### The Tortoise and the Hare, Restart GMRES

#### Moritz Wolter

moritzalexander.wolter @ student.kuleuven.de

December 7, 2015





- Recap GMRES
- 2 The Problem
- 3 The problem in 2d
- More on the noise
- 6 Regions of guaranteed convergence

- Recap GMRES
- 2 The Problem
- 3 The problem in 2d
- More on the noise
- Regions of guaranteed convergence

## Recap GMRES (m)

- **1** Start: Choose  $x_0$  and compute  $r_0 = f Ax_0$  and  $v_1 = r_0 / \|r_0\|$
- Iterate: For j = 1,2,...,m do  $h_{i,j} = (Av_i, v_i), i = 1, \dots, j$  $\hat{v}_{i+1} = Av_i - \sum_{i=1}^{j} h_{i,j} v_i$  $h_{i+1,i} = \|\hat{v}_{i+1}\|$ , and  $v_{i+1} = \hat{v}_{i+1}/h_{i+1,i}$
- **3** Form the approximate solution:  $x_m = x_0 + V_m y_m$  where  $y_m$ minimizes  $\|\beta e_1 - H_m y\|, y \in \mathbb{R}^m$
- **1** Restart: Compute  $r_m = f Ax_m$ ; if satisfied stop, else  $x_0 = x_m, v_1 = r_m / ||r_m||$

- Recap GMRES
- 2 The Problem
- 3 The problem in 2d
- More on the noise
- Regions of guaranteed convergence

# GMRES(m) convergence

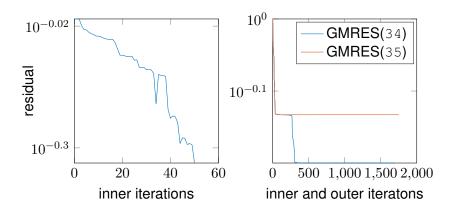


Figure : GMRES(m) convergence on large random matrix  $\mathbf A$  of dimension 60 with  $\mathbf b = [0\dots 1\dots 0]^T$  in blocks of 20 each.



$$\mathbf{A}_{1} = \begin{pmatrix} 1 & 1 & 1 \\ 0 & 1 & 3 \\ 0 & 0 & 1 \end{pmatrix} \mathbf{b}_{1} = \begin{pmatrix} 2 \\ -4 \\ 1 \end{pmatrix} \tag{1}$$

$$\mathbf{A}_2 = \begin{pmatrix} 1 & 2 & -2 \\ 0 & 2 & 4 \\ 0 & 0 & 3 \end{pmatrix} \mathbf{b}_2 = \begin{pmatrix} 3 \\ 1 \\ 1 \end{pmatrix}$$
 (2)

# Gmres convergence

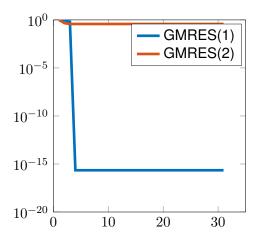


Figure : GMRES convergence on matrix  $A_1$ .



Figure : GMRES convergence on matrix  $\mathbf{A}_2$ .

- Recap GMRES
- 2 The Problem
- 3 The problem in 2d
- More on the noise
- Regions of guaranteed convergence

# Convergence in a two dimesional plane

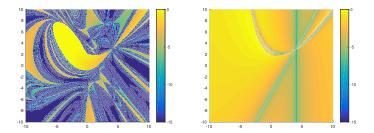


Figure : Residual magnitude Plot for matrix  $A_2, b_2$ , as seen in the Embree paper for GMRES(1)(left) and GMRES(2)(right) in figure 4.

# Convergence in a two dimesional plane

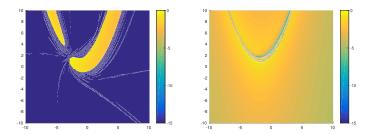


Figure : Residual magnitude Plot for the  $A_1$ ,  $b_1$  pair, as seen in the Embree paper GMRES(1)(left) and GMRES(2)(right) in figure two.

# Conditioning makes a difference.

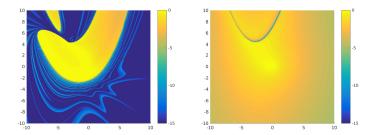


Figure : GMRES (1) and GMRES (2) convergence on  ${\bf A}-0.35\cdot {\bf I}.$   $\kappa({\bf A})=14.2950$  changes to  $\kappa({\bf A}-0.35\cdot {\bf I})=39.1873.$ 

#### A random matrix.

$$\mathbf{R} = \begin{pmatrix} -0.3034 & 0.8884 & -0.8095\\ 0.2939 & -1.1471 & -2.9443\\ -0.7873 & -1.0689 & 1.4384 \end{pmatrix}$$
 (3)

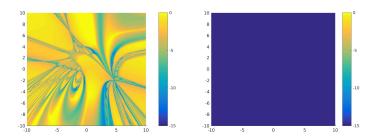


Figure : Convergence of <code>GMRES(1)</code> (left) and <code>GMRES(2)</code> (right) for the random matrix  ${\bf R.}~\kappa({\bf R})=5.1025$ 

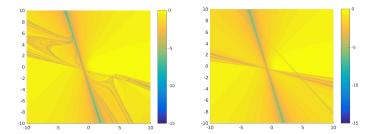


Figure : Convergence results for  $\mathbf{R} + 2\mathbf{I}$ .  $\kappa(\mathbf{R} + 2\mathbf{I}) = 77.5446$ .

5

-10 -10

-5

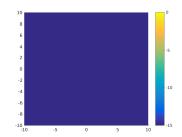


Figure : Convergence results for  ${\bf R}+3{\bf I}.~{\bf R}+3{\bf I}=6.4262.$ 

$$\mathbf{C} = \begin{pmatrix} 1 & -2 \\ 0 & 1 \end{pmatrix} \quad \mathbf{r_0} = \begin{pmatrix} \xi \\ \eta \end{pmatrix} \tag{4}$$

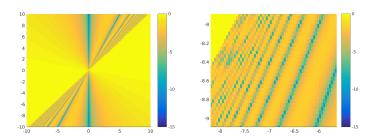
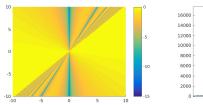


Figure : A plot of the convergence plain for the matrix  ${\bf C}$  proposed at the end of Embree's paper. With zoom on an interesting region.

- Recap GMRES
- 2 The Problem
- 3 The problem in 20
- More on the noise
- Regions of guaranteed convergence



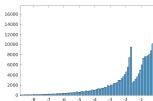


Figure : Convergence Plain and error histogram for matrix  ${\bf C}.$ 

- $\mathcal{D}_1 = 10^{-1} + \|\mathcal{N}(0, 2.5 \cdot 10^{-3})\|$
- $D_2 = 10^{-5} + ||\mathcal{N}(0, 2.5 \cdot 10^{-3})||$

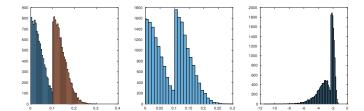


Figure : Plots of the distributions generated by d1 = 0.00001 +0.05\*abs(randn(10000,1)); d2 = 0.1 +0.05\*abs(randn(10000,1)); . The last plot is on a semilogarithmic scale.

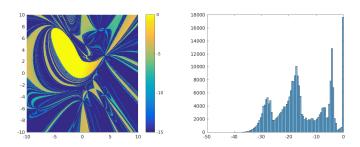


Figure : Convergence Plain and error histogram for matrix  ${\bf A}.$ 

- Recap GMRES
- 2 The Problem
- 3 The problem in 2d
- More on the noise
- 6 Regions of guaranteed convergence

show the convergence regions from the paper.