 / 0.25</b>	5.2

# Experiments: 6. Conditional GANs, off- and on-manifold





# MineGAN - conclusions

- New method for GAN knowledge transfer, first to use multiple GANs
- Less overfitting, more efficient, better results
- Works well with small target sets
- Efficiently uses multiple GANs, correctly estimates relevance of each
- Flexible transfer for conditional GANs
- Does not optimize  $\mathbf{z}$ , but finds more relevant regions
- MineGAN (w/o FT) performs comparable w/ SOTA, preserves knowledge
- Can be applied to different GANs

# MineGAN - future research ideas

## MineGAN + BSA

Add shift and scale to all channels of all conv layers.

Mine  $\mathbf{z}$  -> learn how much to use which filters -> (FT all parameters).

## Nested mining

If the target set is far off-manifold (and/or very small),  
but there is another one between source and target -> transfer to it first.

## Visualizing latent space with MineGAN

Have low-dim  $\mathbf{u}$  (2-4) and map it to higher-dimensional  $\mathbf{z}$ .

Then show outputs along different  $\mathbf{u}$  axes.