

# CS10720 Problems and Solutions

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Today: Computability

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# Plans for Today

## ① Remembering our Goal

Reminder

Revision of Important Concepts

## ② Simulations

Emulators

Simulations

## ③ Non-Computability

Constructing a Proof

Checking the Proof

## ④ Summary

Summary & Take Home Message

# Towards Our Goal

**Remember**    want to find out what kind of **computational problem** computers cannot solve

What do we mean by 'cannot solve'?

What we do **NOT** mean is cannot be solved because of

- lack of resources (memory, time, ...)
- lack of a clever idea
- we do not quite understand problem

What    we **DO** mean is  
cannot be solved for principle reasons  
not today, not tomorrow—**never**

**Remember**

- computational problem
- reduction
- Turing machine

# Computational Problems

## Definition (Computational Problem)

A computational problem is defined by a set of finite inputs over a finite input alphabet and for each input a set of correct finite outputs over a finite output alphabet.

**Example**    **input** directed graph with edge weights, nodes  $A$  and  $B$   
              **output** shortest path from  $A$  to  $B$

## Definition (Optimisation Problem)

A optimisation problem is a computational problem where the output is the value of an optimal solution.

**Example**    **input** directed graph with edge weights, nodes  $A$  and  $B$   
              **output** length of shortest path from  $A$  to  $B$

## Definition (Decision Problem)

A decision problem is a computational problem where the output is 'yes' or 'no' (alternatively, '0' or '1' if we prefer binary encodings).

**Example**    **input** directed graph with edge weights, nodes  $A$  and  $B$ , value  $k$   
              **output** yes if there is a path from  $A$  to  $B$  of length  $\leq k$ , no otherwise

# Reductions

**Fact** Solving some problem  $P$   
 using an algorithm for some other problem  $Q$   
 is called 'reducing  $P$  to  $Q$ '  
 and implies in some sense  $P$  is not much harder than  $Q$

**Special case** solving decision problem  $P$   
 using an algorithm for some other decision problem  $Q$   
 is called 'reducing  $P$  to  $Q$ ' and written as  $P \leq Q$   
 and implies in some sense  $P$  is not much harder than  $Q$

**Observation** reductions can help to find  
 more problems that computers cannot solve  
 If we know that  $P$  **cannot** be solved by computer  
 and if we know that  $P \leq Q$   
 then  $Q$  cannot be solved by computer  
 because we can solve  $P$  with the help of  $Q$   
 and the ' $\leq$ '-algorithm

# Remember: Turing Machine

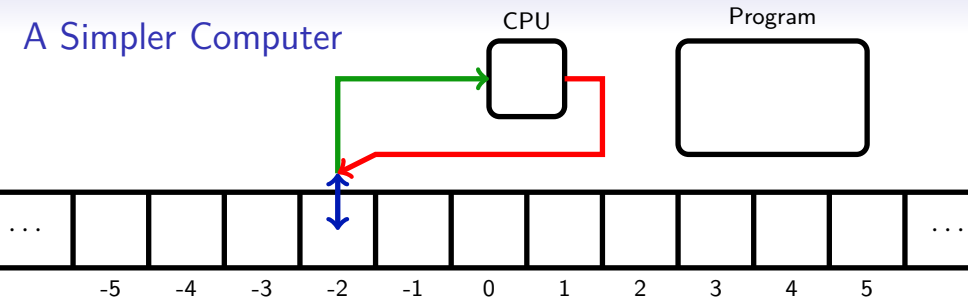
## Definition (Turing Machine)

A **Turing machine** has a finite set of possible states  $Q$ , an initial state  $q_0 \in Q$ , a finite memory alphabet  $\Gamma$  that contains the blank character  $\_$ , a finite input alphabet  $\Sigma$  that does not contain  $\_$ , an infinite memory that is linearly organised, and a current position in the memory. Initially the input is in the memory, the current position is the first position of the input and all unused memory cells contain  $\_$ . Its functioning is defined by a program

$P: Q \times \Gamma \rightarrow Q \times \Gamma \times \{L, R, *\}$ . It operates in steps, in each step it is in some state  $q \in Q$  and reads the contents of the current cell  $a \in \Gamma$ . If  $P(q, a) = (r, b, d)$  then it replaces  $a$  by  $b$ , changes state from  $q$  to  $r$  and changes the current cell to its neighbour if  $d = L$ , to its right neighbour if  $d = R$ , leaving it unchanged if  $d = *$ .

**Observe** Turing machine is our simpler computer  
can solve exactly all problems that any computer can solve 287

## A Simpler Computer



- infinite number of **memory** cells
- **CPU** that is in a state
- **program** the CPU follows (by executing it)
- CPU operates in steps (one command of program in one step)
- in each step, CPU can read from current cell of memory
- in each step, CPU can write to the same cell of memory
- in each step, CPU can change its state
- in each step, current cell can change to neighbouring cell

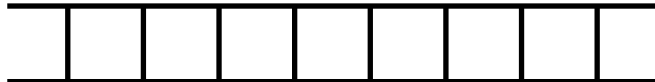
Observation    is Turing machine

## Example: Decide if Number of 1s in Input is Odd

- input alphabet  $\Sigma = \{0, 1\}$
- memory alphabet  $\Gamma = \{0, 1, \_ \}$
- states  $Q = \{q_0, q_1, q_{\text{yes}}, q_{\text{no}}\}$

Program  $P$

$(q, a)$	$(r, b, d)$
$(q_0, 0)$	$(q_0, \_, R)$
$(q_0, 1)$	$(q_1, \_, R)$
$(q_0, \_)$	$(q_{\text{no}}, \_, *)$
$(q_1, 0)$	$(q_1, \_, R)$
$(q_1, 1)$	$(q_0, \_, R)$
$(q_1, \_)$	$(q_{\text{yes}}, \_, *)$





# What Do we Mean By 'Cannot Solve'?

When do we say a computer solves a computational problem?

We expect

- for each input a correct output
- in finite time.

Again to be crystal clear

We say 'program  $P$  solves the computational problem  $Q$ '

if for any input that is an instance of  $Q$

$P$  stops eventually and outputs a correct solution  
for that instance

## Definition (Computability)

We call a computational problem **computable** if there exists a program that solves it.

Are there computational problems that are not computable?

If so, are any of them practically important?

## Concentrating on Decision Problems

**Fact** we will be concentrating on **decision problems**  
i. e., problems where the output is yes/no (or 1/0)

Is this is fundamental restriction?

**Observation** **not** a fundamental restriction ✓  
**because** ① often reduction of computational problem  
to decision problem possible  
② always possible to use binary encoding for  
output of computational problem binary  
and use separate decision problem for each bit of the output

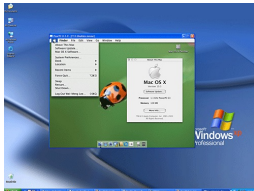
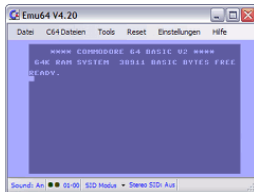
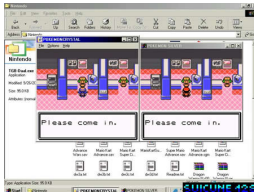
**Remember** decision problems **are** computational problems  
just restricted ones  
(with strong restriction on possible output)

# Towards an Important Non-Computable Problem

We want to know    Is there a non-computable computational problem?  
Is there a practically important one?

Important concept    on the way to an answer  
emulation/simulation  
'computers pretending to be other computers'  
'programs pretending to be other programs'

# Emulators



## Closer to Computational Problems

**Observation**    given a program  $P$  and an input  $I$   
it is **possible** for another program to simulate  $P$  on  $I$

Is that difficult?

**Observation**    depends on the way  $P$  is given  
(e. g., C program, Java program, ...)  
particularly **easy** if  $P$  is given as a Turing machine  
because Turing machines are so restricted

**We can**    simulate any program  $P$  on any input  $I$   
(the simulation may be slower than running  $P$  directly)  
(but in the context of computability this is not important)

## Correctness of Programs

Why would anyone want to simulate a program  $P$  on an input  $I$ ?

Observation could be useful to test correctness of programs

i. e., for program  $P$  and input  $I$ :

- 1 Does  $P$  stop on  $I$ ?
- 2 Is the output  $P$  computes for  $I$  correct?

Let's concentrate on the partial problem 1

We want program taking as input program  $P$  and input  $I$  for  $P$  and outputs if  $P$  stops on  $I$

Observation This is a decision problem.

### Definition (Halting problem)

The decision problem that takes as input a program  $P$  and an input  $I$  for  $P$  and that outputs 'yes' if  $P$  stops on  $I$  and 'no' otherwise is called the halting problem.

Observation halting problem is practically important

# Writing a Relatively Simple Program

Let's **assume** that the halting problem is computable

- i. e., we assume program  $H$  that solves halting problem exists
- i. e.,  $H$  takes as input a program  $P$  and in input  $I$   
 $H$  stops after some time and outputs 'yes' if  $P$  stops on  $I$   
 and outputs 'no' if  $P$  never stops on  $I$

**Remark**  $H$  **cannot** just simulate  $P$  on  $I$   
**because** then  $H$  would not stop if  $P$  does not stop on  $I$   
 $H$  somehow needs to recognise if  $P$  gets stuck on  $I$   
 but we do not care how this is done

**Remember** we **assume**  $H$  solves the halting problem

## Constructing a Program

**Remember** we **assume**  $H$  solves the halting problem

**Define** program  $M$  that accepts as input program  $P$   
(format for  $P$  is the same as for  $H$ )

**Program**  $M$  (with input  $P$ )

Simulate  $H$  on  $(P, P)$ .

If  $H$  outputs 'no' then stop else loop forever.

### Observations

- $M$  is not particularly difficult to build
- $M$  does not do anything particularly useful
- $M$  stops if  $H$  outputs 'no' for  $P$  on  $P$  as input.
- $M$  does not stop if  $H$  outputs 'yes' for  $P$  on  $P$  as input.



## $M$ on a Very Special Input

Program  $M$  (with input  $P$ )

Simulate  $H$  on  $(P, P)$ .

If  $H$  outputs 'no' then stop else loop forever.

What does  $M$  do with  $M$  as input?

Observation if  $M$  receives a description of  $M$  as input  
it simulates  $H$  on  $(M, M)$

What does  $H$  do on input  $(M, M)$ ?

Observation it stops and outputs either 'yes' or 'no'

Case 1  $H$  outputs 'yes' on  $(M, M) \Rightarrow M$  does **not** stop on input  $M$   
**because** it loops forever if  $H$  outputs 'yes'  
 **$H$  was wrong**  $\Rightarrow$  Case 1 is impossible

Case 2  $H$  outputs 'no' on  $(M, M) \Rightarrow M$  stops on input  $M$   
**because** it stops if  $H$  outputs 'no'  
 **$H$  was wrong**  $\Rightarrow$  Case 2 is impossible

In any case  **$H$  makes a mistake** on input  $(M, M)$

# The Halting Problem

**We see** for program  $H$  the supposedly solves the halting problem  
we can construct  $M$  such that  
 $H$  makes a mistake on input  $(M, M)$   
**proving** that  $H$  does **not solve** the halting problem

**Observation** this works for any program  $H$

**Consequence** no program can solve the halting problem  
**because** 'solving' means  
stopping on all inputs and deciding correctly

## Theorem

*The halting problem is not computable.*

# Summary & Take Home Message

## Things to remember

- halting problem
- computability
- halting problem not computable

## Take Home Message

- The halting problem is a practical, important problem with significant applications.
- No computer can ever be able to solve the halting problem.
- There are problems that computers cannot solve and we should be aware of this so that we do not waste our time trying.

**Lecture feedback** <http://onlinetted.com>