## Exercise 2 Bridge Oscillations

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In this report the effects of Wind on a poorly designed bridge will be explored.

## 1 Equation of Motion

The model for the structure leads to the following equation of motion:

$$0 = -F_I - F_d - F_e + F_{dr} (1)$$

$$0 = -m\ddot{y} - r\dot{y} - ky + \frac{1}{2}\rho V^2 a C(\alpha). \tag{2}$$

Where  $C(\alpha)$  is a nonlinear function.

## 2 Linear Analysis

 $C(\alpha)$  is defined as a sum of several odd powers of  $\alpha$ :

$$C(\alpha) = A_1 \alpha - \underbrace{A_3 \alpha^3 + A_5 \alpha^5 - A_7 \alpha^7}_{\approx 0 \text{ for small } \alpha.}$$
(3)

for small  $\alpha$  additionally the approximation  $\alpha = \frac{\dot{y}}{V}$  is given. Plugging into 2 yields:

$$0 = -m\ddot{y} + (\frac{1}{2}\rho V a A_1 - r)\dot{y} - ky. \tag{4}$$

Which may be rewritten in terms of two first order equations:

$$\begin{pmatrix} \dot{x} \\ \dot{y} \end{pmatrix} = \begin{pmatrix} \frac{\frac{1}{2}\rho V a A_1 - r}{m} & -\frac{k}{m} \\ 1 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} \tag{5}$$

Setting the derivatives to zero the fixed point  $\mathbf{x}_1^* = \begin{pmatrix} 0 & 0 \end{pmatrix}^T$  is obtained. As a linear approximation as already taken place the Jacobi-matrix is identical to the system matrix given above. Thus for the trace  $\tau_1$  and determinant  $\Delta_1$  at the fixed point the following equations are obtained:

$$\tau_1 = \frac{\frac{1}{2}\rho V a A_1 - r}{m} - \frac{k}{m} \tag{6}$$

$$\Delta_1 = \frac{k}{m}.\tag{7}$$

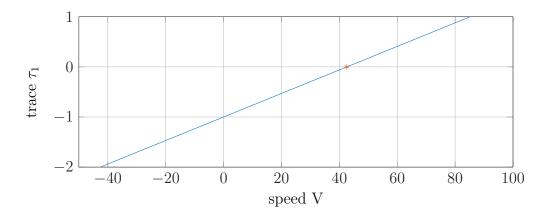


Figure 1: Plot of  $tau_1$  for different speed values. The critical wind speed  $V_c$  is marked with an red asterisk.

Assuming  $(k \wedge m) > 0$  the nature of the fixed point is determined by the trace. The critical value will occur for  $tau_1 = 0$ , therefore it my be found from:

$$0 = \frac{1}{2} \frac{\rho V^2 a A_1}{m V_c} - \frac{r}{m}.$$
 (8)

Solving for  $V_c$  leads to:

$$V_c = \frac{2r}{\rho a A_1} = 42.5985. \tag{9}$$

When m=1,  $\rho=1$ , r=1 k=100, a=1 and  $A_1=100$ . A plot for  $\tau_1$  with respect for different values for V is given in figure 1. As the determinant remains positive at all times the fixed point at the center changes from a stable to an unstable spiral at the critical wind speed  $V_c$ .

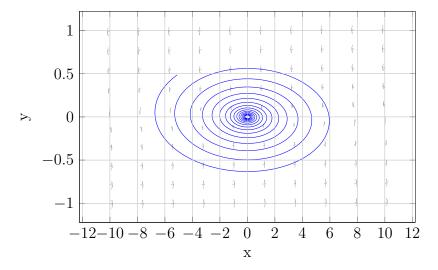


Figure 2: Plot of the two dimensional linearized system with  $V = 10 < V_c$ .

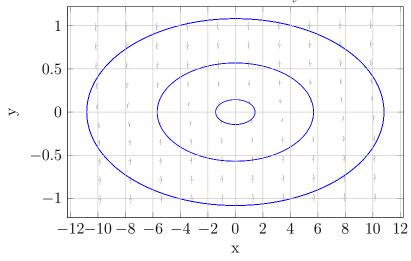


Figure 3: Plot of the two dimensional linearized system with  $V=42.5985=V_c$ .

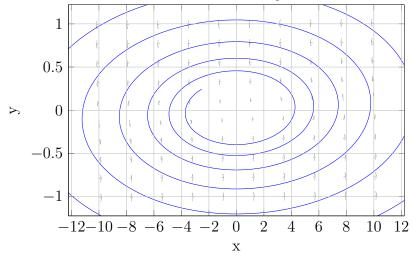


Figure 4: Plot of the two dimensional linearized system with  $V=80>V_c$ .