

General Self-Consistent Field Methods

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1 Introduction

The Schrodinger equation is a certain class of Boundary Value Problem (BVP). Solution of the Schrodinger equation results in the eigenvalues(λ) and eigenvectors (ψ) of the Hamiltonian.

$$\mathcal{L}\psi(x) = \lambda\psi(x)$$

These type of equations where \mathcal{L} is a second order differential operator and self-adjoint (i.e. hermitian) is called a Sturm-Liouville problem (SLP). Sturm-Liouville problems are general eigenvalues problems of the form

$$-\frac{d}{dt} \left(p(t) \frac{dy(t)}{dt} \right) + q(t)y(t) = \lambda g(t)y(t)$$

posed on an interval $-\infty \leq a \leq b \leq \infty$ which may be finite or infinite. Such problem's arise in various fields of physics and chemistry and there exist robust and well studied numerical and analytical methods for their resolution.

In the present manuscript, we shall document numerical methods for the solution of various types of Hamiltonians and analyze their spectra and wavefunctions.

2 Hydrogen atom

We begin with the most simplest SLP which is the solution of the Hamiltonian for the hydrogen atom Eq:??

$$\hat{H}\psi(\mathbf{x}) = \left[-\frac{1}{2} \Delta + V \right] \psi(\mathbf{x})$$

This is the SLP(Eq:??) with $p(t) = \frac{1}{2}$, and $g(t) = 1$, and $q(t) = V$, the potential acting on the particle. The Eq:?? is in cartesian coordinates \mathbf{x} and can be transformed to spherical coordinates via a coordinate transformation.

$$x_1 = r \sin \theta \cos \phi$$

$$x_2 = r \sin \theta \sin \phi$$

$$x_3 = r \cos \theta$$

In spherical coordinates, the operator \hat{H} is transformed to

$$\begin{aligned} \hat{H} = & -\frac{1}{2} \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial}{\partial r} \right) \\ & -\frac{1}{r^2} \frac{1}{\sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial}{\partial \theta} \right) \\ & -\frac{1}{r^2} \frac{1}{\sin^2 \theta} \frac{\partial^2}{\partial \phi^2} + V \end{aligned}$$

We can then separate the wavefunction to three independent variables $\psi(\mathbf{x}) = R(r)\Theta(\theta)\Phi(\phi)$ to obtain three separate SLPs

$$\left(-\frac{1}{2} \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial}{\partial r} \right) + \frac{l(l+1)}{r^2} + V(r) \right) R(r) = \lambda R(r)$$

$$\frac{1}{\sin \theta} \left(-\frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial}{\partial \theta} \right) + \frac{m^2}{\sin^2 \theta} \right) \Theta(\theta) = l(l+1)$$

$$\Theta(\theta) - \frac{\partial^2}{\partial \phi^2} \Phi(\phi) = m^2 \Phi(\phi)$$

With only r being the dependent variable i.e. the first equation. Here we can do a further transformation of the dependent variable $u(r) = rR(r)$ which gives the SLP

$$-\frac{1}{2} \frac{\partial^2 u(r)}{\partial r^2} + q(r)u(r) = \lambda u(r)$$

$$q(r) = \frac{l(l+1)}{r^2} + V(r)$$

$$p(r) = g(r) = 1$$

These (Eq:??) are the working equations.

2.1 Methodology

First, we transform Eq:?? into a set of coupled linear ODEs

$$y = \begin{pmatrix} u \\ u' \end{pmatrix}$$

$$y' = \begin{pmatrix} u' \\ u'' \end{pmatrix} = \begin{pmatrix} u' \\ 2 \left(\frac{l(l+1)}{r^2} - \frac{z}{r} - E \right) u \end{pmatrix}$$

The boundary conditions are at $r = 0$ and $r = \infty$ with $u(r) = 0$ and $u(\infty) = 0$.

1. Vector Field

```
def vectorfield(w, t, p):
    """
    Defines the differential equations for the coupled spring-mass system.

    Arguments:
    w : vector of the state variables:
        w = [x1,y1,x2,y2]
    t : time
    p : vector of the parameters:
        p = [m1,m2,k1,k2,L1,L2,b1,b2]
    """
    x1, y1 = w
    e1, l1, urf, tckur, _, _, _, _, z = p

    # Create f = (x1',y1'):
    f = [y1,
         2*(l1*(l1+1)/(t)**2 - z/(t) - e1 + urf(t,tckur)/t)*x1
        ]

    return f
```

2. Solution

```
def solve_SLP(fn=None, tckfn=None, fnx=None, tckfnx=None, fnc=None, tckfnc=None,

    if fn is None:
        def fn(x,tckfn):
```

```

        return(0.)

if fnx is None:
    def fnx(x,tckfnx):
        return(0.)

if fnc is None:
    def fnc(x,tckfnc):
        return(0.)

if vectorfield is None:
    print("[solve_SLP] Error: Have to supply a vectorfield")
    return(0,0,0)

# Parameter values
# Initial conditions
# x1 and x2 are the initial displacements; y1 and y2 are the initial velocities
x1 = xlim
y1 = ylim

# ODE solver parameters
abserr = 1.0e-8
relerr = 1.0e-6

# Create the time samples for the output of the ODE solver.
# I use a large number of points, only because I want to make
# a plot of the solution that looks nice.
if t is None:
    t = [stoptime * float(i+0.0001) / (numpoints - 1) for i in range(numpoints)]

# Reverse the list to converge from the right
t_rev = t[::-1]

# Pack up the parameters and initial conditions:
p = [e1, l1, fn, tckfn, fnx, tckfnx, fnc, tckfnc, z]
w0 = [x1, y1]

# Call the ODE solver.
wsol = odeint(vectorfield, w0, t_rev, args=(p,),
              atol=abserr, rtol=relerr)

```

```

x1 = wsol[:,0]

# Reverse the result back
x1 = x1[::-1]

if isWF:
    # Normalize wavefunction
    norm = integrate.simps(x1**2, x=t)
    x1 = x1/np.sqrt(norm)

tckfnout = interpolate.splrep(t,x1)

def fnout(x, tck):
    return interpolate.splev(x, tckfnout)
return(x1,fnout,tckfnout)

```

2.1.1 Shooting method

Here we start with $u(\infty) = 0$ and integrate towards $r = 0$. This is more stable for the convergence with respect to the Hydrogen atom.

2.1.2 Code

Main function that does the shooting.

```

def shoot(E, t, l=0, z=1., fn=None, tckfn=None, fnx=None, tckfnx=None, fnc=None, tckfnc=None, vectorfield=None):
    if vectorfield is None:
        print("[shoot] Error: Have to supply a vectorfield")
        return(0,0,0,0)
    u,fnout,tckfnout= solve_SLP(fn=fn, tckfn=None, fnx=fnx, tckfnx=tckfnx, fnc=fnc, tckfnc=tckfnc, t=t, E=E, l=l, z=z)
    u = u/t**l

    # Extrapolate u to the origin r=0.
    return u[0] - t[0] * (u[1] - u[0])/(t[1] - t[0]), u, fnout, tckfnout

```

2.1.3 Testing

Test the function.

```

rr = np.logspace(-6, 5, 500)
numpoints=400

```

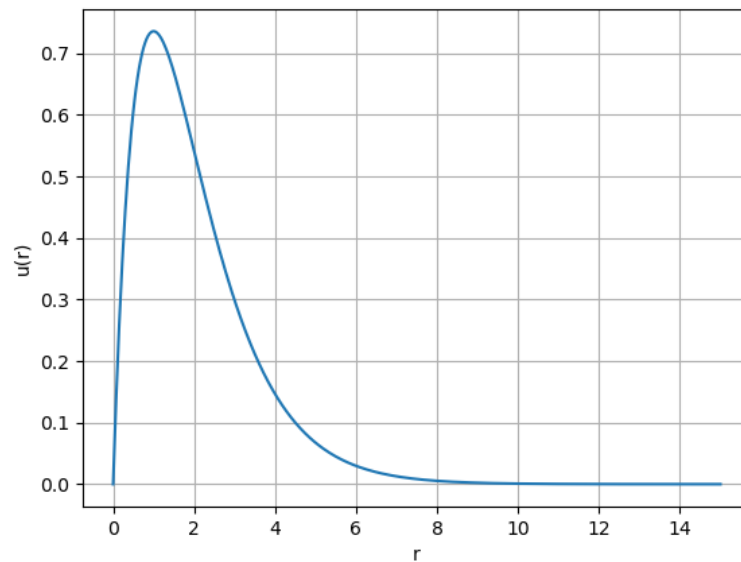
```

stoptime=15.0
rr = np.array([stoptime * float(i+0.0001) / (numpoints - 1) for i in range(numpoints)])
EE = [-1.1]
u0s = [
    shoot(EE[0], rr, l=0, vectorfield=vectorfield)[0] for E in EE
]

```

2.1.4 Plot

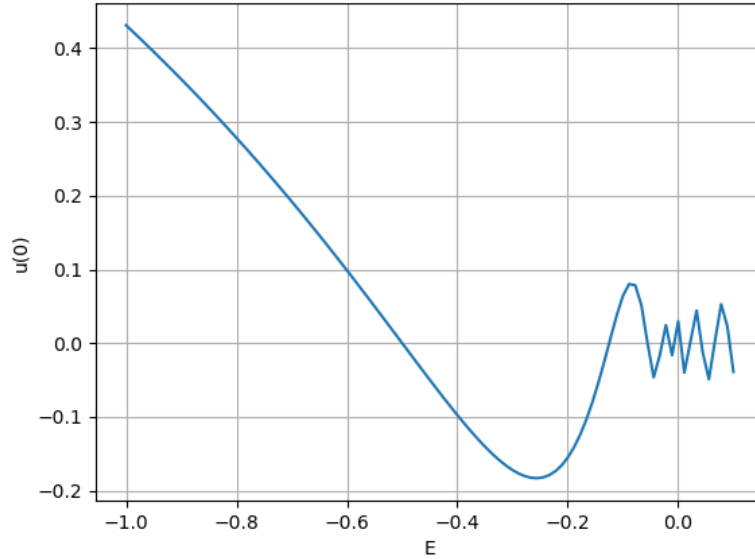
Plot to check results.



2.1.5 Plots

2.1.6 Main

Make some figures.



2.1.7 Solution of the SLP

Here we have to search for the value of E for which the BVP has the final conditions satisfied i.e. $u(r) = 0$. This is done using the optimization routine from `scipy`.

2.1.8 Code

The code is as follows

```
def get_energy_and_density(l,rr,z=1.,E=None, vectorfield=None, urf=None, tckur=None,
    dE = 0.51 # scan resolution to look for sign changes
    if E is None:
        E = -1.0 # starting energy

    if vectorfield is None:
        print("[get_energy_and_density] Error have to supply a vectorfield")
        return(0)

    if urf is None:
        def urf(x,tckur):
            return(0)
```



```

def fn(e):
    u0s = shoot(e, rr, l=1, z=z, fn=urf, tckfn=tckur, fnx=fnx, tckfnx=tckfnx, fnc=fnx)
    return(u0s)
E_bound = root_scalar(fn, x0=E-dE, x1=E+dE).root
_,u_bound,nrf,tck = shoot(E_bound, rr, l=1, z=z, fn=urf, fnx=fnx, tckfnx=tckfnx, fnc=fnx)
return(E_bound, u_bound, nrf, tck)

```

2.1.9 Testing

Test the functions.

```

numpoints=3200
stoptime=60.0
rr = np.array([stoptime * float(i+0.0001) / (numpoints - 1) for i in range(numpoints)])
E_bound,_,_,_ = get_energy_and_density(0,rr,vectorfield=vectorfield)

```

2.1.10 Main

Make figures.

3 Helium atom

Here we need to include the Hartree potential V_H which is the repulsion between the two electrons

$$V_H(\mathbf{r}) = \int d\mathbf{r}'^3 n(\mathbf{r}') \frac{1}{|\mathbf{r} - \mathbf{r}'|}$$

Where the $n(\mathbf{r})$ is the density which is given as

$$n(\mathbf{r}) = 2 \sum_i^{N_{occ}} |\psi(\mathbf{r})|^2$$

where we assume a closed shell spin singlet slater determinant. In order to get the radial part of the density, we can use the radial part of the wavefunction $\psi(\mathbf{r})$ which is $R(\mathbf{r})$.

$$n(r) = 2 \sum_i^{N_{occ}} |R(r)|^2$$

$$n(r) = 2 \sum_i^{N_{occ}} \left| \frac{u(r)}{r} \right|^2$$

3.1 Poisson equation

In order to calculate the Hartree potential Eq:??, we shall transform it into an SLP which we can again solve using the above methodology the solution of the Hydrogen atom.

$$\nabla^2 V_H(\mathbf{r}) = -4\pi n(\mathbf{r})$$

This can again be transformed using the variable substitution $u(r) = rR(r)$ to a 1D equation.

$$\frac{\partial^2 U(r)}{\partial r} = -4\pi r n(r)$$

The fact that $n(r)$ is simply $R(r)^2$ by definition and the fact that $u(r)$ is normalized we can drop off 4π to finally obtain

$$U''(r) = -\frac{u(r)^2}{r}$$

This is the SLP that we need to solve to obtain the hartree potential $V_H(r)$.

3.2 Solution

The BVP Eq:?? takes the following boundary conditions

$$U(0) = 0$$

$$U(r_{max}) = q_{max}$$

where, q_{max} is the total charge. We shall use these conditions in the shooting method to find the correct Hartree potential.

$$q_{max} = \int_0^{max} dr u^2(r)$$

3.2.1 Vector Field

```
def vectorfieldVH(w, t, p):
```

```
    """
```

```
    Defines the differential equations for the coupled spring-mass system.
```

```
    Arguments:
```

```
    w : vector of the state variables:
```

```

        w = [x1,y1,x2,y2]
t :   time
p :   vector of the parameters:
        p = [m1,m2,k1,k2,L1,L2,b1,b2]
"""
x1, y1 = w
_, _, nrf, tck, _, _, _, z = p

# Create f = (x1',y1'):
f = [y1,
      -nrf(t,tck)*nrf(t,tck)/t
     ]
return f

```

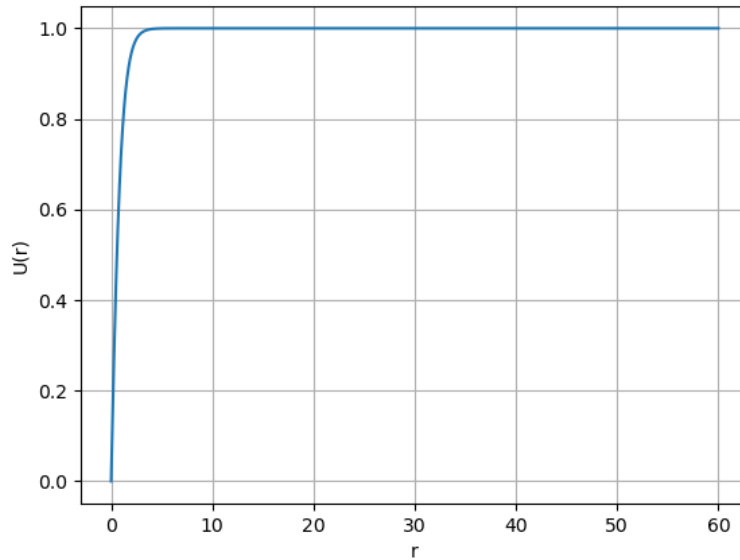
3.2.2 Testing

```

numpoints=400
stoptime=15.0
rr = np.array([stoptime * float(i+0.0001) / (numpoints - 1) for i in range(numpoints)])
qmax = 1.
xlim = qmax
ylim = 0
x1,urf,tckur = solve_SLP(fn=nrf, tckfn=tck, t=rr, xlim=xlim, ylim=ylim, vectorfield=v)

```

3.2.3 Main



3.3 Self-consistent field cycle

In order to find the solution, we need to perform a SCF loop so that the energy stays constant.

In order to calculate the total energy, we now also need to incorporate the Hartree potential

$$E = 2\epsilon - \int dr V_H(r) u^2(r)$$

3.3.1 Vector Field

```
def vectorfieldHe(w, t, p):  
    """  
    Defines the differential equations for the coupled spring-mass system.  
  
    Arguments:  
    w : vector of the state variables:  
        w = [x1,y1,x2,y2]  
    t : time  
    p : vector of the parameters:  
        p = [m1,m2,k1,k2,L1,L2,b1,b2]
```

```

"""
x1, y1 = w
e1, l1, urf, tckur, z = p

# Create f = (x1',y1'):
f = [y1,
      2*(l1*(l1+1)/(t)**2 - z/t - e1 + urf(t,tckur)/t)*x1
     ]

return f

```

3.3.2 Calculate energy

```

def calcEnergy(ei,urf,tckur,nrf,tck,t=None,stoptime=60.0,numpoints=3200):
    E = 2*ei
    if t is None:
        t = [stoptime * float(i+0.0001) / (numpoints - 1) for i in range(numpoints)]
    h = t[1]-t[0]
    VH1 = np.array([urf(x,tckur)/x for x in t])
    Nr2 = np.array([(nrf(x,tck))**2 for x in t])
    eH = integrate.simps(VH1*Nr2, x=t)
    print(eH)
    E = E - eH
    return(E)

```

3.3.3 SCF cycle code

```

stoptime=60.0
numpoints=3200
rr = np.array([stoptime * float(i+0.0001) / (numpoints - 1) for i in range(numpoints)])

# Get initial density
E_bound,_,nrf,tck = get_energy_and_density(0,rr,z=2.,E=-1.50,vectorfield=vectorfield)

# Get initial ur
qmax = 1.
xlim = qmax
ylim = 0.
x1,urf,tckur = solve_SLP(fn=nrf, tckfn=tck, t=rr, xlim=xlim, ylim=ylim, vectorfield=v

```

```

EO = calcEnergy(E_bound, urf, tckur, nrf, tck)
print(E_bound, EO)

E_conv = []
dE_conv = []
E_conv.append(EO)
dE_conv.append(EO)
cnt = 0
Ediff = 10.
while cnt < 9 and abs(Ediff) > 1.E-4:

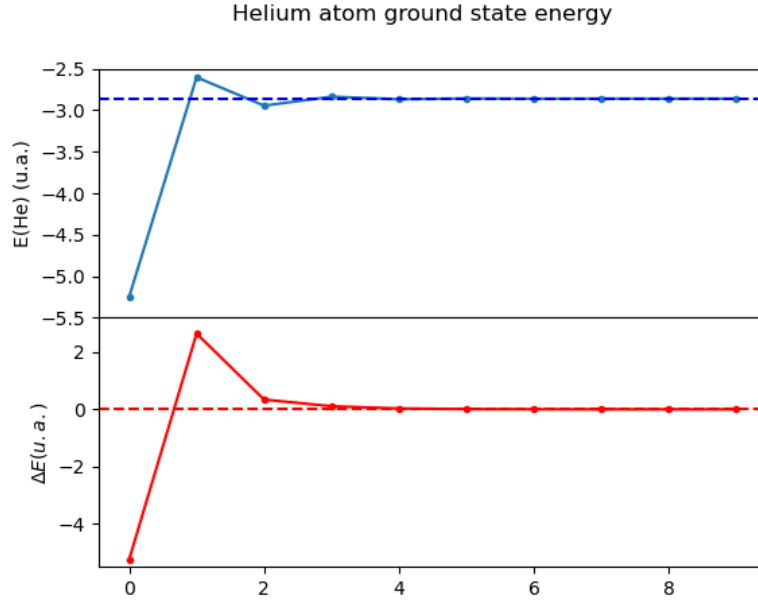
    # Get density
    E_bound,_,nrf,tck = get_energy_and_density(0,rr,z=2.,E=-1.50,vectorfield=vectorfie
    # Get ur
    x1,urf,tckur = solve_SLP(fn=nrf, tckfn=tck, t=rr, xlim=xlim, ylim=ylim, vectorfie
    E1 = calcEnergy(E_bound, urf, tckur, nrf, tck,t=rr)
    #E1 = E_bound
    E_conv.append(E1)
    Ediff = abs(EO-E1)
    dE_conv.append(Ediff)
    print(f"Iter : {cnt} E = {E1} Diff = {Ediff} E_bound={E_bound}")
    EO = E1

    cnt += 1

```

3.3.4 Main

3.4 Figure



3.5 The local density Exchange potential

The Hartree potential used above is not the full potential since we have subtracted half of the electron density to take into account the self-energy correction. However, if we take the actual Hartree potential into account, the energy obtained is very far from the exact energy.

In order to correct for this self interaction energy, we can use the local density exchange potential (LDA). A simple functional based on the electron gas is given as

$$V_x(\mathbf{r}) = - \left(\frac{3}{\pi} \right)^{1/3} \times n^{1/3}(\mathbf{r})$$

This potential is defined as the partial derivative of the exchange energy

$$V_x[n](\mathbf{r}) = \frac{\partial}{\partial n(\mathbf{r})} E_x[n]$$

And the exchange energy is given as

$$E_x[n] = \int d^3r \epsilon_x[n(\mathbf{r})] n(\mathbf{r})$$

where the exchange energy density is given as

$$\epsilon_x[n(\mathbf{r})] = -(3/4)(3/\pi)^{1/3} \times n^{1/3}(\mathbf{r})$$

The local density exchange potential is derived from this local energy density expression.

This local density based potential can correct for part of the self-energy error in the Hartree potential. Note that here, and for the calculation for the Hartree potential, the full density is to be taken. We can again write this in terms of the radial function as

$$V_x(\mathbf{r}) = - \left[\frac{3u^2(r)}{2\pi^2 r^2} \right]^{1/3}$$

and, using the above exchange energy, the total energy can then be written as

$$E = 2\epsilon - \int dr V_H(r)u^2(r) + \frac{1}{2} \int dr V_x(r)u^2(r)$$

The full equation then reads

$$y = \begin{pmatrix} u \\ u' \end{pmatrix}$$

$$y' = \begin{pmatrix} u' \\ u'' \end{pmatrix} = \begin{pmatrix} u' \\ 2 \left(\frac{l(l+1)}{r^2} - \frac{Z}{r} + V_H + V_x - E \right) u \end{pmatrix}$$

3.5.1 Vector Field

```
def vectorfieldX(w, t, p):
```

```
    """
```

```
    Defines the differential equations for the coupled spring-mass system.
```

```
    Arguments:
```

```
    w : vector of the state variables:
```

```
        w = [x1,y1,x2,y2]
```

```
    t : time
```

```
    p : vector of the parameters:
```

```
        p = [m1,m2,k1,k2,L1,L2,b1,b2]
```

```
    """
```

```
    x1, y1 = w
```



```

e1, l1, urf, tckur, urxf, tckurx, nrf, tck, z = p

# Create f = (x1',y1'):
f = [y1,
      2*(l1*(l1+1)/(t)**2 - z/(t) - e1 + 2*urf(t,tckur)/t + urxf(t,nrf,tck) )*x1
     ]

return f

```

3.5.2 Calculate energy

```

def calcEnergyVx(ei,urf,tckur,urxf,tckurx,nrf,tck,t=None,stoptime=60.0,numpoints=3200)
    E = 2*ei
    if t is None:
        t = [stoptime * float(i+0.0001) / (numpoints - 1) for i in range(numpoints)]
    VH1 = np.array([urf(x,tckur)/x for x in t])
    Vx1 = np.array([urxf(x,nrf,tck) for x in t])
    ur2 = np.array([(nrf(x,tck))**2 for x in t])
    eH = integrate.simps(VH1*ur2, x=t)
    ex = integrate.simps(Vx1*ur2, x=t)
    print((eH, (ex/2)))
    E = E - eH + (ex/2)
    return(E)

```

3.5.3 SCF cycle code

```

stoptime=60.0
numpoints=3200
rr = np.array([stoptime * float(i+0.0001) / (numpoints - 1) for i in range(numpoints)])

# Get initial density
E_bound,_,nrf,tck = get_energy_and_density(0,rr,z=2.,E=-2.50,vectorfield=vectorfield)

# Get initial ur
qmax = 1.
xlim = qmax
ylim = 0.
x1,urf,tckur = solve_SLP(fn=nrf, tckfn=tck, t=rr, xlim=xlim, ylim=ylim, vectorfield=vectorfield)
EO = calcEnergy(E_bound, urf, tckur, nrf, tck)

```

```

print(E_bound, E0)

def urxf(x,nrf,tck):
    numer = 3.*nrf(x,tck)*nrf(x,tck)
    denom = 2.*np.pi*np.pi*x*x
    return(-np.power(numer/denom,1/3))

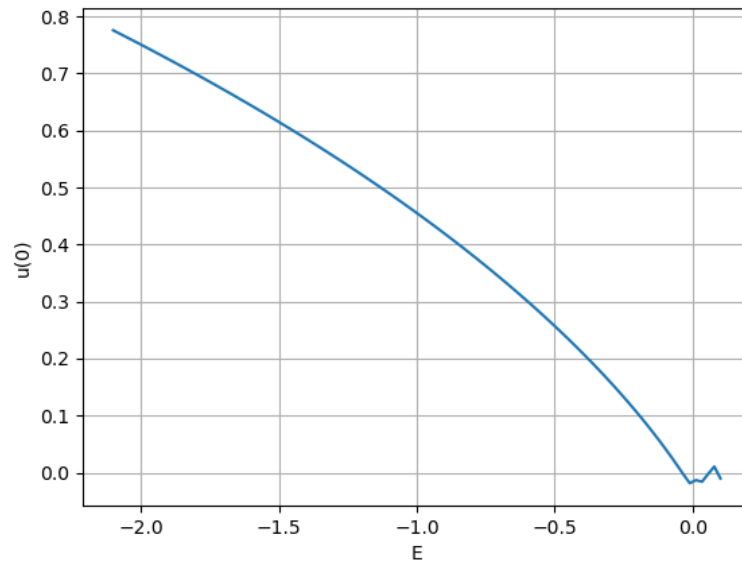
E_conv = []
dE_conv = []
E_conv.append(E0)
dE_conv.append(E0)
cnt = 0
Ediff = 10.
while cnt < 30 and abs(Ediff) > 1.E-4:

    # Get density
    E_bound,_,nrf,tck = get_energy_and_density(0,rr,z=2.,E=-1.00,vectorfield=vectorfie
    # Get ur
    x1,urf,tckur = solve_SLP(fn=nrf, tckfn=tck, t=rr, xlim=xlim, ylim=ylim, vectorfie
    E1 = calcEnergyVx(E_bound, urf, tckur, urxf, tckur, nrf, tck, t=rr)
    #E1 = E_bound
    E_conv.append(E1)
    Ediff = abs(E0-E1)
    dE_conv.append(Ediff)
    print(f"Iter : {cnt} E = {E1} Diff = {Ediff} E_bound={E_bound}")
    E0 = E1

    cnt += 1

```

3.5.4 Main Shoot



3.5.5 Main

3.6 Figure

