

# An Experimental Comparison of Min-Cut/Max-Flow Algorithms for Energy Minimization in Vision

FINAL RESTITUTION

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# OUTLINE

- I. Overview
- II.  $\alpha$  - Expansion
- III.  $\alpha$ - $\beta$  Swap
- IV. Image Segmentation
- V. Application



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## Energy minimization with graph cuts

- Graph Cuts can find the optimal solution to a binary problem.
- When each pixel can be assigned many labels, an algorithmic solution can be computationally expensive.
- Graph Cuts can be used to minimize the following kind of energy law:

Constraints to the smoothing term:

$$1) V(\alpha, \beta) = 0 \Leftrightarrow \alpha = \beta$$

$$2) V(\alpha, \beta) = V(\beta, \alpha) \geq 0$$

$$3) V(\alpha, \beta) \leq V(\alpha, \gamma) + V(\gamma, \beta)$$

Constraints 1 and 2: semi - metric, sufficient for  $\alpha$ - $\beta$  Swap.

All the constraints: metric, necessary for the  $\alpha$ -expansion.

$$E(f) = \sum_{p \in \mathcal{P}} D_p(i_p, f_p) + \sum_{p, q \in \mathcal{N}} V_{p, q}(f_p, f_q)$$

Data term - assures current label  $f$  is coherent with observe data  $i$

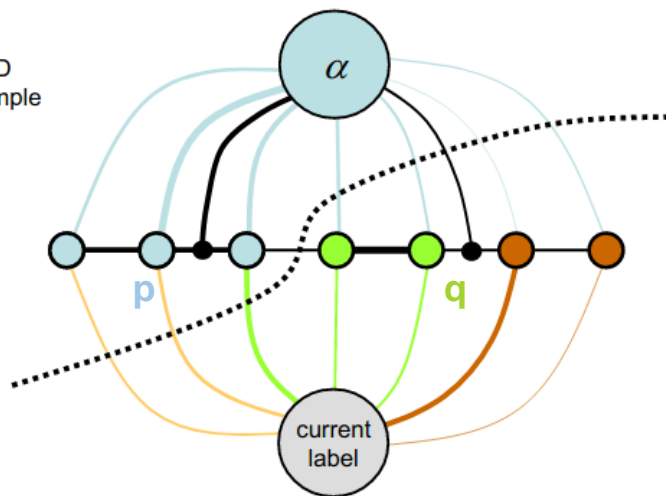
Smooth (regularization) term - assures overall labelling is smooth, penalizes great differences between neighboring pixels.

## II. $\alpha$ - expansion

### Algorithm

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1D  
example



1. Start with an arbitrary labeling  $f$
2. Set  $\text{success} := 0$
3. For each label  $\alpha \in \mathcal{L}$ 
  - 3.1. Find  $\hat{f} = \arg \min E(f')$  among  $f'$  within one  $\alpha$ -expansion of  $f$  (Section 4)
  - 3.2. If  $E(\hat{f}) < E(f)$ , set  $f := \hat{f}$  and  $\text{success} := 1$
4. If  $\text{success} = 1$  goto 2
5. Return  $f$

a Cycle

Obs: Being  $c$  the global minima of  $E(f)$  when the  $\alpha$  - expansion is used is guaranteed to find a convergence in the direction of this minima within a factor of 2 in the best case.

$$2c = 2 \max_{p,q \in \mathcal{N}} \frac{\max_{\alpha \neq \beta} V(\alpha, \beta)}{\min_{\alpha \neq \beta} V(\alpha, \beta)}$$

## II. $\alpha$ - expansion

### Constructing the graph

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Weights to each kind of edge in the graph constructed for the alpha expansion:

$$w(\alpha, p) = D(\alpha)$$

$$w(\bar{\alpha}, p) = D(f_p) \rightarrow \text{if } p \notin \mathcal{P}_\alpha$$

$$w(\bar{\alpha}, p) = \infty \rightarrow \text{if } p \in \mathcal{P}_\alpha$$

$$w(p, a) = V(f_p, \alpha); w(a, q) = V(f_q, \alpha)$$

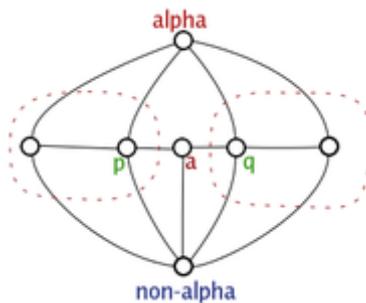
$$w(p, q) = V(f_p, \alpha) \text{ when } \rightarrow f_p = f_q$$

$$w(a, \bar{\alpha}) = V(f_p, f_q)$$

Rules for decision after performing a min cut algorithm:

$$(p - \alpha) \text{ cut} \rightarrow p \in \alpha$$

$$(p - \bar{\alpha}) \text{ cut} \rightarrow p \in \bar{\alpha}$$

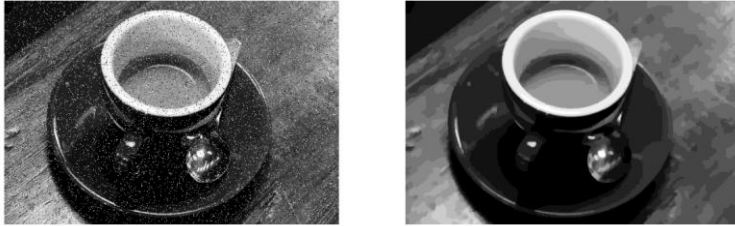


## II. $\alpha$ - expansion

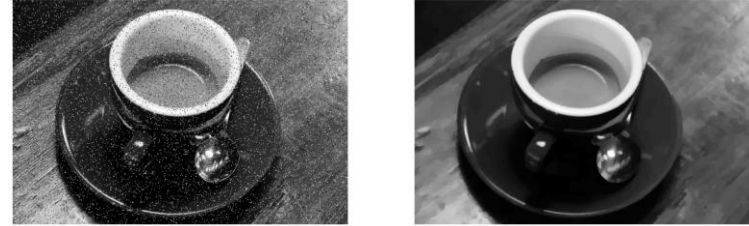
6

### Reconstruction with $\alpha$ - expansion

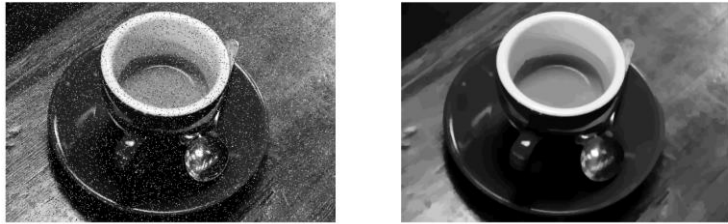
16 levels of gray - Time: 3.01s



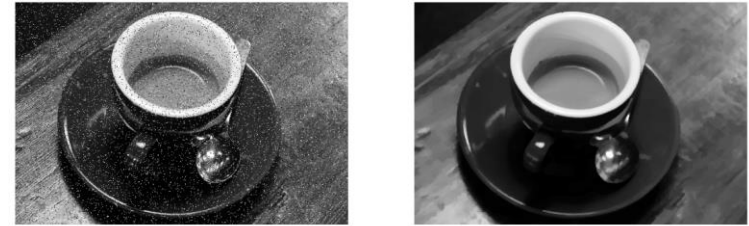
64 levels of gray - Time: 16.76s



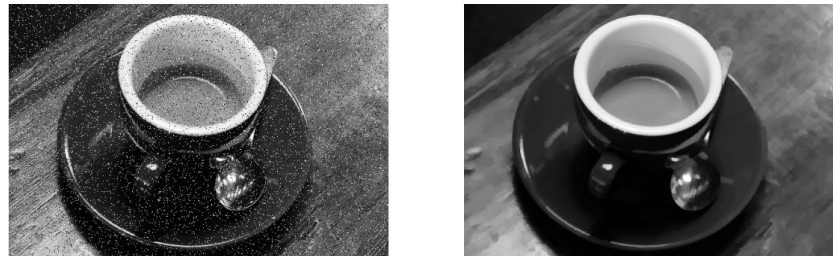
32 levels of gray - Time: 7.14s



128 levels of gray - Time: 39.52s



256 levels of gray - Time: 89.07s



Experiments conducted with images which salt and pepper noise were added.

## Algorithm

a Cycle

1. Start with an arbitrary labeling  $f$  of the image
2. Set  $\text{success} := 0$
3. For each pair of labels  $\{\alpha, \beta\} \in \text{a set of labels } \mathcal{L}$ 
  - 3.1. Find  $\hat{f} = \operatorname{argmin} E(f')$  among  $f'$  within one  $\alpha - \beta$  swap of  $f$  [Graph Cut]
  - 3.2. If  $E(\hat{f}) < E(f)$ , set  $f := \hat{f}$  and  $\text{success} := 1$
4. If  $\text{success} = 1$ , go to 2
5. Return  $f$

**Image restoration:** labels are all distinct pixel values in a image

## Graph construction and Energy specification

For each  $\alpha$ - $\beta$  Swap in a **Cycle**:

- Build a  $\alpha$ - $\beta$  swap graph for pixels having  $\alpha$  or  $\beta$  density values (by weighting the t-links and n-links).
- Apply the graph cut algorithm to find a cut  $C$  yielding the minimum energy.
- The cut  $C$  will redetermine density values for the graph's pixels.

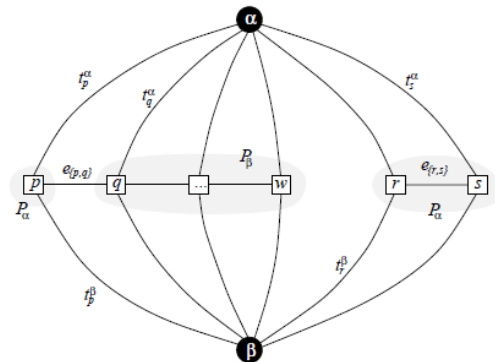


Fig 1. Graph construction in the  $\alpha$ - $\beta$  swap.

edge	weight	for
$t_p^\alpha$	$D_p(\alpha) + \sum_{\substack{q \in \mathcal{N}_p \\ q \notin \mathcal{P}_{\alpha\beta}}} V_{\{p,q\}}(\alpha, f_q)$	$p \in \mathcal{P}_{\alpha\beta}$
$t_p^\beta$	$D_p(\beta) + \sum_{\substack{q \in \mathcal{N}_p \\ q \notin \mathcal{P}_{\alpha\beta}}} V_{\{p,q\}}(\beta, f_q)$	$p \in \mathcal{P}_{\alpha\beta}$
$e_{\{p,q\}}$	$V_{\{p,q\}}(\alpha, \beta)$	$\{p,q\} \in \mathcal{N}$ $p, q \in \mathcal{P}_{\alpha\beta}$

Table 1. Edge weight assignments in the  $\alpha$ - $\beta$  Swap



## Experience setting

Seeking a labeling  $f$  minimize the following defined energy:

### Data term:

$$E_{data}(f) = \sum_{p \in P} (f_p - i_p)^2$$

where  $i_p$  is the observed intensity of the pixel  $p$

- Tested three different potentials for the smoothness term.
- Image tests were generated with pepper & salt noises (10%, 15%, 25% noisy pixels)

### Smoothness term:

$$E_{smooth} = \sum_{\{p,q\} \in E} V_{\{p,q\}}(f_p, f_q)$$

Linear  
potential

$$V_{\{p,q\}}(f_p, f_q) = \text{abs}(f_p - f_q)$$

Truncated  
linear potential

$$V_{\{p,q\}}(f_p, f_q) = \min(200, \text{abs}(f_p - f_q))$$

Potts

$$V_{\{p,q\}}(f_p, f_q) = \begin{cases} 255 & \text{if } \text{abs}(f_p - f_q)^2 > 255 \\ 0 & \text{otherwise} \end{cases}$$

## Results

- The minimum energy value bases on the potential type on which the energy is calculated.
- The algorithm was run in **one** cycle of the  $\alpha$ - $\beta$  swap algorithm.
- After 300 s, the energy began to converge to the minimum value.
- In **one** testing cycle: the lower noisy pixels, the lower value the energy converges to.

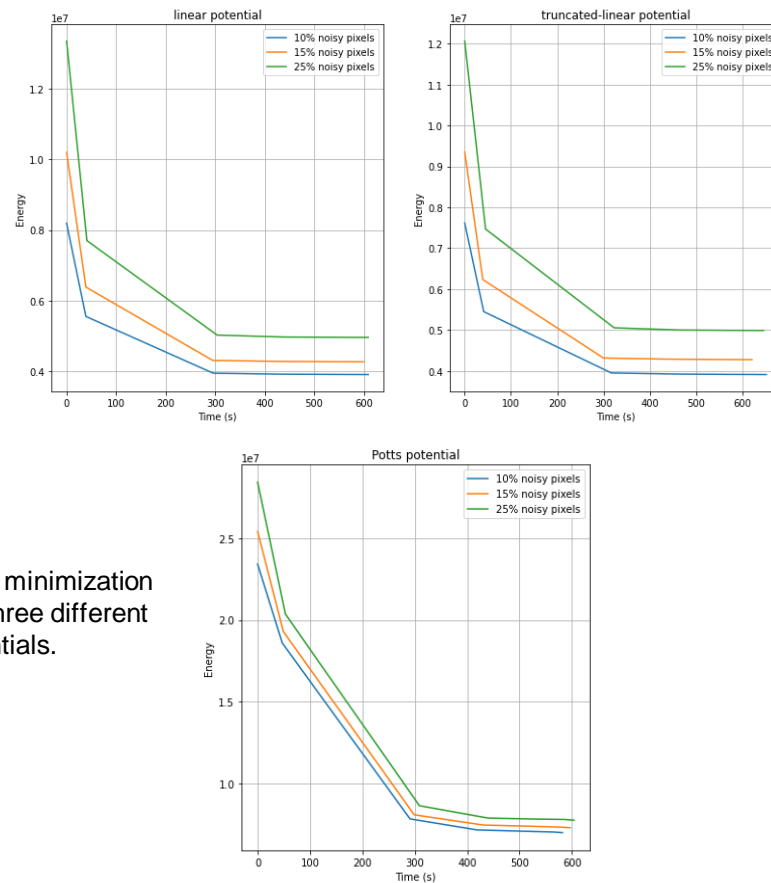
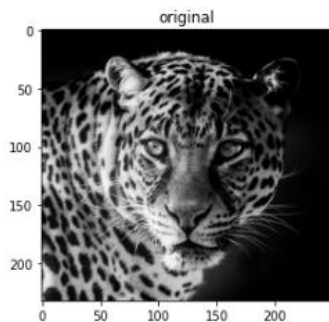


Fig 2. Energy minimization process for three different potentials.

## Results



Noisy pixels	Peak signal noise ratio		
	Linear	Truncated linear	Potts
10%	21.82	21.75	20.25
15%	24.31	24.23	19.45
25%	20.8	20.75	18.02

Table 2. PSNR image restoration

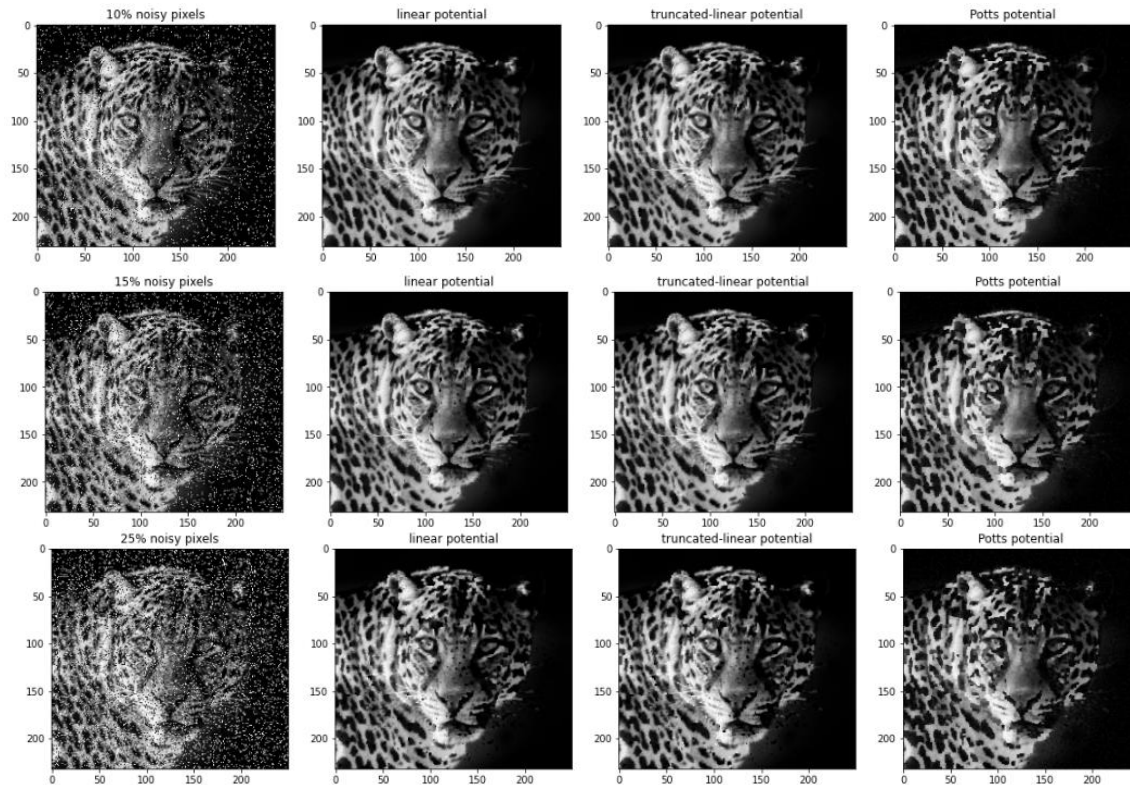


Fig 3. Image restoration results

## Experiment setting

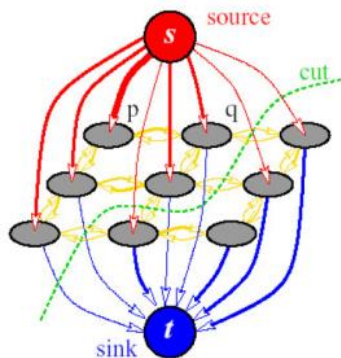


Fig . Image segmentation graph representation

- Two labels: background (sink), foreground (source).
- Seeds added as hard constraints => reduce large feasible solutions.

### Region term:

pixel	$R_p(obj)$	$R_p(bkg)$
bkg seed	0	K
obj seed	K	0
others	0	0

### Boundary term:

$$B_{\{p,q\} \in N} = \frac{1}{1 + \|p - q\|_2^2}$$

- $p, q$  are neighboring pixels (RGB).
- $B_{pq}$  small when  $p, q$  are different.
- $K = \max(B_{pq}) \forall p, q \in N$ .
- $B_{pq} = B_{qp}$ .

## Results

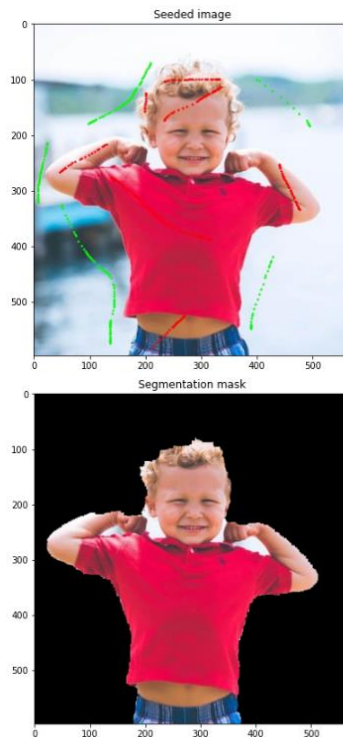
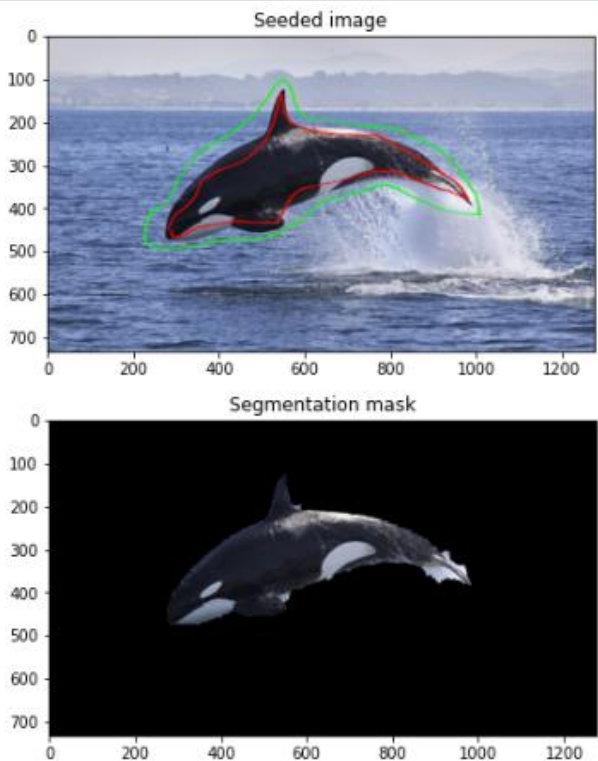


	Image size	Segmentation time (s)
hat	(181,229,3)	1.20
baby	(596,571,3)	10.15
whale	(733,1277,3)	26.85

Table 3. Computational time

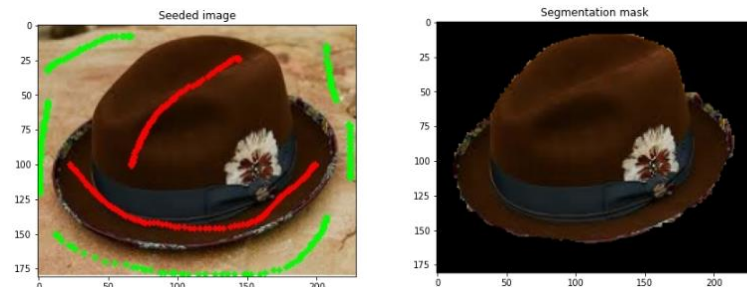
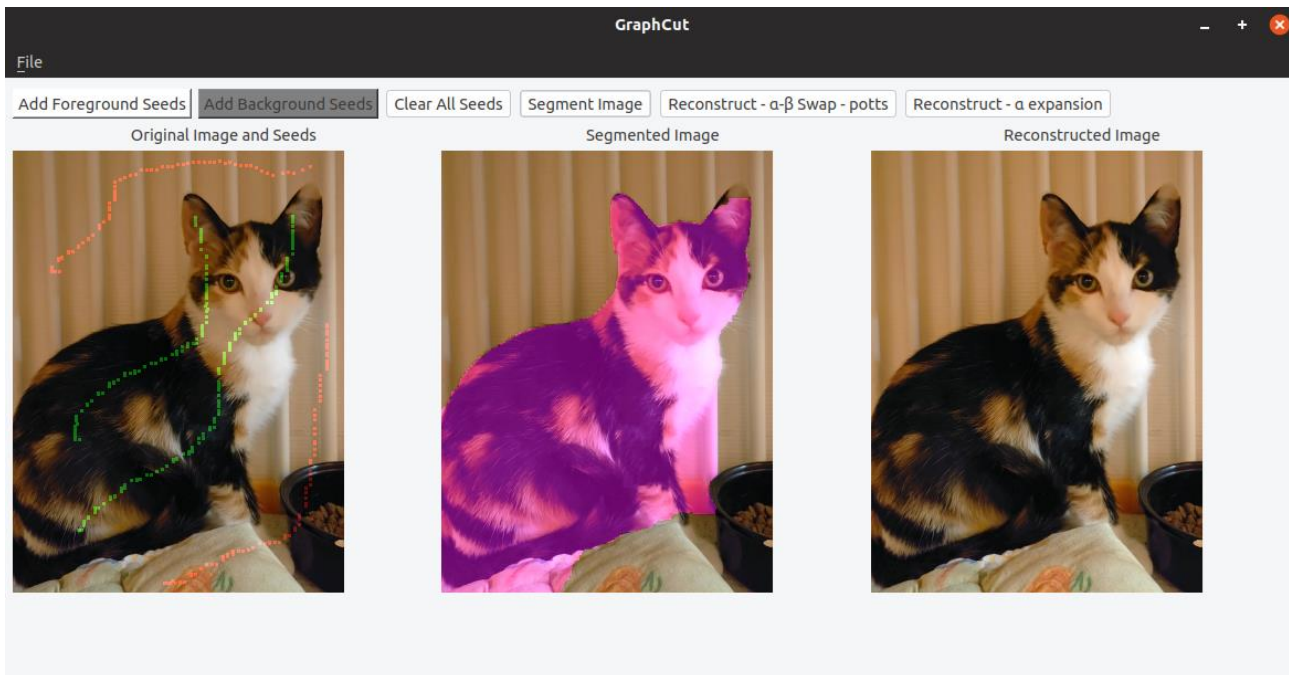


Fig 4. Seeded images and segmentation masks.



An application to illustrate the different algorithms is proposed in an interactive application.

The requirements are the following:

- pyQT 4
- Pillow
- cv2
- Numpy
- Pymaxflow

Obs: The two different reconstructions may take a while to complete the execution. All reconstructions are performed with the grayscale image.

To install all requirements is necessary to execute in a terminal:

```
apt install python3-pyqt4
```

```
pip install -r requirements.txt
```

To launch the application is sufficient to execute: `python3 Graph_cut_UI.py`